# On Weakly Quasi-Conformally Symmetric Manifolds 

Absos Ali Shaikh and Sanjib Kumar Jana

(Received April 10, 2006; Revised February 27, 2007)


#### Abstract

The object of the present paper is to study weakly quasi-conformally symmetric Riemannian manifolds. Among others we obtain various sufficient conditions for such a manifold to be of weakly symmetric. The decomposable weakly quasi-conformally symmetric manifolds are studied and classified regorously. The existence of a weakly quasi-conformally symmetric and decomposable weakly quasi-conformally symmetric manifolds have been ensured by several non-trivial examples.


AMS 2000 Mathematics Subject Classification. 53B35, 53B05.
Key words and phrases. Weakly quasi-conformally symmetric manifold, decomposable manifold, scalar curvature, Einstein manifold.

## §1. Introduction

The notions of weakly symmetric and weakly projective symmetric manifolds were introduced by Tamássy and Binh [8] and later Binh [1] studied decomposable weakly symmetric manifolds. A non-flat Riemannian manifold ( $M^{n}, g$ ) $(n>2)$ is called a weakly symmetric manifold if its curvature tensor $R$ of type $(0,4)$ satisfies the condition

$$
\begin{align*}
\left(\nabla_{X} R\right)(Y, Z, U, V)= & \alpha(X) R(Y, Z, U, V)+\beta(Y) R(X, Z, U, V)  \tag{1.1}\\
& +\gamma(Z) R(Y, X, U, V)+\delta(U) R(Y, Z, X, V) \\
& +\sigma(V) R(Y, Z, U, X)
\end{align*}
$$

for all vector fields $X, Y, Z, U, V \in \chi\left(M^{n}\right)$, where $\alpha, \beta, \gamma, \delta$ and $\sigma$ are 1 -forms (not simultaneously zero), $\chi\left(M^{n}\right)$ is the set of all smooth vector fields over the manifold and $\nabla$ denotes the operator of covariant differentiation with respect to the metric tensor $g$. The 1-forms are called the associated 1-forms of the
manifold and an n-dimensional manifold of this kind is denoted by $(W S)_{n}$. In 1999 U. C. De and S. Bandyopadhyay [3] established the existence of a $(W S)_{n}$ by an example and proved that in a $(W S)_{n}$, the associated 1-forms $\beta=\gamma$ and $\delta=\sigma$. Hence (1.1) reduces to the following:

$$
\begin{align*}
\left(\nabla_{X} R\right)(Y, Z, U, V)= & \alpha(X) R(Y, Z, U, V)+\beta(Y) R(X, Z, U, V)  \tag{1.2}\\
& +\beta(Z) R(Y, X, U, V)+\delta(U) R(Y, Z, X, V) \\
& +\delta(V) R(Y, Z, U, X) .
\end{align*}
$$

Also De and Bandyopadhyay [4] studied weakly conformally symmetric manifolds. In this connection it may be noted that although the definition of a $(W S)_{n}$ is similar to that of a generalized pseudo-symmetric manifold introduced by Chaki [2], but the defining condition of a $(W S)_{n}$ is little weaker than that of a generalized pseudo-symmetric manifold. That is, if in (1.1) the 1 -form $\alpha$ is replaced by $2 \alpha$ and $\sigma$ is replaced by $\alpha$ then the manifold will be a generalized pseudo-symmetric manifold [2]. In 1968 Yano and Sawaki [9] defined and studied a tensor field $W$ on a Riemannian manifold of dimension $n$ which includes both the conformal curvature tensor $C$ and the concircular curvature tensor $\widetilde{C}$ as special cases. This tensor field $W$ is known as quasiconformal curvature tensor given by

$$
\begin{align*}
W(X, Y, Z, U)= & -(n-2) b C(X, Y, Z, U)  \tag{1.3}\\
& +[a+(n-2) b] \widetilde{C}(X, Y, Z, U),
\end{align*}
$$

where $a$ and $b$ are arbitrary constants not simultaneously zero, $C$ and $\widetilde{C}$ are the conformal curvature tensor and the concircular curvature tensor of type $(0,4)$ respectively. The present paper deals with a non-quasi-conformally flat Riemannian manifold $\left(M^{n}, g\right)(n>3)$ [the condition $(n>3)$ is assumed throughout this paper as the conformal curvature tensor vanishes for $n=3$ ] whose quasi-conformal curvature tensor $W$ satisfies the condition

$$
\begin{align*}
\left(\nabla_{X} W\right)(Y, Z, U, V)= & \alpha(X) W(Y, Z, U, V)+\beta(Y) W(X, Z, U, V)  \tag{1.4}\\
& +\gamma(Z) W(Y, X, U, V)+\delta(U) W(Y, Z, X, V) \\
& +\sigma(V) W(Y, Z, U, X)
\end{align*}
$$

where $\alpha, \beta, \gamma, \delta$ and $\sigma$ are 1 -forms (not simultaneously zero). Such a manifold will be called a weakly quasi-conformally symmetric manifold and denoted by $(W Q C S)_{n}$, where the first ' $W$ ' stands for 'weakly' and ' $Q C$ ' stands for 'quasiconformal curvature tensor' as the 'weakly conformally symmetric manifold' was denoted by $(W C S)_{n}[4]$. In particular, if $a=1$ and $b=-\frac{1}{n-2}$ then a $(W Q C S)_{n}$ reduces to a $(W C S)_{n}$. The manifold $(W Q C S)_{n}$ is introduced and studied by the first author and K. K. Baishya [7]. It is also shown in [7] that
in a $(W Q C S)_{n}$, the 1 -forms $\beta=\gamma$ and $\delta=\sigma$ and hence (1.4) reduces to the following form:

$$
\begin{align*}
\left(\nabla_{X} W\right)(Y, Z, U, V)= & \alpha(X) W(Y, Z, U, V)+\beta(Y) W(X, Z, U, V)  \tag{1.5}\\
& +\beta(Z) W(Y, X, U, V)+\delta(U) W(Y, Z, X, V) \\
& +\delta(V) W(Y, Z, U, X)
\end{align*}
$$

where $\alpha, \beta$ and $\delta$ are 1 -forms (not simultaneously zero).
Section 2 is concerned with some basic results of $(W Q C S)_{n}$. It is shown that if in a $(W Q C S)_{n}$ the Ricci tensor is of Codazzi [5] type then $\frac{r}{n}$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $P$ defined by $g(X, P)=\lambda(X)$, where $r$ is the scalar curvature of the manifold. Also it is proved that if a $(W Q C S)_{n}$ is of constant scalar curvature then $\frac{r}{n}$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $L_{1}$ defined by $g\left(X, L_{1}\right)=\alpha(X)$. Section 3 is devoted to the decomposable $(W Q C S)_{n}$, which is generally called the product $(W Q C S)_{n}$ and it is shown that in such a manifold satisfying certain conditions one of the decomposition is locally symmetric and the other is quasi-conformally flat. Also we obtain some other illuminating results on a decomposable $(W Q C S)_{n}$. Section 4 is devoted to the $(W Q C S)_{n}$ satisfying certain conditions and obtained several interesting results for such a manifold to be a $(W S)_{n}$.

The last section deals with several non-trivial examples of $(W Q C S)_{n}$ and also of decomposable $(W Q C S)_{n}$.

## §2. $\quad$ Some basic results of $(W Q C S)_{n}$

In this section we deduce some basic results of a $(W Q C S)_{n}$. The conformal curvature tensor field $C$ of type $(0,4)$ and the concircular curvature tensor field $\widetilde{C}$ of type $(0,4)$ are respectively given by

$$
\begin{aligned}
C(X, Y, Z, U)= & R(X, Y, Z, U)-\frac{1}{n-2}[S(Y, Z) g(X, U)-S(X, Z) g(Y, U) \\
& +g(Y, Z) S(X, U)-g(X, Z) S(Y, U)] \\
& +\frac{r}{(n-1)(n-2)}[g(Y, Z) g(X, U)-g(X, Z) g(Y, U)]
\end{aligned}
$$

and

$$
\begin{aligned}
\widetilde{C}(X, Y, Z, U)= & R(X, Y, Z, U)-\frac{r}{n(n-1)}[g(Y, Z) g(X, U) \\
& -g(X, Z) g(Y, U)]
\end{aligned}
$$

for all vector fields $X, Y, Z, U \in \chi\left(M^{n}\right)$, where $R, S, r$ are the Riemannian curvature tensor of type $(0,4)$, the Ricci tensor of type $(0,2)$ and the scalar
curvature respectively of the manifold. The Riemannian curvature tensor $R$ of type $(0,4)$ on a Riemannian manifold is defined as a quadrilinear mapping $R: \chi(M) \times \chi(M) \times \chi(M) \times \chi(M) \rightarrow C^{\infty}(M)$ and is given by $R(X, Y, Z, U)=$ $g(R(X, Y) Z, U)$ for all $X, Y, Z, U \in \chi\left(M^{n}\right)$, where we have used the same symbol $R$ of the curvature tensor of type $(1,3)$ as well as of type $(0,4)$ and $R(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z, \nabla$ being the Levi-Civita connection and $C^{\infty}(M)$ is the set of all smooth functions over the manifold $M$. The Ricci tensor field $S$ is the covariant tensor field of degree 2 defined by $S(Y, Z)=T r$. $[X \rightarrow R(X, Y) Z]$ and the scalar curvature $r$ is defined as the trace of the $(1,1)$ Ricci tensor $Q$ i.e., $r=T r . Q$ where $S(X, Y)=g(Q X, Y)$ for all $X, Y \in \chi(M)$. Using the above expressions of Weyl conformal curvature tensor $C$ and the concircular curvature tensor $\tilde{C}$ in (1.3) one can easily obtain

$$
\begin{align*}
W(X, Y, Z, U)= & a R(X, Y, Z, U)+b[S(Y, Z) g(X, U)  \tag{2.1}\\
& -S(X, Z) g(Y, U)+g(Y, Z) S(X, U) \\
& -g(X, Z) S(Y, U)]-\frac{r}{n}\left(\frac{a}{n-1}+2 b\right)[g(Y, Z) g(X, U) \\
& -g(X, Z) g(Y, U)] .
\end{align*}
$$

Let $\left\{e_{i}: i=1,2, \ldots, n\right\}$ be an orthonormal basis of the tangent space at any point of the manifold. Then the Ricci tensor $S$ of type ( 0,2 ) and the scalar curvature $r$ are given by the following

$$
\begin{aligned}
& S(X, Y)=\sum_{i=1}^{n} R\left(e_{i}, X, Y, e_{i}\right) \\
& \text { and } r=\sum_{i=1}^{n} S\left(e_{i}, e_{i}\right)=\sum_{i=1}^{n} g\left(Q e_{i}, e_{i}\right) .
\end{aligned}
$$

Again from (2.1) we can obtain

$$
\begin{align*}
\sum_{i=1}^{n} W\left(e_{i}, Y, Z, e_{i}\right) & =\sum_{i=1}^{n} W\left(Y, e_{i}, e_{i}, Z\right)  \tag{2.2}\\
& =\{a+(n-2) b\}\left[S(Y, Z)-\frac{r}{n} g(Y, Z)\right]
\end{align*}
$$

Differentiating (2.1) covariantly and then taking cyclic sum with respect to $X, Y, Z$ we obtain by virtue of Bianchi identity that

$$
\begin{align*}
& \left(\nabla_{X} W\right)(Y, Z, U, V)+\left(\nabla_{Y} W\right)(Z, X, U, V)+\left(\nabla_{Z} W\right)(X, Y, U, V)  \tag{2.3}\\
& =b\left[\left\{\left(\nabla_{X} S\right)(Z, U)-\left(\nabla_{Z} S\right)(X, U)\right\} g(Y, V)+\left\{\left(\nabla_{Y} S\right)(X, U)\right.\right. \\
& \left.-\left(\nabla_{X} S\right)(Y, U)\right\} g(Z, V)+\left\{\left(\nabla_{Z} S\right)(Y, U)-\left(\nabla_{Y} S\right)(Z, U)\right\} g(X, V) \\
& +\left\{\left(\nabla_{X} S\right)(Y, V)-\left(\nabla_{Y} S\right)(X, V)\right\} g(Z, U)+\left\{\left(\nabla_{Z} S\right)(X, V)\right.
\end{align*}
$$

$$
\begin{aligned}
& \left.\left.-\left(\nabla_{X} S\right)(Z, V)\right\} g(Y, U)+\left\{\left(\nabla_{Y} S\right)(Z, V)-\left(\nabla_{Z} S\right)(Y, V)\right\} g(X, U)\right] \\
& -\frac{1}{n}\left(\frac{a}{n-1}+2 b\right)[d r(X)\{g(Z, U) g(Y, V)-g(Z, V) g(Y, U)\} \\
& +d r(Y)\{g(Z, V) g(X, U)-g(Z, U) g(X, V)\} \\
& +d r(Z)\{g(Y, U) g(X, V)-g(X, U) g(Y, V)\}]
\end{aligned}
$$

We now suppose that in a Riemannian manifold the Ricci tensor is of Codazzi type [5]. Then we have

$$
\left(\nabla_{X} S\right)(Y, Z)=\left(\nabla_{Y} S\right)(X, Z)=\left(\nabla_{Z} S\right)(X, Y)
$$

for all vector fields $X, Y, Z$ on the manifold. This implies that

$$
d r(X)=0 \text { for all } X .
$$

Therefore (2.3) yields

$$
\begin{equation*}
\left(\nabla_{X} W\right)(Y, Z, U, V)+\left(\nabla_{Y} W\right)(Z, X, U, V)+\left(\nabla_{Z} W\right)(X, Y, U, V)=0 \tag{2.4}
\end{equation*}
$$

Hence if the Ricci tensor is of Codazzi type then in a Riemannian manifold the relation (2.4) holds. Again if a Riemannian manifold $(M, g)$ satisfies the relation (2.4), then (2.3) yields

$$
\begin{aligned}
& b\left[\left\{\left(\nabla_{X} S\right)(Z, U)-\left(\nabla_{Z} S\right)(X, U)\right\} g(Y, V)+\left\{\left(\nabla_{Y} S\right)(X, U)\right.\right. \\
& \left.-\left(\nabla_{X} S\right)(Y, U)\right\} g(Z, V)+\left\{\left(\nabla_{Z} S\right)(Y, U)-\left(\nabla_{Y} S\right)(Z, U)\right\} g(X, V) \\
& +\left\{\left(\nabla_{X} S\right)(Y, V)-\left(\nabla_{Y} S\right)(X, V)\right\} g(Z, U)+\left\{\left(\nabla_{Z} S\right)(X, V)\right. \\
& \left.\left.-\left(\nabla_{X} S\right)(Z, V)\right\} g(Y, U)+\left\{\left(\nabla_{Y} S\right)(Z, V)-\left(\nabla_{Z} S\right)(Y, V)\right\} g(X, U)\right] \\
& -\frac{1}{n}\left(\frac{a}{n-1}+2 b\right)[d r(X)\{g(Z, U) g(Y, V)-g(Z, V) g(Y, U)\} \\
& +d r(Y)\{g(Z, V) g(X, U)-g(Z, U) g(X, V)\} \\
& +d r(Z)\{g(Y, U) g(X, V)-g(X, U) g(Y, V)\}]=0 .
\end{aligned}
$$

Setting $Y=V=e_{i}$ in the above relation and then taking summation over $i$, $1 \leq i \leq n$ we get

$$
\begin{aligned}
& (n-3) b\left[\left(\nabla_{X} S\right)(Z, U)-\left(\nabla_{Z} S\right)(X, U)\right]-\left\{\frac{(n-2) a}{n(n-1)}\right. \\
& \left.+\frac{(3 n-8) b}{2 n}\right\}[d r(X) g(Z, U)-d r(Z) g(X, U)]=0
\end{aligned}
$$

which yields on contraction over $Z$ and $U$ that $d r(X)=0$ for all $X$ provided $a+(n-2) b \neq 0$ and consequently the last relation reduces to

$$
\begin{aligned}
& \left(\nabla_{X} S\right)(Z, U)=\left(\nabla_{Z} S\right)(X, U) \\
& \text { for all } X, Z, U \in \chi(M) \text { provided } b \neq 0 .
\end{aligned}
$$

Hence the Ricci tensor is of Codazzi type. Thus we can state the following:

Proposition 2.1. In a Riemannian manifold $\left(M^{n}, g\right)$ with $b \neq 0$ and $a+(n-$ $2) b \neq 0$, the Ricci tensor is of Codazzi type if and only if the relation (2.4) holds.

In view of (1.5), the relation (2.4) reduces to

$$
\begin{equation*}
\lambda(X) W(Y, Z, U, V)+\lambda(Y) W(Z, X, U, V)+\lambda(Z) W(X, Y, U, V)=0 \tag{2.5}
\end{equation*}
$$

where $\lambda(X)=\alpha(X)-2 \beta(X)$ for all $X$. By virtue of (2.1), (2.5) takes the form

$$
\begin{align*}
& a[\lambda(X) R(Y, Z, U, V)+\lambda(Y) R(Z, X, U, V)+\lambda(Z) R(X, Y, U, V)]  \tag{2.6}\\
& +b[\lambda(X)\{S(Z, U) g(Y, V)-S(Y, U) g(Z, V)+S(Y, V) g(Z, U) \\
& -S(Z, V) g(Y, U)\}+\lambda(Y)\{S(X, U) g(Z, V)-S(Z, U) g(X, V) \\
& +S(Z, V) g(X, U)-S(X, V) g(Z, U)\}+\lambda(Z)\{S(Y, U) g(X, V) \\
& -S(X, U) g(Y, V)+S(X, V) g(Y, U)-S(Y, V) g(X, U)\}] \\
& -\frac{r}{n}\left(\frac{a}{n-1}+2 b\right)[\lambda(X)\{g(Z, U) g(Y, V)-g(Y, U) g(Z, V)\} \\
& +\lambda(Y)\{g(X, U) g(Z, V)-g(Z, U) g(X, V)\} \\
& +\lambda(Z)\{g(Y, U) g(X, V)-g(X, U) g(Y, V)\}]=0 .
\end{align*}
$$

Setting $Y=V=e_{i}$ in (2.6) and taking summation over $i, 1 \leq i \leq n$, we get

$$
\begin{align*}
& \{a+(n-3) b\}[\lambda(X) S(Z, U)-\lambda(Z) S(X, U)]+a \lambda(R(Z, X) U)  \tag{2.7}\\
& +b[\lambda(Q Z) g(X, U)-\lambda(Q X) g(Z, U)]-\frac{r}{n}\left\{\frac{(n-2) a}{n-1}\right. \\
& +(n-4) b\}[\lambda(X) g(Z, U)-\lambda(Z) g(X, U)]=0 .
\end{align*}
$$

Again putting $X=U=e_{i}$ in (2.7) and taking summation over $i, 1 \leq i \leq n$, we obtain

$$
\begin{aligned}
& \{a+(n-2) b\}\left[\lambda(Q Z)-\frac{r}{n} \lambda(Z)\right]=0, \quad \text { which yields } \\
& S(Z, P)=\frac{r}{n} g(Z, P),
\end{aligned}
$$

provided that $a+(n-2) b \neq 0$ where $\lambda(X)=\alpha(X)-2 \beta(X)$ and $g(X, P)=$ $\lambda(X)$. This leads to the following:

Proposition 2.2. If in $a(W Q C S)_{n}$ the Ricci tensor is of Codazzi type then $\frac{r}{n}$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $P$, defined by $g(X, P)=\lambda(X)$, provided that $a+(n-2) b \neq 0$.

Next in view of (1.5), the relation (2.3) takes the form

$$
\begin{align*}
& b\left[\left\{\left(\nabla_{X} S\right)(Z, U)-\left(\nabla_{Z} S\right)(X, U)\right\} g(Y, V)+\left\{\left(\nabla_{Y} S\right)(X, U)\right.\right.  \tag{2.8}\\
& \left.-\left(\nabla_{X} S\right)(Y, U)\right\} g(Z, V)+\left\{\left(\nabla_{Z} S\right)(Y, U)-\left(\nabla_{Y} S\right)(Z, U)\right\} g(X, V) \\
& +\left\{\left(\nabla_{X} S\right)(Y, V)-\left(\nabla_{Y} S\right)(X, V)\right\} g(Z, U)+\left\{\left(\nabla_{Z} S\right)(X, V)\right. \\
& \left.\left.-\left(\nabla_{X} S\right)(Z, V)\right\} g(Y, U)+\left\{\left(\nabla_{Y} S\right)(Z, V)-\left(\nabla_{Z} S\right)(Y, V)\right\} g(X, U)\right] \\
& -\frac{1}{n}\left(\frac{a}{n-1}+2 b\right)[d r(X)\{g(Z, U) g(Y, V)-g(Z, V) g(Y, U)\} \\
& +d r(Y)\{g(Z, V) g(X, U)-g(Z, U) g(X, V)\} \\
& +d r(Z)\{g(Y, U) g(X, V)-g(X, U) g(Y, V)\}] \\
& =\lambda(X) W(Y, Z, U, V)+\lambda(Y) W(Z, X, U, V)+\lambda(Z) W(X, Y, U, V)
\end{align*}
$$

where $\lambda(X)=\alpha(X)-2 \beta(X)$ for all $X$. Setting $Y=V=e_{i}$ in (2.8) and taking summation over $i, 1 \leq i \leq n$, we obtain by virtue of (2.1) and (2.2) that

$$
\begin{align*}
& (n-3) b\left[\left(\nabla_{X} S\right)(Z, U)-\left(\nabla_{Z} S\right)(X, U)\right]  \tag{2.9}\\
& -\left[\frac{a(n-2)}{n(n-1)}-\frac{b(3 n-8)}{2 n}\right][d r(X) g(Z, U)-d r(Z) g(X, U)] \\
& =[a+(n-3) b][\lambda(X) S(Z, U)-\lambda(Z) S(X, U)] \\
& +a \lambda(R(Z, X) U)+b[\lambda(Q Z) g(X, U)-\lambda(Q X) g(Z, U)] \\
& -\frac{r}{n}\left[\frac{(n-2) a}{n-1}+(n-4) b\right][\lambda(X) g(Z, U)-\lambda(Z) g(X, U)] .
\end{align*}
$$

Putting $X=U=e_{i}$ in (2.9) and taking summation over $i, 1 \leq i \leq n$, we get

$$
\begin{equation*}
\frac{n-2}{2 n} d r(Z)=\lambda(Q Z)-\frac{r}{n} \lambda(Z) \text { for } a+(n-2) b \neq 0 \tag{2.10}
\end{equation*}
$$

If the manifold under consideration is of constant scalar curvature then (2.10) yields

$$
\begin{equation*}
\lambda(Q Z)=\frac{r}{n} \lambda(Z) \quad \text { for } \quad a+(n-2) b \neq 0 \tag{2.11}
\end{equation*}
$$

If $P$ is the vector field associated with $\lambda$ such that $g(X, P)=\lambda(X)=\alpha(X)-$ $2 \beta(X)$ then (2.11) can be written as

$$
\begin{equation*}
S(Z, P)=\frac{r}{n} g(Z, P) \quad \text { for } \quad a+(n-2) b \neq 0 \tag{2.12}
\end{equation*}
$$

Thus we can state the following:
Proposition 2.3. If $a(W Q C S)_{n}$ is of constant scalar curvature with $a+$ $(n-2) b \neq 0$ then $\frac{r}{n}$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $P$, defined by $g(X, P)=\lambda(X)$ for all $X$.

Now using (2.1) in (1.5) we obtain

$$
\begin{align*}
& a\left(\nabla_{X} R\right)(Y, Z, U, V)+b\left[\left(\nabla_{X} S\right)(Z, U) g(Y, V)-\left(\nabla_{X} S\right)(Y, U) g(Z, V)\right.  \tag{2.13}\\
& \left.+\left(\nabla_{X} S\right)(Y, V) g(Z, U)-\left(\nabla_{X} S\right)(Z, V) g(Y, U)\right] \\
& -\frac{1}{n} d r(X)\left(\frac{a}{n-1}+2 b\right)[g(Z, U) g(Y, V)-g(Y, U) g(Z, V)] \\
& =a[\alpha(X) R(Y, Z, U, V)+\beta(Y) R(X, Z, U, V)+\beta(Z) R(Y, X, U, V) \\
& +\delta(U) R(Y, Z, X, V)+\delta(V) R(Y, Z, U, X)]+b[\alpha(X)\{S(Z, U) g(Y, V) \\
& -S(Y, U) g(Z, V)+S(Y, V) g(Z, U)-S(Z, V) g(Y, U)\} \\
& +\beta(Y)\{S(Z, U) g(X, V)-S(X, U) g(Z, V)+S(X, V) g(Z, U) \\
& -S(Z, V) g(X, U)\}+\beta(Z)\{S(X, U) g(Y, V)-S(Y, U) g(X, V) \\
& +S(Y, V) g(X, U)-S(X, V) g(Y, U)\}+\delta(U)\{S(Z, X) g(Y, V) \\
& -S(X, Y) g(Z, V)+S(Y, V) g(Z, X)-S(Z, V) g(X, Y)\} \\
& +\delta(V)\{S(Z, U) g(X, Y)-S(Y, U) g(Z, X)+S(X, Y) g(Z, U) \\
& -S(Z, X) g(Y, U)\}]-\frac{r}{n}\left(\frac{a}{n-1}+2 b\right)[\alpha(X)\{g(Z, U) g(Y, V) \\
& -g(Y, U) g(Z, V)\}+\beta(Y)\{g(Z, U) g(X, V)-g(X, U) g(Z, V)\} \\
& +\beta(Z)\{g(X, U) g(Y, V)-g(Y, U) g(X, V)\} \\
& +\delta(U)\{g(Z, X) g(Y, V)-g(X, Y) g(Z, V)\} \\
& +\delta(V)\{g(Z, U) g(X, Y)-g(Y, U) g(Z, X)\}] .
\end{align*}
$$

Setting $Y=V=e_{i}$ in (2.13) and taking summation over $i, 1 \leq i \leq n$, we get

$$
\begin{align*}
& \{a+(n-2) b\}\left[\left(\nabla_{X} S\right)(Z, U)-\frac{1}{n} d r(X) g(Z, U)\right]  \tag{2.14}\\
& =\{a+(n-2) b\}\left[\alpha(X)\left\{S(Z, U)-\frac{r}{n} g(Z, U)\right\}\right. \\
& +\beta(Z)\left\{S(X, U)-\frac{r}{n} g(X, U)\right\} \\
& \left.+\delta(U)\left\{S(Z, X)-\frac{r}{n} g(Z, X)\right\}\right]+a[\beta(R(X, Z) U) \\
& +\delta(R(X, U) Z)]+b[\beta(X) S(Z, U)-\beta(Z) S(X, U) \\
& +\delta(X) S(Z, U)-\delta(U) S(Z, X) \\
& +\beta(Q X) g(Z, U)-\beta(Q Z) g(X, U)+\delta(Q X) g(Z, U) \\
& -\delta(Q U) g(Z, X)]-\frac{r}{n}\left(\frac{a}{n-1}+2 b\right)[\beta(X) g(Z, U) \\
& -\beta(Z) g(X, U)+\delta(X) g(Z, U)-\delta(U) g(Z, X)] .
\end{align*}
$$

Again contracting (2.14) over $Z$ and $U$ we obtain

$$
\begin{equation*}
\beta(Q X)+\delta(Q X)=\frac{r}{n}[\beta(X)+\delta(X)], \text { for } a+(n-2) b \neq 0 . \tag{2.15}
\end{equation*}
$$

Also contracting (2.14) over $X$ and $U$ we have

$$
\begin{align*}
\frac{n-2}{2 n} d r(Z)= & \alpha(Q Z)-\beta(Q Z)+\delta(Q Z)  \tag{2.16}\\
& -\frac{r}{n}[\alpha(Z)-\beta(Z)+\delta(Z)],
\end{align*}
$$

for $a+(n-2) b \neq 0$. Furthermore, contracting (2.14) over $X$ and $Z$ we obtain

$$
\begin{align*}
\frac{n-2}{2 n} d r(U)= & \alpha(Q U)+\beta(Q U)-\delta(Q U)  \tag{2.17}\\
& -\frac{r}{n}[\alpha(U)+\beta(U)-\delta(U)]
\end{align*}
$$

provided that $a+(n-2) b \neq 0$. Replacing $U$ by $Z$ in (2.17) yields

$$
\begin{align*}
\frac{n-2}{2 n} d r(Z)= & \alpha(Q Z)+\beta(Q Z)-\delta(Q Z)  \tag{2.18}\\
& -\frac{r}{n}[\alpha(Z)+\beta(Z)-\delta(Z)] .
\end{align*}
$$

From (2.16) and (2.18) it follows that

$$
\begin{equation*}
\beta(Q Z)-\delta(Q Z)=\frac{r}{n}[\beta(Z)-\delta(Z)], \text { for } a+(n-2) b \neq 0 \tag{2.19}
\end{equation*}
$$

In view of (2.15) and (2.19), we obtain

$$
\begin{equation*}
\beta(Q Z)=\frac{r}{n} \beta(Z) \tag{2.20}
\end{equation*}
$$

and

$$
\begin{equation*}
\delta(Q Z)=\frac{r}{n} \delta(Z), \text { for } a+(n-2) b \neq 0 . \tag{2.21}
\end{equation*}
$$

This leads to the following:
Proposition 2.4. In $a(W Q C S)_{n}$ with $a+(n-2) b \neq 0, \frac{r}{n}$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvectors $L_{2}$ and $L_{3}$ defined by $g\left(X, L_{2}\right)=\beta(X)$ and $g\left(X, L_{3}\right)=\delta(X)$ respectively, for all $X$.

Using (2.20) and (2.21) in (2.18) we get

$$
\begin{equation*}
\frac{n-2}{2 n} d r(Z)=\alpha(Q Z)-\frac{r}{n} \alpha(Z), \text { for } a+(n-2) b \neq 0 \tag{2.22}
\end{equation*}
$$

If the manifold is of constant scalar curvature then (2.22) yields

$$
\begin{equation*}
\alpha(Q Z)=\frac{r}{n} \alpha(Z), \text { for } a+(n-2) b \neq 0 \tag{2.23}
\end{equation*}
$$

Thus we can state the following:

Proposition 2.5. If $a(W Q C S)_{n}$ is of constant scalar curvature with $a+(n-$ $2) b \neq 0$, then $\frac{r}{n}$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $L_{1}$ defined by $g\left(X, L_{1}\right)=\alpha(X)$ for all $X$.

Using (2.20) and (2.21) in (2.14) we obtain

$$
\begin{align*}
& \{a+(n-2) b\}\left[\left(\nabla_{X} S\right)(Z, U)-\frac{1}{n} d r(X) g(Z, U)\right]  \tag{2.24}\\
& =\{a+(n-2) b\}\left[\alpha(X)\left\{S(Z, U)-\frac{r}{n} g(Z, U)\right\}+\beta(Z)\{S(X, U)\right. \\
& \left.\left.-\frac{r}{n} g(X, U)\right\}+\delta(U)\left\{S(Z, X)-\frac{r}{n} g(Z, X)\right\}\right] \\
& +a[\beta(R(X, Z) U)+\delta(R(X, U) Z)]+b[\beta(X) S(Z, U) \\
& -\beta(Z) S(X, U)+\delta(X) S(Z, U)-\delta(U) S(Z, X)] \\
& -\frac{r}{n}\left(\frac{a}{n-1}+b\right)[\beta(X) g(Z, U)-\beta(Z) g(X, U) \\
& +\delta(X) g(Z, U)-\delta(U) g(Z, X)] .
\end{align*}
$$

The above results will be used in the later sections.

## §3. Decomposable $(W Q C S)_{n}$

A Riemannian manifold $\left(M^{n}, g\right)$ is said to be decomposable or product manifold [6] if it can be expressed as $M_{1}^{p} \times M_{2}^{n-p}$ for $2 \leq p \leq n-2$.

Let $\left(M^{n}, g\right)$ be a Riemannian manifold such that $M^{n}=M_{1}^{p} \times M_{2}^{n-p}$ $(2 \leq p \leq n-2)$. We assume that $M$ is a weakly quasi-conformally symmetric manifold, that is, for $X, Y, Z, U, V \in \chi(M)$

$$
\begin{aligned}
\left(\nabla_{X} W\right)(Y, Z, U, V)= & \alpha(X) W(Y, Z, U, V)+\beta(Y) W(X, Z, U, V) \\
& +\beta(Z) W(Y, X, U, V)+\delta(U) W(Y, Z, X, V) \\
& +\delta(V) W(Y, Z, U, X)
\end{aligned}
$$

where $\alpha, \beta$ and $\delta$ are (not simultaneously zero) 1-forms on $M$. Then we find

$$
\begin{align*}
&\left(\nabla_{\bar{X}} W\right)(\bar{Y}, \bar{Z}, \bar{U}, \bar{V})= \alpha(\bar{X}) W(\bar{Y}, \bar{Z}, \bar{U}, \bar{V})+\beta(\bar{Y}) W(\bar{X}, \bar{Z}, \bar{U}, \bar{V})  \tag{3.1}\\
&+\beta(\bar{Z}) W(\bar{Y}, \bar{X}, \bar{U}, \bar{V})+\delta(\bar{U}) W(\bar{Y}, \bar{Z}, \bar{X}, \bar{V}) \\
&+\delta(\bar{V}) W(\bar{Y}, \bar{Z}, \bar{U}, \bar{X}), \\
& \alpha(\stackrel{*}{X}) W(\bar{Y}, \bar{Z}, \bar{U}, \bar{V})=0  \tag{3.2}\\
& \beta(\stackrel{*}{Y}) W(\bar{X}, \bar{Z}, \bar{U}, \bar{V})=0  \tag{3.3}\\
& \delta(\stackrel{*}{U}) W(\bar{Y}, \bar{Z}, \bar{X}, \bar{V})=0 \tag{3.4}
\end{align*}
$$

$$
\begin{gather*}
\beta(\bar{Z}) W(\stackrel{*}{X}, \stackrel{*}{Y}, \bar{U}, \bar{V})+\delta(\bar{U}) W(\stackrel{*}{X}, \bar{V}, \bar{Z}, \stackrel{*}{Y})-\delta(\bar{V}) W(\stackrel{*}{X}, \bar{U}, \bar{Z}, \stackrel{*}{Y})=0  \tag{3.5}\\
\beta(\bar{Y}) W(\stackrel{*}{X}, \bar{Z}, \bar{V}, \stackrel{*}{U})-\beta(\bar{Z}) W(\stackrel{*}{X}, \bar{Y}, \bar{V}, \stackrel{*}{U})+\delta(\bar{V}) W(\stackrel{*}{X}, \stackrel{*}{U}, \bar{Y}, \bar{Z})=0  \tag{3.6}\\
\left(\nabla_{\bar{X}} W\right)(\stackrel{*}{Y}, \bar{Z}, \bar{U}, \stackrel{*}{V})=  \tag{3.7}\\
\quad \alpha(\bar{X}) W(\stackrel{*}{Y}, \bar{Z}, \bar{U}, \stackrel{*}{V})+\beta(\bar{Z}) W(\stackrel{*}{Y}, \bar{X}, \bar{U}, \stackrel{*}{V}) \\
\\
+\delta(\bar{U}) W(\stackrel{*}{Y}, \bar{Z}, \bar{X}, \stackrel{*}{V})
\end{gather*}
$$

$$
\begin{align*}
& \left(\nabla_{\stackrel{*}{X}} W\right)(\stackrel{*}{Y}, \bar{Z}, \bar{U}, \stackrel{*}{V})=\alpha\left({ }_{X}^{X}\right) W(\stackrel{*}{Y}, \bar{Z}, \bar{U}, \stackrel{*}{V})+\beta(\stackrel{*}{Y}) W(\stackrel{*}{X}, \bar{Z}, \bar{U}, \stackrel{*}{V})  \tag{3.8}\\
& +\delta(\stackrel{*}{V}) W(\stackrel{*}{Y}, \bar{Z}, \bar{U}, \stackrel{*}{X}), \\
& \beta(\stackrel{*}{Z}) W(\bar{X}, \bar{Y}, \stackrel{*}{U}, \stackrel{*}{V})+\delta(\stackrel{*}{U}) W(\stackrel{*}{Z}, \bar{Y}, \bar{X}, \stackrel{*}{V})-\delta\left({ }^{*}\right) W(\stackrel{*}{Z}, \bar{Y}, \bar{X}, \stackrel{*}{U})=0,  \tag{3.9}\\
& \beta(\stackrel{*}{Y}) W(\stackrel{*}{Z}, \bar{X}, \bar{U}, \stackrel{*}{V})-\beta(\stackrel{*}{Z}) W(\stackrel{*}{Y}, \bar{X}, \bar{U}, \stackrel{*}{V})+\delta\left({ }_{V}^{V}\right) W(\stackrel{*}{Y}, \stackrel{*}{Z}, \bar{X}, \bar{U})=0,  \tag{3.10}\\
& \alpha(\bar{X}) W(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})=0,  \tag{3.11}\\
& \beta(\bar{Y}) W(\stackrel{*}{X}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})=0,  \tag{3.12}\\
& \delta(\bar{U}) W(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{X}, \stackrel{*}{V})=0,  \tag{3.13}\\
& \left(\nabla_{X} W\right)(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})=\alpha(\stackrel{*}{X}) W(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})+\beta(\stackrel{*}{Y}) W(\stackrel{*}{X}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})  \tag{3.14}\\
& +\beta(\stackrel{*}{Z}) W(\stackrel{*}{Y}, \stackrel{*}{X}, \stackrel{*}{U}, \stackrel{*}{V})+\delta(\stackrel{*}{U}) W(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{X}, \stackrel{*}{V}) \\
& +\delta(\stackrel{*}{V}) W(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{X})
\end{align*}
$$

for $\bar{X}, \bar{Y}, \bar{Z}, \bar{U}, \bar{V} \in \chi\left(M_{1}\right)$ and $\stackrel{*}{X}, \stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V} \in \chi\left(M_{2}\right)$. From (3.2)-(3.4), we have two cases, namely,
(1) $\alpha=0, \beta=0, \delta=0$ on $M_{2}$,
(2) $M_{1}$ is a quasi-conformally flat.

At first, we consider the case (1). Then from (3.8) it follows that

$$
\begin{align*}
& \left(\nabla_{\underset{X}{*}} W\right)(\stackrel{*}{Y}, \bar{Z}, \bar{U}, \stackrel{*}{V})=0, \text { which implies that } \\
& b\left(\nabla_{*}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{V})=\frac{\stackrel{*}{X} r}{n}\left(\frac{a}{n-1}+2 b\right) g(\stackrel{*}{Y}, \stackrel{*}{V}) \tag{3.15}
\end{align*}
$$

Also from (3.14), we obtain

$$
\left(\nabla_{X} W\right)(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})=0, \text { that is, }
$$

$$
\begin{align*}
& a\left(\nabla_{X} R\right)(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})  \tag{3.16}\\
& +b\left\{\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Z}, \stackrel{*}{U}) g(\stackrel{*}{Y}, \stackrel{*}{V})-\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{U}) g(\stackrel{*}{Z}, \stackrel{*}{V})\right. \\
& \left.+g(\stackrel{*}{Z}, \stackrel{*}{U})\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{V})-g(\stackrel{*}{Y}, \stackrel{*}{U})\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Z}, \stackrel{*}{V})\right\} \\
& -\frac{\stackrel{*}{X}}{n}\left(\frac{a}{n-1}+2 b\right)\{g(\stackrel{*}{Z}, \stackrel{*}{U}) g(\stackrel{*}{Y}, \stackrel{*}{V})-g(\stackrel{*}{Y}, \stackrel{*}{U}) g(\stackrel{*}{Z}, \stackrel{*}{V})\}=0,
\end{align*}
$$

which yields that

$$
\begin{align*}
& \{a+(n-p-2) b\}\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{V})  \tag{3.17}\\
& =\frac{\stackrel{*}{X} \stackrel{*}{r}}{n}\left\{\frac{n-p-1}{n-1} a+(n-2 p-2) b\right\} g(\stackrel{*}{Y}, \stackrel{*}{V}),
\end{align*}
$$

where we denote the scalar curvature on $M_{2}$ by $\stackrel{*}{r}$. It is easy to see from (3.15), (3.17) and $\stackrel{*}{X} \stackrel{*}{r}=\stackrel{*}{X} r$ that

$$
\{a+(n-1) b\}\{a+(n-2) b\} \stackrel{*}{X} r=0 .
$$

Thus we have the following three cases:
(1-1) $a+(n-1) b=0$;
(1-2) $a+(n-2) b=0$;
(1-3) $\quad \stackrel{*}{X} r=0$.
In the case of (1-1), we find from (3.15) and $b \neq 0$

$$
\begin{aligned}
& \left(\nabla_{X} S\right)(\stackrel{*}{Y}, \stackrel{*}{V})=\frac{\stackrel{*}{X} r}{n} g(\stackrel{*}{Y}, \stackrel{*}{V}), \\
& \text { which implies that } \quad \stackrel{*}{X} r=0 .
\end{aligned}
$$

Thus we have $\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{V})=0$. Similarly, if the case (1-2) holds, then we get $\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{V})=0$. By virtue of (3.15) and (3.17), when (1-3) holds, we have $\left(\nabla_{X}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{V})=0$ if $a \neq 0$ or $b \neq 0$. Moreover, from (3.16) we find

$$
\begin{aligned}
& \left(\nabla_{\stackrel{*}{X}} R\right)(\stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, \stackrel{*}{V})=0 \\
& \text { if } \quad a \neq 0
\end{aligned}
$$

Secondly, we discuss the case of (2). From $W=0$ on $M_{1}$, we find

$$
\begin{align*}
& a R(\bar{X}, \bar{Y}, \bar{Z}, \bar{U})+b[S(\bar{Y}, \bar{Z}) g(\bar{X}, \bar{U})-S(\bar{X}, \bar{Z}) g(\bar{Y}, \bar{U})  \tag{3.18}\\
& +g(\bar{Y}, \bar{Z}) S(\bar{X}, \bar{U})-g(\bar{X}, \bar{Z}) S(\bar{Y}, \bar{U})] \\
& -\frac{r}{n}\left(\frac{a}{n-1}+2 b\right)\{g(\bar{Y}, \bar{Z}) g(\bar{X}, \bar{U})-g(\bar{X}, \bar{Z}) g(\bar{Y}, \bar{U})\}=0,
\end{align*}
$$

which implies that

$$
\begin{equation*}
\{a+(p-2) b\} S(\bar{Y}, \bar{Z})+\left\{b \bar{r}-\frac{(p-1) r}{n}\left(\frac{a}{n-1}+2 b\right)\right\} g(\bar{Y}, \bar{Z})=0 \tag{3.19}
\end{equation*}
$$

where $\bar{r}$ is the scalar curvature on $M_{1}$. Thus we find

$$
\begin{equation*}
b \bar{r}-\frac{(p-1) r}{n}\left(\frac{a}{n-1}+2 b\right)=-\frac{\bar{r}}{p}\{a+(p-2) b\} . \tag{3.20}
\end{equation*}
$$

Using (3.20) in (3.19) we obtain

$$
\{a+(p-2) b\}\left\{S(\bar{Y}, \bar{Z})-\frac{\bar{r}}{p} g(\bar{Y}, \bar{Z})\right\}=0 .
$$

Therefore we can consider the following two cases:
(2-1) $a+(p-2) b=0$;
$(2-2) \quad a+(p-2) b \neq 0$.
In the case of (2-1), we get from (3.18), (3.20) and $b \neq 0$

$$
\begin{align*}
& (p-2) R(\bar{X}, \bar{Y}, \bar{Z}, \bar{U})-\{S(\bar{Y}, \bar{Z}) g(\bar{X}, \bar{U})-S(\bar{X}, \bar{Z}) g(\bar{Y}, \bar{U})  \tag{3.21}\\
& +g(\bar{Y}, \bar{Z}) S(\bar{X}, \bar{U})-g(\bar{X}, \bar{Z}) S(\bar{Y}, \bar{U})\} \\
& +\frac{\bar{r}}{p-1}\{g(\bar{Y}, \bar{Z}) g(\bar{X}, \bar{U})-g(\bar{X}, \bar{Z}) g(\bar{Y}, \bar{U})\}=0
\end{align*}
$$

Thus $M_{1}$ is conformally flat if $p \neq 2$. Also, in the case of (2-2), equation (3.18) is rewritten as follows:

$$
\begin{equation*}
R(\bar{X}, \bar{Y}, \bar{Z}, \bar{U})=\frac{\bar{r}}{p(p-1)}\{g(\bar{Y}, \bar{Z}) g(\bar{X}, \bar{U})-g(\bar{X}, \bar{Z}) g(\bar{Y}, \bar{U})\} \tag{3.22}
\end{equation*}
$$

if $a \neq 0$. Hence we have
Theorem 3.1. Let $\left(M^{n}, g\right)$ be a Riemannian manifold such that $M=M_{1}^{p} \times$ $M_{2}^{n-p}(2 \leq p \leq n-2)$. If $M$ is $a(W Q C S)_{n}$, then we get
(1) in the case of $\alpha=0, \beta=0, \delta=0$ on $M_{2}, M_{2}$ is a locally symmetric manifold for $a \neq 0$,
(2) when $M_{1}$ is a quasi-conformally flat,
(i) if $a+(p-2) b=0$ and $p \geq 3$, then $M_{1}$ is conformally flat,
(ii) if $a \neq 0, a+(p-2) b \neq 0$ and $p \geq 3$, then $M_{1}$ is a manifold of constant curvature.

Similarly we have from (3.11)-(3.13)
Theorem 3.2. Let $\left(M^{n}, g\right)$ be a Riemannian manifold such that $M=M_{1}^{p} \times$ $M_{2}^{n-p}(2 \leq p \leq n-2)$. If $M$ is $a(W Q C S)_{n}$, then we get
(1) in the case of $\alpha=0, \beta=0, \delta=0$ on $M_{1}, M_{1}$ is a locally symmetric
manifold for $a \neq 0$,
(2) when $M_{2}$ is a quasi-conformally flat,
(i) if $a+(p-2) b=0$ and $p \leq n-3$, then $M_{2}$ is conformally flat,
(ii) if $a \neq 0, a+(p-2) b \neq 0$ and $p \leq n-3$, then $M_{2}$ is of constant curvature.
Next, we consider the contraction with respect to $\stackrel{*}{X}$ and $\stackrel{*}{U}$ in (3.6) and obtain

$$
\begin{aligned}
& \beta(\bar{Y})\left[b\{\stackrel{*}{r} g(\bar{Z}, \bar{V})+(n-p) S(\bar{Z}, \bar{V})\}-\frac{(n-p) r}{n}\left(\frac{a}{n-1}+2 b\right) g(\bar{Z}, \bar{V})\right] \\
& -\beta(\bar{Z})\left[b\left\{{ }^{*} r g(\bar{Y}, \bar{V})+(n-p) S(\bar{Y}, \bar{V})\right\}-\frac{(n-p) r}{n}\left(\frac{a}{n-1}+2 b\right) g(\bar{Y}, \bar{V})\right] \\
& =0,
\end{aligned}
$$

which yields that

$$
\begin{equation*}
b(n-p) \beta(Q \bar{Y})=-\frac{r_{1}}{n} \beta(\bar{Y}), \tag{3.23}
\end{equation*}
$$

where we put
$r_{1}=(n-p)\left\{\frac{p-1}{n-1} a-(n-2 p+2) b\right\} \bar{r}+(p-1)\left\{\frac{n-p}{n-1} a+(n-2 p) b\right\} \stackrel{*}{r}$.
Similarly, we have from (3.5)

$$
\begin{equation*}
b(n-p) \delta(Q \bar{U})=-\frac{r_{1}}{n} \delta(\bar{U}) . \tag{3.24}
\end{equation*}
$$

If $b=0$, that is, $W=a \widetilde{C}$ on $M$, then from (3.23) and (3.24) we get $r \beta(\bar{Y})=0$ and $r \delta(\bar{U})=0$. Thus we can consider the two cases:
(3) $r=0$,
(4) $r \neq 0$, namely, $\beta=0, \delta=0$ on $M_{1}$.

If $r=0$, then $M$ is a weakly symmetric manifold. When the case of (4) holds, we obtain from (3.7) that

$$
\begin{equation*}
\alpha(\bar{X})=-\bar{X} \log |r| . \tag{3.25}
\end{equation*}
$$

It is clear from (3.1) that

$$
\begin{equation*}
\left(\nabla_{\bar{X}} \widetilde{C}\right)(\bar{Y}, \bar{Z}, \bar{U}, \bar{V})=\alpha(\bar{X}) \widetilde{C}(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) \tag{3.26}
\end{equation*}
$$

Hence we can state the following:
Theorem 3.3. Let $\left(M^{n}, g\right)$ be a Riemannian manifold such that $M=M_{1}^{p} \times$ $M_{2}^{n-p}(2 \leq p \leq n-2)$. If $M$ is a $(W Q C S)_{n}$, then we get
(1) if $b \neq 0$, then we find

$$
\begin{aligned}
\beta(Q \cdot) & =-\frac{r_{1}}{b n(n-p)} \beta(\cdot) \\
\text { and } \quad \delta(Q \cdot) & =-\frac{r_{1}}{b n(n-p)} \delta(\cdot) \text { on } M_{1}
\end{aligned}
$$

(2) in the case of $b=0$,
(i) if $r=0$, then $M$ is a weakly symmetric manifold,
(ii) if $r \neq 0$, then $\alpha(\bar{X})=-\bar{X} \log |r|$ and $\nabla_{\bar{X}} \widetilde{C}=\alpha(\bar{X}) \widetilde{C}$ on $M_{1}$ for $\bar{X} \in \chi\left(M_{1}\right)$. Especially, if $r$ is a non-zero constant, then the concircular curvature tensor field is parallel on $M_{1}$.

Similarly, from (3.9) and (3.10) we can state the following
Theorem 3.4. Let $\left(M^{n}, g\right)$ be a Riemannian manifold such that $M=M_{1}^{p} \times$ $M_{2}^{n-p}(2 \leq p \leq n-2)$. If $M$ is $a(W Q C S)_{n}$, then we get
(1) if $b \neq 0$, then we find

$$
\begin{aligned}
\beta(Q \cdot) & =-\frac{r_{2}}{b n p} \beta(\cdot) \\
\text { and } \quad \delta(Q \cdot) & =-\frac{r_{2}}{b n p} \delta(\cdot) \text { on } M_{2}
\end{aligned}
$$

where we put

$$
r_{2}=(n-p-1)\left\{\frac{p a}{n-1}-(n-2 p) b\right\} \bar{r}+p\left\{\frac{n-p-1}{n-1} a+(n-2 p-2) b\right\} \stackrel{*}{r},
$$

(2) in the case of $b=0$,
(i) if $r=0$, then $M$ is a weakly symmetric manifold,
(ii) if $r \neq 0$, then $\alpha(\stackrel{*}{X})=-\stackrel{*}{X} \log |r|$ and $\nabla_{X}^{*} \widetilde{C}=\alpha(\stackrel{*}{X}) \widetilde{C}$ on $M_{2}$ for $\stackrel{*}{X} \in \chi\left(M_{2}\right)$. Especially, if $r$ is a non-zero constant, then the concircular curvature tensor field is parallel on $M_{2}$.

## §4. $(W Q C S)_{n}$ satisfying certain conditions

Definition 4.1. The Ricci tensor of a Riemannian manifold is said to be cyclic parallel if it satisfies the following condition:

$$
\begin{equation*}
\left(\nabla_{X} S\right)(Y, Z)+\left(\nabla_{Y} S\right)(Z, X)+\left(\nabla_{Z} S\right)(X, Y)=0 \tag{4.1}
\end{equation*}
$$

for all vector fields $X, Y, Z$ on the manifold i.e., the Ricci tensor $S$ of a Riemannian manifold is cyclic parallel if the cyclic sum of the covariant derivative of $S$ vanishes.

From (4.1) it follows that in such a manifold the scalar curvature $r$ is a constant.
We now consider a $(W Q C S)_{n}$ satisfying the relation (4.1). Taking cyclic sum
with respect to $X, Z, U$ in (2.24) we obtain by virtue of (4.1) and Bianchi identity that

$$
\begin{align*}
& \{\alpha(X)+\beta(X)+\delta(X)\}\left[S(Z, U)-\frac{r}{n} g(Z, U)\right]  \tag{4.2}\\
& +\{\alpha(Z)+\beta(Z)+\delta(Z)\}\left[S(X, U)-\frac{r}{n} g(X, U)\right] \\
& +\{\alpha(U)+\beta(U)+\delta(U)\}\left[S(Z, X)-\frac{r}{n} g(Z, X)\right]=0
\end{align*}
$$

for $a+(n-2) b \neq 0$ and $\alpha+\beta+\delta \neq 0$ everywhere.
We now choose the vector fields $L_{1}, L_{2}$ and $L_{3}$ corresponding to the 1-forms $\alpha, \beta$ and $\delta$ respectively as the unit vector fields such that they are mutually orthogonal to each other. We now suppose that $\alpha(Y) \neq 0$ for all $Y$. For if, $\alpha(Y)=0$ for all $Y$ then $g\left(L_{1}, L_{1}\right)=0$, which contradicts to our assumption that $L_{1}$ is a unit vector field. Then multiplying both sides of (4.2) by $\alpha(Y)$ we get

$$
\begin{align*}
& \alpha(Y)\{\alpha(X)+\beta(X)+\delta(X)\}\left[S(Z, U)-\frac{r}{n} g(Z, U)\right]  \tag{4.3}\\
& +\alpha(Y)\{\alpha(Z)+\beta(Z)+\delta(Z)\}\left[S(X, U)-\frac{r}{n} g(X, U)\right] \\
& +\alpha(Y)\{\alpha(U)+\beta(U)+\delta(U)\}\left[S(Z, X)-\frac{r}{n} g(Z, X)\right]=0 .
\end{align*}
$$

Setting $X=Y=e_{i}$ in (4.3) and taking summation over $i, 1 \leq i \leq n$, we have

$$
\begin{align*}
& S(Z, U)-\frac{r}{n} g(Z, U)+\{\alpha(Z)+\beta(Z)+\delta(Z)\}\left[\alpha(Q U)-\frac{r}{n} \alpha(U)\right]  \tag{4.4}\\
& +\{\alpha(U)+\beta(U)+\delta(U)\}\left[\alpha(Q Z)-\frac{r}{n} \alpha(Z)\right]=0
\end{align*}
$$

Since the manifold under consideration is of constant scalar curvature, using (2.23) in (4.4) we get

$$
S(Z, U)=\frac{r}{n} g(Z, U), \text { which means that the manifold is Einstein. }
$$

In a similar manner multiplying (4.3) by $\beta(Y)$ and $\delta(Y)$ respectively we obtain that the manifold is Einstein. This leads to the following:

Theorem 4.1. If in $a(W Q C S)_{n}$, the Ricci tensor is cyclic parallel and $a+$ $(n-2) b \neq 0$ then it is an Einstein manifold unless $\alpha+\beta+\delta$ is non-vanishing everywhere.

Corollary 4.1. If $a(W Q C S)_{n}$ is Ricci symmetric then it is an Einstein manifold, provided that $a+(n-2) b \neq 0$ and $\alpha+\beta+\delta \neq 0$ everywhere.

Again in [7] it is shown that if an Einstein $(W Q C S)_{n}$ is a $(W S)_{n}$ then the scalar curvature of the manifold vanishes, provided that $a \neq 0$ and $\alpha+\beta+\delta \neq 0$. Hence by virtue of Theorem 4.1 we can state the following:

Theorem 4.2. If a $(W Q C S)_{n}$ with cyclic parallel Ricci tensor is a $(W S)_{n}$ then the scalar curvature of the manifold vanishes, provided that $a \neq 0, a+$ $(n-2) b \neq 0$ and $\alpha+\beta+\delta \neq 0$ everywhere.

Next in [7] it is proved that if in an Einstein $(W Q C S)_{n}$ the scalar curvature vanishes then it is a $(W S)_{n}$, provided that $a \neq 0$. Hence by virtue of Theorem 4.1 we can state the following:

Theorem 4.3. If in a $(W Q C S)_{n}$ with cyclic parallel Ricci tensor the scalar curvature vanishes, then it is $a(W S)_{n}$, provided that $a \neq 0, a+(n-2) b \neq 0$ and $\alpha+\beta+\delta \neq 0$ everywhere.

Therefore if a $(W Q C S)_{n}$ satisfying (4.1) is of non-vanishing scalar curvature then in view of Theorem 4.3 we can state the following:

Theorem 4.4. If in $a(W Q C S)_{n}$ with non-vanishing scalar curvature, the Ricci tensor is cyclic parallel then it cannot be $a(W S)_{n}$, provided that $a \neq 0$, $a+(n-2) b \neq 0$ and $\alpha+\beta+\delta \neq 0$ everywhere.

Definition 4.2. A vector field $L$ on a Riemannian manifold is said to be concurrent [6] if $\nabla_{X} L=\rho X$, where $\rho$ is a constant.

In particular, if $\rho=0$ then $L$ is said to be a parallel vector field.
Let us now consider a $(W Q C S)_{n}$ such that the vector field $L=L_{2}+L_{3}$ defined by $g(X, L)=\beta(X)+\delta(X)$ is a concurrent vector field. Then making use of Ricci identity we have

$$
\begin{gather*}
R(X, Y, L, U)=0 \quad \text { which implies that }  \tag{4.5}\\
S(Y, L)=0 . \tag{4.6}
\end{gather*}
$$

Now the relation (2.15) can be written as

$$
\begin{equation*}
S(X, L)=\frac{r}{n} g(X, L), \quad \text { provided that } a+(n-2) b \neq 0 \tag{4.7}
\end{equation*}
$$

From (4.6) and (4.7) it follows that

$$
r=0, \quad \text { if } \quad\|L\|^{2} \neq 0
$$

This leads to the following:

Theorem 4.5. If in a $(W Q C S)_{n}$ the vector field $L$ defined by $g(X, L)=$ $\beta(X)+\delta(X)$ is a concurrent vector field then it is of vanishing scalar curvature, provided that $a+(n-2) b \neq 0$ and $\|L\|^{2} \neq 0$.

Since $r=0$, from (2.20) and (2.21) we get

$$
\begin{equation*}
\beta(Q X)=\delta(Q X)=0 \text { if } a+(n-2) b \neq 0 . \tag{4.8}
\end{equation*}
$$

Now using (4.8) and $r=0$ in (2.14) we obtain

$$
\begin{align*}
& \{a+(n-2) b\}\left(\nabla_{X} S\right)(Z, U)  \tag{4.9}\\
& =\{a+(n-2) b\}[\alpha(X) S(Z, U)+\beta(Z) S(X, U)+\delta(U) S(Z, X)] \\
& +a[\beta(R(X, Z) U)+\delta(R(X, U) Z)]+b[\beta(X) S(Z, U) \\
& -\beta(Z) S(X, U)+\delta(X) S(Z, U)-\delta(U) S(Z, X)] .
\end{align*}
$$

Again from $\nabla_{X} L=\rho X$, we have

$$
\begin{equation*}
\left(\nabla_{X} S\right)(Z, L)=-\rho S(Z, X) \tag{4.10}
\end{equation*}
$$

Setting $U=L$ in (4.9) and then using (4.5) and (4.6) we obtain by virtue of (4.10) that

$$
\begin{equation*}
[\rho\{a+(n-2) b\}+\{a+(n-3) b\} \delta(L)] S(Z, X)+a \delta(R(X, L) Z)=0 \tag{4.11}
\end{equation*}
$$

From (4.5) we have

$$
\begin{aligned}
& R(L, U, X, Y)=0, \quad \text { which implies that } \\
& R(U, L, Y, X)=0 \quad \text { for all vector fields } U, X, Y .
\end{aligned}
$$

The last relation yields (for $\left.X=L_{3}\right)$ that $\delta(R(U, L) Y)=0$ for all vector fields $U, Y \in \chi(M)$. Hence $\delta(R(X, L) Z)=0$ for all $X, Z \in \chi(M)$. Consequently (4.11) reduces to

$$
S(Z, X)=0 \text { for all } X \text { and } Z,
$$

provided that $\rho\{a+(n-2) b\}+\{a+(n-3) b\} \delta(L) \neq 0$.
Thus (2.1) takes the form $W(X, Y, Z, U)=a R(X, Y, Z, U)$ and hence (1.5) reduces to

$$
\begin{aligned}
\left(\nabla_{X} R\right)(Y, Z, U, V)= & \alpha(X) R(Y, Z, U, V)+\beta(Y) R(X, Z, U, V) \\
& +\beta(Z) R(Y, X, U, V)+\delta(U) R(Y, Z, X, V) \\
& +\delta(V) R(Y, Z, U, X)
\end{aligned}
$$

for $a \neq 0$, which implies that the manifold is a $(W S)_{n}$. Thus we can state the following:

Theorem 4.6. If in $a(W Q C S)_{n}$ with $a \neq 0$ and $a+(n-2) b \neq 0$ the non-null vector field $L$ defined by $g(X, L)=\beta(X)+\delta(X)$ is a concurrent vector field then it is $a(W S)_{n}$, provided that $\rho\{a+(n-2) b\}+\{a+(n-3) b\} \delta(L) \neq 0$.

Corollary 4.2. If in $a(W Q C S)_{n}$ with $a \neq 0$ and $a+(n-2) b \neq 0$ the nonnull vector field $L$ defined by $g(X, L)=\beta(X)+\delta(X)$ is a parallel vector field then it is a $(W S)_{n}$, provided that $\{a+(n-3) b\} \delta(L) \neq 0$.

The above corollary certainly improves the Theorem 4.5 of [7].
Definition 4.3. A vector field $L$ on a Riemannian manifold is said to be recurrent [6] if $\nabla_{X} L=\mu(X) L$, where $\mu$ is a non-zero 1-form, called the associated 1-form of the recurrent vector field.

In particular, if $\mu(X)$ is a constant then the recurrent vector field reduces to a concurrent vector field.
Now we consider a $(W Q C S)_{n}$ such that the vector field $L$ defined by $g(X, L)=$ $\beta(X)+\delta(X)$ is a recurrent vector field. Then we have

$$
\nabla_{X} \nabla_{Y} L=(X \mu(Y)) L+\mu(X) \mu(Y) L
$$

and hence using Ricci identity we get

$$
\begin{aligned}
& R(X, Y, L, U)=2 d \mu(X, Y) g(L, U) \text { which implies that } \\
& R(X, Y, L, U)=0, \quad \text { if the } 1 \text {-form } \mu \text { is closed. }
\end{aligned}
$$

Then $S(Y, L)=0$ and hence $r=0$. Therefore proceeding similarly as before we obtain that the manifold is a $(W S)_{n}$. Hence we can state the following:

Theorem 4.7. If in $a(W Q C S)_{n}$ with $a \neq 0$ and $a+(n-2) b \neq 0$, the vector field $L$ defined by $g(X, L)=\beta(X)+\delta(X)$ is a recurrent vector field such that the associated 1-form of the recurrent vector field is closed then it is a $(W S)_{n}$, provided that $a+(n-3) b \neq 0$ and $\delta(L) \neq 0$.

## §5. Some examples of $(W Q C S)_{n}$

This section deals with several examples of $(W Q C S)_{n}$. We calculate the components of the curvature tensor, the Ricci tensor, the quasi-conformal curvature tensor and its covariant derivative.
EXAMPLE 1. Let $M^{4}=\left\{\left(x^{1}, x^{2}, x^{3}, x^{4}\right) \in \mathbf{R}^{4} \mid x^{1}<0, x^{3}>0\right\}$ be an open subset of $\mathbf{R}^{4}$ endowed with the metric

$$
\begin{equation*}
d s^{2}=x^{1}\left(x^{3}\right)^{2}\left(d x^{1}\right)^{2}+2 d x^{1} d x^{2}+\left(d x^{3}\right)^{2}+\left(d x^{4}\right)^{2} . \tag{5.1}
\end{equation*}
$$

Then the only non-vanishing components of the Christoffel's symbols, the curvature tensor, the Ricci tensor, the scalar curvature, the quasi-conformal curvature tensor and its covariant derivatives are

$$
\begin{aligned}
& \Gamma_{11}^{2}=\frac{1}{2}\left(x^{3}\right)^{2}, \quad \Gamma_{11}^{3}=-x^{1} x^{3}=-\Gamma_{13}^{2} \\
& R_{1313}=x^{1}, \quad S_{11}=-x^{1}, \quad r=0 \\
& W_{1313}=(a+b) x^{1}, \quad W_{1414}=b x^{1} \\
& W_{1313,1}=(a+b), \quad W_{1414,1}=b
\end{aligned}
$$

Here ',' denotes the covariant differentiation with respect to the metric tensor $g$. Therefore our $M^{4}$ with the considered metric $g$ in (5.1) is a Riemannian manifold of vanishing scalar curvature which is neither quasi-conformally flat nor quasi-conformally symmetric. We put

$$
\begin{aligned}
& \alpha_{i}\left(\partial_{i}\right)=\alpha_{i}=\left\{\begin{array}{cl}
\frac{1}{2 x^{1}} & \text { for } \quad i=1 \\
0 & \text { otherwise }
\end{array}\right. \\
& \beta_{i}\left(\partial_{i}\right)=\beta_{i}=\left\{\begin{array}{cl}
\frac{1}{3 x^{1}} & \text { for } i=1 \\
0 & \text { otherwise }
\end{array}\right. \\
& \delta_{i}\left(\partial_{i}\right)=\delta_{i}=\left\{\begin{array}{cl}
\frac{1}{6 x^{1}} & \text { for } i=1 \\
0 & \text { otherwise }
\end{array}\right.
\end{aligned}
$$

where $\partial_{i}=\frac{\partial}{\partial x^{i}}$. Then $\left(M^{4}, g\right)$ is a $(W Q C S)_{4}$. Hence we can state the following:

Theorem 5.1. Let $\left(M^{4}, g\right)$ be a Riemannian manifold endowed with the metric given in (5.1). Then $\left(M^{4}, g\right)$ is a weakly quasi-conformally symmetric manifold with vanishing scalar curvature which is neither quasi-conformally symmetric nor quasi-conformally recurrent.

EXAMPLE 2. Let $M^{n}=\mathbf{R}^{n}(n \geq 4)$ be endowed with the metric

$$
\begin{equation*}
d s^{2}=f \cdot\left(d x^{1}\right)^{2}+\sum_{i=2}^{n-1}\left(d x^{i}\right)^{2}+2 d x^{1} d x^{n} \tag{5.2}
\end{equation*}
$$

where $f$ is a continuously differentiable function of $x^{1}, x^{2}, \ldots, x^{n-1}$ such that

$$
\begin{equation*}
f<0, \quad a f_{\cdot m m k}+b \sum_{j=2}^{n-1} f_{\cdot j j k} \neq 0 \quad \text { and } \quad a f_{\cdot m m}+b \sum_{j=2}^{n-1} f_{\cdot j j} \neq 0 \tag{5.3}
\end{equation*}
$$

for $2 \leq m \leq n-1$ and $1 \leq k \leq n-1$ and ' '' denotes the partial differentiation with respect to the coordinates. Then the only non-vanishing components of
the Christoffel's symbols, the curvature tensor, the Ricci tensor, the scalar curvature, the quasi-conformal curvature tensors and their covariant derivatives are given by the following:

$$
\begin{aligned}
& \Gamma_{11}^{m}=-\Gamma_{1 m}^{n}=-\frac{1}{2} f_{\cdot m}, \quad \Gamma_{11}^{n}=\frac{1}{2} f_{\cdot 1}, \\
& R_{1 m 1 m}=\frac{1}{2} f \cdot m m, \quad S_{11}=-\frac{1}{2} \sum_{j=2}^{n-1} f_{\cdot j j}, \quad r=0, \\
& W_{1 m 1 m}=\frac{1}{2}\left(a f \cdot m m+b \sum_{j=2}^{n-1} f_{\cdot j j}\right), \\
& W_{1 m 1 m, k}=\frac{1}{2}\left(a f_{\cdot m m k}+b \sum_{j=2}^{n-1} f_{\cdot j j k}\right) .
\end{aligned}
$$

Thus ( $M^{n}, g$ ) is neither quasi-conformally flat nor quasi-conformally symmetric. We set

$$
\begin{aligned}
& \alpha_{i}\left(\partial_{i}\right)=\alpha_{i}= \begin{cases}\partial_{i} \log \left|a f_{\cdot m m}+b \sum_{j=2}^{n-1} f_{\cdot j j}\right| & \text { for } \\
0 & i=1,2, \ldots, n-1 \\
\text { for } i=n,\end{cases} \\
& \beta_{i}\left(\partial_{i}\right)=\beta_{i}=\left\{\begin{array}{cc}
-\frac{1}{2} & \text { for } i=1 \\
0 & \text { otherwise },
\end{array}\right. \\
& \delta_{i}\left(\partial_{i}\right)=\delta_{i}= \begin{cases}\frac{1}{2} & \text { for } i=1 \\
0 & \text { otherwise },\end{cases}
\end{aligned}
$$

where $\partial_{i}=\frac{\partial}{\partial x^{2}}$. Then $\left(M^{n}, g\right)$ is a $(W Q C S)_{n}$. Hence we can state the following:

Theorem 5.2. Let $\left(M^{n}, g\right)$ be a Riemannian manifold equipped with the metric given in (5.2). Then $\left(M^{n}, g\right)$ is a weakly quasi-conformally symmetric manifold with vanishing scalar curvature which is neither quasi-conformally symmetric nor quasi-conformally recurrent.

EXAMPLE 3. Let $M^{n}=\left\{\left(x^{1}, x^{2}, \ldots, x^{n}\right) \in \mathbf{R}^{n} \mid x^{1}<0, x^{3}>0\right\}$ be endowed with the metric

$$
\begin{equation*}
d s^{2}=x^{1}\left(x^{3}\right)^{2}\left(d x^{1}\right)^{2}+2 d x^{1} d x^{2}+\sum_{i=3}^{n}\left(d x^{i}\right)^{2} \tag{5.4}
\end{equation*}
$$

Then the only non-vanishing components of the Christoffel's symbols, the curvature tensor, the Ricci tensor, the scalar curvature, the quasi-conformal
curvature tensor and their covariant derivatives are given by the following:

$$
\begin{aligned}
& \Gamma_{11}^{2}=\frac{1}{2}\left(x^{3}\right)^{2}, \quad \Gamma_{11}^{3}=-x^{1} x^{3}=-\Gamma_{13}^{2} \\
& R_{1313}=x^{1}, \quad S_{11}=-x^{1}, \quad r=0 \\
& W_{1313}=(a+b) x^{1}, \quad W_{1 k 1 k}=b x^{1} \\
& W_{1313,1}=(a+b), \quad W_{1 k 1 k, 1}=b
\end{aligned}
$$

for $4 \leq k \leq n$. We put

$$
\begin{aligned}
& \alpha_{i}\left(\partial_{i}\right)=\alpha_{i}=\left\{\begin{array}{cl}
\frac{1}{2 x^{1}} & \text { for } i=1 \\
0 & \text { otherwise }
\end{array}\right. \\
& \beta_{i}\left(\partial_{i}\right)=\beta_{i}=\left\{\begin{array}{cl}
\frac{1}{3 x^{1}} & \text { for } i=1 \\
0 & \text { otherwise },
\end{array}\right. \\
& \delta_{i}\left(\partial_{i}\right)=\delta_{i}=\left\{\begin{array}{cl}
\frac{1}{6 x^{1}} & \text { for } i=1 \\
0 & \text { otherwise }
\end{array}\right.
\end{aligned}
$$

where $\partial_{i}=\frac{\partial}{\partial x^{2}}$. Then it can be easily shown that $\left(M^{n}, g\right)$ is a $(W Q C S)_{n}$, which is neither quasi-conformally symmetric nor quasi-conformally recurrent. Hence we can state the following:

Theorem 5.3. Let $\left(M^{n}, g\right)(n \geq 4)$ be a Riemannian manifold equipped with the metric given in (5.4). Then $\left(M^{n}, g\right)(n \geq 4)$ is a weakly quasi-conformally symmetric manifold with vanishing scalar curvature which is neither quasiconformally symmetric nor quasi-conformally recurrent.

Let $\left(M_{1}^{4}, g_{1}\right)$ be a Riemannian manifold in Example 1 and $\left(\mathbf{R}^{n-4}, g_{0}\right)$ be an ( $n-4$ )-dimensional Euclidean space with standard metric $g_{0}$. Then $\left(M^{n}, g\right)$ in Example 3 is a product manifold of $\left(M_{1}^{4}, g_{1}\right)$ and $\left(\mathbf{R}^{n-4}, g_{0}\right)$. Thus we can state the following:

Theorem 5.4. Let $\left(M^{n}, g\right)(n \geq 5)$ be a Riemannian manifold endowed with the metric given in (5.4). Then $\left(M^{n}, g\right)(n \geq 4)$ is a decomposable weakly quasi-conformally symmetric manifold $\left(M_{1}^{4}, g_{1}\right) \times\left(\mathbf{R}^{n-4}, g_{0}\right)$ with vanishing scalar curvature.

## Acknowledgement

The authors wish to express their sincere thanks and gratitude to the referee for his valuable comments and suggestions in the improvement of the paper.

## References

[1] Binh, T. Q., On weakly symmetric Riemannian spaces, Publi. Math. Debrecen., 42 pp. 103-107 (1993).
[2] Chaki, M. C., On generalized pseudo-symmetric manifolds, Publi. Math. Debrecen., 45 pp. 305-312 (1994).
[3] De, U. C. and Bandyopadhyay, S., On weakly symmetric Riemannian spaces, Publi. Math. Debrecen., 54/3-4 pp. 377-381 (1999).
[4] De, U. C. and Bandyopadhyay, S., On weakly conformally symmetric spaces, Publi. Math. Debrecen., 57/1-2 pp. 71-78 (2000).
[5] Ferus, D., A remark on Codazzi tensors on constant curvature space, Lecture Note in Math., 838, Global Differential Geometry and Global Analysis, SpringerVerlag, New York (1981).
[6] Schouten, J. A., Ricci-Calculus, Springer-Verlag, Berlin (1954).
[7] Shaikh, A. A. and Baishya, K. K., On weakly quasi-conformally symmetric manifolds, Soochow J. of Math. 31(4) pp. 581-595 (2005).
[8] Tamássy, L. and Binh, T. Q., On weakly symmetric and weakly projective symmetric Rimannian manifolds, Coll. Math. Soc., J. Bolyai 50 pp. 663-670 (1989).
[9] Yano, K. and Sawaki, S., Riemannian manifolds admitting a conformal transformation group, J. Diff. Geom. 2 pp. 161-184 (1968).

[^0]
[^0]:    A. A. Shaikh and S. K. Jana

    Department of Mathematics, University of Burdwan Golapbag, Burdwan-713 104, West Bengal, India
    E-mail: aask2003@yahoo.co.in, aask@epatra.com

