# PSEUDO-HERMITIAN STRUCTURES ON A REAL HYPERSURFACE 

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## Introduction

The invariance properties of a real hypersurface $M$ (of real dimension $2 n+1$ ) in complex $(n+1)$ space $C^{n+1}$ with respectt o the infinite pseudo-group of biholomorphic transformations are the object of study in pseudo-conformal geometry. The systematic study of such properties for hypersurfaces with nondegenerate Levi form was first made by Cartan [2] in 1932. More recently, the study of invariants for such $M$ was taken up by S. S. Chern and J. Moser [6]. A main aspect of the theory is the existence of a complete system of local differential invariants.

In this paper we take a somewhat different point of view. Such a manifold $M$ has an integrable, nondegenerate, Cauchy-Riemann structure. In particular, there is a subbundle $H(M)$ of the tangent bundle $T(M)$ each fiber of which has the structure of a complex $n$-dimensional vector space. We single out a real nonvanishing one-form $\theta$ annihilating $H(M)$ and consider invariants of the pair ( $M, \theta$ ). $(M, \theta)$ will be called a pseudo-hermitian manifold.

In § 1 we apply the Cartan method of equivalence [3] to find a compete system of invariants. This results in a connection and curvature forms on the coframe bundle of $M$. These are not, in general, pseudo-conformal invariants; they depend on the choice of $\theta$. In §3 we consider the relation between these two systems of invariants. (3.8) gives a formula for the fourth order curvature tensor of Chern and Moser. A similar formula was given by Bochner [1] as a formal analogue of the conformal curvature tensor for a Kähler manifold. Here a geometric interpretation of the formula is given. In $\S 4$ we apply the theory to some examples. It is shown that an ellipsoid is not, in general, equivalent to a sphere.

Also, the author wishes to remark that the theory developed here provides a complete system of invariants for nondegenerate real hypersurfaces under vol-ume-preserving biholomorphic transformations, when the ambient complex space is equipped with a volume form.
We will follow the notation adopted in [6]. Small Greek indices run from 1 to $n$, and the summation convention is used. The Levi form $g_{\alpha \bar{\beta}}$ and its inverse $g^{\beta \alpha}$ are used to lower and raise indices, e.g.,

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$$
\theta_{\alpha}=g_{\alpha \beta} \theta^{\bar{\beta}}, \quad A_{\beta}^{\bar{\alpha}}=g^{\bar{\alpha} \gamma} A_{\gamma \beta}
$$

Thus the vertical as well as the horizontal position of an index carries information. Also, complex conjugation will be reflected in the indices, e.g.,

$$
\theta^{\bar{\beta}}=\bar{\theta}^{\beta}, \quad U_{\bar{\beta}}^{\bar{\alpha}}=\bar{U}_{\beta}^{\alpha}, \quad \bar{A}_{\alpha \bar{\beta} r}=A_{\bar{\alpha} \beta \bar{\gamma}}
$$

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## 1. The equivalence problem

Let $(M, \theta)$ denote a $(2 n+1)$-dimensional pseudo-hermitian manifold. $\theta$ is a fixed real one-form, and locally we can choose $n$ complex one-forms $\theta^{\alpha}$, so that $\left(\theta, \theta^{\alpha}, \theta^{\alpha}\right)$ form a basis of complex covectors. They are determined up to

$$
\begin{equation*}
\theta=\theta^{\prime}, \quad \theta^{\alpha}=\theta^{\beta} U_{\beta}^{\alpha}+\theta v^{\alpha}, \quad \theta^{\bar{\alpha}}=\theta^{\prime \bar{\beta}} U_{\bar{\beta}}^{\bar{\alpha}}+\theta v^{\bar{\alpha}} \tag{1.1}
\end{equation*}
$$

We require our structure to be integrable in the sense that

$$
\begin{equation*}
d \theta \equiv d \theta^{\alpha} \equiv 0, \quad \bmod \theta, \theta^{r} \tag{1.2}
\end{equation*}
$$

Because $\theta=\bar{\theta}$, we must have

$$
\begin{equation*}
d \theta=i g_{\alpha \bar{\beta}} \theta^{\alpha} \wedge \theta^{\bar{\beta}}+\theta \wedge\left(\eta_{\alpha} \theta^{\alpha}+\eta_{\bar{\alpha}} \theta^{\bar{\alpha}}\right) \tag{1.3}
\end{equation*}
$$

where $\eta_{\bar{\alpha}}=\bar{\eta}_{\alpha}$, and $g_{\alpha \bar{\beta}}$ is hermitian:

$$
\begin{equation*}
g_{\alpha \bar{\beta}}=\bar{g}_{\beta \bar{\alpha}}=g_{\bar{\beta} \alpha} \tag{1.4}
\end{equation*}
$$

Under the change (1.1) we have

$$
\begin{equation*}
g_{\alpha \bar{\beta}}=U_{\alpha}^{-1}{ }_{\alpha}^{\rho} g_{\rho \bar{\sigma}}^{\prime} U^{-1} \overline{\bar{\beta}}^{\bar{\sigma}} . \tag{1.5}
\end{equation*}
$$

We will also assume that $(M, \theta)$ is nondegenerate in the sense that the matrix (1.4) is nonsingular at each point. It will have a signature, say $p$ negative and $q$ positive eigenvalues, $p+q=n$, which we will speak of as the signature of $(M, \theta)$. If $g_{\alpha \bar{\beta}}$ is negative definite, $(M, \theta)$ will be said to be strongly pseudoconvex. In the computations to follow $g_{\alpha \bar{\beta}}$ and its inverse $g^{\bar{\beta} \alpha}$ will be used to lower and raise indices.

In other words, we have a nondegenerate, integrable $G$-structure on $M, G$ being the group of matrices

$$
\left(\begin{array}{ccc}
1 & v^{\alpha} & v^{\bar{\alpha}}  \tag{1.6}\\
0 & U_{\beta}{ }^{\alpha} & 0 \\
0 & 0 & U_{\bar{\beta}}^{\bar{\alpha}}
\end{array}\right), \quad v^{\alpha} \in \mathbf{C}, \quad\left(U_{\beta}^{\alpha}\right) \in G L(n, C)
$$

To study the equivalence problem we begin by reducing the group (1.6). Substituting (1.1) with $U_{\beta}{ }^{\alpha}=\delta_{\beta}{ }^{\alpha}$ into (1.3), we get

$$
d \theta=i g_{\alpha \beta} \theta^{\prime \alpha} \wedge \theta^{\prime \beta}+\theta \wedge\left(\eta_{\alpha}^{\prime} \theta^{\prime \alpha}+\eta_{\alpha}^{\prime} \theta^{\prime \alpha}\right),
$$

where

$$
\eta_{\alpha}^{\prime}=\eta_{\alpha}-i g_{\alpha \bar{\gamma}} v^{\overline{7}} .
$$

Since $g_{a \bar{\eta}}$ is nondegenerate we can choose $v^{r}$ so that $\eta^{\prime}{ }_{\alpha}=0$, and if $\eta_{\alpha}=\eta^{\prime}{ }_{\alpha}=0$, then $v^{\alpha}=0$.

Hence by requiring

$$
\begin{equation*}
d \theta=i g_{\alpha \beta} \theta^{\alpha} \wedge \theta^{\beta}, \tag{1.7}
\end{equation*}
$$

we can reduce our group (1.6) to $G L(n, C)$, that is, to changes

$$
\begin{equation*}
\theta^{\alpha}=\theta^{\prime \beta} U_{\beta}^{\alpha}, \quad \theta^{\bar{\alpha}}=\theta^{\prime \bar{\beta}} U_{\bar{\beta}}^{\bar{\alpha}} . \tag{1.8}
\end{equation*}
$$

By also requiring

$$
\begin{equation*}
g_{\alpha \bar{\beta}}=\text { const. }= \pm \delta_{\alpha \bar{\beta}} \tag{1.9}
\end{equation*}
$$

we can reduce our group further to $U(p, q)$, the unitary group with signature ( $p, q$ ). The conditions (1.7) and (1.9) are invariant under maps preserving our structure.

For a geometric interpretation of (1.7) let us consider the dual frame

$$
\begin{equation*}
X=\bar{X}, \quad X_{\alpha}, \quad X_{\bar{\alpha}}=\bar{X}_{\alpha} \tag{1.10}
\end{equation*}
$$

to $\left(\theta, \theta^{\alpha}, \theta^{\alpha}\right)$. The transformation (1.1) gives

$$
\begin{equation*}
X^{\prime}=X+v^{\alpha} X_{\alpha}+v^{\bar{\alpha}} X_{\bar{\alpha}}, \quad X_{\alpha}=U_{\alpha}^{\beta} X_{\beta}, \quad X_{\alpha}=U_{\bar{\alpha}}{ }^{\bar{\beta}} X_{\bar{\beta}} . \tag{1.11}
\end{equation*}
$$

The condition (1.7) then singles out a unique transversal $X$ to $H(M)$.
Our admissible coframes are now those $\left(\theta, \theta^{\alpha}, \theta^{\alpha}\right)$ for which (1.7) holds. We allow $g_{\alpha \bar{\beta}}$ to be variable. Let $P$ be the bundle of such coframes with structure group $G L(n, C)$. On $P$ we have globally defined functions $g_{\alpha \bar{\xi}}$ given locally by (1.5) and globally defined complex one-forms $\theta^{\alpha}, \theta^{a}$ defined by (1.8), where now the $U_{\beta}{ }^{\alpha}$ are independent fibre coordinates on $P$. We also have the real one-form $\theta$ pulled up to $P$ and can view (1.7) as an equation on $P$. Since the real dimension of $P$ is $2 n^{2}+2 n+1$, we must find $2 n^{2}$ more independent, intrinsically defined one-forms on $P$.

We first differentiate (1.8) and see that locally

$$
\begin{equation*}
d \theta^{\alpha}=\theta^{\beta} \wedge\left(-U_{\beta}^{-1}{ }_{\beta}^{\gamma} d U_{r}^{\alpha}\right)+d \theta^{\prime \beta} U_{\beta}^{\alpha} . \tag{1.12}
\end{equation*}
$$

Because of the integrability condition (1.2) for $\theta, \theta^{\prime \alpha}$, we have

$$
\begin{equation*}
d \theta^{\prime \beta} U_{\beta}^{\alpha}=\theta^{\beta} \wedge \xi_{\beta}{ }^{\alpha}+\theta \wedge \xi^{\alpha} \tag{1.13}
\end{equation*}
$$

for some one-forms $\xi_{\beta}{ }^{\alpha}, \xi^{\alpha}$ satisfying

$$
\begin{equation*}
\xi_{\beta}{ }^{\alpha} \equiv \xi^{\alpha} \equiv 0, \quad \bmod \theta, \theta^{r}, \theta^{7} \tag{1.14}
\end{equation*}
$$

It follows from (1.12), (1.13),(1.14), and Cartan's lemma that the most general such expression of type (1.12) is

$$
\begin{equation*}
d \theta^{\alpha}=\theta^{\beta} \wedge \omega_{\beta}{ }^{\alpha}+\theta \wedge \tau^{\alpha} \tag{1.15}
\end{equation*}
$$

where $\omega_{\beta}{ }^{\alpha}$ and $\tau^{\alpha}$ are one-forms satisfying

$$
\begin{gather*}
\omega_{\beta}^{\alpha} \equiv-U^{-1}{ }_{\beta} \gamma d U_{r}^{\alpha}, \quad \bmod \theta, \theta^{r}, \theta^{\bar{\gamma}},  \tag{1.16}\\
\tau^{\alpha} \equiv 0, \quad \bmod \theta, \theta^{r}, \theta^{\overline{7}} \tag{1.17}
\end{gather*}
$$

From the form of (1.15) we see that we may require

$$
\begin{equation*}
\tau^{\alpha} \equiv 0, \quad \bmod \theta^{\tau} \tag{1.18}
\end{equation*}
$$

Now the $\omega_{\beta}{ }^{\alpha}$ are determined up to a transformation of the form

$$
\begin{equation*}
\omega_{\beta}{ }^{\alpha}=\tilde{\omega}_{\beta}{ }^{\alpha}+C_{\beta}{ }^{\alpha}{ }_{\gamma} \omega^{\gamma}, \quad C_{\beta}{ }^{\alpha}{ }_{r}=C_{r}^{\alpha}{ }_{\beta}^{\alpha}, \tag{1.19}
\end{equation*}
$$

and the $\tau^{\alpha}$ are completely determined. The condition (1.18) allows us to put

$$
\begin{equation*}
\tau_{\alpha}=A_{\alpha \gamma} \theta^{r} . \tag{1.20}
\end{equation*}
$$

Now we differentiate (1.7), using (1.15), to get
(1.21) $0=i\left(d g_{\alpha \bar{\beta}}-\omega_{a}^{\gamma} g_{\gamma \bar{\beta}}-g_{\alpha \overline{\bar{\tau}}} \omega_{\bar{\beta}}^{\bar{F}}\right) \wedge \theta^{\alpha} \wedge \theta^{\bar{\beta}}+i \theta \wedge\left(\tau_{\alpha} \wedge \theta^{\alpha}+\theta^{\alpha} \wedge \tau_{\alpha}\right)$.

With (1.20) substituted into (1.21), we see that

$$
\begin{equation*}
d g_{\alpha \bar{\beta}}-\omega_{\alpha \bar{\beta}}-\omega_{\bar{\beta} \alpha}=A_{\alpha \beta_{r}} \theta^{r}+B_{\alpha \beta \bar{\gamma}} \theta^{\bar{T}}, \tag{1.22}
\end{equation*}
$$

where

$$
A_{\alpha \bar{\beta} r}=A_{r \bar{\beta} \alpha}, \quad B_{\alpha \bar{\beta} \bar{\gamma}}=B_{\alpha \bar{\gamma} \bar{\beta}}
$$

and that

$$
\begin{equation*}
\tau_{\alpha} \wedge \theta^{\alpha}=0, \quad \text { or } A_{\alpha \gamma}=A_{\gamma \alpha} \tag{1.23}
\end{equation*}
$$

The hermitian condition (1.4) implies

$$
B_{\alpha \bar{\beta} \bar{\eta}}=A_{\tilde{\beta} \alpha \bar{\gamma}} .
$$

It therefore follows that the change

$$
\begin{equation*}
\omega_{\beta \alpha} \rightarrow \omega_{\beta \alpha}+A_{\beta \alpha \gamma} \theta^{r} \tag{1.23a}
\end{equation*}
$$

is of the form (1.19) and reduces (1.22) to

$$
\begin{equation*}
d g_{\alpha \bar{\beta}}-\omega_{\alpha}{ }_{\alpha}^{\gamma} g_{\gamma \bar{\beta}}-g_{\alpha \bar{\gamma}} \omega_{\bar{\beta}}^{\bar{\gamma}}=0 . \tag{1.24}
\end{equation*}
$$

The condition (1.24) for both $\omega_{\beta}{ }^{\alpha}$ and $\tilde{\omega}_{\beta}{ }^{\alpha}$ implies that $C_{\beta}{ }^{\alpha}{ }_{\gamma}=0$ in (1.19), so that the $\omega_{\beta}{ }^{\alpha}$ are uniquely determined. We have derived the following theorem.

Theorem (1.1). Let $(M, \theta)$ be a nondegenerate, integrable pseudohermitian manifold. Then in the bundle $P$ over $M$ described above there is an intrinsic basis of one-forms

$$
\left\{\theta, \theta^{\alpha}, \theta^{\alpha}, \omega_{\beta}^{\alpha}, \omega_{\bar{\beta}}{ }^{\alpha}\right\},
$$

one-forms $\tau^{\alpha}$, and functions $g_{\alpha \beta}$ satisfying (1.7), (1.15), (1.18), and (1.24). We also have the relations (1.20) and (1.23).

Now that the one-forms $\omega_{\beta}{ }^{\alpha}$ are determined, we want to compute their exterior derivatives. If we differentiate (1.15) and make use of (1.7) and (1.15) itself, we get
(1.25) $0=\theta^{\beta} \wedge\left\{d \omega_{\beta}{ }^{\alpha}-\omega_{\beta}{ }^{r} \wedge \omega_{r}{ }^{\alpha}-i \theta_{\beta} \wedge \tau^{\alpha}\right\}+\theta \wedge\left\{d \tau^{\alpha}-\tau^{\beta} \wedge \omega_{\beta}{ }^{\alpha}\right\}$.

Next, we differentiate (1.24) to get

$$
\begin{equation*}
0=\left(d \omega_{\alpha}{ }^{\gamma}-\omega_{\alpha}{ }^{\mu} \wedge \omega_{\mu}{ }^{\gamma}\right) g_{\gamma \bar{\beta}}+g_{\alpha \bar{\tau}}\left(d \omega_{\bar{\beta}}^{\bar{\tau}}-\omega_{\bar{\beta}}^{\bar{\mu}} \wedge \omega_{\bar{\mu}}^{\bar{\tau}}\right) . \tag{1.26}
\end{equation*}
$$

Therefore, if we put

$$
\begin{gather*}
\Omega_{\beta}{ }^{\alpha}=d \omega_{\beta}{ }^{\alpha}-\omega_{\beta}{ }^{\gamma} \wedge \omega_{r}{ }^{\alpha}-i \theta_{\beta} \wedge \tau^{\alpha}+i \tau_{\beta} \wedge \theta^{\alpha}  \tag{1.27}\\
\Omega^{\alpha}=d \tau^{\alpha}-\tau^{\beta} \wedge \omega_{\beta}{ }^{\alpha} \tag{1.28}
\end{gather*}
$$

then we get from (1.25), noting (1.23),

$$
\begin{equation*}
0=\theta^{\beta} \wedge \Omega_{\beta}^{\alpha}+\theta \wedge \Omega^{\alpha} \tag{1.29}
\end{equation*}
$$

From (1.26) it follows that

$$
\begin{equation*}
0=\Omega_{\beta}^{{ }^{\gamma}} g_{\gamma \bar{\alpha}}+g_{\beta \gamma} \Omega_{\alpha}^{7} \equiv \Omega_{\beta \alpha}+\Omega_{\alpha \beta} . \tag{1.30}
\end{equation*}
$$

For future use we can, via (1.24), write (1.28) as

$$
\begin{equation*}
\Omega_{\alpha}=d \tau_{\alpha}-\omega_{\alpha}{ }^{\beta} \wedge \tau_{\beta} . \tag{1.31}
\end{equation*}
$$

(1.29) implies that

$$
\begin{equation*}
\Omega_{\beta \alpha}=\chi_{\beta \alpha \rho} \wedge \theta^{\rho}+\lambda_{\beta \alpha} \wedge \theta \tag{1.32}
\end{equation*}
$$

for certain one-forms $\chi_{\beta \alpha \rho}$ and $\lambda_{\beta \alpha}$, which we may assume contain no terms in $\theta$. From (1.30) and (1.32) we have

$$
0=\chi_{\beta \alpha \rho} \wedge \theta^{\rho}+\chi_{\alpha \beta \bar{\sigma}} \wedge \theta^{\bar{\sigma}}+\left(\lambda_{\beta \alpha}+\lambda_{\alpha \beta}\right) \wedge \theta
$$

which implies

$$
\chi_{\beta \alpha \rho}=B_{\beta \alpha \rho \tau} \theta^{r}-R_{\beta \alpha \rho \bar{\sigma}} \theta^{\bar{\sigma}}
$$

where

$$
\begin{gather*}
B_{\beta \alpha \rho \gamma}=B_{\beta \alpha \bar{\gamma} \rho}, \\
R_{\beta \alpha \bar{\sigma} \bar{\sigma}}=\bar{R}_{\alpha \beta \sigma \bar{\rho}}=R_{\alpha \beta \bar{\sigma} \rho} \tag{1.33}
\end{gather*}
$$

and furthermore

$$
\begin{equation*}
\lambda_{\beta \alpha}+\lambda_{\alpha \beta}=0 \tag{1.34}
\end{equation*}
$$

Thus we have

$$
\begin{equation*}
\Omega_{\beta \alpha}=R_{\beta \alpha \rho \bar{\sigma}} \theta^{\rho} \wedge \theta^{\bar{\sigma}}+\lambda_{\beta \bar{\alpha}} \wedge \theta \tag{1.35}
\end{equation*}
$$

which, substituted into (1.29), gives

$$
\begin{gather*}
R_{\beta \bar{\alpha} \rho \bar{\sigma}}=R_{\rho \alpha \beta \bar{\sigma}}  \tag{1.36}\\
0=\theta \wedge\left(\theta^{\beta} \wedge \lambda_{\beta}^{\alpha}+\Omega^{\alpha}\right)
\end{gather*}
$$

This last condition implies that

$$
\begin{equation*}
\Omega^{\alpha}=-\theta^{\beta} \wedge \lambda_{\beta}{ }^{\alpha}+\mu^{\alpha} \wedge \theta \tag{1.37}
\end{equation*}
$$

in which $\mu^{\alpha}$ is some one-form, which we assume to have no $\theta$-term.
Now we differentiate (1.23) using (1.31) and (1.15). It follows that

$$
\begin{equation*}
0=\Omega^{\alpha} \wedge \theta_{\alpha}+\theta \wedge \tau^{\alpha} \wedge \tau_{\alpha} \tag{1.38}
\end{equation*}
$$

Putting (1.37) into (1.38) gives

$$
\begin{equation*}
0=\lambda_{\beta \alpha} \wedge \theta^{\beta} \wedge \theta^{\alpha}+\theta \wedge\left(\tau^{\alpha} \wedge \tau_{\alpha}-\mu_{\alpha} \wedge \theta^{\alpha}\right) \tag{1.39}
\end{equation*}
$$

Since $\lambda_{\beta \alpha}$ was chosen to have no $\theta$-term, (1.39) implies that

$$
\lambda_{\beta \bar{\alpha}}=W_{\beta \bar{a} \bar{r}} \theta^{r}+N_{\beta \bar{a} \bar{\tau}} \theta^{\bar{r}},
$$

where

$$
\begin{equation*}
W_{\beta \alpha \gamma}=W_{\gamma \alpha \beta}, \tag{1.40}
\end{equation*}
$$

and, because of (1.34),

$$
N_{\beta \alpha \bar{T}}=-W_{\alpha \beta \bar{T}},
$$

We can now put

$$
\begin{equation*}
\Omega_{\beta}{ }^{\alpha}=R_{\beta}{ }_{\beta}^{\alpha}{ }_{\rho \bar{\sigma}} \theta^{\rho} \wedge \theta^{\bar{\sigma}}+W_{\beta}{ }^{\alpha} \theta^{\circ} \theta^{\rho} \wedge \theta-W_{\beta \bar{\sigma}}^{\alpha} \theta^{\bar{\sigma}} \wedge \theta, \tag{1.41}
\end{equation*}
$$

and the exterior derivatives $d \omega_{\beta}{ }^{\alpha}$ are determined.
(1.39) and the expression (1.20) for $\tau_{\alpha}$ also imply

$$
0=\theta \wedge \theta^{\beta} \wedge\left(A_{\beta r} \tau^{\tau}+\mu_{\beta}\right)
$$

so that

$$
\mu_{\beta}=-A_{\beta r} \tau^{r}+B_{\beta_{r}} \theta^{r},
$$

where

$$
\begin{equation*}
B_{\beta r}=B_{\gamma \beta} . \tag{1.42}
\end{equation*}
$$

Finally, (1.37) becomes

$$
\begin{equation*}
\Omega^{\alpha}=W^{\alpha}{ }_{\rho \bar{\sigma}} \theta^{\rho} \wedge \theta_{\bar{\sigma}}^{\bar{\sigma}}-A_{\bar{\gamma}}^{\alpha} \tau^{\bar{\tau}} \wedge \theta+B_{\bar{\sigma}}^{\alpha} \theta^{\bar{\sigma}} \wedge \theta, \tag{1.43}
\end{equation*}
$$

and we have also determined the derivatives $d \tau^{\alpha}$.
We sum these results up in the following:
Theorem (1.1a). The exterior derivatives of the forms $\omega_{\beta}{ }^{\alpha}$ and $\tau^{\alpha}$ of Theorem (1.1) are given by (1.27) and (1.28), respectively, where $\Omega_{\beta}{ }^{\alpha}$ and $\Omega^{\alpha}$ are given by (1.41) and (1.43), respectively. The coefficients satisfy (1.33), (1.36), (1.40), and (1.42).

The existence of the invariant forms $\omega_{\beta}{ }^{\alpha}$ on the bundle $P$ with structure group reduced to $U(p, q)$ gives the following.

Theorem (1.2). The group $\operatorname{PsH}(M, \theta)$ of all pseudo-hermitian transformations of the pseudo-hermitian space ( $M, \theta$ ) of dimension $2 n+1$ is a Lie transformation group of dimension not exceeding $(n+1)^{2}$, with isotropy subgroups of dimension not exceeding $n^{2}$. If $M$ is strongly pseudo-covex, then the isotropy groups are compact, and $\operatorname{PsH}(M, \theta)$ is compact for compact $M$.

## 2. Geometric interpretation

We shall interpret the $\omega_{\beta}{ }^{\alpha}$ of Theorem (1.1) as connection forms of a connection on the complex vector bundle $H(M)$. If we choose local forms $\theta^{\prime \alpha}$ on $M$, then according to (1.8) and (1.16) we can put

$$
\begin{equation*}
U_{\beta}^{\gamma} \omega_{r}{ }^{\alpha}+d U_{\beta}{ }^{\alpha}=\omega_{\beta}^{\prime}{ }_{\beta}^{\gamma} U_{r}^{\alpha}, \tag{2.1}
\end{equation*}
$$

where

$$
\omega_{\beta}^{\prime}{ }_{\beta}^{r} \equiv 0, \quad \bmod \theta, \theta^{\prime \alpha}, \theta^{\prime \alpha}
$$

In the usual manner [3] we see that the coefficients of the $\omega_{\beta}{ }_{\beta}{ }^{\gamma}$ are independent of $U_{\rho}{ }^{\sigma}$ by differentiating (2.1). Using (2.1) to eliminate $d U_{\beta}{ }^{\alpha}$ we get

$$
\begin{equation*}
U_{\alpha}^{r}\left(d \omega_{r}^{\beta}-\omega_{r}^{\rho} \wedge \omega_{\rho}^{\beta}\right)=\left(d \omega_{\alpha}^{\prime} r-\omega_{\alpha}^{\prime}{ }^{\rho} \wedge \omega_{\rho}^{\prime}{ }^{\gamma}\right) U_{r}^{\beta} . \tag{2.2}
\end{equation*}
$$

By (1.27) and (1.41) we see that the left hand side of (2.2) is a two-form in $\theta, \theta^{\alpha}, \theta^{\alpha}$, therefore so is $d \omega_{\alpha}^{\prime}{ }^{r}$, and so $\omega_{\beta}^{\prime}{ }^{\alpha}$ is a one-form on $M$.

Now we consider $\theta^{\alpha}$, as well as $\theta^{\prime \alpha}$, as local one-forms on $M$ and (1.8) as a change of coframe. Let $\left(X, X_{\alpha}, X_{\alpha}\right)$ be the dual frame to $\left(\theta, \theta^{\alpha}, \theta^{\alpha}\right)$, and let $V=$ $U^{-1}$; then

$$
\begin{equation*}
X_{\alpha}=V_{\alpha}{ }^{\beta} X_{\beta}^{\prime} . \tag{2.3}
\end{equation*}
$$

Define an operator $D$ locally by

$$
\begin{equation*}
D X_{\alpha}=\omega_{\alpha}{ }^{\beta} X_{\beta}, \quad D: \Gamma(H(M)) \rightarrow \Gamma\left(T^{*}(M) \otimes H(M)\right) . \tag{2.4}
\end{equation*}
$$

Under the change (2.3) we get from (2.1)

$$
\begin{equation*}
\omega_{\beta}{ }^{\gamma} V_{r}^{\alpha}=d V_{\beta}^{\alpha}+V_{\beta}^{\gamma} \omega_{r}^{\prime \alpha} ; \tag{2.5}
\end{equation*}
$$

hence, (2.4) defines a connection on $H(M)$.
We can define an hermitian metric $\left(,^{-}\right)$in the fibres of $H(M)$ by

$$
\begin{equation*}
\left(X_{\alpha}, \bar{X}_{\beta}\right)=g_{\alpha \beta} . \tag{2.6}
\end{equation*}
$$

The condition (1.24) yields that $D$ is a metric connection. $\tau^{\alpha}$ in (1.15) can be viewed as a kind of torsion. The condition (1.18) on $\tau^{\alpha}$ is analogous to the requirement in hermitian geometry that the torsion form be of a given type (i.e., of type ( 2,0 )) [5].

With these interpretations we can restate Theorem (1.1) as
Theorem (2.1). Let ( $M, \theta$ ) be a nondegenerate, integrable pseudo-hermitian manifold. Then there are a unique hermitian metric (2.6) determined by the Levi form and a unique metric connection $D$ on $H(M)$ with torsion form satisfying

$$
\tau^{\alpha} \equiv 0, \quad \bmod \theta^{\tau}
$$

Under the change (1.8) (or (2.3)) we have

$$
\begin{equation*}
\theta_{\beta}^{\prime}=U_{\beta}{ }^{\alpha} \theta_{\alpha}, \tag{2.7}
\end{equation*}
$$

By (2.2) the curvature matrix of $\omega_{\beta}{ }^{\alpha}$,

$$
\begin{equation*}
\Pi_{\beta}{ }^{\alpha}=d \omega_{\beta}{ }^{\alpha}-\omega_{\beta}{ }^{\gamma} \wedge \omega_{\gamma}{ }^{\alpha}=\Omega_{\beta}{ }^{\alpha}+i \theta_{\beta} \wedge \tau^{\alpha}-i \tau_{\beta} \wedge \theta^{\alpha} \tag{2.9}
\end{equation*}
$$

transforms by

$$
\begin{equation*}
U_{a}{ }^{\gamma} \Pi_{\gamma}{ }^{\beta}=\Pi_{\alpha}^{\prime}{ }_{\alpha}^{\gamma} U_{\gamma}{ }^{\beta} . \tag{2.10}
\end{equation*}
$$

We also have

$$
\begin{equation*}
U_{\alpha}{ }^{r} \Omega_{r}{ }^{\beta}=\Omega_{\alpha}^{\prime}{ }_{\alpha}^{r} U_{r}^{\beta} . \tag{2.11}
\end{equation*}
$$

The two curvature matrices are equal when the torsion $\tau^{\alpha}$ vanishes.
The vanishing of the torsion has a more geometric interpretation. Let $L_{X}$ be Lie derivation by the transversal $X$ to $H(M)$. By the standard formula

$$
L_{X}=\iota_{X}{ }^{\circ} d+d^{\circ} \iota_{X},
$$

(1.7) and (1.15) imply

$$
\begin{equation*}
L_{X} \theta=0, \quad L_{X} \theta^{\alpha}=-\phi_{\beta}^{\alpha}(X) \theta^{\beta}-\tau^{\alpha}(X) \theta+\tau^{\alpha} . \tag{2.12}
\end{equation*}
$$

So if $\tau^{\alpha}=0$, then $X$ is an infinitesimal pseudo-conformal transformation.
Conversely, given a transverse infinitesimal pseudo-conformal transformation $X$, complete it to a basis by choosing $X_{\alpha}$. On the dual coframe we have

$$
\begin{equation*}
L_{X} \theta=u \theta, \quad L_{X} \theta^{\alpha}=\theta^{\beta} U_{\beta}^{\alpha}+\theta v^{\alpha} . \tag{2.13}
\end{equation*}
$$

From (1.3) it follows that

$$
L_{X} \theta=\eta_{\alpha} \theta^{\alpha}+\eta_{\alpha} \theta^{\alpha} ;
$$

hence $\eta_{\alpha}=u=0$, and we have an admissible coframe with respect to $\theta$. From (2.12) we see that $\tau^{\alpha}=0$.

Hence we have shown
Proposition (2.2). The torsion $\tau^{\alpha}$ vanishes if and only if the transversal $X$ determined by $\theta$ is an infinitesimal pseudo-conformal transformation.

Proposition 2.2 gives the condition required by Tanaka in [9].
Using the curvature tensor $R_{\beta \bar{\alpha} \rho \bar{\sigma}}$ in (1.41), we can define a kind of curvature for holomorphic plane sections in $H(M)$ as follows: if

$$
\begin{equation*}
Z=\xi^{\alpha} X_{\alpha} \tag{2.14}
\end{equation*}
$$

then

$$
\begin{equation*}
K(Z)=-\frac{1}{2}\left(R_{\beta \alpha \rho \sigma} \xi^{\beta} \xi^{\alpha} \xi^{\rho} \xi^{\bar{\sigma}}\right) /\left(g_{\alpha \beta} \xi^{\alpha} \xi^{\bar{\beta}}\right)^{2} . \tag{2.15}
\end{equation*}
$$

The coefficient $-\frac{1}{2}$ makes the unit hypersphere in $C^{n+1}$ have constant curvature +1 (see § 4). We also define the Ricci tensor

$$
\begin{equation*}
R_{\rho \bar{\sigma}}=R_{\alpha}{ }^{\alpha}{ }_{\rho \overline{\bar{c}}} \tag{2.16}
\end{equation*}
$$

and the scalar curvature

$$
\begin{equation*}
R=g^{\rho \bar{\sigma}} R_{\rho \bar{\sigma}} \tag{2.17}
\end{equation*}
$$

Finally, we can define a Riemannian metric on $T(M)$ by

$$
\begin{align*}
d s^{2} & =\theta \otimes \theta-\operatorname{Re}\left(g_{\alpha \bar{\beta}} \theta^{\alpha} \otimes \theta^{\bar{\beta}}\right)  \tag{2.18}\\
& =\theta \otimes \theta-\frac{1}{2}\left(g_{\alpha \bar{\beta}} \theta^{\alpha} \otimes \theta^{\bar{\beta}}+g_{\alpha \beta} \theta^{\alpha} \otimes \theta^{\beta}\right)
\end{align*}
$$

This metric is invariant under a pseudo-hermitian transformation.

## 3. Relation to pseudo-conformal invariants

The object of this section is to derive pseudo-conformal invariants from the curvature tensors introducted in part one. To do this we start with a local coframe field

$$
\begin{equation*}
\omega=\theta, \quad \omega^{\alpha}=\theta^{\alpha}, \quad \omega^{\alpha}=\theta^{\alpha} \tag{3.1}
\end{equation*}
$$

adapted to the particular choice of $\theta$. We then try to find local forms $\phi_{\beta}{ }^{\alpha}, \phi^{\alpha}$, and $\psi$ which will satisfy the structure equations [6, (A.1)-(A.6), p. 269] and [6, (4.21), p. 253]. Note that with our normalization

$$
\begin{equation*}
\phi=0 \tag{3.2}
\end{equation*}
$$

Because of (3.2), (1.15), (1.23), and (1.24) the choice

$$
\phi_{\beta}{ }^{\alpha}=\omega_{\beta}{ }^{\alpha}, \quad \phi^{\alpha}=\tau^{\alpha}, \quad \psi=0
$$

satisfies [6, (A.1), (A.2), (A.3), and (4.21)]. The transformation [6, (4.35)] indicates that we should try

$$
\begin{equation*}
\phi_{\beta}{ }^{\alpha}=\omega_{\beta}{ }^{\alpha}+D_{\beta}^{\alpha} \theta, \quad \phi^{\alpha}=\tau^{\alpha}+D_{r}^{\alpha} \theta^{r}, \quad \psi=0 \tag{3.3}
\end{equation*}
$$

where

$$
\begin{equation*}
D_{\beta \alpha}+D_{\alpha \beta}=0 . \tag{3.4}
\end{equation*}
$$

By the procedure of $[6, \S 4]$ the $D_{\beta \bar{\alpha}}$ are determined by requiring that the contraction of equation [6, (A.4)] be trivial, $\bmod \theta$. Substituting (3.3) into this contracted equation gives

$$
\begin{align*}
\Phi_{\alpha}{ }^{\alpha} & \equiv \Omega_{\alpha}{ }^{\alpha}+i\left(D g_{\rho \bar{\sigma}}+(n+2) D_{\rho \overline{\bar{\sigma}}}\right) \theta^{\rho} \wedge \theta^{\bar{\sigma}} \\
& \equiv\left(R_{\rho \bar{\sigma}}+i\left(D g_{\rho \bar{\sigma}}+(n+2) D_{\rho \bar{\sigma}}\right)\right) \theta^{\rho} \wedge \theta^{\bar{\sigma}}, \quad \bmod \theta, \tag{3.5}
\end{align*}
$$

where

$$
D=D_{\alpha}{ }^{\alpha},
$$

and we have made use of (1.23), (1.27), and (1.41).

To make (3.5) vanish, $\bmod \theta$. we choose

$$
\begin{equation*}
D_{\rho \bar{\sigma}}=\frac{i}{n+2} R_{\rho \bar{\sigma}}-\frac{i}{2(n+1)(n+2)} R g_{\rho \bar{\sigma}} . \tag{3.6}
\end{equation*}
$$

Then the $\phi_{\beta}{ }^{\alpha}$ in (3.3) is the intrinsic (pseudo-conformal) connection form.
The substitution of (3.3) and (3.6) into [6, (A.4)] gives

$$
\begin{align*}
\Phi_{\beta}{ }^{\alpha} & \equiv \Omega_{\beta}{ }^{\alpha}+i\left(D_{\beta}{ }^{\alpha} g_{\rho \bar{\sigma}}+D_{\rho}{ }^{\alpha} g_{\beta \bar{\sigma}}+\delta_{\beta}{ }^{\alpha} D_{\rho \bar{\sigma}}+\delta_{\rho}{ }^{\alpha} D_{\beta \bar{\sigma}}\right) \theta^{\rho} \wedge \theta^{\bar{\sigma}}  \tag{3.7}\\
& \equiv S_{\beta \rho}{ }^{\alpha}{ }_{\bar{\sigma}} \theta^{\rho} \wedge \theta^{\bar{\sigma}}, \quad \bmod \theta .
\end{align*}
$$

It now follows that Chern's pseudo-conformal curvature tensor is given by

$$
\begin{align*}
& S_{\beta \rho}{ }^{\alpha}{ }_{\sigma} \\
&= R_{\beta}{ }^{\alpha}{ }_{\rho \bar{\sigma}}-\frac{1}{n+2}\left(R_{\beta}{ }^{\alpha} g_{\rho \bar{\sigma}}+R_{\rho}{ }^{\alpha} g_{\beta \bar{\sigma}}+\delta_{\beta}{ }^{\alpha} R_{\rho \bar{\sigma}}+\delta_{\rho}{ }^{\alpha} R_{\beta \bar{\sigma}}\right)  \tag{3.8}\\
&+\frac{R}{(n+1)(n+2)}\left(\delta_{\beta}{ }^{\alpha} g_{\rho \bar{\sigma}}+\delta_{\rho}{ }^{\alpha} g_{\beta \bar{\sigma}}\right) .
\end{align*}
$$

Formula (3.8) is similar to H. Weyl's formula for the conformal curvature tensor of a Riemannian manifold (see [7]). The trace of $S$ with respect to $\beta$ and $\alpha$ is zero, so $S$ vanishes identically when $n=1$. When $n>1, S$ vanishes if and only if $M$ is locally equivalent to the real hypersphere in $C^{n+1}$ (see [6] and [10]). Formula (3.8) will be used to compute $S$ for specific hypersurfaces in the next section.

We could continue the procedure of [6] to determine further relations, however, when $n>1$, the Bianchi identities [6] can be used to show that all higher order invariants are obtained from $S$ by covariant differentation with respect to the pseudo-conformal connection [10]. It can then be shown, with the aid of (3.2), (3.3), (3.6), and (3.8), that these invariants can be expressed in terms of the curvatures of $(M, \theta)$ and their covariant derivatives with respect to the connection $\omega_{\beta}{ }^{\alpha}$. Such expressions will be valid only with respect to coframes satisfying (3.2).

As a system of local functions on $M, S$ transforms tensorially (explicit details are in [10]). Under the structure group (4.1) of [6] we have the changes

$$
\begin{equation*}
\tilde{\theta}=u \theta, \quad u g_{\alpha \bar{\beta}}=\tilde{g}_{\rho \bar{\sigma}} U_{\alpha}{ }^{\rho} U_{\bar{\beta}}^{\bar{\sigma}}, \quad S_{\beta \rho \bar{\alpha} \bar{\sigma}}=\tilde{S}_{\mu \nu \bar{\gamma} \bar{\varepsilon}} U_{\beta}{ }^{\mu} U_{\rho}{ }^{\nu} U_{\alpha}^{\bar{\gamma}} U_{\bar{\sigma}}^{\bar{\varepsilon}} . \tag{3.9}
\end{equation*}
$$

If we define the norm of $S$ with respect to $\theta$ by

$$
\begin{equation*}
\|S\|_{\theta}{ }^{2}=g^{\alpha \bar{\beta}} g^{\rho \overline{\bar{\sigma}}} g_{\gamma \bar{\mu}} g^{\nu \bar{E}} S_{\alpha \rho}{ }^{{ }^{\tau} \bar{\varepsilon}} S_{\bar{\beta} \bar{\sigma} \overline{\bar{u}}}{ }_{\nu}, \tag{3.10}
\end{equation*}
$$

then (3.9) gives

$$
\begin{equation*}
\|S\|_{\theta}=|u|\|S\|_{\tilde{\theta}} . \tag{3.11}
\end{equation*}
$$

If $M$ is strongly pseudo-convex, for example, we can restrict to changes (3.9) with $u>0$. If, in addition, $S$ does not vanish (3.11) shows that we can choose a unique $\theta^{*}$ with respect to which $S$ has norm one. This $\theta^{*}$ and all the invariants of $\left(M, \theta^{*}\right)$ are intrinsic to the $C-R$ structure of $M$. In particular, the corresponding transversal $X$ (1.10) and its integral curves are intrinsic to $M$. The latter are called principal curves [2].
Let $N$ be a Kähler manifold with Kähler form $\chi$. Each point of $N$ has a neighborhood $U$, with holomorphic coordinate vector $Z$, on which there is a positive function $h$ satisfying

$$
\chi=i \bar{\partial} \partial \log h .
$$

On $U \times C$ define

$$
r=h(Z, \bar{Z}) w \bar{w}-1, \quad Z \in U, \quad w \in C,
$$

and let $M$ be the real hypersurface on which $r$ vanishes. Then $\chi$ is also the Levi form of ( $M, \theta=i \partial r$ ). It is easily seen that the torsion $\tau^{\alpha}$ vanishes, and that $R_{\beta \bar{\alpha} \rho \bar{\sigma}}$ is also the curvature tensor of the Kähler metric associated to $\chi$. $S_{\beta \rho \bar{\sigma}}{ }^{\alpha}$ is then the same tensor defined by Bochner [1].

## 4. The curvature for real hypersurfaces in $C^{n+1}$, spaces of constant curvature, \& ellipsoids

In this section we will give a procedure for computing the torsion and curvature tensors for a real hypersurface $(M, \theta)$ in $C^{n+1}$ defined as the zero set of a given real valued function $r$.

We have coordinates

$$
Z=\left(z^{1}, \cdots, z^{n}\right), \quad w=z^{n+1}
$$

and, for the applications we have in mind, will assume that the $Z$ and $w$ variables are separated in $r$, i.e.,

$$
\begin{equation*}
r(Z, w, \bar{Z}, \bar{w})=p(Z, \bar{Z})+q(w, \bar{w}) \tag{4.1}
\end{equation*}
$$

$p$ and $q$ being real valued. We choose the one-form

$$
\begin{equation*}
\theta=i \partial r=i\left(p_{\alpha} d z^{\alpha}+q_{w} d w\right) . \tag{4.2}
\end{equation*}
$$

Throughout we shall use the abbreviations

$$
p_{\alpha}=\partial p / \partial z^{\alpha}, \quad q_{w}=\partial q / \partial w, \quad \text { etc. }
$$

Then we have

$$
\begin{equation*}
d \theta=i \bar{\partial} \partial r=i g_{\alpha \bar{\delta}} d z^{\alpha} \wedge d z^{\bar{\beta}}+\eta_{\alpha} d z^{\alpha} \wedge \theta+\eta_{\bar{\alpha}} d z^{\alpha} \wedge \theta=i g_{\alpha \bar{\beta}} \theta^{\alpha} \wedge \theta^{\bar{\beta}} \tag{4.3}
\end{equation*}
$$

where

$$
\begin{gather*}
g_{\alpha \bar{\beta}}=-p_{\alpha \bar{\beta}}-Q p_{\alpha} p_{\bar{\beta}}, \quad Q=\left(q_{w \varpi}\right) /\left(q_{w} q_{w}\right),  \tag{4.4}\\
\eta_{\alpha}=-Q p_{\alpha}, \quad \eta^{\alpha}=g^{\alpha \bar{\gamma}} \eta_{\bar{i}}  \tag{4.5}\\
\theta^{\alpha}=d z^{\alpha}+i \eta^{\alpha} \theta \tag{4.6}
\end{gather*}
$$

The coframe $\left(\theta, \theta^{\alpha}, \theta^{\alpha}\right)$ is admissible for $(M, \theta)$. Our computation will be valid where $q_{\infty} \neq 0$. The dual frame, characterized by

$$
\begin{equation*}
d f=X f \theta+X_{\alpha} f \theta^{\alpha}+X_{\tilde{\alpha}} f \theta^{\alpha} \tag{4.7}
\end{equation*}
$$

for any function $f$ on $M$, is given by

$$
\begin{align*}
X= & -i \eta^{\alpha}\left(\partial / \partial z^{\alpha}\right)+i \eta^{\alpha}\left(\partial / \partial z^{\alpha}\right)-i\left(1-p_{\mu} \eta^{\mu}\right)\left(q_{w}\right)^{-1}(\partial / \partial w)  \tag{4.8}\\
& +i\left(1-p_{\bar{\mu}} \eta^{\mu}\right)\left(q_{\bar{w}}\right)^{-1}(\partial / \partial \bar{w}),
\end{align*}
$$

$$
\begin{equation*}
X_{\alpha}=\left(\partial / \partial z^{\alpha}\right)-p_{\alpha}\left(q_{w}\right)^{-1}(\partial / \partial w), \quad X_{\bar{\alpha}}=\overline{X_{\alpha}} \tag{4.9}
\end{equation*}
$$

We first compute the connection and torsion forms $\omega_{\beta \alpha}, \tau_{\alpha}$. Differentiating (4.6) gives

$$
d \theta^{\alpha}=\theta^{\beta} \wedge\left(-\eta^{\alpha} \theta_{\beta}+i X_{\beta} \eta^{\alpha} \theta\right)+\theta \wedge\left(-i X_{\bar{F}} \eta^{\alpha} \theta^{\bar{\gamma}}\right)=\theta^{\beta} \wedge \omega_{\beta}^{\prime \alpha}+\theta \wedge \tau^{\alpha}
$$

Next, we compute

$$
d g_{\beta \bar{\alpha}}-\omega_{\beta \bar{\alpha}}^{\prime}-\omega_{\bar{\alpha} \beta}^{\prime}=\left(X_{r} g_{\beta \bar{\alpha}}+\eta_{\beta} g_{\gamma \bar{\alpha}}\right) \theta^{r}+\left(X_{\bar{\gamma}} g_{\beta \bar{\alpha}}+\eta_{\bar{\alpha}} g_{\beta \bar{\eta}}\right) \theta^{\bar{\tau}},
$$

where the $\theta$-term vanishes by (1.22). Therefore the change (1.23a) yields

$$
\begin{equation*}
\omega_{\beta \bar{\alpha}}=B_{\beta \bar{\alpha} \gamma} \theta^{r}+C_{\beta \bar{\gamma} \bar{\theta}} \theta^{\bar{\gamma}}+E_{\beta \bar{\alpha}} \theta, \tag{4.10}
\end{equation*}
$$

where

$$
\begin{equation*}
B_{\beta \bar{\alpha} \gamma}=X_{\gamma} g_{\beta \bar{\alpha}}+\eta_{\beta} g_{\alpha \gamma}, \quad C_{\beta \bar{\gamma} \bar{\tau}}=-\eta_{\alpha} g_{\beta \bar{\tau}}, \quad E_{\beta \alpha}=i g_{\alpha \gamma} X_{\beta} \eta^{\gamma} . \tag{4.11}
\end{equation*}
$$

Also, the torsion form is

$$
\begin{equation*}
\tau_{\alpha}=A_{\alpha \gamma} \theta^{r} \tag{4.12}
\end{equation*}
$$

where

$$
\begin{equation*}
A_{\alpha \gamma}=i g_{\alpha \bar{\mu}} X_{\gamma} \eta^{\bar{\mu}}=i X_{\gamma} \eta_{\alpha}-i \eta^{\bar{\mu}} X_{\gamma} g_{\alpha \bar{\mu}} . \tag{4.13}
\end{equation*}
$$

To find the curvature tensor $R_{\beta \alpha \rho \bar{\sigma}}$, we substitute (4.10) and (4.12) into

$$
\Omega_{\beta \bar{\alpha}}=d \omega_{\beta \alpha}-\omega_{\alpha \bar{\alpha}} \wedge \omega_{\beta}^{\gamma}-i \theta_{\beta} \wedge \tau_{\alpha}+i \tau_{\beta} \wedge \theta_{\bar{\alpha}}
$$

and compute $\bmod \theta$. We need to consider only the $\theta^{\circ} \wedge \theta^{\sigma}$-term. The coefficient of this term is

$$
\begin{align*}
& R_{\beta \bar{\alpha} \rho \bar{\sigma}}=-X_{\bar{\sigma}} B_{\beta \alpha \rho}+X_{\rho} C_{\beta \bar{\alpha} \bar{\sigma}}+B_{\beta}{ }^{\gamma}{ }_{\rho} B_{\alpha \gamma \bar{\sigma}}+B_{\beta \bar{\gamma} \gamma} C_{\rho}{ }^{\gamma} \overline{\bar{\sigma}}  \tag{4.14}\\
& -C_{\beta \bar{\tau}} C_{\bar{\partial}{ }_{\rho}{ }^{\bar{T}}}-C_{\beta}{ }_{\beta}{ }_{\bar{\sigma}} C_{\alpha \bar{\alpha} \rho}+i E_{\beta \alpha} g_{\rho \bar{\sigma}} .
\end{align*}
$$

If we substitute (4.11) into (4.14) we get

$$
\begin{align*}
R_{\beta \alpha \bar{\alpha} \bar{\sigma}}= & -X_{\bar{\sigma}} X_{\rho} g_{\beta \bar{\alpha}}+g^{\gamma \bar{\mu}} X_{\rho} g_{\beta \bar{\mu}} \cdot X_{\bar{\sigma}} g_{\bar{\alpha} \gamma}+g_{\rho \overline{\bar{\eta}}} \eta^{\tau} X_{\beta} g_{\bar{\alpha} \gamma} \\
& -g_{\rho \bar{\sigma}} \eta^{\gamma} X_{r} g_{\beta \bar{\alpha}}-g_{\alpha \overline{ }} X_{\bar{\sigma}} \eta_{\beta}-g_{\beta \bar{\sigma}} X_{\rho} \eta_{\bar{\alpha}}-g_{\rho \bar{\sigma}} X_{\beta} \eta_{\bar{\alpha}}  \tag{4.15}\\
& -\eta_{\beta} \eta_{\bar{\alpha}} g_{\rho \bar{\sigma}}-\eta_{r} \eta^{\gamma} g_{\beta \bar{\sigma}} g_{\rho \bar{\alpha}} .
\end{align*}
$$

Examples. A. Spaces of constant curvature. We will consider here three examples in $C^{n+1}$ which are locally equivalent in the pseudo-conformal sense but differ according to the choice (4.2) of $\theta$.

$$
\begin{align*}
Q_{0}: & r_{0}=h_{\alpha \bar{\beta}} z^{\alpha} z^{\bar{\beta}}+\frac{i}{2}(w-\bar{w})=0 .  \tag{4.16.1}\\
Q_{+}(c): & r_{+}=h_{\alpha} z^{\alpha} z^{\bar{\beta}}+w \bar{w}=c .  \tag{4.16.2}\\
Q_{-}(c): & r_{-}=h_{\alpha \beta} z^{\alpha} z^{\bar{\beta}}-w \bar{w}=-c . \tag{4.16.3}
\end{align*}
$$

The constant $c$ is positive, and $h_{\alpha \bar{\beta}}$ is a constant nonsingular hermitian matrix with signature $p$ positive and $q$ negative eigenvalues, $p+q=n$.

The transformation

$$
\begin{equation*}
w=c / w^{\prime}, \quad z^{\alpha}=\sqrt{c} z^{\prime \alpha} / w^{\prime} \tag{4.17}
\end{equation*}
$$

maps $Q_{-}(c)$ onto $Q_{+}(c)$ minus $\{w=0\}$. A transformation mapping $Q_{0}$ onto $Q_{+}(c)$ minus a point is given in [6]. However, these transformations do not preserve the one-forms $\theta=i \partial r$.
(1) $Q_{0}$. Let $G_{0}$ be the group of $(n+1) \times(n+1)$ matrices

$$
\left(\begin{array}{ccc}
1 & b^{\beta} & b  \tag{4.18}\\
0 & B_{\alpha}{ }^{\beta} & b_{\alpha} \\
0 & 0 & 1
\end{array}\right),
$$

where

$$
\begin{equation*}
B_{\alpha}{ }^{\tau} h_{\gamma \beta} B_{\beta^{\delta}}=h_{\alpha \bar{\beta}}, \quad b_{\alpha}=2 i B_{\alpha}{ }^{\rho} h_{\rho \bar{F}} b^{\bar{\gamma}}, \quad 0=\frac{i}{2}(b-\bar{b})+h_{\alpha \beta} b^{\alpha} b^{\bar{\beta}} . \tag{4.19}
\end{equation*}
$$

$G_{0}$ acts on $C^{n+1}$ by

$$
\begin{equation*}
\tilde{z}^{\alpha}=b^{\alpha}+z^{\beta} B_{\beta}{ }^{\alpha}, \quad \tilde{w}=b+z^{\beta} b_{\beta}+w \tag{4.20}
\end{equation*}
$$

preserves the function $r_{0}$ defining $Q_{0}$, and hence preserves $\theta=i \partial r$.
The isotropy group of $(0,0)$ in $Q_{0}$ is the unitary group $U(p, q)$ of the hermitian form $h_{\alpha \beta}$. It follows that $Q_{0}$ is homogeneous,

$$
\begin{equation*}
Q_{0}=G_{0} / U(p, q) \tag{4.21}
\end{equation*}
$$

If we choose as our coframe

$$
\theta, \theta^{\alpha}=d z^{\alpha}, \theta^{\alpha}=d z^{\alpha},
$$

then

$$
d \theta=-i h_{\alpha \beta} \theta^{\alpha} \wedge \theta^{\xi},
$$

and $\omega_{\beta}{ }^{\alpha}=\tau^{\alpha}=0$ since $d \theta^{\alpha}=0$. The curvature and torsion of $\left(Q_{0}, \theta\right)$ vanish identically.
(2) $Q_{+}(c)$. The function $r_{+}$in (4.16.2) is an hermitian form of signature $(p+1, q)$. The unitary group $U(p+1, q)$ acts transitively on $Q_{+}(c)$ and preserves $\theta=i \partial r_{+}$. The isotropy group at $(Z=0, w=\sqrt{c})$ is $U(p, q)$; hence

$$
\begin{equation*}
Q_{+}(c)=U(p+1, q) / U(p, q) . \tag{4.22}
\end{equation*}
$$

(3) $Q_{-}(c)$. The function $r_{-}$in (4.16.3) is an hermitian form of signature $(p, q+1), \theta=i \partial r$ is invariant under $U(p, q+1)$, and

$$
\begin{equation*}
Q_{-}(c)=U(p, q+1) / U(p, q) . \tag{4.23}
\end{equation*}
$$

Because $Q_{+}(c)$ and $Q_{-}(c)$ are homogeneous, it suffices to compute their curvature and torsion at a point where $Z=0$. From (4.13), (4.5), and (4.9) we see that $A_{\alpha \gamma}$ vanishes when $Z=0$. Also, substituting (4.4) and (4.5) into (4.15), we see that, when $Z=0$,

$$
R_{\beta \alpha \rho \bar{\sigma}}=-\frac{\varepsilon}{c}\left(g_{\beta \alpha} g_{\rho \bar{\sigma}}+g_{\rho \alpha} g_{\beta \bar{\sigma}}\right),
$$

where $\varepsilon=+1$ for $Q_{+}(c)$ and $\varepsilon=-1$ for $Q_{-}(c)$. From the definition of sectional curvature (2.15), we have $K \equiv 1 / c$ for $Q_{+}(c)$ and $K \equiv-1 / c$ for $Q_{-}(c)$.
$Q_{0}, Q_{+}(c)$, and $Q_{-}(c)$ each have a transformation group of dimension $(n+1)^{2}$. It is easily seen from (3.8) that the tensor $S_{\beta \rho \bar{\alpha} \bar{\sigma}}$ vanishes identically in each case.
B. Ellipsoids. For a less trivial example we consider the general ellipsoid $E$ in $C^{n+1}$ defined by

$$
\begin{align*}
r= & A_{1}\left(X^{1}\right)^{2}+B_{1}\left(y^{1}\right)^{2}+\cdots+A_{n}\left(x^{n}\right)^{2}+B_{n}\left(y^{n}\right)^{2}  \tag{4.24}\\
& +A(u)^{2}+B(v)^{2}-1=0,
\end{align*}
$$

where $x^{\alpha}+i y^{\alpha}=z^{\alpha}, u+i v=w$, and $A, A_{\alpha}, B, B_{\alpha}$ are all positive constants.
We rewrite this as

$$
\begin{equation*}
r=\sum_{\alpha=1}^{n}\left(a_{\alpha}\left(z^{\alpha}\right)^{2}+a_{\alpha}\left(z^{\bar{\alpha}}\right)^{2}+b_{\alpha} z^{\alpha} z^{\bar{\alpha}}\right)+a\left(w^{2}+\bar{w}^{2}\right)+b w \bar{w}-1=0, \tag{4.25}
\end{equation*}
$$

where

$$
\begin{align*}
& a=\frac{1}{4}(A-B), \quad a_{\alpha}=\frac{1}{4}\left(A_{\alpha}-B_{\alpha}\right), \\
& b=\frac{1}{2}(A+B)>0, \quad b_{\alpha}=\frac{1}{2}\left(A_{\alpha}+B_{\alpha}\right)>0 . \tag{4.26}
\end{align*}
$$

More generally, we take

$$
\begin{equation*}
r=p(Z, \bar{Z})+q(w, \bar{w}), \tag{4.27}
\end{equation*}
$$

where

$$
\begin{gather*}
p=a_{\alpha \beta} z^{\alpha} z^{\beta}+a_{\alpha \bar{\beta}} z^{\alpha} z^{\bar{\beta}}+b_{\alpha \bar{\beta}} z^{\alpha} z^{\bar{\beta}},  \tag{4.27a}\\
q=a w^{2}+\bar{a} \bar{w}^{2}+b w \bar{w}-1, \tag{4.27b}
\end{gather*}
$$

all the coefficients are constant, $a_{\alpha \beta}$ is symmetric, $b_{\alpha \bar{\beta}}$ is positive definite hermitian, and $b$ is positive.

We will compute the curvature tensor $S_{\beta \rho \bar{\alpha} \bar{\sigma}}$ for $E$ along the curve $E \cap(Z=0)$ by computing $R_{\beta \bar{\alpha} \rho \bar{\sigma}}$ and using (3.8). We let $\left.\right|_{0}$ denote evaluation at $Z=0$. We have

$$
\begin{array}{ll}
\left.p_{\alpha}\right|_{0}=0, & \left.q_{w}\right|_{0} \neq 0,  \tag{4.28}\\
p_{\alpha \bar{\beta}}=b_{\alpha \bar{\beta}}, & p_{\alpha \gamma}=2 a_{\alpha \gamma} .
\end{array}
$$

This, together with the expressions (4.4) and (4.5), gives

$$
\begin{align*}
& X_{\rho} g_{\beta \bar{\alpha}}=\frac{Q_{w}}{q_{w}} p_{\rho} p_{\beta} p_{\bar{\alpha}}-Q p_{\beta} b_{\rho \bar{\alpha}}-2 Q a_{\beta \rho} p_{\bar{\alpha}}, \\
& -\left.X_{\bar{\sigma}}\right|_{0}\left(X_{\rho} g_{\beta \alpha}\right)=Q\left(b_{\beta \bar{\alpha}} b_{\rho \bar{\alpha}}+4 a_{\beta \rho} a_{\bar{\alpha} \overline{\bar{\alpha}}}\right),  \tag{4.29}\\
& \left.X_{\rho}\right|_{0}\left(g_{\beta \bar{\alpha}}\right)=0,\left.\quad X_{\bar{\sigma}}\right|_{0}\left(\eta_{\beta}\right)=-Q b_{\beta \bar{\alpha}}
\end{align*}
$$

Substituting (4.29) into (4.15) gives

$$
\begin{equation*}
\left.R_{\beta \alpha \bar{\beta} \bar{\tau}}\right|_{0}=-Q\left(b_{\beta \bar{\alpha}} b_{\rho \bar{\sigma}}+b_{\rho \bar{\alpha}} b_{\beta \bar{\sigma}}-4 a_{\beta \rho} a_{\alpha \bar{\sigma}}\right) \tag{4.30}
\end{equation*}
$$

where $Q=\left.Q\right|_{0} \neq 0$. Let $b^{\bar{\beta} \alpha}$ be the inverse matrix of $b_{\beta \bar{\alpha}}$. Then

$$
\begin{align*}
& \left.R_{\rho \bar{\sigma}}\right|_{0}=Q\left((n+1) b_{\rho \bar{\sigma}}-4 b^{\mu \bar{j}} a_{\mu \rho} a_{\bar{\nu} \bar{\sigma}}\right)  \tag{4.31}\\
& \left.R\right|_{0}=-Q\left(n(n+1)-4 b^{\mu \bar{i}} b^{b \bar{\tau}} a_{\mu \epsilon} a_{\overline{\bar{z}}}\right) \tag{4.32}
\end{align*}
$$

Now, if we put (4.30), (4.31), and (4.32) into (3.8) with the index $\alpha$ lowered, we get, after simplification,

$$
\begin{align*}
& \left.S_{\beta \rho \bar{\alpha} \bar{\tau}}\right|_{0}=4 Q b^{\mu \bar{j}} b^{\varepsilon \bar{\epsilon}} a_{\mu \epsilon} a_{\overline{\bar{\tau}}}\left(b_{\beta \alpha} b_{\rho \bar{\sigma}}+b_{\rho \bar{\alpha}} b_{\beta \bar{\sigma}}\right) \\
& +4 Q a_{\beta \rho} a_{\bar{\alpha} \bar{\sigma}}-\frac{4 Q}{n+2}\left(b^{\mu \nu} a_{\mu \beta} a_{\bar{\Sigma}} b_{\rho \bar{\sigma}}\right.  \tag{4.33}\\
& \left.+b^{\mu \bar{\beta}} a_{\mu \rho} a_{\bar{\nu} \bar{\alpha}} b_{\beta \bar{\sigma}}+b^{\mu \bar{\nu}} a_{\mu \rho} a_{\overline{\bar{\sigma}}} b_{\beta \alpha}+b^{\mu \bar{j}} a_{\mu \beta} a_{\overline{\bar{\sigma}}} b_{\rho \bar{\alpha}}\right) .
\end{align*}
$$

Now let us assume we have the form (4.25)-(4.26). Then

$$
\begin{equation*}
\left.S_{\alpha \alpha \bar{\alpha} \bar{\alpha}}\right|_{0}=\frac{8 Q}{(n+1)(n+2)}\left(\sum_{r=1}^{n} a_{r}{ }^{2} / b_{r}{ }^{2}\right) b_{\alpha}{ }^{2}+4 Q \frac{n-2}{n+2} a_{\alpha}{ }^{2} . \tag{4.34}
\end{equation*}
$$

It follows that if $n=1,\left.S_{11 \overline{1}}\right|_{0}=0$, as expected. However, if $n \geq 2$, then $\left.S_{\alpha \alpha \bar{\alpha} \bar{\alpha}}\right|_{0}$ vanishes for some $\alpha$ if and only if $a_{1}=\cdots=a_{n}=0$. Since we can relable our variables, say $z^{1} \leftrightarrow w$, we see that $E$ has nonflat points if $a \neq 0$, or if $a_{0} \neq 0$ for some $\alpha$. Hence

Theorem (4.1). Let $n \geq 2$. The ellipsoid E given by (4.24) is equivalent to the real hypersphere if and only if

$$
A_{1}=B_{1}, \cdots, A_{n}=B_{n}, A=B
$$

In [8] Fefferman has shown that a biholomorphic map between two bounded strongly pseudo-convex domains with smooth boundaries extends smoothly to the boundaries. Theorem (4.1) then gives a necessary and sufficient condition for an ellipsoidal domain to be equivalent to the unit ball.

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