

A REMARK ON TIME-DEPENDENT GINZBURG-LANDAU EQUATIONS

Akihito Unai

(Received May 12, 1997)

Abstract. The purpose of this paper is to show the existence of unique global C^1 -solutions to the time-dependent complex Ginzburg-Landau equation. We regard the equation as a genuinely nonlinear equation and simultaneously as a semilinear equation.

AMS 1991 Mathematics Subject Classification. Primary 47H20, Secondary 34G20.

Key words and phrases. Ginzburg-Landau equations, global C^1 -solutions, nonlinear evolution equations, semilinear evolution equations.

1. Introduction

In this paper we consider the generalized complex Ginzburg-Landau equation (see e.g. Temam [3])

$$(1) \quad \frac{\partial u}{\partial t} - (\lambda + i\alpha)\Delta u + (\kappa + i\beta)|u|^{p-1}u - \gamma u = 0, \quad (x, t) \in \Omega \times \mathbf{R}_+,$$

where Ω is a bounded domain in \mathbf{R}^n with smooth boundary $\partial\Omega$, $i = \sqrt{-1}$ and u is a complex-valued unknown function. The equation will be supplemented with the homogeneous Dirichlet boundary condition

$$(2-a) \quad u = 0 \quad \text{on} \quad \partial\Omega \times \mathbf{R}_+,$$

or the homogeneous Neumann boundary condition

$$(2-b) \quad \frac{\partial u}{\partial \nu} = 0 \quad \text{on} \quad \partial\Omega \times \mathbf{R}_+,$$

where ν is the unit outward normal on $\partial\Omega$, and the initial value of u :

$$(3) \quad u(x, 0) = u_0(x), \quad x \in \Omega.$$

Recently in [4], we proved that the initial-boundary value problem (1)–(3) has a unique strong global solution in $X := L^2(\Omega; \mathbf{C})$ under some conditions on the exponent $p > 1$ and the real parameters $\lambda, \kappa, \alpha, \beta, \gamma$. We used the theory of nonlinear semi-groups in [4]. Therefore the solution $u(t)$ to the problem (1)–(3) exists globally, but there is no guarantee that $u(t)$ is differentiable for any $t \in [0, \infty)$ ($u(t)$ is differentiable for almost every $t \in [0, \infty)$).

The purpose of this paper is to show the differentiability for any $t \in [0, \infty)$ of the solution $u(t)$ to the problem (1)–(3) under additional restrictions on the exponent p and the dimension n .

The basic idea is that we regard (1) as a genuinely nonlinear equation and simultaneously as a semilinear equation (Lipschitz perturbations of linear equations). As mentioned above, we can obtain a unique *global* strong solution by the theory of nonlinear semi-groups. On the other hand, we can prove the existence of a unique local C^1 -solution (*continuously differentiable* solution) by the theory of semilinear equations. Hence, by combining these two facts, namely the *global* existence by the theory of nonlinear semi-groups and the *continuous differentiability* by the theory of semilinear equations, we can prove the existence of a unique global C^1 -solution to the problem (1)–(3).

2. The Main Result and Proof

For the abstract setting we define three operators A_1, B, A in the complex Hilbert space $X := L^2(\Omega; \mathbf{C})$ with norm and inner product denoted by $\|\cdot\|$ and (\cdot, \cdot) , respectively:

$$\begin{aligned} D(A_1) &:= H_0^1(\Omega; \mathbf{C}) \cap H^2(\Omega; \mathbf{C}) \quad (\text{in case of (2-a)}), \\ D(A_1) &:= \{u \in H^2(\Omega; \mathbf{C}); \frac{\partial u}{\partial \nu} = 0 \text{ on } \partial\Omega\} \quad (\text{in case of (2-b)}), \\ A_1 u &:= -\Delta u \quad \text{for } u \in D(A_1), \\ D(B) &:= \{u \in X; |u|^{p-1}u \in X\} = L^{2p}(\Omega; \mathbf{C}), \\ Bu &:= |u|^{p-1}u \quad \text{for } u \in D(B), \\ D(A) &:= D(A_1) \cap D(B), \\ Au &:= (\lambda + i\alpha)A_1 u + (\kappa + i\beta)Bu - \gamma u \quad \text{for } u \in D(A), \end{aligned}$$

where $H^2(\Omega; \mathbf{C})$ and $H_0^1(\Omega; \mathbf{C})$ are the usual Sobolev Hilbert spaces.

The problem (1)–(3) is now equivalent to the following initial value problem for the abstract evolution equation

$$(4) \quad \begin{aligned} \frac{d}{dt}u(t) + Au(t) &= 0, & t \geq 0, \\ u(0) &= u_0. \end{aligned}$$

For convenience we quote the existence theorem from [4]. It is summarized as follows:

Theorem A ([4]). *Let $\lambda > 0$, $\kappa > 0$, $p > 1$, $\frac{|\beta|}{\kappa} \leq \frac{2\sqrt{p}}{p-1}$, $\lambda\kappa + \alpha\beta > 0$. Then for any $T > 0$ and $u_0 \in D(A)$ there exists a unique strong solution $u(t)$ ($t \in [0, T]$) to the problem (4) such that*

- (a) $u(t) \in D(A)$ for $t \in [0, T]$.
- (b) $u(t)$ is Lipschitz continuous for $t \in [0, T]$.
- (c) $u(t)$ is strongly differentiable for almost every $t \in [0, T]$ and satisfies (4).
- (d) $Au(t)$ is weakly continuous for $t \in [0, T]$ (see [5, Theorem 31.A]).

At the same time we can regard (1)–(3) as a semilinear evolution equation

$$(5) \quad \frac{d}{dt}u(t) + (\lambda + i\alpha)A_1u(t) = -(\kappa + i\beta)Bu(t) + \gamma u(t), \quad t \geq 0,$$

$$u(0) = u_0.$$

Let $n = 1, 2, 3$. Then $H^2(\Omega; \mathbf{C})$ is embedded in $L^\infty(\Omega; \mathbf{C})$, and therefore $D(A_1) \subset D(B)$ (consequently, $D(A) = D(A_1) \cap D(B) = D(A_1)$). Since the function $f(s) = |s|^{p-1}s$ ($p \geq 3$) is three times continuously differentiable, we can see that the operator B is locally Lipschitz continuous on $D(A_1)$ with graph norm $\|\cdot\|_{D(A_1)}$. Hence applying general theory of semilinear equations (see e.g. Ôtani [1, Theorem B] or Pazy [2, Remark after Theorem 6.1.7]), we have

Theorem B. *Let $n = 1, 2, 3$. Assume that $\lambda > 0$ and $p \geq 3$. Then for any $u_0 \in D(A_1)$ there exists T_m ($0 < T_m \leq \infty$) such that the problem (5) has a unique C^1 -solution $u(\cdot) \in \mathbf{C}^1([0, T_m); X) \cap \mathbf{C}([0, T_m); D(A_1)) \cap \mathbf{C}([0, T_m); D(A))$. Furthermore, if $T_m < \infty$ then $\lim_{t \uparrow T_m} (\|u(t)\| + \|A_1u(t)\|) = \infty$.*

As a combination of Theorem A and Theorem B, our theorem is stated as follows:

Theorem. *Let $n = 1, 2, 3$. Assume that $\lambda > 0$, $\kappa > 0$, $p \geq 3$, $\frac{|\beta|}{\kappa} \leq \frac{2\sqrt{p}}{p-1}$, and $\lambda\kappa + \alpha\beta > 0$. Then for any $u_0 \in D(A)$ the problem (4) (or (5)) has a unique global C^1 -solution $u(t)$ such that*

$$u(\cdot) \in C^1([0, \infty); X) \cap C([0, \infty); D(A)) \cap C([0, \infty); D(A_1)).$$

Proof. Under the assumption of our Theorem we can simultaneously apply Theorem A and Theorem B to the problem (4) (or (5)). Hence it is easy to see that the solution obtained by Theorem A coincides with the one obtained by Theorem B in the common time interval $[0, T_m)$. Using the properties (a)–(d)

(especially (d)) of the solution $u(t)$ ($0 \leq t < \infty$) in Theorem A, we shall prove that $T_m = \infty$. To this end, it suffices by Theorem B to show that if $T_m < \infty$, then

$$(6) \quad \sup_{0 \leq t < T_m} (\|u(t)\| + \|A_1 u(t)\|) < \infty.$$

We know that $u(t)$ satisfies the following equation

$$\frac{d}{dt}u(t) - (\lambda + i\alpha)\Delta u(t) + (\kappa + i\beta)|u(t)|^{p-1}u(t) - \gamma u(t) = 0, \quad 0 \leq t < T_m.$$

Dividing by $(\lambda + i\alpha)$ and taking inner product with $|u|^{p-1}u$, we have

$$(7) \quad \frac{1}{\lambda + i\alpha} \left(\frac{d}{dt}u(t), |u(t)|^{p-1}u(t) \right) - (\Delta u(t), |u(t)|^{p-1}u(t)) \\ + \frac{\kappa + i\beta}{\lambda + i\alpha} \|u(t)\|_{L^{2p}}^{2p} - \frac{\gamma}{\lambda + i\alpha} \int_{\Omega} |u(t)|^{p+1} dx = 0.$$

Integration by parts yields

$$(8) \quad -\operatorname{Re}(\Delta u(t), |u(t)|^{p-1}u(t)) = \int_{\Omega} |u(t)|^{p-1} |\nabla u(t)|^2 dx \\ + (p-1) \int_{\Omega} |u(t)|^{p-3} \sum_{j=1}^n \left\{ \operatorname{Re}(\overline{u(t)} \cdot \frac{\partial}{\partial x_j} u(t)) \right\}^2 dx \geq 0,$$

where $\operatorname{Re}(\cdot)$ and $\overline{u(t)}$ mean the real part of (\cdot) and the complex conjugate of $u(t)$, respectively. In view of (7), (8) we obtain for any $\varepsilon > 0$

$$\frac{\lambda\kappa + \alpha\beta}{\lambda^2 + \alpha^2} \|u(t)\|_{L^{2p}}^{2p} \leq \left| \frac{1}{\lambda + i\alpha} \right| \int_{\Omega} \left| \frac{d}{dt}u(t) \right| \cdot |u(t)|^p dx + \frac{\lambda\gamma}{\lambda^2 + \alpha^2} \int_{\Omega} |u(t)|^{p+1} dx \\ \leq \frac{1}{\sqrt{\lambda^2 + \alpha^2}} \int_{\Omega} \left(\frac{1}{4\varepsilon} \left| \frac{d}{dt}u(t) \right|^2 + \varepsilon |u(t)|^{2p} \right) dx \\ + \frac{\lambda|\gamma|}{\lambda^2 + \alpha^2} \int_{\Omega} \left(\varepsilon |u(t)|^{2p} + \frac{1}{4\varepsilon} |u(t)|^2 \right) dx.$$

Thus we have

$$(9) \quad \frac{1}{\lambda^2 + \alpha^2} \{ (\lambda\kappa + \alpha\beta) - \varepsilon(\sqrt{\lambda^2 + \alpha^2} + \lambda|\gamma|) \} \|u(t)\|_{L^{2p}}^{2p} \\ \leq \frac{1}{4\varepsilon} \frac{1}{\sqrt{\lambda^2 + \alpha^2}} \left\| \frac{d}{dt}u(t) \right\|^2 + \frac{1}{4\varepsilon} \frac{\lambda|\gamma|}{\lambda^2 + \alpha^2} \|u(t)\|^2 \\ = \frac{1}{4\varepsilon} \left(\frac{1}{\sqrt{\lambda^2 + \alpha^2}} \|Au(t)\|^2 + \frac{\lambda|\gamma|}{\lambda^2 + \alpha^2} \|u(t)\|^2 \right)$$

for $0 \leq t < T_m$. Choose $\varepsilon > 0$ small enough in such a way that the left hand side of (9) is positive. We know from Theorem A (d) that $\{\|Au(t)\|; t \in [0, T)\}$ is bounded for every $T > 0$. In particular, it follows that

$$(10) \quad \sup_{0 \leq t < T_m} \|Au(t)\| < \infty.$$

Moreover, it is not difficult to see that

$$(11) \quad \sup_{0 \leq t < T_m} \|u(t)\| \leq e^{\gamma T_m} \|u_0\| < \infty.$$

From (9), (10), (11) we have

$$\sup_{0 \leq t < T_m} \|u(t)\|_{L^{2p}} < \infty.$$

Finally, in view of the definition of the operator A , we obtain (6). This completes the proof of Theorem. \square

Acknowledgement

The author would like to thank the referee for his helpful comments and suggestions.

References

1. M. Ôtani, *An Introduction to Nonlinear Evolution Equations*, Summer Seminar Notes, 1983 (in Japanese).
2. A. Pazy, *Semigroups of Linear Operators and Applications to Partial Differential Equations*, Applied Math. Sci., vol. 44, Springer-Verlag, Berlin and New York, 1983.
3. R. Temam, *Infinite-Dimensional Dynamical Systems in Mechanics and Physics*, Applied Math. Sci., vol. 68, Springer-Verlag, Berlin and New York, 1988.
4. A. Unai and N. Okazawa, *Perturbations of nonlinear m -sectorial operators and time-dependent Ginzburg-Landau equations*, Dynamical Systems and Differential Equations (Springfield, 1996), Lecture Notes in Pure and Applied Mathematics, Marcel Dekker, New York, 1997 (to appear).
5. E. Zeidler, *Nonlinear Functional Analysis and its Applications*, II/B: Nonlinear Monotone Operators, Springer-Verlag, Berlin and New York, 1989.

Akihito Unai

Department of Applied Mathematics, Science University of Tokyo
1-3 Kagurazaka, Shinjuku-ku, Tokyo 162, Japan