# LORENTZIAN GEODESIC FLOWS 

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## 1. Introduction

In this paper we consider time oriented Lorentzian manifolds ( $M, g$ ) satisfying condition $C_{Q}$, i.e., $(M, g)$ is
(1) future 1-connected, nonspacelike complete
(2) the sectional curvatures $K(\pi) \geq Q^{2}$ for every timelike two plane $\pi$
for some $Q \geq 0$. Recall that ( $M, g$ ) is future 1 connected if any two smooth timelike curves from $p$ to $q$ are homotopic through smooth timelike curves from $p$ to $q$. Also a Lorentzian manifold is a smooth, connected Hausdorff manifold with a countable base and a metric $g$ of signature $(-,+, . .,+)$. The Riemannian inclined reader may benefit from the remark that the curvature assumption (2) corresponds in some respects to negative Riemannian curvature.

The main results of this paper are the following:
(1) A density theorem for the timelike geodesic flow, cf. Theorem 8.4. Here it is proven that the closed timelike geodesics are dense in the quotient of the future timelike unit tangent bundle with a vicious group of isometries.
(2) A rigidity theorem for $C_{Q}$ surfaces, cf. Theorem 10.3. More precisely we prove that an orientable $C_{Q}$ surface with a vicious isometry group and $Q$ positive must have constant curvature.

These results will follow from structure theorems for geometrically defined subsets of $(M, g)$, notably Theorem 7.4 and Theorem 7.7. In fact the future null cone $K^{+}(p)$ of any point $p \in M$ is a smooth hypersurface of constant signature $(0,+, \ldots,+)$. The implication is that the boundary $N_{\omega}\left(N_{\alpha}\right)$ of the past (future) of a complete timelike geodesic $\gamma$ is a $C^{1}$ hypersurface in $M$ of constant signature $(0,+, \ldots,+)$. In other

[^0]words $N_{\omega}$ is a singular semi-Riemannian manifold. Some theory is available for the geometry of singular semi-Riemannian manifolds, cf. [20], [22], [23], [24]. $N_{\omega}$ is the union of null colines to $\gamma$. These null colines are null axes of a hyperbolic isometry if the induced isometry on the Riemannian manifold $N_{\alpha} \cap N_{\omega}$ has a fixed point, where $\alpha$ and $\omega$ are endpoints of a timelike axis for the hyperbolic isometry. These results are derived in chapter 7. The main tool is the null theory from section 6 . This in turn follows from section 2, deriving a triangle comparison lemma for $C_{Q}$ manifolds. Theorem 5.3 proves the crucial fact that a hyperbolic isometry has a timelike axis.

On the constantly curved $C_{Q}$ manifolds there are properly discontinuous groups of isometries acting on the future timelike unit tangent bundle, cf. section 9. If this group is proper, the geodesic flow induced on the quotient is mixing, hence ergodic. It has a transitive geodesic and dense periodic orbits. In dimension two a horocycle flow is induced on the quotient. It is mixing of all degrees. These results are derived from the Riemannian theory, cf. also [17], [25] and [30]. The Riemannian theory started in the 1920's, cf. [19] and [29].

Chapter nine sets the context for the neighbouring sections. A density theorem for $C_{Q}$ manifolds with vicious Deck transformation group is presented in section 8 . It relies on the definition of the timelike future and the timelike past of a $C_{Q}$ manifold, developed in sections 3 and 4.

The same assumption for the isometry group of a $C_{Q}$ surface forces the curvature to be constant.

To avoid confusion it is emphasized that throughout we shall use the convention that a mapping $F$ from a subset $A$ of a manifold $M$ is $C^{r}, 1 \leq r \leq+\infty$ if for every $q \in A$ there is a $C^{r} \operatorname{map} G$, defined on an open neighbourhood $U$ of $q$, whose restriction to $A \cap U$ coincides with the restriction of $F$ to this set. Also the curvature tensor is

$$
R_{X Y} Z=\nabla_{[X, Y]} Z-\nabla_{X} \nabla_{Y} Z+\nabla_{Y} \nabla_{X} Z
$$

The domain of definition of a mapping $f$ is denoted by $\mathbb{D}(f)$. Maximal geodesics with initial velocity $v$ are denoted by $\gamma_{v}$.

## 2. Timelike geodesic triangles

This section is fundamental. It provides the main tool in this paper,
namely a triangle comparison lemma for timelike geodesic triangles in a $C_{Q}$ manifold $(M, g)$, i.e., a Lorentz manifold satisfying condition $C_{Q}$.

Recall that two points $p$ and $q$ in $M$ are causally related, i. e., $p<q$, sometimes written $q>p$, provided there exists a nonspacelike future directed curve from $p$ to $q$. Also $p \ll q$, sometimes written $q \gg p$, provided there is a timelike future directed curve from $p$ to $q$. As usual

$$
\begin{array}{ll}
I^{+}(p) & =\{q \in M \mid p \ll q\}, \\
J^{+}(p) & =\{q \in M \mid p<q \text { or } p=q\}, I^{-}(p)=\{q \in M \mid q \ll p\} \\
J^{-}(p)=\{q \in M \mid q<p \text { or } p=q\} .
\end{array}
$$

Lemma 2.1. For any point $p$ in $M$, the map

$$
\begin{aligned}
& \Lambda^{+}(p) \rightarrow I^{+}(p), v \mapsto \exp _{p}(v) \\
& \Lambda^{+}(p)=\left\{w \in T_{p} M \mid w \text { timelike and future directed }\right\}
\end{aligned}
$$

is a $C^{\infty}$ diffeomorphism.
Proof. In view of [13] we need only show that $\exp _{p}\left(\Lambda^{+}(p)\right)=I^{+}(p)$. Take any $q \in I^{+}(p)$ and a timelike future directed curve $c$ from $c(0)=p$ to $c(a)=q$. If $q \notin \exp _{p}\left(\Lambda^{+}(p)\right)$ define

$$
\begin{aligned}
& \left.S=\{t \in] 0, a] \mid c(t) \notin \exp _{p}\left(\Lambda^{+}(p)\right)\right\} \\
& s_{*}=\inf S>0
\end{aligned}
$$

Let $\gamma$ denote a timelike geodesic from some $c(t)=\gamma(0), t \in\left[0, s_{*}[\right.$ to $c\left(s_{*}\right)=\gamma(b), b \in \mathbb{D}(\gamma) \cap \mathbb{R}_{+}$. Define

$$
t_{*}=\inf \{t \in] 0, b\left[\mid \gamma(t) \notin \exp _{p}\left(\Lambda^{+}(p)\right)\right\}
$$

By $\phi(t), t \in] 0, t_{*}\left[\right.$ we denote the unique vector in $\Lambda^{+}(p)$ such that $\left.\exp _{p}(\phi(t))=\gamma(t) . t \mapsto \phi(t), t \in\right] 0, t_{*}[$ is then a timelike future directed curve in $\Lambda^{+}(p)$. The function

$$
\left.g(t)=(-\langle\phi(t), \phi(t)\rangle)^{\frac{1}{2}} \quad t \in\right] 0, t_{*}[
$$

is smooth and concave according to [9]. $g$ is then bounded above. Since $\phi(t) \gg \phi(0) \in \Lambda^{+}(p)$ we deduce that $\phi(t)$ is contained in a compact set in $T_{p} M$, hence $\phi\left(t_{n}\right) \rightarrow w$ for a suitable sequence $t_{n} \rightarrow t_{*}$ and some $w \in \Lambda^{+}(p)$. Thus $\exp _{p}(w)=\gamma\left(t_{*}\right)$ in contradiction.

To prove the triangle comparison lemma, let $p, q$ and $r$ be three causally related points in a $C_{Q}$ manifold $(M, g=\langle\rangle$,$) . This means$
that $p \ll q, q \ll r$. Throughout the paper a TF (respectively TP) geodesic is a timelike, complete, unit speed geodesic, which is future (respectively past) directed. According to Lemma 2.1 there are unique TF geodesics $\gamma_{1}, \gamma_{2}$ and $\gamma_{3}$ from $p$ to $q=\gamma_{1}(a), q$ to $r=\gamma_{2}(b)$ and $p$ to $r=\gamma_{3}(c), a, b, c \in \mathbb{R}_{+}$. Define

$$
\begin{align*}
A_{p} & =\left\langle\gamma_{1}^{\prime}(0), \gamma_{3}^{\prime}(0)\right\rangle \leq-1, \\
-A_{q} & =\left\langle\gamma_{1}^{\prime}(a), \gamma_{2}^{\prime}(0)\right\rangle \leq-1,  \tag{2.1}\\
A_{r} & =\left\langle\gamma_{2}^{\prime}(b), \gamma_{3}^{\prime}(c)\right\rangle \leq-1 .
\end{align*}
$$

When $Q=0, M_{Q}$ denotes Minkowski space $\mathbb{R}_{1}^{n}$, whereas
$M_{Q}=\left\{x=\left(x_{1}, . ., x_{n+1}\right) \in \mathbb{R}^{n+1} \mid\langle x, x\rangle=-x_{1}^{2}+x_{2}^{2}+. .+x_{n+1}^{2}=1 / Q^{2}\right\}$
with metric induced by the Minkowski metric 〈, ) when $Q>0$. According to Lemma 2.1, $c \geq a+b$. This means there are causally related points $p_{Q}, q_{Q}, r_{Q} \in M_{Q}$ such that

$$
\begin{equation*}
a=d_{Q}\left(p_{Q}, q_{Q}\right), \quad b=d_{Q}\left(q_{Q}, r_{Q}\right), \quad c=d_{Q}\left(p_{Q}, r_{Q}\right) \tag{2.2}
\end{equation*}
$$

Here $d_{Q}$ is the Lorentzian distance function in $M_{Q}$, and $d$ will always denote the Lorentzian distance function in $(M, g)$, cf. [5, Chapter 3].

Lemma 2.2. Let $p, q, r$ be causally related points in a $C_{Q}$ manifold $(M, g)$, where $Q \geq 0$. When $p_{Q}, q_{Q}$ and $r_{Q}$ are causally related points in $M_{Q}$, satisfying (2.2), then

$$
A_{p_{Q}} \leq A_{p}, \quad A_{q_{Q}} \leq A_{q}, \quad A_{r_{Q}} \leq A_{r}
$$

Proof. We shall use Karcher's method, see [16]. Define

$$
r(x)=d(p, x), \quad x \in I^{+}(p)
$$

and let $y_{Q}$ denote the solution to

$$
y_{Q}^{\prime \prime}=Q^{2} y_{Q}, \quad y_{Q}(0)=0, \quad y_{Q}^{\prime}(0)=1
$$

We claim that

$$
H(r)(v, v) \leq-\langle v, v\rangle y_{Q}^{\prime}(r(x)) / y_{Q}(r(x))
$$

for all $v \perp \operatorname{grad} r_{x}$, where $H(r)$ denotes the hessian of $r$. To this end let $\gamma: I \rightarrow I^{+}(p)$ denote a geodesic with $\gamma^{\prime}(0)=v$ and let

$$
\begin{aligned}
\gamma(s) & =\exp _{p}(v(s)) \\
\alpha(t, s) & =\exp _{p}(t v(s)), \quad t>0, \quad s \in I .
\end{aligned}
$$

$N=\operatorname{Im} \alpha$ is a Lorentz surface with $K^{N} \geq Q^{2}$. A straightforward differentiation yields

$$
H(r)(v, v)=(r \circ \gamma)^{\prime \prime}(0)=-\left\langle v, \alpha_{s t}(1,0)\right\rangle / r(x)
$$

Let $E$ denote a parallel vector field in $N$ orthogonal to $t \mapsto \alpha(t, 0)$. Then $\alpha_{s}(t, 0)=v(t) E(t)$ for some smooth function $v$ satisfying

$$
v^{\prime \prime}=v K^{N} r(x)^{2}
$$

By standard Liouville theory we have

$$
\begin{aligned}
H(r)(v, v) & =-\langle v, v\rangle v^{\prime}(1) /(v(1) r(x)) \\
& \leq-\langle v, v\rangle y_{Q r(x)}^{\prime}(1) /\left(y_{Q r(x)}(1) r(x)\right) \\
& =-\langle v, v\rangle y_{Q}^{\prime}(r(x)) / y_{Q}(r(x))
\end{aligned}
$$

Notice that $H(r)(v, v)=0$ when $v \| \operatorname{grad} r_{x}$. Now define

$$
S(t)= \begin{cases}\frac{1}{2} t^{2}, & Q=0, \\ \left(y_{Q}^{\prime}(t)-1\right) / Q^{2}, & Q>0,\end{cases}
$$

and $r_{s}=S \circ r$. Then

$$
\begin{aligned}
H\left(r_{s}\right)(v, v) & =S^{\prime} \circ r H(r)(v, v) \\
& \leq-\langle v, v\rangle y_{Q}^{\prime}(r(x))=-\langle v, v\rangle\left(Q^{2} r_{s}(x)+1\right), \quad v \perp \operatorname{grad} r_{x} \\
H\left(r_{s}\right)(v, v) & =S^{\prime \prime}(r(x)) v[r]^{2}=-\langle v, v\rangle\left(Q^{2} r_{s}(x)+1\right), \quad v \| \operatorname{grad} r_{x}
\end{aligned}
$$

Now let $f(t)=r_{s} \circ \gamma_{2}(t), \quad t \in[0, b]$. Then

$$
f^{\prime \prime}(t) \leq Q^{2} f(t)+1
$$

Let $p_{Q} \ll q_{Q} \ll r_{Q}$ denote a timelike geodesic triangle in $M_{Q}$ with side lengths $a, b$ and $c$ and sides $\gamma_{1}^{Q}, \gamma_{2}^{Q}$ and $\gamma_{3}^{Q}$. Also let $r_{Q}(x)=$ $d\left(p_{Q}, x\right)$ and $f_{Q}(t)=S \circ r_{Q} \circ \gamma_{2}^{Q}(t), \quad t \in[0, b]$. Then

$$
f_{Q}^{\prime \prime}(t)=Q^{2} f_{Q}(t)+1
$$

Since $f(0)=f_{Q}(0)$ and $f(b)=f_{Q}(b)$, we deduce that

$$
f \geq f_{Q},
$$

and hence

$$
r \circ \gamma_{2}(t) \geq r_{Q} \circ \gamma_{2}^{Q}(t), \quad t \in[0, b]
$$

Finally

$$
\begin{aligned}
& \left(r \circ \gamma_{2}\right)^{\prime}(0)=A_{q} \geq A_{q_{Q}}=\left(r_{Q} \circ \gamma_{2}^{Q}\right)^{\prime}(0), \\
& \left(r \circ \gamma_{2}\right)^{\prime}(b)=-A_{r} \leq-A_{r_{Q}}=\left(r_{Q} \circ \gamma_{2}^{Q}\right)^{\prime}(b)
\end{aligned}
$$

Time reversal produces $A_{p_{Q}} \leq A_{p}$.
We shall present a different argument of competitive simplicity. If $A_{q}=1$, then $A_{p}=A_{p_{Q}}$, so to prove $A_{p_{Q}} \leq A_{p}$ we can assume that $A_{q} \neq 1$. Define future directed vectors $v(s)$ in $T_{p} M$ with

$$
\begin{aligned}
\gamma_{2}(s) & =\exp _{p}(v(s)), \quad s \in[0, b] \\
\alpha(t, s) & =\exp _{p}(t v(s)), \quad t>0
\end{aligned}
$$

Choose $p_{Q}^{*} \in M_{Q}$ and an isometry

$$
I: T_{p} M \rightarrow T_{p_{Q}^{*}} M_{Q}
$$

Define

$$
\begin{aligned}
\alpha^{Q}(t, s) & =\exp _{p_{Q}^{*}}(t I \circ v(s)), \quad t>0, \quad s \in[0, b] \\
Y_{s}(t) & =\alpha_{s}(t, s) \\
Y_{s}^{Q}(t) & =\alpha_{s}^{Q}(t)
\end{aligned}
$$

Then

$$
\begin{equation*}
I\left(\lim _{t \rightarrow 0} Y_{s}^{\prime}(t)\right)=I\left(v^{\prime}(s)\right)=Y_{s}^{Q^{\prime}}(0) \tag{2.3}
\end{equation*}
$$

where $Y_{s}^{\prime}(t)$ denotes the induced covariant derivative of $Y_{s}$ in $N=$ $\operatorname{Im} \alpha$. Take a unit parallel vector field $E^{Q}$ orthogonal to $t \mapsto \alpha^{Q}(t, s)$ such that

$$
Y_{s}^{Q^{\perp}}(t)=y_{Q}(t) E^{Q}(t)
$$

Let $E$ denote a unit parallel vector field orthogonal to $t \mapsto \alpha(t, s)$ in $N$. Define

$$
y=\left\langle Y_{s}, E\right\rangle
$$

Then

$$
\begin{aligned}
y_{Q}^{\prime \prime}-\alpha^{2} Q^{2} y_{Q} & =0, \quad-\alpha^{2}=\left\langle\alpha_{t}, \alpha_{t}\right\rangle(s) \\
y^{\prime \prime}-\alpha^{2} K^{N} y & =0
\end{aligned}
$$

Because of (2.3) we can assume $y^{\prime}(0)=y_{Q}^{\prime}(0)>0$ and $y(0)=y_{Q}(0)=$ 0 . Standard Liouville theory yields

$$
y_{Q} \leq y
$$

hence

$$
\left\|Y_{s}(1)\right\|=\left\|\gamma_{2}^{\prime}(s)\right\| \leq\left\|\alpha_{s}^{Q}(1, s)\right\| .
$$

Thus

$$
b=L\left(\gamma_{2}\right) \leq \int_{0}^{b}\left\|\alpha_{s}^{Q}(1, s)\right\| d s \leq d_{Q}\left(q_{Q}^{*}, r_{Q}^{*}\right)=b_{Q}
$$

where $q_{Q}^{*}=\alpha^{Q}(1,0), r_{Q}^{*}=\alpha^{Q}(1, b)$. When $p_{Q}, q_{Q}, r_{Q}$ are vertices in a timelike geodesic triangle in $M_{Q}$ with side lenghts $a, b$ and $c$ we find

$$
\begin{align*}
A_{p_{Q}} & = \begin{cases}\frac{\cosh (Q b)-\cosh (Q a) \cosh (Q c)}{\sinh (Q a) \sinh (Q c)}, & Q>0 \\
\left(b^{2}-a^{2}-c^{2}\right) / 2 a c, & Q=0\end{cases}  \tag{2.4}\\
& \leq A_{p_{Q}^{*}}=A_{p} .
\end{align*}
$$

Time reversal produces $A_{r_{Q}} \leq A_{r}$. The same method can be used to prove $A_{q_{Q}} \leq A_{q}$ for small $b$. This angle inequality follows for arbitrary $b$ by a subdivision of $\gamma_{2}$ and an induction argument.
Remark 2.3. We shall now briefly indicate how to combine Lemma 2.2 and Lemma 6.1 to show that a $C_{0}$ manifold $(M, g)$ is globally hyperbolic; see also [13]. To verify that $(M, g)$ is strongly causal at some $p \in M$ take some TF geodesic $\gamma$ through $\gamma(0)=p$. Given an open neighbourhood $U$ of $p$ use Lemma 2.2 to find a positive $\epsilon$ such that the causally convex neighbourhood $I(\gamma(-\epsilon), \gamma(\epsilon))$ of $p$ is contained in $U$.

If $p, q \in M$ are causally related, then $J(p, q) \triangleq J^{+}(p) \cap J^{-}(q) \subset$ $J^{+}\left(p_{*}\right) \cap I^{-}\left(q_{*}\right)$ for any $p_{*} \ll p$ and $q \ll q_{*}$. Now we use Lemma 2.2 and a $Q=0$ version of Lemma 6.1 to show that the counterimage of $J(p, q)$ by the restriction of $\exp _{p .}$ to the future cone is closed and bounded. $J(p, q)$ is then compact.

## 3. The timelike coray condition

In this section we consider a TF geodesic $\gamma$ in a $C_{0}$ manifold ( $M, g$ ). Recall from [4, p. 33] that a future coray from

$$
x \in I^{-}(\gamma)=\{q \in M \mid \exists t \in \mathbb{R}: q \ll \gamma(t)\}
$$

to $\gamma$ is a future directed, inextendible, nonspacelike limit curve $\beta: I \rightarrow$ $M$ through $x$ of a sequence of TF geodesics from $x_{n}$ to $\gamma\left(r_{n}\right)$ where $\left\{x_{n}\right\}_{n \in \mathrm{~N}}$ and $\left\{r_{n}\right\}_{n \in \mathrm{~N}}$ are sequences in $M$ and $\mathbb{R}$ respectively such that $x_{n} \rightarrow x, x_{n} \ll \gamma\left(r_{n}\right)$ and $r_{n} \rightarrow+\infty$. Here $I$ is an open interval. We can and will require that $0 \in I$ and $\beta(0)=x$. A smooth curve $\beta_{*}$ is a past coray from

$$
y \in I^{+}\left(\gamma_{*}\right)=\left\{q \in M \mid \exists t \in \mathbb{R}: q \gg \gamma_{*}(t)\right\}
$$

to a TP geodesic $\gamma_{*}$ provided $\beta_{*}$ is a future coray from $y \in I^{+}\left(\gamma_{*}\right)$ to $\gamma_{*}$ in $(M, g)$ with time orientation reversed. There is a future coray to $\gamma$ through every $x \in I^{-}(\gamma)$ according to [5, Proposition 2.18]. This coray definition coincides with the definition in [4]; see also [7]. There are other definitions in [11], [12], [28] and [3]. By definition ( $M, g$ ) satisfies the timelike coray condition if all future and past corays are timelike; cf. [4, Definition 3.1]. Corays are pregeodesics according to [5, Proposition 2.21, Remark 2.22, Lemma 3.5 and Theorem 3.13].

Lemma 3.1. The timelike coray condition holds for any TF geodesic $\gamma$ in a $C_{0}$ manifold $(M, g)$.

Proof. Assume that $x \in I^{-}(\gamma)$ has a future coray $\beta$ to $\gamma$, which is null. Then there are sequences $\left\{x_{n}\right\}$ in $I^{-}(\gamma),\left\{r_{n}\right\}$ in $\mathbb{R}$ and TF geodesics $\beta_{n}$ from $x_{n}$ to $\gamma\left(r_{n}\right)$ such that $\beta$ is a future directed, inextendible, nonspacelike limit curve through $x$ for $\left\{\beta_{n}\right\}$. We can suppose that $x$ and the $x_{n} \in I^{-}\left(\gamma\left(r_{0}\right)\right)$ for some $r_{0}<r_{n}$. According to Lemma 2.1 there is a TF geodesic $\sigma_{n}$ and $\sigma$ from $x_{n}$ and $x$ respectively to $\gamma\left(r_{0}\right)=q$. Put

$$
a_{n}=d\left(x_{n}, q\right), \quad a=d(x, q), \quad b_{n}=d\left(x_{n}, \gamma\left(r_{n}\right)\right), \quad c_{n}=r_{n}-r_{0}
$$

Looking at the timelike geodesic triangle $x_{n}, q=q_{n}, \gamma\left(r_{n}\right)$ we obtain

$$
1 \leq\left(b_{n} / c_{n}\right)^{2} \leq 1+\left(a_{n} / c_{n}\right)^{2}+2\left(a_{n} / c_{n}\right) A_{q_{n}} \rightarrow 1
$$

for $n \rightarrow+\infty$. Hence $b_{n} / c_{n} \rightarrow 1$ for $n \rightarrow+\infty$. We have used that $A_{q_{n}}$ is bounded and that $a_{n} \rightarrow a$. Adding two of the cosine laws give us that
$-1 \geq A_{x_{n}} \geq A_{x_{n}^{Q}}=-a_{n} / b_{n}-c_{n} / b_{n} A_{q_{n}^{Q}} \geq-a_{n} / b_{n}-c_{n} / b_{n} A q_{n}, \quad Q=0$,
contradicting the fact that $A_{x_{n}}$ is unbounded.

We can now define the Buseman function

$$
b^{+}: I^{-}(\gamma) \rightarrow \mathbb{R}, \quad x \mapsto \lim _{r \rightarrow+\infty}\{r-d(x, \gamma(r))\}
$$

The Buseman function is continuous, because ( $M, g$ ) satisfies the timelike coray condition, cf. [5].

Let $\beta$ denote a unit speed future coray from $p \in I^{-}(\gamma)$ to some TF geodesic $\gamma$. Proposition 3.2 below shows that it is unique. A dual statement applies to assert the uniqueness of unit speed past corays through $y \in I^{+}\left(\gamma_{*}\right)$ to some TP geodesic $\gamma_{*}$.

There exists by definition an $s_{0}$ such that $p \ll \gamma(s)$ for all $s \geq s_{0}$. In view of Lemma 2.1 this means that for all $s \geq s_{0}$ there exists a unique future directed timelike unit vector $v_{s}$ such that $\gamma(s)=\exp _{p}\left(t v_{s}\right)$ for some $t>0$.

Proposition 3.2. $v_{s} \rightarrow \beta^{\prime}(0)$ as $s \rightarrow+\infty$.
Proof. We shall consider two timelike geodesic triangles $p, \gamma\left(s_{0}\right)$, $\gamma\left(s_{1}\right)$ and $p, \gamma\left(s_{1}\right), \gamma\left(s_{2}\right)$ where $s_{0}<s_{1}<s_{2}$. Let us for notational convenience rename them $p, p_{0}, p_{1}$ and $q, q_{1}, q_{2}$ respectively. The side lengths are

$$
\begin{aligned}
& a_{1}=d\left(p, \gamma\left(s_{2}\right)\right), \quad a_{2}=d\left(p, \gamma\left(s_{1}\right)\right)=b_{1}, \\
& a_{3}=d\left(\gamma\left(s_{1}\right), \gamma\left(s_{2}\right)\right), \quad b_{2}=d\left(p, \gamma\left(s_{0}\right)\right), \quad b_{3}=s_{1}-s_{0}
\end{aligned}
$$

Lemma 2.2 gives us

$$
\begin{aligned}
& a_{1}^{2}=a_{2}^{2}+a_{3}^{2}+2 a_{2} a_{3} A_{q_{1}^{Q}}, \\
& a_{3}^{2}=a_{1}^{2}+a_{2}^{2}+2 a_{1} a_{2} A_{q^{Q}}
\end{aligned}
$$

which combine to $-A_{q^{Q}} \leq A_{q_{1}^{Q}}$. Notice that $A_{q_{1}}=-A_{p_{1}}$, hence $-A_{q^{Q}} \leq$ $-A_{p_{1}^{\alpha}}$. Applying Lemma 2.2 once again provides

$$
b_{1}^{2} \leq b_{2}^{2}+b_{3}^{2}+2 b_{2} b_{3} A_{p_{0}}
$$

Given $\epsilon>0$ we can make $b_{3} / b_{1} \geq 1-\epsilon$ for all $s_{1}$ sufficiently large. Use

$$
b_{2}^{2}=b_{1}^{2}+b_{3}^{2}+2 b_{1} b_{3} A_{p_{1}^{Q}}
$$

to conclude that $A_{q^{Q}} \geq A_{p_{1}^{Q}} \geq-1-\delta$ for all $s_{1}$ sufficiently large. The proposition now follows from the fact that we can take a sequence $\left\{s_{n}\right\}_{n \in \mathrm{~N}}$ of real numbers $s_{n} \rightarrow+\infty$ such that

$$
v_{s_{n}} \rightarrow \beta^{\prime}(0)
$$

Lemma 3.3. Let $\gamma_{i}, i=1,2$, be two $T F$ geodesics and

$$
\begin{aligned}
\Omega & =\left\{t \in \mathbb{R} \mid \gamma_{1}(t) \ll \gamma_{2}(t)\right\} \\
f(t) & =d\left(\gamma_{1}(t), \gamma_{2}(t)\right), \quad t \in \Omega
\end{aligned}
$$

Then $f$ is $C^{\infty}$ and concave, i.e., $f^{\prime \prime} \leq 0$.
Proof. See [9].

## 4. The timelike future

We shall now define the timelike future and the timelike past from the sets $\Omega_{T F}$ and $\Omega_{T P}$ of TF and TP geodesics respectively in a $C_{0}$ manifold $(M, g)$. We need a preliminary lemma to assert that the coray definition is translation invariant in the geodesic affine parameter.

Lemma 4.1. If $\gamma_{i} \in \Omega_{T F}, i=1,2$, are future corays to $\gamma_{3} \in \Omega_{T F}$ through $\gamma_{1}(0) \ll \gamma_{2}(0)$, then

$$
\gamma_{1}(t) \ll \gamma_{2}(t)
$$

for all $t \in \mathbb{R}_{+}$, and there exists a $K>0$ such that for these values of $t$

$$
d\left(\gamma_{1}(t), \gamma_{2}(t)\right)<K
$$

Proof. Let $c_{s}, d_{s}$ denote TF geodesics from $c_{s}(0)=\gamma_{1}(0), d_{s}(0)=$ $\gamma_{2}(0)$ to

$$
c_{s}\left(t_{s}\right)=d_{s}\left(u_{s}\right)=\gamma_{3}(s)
$$

for all $s$ exceeding some $s_{0}>0$. For $t \in A=\left\{t \geq 0 \mid c_{s}(t) \ll d_{s}(t)\right\}$ define

$$
f_{s}(t)=d\left(c_{s}(t), d_{s}(t)\right)
$$

For these values of $t$ let $\beta_{t}^{s}$ denote the TF geodesic from $\beta_{t}^{s}(0)=c_{s}(t)$ to $\beta_{t}^{s}\left(a_{t}^{s}\right)=d_{s}(t)$, and let

$$
\begin{aligned}
B_{s}(t) & =\left\langle c_{s}^{\prime}(t), \beta_{t}^{s^{\prime}}(0)\right\rangle \\
C_{s}(t) & =\left\langle d_{s}^{\prime}(t), \beta_{t}^{s^{\prime}}\left(a_{t}^{s}\right)\right\rangle .
\end{aligned}
$$

Define

$$
h_{s}(u)=d\left(\beta_{t}^{s}(u), \gamma_{3}(s)\right), \quad u \in\left[0, a_{t}^{s}\right] .
$$

We have seen that $h_{s}^{\prime \prime} \leq 0$, hence

$$
B_{s}(t)=h_{s}^{\prime}(0) \geq h_{s}^{\prime}\left(a_{t}^{s}\right)=C_{s}(t)
$$

and thus

$$
f_{s}^{\prime}(t)=B_{s}(t)-C_{s}(t) \geq 0
$$

It follows that $\left[0, u_{s}\right] \subset A$. For

$$
t \in B=\left\{t \in \left[0,+\infty\left[\mid \gamma_{1}(t) \ll \gamma_{2}(t)\right\}\right.\right.
$$

let $\eta_{t}$ denote the TF geodesic from $\eta_{t}(0)=\gamma_{1}(t)$ to $\eta_{t}\left(b_{t}\right)=\gamma_{2}(t)$ and

$$
f(t)=d\left(\gamma_{1}(t), \gamma_{2}(t)\right)
$$

Then

$$
f_{s}^{\prime}(t) \rightarrow\left\langle\gamma_{2}^{\prime}(t), \eta_{t}^{\prime}\left(b_{t}\right)\right\rangle-\left\langle\gamma_{1}^{\prime}(t), \eta_{t}^{\prime}(0)\right\rangle=f^{\prime}(t \zeta \geq 0
$$

as $s \rightarrow+\infty$ and then $B=[0,+\infty[$.
The Buseman function $b^{+}$for $\gamma_{3}$ is differentiable; see [12], with

$$
\left\langle\operatorname{grad} b^{+}, \operatorname{grad} b^{+}\right\rangle=-1
$$

hence

$$
b^{+} \circ \eta_{t}(s) \geq s+b^{+}\left(\gamma_{1}(t)\right), \quad s \in\left[0, b_{t}\right]
$$

and then
$K=b^{+}\left(\gamma_{2}(0)\right)-b^{+}\left(\gamma_{1}(0)\right)=b^{+} \circ \eta_{t}\left(b_{t}\right)-b^{+} \circ \eta_{t}(0) \geq b_{t}=d\left(\gamma_{1}(t), \gamma_{2}(t)\right)$.
The lemma follows.
Proposition 4.2. If $\gamma_{1} \in \Omega_{T F}$ is a future coray to $\gamma_{2} \in \Omega_{T F}$ through $\gamma_{1}(0)$ in a $C_{0}$ manifold $(M, g)$, then $\gamma_{1}$ is a future coray to $\gamma_{2}$ through $\gamma_{1}(t)$ for every $t \in \mathbb{R}$.

Proof. Let a $t \in \mathbb{R}$ be given. Since $\gamma_{1} \in \Omega_{T F}$ is a future coray to $\gamma_{2}$ through $\gamma_{1}(0)$ we can find an $s \in \mathbb{R}$ such that $\gamma_{1}(t) \ll \gamma_{2}(s)$. This follows from definitions, when $t \leq 0$ and from Lemma 4.1 for $t>0$. Define

$$
c=c(a)=d\left(\gamma_{1}(t+a), \gamma_{2}(s+a)\right)>0, \quad b=d\left(\gamma_{1}(t), \gamma_{2}(s+a)\right)
$$

where $a \in \mathbb{R}_{+}$. The function $c$ has an upper bound by Lemma 4.1. Looking at the timelike geodesic triangle $\gamma_{1}(t), \gamma_{2}(s), \gamma_{2}(s+a)$ we find

$$
\begin{equation*}
b^{2} \leq a^{2}+c^{2}+2 a c A_{q} \tag{4.4}
\end{equation*}
$$

with $q=\gamma_{2}(s)$. It follows from (4.4) that $b / a \geq 1$ is close to 1 , when a is sufficiently big. Let a positive $\epsilon$ be given. Looking at the timelike geodesic triangle $p=\gamma_{1}(t), \gamma_{1}(t+a), \gamma_{2}(s+a)$ we see that

$$
A_{p} \geq A_{p_{Q}}=\left(c^{2}-a^{2}-b^{2}\right) / 2 a b \geq-\frac{1}{2}\left(1+(b / a)^{2}\right) \geq-1-\epsilon
$$

taking $a$ sufficiently large. This means that $\gamma_{1}$ is a future coray to $\gamma_{2}$ through $\gamma_{1}(t)$.

We can now adopt
Definition 4.3. $\gamma_{1} \in \Omega_{T F}$ is a future coray to $\gamma_{2} \in \Omega_{T F}$ provided $\gamma_{1}$ is a future coray to $\gamma_{2}$ through some and hence any $\gamma_{1}(t), t \in \mathbb{R}$.

Two future corays have the same past. In fact we have
Lemma 4.4. If $\gamma_{1} \in \Omega_{T F}$ is a future coray to $\gamma_{2} \in \Omega_{T F}$ in a $C_{0}$ manifold, then $I^{-}\left(\gamma_{1}\right)=I^{-}\left(\gamma_{2}\right)$.

Proof. Since $\gamma_{1} \in \Omega_{T F}$ is a future coray to $\gamma_{2} \in \Omega_{T F}$, there exists an $s \in \mathbb{R}$ such that

$$
\gamma_{1}(0) \ll \gamma_{2}(s)=q
$$

We denote by $\beta$ the TP geodesic through $\gamma_{2}(s)$ and $\gamma_{1}(0)=\beta(a), a \in$ $\mathbb{R}_{+}$. Assume for contradiction there is no $u \in \mathbb{R}_{+}$such that $\gamma_{1}(u) \in$ $I^{+}(q)$. The nonempty subset
$A=\left\{t \in[0, a] \mid\right.$ There exists no positive $s$ such that $\left.\gamma_{\beta(t)}(s) \in I^{+}(q)\right\}$
of $[0, a]$ has an infimum $z>0$. We are using the notation $\gamma_{\beta(t)} \in$ $\Omega_{T F}, t \in[0, a]$ for the future coray to $\gamma_{2}$ through $\beta(t) \in I^{-}\left(\gamma_{2}\right) . z \in$ $A$ because the relation $\ll$ is open, see [27, Proposition 14.3]. This proposition also implies that we can take $v \in[0, z[$ and $u>0$ such that

$$
\beta(v) \ll \gamma_{\beta(z)}(u)
$$

Since $v \notin A$, there exists $r>0$ such that

$$
\gamma_{\beta(v)}(r) \in I^{+}(q)
$$

We can now apply Lemma 4.1 to get

$$
q \ll \gamma_{\beta(v)}(r) \ll \gamma_{\beta(z)}(u+r)
$$

which contradicts the fact that $z \in A$, thus asserting the existence of a $\gamma_{1}(s) \in I^{+}(q), s \in \mathbb{R}_{+}$. Hence $I^{-}\left(\gamma_{1}\right) \subset I^{-}\left(\gamma_{2}\right)$. A second application of Lemma 4.1 yields the reverse inclusion, thereby proving the lemma.

We now define a relation $\underset{+}{\rightarrow} \sim(\xrightarrow{ })$ in $\Omega_{T F}\left(\Omega_{T P}\right)$ by requiring that $\gamma_{1} \xrightarrow{\rightarrow} \sim \gamma_{2}\left(\gamma_{1} \xrightarrow{\longrightarrow} \sim \gamma_{2}\right)$ provided $\gamma_{1}$ is a future ( past) coray to $\gamma_{2}$. This is an equivalence relation. It is reflexive by Proposition 3.2. Symmetry and transitivity follows from Lemma 4.4, Lemma 4.1, Proposition 3.2 and an application of Lemma 2.2. We can then define the timelike future $M^{+}(\infty)$ and the timelike past $M^{-}(\infty)$ to be the quotient spaces of $\Omega_{T F}$ and $\Omega_{T P}$ under the coray equivalence relations $\underset{+}{ } \sim$ and $\longrightarrow \sim$ respectively

$$
M^{+}(\infty)=\Omega_{T F} / \underset{+}{\rightarrow} \sim, \quad M^{-}(\infty)=\Omega_{T P} / \xrightarrow[-]{\longrightarrow} .
$$

Equivalence classes in $M^{+}(\infty)$ and $M^{-}(\infty)$ will be denoted $[\gamma]_{+}$and $[\gamma]$ - respectively. Given $\omega=[\gamma]_{+} \in M^{+}(\infty), \alpha=[\beta]_{-} \in M^{-}(\infty)$ we adopt the convention

$$
I^{-}(\omega)=I^{-}(\gamma), \quad I^{+}(\alpha)=I^{+}(\beta)
$$

which is well defined by Lemma 4.4. It will be convenient to have the following.

Proposition 4.5. Given $\omega=[\gamma]_{+} \in M^{+}(\infty)$ and $p \in I^{-}(\omega)$ in a $C_{0}$ manifold, then there exists a TF geodesic $\beta$ through $\beta(0)=p$ such that $[\beta]_{+}=\omega$. If $\sigma$ is a TF geodesic through $\sigma(0)=p$ such that $[\sigma]_{+}=\omega$, then $\sigma=\beta$.

Proof. The existence of $\beta$ follows from the fact that $(M, g)$ satisfies the timelike coray condition. Suppose $\sigma$ is a TF geodesic with $\sigma(0)=$ $\beta(0)$ and $[\sigma]_{+}=\omega$. Then $\beta(0) \ll \sigma(s)$ for a fixed positive $s$. Now apply Lemma 4.1 to assert the existence of a positive $K$ such that

$$
\beta(t) \ll \sigma(s+t) \quad r=r(t)=d(\beta(t), \sigma(s+t)) \leq K
$$

for all $t \geq 0$. In the timelike geodesic triangle $p=\beta(0), \beta(t), \sigma(t+s)$, using Lemma 2.2 we have the following estimates

$$
A_{p} \geq A_{p_{Q}} \geq \frac{-t^{2}+(t+s)^{2}}{2 t(t+s)}
$$

The right-hand side converges to -1 as $t \rightarrow+\infty$, hence $A_{p}=-1$. Consequently $\sigma=\beta$.

Given $p \in M$ we shall say that $p \ll \omega \in M^{+}(\infty)$ provided there exists $\gamma \in \Omega_{T F}$ such that $\gamma(0)=p,[\gamma]_{+}=\omega$. Similarly $p \gg \alpha \in$ $M^{-}(\infty)$ if there exists $\gamma \in \Omega_{T P}$ such that $\gamma(0)=p,[\gamma]_{-}=\alpha$. We can then define subsets

$$
I_{\infty}^{+}(p)=\left\{\omega \in M^{+}(\infty) \mid p \ll \omega\right\}, \quad I_{\infty}^{-}(p)=\left\{\alpha \in M^{-}(\infty) \mid p \gg \alpha\right\}
$$

of $M^{+}(\infty)$ and $M^{-}(\infty)$ respectively. Also $\alpha \ll \omega, \alpha \in M^{-}(\infty), \omega \in$ $M^{+}(\infty)$ provided there exists $p \in M$ such that $p \gg \alpha, p \ll \omega$. In this case $\alpha$ and $\omega$ are causally related.

A sequence $\left\{\omega_{n}\right\}_{n \in \mathbf{N}}$ in $M^{+}(\infty)$ converges to $\omega \in I_{\infty}^{+}(p)$ with respect to $p \in M$ if there exists an $n_{0} \in \mathbb{N}$ such that $\omega_{n} \in I_{\infty}^{+}(p)$ for all $n \geq n_{0}$ and

$$
c_{n}^{\prime}(0) \rightarrow \gamma^{\prime}(0)
$$

as $n \rightarrow+\infty$. Here $c_{n}$ is the unique TF geodesic from $p$ to $\omega_{n}$ and $\gamma$ is the unique TF geodesic from $p$ to $\omega=[\gamma]_{+}$. As usual time reversal produces a definition of convergence for a sequence $\left\{\alpha_{n}\right\}_{n \in \mathrm{~N}}$ in $M^{-}(\infty)$.

We will adopt the notation

$$
\omega_{n} \rightarrow_{p} \omega, \quad \alpha_{n} \rightarrow_{p} \alpha
$$

when $\left\{\omega_{n}\right\}_{n \in \mathbf{N}}$ and $\left\{\alpha_{n}\right\}_{n \in \mathbf{N}}$ converge with respect to $p$ to $\omega$ and $\alpha$ respectively.

Also a sequence $\left\{p_{n}\right\}_{n \in \mathrm{~N}}$ in $M$ converges to $\omega \in I_{\infty}^{+}(p)$ with respect to $p$ provided there exists an $n_{0} \in \mathbb{N}$ such that $p_{n} \in I^{+}(p)$ and

$$
c_{n}^{\prime}(0) \rightarrow \gamma^{\prime}(0), \quad d\left(p, p_{n}\right) \rightarrow+\infty
$$

as $n \rightarrow+\infty$. Here $c_{n}$ and $\gamma$ are the TF geodesics from $c_{n}(0)=p=\gamma(0)$ to $p_{n}$ and $[\gamma]_{+}=\omega$ respectively. We write

$$
p_{n} \rightarrow_{p} \omega, \quad p_{n} \rightarrow_{p} \alpha
$$

whenever $p_{n}$ converges with respect to $p$ to $\omega$ and $\alpha \in M^{-}(\infty)$ respectively.

In the rest of this section $(M, g)$ is a $C_{Q}$ manifold with $Q>0$.
Proposition 4.6. If $\omega_{n} \rightarrow_{p} \omega$, then $\omega_{n} \rightarrow_{q} \omega$ for every $q \in M$ such that $\omega \in I_{\infty}^{+}(q)$.

Proof. Take TF geodesics $\gamma_{i}, i=1,2$, with $\gamma_{1}(0)=p, \gamma_{2}(0)=q$ and $\left[\gamma_{1}\right]_{+}=\omega=\left[\gamma_{2}\right]_{+}$. Given an $\epsilon>0$, take $r>0$ such that

$$
\cosh ^{2}(Q r) / \sinh ^{2}(Q r)<1+\epsilon
$$

Now $\gamma_{1}$ is a future coray to $\gamma_{2}$ through $p$. We can therefore find a $t>r$ such that $p \ll \gamma_{2}(t)$. But $\gamma_{2}$ is also a coray to $\gamma_{1}$ through $\gamma_{2}(t)$. There is then an $s \in \mathbb{R}$ such that $\gamma_{2}(t) \ll \gamma_{1}(s)$. Recall from [27, p.403] that $I^{+}\left(\gamma_{2}(t)\right)$ is an open neighbourhood of $\gamma_{1}(s)$. Since $\omega_{n} \rightarrow_{p} \omega$, there exist an $n_{0} \in \mathbb{N}$ and TF geodesics $c_{n}$ for $n \geq n_{0}$ having $c_{n}(0)=p,\left[c_{n}\right]_{+}=\omega_{n}$. Their initial tangent vectors converge to $\gamma_{1}^{\prime}(0)$. We can therefore assume $n_{0}$ is chosen to render $c_{n}(s) \in I^{+}\left(\gamma_{2}(t)\right)$ for all $n \geq n_{0}$. It implies that $\omega_{n} \in I_{\infty}^{+}(q)$ for these values of $n$. Looking at the timelike geodesic triangles $q, \gamma_{2}(t), c_{n}(s)$ with side lengths $a_{n}, b_{n}$ and $e_{n}$ we can estimate

$$
\begin{aligned}
A_{q} \geq A_{q_{Q}} & =\frac{\cosh \left(Q b_{n}\right)-\cosh \left(Q e_{n}\right) \cosh \left(Q a_{n}\right)}{\sinh \left(Q e_{n}\right) \sinh \left(Q a_{n}\right)} \\
& \geq-\frac{\cosh \left(Q e_{n}\right) \cosh (Q t)}{\sinh \left(Q e_{n}\right) \sinh (Q t)}>-1-\epsilon
\end{aligned}
$$

showing that $\omega_{n} \rightarrow_{q} \omega$.
The proof of the next proposition is quite similar to that of the previous one and is omitted.

Proposition 4.7. If $p_{n} \rightarrow_{p} \omega$, then $p_{n} \rightarrow_{q} \omega$ for every $q \in M$ such that $\omega \in I_{\infty}^{+}(q)$.

Time reversal of a TF geodesic produces a TP geodesic $\gamma_{-}$, that is, $\gamma_{-}(t)=\gamma(-t)$ for all $t \in \mathbb{R}$. Translations on the real line are denoted $\tau_{a}(t)=t+a, a, t \in \mathbb{R}$.

Proposition 4.8. Let $\alpha \in M^{-}(\infty)$ and $\omega \in M^{+}(\infty)$ be causally related in a $C_{Q}$ manifold $(M, g)$ where $Q>0$. There exists a TF geodesic $\gamma$ with $\left[\gamma_{-}\right]_{-}=\alpha$ and $[\gamma]_{+}=\omega$. If $\sigma$ is a TF geodesic with $\left[\sigma_{-}\right]_{-}=\alpha$ and $[\sigma]_{+}=\omega$, then $\sigma=\gamma \circ \tau_{a}$ for some $a \in \mathbb{R}$.

Proof. According to the definitions there exists a $p \in M$ such that $\alpha \ll p \ll \omega$. In other words there exist a TF geodesic $\gamma_{1}$ and a TP geodesic $\gamma_{2}$ such that

$$
\left[\gamma_{1}\right]_{+}=\omega, \quad\left[\gamma_{2}\right]_{-}=\alpha, \quad \gamma_{i}(0)=p
$$

For all $s$ larger than some positive $s_{0}$ the TF geodesic $\gamma^{s}$ from $\gamma^{s}(0)=$ $\gamma_{2}(s)$ to $\gamma^{s}\left(a_{s}\right)=\gamma_{1}(s), a_{s} \in \mathbb{R}_{+}$gives rise to the definition

$$
t_{s}=\sup \left\{t \geq 0 \mid \gamma^{s}(t) \in J\left(\gamma_{2}(s), p\right)\right\}
$$

Due to [27, 14.1 and 14.5] there exists an NP geodesic $\beta_{s}$ from $\beta_{s}(0)=p$ to $\beta_{s}(1)=\gamma_{s}\left(t_{s}\right)$. Lemma 6.1 implies that

$$
-\left\langle\beta_{s}^{\prime}(0), \gamma_{2}^{\prime}(0)\right\rangle \leq \frac{\cosh \left(Q s_{0}\right)}{Q \sinh \left(Q s_{0}\right)}
$$

which means we can take a sequence of real numbers $s_{n} \rightarrow+\infty$, indexed by $n \in \mathbb{N}$, such that the sequence $\left\{\beta_{s_{n}}^{\prime}(0)\right\}$ is convergent with limit $v$. But then $\gamma^{s_{n}}\left(t_{s_{n}}\right) \rightarrow q \triangleq \exp _{p}(v)$ as $n \rightarrow+\infty$. Define $\beta_{n}=d_{s_{n}} \circ \tau_{s_{n}}$. The sequences $\left\{\beta_{n}\right\}_{n \in \mathrm{~N}}$ and $\left\{\beta_{n_{-}}\right\}_{n \in \mathrm{~N}}$ have unit speed, future directed limit curves $\xi_{1}$ and $\xi_{2}$. They are by definition corays to $\gamma_{1}$ and $\gamma_{2}$ respectively. For an appropriate sequence $\left\{n_{k}\right\}$ in $\mathbb{N}$ we have convergence of

$$
\beta_{n_{k}}^{\prime}(0), \quad \beta_{n_{k}-}^{\prime}(0)
$$

to $\xi_{1}^{\prime}(0)$ and $-\xi_{2}^{\prime}(0)$, which means that $\xi_{1}=\gamma$ is a future coray to $\gamma_{1}$, and $\gamma_{-}$is a past coray to $\gamma_{2}$. This proves the existence.

In the uniqueness proof we may assume $\sigma(0) \ll \gamma(0)$. Due to Lemma $4.1 \sigma(t) \ll \gamma(t)$ for all $t \in \mathbb{R}$ and for these values of $t$ we may then define

$$
f(t)=d(\sigma(t), \gamma(t))
$$

Since $f$ is concave, $f^{\prime}(t) \geq 0$ for all $t \in \mathbb{R}$. Let $\alpha_{t}$ denote the TF geodesic from $\sigma(t)$ to $\gamma(t)$ and define

$$
N(s)=\frac{\partial \alpha}{\partial t}(s, 0)+\left\langle\frac{\partial \alpha}{\partial s}, \frac{\partial \alpha}{\partial t}\right\rangle \frac{\partial \alpha}{\partial s}(s, 0)
$$

Using [5, p.374] we can estimate

$$
f^{\prime \prime}(0) \leq-Q^{2} \int_{0}^{f(0)}\langle N, N\rangle(s) d s
$$

where $\langle N, N\rangle(0)=-1+\left\langle\sigma^{\prime}(0), \frac{\partial \alpha}{\partial s}(0)\right\rangle^{2} \geq 0$. If this scalar product is nonzero, then $f^{\prime \prime}(0)<0$, leading to the existence of a $t_{1} \in \mathbb{R}$ with $f^{\prime}\left(t_{1}\right)>0$, in contradiction. We conclude that $\sigma^{\prime}(0)=\frac{\partial \alpha}{\partial s}(0)$ and hence

$$
\sigma(t+f(0))=\gamma(t)
$$

for all $t \in \mathbb{R}$. Hence the Proposition follows.

## 5. Hyperbolic isometries

Recall that the time orientation of our $C_{0}$ manifold $(M, g)$ is a timelike continuous vector field $X$ on $M$.

Definition 5.1. An isometry $\mu$ of $(M, g)$ is time orientation preserving provided

$$
\langle T \mu(X), X\rangle(\mu(p))<0
$$

for all $p$ in $M$.
Associated with a time orientation preserving isometry $\mu$ on $(M, g)$ is a natural map on $M^{+}(\infty)$ and $M^{-}(\infty)$ defined by

$$
\begin{array}{ll}
\mu_{+}: M^{+}(\infty) \rightarrow M^{+}(\infty), & {[\gamma]_{+} \rightarrow[\mu \circ \gamma]_{+}} \\
\mu_{-}: M^{-}(\infty) \rightarrow M^{-}(\infty), & {[\gamma]_{-} \rightarrow[\mu \circ \gamma]_{-} .}
\end{array}
$$

$\mu_{+}$and $\mu_{-}$have inverses $\mu^{-1}$ and $\mu^{-1}$.
Definition 5.2. A time orientation preserving isometry $\mu$ on ( $M, g$ ) is hyperbolic, provided there exists a $p$ in $M$ such that

$$
\begin{equation*}
\mu(p) \ll p \quad \text { or } \quad p \ll \mu(p) \tag{5.1}
\end{equation*}
$$

A timelike axis $\gamma$ of an isometry $\mu$ is a timelike TF geodesic or TP geodesic such that

$$
\mu \circ \gamma(t)=\gamma\left(t+d_{\mu}\right)
$$

for all $t \in \mathbb{R}$ and some $d_{\mu} \in \mathbb{R}_{+}$.
A null axis $\beta$ of an isometry $\mu$ is an NF geodesic or NP geodesic such that

$$
\mu \circ \beta(t)=\beta\left(\lambda t+d_{\mu}\right)
$$

for all $t \in \mathbb{R}$ and some $\lambda, d_{\mu} \in \mathbb{R}$.
Theorem 5.3. A hyperbolic isometry $\mu$ on a $C_{Q}$ manifold, $Q>0$, has a timelike axis.

Proof. Since $\mu$ is hyperbolic, there exists a $p \in M$ such that (5.1) holds. By considering $\mu^{-1}$ instead if necessary we can suppose that $p \ll \mu(p)$, hence

$$
p \ll \mu(p) \ll \ldots . \ll \mu^{n}(p) \ll \ldots
$$

By $c_{n}, n \geq 1$, we denote the TF geodesic through $c_{n}(0)=p$ and $\mu^{n}(p)$, and $d_{n}$ denotes the TF geodesic through $d_{n}(0)=\mu(p)$ and $\mu^{n}(p), n \geq 2$.

We claim that $\left\{c_{n}^{\prime}(0)\right\}_{n \geq 1}$ and $\left\{d_{n}^{\prime}(0)\right\}_{n \geq 2}$ are convergent sequences. To this end notice that

$$
r=d\left(\mu^{n}(p), \mu^{n+1}(p)\right)=d(p, \mu(p)), \quad n \geq 1,
$$

and define $s_{n} \triangleq d\left(p, \mu^{n}(p)\right), n \geq 1$. The timelike geodesic triangle $p \mu^{n}(p) \mu^{n+1}(p)$ gives us

$$
\begin{aligned}
& \cosh \theta_{i} \triangleq-A_{p} \leq-A_{p} Q \\
& \quad=\frac{-\cosh (Q r)+\cosh \left(Q s_{n}\right) \cosh \left(Q s_{n+1}\right)}{\sinh \left(Q s_{n}\right) \sinh \left(Q s_{n+1}\right)} \\
& \leq\left(1+2 \exp \left(-2 Q s_{n}\right)\right)^{2}\left(1+2 \exp \left(-2 Q s_{n+1}\right)\right)^{2} \\
& \leq 1+\alpha \exp (-2 Q n r) \triangleq 1+x_{n}
\end{aligned}
$$

for all $n$ greater than or equal to some $n_{0} \in \mathbb{N}$, because $s_{n} \geq n r$. Here $\theta_{i}$ is a nonnegative real number and $x_{n}, \alpha \in \mathbb{R}_{+}$. But then

$$
\begin{align*}
\sum_{n \geq n_{0}} \theta_{n} & \leq \sum_{n \geq n_{0}} \log \left(1+x_{n}+\left(\left(1+x_{n}\right)^{2}-1\right)^{\frac{1}{2}}\right) \\
& \leq \sum_{n \geq n_{n}} \log (1+\beta \exp (-n Q r))  \tag{5.2}\\
& \leq \sum_{n \geq 0} \beta \exp (-n Q r) \\
& =\beta \exp \left(-n_{0} Q r\right) /(1-\exp (-Q r))
\end{align*}
$$

for some sufficiently large positive $\beta$. Let $\Lambda_{p}^{+}$denote the future time cone in $T_{p} M$, and $T_{p}^{-1} M^{+}$the set of unit length future directed vectors in $T_{p} M$. According to [27, pp. 144 and 156],

$$
d^{+}: T_{p}^{-1} M^{+} \times T_{p}^{-1} M^{+} \rightarrow \mathbb{R}, \quad(x, y) \mapsto \cosh _{\mid \mathbb{R} \backslash \mathbb{R}_{-}}^{-1}(-\langle x, y\rangle)
$$

is well defined and a metric on $T_{p}^{-1} M^{+}$. Due to (5.2) the sequence $\left\{c_{n}^{\prime}(0)\right\}_{n \in \mathrm{~N}}$ is contained in the compact set

$$
\left\{w \in T_{p}^{-1} M^{+} \mid d^{+}\left(w, c_{1}^{\prime}(0)\right) \leq R\right\},
$$

when $R \in \mathbb{R}_{+}$is large enough. $d^{+}$induces a complete metric space structure on this set. According to (5.2), $\left\{c_{n}^{\prime}(0)\right\}_{n \in \mathrm{~N}}$ is a Cauchy sequence in this metric space and hence convergent as claimed. It follows that also $\left\{d_{n}^{\prime}(0)\right\}_{n \geq 2}$ is convergent.

By $c$ and $d$ we denote the TF geodesics with initial velocities

$$
\lim _{n \rightarrow+\infty} c_{n}^{\prime}(0) \text { and } \lim _{n \rightarrow+\infty} d_{n}^{\prime}(0)
$$

respectively. To show that $c$ and $d$ are future corays argue as in Lemma 4.1 to verify that $c(t) \ll d(t)$ for all $t>0$ and that there exists a positive real number $K$ such that

$$
d(c(t), d(t)) \leq K
$$

for all $t \geq 0$. Hence $[c]_{+}=[d]_{+}$. Notice that $d\left(p, \mu^{n}(p)\right) \geq n r$ by the reverse triangle inequality. By the definition of convergence in Chapter four we have

$$
\mu^{n}(p) \rightarrow_{p}[c]_{+} .
$$

Proposition 4.7 yields

$$
\mu^{n+1}(p) \rightarrow_{\mu(p)}[c]_{+}
$$

Since we also have

$$
\mu\left(\mu^{n}(p)\right) \rightarrow_{\mu(p)}[\mu \circ c]_{+},
$$

we deduce that $[c]_{+}$is a fixed point for $\mu_{+}$. Time orientation reversal produces a fixed point $[e]_{-}, e \in \Omega_{T P}$, for $\mu_{-}$. Proposition 4.8 asserts the existence of a TF geodesic $\gamma$ with $[\gamma]_{+}=[c]_{+}$and $\left[\gamma_{-}\right]_{-}=[e]_{-}$. This $\gamma$ is an axis for $\mu$ due to the uniqueness part in Proposition 4.8, i.e., $\mu \circ \gamma=\gamma \circ \tau_{d_{\mu}}$. To see that $d_{\mu}>0$ let $s_{*}$ denote the smallest real number such that $\gamma\left(s_{*}\right) \in J^{+}(p)$, hence $\gamma\left(s_{*}\right) \notin I^{+}(p)$. Since $p \ll \mu(p)$, we conclude that

$$
\gamma\left(s_{*}\right) \notin J^{+}(\mu(p)) .
$$

But $\mu \circ \gamma\left(s_{*}\right)=\gamma\left(s_{*}+d_{\mu}\right) \in J^{+}(\mu(p))$. Using [27, Corollary 14.1] we deduce that $d_{\mu}>0$, and the Theorem follows.

Example 5.4. The linear map with matrix representation

$$
\left(\begin{array}{ccc}
\cosh \phi \sinh \phi & 0 \\
\sinh \phi \cosh \phi & 0 \\
0 & 0 & 1
\end{array}\right), \quad \phi \in \mathbb{R}_{+}
$$

in the standard basis in $\mathbb{R}_{1}^{3}$ is an isometry of $\mathbb{R}_{1}^{3}$. The restriction of this isometry to $M_{Q}, Q>0$ is a hyperbolic isometry $\mu$. For appropriately chosen causally related points $p$ and $q$ a suitable conformal change of the metric on $I(p, q)$ and its translates by $\mu$ result in a nonconstantly curved $C_{Q}$ manifold with a hyperbolic isometry and $Q>0$.

## 6. Null colines

The concept null coline is crucial to the structure theorems in chapter 7. Their definition relies on Lemmas 6.1 and 6.2 to be derived. To this end let $\gamma_{1}$ and $\gamma_{3}$ be TF geodesics, and $\gamma_{2}$ an NF geodesic in a $C_{Q}$ manifold, $Q>0$. So $\gamma_{2}$ is a future directed complete null geodesic. The three geodesics $\gamma_{1}, \gamma_{2}$ and $\gamma_{3}$ form a nonspacelike geodesic triangle with vertices

$$
\begin{array}{ll}
\gamma_{1}(0)=p, & \gamma_{1}(a)=q \\
\gamma_{2}(0)=q, & \gamma_{2}(1)=r \\
\gamma_{3}(0)=p, & \gamma_{3}(c)=r
\end{array}
$$

Let us introduce the following notation:

$$
e=-\left\langle\gamma_{1}^{\prime}(a), \gamma_{2}^{\prime}(0)\right\rangle, \quad d=-\left\langle\gamma_{2}^{\prime}(1), \gamma_{3}^{\prime}(c)\right\rangle
$$

Then we have the following inequalities.

## Lemma 6.1.

$$
\begin{align*}
& \cosh (Q c) \leq \cosh (Q a)+Q e \sinh (Q a) \\
& 1 \leq \cosh (Q a) \cosh (Q c)+\sinh (Q a) \sinh (Q c) A_{p}  \tag{6.1,2,3}\\
& \cosh (Q a) \leq \cosh (Q c)-\sinh (Q c) Q d
\end{align*}
$$

Proof. According to [15, Corollary 2.5]. there are open neighbourhoods $U$ of $\gamma_{2}^{\prime}(0)$ and $V$ of $\gamma_{3}(c)$ such that

$$
F=\exp _{q \mid U} U \rightarrow V
$$

is a diffeomorphism. Define nonnegative reals $c_{s}$ and $d_{s}$ by

$$
\begin{aligned}
& c_{s}^{2}=-\left\langle\exp _{p}^{-1}\left(\gamma_{3}(s)\right), \exp _{p}^{-1}\left(\gamma_{3}(s)\right)\right\rangle \\
& d_{s}^{2}=-\left\langle F^{-1}\left(\gamma_{3}(s)\right), F^{-1}\left(\gamma_{3}(s)\right)\right\rangle
\end{aligned}
$$

for $s \geq c$. Looking at the timelike geodesic triangle $p, q=q_{s}, \gamma_{3}(s)$ we find that

$$
\sinh \left(Q d_{s}\right) A_{q_{s}} \rightarrow Q e
$$

for $s \rightarrow c$. Then Lemma 2.2 yields

$$
\cosh \left(Q c_{s}\right) \leq \cosh \left(Q d_{s}\right) \cosh (Q a)+\sinh \left(Q d_{s}\right) \sinh (Q a) A_{q_{s}}
$$

Convergence to $s=c$ leads to (6.1). (6.2) and (6.3) are similar.

Suppose we are given an NF geodesic and a point $p \in M$ such that $p \ll \beta\left(s_{*}\right), s_{*} \in \mathbb{R}$. We can then define $v_{s}$ by

$$
\begin{equation*}
\beta(s)=\exp _{p}\left(v_{s} d(p, \beta(s))\right) \tag{6.4}
\end{equation*}
$$

for $s \geq s_{*}$.
Lemma 6.2. There exists a $v \in T_{p}^{-1} M^{+}$such that

$$
d(p, \beta(s)) \rightarrow+\infty, \quad v_{s} \rightarrow v
$$

as $s \rightarrow+\infty$.
Proof. Letting $a=d\left(p, \beta\left(s_{*}\right)\right), B_{s}=\left\langle v_{s_{*}}, v_{s}\right\rangle$ and $c_{s}=d(p, \beta(s))$ for $s>s_{*}$ we find, in consequence of Lemma 6.1,

$$
\begin{aligned}
B_{s} & \geq-\cosh (Q a) \cosh \left(Q c_{s}\right) /\left[\sinh (Q a) \sinh \left(Q c_{s}\right)\right] \\
& \geq-\cosh ^{2}(Q a) / \sinh ^{2}(Q a)=K
\end{aligned}
$$

This follows from the fact that $s \mapsto c_{s}$ is smooth for $s>s_{*}$ with

$$
\frac{d}{d s} c_{s}=-\left\langle\beta^{\prime}(s), T_{v_{s}} \exp _{p}\left(v_{s}\right)\right\rangle
$$

We can then take a sequence $\left\{s_{k}\right\}_{k \in \mathbb{N}}, s_{k} \geq s_{*}$ such that $v_{s_{k}}$ converges to some $v \in T_{p} M$ as $k \rightarrow+\infty$. If the Lorentzian distance from $p$ to $\beta(s)$ were bounded by some $d$ we would have

$$
\begin{aligned}
& \beta\left(s_{k}\right) \in \exp _{p}(C) \\
& C=\left\{s w \mid w \in T_{p}^{-1} M^{+}, K \leq\left\langle w, v_{s_{*}}\right\rangle \leq-1,0 \leq s \leq d\right\}
\end{aligned}
$$

for all $k$ larger than some $k_{0} \in \mathbb{N}$. This however contradicts [27, 14.13] because $\beta$ is future inextendible and ( $M, g$ ) is strongly causal by Remark 2.3.

To show the second statement in this lemma use Lemma 6.1 in the estimate

$$
\left\langle v_{t_{1}}, v_{t_{2}}\right\rangle \geq-\cosh \left(Q c_{t_{1}}\right) \cosh \left(Q c_{t_{2}}\right) /\left(\sinh \left(Q c_{t_{1}}\right) \sinh \left(Q c_{t_{2}}\right)\right)
$$

Given $K \leq-1$, the right-hand side is greater than or equal to $K$ for all $t_{1}, t_{2}$ larger than some $t_{*}$. This means that $\left\{v_{s}\right\}_{s \geq s_{*}}$ is a Cauchy net in the metric space

$$
T_{p}^{-1} M^{+}=\left\{w \in T_{p} M \mid\langle w, w\rangle=-1,\left\langle v_{s_{*}}, w\right\rangle<0\right\}
$$

with metric

$$
d(v, w)=\cosh _{\mathbb{R}-\mathbb{R}_{-}}^{-1}(\langle v, w\rangle), \quad v, w \in T_{p}^{-1} M^{+}:
$$

cf. [27, p.156]. From this the second statement in the lemma follows.
Definition 6.3. The NF geodesic $\beta$ is a future null coline to the TF geodesic $\gamma$ through $\gamma(0)=p$, provided

$$
\lim _{s \rightarrow+\infty} v_{s}=\gamma^{\prime}(0)
$$

Fortunately, we have
Proposition 6.4. If $\beta$ is a future null coline to $\gamma$, then $\beta$ is a future null coline to any TF geodesic $\sigma$, which is a future coray to $\gamma$.

Proof. According to Lemma 6.2 and the definitions,

$$
\beta(n) \rightarrow_{p} \omega \triangleq[\gamma]_{+}
$$

as $n \rightarrow+\infty$, where $p=\gamma(0)$. Proposition 4.7 tells us that

$$
\beta(n) \rightarrow_{q} \omega=[\sigma]_{+}
$$

as $n \rightarrow+\infty$ where now $q=\sigma(0)$. Thus the proposition follows.

## 7. Structure theorems

The future null cone in a $C_{Q}$ manifold $M$ of a point $p \in M$ is by definition

$$
\begin{equation*}
K^{+}(p)=\left\{q \in M \mid p<q, q \notin I^{+}(p)\right\} \tag{7.1}
\end{equation*}
$$

Also define

$$
\begin{equation*}
\mathbb{D}^{+}=\left\{(p, q) \in M \times M \mid p<q, q \notin I^{+}(p)\right\} \tag{7.2}
\end{equation*}
$$

We shall show that (7.1) and (7.2) are $C^{\infty}$ submanifolds of $M$ and $M \times$ $M$ respectively. $K^{+}(p)$ is degenerate of constant signature ( $0,+, \ldots,+$ ). This will imply that the square of the Lorentzian distance function is smooth on

$$
\begin{equation*}
C^{+}=\{(p, q) \in M \times M \mid p \leq q\} \tag{7.3}
\end{equation*}
$$

We start with
Lemma 7.1. Suppose $q=\exp _{p}(v)$ for some future directed null vector $v \in T_{p} M$ in a $C_{Q}$ manifold $(M, g), Q \geq 0$. Then $q \notin I^{+}(p)$.

Proof. Assume for contradiction that $p \ll q$. According to Lemma 2.1 there exists a TF geodesic $\gamma$ from $p$ to $q=\gamma(a), a \in \mathbb{R}_{+}$. Take open neighbourhoods $U$ around $v$ in $\mathbb{D}\left(\exp _{p}\right)$ and $V$ around $q$ such that the restriction of $\exp _{p}$ to $U$ is a diffeomorphism onto $V$. An open interval $I$ around $a$ is mapped by $\gamma$ into $V$. Define

$$
\begin{aligned}
\sigma: I & \rightarrow T_{p} M, \quad t \mapsto \exp _{p \mid U}^{-1} \circ \gamma(t) \\
f(t) & =\langle\sigma(t), \sigma(t)\rangle, \quad t \in I
\end{aligned}
$$

Notice that $a \gamma^{\prime}(0) \notin U$, since this would imply that the timelike vector $a \gamma^{\prime}(0)$ is equal to the null vector $v$. Since the scalar product

$$
\left\langle\gamma^{\prime}(a), T_{\sigma(a)} \exp _{p}(\sigma(a))\right\rangle=\frac{1}{2} f^{\prime}(a)
$$

of two future directed nonspacelike vectors is negative, there exists a positive $t \in I$ such that $\sigma(t) \neq t \gamma^{\prime}(0)$ is a timelike future directed vector. But this means that

$$
\exp _{p}(\sigma(t))=\gamma(t)=\exp _{p}\left(t \gamma^{\prime}(0)\right)
$$

contradicting Lemma 2.1.
We continue with a lemma, involving

$$
\begin{equation*}
\Lambda^{0+}=\{w \in T M \mid\langle w, w\rangle \leq 0,\langle w, X\rangle \leq 0\} \tag{7.4}
\end{equation*}
$$

Dually $\Lambda^{0-}$ consists of the set of $w$ in $T M$ such that $-w \in \Lambda^{0+}$.
Lemma 7.2. Let $v$ be a future directed null vector in a $C_{Q}$ manifold, $Q \geq 0$. Then there exists an open neighbourhood $W$ around $v$ in $\mathbb{D}(E)$ such that

$$
\begin{equation*}
E(w) \notin \mathbb{C}_{*}^{+}=\{(p, q) \in M \times M \mid p<q\} \tag{7.5}
\end{equation*}
$$

for any $w \in W \backslash \Lambda^{0+}$.
Proof. Take a timelike future directed vector

$$
w=T_{v} \exp _{p}(z)
$$

where $p=\pi(v)$. Let $Y$ denote a smooth vector field on an open neighbourhood $\mathbb{D}(Y)$ of $z$ in $T M$ with $Y(v)=z$. We can assume that $T \pi(Y) \equiv 0$. Since

$$
\Lambda^{0}=\{x \in T M \mid x \text { is a future directed null vector }\}
$$

is a hypersurface in $T M$, we can take a local flow

$$
\Phi:]-\epsilon, \epsilon[\times U \rightarrow \mathbb{D}(Y)
$$

for $Y$ around $v$ and adapted to $\Lambda^{0}$. Since $Y(v)=z$, we can assume that

$$
\left.\exp \circ \Phi_{w}:\right]-\epsilon, \epsilon[\rightarrow M
$$

is a smooth timelike future directed curve for all $w \in U$, by taking a smaller $U$ and $\epsilon>0$ if necessary. We can now define $F$ to be the restriction of $\Phi$ to $]-\epsilon, \epsilon\left[\times \Lambda_{U}^{0}\right.$, where $\Lambda_{U}^{0}=\Lambda^{0} \cap U$. By adjusting the domain of definition we can assume that $F$ is a diffeomorphism, because $T_{(0, v)} F$ is an isomorphism. In fact $Y(v) \notin T_{v} \Lambda^{0}$ due to the fact that $Y(v)=z ;$ cf. [13, Proposition 2.2]. If the domain of definition of $F$ is sufficiently small, the restriction of

$$
E: \mathbb{D}(E) \rightarrow M \times M, \quad v \mapsto(\pi(v), \exp (v))
$$

to $W=\operatorname{Im} F$ will be a diffeomorphism onto its open image; cf. [13, Proposition 2.1].

Suppose $w \in W \backslash \Lambda^{0+}$, that is $w=F(t, u),(t, u) \in \mathbb{D}(F)$. By construction $F_{u}$ is a smooth timelike future directed curve in $T_{q} M, q=$ $\pi(w)$. If $t$ was nonnegative, using the causality relations in $T_{q} M$ we would have

$$
0_{q}<u \quad \begin{cases}=F(t, u), & t=0 \\ \ll F(t, u), & t>0\end{cases}
$$

Consequently $w$ is in the causal future $J^{+}\left(0_{q}\right)$ of the zero vector $0_{q}$ in $T_{q} M$. This contradicts the fact that $w \in W \backslash \Lambda^{0+}$. Thus $t<0$. If $(x, y)=E(w)$ was in $\mathbb{C}_{*}^{+}$, we would have

$$
x<y=\exp (F(t, u)) \ll \exp (F(0, u))=\exp (u),
$$

contradicting Lemma 7.1. Consequently $E(w) \notin \mathbb{C}_{*}^{+}$and the lemma follows.

From Lemmas 7.1 and 7.2 we deduce
Proposition 7.3. The square of the Lorentzian distance function $d^{2}: M \times M \rightarrow \mathbb{R}$ is smooth on $C^{+}$.

Proof. Let us first consider $(p, q)=\left(p, \exp _{p}(v)\right) \in \mathbb{D}^{+} \subset C^{+}$, where $v \in \Lambda^{0}$. Take an open neighbourhood $W$ around $v$ in $T M$ such that the restriction of $E$ to $W$ is a diffeomorphism onto its open image and such that (7.5) holds. A careful choice of $W$ ensures that $E(W)$ has empty intersection with the diagonal in $M \times M$. Define a smooth function $F$ on $E(W)$ by

$$
\begin{equation*}
F(x, y)=-\langle w, w\rangle \quad, \quad w=E_{\mid W}^{-1}(x, y) \tag{7.6}
\end{equation*}
$$

If $(x, y) \in C^{+} \cap E(W)$, then by [ 5, Theorem 10.16] we have

$$
\begin{equation*}
d(x, y)^{2}=F(x, y) \tag{7.7}
\end{equation*}
$$

whenever $x \ll y$. We can obtain (7.7) by (7.5) when $x<y, y \notin I^{+}(x)$. The remaining cases $p \ll q$ and $p=q$ follow from the openness of $\ll$, the strong causality of $(M, g)$ and [5, Theorem 10.16].

Given a point $p$ in a $C_{Q}$ manifold $(M, g), Q \geq 0$, we can now prove
Theorem 7.4. $\mathbb{D}^{+}$and $K^{+}(p)$ are $C^{\infty}$ hypersurfaces of $M \times M$ and $M$ respectively. The metric induced on $K^{+}(p)$ has constant signature ( $0,+, \ldots,+$ ).

Proof. If $(p, q) \in \mathbb{D}^{+}$, then according to [27, p. 404], there exists a future directed null vector $v \in T_{p} M$ such that $q=\exp _{p}(v)$. By Lemma 7.2 there exists an open neighbourhood $W$ around $v$ such that the restriction of $E$ to $W$ is a diffeomorphism onto its open image and

$$
\begin{equation*}
E(w) \notin \mathbb{C}_{*}^{+}, \tag{7.8}
\end{equation*}
$$

whenever $w \in W \backslash \Lambda^{0+}$. We claim that

$$
\begin{equation*}
E\left(W \cap \Lambda^{0}\right)=E(W) \cap \mathbb{D}^{+} \tag{7.9}
\end{equation*}
$$

The left-hand side is a subset of the right-hand side according to Lemma 7.1. The reverse inclusion follows from (7.8). Combining (7.9) with the fact that $\Lambda^{0}$ is a hypersurface in $T M$ we conclude that $\mathbb{D}^{+}$is a hypersurface in $M \times M$.

To show that the smooth submanifold $M(p)=\{p\} \times M$ of $M \times M$ is transversal to $\mathbb{D}^{+}$take $(p, q)=E(v), \quad v \in \Lambda^{0}$ and observe that

$$
T_{(p, q)} \mathbb{D}^{+}+T_{(p, q)} M(p)=T_{v} E\left(T_{v} \Lambda^{0}+T_{v} i\left(T_{p} M\right)\right)
$$

where $i: T_{p} M \rightarrow T M$ denotes the inclusion. If we define $\alpha(t)=v+t w$ for some timelike $w \in T_{\pi(v)} M$, then $T_{v} i\left(\alpha^{\prime}(0)\right) \notin T_{v} \Lambda^{0}$. Thus $\mathbb{D}^{+}$is transversal to $M(p)$. It follows that

$$
\mathbb{D}^{+} \cap M(p)=\{p\} \times K^{+}(p)
$$

is a smooth submanifold of $M \times M$. A codimension count shows that $K^{+}(p)$ is a $C^{\infty}$ hypersurface of $M$.

The squared Lorentzian distance function $f$ is smooth on $C^{+}$by Proposition 7.3 and

$$
T_{q} K^{+}(p)=\operatorname{grad} f_{p}(q)^{\perp}
$$

Since grad $f_{p}(q)$ is null, the last statement of the lemma follows.
Lemma 7.5. $C^{+}$is closed.
Proof. Let $(p, q) \in M \times M$ denote the limit point of some sequence $\left\{\left(p_{n}, q_{n}\right)\right\}_{n \in \mathbf{N}}$ from $C^{+}$, converging in $M \times M$. To show that $(p, q)$ belongs to $C^{+}$take $r \in M$ such that $p, q \in I^{-}(r)$. According to Proposition 7.3 there exist an $n_{0} \in \mathbb{N}$ and $K>0$ such that $p_{n} \ll r$ and $c_{n}=d\left(p_{n}, r\right) \geq K$ for all $n \geq n_{0}$. Let $\beta_{n}$ and $\gamma_{n}$ denote nonspacelike or constant geodesics from $p_{n}$ to $q_{n}=\beta_{n}(1)$ and $r=\gamma_{n}\left(c_{n}\right)$ respectively. It follows from Lemmas 2.1 and 6.1 that

$$
\begin{equation*}
-\left\langle\beta_{n}^{\prime}(0), \gamma_{n}^{\prime}(0)\right\rangle \tag{7.1}
\end{equation*}
$$

is bounded above by some $C>0$ for all $n \geq n_{0}$. We can assume that the sequence $\left\{p_{n}\right\}_{n \geq n_{0}}$ belongs to the domain of some orthonormal frame $E_{1}, \ldots, E_{n}$ with $E_{1}$ timelike, future directed, and write

$$
v_{n}=\beta_{n}^{\prime}(0)=\sum_{i} \lambda_{i} E_{i} \quad w_{n}=\gamma_{n}^{\prime}(0)=\sum_{i} \mu_{i} E_{i}
$$

We have an upper bound $D$ on $\mu_{1}$ since $w_{n}$ is a convergent sequence. We can now use (7.10) and the Schwartz inequality to get

$$
\lambda_{1} \mu_{1} \leq C+\lambda_{1}\left(\mu_{1}^{2}-1\right)^{\frac{1}{2}}
$$

and hence

$$
\lambda_{1}^{2}-2 C \lambda_{1}\left(D^{2}-1\right)^{\frac{1}{2}}-C^{2} \leq 0
$$

This shows that there is an upper bound to the absloute value of the $\lambda_{i}$. A subsequence $\left\{v_{n_{k}}\right\}$ of $\left\{v_{n}\right\}$ will then converge to some nonspacelike or zero vector $v$ showing that $(p, q)=\left(p, \exp _{p}(v)\right) \in C^{+}$.

Lemma 7.6. $F: \Lambda^{0+} \rightarrow C^{+} v \mapsto(\pi(v), \exp (v))$ is a homeomorphism.

Proof. To prove injectivity suppose that $F\left(v_{1}\right)=F\left(v_{2}\right)$, so that $p=\pi\left(v_{1}\right)=\pi\left(v_{2}\right)$. If $v_{1}$ and $v_{2}$ are timelike, then $v_{1}=v_{2}$ by Lemma 2.1. $v_{1}=0$ and $v_{2}$ nonspacelike contradicts the strong causality of $(M, g) . v_{1}$ timelike and $v_{2}$ null is impossible by Lemma 7.1. It remains to consider the case, where $v_{1}$ and $v_{2}$ are both null vectors. To this end define $\beta_{i}(s)=\exp _{p}\left(s v_{i}\right), i=1,2$ and observe that

$$
\beta_{i}^{\prime}(1) \in T_{\beta_{1}(1)} K^{+}(p)
$$

It follows from Theorem 7.4 that $\beta_{1}^{\prime}(1)=\beta_{2}^{\prime}(1) \lambda$ for some $\lambda \neq 0$. The strong causality of $(M, g)$ implies that $\lambda=1$, so that $v_{1}=v_{2}$.

Since $F$ is onto by [27, p. 402] we conclude that $F$ is a bijection with inverse $G$. Due to Lemma 2.1, $G$ is smooth on some open neighbourhood of the image by $F$ of any timelike future directed vector.

1) We now insist that $G$ is smooth in the image by $F$ of some zero vector $v \in \Lambda^{0+}$ by taking an open neighbourhood $V$ around 0 in $T M$. We shall require that $0_{\pi(v)} \in V$ whenever $v \in V$ and also that the restriction of $E$ to $V$ is a diffeomorphism onto its open image. Take a causally convex open neighbourhood $U$ of $\pi(v)$ such that $U \times U \subset$ $E(V)$ and define $W=E_{\mid V}^{-1}(U \times U)$.

Suppose $\exp (w) \in J^{+}(\pi(w))$ for some $w \in W$. By definition this means that either $w=0$ or there exists some smooth nonspacelike curve $\alpha:[0, a] \rightarrow M$ from $\alpha(0)=\pi(w)=q$ to $\exp _{q}(w)=\alpha(a) \neq q$. Since $U$ is causally convex we can define

$$
\beta(t)=E_{\mid W}^{-1}(q, \alpha(t)), \quad t \in[0, a]
$$

which is a smooth curve in the future causal cone of $T_{q} M$ by [27, Lemma 5.33], hence $\beta(a)=w \in \Lambda^{0+}$. We have shown

$$
\begin{equation*}
E(w) \notin C^{+} \tag{7.11}
\end{equation*}
$$

when $w \in W \backslash \Lambda^{0+}$.
2) Around any null vector $v$ there is an open neighbourhood $W$ in $\mathbb{D}(E)$ such that (7.11) holds and such that the restriction of $E$ to $W$ is a diffeomorphism onto its open image. This follows from Lemma 7.2.

In both cases the restriction of $G$ to $E(W) \cap C^{+}$coincides with the restriction of $E_{\mid W}^{-1}$ to $E(W) \cap C^{+} . G$ is hence smooth in the image by $F$ of any null or zero vector. The lemma follows.

Theorem 7.7. Let $\omega=[\gamma]_{+}$and $\alpha=\left[\gamma_{-}\right]_{-}$belong to the timelike future $M^{+}(\infty)$ and the timelike past $M^{-}(\infty)$ of a $C_{Q}$ manifold $(M, g)$ with $Q>0$. Then the following hold:

1) $\partial I^{-}(\omega)\left(\partial I^{+}(\alpha)\right)$ is a $C^{1}$ hypersurface in $M$ of constant signature $(0,+, \ldots,+)$. Through every point in $\partial I^{-}(\omega)$ there is a future null coline $\beta$ to $\gamma$.
2) The intersection $\partial I^{-}(\omega) \cap \partial I^{+}(\alpha)$ is a $C^{1}$ Riemannian manifold of dimension $\operatorname{dim} M-2$.

Proof. To prove 1) for any $\omega=[\gamma]_{+} \in M^{+}(\infty)$, suppose $x \in \partial I^{-}(\omega)$.
We claim that there exists a future null coline $\beta$ to $\gamma$ through $\beta(0)=$ $x$. To this end let $\zeta$ denote some TF geodesic through $\zeta(0)=x . \zeta(t)$ is in $I^{-}(\gamma)$ for $t<0$ because then $I^{+}(\zeta(t))$ is an open neighbourhood of $x$. For a suitable increasing sequence $\left\{u_{n}\right\}$ converging to 0 , the sequence $v\left(u_{n}\right)$ with

$$
v(u) \triangleq-V \circ \zeta(u) /\left\langle V, \zeta^{\prime}\right\rangle, \quad u<0
$$

will converge to some $v \in T_{x} M$. Here $V$ denotes the vector field, that assigns to each $x \in I^{-}(\gamma)$ the tangent vector to the future coray from $x$ to $\gamma$. We need to know that for every $t>0$ such that $x \notin J^{+}(\gamma(t))$, the set

$$
K_{t}=I^{-}(\omega) \cap\left(K^{+}(\gamma(t)) \cup\{\gamma(t)\}\right)
$$

is contained in a compact set, $C_{t}$ say. But to any $q \in K_{t}$ there exists an NF geodesic $\beta$ from $\gamma(t)$ to $q$. Since $q \in I^{-}(\omega)$ there is a TF geodesic $\sigma$ from $q$ to some $\gamma(t+c)=\sigma(a)$ with $\cosh (Q c) / \sinh (Q c) \leq 2$. The existence of a compact set $C_{t}$ containing $K_{t}$ now follows from Lemma 6.1 showing that

$$
-\left\langle\beta^{\prime}(0), \gamma^{\prime}(t)\right\rangle \leq(\cosh (Q c)-\cosh (Q a)) / Q \sinh (Q c) \leq 2 / Q
$$

For every $u<0$ there exists an $s_{u}>0$ such that

$$
\exp \left(s_{u} v(u)\right) \in I^{+}(\gamma(t+1))
$$

and hence also a $t_{u} \in\left[0, s_{u}[\right.$ such that

$$
q_{u}=\exp \left(t_{u} v(u)\right) \in K_{t+1}
$$

If $D$ is a compact neighbourhood of $x$, then for all $u<0$ sufficiently close to 0 , we have

$$
t_{u} v(u)=F^{-1}\left(\zeta(u), q_{u}\right) \in F^{-1}\left(\left(D \times C_{t+1}\right) \cap C^{+}\right)
$$

This set is compact by Lemma 7.5 and Lemma 7.6. This means that the convergence of $\left\{t_{u_{n}} v\left(u_{n}\right)\right\}_{n \in \mathrm{~N}}$ to some $w$ can be assumed by taking a subsequence of $\left\{u_{n}\right\}$ if necessary. The nonspacelike geodesic $\beta(s)=$ $\exp _{x}(s w)$ is then in $I^{+}(\gamma(t))$ for all $s \geq 1$. Looking at the timelike geodesic triangle $\gamma(0) \gamma(t) \beta(s)$ with side lengths $t, c$ and $b$ we find

$$
\begin{aligned}
\left\langle c_{s}^{\prime}(0), \gamma^{\prime}(0)\right\rangle & =(\cosh (Q c)-\cosh (Q b) \cosh (Q t)) /[\sinh (Q b) \sinh (Q t)] \\
& \geq-\cosh ^{2}(Q t) / \sinh ^{2}(Q t)
\end{aligned}
$$

Here $c_{s}$ is the TF geodesic from $c_{s}(0)=\gamma(0)$ to $c_{s}(b)=\beta(s)$. Since $x \notin I^{-}(\omega)$ we infer that $\beta$ is a future null coline to $\gamma$ through $x$, thereby proving the claim. Notice that $\sigma(s) \in \partial I^{-}(\omega)$ for all $s \in \mathbb{R}$, due to the convergence of $\left\{t_{u_{n}} v\left(u_{n}\right)\right\}$ to $w$.

Define $p=\beta(s), q=\beta(-s)$ and $f_{s}: J^{-}(\beta(s)) \rightarrow \mathbb{R}$ by

$$
f_{s}(y)=d(y, \beta(s))
$$

for $s>0$. Take some $z \in I^{+}(p)$. Since $z \gg x$, there exists some past directed timelike vector $v$ in $T_{z} M$ such that $\gamma_{v}\left(t_{*}\right)=x$ for some $t_{*}>0$. We shall now prove a sequence of four claims, leading to a proof of the first statement.

First claim. We claim the existence of an open neighbourhood $U$ of $v$ in the set $T_{z}^{-1} M^{-}$of past directed timelike unit vectors in $T_{z} M$ and a $C^{\infty}$ function $t_{s}$ on $U$ such that $t_{s}(v)=t_{*}$ and for all $w$ in $U$ we have

$$
\gamma_{w}\left(t_{s}(w)\right) \in J^{-}(\beta(s)), \quad f_{s}\left(\gamma_{w}\left(t_{s}(w)\right)\right)=0
$$

To see this take an open neighbourhood $V$ of $-s \beta^{\prime}(s)$ in $T M \backslash \Lambda^{0+}$ such that the restriction of $\exp _{p}$ to $V$ is a diffeomorphism onto its open image
 Define

$$
g_{s}(y)=-\langle w, w\rangle \quad, \quad w=\exp _{p \mid V}^{-1}(y)
$$

for $y \in \exp _{p}(V)$. For some open neighbourhood $\Omega$ of $\left(v, t_{u}\right)$ in $T_{z}^{-1} M^{-} \times$ $\mathbb{R}, \exp _{z}(w t) \in \exp _{p}(V)$ for all $(w, t) \in \Omega$. The claim now follows from an application of the inverse function theorem to the function

$$
G_{s}: \Omega \rightarrow \mathbb{R}, \quad(t, w) \mapsto g_{s}\left(\exp _{z}(w t)\right)
$$

Second claim. For all $w \in U$ and all $u>s$ there exists a unique $t_{u}(w) \in\left[0, t_{s}(w)\right]$ such that

$$
\begin{equation*}
\gamma_{w}\left(t_{u}(w)\right) \in J^{-}(\beta(u)), \quad f_{u}\left(\gamma_{w}\left(t_{u}(w)\right)\right)=0 \tag{7.12}
\end{equation*}
$$

Notice that $\gamma_{w}\left(t_{s}(w)\right) \in J^{-}(\beta(s)) \subset J^{-}(\beta(u))$; cf. [27, 14.1 and 14.6]. This means that

$$
t_{u}(w)=\inf \left\{t \in\left[0, t_{s}(w)\right] \mid \gamma_{w}(t) \in J^{-}(\beta(u))\right\}>0
$$

satisfies (7.12). If some $t \in] 0, t_{u}(w)[$ also satisfies the claim, then

$$
\gamma_{w}\left(t_{u}(w)\right) \ll \gamma_{w}(t)<\beta(u)
$$

Consequently $\gamma_{w}\left(t_{u}(w)\right) \in I^{-}(\beta(u))$. Since this is untrue, the uniqueness of $t_{u}(w)$ follows.

Third claim. The function $u \mapsto t_{u}(w)=t_{w}(u)>0, u>s$ is decreasing, hence convergent.

This follows from the above definition of $t_{u}(w)$ and the fact that $J^{-}\left(\beta\left(u_{1}\right)\right) \subset J^{-}\left(\beta\left(u_{2}\right)\right)$, whenever $s<u_{1}<u_{2}$.

We can now define a function $t$ on $U$ by declaring

$$
t(w)=\inf _{u \geq s} t_{u}(w), \quad w \in U
$$

Clearly $r=\gamma_{w}(t(w)) \in$ closure $I^{-}(\omega)$; cf. [27, 14.6 (2)]. Assume for contradiction that $r \in I^{-}(\omega)$; i.e., $r \ll \gamma(a)$ for some $a \in \mathbb{R}$. Since $\beta$ is a null coline to $\gamma, \beta(b) \in I^{+}(\gamma(a))$ for some $b>s$. Define

$$
A=\left\{t \in[0, t(w)] \mid \exp _{z}(t w) \in J(r, \beta(b))\right\}
$$

which is closed by global hyperbolicity of $(M, g)$. Hence $t_{*} \in A$, where $t_{*}=\inf A \in[0, t(w)[$. Since $\ll$ is open,

$$
\exp \left(t_{*} w\right) \in J^{-}(\beta(b)), \quad f_{b}\left(\exp \left(t_{*} w\right)\right)=0
$$

contradicting the definition of $t(w)$. Thus $r=\gamma_{w}(t(w)) \in \partial I^{-}(\omega)$.
Fourth claim. $t$ is $C^{1}$.
To see that $t$ is differentiable in $w \in U$ define $y=\exp _{z}(w t(w)) \in$ $\partial I^{-}(\omega)$. We know that there exists a future null coline $\beta_{y}$ to $\gamma$ through $\beta_{y}(0)=y$. Take some $s>0$ and some $z \in I^{+}\left(\beta_{y}(s)\right)$. According to the first claim and its past dual around any $w \in U$ there exist an open neighbourhood $U_{w}$ of $w$ and $C^{\infty}$ functions $t^{+}$and $t^{-}$such that $t^{+}(w)=t^{-}(w)=t(w)$ and

$$
\gamma_{u}\left(t^{+}(u)\right) \in K^{-}\left(\beta_{y}(s)\right), \quad \gamma_{u}\left(t^{-}(u)\right) \in K^{+}\left(\beta_{y}(-s)\right)
$$

for all $u \in U_{w}$. Since $\gamma_{u}\left(t^{+}(u)\right) \in J^{-}\left(\beta_{y}(s)\right) \subset$ closure $I^{-}(\omega), \quad t^{+}(u) \geq$ $t(u)$.

Lemma 14.1 in [27] tells us that there is no $t \geq 0$ such that $\beta_{y}(t) \in$ $I^{-}(\omega)$. This will not happen for a negative $t$ either according to Lemma 7.1. Using $[27,14.1]$ once more we deduce that $\gamma_{u}\left(t^{-}(u)\right) \notin I^{-}(\omega)$ and hence $t^{-}(u) \leq t(u)$. From the fact that $t^{-}(w)=t(w)=t^{+}(w)$ it follows that $t$ is differentiable.

To see that $t$ is $C^{1}$ in $w \in U$ let $s$ denote a $C^{\infty}$ function on an open neighbourhood $\Omega$ of $\left(w, \beta_{y}(1)\right)$ in $T_{z}^{-1} M^{-} \times M$ such that $s(w, y)=t(w)$ and

$$
\gamma_{v}(s(v, x)) \in K^{-}(x)
$$

for every $(v, x) \in \Omega$. Give some open neighbourhood $W$ of $y$ in $\partial I^{-}(\omega)$ a Riemannian metric $h$. The tangent vectors to differentiable curves through $q$ in $W$ span a subspace

$$
A_{q}=T_{q} K^{-}\left(\beta_{y}(1)\right)
$$

in $T_{q} W$. It has signature $(0,+, . .,+)$ according to Theorem 7.4. We can then define a vector field $X$ on $W$. The value of $X$ at $q$ is the unique future directed null vector of unit Riemannian length in $A_{q}$. Notice that $\beta_{X(q)}$ is a future null coline to $\gamma$ for all $q \in W$.

If $X$ is not continuous at some $q \in W$, there exists a sequence $\left\{q_{n}\right\}$ in $W$ such that $\left\{q_{n}\right\}$ and $\left\{X\left(q_{n}\right)\right\}$ converge to $q$ and $Y_{q} \neq X(q)$ respectively. For some $s<0, \beta_{Y(q)}(s) \in I^{-}(\omega)$, because $Y(q)$ and $X(q)$ are linearly independant null vectors and $\beta_{X(q)}(1) \in \partial I^{-}(\omega)$. Continuity of the geodesic flow implies that

$$
\beta_{X\left(q_{n}\right)}(s) \in I^{-}(\omega)
$$

for some sufficiently large $n$. This contradicts Lemma 7.1. Thus

$$
\left.v \mapsto d t_{v}=d s_{\left(v, \beta_{\boldsymbol{X}}\left(\exp _{\mathbf{z}}(t(v) v)\right)\right.}(1)\right)
$$

is continuous.
The $\operatorname{map} w \mapsto \exp _{z}(w t(w))$ from $U$ to $\partial I^{-}(\omega)$ gives rise to a chart in a $C^{1}$ submanifold structure on $\partial I^{-}(\omega)$. The tangent space to $\partial I^{-}(\omega)$ at $x \in \partial I^{-}(\omega)$ coincides with the tangent space to $K^{-}\left(\beta_{x}(s)\right)$, where $\beta_{x}$ is a future null coline to $\gamma$ through $x$ and $s>0$. Theorem 7.3. now tells us that $\partial I^{-}(\omega)$ has constant signature $(0,+, \ldots,+)$.
2) To verify that $\partial I^{-}(\omega) \cap \partial I^{+}(\alpha)$ is nonempty let $\sigma$ denote some TF geodesic with $\sigma(0)=\gamma(0)$ and

$$
A=\left\langle\sigma^{\prime}(0), \gamma^{\prime}(0)\right\rangle \neq-1
$$

Choose $t>0$ subject to the requirement

$$
A^{2}-\cosh ^{2}(Q t) / \sinh ^{2}(Q t)>0
$$

The reverse triangle inequality shows that we can find some $s_{*}$ such that $\sigma\left(s_{*}\right) \in J^{-}(\gamma(t)) \backslash I^{-}(\gamma(t))$. Using Lemma 6.1 we derive

$$
\begin{equation*}
\left(\cosh ^{2}(Q s)-1\right) \sinh ^{2}(Q t) A^{2} \leq(\cosh (Q t) \cosh (Q s)-1)^{2} \tag{7.13}
\end{equation*}
$$

We conclude that $\cosh (Q s) \leq K$ for some positive $K$ regardless of the value of $t$. It follows that $y=\sigma\left(s^{*}\right) \in \partial I^{-}(\omega)$ for some $s^{*}>0$. We have seen that there exists a future null coline $\beta_{y}$ to $\gamma$ through $\beta_{y}(0)=y$ and that the counter image by the restriction of $\exp _{y}$ to $\Lambda^{0-}(y)=\Lambda^{0-} \cap T_{y} M$ of $K^{-}(y) \cap I^{+}(\alpha)$ is contained in some compact set in $T_{y} M$. We can then find a $t_{*}<0$ such that

$$
x=\beta_{y}\left(t_{*}\right) \in \partial I^{+}(\alpha) \cap \partial I^{-}(\omega)
$$

Combining Proposition 4.8. and Lemma 7.1 we see that $\beta_{y}^{\prime}\left(t_{*}\right)$ cannot belong to the tangent space to $\partial I^{+}(\alpha)$ at $x$, because the signature of this vector space is $(0,+, . .,+)$. We conclude that $\partial I^{-}(\omega)$ and $\partial I^{+}(\alpha)$ have nonempty transversal intersection in a $C^{1}$ submanifold $N$ of $M$. There is also a past null coline $\beta_{x}$ through $x$ to $\gamma_{-} . N$ is Riemannian because

$$
\beta_{y}^{\prime}\left(t_{*}\right)-\beta_{x}^{\prime}(0)
$$

is a timelike vector orthogonal to $T_{x} N$. Hence the Theorem follows.
Example 7.8. There are $C_{Q}$ Robertson Walker spacetimes of nonconstant sectional curvature $Q>0$. In fact let $g_{Q}$ denote the metric on $M_{Q} \subset \mathbb{R}^{n+1}$, and $f_{Q}$ the restriction to $M_{Q}$ of a smooth function $f$ on $\mathbb{R}^{n+1}$, depending only on the first coordinate. With a suitable choice of $f$ the timelike sectional curvatures of $\left(M_{Q}, f_{Q} g_{Q}\right)$ will be bounded below from zero by some $\left.Q_{*} \in\right] 0, Q[$. Nonspacelike completeness of $\left(M_{Q}, f_{Q} g_{Q}\right)$ follows from [26, Lemma 14.13]. It is future 1-connected,
because this is invariant under conformal changes of the metric. Dynamic properties of the geodesic flow on Lorentzian manifolds have been considered in [1], [10] and [32].

## 8. Density of timelike periodic geodesics

In this section we shall show that the timelike periodic geodesics are dense in the future timelike unit tangent bundle

$$
T^{-1} M^{+}=\{v \in T M \mid\langle v, v\rangle=-1, v \text { future directed }
$$

of a $C_{Q}$ manifold $(M, g)$ with $Q$ positive and with vicious Deck transformation group. We shall proceed to define this concept.

Let $\pi$ denote the tangent bundle projection, and $D: T T M \rightarrow T M$ the connection map; see [18]. The tangent bundle to $M$ at $v \in T M$ decomposes into

$$
T_{v} T M=\operatorname{HOR} T_{v} T M \oplus \text { VER } T_{v} T M
$$

where $\operatorname{HOR} T_{v} T M$ is the kernel of $D_{v}$, and VER $T_{v} T M$ is the kernel of $T_{v} \pi$. Any $w \in T_{v} T M$ decomposes uniquely as

$$
w=w^{h}+w^{v}, \quad w^{h} \in \operatorname{HOR} T_{v} T M, \quad w^{v} \in \operatorname{VER} T_{v} T M
$$

The tangent bundle to $M$ carries a canonical metric $G$, defined by

$$
G\left(w_{1}, w_{2}\right)=g\left(w_{1}^{h}, w_{2}^{h}\right)+g\left(w_{1}^{v}, w_{2}^{v}\right) \quad w_{1}, w_{2} \in T_{v} T M
$$

and this induces a Lorentzian metric on the future timelike unit tangent bundle $T^{-1} M^{+}$.

Definition 8.1. A group $\Gamma$ of isometries on $(M, g)$ acting properly discontinuous on $T^{-1} M^{+}$is vicious provided $T^{-1} M^{+} / \Gamma=N$ is time orientable and totally vicious, that is,

$$
I^{+}(p) \cap I^{-}(p)=N
$$

for all $p \in N$.
Remark 8.2. Suppose $\Gamma$ is a group of isometries on $(M, g)$ acting properly discontinuous on $T^{-1} M^{+}$. According to [27, p. 191] there is a unique differentiable structure and metric on $T^{-1} M^{+} / \Gamma$ making the
natural map $\pi_{\Gamma}: T^{-1} M^{+} \rightarrow T^{-1} M^{+} / \Gamma=N$ a semi Riemannian covering map. $N$ will always be given this differentiable structure. The reader may consult remark 9.6 for examples of vicious groups of isometries.

Suppose $\omega \in M^{+}(\infty)$ and $\alpha \in M^{-}(\infty)$ are causally related, i.e., there exists a $p \in M$ such that $p \ll \omega$ and $p \gg \alpha$ respectively. According to Proposition 4.5 there exist a unique TF geodesic $\gamma_{1}$ and a unique TP geodesic $\gamma_{2}$ from $p$ to $[\gamma]_{+}=\omega$ and $\left[\gamma_{-}\right]_{-}=\alpha$ respectively. It will be convenient to define

$$
\begin{aligned}
& B_{\epsilon}(\omega, p)=\left\{\left[\gamma_{w}\right]_{+} \in M^{+}(\infty) \mid w \in T_{p}^{-1} M^{+}\left\langle w, \gamma_{1}^{\prime}(0)\right\rangle \geq-1-\epsilon\right\} \\
& B_{\epsilon}(\alpha, p)=\left\{\left[\gamma_{w}\right]_{-} \in M^{-}(\infty) \mid w \in T_{p}^{-1} M^{-}\left\langle w, \gamma_{2}^{\prime}(0)\right\rangle \geq-1-\epsilon\right\}
\end{aligned}
$$

Proposition 8.3. If $\Gamma$ is a totally vicious group of isometries on $(M, g)$ and $p \gg \alpha, p \ll \omega$ for some $p \in M$, then for every $\epsilon>0$ there exists a TF axis $\gamma_{\xi}$ of a hyperbolic isometry $\xi \in \Gamma$ such that

$$
\left[\gamma_{\xi}\right]_{+} \in B_{\epsilon}(\omega, p) \quad\left[\gamma_{\xi_{-}}\right]_{-} \in B_{\epsilon}(\alpha, p)
$$

Proof. To prove this we first apply Proposition 4.5 to give us a TF geodesic $\gamma_{1}$ and a TP geodesic $\gamma_{2}$ with $\gamma_{1}(0)=\gamma_{2}(0)=p,\left[\gamma_{1}\right]_{+}=\omega$ and $\left[\gamma_{2}\right]_{-}=\alpha$. We will first show that there exist isometries $\mu_{+}$and $\mu_{-}$in $\Gamma$ such that

$$
\begin{equation*}
\mu_{+}(p) \in I^{+}\left(\gamma_{1}(t)\right), \quad \mu_{-}(p) \in I^{-}\left(\gamma_{2}(t)\right) \tag{8.1}
\end{equation*}
$$

We have chosen $t>0$ to satisfy

$$
\cosh ^{2}(Q t) / \sinh ^{2}(Q t)<1+\epsilon
$$

It will suffice to find a $\mu_{+} \in \Gamma$ satisfying (8.1). To introduce notation let $X, Y$ and $Z$ denote the time orientations of $T^{-1} M^{+}, T^{-1} M^{+} / \Gamma=N$ and $M$ respectively. These time orientations may be compatible or incompatible at some $v \in T^{-1} M^{+}, \pi(v)=\gamma_{1}(t)$. That is,

$$
\langle T \pi(X(v)), Z(\pi(v))\rangle\left\langle Y\left(\pi_{\Gamma}(v)\right), T_{v} \pi_{\Gamma}(X)\right\rangle
$$

may be either (i) positive or (ii) negative. Since $N$ is totally vicious, there exists a smooth timelike curve $\beta:[0,1] \rightarrow T^{-1} M^{+} / \Gamma$ from
$\pi_{\Gamma}(v)=\beta(0)$ to some $\pi_{\Gamma}(w)=\beta(1), w \in T_{p}^{-1} M^{+}$with $\pi(w)=p$. We can assume it is future directed in case (i), and past directed in case (ii). The projection $\pi \circ \eta$ to $M$ of the lift $\eta: I \rightarrow T^{-1} M^{+}$of $\beta$ through $\eta(0)=v$ is then a future directed smooth timelike curve in $T^{-1} M^{+}$by definition of the metric on $T^{-1} M^{+}$. But this means that there exists a $\mu_{+} \in \Gamma$ such that $T \mu_{+}(w)=\eta(1)$ hence $\gamma_{1}(t) \ll \mu_{+}(p)$ as claimed.

Having found $\mu_{-} \in \Gamma$ satisfying (8.1) by logically equivalent reasoning we define $\xi=\mu_{+} \circ \mu_{-}^{-1}$ and combine

$$
p \ll \mu_{+}(p), \quad p \ll \mu_{-}^{-1}(p)
$$

to assert that $p \ll \xi(p)$. Let the TF geodesic $\gamma_{\xi}$ denote a timelike axis for $\xi$ with $\xi \circ \gamma_{\xi}=\gamma_{\xi} \circ \tau_{d_{\xi}}$; its existence is guaranteed by Theorem 5.3. Recall that we can assume that $\left[\gamma_{\xi}\right]_{+} \in I_{\infty}^{+}(p)$ and $\left[\gamma_{\xi_{-}}\right]_{-} \in I_{\infty}^{-}(p)$. Combining

$$
\left\langle T \xi\left(\gamma_{\xi}^{\prime}(0)\right), X\right\rangle=\left\langle\gamma_{\xi}^{\prime}\left(\tau_{d_{\xi}}(0)\right), X\right\rangle<0
$$

with the fact that $T^{-1} M^{+}$is path connected we conclude that $T \xi$ preserves time orientation. Let $\sigma$ denote some TF geodesic through $\sigma(0)=p$. Then

$$
p \ll \mu_{+}(p) \ll \mu_{+}\left([\sigma]_{+}\right)
$$

Looking at the timelike geodesic triangle $p \gamma_{1}(t) \mu_{+} \circ \sigma(s)$ with sidelengths $t, v=d\left(p, \mu_{+} \circ \sigma(s)\right)$ and $u=d\left(\gamma_{1}(t), \mu_{+} \circ \sigma(s)\right)$ we find

$$
\begin{aligned}
A_{p} \geq A_{p_{Q}} & =(\cosh (Q u)-\cosh (Q v) \cosh (Q t)) /[\sinh (Q v) \sinh (Q t)] \\
& \geq-\cosh ^{2}(Q t) / \sinh ^{2}(Q t) \geq-1-\epsilon
\end{aligned}
$$

We deduce that $\mu_{+}\left(I_{\infty}^{+}(p)\right) \subset B_{\epsilon}(\omega, p)$. Similarly $\mu_{-}\left(I_{\infty}^{-}(p)\right) \subset B_{\epsilon}(\alpha, p)$. Hence also

$$
\left[\gamma_{\xi}\right]_{+} \in \xi_{+}\left(I_{\infty}^{+}(p)\right) \subset B_{\epsilon}(\omega, p), \quad\left[\gamma_{\xi_{-}}\right]_{-} \in \xi_{-}^{-1}\left(I_{\infty}^{-}(p)\right) \subset B_{\epsilon}(\alpha, p)
$$

and the proposition follows.
We can now prove the density of timelike periodic geodesics in the future timelike unit tangent bundle of a $C_{Q}$ manifold.

Theorem 8.4. Let $(M, g)$ denote a $C_{Q}$ manifold, $Q>0$, with a vicious group of isometries acting on the future timelike unit tangent bundle. Given an open set $U$ in $T^{-1} M^{+}$, there exists a $v \in U$ such that the geodesic with initial velocity $\pi_{\Gamma}(v)$ is periodic.

Proof. We shall prove more, namely: On any $C_{Q}$ manifold with $Q>0$, the tangent vectors to TF geodesics joining any pair $\left[\gamma_{v_{-}}\right]_{-}=$ $\alpha \in M^{-}(\infty)$ and $\left[\gamma_{v}\right]_{+}=\omega \in M^{+}(\infty)$ depend continuously on the endpoints. By this we mean that to any neighbourhood $U$ around $v$ in $T^{-1} M^{+}$there exists an $\epsilon>0$ such that any TF geodesic $\gamma$ joining $[\gamma]_{+}=\omega_{*} \in B_{\epsilon}(\alpha, p)$ and $\left[\gamma_{-}\right]_{-}=\alpha_{*} \in B_{\epsilon}(\omega, p)$ has a tangent vector in $U$.

Choose some $t_{2}>0$ and open neighbourhoods $W, U_{1}$ and $U_{2}$ around $t_{2} v$ in $\Lambda^{+}$and $p_{1}=\gamma_{v}(0)=\gamma_{v}\left(t_{1}\right), p_{2}=\gamma_{v}\left(t_{2}\right)$ in $M$ such that

$$
E_{\mid W}: W \rightarrow U_{1} \times U_{2} \quad w \mapsto(\pi(w), \exp (w))
$$

is a $C^{\infty}$ diffeomorphism. We can assume that $x \ll y$ for all $x \in U_{1}$ and $y \in U_{2}$ cf. [27] p. 404 and also that $u /\|u\| \in U$ for all $u$ in $W$. Let $E_{1}=\gamma_{v}^{\prime}, \ldots, E_{n}$ denote a parallel orthonormal basis along $\gamma_{v}$. There exists $b_{j}>0$ such that any $z_{p_{j}} \in T_{p_{j}} M, j=1,2$ satisfying

$$
\left|\left\langle z_{p_{j}}, E_{i}(0)\right\rangle\right|<2 b_{j}
$$

for all $i=1, . ., n$ is mapped into $U_{j}$ by $\exp _{p_{j}}$.
We claim that there exists an $A_{i}>1$ such that for any TF geodesic $\beta$ with

$$
\begin{align*}
{[\beta]_{+}=} & {\left[c_{i}\right]_{+} \quad\left[\beta_{-}\right]_{-}=\left[d_{i}\right]_{-}, \quad c_{i} \in \Omega_{T F}, d_{i} \in \Omega_{T P}, }  \tag{8.2}\\
& \left\langle c_{i}^{\prime}(0), d_{i}^{\prime}(0)\right\rangle<A_{i}, \quad c_{i}(0)=d_{i}(0)=p_{i}
\end{align*}
$$

there exists a past directed null or zero vector $z_{i} \in T_{p_{i}} M$ with $\exp _{p_{\mathbf{i}}}\left(z_{i}\right) \in \beta(\mathbb{R})$ and

$$
\left|\left\langle z_{i}, d_{i}^{\prime}(0)\right\rangle\right|<b_{i} .
$$

To prove this claim choose $A_{i}>1$ such that

$$
f(x) \triangleq\left(1-x+\left(x^{2}-1\right)^{\frac{1}{2}}\right) / Q<b / 2
$$

whenever $x \in\left[1, A_{i}\left[\right.\right.$. This $A_{i}$ will work. To see this we denote by $d_{s}$ the TF geodesic from $d_{i}(s)=d_{s}(0)$ to $c_{i}(s)=d_{s}\left(u_{s}\right), s>0$, and define

$$
t_{s}=\sup \left\{t \geq 0 \mid d_{s}(t) \in J(d(s), p)\right\}
$$

Then $d_{s}\left(t_{s}\right) \in J^{-}(p) \backslash I^{-}(p)$ by global hyperbolicity of $(M, g)$. According to $[27,14.5]$ there exists a past directed null or zero vector $z_{i}(s)$ satisfying the requirement

$$
\exp _{p_{i}}\left(z_{i}(s)\right)=d_{s}\left(t_{s}\right)
$$

If $z_{i}=0$, the claim follows. Otherwise define $\eta(t)=\exp _{p}\left(t z_{i}\right)$. Lemma 6.1 gives us the following inequalities involving

$$
h=u_{s}-t_{s}, \quad l=t_{s}, \quad d=\left\langle d_{s}^{\prime}(l), \eta^{\prime}(1)\right\rangle=e, \quad d_{*}=-\left\langle\eta^{\prime}(0), d^{\prime}(0)\right\rangle,
$$

namely

$$
\begin{align*}
& \cosh (Q s) \leq \cosh (Q h)-\sinh (Q h) Q d, \\
& \cosh (Q s) \leq \cosh (Q l)+\sinh (Q l) Q e,  \tag{8.3,4,5}\\
& \cosh (Q l) \leq \cosh (Q s)-\sinh (Q s) Q d_{*}
\end{align*}
$$

Combine (8.3) and (8.4) to get

$$
\begin{equation*}
\cosh (Q s)(\sinh (Q l)+\sinh (Q h)) \leq \sinh (Q(l+h)) . \tag{8.6}
\end{equation*}
$$

We will also need to combine

$$
\cosh (Q(h+l)) \leq \cosh ^{2}(Q s)\left(1+A_{p}\right)-A_{p}
$$

with (8.6) to yield

$$
\begin{aligned}
\left(\cosh (Q(h+l))+A_{p}\right) & (\sinh (Q l)+\sinh (Q h))^{2} \\
& \leq\left(1+A_{p}\right) \sinh ^{2}(Q(l+h)) .
\end{aligned}
$$

Squaring the brackets and rearranging the terms we obtain

$$
\begin{gathered}
\cosh (Q(h+l))\left(\sinh ^{2}(Q l)+\sinh ^{2}(Q h)\right)+2 \sinh ^{2}(Q l) \sinh ^{2}(Q h) \\
\leq \cosh ^{2}(Q l) \sinh ^{2}(Q h)+\sinh ^{2}(Q l) \cosh ^{2}(Q h) \\
+2 A_{p} \sinh (Q l) \sinh (Q h)(\cosh (Q(h+l))-1)
\end{gathered}
$$

and then finally

$$
\sinh ^{2}(Q h)-2 A_{p} \sinh (Q l) \sinh (Q h)+\sinh ^{2}(Q l) \leq 0 .
$$

We deduce immediately that

$$
\sinh (Q h) / \sinh (Q l) \leq A_{p}+\left(A_{p}^{2}-1\right)^{\frac{1}{2}} \triangleq \alpha .
$$

The reverse triangle inequality tells us that $h \geq s$. For $s$ greater than or equal to some $s_{0}$, we may then compute from (8.5)

$$
\begin{align*}
d_{*} & \leq \frac{\sinh (Q l) \cosh (Q h)-\cosh (Q s) \sinh (Q l)}{Q \sinh (Q h) \sinh (Q s)}  \tag{8.7}\\
& \leq \cosh (Q s)(1-1 / \alpha) /(Q \sinh (Q s)) \\
& =\cosh (Q s) f\left(A_{p}\right) / \sinh (Q s)<b / 2
\end{align*}
$$

when $s_{0}$ is sufficiently large. From (8.7) it follows that the $\left\{z_{i}(s)\right\}_{s \geq s_{0}}$ lie in a compact subset of $T_{p_{i}} M$. We can then take a sequence of real numbers $s_{n} \geq s_{0}$ converging to $+\infty$ and such that $z_{i}\left(s_{n}\right) \rightarrow z_{i}$ as $n \rightarrow+\infty$. Now $\exp _{p_{i}}\left(z_{i}\right) \in \beta(\mathbb{R})$ because $d_{s_{n}} \circ \tau_{t_{s_{n}}}=\beta^{n}$ and $\beta_{-}^{n}$ have nonspacelike limit curves $\xi$ and $\zeta$ through $d_{s_{n}}\left(t_{s_{n}}\right)$, which are TF geodesics with $\xi^{\prime}(0)=-\zeta^{\prime}(0)$ and $\xi(0)=\zeta(0)=\exp _{p_{i}}\left(z_{i}\right)$. This is due to the fact that

$$
\exp _{p_{i}}\left(z_{i}\left(s_{n}\right)\right)=d_{s_{n}}\left(t_{s_{n}}\right) \rightarrow \exp _{p_{i}}\left(z_{i}\right)
$$

for $n \rightarrow+\infty$. Thus $\xi$ is a future coray to $c$, and $\xi_{-}$a past coray to $d$. By the uniqueness in Proposition 4.8 we conclude that $\beta=\xi \circ \tau_{a}$ for some $a \in \mathbb{R}$ and hence $\exp _{p_{i}}\left(z_{i}\right)=\xi(0)=\beta(-a)$. This establishes the claim.

Due to the claim there are $A_{i}=\cosh a_{i}, a_{i}>0$, such that the conclusion following (8.2) is true. We can also assume that $b_{i} A_{i}+$ $\left(A_{i}^{2}-1\right)^{\frac{1}{2}} b_{i}<2 b_{i}, i=1,2$. Now take $s_{1}<t_{1}, s_{2}>t_{2}$ subject to the requirement that any $c_{j} \in \Omega_{T F}$ and $d_{j} \in \Omega_{T P}$ with

$$
\left[c_{j}\right]_{+} \in I^{+}\left(\gamma_{v}\left(s_{2}\right)\right), \quad\left[d_{j}\right]_{-} \in I^{-}\left(\gamma_{v}\left(s_{1}\right)\right), \quad c_{j}(0)=d_{j}(0)=p_{j}
$$

satisfy the inequalities

$$
\begin{equation*}
-\left\langle c_{j}^{\prime}(0), \gamma_{v}^{\prime}\left(t_{j}\right)\right\rangle \leq \cosh \left(a_{j} / 2\right), \quad\left\langle d_{j}^{\prime}(0), \gamma_{v}^{\prime}\left(t_{j}\right)\right\rangle \leq \cosh \left(a_{j} / 2\right) \tag{8.8}
\end{equation*}
$$

There exists a TF geodesic $\beta$ with

$$
\begin{align*}
& {\left[c_{j}\right]_{+}=[\beta]_{+} \in I_{\infty}^{+}\left(\gamma_{v}\left(s_{2}\right)\right),}  \tag{8.9}\\
& {\left[d_{j}\right]_{-}=\left[\beta_{-}\right]_{-} \in I_{\infty}^{-}\left(\gamma_{v}\left(s_{1}\right)\right),}
\end{align*}
$$

where $c_{j}(0)=p_{j}$. Now (8.8) implies that $\left\langle c_{j}^{\prime}, d_{j}^{\prime}\right\rangle \leq A_{j}$. According to the claim (8.2) there are past directed null or zero vectors $z_{j} \in T_{p_{j}} M$ and $s_{j} \in \mathbb{R}$ such that

$$
\exp _{p_{j}}\left(z_{j}\right)=\beta\left(s_{j}\right), \quad\left|\left\langle z_{j}, d_{j}^{\prime}(0)\right\rangle\right|<b_{j}, \quad j=1,2
$$

It follows that

$$
\left|\left\langle z_{j}, \gamma_{v}^{\prime}\left(t_{j}\right)\right\rangle\right| \leq A_{j} b_{j}+\left(A_{j}^{2}-1\right)^{\frac{1}{2}} b_{j}<2 b_{j} .
$$

Hence $\beta\left(s_{j}\right) \in U_{j}$. Since $\beta\left(s_{1}\right) \ll \beta\left(s_{2}\right)$ we conclude that

$$
\left(s_{2}-s_{1}\right) \beta^{\prime}\left(s_{1}\right)=E_{\mid W}^{-1}\left(\beta\left(s_{1}\right), \beta\left(s_{2}\right)\right) \in W
$$

so that $\beta^{\prime}\left(s_{1}\right) \in U$. Due to Proposition 8.3, we can assume that $\beta$ is an axis of an isometry $\mu \in \Gamma$. This finishes the proof.

## 9. Constant curvature

In this section we will show that there are discrete groups of isometries acting on the future timelike unit tangent bundle of the complete $C_{Q}$ manifolds of constant sectional curvature $Q>0$. To do this consider

$$
\begin{aligned}
\mathbb{X}=\left\{(x, v) \in \mathbb{R}_{1}^{n+1} \times \mathbb{R}_{1}^{n+1} \mid\langle x, x\rangle\right. & =1 / Q^{2},\langle x, v\rangle=0 \\
\langle v, v\rangle & \left.=-1 / Q^{2}, v_{1}>0\right\} \\
\mathbb{Y}=\left\{(y, w) \in \mathbb{R}_{1}^{n+1} \times \mathbb{R}_{1}^{n+1} \mid\langle y, y\rangle\right. & =-1 / Q^{2},\langle y, w\rangle=0 \\
\langle w, w\rangle & \left.=1 / Q^{2}, y_{1}>0\right\}
\end{aligned}
$$

Riemannian hyperbolic space is denoted by

$$
M_{H}=\left\{x \in \mathbb{R}_{1}^{n+1} \mid\langle x, x\rangle=-x_{1}^{2}+\sum_{i=2}^{n+1} x_{i}^{2}=-1 / Q^{2}\right\}
$$

We have the natural maps $G_{\mathbf{X}}$ and $G_{\mathbf{Y}}$ from the future timelike unit tangent bundle

$$
T^{-1} M_{Q}^{+}=\left\{v \in T M_{Q} \mid\langle v, v\rangle=-1,\langle v, X\rangle<0\right\}
$$

of $M_{Q}$ and unit tangent bundle $T^{1} M_{H}$ of $M_{H}$ to $\mathbb{R}^{n+1} \times \mathbb{R}^{n+1}$, defined by the sequences

$$
\begin{aligned}
T^{-1} M_{Q}^{+} & \rightarrow T \mathbb{R}^{n+1}
\end{aligned} \rightarrow \mathbb{R}^{n+1} \times \mathbb{R}^{n+1}, ~ 子, ~ i \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1} \times \mathbb{R}^{n+1}
$$

In each row the first map is the inclusion, the second map the natural identification. The map that takes $(x, v) \in \mathbb{R}^{n+1} \times \mathbb{R}^{n+1}$ to $(x, v \cdot 1 / Q)$ is denoted by $h_{Q}$. Notice that $h_{Q} \circ G_{\mathbf{X}}$ and $h_{Q} \circ G_{\mathbb{Y}} \operatorname{map}$ onto $\mathbb{X}$ and $\mathbb{Y}$. This means that

$$
\begin{array}{r}
F_{\mathbf{X}}: T^{-1} M_{Q}^{+} \rightarrow \mathbb{X} \quad, \quad v \mapsto h_{Q} \circ G_{\mathbf{X}}(v) \\
F_{\mathbf{Y}}: T^{1} M_{H} \rightarrow \mathbb{Y} \quad, \quad v \mapsto h_{Q} \circ G_{Y}(v)
\end{array}
$$

are diffeomorphisms to $\mathbb{X}$ and $\mathbb{Y}$ with their submanifold structures from the ambient $\mathbb{R}^{n+1} \times \mathbb{R}^{n+1}$. Also

$$
G: \mathbb{X} \rightarrow \mathbb{Y} \quad(x, v) \mapsto(v, x)
$$

is a diffeomorphism, showing that $T^{-1} M_{Q}^{+}$and $T^{1} M_{H}$ are diffeomorphic via the composition

$$
\Psi=F_{\mathbf{Y}}^{-1} \circ G \circ F_{\mathbf{X}}
$$

of diffeomorphisms. We have geodesic flows

$$
\begin{aligned}
& \Phi_{Q}: \mathbb{R} \times T^{-1} M_{Q}^{+} \rightarrow T^{-1} M_{Q}^{+} \\
& \Phi_{H}: \mathbb{R} \times T^{1} M_{H} \rightarrow T^{1} M_{H}
\end{aligned}
$$

on $M_{Q}$ and $M_{H}$ respectively. The diffeomorphism $\Psi$ conjugates these two flows. In fact, we have

Proposition 9.1. $\Psi \circ \Phi_{Q}(t, v)=\Phi_{H}(t, \Psi(v))$ for all $v \in T^{-1} M_{Q}^{+}$ and all $t \in \mathbb{R}$.

Proof. Given $t \in \mathbb{R}$ and $F_{\mathbf{x}}(v)=(x, y) \in \mathbb{X}$ define

$$
\begin{aligned}
& \gamma(t)=x \cosh (Q t)+y \sinh (Q t) \\
& \beta(t)=x \sinh (Q t)+y \cosh (Q t)
\end{aligned}
$$

They are geodesics in $M_{Q}$ and $M_{H}$ with initial velocities $\gamma^{\prime}(0)=v$ and $\Psi(v)=\beta^{\prime}(0)$. The proposition follows from a direct computation, showing that $F_{\mathbf{Y}} \circ \Psi\left(\gamma^{\prime}(t)\right)=F_{\mathbf{Y}}\left(\beta^{\prime}(t)\right)$.

The tangent maps of a properly discontinuous group $\Gamma$ of isometries on $M_{H}$ induce a properly discontinuous group $\Gamma_{H}$ of diffeomorphisms of $T^{1} M_{H}$. The properly discontinuous groups of diffeomorphisms

$$
\begin{aligned}
& \Gamma_{\mathbf{Y}}=\left\{F_{\mathbf{Y}} \circ \zeta \circ F_{\mathbf{Y}}^{-1} \mid \zeta \in \Gamma_{H}\right\}, \\
& \Gamma_{\mathbf{X}}=\left\{G^{-1} \circ \zeta \circ G \mid \zeta \in \Gamma_{\mathbf{Y}}\right\}, \\
& \Gamma_{Q}=\left\{F_{\mathbf{X}}^{-1} \circ \zeta \circ F_{\mathbf{X}} \mid \zeta \in \Gamma_{\mathbf{X}}\right\}
\end{aligned}
$$

give rise to the following commutative diagram:

where the vertical maps are the natural maps, and the maps in the bottom row are induced by the maps $F_{\mathbf{X}}, G$ and $F_{\mathbf{Y}}$ in the top row. The restriction maps
$R_{Q}: I\left(\mathbb{R}_{1}^{n+1}\right) \rightarrow I\left(M_{Q}\right), \quad R_{H}: O_{1}^{++}(n+1) \cup O_{1}^{+-}(n+1) \rightarrow I\left(M_{H}\right)$
from the isometry group $I\left(\mathbb{R}_{1}^{n+1}\right)$ of $\mathbb{R}_{1}^{n+1}$ to the isometry groups $I\left(M_{Q}\right)$ and $I\left(M_{H}\right)$ of $M_{Q}$ and $M_{H}$ are isomorphisms, according to [27, 9.8]. Hence

$$
\begin{align*}
\Gamma_{Q}=\left\{T \xi: T^{-1} M_{Q}^{+} \rightarrow T^{-1} M_{Q}^{+} \mid \mu \in \Gamma\right. & \Gamma  \tag{9.2}\\
& \xi=I_{Q}\left(M_{H}\right) \\
& \left.=R_{Q}\left(R_{H}^{-1}(\mu)\right)\right\} .
\end{align*}
$$

Thus $\Gamma_{Q}$ is a properly discontinuous group of tangent maps of isometries of $M_{Q}$. It follows that the commutative diagram in (9-1) provides a link between the geometries of Riemannian and Lorentzian hyperbolic manifolds, making available Riemannian theory applicable to Lorentzian hyperbolic manifolds.

Remark 9.2. It is also clear that the composition $\psi$ of diffeomorphisms from left to right in the bottom row of diagram (9.1) conjugate the geodesic flows $\psi_{Q}$ and $\psi_{H}$ of $T^{-1} M_{Q}^{+} / \Gamma_{Q}$ and $T^{1} M_{H} / \Gamma_{H}$ respectively.

Propositions 9.3 and 9.4 below will enable us to deduce results about the dynamic properties of the geodesic (horocycle) flow on $T^{-1} M_{Q}^{+} / \Gamma_{Q}$. These results set the context for Theorem 8.4; see Remark 9.6.

We shall now show that $\Psi$ and hence $\psi$ preserve Liouville measures $\tau_{Q}$ and $\tau_{H}$ on $T^{-1} M_{Q}^{+} / \Gamma_{Q}$ and $T^{1} M_{H} / \Gamma_{H}$ when $M_{H} / \Gamma$ is orientable.

Proposition 9.3. $\psi_{*} \tau_{H}=\lambda \tau_{Q}$, for some $\lambda \in \mathbb{R} \backslash\{0\}$.
Proof. It is clear that for some $v \in T^{-1} M_{Q}^{+}$we have

$$
\Psi_{*} \zeta_{H}(v)=\lambda \zeta_{Q}(v)
$$

for some $\lambda \in \mathbb{R} \backslash\{0\}$. We have used $\zeta_{Q}$ and $\zeta_{H}$ to denote Liouville measures on $T^{-1} M_{Q}^{+}$and $T^{1} M_{H}$. Given $w \in T^{-1} M_{Q}^{+}=N_{Q}$ we can take an orientation preserving isometry $\mu$ on $M_{H}$ such that

$$
T \mu(\Psi(v))=\Psi(w)=\Psi \circ T \xi(v)
$$

where $\xi=R_{Q}\left(R_{H}^{-1}(\mu)\right)$. Suppressing evaluation in $v$, compute

$$
\lambda T \xi_{*} \zeta_{Q}=\lambda \zeta_{Q}=\Psi_{*} \zeta_{H}=\Psi_{*} T \mu_{*} \zeta_{H}=T \xi_{*} \Psi_{*} \zeta_{H}
$$

hence $\Psi_{*} \zeta_{H}=\lambda \zeta_{Q}$. This property descends to the quotients.
We can define a horocycle flow on $M_{Q}$ when the dimension of $M_{Q}$ is two. We proceed to define it. First of all we need $M_{Q}$ and $M_{H}$ to have compatible orientations. The restrictions of the position vector
field on $\mathbb{R}_{1}^{3} \backslash\{0\}$ to $M_{Q}$ and $M_{H}$ provide normal vector fields $U_{Q}$ and $U_{H}$ on $M_{Q}$ and $M_{H}$. The orientation $\omega=-d x_{1} \wedge d x_{2} \wedge d x_{3}$ in $\mathbb{R}_{1}^{3}$ gives us orientations

$$
\begin{gathered}
\omega_{Q}(x)=\omega\left(U_{Q}(x), \cdot, \cdot\right), \quad x \in M_{Q}, \\
\omega_{H}(y)=\omega\left(U_{H}(y), \cdot, \cdot\right), \quad y \in M_{H}
\end{gathered}
$$

of $T_{x} M_{Q}=x^{\perp}$ and $T_{y} M_{H}=y^{\perp}$. Given $v \in T^{-1} M_{Q}^{+}$, let $b_{v}^{+}$denote the Buseman function for $\gamma_{v}$, defined on $I^{-}(\omega), \omega=\left[\gamma_{v}\right]_{+}$. The horosphere

$$
B_{v}=\left\{q \in I^{-}(\omega) \mid b_{v}^{+}(q)=b_{v}^{+}(\pi(v))\right\}
$$

is a smooth, spacelike hypersurface of $M_{Q}$, since $\left\langle\operatorname{grad} b_{v}^{+}, \operatorname{grad} b_{v}^{+}\right\rangle \equiv$ -1 . There is a unit speed geodesic $\beta_{v}: \mathbb{R} \rightarrow B_{v}$ through $\pi(v)$ such that $\beta_{v}^{\prime}(0)$ and $v$ are positively oriented. The horocycle flow

$$
h_{Q}: \mathbb{R} \times T^{-1} M_{Q}^{+} \rightarrow T^{-1} M_{Q}^{+}
$$

is then

$$
h_{Q}(t, v)=\operatorname{grad} b_{v}^{+}\left(\beta_{v}(t)\right), \quad t \in \mathbb{R}
$$

Similarly the horocycle flow on $M_{H}$ is denoted

$$
h_{H}: \mathbb{R} \times T^{1} M_{H} \rightarrow T^{1} M_{H}
$$

We need to know
Proposition 9.4. $\Psi \circ h_{Q}(t, v)=h_{H}(t, \Psi(v)), \quad(t, v) \in \mathbb{R} \times T^{-1} M_{Q}^{+}$.
Proof. Let us find the horocyclic orbits of $v_{0} \in T^{-1} M_{Q}^{+}$and $w_{0} \in$ $T^{1} M_{H}$, where $F_{\mathbf{X}}\left(v_{0}\right)=1 / Q\left(e_{3}, e_{1}\right)$ and $F_{\mathbf{Y}}\left(w_{0}\right)=1 / Q\left(e_{1}, e_{3}\right)$. Here $\left\{e_{i}\right\}$ denotes the canonical basis in $\mathbb{R}^{3}$. We find that

$$
\begin{aligned}
F_{\mathbf{X}}\left(h_{v_{0}}^{Q}(t)\right) & =\left(\left(-\frac{Q}{2} t^{2}, t, 1 / Q-\frac{Q}{2} t^{2}\right),\left(1 / Q+\frac{Q}{2} t^{2},-t, \frac{Q}{2} t^{2}\right)\right) \\
& =G \circ F_{\mathbf{Y}}\left(h_{w_{0}}^{H}(t)\right),
\end{aligned}
$$

showing

$$
\begin{equation*}
\Psi \circ h_{Q}\left(t, v_{0}\right)=h_{H}\left(t, \Psi\left(v_{0}\right)\right) . \tag{9.3}
\end{equation*}
$$

Since $I\left(M_{H}\right)$ acts transitively on the orthonormal bases of $M_{H}$ (cf. [27, 4.30]), there exists an orientation preserving isometry $\mu \in I\left(M_{H}\right)$
taking some $w=\Psi(v), v \in T^{-1} M_{Q}^{+}$to $T \mu(w)=w_{0}$. Define $\xi=$ $R_{Q}\left(R_{H}^{-1}(\mu)\right)$ and observe that

$$
\begin{aligned}
& T \mu \circ \Psi=\Psi \circ T \xi, \\
& T \mu \circ h_{w}^{H}(t)=h_{T \mu(w)}^{H}(t), \quad t \in \mathbb{R}, \\
& T \xi \circ h_{v}^{Q}(t)=h_{T \xi(v)}^{Q}(t), \quad t \in \mathbb{R}
\end{aligned}
$$

Combining this with (9.3) we conclude

$$
\Psi \circ T \xi\left(h_{v}^{Q}(t)\right)=h_{\Psi\left(v_{0}\right)}^{H}(t)=T \mu \circ \Psi\left(h_{v}^{Q}(t)\right)=T \mu \circ h_{w}^{H}(t) .
$$

Thus the proposition follows.
Definition 9.5. The group $\Gamma_{Q}$ in (9.2) is proper when $\Gamma$ acts properly discontinuously on $M_{H}$ such that $M_{H} / \Gamma$ is a connected, orientable Riemann surface of finite volume.

The horocycle flow descends to the quotient of the future unit timelike tangent bundle $T^{-1} M_{Q}^{+}$with a proper group $\Gamma_{Q}$.

Remark 9.6. In view of Propositions 9.3. and 9.4. a number of available results are now applicable to the quotient $X=T^{-1} M_{Q}^{+} / \Gamma_{Q}$ of the future timelike unit tangent bundle with a proper group $\Gamma_{Q}$. We mention a few as follows.

1) The geodesic flow is mixing and ergodic; cf. [18].
2) The horocycle flow is mixing of all degrees; cf. [26].
3) The timelike periodic geodesics are dense in $X$; cf. [18].
4) There exists a transitive timelike geodesic in $X$; cf. [18].

Notice that $\Gamma_{Q}$ is a vicious group of isometries.
Remark 9.7. A referee pointed out that there is another way of seeing the existence of properly discontinuous groups of isometries acting on $T^{-1} M_{Q}^{+}$. The isometry group of $M_{Q}$ is $O_{1}(n+1)$; see [27, p. 239]. The group $O_{1}(n+1)$ also acts transitively on $M_{Q}$. According to [27, p. 307]

$$
M_{Q}=O_{1}(n+1) / O_{1}(n) .
$$

Take

$$
v_{0}=e_{1 e_{n+1}} \in T^{-1} M_{Q}^{+},
$$

where $e_{1}, . ., e_{n+1}$ is the canonical basis in $\mathbb{R}^{n+1}$. The isotropy group at $v_{0}$ is

$$
O(n-1)=\left\{L \in O_{1}(n+1) \left\lvert\, L=\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & c & 0 \\
0 & 0 & 1
\end{array}\right)\right., c \in O(n-1)\right\}
$$

under the transitive action of

$$
O_{1}^{+}(n+1)=O_{1}^{++}(n+1) \cup O_{1}^{+-}(n+1)
$$

on $T^{-1} M_{Q}^{+}$. From this group we obtain the coset manifolds

$$
\begin{aligned}
\rho: O_{1}^{+}(n+1) / O(n-1) & \rightarrow T^{-1} M_{Q}^{+} L O(n-1) \mapsto T \mu\left(v_{0}\right), \\
\rho^{\prime} & : O_{1}^{+}(n+1) / O(n-1)
\end{aligned} \rightarrow T^{1} M_{H} L O(n-1) \mapsto T \xi\left(\Psi\left(v_{0}\right)\right), ~ f
$$

where

$$
\begin{aligned}
& L \circ i_{Q}=i_{Q} \circ \mu \\
& L \circ i_{H}=i_{H} \circ \xi
\end{aligned}
$$

Then we find

$$
\begin{aligned}
\rho(L O(n-1)) & =T \mu\left(v_{0}\right) \\
\rho^{\prime}(L O(n-1)) & =T \xi\left(\Psi\left(v_{0}\right)\right)=\Psi\left(T \mu\left(v_{0}\right)\right)=\Psi(\rho(L O(n-1)))
\end{aligned}
$$

Thus

$$
\Psi=\rho^{\prime} \circ \rho^{-1}: T^{-1} M_{Q}^{+} \rightarrow O_{1}^{+}(n+1) / O(n-1) \rightarrow T^{1} M_{H}
$$

Taking a properly discontinuous group $\Gamma$ of isometries of $M_{H}$ we obtain a properly discontinuous group of isometries $\Gamma_{Q}$ of $T^{-1} M_{Q}^{+}$via $\rho$.

## 10. $C_{Q}$ surfaces

The existence of null axes for a hyperbolic isometry $\mu$ on a $C_{Q}$ manifold $(M, g)$ with $Q>0$ is related to the existence of fixed points for a Riemannian isometry in the following way.

Proposition 10.1. Let $\alpha=\left[\gamma_{-}\right]_{-} \in M^{-}(\infty)$ and $\omega=[\gamma]_{+} \in$ $M^{+}(\infty)$, where $\gamma$ denotes an axis for $\mu$. If $x \in \partial I^{-}(\omega) \cap \partial I^{+}(\alpha)=N$, and $v_{x}$ denotes a null vector in $T_{x} \partial I^{-}(\omega)$, then the following hold:

1) $N, \partial I^{-}(\omega)$ and $\partial I^{+}(\alpha)$ are $\mu$ invariant.
2) If $x$ is a fixed point for $\mu$, then $\gamma_{v_{x}}$ is a null axis for $\mu$.

Proof. 1) $I^{-}(\omega)$ is $\mu$ invariant and so is $\partial I^{-}(\omega)$, hence also $\partial I^{+}(\alpha)$. The intersection $N$ is then $\mu$ invariant. 2) Simply observe that $T \mu\left(v_{x}\right)=$ $\lambda v_{x}$ for some $\lambda>0$.

This fixed point problem can be solved completely on $C_{Q}$ surfaces with $Q>0$ and a volume form $\omega$. If $\gamma$ denotes a timelike axis for the
orientation preserving hyperbolic isometry $\mu$ and $\omega=[\gamma]_{+}, \alpha=[\gamma]_{-}$ we have indeed

Proposition 10.2. Every future null coline $\beta_{x}$ through $x \in \partial I^{-}(\gamma)$ to $\gamma$ is a null axis for $\mu$. Furthermore there exists a $t_{x} \in \mathbb{R}$ such that $\beta_{x}\left(t_{x}\right) \in \partial I^{-}(\omega) \cap \partial I^{+}(\alpha)$ is a fixed point for $\mu$.

Proof. Due to the definition of a null coline there exists a positive $s$ such that $\beta_{x}(s)=y \in I^{+}(p), p=\gamma(0)$. Let $\beta_{y}$ denote a future null coline to $\gamma$ through $y$. We need only prove $\mu$ invariance of $\beta_{y}$.

To this end let $E$ denote a timelike parallel vector field along $\gamma$ with $\exp _{p}(s E(0))=y$ for some $s>0$. Define a geodesic variation

$$
\alpha:\left\{(s, t) \in \mathbb{R}^{2} \mid t \geq 0\right\} \rightarrow M, \quad(s, t) \mapsto \exp (s E(t))
$$

We claim that for every $t \geq 0$ there exists an $s(t) \geq 0$ such that

$$
\alpha(s(t), t) \in \beta_{y}(\mathbb{R})
$$

This is true for positive $t$ values in a neighbourhood of 0 by the implicit function theorem. If the claim is untrue we can define

$$
t_{*}=\inf \left\{t \geq 0 \mid \alpha(s, t) \notin \beta_{y}(\mathbb{R}) \text { for all } s \geq 0\right\}>0
$$

Notice that $s(t) \leq K$ for some $K>0$ and all $t \in\left[0, t_{*}[;\right.$ cf. (7.13). We can assume convergence of $\left\{s\left(t_{n}\right)\right\}$ to $s_{*}$ for a suitable increasing sequence $\left\{t_{n}\right\}$ of positive real numbers, converging to $t_{*}$. There exists real numbers $z_{n}$ such that

$$
\alpha\left(s\left(t_{n}\right), t_{n}\right)=\beta_{y}\left(z_{n}\right)
$$

Taking subsequences if necessary we can assume the convergence of $\left\{z_{n}\right\}$ to $z_{*}$ too, because $\left\{z_{n}\right\}$ is a bounded sequence. This follows from global hyperbolicity and [27, 14.13]. Since

$$
\beta_{x}^{\prime}\left(z_{*}\right), \frac{\partial \alpha}{\partial s}\left(s_{*}, t_{*}\right)
$$

are linearly independant, we can apply the inverse function theorem to assert the existence of $s(t)$ for $t$ values in a neighbourhood of $t_{*}$. This contradiction verifies the claim. The uniqueness of $s(t) \geq 0$ follows from Lemma 7.1 and the strong causality of $(M, g)$.

Suppose $\mu$ translates $\gamma$ with $a>0$, i.e., $\mu \circ \gamma=\gamma \circ \tau_{a}$. Then $T \mu(E(0))=E(a)$, because $\mu$ is orientation preserving, hence

$$
\begin{equation*}
\mu \circ \alpha(s, 0)=\alpha(s, a) \tag{10.1}
\end{equation*}
$$

Now $\beta_{y}(\mathbb{R}) \subset \partial I^{-}(\omega)$. In view of Proposition 10.1 this implies that $s(0)=s(a)$, so that

$$
\mu\left(\beta_{y}\left(u_{1}\right)\right)=\mu \circ \alpha(s(0), 0)=\alpha(s(a), a)=\beta_{y}\left(u_{2}\right)
$$

for some $u_{1}, u_{2} \in \mathbb{R}$. Since $\partial I^{-}(\omega)$ is one dimensional, we conclude that $\beta_{y}$ is a null axis for $\mu$.

According to the proof of Theorem 7.72 ), there exists a $t<0$ such that $u=\beta_{x}(t) \in \partial I^{-}(\omega) \cap \partial I^{+}(\alpha)$. A past null coline $\beta_{u}$ to $\gamma$ through $u$ is also $\mu$ invariant. Assume for contradiction that some $s<t$ makes $\beta_{x}(s)=\beta_{u}(v), v \in \mathbb{R}$. For $v<0$ this contradicts Lemma 7.6. For $v=0$ it contradicts strong causality of $(M, g)$. For $v>0$ reach a contradiction by applying Lemma 7.2 to find a $w \in] 0, v[$ such that $\beta_{u}(w) \notin J^{+}\left(\beta_{u}(v)\right)$. The uniqueness of $t$ just proven combined with $\mu$ invariance of $\beta_{u}$ and $\beta_{x}$ implies that $\beta_{x}(t)$ is a fixed point for $\mu$.

Definition 10.3. If the NF (NP) geodesic $\beta$ is a future coray to the TF (TP ) geodesic $\gamma$, then $\beta$ has future ( past) endpoint

$$
\omega(\beta)=[\gamma]_{+}, \quad\left(\alpha(\beta)=[\gamma]_{-}\right)
$$

We can now introduce relations $\underset{+}{\rightarrow} \sim_{n}$ and $\rightarrow_{-}$in the sets $\Omega_{N F}$ and $\Omega_{N P}$ of NF geodesics and NP geodesics respectively. For $\beta_{1}, \beta_{2} \in$ $\Omega_{N F}\left(\Omega_{N P}\right)$ we define

$$
\beta_{1} \underset{+}{\rightarrow} \sim_{n} \beta_{2} \quad\left(\beta_{1} \xrightarrow[-]{\longrightarrow} \sim_{n} \beta_{2}\right)
$$

if

$$
\omega\left(\beta_{1}\right)=\omega\left(\beta_{2}\right) \quad\left(\alpha\left(\beta_{1}\right)=\alpha\left(\beta_{2}\right)\right)
$$

Since $\underset{+}{ } \sim_{n}$ and $\rightarrow \sim_{n}$ are equivalence relations, we can finally introduce the null future and the null past as

$$
\begin{aligned}
& M_{N}^{+}(\infty)=\Omega_{N F} / \xrightarrow{\rightarrow} \sim_{n} \\
& M_{N}^{-}(\infty)=\Omega_{N P} / \xrightarrow{\longrightarrow} \sim_{n} .
\end{aligned}
$$

Finally, we have
Theorem 10.3. An orientable $C_{Q}$ surface with $Q>0$ and vicious isometry group $\Gamma$ has constant curvature.

Proof. We shall first verify that a future null coline $\beta_{x}$ to some TF geodesic $\gamma$ through $\beta_{x}(0)=x \in M$ maps into $\partial I^{-}(\gamma)$. To see this take $s>0$ such that

$$
\beta_{x}(s) \in I^{+}(\gamma(0))
$$

Let $\gamma_{s}$ denote the TF geodesic from $\gamma_{s}(0)=\gamma(0)$ to $\gamma_{s}\left(a_{s}\right)=\beta_{x}(s), a_{s}>$ 0 . If $x$ was not in $\partial I^{-}(\gamma)$, then it would neither be in $I^{-}(\gamma)$ according to Lemma 7.1. For some $\left.t_{*} \in\right] 0, a_{s}\left[, \quad \gamma_{s}\left(t_{*}\right) \in \partial I^{-}(\gamma)\right.$. Let $\sigma_{u}$ denote the TF geodesic from $\gamma_{s}\left(t_{*}\right)$ to $\beta_{x}(u), u \geq s$ and $v$ be the limit of $\sigma_{u}^{\prime}(0)$ as $u \rightarrow+\infty$; see Lemma 6.2. $\gamma_{v}$ is not a future coray to $\gamma$ because $\gamma_{s}\left(t_{*}\right) \in \partial I^{-}(\gamma)$. For any $t<t_{*}, \gamma_{s}(t) \in I^{-}(\gamma) \cap I^{-}\left(\gamma_{v}\right)$. By $\tau_{v}$ we denote the TF geodesic from $\gamma_{s}(t)$ to $\beta_{x}(v), v \geq s . \tau_{v}^{\prime}(0)$ converges as $v \rightarrow+\infty$ again by Lemma 6.2. This is incompatible with the fact that $\left[\gamma_{v}\right]_{+} \neq[\gamma]_{+}$, hence $x \in \partial I^{-}(\gamma)$.

Now take some $p \in M$ and a future directed respectively past directed null vector $w_{+}, w_{-} \in T_{p} M$. We need them to be linearly independant. There exists a TF geodesic $\sigma$ with

$$
[\sigma]_{+}=\omega\left(\beta_{w_{+}}\right), \quad\left[\sigma_{-}\right]_{-}=\alpha\left(\beta_{w_{-}}\right)
$$

We aim to assert that

$$
\begin{equation*}
\partial I^{-}(\sigma)=\beta_{x}(\mathbb{R}) \cup \beta_{y}(\mathbb{R}), \quad \beta_{x}(\mathbb{R}) \cap \beta_{y}(\mathbb{R})=\emptyset \tag{10.2}
\end{equation*}
$$

where $\beta_{x}$ and $\beta_{y}$ are future null colines to $\sigma$ through $x, y \in \partial I^{-}(\sigma)$. Let $X_{1}=\sigma^{\prime}(0), X_{2}$ denote an orthonormal basis in $T_{\sigma(0)} M$, and define

$$
v=\cosh 1 X_{1}+\sinh 1 X_{2}, \quad w=\cosh 1 X_{1}-\sinh 1 X_{2}
$$

We have already seen that there exists $s, t>0$ such that $\gamma_{v}(s)=$ $x, \gamma_{w}(t)=y \in \partial I^{-}(\sigma)$. Theorem 7.7 asserts the existence of future null colines $\beta_{x}$ and $\beta_{y}$ to $\gamma$ through $x$ and $y$. For positive $s$ we let $\sigma_{s}^{1}$ and $\sigma_{s}^{2}$ denote the TF geodesics from $\sigma(0)$ to $\beta_{x}(s) \gg \sigma(0)$ and $\beta_{y}(s) \gg \sigma(0)$ respectively.

The two bases $\sigma^{\prime}(0), \sigma_{s}^{1^{\prime}}(0)$ and $\sigma^{\prime}(0), \sigma_{s}^{2^{\prime}}(0)$ have opposite orientations which do not depend on $s$. We have already seen that $\beta_{x}$ and $\beta_{y}$
map into $\partial I^{-}(\sigma)$, which is a $C^{1}$ degenerate hypersurface. It follows that $\beta_{x}(\mathbb{R})$ and $\beta_{y}(\mathbb{R})$ are disjoint.

We can assume $\sigma$ is an axis of a hyperbolic isometry $\mu \in \Gamma$; cf. Proposition 8.3. $\mu$ has fixed points $p_{+}=\beta_{x}\left(t_{x}\right)$ and $p_{-}=\beta_{y}\left(t_{y}\right), t_{x}, t_{y} \in \mathbb{R}$ according to Proposition 10.2. We know from Proposition 10.2 that the future null colines $\beta_{p_{+}}$and $\beta_{p_{-}}$to $\sigma$ through $\beta_{p_{+}}(0)=p_{+}$and $\beta_{p_{-}}(0)=p_{-}$respectively are null axes for $\mu \in \Gamma$. That is,

$$
\begin{gathered}
\mu \circ \beta_{p_{+}}(s)=\beta_{p_{+}}\left(\lambda_{+} s+r_{+}\right), \\
\mu \circ \beta_{p_{-}}(s)=\beta_{p_{-}}\left(\lambda_{-} s+r_{-}\right)
\end{gathered}
$$

for real constants $\lambda_{+}, \lambda_{-}, r_{+}, r_{-}$. Here $r_{+}=r_{-}=0$ since $p_{+}$and $p_{-}$are fixed points for $\mu$. $\beta_{p_{+}}$being a future null coray to $\sigma$, there exists $s>0$ such that $\beta_{p_{+}}(s) \gg r=\sigma(0)$ and hence also $s_{*} \geq 0$ such that

$$
\beta_{p_{+}}\left(s_{*}\right) \in J^{+}(r) \backslash I^{+}(r)
$$

If $\lambda_{+} \leq 1$, then we would have

$$
r \ll \mu(r)<\mu \circ \beta_{p_{+}}\left(s_{*}\right) \leq \beta_{p_{+}}\left(s_{*}\right)
$$

a contradiction, hence $\lambda_{+}>1$. Similarly $\lambda_{-}>1$.
Consider now an arbitrary $q \in M$. Take an arbitrarily small open neighbourhood $U$ around $q \in M$ on which we have defined two linearly independant smooth, future and past directed null vector fields $X_{+}$and $X_{-}$respectively. Notice that the integral curves of $X_{-}$and $X_{+}$are null pregeodesics. There exists a TF geodesic $\tau$ with

$$
\begin{aligned}
{[\tau]_{+} } & =\omega\left(\beta_{+}\right), & {\left[\tau_{-}\right]_{-}=\alpha\left(\beta_{-}\right) } \\
\beta_{+} & =\beta_{X_{+}(q)}, & \beta_{-}=\beta_{X_{-}(q)}
\end{aligned}
$$

We can assume that $U$ is chosen to render

$$
\begin{aligned}
& H_{+}(r) \triangleq \omega\left(\beta_{X_{+}(r)}\right) \in I_{\infty}^{+}(\tau(0)), \\
& H_{-}(r) \triangleq \omega\left(\beta_{X_{-}(r)}\right) \in I_{\infty}^{-}(\tau(0))
\end{aligned}
$$

for all $r \in U$.
For some orthonormal basis $Y_{1}=\tau^{\prime}(0), Y_{2}$ we can define invertible maps

$$
\begin{array}{ll}
I_{+}: \mathbb{R} \rightarrow I_{\infty}^{+}(\tau(0)), & s \mapsto\left[\gamma_{\left.\cosh s Y_{1}+\sinh s Y_{2}\right]}\right. \\
I_{-}: \mathbb{R} \rightarrow I_{\infty}^{-}(\tau(0)), & s \mapsto\left[\gamma_{-\cosh s Y_{1}+\sinh s Y_{2}}\right]
\end{array}
$$

Lemma 2.2 tells us that $f_{+}(t)=I_{+}^{-1} \circ H_{+} \circ \beta_{-}(t)$ and $f_{-}(t)=I_{-}^{-1} \circ H_{-} \circ$ $\beta_{+}(t), t \in I$, are both continuous functions. Here $I$ is an open interval around 0 such that $\beta_{+}(I), \beta_{-}(I) \subset U$.

Assume for contradiction that $H_{+} \circ \beta_{-}\left(t_{1}\right)=H_{+} \circ \beta_{-}\left(t_{2}\right)=[\xi]_{+}$ for some TF geodesic $\xi$ and $t_{1}<t_{2}$ such that $\beta_{-}\left(t_{1}\right), \beta_{-}\left(t_{2}\right) \in U$. Then $\beta_{-}\left(t_{2}\right) \in \partial I^{-}(\xi)$ hence $\beta_{-}\left(t_{1}\right) \in I^{-}(\xi)$. This however contradicts Lemma 7.1. Consequently $H_{+} \circ \beta_{-}$and also $H_{-} \circ \beta_{+}$are both injective on $I$.

It follows from the Implicit Function Theorem that there exists a smooth mapping

$$
G: I_{-} \times I_{+} \rightarrow U
$$

such that $\beta_{-}\left(t_{-}\right), \beta_{+}\left(t_{+}\right) \in U$, and $G\left(t_{-}, t_{+}\right)$is a point of intersection of $\beta_{X_{+}\left(\beta_{-}\left(t_{-}\right)\right)}$and $\beta_{X_{-}\left(\beta_{+}\left(t_{+}\right)\right)}$for every $\left(t_{-}, t_{+}\right) \in I_{-} \times I_{+}$. Here $I_{-}$and $I_{+}$are open intervals around 0 . There are $\epsilon_{-}, \epsilon_{+}>0$ such that

$$
\begin{gathered}
]-\epsilon_{+}, \epsilon_{+}\left[\subset \operatorname{Im} f_{+},\right]-\epsilon_{-}, \epsilon_{-}\left[\subset \operatorname{Im} f_{-},\right. \\
f_{+}^{-1}(s) \in I_{-}, \quad f_{-}^{-1}(s) \in I_{+},
\end{gathered}
$$

whenever $s \in]-\epsilon_{-}, \epsilon_{-}[$, and $s \in]-\epsilon_{+}, \epsilon_{+}[$. According to the proof of Proposition 8.3 there exists a $\xi \in \Gamma$ such that

$$
\omega_{*}=\xi\left([\sigma]_{+}\right)=I_{+}\left(s_{+}\right)
$$

where $\left.s_{+} \in\right]-\epsilon_{+}, \epsilon_{+}\left[\right.$. Define $\left.s_{-} \in\right]-\epsilon_{-}, \epsilon_{-}[$by

$$
\alpha_{*}=\left[\tau_{-}\right]_{-}=I_{-}\left(s_{-}\right)
$$

and also $t_{-}=f_{+}^{-1}\left(s_{+}\right), t_{+}=f_{-}^{-1}\left(s_{-}\right)$. Then using our first assertion

$$
G\left(t_{-}, t_{+}\right) \in \partial I^{-}\left(\omega_{*}\right)=\xi \circ \beta_{p_{+}}(\mathbb{R}) \cup \xi \circ \beta_{p_{-}}(\mathbb{R})
$$

We conclude that $G\left(t_{-}, t_{+}\right)$is equal to $\xi \circ \beta_{p_{+}}\left(v_{+}\right)$or $\xi \circ \beta_{p_{-}}\left(v_{-}\right)$for some $v_{+}, v_{-} \in \mathbb{R}$. Notice that

$$
\begin{aligned}
& K\left(\beta_{p_{+}}\left(v_{+}\right)\right)=K\left(\xi \circ \beta_{p_{+}}\left(v_{+}\right)\right)=K\left(\mu^{-n}\left(\beta_{p_{+}}\left(v_{+}\right)\right)\right) \rightarrow K\left(p_{+}\right) \\
& K\left(\beta_{p_{-}}\left(v_{-}\right)\right)=K\left(\xi \circ \beta_{p_{-}}\left(v_{-}\right)\right)=K\left(\mu^{-n}\left(\beta_{p_{-}}\left(v_{-}\right)\right)\right) \rightarrow K\left(p_{-}\right)
\end{aligned}
$$

as $n \rightarrow+\infty$, hence

$$
\begin{aligned}
& K\left(\beta_{p_{+}}\left(v_{+}\right)\right)=K\left(\xi \circ \beta_{p_{+}}\left(v_{+}\right)\right)=K\left(p_{+}\right) \\
& K\left(\beta_{p_{-}}\left(v_{-}\right)\right)=K\left(\xi \circ \beta_{p_{-}}\left(v_{-}\right)\right)=K\left(p_{-}\right)
\end{aligned}
$$

It follows that we can take a sequence $\left\{\xi_{n}\right\}_{n \in \mathbb{N}}$ in $\Gamma$ and $\left\{v_{n}^{+}\right\}$or $\left\{v_{n}^{-}\right\}$ in $\mathbb{R}$ such that $\left\{\xi_{n} \circ \beta_{p_{+}}\left(v_{n}^{+}\right)\right\}_{n \in \mathrm{~N}}$ or $\left\{\xi_{n} \circ \beta_{p_{-}}\left(v_{n}^{-}\right)\right\}_{n \in \mathrm{~N}}$ is a sequence in $M$ converging to $q$. The sectional curvatures at the arbitrary point $q$ is then either $K\left(p_{-}\right)$or $K\left(p_{+}\right)$, and the Theorem follows.

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