# BLASCHKE'S THEOREM FOR CONVEX HYPERSURFACES 

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## 1. Introduction

The aim of this paper is to prove some generalizations of the following theorem.

Theorem A [6]. Let M and $\tilde{M}$ be compact connected oriented hypersurfaces in $R^{n}$ with positive curvatures. Assume that the second fundamental form of $\tilde{M}$ at $\tilde{m}$ is great than or equal to the second fundamental form of $M$ at $m$ whenever the Gauss' map of $\tilde{M}$ at $\tilde{m}$ is equal the Gauss' map of $M$ at $m$. Then, up to a translation, $\tilde{M}$ is included in the convex region bounded by $M$.

We will prove a similar theorem when $M$ and $\tilde{M}$ are complete rather than compact. Actually, with additional hypothesis on the curvatures of $M$ and $\tilde{M}$ our proof holds for hypersurfaces of a Hilbert space.

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## 2. Notation and main results

Except when explicitly stated, $M$ and $\tilde{M}$ will denote complete connected oriented hypersurfaces in $R^{n}$ with positive curvatures (that is, at each two-dimensional subspace $\sigma$ of $T_{m} M$, the sectional curvature $K(\sigma)$ is strictly positive). Such manifolds are convex by Sacksteder's theorem [7]. We will denote the Gauss' normal map of $M$ by $N$, its inverse (when it exists) by $n$, and the second fundamental form of $M$ by $\tilde{I I}$, and we will consider $M$ and $\tilde{M}$ oriented by outward normals. We will also use $\tilde{N}, \tilde{n}$ and $\widetilde{I}$ to denote the corresponding objects in $\tilde{M}$.

Definition. We say that two hypersurfaces $M$ and $\tilde{M}$ are internally tangent at a point $m \in M \cap \tilde{M}$ if $N(m)=\tilde{N}(\tilde{m})$.

Now we can state the main result of our work.
Theorem 1. Let $M$ and $\tilde{M}$ be two complete hypersurfaces in $R^{n}$ such that if $N(m)=\tilde{N}(\tilde{m})$ then

$$
I I_{m}(v) \leqslant \widetilde{I}_{\tilde{m}}(v)
$$

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for all $v \in T_{m} M \cong T_{\tilde{m}} \tilde{M}$. Assume that $M$ and $\tilde{M}$ are internally tangent at a point $m_{0} \in M \cap \tilde{M}$. Then $\tilde{M}$ is included in the convex body of $M$.

Definition. We say that a convex hypersurface $\tilde{M}$ rolls freely inside the convex hypersurface $M$ if whenever $\tilde{M}$ is internally tangent to $M$ at a point, then $\tilde{M}$ lies in the convex region bounded by $M$.

Corollary. Let $M$ be a hypersurface in $R^{n}$ such that its principal curvatures are bounded above. Then the sphere with radius equal to the inverse of the supremum of the principal curvatures of $M$ rolls freely inside $M$. Moreover $M$ is tangent to the sphere at a point or along a geodesic arc.

Remark 1. Assume that $N(M) \cap \tilde{N}(\tilde{M}) \neq \varnothing$. It is easy to see that $M$ and $\tilde{M}$ are internally tangent up to a translation. Therefore, if $N(M) \cap \tilde{N}(\tilde{M}) \neq$ $\varnothing$ in Theorem 1, we can drop out the hypothesis "internally tangent" and replace its conclusion by "up to a translation $\tilde{M}$ is included in the convex body of $M$ ".

Historical comments. W. Blaschke [1, pp. 114-117] proved Theorem 1 for closed curves in $R^{2}$. H. Karcher [5] formulated and proved, for closed curves in the sphere, a proposition analogous to the corollary. D. Koutroufiotis [4] proved Theorem 1 for complete curves in $R^{2}$ and complete hypersurfaces in $R^{3}$ (but his proof is different from the one presented here). Finally J. Rauch [6], by using Blaschke's techniques, proved Theorem 1 for compact hypersurfaces in $R^{n}$. Our proof is inspired in [6] that in its turn was inspired in [1].

## 3. Proof of the main result

First a sketch of the proof. We know from H . Wu [8] that $N$ is a diffeomorphism from $M$ onto its image and that $N(M)$ is an open convex set in the unit sphere in $R^{n}$. On the other hand, we will prove (Lemma 2) that $\tilde{M}$ is included in the convex body of $M$ if and only if $h(x)=\langle n(x)-\tilde{n}(x), x\rangle$, $x \in N(M)$, does not change sign. By restricting $h$ to an arc of great circle $C$, $C \subseteq N(M)$, we obtain a second order differential equation for $h$ the solution of which has a constant sign on $C$. The result follows by convexity of $N(M)$.

We now start the proof. By defining $I I_{m}(v)=\left\langle d N_{m} \cdot v, v\right\rangle, m \in M, v \in$ $T_{m} M$, and by noting the previous orientation convention we have that the principal curvatures are positive.

Lemma 1. Let $M$ and $\tilde{M}$ satisfy the hypothesis of Theorem 1 . Then $N(M) \subseteq$ $\tilde{N}(\tilde{M})$.

Proof. Assume that $\tilde{M}$ is bounded. Then $\tilde{N}(\tilde{M})=S^{n-1}$, and there is nothing to prove. Suppose that $\tilde{M}$ is unbounded and that $N(M) \notin \tilde{N}(\tilde{M})$. Let $y \in N(M)-\tilde{N}(\tilde{M})$. It follows from the convexity of $N(M)$ and the fact that $M$ and $\tilde{M}$ are internally tangent at the point $m_{0}$, that there exists a minimal
geodesic $\underset{\tilde{N}}{\gamma}:[0, l] \rightarrow S^{n-1}$ with $\gamma([0, l]) \subseteq N(M), \gamma(l)=y$ and $\gamma(0)=m_{0}$. Since $\tilde{N}(\tilde{M})$ is connected, there exists a point $t_{0} \in(0, l)$ such that $\left(\gamma\left[0, t_{0}\right)\right) \subseteq$ $\tilde{N}(\tilde{M})$ and $\gamma\left(t_{0}\right)$ belongs to the boundary of $\tilde{N}(\tilde{M})$. Therefore we can define a curve $e:\left[0, t_{0}\right) \rightarrow \tilde{M}$ by setting $\tilde{e}(t)=\tilde{n}(\gamma(t))$. Since $\tilde{M}$ is unbounded

$$
\begin{equation*}
\lim _{t \rightarrow t_{0}} d(\tilde{e}(t), \tilde{e}(0))=\infty, \tag{1}
\end{equation*}
$$

where $d$ denotes the distance function in $\tilde{M}$. We claim that there exists a sequence of points $\left(t_{n}\right) \subset(0, l)$ with $\lim _{n} t_{n}=t_{0}$, such that if $v_{n}=$ $\tilde{e}^{\prime}\left(t_{n}\right) /\left|\tilde{e}^{\prime}\left(t_{n}\right)\right|$ then

$$
\begin{equation*}
\lim _{n}\left\langle d \tilde{N}_{\tilde{e}\left(t_{n}\right)} \cdot v_{n}, v_{n}\right\rangle=0 \tag{2}
\end{equation*}
$$

In fact, since $\tilde{N}(\tilde{e})$ is a geodesic in $S^{n-1}$ we have

$$
\int_{0}^{t_{0}}\left|d \tilde{N}_{\tilde{e}(t)} \cdot \tilde{e}(t)\right| d t \leqslant 2 \pi
$$

By using in succession the equality

$$
\int_{0}^{t_{0}}\left|d \tilde{N}_{\tilde{e}(t)} \cdot \tilde{e}^{\prime}(t)\right| d t=\int_{0}^{t_{0}}\left|d \tilde{N}_{\tilde{e}(t)} \cdot v\right|\left|\tilde{e}^{\prime}(t)\right| d t
$$

where $v=\tilde{e}^{\prime}(t) /\left|\tilde{e}^{\prime}(t)\right|$, and using Schwarz's inequality in the integrand, we obtain

$$
\begin{equation*}
\int_{0}^{t_{0}}\left|\tilde{e}^{\prime}(t)\right|\left\langle d \tilde{N}_{\tilde{e}(t)} \cdot v, v\right\rangle d t \leqslant 2 \pi . \tag{3}
\end{equation*}
$$

Our claims follows from (1) and (3). Now let $e:[0, l) \rightarrow M$ be defined by $e(t)=n(\gamma(t))$. Thus from the fact that $e\left(t_{0}\right)$ is in $M$ and that the principal curvatures of $M$ are positive, it follows that

$$
\begin{equation*}
\lim _{n}\left\langle d N_{e\left(t_{n}\right)} \cdot v_{n}, v_{n}\right\rangle>0, \tag{4}
\end{equation*}
$$

where $v_{n}=e^{\prime}\left(t_{n}\right) /\left|e^{\prime}\left(t_{n}\right)\right|$, and $t_{n}$ is given by (2). Since by hypothesis $I I_{e\left(t_{n}\right)}\left(v_{n}\right)$ $\leqslant I I_{\tilde{e}\left(t_{n}\right)}\left(v_{n}\right)$ we have

$$
\begin{equation*}
\lim _{n}\left\langle d N_{e\left(t_{n}\right)} \cdot v_{n}, v_{n}\right\rangle \leqslant \lim _{n}\left\langle d \tilde{N}_{\tilde{e}\left(t_{n}\right)} \cdot v_{n}, v_{n}\right\rangle . \tag{5}
\end{equation*}
$$

But from (2) the second member of (5) is zero, which contradicts the inequality (4). Therefore $N(M) \subseteq \tilde{N}(\tilde{M})$, and this completes the proof of Lemma 1.

Remark 2. Let $M$ and $\tilde{M}$ be two hypersurfaces such that $N(m)=\tilde{N}(\tilde{m})$ implies that $I_{m}(v)=\widetilde{I}_{\tilde{m}}(v)$ for all $v \in T_{\tilde{m}} M \cong T_{\tilde{m}} M$. Then the above proof shows that up a rigid motion, $N(M)=\tilde{N}(\tilde{M})$.

Remark 3. It is interesting to notice the following fact which is contained in the above proof: let $e:(a, b) \rightarrow M$ ( $M$ complete hypersurface in $R^{n}$, noncompact and not necessarily convex) be a differentiable curve of infinite
length, such that $N \circ e:(a, b) \rightarrow S^{n-1}$ has finite length. Then either

$$
\lim _{t \rightarrow b}\left(\inf _{\substack{s>t \\ 1<i<n-1}} k_{i}(e(s))\right) \leqslant 0,
$$

or

$$
\lim _{t \rightarrow a}\left(\inf _{\substack{s<t \\ 1<i<n-1}} k_{i}(e(s))\right) \leqslant 0
$$

where $k_{i}(e(s))$ denotes the $i$ th principal curvature at the point $e(s)$.
Since the Gauss' normal map is a diffeomorphism and $N(M)$ is included in $\tilde{N}(\tilde{M})$, we can define on $N(M)$ a map $h: N(M) \rightarrow R$ by setting $h(y)=\langle n(y)$ $-\tilde{n}(y), y\rangle, y \in N(M)$. The lemma below characterizes through the function $h$ the fact that $\tilde{M}$ is included in the convex body of $M$.

Lemma 2. Let $M$ and $\bar{M}$ satisfy the hypothesis of Theorem 1. Then $h$ does not change sign if and only if $\tilde{M}$ is included in the convex body of $M$.

Proof. Suppose that $\tilde{M}$ is included in the convex body of $M$. The vector radius $\tilde{m} m$, for all $\tilde{m} \in M$ and all $m \in M$, points to the positive half-space determined by $T_{m} M$ and $N(m)$. Thus, if $y=N(m)$, we have $h(y) \geqslant 0$.

Conversely, suppose that $h \geqslant 0$, and denote by $K$ the convex body of $M$. If $\tilde{M}-K \neq \varnothing$, we will show that there exists $y \in N(M)$ such that $h(y)<0$, which contradicts the hypothesis and concludes the proof. In fact, let $m_{1} \in M$ be a minimum for the function $\beta(m)=|m-\tilde{m}|$ for a fixed $\tilde{m} \in M-K$. Thus $\tilde{m}-m_{1}$ is parallel to a certain $y=N\left(m_{1}\right)$. We set $\tilde{m}-m_{1}=\lambda y$ where $|y|=1$, and observe that $\lambda>0$. Since $\tilde{M}$ is convex, we have

$$
0 \leqslant\langle\tilde{n}(y)-\tilde{m}, y\rangle .
$$

Hence

$$
0 \leqslant\left\langle\tilde{n}(y)-m_{1}, y\right\rangle+\left\langle m_{1}-\tilde{m}, y\right\rangle=-h(y)-\lambda,
$$

implying $h(y)<0$.
The proof of the lemma below can be found in [6].
Lemma 3. Let $T$ and $S$ be two positive (invertible) operators in a hilbert space $H$. If $T \geqslant S$, then $T^{-1} \leqslant S^{-1}$.
Proof of Theorem 1. Let $m_{0}$ be the point where $M$ and $\tilde{M}$ are internally tangent. Set $y_{0}=N\left(m_{0}\right)=\tilde{N}\left(m_{0}\right)$. Parametrize a great circle $C$ passing through $y_{0}$ by $\alpha(s)$, where $s$ is the arc length in such a way that $\alpha(0)=y_{0}$. Set $h(s)=h(\alpha(s))$. We will show that

$$
h^{\prime \prime}+h=u,
$$

where $u \geqslant 0$ and

$$
\begin{equation*}
h^{\prime}(0)=h(0)=0 \tag{7}
\end{equation*}
$$

First we claim that the support function $p$ restricted to $C$,

$$
p(s)=\langle n(\alpha(s)), \alpha(s)\rangle,
$$

satisfies the equation

$$
p^{\prime \prime}+p=\left\langle\alpha^{\prime}, n^{\prime}\right\rangle
$$

In fact

$$
p^{\prime}=\left\langle n^{\prime}, \alpha\right\rangle+\left\langle n, \alpha^{\prime}\right\rangle=\left\langle n, \alpha^{\prime}\right\rangle
$$

because $n^{\prime}=d n \cdot \alpha^{\prime}$ is orthogonal to $\alpha$ for all $s$. Since $\alpha$ is a parametrization by arc length we obtain, by derivation of the last equation,

$$
p^{\prime \prime}+p=\left\langle\alpha^{\prime}, n^{\prime}\right\rangle
$$

which was our claim. If we restrict $\tilde{p}$ to $\alpha$, we obtain similarly

$$
\tilde{p}^{\prime \prime}+\tilde{p}=\left\langle\alpha^{\prime}, \tilde{n}^{\prime}\right\rangle .
$$

It follows that

$$
h^{\prime \prime}+h=\left\langle\alpha^{\prime}, n^{\prime}-\tilde{n}^{\prime}\right\rangle
$$

By using Lemma 3, the fact that $n^{\prime}=d n \cdot \alpha^{\prime}, \tilde{n}^{\prime}=d \tilde{n} \cdot \alpha^{\prime}$, and the hypothesis of the second fundamental forms we obtain

$$
h^{\prime \prime}+h=u
$$

where $u$ is a nonnegative function in $s$. Moreover from the fact that $M$ and $\tilde{M}$ are internally tangent at the point $m_{0}=n\left(y_{0}\right)=\tilde{n}\left(y_{0}\right)$ we have that the last equation satisfies the initial conditions

$$
h(0)=h^{\prime}(0)=0 .
$$

This proves (6) and (7). It is easy to see, by derivation, that

$$
h(s)=\int_{0}^{s} u(t) \operatorname{sen}(s-t) d t
$$

is the solution to (6) which satisfies (7). We notice that if $-\pi \leqslant s \leqslant \pi$, then $h(s) \geqslant 0$. Since $N(M)$ is included in a hemisphere [8] and $s$ is the arc length of a geodesic in $S^{n-1}$, we obtain that $h$ is nonnegative on $\alpha$. But $N(M)$ is convex [8]. Therefore $h$ is nonnegative on $N(M)$. By Lemma 2 this concludes the proof of Theorem 1.

Proof of corollary. The first part is an immediate consequence of Theorem 1. In fact, in this case $M$ is complete and $\tilde{M}$ is a sphere of radius $1 / a$, where $a$ is an upper bound for the principal curvatures, in particular the supremum. The second claim follows immediately from the following facts:
(i) If $h\left(s_{0}\right)=0$ for any $s_{0}$ then $h=0$ in $\left[0, s_{0}\right]$.
(ii) If two hypersurfaces $M$ and $\tilde{M}$ in $R^{n}$ are tangent along a curve $C$, then the geodesic curvature of $C$ is the same whether with respect to $M$ or $\tilde{M}$. This concludes the proof of corollary.

At this point it is interesting to remark that the function $h(s)=$ $\int_{0}^{s} u(t) \operatorname{sen}(s-t) d t$ allows us to conclude that if the second fundamental forms are equal for all points then the hypersurfaces $M$ and $\tilde{M}$ coincide (see Remark 2).

## 4. Generalizations

A careful observation shows that the proof of Theorem 1 still holds for hypersurfaces in a Hilbert space once the following two facts are true: (i) the Gauss' normal map $N$ is a diffeomorphism onto its image, (ii) $N(M)$ is convex.

By using a result of R. L. de Andrade [2] we can make sure of the two facts mentioned above if we assume that the hypersurfaces have sectional curvatures bounded away from zero (that is, for each point $m \in M$ there exists $\delta(m)>0$ such that $K(\sigma) \geqslant \delta(m)$ for all two-dimensional subspace $\sigma \subseteq T_{m} M$ where $K(\sigma)$ is the sectional curvature of the $\sigma$-plane). Therefore we can obtain

Theorem 1'. Let $M$ and $\tilde{M}$ be connected, convex, complete, oriented hypersurfaces in a Hilbert space $H$ with sectional curvatures bounded away from zero and such that if $N(M)=\tilde{N}(\tilde{M})$ then

$$
\left\langle d N_{m} \cdot v, v\right\rangle \leqslant\left\langle d \tilde{N}_{\tilde{m}} \cdot v, v\right\rangle,
$$

for all $v \in T_{m} M \cong T_{\tilde{m}} \tilde{M}$. Assume that $M$ and $\tilde{M}$ are internally tangent at a point $m_{0} \in M \cap \tilde{M}$. Then $\tilde{M}$ is included in the convex body of $M$.

The following corollaries are proved in a way similar to the corollary of Theorem 1.

Corollary 1. Let $M$ and $\tilde{M}$ be as in the Theorem $1^{\prime}$, and assume that $M$ is bounded. Then $\tilde{M}$ is bounded.

Corollary 2. Let $M$ be a connected, convex, complete, oriented hypersurface in a Hilbert space with sectional curvatures bounded away from zero and such that

$$
a=\operatorname{Sup}\left\{\left\langle d N_{m} \cdot v, v\right\rangle, v \in T_{m} M,|v|=1, m \in M\right\}
$$

is finite. Then the sphere with radius $1 / a$ rolls freely inside $M$, and is tangent to $M$ at a point or along a geodesic arc.

Corollary 3. Let $M$ be a connected, convex, complete, oriented hypersurface in a Hilbert space $H$ with sectional curvatures bounded away from zero and such that

$$
a=\operatorname{Inf}\left\{\left\langle d N_{m} \cdot v, v\right\rangle, m \in M, v \in T_{m} M,|v|=1\right\}
$$

is not zero. Then the hypersurface $M$ rolls freely inside the sphere of radius $1 / a$. Moreover, $M$ is bounded with diameter smaller than $2 \pi / a$, and is tangent to the sphere at a point or along a geodesic arc.

A crucial point in the proof of Theorem 1 is the fact that the hypersurfaces have positive curvatures. A natural question is whether the same theorem would be true when we consider nonnegative rather than positive curvatures.

If two curves in $R^{2}$ have subsets with zero curvatures, the theorem is not true as we see in the followng example.

Example. We consider two curves in $R^{2}$ by given

$$
\begin{gathered}
\gamma_{1}(t)=\left(p t, t^{4}\right) t \in R \text { and } p>1, \\
\gamma_{2}(s)=\left\{\begin{array}{lll}
\left(s,(s-1)^{4}\right), & s \in R, \quad s \geqslant 1, \\
(s, 0), & s \in R, & |s| \leqslant 1, \\
\left(s,(s+1)^{4}\right), & s \in R, & s \leqslant-1 .
\end{array}\right.
\end{gathered}
$$

If $N_{1}\left(\right.$ resp. $\left.N_{2}\right)$ is the unit outward normal on $\gamma_{1}$ (resp. $\gamma_{2}$ ), we have

$$
\begin{gathered}
N_{1}(t)=\frac{1}{\left(p^{2}+16 t^{6}\right)^{1 / 2}}\left(4 t^{3},-p\right), \\
N_{2}(s)= \begin{cases}(0,-1), & \text { if }|s| \leqslant 1, \\
\frac{1}{\left(1+16(s-1)^{6}\right)^{1 / 2}}\left(4(s-1)^{3},-1\right), & \text { if } s \geqslant 1, \\
\frac{1}{\left(1+16(s+1)^{6}\right)^{1 / 2}}\left(4(s+1)^{3},-1\right), & \text { if } s \leqslant-1 .\end{cases}
\end{gathered}
$$

Therefore $N_{1}(t)=N_{2}(s)$ if and only if $s \geqslant 1$ and $t=\sqrt[3]{p}(s-1)$ or $s \leqslant-1$ and $t=\sqrt[3]{p}(s+1)$. Since

$$
k\left(\gamma_{1}(t)\right)=\frac{12 t^{2}}{\left(p^{2}+16 t^{6}\right)^{1 / 2}}
$$

and

$$
k\left(\gamma_{2}(s)\right)= \begin{cases}0, & \text { if }|s| \leqslant 1 \\ \frac{12(s-1)^{2}}{\left(1+16(s-1)^{6}\right)^{1 / 2}}, & \text { if } s \geqslant 1 \\ \frac{12(s+1)^{2}}{\left(1+16(s+1)^{6}\right)^{1 / 2}}, & \text { if } s \leqslant-1\end{cases}
$$

we have that

$$
k\left(\gamma_{1}(t)\right) \geqslant k\left(\gamma_{2}(s)\right)
$$

whenever $N_{1}(t)=N_{2}(s)$. But the points $\left(p t, t^{4}\right)$ with $t>1 /(p-1)$ are not in
the convex region bounded by $\gamma_{2}(R)$. This example shows that the Koutroufiotis' result [4], for curves in $R^{2}$, is the best possible.

It would be interesting to prove or to find a counterexample for the following statement.

Let $M$ and $\tilde{M}$ be connected, complete, oriented, convex hypersurfaces in $R^{n}$ such that if $N(m)=\tilde{N}(\tilde{m})$ then

$$
\widetilde{I}_{m}(v) \leqslant I_{\tilde{m}}(v)
$$

for all $v \in T_{m} M \approx T_{\tilde{m}} \tilde{M}$. Assume that $M$ has nonnegative curvatures, $\tilde{M}$ has positive curvatures, and $M$ and $\tilde{M}$ are internally tangent at a point $m_{0} \in M \cap$ $\tilde{M}$. Then $\tilde{M}$ is included in the convex body of $M$.

We refer to [4] for a proof of this fact when $M$ and $\tilde{M}$ are curves in $R^{2}$.

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