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Ground State and Lowest Eigenvalue of the Laplacian for Non-Compact Hyperbolic Surfaces

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Abstract. Let M be a complete Riemannian surface with constant curvature -1, infinite volume, and a finitely generated fundamental group. Denote by $\lambda(M)$ the lowest eigenvalue of the Laplacian on M, and let ψ_M be the associated eigenfunction. We estimate the size of $\lambda(M)$ and the shape of ψ_M by a finite procedure which has an electrical circuit analogue. Using the Margulis lemma, we decompose M into its thick and thin parts. On the compact thick components, we show that ψ_M varies from a constant value by no more than $O(\sqrt[]{\lambda(M)})$. The estimate for $\lambda(M)$ is calculable in terms of the topology of M and the lengths of short geodesics of M. An analogous theorem of the compact case was treated in [SWY].

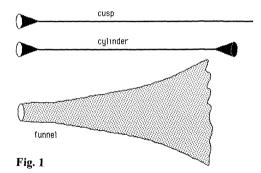
Let M be a complete Riemannian surface with constant curvature -1, infinite volume, and a finitely generated fundamental group. The lowest eigenvalue of the Laplacian, $\lambda(M)$, belongs to (0, 1/4] and if $\lambda(M)$ belongs to (0, 1/4), there is a unique positive eigenfunction ψ_M for $\lambda(M)$ of L^2 norm one (see [P1, S, S2]). If one writes $\lambda(M) = D(1-D)$ with D > 1/2 then D is the Hausdorff dimension of the limit set of the Fuchsian group representing M. Also the value of ψ_M lifted to the unit disk at a point p is just the (packing) Hausdorff D-measure of the limit set in the metric on rays from p (see [S, S2]).

In this paper we will describe a finite procedure for determining the size of $\lambda(M)$ and the shape of ψ_M . The procedure has an electrical circuit analogue which could, in principle, be used to compute this size and shape.

As a corollary let Γ_{ε} be the Fuchsian group generated by $z \to -1/z$ and the translation by $2 + \varepsilon$. Our Theorem 1 implies the Hausdorff dimension of the limit set of Γ_{ε} differs from one by the quantity $\sqrt{\varepsilon}$. This estimation implies the derivative of the dimension at the critical value $\varepsilon = 0$ is $+\infty$ (see [P2]).

Furthermore, the estimate has the simple interpretation often observed in dynamically defined Cantor sets on the line, namely that when the dimension is

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near one, the discrepancy from one is on the order of the size of the largest gap in the Cantor set.

To describe this procedure we divide M into the thick part M_T (in which each point is the center of an embedded disk of a definite convenient radius) and the complementary thin part M_t (which is proven to consist of *cusps*, or pseudospheres, and *cylinders*, which are approximately doubled truncated cusps) see [T].

The thick part M_T has finitely many components: some compact of bounded geometry, called *nodes* here; and others non-compact which, up to bounded pieces, are made of canonical pieces called *funnels* (see Fig. 2).

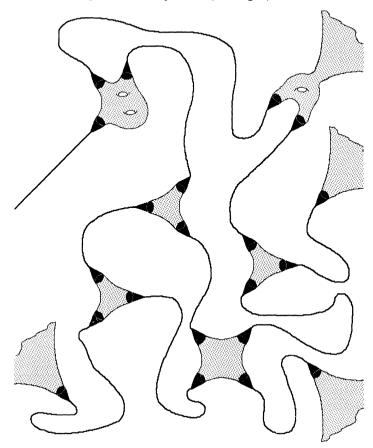


Fig. 2



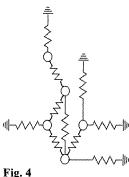


Fig. 3 Fig.

We associate a finite graph and a circuit diagram to this decomposition as follows. There is one vertex for each compact component of M_T , and one vertex called ground which is associated to all the non-compact components. There is an edge between two vertices for each cylinder. For reasons which will become clear below, one may forget the cusps in the formation of this graph.

From this graph one forms a circuit diagram where each nodal vertex has a variable voltage with respect to the ground vertex (at zero potential), and each edge becomes a resistor with resistance the reciprocal of the length of the short geodesic of that cylinder.

The finite procedure is to form the quantity

$$m_a = \inf_f \sum_{\text{edges}} (\delta f)^2 \ell$$

where f is a vertex function of square norm one $\left(\sum_{\text{vertices}} f(V)^2 = 1\right)$, f(ground) = 0, $\delta f(\text{edge}) = \text{difference}$ of values of f at either end, and ℓ is the length of the edge.

The size of the number m_a can be calculated physically as follows: create a voltage of one at a node and using an ammeter record the maximum of $(\text{current})^2 \cdot (\text{resistance})$ across each resistor. The minimum m_c over the nodes of these maxima has the same size as m_a . Denote by m the size of either of these quantities.

Theorem 1. $\lambda(M)$ and m have the same size, i.e. their ratio is bounded above and below by constants depending only on the topology of M.

Proof. To see that m is an upper bound we construct a test function. To see that m is a lower bound we use conformal invariance of the energy in dimension two to show that the basic eigenfunction for $\lambda(M)$ resembles this test function.

I. The Upper Bound

By definition, $\lambda(M) = \inf_{\psi} \int |\operatorname{grad} \psi|^2$, where ψ ranges over smooth functions with compact support and square integral one. Thus upper bounds for $\lambda(M)$ can be found by considering test functions. For example, choose constant functions V_1, V_2, \ldots for each compact component of M_T (the nodes) and choose zero on each non-compact component of M_T (the ground). In the unit tubular neighborhood of

the short geodesic of each cylinder interpolate a linear function between these constants. If ℓ is the length of the short geodesic and V_1 , V_2 are the constants, the energy $\int |\operatorname{grad}\psi|^2$ on this part is about $(V_1-V_2)^2\ell$. In each cusp we can interpolate the constant to zero so far out in the cusp that the energy is negligible (by the above). If the maximum constant is one, the L^2 norm of our test function is comparable to one, and the energy is comparable to the maximum of $(V_1-V_2)^2\ell$ over the cylinders.

If the one occurs at a certain node, the circuit analogue chooses the other voltages V_{∞} between zero and one to minimize the sum of the energy terms $(\text{current})^2 \cdot \text{resistance}$ which are just the terms $(V_1 - V_2)^2 \ell$.

This completes our discussion of the upper bound.

II. The Lower Bound

Now the fun begins. We will show that the actual basic eigenfunction ψ_M resembles one of the test functions above, thus proving that m gives a lower bound for $\lambda(M)$.

We suppose $\lambda(M)$ is much less than m, for otherwise we would be done.

- 1) Since $\int (\operatorname{grad} \psi_M)^2 = \lambda(M) \ll m$, the L^2 norm of $(\operatorname{grad} \psi_M) \ll \sqrt{m}$. Thus the derivative of $\operatorname{grad} \psi_M \ll \sqrt{m}$ at any point of M_T by Harnack. Thus if $\operatorname{grad} \psi_M$ is not much smaller than \sqrt{m} at a point of M_T then $\operatorname{grad} \psi_M$ would have the size \sqrt{m} on a ball of definite radius. (See Harnack principle in Appendix.) So the $\int (\operatorname{grad} \psi_M)^2$ would have at least the size m, contradicting our assumption $\lambda(M) \ll m$. Thus we deduce, using the uniform bounds on diameters of compact components of M_T ,
 - 2) the variation of ψ_M on each compact component of M_T is $\ll \sqrt{m}$.
- 3) Define a test function f, as above, where V_i is the average of ψ_M on the corresponding component of M_T . We claim a) the L^2 norm of f is not much smaller than the L^2 norm of ψ_M which is one, b) the energy of f is not much bigger than the energy of ψ_M which is $\lambda(M)$. From the claim we deduce the lower bound.
- 4) Proof of b). Consider any cylinder. Let ℓ be its waist size and suppose f is V_1 at one end and V_2 at the other. Recall the energy of f in the cylinder is $(V_1 V_2)^2 \ell$. Let C be the cylinder where this energy contribution to f is a maximum. Then of course, the total energy of f is comparable to $(V_1 V_2)^2 \ell$, since there is a fixed number of cylinders.

Now ψ_M must also vary across the cylinder by 2). Namely if $V_1 < V_2$, $\psi_M \le C_1 = V_1 + (\text{small fraction of } \sqrt{m})$ at the V_1 end and $\psi_M \ge C_2 = V_2 - (\text{small fraction of } \sqrt{m})$ at the V_2 end, using 2). By Lemma 2, the energy of ψ_M in the cylinder is at least $(C_1 - C_2)^2 \ell$. (An easy calculation shows the modulus of a cylinder of waist ℓ is $1/\ell$.) Since $(V_1 - V_2)^2 \ell$ is comparable to m, so is $(C_1 - C_2)^2 \ell$. This proves b).

The proof of a) takes several steps. We continue to pretend that $\lambda(M) \ll m$. This assumption now entails that each V_i is much less than one, for otherwise f determines a normalized test function showing $\lambda(M)$ and m are comparable.

We will use this information to show each contribution to the L^2 norm of ψ_M is small, contradicting the fact that the L^2 norm of ψ_M is one.

5) (the structure of ψ_M in a cusp) If $\psi_M(x)$ is c for x in the boundary of a cusp, then ψ_M has the size of c on the entire boundary (Harnack). By [P1] and [S] there is an upper bound $\psi_M(y) \le c \exp(1-D)R$, where R = distance(x, y) and $\lambda(M)$ is

D(1-D), D>1/2. The width of the cusp at distance R is e^{-R} , thus the square integral of ψ_M in the cusp has the size c^2 . If the cusp touches a compact component of M_T , then c is comparable to one of the V_i 's and thus the L^2 norm of ψ_M in the cusp is small. If the cusp touches a non-compact component we deduce this contribution to the L^2 norm of ψ_M is small using 6) below.

We note that the estimate is easy to derive using the fact that ψ_M belongs to L^2 , and an argument like 7) below. However, this estimate is proved independently of this fact in [P1] or [S] to show ψ_M belongs to L^2 .

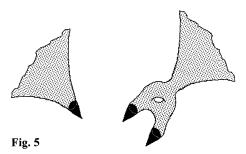
6) (structure of ψ_M in a non-compact component of M_T) We study ψ_M on the non-compact part of M_T by isolating each end by closed geodesics. There are two cases: i) the component of M_T containing that end is itself an annulus entirely contained in a larger annulus between a (short) closed geodesic and infinity, ii) the end of M_T may be isolated by a geodesic in that component of M_T (see Fig. 5).

In either case if k is the value of ψ_M at a point x of that geodesic, then for any y between the geodesic and infinity, $\psi_M(y)$ has the size $k(\exp - DR)$ where $R = \operatorname{distance}(x, y)$ and $D = 1/2 + \sqrt{[1/4 - \lambda(M)]}$ (see [S]). Thus in both cases i) and ii) we see that the contribution to the L^2 norm of ψ_M from a funnel is comparable to the size of ψ_M in the boundary of the funnel. (Recall that the boundary component has diameter of size one.) If c is this value, by Lemma 1 the energy of ψ_M in the funnel is at least size c^2 . Thus the size of c is smaller than $\sqrt{\lambda}$, which is smaller than one.

We note that this estimate follows easily from the geometric observation that as a point moves away from the closed geodesic its image in the universal cover is moving away from the convex hull of the limit set (where the boundary measure of ψ_M is concentrated) at the same rate, up to an additive constant.

7) (structure of ψ_M in a cylinder) Average ψ_M over the rotations of the cylinder to construct a new function ψ . By Harnack ψ has the same size as ψ_M . Also, ψ satisfies a second order differential equation with two independent solutions ψ_+ and ψ_- . When one symmetric half of the cylinder is close to a cusp these solutions are close to y^D and y^{1-D} (upper half plane model). If c < 1 is the value of ψ on the boundary and the L^2 norm of ψ is less than or equal to one, a calculation (see below) using $\psi = A_+\psi_+ + A_-\psi_- \sim A_+y^D + A_-y^{1-D}$ yields boundary values of ψ_M and the eigenvalue controls its L^2 norm on a cylinder.

Here is the calculation: If in the upper half plane model $f = A_+ y^D + A_- y^{1-D}$ on $0 \le x \le 1$, $1 \le y \le 1/\ell$ (recall this rectangle is approximately isometric to half of a



cylinder with short geodesic of length ℓ) then, letting $L=1/\ell$, the L^2 norm of f is

$$\int f^2 y^{-2} dx dy = \int_1^L (A_+^2 y^{2D-2} + 2A_+ A_- y^{-1} + A_-^2 y^{-2D}) dy,$$

or (*) $(\sim 1)A_+^2L^{2D-1} + 2A_-A_+ \log L + A_-^2(\sim 1)$. We now calculate the energy in the half cylinder. In the upper half plane model, $\operatorname{grad}(y^{\alpha}) = y \cdot (\alpha y^{\alpha-1}) = \alpha y^{\alpha}$. Thus

$$\begin{split} \text{energy} &= \int\limits_{1}^{L} \left[\text{grad} (A_{+} y^{D} + A_{-} y^{1-D}) \right]^{2} y^{-2} dy \\ &= \int\limits_{1}^{L} \left[D A_{+} y^{D} + (1-D) A_{-} y^{1-D} \right]^{2} y^{-2} dy \\ &= \int\limits_{1}^{L} \left[D^{2} A_{+}^{2} y^{2D-2} + D (1-D) A_{+} A_{-} y^{-1} + (1-D)^{2} A_{-}^{2} y^{-2D} \right] dy \\ &= (\sim 1) A_{+}^{2} L^{2D-1} + \lambda (M) A_{+} A_{-} \log L + (1-D)^{2} A_{-}^{2} (\sim 1) \,. \end{split}$$

Since ψ is positive and $A_+ + A_- = c$, there are three possibilities: 1) A_+ and the magnitude of A_- have the same size, 2) $A_+ \sim c$ and is much greater than the magnitude of A_- , or 3) the magnitude of A_+ is much smaller than that of A_- , which is approximately c. In cases 1) and 2) using the facts that $D > \frac{1}{2}$ and L is large, we see that the dominant term is $A_+^2 L^{2D-1}$ in both the energy and the L^2 norm expressions. Thus the L^2 norm and the energy in the half cylinder have the same size and this size is dominated by $\lambda(M)$ which is small. In case 3) using the above facts and assuming that $A_+A_-\log L$ dominates the L^2 norm expression leads to the contradiction that $A_- \gg c$. Thus either $\lambda(M)$ controls the L^2 norm, as in the previous cases; or, if A_+ is small enough, A_-^2 and hence c controls it. This completes the proof of Theorem 1.

Shape of the Basic Eigenfunction ψ_M . We summarize the information about ψ_M derived from the proof of Theorem 1.

- 1) On each compact component of M_T , ψ_M varies from a constant value by no more than $O(\sqrt{\lambda})$. A definite proportion of the L^2 norm of ψ_M lives on these compact components.
- 2) In the cusps, cylinders and funnels, the size of ψ_M is determined by the sizes on the boundary and the eigenvalue.
- 3) The test function produced from the constants on the compact components of the thick part by linear interpolation on the cylinders has the correct size energy and L^2 norm to compute the magnitude of $\lambda(M)$.
- 4) We have not shown that the energy of ψ_M is situated in the same place as the energy of the test function.

Appendix

Harnack Principle. 1) The value of a positive eigenfunction at a point controls its values on a unit neighborhood. 2) A bound on a disk neighborhood for any eigenfunction controls any finite number of derivatives on a centered disk of half the radius. 3) The L^2 norm of the gradient of an eigenfunction on a disk of definite

size controls a finite number of derivatives on an interior centered disk of half the radius.

The basis for these general facts can be found in references on elliptic equations.

Lemma 1. Let M be a Riemannian surface homeomorphic to $S^1x[0, \infty)$. Let ψ be a positive smooth function greater than or equal to a constant C on ∂M and such that $\psi \to 0$ as $x \to \infty$. Then energy $(\psi) \ge C^2/\text{modulus}(M)$.

Proof. We assume that modulus $(M) < \infty$ and note that the energy of a function is a conformal invariant of the metric. Let h be the harmonic function on M with the same boundary values as ψ and which vanishes at infinity. Recall that energy (h) \leq energy (ψ) .

By Sard's theorem, there exists C_0 arbitrarily close to C, $C_0 < C$, for which the level set $\xi = \{x \in M : h(x) = C_0\}$ is a compact one-manifold. If this one-manifold separates an interior piece of M, then h is identically constant. Thus ξ is a connected curve separating ∂M from infinity. Let M_0 be the subannulus between ξ and infinity. Note that modulus $(M_0) \le \text{modulus}(M)$ and h is constant on ∂M_0 .

We can map M_0 conformally to a right circular cylinder. On the cylinder, the function h becomes the linear function with energy C^2 (modulus of the cylinder)⁻¹.

By a similar type of reasoning, we obtain

Lemma 2. If M is a Riemannian surface homeomorphic to $S^1x[0,1]$ and ψ is a positive smooth function greater than or equal to a constant C_1 on one boundary component of M and less than or equal to another constant $C_2 < C_1$ on the other boundary component, then

energy
$$(\psi) \ge (C_1 - C_2)^2 / \text{modulus}(M)$$
.

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b) The paper [SWY] came to our attention at the end of the writing. They give bounds in a form equivalent to ours for the first 2g-3 eigenvalues of a compact surface of genus g and negative curvature.

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