## Research Article

# Dynamical Yang-Baxter Maps Associated with Homogeneous Pre-Systems ${ }^{\star}$ 

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#### Abstract

We construct dynamical Yang-Baxter maps, which are set-theoretical solutions to a version of the quantum dynamical Yang-Baxter equation, by means of homogeneous pre-systems, that is, ternary systems encoded in the reductive homogeneous space satisfying suitable conditions. Moreover, a characterization of these dynamical YangBaxter maps is presented.


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## 1 Introduction

The quantum dynamical Yang-Baxter equation (QDYBE for short) [9, 10], a generalization of the quantum YangBaxter equation (QYBE for short) [2,3,40,41], has been studied extensively in recent years (see [7] and the references therein). Dynamical Yang-Baxter maps $[31,32,34]$ are set-theoretical solutions to a version of the QDYBE.

Let $H$ and $X$ be nonempty sets with a map $(\cdot): H \times X \ni(\lambda, x) \mapsto \lambda \cdot x \in H$. A map $R(\lambda): X \times X \rightarrow X \times X$ $(\lambda \in H)$ is a dynamical Yang-Baxter map associated with $H, X$ and $(\cdot)$, if and only if, for every $\lambda \in H, R(\lambda)$ satisfies the following equation on $X \times X \times X$ :

$$
\begin{equation*}
R_{23}(\lambda) R_{13}\left(\lambda \cdot X^{(2)}\right) R_{12}(\lambda)=R_{12}\left(\lambda \cdot X^{(3)}\right) R_{13}(\lambda) R_{23}\left(\lambda \cdot X^{(1)}\right) \tag{1.1}
\end{equation*}
$$

Here $R_{12}(\lambda), R_{12}\left(\lambda \cdot X^{(3)}\right), R_{23}\left(\lambda \cdot X^{(1)}\right)$, and others are the maps from $X \times X \times X$ to itself defined as follows: for $u, v, w \in X$,

$$
\begin{aligned}
R_{12}(\lambda)(u, v, w) & =(R(\lambda)(u, v), w), \\
R_{12}\left(\lambda \cdot X^{(3)}\right)(u, v, w) & =R_{12}(\lambda \cdot w)(u, v, w), \\
R_{23}\left(\lambda \cdot X^{(1)}\right)(u, v, w) & =(u, R(\lambda \cdot u)(v, w)) .
\end{aligned}
$$

Set-theoretical solutions to the QYBE [6], also known as Yang-Baxter maps [39], are dynamical Yang-Baxter maps constant for the parameter $\lambda$ of any set $H$; indeed, the dynamical Yang-Baxter map is a generalization of the set-theoretical solution to the QYBE.

This dynamical Yang-Baxter map yields a bialgebroid [4]. Every dynamical Yang-Baxter map with some conditions gives birth to an $(H, X)$-bialgebroid [35], a generalization of the quantum group [5,11], through the Faddeev-Reshetikhin-Takhtajan construction [8].

It is worth pointing out that a ternary system (Definition 1(3)) can produce the dynamical Yang-Baxter map [32]. Each triple ( $L, M, \pi$ ) consisting of a left quasigroup $L=(L, \cdot)$ (Definition 1(1)), a ternary system $M$ satisfying (2.2) and (2.3), and a (set-theoretic) bijection $\pi: L \rightarrow M$ gives a dynamical Yang-Baxter map $R(\lambda)$ associated with $L, L$ and $(\cdot)$ (see Section 2 for more details).

Homogeneous systems [ $18,19,20,21,22,23$ ] are algebraic features of the reductive homogeneous space [24,28] satisfying suitable conditions. Let $A$ be a group with its subgroup $K$. We assume that a subset $G$ of the group $A$ satisfies the following:

[^0](1) the group $A$ is uniquely factorized as $A=G K$,
(2) $G^{-1}=G$,
(3) $k G k^{-1}=G$, for all $k \in K$.

Let $p: A \rightarrow G$ denote the canonical projection with respect to the factorization $A=G K$, and (.) the binary operation on $G$ defined by $x \cdot y=p(x y)(x, y \in G)$. Because the map $L_{x}: G \ni y \mapsto x \cdot y \in G$ is bijective, we define the ternary operation $\eta$ on $G$ by

$$
\eta(x, y, z)=L_{x}\left(\left(L_{x}\right)^{-1}(y) \cdot\left(L_{x}\right)^{-1}(z)\right), \quad x, y, z \in G .
$$

This ternary system $G=(G, \eta)$ is a homogeneous system [23, Proposition 1] (see also Definition 7), and every homogeneous system is constructed in such a way.

If $G$ is a connected and second countable $C^{\infty}$-manifold with a $C^{\infty}$-map $\eta: G \times G \times G \rightarrow G$, then the homogeneous system $G=(G, \eta)$ is isomorphic to a reductive homogeneous space $A / K$ for a connected Lie group $A$ with its closed subgroup $K$ [19, Theorem 1]. The homogeneous system is a ternary system, an algebraic structure, encoded in the reductive homogeneous space (for ternary systems in differential geometry and mathematical physics, see $[13,14,15,29])$.

It is natural to relate this homogeneous system to the dynamical Yang-Baxter map through the ternary system.
The aim of this paper is to produce the dynamical Yang-Baxter maps by means of homogeneous pre-systems, which generalize the homogeneous system. Furthermore, we characterize such dynamical Yang-Baxter maps.

The organization of this paper is as follows.
Section 2 contains a brief summary of the dynamical Yang-Baxter map. We focus on its construction by means of the ternary system. This construction yields a category $\mathcal{A}$ concerning the ternary systems, which is equivalent to a category $\mathcal{D}$ consisting of the dynamical Yang-Baxter maps.

Section 3 presents the notion of a homogeneous pre-system, together with examples.
In Section 4, our main results are stated and proved. Every homogeneous pre-system satisfying (4.1) can produce a dynamical Yang-Baxter map via the ternary system. More precisely, we construct a category $\mathcal{H}$, isomorphic to the category $\mathcal{A}$, by means of the homogeneous pre-systems with (4.1). Because the category $\mathcal{A}$ is equivalent to the category $\mathcal{D}$, each object of $\mathcal{H}$ gives a dynamical Yang-Baxter map; in particular, we demonstrate dynamical YangBaxter maps provided by a certain left quasigroup and the examples in Section 3.

The last section, Section 5, deals with a relation between the homogeneous pre-system satisfying (4.1) and the left quasigroup with (5.1), which is due to the work in [32, Section 6]. We introduce a category $\mathcal{B}$ concerning the left quasigroups satisfying (5.1) and an essentially surjective functor $J: \mathcal{B} \rightarrow \mathcal{H}$ to construct the dynamical Yang-Baxter maps by means of quasigroups of reflection $[17,27]$.

Our viewpoint sheds some light on the relation between geometry and the dynamical Yang-Baxter map.

## 2 Dynamical Yang-Baxter maps

In this section, we briefly summarize without proofs the relevant material in [32] on the construction of the dynamical Yang-Baxter map.

Definition 1. (1) $(L, \cdot)$ is a left quasigroup (resp. right quasigroup [38, Section I.4.3]), if and only if $L$ is a nonempty set, together with a binary operation $(\cdot)$ on $L$ having the property that, for all $u, w \in L$, there uniquely exists $v \in L$ such that $u \cdot v=w$ (resp. $v \cdot u=w$ ). For the simplicity, one uses the notation $u v$ instead of $u \cdot v(u, v \in L)$.
(2) A quasigroup ( $Q, \cdot)$ is a left and right quasigroup (see [30, Definition I.1.1] and [38, Section I.2]).
(3) A ternary system $(M, \mu)$ is a pair of a nonempty set $M$ and a ternary operation $\mu: M \times M \times M \rightarrow M$.

By this definition, the left quasigroup $L=(L, \cdot)$ has another binary operation $\backslash_{L}$ called a left division [38, Section I.2.2]. For $u, w \in L$, we denote by $u \backslash_{L} w$ the unique element $v \in L$ satisfying $u v=w$,

$$
\begin{equation*}
u \backslash_{L} w=v \Longleftrightarrow u v=w . \tag{2.1}
\end{equation*}
$$

The binary operation on the quasigroup is not always associative.
Example 2. We define the binary operation $(*)$ on the set $Q=\{1,2,3,4,5\}$ of five elements by Table 1. Here $1 * 2=3$. This $Q=(Q, *)$ is a quasigroup, because each element in $Q$ appears once and only once in each row and in each column of Table 1 [30, Theorem I.1.3]. The binary operation $(*)$ is not associative, since $(1 * 2) * 3 \neq 1 *(2 * 3)$. This quasigroup $Q$ is due to Nobusawa [27, Section 6, type 1]. However, the order of the binary operation (*) in Table 1 is reversed.

| $*$ | 1 | 2 | 3 | 4 | 5 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 1 | 1 | 3 | 5 | 2 | 4 |
| 2 | 5 | 2 | 4 | 1 | 3 |
| 3 | 4 | 1 | 3 | 5 | 2 |
| 4 | 3 | 5 | 2 | 4 | 1 |
| 5 | 2 | 4 | 1 | 3 | 5 |

Table 1: Binary operation $(*)$ on $Q$.

Each ternary system $M=(M, \mu)$ satisfying

$$
\begin{align*}
& \mu(a, \mu(a, b, c), \mu(\mu(a, b, c), c, d))=\mu(a, b, \mu(b, c, d))  \tag{2.2}\\
& \mu(\mu(a, b, \mu(b, c, d)), \mu(b, c, d), d)=\mu(\mu(a, b, c), c, d) \tag{2.3}
\end{align*}
$$

for any $a, b, c, d \in M$, can provide a dynamical Yang-Baxter map [32, Theorem 3.2]. Let $L=(L, \cdot)$ be a left quasigroup isomorphic to $M$ as sets, and $\pi: L \rightarrow M$ (set-theoretic) bijection. For $\lambda, u \in L$, we define the maps $\xi_{\lambda}^{(L, M, \pi)}(u): L \rightarrow L$ and $\eta_{\lambda}^{(L, M, \pi)}(u): L \rightarrow L$ as follows: for $v \in L$,

$$
\begin{align*}
& \xi_{\lambda}^{(L, M, \pi)}(u)(v)=\lambda \backslash_{L} \pi^{-1}(\mu(\pi(\lambda), \pi(\lambda u), \pi((\lambda u) v))),  \tag{2.4}\\
& \eta_{\lambda}^{(L, M, \pi)}(u)(v)=\left(\lambda \xi_{\lambda}^{(L, M, \pi)}(v)(u)\right) \backslash_{L}((\lambda v) u) \tag{2.5}
\end{align*}
$$

Let $R^{(L, M, \pi)}(\lambda)(\lambda \in L)$ denote the map from $L \times L$ to itself defined by

$$
\begin{equation*}
R^{(L, M, \pi)}(\lambda)(u, v)=\left(\eta_{\lambda}^{(L, M, \pi)}(v)(u), \xi_{\lambda}^{(L, M, \pi)}(u)(v)\right), \quad u, v \in L \tag{2.6}
\end{equation*}
$$

Theorem 3. The map $R^{(L, M, \pi)}(\lambda)(2.6)$ is a dynamical Yang-Baxter map (1.1) associated with $L, L$ and $(\cdot)$.
We now introduce two categories $\mathcal{A}$ and $\mathcal{D}$ concerning a special class of the dynamical Yang-Baxter maps, which play a central role in this article.

The first task is to explain the category $\mathcal{A}$ (cf. the category $\mathcal{A}_{2}$ in [32, Section 6]). We follow the notation of [16, Chapter XI]. Let $L=(L, \cdot)$ be a left quasigroup, $M=(M, \mu)$ a ternary system satisfying (2.2) and

$$
\begin{gather*}
\mu(a, b, b)=a, \quad \forall a, b \in M  \tag{2.7}\\
\mu(\mu(a, b, c), c, d)=\mu(a, b, d), \quad \forall a, b, c, d \in M \tag{2.8}
\end{gather*}
$$

and $\pi: L \rightarrow M$ a bijection. The object of $\mathcal{A}$ is, by definition, a triple $(L, M, \pi)$.
The morphism $f:(L,(M, \mu), \pi) \rightarrow\left(L^{\prime},\left(M^{\prime}, \mu^{\prime}\right), \pi^{\prime}\right)$ of $\mathcal{A}$ is a homomorphism $f: L \rightarrow L^{\prime}$ of left quasigroups such that $h:=\pi^{\prime} \circ f \circ \pi^{-1}: M \rightarrow M^{\prime}$ is a homomorphism of ternary systems; that is, the map $f: L \rightarrow L^{\prime}$ satisfies

$$
\begin{gather*}
f\left(a \cdot{ }_{L} b\right)=f(a) \cdot L^{\prime} f(b), \quad \forall a, b \in L \\
h(\mu(a, b, c))=\mu^{\prime}(h(a), h(b), h(c)), \quad \forall a, b, c \in M \tag{2.9}
\end{gather*}
$$

The identity id, the source $s(f)$ and the target $b(f)$ of a morphism $f:(L, M, \pi) \rightarrow\left(L^{\prime}, M^{\prime}, \pi^{\prime}\right)$, and the composition $g \circ f$ for morphisms $f:(L, M, \pi) \rightarrow\left(L^{\prime}, M^{\prime}, \pi^{\prime}\right)$ and $g:\left(L^{\prime}, M^{\prime}, \pi^{\prime}\right) \rightarrow\left(L^{\prime \prime}, M^{\prime \prime}, \pi^{\prime \prime}\right)$ are defined as follows: for an object $(L, M, \pi) \in \mathcal{A}$,

$$
\begin{gathered}
\operatorname{id}_{(L, M, \pi)}=\operatorname{id}_{L} \\
s\left(f:(L, M, \pi) \longrightarrow\left(L^{\prime}, M^{\prime}, \pi^{\prime}\right)\right)=(L, M, \pi) \\
b\left(f:(L, M, \pi) \longrightarrow\left(L^{\prime}, M^{\prime}, \pi^{\prime}\right)\right)=\left(L^{\prime}, M^{\prime}, \pi^{\prime}\right)
\end{gathered}
$$

the composition $g \circ f$ is the usual one of the maps $f: L \rightarrow L^{\prime}$ and $g: L^{\prime} \rightarrow L^{\prime \prime}$.
Proposition 4. $\mathcal{A}$ is a category.

The next task is to describe the category $\mathcal{D}$, which is exactly the category $\mathcal{D}_{2}$ in [32, Section 6]. The object of this category $\mathcal{D}$ is a pair $(L, R)$ of a left quasigroup $L=(L, \cdot)$ and a dynamical Yang-Baxter map $R(\lambda): L \times L \rightarrow L \times L$ $(\lambda \in L)$ satisfying

$$
\begin{aligned}
\xi_{\lambda}(u)\left((\lambda u) \backslash_{L}(\lambda u)\right) & =\lambda \backslash_{L} \lambda, \quad \forall \lambda, u \in L \\
\left(\lambda \xi_{\lambda}(u)(v)\right) \eta_{\lambda}(v)(u) & =(\lambda u) v, \quad \forall \lambda, u, v \in L \\
\left(\lambda \xi_{\lambda}(u)(v)\right) \xi_{\lambda \xi_{\lambda}(u)(v)}\left(\eta_{\lambda}(v)(u)\right)(w) & =\lambda \xi_{\lambda}(u)\left((\lambda u) \backslash_{L}(((\lambda u) v) w)\right), \quad \forall \lambda, u, v, w \in L
\end{aligned}
$$

Here, $\left(\eta_{\lambda}(v)(u), \xi_{\lambda}(u)(v)\right):=R(\lambda)(u, v)(\lambda, u, v \in L)$.
The morphism $f:(L, R) \rightarrow\left(L^{\prime}, R^{\prime}\right)$ of $\mathcal{D}$ is a homomorphism $f: L \rightarrow L^{\prime}$ of left quasigroups satisfying

$$
R^{\prime}(f(\lambda)) \circ f \times f=f \times f \circ R(\lambda), \quad \forall \lambda \in L
$$

Proposition 5. $\mathcal{D}$ is a category; the definitions of the identity, the source, the target and the composition are similar to those of the category $\mathcal{A}$.

We can construct functors $S: \mathcal{A} \rightarrow \mathcal{D}$ and $T: \mathcal{D} \rightarrow \mathcal{A}$, which establish an equivalence of the categories $\mathcal{A}$ and $\mathcal{D}$ (cf. [32, Proposition 6.15]): for $(L, M, \pi) \in \mathcal{A}$, set $S(L, M, \pi)=\left(L, R^{(L, M, \pi)}\right)$. Here, $R^{(L, M, \pi)}(\lambda)$ is defined by (2.4), (2.5) and (2.6); for a morphism $f$ of $\mathcal{A}$, write $S(f)=f$; for $(L, R) \in \mathcal{D}, T(L, R)$ denotes the triple $\left(L,(M, \mu), \mathrm{id}_{L}\right)$, where $M=L$ as sets and $\mu(a, b, c)=a \xi_{a}\left(a \backslash_{L} b\right)\left(b \backslash_{L} c\right)(a, b, c \in M(=L))$; for a morphism $f$ of $\mathcal{D}$, set $T(f)=f$.

These functors $S$ and $T$ satisfy $S T=\operatorname{id}_{\mathcal{D}}$, and $\theta(L, M, \pi):=\operatorname{id}_{L}((L, M, \pi) \in \mathcal{A})$ gives a natural isomorphism $\theta: T S \rightarrow \mathrm{id}_{\mathcal{A}}$. Thus, the following theorem holds.

Theorem 6. $S: \mathcal{A} \rightarrow \mathcal{D}$ is an equivalence of categories.

## 3 Homogeneous pre-systems

This section is devoted to introducing homogeneous pre-systems.
Definition 7. (1) A ternary system $G=(G, \eta)$ (Definition 1(3)) is a homogeneous pre-system if and only if the ternary operation $\eta$ satisfies

$$
\begin{gather*}
\eta(x, y, x)=y, \quad \forall x, y \in G  \tag{3.1}\\
\eta(x, y, \eta(u, v, w))=\eta(\eta(x, y, u), \eta(x, y, v), \eta(x, y, w)) \tag{3.2}
\end{gather*}
$$

for all $x, y, u, v, w \in G$.
(2) A homogeneous system $G=(G, \eta)[18]$ is a homogeneous pre-system satisfying

$$
\begin{gather*}
\eta(x, x, y)=y, \quad \forall x, y \in G \\
\eta(x, y, \eta(y, x, z))=z, \quad \forall x, y, z \in G \tag{3.3}
\end{gather*}
$$

We explain two examples in this section: one homogeneous pre-system and one homogeneous system, which imply dynamical Yang-Baxter maps in the next section.

Let $G$ be an abelian group. We define the ternary operation $\eta$ on $G$ by

$$
\begin{equation*}
\eta(x, y, z)=x+y-z, \quad x, y, z \in G \tag{3.4}
\end{equation*}
$$

A trivial verification shows that $G=(G, \eta)$ is a homogeneous pre-system, which is not always a homogeneous system because of (3.3) (cf. [18, Remark 4]).

Another example is a homogeneous system on an arbitrary group $G$ [18, Example in Section 1]. We define the ternary operation $\eta$ on the group $G$ by

$$
\begin{equation*}
\eta(x, y, z)=y x^{-1} z, \quad x, y, z \in G \tag{3.5}
\end{equation*}
$$

It is clear that this $G=(G, \eta)$ is a homogeneous system.
Remark 8. The homogeneous system $(G, \eta)(3.5)$ is equivalent to the notion of a torsor [25,33,36], also known as the principal homogeneous space, up to the choice of the unit element. Hence, the principal homogeneous space provides a homogeneous system.

## 4 A relation between dynamical Yang-Baxter maps and homogeneous pre-systems

In this section, we construct dynamical Yang-Baxter maps (2.6) by means of homogeneous pre-systems $G=(G, \eta)$ satisfying

$$
\begin{equation*}
\eta(x, y, z)=\eta(w, \eta(x, y, w), z), \quad \forall x, y, z, w \in G \tag{4.1}
\end{equation*}
$$

In fact, we present a category $\mathcal{H}$ concerning the homogeneous pre-systems with (4.1); this $\mathcal{H}$ is isomorphic to the category $\mathcal{A}$ in Section 2, and, on account of Theorem 6, every object of $\mathcal{H}$ consequently gives a dynamical YangBaxter map.

Let $L=(L, \cdot)$ be a left quasigroup, $G=(G, \eta)$ a homogeneous pre-system satisfying (4.1) and $\pi: L \rightarrow G$ a (set-theoretic) bijection. The object of $\mathcal{H}$ is a triple $(L, G, \pi)$.

The morphism $f:(L,(G, \eta), \pi) \rightarrow\left(L^{\prime},\left(G^{\prime}, \eta^{\prime}\right), \pi^{\prime}\right)$ of $\mathcal{H}$ is a homomorphism $f: L \rightarrow L^{\prime}$ of left quasigroups such that $h:=\pi^{\prime} \circ f \circ \pi^{-1}: G \rightarrow G^{\prime}$ is a homomorphism of ternary systems; that is, the map $f: L \rightarrow L^{\prime}$ satisfies (2.9) and

$$
h(\eta(x, y, z))=\eta^{\prime}(h(x), h(y), h(z)), \quad \forall x, y, z \in G
$$

Proposition 9. $\mathcal{H}$ is a category; the definitions of the identity, the source, the target and the composition are similar to those of the category $\mathcal{A}$.

In order to prove that the category $\mathcal{H}$ is isomorphic to the category $\mathcal{A}$, we construct functors $F: \mathcal{A} \rightarrow \mathcal{H}$ and $F^{\prime}: \mathcal{H} \rightarrow \mathcal{A}$.

We first introduce the functor $F: \mathcal{A} \rightarrow \mathcal{H}$. Let $(L,(M, \mu), \pi) \in \mathcal{A}$. Define the ternary system $G=(G, \eta)$ by $G=M$ as sets and

$$
\begin{equation*}
\eta(x, y, z)=\mu(y, x, z), \quad x, y, z \in G(=M) . \tag{4.2}
\end{equation*}
$$

Proposition 10. $(L, G, \pi) \in \mathcal{H}$.
Proof. We need only show that $G$ is a homogeneous pre-system satisfying (4.1).
An easy computation shows (3.1) and (4.1).
By virtue of (4.2), the left-hand side of (3.2) is $\mu(y, x, \mu(v, u, w))$, and, with the aid of (2.2), (2.7) and (2.8),

$$
\begin{aligned}
\mu(y, x, \mu(v, u, w)) & =\mu(\mu(y, x, v), v, \mu(v, u, w)) \\
& =\mu(\mu(y, x, v), \mu(\mu(y, x, v), v, u), \mu(\mu(\mu(y, x, v), v, u), u, w)) \\
& =\mu(\mu(y, x, v), \mu(y, x, u), \mu(y, x, w)),
\end{aligned}
$$

which is the right-hand side of (3.2). This proves the proposition.
By setting $F(L,(M, \mu), \pi)=(L, G, \pi)$ and $F(f)=f$ for a morphism $f$ of $\mathcal{A}$, the following proposition holds.
Proposition 11. $F: \mathcal{A} \rightarrow \mathcal{H}$ is a functor.
The next task is to construct a functor $F^{\prime}: \mathcal{H} \rightarrow \mathcal{A}$. Let $(L,(G, \eta), \pi) \in \mathcal{H}$. We define the ternary system $M_{G}=\left(M_{G}, \mu\right)$ by $M_{G}=G$ as sets and

$$
\begin{equation*}
\mu(a, b, c)=\eta(b, a, c), \quad a, b, c \in M_{G}(=G) . \tag{4.3}
\end{equation*}
$$

Proposition 12. $\left(L, M_{G}, \pi\right) \in \mathcal{A}$.
Proof. It suffices to prove that $M_{G}$ satisfies (2.2), (2.7) and (2.8).
A trivial verification shows (2.7) and (2.8).
Due to (4.1) and (4.3), the left-hand side of (2.2) is

$$
\mu(a, \mu(a, b, c), \mu(\mu(a, b, c), c, d))=\eta(\eta(b, a, c), a, \eta(b, a, d)) .
$$

From (3.1) and (3.2),

$$
\eta(\eta(b, a, c), a, \eta(b, a, d))=\eta(\eta(b, a, c), \eta(b, a, b), \eta(b, a, d))=\eta(b, a, \eta(c, b, d)) \text {, }
$$

which is exactly the right-hand side of (2.2).

By setting $F^{\prime}(L,(G, \eta), \pi)=\left(L, M_{G}, \pi\right)$ and $F^{\prime}(f)=f$ for a morphism $f$ of $\mathcal{H}$, the following proposition holds.

Proposition 13. $F^{\prime}: \mathcal{H} \rightarrow \mathcal{A}$ is a functor.
Since the functors $F$ and $F^{\prime}$ satisfy $F^{\prime} F=\operatorname{id}_{\mathcal{A}}$ and $F F^{\prime}=\operatorname{id}_{\mathcal{H}}$, the following theorem holds.
Theorem 14. The categories $\mathcal{A}$ and $\mathcal{H}$ are isomorphic.
By taking account of Theorem 6, we have the following corollary.
Corollary 15. Each object of $\mathcal{H}$ provides a dynamical Yang-Baxter map.
The proof of the following proposition is straightforward.
Proposition 16. The ternary operations (3.4) and (3.5) satisfy (4.1).
As a consequence of Corollary 15 and Proposition 16, the homogeneous pre-system $G$ (3.4) and the homogeneous system $G(3.5)$ imply dynamical Yang-Baxter maps. Let $L=(G, \cdot)$ denote the left quasigroup whose binary operation $(\cdot)$ is defined by

$$
\begin{equation*}
u \cdot v=v, \quad u, v \in L \tag{4.4}
\end{equation*}
$$

and let $\pi: L(=G) \rightarrow G$ be the identity map on $G$. The corresponding dynamical Yang-Baxter maps are as follows: if $G$ is a homogeneous pre-system (3.4), then

$$
R^{\left(L, M_{G}, \pi\right)}(\lambda)(u, v)=(v, \lambda+u-v), \quad \lambda, u, v \in L(=G)
$$

and if $G$ is a homogeneous system (3.5), then

$$
R^{\left(L, M_{G}, \pi\right)}(\lambda)(u, v)=\left(v, \lambda u^{-1} v\right), \quad \lambda, u, v \in L(=G)
$$

## 5 A relation between homogeneous pre-systems and left quasigroups

Because of the work in [32, Section 6] and the fact that the categories $\mathcal{A}$ and $\mathcal{H}$ are isomorphic, every homogeneous pre-system $G$ (Definition 7(1)) in the object $(L, G, \pi) \in \mathcal{H}$ is a left quasigroup (Definition 1(1)) whose binary operation gives the ternary operation of $G$. This last section demonstrates it by constructing a category $\mathcal{B}$ concerning the left quasigroups with (5.1) and an essentially surjective functor $J: \mathcal{B} \rightarrow \mathcal{H}$ (see [32, Proposition 6.17]). The functors $J: \mathcal{B} \rightarrow \mathcal{H}, S: \mathcal{A} \rightarrow \mathcal{D}$ in Section 2, and $F^{\prime}: \mathcal{H} \rightarrow \mathcal{A}$ in Section 4, together with quasigroups of reflection [17,27], provide examples of the dynamical Yang-Baxter map.

The first task is to introduce a category $\mathcal{B}$. Let $L_{1}, L_{2}=\left(L_{2}, *\right)$ be left quasigroups. We assume that the left quasigroup $L_{2}$ satisfies

$$
\begin{equation*}
(a * c) \backslash_{L_{2}}((a * b) * c)=\left(a^{\prime} * c\right) \backslash_{L_{2}}\left(\left(a^{\prime} * b\right) * c\right), \quad \forall a, a^{\prime}, b, c \in L_{2} . \tag{5.1}
\end{equation*}
$$

Here the symbol $\backslash_{L_{2}}$ is the left division (2.1) of $L_{2}$. Let $\pi: L_{1} \rightarrow L_{2}$ be a (set-theoretic) bijection. An object of $\mathcal{B}$ is such a triple $\left(L_{1}, L_{2}, \pi\right)$.

A morphism $f:\left(L_{1}, L_{2}, \pi\right) \rightarrow\left(L_{1}^{\prime}, L_{2}^{\prime}, \pi^{\prime}\right)$ is a homomorphism $f: L_{1} \rightarrow L_{1}^{\prime}$ of left quasigroups such that $\pi^{\prime} \circ f \circ \pi^{-1}: L_{2} \rightarrow L_{2}^{\prime}$ is also a homomorphism of left quasigroups.

Proposition 17. $\mathcal{B}$ is a category; the definitions of the identity, the source, the target and the composition are similar to those of the category $\mathcal{A}$.

The next task is to construct a functor $J: \mathcal{B} \rightarrow \mathcal{H}$. Let $\left(L_{1},\left(L_{2}, *\right), \pi\right) \in \mathcal{B}$. We define the ternary system $G_{L_{2}}=\left(G_{L_{2}}, \eta_{L_{2}}\right)$ by $G_{L_{2}}=L_{2}$ as sets and

$$
\begin{equation*}
\eta_{L_{2}}(x, y, z)=z *\left(x \backslash_{L_{2}} y\right), \quad x, y, z \in G_{L_{2}}\left(=L_{2}\right) \tag{5.2}
\end{equation*}
$$

Proposition 18. $\left(L_{1}, G_{L_{2}}, \pi\right) \in \mathcal{H}$.

Proof. It suffices to prove that $G_{L_{2}}$ is a homogeneous pre-system satisfying (4.1).
We give a proof only for (3.2) because the rest of the proof is straightforward. Let $x, y, u, v, w \in G\left(=L_{2}\right)$. From (5.2) we have

$$
\begin{align*}
\eta_{L_{2}}\left(x, y, \eta_{L_{2}}(u, v, w)\right) & =\left(w *\left(u \backslash_{L_{2}} v\right)\right) *\left(x \backslash_{L_{2}} y\right) \\
& =\left(w *\left(x \backslash_{L_{2}} y\right)\right) *\left(\left(w *\left(x \backslash_{L_{2}} y\right)\right) \backslash_{L_{2}}\left(\left(w *\left(u \backslash_{L_{2}} v\right)\right) *\left(x \backslash_{L_{2}} y\right)\right)\right) . \tag{5.3}
\end{align*}
$$

With the aid of (5.1), the right-hand side of (5.3) is

$$
\begin{aligned}
(w * & \left.\left(x \backslash_{L_{2}} y\right)\right) *\left(\left(w *\left(x \backslash_{L_{2}} y\right)\right) \backslash_{L_{2}}\left(\left(w *\left(u \backslash_{L_{2}} v\right)\right) *\left(x \backslash_{L_{2}} y\right)\right)\right) \\
& =\left(w *\left(x \backslash_{L_{2}} y\right)\right) *\left(\left(u *\left(x \backslash_{L_{2}} y\right)\right) \backslash_{L_{2}}\left(\left(u *\left(u \backslash_{L_{2}} v\right)\right) *\left(x \backslash_{L_{2}} y\right)\right)\right) \\
& =\left(w *\left(x \backslash_{L_{2}} y\right)\right) *\left(\left(u *\left(x \backslash_{L_{2}} y\right)\right) \backslash_{L_{2}}\left(v *\left(x \backslash_{L_{2}} y\right)\right)\right)
\end{aligned}
$$

which is exactly $\eta_{L_{2}}\left(\eta_{L_{2}}(x, y, u), \eta_{L_{2}}(x, y, v), \eta_{L_{2}}(x, y, w)\right)$. This is the desired conclusion.
Let $f:\left(L_{1}, L_{2}, \pi\right) \rightarrow\left(L_{1}^{\prime}, L_{2}^{\prime}, \pi^{\prime}\right)$ be a morphism of the category $\mathcal{B}$. The map $f: L_{1} \rightarrow L_{1}^{\prime}$ is a homomorphism of left quasigroups. Moreover, $h:=\pi^{\prime} \circ f \circ \pi^{-1}: L_{2} \rightarrow L_{2}^{\prime}$ is a homomorphism of ternary systems from $G_{L_{2}}$ to $G_{L_{2}^{\prime}}$, because $h$ is a homomorphism of left quasigroups. As a result, $f:\left(L_{1}, L_{2}, \pi\right) \rightarrow\left(L_{1}^{\prime}, L_{2}^{\prime}, \pi^{\prime}\right)$ is a morphism of the category $\mathcal{H}$.

We set $J\left(L_{1}, L_{2}, \pi\right)=\left(L_{1}, G_{L_{2}}, \pi\right)$ for $\left(L_{1}, L_{2}, \pi\right) \in \mathcal{B}$ and $J(f)=f$ for a morphism $f$ of $\mathcal{B}$.
Proposition 19. $J: \mathcal{B} \rightarrow \mathcal{H}$ is a functor.
This functor $J$ is essentially surjective. In fact, for any $(L, G, \pi) \in \mathcal{H}$, we can construct a left quasigroup $L_{2}$ such that $\left(L, L_{2}, \pi\right) \in \mathcal{B}$ and $J\left(L, L_{2}, \pi\right)=(L, G, \pi)$. We fix any element $\lambda_{0} \in G$. Set $L_{2}=G$ as sets and

$$
\begin{equation*}
a * b=\eta\left(\lambda_{0}, b, a\right), \quad a, b \in L_{2}(=G) \tag{5.4}
\end{equation*}
$$

Due to (3.1) and (4.1), $L_{2}$ is a left quasigroup; its left division is defined by

$$
\begin{equation*}
a \backslash_{L_{2}} c=\eta\left(a, c, \lambda_{0}\right), \quad a, c \in L_{2} . \tag{5.5}
\end{equation*}
$$

Proposition 20. $\left(L, L_{2}, \pi\right) \in \mathcal{B}$.
Proof. We need only show (5.1). Let $a, a^{\prime}, b, c \in L_{2}(=G)$. With the aid of (5.4) and (5.5) we have

$$
\begin{equation*}
(a * c) \backslash_{L_{2}}((a * b) * c)=\eta\left(\eta\left(\lambda_{0}, c, a\right), \eta\left(\lambda_{0}, c, \eta\left(\lambda_{0}, b, a\right)\right), \lambda_{0}\right) . \tag{5.6}
\end{equation*}
$$

From (3.2) and (4.1),

$$
\begin{aligned}
\eta\left(\lambda_{0}, c, \eta\left(\lambda_{0}, b, a\right)\right) & =\eta\left(\lambda_{0}, c, \eta\left(a^{\prime}, \eta\left(\lambda_{0}, b, a^{\prime}\right), a\right)\right) \\
& =\eta\left(\eta\left(\lambda_{0}, c, a^{\prime}\right), \eta\left(\lambda_{0}, c, \eta\left(\lambda_{0}, b, a^{\prime}\right)\right), \eta\left(\lambda_{0}, c, a\right)\right)
\end{aligned}
$$

By taking into account (4.1) again, the right-hand side of (5.6) is

$$
\eta\left(\eta\left(\lambda_{0}, c, a\right), \eta\left(\lambda_{0}, c, \eta\left(\lambda_{0}, b, a\right)\right), \lambda_{0}\right)=\eta\left(\eta\left(\lambda_{0}, c, a^{\prime}\right), \eta\left(\lambda_{0}, c, \eta\left(\lambda_{0}, b, a^{\prime}\right)\right), \lambda_{0}\right)
$$

which is exactly the right-hand side of (5.1) by virtue of (5.4) and (5.5). This proves the proposition.
It is immediate that $J\left(L, L_{2}, \pi\right)=(L, G, \pi)$, and consequently, the following holds.
Proposition 21. The functor $J: \mathcal{B} \rightarrow \mathcal{H}$ is essentially surjective.
Corollary 22. The functor $S F^{\prime} J: \mathcal{B} \rightarrow \mathcal{D}$ is essentially surjective.
The final task of this section is to construct dynamical Yang-Baxter maps by means of the functor $S F^{\prime} J: \mathcal{B} \rightarrow \mathcal{D}$ and quasigroups of reflection; see [17, Section 1].
Definition 23. A pair $(G, *)$ of a nonempty set $G$ and a binary operation $(*)$ on $G$ is called a quasigroup of reflection if and only if $(G, *)$ is a left quasigroup (Definition 1(1)) satisfying

$$
\begin{gather*}
x * x=x, \quad \forall x \in G \\
(x * y) * y=x, \quad \forall x, y \in G  \tag{5.7}\\
(x * y) * z=(x * z) *(y * z), \quad \forall x, y, z \in G \tag{5.8}
\end{gather*}
$$

It follows from (5.7) that $(G, *)$ is a quasigroup (Definition 1(2)).
Remark 24. (1) The above definition is slightly different from that in [17] (see also [26, II.1.1] and [27, Section 1]); the order of the binary operation $(*)$ on $G$ is reversed.
(2) The identity (5.8) is called a right distributive law [30, Section V.2].
(3) The quasigroup of reflection gives an involutory quandle $[1,12,37]$ by reversing the order of the binary operation in Definition 23.

A straightforward computation shows that Nobusawa's quasigroup $(Q, *)$ in Example 2 is a quasigroup of reflection.

Let $(G, *)$ be a quasigroup of reflection, and $L$ a left quasigroup isomorphic to $G$ as sets. We denote by $\pi$ a set-theoretic bijection from $L$ to $G$. Because (5.8) immediately induces (5.1),
Proposition 25. $(L, G, \pi) \in \mathcal{B}$.
The quasigroup $G=(G, *)$ of reflection hence produces the dynamical Yang-Baxter map $R(\lambda)$ defined by $(L, R)=S F^{\prime} J(L, G, \pi) \in \mathcal{D}$.

For example, let $L=(G, \cdot)$ denote the left quasigroup (4.4) and $\pi: L(=G) \rightarrow G$ the identity map on $G$. The above dynamical Yang-Baxter map $R(\lambda)$ induced by $(L, G, \pi) \in \mathcal{B}$ is

$$
\begin{equation*}
R(\lambda)(u, v)=\left(v, v *\left(u \backslash_{G} \lambda\right)\right), \quad \lambda, u, v \in L(=G) . \tag{5.9}
\end{equation*}
$$

For Nobusawa's quasigroup $Q=(Q, *)$, the corresponding dynamical Yang-Baxter map (5.9) is really dependent on the parameter $\lambda$; in fact,

$$
R(1)(1,1)=(1,1), \quad R(2)(1,1)=(1,2)
$$

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