# MULTIPLIER HERMITIAN STRUCTURES ON KÄHLER MANIFOLDS 

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#### Abstract

The main purpose of this paper is to make a systematic study of a special type of conformally Kähler manifolds, called multiplier Hermitian manifolds, which we often encounter in the study of Hamiltonian holomorphic group actions on Kähler manifolds. In particular, we obtain a multiplier Hermitian analogue of Myers' Theorem on diameter bounds with an application (see [M5]) to the uniquness up to biholomorphisms of the "Kähler-Einstein metrics" in the sense of [M1] on a given Fano manifold with nonvanishing Futaki character.


## §1. Introduction

For a connected complete Kähler manifold ( $M, \omega_{0}$ ) of complex dimension $n$, let $\mathcal{K}$ denote the set of all Kähler forms on $M$ expressible as

$$
\begin{equation*}
\omega_{\varphi}:=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi \tag{1.1}
\end{equation*}
$$

for some real-valued smooth function $\varphi \in C^{\infty}(M)_{\mathbb{R}}$ on $M$. In this paper, we fix once for all a holomorphic vector field $X \neq 0$ on $M$, and $M$ is assumed to be compact except in Section 4 and in Theorem B below. Put

$$
\mathcal{K}_{X}:=\left\{\omega \in \mathcal{K} ; L_{X_{\mathbb{R}}} \omega=0\right\},
$$

where $X_{\mathbb{R}}:=X+\bar{X}$ denotes the real vector field on $M$ associated to the holomorphic vector field $X$. Let $\mathcal{H}_{X}$ denote the set of all $X_{\mathbb{R}^{-}}$-invariant functions $\varphi$ in $C^{\infty}(M)_{\mathbb{R}}$ such that $\omega_{\varphi}$ is in $\mathcal{K}_{X}$. Let $\mathcal{K}_{X} \neq \emptyset$, so that we may assume without loss of generality that

$$
\omega_{0} \in \mathcal{K}_{X} .
$$

In terms of a system $\left(z^{1}, z^{2}, \ldots, z^{n}\right)$ of holomorphic local coordinates on $M$ above, we write each Kähler form $\omega$ in $\mathcal{K}_{X}$ as

$$
\omega=\sqrt{-1} \sum_{\alpha, \beta} g_{\alpha \bar{\beta}} d z^{\alpha} \wedge d z^{\bar{\beta}}
$$

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Throughout this paper, we assume that $X$ is Hamiltonian, i.e., to each $\omega \in$ $\mathcal{K}_{X}$, we can associate a function $u_{\omega} \in C^{\infty}(M)_{\mathbb{R}}$ such that $X$ is expressible as

$$
\operatorname{grad}_{\omega}^{\mathbb{C}} u_{\omega}:=\frac{1}{\sqrt{-1}} \sum_{\alpha, \beta} g^{\bar{\beta} \alpha} \frac{\partial u_{\omega}}{\partial z^{\bar{\beta}}} \frac{\partial}{\partial z^{\alpha}}
$$

Then $u_{\omega}$ is an $X_{\mathbb{R}}$-invariant function, and the image $I_{X}$ of the function $u_{\omega}$ on $M$ is an interval in $\mathbb{R}$. For an arbitrary nonconstant real-valued smooth function

$$
\sigma: I_{X} \longrightarrow \mathbb{R}, \quad s \longmapsto \sigma(s)
$$

we define functions $\dot{\sigma}=\dot{\sigma}(s)$ and $\ddot{\sigma}=\ddot{\sigma}(s)$ on $I_{X}$ as the derivatives $\dot{\sigma}:=$ $(\partial / \partial s) \sigma$ and $\ddot{\sigma}:=\left(\partial^{2} / \partial s^{2}\right) \sigma$, respectively. We further define a function $\psi_{\omega} \in C^{\infty}(M)_{\mathbb{R}}$ by

$$
\begin{equation*}
\psi_{\omega}=\sigma\left(u_{\omega}\right) \tag{1.2}
\end{equation*}
$$

which is obviously $X_{\mathbb{R}}$-invariant. The function $\sigma$ is said to be strictly convex or weakly convex, according as $\ddot{\sigma}>0$ on $I_{X}$ or $\ddot{\sigma} \geq 0$ on $I_{X}$. By abuse of terminology, $\sigma$ is said to be convex if either $\sigma$ is strictly convex or $\sigma$ satisfies $\dot{\sigma} \leq 0 \leq \ddot{\sigma}$ on $I_{X}$.

Let $G:=\operatorname{Aut}^{0}(M)$ be the identity component of the group of all holomorphic automorphisms of $M$. Let
$Q:$ closure in $G$ of the real one-parameter group $\left\{\exp \left(t X_{\mathbb{R}}\right) ; t \in \mathbb{R}\right\}$.
Under the assumption of the compactness of $M$, we require the function $u_{\omega}$ to satisfy the equality $\int_{M} u_{\omega} \omega^{n}=0$, and applying the theory of moment maps to the action on $M$ of the compact torus $Q$, we obtain

$$
I_{X}=\left[\alpha_{X}, \beta_{X}\right]
$$

where both $\alpha_{X}:=\min _{M} u_{\omega}$ and $\beta_{X}:=\max _{M} u_{\omega}$ are independent of the choice of $\omega$ in $\mathcal{K}_{X}$. To each $\omega \in \mathcal{K}_{X}$, we associate the corresponding Laplacian $\square_{\omega}$ of the Kähler manifold $(M, \omega)$, and define an operator $\tilde{\square}_{\omega}$ on $C^{\infty}(M)_{\mathbb{R}}$ by

$$
\begin{equation*}
\tilde{\square}_{\omega}:=\sum_{\alpha, \beta} g^{\bar{\beta} \alpha} \frac{\partial^{2}}{\partial z^{\alpha} \partial z^{\bar{\beta}}}-\sum_{\alpha, \beta} g^{\bar{\beta} \alpha} \frac{\partial \psi_{\omega}}{\partial z^{\alpha}} \frac{\partial}{\partial z^{\bar{\beta}}}=\square_{\omega}+\sqrt{-1} \dot{\sigma}\left(u_{\omega}\right) \bar{X} \tag{1.3}
\end{equation*}
$$

The natural connection, induced by $\omega$, on the holomorphic tangent bundle $T M$ of $M$ is denoted by $\nabla$. To each $\omega$ in $\mathcal{K}_{X}$, we associate a conformally Kähler metric $\tilde{\omega}$ by

$$
\begin{equation*}
\tilde{\omega}:=\omega \exp \left(-\psi_{\omega} / n\right) \tag{1.4}
\end{equation*}
$$

which is called a multiplier Hermitian metric (of type $\sigma$ ). Here, a Hermitian form and the corresponding Hermitian metric are used interchangeably. The Hermitian metric $\tilde{\omega}$ naturally induces a Hermitian connection $\tilde{\nabla}: \mathcal{A}^{0}(T M) \rightarrow \mathcal{A}^{1}(T M)$ such that

$$
\tilde{\nabla}=\nabla-\frac{\partial \psi_{\omega}}{n} \mathrm{id}_{T M}
$$

where $\mathcal{A}^{q}(T M)$ denotes the sheaf of germs of $T M$-valued $C^{\infty} q$-forms on $M$. By abuse of terminology, the Ricci form of $(\tilde{\omega}, \tilde{\nabla})$ is denoted by $\operatorname{Ric}^{\sigma}(\omega)$. Then (see [L2], [K1], [Mat])

$$
\begin{equation*}
\operatorname{Ric}^{\sigma}(\omega)=\sqrt{-1} \bar{\partial} \partial \log \left(\tilde{\omega}^{n}\right)=\operatorname{Ric}(\omega)+\sqrt{-1} \partial \bar{\partial} \psi_{\omega} \tag{1.5}
\end{equation*}
$$

where we set $\operatorname{Ric}(\omega):=\sqrt{-1} \bar{\partial} \partial \log \left(\omega^{n}\right)$. For each nonnegative real number $\nu$, let $\mathcal{K}_{X}^{(\nu)}$ denote the set of all $\omega \in \mathcal{K}_{X}$ such that

$$
\operatorname{Ric}^{\sigma}(\omega) \geq \nu \omega
$$

i.e., $\operatorname{Ric}^{\sigma}(\omega)-\nu \omega$ is a positive semi-definite $(1,1)$-form on $M$. Now for $\varphi \in \mathcal{H}_{X}$, we set $\operatorname{Osc}(\varphi):=\max _{M} \varphi-\min _{M} \varphi$. Consider the set $\mathcal{S}^{\sigma}$ of all $\omega$ in $\mathcal{K}_{X}$ such that

$$
\operatorname{Ric}^{\sigma}(\omega)=t \omega+(1-t) \omega_{0} \quad \text { for some } t \in[0,1]
$$

Let $\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}$ be the analogue of Aubin's functional as in Appendix 1. The main purpose of this paper is to prove the following theorems (see Sections $3,4$ and 5$)$ :

Theorem A. (a) If $\dot{\sigma} \leq 0 \leq \ddot{\sigma}$ on $I_{X}$, then for each $\nu>0$, we have positive real constants $C_{0}, C_{1}, C_{1}^{\prime}, C_{1}^{\prime \prime}, C_{2}$ independent of the choice of the pair $\left(\omega_{\varphi}, \nu\right)$ such that

$$
\begin{equation*}
\operatorname{Osc}(\varphi) \leq C_{0}\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \omega_{\varphi}\right)+\frac{C(\nu)}{\nu} \tag{1.6}
\end{equation*}
$$

for all $\omega_{\varphi}$ in $\mathcal{K}_{X}^{(\nu)} \cap \mathcal{S}^{\sigma}$, where $C(\nu):=C_{1}+C_{1}^{\prime} \nu+C_{1}^{\prime \prime} e^{C_{2} / \nu}$.
(b) If $\sigma$ is strictly convex, then for each $\nu>0$, there exist positive real constants $C_{0}, C_{1}, C_{1}^{\prime}$ independent of the choice of the pair $\left(\omega_{\varphi}, \nu\right)$ such that, by setting $C(\nu):=C_{1}+C_{1}^{\prime} \nu$, we have the inequality (1.6) for all $\omega_{\varphi}$ in $\mathcal{K}_{X}^{(\nu)}$.

Theorem B. Let $\nu>0$ and $\omega \in \mathcal{K}_{X}^{(\nu)}$. Furthermore, let $(X, \sigma)$ be of Hamiltonian type (cf. Definition 4.1), where $\sigma$ is weakly convex. Let $p$ be an arbitrary point in zero $(X)$ or in $M$, according as (4.1.1) or (4.1.2) holds (cf. Section 4). Put $c:=\sup _{s \in I_{X}}|\sigma(s)|$. Then

$$
\operatorname{dist}_{\omega}(p, q) \leq \pi\{(2 n-1+4 c) / \nu\}^{1 / 2} \quad \text { for all } q \in M
$$

where $\operatorname{dist}_{\omega}(p, q)$ denotes the distance between $p$ and $q$ on the complete Kähler manifold $(M, \omega)$. Hence, the diameter $\operatorname{Diam}(M, \omega)$ of the complete Kähler manifold $(M, \omega)$ satisfies

$$
\begin{equation*}
\operatorname{Diam}(M, \omega) \leq 2^{\delta} \pi\{(2 n-1+4 c) / \nu\}^{1 / 2} \tag{1.7}
\end{equation*}
$$

where $\delta$ denotes 1 or 0 , according as (4.1.1) or (4.1.2) holds. In particular, if $\left|\psi_{\omega}\right|$ is bounded from above on $M$, then $M$ is compact and $\pi_{1}(M)$ is finite.

Let $\mathcal{E}_{X}^{\sigma}$ be the set of all $\omega \in \mathcal{K}_{X}$ such that $\operatorname{Ric}^{\sigma}(\omega)=\omega$. We also consider the subgroup $Z(X)$ of $G$ consisting of all $g \in G$ such that $\operatorname{Ad}(g) X=X$, and let $Z^{0}(X)$ denote the identity component of $Z(X)$. Then in Section 5, we apply Theorems A and B (Theorem B will be implicitly used) to showing that $\mathcal{E}_{X}^{\sigma}$ consists of a single $Z^{0}(X)$-orbit ${ }^{\dagger}$ under the assumption of convexity of $\sigma$.

Theorem C. Assume that $\sigma$ is convex. Then $\mathcal{E}_{X}^{\sigma}$ consists of a single $Z^{0}(X)$-orbit, whenever $\mathcal{E}_{X}^{\sigma}$ is nonempty.

This work is mainly motivated by the study of "Kähler-Einstein metrics" (cf. [M1]) which are closely related to the case where $\sigma(s)=-\log (s+$ $C)$ (cf. [M5]). Parts of this work were done during my stay in International Centre for Mathematical Sciences (ICMS), Edinburgh in 1997. I thank especially Professor Michael Singer who invited me to give lectures at ICMS on various subjects of Kähler-Einstein metrics.

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## §2. Notation, convention and preliminaries

To each $\omega \in \mathcal{K}_{X}$ as in the introduction, we associate a multiplier Hermitian metric $\tilde{\omega}$ in (1.4) and an operator $\tilde{\square}_{\omega}$ in (1.3). For complex-valued functions $u, v \in C^{\infty}(M)_{\mathbb{C}}$ on $M$, we put (cf. [L2], [K1], [Mat], [F1])

$$
\langle\langle u, v\rangle\rangle_{\tilde{\omega}}:=\int_{M} u \bar{v} e^{-\psi_{\omega}} \omega^{n}=\int_{M} u \bar{v} \tilde{\omega}^{n}
$$

In the arguments in [F1, p. 41], we replace the function $F$ by $\psi$. Then $\tilde{\square}_{\omega}$ is easily shown to be self-adjoint with respect to the above Hermitian inner product as follows:

Lemma 2.1.

$$
\left\langle\left\langle u, \tilde{\square}_{\omega} v\right\rangle\right\rangle_{\tilde{\omega}}=-\int_{M}(\bar{\partial} u, \bar{\partial} v)_{\omega} \tilde{\omega}^{n}=\left\langle\left\langle\tilde{\square}_{\omega} u, v\right\rangle\right\rangle_{\tilde{\omega}}, \quad u, v \in C^{\infty}(M)_{\mathbb{C}}
$$

Proof. $\left\langle\left\langle u, \tilde{\square}_{\omega} v\right\rangle\right\rangle_{\tilde{\omega}}$ is written as

$$
\begin{array}{rl}
\int_{M} u & u\left\{\overline{\square_{\omega} v}-\left(\bar{\partial} \psi_{\omega}, \bar{\partial} v\right)_{\omega}\right\} \tilde{\omega}^{n} \\
& =\int_{M}\left\{-\left(\bar{\partial}\left(u e^{-\psi_{\omega}}\right), \bar{\partial} v\right)_{\omega}-u\left(\bar{\partial} \psi_{\omega}, \bar{\partial} v\right)_{\omega} e^{-\psi_{\omega}}\right\} \omega^{n} \\
& =-\int_{M}(\bar{\partial} u, \bar{\partial} v)_{\omega} \tilde{\omega}^{n}
\end{array}
$$

while $\left\langle\left\langle\tilde{\square}_{\omega} u, v\right\rangle\right\rangle_{\tilde{\omega}}$ is just

$$
\begin{aligned}
\int_{M}\{ & \left.\square_{\omega} u-\left(\bar{\partial} u, \bar{\partial} \psi_{\omega}\right)_{\omega}\right\} v \tilde{\omega}^{n} \\
& =\int_{M}\left\{-\left(\bar{\partial} u, \bar{\partial}\left(e^{-\psi_{\omega}} v\right)\right)_{\omega}-v\left(\bar{\partial} u, \bar{\partial} \psi_{\omega}\right)_{\omega} e^{-\psi_{\omega}}\right\} \omega^{n} \\
& =-\int_{M}(\bar{\partial} u, \bar{\partial} v)_{\omega} \tilde{\omega}^{n}
\end{aligned}
$$

Hence Lemma 2.1 is immediate.
To an arbitrary smooth path $\phi=\left\{\varphi_{t} ; a \leq t \leq b\right\}$ in $\mathcal{H}_{X}$, we associate a one-parameter family of Kähler forms $\omega(t), a \leq t \leq b$, in $\mathcal{K}_{X}$ by

$$
\begin{equation*}
\omega(t):=\omega_{\varphi_{t}}=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi_{t}, \quad a \leq t \leq b \tag{2.2}
\end{equation*}
$$

Let $\dot{\varphi}_{t}$ denote the partial derivative $\partial \varphi_{t} / \partial t$ of $\varphi_{t}$ with respect to $t$. Next, by the notation (1.4) in the introduction, we consider the Hermitian form $\tilde{\omega}(t)$ on $M$ defined by

$$
\begin{equation*}
\tilde{\omega}(t):=\omega(t) \exp \left\{-\psi_{\omega(t)} / n\right\} \tag{2.3}
\end{equation*}
$$

Lemma 2.4. (a) $(\partial / \partial t) \tilde{\omega}(t)^{n}=\left(\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}\right) \tilde{\omega}(t)^{n}$.
(b) $\int_{M} \tilde{\omega}^{n}=V_{0}$ for all $\omega \in \mathcal{K}_{X}$, where $V_{0}:=\int_{M} \tilde{\omega}_{0}^{n}>0$.

Proof. (a) Recall that $u_{\omega(t)}$ is expressible as $u_{\omega_{0}}+\sqrt{-1} X \varphi_{t}$ (cf. [FM]). On the other hand, by $\varphi_{t} \in \mathcal{H}_{X}$, we see that $X_{\mathbb{R}} \varphi_{t}=0$. Hence,

$$
\begin{equation*}
u_{\omega(t)}=u_{\omega_{0}}-\sqrt{-1} \bar{X} \varphi_{t} \tag{2.5}
\end{equation*}
$$

Then we obtain the required equality as follows:

$$
\begin{aligned}
\frac{\partial}{\partial t} \tilde{\omega}(t)^{n} & =\frac{\partial}{\partial t}\left\{e^{-\psi_{\omega(t)}} \omega(t)^{n}\right\} \\
& =\left\{\square_{\omega(t)} \dot{\varphi}_{t}-\dot{\sigma}\left(u_{\omega(t)}\right) \frac{\partial}{\partial t} u_{\omega(t)}\right\} e^{-\psi_{\omega(t)}} \omega(t)^{n} \\
& =\left\{\square_{\omega(t)} \dot{\varphi}_{t}+\sqrt{-1} \dot{\sigma}\left(u_{\omega(t)}\right) \bar{X} \dot{\varphi}_{t}\right\} e^{-\psi_{\omega(t)}} \omega(t)^{n} \\
& =\left(\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}\right) \tilde{\omega}(t)^{n} .
\end{aligned}
$$

(b) In (a) above, we have $(\partial / \partial t) \int_{M} \tilde{\omega}(t)^{n}=\int_{M}\left(\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}\right) \tilde{\omega}(t)^{n}=$ $\left\langle\left\langle\tilde{\square}_{\omega} \dot{\varphi}_{t}, 1\right\rangle\right\rangle_{\tilde{\omega}}=0$ and hence the function $V: \mathcal{K}_{X} \rightarrow \mathbb{R}$ defined by

$$
V(\omega):=\int_{M} \tilde{\omega}^{n}, \quad \omega \in \mathcal{K}_{X}
$$

is constant along any smooth path in $\mathcal{K}_{X}$. Since every $\omega \in \mathcal{K}_{X}$ and $\omega_{0}$ are joined by the smooth path $t \omega_{0}+(1-t) \omega, 0 \leq t \leq 1$, in $\mathcal{K}_{X}$, we now conclude that $V$ is constant on $\mathcal{K}_{X}$, as required.

By $\left\langle\left\langle u, \tilde{\square}_{\omega} u\right\rangle\right\rangle_{\tilde{\omega}}=-\int_{M}(\bar{\partial} u, \bar{\partial} u)_{\omega} \tilde{\omega}^{n} \leq 0$, all eigenvalues of $-\tilde{\square}_{\omega}$ are nonnegative real numbers. Let $\lambda_{1}=\lambda_{1}(\tilde{\omega})>0$ be the first positive eigenvalue of $-\tilde{\square}_{\omega}$, and assume

$$
\mathcal{K}_{X}^{(\nu)} \neq \emptyset
$$

for some $\nu>0$. Then we have $c_{1}(M)>0$, and by the Kodaira vanishing theorem, we see that $0=h^{0,1}(M)=h^{1,0}(M)$. In particular, $G:=\operatorname{Aut}^{0}(M)$
is a linear algebraic group. The corresponding Lie algebra $\mathfrak{g}$ is just the space $H^{0}(M, \mathcal{O}(T M))$ of holomorphic vector fields on $M$. We now have a $\mathbb{C}$-linear isomorphism of vector spaces

$$
\begin{equation*}
\mathfrak{g}^{\omega} \cong \mathfrak{g}, \quad u \leftrightarrow \operatorname{grad}_{\omega}^{\mathbb{C}} u, \tag{2.6}
\end{equation*}
$$

where $\mathfrak{g}^{\omega}$ denotes the space of all $u \in C^{\infty}(M)_{\mathbb{C}}$, normalized by $\int_{M} u \tilde{\omega}^{n}=0$, such that the condition $\operatorname{grad}_{\omega}^{\mathbb{C}} \varphi \in \mathfrak{g}$ is satisfied. Recall that

FACT 2.7. (see for instance [M3]) For a real number $\nu>0$, let $\omega \in$ $\mathcal{K}_{X}^{(\nu)}$. Then
(a) $\lambda_{1}(\tilde{\omega}) \geq \nu$.
(b) If $\lambda_{1}(\tilde{\omega})=\nu$, then $\left\{u \in C^{\infty}(M)_{\mathbb{C}} ; \tilde{\square}_{\omega} u=-\lambda_{1}(\tilde{\omega}) u\right\}$ is a subspace of $\mathfrak{g}^{\omega}$.

Next, we consider the special case where the Kähler class of $\mathcal{K}_{X}$ is $2 \pi c_{1}(M)_{\mathbb{R}}$. In this case, to each $\omega \in \mathcal{K}_{X}$, we can associate a unique function $f_{\omega}$ in $C^{\infty}(M)_{\mathbb{R}}$ satisfying $\int_{M}\left(e^{f_{\omega}}-1\right) \omega^{n}=0$ and $\operatorname{Ric}(\omega)-\omega=\sqrt{-1} \partial \bar{\partial} f_{\omega}$. Put $c_{\omega}:=\int_{M} \tilde{\omega}^{n} / \int_{M} \omega^{n}=\int_{M} \tilde{\omega}_{0}^{n} / \int_{M} \omega_{0}^{n}$, which is independent of the choice of $\omega$ in $\mathcal{K}_{X}$. We now put

$$
\begin{equation*}
\tilde{f}_{\omega}:=f_{\omega}+\psi_{\omega}+\log c_{\omega}=f_{\omega}+\sigma\left(u_{\omega}\right)+\log c_{\omega} . \tag{2.8}
\end{equation*}
$$

Lemma 2.9. (a) $\operatorname{Ric}^{\sigma}(\omega)-\omega=\sqrt{-1} \partial \bar{\partial} \tilde{f}_{\omega}$.
(b) $\int_{M}\left(e^{\tilde{f_{\omega}}}-1\right) \tilde{\omega}^{n}=0$ for all $\omega \in \mathcal{K}_{X}$.

Proof. (a) follows immediately from (1.5), (2.8) and $\operatorname{Ric}(\omega)-\omega=\partial \bar{\partial} f_{\omega}$. As to (b), in view of (b) of Lemma 2.4, we obtain

$$
\int_{M} e^{\tilde{f}_{\omega}} \tilde{\omega}^{n}=\left(\int_{M} e^{f_{\omega}} e^{\psi_{\omega}} \tilde{\omega}^{n}\right) \frac{\int_{M} \tilde{\omega}_{0}^{n}}{\int_{M} \omega_{0}^{n}}=\left(\int_{M} e^{f_{\omega}} \omega^{n}\right) \frac{\int_{M} \tilde{\omega}^{n}}{\int_{M} \omega^{n}}=\int_{M} \tilde{\omega}^{n},
$$

as required.

## §3. Proof of Theorem A

Let $\omega \in \mathcal{K}_{X}$. In the definition of $\tilde{\omega}$ in (1.4), replacing $\sigma$ by $2 \sigma$, we consider volume forms $\operatorname{vol}_{\tilde{\omega}}$ and $\operatorname{vol}_{\tilde{\omega}_{0}}$ on $M$ by setting

$$
\operatorname{vol}_{\tilde{\omega}}:=\omega^{n} \exp \left\{-2 \sigma\left(u_{\omega}\right)\right\} \quad \text { and } \quad \operatorname{vol}_{\tilde{\omega}_{0}}:=\omega_{0}^{n} \exp \left\{-2 \sigma\left(u_{\omega_{0}}\right)\right\} .
$$

Put $V:=\int_{M} \operatorname{vol}_{\tilde{\omega}}=\int_{M} \operatorname{vol}_{\tilde{\omega}_{0}}$. Replacing $\sigma$ again by $2 \sigma$ in the definition of $\tilde{\square}_{\omega}$ in (1.3), we consider the operators $D_{\omega}$ and $D_{\omega_{0}}$ acting on $C^{\infty}(M)_{\mathbb{R}}$ by

$$
\begin{equation*}
D_{\omega}:=\square_{\omega}+2 \sqrt{-1} \dot{\sigma}\left(u_{\omega}\right) \bar{X} \quad \text { and } \quad D_{\omega_{0}}:=\square_{\omega_{0}}+2 \sqrt{-1} \dot{\sigma}\left(u_{\omega_{0}}\right) \bar{X} \tag{3.1}
\end{equation*}
$$

Note that a smooth function on $M$ is $X_{\mathbb{R}}$-invariant if and only if it is $Q$ invariant. Hence, we can write $\omega=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi$ for some $Q$-invariant function $\varphi$ in $\mathcal{H}_{X}$. Then we obtain

$$
\begin{equation*}
-\square_{\omega_{0}} \varphi<n \quad \text { and } \quad-\square_{\omega} \varphi>-n \tag{3.2}
\end{equation*}
$$

Now by (2.5), we have $\sqrt{-1} \bar{X} \varphi=u_{\omega_{0}}-u_{\omega}$. On the other hand, $\min _{M} u_{\omega_{0}}=$ $\min _{M} u_{\omega}=\alpha_{X}$ and $\max _{M} u_{\omega_{0}}=\max _{M} u_{\omega}=\beta_{X}$. In particular,

$$
\begin{equation*}
\max _{M}|\bar{X} \varphi|=\max _{M}|X \varphi| \leq \max _{M}|u|+\max _{M}\left|u_{0}\right| \leq 2 C_{3}, \tag{3.3}
\end{equation*}
$$

where $C_{3}:=\max \left\{\left|\alpha_{X}\right|,\left|\beta_{X}\right|\right\}$ is a positive constant independent of the choice of $\omega_{0}$ and $\omega$ in $\mathcal{K}_{X}$. Put $C_{4}:=\max _{s \in I_{X}}|\dot{\sigma}(s)|>0$. Then (3.1) and (3.2) above imply

$$
\begin{align*}
& -D_{\omega} \varphi=-\square_{\omega} \varphi-2 \sqrt{-1} \dot{\sigma}\left(u_{\omega}\right) \bar{X} \varphi \geq-k^{\prime}:=-n-4 C_{3} C_{4}  \tag{3.4}\\
& -D_{\omega_{0}} \varphi=-\square_{\omega_{0}} \varphi-2 \sqrt{-1} \dot{\sigma}\left(u_{\omega_{0}}\right) \bar{X} \varphi \leq k^{\prime \prime}:=n+4 C_{3} C_{4} \tag{3.5}
\end{align*}
$$

Let $\operatorname{Re} D_{\omega}:=\left(D_{\omega}+\bar{D}_{\omega}\right) / 2$ and $\operatorname{Re} D_{\omega_{0}}:=\left(D_{\omega_{0}}+\bar{D}_{\omega_{0}}\right) / 2$ denote respectively the real part of $D_{\omega}$ and $D_{\omega_{0}}$. Moreover, let $G_{\omega}(x, y)$ and $G_{\omega_{0}}(x, y)$ be the Green functions for the operators $\operatorname{Re} D_{\omega}$ and $\operatorname{Re} D_{\omega_{0}}$, respectively. More precisely,

$$
\left\{\begin{array}{l}
h(x)=V^{-1} \int_{M} h(y) \operatorname{vol}_{\tilde{\omega}}(y)+\int_{M} G_{\omega}(x, y)\left\{-\left(\operatorname{Re} D_{\omega}\right)(h)\right\}(y) \operatorname{vol}_{\tilde{\omega}}(y) \\
\int_{M} G_{\omega}(x, y) \operatorname{vol}_{\tilde{\omega}}(y)=0
\end{array}\right.
$$

hold for all $x \in M$ and $h \in C^{\infty}(M)_{\mathbb{R}}$, where equalities similar to the above hold also for the Green function $G_{\omega_{0}}(x, y)$ in terms of $\operatorname{vol} \tilde{\omega}_{0}$ and $\operatorname{Re} D_{\omega_{0}}$.

Proof of Theorem A. Assuming $\omega \in \mathcal{K}_{X}^{(\nu)}$, let $\ddot{\sigma} \geq 0$ on $I_{X}$. We further assume that one of the following holds:
(a) $\dot{\sigma} \leq 0$ on $I_{X}$ and $\omega \in \mathcal{S}^{\sigma}$;
(b) or $\sigma$ is strictly convex.

For the $Q$-action on $M$, take the averages $\tilde{G}_{\omega}(x, y), \tilde{G}_{\omega_{0}}(x, y)$ of the functions $G_{\omega}(x, y), G_{\omega_{0}}(x, y)$ respectively, i.e.,

$$
\left\{\begin{array}{l}
\tilde{G}_{\omega}(x, y):=\int_{Q} G_{\omega}(q \cdot x, y) d \mu(q)=\int_{Q} G_{\omega}(x, q \cdot y) d \mu(q) \\
\tilde{G}_{\omega_{0}}(x, y):=\int_{Q} G_{\omega_{0}}(q \cdot x, y) d \mu(q)=\int_{Q} G_{\omega_{0}}(x, q \cdot y) d \mu(q)
\end{array}\right.
$$

where $d \mu=d \mu(q)$ denotes the Haar measure for the compact group $Q$ of total volume 1. Let $K_{\omega}, K_{\omega_{0}}$ be the positive real numbers defined by

$$
-K_{\omega}=\inf _{x \neq y} \tilde{G}_{\omega}(x, y) \quad \text { and } \quad-K_{\omega_{0}}=\inf _{x \neq y} \tilde{G}_{0}(x, y)
$$

where the infimums are taken over all $(x, y) \in M \times M$ such that $x \neq y$. By writing $\omega=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi$ for some $Q$-invarant function $\varphi \in C^{\infty}(M)_{\mathbb{R}}$ as above, we first of all see the equality $\left(\operatorname{Re} D_{\omega_{0}}\right)(\varphi)=D_{\omega_{0}} \varphi$. Then by (3.5), we obtain

$$
\begin{align*}
\varphi(x) & =V^{-1} \int_{M} \varphi \operatorname{vol}_{\tilde{\omega}_{0}}+\int_{M}\left\{\tilde{G}_{\omega_{0}}(x, y)+K_{\omega_{0}}\right\}\left\{-\left(\operatorname{Re} D_{\omega_{0}}\right)(\varphi)\right\}(y) \operatorname{vol}_{\tilde{\omega}_{0}}(y)  \tag{3.6}\\
& \leq V^{-1} \int_{M} \varphi \operatorname{vol}_{\tilde{\omega}_{0}}+k^{\prime \prime} V K_{\omega_{0}}
\end{align*}
$$

On the other hand, by $\left(\operatorname{Re} D_{\omega}\right)(\varphi)=D_{\omega} \varphi$ and (3.4), we also obtain

$$
\begin{align*}
\varphi(x) & =V^{-1} \int_{M} \varphi \operatorname{vol}_{\tilde{\omega}}+\int_{M}\left\{\tilde{G}_{\omega}(x, y)+K_{\omega}\right\}\left\{-\left(\operatorname{Re} D_{\omega}\right)(\varphi)\right\}(y) \operatorname{vol}_{\tilde{\omega}}(y)  \tag{3.7}\\
& \geq V^{-1} \int_{M} \varphi \operatorname{vol}_{\tilde{\omega}}-k^{\prime} V K_{\omega}
\end{align*}
$$

Now by (3.6) and (3.7), we see that (cf. (A.1.1) in Appendix 1)

$$
\begin{align*}
\operatorname{Osc}(\varphi) & \leq V^{-1} \int_{M} \varphi\left(\operatorname{vol}_{\tilde{\omega}_{0}}-\operatorname{vol}_{\tilde{\omega}}\right)+\left(k^{\prime \prime} K_{\omega_{0}}+k^{\prime} K_{\omega}\right) V  \tag{3.8}\\
& \leq V^{-1} \mathcal{I}^{2 \sigma}\left(\omega_{0}, \omega\right)+\left(k^{\prime \prime} K_{\omega_{0}}+k^{\prime} K_{\omega}\right) V
\end{align*}
$$

where by [M3], there exist positive real constants $C^{\prime}, C^{\prime \prime}$ and $C_{2}$ independent of the choice of $\nu>0$ and $\omega$, such that

$$
\begin{equation*}
K_{\omega} \leq \nu^{-1}\left(C^{\prime}+C^{\prime \prime} e^{C_{2} / \nu}\right) \tag{3.9}
\end{equation*}
$$

under the assumption (a) above, while under the assumption (b) above, we also have (3.9) with $C^{\prime \prime}=0$. Now by Lemma A.1.5 and Proposition A. 1 in Appendix 1, we have

$$
\mathcal{I}^{2 \sigma}\left(\omega_{0}, \omega\right) \leq(m+2)\left(\mathcal{I}^{2 \sigma}-\mathcal{J}^{2 \sigma}\right)\left(\omega_{0}, \omega\right) \leq(m+2) e^{c}\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \omega\right)
$$

where $m:=n-1+b_{2 \sigma}$ by the notation in Lemma A.1.6 in Appendix 1, and we put $c:=\max _{s \in I_{X}}|\sigma(s)|=\max \left\{\left|\alpha_{X}\right|,\left|\beta_{X}\right|\right\}$ as in the introduction. Hence in view of (3.8) and (3.9), by setting $C(\nu):=C_{1}+C_{1}^{\prime} \nu+C_{1}^{\prime \prime} e^{C_{2} / \nu}$, we obtain

$$
\operatorname{Osc}(\varphi) \leq C_{0}\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \omega\right)+\frac{C(\nu)}{\nu}
$$

where $C_{1}:=k^{\prime} C^{\prime} V, C_{1}^{\prime}:=k^{\prime \prime} K_{\omega_{0}} V, C_{1}^{\prime \prime}:=k^{\prime} C^{\prime \prime} V$ and $C_{0}:=V^{-1}(m+2) e^{c}$ are positive real constants depending neither on the choice of $\omega$ nor on $\nu>0$, as required.

## §4. Proof of Theorem B

In this section, $M$ is not necessarily compact, and we fix a nonconstant real-valued function $\sigma: I_{X} \rightarrow \mathbb{R}$ which is weakly convex, i.e., $\ddot{\sigma} \geq 0$ on $I_{X}$. Let zero $(X)$ be the set of all points on $M$ at which the nonzero holomorphic vector field $X=\operatorname{grad}_{\omega}^{\mathbb{C}} u_{\omega}$ vanishes.

Definition 4.1. Under the above assumption of weak convexity of $\sigma$, we say that $(X, \sigma)$ is of Hamiltonian type, if one of the following two conditions is satisfied:

$$
\begin{align*}
& \operatorname{zero}(X) \neq \emptyset  \tag{4.1.1}\\
& \ddot{\sigma}(s)=0 \quad \text { for all } s \in I_{X} . \tag{4.1.2}
\end{align*}
$$

Remark 4.2. If $M$ is compact, then the assumption $\mathcal{K}_{X}^{(\nu)} \neq \emptyset$ in Theorem A implies that $c_{1}(M)>0$, and in particular $G$ is a linear algebraic group. Hence, in this case (4.1.1) automatically holds.

Proof of Theorem B. The proof is divided into the following three steps:
Step 1. In this step, we apply the arguments in [Mil] to the Kähler manifold $(M, \omega)$. Let $\zeta:[0, \ell] \rightarrow M$ be an arclength-parametrized geodesic with $\zeta(0)=p$. Put $\zeta(\ell)=q$, and consider the set $\Omega(M ; p, q)$ of all smooth
paths $\gamma:[0, \ell] \rightarrow M$ such that $\gamma(0)=p$ and $\gamma(\ell)=q$. Recall that the energy functional $E: \Omega(M ; p, q) \rightarrow \mathbb{R}$ is defined by

$$
E(\gamma):=\int_{0}^{\ell}\left\|\gamma_{*}(\partial / \partial t)\right\|_{\omega}^{2} d t, \quad \gamma \in \Omega(M ; p, q)
$$

Then $\zeta$ is a critical point of the functional $E$. Let $P_{k}=P_{k}(t), k=$ $1,2, \ldots, 2 n$, be parallel vector fields along $\zeta$ which are orthonormal everywhere along $\zeta$. Consider the complex structure $J: T M_{\mathbb{R}} \rightarrow T M_{\mathbb{R}}$ of the complex manifold $M$, where $T M_{\mathbb{R}}$ denotes the real tangent bundle of $M$. Then by $\nabla J=0$, we may assume that $P_{1}=\zeta_{*}(\partial / \partial t)$ and $P_{2}=J P_{1}$. Put $\hat{P}_{k}(t)=\sin (\pi t / \ell) P_{k}(t)$. Let $\operatorname{Hess}_{\zeta} E$ denote the Hessian of $E$ at $\zeta$. Then by setting $\hat{n}:=2 n-1$, we obtain

$$
\begin{equation*}
\frac{1}{2} \sum_{k=2}^{2 n}\left(\operatorname{Hess}_{\zeta} E\right)\left(\hat{P}_{k}, \hat{P}_{k}\right)=\int_{0}^{\ell} \sin ^{2}(\pi t / \ell)\left\{\frac{\hat{n} \pi^{2}}{\ell^{2}}-S_{\omega}\left(P_{1}, P_{1}\right)\right\} d t \tag{4.3.1}
\end{equation*}
$$

where $S_{\omega}$ denotes the Ricci tensor of the Kähler metric $\omega$, and is related to the Ricci form $\operatorname{Ric}(\omega)$ by $S_{\omega}\left(P_{1}, P_{1}\right)=\operatorname{Ric}(\omega)\left(P_{1}, J P_{1}\right)$.

Step 2. Fix an arbitrary $\tau \in[0, \ell]$. In a small open neighbourhood of $\zeta(\tau)$ in $M$, we choose a system $z=\left(z^{1}, z^{2}, \ldots, z^{n}\right)$ of holomorphic local coordinates centered at $\zeta(\tau)$ such that

$$
P_{1}(\tau)=\partial / \partial x^{1} \quad \text { and } \quad J P_{1}(\tau)=\partial / \partial y^{1}
$$

where we write each $z^{\alpha}$ as a sum $x^{\alpha}+\sqrt{-1} y^{\alpha}$ of the real part and the imaginary part, and the vector fields $\partial / \partial x^{\alpha}, \partial / \partial y^{\alpha}$ are taken in terms of the coordinates system $\left(x^{1}, \ldots, x^{n}, y^{1}, \ldots, y^{n}\right)$. Since
$\partial / \partial z^{\alpha}=\left(\partial / \partial x^{\alpha}-\sqrt{-1} \partial / \partial y^{\alpha}\right) / 2$ and $\partial / \partial z^{\bar{\beta}}=\left(\partial / \partial x^{\beta}+\sqrt{-1} \partial / \partial y^{\beta}\right) / 2$,
we observe that the coordinates system $z=\left(z^{1}, z^{2}, \ldots, z^{n}\right)$ can be chosen in such a way that $g_{\alpha \bar{\beta}}$ in the local expression of $\omega$ (cf. Section 1) satisfies

$$
\begin{equation*}
g_{\alpha \bar{\beta}}(\zeta(\tau))=\frac{1}{2} \delta_{\alpha \beta} \quad \text { and } \quad d g_{\alpha \bar{\beta}}(\zeta(\tau))=0 \tag{4.3.2}
\end{equation*}
$$

Let $\exp _{\zeta(\tau)}:\left(T M_{\mathbb{R}}\right)_{\zeta(\tau)} \rightarrow M$ denotes the exponential map at the point $\zeta(\tau)$ of the Kähler manifold $(M, \omega)$, and put $\xi(s):=\exp _{\zeta(\tau)}\left(s J P_{1}\right),-\varepsilon \leq s \leq \varepsilon$,
with a sufficiently small positive real number $\varepsilon$. Then in a neighbourhood of $\zeta(\tau)$,

$$
\left\{\begin{array}{l}
P_{1}(t)=\zeta_{*}(\partial / \partial t)=\partial / \partial x^{1}+O\left(|t-\tau|^{2}\right)  \tag{4.3.3}\\
\xi_{*}(\partial / \partial s)=\partial / \partial y^{1}+O\left(|s|^{2}\right)
\end{array}\right.
$$

where $O(w)$ denotes a function which is bounded by some constant times $w$. Now by our assumption, $X=\operatorname{grad}_{\omega}^{\mathbb{C}} u_{\omega}$ is a holomorphic vector field on $M$. Hence by the equality $\bar{\partial} X=0$ and (4.3.2), we obtain $\left(\partial / \partial z^{\overline{1}}\right)^{2}\left(u_{\omega}\right)_{\mid \zeta(\tau)}=0$ at the point $\zeta(\tau)$, and hence

$$
\left\{\begin{array}{l}
\left(\partial / \partial x^{1}\right)^{2}\left(u_{\omega}\right)_{\mid \zeta(\tau)}=\left(\partial / \partial y^{1}\right)^{2}\left(u_{\omega}\right)_{\mid \zeta(\tau)}  \tag{4.3.4}\\
\left(\partial^{2} / \partial x^{1} \partial y^{1}\right)\left(u_{\omega}\right)_{\mid \zeta(\tau)}=0
\end{array}\right.
$$

We now define a $C^{\infty} \operatorname{map} F:[-\varepsilon, \varepsilon] \times[0, \ell] \rightarrow M$ by sending each $(s, t) \in$ $[-\varepsilon, \varepsilon] \times[0, \ell]$ to $F(s, t):=\exp _{\zeta(t)}\left(s J P_{1}\right) \in M$. Put $\tilde{u}:=F^{*} u_{\omega}$ and $\tilde{\psi}:=$ $F^{*} \psi_{\omega}$ which are functions on $[-\varepsilon, \varepsilon] \times[0, \ell]$. Then by (1.2), we have $\tilde{\psi}=$ $\sigma(\tilde{u})$. Next by (4.3.3),

$$
\left\{\begin{array}{l}
(\partial / \partial t)(\tilde{u})_{\mid s=0}=\zeta^{*}\left\{\left(\partial / \partial x^{1}\right)\left(u_{\omega}\right)\right\}+O\left(|t-\tau|^{2}\right)  \tag{4.3.5}\\
(\partial / \partial s)(\tilde{u})_{\mid t=\tau}=\xi^{*}\left\{\left(\partial / \partial y^{1}\right)\left(u_{\omega}\right)\right\}+O\left(|s|^{2}\right)
\end{array}\right.
$$

in a neighbourhood of $(s, t)=(0, \tau)$. In view of (4.3.3), we differentiate the first line of (4.3.5) with respect to $t$ at $t=\tau$, while we differentiate the second line of (4.3.5) with respect to $s$ at $s=0$. Then, since $\tau \in[0, \ell]$ is arbitrary, the first line of (4.3.4) yields

$$
\begin{equation*}
(\partial / \partial t)^{2}(\tilde{u})=(\partial / \partial s)^{2}(\tilde{u}) \tag{4.3.6}
\end{equation*}
$$

when restricted to $\{0\} \times[0, \ell]$. Recall that $\nabla$ is the natural Hermitian connection associated to the Kähler metric $\omega$ (see Section 1). Since $P_{2}=$ $J P_{1}$ is parallel along the geodesic $\zeta$, and since $\xi$ is a geodesic, we obtain

$$
\left(\nabla_{\partial / \partial t} \partial / \partial s\right)_{\mid(s, t)=(0, \tau)}=\left(\nabla_{\partial / \partial s} \partial / \partial s\right)_{\mid(s, t)=(0, \tau)}=0,
$$

where the pullback $F^{*} \nabla$ is denoted also by $\nabla$ for simplicity. By combining this with (4.3.2) and $F_{*} \partial / \partial s_{\mid(s, t)=(0, \tau)}=\partial / \partial y^{1}$, we obtain

$$
F_{*}(\partial / \partial s)=\partial / \partial y^{1}+O\left(|s|^{2}+|t-\tau|^{2}\right) \quad \text { for }|s|^{2}+|t-\tau|^{2} \ll 1
$$

in a small neighbourhood of $\zeta(\tau)=F(0, \tau)$ in the image of $F$. Hence, together with the first line of (4.3.3), the second line of (4.3.4) implies

$$
\begin{equation*}
\left(\partial^{2} / \partial t \partial s\right)(\tilde{u})=0 \tag{4.3.7}
\end{equation*}
$$

when restricted to $\{0\} \times[0, \ell]$. For the time being, until the end of Step 2, we assume that (4.1.1) above holds. Then by $p=\zeta(0) \in \operatorname{Zero}(X)$, the function $u_{\omega}$ on $M$ has a critical value at $p$. In particular, $(\partial \tilde{u} / \partial s)(0,0)=0$. On the other hand, (4.3.7) shows that $\partial \tilde{u} / \partial s$ is constant along $\{0\} \times[0, \ell]$. Therefore,

$$
\begin{equation*}
(\partial \tilde{u} / \partial s)(0, t)=0 \quad \text { for all } t \in[0, \ell] \text {, if (4.1.1) holds. } \tag{4.3.8}
\end{equation*}
$$

Step 3. Let $\sigma$ be as in Definition 4.1, so that either (4.1.1) or (4.1.2) holds. Consider the function $\psi_{\omega}=\sigma\left(u_{\omega}\right)$. In view of (4.3.3), we see for all $\tau \in[0, \ell]$ the following:

$$
\begin{align*}
2 \sqrt{-1} & \left(\partial \bar{\partial} \psi_{\omega}\right)\left(P_{1}, J P_{1}\right)_{\mid \zeta(\tau)}  \tag{4.3.9}\\
& =2 \sqrt{-1}\left(\partial \bar{\partial} \psi_{\omega}\right)\left(\zeta_{*}(\partial / \partial t), \xi_{*}(\partial / \partial s)\right)_{\mid \zeta(\tau)} \\
& =\left\{\left(\partial / \partial x^{1}\right)^{2}\left(\psi_{\omega}\right)+\left(\partial / \partial y^{1}\right)^{2}\left(\psi_{\omega}\right)\right\}_{\mid \zeta(\tau)} \\
& =\frac{\partial^{2} \tilde{\psi}}{\partial t^{2}}(0, \tau)+\frac{\partial^{2} \tilde{\psi}}{\partial s^{2}}(0, \tau)
\end{align*}
$$

Consider the vector fields $Z_{1}:=\left(P_{1}-\sqrt{-1} J P_{1}\right) / 2$ and $\bar{Z}_{1}:=\left(P_{1}+\sqrt{-1}\right.$ $\left.J P_{1}\right) / 2$ along the geodesic $\zeta$. Since $(2 / \sqrt{-1}) \theta\left(Z_{1}, \bar{Z}_{1}\right)$ equals $\theta\left(P_{1}, J P_{1}\right)$ along the geodesic for every 2-form $\theta$ on $M$, and since $\operatorname{Ric}(\omega)+\sqrt{-1} \partial \bar{\partial} \psi_{\omega}=$ $\operatorname{Ric}^{\sigma}(\omega) \geq \nu \omega$, it now follows that

$$
\begin{aligned}
& \operatorname{Ric}(\omega)\left(P_{1}, J P_{1}\right)+\sqrt{-1}\left(\partial \bar{\partial} \psi_{\omega}\right)\left(P_{1}, J P_{1}\right)=\operatorname{Ric}^{\sigma}(\omega)\left(P_{1}, J P_{1}\right) \\
& \quad \geq \nu \omega\left(P_{1}, J P_{1}\right)=(2 \nu / \sqrt{-1}) \omega\left(Z_{1}, \bar{Z}_{1}\right)=\nu
\end{aligned}
$$

By plugging the expression (4.3.9) of $2 \sqrt{-1}\left(\partial \bar{\partial} \psi_{\omega}\right)\left(P_{1}, J P_{1}\right)_{\mid \zeta(\tau)}$ into the inequality just above, we see that the following inequality holds for all $\tau \in[0, \ell]:$

$$
\operatorname{Ric}(\omega)\left(P_{1}, J P_{1}\right)_{\mid \zeta(\tau)} \geq \nu-\frac{1}{2} \frac{\partial^{2} \tilde{\psi}}{\partial t^{2}}(0, \tau)-\frac{1}{2} \frac{\partial^{2} \tilde{\psi}}{\partial s^{2}}(0, \tau)
$$

By this together with (4.3.1), we obtain

$$
\begin{aligned}
& \frac{1}{2} \sum_{k=2}^{2 n}\left(\operatorname{Hess}_{\zeta} E\right)\left(\hat{P}_{k}, \hat{P}_{k}\right) \\
& \quad \leq \int_{0}^{\ell} \sin ^{2}(\pi t / \ell)\left\{\frac{\hat{n} \pi^{2}}{\ell^{2}}-\nu+\frac{1}{2} \frac{\partial^{2} \tilde{\psi}}{\partial t^{2}}(0, t)+\frac{1}{2} \frac{\partial^{2} \tilde{\psi}}{\partial s^{2}}(0, t)\right\} d t
\end{aligned}
$$

If (4.1.1) holds, then by (4.3.6) and (4.3.8), we see from $\tilde{\psi}=\sigma(\tilde{u})$ that

$$
\begin{aligned}
\frac{\partial^{2} \tilde{\psi}}{\partial s^{2}}(0, t) & =\left\{\dot{\sigma}(\tilde{u}) \frac{\partial^{2} \tilde{u}}{\partial s^{2}}+\ddot{\sigma}(\tilde{u})\left(\frac{\partial \tilde{u}}{\partial s}\right)^{2}\right\}_{\mid(0, t)}=\left\{\dot{\sigma}(\tilde{u}) \frac{\partial^{2} \tilde{u}}{\partial t^{2}}\right\}_{\mid(0, t)} \\
& \leq\left\{\dot{\sigma}(\tilde{u}) \frac{\partial^{2} \tilde{u}}{\partial t^{2}}+\ddot{\sigma}(\tilde{u})\left(\frac{\partial \tilde{u}}{\partial t}\right)^{2}\right\}_{\mid(0, t)}=\frac{\partial^{2} \tilde{\psi}}{\partial t^{2}}(0, t)
\end{aligned}
$$

where the inequality just above follows from the weak convexity of $\sigma$. On the other hand, if (4.1.2) holds, then again by (4.3.6)

$$
\frac{\partial^{2} \tilde{\psi}}{\partial s^{2}}(0, t)=\dot{\sigma}(\tilde{u}) \frac{\partial^{2} \tilde{u}}{\partial s^{2}}(0, t)=\dot{\sigma}(\tilde{u}) \frac{\partial^{2} \tilde{u}}{\partial t^{2}}(0, t)=\frac{\partial^{2} \tilde{\psi}}{\partial t^{2}}(0, t)
$$

In both cases, we obtain

$$
\frac{1}{2} \sum_{k=2}^{2 n}\left(\operatorname{Hess}_{\zeta} E\right)\left(\hat{P}_{k}, \hat{P}_{k}\right) \leq \int_{0}^{\ell} \sin ^{2}(\pi t / \ell)\left\{\frac{\hat{n} \pi^{2}}{\ell^{2}}-\nu+\frac{\partial^{2} \tilde{\psi}}{\partial t^{2}}(0, t)\right\} d t
$$

Let R.H.S. denote the right-hand side of this inequality. Then by taking integral by parts over and over again, we see that

$$
\begin{aligned}
\text { R.H.S. } & =\int_{0}^{\ell}\left\{\left(\frac{\hat{n} \pi^{2}}{\ell^{2}}-\nu\right) \sin ^{2}(\pi t / \ell)-\frac{\pi}{\ell} \frac{\partial \tilde{\psi}}{\partial t}(0, t) \sin (2 \pi t / \ell)\right\} d t \\
& =\int_{0}^{\ell}\left\{\left(\frac{\hat{n} \pi^{2}}{\ell^{2}}-\nu\right) \sin ^{2}(\pi t / \ell)+\frac{2 \pi^{2}}{\ell^{2}} \tilde{\psi}(0, t) \cos (2 \pi t / \ell)\right\} d t \\
& \leq \frac{2 \pi^{2} c}{\ell}+\int_{0}^{\ell}\left(\frac{\hat{n} \pi^{2}}{\ell^{2}}-\nu\right) \sin ^{2}(\pi t / \ell) d t=\frac{(\hat{n}+4 c) \pi^{2}}{2 \ell}-\frac{\ell \nu}{2} .
\end{aligned}
$$

Therefore, if $\ell>\pi\{(\hat{n}+4 c) / \nu\}^{1 / 2}$, then R.H.S. $<0$, and hence

$$
\sum_{k=2}^{2 n}\left(\operatorname{Hess}_{\zeta} E\right)\left(\hat{P}_{k}, \hat{P}_{k}\right)<0
$$

which shows that $\zeta:[0, \ell] \rightarrow M$ is not an arclength-minimizing geodesic. Thus, we obtain $\operatorname{dist}_{\omega}(p, q) \leq \pi\{(\hat{n}+4 c) / \nu\}^{1 / 2}$ for every $q \in M$, as required.

## §5. Proof of Theorem C

Fix $0<\alpha<1$. Let $\mathcal{H}_{X, 0}^{2, \alpha}$ denote the set of all $X_{\mathbb{R}^{-}}$invariant function $\varphi \in C^{2, \alpha}(M)_{\mathbb{R}}$ such that $\int_{M} \varphi \tilde{\omega}_{0}^{n}=0$ and that $\omega_{\varphi}$ is positive definite on $M$. Put

$$
\begin{equation*}
A(\varphi):=\tilde{\omega}_{\varphi}^{n} / \tilde{\omega}_{0}^{n}, \quad \varphi \in \mathcal{H}_{X, 0}^{2, \alpha} . \tag{5.1.1}
\end{equation*}
$$

For each $0 \leq k \in \mathbb{Z}$, we consider the space $C_{X, 0}^{k, \alpha}(M)_{\mathbb{R}}$ of all $X_{\mathbb{R}}$ invariant functions $\varphi$ in $C^{k, \alpha}(M)_{\mathbb{R}}$ such that $\int_{M} \varphi \tilde{\omega}_{0}^{n}=0$. Define $\Gamma: \mathcal{H}_{X, 0}^{2, \alpha} \times \mathbb{R} \rightarrow$ $C_{X, 0}^{0, \alpha}(M)_{\mathbb{R}}$ by setting (cf. [BM], [S1])

$$
\begin{equation*}
\Gamma(\varphi, t):=A(\varphi)-\left\{\frac{1}{V_{0}} \int_{M} \exp \left(-t \varphi+\tilde{f}_{\omega_{0}}\right) \tilde{\omega}_{0}^{n}\right\}^{-1} \exp \left(-t \varphi+\tilde{f}_{\omega_{0}}\right) \tag{5.1.2}
\end{equation*}
$$

for all $(\varphi, t) \in \mathcal{H}_{X, 0}^{2, \alpha} \times \mathbb{R}$, where $V_{0}$ is as in (b) of Lemma 2.4. Let $T$ be the set of all $t \in[0,1)$ for which the generalized Aubin's equation

$$
\begin{equation*}
\Gamma(\varphi, t)=0 \tag{5.1.3}
\end{equation*}
$$

admits a solution $\varphi=\varphi_{t}$ in $\mathcal{H}_{X, 0}^{2, \alpha}$. Note that $\varphi$ automatically belongs to $\mathcal{H}_{X}$. For such a solution $\varphi_{t}$, we set $\omega(t):=\omega_{\varphi_{t}}=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi_{t}$ as in (A.2.2) in Appendix 2. Then

$$
\begin{equation*}
\operatorname{Ric}^{\sigma}(\omega(t))=\omega_{0}+t \sqrt{-1} \partial \bar{\partial} \varphi_{t}=t \omega(t)+(1-t) \omega_{0} \tag{5.1.4}
\end{equation*}
$$

where $\tilde{\omega}(t)$ is as in (2.3). In particular, $\omega(t)$ sits in $\mathcal{K}_{X}^{\left(t^{\prime}\right)}$ for some $t^{\prime}$ which exceeds $t$. Suppose that $\Gamma(\hat{\varphi}, \hat{t})=0$ for some $(\hat{\varphi}, \hat{t}) \in \mathcal{H}_{X, 0}^{2, \alpha} \times[0,1)$. Then the Fréchet derivative $D_{\varphi} \Gamma: C_{X, 0}^{2, \alpha}(M)_{\mathbb{R}} \rightarrow C_{X, 0}^{0, \alpha}(M)_{\mathbb{R}}$ of $\Gamma$ at $(\hat{\varphi}, \hat{t})$ with respect to the factor $\varphi$ is given by

$$
\begin{equation*}
\left\{D_{\varphi} \Gamma_{\mid(\varphi, t)=(\hat{\varphi}, \hat{t})}\right\}(\eta):=A(\hat{\varphi})\left(\tilde{\square}_{\hat{\varphi}}+\hat{t}\right)\left(\eta-C_{\eta, \hat{\varphi}}\right), \quad \eta \in C_{X, 0}^{2, \alpha}(M)_{\mathbb{R}} \tag{5.1.5}
\end{equation*}
$$

where $C_{\eta, \hat{\varphi}}:=V_{0}^{-1} \int_{M} \eta \tilde{\omega}_{\hat{\varphi}}^{n}$ and $\tilde{\square}_{\hat{\varphi}}:=\tilde{\square}_{\tilde{\omega}_{\hat{\varphi}}}$. By (5.1.4) and Fact 2.7, $\hat{t}$ is less than the first positive eigenvalue of $-\tilde{\square}_{\hat{\varphi}}$. Hence, $D_{\varphi} \Gamma_{\mid(\varphi, t)}$ is invertible. Then by the implicit function theorem, we obtain

Theorem 5.1. If $(\hat{\varphi}, \hat{t}) \in \mathcal{H}_{X, 0}^{2, \alpha} \times[0,1)$ satisfies $\Gamma(\hat{\varphi}, \hat{t})=0$, then there exist $0<\varepsilon \ll 1$ and a smooth one-parameter family of functions $\left\{\varphi_{t} ; \hat{t}-\varepsilon<t<\hat{t}+\varepsilon\right\}$ in $\mathcal{H}_{X, 0}^{2, \alpha}$ satisfying $\varphi_{\hat{t}}=\hat{\varphi}$ such that $\varphi=\varphi_{t}$ is the unique solution of (5.1.3) for each $t$ under the condition $\|\varphi-\hat{\varphi}\|_{C^{2, \alpha}} \leq \varepsilon$. In particular, $T$ is an open subset of $[0,1)$.

Let $0 \leq a<b \leq 1$, and let $\varphi_{t}, a<t \leq b$, be a smooth one-parameter family of functions in $\mathcal{H}_{X, 0}^{2, \alpha}$ such that, for all $a<t \leq b$, we have

$$
\begin{equation*}
\Gamma\left(\varphi_{t}, t\right)=0 \tag{5.2.1}
\end{equation*}
$$

Then each $\varphi_{t}$ automatically belongs to $\mathcal{H}_{X}$. By setting $\omega(t):=\omega_{\varphi_{t}}$ as in the above, we obtain (5.1.4). We further put $\psi_{t}:=\psi_{\omega(t)}$ and $\tilde{f}_{t}:=\tilde{f}_{\omega(t)}$, where on the right-hand sides, we use the notation in the introduction and (2.8). Since $\operatorname{Ric}^{\sigma}(\omega(t))=\omega(t)+\sqrt{-1} \partial \bar{\partial} \tilde{f}_{t}$, and since $\omega(t)=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi_{t}$, the identity (5.1.4) implies

$$
\begin{equation*}
\tilde{f}_{t}=-(1-t) \varphi_{t}+C_{t} \tag{5.2.2}
\end{equation*}
$$

where $C_{t}$ is a real constant depending on $t$. By (5.1.1) and (a) of Lemma 2.4, we have $\partial A\left(\varphi_{t}\right) / \partial t=\left\{\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}\right\} A\left(\varphi_{t}\right)$. By differentiating (5.2.1) with respect to $t$, we obtain

$$
\begin{equation*}
\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}+t \dot{\varphi}_{t}+\varphi_{t}=\hat{C}_{t} \tag{5.2.3}
\end{equation*}
$$

for some real constant $\hat{C}_{t}$ depending on $t$. By (A.1.1) in Appendix 1 and by (b) of Proposition A. 2 in Appendix 2, we see from (5.2.2) and (5.2.3) the following:

$$
\begin{aligned}
& \frac{d}{d t} \mu^{\sigma}(\omega(t))=\int_{M}\left(\bar{\partial} \tilde{f}_{t}, \bar{\partial} \dot{\varphi}_{t}\right)_{\omega(t)} \tilde{\omega}(t)^{n}=-(1-t) \int_{M}\left(\bar{\partial} \varphi_{t}, \bar{\partial} \dot{\varphi}_{t}\right)_{\omega(t)} \tilde{\omega}(t)^{n} \\
& \quad=-(1-t) \frac{d}{d t}\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \omega(t)\right)=(1-t) \int_{M} \varphi_{t}\left\{\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}\right\} \tilde{\omega}(t)^{n} \\
& \quad=-(1-t) \int_{M}\left\{\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}+t \dot{\varphi}_{t}\right\}\left\{\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}\right\} \tilde{\omega}(t)^{n} \leq 0
\end{aligned}
$$

where in the last inequality, we apply (a) of Fact 2.7 to $\omega(t) \in \mathcal{K}_{X}^{(t)}$. Thus, for any $0 \leq a<b \leq 1$, we obtain

TheOrem 5.2. Along any smooth one-parameter family $\varphi_{t}, a<t \leq$ b, of solutions in $\mathcal{H}_{X}$ of (5.2.1), the corresponding $\omega(t):=\omega_{\varphi_{t}}=\omega_{0}+$ $\sqrt{-1} \partial \bar{\partial} \varphi_{t}$ satisfies

$$
\frac{d}{d t} \mu^{\sigma}(\omega(t))=-(1-t) \frac{d}{d t}\left(\mathcal{I}^{\sigma}-\mathcal{J}_{\sigma}\right)\left(\omega_{0}, \omega(t)\right) \leq 0, \quad a<t \leq b
$$

Given an element $\theta \in \mathcal{E}_{X}^{\sigma}$, we consider the set $T_{\theta}$ of all $\tau \in[0,1]$ such that there exists a smooth one-parameter family of solutions

$$
\begin{equation*}
\varphi_{t} \in \mathcal{H}_{X, 0}^{2, \alpha}, \quad \tau \leq t \leq 1 \tag{5.3.1}
\end{equation*}
$$

of (5.2.1) satisfying $\omega_{\varphi_{1}}=\theta$. Put $\tau_{\infty}:=\inf T_{\theta}$. Later in Theorem 5.6, we see that a slight perturbation of $\omega_{0}$ allows us to assume $\tau_{\infty}<1$. Under this assumption, we obtain

Lemma 5.3.2. Suppose that $\sigma$ is convex. Then we have the following:
(a) $\tau_{\infty}=0$.
(b) If $\sigma$ is furthermore strictly convex, then 0 belongs to $T_{\theta}$.

Proof. Take a sequence $\mathcal{S}:=\left\{\tau_{j}\right\}_{j=1}^{\infty}$ of points in the open interval $\left(\tau_{\infty}, 1\right]$ such that $\tau_{j}$ converges to $\tau_{\infty}$ as $j \rightarrow \infty$. Let

$$
\varphi_{\tau_{j}} \in \mathcal{H}_{X, 0}^{2, \alpha}, \quad j=1,2, \ldots
$$

be the corresponding solutions of (5.2.1) at $t=\tau_{j}$. For simplicity, $\varphi_{\tau_{j}}$ is denoted by $\varphi_{j}$, and we put $\omega^{(j)}:=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi_{j}$. In view of Theorem 5.1, the proof is reduced to showing that some subsequence of $\mathcal{S}$ is convergent in $C^{2, \alpha}(M)_{\mathbb{R}}$ assuming that either $\tau_{\infty}$ is positive or $\sigma$ is strictly convex. By Theorem 5.2,

$$
\begin{equation*}
\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \omega^{(j)}\right) \leq C_{3}, \quad \text { for all } j=1,2, \ldots \tag{5.3.3}
\end{equation*}
$$

where $C_{3}:=\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \theta\right)$. Since $\omega^{(j)}$ belongs to $\mathcal{K}_{X}^{\left(\tau_{j}\right)}$, and since $\tau_{j} \leq 1$ for all $j$, the combination of (1.6) and (5.3.3) implies

$$
\begin{aligned}
\left|\tau_{j} \operatorname{Osc} \varphi_{j}\right| & \leq \tau_{j} C_{0}\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \omega^{(j)}\right)+C\left(\tau_{j}\right) \\
& \leq C_{0} C_{3} \tau_{j}+C\left(\tau_{j}\right)=C_{0} C_{3} \tau_{j}+C_{1}+C_{1}^{\prime} \tau_{j}+C_{1}^{\prime \prime} e^{C_{2} / \tau_{j}} \\
& \leq C_{0} C_{3}+C_{1}+C_{1}^{\prime}+C_{1}^{\prime \prime} e^{C_{2} / \tau_{j}}
\end{aligned}
$$

where if $\sigma$ is strictly convex, we can set $C_{1}^{\prime \prime}=0$ by Theorem A. Note that the constant $C_{0}, C_{1}, C_{1}^{\prime}, C_{1}^{\prime \prime}, C_{2}, C_{3}$ are independent of the choice of $j$, and that $\left|\tau_{j} \operatorname{Osc} \varphi_{j}\right|, j=1,2, \ldots$, are bounded from above by $C_{0} C_{3}+$ $C_{1}+C_{1}^{\prime}+C_{1}^{\prime \prime} e^{C_{2} / \tau_{\infty}}$ or $C_{0} C_{3}+C_{1}+C_{1}^{\prime}$ according as $\tau_{\infty}$ is positive or $\sigma$ is strictly convex. Hence, in both of these cases, we have a positive constant $C_{4}$ independent of $j$ such that

$$
\left\|\tau_{j} \varphi_{j}\right\|_{C^{0}(M)} \leq C_{4}
$$

since we have $\varphi_{j}\left(p_{j}\right)=0$ at some point $p_{j} \in M$ in view of the identity $\int_{M} \varphi_{j} \tilde{\omega}_{0}^{n}=0$. Moreover, for all $j$,

$$
\begin{aligned}
& \omega_{\varphi_{j}}^{n}=A\left(\varphi_{j}\right) \exp \left\{\psi_{\omega^{(j)}}-\psi_{\omega_{0}}\right\} \omega_{0}^{n} \\
& =\left(\frac{1}{V_{0}} \int_{M} \exp \left(-\tau_{j} \varphi_{j}+\tilde{f}_{\omega_{0}}\right) \tilde{\omega}_{0}^{n}\right)^{-1} \exp \left\{-\tau_{j} \varphi_{j}+\tilde{f}_{\omega_{0}}+\psi_{\omega^{(j)}}-\psi_{\omega_{0}}\right\} \omega_{0}^{n},
\end{aligned}
$$

where $\left|\psi_{\omega^{(j)}}\right|, j=1,2, \ldots$, on $M$ are bounded from above by

$$
c:=\max _{s \in\left[\ell_{0}, \ell_{1}\right]}|\sigma(s)| .
$$

Therefore, we have a positive constant $C_{5}$ independent of $j$ such that

$$
\left\|\varphi_{j}\right\|_{C^{0}(M)} \leq C_{5}, \quad \text { for all } j
$$

Then by standard arguments for complex Monge-Ampère equations (see for instance $[\mathrm{M} 4]), \mathcal{S}$ is uniformly bounded in $C^{k, \alpha}(M)_{\mathbb{R}}$ for all $0 \leq k \in \mathbb{Z}$, and consequently some subsequence of $\mathcal{S}$ is convergent in $C^{2, \alpha}(M)_{\mathbb{R}}$, as required.

Remark 5.3.4. In (b) of Lemma 5.3.2, even if $\sigma$ is not strictly convex, we obtain $0 \in T_{\theta}$ just by the convexity of $\sigma$. This can be seen as follows: For each $r \in \mathbb{R}$, we put

$$
\sigma_{r}(s):=\sigma(s)-r \log \left(s-\alpha_{X}+1\right), \quad s \in I_{X}
$$

where $\alpha_{X}$ and $I_{X}$ are as in the introduction. If $r$ is positive, then $\ddot{\sigma}_{r}(s)>0$ for all $s \in I_{X}$, and $\sigma_{r}$ is strictly convex. In the arguments above, replacing $\sigma$ by $\sigma_{r}$, we put $\psi_{\omega}^{[r]}:=\sigma_{r}\left(u_{\omega}\right)$ and $\tilde{\omega}^{[r]}:=\omega \exp \left(-\psi_{\omega}^{[r]} / n\right)$ for all $\omega \in \mathcal{K}_{X}$. For each $\varphi \in \mathcal{H}_{X, 0}^{2, \alpha}$, we put

$$
\left\{\begin{array}{l}
A^{[r]}(\varphi)=\frac{\left(\tilde{\omega}_{\varphi}^{[r]}\right)^{n}}{\left(\tilde{\omega}_{0}^{[r]}\right)^{n}}=\frac{\omega_{\varphi}^{n} \exp \left(-\psi_{\omega_{\varphi}}^{[r]}\right)}{\omega_{0}^{n} \exp \left(-\psi_{\omega_{0}}^{[r]}\right)} \\
\varphi^{[r]}=\varphi-\frac{1}{V_{r}} \int_{M} \varphi\left(\tilde{\omega}_{0}^{[r]}\right)^{n}
\end{array}\right.
$$

where $V_{r}:=\int_{M}\left(\tilde{\omega}_{0}^{[r]}\right)^{n}$. Put $\tilde{f}_{\omega}^{[r]}:=f_{\omega}+\psi_{\omega}^{[r]}+\log \left\{\int_{M}\left(\tilde{\omega}_{0}^{[r]}\right)^{n} / \int_{M} \omega_{0}^{n}\right\}$ for all $\omega \in \mathcal{K}_{X}$. Let us define a mapping $\tilde{\Gamma}: \mathcal{H}_{X, 0}^{2, \alpha} \times \mathbb{R}^{2} \rightarrow C_{0}^{0, \alpha}(M)_{\mathbb{R}}$ by

$$
\begin{aligned}
\tilde{\Gamma}(\varphi, t, r):= & \frac{\left(\tilde{\omega}_{0}^{[r]}\right)^{n}}{\tilde{\omega}_{0}^{n}}\left\{A^{[r]}(\varphi)\right. \\
& \left.-\left(\frac{1}{V_{r}} \int_{M} \exp \left(-t \varphi^{[r]}+\tilde{f}_{\omega_{0}}^{[r]}\right)\left(\tilde{\omega}_{0}^{[r]}\right)^{n}\right)^{-1} \exp \left(-t \varphi^{[r]}+\tilde{f}_{\omega_{0}}^{[r]}\right)\right\}
\end{aligned}
$$

where $(\varphi, t, r) \in \mathcal{H}_{X, 0}^{2, \alpha} \times \mathbb{R}^{2}$. Suppose that $\tilde{\Gamma}(\hat{\varphi}, \hat{t}, 0)=0$ for some $(\hat{\varphi}, \hat{t}) \in$ $\mathcal{H}_{X, 0}^{2, \alpha} \times[0,1)$. Then $\Gamma(\hat{\varphi}, \hat{t})=0$, and the Fréchet derivative $D_{\varphi} \tilde{\Gamma}: C_{X, 0}^{2, \alpha}(M)_{\mathbb{R}}$ $\rightarrow C_{X, 0}^{0, \alpha}(M)_{\mathbb{R}}$ of $\tilde{\Gamma}$ with respect to $\varphi$ is written as

$$
\begin{equation*}
D_{\varphi} \tilde{\Gamma}_{\mid(\varphi, t, r)=(\hat{\varphi}, \hat{t}, 0)}=D_{\varphi} \Gamma_{\mid(\varphi, t)=(\hat{\varphi}, \hat{t})}, \tag{5.3.5}
\end{equation*}
$$

which is invertible. Hence, in a neighbourhood $U$ of $(\hat{t}, 0)$ in $\mathbb{R}^{2}$, the solution $\hat{\varphi}$ of $\tilde{\Gamma}(\varphi, t, r)=0$ at $(t, r)=(\hat{t}, 0)$ extends uniquely to

$$
\hat{\varphi}_{t, r} \in C_{X, 0}^{2, \alpha}(M)_{\mathbb{R}}, \quad(t, r) \in U
$$

depending on $(t, r)$ continuously and satisfying $\tilde{\Gamma}\left(\hat{\varphi}_{t, r}, t, r\right)=0$ for all $(t, r) \in$ $U$ with $\hat{\varphi}_{\hat{t}, 0}=\hat{\varphi}$. As in Theorem 5.6 proved later, a slight perturbation of $\omega_{0}$ (see (5.5.3)) allows us to assume that, for a sufficiently small $\delta>0$, a smooth two-parameter family of functions

$$
\begin{equation*}
\varphi_{t, r} \in C_{X, 0}^{2, \alpha}(M)_{\mathbb{R}}, \quad(t, r) \in[1-\delta, 1] \times[0, \delta] \tag{5.3.6}
\end{equation*}
$$

exists satisfying $\theta=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi_{1,0}$ and $\tilde{\Gamma}\left(\varphi_{t, r}, t, r\right)=0$ for all $(t, r) \in$ $[1-\delta, 1] \times[0, \delta]$. Then by Lemma 5.3.2 and Theorem 5.1, we see that (5.3.6) uniquely extends to a continuous family, denoted by the same notation, of functions

$$
\begin{equation*}
\varphi_{t, r} \in C_{X, 0}^{2, \alpha}(M)_{\mathbb{R}}, \quad(0,0) \neq(t, r) \in[0,1] \times[0, \delta] \tag{5.3.7}
\end{equation*}
$$

satisfying $\tilde{\Gamma}\left(\varphi_{t, r}, t, r\right)=0$ for all $(0,0) \neq(t, r) \in[0,1] \times[0, \delta]$. On the other hand, by Appendix 4, there exists a unique element $\gamma_{r}$ of $\mathcal{H}_{X, 0}^{2, \alpha}$ such that

$$
\operatorname{Ric}^{\sigma_{r}}\left(\omega_{\gamma_{r}}\right)=\omega_{0}
$$

Then for each $r \in[0, \delta]$, the equation $\tilde{\Gamma}(\varphi, 0, r)=0$ in $\varphi \in \mathcal{H}_{X, 0}^{2, \alpha}$ has a unique solution $\varphi=\gamma_{r}$. In view of (5.3.7) above, this implies

$$
\varphi_{0, r}=\gamma_{r}, \quad 0<r \leq \delta
$$

By (5.3.5) applied to $(\hat{\varphi}, \hat{t})=\left(\gamma_{0}, 0\right)$, letting $\delta$ be smaller if necessary, we see from the inverse function theorem that the solution $\varphi=\gamma_{r}$ of the equation $\tilde{\Gamma}(\varphi, 0, r)=0$ in $\varphi \in \mathcal{H}_{X, 0}^{2, \alpha}$ for $0 \leq r \leq \delta$ uniquely extends to a continuous family of functions

$$
\begin{equation*}
\varphi_{t, r}^{\prime} \in C_{X, 0}^{2, \alpha}(M)_{\mathbb{R}}, \quad(t, r) \in[0, \delta] \times[0, \delta] \tag{5.3.8}
\end{equation*}
$$

satisfying $\varphi_{0, r}^{\prime}=\gamma_{r}$ for $0 \leq r \leq \delta$ and $\tilde{\Gamma}\left(\varphi_{t, r}^{\prime}, t, r\right)=0$ for all $(t, r) \in$ $[0, \delta] \times[0, \delta]$. Comparing (5.3.7) and (5.3.8), we obtain $\varphi_{t, r}=\varphi_{t, r}^{\prime}$ for all $(0,0) \neq(t, r) \in[0, \delta] \times[0, \delta]$. In particular, $\varphi_{t, 0}\left(=\varphi_{t, 0}^{\prime}\right)$ converges to $\gamma_{0}$ $\left(=\varphi_{0,0}^{\prime}\right)$ in $C^{2, \alpha}$ as $t$ tends to 0 . Thus, $0 \in T_{\theta}$.

By combining Lemma 5.3.2 and Remark 5.3.4, we obtain

Theorem 5.3. If $\sigma$ is convex, then by a slight perturbation of $\omega_{0}$ as in (5.5.3), we have the situation that 0 belongs to $T_{\theta}$.

Take an arbitrary $Z^{0}(X)$-orbit $\mathbf{O}$ in $\mathcal{E}_{X}^{\sigma}$, which is a connected component of $\mathcal{E}_{X}^{\sigma}$ by Proposition A. 5 in Appendix 5. Define a nonnegative $C^{\infty}$ function $\iota: \mathbf{O} \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
\iota(\theta):=\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \theta\right), \quad \theta \in \mathbf{O} \tag{5.4.1}
\end{equation*}
$$

For $\tilde{\mathcal{E}}_{X}^{\sigma}:=\left\{\lambda \in \mathcal{H}_{X} ; A(\lambda)=\exp \left(-\lambda+\tilde{f}_{0}\right)\right\}$, we have a natural identification $\tilde{\mathcal{E}}_{X}^{\sigma} \simeq \mathcal{E}_{X}^{\sigma}$ by sending each $\lambda \in \tilde{\mathcal{E}}_{X}^{\sigma}$ to $\omega_{\lambda} \in \mathcal{E}_{X}^{\sigma}$. Then the preimage, denoted by $\tilde{\mathbf{O}}$, of $\mathbf{O}$ under the identification $\tilde{\mathcal{E}}_{X}^{\sigma} \simeq \mathcal{E}_{X}^{\sigma}$ is written as

$$
\begin{equation*}
\tilde{\mathbf{O}}=\left\{\lambda \in C^{2, \alpha}(M)_{\mathbb{R}} ; A(\lambda)=\exp \left(-\lambda+\tilde{f}_{0}\right) \text { and } \omega_{\lambda} \in \mathbf{O}\right\} \tag{5.4.2}
\end{equation*}
$$

Moreover, we put $\mathbf{O}^{\Gamma}:=\left\{\lambda \in \mathcal{H}_{X, 0}^{2, \alpha} ; \Gamma(\lambda, 1)=0\right.$ and $\left.\omega_{\lambda} \in \mathbf{O}\right\}$. Then $\mathbf{O}^{\Gamma}$, $\mathbf{O}$ and $\tilde{\mathbf{O}}$ are identified by

$$
\begin{equation*}
\mathbf{O}^{\Gamma} \simeq \mathbf{O} \simeq \tilde{\mathbf{O}}, \quad \lambda \leftrightarrow \omega_{\lambda} \leftrightarrow \lambda+\log \left\{\frac{1}{V_{0}} \int_{M} \exp \left(-\lambda+\tilde{f}_{\omega_{0}}\right) \tilde{\omega}_{0}^{n}\right\} \tag{5.4.3}
\end{equation*}
$$

Theorem 5.4. (a) Assume that $\sigma$ is convex. Then the function $\iota$ : $\mathbf{O} \rightarrow \mathbb{R}$ is a proper map, and hence its absolute minimum is always attained at some point of the orbit $\mathbf{O}$.
(b) Let $\mathfrak{k}^{\theta}$ be as in (A.5.3) of Appendix 5. By (5.4.3), to each $\theta \in \mathbf{O}$, we associate a unique $\lambda_{\theta} \in \tilde{\mathbf{O}}$ such that $\theta=\omega_{\lambda_{\theta}}$. Then the following are equivalent:
(i) $\theta$ is a critical point for $\iota$;
(ii) $\int_{M} \lambda_{\theta} v \tilde{\theta}^{n}=0$ for all $v \in \mathfrak{k}^{\theta}$.

Proof of (a). For each positive real number $r$, we put $\mathbf{O}_{r}^{\Gamma}:=\{\lambda \in$ $\left.\mathbf{O}^{\Gamma} ; \iota\left(\omega_{\lambda}\right) \leq r\right\}$. By the same argument as in the proof of Lemma 5.3.2
(see the arguments after (5.3.3)), there exists a constant $C_{5}=C_{5}(r)>0$ independent of the choice of $\lambda$ in $\mathbf{O}_{r}^{\Gamma}$ such that

$$
\|\varphi\|_{C^{2, \alpha}(M)} \leq C_{5}
$$

holds for all $\varphi \in \mathbf{O}_{r}^{\Gamma}$, where in this proof we use the inequality $\iota\left(\omega_{\varphi}\right) \leq r$ in place of (5.3.3). Now, (a) is straightforward.

Proof of (b). Let $\lambda=\lambda(t),-\varepsilon<t<\varepsilon$, be a smooth one-parameter family in $\tilde{\mathbf{O}}$ such that $\lambda(0)=\lambda_{\theta}$. Then $\omega_{\lambda(0)}=\theta$. In view of (A.1.1) in Appendix 1,

$$
\begin{align*}
& \left\{\frac{d}{d t} \iota(\omega(t))\right\}_{\mid t=0}=\int_{M}(\bar{\partial} \lambda(0), \bar{\partial} \dot{\lambda}(0))_{\theta} \tilde{\theta}^{n}  \tag{5.4.4}\\
& \quad=-\int_{M} \lambda(0)\left(\tilde{\square}_{\theta} \dot{\lambda}(0)\right) \tilde{\theta}^{n}=\int_{M} \lambda(0) \dot{\lambda}(0) \tilde{\theta}^{n}
\end{align*}
$$

where we have $\dot{\lambda}(0) \in \mathfrak{k}^{\theta}\left(=T_{\theta}\left(\tilde{\mathcal{E}}_{X}^{\sigma}\right)=T_{\theta}(\tilde{\mathbf{O}})\right)$ by (A.5.6) and (b) of Proposition A. 5 of Appendix 5. The equivalence of (i) and (ii) is now immediate.

We now consider the Hessian of $\iota: \mathbf{O} \rightarrow \mathbb{R}$ at a critical point $\theta=$ $\omega_{\lambda_{\theta}} \in \mathbf{O}$ of $\iota$, where $\lambda_{\theta} \in \tilde{\mathbf{O}}$ is as in (b) of Theorem 5.4. Let $\varphi_{s, t},(s, t) \in$ $[-\varepsilon, \varepsilon] \times[-\varepsilon, \varepsilon]$, be a smooth two-parameter family of functions in $\tilde{\mathbf{O}}$ such that $\lambda_{\theta}=\varphi_{0,0}$. Put $\omega_{s, t}:=\omega_{\varphi_{s, t}}$. Then

$$
\varphi^{\prime}:={\left.\frac{\partial \varphi_{s, t}}{\partial s} \quad \right\rvert\,(s, t)=(0,0)} \quad \text { and } \quad \varphi^{\prime \prime}:={\frac{\partial \varphi_{s, t}}{\partial t}}_{\mid(s, t)=(0,0)}
$$

are regarded as elements in $T_{\theta}(\mathbf{O})\left(=T_{\theta}\left(\mathcal{E}_{X}^{\sigma}\right)\right)$ by the isomorphism $T_{\theta}\left(\mathcal{E}_{X}^{\sigma}\right) \cong$ $\mathfrak{k}^{\theta}$ in (A.5.6) of Appendix 5. By differentiating $A\left(\varphi_{s, t}\right)=\exp \left(-\varphi_{s, t}+\tilde{f}_{\omega_{0}}\right)$ with respect to $t$, we obtain

$$
\begin{equation*}
\tilde{\square}_{s, t}\left(\frac{\partial \varphi_{s, t}}{\partial t}\right)=-\frac{\partial \varphi_{s, t}}{\partial t} \tag{5.5.1}
\end{equation*}
$$

where we put $\psi_{s, t}:=\psi_{\omega_{s, t}}, u_{s, t}:=u_{\omega_{s, t}}, \square_{s, t}:=\square_{\omega_{s, t}}, \tilde{\square}_{s, t}:=\tilde{\square}_{\omega_{s, t}}$ for simplicity. Differentiating (5.5.1) with respect to $s$ at the origin $(s, t)=$ $(0,0)$, we obtain

$$
\begin{equation*}
\left(\partial \bar{\partial} \varphi^{\prime}, \partial \bar{\partial} \varphi^{\prime \prime}\right)_{\theta}-\ddot{\sigma}\left(u_{\theta}\right)\left(\bar{X} \varphi^{\prime}\right)\left(\bar{X} \varphi^{\prime \prime}\right)=\left(\tilde{\square}_{\theta}+1\right) \partial_{s} \partial_{t} \varphi(0) \tag{5.5.2}
\end{equation*}
$$

Here, we used the identities $\tilde{\square}_{s, t}=\square_{s, t}+\sqrt{-1} \dot{\sigma}\left(u_{s, t}\right) \bar{X}, u_{s, t}=u_{\omega_{0}}-$ $\sqrt{-1} \bar{X} \varphi_{s, t}$ (see (1.3) and (2.5)) and we put

$$
\partial_{s} \partial_{t} \varphi(0):=\left(\frac{\partial^{2} \varphi_{s, t}}{\partial s \partial t}\right)_{\mid(s, t)=(0,0)}
$$

Since $\tilde{\square}_{\theta} \varphi^{\prime}=-\varphi^{\prime}$, by comparing the identity (5.5.2) with (A.3.1) in Appendix 3 applied to $(\omega, \zeta, v)=\left(\theta, \varphi^{\prime}, \varphi^{\prime \prime}\right)$, we obtain

$$
\begin{equation*}
\left(\tilde{\square}_{\theta}+1\right)\left(\partial \varphi^{\prime}, \partial \varphi^{\prime \prime}\right)_{\theta}=\left(\tilde{\square}_{\theta}+1\right) \partial_{s} \partial_{t} \varphi(0) \tag{5.5.3}
\end{equation*}
$$

Next, we put $\iota_{s, t}:=\iota\left(\omega_{s, t}\right)$ for simplicity. Then by the same computation as in (5.4.4), we obtain the identity

$$
\frac{\partial \iota_{s, t}}{\partial t}=\int_{M} \varphi_{s, t} \frac{\partial \varphi_{s, t}}{\partial t} \tilde{\omega}_{s, t}^{n}
$$

In view of $\lambda_{\theta}=\varphi_{0,0}$ and (a) of Lemma 2.4, we further differentiate this with respect to $s$ at the origin $(s, t)=(0,0)$. Then the Hessian $(H e s s ~ \iota)_{\theta}$ of $\iota$ at $\theta$ is given by

$$
\begin{align*}
& \left.(\text { Hess } \iota)_{\theta}\left(\varphi^{\prime}, \varphi^{\prime \prime}\right)=\frac{\partial^{2} \iota_{s, t}}{\partial s \partial t} \right\rvert\,(s, t)=(0,0)  \tag{5.5.4}\\
& \quad=\int_{M}\left\{\varphi^{\prime} \varphi^{\prime \prime}+\lambda_{\theta} \partial_{s} \partial_{t} \varphi(0)+\lambda_{\theta} \varphi^{\prime \prime}\left(\tilde{\square}_{\theta} \varphi^{\prime}\right)\right\} \tilde{\theta}^{n} \\
& \quad=\int_{M}\left\{\varphi^{\prime} \varphi^{\prime \prime}\left(1-\lambda_{\theta}\right)+\lambda_{\theta} \partial_{s} \partial_{t} \varphi(0)\right\} \tilde{\theta}^{n}
\end{align*}
$$

By (b) of Theorem 5.4 together with (A.5.3) of Appendix 5, we have an $X_{\mathbb{R}}$-invariant function $\xi \in C^{\infty}(M)_{\mathbb{R}}$ such that $\lambda_{\theta}=\left(\tilde{\square}_{\theta}+1\right) \xi$. As in $[\mathrm{BM}$, (6.7)], (5.5.4) is rewritten as

$$
\begin{align*}
& (\operatorname{Hess} \iota)_{\theta}\left(\varphi^{\prime}, \varphi^{\prime \prime}\right)=\int_{M}\left\{\varphi^{\prime} \varphi^{\prime \prime}\left(1-\lambda_{\theta}\right)+\xi\left(\tilde{\square}_{\theta}+1\right) \partial_{s} \partial_{t} \varphi(0)\right\} \tilde{\theta}^{n}  \tag{5.5.5}\\
& =\int_{M}\left\{\varphi^{\prime} \varphi^{\prime \prime}\left(1-\lambda_{\theta}\right)+\xi\left(\tilde{\square}_{\theta}+1\right)\left(\partial \varphi^{\prime}, \partial \varphi^{\prime \prime}\right)_{\theta}\right\} \tilde{\theta}^{n} \quad(\mathrm{cf.}(5.5 .3  \tag{5.5.3}\\
& =\int_{M} \varphi^{\prime} \varphi^{\prime \prime} \tilde{\theta}^{n}+\frac{1}{2} \int_{M} \lambda_{\theta}\left\{\left(\tilde{\square}_{\theta} \varphi^{\prime}\right) \varphi^{\prime \prime}+\varphi^{\prime}\left(\tilde{\square}_{\theta} \varphi^{\prime \prime}\right)\right\} \tilde{\theta}^{n} \\
& \quad+\int_{M} \lambda_{\theta}\left(\partial \varphi^{\prime}, \partial \varphi^{\prime \prime}\right)_{\theta} \tilde{\theta}^{n}
\end{align*}
$$

$$
\begin{aligned}
& =\int_{M} \varphi^{\prime} \varphi^{\prime \prime} \tilde{\theta}^{n}+\frac{1}{2} \int_{M} \lambda_{\theta} \tilde{\square}_{\theta}\left(\varphi^{\prime} \varphi^{\prime \prime}\right) \tilde{\theta}^{n} \\
& =\int_{M} \varphi^{\prime} \varphi^{\prime \prime}\left(1+\frac{1}{2} \tilde{\square}_{\theta} \lambda_{\theta}\right) \tilde{\theta}^{n} .
\end{aligned}
$$

We now follows the arguments in [BM, Section 7]. Let $0<t \leq 1$ and $0<\alpha<1$. For each nonnegative integer $k$, let $C_{X}^{k, \alpha}(M)_{\mathbb{R}}$ be the space of all $X_{\mathbb{R}^{-}}$-invariant functions in $C^{k, \alpha}(M)_{\mathbb{R}}$, and consider the set $\mathcal{H}_{X}^{2, \alpha}$ of all $\varphi \in C_{X}^{2, \alpha}(M)_{\mathbb{R}}$ such that $\omega_{\varphi}:=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi$ is a positive definite $C^{0, \alpha}$ form on $M$. Put

$$
\left(\mathfrak{k}_{k}^{\theta}\right)^{\perp}:=\left\{w \in C_{X}^{k, \alpha}(M)_{\mathbb{R}} ; \int_{M} w v \tilde{\theta}^{n}=0 \text { for all } v \in \mathfrak{k}^{\theta}\right\} .
$$

We here observe that $\mathfrak{z}^{\theta}(X)=\mathfrak{k}_{\mathbb{C}}^{\theta}$ by Proposition A. 5 in Appendix 5. In order to solve the equation $\Gamma(\varphi, t)=0$ in $\varphi \in \mathcal{H}_{X, 0}^{2, \alpha}$, it suffices to solve the following equation in $\gamma \in \mathcal{H}_{X}^{2, \alpha}$ :

$$
\begin{equation*}
A(\gamma)=\exp \left(-t \gamma+\tilde{f}_{\omega_{0}}\right) \tag{5.5.6}
\end{equation*}
$$

Because any solution $\gamma \in \mathcal{H}_{X}^{k, \alpha}$ of (5.5.6) allows us to obtain a solution $\varphi \in \mathcal{H}_{X, 0}^{k, \alpha}$ of the equation $\Gamma(\varphi, t)=0$ by setting $\varphi:=\gamma-\left(1 / V_{0}\right) \int_{M} \gamma \tilde{\omega}_{0}^{n}$. Next, we see that (5.5.6) is further reduced to the equation

$$
\begin{equation*}
\Phi(t, \gamma)=0 \tag{5.5.7}
\end{equation*}
$$

where $\Phi(t, \gamma):=t \gamma-\tilde{f}_{\omega_{0}}+\log A(\gamma)$. Note that $\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp} \subset\left(\mathfrak{k}_{0}^{\theta}\right)^{\perp}$. Let $P$ : $C_{X}^{0, \alpha}(M)_{\mathbb{R}}\left(\cong \mathfrak{k}^{\theta} \oplus\left(\mathfrak{k}_{0}^{\theta}\right)^{\perp}\right) \rightarrow \mathfrak{k}^{\theta}$ be the projection to the first factor. For each $\gamma \in \mathcal{H}_{X}^{2, \alpha}$, write

$$
\gamma=\lambda_{\theta}+x+y
$$

with $x:=P\left(\gamma-\lambda_{\theta}\right) \in \mathfrak{k}^{\theta}$ and $y:=(1-P)\left(\gamma-\lambda_{\theta}\right) \in\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}$. Now, the equation (5.5.7) is written in the form

$$
P \Phi\left(t, \lambda_{\theta}+x+y\right)=0 \quad \text { and } \quad \Psi(t, x, y)=0
$$

where $\Psi: \mathbb{R} \times \mathfrak{k}^{\theta} \times\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp} \rightarrow\left(\mathfrak{k}_{0}^{\theta}\right)^{\perp}$ is the mapping defined by

$$
\Psi(t, x, y):=(1-P) \Phi\left(t, \lambda_{\theta}+x+y\right), \quad(t, x, y) \in \mathbb{R} \times \mathfrak{k}^{\theta} \times\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}
$$

Then $\Psi(1,0,0)=0$ and the Fréchet derivative $D_{y} \Psi_{\mid(1,0,0)}$ of $\Psi$ with respect to $y$ at $(t, x, y)=(1,0,0)$ is

$$
\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp} \ni y^{\prime} \longmapsto D_{y} \Psi_{\mid(1,0,0)}\left(y^{\prime}\right)=\left(\tilde{\square}_{\theta}+1\right) y^{\prime} \in\left(\mathfrak{k}_{0}^{\theta}\right)^{\perp},
$$

which is invertible. Hence, the implicit function theorem enables us to obtain a smooth mapping $V \ni(t, x) \mapsto y_{t, x} \in\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}$ of a small neighbourhood $V$ of $(1,0)$ in $\mathbb{R} \times \mathfrak{k}^{\theta}$ to the Banach space $\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}$ such that
i) $y_{1,0}=0$,
ii) $\left\|y_{t, x}\right\|_{C^{2, \alpha}} \leq \delta$ on $V$ for some $\delta>0$, and
iii) $\Psi(t, x, y)=0\left(\right.$ where $\left.\|y\|_{C^{2, \alpha}} \leq \delta\right)$ is, as an equation in $y \in\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}$, uniquely solvable in the form $y=y_{t, x}$ on $U$.

The derivative $(\partial / \partial t) y_{t, x}$ is denoted by $\dot{y}_{t, x}$ for simplicity. Then by differentiating the identity $\Psi\left(t, x, y_{t, x}\right)=0$ at $(t, x)=(1,0)$, we obtain

$$
\left\{\begin{array}{l}
\left(\tilde{\square}_{\theta}+1\right)\left(\dot{y}_{t, x \mid(1,0)}\right)=-\lambda_{\theta},  \tag{5.5.8}\\
\left(D_{x} y_{t, x}\right)_{\mid(1,0)}\left(\varphi^{\prime}\right)=0
\end{array} \text { for all } \varphi^{\prime} \in \mathfrak{k}^{\theta}\right.
$$

where $\left(D_{x} y_{t, x}\right)_{\mid(1,0)}: \mathfrak{k}^{\theta} \rightarrow\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}$ denotes the Fréchet derivative of the smooth mapping $V \ni(t, x) \mapsto y_{t, x} \in\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}$ with respect to $x$ at $(t, x)=$ $(1,0)$. Then the equation (5.5.7), on a small neighbourhood of $(t, \gamma)=$ $\left(1, \lambda_{\theta}\right)$, reduces to

$$
\Phi_{0}(t, x)=0 \quad\left(\text { with } \gamma=\lambda_{\theta}+x+y_{t, x}\right)
$$

where we put $\Phi_{0}(t, x):=P \Phi\left(t, \lambda_{\theta}+x+y_{t, x}\right)$ for $(t, x) \in V$. Since $\Phi(1, x)=0$ for all $x \in \tilde{\mathbf{O}}$, we have $\Phi_{0}=0$ on $\{t=1\}$, and hence the mapping

$$
V_{\mid\{t \neq 1\}} \ni(t, x) \longmapsto \Phi_{1}(t, x):=\Phi_{0}(t, x) /(t-1) \in \mathfrak{k}^{\theta}
$$

naturally extends to a smooth map, denoted by the same $\Phi_{1}$, of $V$ to $\mathfrak{k}^{\theta}$. In view of the first identity of (5.5.8), we obtain

$$
\Phi_{1}(1,0)=\left(\partial \Phi_{0} / \partial t\right)(1,0)=0
$$

Then the Fréchet derivative $D_{x} \Phi_{1 \mid(1,0)}: \mathfrak{k}^{\theta} \rightarrow \mathfrak{k}^{\theta}$ of $\Phi_{1}$ with respect to $x$ at $(t, x)=(1,0)$ is given by the following:

Theorem 5.5. By using the notation in Section 2 on the left-hand side, we have

$$
\left\langle\left\langle D_{x} \Phi_{1 \mid(1,0)}\left(\varphi^{\prime}\right), \varphi^{\prime \prime}\right\rangle\right\rangle_{\tilde{\theta}}=(\operatorname{Hess} \iota)_{\theta}\left(\varphi^{\prime}, \varphi^{\prime \prime}\right), \quad \varphi^{\prime}, \varphi^{\prime \prime} \in \mathfrak{k}^{\theta}
$$

Proof. Since $P\left(\tilde{\square}_{\theta}+1\right)=0$ on $\left(\mathfrak{k}_{2}^{\theta}\right)^{\perp}$, the latter identity of (5.5.8) above together with (1.3) and (2.5) implies

$$
\begin{aligned}
D_{x} \Phi_{1 \mid(1,0)}\left(\varphi^{\prime}\right) & =\left\{D_{x}\left(\partial \Phi_{0} / \partial t\right)\right\}_{\mid(1,0)}\left(\varphi^{\prime}\right) \\
& =\varphi^{\prime}-P\left(\partial \bar{\partial} \dot{y}_{t, x \mid(1,0)}, \partial \bar{\partial} \varphi^{\prime}\right)_{\theta}+P\left\{\ddot{\sigma}\left(u_{\theta}\right)\left(\bar{X} \varphi^{\prime}\right) \bar{X} \dot{y}_{t, x \mid(1,0)}\right\}
\end{aligned}
$$

Moreover, we observe the first identity of (5.5.8). Then by (A.3.2) in Appendix 3 applied to $\left(\omega, v_{1}, v_{2}, \zeta\right)=\left(\theta, \varphi^{\prime \prime}, \varphi^{\prime}, \dot{y}_{t, x \mid(1,0)}\right)$, we obtain

$$
\begin{aligned}
& \left\langle\left\langle D_{x} \Phi_{1 \mid(1,0)}\left(\varphi^{\prime}\right), \varphi^{\prime \prime}\right\rangle\right\rangle_{\tilde{\theta}} \\
& \quad=\int_{M}\left(\varphi^{\prime}-P\left(\partial \bar{\partial} \dot{y}_{t, x \mid(1,0)}, \partial \bar{\partial} \varphi^{\prime}\right)_{\theta}+P\left\{\ddot{\sigma}\left(u_{\theta}\right)\left(\bar{X} \varphi^{\prime}\right) \bar{X} \dot{y}_{t, x \mid(1,0)}\right\}\right) \varphi^{\prime \prime} \tilde{\theta}^{n} \\
& \quad=\int_{M}\left(\varphi^{\prime} \varphi^{\prime \prime}-\varphi^{\prime \prime}\left(\partial \bar{\partial} \dot{y}_{t, x \mid(1,0)}, \partial \bar{\partial} \varphi^{\prime}\right)_{\theta}+\varphi^{\prime \prime}\left\{\ddot{\sigma}\left(u_{\theta}\right)\left(\bar{X} \varphi^{\prime}\right) \bar{X} \dot{y}_{t, x \mid(1,0)}\right\}\right) \tilde{\theta}^{n} \\
& \quad=\int_{M}\left\{\varphi^{\prime} \varphi^{\prime \prime}-\varphi^{\prime \prime} \varphi^{\prime} \lambda_{\theta}+\left(\partial \varphi^{\prime \prime}, \partial \varphi^{\prime}\right)_{\theta} \lambda_{\theta}\right\} \tilde{\theta}^{n} \\
& \quad=\int_{M}\left\{\varphi^{\prime} \varphi^{\prime \prime}\left(1-\lambda_{\theta}\right)+\left(\partial \varphi^{\prime}, \partial \varphi^{\prime \prime}\right)_{\theta} \lambda_{\theta}\right\} \tilde{\theta}^{n}
\end{aligned}
$$

This together with the second equality of (5.5.5) implies the required identity.

Regarding $\omega_{0}$ as a function in $\varepsilon$, we write

$$
\begin{equation*}
\omega_{0}=\omega_{0}(\varepsilon), \quad \varepsilon \in[0,1] \tag{5.5.1}
\end{equation*}
$$

Hence, the corresponding $\omega_{\varphi}:=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi, \tilde{f}_{\omega_{0}}, \iota, A(\varphi), \Gamma(t, \gamma), \mu^{\sigma}$ and $\mathcal{H}_{X, 0}^{2, \alpha}$ will be written respectively as $\omega_{\varphi}(\varepsilon), \tilde{f}_{\omega_{0}(\varepsilon)}, \iota_{\varepsilon}, A_{\varepsilon}(\varphi), \Gamma_{\varepsilon}(t, \gamma)$, $\mu_{\varepsilon}^{\sigma}$ and $\mathcal{H}_{X, 0}^{2, \alpha}(\varepsilon)$. For $\iota_{\varepsilon}$ at $\varepsilon=0$, we see by (a) of Theorem 5.4 that the functional $\iota_{0}: \mathbf{O} \rightarrow \mathbb{R}$ takes its absolute minimum at some point $\theta \in \mathbf{O}$. Then we have a unique function $\lambda_{\theta ; 0} \in C^{\infty}(M)_{\mathbb{R}}$ such that $\theta=\omega_{\lambda_{\theta ; 0}}(0)$ and that $A_{0}\left(\lambda_{\theta ; 0}\right)=\exp \left(-\lambda_{\theta ; 0}+\tilde{f}_{\omega_{0}(0)}\right)$. Then by (b) of Theorem 5.4,

$$
\begin{equation*}
\int_{M} \lambda_{\theta ; 0} v \tilde{\theta}^{n}=0 \quad \text { for all } v \in \mathfrak{k}^{\theta} \tag{5.5.2}
\end{equation*}
$$

and the bilinear form $\left(\operatorname{Hess} \iota_{0}\right)_{\theta}: \mathfrak{k}^{\theta} \times \mathfrak{k}^{\theta} \rightarrow \mathbb{R}$ is positive semidefinite. Let us now perturb $\omega_{0}(0)$ by setting

$$
\begin{equation*}
\omega_{0}(\varepsilon):=(1-\varepsilon) \omega_{0}(0)+\varepsilon \theta=\omega_{0}(0)+\sqrt{-1} \partial \bar{\partial}\left(\varepsilon \lambda_{\theta ; 0}\right), \quad 0 \leq \varepsilon \leq 1 \tag{5.5.3}
\end{equation*}
$$

Let $\lambda_{\theta ; \varepsilon} \in C^{\infty}(M)_{\mathbb{R}}$ be the unique function satisfying $\theta=\omega_{\lambda_{\theta ; \varepsilon}}(\varepsilon)$ and $A_{\varepsilon}\left(\lambda_{\theta ; \varepsilon}\right)=-\lambda_{\theta ; \varepsilon}+\tilde{f}_{\omega_{0}(\varepsilon)} . \quad$ By $\omega_{\lambda_{\theta ; 0}}(0)=\theta=\omega_{\lambda_{\theta ; \varepsilon}}(\varepsilon)=\omega_{0}(0)+$ $\sqrt{-1} \partial \bar{\partial}\left(\varepsilon \lambda_{\theta ; 0}\right)+\sqrt{-1} \partial \bar{\partial} \lambda_{\theta ; \varepsilon}$, we have

$$
\begin{equation*}
\lambda_{\theta ; \varepsilon}=(1-\varepsilon) \lambda_{\theta ; 0}+C_{\varepsilon} \quad \text { for some } C_{\varepsilon} \in \mathbb{R} \tag{5.5.4}
\end{equation*}
$$

Since $\int_{M} v \tilde{\theta}^{n}=0$ for all $v \in \mathfrak{k}^{\theta}$, (5.5.2) and (5.5.4) aboved imply $\int_{M} \lambda_{\theta ; \varepsilon} v \tilde{\theta}^{n}=0$ for all $v \in \mathfrak{k}^{\theta}$. Hence by (b) of Theorem 5.4, it follows that

$$
\begin{equation*}
\theta \text { is a critical point for } \iota_{\varepsilon}: \mathbf{O} \rightarrow \mathbb{R} \tag{5.5.5}
\end{equation*}
$$

Let $0<\varepsilon \ll 1$. For all $0 \neq v \in \mathfrak{k}^{\theta}$,

$$
\begin{align*}
& \left(\operatorname{Hess} \iota_{\varepsilon}\right)_{\theta}(v, v)=\int_{M} v^{2}\left(1+\frac{1}{2} \tilde{\square}_{\theta} \lambda_{\theta ; \varepsilon}\right) \tilde{\theta}^{n}  \tag{5.5.5}\\
& \quad=(1-\varepsilon) \int_{M} v^{2}\left(1+\frac{1}{2} \tilde{\square}_{\theta} \lambda_{\theta ; 0}\right) \tilde{\theta}^{n}+\varepsilon \int_{M} v^{2} \tilde{\theta}^{n}  \tag{5.5.4}\\
& \quad=(1-\varepsilon)\left(\operatorname{Hess} \iota_{0}\right)_{\theta}(v, v)+\varepsilon \int_{M} v^{2} \tilde{\theta}^{n}>0
\end{align*}
$$

Then for such a $\omega_{0}=\omega_{0}(\varepsilon)$ with $\varepsilon$ fixed, Theorem 5.5 shows that $D_{x} \Phi_{1 \mid(1,0)}$ : $\mathfrak{k}^{\theta} \rightarrow \mathfrak{k}^{\theta}$ is invertible. Now by the implicit function theorem, the equation $\Phi_{1}(t, x)=0$ in $x \in \mathfrak{k}^{\theta}$ is uniquely solvable in a small neighbourhood of $(t, x)=(1,0)$ to produce a smooth curve $x(t), 1-\delta \leq t \leq 1$, in $\mathfrak{k}^{\theta}$ for some $0<\delta \ll 1$ such that

$$
x(1)=0 \quad \text { and } \quad \Phi_{1}(t, x(t))=0 \quad(1-\delta \leq t \leq 1)
$$

Replacing $\delta>0$ by a smaller number if necessary, we obtain $\Phi\left(t, \lambda_{\theta ; \varepsilon}+\right.$ $\left.x(t)+y_{t, x(t)}\right)=0$ for $1-\delta \leq t \leq 1$. In view of the reduction to (5.5.6) and (5.5.7), we obtain

Theorem 5.6. For each $Z^{0}(X)$-orbit $\mathbf{O}$ in $\mathcal{E}_{X}^{\sigma}$, let $\theta$ be a point on $\mathbf{O}$ at which $\iota$ in (5.4.1) takes its absolute minimum. Then replacing $\omega_{0}$ by $(1-\varepsilon) \omega_{0}+\varepsilon \theta$ for some $0<\varepsilon \ll 1$, we have a $0<\delta \ll 1$ such that there exists a smooth one-parameter family of functions $\left\{\varphi_{t} ; 1-\delta \leq t \leq 1\right\}$ in $\mathcal{H}_{X, 0}^{2, \alpha}$ satisfying $\omega_{\varphi_{1}}=\theta$ and $\Gamma\left(t, \varphi_{t}\right)=0$ for all $t \in[1-\delta, 1]$.

Proof of Theorem C. Let $\mathbf{O}^{\prime}$ and $\mathbf{O}^{\prime \prime}$ be $Z^{0}(X)$-orbits in $\mathcal{E}_{X}^{\sigma}$. We consider the nonnegative function $\iota: \mathcal{K}_{X} \rightarrow \mathbb{R}$ defined by

$$
\iota(\omega):=\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}, \omega\right), \quad \omega \in \mathcal{K}_{X}
$$

The restrictions of $\iota$ to $\mathbf{O}^{\prime}$ and $\mathbf{O}^{\prime \prime}$ are denoted by $\iota^{\prime}: \mathbf{O}^{\prime} \rightarrow \mathbb{R}$ and $\iota^{\prime \prime}$ : $\mathbf{O}^{\prime \prime} \rightarrow \mathbb{R}$, respectively. We follow the arguments in [BM, (8.2)]. The proof is divided into three steps.

Step 1. In view of Theorem 5.6, by perturbing $\omega_{0}$ if necessary, we may assume that the function $\iota^{\prime}$ is critical at some $\theta^{\prime} \in \mathbf{O}^{\prime}$ with positive definite Hessian. Next by (a) of Theorem 5.4, the function $\iota^{\prime \prime}$ takes its absolute minimum at some point $\theta^{\prime \prime} \in \mathbf{O}^{\prime \prime}$. For $0<\varepsilon \ll 1$, we define a nonnegative function $\iota_{\varepsilon}$ on $\mathcal{K}_{X}$ by

$$
\iota_{\varepsilon}(\omega):=\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega_{0}(\varepsilon), \omega\right), \quad \omega \in \mathcal{K}_{X}
$$

Let $\iota_{\varepsilon}^{\prime}: \mathbf{O}^{\prime} \rightarrow \mathbb{R}$ and $\iota_{\varepsilon}^{\prime \prime}: \mathbf{O}^{\prime \prime} \rightarrow \mathbb{R}$ be the restrictions of the function $\iota_{\varepsilon}$ to $\mathbf{O}^{\prime}$ and $\mathbf{O}^{\prime \prime}$, respectively. Put $\omega_{0}(\varepsilon):=(1-\varepsilon) \omega_{0}+\varepsilon \theta^{\prime \prime}$. Then by (5.5.5), the function $\iota_{\varepsilon}^{\prime \prime}$ is critical at $\theta^{\prime \prime}$ with positive definite Hessian. Moreover, by $\varepsilon \ll 1$, the restriction $\iota_{\varepsilon}^{\prime}$ takes its local minimum with positive definite Hessian at some point $\theta_{\varepsilon}^{\prime}$ of $\mathbf{O}^{\prime}$ near $\theta^{\prime}$. Hence, replacing $\omega_{0}$ by $\omega_{0}(\varepsilon)$, we may assume from the begining that both $\iota^{\prime}: \mathbf{O}^{\prime} \rightarrow \mathbb{R}$ and $\iota^{\prime \prime}: \mathbf{O}^{\prime \prime} \rightarrow \mathbb{R}$ have critical points with positive definite Hessian. Therefore by Theorem 5.6, for some $0<\delta \ll 1$, we have smooth one-parameter families of functions $\left\{\varphi_{t}^{\prime} ; 1-\delta \leq t \leq 1\right\}$ and $\left\{\varphi_{t}^{\prime \prime} ; 1-\delta \leq t \leq 1\right\}$ in $\mathcal{H}_{X, 0}^{2, \alpha}$ satisfying the following conditions:

$$
\begin{gather*}
\Gamma\left(t, \varphi_{t}^{\prime}\right)=\Gamma\left(t, \varphi_{t}^{\prime \prime}\right)=0 \quad \text { for all } t \in[1-\delta, 1]  \tag{5.7.1}\\
\lim _{t \rightarrow 1} \omega_{\varphi_{t}^{\prime}}=\omega_{\varphi_{1}^{\prime}} \in \mathbf{O}^{\prime} \quad \text { and } \quad \lim _{t \rightarrow 1} \omega_{\varphi_{t}^{\prime \prime}}=\omega_{\varphi_{1}^{\prime \prime}} \in \mathbf{O}^{\prime \prime} \tag{5.7.2}
\end{gather*}
$$

Then by Theorem 5.3, these extend to smooth one-parameter families of functions $\left\{\varphi_{t}^{\prime} ; 0 \leq t \leq 1\right\}$ and $\left\{\varphi_{t}^{\prime \prime} ; 0 \leq t \leq 1\right\}$ in $\mathcal{H}_{X, 0}^{2, \alpha}$ satisfying the equalities in (5.7.1) for all $t \in[0,1]$.

Step 2. Appendix 4 shows that $\varphi_{0} \in \mathcal{H}_{X, 0}^{2, \alpha}$ satisfying the equation $\Gamma\left(\varphi_{0}, 0\right)=0$ is unique. Hence, by Theorem 5.3 together with Step 1, the local uniqueness in Theorem 5.1 implies the uniqueness of a smooth oneparameter family of functions

$$
\left\{\varphi_{t} ; 0 \leq t<1\right\}
$$

in $\mathcal{H}_{X, 0}^{2, \alpha}$ satisfying $\Gamma\left(\varphi_{t}, t\right)=0$ for all $0 \leq t<1$. In particular, we obtain $\varphi_{t}^{\prime}=\varphi_{t}^{\prime \prime}$ for all $0 \leq t<1$. This together with (5.7.2) implies $\mathbf{O}^{\prime}=\mathbf{O}^{\prime \prime}$, as required.

## $\S 6$. Corollaries of Theorem C

Throughout this section, we assume that $\sigma$ is convex. Let $\mu^{\sigma}: \mathcal{K}_{X} \rightarrow \mathbb{R}$ be the function defined in Appendix 2. Then by the arguments in $[\mathrm{BM}]$ and [Ba], we obtain the following corollaries of Theorem C:

Corollary D. If $\mathcal{E}_{X}^{\sigma} \neq \emptyset$, then the function $\mu^{\sigma}: \mathcal{K}_{X} \rightarrow \mathbb{R}$ takes its absolute minimum exactly on $\mathcal{E}_{X}^{\sigma}$.

Corollary E. If $\mathcal{E}_{X}^{\sigma} \neq \emptyset$, then for any, possibly non-connected, compact subgroup $H$ of $Z(X)$, there exists an $H$-invariant metric $\omega$ in $\mathcal{E}_{X}^{\sigma}$.

Proof of Corollary D. For an arbitrary element $\eta$ of $\mathcal{K}_{X}$, we have a unique element $\eta^{\prime}$ of $\mathcal{K}_{X}$ such that $\eta=\operatorname{Ric}^{\sigma}\left(\eta^{\prime}\right)$ (see for instance [M4] and Appendix 4). Put

$$
\omega_{0}(0)=\eta
$$

by the notation in (5.5.1). Choosing a $Z^{0}(X)$-orbit $\mathbf{O}$ in $\mathcal{E}_{X}^{\sigma}$, let $\theta$ be a point at which $\iota: \mathbf{O} \rightarrow \mathbb{R}$ in (5.4.1) takes its absolute minimum. For $0<\varepsilon \ll 1$, we perturb $\eta=\omega_{0}(0)$ by

$$
\omega_{0}(\varepsilon):=(1-\varepsilon) \eta+\varepsilon \theta
$$

as in (5.5.3). Then by Theorem 5.3 together with Theorem 5.6, we have a smooth one-parameter family of functions $\left\{\varphi_{t ; \varepsilon} ; 0 \leq t \leq 1\right\}$ in $\mathcal{H}_{X, 0}^{2, \alpha}(\varepsilon)$ satisfying

$$
\omega(1 ; \varepsilon)=\theta \quad \text { and } \quad \Gamma_{\varepsilon}\left(t, \varphi_{t ; \varepsilon}\right)=0, \quad 0 \leq t \leq 1
$$

where $\Gamma_{\varepsilon}$ and $\mathcal{H}_{X, 0}^{2, \alpha}(\varepsilon)$ are as in the arguments immediately after (5.5.1), and for simplicity we put $\omega(t ; \varepsilon):=\omega_{\varphi_{t, \varepsilon}}$ for all $0 \leq t \leq 1$. Now by Theorem 5.2,

$$
\begin{equation*}
M^{\sigma}(\omega(0 ; \varepsilon), \theta) \leq 0 \tag{6.1}
\end{equation*}
$$

where $M^{\sigma}$ is as in Appendix 2. We next observe that $\operatorname{Ric}^{\sigma}\left(\eta^{\prime}\right)=\eta=\omega_{0}(0)$, and that $\operatorname{Ric}^{\sigma}(\omega(0 ; \varepsilon))=\omega_{0}(\varepsilon)$. Let $\varepsilon \rightarrow 0$. Since $\omega_{0}(\varepsilon) \rightarrow \omega_{0}(0)$ in $C^{0, \alpha}$, it follows that $\omega(0 ; \varepsilon) \rightarrow \eta^{\prime}$ in $C^{2, \alpha}$. Hence, (6.1) implies

$$
\begin{equation*}
M^{\sigma}\left(\eta^{\prime}, \theta\right) \leq 0, \text { i.e., } B_{\sigma} \leq \mu^{\sigma}\left(\eta^{\prime}\right) \text { for all } \eta \in \mathcal{K}_{X} \tag{6.2}
\end{equation*}
$$

where we put $B_{\sigma}:=\mu^{\sigma}(\theta)$. On the other hand, by Theorem C and (a) of Proposition A. 2 in Appendix 2, the function $\mu^{\sigma}$ takes a constant value $B_{\sigma}$ on $\mathcal{E}_{X}^{\sigma}$. Then by Lemma 6.3 below, we have the inequality $B_{\sigma} \leq \mu^{\sigma}\left(\eta^{\prime}\right) \leq$ $\mu^{\sigma}(\eta)$, and the equality $B_{\sigma}=\mu^{\sigma}(\eta)$ holds if and only if $\eta \in \mathcal{E}_{X}^{\sigma}$, as required.

Lemma 6.3. (cf. [Ba] for Kähler-Einstein cases) For each $\omega \in \mathcal{K}_{X}$, let $\omega^{\prime}$ be the element of $\mathcal{K}_{X}$ such that $\operatorname{Ric}^{\sigma}\left(\omega^{\prime}\right)=\omega$. Then the inequality $\mu^{\sigma}\left(\omega^{\prime}\right) \leq \mu^{\sigma}(\omega)$ holds, and the equality $\mu^{\sigma}\left(\omega^{\prime}\right)=\mu^{\sigma}(\omega)$ holds if and only if $\omega^{\prime}=\omega$, i.e., $\omega \in \mathcal{E}_{X}^{\sigma}$.

Proof. Put $\omega_{0}:=\omega$. For $c_{t}:=\log V_{0}-\log \left\{\int_{M} \exp \left(t \tilde{f}_{\omega_{0}}\right) \tilde{\omega}_{0}^{n}\right\}$, let $\varphi_{t} \in \mathcal{H}_{X, 0}^{2, \alpha}$ denote the solution (see for instance [M4]) of the equation:

$$
\begin{equation*}
A\left(\varphi_{t}\right)=\exp \left(t \tilde{f}_{\omega_{0}}+c_{t}\right), \quad 0 \leq t \leq 1 \tag{6.4}
\end{equation*}
$$

For simplicity, we put $\omega(t):=\omega_{\varphi_{t}}$ and $\tilde{\square}_{t}:=\tilde{\square}_{\omega(t)}$. Then $\omega(0)=\omega_{0}=$ $\omega$. Differentiating (6.4) with respect to $t$, we obtain $\tilde{\square}_{t} \dot{\varphi}_{t}=\tilde{f}_{\omega_{0}}+\dot{c}_{t}$. Next by taking $\underset{\tilde{\partial}}{\bar{\partial}} \partial$ of both sides of (6.4), we see that $\operatorname{Ric}^{\sigma}(\omega(t))-\omega(t)=$ $\sqrt{-1} \partial \bar{\partial}\left\{(1-t) \tilde{f}_{\omega_{0}}-\varphi_{t}\right\}$. Therefore,

$$
\begin{aligned}
\frac{d}{d t} \mu^{\sigma}(\omega(t)) & =-\int_{M} \dot{\varphi}_{t} \tilde{\square}_{t}\left\{(1-t) \tilde{f}_{\omega_{0}}-\varphi_{t}\right\} \tilde{\omega}(t)^{n} \\
& =-(1-t) \int_{M}\left(\tilde{\square}_{t} \dot{\varphi}_{t}\right)^{2} \tilde{\omega}(t)^{n}+\int_{M} \dot{\varphi}_{t}\left(\tilde{\square}_{t} \varphi_{t}\right) \tilde{\omega}(t)^{n} \\
& \leq-\frac{d}{d t}\left\{\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)(\omega(0), \omega(t))\right\}
\end{aligned}
$$

where $\tilde{\omega}(t)$ is as in (2.3). Thus, by $\omega(0)=\omega$ and $\omega(1)=\omega^{\prime}$ (cf. Appendix 4), we obtain $\mu^{\sigma}\left(\omega^{\prime}\right)-\mu^{\sigma}(\omega) \leq-\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega, \omega^{\prime}\right) \leq 0$, and $\mu^{\sigma}\left(\omega^{\prime}\right)=\mu^{\sigma}(\omega)$ if and only if $\omega^{\prime}=\omega$.

We consider an arbitrary smooth path $\Lambda=\left\{\omega_{\lambda_{t}} ; a \leq t \leq b\right\}$ sitting in $\mathcal{E}_{X}^{\sigma}$, where $\left\{\lambda_{t} ; a \leq t \leq b\right\}$ is the corresponding smooth path in $C^{\infty}(M)_{\mathbb{R}}$ such that $\int_{M} \dot{\lambda}_{t} \tilde{\omega}_{\lambda_{t}}^{n}=0$ for all $t$. Then the length $\mathcal{L}(\Lambda)$ of the path $\Lambda$ in $\mathcal{E}_{X}^{\sigma}$ is defined by

$$
\mathcal{L}(\Lambda):=\int_{a}^{b}\left(\int_{M} \dot{\lambda}_{t}^{2} \tilde{\omega}_{\lambda_{t}}^{n}\right)^{1 / 2} d t
$$

This naturally defines a Riemannian metric on $\mathcal{E}_{X}^{\sigma}$. Let $\theta \in \mathcal{E}_{X}^{\sigma}$. Then by the notation in Appendix 5, the identity component $Z^{0}(X)$ of $Z(X)$ (see
also Section 1) is nothing but the complexification $K_{\mathbb{C}}$ of $K$ in $G$ (cf. (a) of Proposition A.5). Then we have:

Proposition 6.5. If $\mathcal{E}_{X}^{\sigma} \neq \emptyset$, then $Z(X)$ acts isometrically on $\mathcal{E}_{X}^{\sigma}$, and in particular, $\mathcal{E}_{X}^{\sigma}$ is isometric to the Riemannian symmetric space $K_{\mathbb{C}} / K$ endowed with a suitable metric.

Proof. Note that $\mathcal{E}_{X}^{\sigma} \cong Z^{0}(X) / K=K^{\mathbb{C}} / K$ by Theorem C. Then it suffices to show that $Z(M)$ acts isometrically on $\mathcal{E}_{X}^{\sigma}$. Let $g \in Z(M)$, and we can write $g^{*} \omega_{0}=\omega_{\varphi_{g}}$ for some $\varphi_{g} \in C^{\infty}(M)_{\mathbb{R}}$. For a smooth path $\Lambda$ in $\mathcal{E}_{X}^{\sigma}$ as above, we have $g^{*} \omega_{\lambda_{t}}=\omega_{\xi_{t}}$ for all $t$, where $\xi_{t}:=\varphi_{g}+g^{*} \lambda_{t}$. In view of $g^{*} \tilde{\omega}_{\lambda_{t}}=\tilde{\omega}_{\xi_{t}}$, we obtain

$$
\mathcal{L}\left(g^{*} \Lambda\right)=\int_{a}^{b}\left(\int_{M} \dot{\xi}_{t}^{2} \tilde{\omega}_{\xi_{t}}^{n}\right)^{1 / 2} d t=\int_{a}^{b}\left(\int_{M} g^{*} \dot{\lambda}_{t}^{2} g^{*} \tilde{\omega}_{\lambda_{t}}^{n}\right)^{1 / 2} d t=\mathcal{L}(\Lambda)
$$

as required.
Proof of Corollary E. We follow the arguments in [BM]. By Proposition $6.5, \mathcal{E}_{X}^{\sigma}$ is isometric to the Riemannian symmetric space $K^{\mathbb{C}} / K$ without compact factors. Hence, $\mathcal{E}_{X}^{\sigma}$ is a simply connected Riemannian manifold with nonpositive sectional curvature. Since the compact group $H$ acts isometrically on $\mathcal{E}_{X}^{\sigma}$, the action has a fixed point in $\mathcal{E}_{X}^{\sigma}$, as required.

## Appendix 1. Inequalities between Aubin's functionals

For $\sigma \in C^{\infty}\left(I_{X}\right)_{\mathbb{R}}$ as in the introduction, the purpose of this appendix is to establish inequalities between multiplier Hermitian analogues $\mathcal{I}^{\sigma}$ : $\mathcal{K}_{X} \times \mathcal{K}_{X} \rightarrow \mathbb{R}$ and $\mathcal{J}^{\sigma}: \mathcal{K}_{X} \times \mathcal{K}_{X} \rightarrow \mathbb{R}$ of Aubin's functionals (cf. [A1], $[\mathrm{BM}],[\mathrm{T} 1])$. Let $\omega^{\prime}, \omega^{\prime \prime} \in \mathcal{K}_{X}$. In view of (1.1), we can write $\omega^{\prime}:=\omega_{\varphi^{\prime}}$ and $\omega^{\prime \prime}:=\omega_{\varphi^{\prime \prime}}$ for some $\varphi^{\prime}, \varphi^{\prime \prime} \in \mathcal{H}_{X}$. Then by using the notation in (1.4), we define $\mathcal{I}^{\sigma}$ and the difference $\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}$ by

$$
\left\{\begin{array}{l}
\mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right):=\int_{M}\left(\varphi^{\prime \prime}-\varphi^{\prime}\right)\left\{\left(\tilde{\omega}^{\prime}\right)^{n}-\left(\tilde{\omega}^{\prime \prime}\right)^{n}\right\}  \tag{A.1.1}\\
\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right):=\int_{a}^{b}\left\{\int_{M}\left(\bar{\partial} \varphi_{t}, \bar{\partial} \dot{\varphi}_{t}\right)_{\omega(t)} \tilde{\omega}(t)^{n}\right\} d t
\end{array}\right.
$$

where $\phi:=\left\{\varphi_{t} ; a \leq t \leq b\right\}$ is an arbitrary smooth path in $\mathcal{H}_{X}$ satisfying the equalities $\varphi_{a}=0, \varphi_{b}=\varphi^{\prime \prime}-\varphi^{\prime}$ and $\omega(t)=\omega^{\prime}+\sqrt{-1} \partial \bar{\partial} \varphi_{t}$ for all $t$ with $a \leq t \leq b$.

Claim. $\quad\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right)$ defined in the second line of (A.1.1) depends only on $\left(\omega^{\prime}, \omega^{\prime \prime}\right)$, and is independent of the choice of the path $\phi$.

Proof. In view of (a) of Lemma 2.4 and the first line of (A.1.1), by using the notation in (2.3), we obtain

$$
\begin{equation*}
\frac{d}{d t} \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega(t)\right)=\int_{M} \dot{\varphi}_{t}\left\{\left(\tilde{\omega}^{\prime}\right)^{n}-\tilde{\omega}(t)^{n}\right\}+\int_{M}\left(\bar{\partial} \varphi_{t}, \bar{\partial} \dot{\varphi}_{t}\right)_{\omega(t)} \tilde{\omega}(t)^{n} \tag{A.1.2}
\end{equation*}
$$

Hence, it suffices to show that the integral $\int_{a}^{b}\left(\int_{M} \dot{\varphi}_{t}\left\{\left(\tilde{\omega}^{\prime}\right)^{n}-\tilde{\omega}(t)^{n}\right\}\right) d t$ is independent of the choice of the path $\phi$ above. Let

$$
[0,1] \times[a, b] \ni(s, t) \longmapsto \varphi_{s, t} \in C^{\infty}(M)_{\mathbb{R}}
$$

be a smooth 2-parameter family of functions in $C^{\infty}(M)_{\mathbb{R}}$ such that $\omega_{\varphi_{s, t}} \in$ $\mathcal{K}_{X}$ for all $(s, t)$. For such a family $\varphi=\varphi_{s, t}$ of functions, we consider the 1-form

$$
\Theta:=\left(\int_{M} \frac{\partial \varphi}{\partial s}\left\{\left(\tilde{\omega}^{\prime}\right)^{n}-\tilde{\omega}_{\varphi}^{n}\right\}\right) d s+\left(\int_{M} \frac{\partial \varphi}{\partial t}\left\{\left(\tilde{\omega}^{\prime}\right)^{n}-\tilde{\omega}_{\varphi}^{n}\right\}\right) d t
$$

on $[0,1] \times[a, b]$. In view of (2.2) and (2.5),

$$
\begin{aligned}
d \Theta & =d s \wedge d t \int_{M}\left\{\frac{\partial \varphi}{\partial s} \frac{\partial}{\partial t}\left(\tilde{\omega}_{\varphi}^{n}\right)-\frac{\partial \varphi}{\partial t} \frac{\partial}{\partial s}\left(\tilde{\omega}_{\varphi}^{n}\right)\right\} \\
& =d s \wedge d t \int_{M}\left\{\frac{\partial \varphi}{\partial s}\left(\tilde{\square}_{\omega_{\varphi}} \frac{\partial \varphi}{\partial t}\right)-\frac{\partial \varphi}{\partial t}\left(\tilde{\square}_{\omega_{\varphi}} \frac{\partial \varphi}{\partial s}\right)\right\} \tilde{\omega}_{\varphi}^{n}=0
\end{aligned}
$$

and this implies the required independence.
Next, take the infinitesimal form of the second line of (A.1.1) with respect to $t$, and subtract it from (A.1.2). Then by integration,

$$
\begin{equation*}
\mathcal{J}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)=\int_{a}^{b}\left(\int_{M} \dot{\varphi}_{t}\left\{\left(\tilde{\omega}^{\prime}\right)^{n}-\tilde{\omega}(t)^{n}\right\}\right) d t \tag{A.1.3}
\end{equation*}
$$

for $\omega(t)$ and $\phi$ as above. In (A.1.1) and (A.1.3), we choose $\phi$ such that $\varphi_{t}:=t \hat{\varphi}, 0 \leq t \leq 1$, where $a=0, b=1$ and $\hat{\varphi}:=\varphi^{\prime \prime}-\varphi^{\prime}$. Then

$$
\begin{cases}\mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)=f(1), \quad \mathcal{J}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)=\int_{0}^{1} f(t) d t  \tag{A.1.4}\\ \left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right)= & \int_{0}^{1}\{f(1)-f(t)\} d t \\ \left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right)= & \int_{0}^{1}\left\{\int_{M} t(\bar{\partial} \hat{\varphi}, \bar{\partial} \hat{\varphi})_{\omega(t)} \tilde{\omega}(t)^{n}\right\} d t \geq 0\end{cases}
$$

where $f=f(t)$ is defined by

$$
\begin{aligned}
f(t) & :=\int_{M} \hat{\varphi}\left\{\left(\tilde{\omega}^{\prime}\right)^{n}-\tilde{\omega}(t)^{n}\right\}=t^{-1} \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega(t)\right) \\
& =t^{-1} \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime}+t\left(\omega^{\prime \prime}-\omega^{\prime}\right)\right)
\end{aligned}
$$

In the last inequality of (A.1.4), we easily see that $\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right)=0$ if and only if $\omega^{\prime}$ coincides with $\omega^{\prime \prime}$. Let $k$ be a nonnegative real number. Replacing $\sigma \in C^{\infty}\left(I_{X}\right)_{\mathbb{R}}$ by $k \sigma \in C^{\infty}\left(I_{X}\right)_{\mathbb{R}}$, we have functionals $\mathcal{J}^{k \sigma}$ : $\mathcal{K}_{X} \times \mathcal{K}_{X} \rightarrow \mathbb{R}$ and $\mathcal{I}^{k \sigma}: \mathcal{K}_{X} \times \mathcal{K}_{X} \rightarrow \mathbb{R}$. For instance, if $k=0$, then $\mathcal{I}^{k \sigma}$ and $\mathcal{J}^{k \sigma}$ are nothing but the restriction to $\mathcal{K}_{X} \times \mathcal{K}_{X}$ of the ordinary Aubin's functional $\mathcal{I}$ and $\mathcal{J}$. Put $c:=\max _{s \in I_{X}}|\sigma(s)|$ as in the introduction. Then by the last line of (A.1.4), we can easily compare $\mathcal{I}^{k \sigma}-\mathcal{J}^{k \sigma}$ and $\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}$ as follows:

Lemma A.1.5. For all $\omega^{\prime}, \omega^{\prime \prime} \in \mathcal{K}_{X}$, using the notation in (1.2), we have the inequalities $e^{-|k-1| c}\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right) \leq\left(\mathcal{I}^{k \sigma}-\mathcal{J}^{k \sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right) \leq$ $e^{|k-1| c}\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right)$.

Put $b_{\sigma}:=\left(\beta_{X}-\alpha_{X}\right) \max _{s \in I_{X}}|\dot{\sigma}(s)|>0$. To each positive real number $m>0$, we associate a function $q_{m}=q_{m}(t)$ on the closed interval $[0,1]$ by setting

$$
q_{m}(t):=1-(1-t)^{m+1}, \quad 0 \leq t \leq 1
$$

Lemma A.1.6. If $m:=n-1+b_{\sigma}$, then $f(t) \leq f(1) q_{m}(t)$ for all $0 \leq$ $t \leq 1$,

Proof. We may assume that $\hat{\varphi}$ is nonconstant. For $\omega(t)=\omega^{\prime}+$ $t \sqrt{-1} \partial \bar{\partial} \hat{\varphi}$, we write the function $\psi_{\omega(t)}$ just as $\psi(t)$ for simplicity. By differentiation, the definition of $f(t)$ yields

$$
\begin{aligned}
\dot{f}(t) & =-\int_{M} \hat{\varphi}\left(\tilde{\square}_{\omega(t)} \hat{\varphi}\right) \tilde{\omega}(t)^{n}=\int_{M}(\bar{\partial} \hat{\varphi}, \bar{\partial} \hat{\varphi})_{\omega(t)} \tilde{\omega}(t)^{n} \\
& =n \sqrt{-1} \int_{M}(\partial \hat{\varphi} \wedge \bar{\partial} \hat{\varphi}) e^{-\psi(t)} \omega(t)^{n-1}>0
\end{aligned}
$$

and by $f(0)=0$, we have $f(t)>0$ for all $0<t \leq 1$. Differentiate the equality just above with respect to $t$. Then by $u_{\omega(t)}=u_{\omega^{\prime}}+t \sqrt{-1} X \hat{\varphi}$ and $\dot{\psi}(t)=\sqrt{-1} \dot{\sigma}\left(u_{\omega}\right) X \hat{\varphi}$,

$$
\ddot{f}(t)=n \sqrt{-1} \int_{M} \partial \hat{\varphi} \wedge \bar{\partial} \hat{\varphi}\{-\omega(t) \dot{\psi}(t)+(n-1) \sqrt{-1} \partial \bar{\partial} \hat{\varphi}\} e^{-\psi(t)} \omega(t)^{n-2}
$$

$$
\begin{aligned}
=n & \sqrt{-1} \int_{M} \partial \hat{\varphi} \wedge \bar{\partial} \hat{\varphi} \\
& \wedge\left\{-\sqrt{-1} \omega(t) \dot{\sigma}\left(u_{\omega(t)}\right) X \hat{\varphi}+(n-1) \sqrt{-1} \partial \bar{\partial} \hat{\varphi}\right\} e^{-\psi(t)} \omega(t)^{n-2}
\end{aligned}
$$

Now by $\max _{M}|X \hat{\varphi}| \leq \max _{M}\left|u_{\omega(1)}-u_{\omega(0)}\right| \leq \beta_{X}-\alpha_{X}$, we have

$$
\max _{M}\left|\dot{\sigma}\left(u_{\omega(t)}\right) X \hat{\varphi}\right| \leq b_{\sigma}
$$

for all $0 \leq t \leq 1$. By $(1-t) \sqrt{-1} \partial \bar{\partial} \hat{\varphi}+\omega(t)=\omega^{\prime \prime}>0$, we further obtain

$$
(1-t)\left\{-\sqrt{-1} \omega(t) \dot{\sigma}\left(u_{\omega(t)}\right) X \hat{\varphi}+(n-1) \sqrt{-1} \partial \bar{\partial} \hat{\varphi}\right\}+m \omega(t)>0
$$

for all $0 \leq t \leq 1$. Hence,

$$
(1-t) \ddot{f}(t)+m \dot{f}(t)>0, \quad 0 \leq t \leq 1
$$

This implies $(d / d t)(\log \dot{f}(t))>-m /(1-t)=(d / d t)(\log \dot{q}(t))$ for $0 \leq t<1$, where we put $q(t):=f(1) q_{m}(t)$ for simplicity. Hence, $\dot{f}(t) / \dot{q}(t)$ is monotone increasing for $0 \leq t<1$, while we have both $\dot{f}(1)>0=\dot{q}(1)$ and $f(1)=$ $q(1)$. Therefore, if there were $t_{0} \in(0,1)$ such that $f\left(t_{0}\right)=q\left(t_{0}\right)$, then in view of the behaviour of the curve $\{(f(t), q(t)) ; 0 \leq t \leq 1\}$, it would follow that $\dot{f}\left(t_{0}\right)<\dot{q}\left(t_{0}\right)$ in contradiction to $f(0)=0=q(0)$. We now conclude that $f(t) \leq q(t)$ for all $0 \leq t \leq 1$, as required.

Remark A.1.7. If $\sigma(s)=-\log (s+C), s \in I_{X}$, for some real constant $C>-\alpha_{X}$, then we obtain $f(t) \leq f(1) q_{n}(t)$ for all $0 \leq t \leq 1$ as follows: For such a function $\sigma$, we have

$$
e^{-\psi_{\omega(t)}}=u_{\omega^{\prime}}+t \sqrt{-1} X \hat{\varphi}+C \quad \text { and } \quad-\dot{\sigma}\left(u_{\omega(t)}\right) e^{-\psi_{\omega(t)}}=1
$$

and $-(1-t) \sqrt{-1} \dot{\sigma}\left(u_{\omega(t)}\right) e^{-\psi_{\omega(t)}} X \hat{\varphi}+e^{-\psi_{\omega(t)}}=u_{\omega^{\prime}}+\sqrt{-1} X \hat{\varphi}+C=$ $e^{-\psi_{\omega^{\prime \prime}}}>0$ follows. Hence, in view of $(1-t) \sqrt{-1} \partial \bar{\partial} \hat{\varphi}+\omega(t)=\omega^{\prime \prime}>0$, we obtain

$$
(1-t)\left\{-\sqrt{-1} \omega(t) \dot{\sigma}\left(u_{\omega(t)}\right) X \hat{\varphi}+(n-1) \sqrt{-1} \partial \bar{\partial} \hat{\varphi}\right\}+n \omega(t)>0
$$

Then $(1-t) \ddot{f}(t)+n \dot{f}(t)>0$ for all $0 \leq t \leq 1$. Finally, the same argument as in the above proof of Lemma A.1.6 yields the required inequality.

In the definition of $f(t)$, since $\omega(1)=\omega^{\prime \prime}$, we obtain

$$
f(1)-f(t)=\int_{M}(-\hat{\varphi})\left\{\left(\tilde{\omega}^{\prime \prime}\right)^{n}-\tilde{\omega}(t)^{n}\right\}
$$

where $\omega(t)=\omega^{\prime \prime}+(1-t) \partial \bar{\partial}(-\hat{\varphi})$. Replace $1-t$ by $t$. Then by (A.1.3), the right-hand side of the middle line of (A.1.4) is regarded as $\mathcal{J}^{\sigma}\left(\omega^{\prime \prime}, \omega^{\prime}\right)$. Hence,

$$
\begin{equation*}
\mathcal{J}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)+\mathcal{J}^{\sigma}\left(\omega^{\prime \prime}, \omega^{\prime}\right)=\mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)=\mathcal{I}^{\sigma}\left(\omega^{\prime \prime}, \omega^{\prime}\right), \quad \omega^{\prime}, \omega^{\prime \prime} \in \mathcal{K}_{X} \tag{A.1.8}
\end{equation*}
$$

By Lemma A.1.6, we have $f(1)-f(t) \geq f(1)\left(1-q_{m}(t)\right)$ for all $0 \leq t \leq 1$. Integrating this inequality over $[0,1]$, we see that

$$
\begin{aligned}
\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right) & \geq f(1) \int_{0}^{1}\left(1-q_{m}(t)\right) d t \\
& =(m+2)^{-1} f(1)=(m+2)^{-1} \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)
\end{aligned}
$$

Hence, by (A.1.8), we obtain the following fundamental inequalities between the multiplier Hermitian analogues of Aubin's functionals:

Proposition A.1. $0 \leq \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right) \leq(m+2)\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right) \leq$ $(m+1) \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)$ for all $\omega^{\prime}, \omega^{\prime \prime} \in \mathcal{K}_{X}$, where $m:=n-1+b_{\sigma}$.

Remark A.1.9. Suppose that $\sigma(s)=-\log (s+C), s \in I_{X}$, for some real constant $C>-\alpha_{X}$. Then by Remark A.1.7, we can improve the estimate as follows:

$$
0 \leq \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right) \leq(n+2)\left(\mathcal{I}^{\sigma}-\mathcal{J}^{\sigma}\right)\left(\omega^{\prime}, \omega^{\prime \prime}\right) \leq(n+1) \mathcal{I}^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)
$$

## Appendix 2. K-energy maps for multiplier Hermitian metrics

In this appendix, we shall define a multiplier Hermitian analogue $\mu^{\sigma}$ : $\mathcal{K}_{X} \rightarrow \mathbb{R}$ of the K-energy map, where the Kähler class of $\mathcal{K}$ is assumed to be $2 \pi c_{1}(M)_{\mathbb{R}}$. As in (2.8) in Section 2, we have functions $\tilde{f}_{\omega} \in \mathcal{K}_{X}, \omega \in \mathcal{K}_{X}$, such that

$$
\left\{\begin{array}{l}
\operatorname{Ric}^{\sigma}(\omega)-\omega=\sqrt{-1} \partial \bar{\partial} \tilde{f}_{\omega}  \tag{A.2.1}\\
\tilde{f}_{\omega}:=f_{\omega}+\psi_{\omega}+\log \left(\frac{\int_{M} \tilde{\omega}_{0}^{n}}{\int_{M} \omega_{0}^{n}}\right)=f_{\omega}+\sigma\left(u_{\omega}\right)+\log \left(\frac{\int_{M} \tilde{\omega}_{0}^{n}}{\int_{M} \omega_{0}^{n}}\right)
\end{array}\right.
$$

where $f_{\omega}$ is as in (2.8). For $\omega^{\prime}$ and $\omega^{\prime \prime}$ in $\mathcal{K}_{X}$, let $\left\{\varphi_{t} ; a \leq t \leq b\right\}$ be an arbitrary smooth path in $\mathcal{H}_{X}$ such that $\omega(a)=\omega^{\prime}$ and $\omega(b)=\omega^{\prime \prime}$, where we put

$$
\begin{equation*}
\omega(t):=\omega_{\varphi_{t}}=\omega_{0}+\sqrt{-1} \partial \bar{\partial} \varphi_{t}, \quad a \leq t \leq b \tag{A.2.2}
\end{equation*}
$$

Lemma A.2.3. In the below, we use the notation (1.4), and in particular, $\tilde{\omega}(t)$ is as in (2.3). Then the integral $M^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)$ defined below depends only on the pair $\left(\omega^{\prime}, \omega^{\prime \prime}\right)$, and is independent of the choice of the path $\left\{\varphi_{t} ; a \leq t \leq b\right\}$ in $\mathcal{H}_{X}$ :

$$
\begin{aligned}
M^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right) & :=\int_{a}^{b}\left\{\int_{M}\left(\bar{\partial} \tilde{f}_{\omega(t)}, \bar{\partial} \dot{\varphi}_{t}\right)_{\omega(t)} \tilde{\omega}(t)^{n}\right\} \\
& =-\int_{a}^{b}\left\{\int_{M} \tilde{f}_{\eta_{t}}\left(\tilde{\square}_{\omega(t)} \dot{\varphi}_{t}\right) \tilde{\omega}(t)^{n}\right\}
\end{aligned}
$$

Proof. Let $[0,1] \times[a, b] \ni(s, t) \mapsto \varphi_{s, t} \in \mathcal{H}_{X}$ be a smooth 2-parameter family of functions in $\mathcal{H}_{X}$. Then $\eta_{s, t}:=\omega_{\varphi_{s, t}}$ sits in $\mathcal{K}_{X}$ for all $(s, t)$. For simplicity, $f_{\eta_{s, t}}, \tilde{f}_{\eta_{s, t}}, \psi_{\eta_{s, t}}, u_{\eta_{s, t}}, \square_{\eta_{s, t}}, \tilde{\square}_{\eta_{s, t}}$ are denoted by $f_{s, t}, \tilde{f}_{s, t}, \psi_{s, t}$, $u_{s, t}, \square_{s, t}, \tilde{\square}_{s, t}$, respectively. We define

$$
\Theta:=\left\{\int_{M} \tilde{f}_{s, t}\left(\tilde{\square}_{s, t} \partial_{s} \varphi\right) \tilde{\omega}_{s, t}^{n}\right\} d s+\left\{\int_{M} \tilde{f}_{s, t}\left(\tilde{\square}_{s, t} \partial_{t} \varphi\right) \tilde{\omega}_{s, t}^{n}\right\} d t
$$

where $\partial_{s} \varphi:=\partial \varphi_{s, t} / \partial s$ and $\partial_{t} \varphi:=\partial \varphi_{s, t} / \partial t$. Then the proof is reduced to showing $d \Theta=0$ on $[0,1] \times[a, b]$. By $\tilde{\square}_{s, t}=\square_{s, t}+\sqrt{-1} \dot{\sigma}\left(u_{s, t}\right) \bar{X}$ and [M5, (2.6.1)],

$$
\begin{aligned}
\frac{\partial}{\partial t} & \left(\tilde{\square}_{s, t} \partial_{s} \varphi\right)-\frac{\partial}{\partial s}\left(\tilde{\square}_{s, t} \partial_{t} \varphi\right) \\
& =\sqrt{-1} \frac{\partial}{\partial t}\left\{\dot{\sigma}\left(u_{s, t}\right) \bar{X}\left(\partial_{s} \varphi\right)\right\}-\sqrt{-1} \frac{\partial}{\partial s}\left\{\dot{\sigma}\left(u_{s, t}\right) \bar{X}\left(\partial_{t} \varphi\right)\right\} \\
& =\sqrt{-1} \ddot{\sigma}\left(u_{s, t}\right) \frac{\partial u_{s, t}}{\partial t} \bar{X}\left(\partial_{s} \varphi\right)-\sqrt{-1} \ddot{\sigma}\left(u_{s, t}\right) \frac{\partial u_{s, t}}{\partial s} \bar{X}\left(\partial_{t} \varphi\right) \\
& =\ddot{\sigma}\left(u_{s, t}\right) \bar{X}\left(\partial_{t} \varphi\right) \bar{X}\left(\partial_{s} \varphi\right)-\ddot{\sigma}\left(u_{s, t}\right) \bar{X}\left(\partial_{s} \varphi\right) \bar{X}\left(\partial_{t} \varphi\right)=0
\end{aligned}
$$

where we used the equality $u_{s, t}=u_{\omega_{0}}-\sqrt{-1} \bar{X} \varphi_{s, t}$ (see Section 2). Hence, by $(\partial / \partial t)\left(\tilde{\omega}_{s, t}^{n}\right)=\left(\tilde{\square}_{s, t} \partial_{t} \varphi\right) \tilde{\omega}_{s, t}^{n}$ and $(\partial / \partial s)\left(\tilde{\omega}_{s, t}^{n}\right)=\left(\tilde{\square}_{s, t} \partial_{s} \varphi\right) \tilde{\omega}_{s, t}^{n}$, we obtain

$$
\begin{equation*}
d \Theta=d s \wedge d t \int_{M}\left\{-\frac{\partial \tilde{f}_{s, t}}{\partial t}\left(\tilde{\square}_{s, t} \partial_{s} \varphi\right)+\frac{\partial \tilde{f}_{s, t}}{\partial s}\left(\tilde{\square}_{s, t} \partial_{t} \varphi\right)\right\} \tilde{\omega}_{s, t}^{n} . \tag{A.2.4}
\end{equation*}
$$

On the other hand,

$$
\frac{\partial f_{s, t}}{\partial t}=-\left(\square_{s, t}+1\right) \partial_{t} \varphi+C_{s, t}^{\prime} \quad \text { and } \quad \frac{\partial f_{s, t}}{\partial s}=-\left(\square_{s, t}+1\right) \partial_{s} \varphi+C_{s, t}^{\prime \prime}
$$

for some real constants $C_{s, t}^{\prime}$ and $C_{s, t}^{\prime \prime}$ depending only on $s$ and $t$. Hence, by $\psi_{s, t}=\sigma\left(u_{s, t}\right)=\sigma\left(u_{\omega_{0}}-\sqrt{-1} \bar{X} \varphi_{s, t}\right)$, we see that

$$
\left\{\begin{array}{l}
\frac{\partial \tilde{f}_{s, t}}{\partial t}=-\left(\square_{s, t}+1\right) \partial_{t} \varphi+\frac{\partial \psi_{s, t}}{\partial t}+C_{s, t}^{\prime}=-\left(\tilde{\square}_{s, t}+1\right) \partial_{t} \varphi+C_{s, t}^{\prime}  \tag{A.2.5}\\
\frac{\partial \tilde{f}_{s, t}}{\partial s}=-\left(\square_{s, t}+1\right) \partial_{s} \varphi+\frac{\partial \psi_{s, t}}{\partial s}+C_{s, t}^{\prime \prime}=-\left(\tilde{\square}_{s, t}+1\right) \partial_{s} \varphi+C_{s, t}^{\prime \prime}
\end{array}\right.
$$

By (A.2.4) and (A.2.5), we finally obtain the following required identity:

$$
d \Theta=d s \wedge d t \int_{M}\left\{\partial_{t} \varphi\left(\tilde{\square}_{s, t} \partial_{s} \varphi\right)-\partial_{s} \varphi\left(\tilde{\square}_{s, t} \partial_{t} \varphi\right)\right\} \tilde{\omega}_{s, t}^{n}=0 .
$$

By Lemma A.2.3 above, for all $\omega, \omega^{\prime}, \omega^{\prime \prime} \in \mathcal{K}_{X}$, it is easily seen that $M^{\sigma}$ satisfies the 1-cocycle conditions

$$
\left\{\begin{array}{l}
M^{\sigma}\left(\omega, \omega^{\prime}\right)+M^{\sigma}\left(\omega^{\prime}, \omega\right)=0 \\
M^{\sigma}\left(\omega, \omega^{\prime}\right)+M^{\sigma}\left(\omega^{\prime}, \omega^{\prime \prime}\right)+M^{\sigma}\left(\omega^{\prime \prime}, \omega\right)=0
\end{array}\right.
$$

As a multiplier Hermitian analogue of a K-energy map, we can now define $\mu^{\sigma}: \mathcal{K}_{X} \rightarrow \mathbb{R}$ by setting $\mu^{\sigma}(\omega):=M^{\sigma}\left(\omega_{0}, \omega\right)$ for all $\omega \in \mathcal{K}_{X}$. As in the introduction, let $\mathcal{E}_{X}^{\sigma}$ denote the set of all $\omega$ in $\mathcal{K}_{X}$ such that $\operatorname{Ric}^{\sigma}(\omega)=\omega$. Then by (A.2.1) and Lemma A.2.3 together with (b) of Lemma 2.9, we obtain

Proposition A.2. (a) An element $\omega$ in $\mathcal{K}_{X}$ is a critical point of $\mu_{\sigma}$ : $\mathcal{K}_{X} \rightarrow \mathbb{R}$ if and only if $\omega \in \mathcal{E}_{X}^{\sigma}$, i.e., the function $\tilde{f}_{\omega}$ defined in (A.2.1) is zero everywhere on $M$.
(b) For an arbitrary smooth path $\left\{\varphi_{t} ; a \leq t \leq b\right\}$ in $\mathcal{H}_{X}$, the oneparameter family of Kähler forms $\omega(t), a \leq t \leq b$, in $\mathcal{K}_{X}$ defined by (A.2.2) satisfies

$$
\frac{d}{d t} \mu^{\sigma}(\omega(t))=\int_{M}\left(\bar{\partial} \tilde{f}_{\omega(t)}, \bar{\partial} \dot{\varphi}_{t}\right)_{\omega(t)} \tilde{\omega}(t)^{n}, \quad a \leq t \leq b
$$

## Appendix 3. Technical equalities related to the operator $\tilde{\square}_{\omega}$

In this appendix, related to the operator $\tilde{\square}_{\omega}$, some technical equalities analogous to those in [BM, Lemma 2.3] will be given. Note that, by the notation in (2.6) and Appendix 5, we have the inclusion $\operatorname{Ker}_{\mathbb{R}}\left(\tilde{\square}_{\omega}+1\right) \subset \mathfrak{g}^{\omega}$ for all $\omega \in \mathcal{E}_{X}^{\sigma}$. Now, we have:

Proposition A.3. Let $\omega \in \mathcal{E}_{X}^{\sigma}$ and $\zeta \in C^{\infty}(M)_{\mathbb{R}}$. Then for all $v, v_{1}, v_{2} \in \operatorname{Ker}_{\mathbb{R}}\left(\tilde{\square}_{\omega}+1\right)$,

$$
\begin{equation*}
\tilde{\square}_{\omega}(\partial \zeta, \partial v)_{\omega}=(\partial \bar{\partial} \zeta, \partial \bar{\partial} v)_{\omega}+\left(\partial\left(\tilde{\square}_{\omega} \zeta\right), \partial v\right)_{\omega}-\ddot{\sigma}\left(u_{\omega}\right)(\bar{X} \zeta)(\bar{X} v) . \tag{A.3.1}
\end{equation*}
$$

In particular, $\left(\tilde{\square}_{\omega}+1\right)\left(\partial v_{1}, \partial v_{2}\right)_{\omega}=\left(\partial \bar{\partial} v_{1}, \partial \bar{\partial} v_{2}\right)_{\omega}-\ddot{\sigma}\left(u_{\omega}\right)\left(\bar{X} v_{1}\right)\left(\bar{X} v_{2}\right)=$ $\left(\tilde{\square}_{\omega}+1\right)\left(\partial v_{2}, \partial v_{1}\right)_{\omega}$, and

$$
\begin{align*}
& \int_{M}\left\{v_{1} v_{2}-\left(\partial v_{1}, \partial v_{2}\right)_{\omega}\right\}\left\{\left(\tilde{\square}_{\omega}+1\right) \zeta\right\} \tilde{\omega}^{n}  \tag{A.3.2}\\
& \quad=-\int_{M} v_{1}\left(\partial \bar{\partial} \zeta, \partial \bar{\partial} v_{2}\right)_{\omega} \tilde{\omega}^{n}+\int_{M} \ddot{\sigma}\left(u_{\omega}\right) v_{1}(\bar{X} \zeta)\left(\bar{X} v_{2}\right) \tilde{\omega}^{n}
\end{align*}
$$

Proof. (A.3.1) follows from (1.3) and [BM, (2.3.1)] in view of the following identities:

$$
\begin{aligned}
& \left(\partial\left\{\sqrt{-1} \dot{\sigma}\left(u_{\omega}\right) \bar{X} \zeta\right\}, \partial v\right)_{\omega}-\sqrt{-1} \dot{\sigma}\left(u_{\omega}\right) \bar{X}(\partial \zeta, \partial v)_{\omega} \\
& \quad=(\bar{X} \zeta) \ddot{\sigma}\left(u_{\omega}\right) \sqrt{-1}\left(\partial u_{\omega}, \partial v\right)_{\omega}=\ddot{\sigma}\left(u_{\omega}\right)(\bar{X} \zeta)(\bar{X} v)
\end{aligned}
$$

For (A.3.2), put $\xi:=\left(\tilde{\square}_{\omega}+1\right) \zeta$. Then following [BM, p. 21], by (1.3) and (1.4), we obtain

$$
\begin{aligned}
& \int_{M}\left\{v_{1} v_{2}-\left(\partial v_{1}, \partial v_{2}\right)_{\omega}\right\} \xi \tilde{\omega}^{n}=-\int_{M}\left\{v_{1}\left(\tilde{\square}_{\omega} v_{2}\right)+\left(\partial v_{1}, \partial v_{2}\right)_{\omega}\right\} \xi \tilde{\omega}^{n} \\
&=-\sqrt{-1} \int_{M}\left(v_{1} \partial \bar{\partial} v_{2}\right.\left.+\partial v_{1} \wedge \bar{\partial} v_{2}\right) \xi \wedge n e^{-\psi_{\omega} \omega^{n-1}} \\
&+\int_{M} v_{1}\left(\partial \psi_{\omega}, \partial v_{2}\right)_{\omega} \xi e^{-\psi_{\omega}} \omega^{n} \\
&=-\sqrt{-1} \int_{M} \partial\left(v_{1} \bar{\partial} v_{2}\right) \xi \wedge n e^{-\psi_{\omega} \omega^{n-1}} \\
&+\sqrt{-1} \int_{M} v_{1}\left(\partial \psi_{\omega} \wedge \bar{\partial} v_{2}\right) \xi \wedge n e^{-\psi_{\omega} \omega^{n-1}} \\
&=\sqrt{-1} \int_{M} v_{1} \partial \xi \wedge \bar{\partial} v_{2} \wedge n e^{-\psi_{\omega}} \omega^{n-1}=\int_{M} v_{1}\left(\partial \xi, \partial v_{2}\right)_{\omega} \tilde{\omega}^{n}
\end{aligned}
$$

$$
=\int_{M} v_{1}\left(\partial\left(\tilde{\square}_{\omega} \zeta\right), \partial v_{2}\right)_{\omega} \tilde{\omega}^{n}+\int_{M} v_{1}\left(\partial \zeta, \partial v_{2}\right)_{\omega} \tilde{\omega}^{n}
$$

This together with (A.3.1) above implies the required identity (A.3.2) as follows:

$$
\begin{aligned}
\int_{M} & \left\{v_{1} v_{2}-\left(\partial v_{1}, \partial v_{2}\right)_{\omega}\right\} \xi \tilde{\omega}^{n}+\int_{M}\left(\partial \bar{\partial} \zeta, \partial \bar{\partial} v_{2}\right)_{\omega} v_{1} \tilde{\omega}^{n} \\
& =\int_{M}\left\{\tilde{\square}_{\omega}\left(\partial \zeta, \partial v_{2}\right)_{\omega}+\ddot{\sigma}\left(u_{\omega}\right)(\bar{X} \zeta)\left(\bar{X} v_{2}\right)\right\} v_{1} \tilde{\omega}^{n}+\int_{M} v_{1}\left(\partial \zeta, \partial v_{2}\right)_{\omega} \tilde{\omega}^{n} \\
& =\int_{M}\left(\partial \zeta, \partial v_{2}\right)_{\omega} \overline{\left\{\left(\tilde{\square}_{\omega}+1\right) v_{1}\right\}} \tilde{\omega}^{n}+\int_{M} \ddot{\sigma}\left(u_{\omega}\right) v_{1}(\bar{X} \zeta)\left(\bar{X} v_{2}\right) \tilde{\omega}^{n} \\
& =\int_{M} \ddot{\sigma}\left(u_{\omega}\right) v_{1}(\bar{X} \zeta)\left(\bar{X} v_{2}\right) \tilde{\omega}^{n}
\end{aligned}
$$

## Appendix 4. Uniqueness of solutions for equations of CalabiYau's type

Fix $\omega_{0} \in \mathcal{K}_{X}$ and $\sigma \in C^{\infty}\left(I_{X}\right)_{\mathbb{R}}$ as in the introduction, and let $V_{0}$ be as in Lemma 2.4. In this appendix, we discuss the following equation of Calabi-Yau's type:

$$
\begin{equation*}
\operatorname{Ric}^{\sigma}(\omega)=\omega_{0} \tag{A.4.1}
\end{equation*}
$$

Here, any solution $\omega$ of (A.4.1) is required to belong to $\mathcal{K}_{X}$. The purpose of this appendix is to show the following uniqueness:

Proposition A.4. The equation (A.4.1) has a unique solution $\omega$ in $\mathcal{K}_{X}$.

Before getting into the proof, we give some remark. Let $0<\alpha<1$, and we consider the mapping $\Gamma: \mathcal{H}_{X, 0}^{2, \alpha} \times \mathbb{R} \rightarrow C_{0}^{0, \alpha}(M)_{\mathbb{R}}$ defined in (5.1.2) by

$$
\Gamma(\varphi, t):=A(\varphi)-\left\{\frac{1}{V_{0}} \int_{M} \exp \left(-t \varphi+\tilde{f}_{\omega_{0}}\right) \tilde{\omega}_{0}^{n}\right\}^{-1} \exp \left(-t \varphi+\tilde{f}_{\omega_{0}}\right)
$$

where $V_{0}:=\int_{M} \tilde{\omega}^{n}$ and $A(\varphi):=\tilde{\omega}_{\varphi}^{n} / \tilde{\omega}_{0}^{n}$. Note that, if $(\varphi, t) \in \mathcal{H}_{X, 0}^{2, \alpha} \times \mathbb{R}$ satisfies $\Gamma(\varphi, t)=0$, then $\varphi$ automatically belongs to $C^{\infty}(M)_{\mathbb{R}}$. Hence, it is easily seen that the set of the solutions of (A.4.1) and the set of the solutions of $\Gamma(\varphi, 0)=0$ are identified by

$$
\begin{equation*}
\left\{\varphi \in \mathcal{H}_{X, 0}^{2, \alpha} ; \Gamma(\varphi, 0)=0\right\} \simeq\left\{\omega \in \mathcal{K}_{X} ; \operatorname{Ric}^{\sigma}(\omega)=\omega_{0}\right\}, \quad \varphi \leftrightarrow \omega_{\varphi} \tag{A.4.2}
\end{equation*}
$$

Proof of Proposition A.4. By (A.4.2), it suffices to show that $\varphi \in \mathcal{H}_{X, 0}^{2, \alpha}$ satisfying $\Gamma(\varphi, 0)=0$ is unique. Suppose that $\varphi^{\prime}, \varphi^{\prime \prime}$ in $\mathcal{H}_{X, 0}^{2, \alpha}$ satisfy

$$
\Gamma\left(\varphi^{\prime}, 0\right)=0=\Gamma\left(\varphi^{\prime \prime}, 0\right)
$$

Since the Fréchet derivatives $D_{\varphi} \Gamma_{\mid\left(\varphi^{\prime}, 0\right)}, D_{\varphi} \Gamma_{\mid\left(\varphi^{\prime \prime}, 0\right)}$ are invertible (cf. (5.1.5)), we have smooth one-parameter families $\left\{\varphi_{t}^{\prime} ;-\varepsilon<t \leq 0\right\}$, $\left\{\varphi_{t}^{\prime \prime} ;-\varepsilon<t \leq 0\right\}$ (where $0<\varepsilon \ll 1$ ) of functions in $\mathcal{H}_{X, 0}^{k, \alpha}$ satisfying $\varphi_{0}^{\prime}=\varphi^{\prime}$ and $\varphi_{0}^{\prime \prime}=\varphi^{\prime \prime}$ such that $\Gamma\left(\varphi_{t}^{\prime}, t\right)=0=\Gamma\left(\varphi_{t}^{\prime \prime}, t\right)$ for all $t$ with $-\varepsilon<t \leq 0$. Put

$$
e_{t}^{\prime}:=\frac{1}{V_{0}} \int_{M} \exp \left(-t \varphi_{t}^{\prime}+\tilde{f}_{\omega_{0}}\right) \tilde{\omega}_{0}^{n} \quad \text { and } \quad e_{t}^{\prime \prime}:=\frac{1}{V_{0}} \int_{M} \exp \left(-t \varphi_{t}^{\prime \prime}+\tilde{f}_{\omega_{0}}\right) \tilde{\omega}_{0}^{n}
$$

For $t=0$, (b) of Lemma 2.9 yields $e_{0}^{\prime}=1$ and $e_{0}^{\prime \prime}=1$, and hence we can find $c_{t}^{\prime}, c_{t}^{\prime \prime} \in \mathbb{R},-\varepsilon<t \leq 0$, depending on $t$ continuously such that $e_{t}^{\prime}=\exp \left(t c_{t}^{\prime}\right)$ and $e_{t}^{\prime \prime}=\exp \left(t c_{t}^{\prime \prime}\right)$ for all $t$ with $-\varepsilon<t \leq 0$. Then by setting $\xi_{t}^{\prime}:=\varphi_{t}^{\prime}+c_{t}^{\prime}$ and $\xi_{t}^{\prime \prime}:=\varphi_{t}^{\prime \prime}+c_{t}^{\prime \prime}$, we have

$$
\begin{equation*}
A\left(\xi_{t}^{\prime}\right)=\exp \left(-t \xi_{t}^{\prime}+\tilde{f}_{\omega_{0}}\right) \quad \text { and } \quad A\left(\xi_{t}^{\prime \prime}\right)=\exp \left(-t \xi_{t}^{\prime \prime}+\tilde{f}_{\omega_{0}}\right) \tag{A.4.3}
\end{equation*}
$$

For simplicity, we put $\omega_{t}^{\prime}:=\omega_{\xi_{t}^{\prime}}$ and $\omega_{t}^{\prime \prime}:=\omega_{\xi_{t}^{\prime \prime}}(-\varepsilon<t \leq 0)$. Note that, by (2.5), $\psi_{\omega_{t}^{\prime}}=\sigma\left(u_{\omega_{t}^{\prime}}\right)=\sigma\left(u_{\omega_{0}}-\sqrt{-1} \bar{X} \xi_{t}^{\prime}\right)$ and $\psi_{\omega_{t}^{\prime \prime}}=\sigma\left(u_{\omega_{0}}-\sqrt{-1} \bar{X} \xi_{t}^{\prime \prime}\right)=$ $\sigma\left(u_{\omega_{t}^{\prime}}-\sqrt{-1} \bar{X}\left(\xi_{t}^{\prime \prime}-\xi_{t}^{\prime}\right)\right)$, while $A\left(\xi_{t}^{\prime \prime}\right) / A\left(\xi_{t}^{\prime}\right)=\left\{e^{-\psi_{\omega_{t}^{\prime \prime}}}\left(\omega_{t}^{\prime \prime}\right)^{n}\right\} /\left\{e^{-\psi_{\omega_{t}^{\prime}}}\left(\omega_{t}^{\prime}\right)^{n}\right\}$. For each $t$ with $-\varepsilon<t<0$, let $p_{t}$ be the point on $M$ at which the function $\xi_{t}^{\prime \prime}-\xi_{t}^{\prime}$ on $M$ takes its maximum. Then by (A.4.3), the maximum principle shows that

$$
1 \geq\left\{A\left(\xi_{t}^{\prime \prime}\right) / A\left(\xi_{t}^{\prime}\right)\right\}\left(p_{t}\right)=\exp \left\{-t\left(\xi_{t}^{\prime \prime}-\xi_{t}^{\prime}\right)\left(p_{t}\right)\right\}
$$

Then $\left(\xi_{t}^{\prime \prime}-\xi_{t}^{\prime}\right)(p) \leq\left(\xi_{t}^{\prime \prime}-\xi_{t}^{\prime}\right)\left(p_{t}\right) \leq 0$ for all $p \in M$, i.e., $\xi_{t}^{\prime \prime} \leq \xi_{t}^{\prime}$ on $M$. By exactly the same argument, we have $\xi_{t}^{\prime} \leq \xi_{t}^{\prime \prime}$ on $M$. Hence, $\xi_{t}^{\prime \prime}=\xi_{t}^{\prime}$ on $M$ for all $t$ with $-\varepsilon<t<0$. Let $t$ tend to 0 . By passing to the limit, we see that $\xi_{0}^{\prime \prime}=\xi_{0}^{\prime}$, i.e., $\varphi^{\prime \prime}-\varphi^{\prime}$ is a constant on $M$. Then by $\varphi^{\prime}, \varphi^{\prime \prime} \in \mathcal{H}_{X, 0}^{2, \alpha}$, we immediately obtain $\varphi^{\prime \prime}=\varphi^{\prime}$ on $M$, as required.

## Appendix 5. A multiplier Hermitian analogue of Matsushima's obstruction

In this appendix, Matsushima's obstruction [Mat] will be generalized for multiplier Hermitian metrics of type $\sigma$, where $\sigma$ is an arbitrary realvalued function on $I_{X}$. Assuming $\mathcal{E}_{X}^{\sigma} \neq \emptyset$, let $\theta \in \mathcal{E}_{X}^{\sigma}$. Write

$$
\theta=\sqrt{-1} \sum_{\alpha, \beta} g(\theta)_{\alpha \bar{\beta}} d z^{\alpha} \wedge d z^{\bar{\beta}}
$$

in terms of a system $\left(z^{1}, z^{2}, \ldots, z^{n}\right)$ of holomorphic local coordinates on $M$. Since $\operatorname{Ric}^{\sigma}(\theta)=\theta$, the Kähler class of $\mathcal{K}_{X}$ is $2 \pi c_{1}(M)_{\mathbb{R}}$. Then by (2.8) and (a) of Lemma 2.9,

$$
\begin{equation*}
f_{\theta}=-\psi_{\theta}+C_{0} \tag{A.5.1}
\end{equation*}
$$

for some real constant $C_{0}$. By [F1, p. 41], $\mathfrak{g}^{\theta}$ in (2.6) coincides with the kernel $\operatorname{Ker}_{\mathbb{C}}\left(\tilde{\square}_{\theta}+1\right)$ of the operator $\tilde{\square}_{\theta}+1$ on $C^{\infty}(M)_{\mathbb{C}}$, since by (A.5.1), $\tilde{\square}_{\theta}$ is written in the form

$$
\tilde{\square}_{\theta}=\square_{\theta}+\sum_{\alpha, \beta} g(\theta)^{\bar{\beta} \alpha} \frac{\partial f_{\theta}}{\partial z^{\alpha}} \frac{\partial}{\partial z^{\bar{\beta}}}
$$

Lemma A.5.2. The vector space $\mathfrak{g}^{\theta}$ in (2.6) forms a complex Lie algebra in terms of the Poisson bracket by $\theta$, and in particular the $\mathbb{C}$-linear isomorphism $\mathfrak{g}^{\theta} \cong \mathfrak{g}$ in (2.6) is an isomorphism of complex Lie algebras.

Proof. For each $v_{1}, v_{2} \in C^{\infty}(M)_{\mathbb{C}}$, we consider their Poisson bracket $\left[v_{1}, v_{2}\right] \in C^{\infty}(M)_{\mathbb{C}}$ on the Kähler manifold $(M, \theta)$ as in $[F M]$. Let $u_{1}, u_{2} \in$ $\mathfrak{g}^{\theta}$. Then by $\operatorname{grad}_{\theta}^{\mathbb{C}}\left[u_{1}, u_{2}\right]=\left[\operatorname{grad}_{\theta}^{\mathbb{C}} u_{1}, \operatorname{grad}_{\theta}^{\mathbb{C}} u_{2}\right]$, we see that $\left[u_{1}, u_{2}\right]+k_{0}$ belongs to $\mathfrak{g}^{\theta}$ for some constant $k_{0} \in \mathbb{C}$. Hence it suffices to show $k_{0}=0$, i.e.,

$$
\int_{M}\left[u_{1}, u_{2}\right] \tilde{\theta}^{n}=0
$$

Let $F: \mathfrak{g} \rightarrow \mathbb{C}$ be the Futaki character. Then by $[F M,(2.1)]$ and $[\mathrm{M} 1$, Theorem 2.1], we see that $\int_{M}\left(1-e^{f_{\theta}}\right)\left[u_{1}, u_{2}\right] \theta^{n}=F\left(\left[\operatorname{grad}_{\theta}^{\mathbb{C}} u_{1}, \operatorname{grad}_{\theta}^{\mathbb{C}} u_{2}\right]\right)=$ 0 . Therefore, in view of (A.5.1), we obtain

$$
\int_{M}\left[u_{1}, u_{2}\right] \tilde{\theta}^{n}=\exp \left(-C_{0}\right) \int_{M}\left[u_{1}, u_{2}\right] e^{f_{\theta}} \theta^{n}=\exp \left(-C_{0}\right) \int_{M}\left[u_{1}, u_{2}\right] \theta^{n}=0
$$

as required.
For the centralizer $\mathfrak{z}(X)$ of $X$ in $\mathfrak{g}$, the group $Z^{0}(X)$ in the introduction is exactly the complex Lie group generated by $\mathfrak{z}(X)$ in $G$. Consider the Lie subalgebra $\mathfrak{k}$ of $\mathfrak{z}(X)$ associated to the group $K$ of all isometries in $Z^{0}(X)$ on the Kähler manifold $(M, \theta)$. Let $\mathfrak{k}_{\mathbb{C}}$ be the complexification of $\mathfrak{k}$ in the complex Lie algebra $\mathfrak{g}$. Put

$$
\left\{\begin{align*}
\mathfrak{z}^{\theta}(X) & :=\left\{u \in \operatorname{Ker}_{\mathbb{C}}\left(\tilde{\square}_{\theta}+1\right) ; X_{\mathbb{R}} u=0\right\}  \tag{A.5.3}\\
\mathfrak{k}^{\theta} & :=\left\{u \in \operatorname{Ker}_{\mathbb{R}}\left(\tilde{\square}_{\theta}+1\right) ; X_{\mathbb{R}} u=0\right\}
\end{align*}\right.
$$

where $\operatorname{Ker}_{\mathbb{R}}\left(\tilde{\square}_{\theta}+1\right)$ denotes the kernel of the operator $\left(\tilde{\square}_{\theta}+1\right)$ on $C^{\infty}(M)_{\mathbb{R}}$. Put $\mathfrak{k}_{\mathbb{C}}^{\theta}:=\mathfrak{k}^{\theta}+\sqrt{-1} \mathfrak{k}^{\theta}$ in $C^{\infty}(M)_{\mathbb{C}}$. Then by $\mathfrak{k}_{\mathbb{C}}^{\theta} \subset \mathfrak{z}^{\theta}(X) \subset \mathfrak{g}^{\theta}$ and $\mathfrak{g}^{\theta} \cong \mathfrak{g}$, we obtain

$$
\begin{equation*}
\mathfrak{k}_{\mathbb{C}} \subset \mathfrak{z}(X) \tag{A.5.4}
\end{equation*}
$$

Note that $Z(X)$ acts on $\mathcal{E}_{X}^{\sigma}$ by $Z(X) \times \mathcal{E}_{X}^{\sigma} \ni(g, \theta) \mapsto\left(g^{-1}\right)^{*} \theta \in \mathcal{E}_{X}^{\sigma}$. Since the isotropy subgroup of $Z^{0}(X)$ at $\theta$ is $K$, we can write the $Z^{0}(X)$-orbit $\mathbf{O}$ through $\theta$ as

$$
\begin{equation*}
\mathbf{O} \cong Z^{0}(X) / K \tag{A.5.5}
\end{equation*}
$$

Let $T_{\theta}\left(\mathcal{E}_{X}^{\sigma}\right)$ and $T_{\theta}(\mathbf{O})$ denote the tangent spaces at $\theta$ of $\mathcal{E}_{X}^{\sigma}$ and $\mathbf{O}$, respectively. In view of the homeomorphism $\tilde{\mathcal{E}}_{X}^{\sigma} \simeq \mathcal{E}_{X}^{\sigma}$ immediately after (5.4.1) in Section 5 , the differentiation of the equation $A(\varphi)=\exp \left(-\varphi+\tilde{f}_{0}\right)$ with respect to $\varphi$ yields

$$
\begin{array}{rlll}
T_{\theta}\left(\mathcal{E}_{X}^{\sigma}\right) & \cong & \mathfrak{k}_{\mathbb{C}} / \mathfrak{k} & \cong \mathfrak{k}^{\theta} \quad\left(=T_{\theta}\left(\tilde{\mathcal{E}}_{X}^{\sigma}\right)\right)  \tag{A.5.6}\\
\sqrt{-1} \partial \bar{\partial} v & \leftrightarrow & {\left[\sqrt{-1} \operatorname{grad}_{\theta}^{\mathbb{C}} v / 2\right]} & \leftrightarrow v
\end{array}
$$

where for every $\gamma$ in $\mathfrak{k}_{\mathbb{C}}$, we mean by $[\gamma]$ the natural image of $\gamma$ under the projection of $\mathfrak{k}_{\mathbb{C}}$ onto $\mathfrak{k}_{\mathbb{C}} / \mathfrak{k}$. On the other hand, by (A.5.5), we have the isomorphism

$$
\begin{equation*}
T_{\theta}(\mathbf{O}) \cong \mathfrak{z}(X) / \mathfrak{k} \tag{A.5.7}
\end{equation*}
$$

Since $\mathbf{O} \subset \mathcal{E}_{X}^{\sigma}$, we have $T_{\theta}(\mathbf{O}) \subset T_{\theta}\left(\mathcal{E}_{X}^{\sigma}\right)$. This together with (A.5.4), (A.5.6) and (A.5.7) implies that $\mathfrak{z}(X)=\mathfrak{k}_{\mathbb{C}}$, i.e., $T_{\theta}(\mathbf{O})=T_{\theta}\left(\mathcal{E}_{X}^{\sigma}\right)$. Thus, we obtain

Proposition A.5. (a) If $\mathcal{E}_{X}^{\sigma} \neq \emptyset$, then $Z^{0}(X)$ is a reductive algebraic group. Actually for an arbitrary $\theta \in \mathcal{E}_{X}^{\sigma}$, we have $\mathfrak{z}(X)=\mathfrak{k}_{\mathbb{C}}$, i.e., $\mathfrak{z}^{\theta}(X)=$ $\mathfrak{k}_{\mathbb{C}}^{\theta}$ by the above notation.
(b) If $\mathcal{E}_{X}^{\sigma} \neq \emptyset$, then each connected component of $\mathcal{E}_{X}^{\sigma}$ is a single $Z^{0}(X)$ orbit under the natural action of $Z^{0}(X)$ on $\mathcal{E}_{X}^{\sigma}$.

Remark A.5.8. The above arguments are valid also for $X=0$. If $X=0$, then (a) of Proposition A. 5 is nothing but Matsushima's theorem [Mat].

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[^0]:    ${ }^{\dagger}$ For a similar result on Kähler-Ricci solitons, see [TZ1]. For "Kähler-Einstein metrics" in the sense of [M1], the arguments in Section 5 were given at the meeting in 1997 at ICMS, though at that time a crucial gap in a priori $C^{0}$ estimates was pointed out by G. Tian. Theorems A and B above solve this gap.

