# Mappings of finite distortion: Sharp Orlicz-conditions 

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#### Abstract

We establish continuity, openness and discreteness, and the condition $(N)$ for mappings of finite distortion under minimal integrability assumptions on the distortion.


## 1. Introduction

This paper is part of our program to establish the fundamentals of the theory of mappings of finite distortion [5], [1], [6], [9], [10] which form a natural generalization of the class of quasiregular mappings, also called mappings of bounded distortion. In the previous papers we considered mappings $f \in W^{1,1}\left(\Omega, \mathbb{R}^{n}\right)$ of exponentially integrable distortion. Here and throughout the paper, $\Omega \subset \mathbb{R}^{n}$ is an open, connected set. If $f \in W^{1,1}\left(\Omega, \mathbb{R}^{n}\right)$ satisfies

$$
|D f(x)|^{n} \leq K(x) J(x, f) \quad \text { a.e., }
$$

where $K(x)<\infty$ and if $J(\cdot, f) \in L_{\text {loc }}^{1}(\Omega)$, we say that $f$ is a mapping of finite distortion. We call $f$ a mapping of exponentially integrable distortion if furthermore $\exp (\lambda K) \in L_{\mathrm{loc}}^{1}(\Omega)$ for some $\lambda>0$. Mappings of exponentially integrable distortion in this sense were shown to have many of the nice properties of a mapping of bounded distortion. Regarding the necessity of the exponential integrability, an example from [9] shows that no topological properties like openness can be expected if we merely assume that $\exp \left(K / \log (e+K)^{2}\right)$ be integrable. In this paper we further examine the integrability assumptions on $K$. Let us replace the assumption $\exp (\lambda K) \in L_{\mathrm{loc}}^{1}(\Omega)$ with $\exp (\Psi(K)) \in L_{\mathrm{loc}}^{1}(\Omega)$. By the above, the critical
power-like behavior of $\Psi$ is linear. For the first theorem, we assume that $\Psi$ is a strictly increasing, differentiable function, and we make the following two assumptions, the second of which is entirely harmless (see Remark 2.2):
( $\Psi-1) \quad \int_{1}^{\infty} \frac{\Psi^{\prime}(t)}{t} d t=\infty$,
$(\Psi-2) \quad \lim _{t \rightarrow \infty} t \Psi^{\prime}(t)=\infty$.
Then we have the following regularity result.
Theorem 1.1. Suppose that $\Psi$ satisfies $(\Psi-1)$ and ( $\Psi-2$ ). Let $f$ be a mapping of finite distortion $K$ with $\exp (\Psi(K)) \in L_{\mathrm{loc}}^{1}(\Omega)$ and suppose that $\operatorname{det} D f=$ $J(\cdot, f) \in L_{\mathrm{loc}}^{1}(\Omega)$. Then $f$ is continuous and either constant or both open and discrete. Moreover, $f$ maps sets of Lebesgue measure zero to sets of measure zero.

The continuity here means the existence of a continuous representative. The claims of Theorem 1.1 were established in [6], [9] and [10] for $\Psi(t)=\lambda t, \lambda>0$. In the planar setting, Theorem 1.1 is partially covered by the results in [7].

As practical examples, Theorem 1.1 allows for

$$
\Psi(t)=t, \frac{t}{\log (e+t)}, \frac{t}{\log (1+t) \log \log \left(e^{e}+t\right)}, \ldots
$$

for any string of iterated logarithms. Regarding the sharpness, we will show, in particular, that

$$
\Psi(t)=\frac{t}{t^{\epsilon}}, \frac{t}{\log ^{1+\epsilon}(e+t)}, \frac{t}{\log (e+t) \log ^{1+\epsilon} \log \left(e^{e}+t\right)}, \ldots
$$

are not sufficient, for any $\epsilon>0$. This easily follows from our next result that is a substantial improvement on the construction that we gave in [9], also see [7] regarding the part (a).
Theorem 1.2. Suppose that $\Psi$ is a strictly increasing function and

$$
\begin{equation*}
\int_{1}^{\infty} \frac{\Psi^{\prime}(s)}{s} d s<\infty \tag{1.1}
\end{equation*}
$$

(a) There exists a mapping $f: \mathbb{B} \rightarrow \mathbb{R}^{n}$ of finite distortion $K(x)=\frac{|D f(x)|^{n}}{J(x, f)}$, with integrable Jacobian, with

$$
\int_{\mathbb{B}} \exp [\Psi(K(x))] d x<\infty
$$

and so that $f$ maps $\mathbb{B} \backslash\{0\}$ homeomorphically onto the annulus $\{x \in$ $\left.\mathbb{R}^{n}: 1<|x|<b\right\}$. In particular, $f$ has no continuous representative.
(b) There exists a continuous, non-constant mapping $f: Q_{0}=[0,1]^{n} \rightarrow \mathbb{R}^{n}$ of finite distortion $K(x)=\frac{|D f(x)|^{n}}{J(x, f)}$, with integrable Jacobian, with

$$
\int_{Q_{0}} \exp [\Psi(K(x))] d x<\infty
$$

and so that $f$ is neither open, nor discrete, and it maps a set of measure zero to a set of positive measure.

Theorem 1.1 is based on the arguments in [6], [9], [10] together with the following new observations. The integrability conditions on $K, \Psi$ guarantee that $\Phi(|D f|)$ is locally integrable in $\Omega$ for a strictly increasing function $\Phi$ that satisfies the conditions
$(\Phi-1) \int_{1}^{\infty} \frac{\Phi(t)}{t^{1+n}} d t=\infty$.
( $\Phi-2)$ There is $p \in(n-1, n)$ such that $t \mapsto t^{-p} \Phi(t)$ increases for large values of $t$.

Secondly, relying on recent results in [4], [11] and [3], we conclude that the point-wise Jacobian $J(x, f)$ then coincides with the so-called distributional Jacobian. This is the key fact in many of the estimates in [6], [9], [10] and we obtain the proposed topological and analytical results.

In the course of this argument we in fact establish the following result.
Theorem 1.3. Let $f \in W_{\text {loc }}^{1,1}\left(\Omega, \mathbb{R}^{n}\right)$ be a mapping of finite distortion $K$. Suppose that $\Phi(|D f|)+K^{q} \in L_{\mathrm{loc}}^{1}(\Omega)$, with $q>n-1$ and $\Phi$ satisfying $(\Phi-1)$ and ( $\Phi-2)$. Then $f$ is continuous and either constant or both open and discrete. Moreover, $f$ maps sets of Lebesgue measure zero to sets of measure zero.

Here, the assumption ( $\Phi-1$ ) is critical: the examples referred to in part (b) of Theorem 1.2 satisfy

$$
\Phi(|D f|)+\exp [\Psi(K(x))] \in L^{1}\left(Q_{0}\right) ;
$$

see formulas (3.10) and (3.13). The assumption ( $\Phi-2$ ) is also necessary. For (a), it is enough to consider $f(x)=x(1+|x|) /|x|$, then $\Phi(D f) \in L^{1}(\mathbb{B})$ for any $\Phi$ violating ( $\Phi-2$ ). Concerning the necessity for (b), see Remark 3.1. Thus Theorem 1.3 gives a sharp extension of the celebrated results by Reshetnyak (c.f. [13], [14], [15]) on mappings of bounded distortion. It still remains unknown if the $L^{n-1}$-integrability of $K$ is already sufficient under the given assumptions on $|D f|$; this is not known even when $|D f| \in L^{n}(\Omega)$. For this see [12], the monograph [8], and the references therein.

## 2. Proof of Theorem 1.1

We call a continuously differentiable and strictly increasing function $\Psi$ : $[0, \infty) \rightarrow[0, \infty)$ with $\Psi(0)=0$ and $\lim _{t \rightarrow \infty} \Psi(t)=\infty$ an Orlicz function.

In the course of this section, we associate with $\Psi$ two other Orlicz functions (see equation (2.2)):

$$
\begin{align*}
\psi(t) & =t \exp (\Psi(t)) \\
g(s) & =\frac{s}{\psi^{-1}(s)}-1, s>0, \text { and } g(0)=0 \tag{2.1}
\end{align*}
$$

We notice that $\psi$ is strictly increasing so that the inverse function $\psi^{-1}$ makes sense. We immediately have

$$
\begin{equation*}
g(\psi(t))=\exp (\Psi(t))-1 . \tag{2.2}
\end{equation*}
$$

In the first lemma we do not assume ( $\Psi-2$ ).
Lemma 2.1. Assume that $\Psi$ is an Orlicz function satisfying ( $\Psi-1$ ). Then
(a) $\int_{1}^{\infty} \frac{g(s)}{s^{2}} d s=\infty$ and
(b) given $a, b \geq 0$ we have

$$
g(a b) \leq a+\exp (\Psi(b))-1 .
$$

Proof. By the change of variables $s=\psi(t)$ and (2.2) we obtain

$$
\begin{aligned}
\int_{\psi(1)}^{\infty} \frac{g(s)+1}{s^{2}} d s & =\int_{1}^{\infty} \frac{(g(\psi(t))+1) \psi^{\prime}(t)}{\psi(t)^{2}} d s \\
& =\int_{1}^{\infty} \frac{\psi^{\prime}(t)}{t \psi(t)} d t \\
& =\int_{1}^{\infty} \frac{\left(1+t \Psi^{\prime}(t)\right) \exp (\Psi(t))}{t^{2} \exp (\Psi(t))} d t \\
& =\int_{1}^{\infty}\left(\frac{1}{t^{2}}+\frac{\Psi^{\prime}(t)}{t}\right) d t=\infty .
\end{aligned}
$$

This proves (a). Regarding (b), we distinguish two cases; naturally we may assume that $a \neq 0 \neq b$. If $a b \leq \psi(b)$, then by (2.2)

$$
g(a b) \leq g(\psi(b))=\exp (\Psi(b))-1
$$

If $a b \geq \psi(b)$, then

$$
g(a b)=\frac{a b}{\psi^{-1}(a b)}-1 \leq \frac{a b}{b}-1=a-1 .
$$

Remark 2.2. The condition ( $\Psi-1$ ) is crucial for our considerations and shown to be necessary by our counterexamples. However, this condition alone is too weak for our purposes. To demonstrate this, let us consider a sequence $\left\{a_{k}\right\}$ with $a_{k+1}>k a_{k}$ and function $\Psi$ which increases from $2 a_{k-1}$ to $a_{k}$ on $\left[a_{k}, 2 a_{k}\right]$ and from $a_{k}$ to $2 a_{k}$ on $\left[2 a_{k}, a_{k+1}\right]$. Then

$$
\int_{a_{k}}^{2 a_{k}} \frac{\Psi^{\prime}(t)}{t} d t \geq \frac{a_{k}-2 a_{k-1}}{2 a_{k}} \longrightarrow \frac{1}{2}
$$

and thus ( $\Psi-1$ ) is verified. On the other hand, if $e^{2 a_{k}}<a_{k+1}^{1 / k}$ then $\exp (\Psi(t))$ is not comparable with any $t^{q}, q>1$. This means also that integrability of $\exp (\Psi(K))$ would not imply integrability of $K^{q}$.

This consideration shows that something should be added to the condition ( $\Psi-1$ ). The condition ( $\Psi-1$ ) implies that $\limsup _{t \rightarrow \infty} t \Psi^{\prime}(t)=\infty$. It will not exclude important examples of Orlicz functions if we assume that this limsup turns to limit. Among power-like functions $\Psi(t)=t^{\alpha},(\Psi-1)$ corresponds to $\alpha<1$, while ( $\Psi-2$ ) is true for all $\alpha>0$. This explains in what sense we regard ( $\Psi-2$ ) to be "harmless".

Lemma 2.3. Assume that $\Psi$ is an Orlicz function satisfying ( $\Psi-2$ ) and $\varepsilon \in$ $(0,1)$. Then there exists $s_{0} \in(0, \infty)$ such that the functions $h: s \mapsto s^{\varepsilon-1} g(s)$ is increasing on $\left(s_{0}, \infty\right)$.

Proof. By (2.2) we rewrite

$$
h(\psi(t))=\psi(t)^{\varepsilon-1}\left(1+g(\psi(t))=t^{\varepsilon-1} \exp (\varepsilon \Psi(t)) .\right.
$$

Hence

$$
(h(\psi(t)))^{\prime}=t^{\varepsilon-2} \exp (\varepsilon \Psi(t))\left[\varepsilon t \Psi^{\prime}(t)-(1-\varepsilon)\right] .
$$

By ( $\Psi-2)$ we find a $t_{0}$ such that $h(\psi(t))$ increases for $t>t_{0}$. We conclude that $h(s)=s^{\varepsilon-1}(g(s)+1)-s^{\varepsilon-1}$ is increasing on $\left(s_{0}, \infty\right)$, where $s_{0}=\psi\left(t_{0}\right)$.

Now we collect results which enable us to derive regularity properties of a mapping of finite distortion from integrability of its differential. Let us consider a class $X(\Omega) \subset L^{n-1}(\Omega)$ of measurable functions on $\Omega$ satisfying the following two conditions:
$(\mathrm{X}-1) J(\cdot, f) \in L_{\mathrm{loc}}^{1}(\Omega)$ and $\operatorname{det} D f=\operatorname{Det} D f$ provided $f \in W^{1,1}\left(\Omega, \mathbb{R}^{n}\right)$, $|D f| \in X(\Omega)$ and $J(\cdot, f) \geq 0$ a.e.
(X-2) if $g, h \geq 0$ are measurable, $g \leq c h$ for some $0<c<\infty$ and $h \in X(\Omega)$, then $g \in X(\Omega)$.

Here the statement det $D f=\operatorname{Det} D f$ means that

$$
\int_{\Omega} \varphi J(x, f) d x=-\int_{\Omega} f_{i} J\left(x, f_{1}, \ldots, f_{i-1}, \varphi, f_{i+1}, \ldots, f_{n}\right) d x
$$

for each $i=1, \ldots, n$ and for all $\varphi \in C_{0}^{\infty}(\Omega)$.
The following proposition states the weak monotonicity of a mapping $f$, see [6, Definition 1.5], under assumptions which are adapted to our situation.

Proposition 2.4. Let $X$ be a space of measurable functions satisfying (X-1) and (X-2). Let $f=\left(f_{1}, \ldots, f_{n}\right) \in W^{1, n-1}(\Omega)$ be a mapping of finite distortion with $|D f| \in X(\Omega)$. Then the coordinate functions of $f$ are weakly monotone.

Proof. We follow the standard idea as in [6, Section 4]. Let us consider a ball $B \subset \subset \Omega$. We prove e.g. that if $f_{1} \leq M$ on $\partial B$ in the sense of traces, i.e. the positive part of $f_{1}-M$ belongs to $W_{0}^{1,1}(B)$, then $f_{1} \leq M$ a.e. in $B$. We consider the truncated function $\tilde{f}_{1}=\min \left(f_{1}, M\right)$ and the mapping $\tilde{f}=\left(\tilde{f}_{1}, f_{2}, \ldots, f_{n}\right)$. Notice that, by $(\mathrm{X}-2),|D \tilde{f}| \in X(\Omega)$. Let $\varphi$ be a smooth test function with compact support in $\Omega$ such that $\varphi=1$ on $B$. Since $f_{1}$ differs from $\tilde{f}_{1}$ only on $B$ where $D \varphi=0$, we have $f_{1} D \varphi=\tilde{f}_{1} D \varphi$, and thus

$$
\begin{aligned}
\int_{\Omega} \varphi J(x, f) d x & =-\int_{\Omega} f_{1} J\left(x, \varphi, f_{2}, \ldots, f_{n}\right) d x \\
& =-\int_{\Omega} \tilde{f}_{1} J\left(x, \varphi, f_{2}, \ldots, f_{n}\right) d x=\int_{\Omega} \varphi J(x, \tilde{f}) d x
\end{aligned}
$$

Hence, if we set $E=\{\tilde{f} \neq f\}$, we have

$$
\int_{E} J(x, f) d x=\int_{E} J(x, \tilde{f}) d x=0
$$

Since $J(x, f) \geq 0$, it follows that $J f=0$ a.e. on $E$ and thus, as $f$ is a mapping of finite distortion, $D f=0$ a.e. in $E$. It follows that $D\left(f_{1}-\tilde{f}_{1}\right)=0$ a.e. in $\Omega$ which yields that $f_{1}=\tilde{f}_{1} \leq M$ a.e. in $B$.

The following proposition summarizes the outcome of [9] and [10].
Proposition 2.5. Let $X$ be a space of measurable functions satisfying (X-1) and (X-2). Let $f=\left(f_{1}, \ldots, f_{n}\right) \in W^{1, n-1}(\Omega)$ be a mapping of finite distortion $K \in L^{q}(\Omega), q>n-1$, and $|D f| \in X(\Omega)$. Suppose that $f$ is continuous. Then $f$ is open and discrete and maps sets of measure zero to sets of measure zero.

Proof. In [9, Theorems 2.1, 2.4, 3.1] it was shown that a mapping satisfying the hypotheses is open, discrete, and sense-preserving. By [10, Lemma 3.2], a continuous sense-preserving mapping $f \in W^{1, p}\left(\Omega, \mathbb{R}^{n}\right), p>n-1$, for which $\operatorname{det} D f=\operatorname{Det} D f$ maps sets of measure zero to sets of measure zero. We only need to check that $f \in W^{1, p}\left(\Omega, \mathbb{R}^{n}\right)$ for some $p>n-1$. Because of the locality of our claim, it suffices to check that $|D f| \in L_{\text {loc }}^{p}(\Omega)$ for some $p>$ $n-1$, which follows by means of the Hölder inequality from the assumption $J(\cdot, f) \in L_{\mathrm{loc}}^{1}(\Omega)$ and from the fact that $K \in L_{\mathrm{loc}}^{q}(\Omega)$ with $q>n-1$.

The assumption $\int_{\Omega} \Phi(|D f(x)|) d x<\infty$ with $\Phi$ as above has two important consequences.

Proposition 2.6. [11, Corollary 1.3] Let $\Phi$ be an Orlicz-function that satisfies ( $\Phi-1$ ) and ( $\Phi-2)$. Let $f \in W^{1,1}\left(\Omega, \mathbb{R}^{n}\right)$ satisfy $J(x, f) \geq 0$ a.e. $x \in \Omega$, and assume that $\int_{\Omega} \Phi(|D f(x)|) d x<\infty$. Then $\operatorname{det} D f \in L_{\mathrm{loc}}^{1}(\Omega)$ and $\operatorname{det} D f=\operatorname{Det} D f$.

The following proposition is essentially [6, Theorem 1.6], but with slightly weakened assumptions on $\Phi$.

Proposition 2.7. Let $\Phi$ be an Orlicz-function that satisfies ( $\Phi-1$ ) and ( $\Phi-2)$. Let $u \in W^{1,1}(\Omega)$ be a weakly monotone function, and assume that $\int_{\Omega} \Phi(|D u(x)|) d x<\infty$. Then $u$ has a continuous representative.
Proof. We will follow the proof of [6, Theorem 1.6] with a small modification. By $C$ we denote various constants which may change from line to line. Fix a point $a \in \Omega$ and $R>0$ with $B(a, 2 R) \subset \Omega$, and denote by $\omega(r)$ the essential oscillation of $u$ on $B(a, r), 0<r<R$. By [6, Lemma 7.2], for almost every radius $r \in(0, R)$ we have

$$
\omega(r)^{p} \leq C r^{p-n+1} \int_{\partial B(a, r)}|\nabla u|^{p} d S .
$$

We consider a $t_{0}$ such that $t^{-p} \Phi(t)$ is increasing on $\left(t_{0}, \infty\right)$ and a constant $\tau$ such that

$$
\begin{equation*}
\Phi(\tau)=f_{\partial B(a, r)} \Phi(\nabla u) d S \tag{2.3}
\end{equation*}
$$

where $f$ stands for the integral average. Write $\lambda=\max \left(\tau, t_{0}\right)$. Then we estimate

$$
\begin{aligned}
\int_{\partial B(a, r)}|\nabla u|^{p} d S & \leq \int_{\partial B(a, r) \cap\{|\nabla u|>\lambda\}}|\nabla u|^{p} d S+\int_{\partial B(a, r) \cap\{|\nabla u| \leq \lambda\}}|\nabla u|^{p} d S \\
& \leq \frac{\lambda^{p}}{\Phi(\lambda)} \int_{\partial B(a, r)} \Phi(\nabla u) d S+C r^{n-1} \lambda^{p} \leq 2 C r^{n-1} \lambda^{p} .
\end{aligned}
$$

It follows that

$$
\frac{\omega(r)}{C r} \leq \lambda
$$

and thus

$$
\Phi\left(\frac{\omega(r)}{C r}\right) \leq \Phi(\lambda) \leq f_{\partial B(a, r)}\left[\Phi\left(t_{0}\right)+\Phi(\nabla u)\right] d S .
$$

Now we may continue as in the proof of [6, Theorem 1.6].
Proof of Theorem 1.3. Proposition 2.6 shows that our space $L^{\Phi}(\Omega)$ qualifies for $X(\Omega)$ with (X-1) and (X-2). By Proposition 2.4 we see that the coordinate functions of $f$ are weakly monotone which implies continuity by Proposition 2.7. Then Proposition 2.5 yields the conclusion.

Proof of Theorem 1.1. Let $\Phi(t)=g\left(t^{n}\right)$ where $g$ is as in (2.1). Then by Lemma 2.1 (b)

$$
\begin{aligned}
\int_{\Omega} \Phi(|D f|) d x & =\int_{\Omega} g\left(|D f|^{n}\right) d x \leq \int_{\Omega} g(J(x, f) K(x)) d x \\
& \leq \int_{\Omega} J(x, f) d x+\int_{\Omega} \exp (K(x)) d x<\infty
\end{aligned}
$$

By Lemma 2.3 and Lemma 2.1 (a), the function $\Phi$ satisfies ( $\Phi-1$ ) and ( $\Phi-2$ ) (for all $p \in(n-1, n)$ ), and the inclusion $L_{\mathrm{loc}}^{\Phi}(\Omega) \subset L_{\mathrm{loc}}^{p}(\Omega)$ holds for all $p \in(n-1, n)$. Hence the assumptions of Theorem 1.3 are verified.

## 3. Proof of Theorem 1.2

We begin by giving examples of discontinuous mappings of finite distortion with the distortion function having the desired degree of regularity (also see [7]). We consider mappings $f: \mathbb{B} \rightarrow \mathbb{R}^{n}$ of the form

$$
\begin{equation*}
f(x)=\frac{x}{|x|} \rho(|x|) . \tag{3.1}
\end{equation*}
$$

The function $t \rightarrow \rho(t)$, for $0 \leq t \leq 1$, will continuously increase from the value 1 at $t=0$ to $b>1$ at $t=1$. Thus $f$ will map homeomorphically the punctured unit ball $\mathbb{B} \backslash\{0\}$ onto the annulus $\left\{x \in \mathbb{R}^{n}: 1<|x|<b\right\}$. We may calculate the differential matrix of $f$ and its determinant by using the familiar formulas

$$
\begin{equation*}
D f(x)=\frac{\rho(|x|)}{|x|} \mathbf{I}+\left(\rho^{\prime}(|x|)-\frac{\rho(|x|)}{|x|}\right) \frac{x \otimes x}{|x|^{2}} \tag{3.2}
\end{equation*}
$$

where $x \otimes x$ is the $n \times n$ matrix whose $i, j$-entry equals $x_{i} x_{j}$, and

$$
\begin{equation*}
J(x, f)=\rho^{\prime}(|x|)\left(\frac{\rho(|x|)}{|x|}\right)^{n-1} \tag{3.3}
\end{equation*}
$$

Our choice for $\rho$ will satisfy

$$
\begin{equation*}
\rho^{\prime}(t) \leq \beta \frac{\rho(t)}{t} \tag{3.4}
\end{equation*}
$$

for some $\beta \geq 1$. Consequently, the norm of differential matrix in question satisfies

$$
\begin{equation*}
|D f(x)| \leq(\beta+2) \frac{\rho(|x|)}{|x|} \tag{3.5}
\end{equation*}
$$

and the dilatation function K satisfies

$$
\begin{equation*}
K(x)=\frac{|D f(x)|^{n}}{J(x, f)} \leq(\beta+2)^{n} \frac{\rho(|x|)}{|x| \rho^{\prime}(|x|)} \tag{3.6}
\end{equation*}
$$

We may assume that $\Psi(1)=1$. We define $\rho$ by setting

$$
\rho(t)=\exp \left(\lambda \int_{\Psi^{-1}\left(\log \frac{e}{t}\right)}^{\infty} \frac{\Psi^{\prime}(s)}{s} d s\right)
$$

for $0<t<1$, where $\lambda$ is a constant, whose value will be determined later. Using the change of variables

$$
s=\Psi^{-1}\left(\log \frac{e}{r}\right)
$$

we obtain

$$
\rho(t)=\exp \left(\lambda \int_{0}^{t} \frac{d r}{r \Psi^{-1}\left(\log \frac{e}{r}\right)}\right) .
$$

For the Jacobian integral we compute

$$
\int_{\mathbb{B}} J(x, f) d x=C(n) \int_{0}^{1} \rho^{n-1}(t) \rho^{\prime}(t) d t=C(n)\left(\rho^{n}(1)-\rho^{n}(0)\right)<\infty .
$$

We also have

$$
\begin{equation*}
\frac{t \rho^{\prime}(t)}{\rho(t)}=t(\log \rho(t))^{\prime}=\frac{\lambda}{\Psi^{-1}\left(\log \frac{e}{t}\right)} \tag{3.7}
\end{equation*}
$$

This quantity tends to zero as $t \rightarrow 0$ and thus there exists $t_{0}>0$ such that (3.4) follows with constant 1 for all $t \in\left(0, t_{0}\right)$. Fix $\lambda=3^{n}$. By (3.6) and (3.7) we obtain

$$
\begin{aligned}
\exp \Psi(K(x)) & \leq \exp \Psi\left(\frac{3^{n} \rho(|x|)}{|x| \rho^{\prime}(|x|)}\right) \\
& \leq \exp \Psi\left(\Psi^{-1}\left(\log \frac{e}{|x|}\right)\right)=\frac{e}{|x|}
\end{aligned}
$$

for all $x \in B\left(0, t_{0}\right) \backslash\{0\}$. Hence $\exp \Psi \circ K \in L^{1}(\mathbb{B})$, as desired.
The construction we need for part (b) of Theorem 1.2 is a substantial improvement on the construction in [9]. For the convenience of the reader we present here also the part of the construction from [9] that need not be altered.

We begin by introducing some notation. Besides the usual Euclidean norm $|x|=\left(x_{1}^{2}+\cdots+x_{n}^{2}\right)^{1 / 2}$ we will use the cubic norm $\|x\|=\max _{i}\left|x_{i}\right|$. Using the cubic norm, the $x_{0}$-centered closed cube with edge length $2 r>0$ and sides parallel to coordinate axes can be represented in the form

$$
Q\left(x_{0}, r\right)=\left\{x \in \mathbb{R}^{n}:\left\|x-x_{0}\right\| \leq r\right\}
$$

We then call $r$ the radius of $Q$. Let us denote $c Q\left(x_{0}, r\right)=Q\left(x_{0}, c r\right)$ if $c>0$. We will use the notation $a \lesssim b$ if there is a constant $c>0$ (not depending on (integration) variables or summation indices) such that $a \leq c b$, and we write $a \approx b$ if $a \lesssim b$ and $b \lesssim a$. For technical reasons we will assume that $\Psi(1)=1$.

We will prove part (b) of Theorem 1.2 by giving a mapping $f: Q_{0} \rightarrow$ $\mathbb{R}^{n}$ so that $f=\operatorname{Id}$ on $\partial Q_{0}, J(x, f)<0$ a.e. and so that the rest of the requirements hold for $|J(x, f)|$; the desired mapping is then obtained by employing an auxiliary reflection in a hyperplane.

In the following, we will construct a sequence of continuous, piecewise continuously differentiable mappings $f_{k}: Q_{0} \rightarrow \mathbb{R}^{n}$. First we introduce a sequence of compact sets in $Q_{0}$ whose intersection is a Cantor set.

The unit cube $Q_{0}$ is first divided into $2^{n}$ cubes with radius $1 / 4$, which are each in turn divided into a subcube with radius $(1 / 4) / 2$ and a difference of two cubes which we refer to as an annulus. The family $\mathcal{Q}_{1}$ consists of these $2^{n}$ subcubes. The remainder of the construction is then self-similar. The subcube is divided into $2^{n}$ cubes which are each in turn divided into a subcube with radius $4^{-2} / 2$ and an annulus. The family $\mathcal{Q}_{2}$ consists of these $2^{2 n}$ subcubes (see Figure 1). Continuing this way, we get the families $\mathcal{Q}_{k}, k=1,2,3, \ldots$, for which the radius of $Q \in \mathcal{Q}_{k}$ is $r(Q)=r_{k}=2^{-2 k-1}$ and the number of cubes in $\mathcal{Q}_{k}$ is $\# \mathcal{Q}_{k}=2^{n k}$. It easily follows that the resulting Cantor set is of measure zero.


Figure 1: Families $\mathcal{Q}_{1}$ and $\mathcal{Q}_{2}$.

We are now ready to define the mappings $f_{k}$. Define $f_{0}(x)=x$. We will give a mapping $f_{1}$ that leaves the boundaries $\partial(2 Q), Q \in \mathcal{Q}_{1}$ fixed, turns each annulus $2 Q \backslash Q$ inside out and stretches the cube $Q$ so that $f_{1}$ is continuous (see Figure 2). The Jacobian determinant $J_{f_{1}}$ will be negative in each annulus $2 Q \backslash Q$ and positive in each cube $Q$. Next, $f_{2}$ equals $f_{1}$ in the annulae $2 Q \backslash Q, Q \in \mathcal{Q}_{1}$, turns each annulus $2 Q \backslash Q, Q \in \mathcal{Q}_{2}$, inside out, stretches the cube $Q$ and shifts the image so that $f_{2}$ is continuous. Moreover, $J_{f_{2}}$ is negative a.e. in $Q_{0} \backslash \bigcup_{Q \in \mathcal{Q}_{2}} Q$ and positive in $\bigcup_{Q \in \mathcal{Q}_{2}} Q$. We will then continue in this manner.


Figure 2: The mapping $f_{1}$ acting on $2 Q, Q \in \mathcal{Q}_{1}$.
To be precise, let $f_{0}(x)=x$ on $Q_{0}$ and let a sequence $\left\{\epsilon_{k}\right\}_{k \in \mathbb{N}}$ of small positive real numbers satisfy

$$
\begin{equation*}
\sum_{k=1}^{\infty} \epsilon_{k}<\infty \tag{3.8}
\end{equation*}
$$

This sequence will be fixed later. For $k=1,2, \ldots$ define

$$
\varphi_{k}(r)= \begin{cases}2^{-k-1}\left(1+\epsilon_{1}\right) \cdots\left(1+\epsilon_{k-1}\right)\left(1+\frac{2 r_{k}-r}{r_{k}} \epsilon_{k}\right), & r_{k} \leq r \leq 2 r_{k} \\ 2^{-k-1}\left(1+\epsilon_{1}\right) \cdots\left(1+\epsilon_{k}\right) \frac{r}{r_{k}}, & 0 \leq r \leq r_{k}\end{cases}
$$

and

$$
f_{k}(x)= \begin{cases}f_{k-1}(x), & x \notin \bigcup_{Q \in \mathcal{Q}_{k}} 2 Q \\ f_{k-1}(z(Q))+\frac{x-z(Q)}{\|x-z(Q)\|} \varphi_{k}(\|x-z(Q)\|), & x \in 2 Q, Q \in \mathcal{Q}_{k}\end{cases}
$$

Here $z(Q)$ is the center of the cube $Q$. Now

$$
\log \prod_{j=1}^{k}\left(1+\epsilon_{j}\right)=\sum_{j=1}^{k} \log \left(1+\epsilon_{j}\right) \leq \sum_{j=1}^{k} \epsilon_{j},
$$

and using the fact (3.8) we infer that

$$
\prod_{j=1}^{\infty}\left(1+\epsilon_{j}\right)<\infty
$$

Thus

$$
\begin{equation*}
\prod_{j=1}^{k}\left(1+\epsilon_{j}\right) \approx 1, \quad k=1,2, \ldots \tag{3.9}
\end{equation*}
$$

Using this we obtain

$$
\left|f_{k+1}(x)-f_{k}(x)\right| \lesssim 2^{-k}
$$

and so the sum

$$
\sum_{k=1}^{\infty}\left|f_{k+1}(x)-f_{k}(x)\right|
$$

and the sequence $\left(f_{k}\right)$ converge uniformly. Hence the limit $f=\lim _{k \rightarrow \infty} f_{k}$ is continuous. Clearly $f$ is differentiable almost everywhere, its Jacobian determinant is strictly negative almost everywhere, and $f$ is absolutely continuous on almost all lines parallel to coordinate axes.

We next estimate $|D f(x)|,|J(x, f)|$ and $K(x)$ at $x \in \operatorname{int}(2 Q \backslash Q)$, $Q \in \mathcal{Q}_{k}$. Fix $k \in \mathbb{N}$. We see that, in the annulus $\operatorname{int}(2 Q \backslash Q), f$ is a radial mapping: $f(x)=(x /\|x\|) \varphi_{k}(\|x\|)$. Hence we have

$$
|D f(x)| / C_{1}(n) \leq \max \left\{\frac{\varphi_{k}(\|x\|)}{\|x\|},\left|\varphi_{k}^{\prime}(\|x\|)\right|\right\} \leq C_{1}(n)|D f(x)|
$$

and

$$
J_{f}(x) / C_{2}(n) \leq \frac{\varphi_{k}^{\prime}(\|x\|) \varphi_{k}(\|x\|)^{n-1}}{\|x\|^{n-1}} \leq C_{2}(n) J_{f}(x)
$$

a.e. in $\operatorname{int}(2 Q \backslash Q)$, see the formulas (3.2) and (3.3). By (3.8) and (3.9) we obtain

$$
\begin{equation*}
|D f(x)| \lesssim \frac{\varphi_{k}\left(r_{k}\right)}{r_{k}} \approx 2^{k} \tag{3.10}
\end{equation*}
$$

and

$$
\begin{equation*}
J(x, f) \approx\left(\frac{\varphi_{k}\left(r_{k}\right)}{r_{k}}\right)^{n-1} \varphi_{k}^{\prime}\left(r_{k}\right) \approx-\left(2^{k}\right)^{n-1} 2^{k} \epsilon_{k}=-2^{k n} \epsilon_{k} \tag{3.11}
\end{equation*}
$$

and finally

$$
\begin{equation*}
K(x):=\frac{|D F(x)|}{|J(x, f)|} \lesssim \frac{2^{k n}}{2^{k n} \epsilon_{k}}=\frac{1}{\epsilon_{k}} . \tag{3.12}
\end{equation*}
$$

Since

$$
\begin{equation*}
\left|\bigcup_{Q \in \mathcal{Q}_{k}} 2 Q \backslash Q\right| \approx 2^{-k n} \tag{3.13}
\end{equation*}
$$

we obtain in view of (3.8)

$$
\int_{Q_{0}}|J(x, f)| d x \lesssim \sum_{k=1}^{\infty} \epsilon_{k}<\infty
$$

By (3.12) there exists a constant $\beta$ such that

$$
K(x) \leq \frac{\beta}{\epsilon_{k}}, \quad x \in 2 Q \backslash Q, Q \in \mathcal{Q}_{k} .
$$

We now define the numbers $\epsilon_{k}$ explicitly by setting

$$
\begin{equation*}
\epsilon_{k}=\frac{\beta}{\Psi^{-1}(k)} \tag{3.14}
\end{equation*}
$$

Because $\int_{1}^{\infty} \frac{\Psi^{\prime}(s)}{s} d s<\infty$, the change of variables

$$
s=\Psi^{-1}(t)
$$

shows that

$$
\int_{1}^{\infty} \frac{d t}{\Psi^{-1}(t)}<\infty
$$

Thus the integral criterion for convergence of series establishes (3.8). By (3.12) and (3.14),

$$
\exp \Psi(K(x)) \leq \exp \Psi\left(\frac{\beta}{\epsilon_{k}}\right)=\exp k, \quad x \in 2 Q \backslash Q, Q \in \mathcal{Q}_{k}
$$

and thus

$$
\int_{Q_{0}} \exp \Psi(K(x)) d x \leq C \sum_{k=1}^{\infty}\left(2^{-n} e\right)^{k}<\infty
$$

Next we will show that $f$ maps a set of measure zero to a set of positive measure by showing that

$$
Q_{0} \subset f\left(\bigcap_{k=1}^{\infty} \bigcup_{Q \in \mathcal{Q}_{k}} Q\right)
$$

recall that the Cantor set $\bigcap_{k=1}^{\infty} \bigcup_{Q \in \mathcal{Q}_{k}} Q$ has measure zero. From the construction it follows that for each $k=1,2,3, \ldots$

$$
f_{k}\left(\bigcup_{Q \in \mathcal{Q}_{k}} Q\right) \subset f_{k}\left(\bigcup_{Q \in \mathcal{Q}_{k+1}} 2 Q\right) \subset f_{k+1}\left(\bigcup_{Q \in \mathcal{Q}_{k+1}} Q\right)
$$

Since $Q_{0} \subset f_{1}\left(\bigcup_{Q \in \mathcal{Q}_{1}} Q\right)$, denoting

$$
H_{k}=\bigcup_{Q \in \mathcal{Q}_{k}} Q
$$

we have $Q_{0} \subset f_{k}\left(H_{k}\right) \subset f_{l}\left(H_{k}\right)$ for all $l \geq k \geq 1$. Now $\left(H_{k}\right)$ is a decreasing sequence of compact sets, whence

$$
Q_{0} \subset \bigcap_{k=1}^{\infty} \bigcap_{l \geq k} f_{l}\left(H_{k}\right) \subset \bigcap_{k=1}^{\infty} f\left(H_{k}\right) \subset f\left(\bigcap_{k=1}^{\infty} H_{k}\right) .
$$

Notice that $f$ is not open: it follows from the construction that $f\left(\partial Q_{0}\right)=$ $\partial Q_{0} \subset f\left(\operatorname{int} Q_{0}\right)$ whence $f\left(Q_{0}\right)=f\left(\operatorname{int} Q_{0}\right)$. Because $f\left(Q_{0}\right)$ is a nonempty compact set, $f\left(\right.$ int $\left.Q_{0}\right)$ is not open. To prove non-discreteness of $f$, let

$$
G_{k}=\bigcup_{l \geq k} f\left(\bigcup_{Q \in \mathcal{Q}_{l}} \operatorname{int} 2 Q \backslash Q\right) .
$$

Then the sets $G_{k}$ are dense and open, and by the Baire category theorem their intersection is nonempty. But if $y \in \cap_{k} G_{k}$, then $f^{-1}(y)$ is an infinite compact set and thus it is not discrete.

Remark 3.1. The example can be easily modified to show sharpness of the condition ( $\Phi-1$ ) by setting

$$
\epsilon_{k}=2^{-k n} \Phi\left(2^{k}\right)
$$

in place of (3.14).

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