# Chaotic semigroups generated by certain differential operators of order 1

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**Abstract.** We consider the initial value problem of a partial differential equation  $\frac{\partial u}{\partial t} = c(x)\frac{\partial u}{\partial x} + g(x,u)$  in some function spaces X on the interval I of the real line. By using the representation formula of the solution to the equation, we define a  $C_0$ -semigroup  $\{T_t\}_{t\geq 0}$  of bounded linear operators on X. When  $c(x) = \gamma x \ (\gamma \in \mathbb{R}), \ g(x,u) = h(x)u \ (h \in C(I,\mathbb{C}))$  and I is [0,1] or  $[1,\infty)$ , we give sufficient conditions for the semigroup to be chaotic by using the spectral property of its infinitesimal generator. When c(x) = 1 and g(x,u) = h(x)u, we also give sufficient conditions for the semigroup to be chaotic by using the property of an admissible weight function.

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#### §1. Introduction

The equation

(1.1) 
$$\frac{\partial u}{\partial t} = c(x)\frac{\partial u}{\partial x} + g(x, u) \qquad (x, t \ge 0)$$

has been used to model the dynamics of a population of cells undergoing simultaneous proliferation and maturation, where x is the maturation variable ([4], [5]). The solution of (1.1) has some connection with Wiener process. In fact, A. Lasota and M. C. Mackey [3] showed how to construct an exact, continuous time, semidynamical system that corresponds to the partial differential equation above with c(x) = -x ( $x \in [0,1]$ ) and  $g(x,u) = \frac{1}{2}u$  by using a one-dimensional Wiener process.

In this paper, we consider some special cases of (1.1) which generates chaotic semigroups and generalize the result of A. Lasota and M. C. Mackey [3].

In §2, we consider the space  $X_1 = \{f \in C([0,1], \mathbb{C}) \mid f(0) = 0\}$  and the following initial value problem of the partial differential equation:

(1.2) 
$$\begin{cases} \frac{\partial u}{\partial t} = \gamma x \frac{\partial u}{\partial x} + h(x)u, \\ u(0,x) = f(x), \end{cases}$$

where  $\gamma \in \mathbb{C}$ ,  $h \in C([0,1],\mathbb{C})$  and  $f \in X_1$ .

If u(t,x) is the classical solution of (1.2) for  $f \in C^1([0,1],\mathbb{C}) \cap X_1$ , then it must be of the form  $u(t,x) = f(e^{\gamma t}x) \exp(\int_0^t h(e^{\gamma(t-s)}x) ds)$ . In order to satisfy  $e^{\gamma t}x \in [0,1]$  for  $x \in [0,1]$  and  $t \geq 0$ ,  $\gamma$  must be a non-positive number. In this case, by using this representation formula  $f(e^{\gamma t}x) \exp(\int_0^t h(e^{\gamma(t-s)}x) ds)$  of the solution of (1.2), we can define the bounded linear operators  $\{T_t\}_{t\geq 0}$  on  $X_1$  by  $T_t f(x) = f(e^{\gamma t}x) \exp(\int_0^t h(e^{\gamma(t-s)}x) ds)$  for  $f \in X_1$ . Then  $\{T_t\}_{t\geq 0}$  is a strongly continuous semigroup on  $X_1$  (Theorem 1). In this paper we call  $\{T_t\}_{t\geq 0}$  the solution semigroup on  $X_1$  to the partial differential equation (1.2).

In [1], W. Desch, W. Schappacher and G. F. Webb gave a sufficient condition (Theorem A) for  $\{T_t\}_{t\geq 0}$  to be chaotic, by using the eigenvectors of the infinitesimal generator A of the strongly continuous semigroup  $\{T_t\}_{t\geq 0}$ . By applying their result to the solution semigroup, we give a sufficient condition for the solution semigroup to be chaotic on  $X_1$  (Theorem 1). In §3, we also give a sufficient condition for the solution semigroup to be chaotic on  $L^2([0,1],\mathbb{C})$  (Theorem 2).

In §4, we deal with the partial differential equation

(1.3') 
$$\frac{\partial u}{\partial t} = \gamma \frac{\partial u}{\partial x} + h(x)u \qquad (x, t \ge 0)$$

with the initial condition u(0,x) = f(x) with some  $f \in C_0(I,\mathbb{C})$ , where  $I = [0,\infty)$  and  $C_0(I,\mathbb{C})$  is the space of all complex-valued continuous functions on I satisfying  $\lim_{x\to\infty} f(x) = 0$ . If u(t,x) is the classical solution of (1.3') for  $f \in C_0(I,\mathbb{C})$ , then it must be of the form  $u(t,x) = e^{\int_x^{x+t} h(s)ds} f(x+\gamma t)$ . In order to satisfy  $x+t \in [0,\infty)$  for  $x \in [0,\infty)$  and  $t \geq 0$ ,  $\gamma$  must be a nonnegative number. Since the case  $\gamma = 0$  is a special case, we shall consider the case  $\gamma > 0$ . So by replacing  $\gamma t$  by t, we shall consider the following partial differential equation instead of (1.3'):

(1.3) 
$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} + h(x)u. \qquad (x, t \ge 0)$$

Since the method of the proof in §2 is not applicable in this case, we use the result in [7] and show that the solution semigroup  $\{T_t\}_{t\geq 0}$  to the partial differential equation (1.3) is a chaotic, strongly continuous semigrroup on

 $C_0(I,\mathbb{C})$  (Theorem 4), if h is a bounded continuous function on I satisfying  $\int_0^\infty h(s)ds = \infty$ .

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### §2. Chaotic semigroups on $C(I, \mathbb{C})$

Recall that a family  $\{T_t\}_{t\geq 0}$  of bounded linear operators on a Banach space X is called a strongly continuous semigroup if it satisfies the following conditions: (1)  $T_{t+s} = T_t T_s$  for all  $t, s \in \mathbb{R}_+$ , (2)  $T_0 = Id$ , and (3) the mapping :  $t \mapsto T_t x$  is continuous from  $\mathbb{R}_+$  to X for every  $x \in X$ . A strongly continuous semigroup  $\{T_t\}_{t\geq 0}$  is called hypercyclic if there exists  $x \in X$  such that the set  $\{T_t x \mid t \geq 0\}$  is dense in X. The semigroup  $\{T_t\}_{t\geq 0}$  is called chaotic if  $\{T_t\}_{t\geq 0}$  is hypercyclic and the set of periodic points  $X_{\text{per}} = \{x \in X \mid \exists t > 0 \text{ s.t. } T_t x = x\}$  is dense in X.

As to a sufficient condition for a semigroup to be chaotic, the following theorem is known.

**Theorem A** ([1]). Let X be a separable Banach space and let A be the infinitesimal generator of a strongly continuous semigroup  $\{T_t\}_{t\geq 0}$  on X. Let U be an open subset of the point spectrum of A, which intersects the imaginary axis, and for each  $\lambda \in U$  let  $x_{\lambda}$  be a nonzero eigenvector, i.e.  $Ax_{\lambda} = \lambda x_{\lambda}$ . For each  $\phi \in X^*$  we define a function  $F_{\phi}$ :  $U \to \mathbb{C}$  by  $F_{\phi}(\lambda) = \langle \phi, x_{\lambda} \rangle$ . Assume that for each  $\phi \in X^*$  the function  $F_{\phi}$  is analytic and that  $F_{\phi}$  does not vanish identically on U unless  $\phi = 0$ . Then  $\{T_t\}_{t\geq 0}$  is chaotic.

We shall apply this theorem to the semigroup related to the following partial differential equation. We consider the space  $X_1 = \{f \in C([0,1],\mathbb{C}) \mid f(0) = 0\}$  and the following initial value problem of a partial differential equation:

(2.1) 
$$\begin{cases} \frac{\partial u}{\partial t} = \gamma x \frac{\partial u}{\partial x} + h(x)u \\ u(0,x) = f(x) \end{cases}$$

where  $\gamma < 0$ ,  $h \in C([0,1], \mathbb{C})$  and  $f \in X_1$ . By using the representation formula  $\exp\left\{\int_0^t h(e^{\gamma(t-s)}x) \, ds\right\} f(e^{\gamma t}x)$  of the classical solution of (2.1), we define the

bounded linear operator  $\{T_t\}_{t>0}$  on  $X_1$  as follows:

$$T_t f(x) = \exp\left\{ \int_0^t h(e^{\gamma(t-s)}x) \, ds \right\} f(e^{\gamma t}x)$$
 for  $f \in X_1$ .

Note that if  $\gamma > 0$  then  $e^{\gamma t}x \notin [0,1]$  holds for  $x \in (e^{-\gamma t},1]$ . Since we are interested in the case  $\gamma \neq 0$ , we suppose  $\gamma < 0$ . Since the equations  $T_{t_1+t_2}f(x) = \exp\left\{\int_0^{t_1+t_2} h(e^{\gamma(t_1+t_2-s)}x)\,ds\right\} f(e^{\gamma(t_1+t_2)}x) = T_{t_1}\cdot T_{t_2}f(x)$  and  $T_0f(x) = f(x)$  hold for any  $f \in X_1$ ,  $\{T_t\}_{t\geq 0}$  is a semigroup. Moreover the semigroup  $\{T_t\}_{t\geq 0}$  becomes a strongly continuous semigroup on  $X_1$ . The proof of continuity is shown in the following theorem. Recall that the infinitesimal generator  $A\colon D(A)\subseteq X_1\to X_1$  of the strongly continuous semigroup  $\{T_t\}_{t\geq 0}$  on  $X_1$  is given by

$$Af = \lim_{t \downarrow 0} \frac{T_t f - f}{t}$$

for every f in its domain

$$D(A) = \left\{ f \in X_1 \middle| \lim_{t \downarrow 0} \frac{T_t f - f}{t} \text{ exists. } \right\}.$$

In this paper we call  $\{T_t\}_{t\geq 0}$  the solution semigroup to the partial differential equation. By applying Theorem A to the solution semigroup, we have a sufficient condition for the solution semigroup to be chaotic.

**Theorem 1.** Let  $X_1$  be the space  $\{f \in C([0,1], \mathbb{C}) \mid f(0) = 0\}$  with sup norm. We consider the following initial value problem of a partial differential equation:

(2.2) 
$$\begin{cases} \frac{\partial u}{\partial t} = \gamma x \frac{\partial u}{\partial x} + h(x)u \\ u(0, x) = f(x) \end{cases}$$

where  $\gamma < 0$ ,  $h \in C([0,1],\mathbb{C})$  and  $f \in X_1$ . Then the solution semigroup  $\{T_t\}_{t\geq 0}$   $(T_tf(x) = \exp\left\{\int_0^t h(e^{\gamma(t-s)}x)\,ds\right\}f(e^{\gamma t}x))$  to the partial differential equation is a strongly continuous semigroup on  $X_1$ . Moreover if  $\min\left\{\Re(h(x))\mid x\in[0,1]\right\}$  is positive, then  $\{T_t\}_{t\geq 0}$  is chaotic.

*Proof.* Put  $a = \sup_{x \in A} |h(x)|$ . For  $f \in X_1$ , we have

$$||T_{t}f - f|| = \sup_{\substack{0 \ x \ 1}} |e^{\int_{0}^{t} h(e^{\gamma(t-s)}x)ds} f(e^{\gamma t}x) - f(x)|$$

$$\cdot |e^{at} - 1| \sup_{\substack{0 \ x \ 1}} |f(e^{\gamma t}x)| + \sup_{\substack{0 \ x \ 1}} |f(e^{\gamma t}x) - f(x)|$$

$$= |e^{at} - 1| ||f|| + \sup_{\substack{0 \ x \ 1}} |f(e^{\gamma t}x) - f(x)|,$$

which implies the strong continuity of  $\{T_t\}_{t\geq 0}$ .

We shall show that  $\{T_t\}_{t\geq 0}$  is chaotic if  $\min\{\Re(h(x))\mid x\in[0,1]\}>0$ . To show that all assumptions of Theorem A hold, we verify the following:

- (i)  $X_1$  is a separable Banach space.
- (ii) The existence of an open set U of the point spectrum of the infinitesimal generator A which intersects the imaginary axis.
- (iii) For  $\lambda \in U$ , put  $f_{\lambda}(x) = \exp(-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda h(s)}{s} ds)$ . For each  $\phi \in X_{1}^{*}$  we define a function  $F_{\phi}: U \to \mathbb{C}$  by  $F_{\phi}(\lambda) = \langle \phi, f_{\lambda} \rangle$ . Then for each  $\phi \in X_{1}^{*}$  the function  $F_{\phi}$  is analytic on U.
- (iv) If  $F_{\phi} = 0$  on U, then  $\phi = 0$ .
- (i) It is clear that  $X_1$  is a separable Banach space by Weierstrass approximation theorem.
- (ii) Let  $A: D(A) \subseteq X_1 \to X_1$  be the infinitesimal generator of the strongly continuous semigroup  $\{T_t\}_{t>0}$ . Put

$$D_1 = \left\{ f \in X_1 \cap C^1((0,1], \mathbb{C}) \, \middle| \, \lim_{x \to 0} x f'(x) = 0 \right\}.$$

Then we shall show that  $D_1=D(A)$  holds. For  $f\in D(A)$ , Af belongs to  $X_1$  and f is differentiable on (0,1). By a standard argument, we can see that  $Af(x)=h(x)f(x)+\gamma xf'(x)$  holds for  $x\in (0,1]$ . So  $\lim_{x\to 0}xf'(x)=0$ , which implies  $D(A)\subset D_1$ . Conversely, suppose  $f\in D_1$ . Then  $hf+\gamma xf'\in X_1$ . So for any  $\varepsilon>0$ , there exists  $1>\delta_1>0$  such that  $|h(x)f(x)+\gamma xf'(x)|<\varepsilon$  for any  $x\in [0,\delta_1], |xf'(x)-x'f'(x')|<\varepsilon$  and  $|f(x)-f(x')|<\varepsilon$  for any  $x,x'\in [0,1]$  with  $|x-x'|<\delta_1$ . Since h is continuous, there exists  $\delta_2>0$  such that  $|h(e^{\gamma s}x)-h(x)|<\varepsilon$  for every  $0\cdot s<\delta_2$  and  $x\in [0,1]$ . So we have

$$\left| \frac{e^{\int_0^t h(e^{\gamma(t-s)}x)ds} - 1}{t} - h(x) \right| < \left| \frac{\int_0^t h(e^{\gamma(t-s)}x)ds}{t} - h(x) \right| + \frac{t}{2} ||h||_{\infty}^2 e^{t||h||_{\infty}}$$

$$< \varepsilon + 2t||h||_{\infty}^2 < 2\varepsilon$$

for  $0 \cdot t < \delta_3$ , where  $\delta_3 = \min \left\{ \delta_2, \frac{1}{||h||_{\infty}}, \frac{\varepsilon}{2||h||_{\infty}^2} \right\}$ . For  $0 < t < \min \left\{ \frac{1}{\gamma} \log(1 - \delta_1), \delta_3 \right\}$ , by using the relations  $0 \cdot x - e^{\gamma t}x < \delta_1$  and  $f(e^{\gamma t}x) - f(x) = 0$ 

 $\int_0^t \gamma e^{\gamma s} x f'(e^{\gamma s} x) ds$ , we have

$$\left| \frac{T_t f(x) - f(x)}{t} - (\gamma x f'(x) + h(x) f(x)) \right|$$

$$\cdot \left| \frac{e^{\int_0^t h(e^{\gamma(t-s)}x)ds} - 1}{t} f(e^{\gamma t}x) - h(x) f(x) \right|$$

$$+ \frac{1}{t} \int_0^t |\gamma e^{\gamma s} x f'(e^{\gamma s}x) - \gamma x f'(x)| ds$$

$$\cdot (2||f||_{\infty} + ||h||_{\infty} + \gamma) \varepsilon,$$

which implies  $D_1 \subset D(A)$ . Hence  $D(A) = D_1$ .

Put  $\alpha = \min \{ \Re(h(x)) \mid x \in [0,1] \}$  and

$$U = \{ \lambda \in \mathbb{C} \mid \Re(\lambda) < \alpha \}.$$

Since we assumed  $\alpha > 0$ , the set U intersects the imaginary axis. For  $\lambda \in U$ ,  $f_{\lambda}(x) = \exp(-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda - h(s)}{s} ds)$  is continuous on [0,1]. It is easy to see that  $f_{\lambda}(x)$  belongs to  $D_{1} = D(A)$  and satisfies  $Af_{\lambda} = \lambda f_{\lambda}$ . So U is an open subset of the point spectrum of A.

(iii) Let  $\lambda \in U$ . Put  $v_{p,\lambda}(x) = \frac{f_{\lambda+p}(x) - f_{\lambda}(x)}{p}$  for  $p \neq 0$  with |p| small enough and set  $g_{\lambda}(x) = \frac{\log x}{\gamma} \exp(-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda - h(s)}{s} ds)$  for  $x \in (0,1]$  and  $g_{\lambda}(0) = 0$ . Since  $\lim_{x \to 0} g_{\lambda}(x) = 0$ , we have  $g_{\lambda} \in X_{1}$ . By using the relation  $f_{\lambda+p}(x) - f_{\lambda}(x) = 0$  $p \int_0^1 \frac{\log x}{\gamma} \exp(-\frac{1}{\gamma} \int_x^1 \frac{\lambda - h(s) + tp}{s} ds) dt$ , we have for  $x \in (0, 1]$ ,

$$v_{p,\lambda}(x) - g_{\lambda}(x)$$

$$= \int_0^1 \frac{\log x}{\gamma} \left\{ \exp(-\frac{1}{\gamma} \int_x^1 \frac{\lambda - h(s) + tp}{s} ds) - \exp(-\frac{1}{\gamma} \int_x^1 \frac{\lambda - h(s)}{s} ds) \right\} dt$$

$$= g_{\lambda}(x) \int_0^1 (x^{\frac{tp}{\gamma}} - 1) dt.$$

Put  $c = \frac{\alpha - \Re(\lambda)}{2} > 0$ . For any  $\varepsilon > 0$ , there exists  $\delta_1 > 0$  such that  $\left|\frac{\log x}{\gamma} \exp(-\frac{1}{\gamma} \int_x^1 \frac{\lambda - h(s) + c}{s} ds)\right| < \varepsilon$  for  $0 \cdot x < \delta_1$ , and there exists  $\delta_2 > 0$  such that  $|x^{\frac{tp}{\gamma}} - 1| < \frac{\varepsilon}{\|g_{\lambda}\|}$  for  $\delta_1 \cdot x \cdot 1$  and  $0 < |p| < \delta_2$ . For  $x \in [0, \delta_1]$  and 0 < |p| < c, we have

$$|v_{p,\lambda}(x) - g_{\lambda}(x)|$$

$$\cdot \int_{0}^{1} \left\{ \left| \frac{\log x}{\gamma} \exp(-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda - h(s) + tp}{s} ds) \right| + \left| \frac{\log x}{\gamma} \exp(-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda - h(s)}{s} ds) \right| \right\} dt$$

$$< 2\varepsilon.$$

For  $x \in [\delta_1, 1]$  and for  $0 < |p| < \delta_2$ , we have

$$|v_{p,\lambda}(x)-g_{\lambda}(x)|\cdot |g_{\lambda}(x)|\int_0^1|x^{rac{tp}{\gamma}}-1|dt$$

Hence we have  $|v_{p,\lambda}(x)-g_{\lambda}(x)|<2\varepsilon$  for  $0<|p|<\min{\{c,\delta_2\}}$  and for  $x\in[0,1]$ . So  $|v_{p,\lambda}(x)-g_{\lambda}(x)|$  goes to 0 uniformly on [0,1] as  $p\to 0$  and

$$\langle \phi, g_{\lambda} \rangle = \lim_{p \to 0} \langle \phi, \frac{f_{\lambda+p} - f_{\lambda}}{p} \rangle = \frac{dF_{\phi}}{d\lambda}.$$

Therefore  $F_{\phi}(\lambda)$  is analytic with respect to  $\lambda \in U$ .

(iv) We shall show that if  $F_{\phi}(\lambda) = 0$  for all  $\lambda \in U$  then  $\phi = 0$ . We recall the following:  $U = \{\lambda \in \mathbb{C} \mid \Re(\lambda) < \alpha\}$  and  $f_{\lambda}(x) = \exp(-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda - h(s)}{s} ds)$  for  $\lambda \in U$ . Take a real constant  $\lambda_0$  satisfying  $\lambda_0 < \alpha$ . For  $\Re(\lambda) < \lambda_0$ ,

$$f_{\lambda}(x) = \exp\left\{-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda - \lambda_{0}}{s} ds - \frac{1}{\gamma} \int_{x}^{1} \frac{\lambda_{0} - h(s)}{s} ds\right\}$$

$$= \exp\left\{-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda - \lambda_{0}}{s} ds\right\} \exp\left\{-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda_{0} - h(s)}{s} ds\right\}$$

holds. Put the second factor of (2.3) as follows:

$$q(x) = \exp\left\{-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda_0 - h(s)}{s} ds\right\}.$$

It is easy to see that q is continuous on [0,1] and positive except for x=0. The first factor of (2.3) becomes

$$\exp\left\{-\frac{\lambda-\lambda_0}{\gamma}\cdot\log(\frac{1}{x})\right\} = x^{\frac{\lambda-\lambda_0}{\gamma}}.$$

For  $n \in \{1, 2, 3, \dots\}$ , put  $\lambda_n = \gamma n + \lambda_0$ . The assumption  $\gamma < 0$  implies  $\lambda_n \in U$  for  $n = 1, 2, 3, \dots$ .

Then we have  $f_{\lambda_n}(x) = x^n q(x)$  for  $n = 1, 2, 3, \cdots$ .

¿From the assumption,  $0 = F_{\phi}(\lambda_n) = \langle \phi, f_{\lambda_n} \rangle = \langle \phi, x^n q \rangle$  holds for  $n = 1, 2, 3, \cdots$ . By the Stone-Weierstrass theorem, the linear span of  $\{x^n \mid n = 1, 2, 3, \cdots\}$  is dense in  $X_1$ . Since q(x) > 0 for any  $x \in (0, 1]$ , the linear span of  $\{x^n \mid n = 1, 2, 3, \cdots\}$  is also dense in  $X_1$ . So we have  $\phi = 0$ .

By (i) to (iv), all assumptions of Theorem A hold. So  $\{T_t\}_{t\geq 0}$  is chaotic by Theorem A.

The space  $Y_1 = \{ f \in C([1,\infty),\mathbb{C}) \mid \lim_{x\to\infty} f(x) = 0 \}$  has relation with the space  $X_1 = \{ f \in C([0,1],\mathbb{C}) \mid f(0) = 0 \}$  by the mapping  $\phi: X_1 \to Y_1$  defined

by  $(\phi f)(x) = f(\frac{1}{x})$ . So we shall consider the corresponding equation in  $Y_1$  to the equation (2.2) considered in  $X_1$  as follows:

(2.4) 
$$\frac{\partial u}{\partial t} = -\gamma y \frac{\partial u}{\partial y} + h(y)u.$$

Let  $\{T_t\}_{t\geq 0}$  be the solution semigroup on  $X_1$  with respect to (2.2) and  $\{S_t\}_{t\geq 0}$  be the solution semigroup on  $Y_1$  generated from the classical solution of (2.4). Then the following diagram commutes.

$$X_1 \xrightarrow{T_t} X_1$$

$$\downarrow \phi \qquad \qquad \downarrow \phi$$

$$Y_1 \xrightarrow{S_t} Y_1$$

Hence we have the following.

#### Corollary.

Let  $Y_1$  be the space  $\{f \in C([1,\infty),\mathbb{C}) \mid \lim_{x\to\infty} f(x) = 0\}$  with sup norm. We consider the following initial value problem of a partial differential equation:

$$\begin{cases} \frac{\partial u}{\partial t} = \gamma x \frac{\partial u}{\partial x} + h(x)u \\ u(0, x) = f(x) \end{cases}$$

where  $\gamma > 0$ ,  $f \in Y_1$ ,  $h \in C([1,\infty),\mathbb{C})$  and  $\lim_{x\to\infty} h(x)$  exists. Then the solution semigroup  $\{S_t\}_{t\geq 0}$   $(S_t f(x) = e^{\int_0^t h(e^{\gamma(t-s)}x)ds} f(e^{\gamma t}x))$  to the partial differential equation is a strongly continuous semigroup on  $Y_1$ .

Moreover if  $\inf \{\Re h(x) \mid x \in [1,\infty)\} > 0$ , then  $\{S_t\}_{t>0}$  is chaotic.

## §3. Chaotic semigroups on $L^2(I)$

Let  $X_2$  be the space  $L^2([0,1],\mathbb{C})$ . We shall consider the partial differential equation in  $L^2([0,1],\mathbb{C})$ :

(3.1) 
$$\begin{cases} \frac{\partial u}{\partial t} = \gamma x \frac{\partial u}{\partial x} + h(x)u \\ u(0,x) = f(x) \end{cases}$$

where  $\gamma < 0$ ,  $h \in C([0,1], \mathbb{C})$  and  $f \in X_2$ . By using the representation formula  $\exp\left\{\int_0^t h(e^{\gamma(t-s)}x) \, ds\right\} f(e^{\gamma t}x)$  of the classical solution of (3.1), we can define a family  $\{T_t\}_{t\geq 0}$  of bounded linear operators on  $X_2$  by  $T_t f(x) = \exp\left\{\int_0^t h(e^{\gamma(t-s)}x) \, ds\right\} f(e^{\gamma t}x)$  for  $f \in X_2$ . Then  $\{T_t\}_{t\geq 0}$  is a semigroup.

Moreover the semigroup  $\{T_t\}_{t\geq 0}$  is a strongly continuous semigroup on  $X_2$ . The proof of continuity is shown in the following theorem. By applying Theorem A to the solution semigroup  $\{T_t\}_{t\geq 0}$ , we shall give a sufficient condition for the solution semigroup to be chaotic.

#### Theorem 2.

Let  $X_2$  be the space  $L^2([0,1],\mathbb{C})$ . We consider the following initial value problem of a partial differential equation:

$$\begin{cases} \frac{\partial u}{\partial t} = \gamma x \frac{\partial u}{\partial x} + h(x)u \\ u(0, x) = f(x) \end{cases}$$

where  $\gamma < 0$ ,  $h \in C([0,1],\mathbb{C})$  and  $f \in X_2$ . Then the solution semigroup  $\{T_t\}_{t\geq 0}$   $\{T_tf(x) = \exp\left\{\int_0^t h(e^{\gamma(t-s)}x)\,ds\right\}f(e^{\gamma t}x)\}$  to the partial differential equation is a strongly continuous semigroup on  $X_2$ .

Moreover if  $\min \{\Re(h(x)) \mid x \in [0,1]\} > \frac{\gamma}{2}$ , then  $\{T_t\}_{t>0}$  is chaotic.

*Proof.* To check the strong continuity of  $\{T_t\}_{t\geq 0}$ , we shall show the continuity of  $\{T_t\}_{t\geq 0}$  at t=0.

Let  $\bar{f}$  be an element of  $X_2$ . Then for any  $\varepsilon > 0$  there exists a continuous function  $\xi$  on [0,1] such that

$$||f-\xi||_{L^2}<rac{arepsilon}{6}.$$

Since  $\xi$  is continuous, there exists  $\delta_1 > 0$  such that

$$||T_t\xi-\xi||_{\infty}<rac{arepsilon}{2}$$

holds with  $0 < t < \delta_1,$  where  $||\cdot||_{\infty}$  is the sup norm . For  $k \in L^2,$  we have

$$||T_t k||_{L^2} \cdot e^{\alpha_0 t} ||k||_{L^2},$$

where  $\alpha_0 = \max_{x \in \mathcal{X}} \{\Re(h(x))\} - \frac{\gamma}{2}$ . Put  $\delta = \min(\delta_1, \frac{\log 2}{\alpha_0})$ . Then we have

$$||T_{t}f - f||_{L^{2}} \cdot ||T_{t}f - T_{t}\xi||_{L^{2}} + ||T_{t}\xi - \xi||_{L^{2}} + ||\xi - f||_{L^{2}}$$

$$\cdot e^{\alpha_{0}t}||f - \xi||_{L^{2}} + ||T_{t}\xi - \xi||_{\infty} + ||f - \xi||_{L^{2}}$$

$$< ||f - \xi||_{L^{2}}(1 + e^{\alpha_{0}t}) + \frac{\varepsilon}{2}$$

$$< \frac{\varepsilon}{6}(1 + 2) + \frac{\varepsilon}{2} = \varepsilon$$

for  $t \in (0, \delta)$ . So  $\{T_t\}_{t>0}$  is a strongly continuous semigroup.

Hereafter we shall check the following (i) – (iv) as in the proof of Theorem 1 to show that all assumptions of Theorem A hold if min  $\{\Re(h(x)) \mid x \in [0,1]\} > \frac{\gamma}{2}$  holds.

- (i)  $X_1$  is a separable Banach space.
- (ii) The existence of an open set U of the point spectrum of the infinitesimal generator A which intersects the imaginary axis.
- (iii) For  $\lambda \in U$ , put  $f_{\lambda}(x) = \exp(-\frac{1}{\gamma} \int_{x}^{1} \frac{\lambda h(s)}{s} ds)$ . For each  $\phi \in X_{1}^{*}$  we define a function  $F_{\phi}: U \to \mathbb{C}$  by  $F_{\phi}(\lambda) = \langle \phi, f_{\lambda} \rangle$ . Then for each  $\phi \in X_{1}^{*}$  the function  $F_{\phi}$  is analytic on U.
- (iv) If  $F_{\phi} = 0$  on U, then  $\phi = 0$ .
- (i) It is obvious.
- (ii) Let  $A: D(A) \subseteq X_1 \to X_1$  be the infinitesimal generator of the strongly continuous semigroup  $\{T_t\}_{t>0}$ . Put

$$D_2 = \{ f \in X_2 \mid xf \text{ is absolutely continuous and } (xf)' \in X_2 \}.$$

We recall that  $f \in D_2$  holds if and only if  $f \in X_2$  and xf belongs to the Sobolev space  $H^1(0,1)$ . For  $f \in D(A)$ , there exists  $g \in X_2$  such that  $\lim_{t\downarrow 0} \frac{T_t f - f}{t} = g$ . Since f is integrable on [0,1], we see that for  $l, m \in [0,1]$ 

$$\int_{l}^{m} \frac{T_{t}f(x) - f(x)}{t} dx = \int_{l}^{m} \frac{e^{\int_{0}^{t} h(e^{\gamma(t-s)}x)ds} f(e^{\gamma t}x) - f(x)}{t} dx$$

$$= \int_{le^{\gamma t}}^{me^{\gamma t}} \frac{e^{\int_{0}^{t} h(e^{-\gamma s}x)ds - \gamma t}}{t} f(x) dx - \int_{l}^{m} \frac{f(x)}{t} dx$$

$$= \frac{1}{l - le^{\gamma t}} \int_{le^{\gamma t}}^{l} \frac{l(1 - e^{\gamma t})}{t} e^{\int_{0}^{t} h(e^{-\gamma s}x)ds - \gamma t} f(x) dx$$

$$+ \int_{l}^{m} \frac{e^{\int_{0}^{t} h(e^{-\gamma s}x)ds - \gamma t} - 1}{t} f(x) dx$$

$$- \frac{1}{m - me^{\gamma t}} \int_{me^{\gamma t}}^{m} \frac{m(1 - e^{\gamma t})}{t} e^{\int_{0}^{t} h(e^{-\gamma s}x)ds - \gamma t} f(x) dx$$

converges to

$$-l\gamma f(l) + \int_{l}^{m} (h(x) - \gamma)f(x)dx + m\gamma f(m)$$

as  $t \downarrow 0$  for almost all l, m ([6], Theorem 9-8 VI]). However, the left hand side converges to  $\int_{l}^{m} g(x)dx$ . By redefining f on a null set we obtain

$$mf(m) = \int_{l}^{m} \frac{1}{\gamma} \{g(x) - (h(x) - \gamma)f(x)\} dx + lf(l),$$

which implies that xf(x) is an absolutely continuous function with derivative (almost everywhere) equal to  $\frac{1}{\gamma}\{g(x)-(h(x)-\gamma)f(x)\}$  and hence (xf)' belongs to  $X_2$ . So  $D(A) \subset D_2$ .

Conversely for  $f \in D_2$ , we have

$$\frac{T_{t}f(x) - f(x)}{t} - (\gamma x f'(x) + h(x)f(x))$$

$$= \left(\frac{e^{\int_{0}^{t} h(e^{\gamma(t-s)}x)ds} - 1}{t} - h(x)\right) f(e^{\gamma t}x)$$

$$+ h(x)(f(e^{\gamma t}x) - f(x)) + \left\{\frac{f(e^{\gamma t}x) - f(x)}{t} - \gamma x f'(x)\right\}.$$

We will show that each term of (3.2) goes to 0 as  $t \to 0$ . It is obvious that the norm of the first term of (3.2) converges to 0 as  $t \to 0$  in a similar way to that in Theorem 1. For each  $\varepsilon > 0$  and each  $t(t_0 > t \ge 0)$  with some fixed  $t_0 > 0$ , there exists  $\delta_1 > 0$  such that

$$\int_0^{\delta_1} |f(e^{\gamma t}x) - f(x)|^2 dx < \varepsilon.$$

Since xf is absolutely continuous, f is absolutely continuous on  $[\delta_1, 1]$  and  $||h(x)(f(e^{\gamma t}x) - f(x))||$  converges to 0 as  $t \to 0$ .

Put  $\eta(x) = \gamma x f'(x)$ . Then  $f \in D_2$  implies  $\eta \in X_2$ . For any  $\varepsilon > 0$ , there exists  $\xi \in C([0,1],\mathbb{C})$  such that  $\|\xi - \eta\| < \varepsilon$  and there exists  $\delta > 0$  such that  $\|\xi(e^{\gamma s}x) - \xi(e^{\gamma t}x)\| < \varepsilon$  for any  $0 \cdot s \cdot t < \delta$  and any  $0 \cdot x \cdot 1$ . Moreover, for  $0 \cdot s < \delta$ ,

$$\|\eta(e^{\gamma s}x) - \xi(e^{\gamma s}x)\|^2 = \int_0^1 (\eta(e^{\gamma s}x) - \xi(e^{\gamma s}x))^2 dx$$
$$= \int_0^{e^{\gamma s}} (\eta(y) - \xi(y))^2 e^{-\gamma s} dy \cdot e^{-\gamma \delta} \|\eta - \xi\|^2.$$

So  $\|\eta(e^{\gamma s}x) - \eta(e^{\gamma t}x)\|^2 \cdot (2 + e^{-\frac{\gamma \delta}{2}})\varepsilon$  for  $0 \cdot s \cdot t < \delta$ , which implies that the map  $s \in [0, \infty) \mapsto \eta(e^{\gamma s}\cdot) \in L^2$  is continuous. Therefore the  $X_2$ -valued Riemann integral  $\int_0^t \eta(e^{\gamma s}x)ds$  exists. Since the equation

$$\frac{f(e^{\gamma t}x) - f(x)}{t} - \gamma x f'(x) = \frac{1}{t} \int_0^t \gamma e^{\gamma s} x f'(e^{\gamma s}x) ds - \eta(x)$$

holds, for  $0 < t < \delta$ , the norm of the third term of (3.2) can be rewritten as follows:

$$\|\frac{f(e^{\gamma t}x) - f(x)}{t} - \gamma x f'(x)\| = \|\frac{1}{t} \int_0^t \eta(e^{\gamma s}x) ds - \eta(x)\|$$

$$\cdot \frac{1}{t} \int_0^t \|\eta(e^{\gamma s}x) - \eta(x)\| ds < (2 + e^{-\frac{\gamma \delta}{2}})\varepsilon,$$

where  $\int_0^t \eta(e^{\gamma s}x)ds$  is the  $X_2$ -valued Riemann integral.

This implies that  $\|\frac{f(e^{\gamma t}x)-f(x)}{t}-\gamma xf'(x)\|$  goes to zero as  $t\to 0$ . So f belongs to D(A). Hence  $D(A)=D_2$ .

Put  $\alpha = \min \{ \Re(h(x)) \mid x \in [0,1] \}$  and

$$U = \left\{ \lambda \in \mathbb{C} \mid \Re(\lambda) < \alpha - \frac{\gamma}{2} \right\}.$$

Since we assume  $\alpha>\frac{\gamma}{2}$ , the set U intersects the imaginary axis. For  $\lambda\in U$ , it is easy to see that  $f_\lambda(x)=\exp(-\frac{1}{\gamma}\int_x^1\frac{\lambda-h(s)}{s}ds)$  belongs to  $D_2=D(A)$  and  $Af_\lambda=\lambda f_\lambda$ , i.e.  $f_\lambda$  is an eigenvector of A. So U is an open subset of the point spectrum of A.

(iii) For  $\phi \in X_2^* = X_2$ , we have

(3.3) 
$$F_{\phi}(\lambda) = \langle \phi, f_{\lambda} \rangle_{L^{2}} = \int_{0}^{1} \phi(x) f_{\lambda}(x) dx.$$

For  $\lambda \in U$ , we shall show that  $\frac{\partial f_{\lambda}(x)}{\partial \lambda}$  exists. For each  $x \in (0,1)$ ,  $f_{\lambda}(x)$  is differentiable with respect to  $\lambda$  on U and

$$\begin{split} |\frac{1}{\nu}\{f_{\lambda+\nu}(x)-f_{\lambda}(x)\}| &= |\frac{1}{\nu}\left\{e^{-\frac{1}{\gamma}\int_{x}^{1}\frac{\lambda+\nu-h(s)}{s}ds}-e^{-\frac{1}{\gamma}\int_{x}^{1}\frac{\lambda-h(s)}{s}ds}\right\}| \\ &= |e^{-\frac{1}{\gamma}\int_{x}^{1}\frac{\lambda-h(s)}{s}ds}\frac{1}{\nu}\left\{e^{-\frac{1}{\gamma}\int_{x}^{1}\frac{\nu}{s}ds}-1\right\}| \\ &\cdot x^{\frac{\Re(\lambda)-\alpha}{\gamma}}\cdot\frac{\log x}{\gamma}x^{\frac{\theta\nu}{\gamma}}, \end{split}$$

with some  $0<\theta<1$ . Since  $\frac{\Re(\lambda)-\alpha}{\gamma}>-\frac{1}{2}$ , we can choose a small number  $\nu_0>0$  satisfying  $\frac{\Re(\lambda)-\alpha}{\gamma}+\frac{\nu_0}{\gamma}>-\frac{1}{2}$ . Furthermore, we can take b>0 satisfying  $\frac{\Re(\lambda)-\alpha}{\gamma}+\frac{\nu_0}{\gamma}-b>-\frac{1}{2}$ . Since  $x^b\log x\in C((0,1],\mathbb{C})$  and  $\lim_{x\to 0}x^b\log x=0$ , there exists M>0 such that  $||x^b\log x||_\infty\cdot M$ . Put  $\beta=\frac{\Re(\lambda)-\alpha}{\gamma}+\frac{\nu_0}{\gamma}-b$ . Then  $|\frac{1}{\nu}\{f_{\lambda+\nu}(x)-f_{\lambda}(x)\}|\cdot\frac{M}{|\gamma|}x^{\beta}$  and the function  $\frac{M}{|\gamma|}x^{\beta}$  belongs to  $L^2([0,1],\mathbb{C})$ , since  $\beta>-\frac{1}{2}$ . By putting  $\psi(x)=|\phi(x)|\frac{Mx^{\beta}}{|\gamma|}$ , we have  $\psi\in L^1([0,1],\mathbb{C})$  and

$$\left|\phi(x)\frac{1}{\nu}\{f_{\lambda+\nu}(x)-f_{\lambda}(x)\}\right|$$
  $\cdot$   $\psi(x)$ 

for any  $\nu$  with  $0 < |\nu| \cdot \nu_0$  and  $x \in [0, 1]$ . So we can apply Lebesgue's dominated convergence theorem to the equation (3.3). Hence  $F_{\phi}$  is analytic. (iv) In a similar way to (iv) in the proof of Theorem 1, we can show that  $\phi = 0$  if  $F_{\phi}(\lambda) = 0$  for all  $\lambda \in U$ .

By (i) to (iv), if min  $\{\Re(h(x)) \mid x \in [0,1]\} > \frac{\gamma}{2}$  then all assumptions of Theorem A hold. So  $\{T_t\}_{t>0}$  is chaotic by Theorem A.

We have the following similar corollary to that of Theorem 1.

**Corollary.** Let  $Y_2$  be the space  $L^2([1,\infty),\mathbb{C})$ . We consider the following initial value problem of a partial differential equation:

$$\begin{cases} \frac{\partial u}{\partial t} = \gamma x \frac{\partial u}{\partial x} + h(x)u \\ u(0, x) = f(x) \end{cases}$$

where  $\gamma > 0$ ,  $f \in Y_2$ ,  $h \in C([1,\infty),\mathbb{C})$  and  $\lim_{x\to\infty} h(x)$  exists. Then the solution semigroup  $\{T_t\}_{t\geq 0}$   $\{T_tf(x) = \exp\left\{\int_0^t h(e^{\gamma(t-s)}x)\,ds\right\}f(e^{\gamma t}x)\}$  to the partial differential equation is a strongly continuous semigroup on  $Y_2$ .

Moreover if  $\inf \{\Re(h(x)) \mid x \in [1,\infty)\} > \frac{\gamma}{2}$ , then  $\{T_t\}_{t\geq 0}$  is chaotic.

# §4. Chaotic semigroups on $C_0(I,\mathbb{C})$ related to chaotic translation semigroups on admissible weighted function spaces

Let I be the interval  $[0, \infty)$  and  $\widetilde{X}$  be the space  $C_0(I, \mathbb{C})$  of all complexvalued continuous functions on I satisfying  $\lim_{x\to\infty} f(x) = 0$  with  $||f||_{\infty} = \sup_{x\in I} |f(x)|$ . We shall consider the following partial differential equation:

(4.1) 
$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} + h(x)u\\ u(0,x) = f(x), \end{cases}$$

where h is a bounded continuous function on I and  $f \in \widetilde{X}$ .

By using the representation formula  $e^{\int_x^{x+t} h(s)ds} f(x+t)$  of the classical solution of (4.1), we define the bounded linear operator  $\{\widetilde{T}_t\}_{t\geq 0}$  on  $\widetilde{X}$  as follows:

$$\widetilde{T}_t f(x) = e^{\int_x^{x+t} h(s)ds} f(x+t)$$
 for  $f \in \widetilde{X}$ .

According to the paper [1], we call  $\{\widetilde{T}_t\}_{t\geq 0}$  the solution semigroup on  $\widetilde{X}$  to the partial differential equation (4.1).

If  $\lambda$  is an eigenvalue of the infinitesimal generator A of the strongly continuous semigroup  $\left\{\widetilde{T}_t\right\}_{t\geq 0}$ , then the eigenfunction  $f_\lambda$  is of the form  $f_\lambda(x)=$  const.  $\times e^{\lambda x-\int_0^x h(s)ds}$ . It seems impossible that there exists an open subset of

the point spectrum of A, which intersects the imaginary axis. So we cannot apply the method of Theorem A to show that  $\{\widetilde{T}_t\}_{t\geq 0}$  is chaotic. Hence we introduce the space  $C_{0,\rho}(I,\mathbb{C})$  defined by an admissible weight function  $\rho$ .

By an admissible weight function on I we mean a measurable function  $\rho: I \to \mathbb{R}$  satisfying the following conditions:

- (i)  $\rho(x) > 0$  for all  $x \in I$ ;
- (ii) there exist constants  $M \ge 1$  and  $\omega \in \mathbb{R}$  such that  $\rho(x) \cdot Me^{\omega t}\rho(t+x)$  for all  $x \in I$  and t > 0.

For an admissible weight function  $\rho$  on  $I=[0,\infty)$ , we consider the following function space:

$$C_{0,\rho}(I,\mathbb{C}) = \left\{ f: I \to \mathbb{C} \mid f \text{ continuous, } \lim_{x \to \infty} \rho(x) f(x) = 0 \right\}$$

with  $||f||_{\rho} = \sup_{x \in I} |f(x)| \rho(x)$ .

Let X be the space  $C_{0,\rho}(I,\mathbb{C})$  defined by an admissible weight function  $\rho$ . For  $t \geq 0$ , we define  $T_t \in \mathfrak{L}(X)$  by

$$T_t f(x) = f(x+t)$$

for  $f \in X$ . We call  $\{T_t\}_{t>0}$  the translation semigroup on X.

Put  $\rho(x) = e^{-\int_0^x h(s)ds}$ . Since h is a bounded function, there exists a constant  $\omega > 0$  such that  $h(x) \cdot \omega$  for any  $x \in I$ . So

$$\int_{x}^{x+t} h(s)ds \cdot \omega t$$

holds. Rewriting the inequality we have

$$e^{-\int_0^x h(s)ds} \cdot e^{\omega t} \cdot e^{-\int_0^{x+t} h(s)ds}$$

So  $\rho$  is continuous by the continuity of h, and  $\rho$  is an admissible weight function since  $\rho(x) \cdot e^{\omega t} \rho(x+t)$  holds.

By the definition of  $\rho$ , the equality  $-\frac{\rho'(x)}{\rho(x)} = h(x)$  holds. So the partial differential equation (4.1) is rewritten as follows:

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} - \frac{\rho'(x)}{\rho(x)} u\\ u(0, x) = f(x) \end{cases}$$

with a continuous admissible weight function  $\rho$ . Hence we have

(4.2) 
$$u(t,x) = \widetilde{T}_t f(x) = \frac{\rho(x)}{\rho(x+t)} f(x+t) \in C_0(I,\mathbb{C}).$$

Recall that  $\widetilde{X}$  is the space  $C_0(I,\mathbb{C})$  of all complex-valued continuous functions on I satisfying  $\lim_{x\to\infty} f(x) = 0$  with  $||f||_{\infty} = \sup_{x\in I} |f(x)|$ . We shall define the following operator  $\varphi: X \to \widetilde{X}$  as

$$\varphi(f)(x) = \rho(x)f(x)$$

for  $f \in X$  and for  $x \in I$ .

It is easy to see that the following diagram commutes:  $\begin{array}{ccc} X & \xrightarrow{T_t} X \\ & & \downarrow \varphi \\ & \widetilde{X} & \xrightarrow{\widetilde{T}_t} & \widetilde{X} \end{array}$ 

Since  $\rho(x) > 0$  for all  $x \in I$ ,  $\varphi$  is an isometric isomorphism. So we have the following.

**Proposition 3.** Let X be the space  $C_{0,\rho}(I,\mathbb{C})$  with a continuous admissible weight function  $\rho$  and  $\{T_t\}_{t\geq 0}$  be the translation semigroup on X. Let  $\widetilde{X}$  be the space  $C_0(I,\mathbb{C})$  and  $\{\widetilde{T}_t\}_{t\geq 0}$  be the semigroup defined by (4.2). Then

- (1)  $\{T_t\}_{t\geq 0}$  is hypercyclic on  $\widetilde{X}$  iff  $\{\widetilde{T}_t\}_{t\geq 0}$  is hypercyclic on  $\widetilde{X}$ .
- (2)  $\{T_t\}_{t\geq 0}$  is chaotic on X iff  $\{\widetilde{T}_t\}_{t\geq 0}$  is chaotic on  $\widetilde{X}$ .

To prove the following Theorem 4, we need the next result.

**Theorem B** ([7]). Let  $\rho$  be an admissible weight function and X be  $C_{0,\rho}(I,\mathbb{C})$  with  $I = [0,\infty)$ . Then the following assertions are equivalent:

- (i) the translation semigroup  $\{T_t\}_{t\geq 0}$  on X is chaotic;
- (ii) for any  $\varepsilon > 0$  and for any l > 0, there exists P > 0 such that  $\rho(l + nP) < \varepsilon$  for all  $n \in \mathbb{N}$ .

**Theorem 4.** Let  $\widetilde{X} = C_0(I, \mathbb{C})$  with  $I = [0, \infty)$ . We consider the partial differential equation:

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} + h(x)u\\ u(0, x) = f(x) & \text{with some } f \in \widetilde{X}, \end{cases}$$

where h is a bounded continuous function on I.

Then the solution semigroup  $\left\{\widetilde{T}_t\right\}_{t\geq 0}$  is a strongly continuous semigroup on  $\widetilde{X}$ . Moreover if h(x) satisfies  $\int_0^\infty h(s)ds = \infty$ , then  $\left\{\widetilde{T}_t\right\}_{t\geq 0}$  is chaotic.

*Proof.* By the relation  $\widetilde{T}_t f(x) = \frac{\rho(x)}{\rho(x+t)} f(x+t)$ , it is easy to see that  $\left\{\widetilde{T}_t\right\}_{t\geq 0}$  is a semigroup.

To show the strong continuity of  $\left\{\widetilde{T}_t\right\}_{t\geq 0}$ , we shall show the continuity at t=0. Put  $\rho(x)=e^{-\int_0^x h(s)ds}$ . Since h is a bounded function, there exists a constant  $\omega>0$  such that  $h(x)\cdot\omega$  for any  $x\in I$ . For any  $\varepsilon>0$  there exists R>0 such that  $|f(x)|<\frac{\varepsilon}{3e^{\omega}}$  for x>R. Then  $|u(t,x)|=|\frac{\rho(x)}{\rho(x+t)}f(x+t)|\cdot e^{\omega t}|f(x+t)|\cdot\frac{\varepsilon}{3}$  for  $0\cdot t<1$  and x>R. Since u(t,x) is uniformly continuous on  $[0,1]\times[0,R]$ , there exists  $1>\delta>0$  such that  $|u(t,x)-u(0,x)|<\frac{\varepsilon}{3}$  for  $0\cdot t<\delta$  and x>0. So

$$\begin{split} ||\widetilde{T}_t f - f|| &= \sup_{x \in [0, \infty)} |u(t, x) - u(0, x)| \\ \cdot &\sup_{x \in [0, R]} |u(t, x) - u(0, x)| + \sup_{x \in [R, \infty)} |u(t, x) - u(0, x)| < \frac{\varepsilon}{3} + \frac{2\varepsilon}{3} = \varepsilon \end{split}$$

for  $0 \cdot t < \delta$ . Hence  $\left\{\widetilde{T}_t\right\}_{t \geq 0}$  is a strongly continuous semigroup.

We shall check that  $\left\{\widetilde{T}_t\right\}_{t\geq 0}$  is chaotic on  $C_0(I,\mathbb{C})$ . By the assumption  $\int_0^\infty h(s)ds = \infty$ , we have  $\lim_{x\to\infty} \rho(x) = 0$ . By Theorem B, the translation semigroup  $\{T_t\}_{t\geq 0}$  is chaotic on  $C_{0,\rho}(I,\mathbb{C})$  where  $T_tf(x) = f(x+t)$ . By Proposition 3,  $\left\{\widetilde{T}_t\right\}_{t\geq 0}$  is chaotic on  $C_0(I,\mathbb{C})$ .

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