ISOMETRIC IMMERSIONS OF SPACE FORMS IN SPACE FORMS

JOHN DOUGLAS MOORE

Let M be a connected n-dimensional space form isometrically immersed in a simply connected (2n-1)-dimensional space form of strictly larger curvature. If M is minimal, it is proven that it must be a piece of the flat Clifford torus in the (2n-1)-sphere. If M is complete and simply connected, it is proven that M possesses a global coordinate system whose coordinate vectors are unit-length asymptotic vectors.

Introduction. A well-known theorem of David Hilbert states that a complete two-dimensional riemannian manifold of constant negative curvature cannot be isometrically immersed in three-dimensional euclidean space [5], [7, p. 265]. There is reason to believe that the natural generalization of Hilbert's theorem to higher dimensions would be the following conjecture: A complete n-dimensional riemannian manifold of constant negative curvature cannot be isometrically immersed in E^{2n-1} . If completeness is strengthened to compactness the conjecture is known to be true by work of Chern, Kuiper, and Otsuki [6, vol. 2, p. 29].

The local problem of isometrically immersing a space form in a space form was studied by Élie Cartan [3]. He used his theory of exterior differential systems to show, among other things, that real analytic n-dimensional submanifolds of constant negative curvature in (2n-1)-dimensional euclidean space E^{2n-1} depend upon n(n-1) functions of a single variable. Cartan also showed that no n-dimensional hyperbolic space form can be isometrically immersed in E^{2n-2} . To construct an explicit example, we choose nonzero real numbers a_i , $1 \le i \le n-1$, so that $\sum_i a_i^2 = 1$, and we define an immersion from

$$D = \{(y_1, y_2, \dots, y_n) \in \mathbb{R}^n \mid y_n < 0\}$$

into E^{2n-1} with rectangular cartesian coordinates $x_1, x_2, \dots, x_{2n-1}$ by the equations

$$egin{aligned} x_{2i-1} &= a_i e^{y_n} \mathrm{cos}(y_i/a_i) \;, \ x_{2i} &= a_i e^{y_n} \mathrm{sin}(y_i/a_i) \;, \ x_{2n-1} &= \int_0^{y_n} (1 - e^{2u})^{1/2} du \;. \end{aligned}$$
 $1 \leq i \leq n-1,$

We find that the submanifold metric on D is of constant negative curvature; however D is not complete in this metric.

In §3 of this paper we prove that one of the main steps in the proof of Hilbert's theorem, the construction of a global coordinate system whose coordinate vectors are unit-length asymptotic vectors, can be generalized to the *n*-dimensional context. Our treatment is based upon a theorem of Cartan, a proof of which is given in §1. Section 2 is devoted to the local properties of space forms isometrically immersed in space forms, and includes a rigidity theorem for minimal submanifolds of constant curvature.

Unless otherwise stated all manifolds are connected and C^{∞} .

1. Exteriorly orthogonal symmetric bilinear forms. Let V be an n-dimensional real vector space and let $\Phi^1, \Phi^2, \dots, \Phi^n$ be n symmetric bilinear forms on V. We say that $\Phi^1, \Phi^2, \dots, \Phi^n$ are exteriorly orthogonal if

$$\sum\limits_{\lambda=1}^{n}\left[arPhi^{\lambda}(X,\ Y)arPhi^{\lambda}(Z,\ W)\,-\,arPhi^{\lambda}(X,\ W)arPhi^{\lambda}(Z,\ Y)
ight]\,=\,0$$

for $X, Y, Z, W \in V$.

THEOREM 1. (Élie Cartan [3]). Suppose that Φ^1 , Φ^2 , ..., Φ^n are n exteriorly orthogonal symmetric bilinear forms on an n-dimensional real vector space V with the following property: if X is a vector in V such that $\Phi^1(X, Y) = 0$ for $1 \leq \lambda \leq n$ and for all $Y \in V$, then X = 0. Then there exists a real orthogonal matrix (a_r^{λ}) and n linear functionals Φ^1 , Φ^2 , ..., Φ^n such that

$$arPhi^{\lambda} = \sum_{\mu} lpha^{\lambda}_{\mu} arphi^{\mu} igotimes arphi^{\mu}$$
 , $1 \leqq \lambda \leqq n$.

It follows that Φ^1 , Φ^2 , ..., Φ^n are simultaneously diagonalized with respect to the basis dual to $\{\varphi^1, \varphi^2, \dots, \varphi^n\}$. Theorem 1 is trivial when n=1 and when n=2 it is a consequence of the following well-known fact: two symmetric bilinear forms, one of which is positive definite, can be simultaneously diagonalized.

We will find it convenient to regard Φ^{λ} as a linear transformation from V to the dual space V^* so that it induces a linear map

$$\Phi^{\lambda} \wedge \Phi^{\lambda}$$
: $V \wedge V \rightarrow V^* \wedge V^*$.

Then $\Phi^{\lambda} \wedge \Phi^{\lambda} = 0$ if and only if $\Phi^{\lambda} = \pm \varphi^{\lambda} \otimes \varphi^{\lambda}$ for some linear functional φ^{λ} . We can now restate Theorem 1 as follows: Suppose that $\Phi^{1}, \Phi^{2}, \dots, \Phi^{n}$ are linear transformations from an *n*-dimensional real vector space to its dual such that $[\Phi^{\lambda}(X)](Y) = [\Phi^{\lambda}(Y)](X)$. If

$$\bigcap_{\lambda} \ker(\Phi^{\lambda}) = (0)$$
 and $\sum_{\lambda} \Phi^{\lambda} \wedge \Phi^{\lambda} = 0$,

then there exists a real orthogonal matrix (a_u^{λ}) such that if

$$arPsi^\lambda=\sum\limits_\mu a^\lambda_\mu arPhi^\mu$$
 , then $arPsi^\lambda\wedgearPsi^\lambda=0$ for $1\leqq\lambda\leqq n$.

The first step in the proof of Theorem 1 consists of showing that there exists a vector X in V such that $\Phi^1(X)$, $\Phi^2(X)$, \cdots , $\Phi^n(X)$ are linearly independent. We prove this by contradiction. If $X \in V$, let $U^*(X)$ be the subspace of V^* generated by $\{\Phi^\lambda(X)\colon 1 \leq \lambda \leq n\}$ and let p be the maximum dimension of $U^*(X)$ for $X \in V$. We assume that p < n. If M is a vector for which the maximum dimension p is attained, we can assume without loss of generality that

$$\Phi^1(M), \Phi^2(M), \cdots, \Phi^p(M)$$

are linearly independent, and $\Phi^{p+1}(M) = \cdots = \Phi^{n}(M) = 0$. If Y is any other vector in V, then

$$\sum\limits_{lpha=1}^p arPhi^lpha(M) \wedge arPhi^lpha(Y) = 0$$
 ,

so that by Cartan's lemma there exists a $p \times p$ symmetric matrix (c^{α}_{β}) such that

If we let W^* be the subspace of V^* generated by

$$\{\Phi^{\alpha}(X): X \in V, 1 \leq \alpha \leq p\}$$

then (1) shows that W^* is exactly p-dimensional. Since p < n there exists a nonzero vector Z in V which is annihilated by W^* . But by hypothesis there exists λ , $1 \le \lambda \le n$, and a vector $N \in V$ such that $\Phi^{\lambda}(Z, N) \ne 0$. Since Z is annihilated by W^* , $\lambda \ge p + 1$. If $\varepsilon > 0$ is sufficiently small, $\{\Phi^{\alpha}[(\cos \varepsilon)M + (\sin \varepsilon)N] \mid 1 \le \alpha \le p\}$ will generate W^* and $\Phi^{\lambda}[(\cos \varepsilon)M + (\sin \varepsilon)N]$ will be outside of W^* . Hence

$$U^*[(\cos \varepsilon)M + (\sin \varepsilon)N]$$

is at least (p + 1)-dimensional; this contradicts the definition of p, and the first step is established.

Let $\{v_1, v_2, \dots, v_n\}$ be a basis for V such that

$$\Phi^{\scriptscriptstyle 1}(v_{\scriptscriptstyle 1}), \Phi^{\scriptscriptstyle 2}(v_{\scriptscriptstyle 1}), \cdots, \Phi^{\scriptscriptstyle n}(v_{\scriptscriptstyle 1})$$

are linearly independent. Then we can apply Cartan's lemma to the equation

$$\sum_{\lambda} \Phi^{\lambda}(v_{\scriptscriptstyle 1}) \, \wedge \, \Phi^{\lambda}(v_{\scriptscriptstyle i}) \, = \, 0$$

and conclude that there exists a symmetric matrix $C(i)=(c(i)^{\lambda}_{\mu})$ such that

$$arPhi^{\wr}(v_i) = \sum_{\mu} c(i)^{\wr}_{\mu} arPhi^{\mu}(v_{\scriptscriptstyle 1})$$
 , $1 \leqq \lambda \leqq n$.

(Notice that C(1) is the identity matrix.) We next observe that it follows from the equation

$$\sum_{i} \Phi^{\lambda}(v_{i}) \wedge \Phi^{\lambda}(v_{j}) = 0$$

that the matrices C(i) and C(j) commute with each other. By a well-known theorem from linear algebra there exists an orthogonal matrix $A=(a_{\mu}^{\lambda})$ such that $A[C(i)][^{t}A]$ is diagonal for $1\leq i\leq n$. If we let $\Psi^{\lambda}=\sum_{\mu}a_{\mu}^{\lambda}\Phi^{\mu}$ then $\Psi^{\lambda}(v_{i})$ is a constant multiple of $\Psi^{\lambda}(v_{i})$ for $1\leq i\leq n$, so that

$$\Psi^{\lambda}(v_i) \wedge \Psi^{\lambda}(v_j) = 0$$
, $1 \leq i, j, \lambda \leq n$.

It follows that $\Psi^{\lambda} \wedge \Psi^{\lambda} = 0$, $1 \leq \lambda \leq n$, and Theorem 1 is proven.

An examination of the above proof shows that $\Psi^1, \Psi^2, \dots, \Psi^n$ are uniquely determined up to a permutation. Hence the linear functionals $\varphi^1, \varphi^2, \dots, \varphi^n$ are uniquely determined up to changes of sign and a possible permutation.

2. Submanifolds of constant curvature: local theory. In the rest of this paper, our setup will be as follows: we will let M be an n-dimensional riemannian manifold of constant curvature k isometrically immersed in a (2n-1)-dimensional riemannian manifold N of constant curvature K. We will use the following conventions on ranges of indices:

$$1 \le i, j, k, l \le n$$
, $n + 1 \le \lambda, u \le 2n - 1$, $1 \le A, B, C \le 2n - 1$.

Let $e_1, e_2, \dots, e_{2n-1}$ be a moving oriented orthonormal frame on an open set U in N, chosen so that at points of a suitable open subset V of the submanifold M the first n frame vectors are tangent to M. Let $\theta^1, \theta^2, \dots, \theta^{2n-1}$ be the dual orthonormal coframe. A fundamental theorem of riemannian geometry states that there exists a unique collection of 1-forms θ^A_B on U which satisfy the structure equation

$$d heta^{\scriptscriptstyle A}=-\sum\limits_{\scriptscriptstyle B} heta^{\scriptscriptstyle A}_{\scriptscriptstyle B}\wedge heta^{\scriptscriptstyle B},\, heta^{\scriptscriptstyle A}_{\scriptscriptstyle B}=- heta^{\scriptscriptstyle B}_{\scriptscriptstyle A}$$
 .

The fact that N has constant curvature K is expressed by the equation

(3)
$$d heta_{\scriptscriptstyle B}^{\scriptscriptstyle A} = -\sum\limits_{\scriptscriptstyle C} heta_{\scriptscriptstyle C}^{\scriptscriptstyle A} \wedge heta_{\scriptscriptstyle B}^{\scriptscriptstyle C} + K heta_{\scriptscriptstyle A} \wedge heta_{\scriptscriptstyle B}$$
 .

If we restrict these equations to the open subset V of M and make use of the fact that $\theta^{\lambda}=0$ on V, we obtain from (2) the equations

$$d\theta^i = -\sum_k \theta^i_k \wedge \theta^k, \ 0 = -\sum_k \theta^i_k \wedge \theta^k.$$

The second of these implies via Cartan's lemma that

$$(5)$$
 $heta_i^{\scriptscriptstyle
m l}=\sum_i^{\scriptscriptstyle
m l}b_{ij}^{\scriptscriptstyle
m l} heta^{\scriptscriptstyle
m l},\;b_{ij}^{\scriptscriptstyle
m l}=b_{ji}^{\scriptscriptstyle
m l}$,

where the b_{ij}^{γ} 's are differentiable functions on V called the components of the second fundamental forms. From equation (3) we obtain the equation

$$d heta^i_j = -\sum_k heta^i_k \wedge heta^k_j - \sum_\lambda heta^i_\lambda \wedge heta^\lambda_j + K heta^i \wedge heta^j$$
 .

Since M is of constant curvature k

$$-\sum\limits_{i} heta_{\lambda}^{i}\wedge\, heta_{j}^{\lambda}=(k-K) heta^{i}\wedge\, heta^{j}$$
 ,

or equivalently

$$(6) \qquad \qquad \sum_{i} (b_{ij}^{i} b_{kl}^{\lambda} - b_{il}^{\lambda} b_{kj}^{\lambda}) = (k - K)(\delta_{ij} \delta_{kl} - \delta_{il} \delta_{kj}) ,$$

where δ_{ij} is the usual Kronecker delta.

Assume now that k < K. Equation (6) then states that the second fundamental forms $\Phi^i = \sum_i \theta_i^i \otimes \theta^i$ and the symmetric bilinear form

$$\Psi = \sqrt{K - k} \left(\sum_{i} \theta^{i} \otimes \theta^{i} \right)$$

are exteriorly orthogonal, and Theorem 1 implies that they can be simultaneously diagonalized by a basis for the tangent space to M. Since the basis diagonalizes Ψ it can be chosen to be orthonormal, and hence we can assume that the moving frame $e_1, e_2, \dots, e_{2n-1}$ chosen in the preceding paragraphs satisfies the equations $b_{ij}^2 = 0$ for $i \neq j$. In view of the remark at the end of § 1, any two diagonalizing orthonormal bases differ at most by changes of sign and a possible permutation. Hence if M is simply connected we can choose a global moving frame e_1, e_2, \dots, e_n on M which diagonalizes the second fundamental forms. In particular, the universal covering space of M is parallelizable.

In terms of the diagonalizing moving frame, equation (6) takes the simpler form

(7)
$$\sum_{j}b_{ii}^{\gamma}b_{jj}^{\gamma}=(k-K)\;,\qquad i
eq j\;.$$

We claim that it follows from this equation that there exist unique positive functions x_1, x_2, \dots, x_n such that

(8)
$$\sum_i b_{ii}^2 x_i^2 = 0 \text{ and } \sum_i x_i^2 = 1.$$

Indeed, such functions need to satisfy the equation

$$0=\sum\limits_{i,j}b_{jj}^{\lambda}b_{ii}^{\lambda}x_i^2=\sum\limits_{j}b_{jj}^{\lambda}b_{jj}^{\lambda}x_j^2-(K-k)(1-x_j^2)$$
 ,

from which it follows that

(9)
$$\sum_{\lambda} b_{ii}^{\lambda} b_{ii}^{\lambda} = (K-k)(1-x_{i}^{2})/x_{i}^{2}$$
 .

We can solve for x_i to obtain the expression

(10)
$$x_i = \left[\left(\sum_{\lambda} b_{ii}^{\lambda} b_{ii}^{\lambda} \right) / (K - k) + 1 \right]^{-1/2},$$

and check that the functions defined by this equation satisfy equations (8). A slight modification of this argument shows that any n-1 of the "principal normal curvature vectors" $\sum_{\lambda} b_{ii}^{\lambda} e_{\lambda}$ are linearly independent.

A restatement of what we proved in the preceding paragraph is that there exist exactly 2ⁿ unit-length vectors on which all the second fundamental forms vanish simultaneously. They are all of the form

$$(11) \pm x_1 e_1 \pm x_2 e_2 \pm \cdots \pm x_n e_n ,$$

where the signs can be chosen in 2^n ways, and they are called asymptotic vectors.

We remark that the normal bundle of M in N has zero curvature because the curvature forms of the normal bundle are $-\sum_i \theta_i^i \wedge \theta_\mu^i$ and both θ_i^i and θ_μ^i are multiples of θ^i . Hence without loss of generality we will assume that e_{n+1}, \dots, e_{2n-1} have been chosen so that $\theta_\mu^i = 0$.

Our next objective is to find an expression for the differential 1-forms θ_j^i in terms of the functions x_i . For this purpose we will use the tensor b_{ijk}^2 defined by the following equation

(12)
$$db_{ij}^{\lambda} + \sum_{\mu} b_{ij}^{\mu} \theta_{\mu}^{\lambda} - \sum_{k} b_{kj}^{\lambda} \theta_{i}^{k} - \sum_{k} b_{ik}^{\lambda} \theta_{j}^{k} = \sum_{k} b_{ijk}^{\lambda} \theta^{k}.$$

The exterior derivative of equation (5) shows that the tensor b_{ijk}^{λ} is symmetric in its lower indices. If we make use of the facts that $b_{ij}^{\lambda}=0$ for $i\neq j$ and $\theta_{\mu}^{\lambda}=0$, we can simplify (12) and obtain the equations

(13)
$$db_{ii}^{\scriptscriptstyle
ho} = \sum\limits_{\scriptscriptstyle k} b_{iik}^{\scriptscriptstyle
ho} heta^{\scriptscriptstyle k}$$
 ,

(14)
$$(b_{jj}^{i}-b_{ii}^{i})\theta_{j}^{i}=\sum_{k}b_{ijk}^{i}\theta_{k}^{k}, \qquad i\neq j.$$

If we choose e_{n+1} at a point $x \in M$ so that $b_{11}^{n+2}(x) = \cdots = b_{11}^{2n-1}(x) = 0$, then it follows from equation (7) that

$$b_{ii}^{n+1}(x) = (k-K)/b_{ii}^{n+1}(x)$$
.

Equation (14) therefore implies that $b_{ijk}^{n+1}(x) = 0$ for i, j, 1 distinct. It follows that $b_{ijk}^{n+1}(x) = 0$ for i, j, k distinct, and since the principal normal curvature vectors span the normal space, $b_{ijk}^{i}(x) = 0$ for i, j, k distinct. Since x is arbitrary, equation (14) now becomes

$$(b_{ij}^{i}-b_{ii}^{i}) heta_{j}^{i}=b_{iii}^{i} heta^{i}+b_{iij}^{i} heta^{j}$$
 , $i
eq j$.

We multiply this last equation by b_{ii}^{γ} and sum with respect to λ to conclude that

$$(k-K-\sum\limits_{j}b_{ii}^{j}b_{ii}^{\lambda}) heta_{j}^{i}=\sum\limits_{j}b_{ii}^{\lambda}b_{iij}^{\lambda} heta^{i}+\sum\limits_{j}b_{ii}^{\lambda}b_{jji}^{\lambda} heta^{j}\;,\qquad i
eq j$$
 .

We now need to use the following fact which is a consequence of (9):

(15)
$$2\sum_{j}b_{ii}^{j}b_{iij}^{j}=(K-k)e_{j}[(1-x_{i}^{2})/x_{i}^{2}].$$

We can use this to derive the following equation for the 1-forms θ_i^i :

$$\theta_i^i = (1/x_i)e_i(x_i)\theta^i + (\text{something})\theta^j$$
.

Using skew-symmetry we conclude that

(16)
$$\theta_{j}^{i} = (1/x_{i})e_{j}(x_{i})\theta^{i} - (1/x_{j})e_{i}(x_{j})\theta^{j}.$$

As an application of these ideas we prove the following theorem closely related to recent work of do Carmo and Wallach [2]:

Theorem 2. Let M be a connected n-dimensional riemannian manifold of constant curvature k isometrically and minimally immersed in a simply connected (2n-1)-dimensional riemannian manifold N of constant curvature K. Then either M is totally geodesic or it is flat. In the flat case it is immersed as a piece of the n-dimensional Clifford torus in the (2n-1)-sphere.

The proof is local. The fact that the immersion is minimal is expressed by the equation

$$\sum_{i} b_{ii}^{\lambda} = 0$$

which together with equation (6) implies that

$$\sum\limits_{i,j}b_{ij}^{j}b_{ik}^{i}=(n-1)(K-k)\delta_{jk}$$
 .

Hence $k \leq K$ and if k = K then the submanifold M is totally geodesic. Therefore we assume without loss of generality that k < K.

In the case where k < K we will actually prove a little more

than the theorem states: if the hypothesis that M be minimal is replaced by the weaker condition that its mean curvature vector be parallel, it still follows that M is flat.

Since the normal moving frame vectors are parallel, the mean curvature vector is parallel if and only if there exist constants c^{λ} such that

$$\sum_i b_{ii}^{\scriptscriptstyle \lambda} = c^{\scriptscriptstyle \lambda}$$
 .

On the other hand, equations (13) and (7) imply that

$$\sum_i b_{iij}^\gamma = 0$$
, and $\sum_k b_{iij}^k b_{kk}^\gamma = -\sum_k b_{ii}^\gamma b_{kkj}^\gamma$ if $i \neq k$.

Hence we conclude that

$$egin{aligned} \sum_{i,\lambda} b_{ii_1}^{ar{\prime}} b_{ii}^{ar{\prime}} &= -\sum\limits_{\substack{\lambda \ k
eq i}} b_{kk_J}^{ar{\prime}} b_{ii}^{ar{\prime}} &= \sum\limits_{\substack{\lambda \ k
eq i}} b_{kk_L}^{ar{\prime}} b_{iij}^{ar{\prime}} \ &= \sum\limits_{i,\lambda} c^{ar{\prime}} b_{iij}^{ar{\prime}} - \sum\limits_{i,\lambda} b_{ii}^{ar{\prime}} b_{ii_J}^{ar{\prime}} &= -\sum\limits_{i,\lambda} b_{ii}^{ar{\prime}} b_{iij}^{ar{\prime}} \;. \end{aligned}$$

It follows that $\sum_{i,\lambda} b_{iij}^{\lambda} b_{ii}^{\lambda} = 0$, and hence equation (15) implies that $e_j(x_i) = 0$. Now by equation (16) the differential forms θ_j^i vanish, proving that M is flat.

To finish the proof of the theorem, we notice that if M is minimal the principal normal curvature vectors (i.e., the b_{ii}^{γ} 's) are determined up to a rotation of e_{n+1} , \cdots , e_{2n-1} by equations (7) and (17). Since the b_{ii}^{γ} 's determine the θ_{i}^{γ} 's and $\theta_{j}^{i} = 0 = \theta_{\mu}^{\gamma}$, it follows from the classical rigidity theorem [1, p. 202] that locally there is at most one minimal flat n-dimensional submanifold of N, up to a rigid motion. Therefore M must be a piece of the Clifford torus, and the theorem is proven.

3. The global existence of asymptotic coordinates. If M is complete and simply connected, then any choice of signs in expression (11) determines a globally defined unit-length asymptotic vector field on M. If n unit-length asymptotic vector fields are linearly independent at one point, they are linearly independent everywhere.

THEOREM 3. If M is a complete simply connected riemannian manifold of constant curvature k isometrically immersed in a (2n-1)-dimensional riemannian manifold N of constant curvature K > k, then any n linearly independent unit-length asymptotic vector fields Z_1, Z_2, \dots, Z_n determine a global coordinate system whose coordinate vectors are the Z_i 's.

First we establish local existence. Because of the theorem of Frobenius, it suffices to show that the Lie bracket of any two asymptotic vector fields is zero. But

$$\begin{array}{l} \theta^{i}([x_{j}e_{j},\,x_{k}e_{k}]) \,=\, x_{j}e_{j}(\theta^{i}(x_{k}e_{k})) \,-\, x_{k}e_{k}(\theta^{i}(x_{j}e_{j})) \,-\, 2d\theta^{i}(x_{j}e_{j},\,x_{k}e_{k}) \\ &=\, x_{j}e_{j}(\theta^{i}(x_{k}e_{k})) \,-\, x_{k}e_{k}(\theta^{i}(x_{j}e_{j})) \,+\, 2\, \sum_{l}\theta^{i}_{l} \wedge\, \theta^{l}(x_{j}e_{j},\,x_{k}e_{k}) \\ &=\, \delta_{ik}x_{j}e_{j}(x_{k}) \,-\, \delta_{ij}x_{k}e_{k}(x_{j}) \,+\, \delta_{ij}x_{k}e_{k}(x_{j}) \,-\, \delta_{ik}x_{j}e_{j}(x_{k}) \\ &=\, 0 \,\,. \end{array}$$

In this derivation we have used equations (4) and (16). Since the asymptotic vectors are sums of $\pm x_i e_i$, local existence is proven.

To prove global existence, we let $\varphi_i(x, t)$, $x \in M$, $t \in R$ be the one-parameter group of transformations corresponding to Z_i . Since Z_i is a vector field of unit length, it follows from the theory of ordinary differential equations [4, p. 15] that $\varphi_i(x, t)$ is defined for all values of x and t. Let x_0 be a fixed point in M and define a function $F: \mathbf{R}^n \to M$ by

$$F(t_1, t_2, \dots, t_n) = \varphi_n(\varphi_{n-1}(\dots \varphi_2(\varphi_1(x_0, t_1), t_2), \dots), t_n)$$
.

Since the Lie bracket $[Z_i, Z_j]$ vanishes, the one-parameter groups φ_i and φ_j commute. Using this fact we can verify the following equation:

(18)
$$F(s_1 + t_1, \dots, s_n + t_n) = \varphi_n(\varphi_{n-1}(\dots, \varphi_1(F(s_1, \dots, s_n), t_1), \dots), t_n)$$
.

We claim that F is a covering map. Let x be a point in the manifold M and let U_x be an open neighborhood of x on which local asymptotic coordinates z_1, z_2, \dots, z_n exist, and we can assume that $z_1(x) = z_2(x) = \dots = z_n(x) = 0$. For $\delta > 0$, let

$$B_{\delta}(x) = \{ y \in U_x : |z_i(y)| < \delta \}$$

and choose ε so small that (z_1, z_2, \dots, z_n) give a diffeomorphism from $B_{2\varepsilon}(x)$ onto an open ball of radius 2ε in \mathbb{R}^n . Let \widetilde{x}_{α} , $\alpha \in A$, be the points in $F^{-1}(x)$, and let $B_{\varepsilon}(\widetilde{x}_{\alpha})$ denote the open ball of radius δ around x_{α} . To show that F is a covering map, it suffices to check the following facts:

- 1. $F \mid B_{2\varepsilon}(\widetilde{x}_{\alpha})$ is a diffeomorphism from $B_{2\varepsilon}(\widetilde{x}_{\alpha})$ onto $B_{2\varepsilon}(x)$ for $\alpha \in A$.
- 2. $B_{\varepsilon}(\widetilde{x}_{lpha})\cap B_{\varepsilon}(\widetilde{x}_{eta})=\phi \ \ ext{if} \ \ \widetilde{x}_{lpha}
 eq \ \widetilde{x}_{eta}$.
- 3. $\widetilde{y} \in F^{-1}(B_{\varepsilon}(x)) \Longrightarrow \widetilde{y} \in B_{\varepsilon}(\widetilde{x}_{\alpha})$ for some $\alpha \in A$.

To prove 1, we need only check that the local asymptotic coordinates define an inverse to $F|B_{2\varepsilon}(\widetilde{x}_{\alpha})$ using equation (18). 2 follows from 1, and 3 follows from the fact that $\widetilde{y} - (z_1(F(\widetilde{y})), \dots, z_n(F(\widetilde{y})))$ goes to x under F.

Thus F is a covering map, and since M is simply connected it is a diffeomorphism. Therefore F defines a global coordinate system whose coordinate vectors are the Z_i 's and Theorem 3 is proven.

A straightforward modification of the above proof establishes the existence of "principal coordinates" whose coordinate vectors are $x_1e_1, x_2e_2, \dots, x_ne_n$.

Since \mathbb{R}^n is not a covering space for the *n*-sphere when n > 1, we obtain the positive curvature analogue of our conjecture:

COROLLARY. A complete n-dimensional riemannian manifold of constant positive curvature k cannot be isometrically immersed in a (2n-1)-sphere of constant curvature K > k.

The corresponding local assertion is false, as Cartan proved in [3]. An n-sphere of constant curvature can be isometrically immersed in a (2n+1)-sphere of constant curvature by first embedding it in E^{n+1} in the usual fashion, and then immersing E^{n+1} in the (2n+1)-sphere as a flat torus.

If M is a complete simply connected space form as in Theorem 3, we will use the term "asymptotic surface" to denote a complete two-dimensional submanifold generated by two unit-length asymptotic vector fields. Every asymptotic surface possesses a global Tchebychef net ([7], p. 198) and it follows from the formula of Hazzidakkis that the integral of the Gaussian curvature over any parallelogram of the Tchebychef net is bounded in absolute value by 2π .

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UNIVERSITY OF CALIFORNIA, SANTA BARBARA