

Research Article

Pullback D -Attractor of Coupled Rod Equations with Nonlinear Moving Heat Source

Danxia Wang, Jianwen Zhang, and Yinzhu Wang

Department of Mathematics, Taiyuan University of Technology, Taiyuan 030024, China

Correspondence should be addressed to Jianwen Zhang; jianwen.z2008@163.com

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We consider the pullback D -attractor for the nonautonomous nonlinear equations of thermoelastic coupled rod with a nonlinear moving heat source. By Galerkin method, the existence and uniqueness of global solutions are proved under homogeneous boundary conditions and initial conditions. By prior estimates combined with some inequality skills, the existence of the pullback D -absorbing set is obtained. By proving the properties of compactness about the nonlinear operator $g_1(\cdot)$, $g_2(\cdot)$, and then proving the pullback D -condition (C), the existence of the pullback D -attractor of the equations previously mentioned is given.

1. Introduction

In this paper, we consider a thermoelastic coupled rod system:

$$u_{tt} - \beta \Delta u + \gamma u_t + \nabla \tilde{\theta} + g_1(u) = f(x, t), \quad (1)$$

$$\tilde{\theta}_t - k \Delta \tilde{\theta} + \nabla u_t = g_2(\tilde{\theta}) + Q(x, t), \quad (2)$$

$$u|_{\partial\Omega} = 0, \quad \nabla \tilde{\theta}|_{\partial\Omega} = 0, \quad x \in \partial\Omega, \quad (3)$$

$$u(x, \tau) = u_0(x), \quad u_t(x, \tau) = p_0(x), \quad \tilde{\theta}(x, \tau) = \tilde{\theta}_0(x), \quad (4)$$

$x \in \Omega$

with an external force function and a nonlinear moving heat source function. Here $u(x, t)$ is the rod elastic displacement. $\tilde{\theta}(x, t)$ is the dimensionless temperature. β, γ, k are all positive constants, where β is the square of wave velocity, γ is the damping coefficient, and k is the thermal diffusivity. $\Omega \subset \mathbb{R}^2$ is a bounded smooth domain. $f(x, t)$ is the external force and $f(x, t)$ is locally square integrable with respect to time for $t \in \mathbb{R}, x \in \Omega$; that is, $f(x, t) \in L^2_{\text{loc}}(\mathbb{R}, L^2(\Omega))$. $Q(x, t)$ is the moving heat source and $Q(x, t)$ is locally square integrable in time for $t \in \mathbb{R}, x \in \Omega$; that is, $Q(x, t) \in L^2_{\text{loc}}(\mathbb{R}, L^2(\Omega))$. $g_1(u)$ and $g_2(\tilde{\theta})$ are all the nonlinear function, and $g_1(u)$ and

$g_2(\tilde{\theta})$ are continuous on \mathbb{R} , respectively. We give the pullback D -attractor for the nonautonomous nonlinear equations of thermoelastic coupled rod in space $E_1 = D(A) \times V \times V$, where $A = -\Delta, V = H^1_0(\Omega)$.

Recently the research of the nonautonomous infinite dimensional dynamical system has been paid much attention and developed fast as evidence by the references cited in [1–7]. Chepyzhov and Vishik [1] firstly extend the notion of global attractor in the autonomous case to the concept of the uniform attractor for the nonautonomous case. But the uniform attractor is not applicable to the nonautonomous systems in which the trajectories can be unbounded as time increases to infinity. Therefore some new concepts and theories must be brought up for such nonautonomous case, where the concepts and the theorem of existence of the pullback D -attractor were advanced in [2–8] and so on.

Caraballo et al. [2] and so forth gave the existence of the pullback D -attractor for a nonautonomous N-S equation under the assumptions of asymptotic compactness and existence of a family of absorbing sets. Wang and Zhong [3] advanced the existence of the pullback D -attractor for the dissipative Sine-Gordon wave equation in an unbounded domain in which the external force did not need to be bounded. In [4, 5], The author studied the pullback attractor of the reaction-diffusion equation and the generalized Korteweg-de Vries-Burgers equation, respectively. S. H. Park

and J. Y. Park [6] considered the nonautonomous modified Swift-Hohenberg equation

$$u_t + \Delta^2 u + 2\Delta u + au + b|\nabla u|^2 + u^3 = g(x, t) \quad (5)$$

and proved the existence of the pullback attractor when its external force has exponential growth. The abovementioned systems are all specific systems. For the widespread used nonautonomous structural system in engineering, the study has been paid less attention. Park and Kang [7] studied the existence of the pullback D -attractor for nonautonomous suspension bridge equation because of being motivated by Ma et al. [8, 9]:

$$u_{tt} + \Delta^2 u + \mu u_t + ku^+ + g(u) = f(x, t). \quad (6)$$

In this paper, based on Al-Hunuti et al. [10] as the relaxation time $\bar{\tau}$ is not considered and Carlson [11], we study a more general nonlinear thermoelastic coupled system (1)–(4) of a rod due to a nonlinear moving heat source $Q(x, t)$. We give the existence of a pullback D -attractor of above system by proving the existence of a pullback D -absorbing set and pullback condition (C) for the external force $f(x, t)$ unnecessarily bounded.

In fact, we assume that the external forces $f(x, t)$ and $Q(x, t)$ satisfy $f(x, t) \in L^2_{\text{loc}}(R, L^2(\Omega))$, $f'(x, t) \in L^2_{\text{loc}}(R, L^2(\Omega))$, and $Q(x, t) \in L^2_{\text{loc}}(R, L^2(\Omega))$, respectively, and for any $t \in R$

$$\int_{-\infty}^t e^{\delta s} (|f(s)|^2 + |f'(s)|^2 + |Q(s)|^2) ds < \infty, \quad (7)$$

where $\delta > 0$ is a small real number which will be characterized later.

On the assumptions of the nonlinear function $g_1(\cdot)$, Park and Kang gave the assumption

$$\limsup_{|s| \rightarrow \infty} \frac{|g'_1(s)|}{|s|^\gamma} = 0, \quad (8)$$

(where $0 \leq \gamma < \infty$) for nonautonomous suspension bridge equations in [7]. At present, we remove the assumption of [7] and we assume that the nonlinear function $g_1(\cdot) \in C^2(R, R)$ satisfies the following assumptions:

(H_1) we denote by $G(s)$ the primitive of $g_1(s)$; that is, $G(s) = \int_0^s g_1(\tau) d\tau$, and then

$$\liminf_{|s| \rightarrow \infty} \frac{|G(s)|}{s^2} \geq 0; \quad (9)$$

(H_2) $g_1(u) \leq 1 + |u|^{\rho+1}$ for some $0 \leq \rho < \infty$;

(H_3) $g'_1(u) \leq C'(1 + |u|^\rho)$ for some $0 \leq \rho < \infty$;

(H_4) there exists a constant $C_0 > 0$ such that

$$\liminf_{|s| \rightarrow \infty} \frac{s g_1(s) - C_0 G(s)}{s^2} \geq 0; \quad (10)$$

(H_5) $g_1(0) = 0$.

We also assume that the nonlinear function $g_2(\cdot) \in C^1(R, R)$ satisfies the following assumptions: there exists a constant a_1 such that

$$g_2(0) = 0, \quad |g'_2(s)| \leq a_1, \quad \forall s \in R. \quad (11)$$

Throughout this paper, we introduce the spaces $H = L^2(\Omega)$ and $V = H_0^1(\Omega)$ and endow these spaces with the usual scalar products and norms (\cdot, \cdot) , $|\cdot|$, $((\cdot, \cdot))$, $\|\cdot\|$, where $(u, v) = \int_{\Omega} uv dx$, $((u, v)) = \int_{\Omega} \nabla u \nabla v dx$. Because of defining $A = -\Delta$, with reference to [7] we have the scalar products (Au, Au) and norm $|Au|^2$ in the space $D(A)$. By the Poincaré inequality, there exists a proper constant $\lambda_1, \lambda_2 > 0$ such that

$$\begin{aligned} \|u\|^2 &\geq \lambda_1 |u|^2, \quad \forall u \in V, \\ |Au|^2 &\geq \lambda_2 \|u\|^2, \quad \forall u \in D(A). \end{aligned} \quad (12)$$

2. Pullback D_{δ, E_1} -Attracting Set

By normal Galerkin method (see [1, 12–14]), we have the following theorem of existence and uniqueness of solutions to problems (1)–(4).

Theorem 1. Assume that $\beta, \gamma, k > 0$, $f(x, t), Q(x, t) \in L^2_{\text{loc}}(R, H)$ and the assumptions of the functions $g_1(\cdot), g_2(\cdot)$ hold; then, for all $T > 0$ and any given $u_0 \in V, p_0 \in H, \bar{\theta}_0 \in H$, problems (1)–(4) have a unique solution $(u, \bar{\theta})$ such that

$$u \in C^0(R_{\tau}; V) \cap C^1(R_{\tau}; H), \quad \bar{\theta} \in C^0(R_{\tau}; H), \quad (13)$$

where $R_{\tau} = [\tau, \infty)$.

Moreover $f'(x, t) \in L^2_{\text{loc}}(\tau, T; H)$, for all $T > 0, u_0 \in D(A), p_0 \in V, \bar{\theta}_0 \in V$; then

$$u \in C^0(R_{\tau}; D(A)) \cap C^1(R_{\tau}; V), \quad \bar{\theta} \in C^0(R_{\tau}; V). \quad (14)$$

For simplicity, we write $y(r) = (u(r), \partial_r u(r), \bar{\theta}(r)) = (u(r), p(r), \bar{\theta}(r))$, $y_0 = (u_0, p_0, \bar{\theta}_0)$. We denote by $E_0 = V \times H \times H$ the space of vector functions $y(r) = (u(r), p(r), \bar{\theta}(r))$ with the norm $\|y\|_{E_0} = \|u\|^2 + |p|^2 + |\bar{\theta}|^2$ in E_0 and denote by $E_1 = D(A) \times V \times V$ the space of vector functions $y(r) = (u(r), p(r), \bar{\theta}(r))$ with the norm $\|y\|_{E_1} = |Au|^2 + \|p\|^2 + \|\bar{\theta}\|^2$ in E_1 . We can construct the nonautonomous dynamical system generated by problems (1)–(4) in E_0 or E_1 . We consider $Q = R, \theta_t \tau = \tau + t$, and then we define

$$\begin{aligned} \Phi(t, \tau, y_0) &= y(t + \tau, \tau, y_0) \\ &= (u(t + \tau), p(t + \tau), \bar{\theta}(t + \tau)), \end{aligned} \quad (15)$$

$$\tau \in R, \quad t \geq 0, \quad y_0 \in E_0, E_1.$$

The uniqueness of solutions to problems (1)–(4) implies that

$$\begin{aligned} \Phi(t, \tau, y_0) &= \Phi(t, s + \tau, \Phi(s, \tau, y_0)), \\ \tau \in R, \quad t \geq 0, \quad y_0 \in E_0, E_1. \end{aligned} \quad (16)$$

And, for all $\tau \in R, t \geq 0$, the mapping $\Phi(t, \tau, \cdot) : E_0 \rightarrow E_0$ (or $E_1 \rightarrow E_1$) defined by (15) is continuous. Consequently, the mapping $\Phi(t, \tau, \cdot)$ defined by (15) is a continuous cocycle on E_0 or E_1 .

Let \mathfrak{R}_δ be the set of all functions $r : R \rightarrow (0, +\infty)$ such that

$$\lim_{t \rightarrow \infty} e^{\delta t} r^2(t) = 0, \tag{17}$$

where $0 < \delta < 2\alpha_1$ and $\alpha_1 = \min\{3\alpha/16, \gamma/2, k\lambda/4, \alpha C_0/2\}$ and D_{δ, E_0} denotes the class of all families $\widehat{D} = \{D(t); t \in R\} \subset P(E_0)$ such that $D(t) \subset \overline{B}(0, r_{\widehat{D}}(t))$ for some $r_{\widehat{D}} \in \mathfrak{R}_\delta$, where $\overline{B}(0, r_{\widehat{D}}(t))$ denotes the closed ball in E_0 centered on 0 with radius $r_{\widehat{D}}(t)$.

Theorem 2. Assume that $\beta, \gamma, k > 0$ and the assumptions of the functions $g_1(\cdot), g_2(\cdot)$ hold. Suppose that $f(x, t) \in L^2_{loc}(R, H)$ and $Q(x, t) \in L^2_{loc}(R, H)$ satisfy (7). Then there exists a pullback D_{δ, E_0} -attracting set in E_0 for the nonautonomous dynamical system (θ, Φ) defined by (15).

Proof. Let $t \in R, \tau \geq 0$, and $y_0 = (u_0, p_0, \tilde{\theta}_0) \in E_0$ be fixed. Define

$$\begin{aligned} u(r) &= u(r, t - \tau, u_0), \\ p(r) &= u'(r, t - \tau, p_0), \\ \tilde{\theta}(r) &= \tilde{\theta}(r, t - \tau, \tilde{\theta}_0), \\ &\text{for } r \geq t - \tau, \\ (u(r), p(r), \tilde{\theta}(r)) &= \Phi(r - t + \tau, t - \tau, y_0) \\ &\text{for } r \geq t - \tau. \end{aligned} \tag{18}$$

Taking the scalar product in H of (1) with $v = u' + \alpha u$ and taking the scalar product in H of (2) with $\tilde{\theta}$, after a computation of addition, we obtain

$$\begin{aligned} &\frac{1}{2} \frac{d}{dr} (\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2) + \gamma |v|^2 - \alpha |v|^2 \\ &+ \alpha \beta \|u\|^2 + k \|\tilde{\theta}\|^2 + \alpha^2(u, v) \\ &- \gamma \alpha(u, v) + \alpha(\nabla \tilde{\theta}, u) + (g_1(u), v) \\ &= (f, v) + (g_2(\tilde{\theta}), \tilde{\theta}) + (Q, \tilde{\theta}). \end{aligned} \tag{19}$$

For simplicity, define $\phi(u) = \int_\Omega G(u) d\Omega$. By the assumption (H_1) , it is obvious that $\phi(u) \geq 0$. By the assumption (H_4) of $g_1(\cdot)$, we have

$$(g_1(u), u) - C_0 \int_\Omega G(u) d\Omega + \frac{\lambda}{16} |u|^2 \geq -M, \tag{20}$$

so

$$\begin{aligned} &(g_1(u), v) \\ &= (g_1(u), u') + \alpha (g_1(u), u) \\ &\geq \int_\Omega \frac{d}{dr} G(u) d\Omega + \alpha C_0 \int_\Omega G(u) d\Omega - \alpha \frac{\lambda}{16} |u|^2 - \alpha M \\ &\geq \frac{d}{dr} \phi(u) + \alpha C_0 \phi(u) - \alpha \frac{\lambda}{16} |u|^2 - \alpha M. \end{aligned} \tag{21}$$

Considering assumption (11) of $g_2(\cdot)$, we have

$$|(g_2(\tilde{\theta}), \tilde{\theta})| \leq |g_2(\tilde{\theta})| |\tilde{\theta}| \leq a_1 |\tilde{\theta}|^2. \tag{22}$$

By the Young inequality and (12), we have

$$\begin{aligned} |(f, v)| &\leq \frac{1}{\gamma} |f|^2 + \frac{\gamma}{4} |v|^2; \\ |(Q, \tilde{\theta})| &\leq \frac{1}{\lambda k} |Q|^2 + \frac{k\lambda}{4} |\tilde{\theta}|^2 \leq \frac{1}{\lambda k} |Q|^2 + \frac{k}{4} \|\tilde{\theta}\|^2, \\ \alpha^2(u, v) &\geq -\frac{\alpha^2}{2} |u|^2 - \frac{\alpha^2}{2} |v|^2; \\ -\gamma \alpha(u, v) &\geq -\frac{2\gamma^2 \alpha}{\lambda} |v|^2 - \frac{\alpha \lambda}{8} |u|^2; \\ \alpha(\nabla \tilde{\theta}, u) &\geq -\frac{\alpha}{2\beta} |\tilde{\theta}|^2 - \frac{\alpha \beta}{2} \|u\|^2. \end{aligned} \tag{23}$$

Letting $0 < \alpha \leq \min\{\beta\lambda/2 + \lambda/4, -(1 + 2\gamma^2/\lambda) + \sqrt{(2\gamma^2/\lambda + 1)^2 + \gamma/2}, k\lambda\beta/2, 1\}$ and taking $a_1/k < \lambda/4$ and $\beta \geq 1$, we infer from (19) that

$$\begin{aligned} &\frac{1}{2} \frac{d}{dr} (\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u)) \\ &+ \frac{3\alpha\beta}{16} \|u\|^2 + \frac{\gamma}{2} |v|^2 + \frac{k\lambda}{4} |\tilde{\theta}|^2 + \alpha C_0 \phi(u) \\ &\leq \frac{1}{\gamma} |f|^2 + \alpha M + \frac{1}{\lambda k} |Q|^2. \end{aligned} \tag{24}$$

Also taking $\alpha_1 = \min\{3\alpha/16, \gamma/2, k\lambda/4, \alpha C_0/2\}$, we have

$$\begin{aligned} &\frac{d}{dr} (\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u)) \\ &+ 2\alpha_1 (\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u)) \\ &\leq \frac{2}{\gamma} |f|^2 + 2\alpha M + \frac{2}{\lambda k} |Q|^2. \end{aligned} \tag{25}$$

Note that

$$\begin{aligned} &\frac{d}{dr} e^{\delta r} (\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u)) \\ &= \delta e^{\delta r} (\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u)) \\ &+ e^{\delta r} \frac{d}{dr} (\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u)), \end{aligned} \tag{26}$$

and by (25), we have

$$\begin{aligned} & \frac{d}{dr} e^{\delta r} \left(\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u) \right) \\ & \leq (\delta - 2\alpha_1) e^{\delta r} \left(\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u) \right) \\ & \quad + e^{\delta r} \left(\frac{2}{\gamma} |f|^2 + 2\alpha M + \frac{2}{\lambda k} |Q|^2 \right). \end{aligned} \quad (27)$$

By integrating (27) over the interval $[t - \tau, t]$, we obtain

$$\begin{aligned} & e^{\delta t} \left(\beta \|u(t)\|^2 + |v(t)|^2 + |\tilde{\theta}(t)|^2 + 2\phi(u) \right) \\ & \leq e^{\delta(t-\tau)} \left(\beta \|u(t-\tau)\|^2 + |v(t-\tau)|^2 \right. \\ & \quad \left. + |\tilde{\theta}(t-\tau)|^2 + 2\phi(u(t-\tau)) \right) \\ & \quad + \int_{t-\tau}^t e^{\delta s} \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds + \frac{2\alpha M}{\delta} (e^{\delta t} - e^{\delta(t-\tau)}) \\ & \quad + \int_{t-\tau}^t (\delta - 2\alpha_1) e^{\delta s} \left(\beta \|u(s)\|^2 + |v(s)|^2 \right. \\ & \quad \left. + |\tilde{\theta}(s)|^2 + 2\phi(u(s)) \right) ds. \end{aligned} \quad (28)$$

Since $\delta < 2\alpha_1$, we have

$$\begin{aligned} & \beta \|u(t)\|^2 + |v(t)|^2 + |\tilde{\theta}(t)|^2 + 2\phi(u(t)) \\ & \leq e^{-\delta\tau} \left(\beta \|u(t-\tau)\|^2 + |v(t-\tau)|^2 \right. \\ & \quad \left. + |\tilde{\theta}(t-\tau)|^2 + 2\phi(u(t-\tau)) \right) \\ & \quad + e^{-\delta t} \int_{t-\tau}^t e^{\delta s} \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds + \frac{2\alpha M}{\delta} (1 - e^{-\delta\tau}). \end{aligned} \quad (29)$$

Note that

$$\begin{aligned} & \|u\|^2 + |p|^2 + |\tilde{\theta}|^2 + 2\phi(u) \\ & \leq \left(1 + \frac{2\alpha^2}{\lambda\beta} \right) (\beta \|u\|^2) + 2|v|^2 + |\tilde{\theta}|^2 + 2\phi(u). \end{aligned} \quad (30)$$

If we take $C_1 = \max\{2, 1 + 2\alpha^2/\lambda\beta\}$, we infer from (29) that

$$\begin{aligned} & \|u\|^2 + |p|^2 + |\tilde{\theta}|^2 + 2\phi(u) \\ & \leq C_1 \left(\beta \|u\|^2 + |v|^2 + |\tilde{\theta}|^2 + 2\phi(u) \right) \\ & \leq C_1 e^{-\delta\tau} \left(\beta \|u(t-\tau)\|^2 + |v(t-\tau)|^2 \right. \\ & \quad \left. + |\tilde{\theta}(t-\tau)|^2 + 2\phi(u(t-\tau)) \right) \end{aligned}$$

$$\begin{aligned} & + C_1 e^{-\delta t} \int_{t-\tau}^t e^{\delta s} \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds \\ & \quad + \frac{2C_1\alpha M}{\delta} (1 - e^{-\delta\tau}) \\ & \leq C_1 C_2 e^{-\delta\tau} \left[\|u(t-\tau)\|^2 + |p(t-\tau)|^2 \right. \\ & \quad \left. + |\tilde{\theta}(t-\tau)|^2 + 2\phi(u(t-\tau)) \right] \\ & \quad + C_1 e^{-\delta t} \int_{t-\tau}^t e^{\delta s} \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds \\ & \quad + \frac{2C_1\alpha M}{\delta} (1 - e^{-\delta\tau}). \end{aligned} \quad (31)$$

Let $\widehat{D}_{\delta, E_0}$ be given. For all $y(t-\tau) = y_0 \in D(t-\tau)$, $t \in R$ and $\tau \geq 0$, from the assumption (H_4) of $g_1(\cdot)$, we know that $\phi(u(t-\tau))$ is bounded. So we easily obtain from (31)

$$\begin{aligned} & \|\Phi(t, t-\tau, y_0)\|_{E_0}^2 \\ & \leq C_1 C_2 e^{-\delta\tau} \left[\|u(t-\tau)\|^2 + |p(t-\tau)|^2 \right. \\ & \quad \left. + |\tilde{\theta}(t-\tau)|^2 + 2\phi(u(t-\tau)) \right] \end{aligned} \quad (32)$$

$$\begin{aligned} & + C_1 e^{-\delta t} \int_{t-\tau}^t e^{\delta s} \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds \\ & \quad + \frac{2C_1\alpha M}{\delta} (1 - e^{-\delta\tau}) \end{aligned}$$

for all $y_0 \in D(t-\tau)$, $t \in R$, and $\tau \geq 0$. Set

$$\begin{aligned} (R_\delta(t))^2 & = 2C_1 e^{-\delta t} \int_{t-\tau}^t e^{\delta s} \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds \\ & \quad + \frac{4C_1\alpha M}{\delta} (1 - e^{-\delta\tau}), \end{aligned} \quad (33)$$

and consider the family $\widehat{B}_{\delta, E_0}$ of closed balls in E_0 defined by $B_\delta(t) = \{y \in E_0, \|y\|_{E_0} \leq R_\delta(t)\}$. It is easy to check that $\widehat{B}_{\delta, E_0} \in D_{\delta, E_0}$ and \widehat{B}_δ is pullback D_{δ, E_0} -absorbing for the cocycle Φ by (15). \square

In order to prove the pullback D_{δ, E_1} -attractor, let R_δ be the set of all functions $r : R \rightarrow (0, +\infty)$ which satisfies (17) and D_{δ, E_1} denotes the class of all families $\widehat{D} = \{D(t); t \in R\} \subset P(E_1)$ such that $D(t) \subset \overline{B}(0, r_{\widehat{D}}(t))$ for some $r_{\widehat{D}} \in \mathfrak{R}_\delta$, where $\overline{B}(0, r_{\widehat{D}}(t))$ denotes the closed ball in E_1 centered on 0 with radius $r_{\widehat{D}}(t)$.

Theorem 3. Assume that $\beta, \gamma, k > 0$ and the assumptions of $g_1(\cdot)$, $g_2(\cdot)$ hold. $f(x, t) \in L_{loc}^2(R, L^2(\Omega))$, $f'(x, t) \in L_{loc}^2(R, L^2(\Omega))$, and $Q(x, t) \in L_{loc}^2(R, L^2(\Omega))$ satisfy (7). Then there exists a pullback D_{δ, E_1} -attracting set in E_1 for the nonautonomous dynamical system (θ, Φ) defined by (15).

Proof. Let $t \in R, \tau \geq 0$ and $y_0 = (u_0, p_0, \bar{\theta}_0) \in E_1$ be fixed. Take the scalar product in H of (1) with $Av = Au' + \alpha Au$, and take the scalar product in H of (2) with $A\bar{\theta}$; then make summation to get

$$\begin{aligned} & \frac{1}{2} \frac{d}{dr} \left(\beta |Au|^2 + \|v\|^2 + \|\bar{\theta}\|^2 \right) + \gamma \|v\|^2 - \alpha \|v\|^2 \\ & + \alpha \beta |Au|^2 + k |A\bar{\theta}|^2 + \alpha^2 ((u, v)) \\ & - \gamma \alpha (Au, v) + \alpha (A^{1/2} \bar{\theta}, Au) + (g_1(u), Av) \\ & = (g_2(\bar{\theta}), A\bar{\theta}) + (f, Av) + (Q, A\bar{\theta}). \end{aligned} \tag{34}$$

Since

$$\begin{aligned} & (g_1(u), Av) \\ & = (g_1(u), Au') + \alpha (g_1(u), Au) \\ & = \frac{d}{dt} (g_1(u), Au) - (g_1'(u) u', Au) + \alpha (g_1(u), Au); \\ & (f, Av) \\ & = \frac{d}{dt} (f, Au) + \alpha (f, Au) - (f', Au), \end{aligned} \tag{35}$$

we infer from (34) that

$$\begin{aligned} & \frac{1}{2} \frac{d}{dr} \left(\beta |Au|^2 + \|v\|^2 + \|\bar{\theta}\|^2 + 2(g_1(u), Au) - 2(f, Au) \right) \\ & + \gamma \|v\|^2 - \alpha \|v\|^2 + \alpha \beta |Au|^2 + k |A\bar{\theta}|^2 + \alpha^2 (Au, v) \\ & - \gamma \alpha (Au, v) + \alpha (A^{1/2} \bar{\theta}, Au) + \alpha (g_1(u), Au) - \alpha (f, Au) \\ & \leq - (f', Au) + (Q, A\bar{\theta}) + (g_2(\bar{\theta}), A\bar{\theta}) + (g_1'(u) u', Au). \end{aligned} \tag{36}$$

Also

$$\begin{aligned} & \alpha^2 (Au, v) \geq -\frac{\alpha \beta}{16} |Au|^2 - \frac{4\alpha^3}{\beta} |v|^2; \\ & -\gamma \alpha (Au, v) \geq -\frac{\alpha \beta}{16} |Au|^2 - \frac{4\gamma^2 \alpha}{\beta} |v|^2; \\ & \alpha (A^{1/2}(\bar{\theta}), Au) \geq -\frac{4\alpha}{\beta} |A^{1/2} \bar{\theta}|^2 - \frac{\alpha \beta}{16} |Au|^2; \\ & - (f', Au) \leq \frac{4}{\alpha \beta} |f'|^2 + \frac{\alpha \beta}{16} |Au|^2; \\ & (Q, A\bar{\theta}) \leq \frac{2}{k} |Q|^2 + \frac{k}{8} |A\bar{\theta}|^2; \\ & (g_2(\bar{\theta}), A\bar{\theta}) \leq \frac{2}{k} |g_2(\bar{\theta})|^2 + \frac{k}{8} |A\bar{\theta}|^2 \end{aligned} \tag{37}$$

and consider the assumption (H_3) of $g_1(\cdot)$ combined with Sobolev-embed theorem

$$\begin{aligned} & \left| (g_1'(u) u', Au) \right| \\ & = \int_{\Omega} g_1'(u) u' Au \, dx \\ & \leq |C'| \int_{\Omega} (1 + |u|^\rho) u' Au \, dx \\ & \leq \frac{8C'^2}{\alpha \beta} |p|^2 + \frac{\alpha \beta}{16} |Au|^2 + \frac{4C'^2}{\alpha \beta} \int_{\Omega} |u|^{2\rho} (u')^2 \, dx \\ & \leq \frac{8C'^2}{\alpha \beta} |p|^2 + \frac{\alpha \beta}{16} |Au|^2 + \gamma \left(\frac{4C'^2}{\alpha \beta} \right)^2 \|u\|^2 + \frac{\gamma}{4} \|p\|^2 \\ & \leq \frac{8C'^2}{\alpha \beta} |p|^2 + \frac{\alpha \beta}{16} |Au|^2 + \gamma \left(\frac{4C'^2}{\alpha \beta} \right)^2 \|u\|^2 \\ & + \frac{\gamma}{2} \|v\|^2 + \frac{\alpha^2 \gamma}{2} \|u\|^2, \end{aligned} \tag{38}$$

and then we infer from (36) that

$$\begin{aligned} & \frac{1}{2} \frac{d}{dr} \left(\beta |Au|^2 + \|v\|^2 + \|\bar{\theta}\|^2 + 2(g_1(u), Au) - 2(f, Au) \right) \\ & + \frac{\gamma}{2} \|v\|^2 - \alpha \|v\|^2 + \frac{11\alpha \beta}{16} |Au|^2 + \frac{3k}{4} |A\bar{\theta}|^2 \\ & - \frac{4\alpha}{\beta} \|\bar{\theta}\|^2 + \alpha (g_1(u), Au) - \alpha (f, Au) \\ & \leq \frac{4}{\alpha \beta} |f'|^2 + \frac{2}{k} |Q|^2 + \frac{2}{k} |g_2(\bar{\theta})|^2 + \frac{4\alpha^3 + 4\alpha \gamma^2}{\beta} |v|^2 \\ & + \left[\frac{\alpha^2}{2} + \left(\frac{4C'^2}{\alpha \beta} \right)^2 \right] \gamma \|u\|^2 + \frac{8C'^2}{\alpha \beta} |p|^2. \end{aligned} \tag{39}$$

Let $0 < \alpha \leq \min\{3k\lambda\beta/(16 + 2\beta), 3\gamma/4\}$. By the Gronwall lemma we have from (39)

$$\begin{aligned} & \beta |Au|^2 + \|v\|^2 + \|\bar{\theta}\|^2 + 2(g_1(u), Au) - 2(f, Au) \\ & \leq e^{-\alpha r} \left(\beta |Au_0|^2 + \|v_0\|^2 + \|\bar{\theta}_0\|^2 \right) \\ & + 2(g_1(u_0), Au_0) - 2(f(t - \tau), Au_0) \\ & + \int_{t-\tau}^t e^{-\alpha(t-s)} \left\{ \frac{8}{\alpha \beta} |f'|^2 + \frac{4}{k} |Q|^2 + \frac{4\alpha_1^2}{k} |\bar{\theta}|^2 \right. \\ & \left. + \frac{8(\alpha^3 + \gamma \alpha^2)}{\beta} |v|^2 \right\} ds \\ & + \int_{t-\tau}^t e^{-\alpha(t-s)} \left\{ \left[\left(\frac{\alpha^2}{2} + \frac{4C'^2}{\alpha \beta} \right)^2 \right] \gamma \|u\|^2 + \frac{8C'^2}{\alpha \beta} |p|^2 \right\} ds. \end{aligned} \tag{40}$$

Considering that

$$2(g_1(u), Au) \geq -\frac{1}{4}|Au|^2 - 4 \int_{\Omega} |g_1(u)|^2 dx;$$

$$2(f, Au) \geq -\frac{1}{4}|Au|^2 - 4|f|^2,$$

$$\int_{\Omega} |g_1(u)|^2 dx \leq \int_{\Omega} (1 + |u|^{(\rho+1)})^2 dx \leq 2|\Omega|^2 + 2\|u\|^2, \tag{41}$$

by the assumption (H_2) of $g_1(\cdot)$, we have

$$\begin{aligned} &|Au|^2 + \|v\|^2 + \|\tilde{\theta}\|^2 \\ &\leq 2e^{-\alpha\tau} (\beta|Au_0|^2 + \|v_0\|^2 + \|\tilde{\theta}_0\|^2 \\ &\quad + 2(g_1(u_0), Au_0) - 2(f(t-\tau), Au_0)) \\ &+ 4 \int_{t-\tau}^t e^{-\alpha(t-s)} \left\{ \frac{4}{\alpha\beta}|f'|^2 + \frac{2}{k}|Q|^2 + \frac{2\alpha^2}{k}|\tilde{\theta}|^2 \right. \\ &\quad + \frac{4(\alpha^3 + \alpha\gamma^2)}{\beta} \left(2|p|^2 + \frac{2a^2}{\lambda}\|u\|^2 \right) \\ &\quad + \left[\left(\frac{\alpha^2}{2} + \frac{4C'^2}{\alpha\beta} \right)^2 \right] \gamma\|u\|^2 \\ &\quad \left. + \frac{8C'^2}{\alpha\beta}|p|^2 \right\} ds \\ &+ 16|\Omega|^2 + 16\|u\|^2 + 8|f|^2. \end{aligned} \tag{42}$$

Set

$$\begin{aligned} C_3 &= \max \left\{ \frac{8(\alpha^2 + \gamma^2)\alpha^3}{\beta\lambda} + \frac{\alpha^2\gamma}{2} + \left(\frac{4C'^2}{\alpha\beta} \right)^2 \gamma, \right. \\ &\quad \left. \frac{8\alpha^4 + 8\alpha^2\gamma^2 + 8C'^2}{\alpha\beta}, \frac{2a_1^2}{k} \right\}, \\ C_4 &= \max \left\{ \frac{4}{\alpha}, \frac{2}{k} \right\}, \\ C_5 &= 2\beta + \frac{4\alpha^2 + 2}{\lambda} + 4, \\ C_6 &= \max \left\{ 1 + \frac{2\alpha^2}{\lambda}, 2 \right\}. \end{aligned} \tag{43}$$

Since $\delta < \alpha$, we have from (32)

$$\begin{aligned} &C_3 \int_{t-\tau}^t e^{-\alpha(t-s)} \left\{ \|u(s)\|^2 + |p(s)|^2 + |\tilde{\theta}(s)|^2 \right\} \\ &\leq \frac{C_1C_2C_3}{\alpha\lambda} e^{-\delta\tau} (|Au_0|^2 + \|p_0\|^2 + \|\tilde{\theta}_0\|^2) \\ &\quad + \frac{2C_1C_2C_3}{\alpha} e^{-\delta\tau} \phi(u_0) \end{aligned}$$

$$\begin{aligned} &+ \frac{C_1C_3}{\alpha - \delta} \int_{-\infty}^t e^{-\delta(t-s)} \left(\frac{2}{\gamma}|f|^2 + \frac{2}{\lambda k}|Q|^2 \right) ds \\ &+ \frac{2C_1C_2\alpha M}{\alpha\delta}, \end{aligned} \tag{44}$$

and then we have from (42)

$$\begin{aligned} &|Au|^2 + \|p\|^2 + \|\tilde{\theta}\|^2 \\ &\leq e^{-\alpha\tau} \left(\left(2\beta + \frac{4\alpha^2 + 2}{\lambda} + 2 \right) C_6|Au_0|^2 \right. \\ &\quad \left. + 2\|p_0\|^2 + \|\tilde{\theta}_0\|^2 \right) \\ &+ 2C_6e^{-\alpha\tau} (|\Omega|^2 + |f(t-\tau)|^2) \\ &+ \frac{C_1C_2C_3C_6}{\alpha\lambda} e^{-\delta\tau} (|Au_0|^2 + \|p_0\|^2 + \|\tilde{\theta}_0\|^2) \\ &+ \frac{2C_1C_2C_3C_6}{\alpha} e^{-\delta\tau} \phi(u_0) \\ &+ \frac{C_1C_3C_6}{\alpha - \delta} \int_{-\infty}^t e^{-\delta(t-s)} \left(\frac{2}{\gamma}|f|^2 + \frac{2}{\lambda k}|Q|^2 \right) ds \\ &+ \frac{2MC_1C_3C_6}{\delta} + C_4C_6 \\ &\times \int_{-\infty}^t e^{-\alpha(t-s)} (|f|^2 + |Q|^2) ds + 16|\Omega|^2 \\ &+ 16\|u\|^2 + 8|f|^2 \\ &\leq \left(\frac{C_1C_2C_3C_6}{\alpha\lambda} e^{-\delta\tau} + C_5C_6e^{-\alpha\tau} \right) \\ &\times (|Au_0|^2 + \|p_0\|^2 + \|\tilde{\theta}_0\|^2) \\ &+ \frac{2C_1C_2C_3C_6}{\alpha} e^{-\delta\tau} \phi(u_0) \\ &+ 2C_6e^{-\alpha\tau} (|\Omega|^2 + |f(t-\tau)|^2) + \frac{C_1C_3C_6}{\alpha - \delta} \\ &\times \int_{-\infty}^t \left(\frac{2}{\gamma}|f|^2 + \frac{2}{\lambda k}|Q|^2 \right) ds + \frac{2MC_1C_3C_6}{\delta} + C_4C_6 \\ &\times \int_{-\infty}^t e^{-\alpha(t-s)} (|f|^2 + |Q|^2) ds + 16C_6|\Omega|^2 \\ &+ 16C_6\|u\|^2 + 8C_6|f|^2. \end{aligned} \tag{45}$$

Let $\tilde{D} \in D_{\delta, E_1}$ be given. For all $y(t-\tau) = y_0 \in D(t-\tau)$, $t \in R$ and $\tau \geq 0$, from the assumption (H_1) of $g_1(\cdot)$, we know that $\phi(u(t-\tau))$ is bounded and positive. So we easily obtain from (45)

$$\begin{aligned} &\|\Phi(t, t-\tau, y_0)\|_{E_1}^2 \\ &\leq \left(\frac{C_1C_2C_3C_6}{\alpha\lambda} e^{-\delta\tau} + C_5C_6e^{-\alpha\tau} \right) \end{aligned}$$

$$\begin{aligned}
 & \times \left(|Au_0|^2 + \|p_0\|^2 + \|\bar{\theta}_0\|^2 \right) + \frac{2C_1C_2C_3C_6}{\alpha} e^{-\delta\tau} \phi(u_0) \\
 & + 2C_6 e^{-\alpha\tau} \left(|\Omega|^2 + |f(t-\tau)|^2 \right) \\
 & + \frac{C_1C_3C_6}{\alpha-\delta} \int_{-\infty}^t \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds + \frac{2MC_1C_3C_6}{\delta} \\
 & + C_4C_6 \int_{-\infty}^t e^{-\alpha(t-s)} \left(|f|^2 + |Q|^2 \right) ds + 16C_6|\Omega|^2 \\
 & + 16C_6\|u\|^2 + 8C_6|f|^2
 \end{aligned} \tag{46}$$

for all $y_0 \in D(t-\tau)$, $t \in R$, and $\tau \geq 0$. Set

$$\begin{aligned}
 & \left(R_{\delta, E_1}(t) \right)^2 \\
 & = 2 \left\{ \frac{C_1C_3C_6}{\alpha-\delta} \int_{-\infty}^t e^{-\delta(t-s)} \left(\frac{2}{\gamma} |f|^2 + \frac{2}{\lambda k} |Q|^2 \right) ds \right. \\
 & \quad + \frac{2MC_1C_3C_6}{\delta} + C_4C_6 \int_{-\infty}^t e^{-\alpha(t-s)} \left(|f|^2 + |Q|^2 \right) ds \\
 & \quad \left. + 16C_6|\Omega|^2 + 16C_6 \left(R_{\delta, E_0}(t) \right)^2 + 8C_6|f|^2 \right\}.
 \end{aligned} \tag{47}$$

The family $\widehat{B}_{\delta, E_1}$ of closed balls in E_1

$$B_{\delta, E_1}(t) = \{y \in E_1, \|y\|_{E_1} \leq R_{\delta, E_1}(t)\} \tag{48}$$

is pullback D_{δ, E_1} -absorbing for the cocycle Φ in E_1 . \square

3. The Pullback D_{δ, E_1} -Attractor in E_1

In order to get the existence of the pullback D_{δ, E_1} -attractor, we first introduce the following Lemma.

Lemma 4. *Let H be an infinite dimensional Hilbert space and let the family $\{\omega_i\}_{i \in N}$ be an orthonormal basis of H . Suppose that $f(x, t), f'(x, t), Q(x, t) \in L^2_{loc}(R, H)$ and for any $t \in R$,*

$$\begin{aligned}
 & \int_{-\infty}^t e^{\sigma s} \left(|f(x, s)|^2_H + |f'(x, s)|^2_H + |Q(x, s)|^2_H \right) ds < \infty, \\
 & \text{for any } \sigma \geq 0.
 \end{aligned} \tag{49}$$

Then

$$\begin{aligned}
 & \lim_{n \rightarrow \infty} \int_{-\infty}^t e^{\sigma s} \left(|(I - P_n) f(x, s)|^2_H + |(I - P_n) f'(x, s)|^2_H \right. \\
 & \quad \left. + |(I - P_n) Q(x, s)|^2_H \right) ds = 0, \\
 & \quad \forall t \in R,
 \end{aligned} \tag{50}$$

where $P_n : H \rightarrow \text{span}\{\omega_1, \omega_2, \dots, \omega_n\}$ is the orthogonal projector.

Proof. Let $\eta_i(t) = (f(x, t), \omega_i)_H$, $\xi_i = (f'(x, t), \omega_i)_H$, and $\zeta_i(t) = (Q(x, t), \omega_i)$, so

$$\begin{aligned}
 f(x, t) &= \sum_{i=1}^{\infty} \eta_i(t) \omega_i, & f'(x, t) &= \sum_{i=1}^{\infty} \xi_i(t) \omega_i, \\
 Q(x, t) &= \sum_{i=1}^{\infty} \zeta_i(t) \omega_i.
 \end{aligned} \tag{51}$$

For any $t \in R$ and any $\varepsilon > 0$,

$$\begin{aligned}
 & \int_{-\infty}^t e^{\sigma s} \left(|f(x, s)|^2_H + |f'(x, s)|^2_H + |Q(x, s)|^2_H \right) ds \\
 & = \sum_{i=1}^{\infty} \int_{-\infty}^t e^{\sigma s} \left(|\eta_i(s)|^2 + |\xi_i(s)|^2 + |\zeta_i(s)|^2 \right) ds < \infty
 \end{aligned} \tag{52}$$

we can choose N_1, N_2, N_3 large enough so that

$$\begin{aligned}
 & \sum_{i=N_1}^{\infty} \int_{-\infty}^t e^{\sigma s} |\eta_i(s)|^2 ds \leq \frac{\varepsilon}{3}, \\
 & \sum_{i=N_2}^{\infty} \int_{-\infty}^t e^{\sigma s} |\xi_i(s)|^2 ds \leq \frac{\varepsilon}{3}, \\
 & \sum_{i=N_3}^{\infty} \int_{-\infty}^t e^{\sigma s} |\zeta_i(s)|^2 ds \leq \frac{\varepsilon}{3}.
 \end{aligned} \tag{53}$$

Then for any $t \in R$ and any $\varepsilon > 0$, we put $N_0 = \max\{N_1, N_2, N_3\}$ to get

$$\sum_{i=N_0}^{\infty} \int_{-\infty}^t e^{\sigma s} \left(|\eta_i(s)|^2 + |\xi_i(s)|^2 + |\zeta_i(s)|^2 \right) ds \leq \varepsilon. \tag{54}$$

That is, for any $t \in R$, any $\varepsilon > 0$, and $n \geq N_0$,

$$\begin{aligned}
 & \int_{-\infty}^t e^{\sigma s} \left(|(I - P_n) f(x, s)|^2_H + |(I - P_n) f'(x, s)|^2_H \right. \\
 & \quad \left. + |(I - P_n) Q(x, s)|^2_H \right) ds \leq \varepsilon.
 \end{aligned} \tag{55}$$

So

$$\begin{aligned}
 & \lim_{n \rightarrow \infty} \int_{-\infty}^t e^{\sigma s} \left(|(I - P_n) f(x, s)|^2_H + |(I - P_n) f'(x, s)|^2_H \right. \\
 & \quad \left. + |(I - P_n) Q(x, s)|^2_H \right) ds = 0.
 \end{aligned} \tag{56}$$

In order to obtain the pullback D_{δ, E_1} -attractor in E_1 , we also need the following Lemmas of the properties of compactness about the nonlinear operator $g_1(\cdot), g_2(\cdot)$.

Lemma 5. *Let $g_1(\cdot)$ be a $C^2(R, R)$ function from R into R satisfying (H_2) ; then $g_1 : D(A) \rightarrow H^1_0(\Omega)$ is continuously compact; that is, $g_1(\cdot)$ is continuous and maps a bounded subset of $D(A)$ into a precompact subset of $H^1_0(\Omega)$.*

Proof. Let $B = B_{D(A)}$ be a bounded set in $D(A)$. Assume that $\{u_n\}$ is a bounded sequence in B . From Sobolev embedding Theorem, the embeddings $D(A) \mapsto L^p, \forall p \geq 1$ and $D(A) \mapsto w^{1,p}(\forall p \geq 1)$ are compact. We assume that $\{u_n\}$ is bounded and converges to u_0 in L^p and $W^{1,p}$, respectively. By Minkowski inequality, we see that

$$\begin{aligned} & \left(\int_{\Omega} |\nabla (g_1(u_n) - g_1(u_0))|^2 dx \right)^{1/2} \\ & \leq \left\{ \int_{\Omega} [g'_1(u_n) - g'_1(u_0) \nabla u_n]^2 dx \right\}^{1/2} \\ & \quad + \left\{ \int_{\Omega} [g'_1(u_0) \nabla (u_n - u_0)]^2 dx \right\}^{1/2}. \end{aligned} \quad (57)$$

By Holder inequality, we have

$$\begin{aligned} & \left\{ \int_{\Omega} [g'_1(u_n) - g'_1(u_0)]^2 dx \right\}^{1/2} \\ & \leq \left(\int_{\Omega} |g'_1(u_n) - g'_1(u_0)|^{2p} dx \right)^{1/2p} \left(\int_{\Omega} |\nabla u_n|^{2q} dx \right)^{1/2q} \\ & \leq C(R_{\delta, E_1}(t))^2 |g'_1(u_n) - g'_1(u_0)|_{L^{2p}}, \end{aligned} \quad (58)$$

where $1/p' + 1/q' + 1/2 = 1$ and $C(R_{\delta, E_1}^2(t))$ is a constant depending on $R_{\delta, E_1}^2(t)$ and the embedding constant. Due to the assumption (H_3) of $g_1(\cdot)$ and a classical continuity result, it follows that

$$|g'_1(u_n) - g'_1(u_0)|_{L^{2p}} \rightarrow 0. \quad (59)$$

Also by the Holder inequality

$$\left\{ \int_{\Omega} [g'_1(u_0) \nabla (u_n - u_0)]^2 dx \right\}^{1/2} \rightarrow 0. \quad (60)$$

The proof is completed. \square

Lemma 6. Let $g_2(\cdot)$ be a $C^1(R, R)$ function from R into R satisfying (11); then $g_2 : H_0^1(\Omega) \rightarrow L^2(\Omega)$ is continuously compact.

Proof. Let $B = B_{H_0^1(\Omega)}$ be a bounded set in $H_0^1(\Omega)$ and assume $\{\tilde{\theta}\}$ to be a bounded sequence in B . From Sobolev embedding theorem, the embedding $H_0^1(\Omega) \mapsto L^p, \forall p \geq 1$ is compact, so we assume that $\tilde{\theta}_n$ is bounded and converges to $\tilde{\theta}_0$ in L^p . Let $\tilde{\theta}_n - \tilde{\theta}_0 = \omega_n$; then there exists $\theta = \theta(x) \in [0, 1]$ such that

$$\begin{aligned} & \left(\int_{\Omega} |(g_2(\tilde{\theta}_n) - g_2(\tilde{\theta}_0))|^2 dx \right)^{1/2} \\ & = \left\{ \int_{\Omega} [g'_2(\tilde{\theta}_0 + \theta \omega_n) \omega_n]^2 dx \right\}^{1/2}. \end{aligned} \quad (61)$$

By Holder inequality, we have

$$\begin{aligned} & \left(\int_{\Omega} |(g_2(\tilde{\theta}_n) - g_2(\tilde{\theta}_0))|^2 dx \right)^{1/2} \\ & \leq |g'_2(\tilde{\theta}_0 + \theta \omega_n)|_{L^{2p'}} |\omega_n|_{L^{2q'}}, \end{aligned} \quad (62)$$

where q' is the conjugate of p' (i.e., $1/p' + 1/q' = 1$). Combined with the assumption (11), the proof is completed. \square

Lemma 7. Let $g_1(\cdot)$ be a $C^2(R, R)$ function from R into R satisfying (H_2) ; moreover, $g_1(0) = 0$. Let B be a bounded subset of $D(A)$. Then for any $\varepsilon > 0$, there exists some n_0 such that when $n \geq n_0$

$$\|(I - P_n) g_1(u)\| \leq \varepsilon, \quad \forall u \in B, \quad (63)$$

where $P_n : V \rightarrow \text{span}\{\omega_1, \omega_2, \dots, \omega_n\}$ is the orthogonal projection.

Proof. Note that $g_1(u) \in L^2(\Omega)$ for $u \in D(A)$. By Lemma 5, we see that $g_1(\cdot)$ maps bounded subsets of $D(A)$ into precompact subsets of $H_0^1(\Omega)$. Let B be a bounded subset of $D(A)$ and let $\varepsilon > 0$ be given arbitrarily. Since $g_1(B)$ is precompact in $H_0^1(\Omega)$, there is a finite number of elements $v_1, v_2, \dots, v_k \in g_1(B)$ such that

$$g_1(B) \subset \bigcup_{1 \leq i \leq k} B\left(v_i, \frac{\varepsilon}{2}\right). \quad (64)$$

We take $n_0 > 0$ sufficiently large so that

$$\|(I - P_n) g_1(u)\| \leq \varepsilon, \quad \forall u \in B \quad (65)$$

for all $1 \leq i \leq k$, when $n \geq n_0$. Then by $g_1(B) \subset \bigcup_{1 \leq i \leq k} B(v_i, \varepsilon/2)$, we have

$$\|(I - P_n) g_1(u)\| \leq \varepsilon, \quad \forall u \in V, \quad (66)$$

where $P_n : D(A) \rightarrow \text{span}\{\omega_1, \dots, \omega_n\}$ is the orthogonal projection. \square

Lemma 8. Let $g_2(\cdot)$ be a $C^2(R, R)$ function from R into R satisfying (11). Let B be a bounded subset of $H_0^1(\Omega)$. Then for any $\varepsilon > 0$, there exists some n_0 such that when $n \geq n_0$

$$\|(I - P_n) g_2(\tilde{\theta})\| \leq \varepsilon, \quad \forall \tilde{\theta} \in B, \quad (67)$$

where $P_n : H_0^1(\Omega) \rightarrow \text{span}\{\omega_1, \omega_2, \dots, \omega_n\}$ is the orthogonal projection.

Theorem 9. Assume that $\beta, \gamma, k > 0$ and the assumptions of $g_1(\cdot), g_2(\cdot), h(\cdot)$ hold. $f(x, t) \in L_{loc}^2(R, L^2(\Omega)), f'(x, t) \in L_{loc}^2(R, L^2(\Omega))$, and $Q(x, t) \in L_{loc}^2(R, L^2(\Omega))$ satisfy (7); then there exists a pullback D_{δ, E_1} -attractor in E_1 for the nonautonomous dynamical system (θ, Φ) defined by (15).

Proof. In order to prove the result of the theorem, we only need to check the pullback D_{δ, E_1} -condition (C).

Let $\{\omega_k\}_{k=1}^{\infty}$ be an orthonormal basis of H which consists of eigenvectors of A . The corresponding eigenvalues are denoted by $\lambda_k, k = 1, 2, \dots$ and $0 < \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \dots, \lambda_j \rightarrow \infty$, as $j \rightarrow \infty$. Then $\{\omega_k\}_{k=1}^{\infty}$ is also an orthonormal basis of V and $D(A)$. We write $V_n = \{\omega_1, \omega_2, \dots, \omega_n\}$ and $P_n : V \rightarrow V_n$ is an orthogonal projector. For any $u \in V$, we write

$$u = P_n u + (I - P_n) u \triangleq u_1 + u_2. \quad (68)$$

Take the scalar product in H of (1) with $Av_2 = Au_2' + \alpha Au_2$, and take the scalar product in H of (2) with $A\tilde{\theta}_2$; then make summation to get

$$\begin{aligned} & \frac{1}{2} \frac{d}{dr} \left(\beta |Au_2|^2 + \|v_2\|^2 + \|\tilde{\theta}_2\|^2 \right) + \gamma \|v_2\|^2 - \alpha \|v_2\|^2 \\ & + \alpha \beta |Au_2|^2 + k |A\tilde{\theta}_2|^2 + \alpha^2 ((u_2, v_2)) \\ & - \gamma \alpha (Au_2, v_2) + \alpha (A^{1/2} \tilde{\theta}_2, Au_2) \\ & + (((I - P_n) g_1(u), v_2)) \\ & = ((I - P_n) g_2(\tilde{\theta}), A\tilde{\theta}_2) + ((I - P_n) f, Av_2) \\ & + ((I - P_n) Q, A\tilde{\theta}_2). \end{aligned} \tag{69}$$

Since

$$\begin{aligned} \alpha^2 ((u_2, v_2)) & \geq -\frac{\alpha^2}{2} \|u_2\|^2 - \frac{\alpha^2}{2} \|v_2\|^2; \\ -\gamma \alpha (Au_2, v_2) & \geq -\frac{\alpha \gamma^2}{\beta} |v_2|^2 - \frac{\alpha \beta}{4} |Au_2|^2; \\ \alpha (A^{1/2} \tilde{\theta}_2, Au_2) & \geq -\frac{\alpha}{\beta} \|\tilde{\theta}_2\|^2 - \frac{\alpha \beta}{4} |Au_2|^2, \\ |((I - P_n) g_1(u), v_2)| & \leq \frac{1}{\gamma} \|(I - P_n) g_1(u)\|^2 + \frac{\gamma}{4} \|v_2\|^2; \\ |((I - P_n) g_2(\tilde{\theta}), A\tilde{\theta}_2)| & \leq \frac{1}{k} \|(I - P_n) g_2(\tilde{\theta})\|^2 + \frac{k}{4} \|A\tilde{\theta}_2\|^2; \\ |((I - P_n) f, Av_2)| \\ & = \frac{d}{dt} (f_2, Au_2) + \alpha (f_2, Au_2) - (f', Au_2) \\ & \leq \frac{d}{dt} (f_2, Au_2) + \frac{\alpha \beta}{4} |Au_2|^2 + \frac{2\alpha}{\beta} |f_2|^2 + \frac{2}{\alpha \beta} |f_2'|^2 \end{aligned} \tag{70}$$

here we set $f_2 = (I - P_n)f$, and

$$|((I - P_n) Q, A\tilde{\theta}_2)| \leq \frac{1}{k} |(I - P_n) Q|^2 + \frac{k}{4} |A\tilde{\theta}_2|^2, \tag{71}$$

and letting $0 \leq \alpha \leq \min\{\beta\lambda/4, ((-\lambda + \gamma^2/\beta) + \sqrt{(\lambda + \gamma^2/\beta)^2 + \gamma\lambda^2/2})/\lambda, k\lambda\beta/2\}$, setting $\alpha_1 = \min\{\alpha/8, \gamma\lambda/2, k\lambda/4\}$, we have, from (69),

$$\begin{aligned} & \frac{d}{dr} \left(\beta \left| Au_2 - \frac{1}{\beta} f_2 \right|^2 + \|v_2\|^2 + \|\tilde{\theta}_2\|^2 \right) \\ & + 2\alpha_1 \left(\beta \left| Au_2 - \frac{1}{\beta} f_2 \right|^2 + \|v_2\|^2 + \|\tilde{\theta}_2\|^2 \right) \end{aligned}$$

$$\begin{aligned} & \leq \frac{2}{\gamma} \|(I - P_n) g_1(u)\|^2 + \frac{2}{k} |(I - P_n) g_1(\tilde{\theta})|^2 \\ & + \frac{2}{k} |(I - P_n) Q|^2 + \frac{2\alpha}{\beta} |(I - P_n) f_2|^2 \\ & + \frac{2}{\alpha \beta} |(I - P_n) f_2'|^2 + \frac{2}{\beta} (f_2, f_2') + \frac{2\alpha_1}{\beta} |f_2|^2. \end{aligned} \tag{72}$$

By the Gronwall lemma, we obtain

$$\begin{aligned} & \beta \left| Au_2 - \frac{1}{\beta} f_2 \right|^2 + \|v_2\|^2 + \|\tilde{\theta}_2\|^2 \\ & \leq e^{-2\alpha_1 \tau} \left[\beta \left| Au_2(t - \tau) - \frac{1}{\beta} f_2(t - \tau) \right|^2 \right. \\ & \quad \left. + \|v_2(t - \tau)\|^2 + \|\tilde{\theta}_2(t - \tau)\|^2 \right] \\ & + \int_{t-\tau}^t e^{-2\alpha_1(t-s)} \left(\frac{2}{\gamma} \|(I - P_n) g_1(u)\|^2 \right. \\ & \quad + \frac{2}{k} |(I - P_n) g_1(\tilde{\theta})|^2 + \frac{2}{k} |(I - P_n) Q|^2 \\ & \quad + \frac{2\alpha}{\beta} |(I - P_n) f_2|^2 + \frac{2}{\alpha \beta} |(I - P_n) f_2'|^2 \\ & \quad \left. + \frac{2}{\beta} (f_2, f_2') + \frac{2\alpha_1}{\beta} |f_2|^2 \right) ds. \end{aligned} \tag{73}$$

So

$$\begin{aligned} & |Au_2|^2 + \|p_2\|^2 + \|\tilde{\theta}_2\|^2 \\ & \leq 2e^{-2\alpha_1 \tau} \left[2 \left(\beta^2 + \frac{2\alpha^2}{\lambda} \right) |Au_2(t - \tau)|^2 + 2\|p_2(t - \tau)\|^2 \right. \\ & \quad \left. + \|\tilde{\theta}_2(t - \tau)\|^2 + \frac{2}{\beta} |f_2(t - \tau)|^2 \right] \\ & + 2 \int_{t-\tau}^t e^{-2\alpha_1(t-s)} \left(\frac{2}{\gamma} \|(I - P_n) g_1(u)\|^2 \right. \\ & \quad + \frac{2}{k} |(I - P_n) g_1(\tilde{\theta})|^2 \\ & \quad + \frac{2}{k} |(I - P_n) Q|^2 \\ & \quad + \frac{2\alpha}{\beta} |(I - P_n) f_2|^2 \\ & \quad \left. + \frac{2}{\alpha \beta} |(I - P_n) f_2'|^2 \right) ds \end{aligned}$$

$$\begin{aligned}
 & + \frac{2}{\beta} (f_2, f_2') + \frac{2\alpha_1}{\beta} |f_2|^2) ds \\
 & + 2\alpha^2 \|u_2\|^2 + \frac{2}{\beta} |f_2|^2.
 \end{aligned} \tag{74}$$

Then given any $\widehat{D} \in D_{\delta, E_1}$, we have

$$\begin{aligned}
 & \|\Phi_2(\tau, t - \tau, y_0)\|_{E_1}^2 \\
 & \leq 2e^{-2\alpha_1\tau} \left[2 \left(\beta^2 + \frac{2\alpha^2}{\lambda} \right) |Au_2(t - \tau)|^2 + 2\|p_2(t - \tau)\|^2 \right. \\
 & \quad \left. + \|\bar{\theta}_2(t - \tau)\|^2 + \frac{2}{\beta} |f_2(t - \tau)|^2 \right] \\
 & + 2 \int_{t-\tau}^t e^{-2\alpha_1(t-s)} \left(\frac{2}{\gamma} \|(I - P_n)g_1(u)\|^2 \right. \\
 & \quad \left. + \frac{2}{k} |(I - P_n)g_1(\bar{\theta})|^2 \right) ds \\
 & + 2 \int_{-\infty}^t \left(\frac{2}{k} |(I - P_n)Q|^2 + \frac{2\alpha + 4 + 2\alpha_1}{\beta} |(I - P_n)f_2|^2 \right. \\
 & \quad \left. + \left(\frac{2}{\alpha\beta} + \frac{4}{\beta} \right) |(I - P_n)f_2'|^2 \right) ds \\
 & + 2\alpha^2 \|u_2\|^2 + \frac{2}{\beta} |f_2|^2 \\
 & := I_1 + I_2 + I_3 + I_4
 \end{aligned} \tag{75}$$

for any $y(t - \tau) = y_0 \in D(t - \tau)$ and $t \in R, \tau \geq 0$. Now we estimate I_1, I_2, I_3, I_4 one by one. Given any $\varepsilon > 0$ and any $t \in R$, it is easy to see that

$$\frac{2}{\beta} |f_2|^2 \rightarrow 0, \tag{76}$$

so there exists $\tau_1 \geq 0$ such that

$$I_1 \leq \frac{\varepsilon}{4} \tag{77}$$

for all $\tau \geq \tau_1, y_0 \in D(t - \tau)$.

By Lemmas 7–8, we can choose $n_1 \in N$ such that

$$I_2 \leq \frac{\varepsilon}{4} \tag{78}$$

for any $n \geq n_1, \tau \geq \tau_2$.

By Lemma 4, we can choose n_2 large enough such that

$$I_3 \leq \frac{\varepsilon}{4} \tag{79}$$

for $n \geq n_2$.

By (32), there exists $\tau_3 > 0$ such that, for $\tau > \tau_3, \|u(t)\|^2 < \infty$ and the embedding from $D(A)$ into V is

compact combined with $(2/\beta)|f_2|^2 \rightarrow 0$, so we can choose n_3 large enough such that

$$I_4 \leq \frac{\varepsilon}{4} \tag{80}$$

for $n \geq n_3, \tau > \tau_3$.

By above analysis, if we choose $\tau_0 = \max\{\tau_1, \tau_2, \tau_3\}, n_0 = \max\{n_1, n_2, n_3\}$, then

$$\|\Phi_2(\tau, t - \tau, y_0)\|_{E_1}^2 \leq \varepsilon \tag{81}$$

for any $\tau \geq \tau_0, n \geq n_0, y_0 \in D(t - \tau)$.

This implies pullback D_{δ, E_1} -condition (C). \square

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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