# COMPLETE RIEMANNIAN MANIFOLDS WITH ( $f, g, u, v, \lambda$ )-STRUCTURE 

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Yano and Okumura [10] defined the so-called ( $f, g, u, v, \lambda$ )-structure, studied its fundamental properties and gave a characterization of even-dimensional spheres in terms of this structure. In the intrinsic geometry of ( $f, g, u, v, \lambda$ )structures, some global properties of manifolds with such a structure have been obtained (cf. [2], [5], [6], [8], [9] and [10]). On the other hand, submanifolds of codimension 2 in an almost Hermitian manifold or in an even-dimensional Euclidean space with canonical Kaehlerian structure, and hypersurfaces of an almost contact metric manifold or of an odd-dimensional sphere with canonical contact structure carry, under certain conditions, an ( $f, g, u, v, \lambda$ )-structure. In the differential geometry of submanifolds of a sphere admitting the induced ( $f, g, u, v, \lambda$ )-structure, several results have been proved (cf. [1], [3], [6], [9] and [10]). The main purposes of the present paper are to prove Theorem 3.1, which are closely related to a theorem due to Nakagawa and Yokote [3], and to show that some known theorems concerning ( $f, g, u, v, \lambda$ )structure can be proved as consequences of the theorems established in the present paper.

In $\S 1$ we discuss properties of almost product structure in a Riemannian manifold, and prove a lemma on the almost product structure and a theorem on the characterization of product spaces of two spheres, using a theorem due to Obata [4]. In $\S 2$ we prove some lemmas on ( $f, g, u, v, \lambda$ )-stuctures for later use. In $\S 3$ complete Riemannian manifolds admitting an ( $f, g, u, v, \lambda$ )-structure and satisfying certain conditions are discussed, and some theorems are proved. Theorem 3.5 stated in § 3 has been already proved by Nakagawa and Yokote [3] under weaker conditions.

## 1. Riemannian manifolds with almost product structure

Let there be given an $m$-dimensional Riemannian manifold $(M, g)$ with metric tensor $g$, components of $g$ being denoted by $g_{j i}$. (Manifolds, functions, vector fields and other geometric objects throughout this paper are assumed to be differentiable and of class $C^{\infty}$. The indices $h, i, j, k, l, r, s, t$ run over the range $\{1, \cdots, m\}$ and the summation convention will be used with respect to these
indices.) Let there be given in $(M, g)$ a tensor field $P_{i}^{h}$ of type $(1,1)$ satisfying

$$
\begin{align*}
& P_{s}{ }^{h} P_{i}{ }^{s}=P_{i}{ }^{h},  \tag{1.1}\\
& P_{j}{ }^{t} P_{i}{ }^{s} g_{t s}=P_{j i} \tag{1.2}
\end{align*}
$$

where $P_{j i}=P_{j}{ }^{t} g_{i t}$. Such a tensor field $P_{i}{ }^{h}$ is called an almost product structure in ( $M, g$ ). From (1.2), we have $P_{j i}=P_{i j}$. If we put $Q_{i}{ }^{h}=\delta_{i}^{h}-P_{i}{ }^{h}$, then we see that $Q_{i}{ }^{h}$ is also an almost product structure and $P_{i}{ }^{h} Q_{i}{ }^{s}=Q_{i}{ }^{h} P_{i}{ }^{s}=0$. Such almost product structures $P_{i}{ }^{h}$ and $Q_{i}{ }^{h}$ are said to be mutually complementary. In the sequel, we put $Q_{j i}=Q_{j}{ }^{s} g_{i s}$. If $M$ is connected, then the rank $r$ of $P_{i}{ }^{h}$ is constant, and $Q_{i}{ }^{h}$ is of constant rank $m-r$.

Lemma 1.1. Let $P_{i}{ }^{h}$ be an almost product structure in $(M, g)$. If $\nabla_{k} P_{j}{ }^{h}=$ $\nabla_{j} P_{k}{ }^{h}$, then $\nabla_{k} P_{j}{ }^{h}=0$,

Proof. Differentiating (1.1) covariantly we obtain $\left(\nabla_{k} P_{s}{ }^{h}\right) P_{i}{ }^{s}+P_{i}{ }^{h}\left(\nabla_{k} P_{i}{ }^{s}\right)$ $=\nabla_{k} P_{i}{ }^{h}$, to which transvecting $g_{j h}$ gives

$$
\begin{equation*}
\left(\nabla_{k} P_{s j}\right) P_{i}^{s}+P_{s j}\left(\nabla_{k} P_{i}^{s}\right)=\nabla_{k} P_{i j} \tag{1.3}
\end{equation*}
$$

By taking the skew-symmetric parts of both sides of (1.3) with respect to $i$ and $k$, we have

$$
\begin{equation*}
\left(\nabla_{k} P_{s j}\right) P_{i}^{s}-\left(\nabla_{i} P_{s j}\right) P_{k}^{s}=0 \tag{1.4}
\end{equation*}
$$

since $P_{i j}=P_{j i}$ and $\nabla_{k} P_{j i}=\nabla_{j} P_{k i}$. Interchanging $j$ and $k$ in (1.4), we get

$$
\begin{equation*}
\left(\nabla_{j} P_{s k}\right) P_{i}^{s}-\left(\nabla_{i} P_{s k}\right) P_{j}^{s}=0 \tag{1.5}
\end{equation*}
$$

Adding (1.3) to (1.5) yields

$$
\begin{equation*}
2\left(\nabla_{k} P_{j s}\right) P_{i}^{s}=\nabla_{k} P_{j i} \tag{1.6}
\end{equation*}
$$

since $\nabla_{k} P_{j i}=\nabla_{j} P_{k i}$ and $P_{j i}=P_{i j}$. Transvecting (1.6) with $P_{l}{ }^{i}$ and taking account of (1.1), we have $2\left(\nabla_{k} P_{j_{s}}\right) P_{l}{ }^{s}=\left(\nabla_{k} P_{j i}\right) P_{l}{ }^{i}$, from which follows $\left(\nabla_{k} P_{j i}\right) P_{l}{ }^{i}$ $=0$. Using this equation and (1.6), we find $\nabla_{k} P_{j i}=0$, which proves Lemma 1.1.

We need the following theorem stated in [4]:
Theorem A. Let $(M, g)$ be a complete connected Riemannian manifold of dimension $m$. If there is a nonconstant function $\rho$ in $M$ satisfying

$$
\begin{equation*}
\nabla_{j} \nabla_{i} \rho=-\rho g_{j i} / a^{2} \tag{1.7}
\end{equation*}
$$

a being a positive constant, and if $\operatorname{dim} M=m \geq 2$, then $(M, g)$ is isometric to a sphere $S^{m}(a)$ of radius a defined by $\left(x^{1}\right)^{2}+\cdots+\left(x^{m+1}\right)^{2}=a^{2}$ with respect to rectangular coordinates $\left(x^{1}, \cdots, x^{m+1}\right)$ in an $(m+1)$-dimensional Euclidean space $E^{m+1}$ and $\rho \circ i^{-1}$ coincides with the function $k x^{1}, k$ being a positive constant, in $S^{m}(a)$ where $i: M \rightarrow S^{m}(a)$ is the isometry.

We now give an example of Riemannian manifolds for later use. Let $S^{r}(a) \times$ $S^{s}(b)$ be the pythagorean product of an $r$-dimensional sphere $S^{r}(a)$ with radius $a$ and an $s$-dimensional sphere $S^{s}(b)$ with radius $b$. If, for two points $(p, q)$ and ( $p^{\prime}, q^{\prime}$ ) of $S^{r}(a) \times S^{s}(b), p^{\prime}$ and $q^{\prime}$ are the antipodes of $p$ and $q$ respectively, then we say that $(p, q)$ is equivalent to ( $p^{\prime}, q^{\prime}$ ), or that $(p, q) \sim\left(p^{\prime}, q^{\prime}\right)$. The factor space $S^{r}(a) \times S^{s}(b) / \sim$ with Riemannian metric induced from that of $S^{r}(a) \times S^{s}(b)$ by the projection $\pi: S^{r}(a) \times S^{s}(b) \rightarrow S^{r}(a) \times S^{s}(b) / \sim$ is denoted by $\left[S^{r}(a) \times S^{s}(b)\right]^{*}$. We now prove

Theorem 1.2. Let $(M, g)$ be a complete connected Riemannian manifold of dimension $m$, and let there be given in $(M, g)$ two complementary almost product structures $P_{i}{ }^{h}$ and $Q_{i}{ }^{h}$ such that $\nabla_{k} P_{i}{ }^{h}=0$. Assume that $P_{i}{ }^{h}$ is of rank $r, 2 \leq r \leq m-2$. If there is a nonconstant function $\lambda$ in $(M, g)$ satisfying

$$
\begin{align*}
& P_{j}{ }^{t} P_{t}{ }^{s} \nabla_{t} \nabla_{s} \lambda=-\lambda P_{j i} / a^{2}  \tag{1.8}\\
& Q_{j}{ }^{t} Q_{i}{ }^{s} \nabla_{t} \nabla_{s} \lambda=-\lambda Q_{j i} / b^{2} \tag{1.9}
\end{align*}
$$

where $a$ and $b$ are positive constants, then $(M, g)$ is isometric to $S^{r}(a) \times S^{m-r}(b)$ or $\left[S^{r}(a) \times S^{m-r}(b)\right]^{*}$.

Proof. Since $\nabla_{k} P_{i}{ }^{h}=0$, we have $V_{k} Q_{i}{ }^{h}=0$. Thus the distribution $D: \sigma \rightarrow$ $P T_{\sigma}(M)$ is integrable, where $\sigma$ is an arbitrary point of $M, P$ denotes the linear endomorphism determined by the tensor field $P_{i}{ }^{h}$, and $T_{\sigma}(M)$ the tangent space to $M$ at $\sigma$. The distribution $\bar{D}$ determined by $Q_{i}{ }^{h}$ is also integrable, and the integral manifolds of $D$ and $\bar{D}$ are all totally geodesic in $(M, g)$. Thus any maximal integral manifolds $V$ and $\bar{V}$ of $D$ and $\bar{D}$ respectively are connected and complete with respect to their induced Riemannian metrics $\gamma$ and $\bar{\gamma}$ respectively.

Consider a maximal integral manifold $V$ of $D$, and denote the restriction of $\lambda$ to $V$ by $\rho$. The $\rho$ satisfies

$$
\begin{equation*}
\nabla_{\beta} \nabla_{\alpha} \rho=-\rho \gamma_{\beta \alpha} / a^{2} \tag{1.10}
\end{equation*}
$$

because of (1.8), where $\gamma_{\beta \alpha}$ are the components of $\gamma$ in $V$, and the indices $\alpha$ and $\beta$ run over the range $\{1, \cdots, r\}$. Since $\lambda$ is not constant in $M$, there is in $M$ a point $\sigma$ at which $\lambda \neq 0$, so that we may assume that $V$ passes through such a point $\sigma$. Since $\rho \neq 0$ at $\sigma \in V$, due to (1.10) $\rho$ is not constant in $V$. Therefore, by Theorem A and (1.10), $V$ is isometric to $S^{r}(a)$. If $i: V \rightarrow S^{r}(a)$ is the isometry, where $S^{r}(a)$ is a sphere defined by $\left(x^{1}\right)^{2}+\cdots+\left(x^{r+1}\right)^{2}=a^{2}$ in $E^{r+1}$, then $\rho \circ i^{-1}$ coincides with $k x^{1}, k$ being a positive constant. Thus the set of all zero points of $\rho$ is $X_{0}=i^{-1}\left(S^{r-1}(a)\right), S^{r-1}(a)$ being a great sphere of $S^{r}(a)$, and $X_{0}$ is a bordered set in $V$.

We now take a point $\sigma$ of $V-X_{0}$, and denote by $\bar{V}_{\sigma}$ the maximal integral manifold of $\bar{D}$ passing through $\sigma$. Then the restriction $\bar{\rho}$ of $\lambda$ to $\bar{V}_{\sigma}$ satisfies

$$
\begin{equation*}
\nabla_{\mu} \nabla_{\nu \nu} \bar{\rho}=-\rho \bar{\gamma}_{\mu \nu} / b^{2}, \tag{1.11}
\end{equation*}
$$

because of (1.9), where $\bar{\gamma}_{\mu \nu}$ are the components of $\bar{\gamma}$ in $\bar{V}_{\sigma}$, and the indices $\mu$ and $\nu$ run over the range $\{r+1, \cdots, m\}$. Since $\lambda \neq 0$ at $\sigma \in V-X_{0}, \bar{\rho} \neq 0$ at $\sigma$ and hence $\bar{\rho}$ is not constant in $\bar{V}_{\sigma}$ in consequence of (1.11). Therefore, by Theorem A and (1.11), $\bar{V}_{\sigma}$ is isometric to $S^{m-r}(b)$. If $j: \bar{V}_{\sigma} \rightarrow S^{m-r}(b)$ is the isometry, where $S^{m-r}(b)$ is a sphere defined by $\left(y^{r+1}\right)^{2}+\cdots+\left(y^{m}\right)^{2}=b^{2}$ in $E^{m-r+1}$, then $\bar{\rho} \circ j^{-1}$ coincides with $\bar{k} y^{r+1}, \bar{k}$ being a positive constant.
Let $M_{0}=\bigcup_{\sigma \in V} \bar{V}_{\sigma}$ and $M_{0}^{\prime}=\bigcup_{\sigma \in V-X_{0}} \bar{V}_{\sigma}$. Then $M_{0}$ is an open submanifold of $M$, and $M_{0}^{\prime}$ is dense in $M_{0}$. Taking account of the arguments developed above we see that the Riemannnian manifold ( $M_{0}^{\prime}, g$ ) with restriction of $g$ is locally isometric to a pythagorean product $S^{r}(a) \times S^{m-r}(b)$ and hence is locally symmetric. That is, denoting the curvature tensor of $\left(M_{0}, g\right)$ by $K$, we have $\nabla K=0$ in $\left(M_{0}^{\prime}, g\right)$ and therefore also in $\left(M_{0}, g\right)$, since $\nabla K$ is continuous and $\left(M_{0}^{\prime}, g\right)$ is dense in $\left(M_{0}, g\right)$. Thus the restricted linear holomomy group of ( $M_{0}, g$ ) coincides with that of ( $M_{0}^{\prime}, g$ ), which is the direct product $R(r) \times R(m-r)$ of the rotation groups $R(r)$ and $R(m-r)$ of the respective dimensions. Consequently, by a theorem of de Rham, the universal covering space ( $\left.\tilde{M}_{0}, \tilde{g}\right)$ of $\left(M_{0}, g\right)$ with Riemannian metric $\tilde{g}$ induced naturally from $g$ in $M_{0}$ is isometric to the pythagorean product $M_{1} \times M_{2}$, where $M_{1}$ and $M_{2}$ are irreducible Riemannian manifolds of dimension $r$ and $m-r$ respectively, since ( $M_{0}^{\prime}, g$ ) is locally isometric to $S^{r}(a) \times S^{m-r}(b),\left(\tilde{M}_{0}, \tilde{g}\right)$ is isometric to $S^{r}(a) \times S^{m-r}(b)$. Since $\tilde{M}_{0}$ is compact, $M_{0}$ is also so. On the other hand, $M_{0}$ is open in $M$, and $M$ is connected. Thus $M$ coincide with $M_{0}$. Summing up, we can say that the universal covering space $(\tilde{M}, \tilde{g})$ of $(M, g)$ is isometric to $S^{r}(a) \times S^{m-r}(b)$. Thus, if $M$ is simply connected, then $(M, g)$ is isometric to $S^{r}(a) \times S^{m-r}(b)$.

Next, we assume that $(M, g)$ is not simply connected, and denote the covering projection by $\pi:(\tilde{M}, \tilde{g}) \rightarrow(M, g)$. Taking account of the arguments developed above we see that $\tilde{\lambda}=\lambda \circ \pi$ coincides with the function $h x^{1} y^{r+1}$ in $(\tilde{M}, \tilde{g})$, $h$ being a positive constant, if ( $\tilde{M}, \tilde{g}$ ) is identified with $S^{r}(a) \times S^{m-r}(b)$. We obtain $\tilde{\lambda}=h a b$ only at two points $\left(p_{0}, q_{0}\right)$ and $\left(p_{0}^{\prime}, q_{0}^{\prime}\right)$ where $p_{0} \in S^{r}(a)$ has coordinates $(a, 0, \cdots, 0)$ in $E^{r+1}, q \in S^{m-r}(b)$ has coordinates $(b, 0, \cdots, 0)$ in $E^{m-r+1}$, and $p_{0}^{\prime}$ and $q_{0}^{\prime}$ are the antipodes of $p$ and $q$ respectively. Thus ( $\tilde{M}, \tilde{g}$ ) is a double covering of $(M, g)$, so that $\pi(p, q)=\pi\left(p^{\prime}, q^{\prime}\right)$ implies that $p^{\prime}$ and $q^{\prime}$ are necessarily the antipodes of $p$ and $q$ respectively. Consequently, for any two points $(p, q)$ and $\left(p^{\prime}, q^{\prime}\right)$ of $\tilde{M}=S^{r}(a) \times S^{m-r}(b), \pi(p, q)=\pi\left(p^{\prime}, q^{\prime}\right)$ if and only if $(p, q) \sim\left(p^{\prime}, q^{\prime}\right)$. Hence $(M, g)$ is isometric with $\left[S^{r}(a) \times S^{m-r}(b)\right]^{*}=$ $S^{r}(a) \times S^{m-r}(b) / \sim$, and Theorem 1.2 is proved.

## 2. ( $f, g, u, v, \lambda)$-structures

Let $M$ be a manifold of dimension $m(\geq 2)$ with an $(f, g, u, v, \lambda)$-structure, that is, a Riemannian manifold $(M, g)$ which admits a tensor field $f_{i}{ }^{h}$ of type ( 1,1 ), two 1 -forms $u_{i}$ and $v_{i}$ (or two vector fields $u^{h}=u_{i} g^{i h}$ and $v^{h}=v_{i} g^{i h}$ ) and a function $\lambda$ satisfying

$$
\begin{align*}
& f_{t}{ }^{h} f_{j}{ }^{t}=-\delta_{i}^{h}+u_{j} u^{h}+v_{j} v^{h}, \quad f_{j}^{t} f_{i}^{s} g_{t s}=g_{j i}-u_{j} u_{i}-v_{j} v_{i},  \tag{2.1}\\
& f_{j}{ }^{t} u_{t}=\lambda v_{j}, \quad f_{j}{ }^{t} v_{t}=-\lambda u_{j}, \quad u_{t} u^{t}=v_{t} v^{t}=1-\lambda^{2}, \quad u_{t} v^{t}=0,
\end{align*}
$$

where $\left(g^{j i}\right)=\left(g_{j i}\right)^{-1}$. $f_{j i}$ defined by $f_{j i}=f_{j}{ }^{t} g_{i t}$ is skew-symmetric and of rank $m-2$ or $m$, and the manifold $M$ is necessarily of even-dimension, i.e., of dimension $m=2 n$, where $n \geq 2$ (cf. [11]).

Define a tensor field $S_{j i}{ }^{h}$ of type (1.2) by

$$
\begin{equation*}
S_{j i}{ }^{h}=N_{j i}^{h}+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h} \tag{2.2}
\end{equation*}
$$

where $N_{j i}{ }^{h}=f_{j}{ }^{t} \nabla_{t} f_{i}{ }^{h}-f_{i}{ }^{t} \nabla_{t} f_{j}{ }^{h}-\left(\nabla_{j} f_{i}{ }^{t}-\nabla_{i} f_{j}\right) f_{t}{ }^{h}$ are the components of the Nijenhuis tensor of $f_{i}{ }^{h}$. In the sequel, we put $N_{0}=\{p \in M \mid \lambda(p)=0\}, N_{1}=$ $\left\{p \in M \mid \lambda(p)^{2}=1\right\}, \bar{N}_{0}=M-N_{0}$ and $\bar{N}_{1}=M-N_{0}$. In this section, we establish some lemmas concerning $(f, g, u, v, \lambda)$-structures for later use.

Lemma 2.1. Assume that in a Riemannian manifold ( $M, g$ ) with an ( $f, g, u, v, \lambda$ )-structure, $\lambda$ is not zero almost everywhere, and

$$
\begin{align*}
& \nabla_{j} u_{i}-\nabla_{i} u_{j}=2 f_{j i}  \tag{2.3}\\
& \nabla_{j} v_{i}-\nabla_{i} v_{j}=2 \phi f_{j i} \tag{2.4}
\end{align*}
$$

hold, where $\phi$ is a certain function in M. Moreover, assume that there be given in $M$ a symmetric tensor field $H_{j i}$ of type $(0,2)$ satisfying

$$
\begin{equation*}
\nabla_{j} u_{i}+\nabla_{i} u_{j}=-2 \lambda H_{j i} \tag{2.5}
\end{equation*}
$$

and that $v_{i}$ satisfies

$$
\begin{equation*}
\nabla_{j} v_{i}=-H_{j t} f_{i}^{t}+\lambda g_{j i} \tag{2.6}
\end{equation*}
$$

Then in $M$

$$
\begin{align*}
& \nabla_{j} u_{i}=f_{j i}-\lambda H_{j i}  \tag{2.7}\\
& \nabla_{j} \lambda=H_{j t} u^{t}-v_{j}  \tag{2.8}\\
& H_{i t} f_{j}^{t}-H_{j t} f_{i}^{t}=2 \phi f_{j i} \tag{2.9}
\end{align*}
$$

Proof. (2.3) and (2.5) imply (2.7). Transvecting (2.7) with $u^{i}$ and using (2.1) we have $\lambda \nabla_{j} \lambda=-\lambda v_{j}+\lambda H_{j i} u^{i}$ from which follows $\nabla_{j} \lambda=-v_{j}+$ $H_{j i} u^{i}$ in $\bar{N}_{0}$. Thus we have (2.8) in $M$ because of the continuity of its both sides and the nonvanishing of $\lambda$ almost everywhere in $M$. If we take the skewsymmetric parts of both sides of (2.6), then we obtain (2.9) by means of (2.4). Hence Lemma 2.1 is proved.

Remark. If $(M, g)$ is a hypersurface of a sphere $S^{2 n+1}(1)$ of radius 1, the $(f, g, u, v, \lambda)$-structure of $(M, g)$ is the induced one, and $H_{j i}$ is the second fundamental tensor of the hypersurface $M$ immersed in $S^{2 n+1}(1)$, then (2.6), (2.7) and (2.8) hold (cf. [1], [6], [7] and [10]). Thus (2.3), (2.5) and (2.6) hold and (2.4)
is equivalent to (2.9) for a hypersurface $M$ of $S^{2 n+1}(1)$. In [3] Nakagawa and Yokota have studied hypersurfaces of $S^{2 n+1}(1)$ satisfying the condition (2.4).

Under the assumptions in Lemma 2.1 the set $N_{1}$ is a bordered set. In fact, if we suppose that there is an open subset $U$ contained in $N_{1}$, then by means of (2.7) we have $f_{j i} \pm H_{j i}=0$ in $U$, because $u_{i} u^{i}=1-\lambda^{2}=0$ in $U$ and hence $u_{i}=0$ in $U$, which together with (2.7) implies that $f_{j i}=0$ in $U$, since $f_{j i}$ is skew-symmetric and $H_{j i}$ is symmetric. This contradicts the fact that $f_{j i}$ is of rank $m-2$ or $m$ in $M$. Consequently $N_{1}$ is necessarily a bordered set (cf. [3]).
Lemma 2.2. Assume that in $(M, g)$ with an $(f, g, u, v, \lambda)$-structure, $\lambda$ is not zero almost everywhere, (2.3), (2.4) and

$$
\begin{equation*}
S_{j i h}=v_{j}\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}-2 \lambda g_{i h}\right)-v_{i}\left(\nabla_{j} v_{h}+\nabla_{h} v_{j}-2 \lambda g_{j h}\right) \tag{2.10}
\end{equation*}
$$

hold, and there is a symmetric tensor field $H_{j i}$ of type $(0,2)$ satisfying (2.5), where $S_{j i n}=S_{j i}{ }^{t} g_{h t}$. Then in $M$ we have (2.6), (2.7), (2.8) and (2.9).

Proof. (2.7) and (2.8) can be proved by using (2.3) and (2.5). We are now going to prove (2.6). For any $(f, g, u, v, \lambda)$-structure we have the identity (cf. [9, (1.11)])

$$
\begin{align*}
& v^{j}\left[S_{j i h}-\left(f_{j}^{t} f_{t i h}-f_{i}{ }^{t} f_{t j h}\right)\right] \\
& =\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}\right)-v_{i} v^{t}\left(\nabla_{t} v_{h}+\nabla_{h} v_{t}\right)-\lambda f_{i}^{t}\left(\nabla_{t} u_{h}+\nabla_{h} u_{t}\right)  \tag{2.11}\\
& \quad-\lambda^{2}\left(\nabla_{i} v_{h}-\nabla_{h} v_{i}\right)+\left(\lambda f_{i}^{t}-u_{i} v^{t}\right)\left(\nabla_{t} u_{h}-\nabla_{h} u_{t}\right),
\end{align*}
$$

where $f_{j i n}=\nabla_{j} f_{i n}+\nabla_{i} f_{h j}+\nabla_{h} f_{j i}$. Substituting (2.3), (2.4) and (2.5) into (2.11) and using $f_{j i h}=0$ which is a direct consequence of (2.3), we obtain

$$
\begin{aligned}
v^{j} S_{j i h}= & \left(\nabla_{i} v_{h}+\nabla_{h} v_{i}\right)-v_{i} v^{t}\left(\nabla_{t} v_{h}+\nabla_{h} v_{t}\right)+2 \lambda^{2} f_{i}^{t} H_{t h} \\
& -2 \lambda^{2} \phi f_{i h}+2\left(\lambda f_{i}^{t}-u_{i} v^{t}\right) f_{t h}
\end{aligned}
$$

On the other hand, transvecting (2.10) with $v^{j}$ gives

$$
v^{j} S_{j i h}=\left(1-\lambda^{2}\right)\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}-2 \lambda g_{i h}\right)-v_{i}\left(\nabla_{t} v_{h}+\nabla_{h} v_{t}\right) v^{t}+2 \lambda v_{i} v_{h}
$$

Thus using (2.1), from the above two equations we have $\nabla_{i} v_{h}+\nabla_{h} v_{i=}^{\prime}=$ $-2 H_{h t} f_{i}^{t}+2 \lambda g_{i n}+2 \phi f_{i n}$, which together with (2.4) implies (2.6) in $\bar{N}_{0}$ and consequently in $M$. Finally we have (2.9) by substituting (2.6) into (2.4). Thus Lemma 2.2 is proved.

Lemma 2.3. Under the assumptions in Lemma 2.1 we have

$$
\begin{equation*}
H_{t}{ }^{t}=2 n \phi \tag{2.12}
\end{equation*}
$$

in $M$, and

$$
\begin{equation*}
H_{j t} u^{t}=\alpha u_{j}+\beta v_{j} \tag{2.13}
\end{equation*}
$$

$$
\begin{align*}
& H_{j t} v^{t}=\beta u_{j}+\gamma v_{j}  \tag{2.14}\\
& \alpha+\gamma=2 \phi \tag{2.15}
\end{align*}
$$

in $\bar{N}_{1}$, where $H_{i}{ }^{h}=H_{i t} g^{h t}$, and $\alpha, \beta$ and $\gamma$ are functions in $\bar{N}_{1}$ defined by $\left(1-\lambda^{2}\right) \alpha=H_{s t} u^{s} u^{t},\left(1-\lambda^{2}\right) \beta=H_{s t} u^{s} v^{t}$ and $\left(1-\lambda^{2}\right) \gamma=H_{s t} v^{s} v^{t}$ respectively.

Proof. Transvecting (2.9) with $f_{k}{ }^{i}$ gives

$$
H_{t s} s_{j}{ }_{j}^{t} f_{k}^{s}+H_{j k}-H_{j t} u^{t} u_{k}-H_{j t} v^{t} v_{k}=2 \phi\left(g_{j k}-u_{j} u_{k}-v_{j} v_{k}\right) .
$$

By taking the skew-symmetric parts of the above equation we obtain

$$
\left(H_{j t} u^{t}\right) u_{k}-\left(H_{k t} u^{t}\right) u_{j}+\left(H_{j t} v^{t}\right) v_{k}-\left(H_{k t} v^{t}\right) v_{j}=0
$$

Thus transvecting the above equation with $u^{k}$ and $v^{k}$ and using (2.1), we have (2.3) and (2.14) respectively, because $u_{i}$ and $v_{i}$ do not vanish in $\bar{N}_{1}$.

Next, transvecting (2.9) with $f^{j i}=g^{j t} f_{t}{ }^{i}$ and using (2.1), we obtain

$$
\begin{equation*}
H_{t}{ }^{t}=2 \phi\left(n-\left(1-\lambda^{2}\right)\right)+H_{t s} u^{t} u^{s}+H_{t s} v^{t} v^{s} \tag{2.16}
\end{equation*}
$$

On the other hand, transvecting (2.9) with $u^{j} v^{i}$ and using (2.1) yield $\lambda\left(H_{t s} u^{t} u^{s}+H_{t s} v^{t} v^{s}\right)=2 \lambda\left(1-\lambda^{2}\right) \phi$. Thus we have

$$
\begin{equation*}
H_{t s} u^{t} u^{s}+H_{t s} v^{t} v^{s}=2\left(1-\lambda^{2}\right) \phi \tag{2.17}
\end{equation*}
$$

in $\bar{N}_{0}$ and consequently in $M$. Restricting (2.17) to $\bar{N}_{1}$ gives (2.15). Finally by substituting (2.17) into (2.16) we have (2.12) in $M$. Thus Lemma 2.3 is proved.

Lemma 2.4. If in Lemma 2.1 the tensor $H_{j i}$ satisfies the condition

$$
\begin{equation*}
\nabla_{k} H_{j i}-\nabla_{j} H_{k i}=0 \tag{2.18}
\end{equation*}
$$

then we have in $\bar{N}_{1}$

$$
\begin{align*}
& \phi(1-\beta)=\alpha  \tag{2.19}\\
& v^{t} \nabla_{t} \alpha=u^{t} \nabla_{t} \beta \tag{2.20}
\end{align*}
$$

Proof. Differentiating (2.13) covariantly gives

$$
\left(\nabla_{k} H_{j t}\right) u^{t}+H_{j t}\left(\nabla_{k} u^{t}\right)=\left(\nabla_{k} \alpha\right) u_{j}+\left(\nabla_{k} \beta\right) v_{j}+\alpha \nabla_{k} u_{j}+\beta \nabla_{k} v_{j}
$$

in $\bar{N}_{1}$. Taking skew-symmetric parts of both sides of the above equation and using (2.18) we obtain

$$
\begin{aligned}
H_{j t}\left(\nabla_{k} u^{t}\right)-H_{k t}\left(\nabla_{j} u^{t}\right)= & \left(\nabla_{k} \alpha\right) u_{j}-\left(\nabla_{j} \alpha\right) u_{k}+\left(\nabla_{k} \beta\right) v_{j}-\left(\nabla_{j} \beta\right) v_{k} \\
& +\alpha\left(\nabla_{k} u_{j}-\nabla_{j} u_{k}\right)+\beta\left(\nabla_{k} v_{j}-\nabla_{j} v_{k}\right) .
\end{aligned}
$$

Next, if we substitute (2.3), (2.4), (2.6) and (2.7) into the above equation and use (2.9), then we have

$$
\begin{equation*}
2\{\phi(1-\beta)-\alpha\} f_{k j}=\left(\nabla_{k} \alpha\right) u_{j}-\left(\nabla_{j} \alpha\right) u_{k}+\left(\nabla_{k} \beta\right) v_{j}-\left(\nabla_{j} \beta\right) v_{k} \tag{2.21}
\end{equation*}
$$

from which it follows that $\nabla_{j} \alpha$ and $\nabla_{j} \beta$ are linear combinations of $u_{j}$ and $v_{j}$, i.e., that

$$
\begin{equation*}
\nabla_{j} \alpha=A_{1} u_{j}+A_{2} v_{j}, \quad \nabla_{j} \beta=B_{1} u_{j}+B_{2} v_{j} \tag{2.22}
\end{equation*}
$$

where $A_{1}, A_{2}, B_{1}$ and $B_{2}$ are certain functions in $\bar{N}_{1}$. Thus (2.21) reduces to $2\{\phi(1-\beta)-\alpha\} f_{k j}=-\left(A_{2}-B_{1}\right)\left(u_{k} v_{j}-u_{j} v_{k}\right)$, which implies that $\phi(1-$ $\beta)=\alpha$ and $A_{2}=B_{1}$, since $f_{j i}$ is of rank $2 n-2 \geq 2$ in $\bar{N}_{1}$ by assumption. Thus we have (2.19) and (2.20), and Lemma 2.4 is proved.

Remark. If $(M, g)$ is a hypersurface of a sphere $S^{2 n+1}(1)$, the ( $\left.f, g, u, v, \lambda\right)$ structure of $(M, g)$ is the induced one, and $H_{j i}$ is the second fundamental tensor of the hypersurface, then the condition (2.18) is nothing but the structure equation of Codazzi for the immersion of $M$ into $S^{2 n+1}(1)$.

Lemma 2.5. Under the conditions in Lemma 2.4, the equation

$$
\begin{align*}
& H_{k t} H_{i}^{t}-2 \phi H_{k i}+\left\{\beta+\phi^{2}(1+\beta)\right\} g_{k i}  \tag{2.23}\\
& \quad=\left(1-\lambda^{2}\right)^{-1} \beta(\beta+1)\left(1+\phi^{2}\right)\left(u_{k} u_{i}+v_{k} v_{i}\right)
\end{align*}
$$

holds in $\bar{N}_{1}$, and the function $\phi$ is constant in $M$.
Proof. Differentiating (2.14) covariantly and using (2.6) and (2.7), we have

$$
\begin{aligned}
& \left(\nabla_{k} H_{j t}\right) v^{t}+H_{j t}\left(-H_{k s} f^{t s}+\lambda \delta_{k}^{t}\right) \\
& \quad=\left(\nabla_{k} \beta\right) u_{j}+\left(\nabla_{k} \gamma\right) v_{j}+\beta\left(f_{k j}-\lambda H_{k j}\right)+\gamma\left(-H_{k t} f_{j}^{t}+\lambda g_{k j}\right)
\end{aligned}
$$

By taking the skew-symmetric parts of the above equation and using (2.9) and (2.18), we obtain

$$
\begin{align*}
& -2 H_{j t} H_{k s} f^{t s}-2(\beta+\gamma \phi) f_{k j}  \tag{2.24}\\
& \quad=\left(\nabla_{k} \beta\right) u_{j}-\left(\nabla_{j} \beta\right) u_{k}+\left(\nabla_{k} \gamma\right) v_{j}-\left(\nabla_{j} \gamma\right) v_{k} .
\end{align*}
$$

Transvecting (2.24) with $v^{k}$ gives that $\nabla_{j} \gamma$ is a linear combination of $u_{j}$ and $v_{j}$, i.e., that

$$
\begin{equation*}
\nabla_{j \gamma}=C_{1} u_{j}+C_{2} v_{j} \tag{2.25}
\end{equation*}
$$

where $C_{1}$ and $C_{2}$ are certain functions in $\bar{N}_{1}$. Using (2.22) and (2.25), we can reduce (2.24) to

$$
\begin{equation*}
\left.-2 H_{j t} H_{k s}\right)^{t s}-2(\beta+\phi \gamma) f_{k j}=\left(B_{2}-C_{1}\right)\left(v_{k} u_{j}-v_{j} u_{k}\right) \tag{2.26}
\end{equation*}
$$

Transvecting (2.26) with $v^{k} u^{j}$ gives that $2 \lambda\left(\alpha \gamma-\beta^{2}-\beta-\gamma \phi\right)=\left(B_{2}-C_{1}\right)$ $\cdot\left(1-\lambda^{2}\right)$ in $\bar{N}_{1}$, which together with (2.15) and (2.19) implies

$$
\begin{equation*}
-2 \lambda \beta(1+\beta)\left(1+\phi^{2}\right)=\left(B_{2}-C_{1}\right)\left(1-\lambda^{2}\right) \tag{2.27}
\end{equation*}
$$

in $\bar{N}_{1}$. Substituting (2.27) into (2.26) and using (2.9), we have in $\bar{N}_{1}$

$$
\begin{aligned}
& \left(H_{k s} f_{t}^{s}-2 \phi H_{k t}\right) f_{j}^{t}-(\beta+\phi \gamma) f_{k j} \\
& \quad=\lambda\left(1-\lambda^{2}\right)^{-1} \beta(\beta+1)\left(1+\phi^{2}\right)\left(v_{j} u_{k}-u_{j} v_{k}\right)
\end{aligned}
$$

Transvecting the above equation with $f_{i}{ }^{j}$ and using (2.13), (2.14), (2.15) and (2.19), we obtain (2.23) in $\bar{N}_{1}$.

Next, we are going to prove that $\phi$ is constant in $M$. Let $\rho$ be an eigenvalue of $H_{i}{ }^{h}$ associated with an eigenvector of $H_{i}{ }^{h}$, which is orthogonal to $u^{h}$ and $v^{h}$. Then using (2.23) we see that $\rho$ satisfies the quadrastic equation

$$
\begin{equation*}
\rho^{2}-2 \phi \rho+\left\{\beta+\phi^{2}(1+\beta)\right\}=0 \tag{2.28}
\end{equation*}
$$

in $\bar{N}_{1}$, which implies that $\beta$ is nonpositive because $\rho$ is real due to $H_{j i}=H_{i j}$. Differentiating covariantly the second equation of (2.22) yields $\nabla_{k} \nabla_{j} \beta=$ $\left(\nabla_{k} B_{1}\right) u_{j}+B_{1}\left(\nabla_{k} u_{j}\right)+\left(\nabla_{k} B_{2}\right) v_{j}+B_{2} \nabla_{k} v_{j}$. By taking the skew-symmetric parts of this equation and using (2.3) and (2.4), we obtain $\left(\nabla_{k} B_{1}\right) u_{j}-\left(\nabla_{j} B_{1}\right) u_{k}$ $+\left(\nabla_{k} B_{2}\right) v_{j}-\left(\nabla_{j} B_{2}\right) v_{k}=2\left(B_{1}+\phi B_{2}\right) f_{j k}$. Since $f_{j i}$ is of rank $2 n \geq 4$ in $\bar{N}_{1}$, we have

$$
\begin{equation*}
B_{1}+\phi B_{2}=0 \tag{2.29}
\end{equation*}
$$

in $\bar{N}_{0} \cap \bar{N}_{1}$ and consequently in $\bar{N}_{1}$. If we now differentiate (2.19) covariantly, then we have ${ }_{j} \alpha=(1-\beta) \nabla_{j} \phi-\phi \nabla_{j} \beta$, which together with (2.22) implies

$$
\begin{equation*}
A_{1} u_{j}+A_{2} v_{j}=(1-\beta) \nabla_{j} \phi-\phi\left(B_{1} u_{j}+B_{2} v_{j}\right) \tag{2.30}
\end{equation*}
$$

On the other hand, we have already proved $A_{2}=B_{1}$ (cf. (2.20)) in the proof of Lemma 2.4. Thus using (2.29), (2.30) and $A_{2}=B_{1}$ we find $(1-\beta) \nabla_{j} \phi=$ $\left(A_{1}+\phi B_{1}\right) u_{j}$. Since $\beta$ is nonpositive, we have $1-\beta \neq 0$, and therefore the above equation becomes $\nabla_{j} \phi=\tau u_{j}, \tau$ being a certain function in $\bar{N}_{1}$. Differentiating this equation covariantly, taking the skew-symmetric parts, and using (2.3), we obtain $\left(\nabla_{k} \tau\right) u_{j}-\left(\nabla_{j} \tau\right) u_{k}+2 \tau f_{k j}=0$. Since $f_{k j}$ is of rank $2 n \geq 4$ in $\bar{N}_{1}, \tau=0$. Consequently, $\phi$ is necessarily constant in $\bar{N}_{1}$ and hence in $M$. Thus Lemma 2.5 is proved.

Lemma 2.6. Assume that in Lemma 2.1 the tensor field $H_{j i}$ satisfies the condition (2.18), and the sectional curvature $K(\theta)$ of $(M, g)$ with respect to the section $\theta$ spanned by $u^{h}$ and $v^{h}$ is constant in $\bar{N}_{1}$. Then $\alpha, \beta$ and $\gamma$ are all constant and, in particular, $\beta=0$ or -1 . Moreover, we have

$$
\begin{equation*}
T_{t}{ }^{h} T_{i}{ }^{t}=-\beta\left(1+\phi^{2}\right) \delta_{i}^{h} \tag{2.31}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{k} T_{j i}-\nabla_{j} T_{k i}=0 \tag{2.32}
\end{equation*}
$$

where $T_{j i}=H_{j i}-\phi g_{j i}$ and $T_{j}^{h}=T_{j t} g^{h t}$.
Proof. Differentiating (2.7) covariantly and using (2.8) give $\nabla_{k} \nabla_{j} u_{i}=$ $\nabla_{k} f_{j i}-\left(H_{k t} u^{t}-v_{k}\right) H_{j i}-\lambda \nabla_{k} H_{j i}$. By taking the skew-symmetric parts with respect to $j$ and $k$ from this equation and using the Ricci identity and (2.18), we have

$$
-K_{k j i h} u^{h}=\nabla_{k} f_{j i}-\nabla_{j} f_{k i}-\left(H_{k t} u^{t}-v_{k}\right) H_{j i}+\left(H_{j t} u^{t}-v_{j}\right) H_{k i}
$$

where $K_{k j i h}$ are the components of the curvature tensor of $(M, g)$. Transvecting the above equation with $v^{i}$ and using (2.13) and (2.14), we find

$$
\begin{aligned}
-K_{k j i h} v^{i} u^{h}= & \left(\nabla_{k} f_{j i}\right) v^{i}-\left(\nabla_{j} f_{k i}\right) v^{i}-\left(\alpha u_{k}+\beta v_{k}-v_{k}\right)\left(\beta u_{j}+\gamma v_{j}\right) \\
& +\left(\alpha u_{j}+\beta v_{j}-v_{j}\right)\left(\beta u_{k}+\gamma v_{k}\right)
\end{aligned}
$$

which reduces to, in consequence of (2.1), (2.6), (2.7) and (2.8),

$$
K_{k j i h} v^{i} u^{h}=\left(\alpha \gamma-\beta^{2}+1\right)\left(v_{j} u_{k}-v_{k} v_{j}\right)
$$

Thus the sectional curvature $K(\theta)$ is given by

$$
K(\theta)=-K_{k j i \hbar} v^{k} u^{j} v^{i} u^{h} /\left[\left(u_{i} u^{i}\right)\left(v_{i} v^{i}\right)\right]=\alpha \gamma-\beta^{2}+1
$$

Since $K(\theta)$ is constant, $\alpha \gamma-\beta^{2}+1$ is also so. Thus $\alpha, \beta$ and $\gamma$ are constant because of (2.15) and (2.19).

Since $\beta$ and $\gamma$ are constant, we have $B_{2}=C_{1}=0$, where $B_{2}$ and $C_{1}$ are functions appearing in (2.22) and (2.25). Thus using (2.27) we obtain $\beta(\beta+1)=0$ in $\bar{N}$ and hence $\beta=0$ or -1 in $M$. Substituting $\beta(\beta+1)=0$ into (2.23) gives

$$
H_{k t} H_{i}^{t}-2 \phi H_{k i}+\left\{\beta+\phi^{2}(1+\beta)\right\} g_{k i}=0
$$

which is equivalent to (2.31). Next by means of (2.18) we have (2.32) since $\phi$ is constant. Hence Lemma 2.6 is proved.

Lemma 2.7. Let $(M, g)$ be a Riemmannian manifold with an $(f, g, u, v, \lambda)$ structure satisfying the conditions in Lemma 2.6. If $\beta=0$, then $H_{j i}=\phi g_{j i}$. If $\beta=-1$, then the tensor field $P_{i}{ }^{h}$ of type $(1,1)$ defined by

$$
\begin{equation*}
P_{i}{ }^{h}=\frac{1}{2}\left(1+\phi^{2}\right)^{-1 / 2}\left(\left(-\phi+\sqrt{1+\phi^{2}}\right) \delta_{i}^{h}+H_{i}{ }^{h}\right) \tag{2.33}
\end{equation*}
$$

is an almost product structure of rank $n$ in $(M, g)$ such that

$$
\begin{equation*}
\nabla_{k} P_{j i}-\nabla_{j} P_{k i}=0 \tag{2.34}
\end{equation*}
$$

where $P_{j i}=P_{j}{ }^{t} g_{i t}$.

Proof. First we assume that $\beta=0$. Then by substituting $\beta=0$ into (2.31) we have $T_{j i}=0$, which implies $H_{j i}=\phi g_{j i}$.

Next we assume that $\beta=-1$. Then substituting $\beta=-1$ into (2.31) we find

$$
\begin{equation*}
T_{t}{ }^{h} T_{i}{ }^{t}=\left(1+\phi^{2}\right) \delta_{i}^{h} . \tag{2.35}
\end{equation*}
$$

On the other hand, using (2.33) and $T_{i}{ }^{h}=H_{i}{ }^{h}-\phi \delta_{i}^{h}$ we have

$$
\begin{equation*}
P_{i}{ }^{h}=\frac{1}{2}\left(\delta_{i}^{h}+\left(1+\phi^{2}\right)^{-1 / 2} T_{i}{ }^{h}\right) . \tag{2.36}
\end{equation*}
$$

(2.36) and (2.35) imply $P_{t}{ }^{h} P_{i}{ }^{t}=P_{i}{ }^{h}$, which shows that $P_{i}{ }^{h}$ is an almost product structure. (2.32) and (2.36) imply (2.34). Contracting $i$ and $h$ in (2.33) and using (2.12) we find $P_{t}{ }^{t}=n$, which means that $P_{i}{ }^{h}$ is of rank $n$. Thus Lemma 2.7 is proved.

Lemma 2.8. Assume that in Lemma 2.1 the tensor field $H_{j i}$ satisfies (2.18), and the curvature tensor of $(M, g)$ is of the form

$$
\begin{equation*}
K_{k j i n}=g_{k h} g_{j i}-g_{j h} g_{k i}+H_{k h} H_{j i}-H_{j h} H_{k i} \tag{2.37}
\end{equation*}
$$

If the scalar curvature $K=K_{k j i h} g^{k h} g^{j i}$ is constant, then $\alpha, \beta$ and $\gamma$ are all constant and the same conclusions as those stated in Lemma 2.7 are valid.

Proof. From (2.37), we have by contraction

$$
\begin{equation*}
K=2 n(2 n-1)+\left(H_{t}^{t}\right)^{2}-H_{t s} H^{t s}, \tag{2.38}
\end{equation*}
$$

where $H^{t s}=g^{t j} g^{s i} H_{j i}$. On the other hand, from (2.23) we obtain by transvecting with $g^{k i}$

$$
\begin{equation*}
H_{t s} H^{t s}-2 \phi H_{t}^{t}+2 n\left\{\beta+\phi^{2}(1+\beta)\right\}=2 \beta(\beta+1)\left(1+\phi^{2}\right) \tag{2.39}
\end{equation*}
$$

Using now (2.12), (2.38) and (2.39), we see that $\beta$ is constant, since $K$ is constant. Thus from (2.15) and (2.19) it follows that $\alpha$ and $\gamma$ are also constant, because $\beta$ and $\phi$ are constant. Therefore we can derive the same conclusions as stated in Lemma 2.7, and Lemma 2.8 is proved.

Remark. If $(M, g)$ is a hypersurface of a sphere $S^{2 n+1}(1)$, the $(f, g, u, v, \lambda)$ structure of $(M, g)$ is the induced one, and $H_{j i}$ is the second fundamental tensor of the hypersurface, then (2.37) is nothing but the structure equation of Gauss for the hypersurface.

In the sequel we need the following lemma proved by Nakagawa and Yokote [4].

Lemma 2.9. Assume that in Lemma 2.1 the tensor field $H_{j i}$ satisfies (2.18), and the curvature tensor of $(M, g)$ is of the form (2.37). If $(M, g)$ is compact, then we have $\beta(\beta+1)=0$, that is, $\beta=0$ or -1 in $M$.

## 3. Complete Riemannian manifolds with an $(f, g, u, v, \lambda)$-structure

First, we prove
Theorem 3.1. Let $(M, g)$ be a complete connected Riemannian manifold of dimension $2 n \geq 4$ with an ( $f, g, u, v, \lambda)$-structure such that $\lambda$ is not zero almost everywhere in $M$ and that there be given a tensor field $H_{j i}$ of type (0.2) satisfying (2.5), (2.18). Further assume that the ( $f, g, u, v, \lambda$ )-structure satisfies (2.3), (2.4), (2.6) where $\phi$ is a certain function in M. If the sectional curvature $K(\theta)$ of $(M, g)$ with respect to the section $\theta$ spanned by $u^{h}$ and $v^{h}$ is constant in $\bar{N}_{1}$, then the function $\phi$ is necessarily constant, and $(M, g)$ is isometric to one of the following manifolds:

$$
S^{2 n}(r), \quad S^{n}\left(r_{1}\right) \times S^{n}\left(r_{2}\right), \quad\left[S^{n}\left(r_{1}\right) \times S^{n}\left(r_{2}\right)\right]^{*},
$$

where

$$
\begin{gathered}
r^{-2}=1+\phi^{2}, \quad r_{1}^{-2}=2\left(1+\phi^{2}+\phi \sqrt{1+\phi^{2}}\right), \\
r_{2}^{-2}=2\left(1+\phi^{2}-\phi \sqrt{1+\phi^{2}}\right)
\end{gathered}
$$

Moreover, $H_{j i}$ takes the form

$$
\begin{equation*}
H_{j i}=\phi g_{j i} \tag{3.1}
\end{equation*}
$$

if $(M, g)$ is isometric to $S^{2}(r)$, or

$$
\begin{equation*}
H_{j i}=2 \sqrt{1+\phi^{2}} P_{j i}+\left(\phi-\sqrt{1+\phi^{2}}\right) g_{j i} \tag{3.2}
\end{equation*}
$$

if $(M, g)$ is isometric to $S^{n}\left(r_{1}\right) \times S^{n}\left(r_{2}\right)$ or $\left[S^{n}\left(r_{1}\right) \times S^{n}\left(r_{2}\right)\right]^{*}$, where $P_{i}{ }^{h}$ is the almost product structure of rank $n$ determined by the local reducibility of $(M, g), P_{j i}=P_{j}{ }^{t} g_{i t}$ and $\nabla_{k} P_{j i}=0$.

Proof. Under the assumptions of this theorem, Lemmas 2.1, 2.3, $\cdots, 2.7$ are all valid. By Lemma 2.6 we have $\beta=0$ or -1 , and therefore we consider the following two cases.

Case I: $\beta=0$. Using (2.13) and (2.19) with $\beta=0$ we can reduce (2.8) to $\nabla_{i} \lambda=\phi u_{i}-v_{i}$. Covariant differentiation of this equation gives $\nabla_{j \Delta_{i}} \lambda=$ $-\lambda\left(1+\phi^{2}\right) g_{j i}$, in consequence of (2.6), (2.7) and $H_{j i}=\phi g_{j i}$ due to Lemma 2.7. On the other hand, $\lambda$ is not constant; otherwise, from (2.8) with $\nabla_{i} \lambda=0$ and (2.13) it follows that $\beta=1$, which contradicts to the assumption. Since ( $M, g$ ) is complete and connected, by Theorem A we thus see that $(M, g)$ is isometric to $S^{n}(r)$, where $1 / r^{2}=1+\phi^{2}$.

Case II: $\beta=-1$. Using (2.13) and (2.19) with $\beta=-1$ we can reduce (2.8) to $\nabla_{i} \lambda=2\left(\phi u_{i}-v_{i}\right)$. Covariant differentiation of this equation and use of (2.6) and (2.7) yields

$$
\begin{equation*}
\nabla_{j} \nabla_{i} \lambda=2 T_{j t} f_{i}^{t}-2 \lambda \phi T_{j i}-2 \lambda\left(1+\phi^{2}\right) g_{j i}, \tag{3.3}
\end{equation*}
$$

where $T_{j i}$ is given in Lemma 2.6. From (2.35), (2.36) and (3.3) it follows that

$$
\begin{align*}
& P_{j}{ }^{t} P_{i}{ }^{s} \nabla_{t} \nabla_{s} \lambda=-2 \lambda\left(1+\phi^{2}+\phi \sqrt{1+\phi^{2}}\right) P_{j i} \\
& Q_{j}{ }^{t} Q_{i}{ }^{s} \nabla_{t} \nabla_{s} \lambda=-2 \lambda\left(1+\phi^{2}-\phi \sqrt{1+\phi^{2}}\right) Q_{j i} \tag{3.4}
\end{align*}
$$

where $P_{i}{ }^{h}$ is the almost product structure defined in $(M, g)$ by (2.33) and $Q_{j}{ }^{h}=$ $\delta_{i}^{h}-P_{i}{ }^{h}$. On the other hand, $\lambda$ is not constant (see Case I). Thus $\nabla_{k} P_{j i}=0$ because of (2.34) and Lemma 1.1.

Since $P_{i}{ }^{h}$ is of rank $n$ and $(M, g)$ is complete and conncted, taking account of Theorem 1.2 and (3.4) we see that $(M, g)$ is isometric to $S^{n}\left(r_{1}\right) \times S^{n}\left(r_{2}\right)$ or [ $\left.S^{n}\left(r_{1}\right) \times S^{n}\left(r_{2}\right)\right]^{*}$. Finally, we obtain (3.2) from (2.33). Thus Theorem 3.1 is proved.

Theorem 3.2. Let $(M, g)$ be a complete connected Riemannian manifold of dimension $2 n \geq 4$ with an ( $f, g, u, v, \lambda$ )-structure such that $\lambda$ is not zero almost everywhere in $M$, and there be given in $M$ a tensor field $H_{j i}$ of type $(0,2)$ satisfying (2.5) and (2.18). Assume that the ( $f, g, u, v, \lambda$ )-structure of $(M, g)$ satisfies (2.3), (2.4) and (2.6), and further that the curvature tensor of $(M, g)$ is given by

$$
\begin{equation*}
K_{k j i h}=g_{k h} g_{j i}-g_{j h} g_{k i}+H_{k h} H_{j i}-H_{j h} H_{k i} \tag{2.37}
\end{equation*}
$$

If the scalar curvature $K$ of $(M, g)$ is constant, then the same conclusions as those stated in Theorem 3.1 are valid.

Proof. Under the assumptions in Theorem 3.2, Lemma 2.7 follows from Lemma 2.8. Therefore we can prove Theorem 3.2 in the same way as we prove Theorem 3.1.

Taking account of Lemma 2.9, we can prove the following Theorem 3.3 by the same devices as developed in the proof of Theorem 3.1.

Theorem 3.3. Let $(M, g)$ be a compact connected Riemannian manifold $2 n \geq 4$ with an $(f, g, u, v, \lambda)$-structure such that $\lambda$ is not zero almost everywhere in $M$, and let there be given in $M$ a tensor field $H_{j i}$ of type $(0,2)$ satisfying (2.5) and (2.18). Assume that the ( $f, g, u, v, \lambda$ )-structure of $(M, g)$ satisfies (2.3), (2.4) and (2.6), and that the curvature tensor of $(M, g)$ is given by (2.37). Then the same conclusions as those stated in Theorem 3.1 are valid.

Theorem 3.4. The conclusions in Theorem 3.1 (resp. Theorem 3.2, Theorem 3.3) are valid, even if in Theorem 3.1 (resp. Theorem 3.2, Theorem 3.3) the condition (2.6) is replaced by

$$
\begin{equation*}
S_{j i h}=v_{j}\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}-2 \lambda g_{i h}\right)-v_{i}\left(\nabla_{j} v_{h}+\nabla_{h} v_{j}-2 \lambda g_{j h}\right) \tag{2.10}
\end{equation*}
$$

Proof. By Lemma 2.2, the conditions (2.3), (2.4) and (2.10) imply (2.6). Thus using Lemmas 2.7, 2.8 and 2.9 we can obtain Theorem 3.4.

By means of Theorems 3.1, 3.2 or 3.4 we can prove the theorem in [2], Theorems 9.1, 9.2 in [7] and Theorem 3.2 in [10]. We now state

Lemma 3.5. Let $(M, g)$ be a complete connected hypersurface immersed in a sphere $S^{m+1}(1)$ with induced metric $g_{j i}$, and assume that in $(M, g)$ there is an almost product structure $P_{i}{ }^{k}$ of rank $p$ such that $\nabla_{j} P_{i}{ }^{h}=0$. If the second fundamental tensor $H_{j i}$ of the hypersurface ( $M, g$ ) takes the form $H_{j i}=a P_{j i}+$ $b Q_{j i}$, and $m-1 \geq p \geq 1$, where $a$ and $b$ are nonzero constants, $P_{j i}=P_{j}{ }^{t} g_{i t}$, and $Q_{j i}=g_{j i}-P_{j i}$, then the hypersurface $(M, g)$ is congruent to the hypersurfaces $S^{p}\left(r_{1}\right) \times S^{m-p}\left(r_{2}\right)$ naturally embedded in $S^{m+1}(1)$, where $1 / r_{1}{ }^{2}=1+a^{2}$ and $1 / r_{2}{ }^{2}=1+b^{2}$.

By means of Theorems 3.1, 3.2, and Lemma 3.5 we can prove
Theorem 3.6. Let $(M, g)$ be a complete connected hypersurface immersed in a sphere $S^{2 n+1}(1)$ with induced $(f, g, u, v, \lambda)$-structure such that $\lambda$ is not zero almost everywhere in $M$. Assume that the induced ( $f, g, u, v, \lambda$ )-structure satisfies the condition $\nabla_{j} v_{i}-\nabla_{i} v_{j}=2 \phi f_{j i}, \phi$ being a certain function in $M$. If $(M, g)$ satisfies one of the following conditions: (i) $(M, g)$ is compact, (ii) the scalar curvature $K$ of $(M, g)$ is constant, (iii) the sectional curvature $K(\theta)$ of $(M, g)$ with respect to the section $\theta$ spanned by $u^{h}$ and $v^{h}$ is constant, then $\phi$ is necessarily constant and the hypersurface $(M, g)$ is congruent to $S^{2 n}(r)$ or $S^{n}\left(r_{1}\right) \times S^{n}\left(r_{2}\right)$ naturally embedded in $S^{2 n+1}(1)$, where $1 / r^{2}=1+\phi^{2}, 1 / r_{1}^{2}=$ $2\left(1+\phi^{2}+\phi \sqrt{1+\phi^{2}}\right)$ and $1 / r_{2}{ }^{2}=2\left(1+\phi^{2}-\phi \sqrt{1+\phi^{2}}\right)$, (cf. Nakagawa and Yokote [3], [4]).

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