# COHOMOLOGY OF SUBGROUPS OF FINITE INDEX OF $S L(3, \mathrm{Z})$ AND $S L(4, \mathrm{Z})$ <br> BY AVNER ASH <br> Communicated by Hyman Bass, November 10, 1976 

Let $S L(n, \mathbf{Z})(p)$ for $n \geqslant 2$ and $p \geqslant 3$ denote the kernel of the reduction modulo $p: S L(n, \mathbf{Z}) \rightarrow S L(n, \mathbf{Z} / p)$. The integral homology and cohomology of $\operatorname{SL}(3, \mathbf{Z})(3)$ have been entirely computed in [1]. On p. 28 the authors make a conjecture that would imply that $H^{3}(S L(3, \mathbf{Z})(p), \mathbf{Z}) \simeq H_{1}(T / S L(3, \mathbf{Z})(p), \mathbf{Z})$, where $T$ is the Tits building associated to $\operatorname{SL}(3, \mathbf{Q}), \operatorname{SL}(3, \mathbf{Z})(p)$ acts naturally on it, and $p$ is prime. This conjecture is wrong.

Theorem 1. There is a natural surjective map

$$
H^{3}(S L(3, \mathbf{Z})(p), \mathbf{R}) \rightarrow H_{1}(T / S L(3, \mathbf{Z})(p), \mathbf{R}) \oplus\left[H_{1}(X(p), \mathbf{R})\right]^{k}
$$

Here $p \geqslant 3 . X(p)$ is the closed Riemann surface obtained by adding in the cusps to the quotient of the upper half-plane by $\operatorname{SL}(2, \mathrm{Z})(p)$, and $k$ is the number of orbits of maximal parabolic subgroups of $\operatorname{SL}(3, \mathbf{Q})$ under conjugation by $S L(3, Z)(p)$. If $p$ is prime, $k=p^{3}-1$.

Let $h^{i}(A)=\operatorname{dim} H^{i}(A, \mathbf{R})$. Since the euler characteristic of $\operatorname{SL}(3, \mathbf{Z})$ is 0 (for example, see [2]) and $H^{1}(\operatorname{SL}(3, \mathbf{Z})(p), \mathbf{R})=0$ by [3], Theorem 1 also gives a lower bound on $h^{2}(S L(3, Z)(p))$.

My original proof of Theorem 1 was along the lines described below for Theorem 2. With the help of A. Borel, we could prove the natural generalization of Theorem 1 for arithmetic subgroups of any $\mathbf{Q}$-rank 2 group $G$. The proof involves the manifold with corners $M$ for $G$, the Leray spectral sequence for $\partial M \rightarrow$ Tits building $(G)$, and the vanishing of $h^{1}$.

The kernel of the map in Theorem 1 probably contains only classes which are in the image of the cohomology with compact supports. This kernel in general is nonempty. For instance,

THEOREM 2. $h^{3}(S L(3, Z)(7))>h_{1}(T / S L(3, Z)(7))+k h_{1}(X(7))=5815$.
Similar results could be obtained for other primes. The demonstration of this theorem depends upon the following.

Proposition. Let $C$ be the cone of all $n \times n$ positive-definite symmetric matrices, $A$ be the set of nonzero integral column vectors, and let $K=\{x \in C$ : ${ }^{t} a \times a \geqslant 1$ for all $a$ in $\left.A\right\}$.

Let $K_{0}$ be the union of the compact faces of $K . K_{0}$ is $S L(n, \mathbf{Z})$-invariant under the action $(g, x) \mapsto{ }^{t} g x g$, $g$ in $\operatorname{SL}(n, \mathbf{Z}), x$ in $C$. If $\Gamma$ is any torsion-free subgroup of finite index of $\operatorname{SL}(n, \mathbf{Z})$ and $n \leqslant 4, K_{0} / \Gamma$ is a deformation retract of С/Г.

I do not know if this stays true for $n \geqslant 5$. The proof is similar to methods in [4] and [5].

The computation of $K_{0}$ for $n=3$ is not difficult given some knowledge of 3-dimensional crystallography, and a description of $K_{0}$ for $n=4$ has been graciously supplied to me by M. I. Stogrin. See also [6] , [7] .

In $K_{0}$, I have an explicit simplicial complex homotopic to $C / \Gamma$. Since $C$ is contractible, I can use it to compute $H(\Gamma)$. Iobtained Theorem 2 by decomposing the corresponding chain complex into $S L(3, \mathrm{Z} / 7)$-invariant subspaces and taking the euler characteristics of invariant complexes, using [8].

For $n=4$, this procedure is already too difficult to carry out by hand, but I can obtain one result:

Theorem 3. If $\Gamma$ is as in the proposition above, the images of the $\operatorname{SL}(4, \mathbf{R})$-invariant differential forms on $\operatorname{SL}(4, \mathbf{R}) / S O(4, \mathbf{R})$ are zero in

$$
\widetilde{H}^{*}(\Gamma \backslash S L(4, \mathbf{R}) / S O(4, \mathbf{R}), \mathbf{R}),
$$

thought of as de Rham Cohomology.
In view of [9], we can call Theorem 3 an "instability result".

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