

## Initial Boundary Value Problem for the Wave Equation in a Domain with a Corner

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### Introduction.

In this paper, we consider the mixed problem for the wave equation in the domains  $\{(t, x, y, w) \mid t > 0, x > 0, y > 0, w \in \mathbf{R}^n\}$  and  $\{(t, x, y, z, w) \mid t > 0, x > 0, y > 0, z > 0, w \in \mathbf{R}^n\}$ . On the boundary  $x = 0$ , an oblique boundary condition is given and on the other boundary ( $y = 0$  or  $z = 0$ ), the Dirichlet or Neumann boundary condition is given. Such a problem was considered in [1], [2], [5], [14], [16] and [17].

The aim of this paper is to give the energy inequality for the above problem with non-homogeneous boundary condition, with the aid of which we can prove an existence and uniqueness theorem. Our result is an extension of the result in [1], [16] and [17]. This energy estimate is the same as the one for the mixed problem in the domain with smooth boundary. The similar result is obtained only in [16] and [17].

Our method is to reduce the mixed problem for the wave equation in a domain with a corner to the one for symmetric hyperbolic systems of first order with positive (or non-negative) boundary condition on the boundaries. This method is discovered in [27], and is given in Appendix. Such a method is treated and developed in [18], [7], [19], [20], [22], [24] and [26], and used in [17], [23] and [25]. In [27], we improved the results in [19: §4] and [26: §3], and obtain our results by the use of its reformation in [27].

As for the other results on the mixed problem for hyperbolic equations in a domain with non-smooth boundary, we can refer to [6], [13], [15] and [21].

As for the other symmetrization on the Cauchy problem and the mixed problem for hyperbolic equation, we can refer to [3], [4], [8], [9], [10] and [11].

An outline of this paper is as follows. In §1, we give the notations. In §2, we state the problems and the results. In §3, we discuss the symmetrization of the mixed problems (P.1), (P.2) and (P.3). In §4, we treat the boundary estimate of the solution. In §5, we prove Main Theorem 1. In §6, we prove Main Theorem 2. In §7, we prove Main

Theorem 3. In Appendix, we state a result in [27].

### §1. Notation.

$\mathbf{R}^m (\mathbf{C}^m)$  :  $m$ -dimensional real (complex) Euclidean space .

$\mathbf{R}_+^m$  : the set  $\{(x, y) \mid x > 0, y \in \mathbf{R}^{m-1}\}$  .

[ , ] : the inner product in  $\mathbf{C}^m$  .

$$(u, v) = \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} u \cdot \bar{v} dw dy dx \quad \text{or} \quad \int_0^\infty \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} u \cdot \bar{v} dw dz dy dx .$$

$$\langle u, v \rangle = \int_0^\infty \int_{\mathbf{R}^n} u \cdot \bar{v} dw dy \quad \text{or} \quad \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} u \cdot \bar{v} dw dz dy .$$

$$\langle\langle u, v \rangle\rangle = \int_0^\infty \int_{\mathbf{R}^n} u \cdot \bar{v} dw dx \quad \text{or} \quad \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} u \cdot \bar{v} dw dz dx .$$

$$\langle\langle\langle u, v \rangle\rangle\rangle = \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} u \cdot \bar{v} dw dy dx .$$

$$\|u\|_{m, \mu, T}^2 = \sum_{\alpha + \beta + \gamma + \delta + |\rho| = m} \int_0^T \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial x} \right)^\gamma \left( \frac{\partial}{\partial y} \right)^\delta \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dy dx dt$$

$$\text{or} \quad \sum_{\alpha + \beta + \gamma + \delta + |\rho| = m} \int_0^T \int_0^\infty \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial x} \right)^\gamma \left( \frac{\partial}{\partial y} \right)^\delta \left( \frac{\partial}{\partial z} \right)^\theta \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dz dy dx dt .$$

$$\langle u \rangle_{m, \mu, T}^2 = \sum_{\alpha + \beta + \gamma + |\rho| = m} \int_0^T \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial y} \right)^\gamma \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dy dt$$

$$\text{or} \quad \sum_{\alpha + \beta + \gamma + \delta + |\rho| = m} \int_0^T \int_0^\infty \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial y} \right)^\gamma \left( \frac{\partial}{\partial z} \right)^\delta \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dz dy dt .$$

$$\langle\langle u \rangle\rangle_{m, \mu, T}^2 = \sum_{\alpha + \beta + \gamma + |\rho| = m} \int_0^T \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial x} \right)^\gamma \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dx dt$$

or  $\sum_{\alpha+\beta+\gamma+\delta+|\rho|=m} \int_0^T \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial x} \right)^\gamma \left( \frac{\partial}{\partial z} \right)^\delta \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dz dx dt .$

$\langle\langle u \rangle\rangle_m \cdots$  the norm of Sobolev space  $H_m(\mathbf{R}_{x+}^1 \times \mathbf{R}_w^n)$   
 or the norm of Sobolev space  $H_m(\mathbf{R}_{x+}^1 \times \mathbf{R}_{z+}^1 \times \mathbf{R}_w^n)$ .

$$\langle\langle\langle u \rangle\rangle\rangle_{m,\mu,T} = \sum_{\alpha+\beta+\gamma+\delta+|\rho|=m} \int_0^T \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial x} \right)^\gamma \left( \frac{\partial}{\partial y} \right)^\delta \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dy dx dt .$$

$\langle\langle\langle u \rangle\rangle\rangle_m \cdots$  the norm of Sobolev space  $H_m(\mathbf{R}_{x+}^1 \times \mathbf{R}_{y+}^1 \times \mathbf{R}_w^n)$ .

$$\|u(t)\|_{m,\mu}^2 = \sum_{\alpha+\beta+\gamma+\delta+|\rho|=m} \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial x} \right)^\gamma \left( \frac{\partial}{\partial y} \right)^\delta \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dy dx$$

or  $\sum_{\alpha+\beta+\gamma+\delta+\theta+|\rho|=m} \int_0^\infty \int_0^\infty \int_0^\infty \int_{\mathbf{R}^n} \left| e^{-\mu t} \mu^\alpha \left( \frac{\partial}{\partial t} \right)^\beta \left( \frac{\partial}{\partial x} \right)^\gamma \left( \frac{\partial}{\partial y} \right)^\delta \left( \frac{\partial}{\partial z} \right)^\theta \left( \frac{\partial}{\partial w} \right)^\rho u \right|^2 dw dz dy dx .$

$$\mathcal{F}_{(x,w)} u = \int_{-\infty}^{\infty} \int_{\mathbf{R}^n} e^{-(ix \cdot \xi + iw \cdot \zeta)} u(x, w) dw dx$$

( $w = (w_1, \dots, w_n)$ ,  $\zeta = (\zeta_1, \dots, \zeta_n)$ ,  $w \cdot \zeta = \sum_{j=1}^n w_j \zeta_j$ ).

$$A_{x,w,\mu}^{\pm\theta} = \bar{\mathcal{F}}_{(x,w)} ((\xi^2 + |\zeta|^2 + \mu^2)^{\pm\theta/2}) \mathcal{F}_{(x,w)} \quad (|\zeta| = (\zeta_1^2 + \dots + \zeta_n^2)^{1/2}).$$

$\mathcal{H}_{m,\mu}[(\mathbf{R}_+^1)^l \times \mathbf{R}^n]$ : the space of functions which are obtained by the completion of  $C_0^\infty[(\overline{\mathbf{R}_+^1})^l \times \mathbf{R}^n]$  with the norm  $\|u\|_{m,\mu,\infty}$  ( $l=3, 4$ ).

## §2. The statement of the problem and the result.

We consider the mixed problems

$$\begin{cases} L_1[u] = \frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial y^2} - \sum_{j=1}^n \frac{\partial^2 u}{\partial w_j^2} + m(t, x, y, w)u = f(t, x, y, w) \\ u(0, x, y, w) = u_0(x, y, w), \quad u_t(0, x, y, w) = u_1(x, y, w) \end{cases}$$

$$(P.1) \quad \begin{cases} B_1[u]|_{x=0} = \frac{\partial u}{\partial x} + b(t, y, w) \frac{\partial u}{\partial y} + \sum_{j=1}^n d_j(t, y, w) \frac{\partial u}{\partial w_j} \\ \quad - c(t, y, w) \frac{\partial u}{\partial t} + \gamma(t, y, w) u|_{x=0} = g(t, y, w) \\ B_2[u]|_{y=0} = u|_{y=0} = h(t, x, w) \\ (t, x, y, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n, \end{cases}$$

$$(P.2) \quad \begin{cases} L_1[u] = f(t, x, y, w) \\ u(0, x, y, w) = u_0(x, y, w), \quad u_t(0, x, y, w) = u_1(x, y, w) \\ B_1[u]|_{x=0} = g(t, y, w) \\ B_3[u]|_{y=0} = \frac{\partial u}{\partial y}|_{y=0} = h(t, x, w) \\ (t, x, y, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n \end{cases}$$

and

$$(P.3) \quad \begin{cases} L_2[u] = \frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 u}{\partial z^2} - \sum_{j=1}^n \frac{\partial^2 u}{\partial w_j^2} + m(t, x, y, z, w) u = f(t, x, y, z, w) \\ u(0, x, y, z, w) = u_0(x, y, z, w), \quad u_t(0, x, y, z, w) = u_1(x, y, z, w) \\ B_4[u]|_{x=0} = \frac{\partial u}{\partial x} + b_1(t, y, z, w) \frac{\partial u}{\partial y} + b_2(t, y, z, w) \frac{\partial u}{\partial z} + \sum_{j=1}^n d_j(t, y, z, w) \frac{\partial u}{\partial w_j} \\ \quad - c(t, y, z, w) \frac{\partial u}{\partial t} + \gamma(t, y, z, w) u|_{x=0} = g(t, y, z, w) \\ B_5[u]|_{y=0} = u|_{y=0} = h(t, x, z, w) \\ B_6[u]|_{z=0} = u|_{z=0} = k(t, x, y, w) \\ (t, x, y, z, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n, \end{cases}$$

where  $w = (w_1, w_2, \dots, w_n)$  ( $n \geq 1$ ), the coefficient  $m$  belongs to  $\mathcal{B}^0((\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n)$  ( $(\mathcal{B}^0((\overline{\mathbf{R}_+^1})^4 \times \mathbf{R}^n))$  and is constant outside a compact set in  $(\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n$  ( $(\overline{\mathbf{R}_+^1})^4 \times \mathbf{R}^n$ )), the coefficients  $b, d_j, c$  and  $\gamma$  in (P.1) and (P.2) belong to  $\mathcal{B}^1((\overline{\mathbf{R}_+^1})^2 \times \mathbf{R}^n)$  and are constant outside a compact set in  $(\overline{\mathbf{R}_+^1})^2 \times \mathbf{R}^n$ , the coefficients  $b_1, b_2, d_j, c$  and  $\gamma$  in (P.3) belong to  $\mathcal{B}^1((\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n)$  and are constant outside a compact set in  $(\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n$ .

We assume the following condition for the problem (P.1) or (P.2),

$$(A.I) \quad |1+c|-|1-c|>2\left\{|b|^2+\sum_{j=1}^n|d_j|^2\right\}^{1/2}$$

for all  $(t, y, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n$ .

We assume the following condition for the problem (P.3),

$$(A.II) \quad |1+c|-|1-c| > 2 \left\{ |b_1|^2 + |b_2|^2 + \sum_{j=1}^n |d_j|^2 \right\}^{1/2}$$

for all  $(t, y, z, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n$ .

**REMARK 1.** Assume the condition (A.I) ((A.II)). Then, the boundary operator  $B_1$  ( $B_4$ ) satisfies the uniform Lopatinski condition.

Now, we state our results.

**MAIN THEOREM 1.** Assume the condition (A.I). Then, there exist positive constants  $C$  and  $\mu_0$  such that, for a solution  $u$  of (P.1) which belongs to  $\mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^3 \times \mathbf{R}^n]$ , the following energy inequality holds,

$$(2.1) \quad \begin{aligned} & \|u(t)\|_{1,\mu}^2 + \mu \|u\|_{1,\mu,t}^2 + \langle u \rangle_{1,\mu,t}^2 + \langle\langle u \rangle\rangle_{1,\mu,t}^2 \\ & \leq C \left\{ \|u(0)\|_{1,\mu}^2 + \frac{1}{\mu} \|f\|_{0,\mu,t}^2 + \langle g \rangle_{0,\mu,t}^2 + \langle\langle h \rangle\rangle_{1,\mu,t}^2 \right\} \end{aligned}$$

for all  $t \in \mathbf{R}_+^1$  and all  $\mu \geq \mu_0$ .

**REMARK 2.** Under the condition

$$|1-c|-|1-c| \geq 2 \left\{ |b|^2 + \sum_{j=1}^n |d_j|^2 \right\}^{1/2}$$

for all  $(t, y, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n$ , we hope to solve the problem (P.1) in future.

**MAIN THEOREM 2.** Assume the condition (A.I). Then, there exist positive constants  $C$  and  $\mu_0$  such that, for a solution  $u$  of (P.2) which belongs to  $\mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^3 \times \mathbf{R}^n]$ , the following energy inequality holds,

$$(2.2) \quad \begin{aligned} & \|u(t)\|_{1,\mu}^2 + \mu \|u\|_{1,\mu,t}^2 + \langle u \rangle_{1,\mu,t}^2 + \mu \sum_{j=0}^1 \left\langle \left\langle A_{x,w,\mu}^{-1/2} \left( \frac{\partial}{\partial y} \right)^j u \right\rangle \right\rangle_{1-j,\mu,t}^2 \\ & \leq C \left\{ \|u(0)\|_{1,\mu}^2 + \frac{1}{\mu} \|f\|_{0,\mu,t}^2 + \langle g \rangle_{0,\mu,t}^2 + \frac{1}{\mu} \langle\langle A_{x,w,\mu}^{1/2} h \rangle\rangle_{0,\mu,t}^2 \right\} \end{aligned}$$

for all  $t \in \mathbf{R}_+^1$  and all  $\mu \geq \mu_0$ .

**REMARK 3.** For the problem (P.2) with homogeneous boundary conditions, the condition (A.I) is replaced by the following conditions:

$$|1-c|-|1-c| \geq 2 \left\{ |b|^2 + \sum_{j=1}^n |d_j|^2 \right\}^{1/2}$$

and

$$(\tilde{b}, c) \neq (1, 1) \quad (\tilde{b}) = \left( |b|^2 + \sum_{j=1}^n |d_j|^2 \right)^{1/2}$$

for all  $(t, y, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n$ . Then, we have

$$(2.3) \quad ||| u(t) |||_{1,\mu}^2 + \mu \| u \|_{1,\mu,t}^2 \leq C \left\{ ||| u(0) |||_{1,\mu}^2 + \frac{1}{\mu} \| f \|_{0,\mu,t}^2 \right\}.$$

**MAIN THEOREM 3.** *Assume the condition (A.II). Then, there exist positive constants  $C$  and  $\mu_0$  such that, for a solution  $u$  of (P.3) which belongs to  $\mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^4 \times \mathbf{R}^n]$ , the following energy inequality holds,*

$$(2.4) \quad \begin{aligned} & ||| u(t) |||_{1,\mu}^2 + \mu \| u \|_{1,\mu,t}^2 + \langle u \rangle_{1,\mu,t}^2 + \langle \langle u \rangle \rangle_{1,\mu,t}^2 + \langle \langle \langle u \rangle \rangle \rangle_{1,\mu,t}^2 \\ & \leq C \left\{ ||| u(0) |||_{1,\mu}^2 + \frac{1}{\mu} \| f \|_{0,\mu,t}^2 + \langle g \rangle_{0,\mu,t}^2 + \langle \langle h \rangle \rangle_{1,\mu,t}^2 + \langle \langle \langle k \rangle \rangle \rangle_{1,\mu,t}^2 \right\} \end{aligned}$$

for all  $t \in \mathbf{R}_+^1$  and all  $\mu \geq \mu_0$ .

**REMARK 4.** Under the condition

$$|1+c| - |1-c| \geq 2 \left\{ |b_1|^2 + |b_2|^2 + \sum_{j=1}^n |d_j|^2 \right\}^{1/2}$$

for all  $(t, y, z, w) \in \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n$ , we hope to solve the problem (P.3) in future.

**REMARK 5.** We will treat the regularity problem of the solution  $u$  of the problems (P.1), (P.2) and (P.3) in future.

### §3. The symmetrization of the mixed problems (P.1), (P.2) and (P.3).

In this section, we transform the mixed problems (P.1), (P.2) and (P.3) to the ones for symmetric hyperbolic systems of first order which have a positive boundary condition on a boundary  $x=0$  and a non-negative boundary condition on the boundary  $y=0$  ( $z=0$ ), by using the result in [27].

We set

$$(3.1) \quad U = \begin{pmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \end{pmatrix} = \begin{pmatrix} u_t - u_x + \theta_1(\alpha - i\beta)u_y + \theta_1(p - iq)u_z \\ \theta_1(u_t + u_x) + (\alpha + i\beta)u_y + (p + iq)u_z \\ u_y \\ u_z \end{pmatrix}$$

where  $u_{tt} - u_{xx} - u_{yy} - u_{zz} = 0$ ,  $\theta_1$  is a complex constant,  $\alpha$ ,  $\beta$ ,  $p$  and  $q$  are real constants which satisfy the inequalities  $\alpha^2 + \beta^2 \leq 1$  and  $p^2 + q^2 \leq 1$ .

**LEMMA 3.1.** *U satisfies the following equation:*

$$(3.2) \quad M_1 U_t = A_{11} U_x + A_{12} U_y + A_{13} U_z$$

where

$$M_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \gamma l & -al \\ 0 & 0 & -al & sl \end{pmatrix}, \quad A_{11} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \gamma m & -am \\ 0 & 0 & -am & sm \end{pmatrix},$$

$$A_{12} = \begin{pmatrix} 0 & \alpha - i\beta & \gamma & -a \\ \alpha + i\beta & 0 & \gamma\theta_1 & -a\theta_1 \\ \gamma & \gamma\bar{\theta}_1 & -2\gamma \operatorname{Re}\{\theta_1(\alpha - i\beta)\} & 2a \operatorname{Re}\{\theta_1(\alpha - i\beta)\} \\ -a & -a\bar{\theta}_1 & 2a \operatorname{Re}\{\theta_1(\alpha - i\beta)\} & -2s \operatorname{Re}\{\theta_1(\alpha - i\beta)\} \end{pmatrix},$$

$$A_{13} = \begin{pmatrix} 0 & p - iq & -a & s \\ p + iq & 0 & -a\theta_1 & s\theta_1 \\ -a & -a\bar{\theta}_1 & -2\gamma \operatorname{Re}\{\theta_1(p - iq)\} & 2a \operatorname{Re}\{\theta_1(p - iq)\} \\ s & s\bar{\theta}_1 & 2a \operatorname{Re}\{\theta_1(p - iq)\} & -2s \operatorname{Re}\{\theta_1(p - iq)\} \end{pmatrix},$$

$$a = \operatorname{Re}\{(\alpha - i\beta)(p + iq)\}, \quad l = 1 + |\theta_1|^2, \quad m = 1 - |\theta_1|^2,$$

$$\gamma = 1 - \alpha^2 - \beta^2 \quad \text{and} \quad s = 1 - p^2 - q^2.$$

PROOF. By simple calculations, we obtain Lemma 3.1.

Q.E.D.

REMARK 6. We have that

$$(3.3) \quad M_1 > 0 \quad \text{if and only if} \quad \begin{cases} \gamma > 0 \\ \gamma s - a^2 > 0. \end{cases}$$

COROLLARY. For  $U = {}^t(U_1, U_2, U_3, \dots, U_n, U_{n+1}) = {}^t(u_t - u_{x_1}, \theta_2(u_t + u_{x_1}), u_{x_2}, \dots, u_{x_{n-1}}, u_{x_n})$ , we have

$$(3.4) \quad M_2 U_t = A_{21} U_{x_1} + \sum_{j=2}^n A_{2j} U_{x_j}$$

where  $u_{tt} - \sum_{j=1}^n u_{x_j x_j} = 0$ ,

$$M_2 = \operatorname{diag}(1, 1, 1 + |\theta_2|^2, \dots, 1 + |\theta_2|^2, 1 + |\theta_2|^2),$$

$$A_{21} = \operatorname{diag}(-1, 1, 1 - |\theta_2|^2, \dots, 1 - |\theta_2|^2, 1 - |\theta_2|^2),$$

$$A_{22} = \begin{pmatrix} 0 & 0 & 1 & 0 & \dots \\ 0 & 0 & \theta_2 & 0 & \dots \\ 1 & \bar{\theta}_2 & 0 & \dots & \dots \\ & 0 & & \dots & \dots \\ 0 & \dots & \dots & \dots & 0 \end{pmatrix}, \quad A_{23} = \begin{pmatrix} 0 & 0 & 0 & 1 & \dots \\ 0 & 0 & 0 & \theta_2 & 0 \\ 0 & 0 & 0 & 0 & \dots \\ 1 & \bar{\theta}_2 & 0 & 0 & \dots \\ & 0 & & 0 & \dots \end{pmatrix},$$

From now on, we treat the symmetrization of the problems (P.1), (P.2) and (P.3). Firstly, we consider the problem (P.1) under the condition (A.I).

The functions  $c(t, y, w)$ ,  $b(t, y, w)$  and  $d_j(t, y, w)$  belong to  $\mathcal{B}^1(\overline{\mathbb{R}_+^1})^2 \times \mathbb{R}^n$  and are constant outside a compact set in  $(\overline{\mathbb{R}_+^1})^2 \times \mathbb{R}^n$ . Therefore, by the condition (A.I), we obtain

$$(3.5) \quad \inf_{(t, y, w) \in (\overline{R_+^n})^2 \times R^n} \left\{ 1 - \frac{2}{|1 + c(t, y, w)|} (|b(t, y, w)|^2 + \sum_{j=1}^n |d_j(t, y, w)|^2)^{1/2} \right\} > 0.$$

We set

$$(3.6) \quad \begin{cases} \delta_0 = \frac{1}{2} \inf_{(t, y, w) \in (\overline{\mathbf{R}}^1_+)^2 \times \mathbf{R}^n} \left\{ 1 - \frac{2}{|1+c|} (|b|^2 + \sum_{j=1}^n |d_j|^2)^{1/2} \right\} \\ O_1 = \{(t, y, w) \in \overline{\mathbf{R}}^1_+ \times \overline{\mathbf{R}}^1_+ \times \mathbf{R}^n \mid |1-c(t, y, w)| < \delta_0\} \\ O_2 = \{(t, y, w) \in \overline{\mathbf{R}}^1_+ \times \overline{\mathbf{R}}^1_+ \times \mathbf{R}^n \mid |1-c(t, y, w)| > \delta_0/2\}. \end{cases}$$

Then,  $\{O_j\}_{j=1}^2$  is an open covering of  $\overline{\mathbf{R}_+^1} \times \overline{\mathbf{R}_+^1} \times \mathbf{R}^n$ . Therefore, we have the functions  $\varphi_1(t, y, w)$  and  $\varphi_2(t, y, w)$  which belong to  $\mathcal{B}((\overline{\mathbf{R}_+^1})^2 \times \mathbf{R}^n)$ ,  $\varphi_1 + \varphi_2 = 1$  on  $(\overline{\mathbf{R}_+^1})^2 \times \mathbf{R}^n$  and  $\text{supp}[\varphi_j] \subseteq O_j$  ( $j = 1, 2$ ). Now, we consider the localization problem for (P.1)

$$(3.7) \quad \begin{cases} L_1[\varphi_j u] = \varphi_j f \\ (\varphi_j u)(0, x, y, w) = \varphi_j(0, y, w)u_0 \\ (\varphi_j u)_t(0, x, y, w) = \varphi_j(0, y, w)u_1 + \varphi_{jt}(0, y, w)u_0 \\ B_1[\varphi_j u]|_{x=0} = [B_1, \varphi_j]u|_{x=0} + \varphi_j(t, y, w)g(t, y, w) \\ B_2[\varphi_j u]|_{y=0} = \varphi_j(t, 0, w)h \\ (t, x, y, w) \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^n \end{cases} \quad (j=1, 2).$$

We set

$$(3.8) \quad v_j = \varphi_j(t, y, w) u(t, x, y, w) \quad (j=1, 2),$$

$$(3.9) \quad U = \begin{pmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ \vdots \\ \vdots \\ U_{n+3} \\ U_{n+4} \end{pmatrix} = \begin{pmatrix} v_{1t} - (v_{1x} + \gamma v_1) \\ \theta_3(v_{1t} + (v_{1x} + \gamma v_1)) \\ v_{1y} \\ v_{1w_1} \\ \vdots \\ \vdots \\ v_{1w_n} \\ v_1 \end{pmatrix}$$

and

$$(3.10) \quad V = \begin{pmatrix} V_1 \\ V_2 \\ V_3 \\ V_4 \\ \vdots \\ \vdots \\ V_{n+3} \\ V_{n+4} \end{pmatrix} = \begin{pmatrix} v_{2t} - (v_{2x} + \gamma v_2) \\ \theta_4(v_{2t} + (v_{2x} + \gamma v_2)) \\ v_{2y} \\ v_{2w_1} \\ \vdots \\ \vdots \\ v_{2w_n} \\ v_2 \end{pmatrix}$$

where

$$(3.11) \quad \theta_3 = \frac{\sqrt{\delta_0}}{1 + c(t, y, w)}$$

and

$$(3.12) \quad \theta_4 = \sqrt{\frac{1 - c(t, y, w)}{1 + c(t, y, w)}}$$

Then, we have the following theorems by Corollary of Lemma 3.1.

**THEOREM 3.2.** *For  $U$  in (3.9), we obtain*

$$(3.13) \quad \begin{cases} M_3 U_t = A_3 U_x + A_{30} U_y + \sum_{j=1}^n A_{3j} U_{w_j} + E_3 U + F_3 \\ U(0, x, y, w) = U_0(x, y, w) \\ P_3 U|_{x=0} = G_3(t, y, w) \\ Q_3 U|_{y=0} = H_3(t, x, w) \\ (t, x, y, w) \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^n \end{cases}$$

where

$$M_3 = \text{diag}(1, 1, 1 + |\theta_3|^2, \dots, 1 + |\theta_3|^2, 1),$$

$$A_3 = \text{diag}(-1, 1, 1 - |\theta_3|^2, \dots, 1 - |\theta_3|^2, 1),$$

$$A_{30} = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & \theta_3 & 0 \\ 1 & \bar{\theta}_3 & 0 & \cdot \\ & 0 & \cdot & \cdot \\ 0 & & 0 & 0 \\ 0 & \cdot & \cdot & 0 & 1 \end{pmatrix}, \quad \dots, \quad A_{3n} = \begin{pmatrix} & 1 & 0 \\ & \theta_3 & \cdot \\ 0 & 0 & \cdot \\ \cdot & \cdot & \cdot \\ 1 & \bar{\theta}_3 & 0 & \cdot & 0 & 0 \\ 0 & \cdot & \cdot & \cdot & 0 & 1 \end{pmatrix},$$

$E_3$  is an  $(n+4) \times (n+4)$  matrix which has the property that for  $E_3 = (e_{ij})$ ,  $e_{ij}$  belongs to  $\mathcal{B}^0((\overline{\mathbf{R}}_+^1)^3 \times \mathbf{R}^n)$  and is a constant outside a compact set in  $(\overline{\mathbf{R}}_+^1)^3 \times \mathbf{R}^n$ ,

$$F_3 = {}^t(\tilde{f}, \theta_3 \tilde{f}, 0, \dots, 0) \quad (\tilde{f} = \varphi_1 f),$$

$$P_3 = \left( 1, -\frac{1-c}{\sqrt{\delta_0}}, -\frac{2b}{1+c}, -\frac{2d_1}{1+c}, \dots, -\frac{2d_n}{1+c}, 0 \right),$$

$$Q_3 = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & \cdot \\ & 0 & \cdot & \cdot & \cdot \\ & & 0 & \cdot & \cdot \\ & & & 0 & 1 & 0 \\ 0 & \cdot & \cdot & \cdot & 0 & 1 & 0 \\ 0 & \cdot & \cdot & \cdot & \cdot & 0 & 1 \end{pmatrix},$$

$$G_3 = -\frac{2}{1+c} \{ [B_1, \varphi_1] u|_{x=0} + \varphi_1(t, y, w) g \},$$

$$H_3 = {}^t(\tilde{h}_t - \tilde{h}_x - \tilde{\gamma} \tilde{h}, \theta_{30}(\tilde{h}_t + \tilde{h}_x + \tilde{\gamma} \tilde{h}), \tilde{h}_{w_1}, \dots, \tilde{h}_{w_n}, \tilde{h})$$

$$(\tilde{h} = \varphi_1(t, 0, w) h, \theta_{30} = \theta_3|_{y=0}, \tilde{\gamma} = \gamma|_{y=0}),$$

and there exists a positive constant  $C$  such that

$$(3.14) \quad \begin{cases} [A_3 U, U] \geq C[U, U] & \text{for all } U \in \text{Ker } P_3 \\ [A_{30} U, U] = 0 & \text{for all } U \in \text{Ker } Q_3. \end{cases}$$

REMARK 7. In [27], we obtained the same result for second order hyperbolic equations in  $\mathbf{R}_{t+}^1 \times \mathbf{R}_{x+}^1 \times \mathbf{R}^n$  as (3.13) and (3.14) (see Appendix for a result in [27]).

Here, we give the proof of Theorem 3.2 by the same method as the one in [27].

**PROOF.** By simple calculations, we have (3.13). Furthermore, we get easily

$$[A_{30}U, U] = 0 \quad \text{for all } U \in \text{Ker } Q_3.$$

Let  $U \in \text{Ker } Q_3$ . Then, we obtain

$$(3.15) \quad U_1 = \tilde{\theta}_3 U_2 + \frac{2b}{1+c} U_3 + \frac{2}{1+c} \sum_{j=1}^n d_j U_{j+3} \quad \left( \tilde{\theta}_3 = \frac{1-c}{\sqrt{\delta_0}} \right).$$

We set

$$(3.16) \quad I = [A_3 U, U] \quad \text{for } U \in \text{Ker } P_3$$

and

$$(3.17) \quad |\tilde{b}| = \left( |b|^2 + \sum_{j=1}^n |d_j|^2 \right)^{1/2}.$$

Then, we have

$$(3.18) \quad I = \left\{ -|U_1|^2 + |U_2|^2 + (1 - |\theta_3|^2) |U_3|^2 + (1 - |\theta_3|^2) \sum_{j=1}^n |U_{j+3}|^2 + |U_{n+4}|^2 \right\}.$$

For  $|\tilde{b}| > 0$ , by (3.15), we get

$$\begin{aligned} (3.19) \quad |U_1|^2 &= \left| \tilde{\theta}_3 U_2 + \frac{2}{1+c} \left( b U_3 + \sum_{j=1}^n d_j U_{j+3} \right) \right|^2 \\ &\leq |\tilde{\theta}_3|^2 |U_2|^2 + 4 \frac{|\tilde{b}|^{1/2}}{\sqrt{|1+c|}} |U_2| \cdot \frac{|\tilde{\theta}_3|}{\sqrt{|1+c|}} |\tilde{b}|^{1/2} \\ &\quad \cdot \left| \frac{b}{|\tilde{b}|} U_3 + \sum_{j=1}^n \frac{d_j}{|\tilde{b}|} U_{j+3} \right| + \frac{4}{|1+c|^2} |\tilde{b}|^2 \left\{ |U_3|^2 + \sum_{j=1}^n |U_{j+3}|^2 \right\} \\ &\leq \left( |\tilde{\theta}_3|^2 + \frac{2|\tilde{b}|}{|1+c|} \right) |U_2|^2 + \left\{ \frac{2|\tilde{\theta}_3|^2|\tilde{b}|}{|1+c|} + \frac{4|\tilde{b}|^2}{|1+c|^2} \right\} \left( |U_3|^2 + \sum_{j=1}^n |U_{j+3}|^2 \right). \end{aligned}$$

We notice that (3.19) holds for  $|\tilde{b}| = 0$ . By (3.18) and (3.19), we obtain

$$\begin{aligned} (3.20) \quad I &\geq \left\{ 1 - |\tilde{\theta}_3|^2 - \frac{2|\tilde{b}|}{|1+c|} \right\} |U_2|^2 \\ &\quad + \left\{ 1 - |\theta_3|^2 - \frac{2|\tilde{\theta}_3|^2|\tilde{b}|}{|1+c|} - \frac{4|\tilde{b}|^2}{|1+c|^2} \right\} \left( |U_3|^2 + \sum_{j=1}^n |U_{j+3}|^2 \right) + |U_{n+4}|^2. \end{aligned}$$

We set

$$(3.21) \quad K_1 = 1 - |\tilde{\theta}_3|^2 - \frac{2|\tilde{b}|}{|1+c|}, \quad K_2 = 1 - |\theta_3|^2 - \frac{2|\tilde{\theta}_3|^2|\tilde{b}|}{|1+c|} - \frac{4|\tilde{b}|^2}{|1+c|^2}.$$

By  $\operatorname{Re} c > 0$ ,  $\operatorname{supp}[\varphi_1] \subseteq O_1$ , (3.11) and  $\tilde{\theta}_3 = (1-c)/\sqrt{\delta_0}$ , we get

$$(3.22) \quad |\tilde{\theta}_3|^2 < \delta_0, \quad |\theta_3|^2 < \delta_0.$$

Then, by (3.6) and (3.22), we have

$$K_1 > 1 - \frac{2|\tilde{b}|}{|1+c|} - \delta_0 \geq 2\delta_0 - \delta_0 = \delta_0 > 0$$

and

$$\begin{aligned} K_2 &> 1 - \frac{4|\tilde{b}|^2}{|1+c|} - \left(1 + \frac{2|\tilde{b}|}{|1+c|}\right)\delta_0 \\ &= \left(1 + \frac{2|\tilde{b}|}{|1+c|}\right)\left(1 - \frac{2|\tilde{b}|}{|1+c|} - \delta_0\right) \\ &\geq \left(1 + \frac{2|\tilde{b}|}{|1+c|}\right)(2\delta_0 - \delta_0) = \left(1 + \frac{2|\tilde{b}|}{|1+c|}\right)\delta_0 > 0. \end{aligned}$$

Therefore, we have Theorem 3.2. Q.E.D.

**THEOREM 3.3.** *For  $V$  in (3.10), we have*

$$(3.23) \quad \begin{cases} M_4 V_t = A_4 V_x + A_{40} V_y + \sum_{j=1}^n A_{4j} V_{w_j} + E_4 V + F_4 \\ V(0, x, y, w) = V_0(x, y, w) \\ P_4 V|_{x=0} = G_4(t, y, w) \\ Q_4 V|_{y=0} = H_4(t, x, w) \\ (t, x, y, w) \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^n \end{cases}$$

where

$$M_4 = \operatorname{diag}(1, 1, 1 + |\theta_4|^2, \dots, 1 + |\theta_4|^2, 1),$$

$$A_4 = \operatorname{diag}(-1, 1, 1 - |\theta_4|^2, \dots, 1 - |\theta_4|^2, 1),$$

$$A_{40} = \begin{pmatrix} 0 & 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & \theta_4 & 0 & \cdots & \cdot \\ 1 & \bar{\theta}_4 & 0 & \ddots & & \cdot \\ & 0 & & \ddots & & \cdot \\ 0 & \ddots & \ddots & 0 & 0 & \end{pmatrix}, \quad \dots, \quad A_{4n} = \begin{pmatrix} 1 & 0 & \cdots & 0 & 0 & 0 \\ 0 & \bar{\theta}_4 & 0 & \ddots & 0 & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ 0 & \ddots & \ddots & \ddots & 0 & 1 \end{pmatrix},$$

$E_4$  is an  $(n+4) \times (n+4)$  matrix with the same property as  $E_3$ ,

$$F_4 = (\tilde{f}, \theta_4 \tilde{f}, 0, \dots, 0) \quad (\tilde{f} = \varphi_2 f),$$

$$P_4 = \left( 1, -\theta_4, -\frac{2b}{1+c}, -\frac{2d_1}{1+c}, \dots, -\frac{2d_n}{1+c}, 0 \right),$$

$$Q_4 = Q_3,$$

$$G_4 = -\frac{2}{1+c} \{ [B_1, \varphi_2] u|_{x=0} + \varphi_2(t, y, w) g \},$$

$$H_4 = (\tilde{h}_t - \tilde{h}_x - \tilde{\gamma} \tilde{h}, \theta_{40}(\tilde{h}_t + \tilde{h}_x + \tilde{\gamma} \tilde{h}), \tilde{h}_{w_1}, \dots, \tilde{h}_{w_n}, \tilde{h}) \\ (\tilde{h} = \varphi_2(t, 0, w) h, \theta_{40} = \theta_4|_{y=0}, \tilde{\gamma} = \gamma|_{y=0}),$$

and there exists a positive constant  $C$  such that

$$(3.24) \quad \begin{cases} [A_4 V, V] \geq C[V, V] & \text{for all } V \in \text{Ker } P_4 \\ [A_{40} V, V] = 0 & \text{for all } V \in \text{Ker } Q_4. \end{cases}$$

**REMARK 8.** In [27], we obtained the same result for second order hyperbolic equations in  $\mathbf{R}_{t+}^1 \times \mathbf{R}_{x+}^1 \times \mathbf{R}^n$  as (3.23) and (3.24) (see Appendix for a result in [27]). Here, we give the proof of Theorem 3.3 by the same method as the one in [27].

**PROOF.** By simple calculations, we obtain (3.23). Furthermore, we get easily

$$[A_{40} V, V] = 0 \quad \text{for all } V \in \text{Ker } Q_4.$$

Let  $V \in \text{Ker } P_4$ . Then, we have

$$(3.25) \quad V_1 = \theta_4 V_2 + \frac{2b}{1+c} V_3 + \frac{2}{1+c} \sum_{j=1}^n d_j V_{j+3}.$$

We set

$$(3.26) \quad J = [A_4 V, V] \quad \text{for } V \in \text{Ker } P_4.$$

Then, by the same method as the one in Theorem 3.2, we obtain

$$(3.27) \quad J \geq \left\{ 1 - |\theta_4|^2 - \frac{2|\tilde{b}|}{|1+c|} \right\} |V_2|^2 \\ + \left\{ 1 - |\theta_4|^2 - \frac{2|\theta_4|^2|\tilde{b}|}{|1+c|} - \frac{4|\tilde{b}|^2}{|1+c|^2} \right\} \left( |V_3|^2 + \sum_{j=1}^n |V_{j+3}|^2 \right) + |V_{n+4}|^2$$

where  $|\tilde{b}| = (\|b\|^2 + \sum_{j=1}^n |d_j|^2)^{1/2}$ .

We set

$$(3.28) \quad K_3 = 1 - |\theta_4|^2 - \frac{2|\tilde{b}|}{|1+c|}, \quad K_4 = 1 - |\theta_4|^2 - \frac{2|\theta_4|^2|\tilde{b}|}{|1+c|} - \frac{4|\tilde{b}|^2}{|1+c|^2}.$$

By (A.I) and (3.12), we get

$$(3.29) \quad K_3 = 1 - \frac{|1-c|}{|1+c|} - \frac{2|\tilde{b}|}{|1+c|} = \frac{|1+c|-|1-c|-2|\tilde{b}|}{|1+c|} > 0$$

and

$$(3.30) \quad \begin{aligned} K_4 &= 1 - \frac{|1-c|}{|1+c|} - \frac{2|1-c||\tilde{b}|}{|1+c|^2} - \frac{4|\tilde{b}|^2}{|1+c|^2} \\ &= \left(1 + \frac{2|\tilde{b}|}{|1+c|}\right) \frac{1}{|1+c|} (|1+c|-|1-c|-2|\tilde{b}|) > 0. \end{aligned}$$

Therefore, we have Theorem 3.3.

Q.E.D.

Secondly, we consider the problem (P.2) under the condition (A.I).

**THEOREM 3.4.** *For  $U$  in (3.9), we obtain*

$$(3.31) \quad \begin{cases} M_3 U_t = A_3 U_x + A_{30} U_y + \sum_{j=1}^n A_{3j} U_{w_j} + E_3 U + F_3 \\ U(0, x, y, w) = U_0(x, y, w) \\ P_3 U|_{x=0} = G_3(t, y, w) \\ Q_5 U|_{y=0} = H_5(t, x, w) \\ (t, x, y, w) \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^n \end{cases}$$

where

$$Q_5 = (0, 0, 1, 0, \dots, 0), \quad H_5 = \varphi_1(t, 0, w)h + \varphi_{1y}(t, 0, w)u(t, x, 0, w),$$

and there exists a positive constant  $C$  such that

$$(3.32) \quad \begin{cases} [A_3 U, U] \geq C[U, U] & \text{for all } U \in \text{Ker } P_3 \\ [A_{30} U, U] \geq 0 & \text{for all } U \in \text{Ker } Q_5. \end{cases}$$

**PROOF.** By simple calculations, we have (3.31) and

$$[A_{30} U, U] \geq 0 \quad \text{for all } U \in \text{Ker } Q_5.$$

Also, we obtain

$$[A_3 U, U] \geq C[U, U] \quad \text{for all } U \in \text{Ker } P_3$$

by the proof of Theorem 3.2.

Q.E.D.

**THEOREM 3.5.** *For  $V$  in (3.10), we have*

$$(3.33) \quad \begin{cases} M_4 V_t = A_4 V_x + A_{40} V_y + \sum_{j=1}^n A_{4j} V_{w_j} + E_4 V + F_4 \\ V(0, x, y, w) = V_0(x, y, w) \\ P_4 V|_{x=0} = G_4(t, y, w) \\ Q_6 V|_{y=0} = H_6(t, x, w) \\ (t, x, y, w) \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^n \end{cases}$$

where

$$Q_6 = Q_5 = (0, 0, 1, 0, \dots, 0), \quad H_6 = \varphi_2(t, 0, w)h + \varphi_{2y}(t, 0, w)u(t, x, 0, w)$$

and there exists a positive constant  $C$  such that

$$(3.34) \quad \begin{cases} [A_4 V, V] \geq C[V, V] & \text{for all } V \in \text{Ker } P_4 \\ [A_{40} V, V] \geq 0 & \text{for all } V \in \text{Ker } Q_6. \end{cases}$$

PROOF. By simple calculations, we have (3.33) and

$$[A_{40} V, V] \geq 0 \quad \text{for all } V \in \text{Ker } Q_6.$$

Also, we get

$$[A_4 V, V] \geq C[V, V] \quad \text{for all } V \in \text{Ker } P_4$$

by the proof of Theorem 3.3.

Q.E.D.

Thirdly, we treat the problem (P.3) under the condition (A.II).

We use the same method as the one in treating the problem (P.1) under the condition (A.I).

We set

$$(3.35) \quad \begin{cases} \delta_1 = \frac{1}{2} \inf_{(t, y, z, w) \in (\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n} \left\{ 1 - \frac{2}{|1+c|} \left( |b_1|^2 + |b_2|^2 + \sum_{j=1}^n |d_j|^2 \right)^{1/2} \right\} \\ \tilde{O}_1 = \{(t, y, z, w) \in (\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n \mid |1-c(t, y, z, w)| < \delta_1\} \\ \tilde{O}_2 = \{(t, y, z, w) \in (\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n \mid |1-c(t, y, z, w)| > \delta_1/2\}. \end{cases}$$

Then,  $\delta_1 > 0$  and  $\{\tilde{O}_j\}_{j=1}^2$  is an open covering of  $(\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n$ . Therefore, we have the functions  $\psi_1(t, y, z, w)$  and  $\psi_2(t, y, z, w)$  which belong to  $\mathcal{B}((\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n)$ ,  $\psi_1 + \psi_2 = 1$  on  $(\overline{\mathbf{R}_+^1})^3 \times \mathbf{R}^n$  and  $\text{supp}[\psi_j] \subseteq \tilde{O}_j$  ( $j = 1, 2$ ). Now, we treat the localization problem for (P.3)

$$(3.36) \quad \begin{cases} L_2[\psi_j u] = \psi_j f \\ (\psi_j u)(0, x, y, z, w) = \psi_j(0, y, z, w)u_0 \\ (\psi_j u)_t(0, x, y, z, w) = \psi_j(0, y, z, w)u_1 + \psi_{jt}(0, y, z, w)u_0 \\ B_4[\psi_j u]|_{x=0} = [B_4, \psi_j]u|_{x=0} + \psi_j(t, y, z, w)g \end{cases}$$

$$\begin{cases} B_5[\psi_j u] \Big|_{y=0} = \psi_j(t, 0, z, w) h \\ B_6[\psi_j u] \Big|_{z=0} = \psi_j(t, y, 0, w) k \\ (t, x, y, z, w) \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^n \end{cases} \quad (j=1, 2).$$

We set

$$(3.37) \quad v_j = \psi_j(t, y, z, w) u(t, x, y, z, w) \quad (j=1, 2),$$

$$(3.38) \quad U = \begin{pmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ U_5 \\ \vdots \\ \vdots \\ U_{n+4} \\ U_{n+5} \end{pmatrix} = \begin{pmatrix} v_{1t} - (v_{1x} + \gamma v_1) \\ \theta_5(v_{1t} + (v_{1x} + \gamma v_1)) \\ v_{1y} \\ v_{1z} \\ v_{1w_1} \\ \vdots \\ \vdots \\ v_{1w_n} \\ v_1 \end{pmatrix}$$

and

$$(3.39) \quad V = \begin{pmatrix} V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \\ \vdots \\ \vdots \\ V_{n+4} \\ V_{n+5} \end{pmatrix} = \begin{pmatrix} v_{2t} - (v_{2x} + \gamma v_2) \\ \theta_6(v_{2t} + (v_{2x} + \gamma v_2)) \\ v_{2y} \\ v_{2z} \\ v_{2w_1} \\ \vdots \\ \vdots \\ v_{2w_n} \\ v_2 \end{pmatrix}$$

where

$$(3.40) \quad \theta_5 = \frac{\sqrt{\delta_1}}{1 + c(t, y, z, w)}$$

and

$$(3.41) \quad \theta_6 = \sqrt{\frac{1 - c(t, y, z, w)}{1 + c(t, y, z, w)}}.$$

Then, by the same method as the one in the proof of Theorem 3.2 and Theorem 3.3, we have the following theorems.

**THEOREM 3.6.** *For  $U$  in (3.38), we obtain*

$$(3.42) \quad \begin{cases} M_7 U_t = A_7 U_x + A_{70} U_y + A_{700} U_z + \sum_{j=1}^n A_{7j} U_{w_j} + E_7 U + F_7 \\ U(0, x, y, z, w) = U_0(x, y, z, w) \\ P_7 U|_{x=0} = G_7(t, y, z, w) \\ Q_7 U|_{y=0} = H_7(t, x, z, w) \\ R_7 U|_{z=0} = K_7(t, x, y, w) \\ (t, x, y, z, w) \in (\mathbf{R}_+^1)^4 \times \mathbf{R}^n \end{cases}$$

where

$$M_7 = \text{diag}(1, 1, 1 + |\theta_5|^2, \dots, 1 + |\theta_5|^2, 1),$$

$$A_7 = \text{diag}(-1, 1, 1 - |\theta_5|^2, \dots, 1 - |\theta_5|^2, 1),$$

$$A_{70} = \begin{pmatrix} 0 & 0 & 1 & 0 & \dots \\ 0 & 0 & \theta_5 & 0 & \dots \\ 1 & \bar{\theta}_5 & 0 & \dots \\ 0 & & & \dots \\ 0 & & & 0 \\ 0 & \dots & \dots & 0 & 1 \end{pmatrix}, \quad A_{700} = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 & \dots \\ 0 & 0 & 0 & \theta_5 & 0 & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots \\ 1 & \bar{\theta}_5 & 0 & 0 & \dots & \dots \\ 0 & & & & \dots & 0 \\ 0 & \dots & \dots & \dots & 0 & 1 \end{pmatrix},$$

$$\dots, \quad A_{7n} = \begin{pmatrix} & & 1 & 0 \\ & & \theta_5 & \dots \\ 0 & & 0 & \dots \\ & & \dots & \dots \\ 1 & \bar{\theta}_5 & 0 & \dots & 0 & 0 \\ 0 & \dots & \dots & \dots & 0 & 1 \end{pmatrix},$$

$E_7 \cdots$  an  $(n+5) \times (n+5)$  matrix with the same property as  $E_3$ ,

$$F_7 = {}^t(f_1, \theta_5 f_1, 0, \dots, 0) \quad (f_1 = \psi_1 f),$$

$$P_7 = \left( 1, -\frac{1-c}{\sqrt{\delta_1}}, -\frac{2b_1}{1+c}, -\frac{2b_2}{1+c}, -\frac{2d_1}{1+c}, \dots, -\frac{2d_n}{1+c}, 0 \right),$$

$$Q_7 = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & \cdot \\ 0 & 0 & 0 & 1 & \cdot & \cdot \\ & 0 & & & \cdot & \cdot \\ & & 0 & & 0 & \cdot \\ 0 & \cdot & \cdot & \cdot & 0 & 1 \\ 0 & \cdot & \cdot & \cdot & \cdot & 0 & 1 \end{pmatrix},$$

$$R_7 = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & \cdot \\ 0 & 0 & 1 & 0 & 0 & \cdot & \cdot \\ 0 & 0 & 0 & 0 & 1 & \cdot & \cdot \\ & 0 & & & & \cdot & \cdot \\ & & 0 & & & 0 & \cdot \\ 0 & \cdot & \cdot & \cdot & \cdot & 0 & 1 \\ 0 & \cdot & \cdot & \cdot & \cdot & \cdot & 0 & 1 \end{pmatrix},$$

$$G_7 = -\frac{2}{1+c} \{ [B_4, \psi_1] u|_{x=0} + \psi_1(t, y, z, w) g \},$$

$$H_7 = {}^t(h_{1t} - h_{1x} - \gamma_1 h_1, \theta_{51}(h_{1t} + h_{1x} + \gamma_1 h_1), h_{1z}, h_{1w_1}, \dots, h_{1w_n}, h_1) \\ (h_1 = \psi_1(t, 0, z, w) h, \theta_{51} = \theta_5|_{y=0}, \gamma_1 = \gamma|_{y=0}),$$

$$K_7 = {}^t(k_{1t} - k_{1x} - \gamma_2 k_1, \theta_{52}(k_{1t} + k_{1x} + \gamma_2 k_1), k_{1y}, k_{1w_1}, \dots, k_{1w_n}, k_1) \\ (k_1 = \psi_1(t, y, 0, w) k, \theta_{52} = \theta_5|_{z=0}, \gamma_2 = \gamma|_{z=0}),$$

and there exists a positive constant  $C$  such that

$$(3.43) \quad \begin{cases} [A_7 U, U] \geq C[U, U] & \text{for all } U \in \text{Ker } P_7 \\ [A_{70} U, U] = 0 & \text{for all } U \in \text{Ker } Q_7 \\ [A_{700} U, U] = 0 & \text{for all } U \in \text{Ker } R_7. \end{cases}$$

**THEOREM 3.7.** For  $V$  in (3.39), we have

$$(3.44) \quad \begin{cases} M_8 V_t = A_8 V_x + A_{80} V_y + A_{800} V_z + \sum_{j=1}^n A_{8j} V_{w_j} + E_8 U + F_8 \\ V(0, x, y, z, w) = V_0(x, y, z, w) \\ P_8 V|_{x=0} = G_8(t, y, z, w) \\ Q_8 V|_{y=0} = H_8(t, x, z, w) \\ R_8 V|_{z=0} = K_8(t, x, y, w) \\ (t, x, y, z, w) \in (\mathbf{R}_+^1)^4 \times \mathbf{R}^n \end{cases}$$

where

$$M_8 = \text{diag}(1, 1, 1 + |\theta_6|^2, \dots, 1 + |\theta_6|^2, 1),$$

$$A_8 = \text{diag}(-1, 1, 1 - |\theta_6|^2, \dots, 1 - |\theta_6|^2, 1),$$

$$A_{80} = \begin{pmatrix} 0 & 0 & 1 & 0 & \dots \\ 0 & 0 & \theta_6 & 0 & \dots \\ 1 & \bar{\theta}_6 & 0 & \dots \\ \dots & 0 & \dots & 0 & \dots \\ 0 & \dots & \dots & 0 & 1 \end{pmatrix}, \quad A_{800} = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 & \dots \\ 0 & 0 & 0 & \theta_6 & 0 & \dots \\ 0 & 0 & 0 & 0 & \dots & \dots \\ 1 & \bar{\theta}_6 & 0 & 0 & \dots & \dots \\ \dots & 0 & \dots & 0 & \dots & 0 \\ 0 & \dots & \dots & \dots & 0 & 1 \end{pmatrix},$$

$$\dots, \quad A_{8n} = \begin{pmatrix} & 1 & 0 \\ & \theta_6 & \dots \\ 0 & 0 & \dots \\ \dots & \dots & \dots \\ 1 & \bar{\theta}_6 & 0 & \dots & 0 & 0 \\ 0 & \dots & \dots & \dots & 0 & 1 \end{pmatrix},$$

$E_8 \cdots$  an  $(n+5) \times (n+5)$  matrix with the same property as  $E_3$ ,

$$F_8 = {}^t(f_2, \theta_6 f_2, 0, \dots, 0) \quad (f_2 = \psi_2 f),$$

$$P_8 = \left( 1, -\theta_6, -\frac{2b_1}{1+c}, -\frac{2b_2}{1+c}, -\frac{2d_1}{1+c}, \dots, -\frac{2d_n}{1+c}, 0 \right),$$

$$Q_8 = Q_7, \quad R_8 = R_7,$$

$$G_8 = -\frac{2}{1+c} \{ [B_4, \psi_2] u|_{x=0} + \psi_2(t, y, z, w) g \},$$

$$H_8 = {}^t(h_{2t} - h_{2x} - \gamma_1 h_2, \theta_{61}(h_{2t} + h_{2x} + \gamma_1 h_2), h_{2z}, h_{2w_1}, \dots, h_{2w_n}, h_2) \\ (h_2 = \psi_2(t, 0, z, w) h, \theta_{61} = \theta_6|_{y=0}, \gamma_1 = \gamma|_{y=0}),$$

$$K_8 = {}^t(k_{2t} - k_{2x} - \gamma_2 k_2, \theta_{62}(k_{2t} + k_{2x} + \gamma_2 k_2), k_{2y}, k_{2w_1}, \dots, k_{2w_n}, k_2) \\ (k_2 = \psi_2(t, y, 0, w) k, \theta_{62} = \theta_6|_{z=0}, \gamma_2 = \gamma|_{z=0}),$$

and there exists a positive constant  $C$  such that

$$(3.45) \quad \begin{cases} [A_8 V, V] \geq C[V, V] & \text{for all } V \in \text{Ker } P_8 \\ [A_{80} V, V] = 0 & \text{for all } V \in \text{Ker } Q_8 \\ [A_{800} V, V] = 0 & \text{for all } V \in \text{Ker } R_8. \end{cases}$$

**§4. Boundary estimates.**

In this section, we prepare several propositions to estimate the boundary value of  $u$  on the boundaries  $y=0$  and  $z=0$ .

Firstly, we consider the problem (P.1) under the condition (A.I).

We set

$$(4.1) \quad U = \begin{pmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ \vdots \\ \vdots \\ U_{n+3} \\ U_{n+4} \end{pmatrix} = \begin{pmatrix} u_t - u_x + \sqrt{2}^{-1} u_y \\ u_t + u_x + \sqrt{2}^{-1} u_y \\ u_y \\ u_{w_1} \\ \vdots \\ \vdots \\ u_{w_n} \\ u \end{pmatrix}$$

for the solution  $u$  of the problem (P.1) which belongs to  $\mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^3 \times \mathbf{R}^n]$ .

**PROPOSITION 4.1.** *For  $U$  in (4.1), we have*

$$(4.2) \quad \begin{cases} \tilde{M}_1 U_t = \tilde{A}_1 U_x + \tilde{A}_{10} U_y + \sum_{j=1}^n \tilde{A}_{1j} U_{w_j} + \tilde{E}_1 U + \tilde{F}_1 \\ (t, x, y, w) \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^n \end{cases}$$

and

$$(4.3) \quad U|_{y=0} = \left( h_t - h_x + \frac{u_y}{\sqrt{2}}, h_1 + h_x + \frac{u_y}{\sqrt{2}}, u_y, h_{w_1}, \dots, h_{w_n}, h \right)$$

where

$$\tilde{M}_1 = \text{diag}(1, 1, 1, 2, \dots, 2, 1), \quad \tilde{A}_1 = \text{diag}(-1, 1, 0, 0, \dots, 0, 1),$$

$$\tilde{A}_{10} = \begin{pmatrix} 0 & 1/\sqrt{2} & 1/2 & & & & & \\ 1/\sqrt{2} & 0 & 1/2 & & & & & 0 \\ 1/2 & 1/2 & -1/\sqrt{2} & & & & & -\sqrt{2} \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ 0 & & & & & & & -\sqrt{2} \\ & & & & & & & 1 \end{pmatrix},$$

$$\tilde{A}_{1j} = \begin{pmatrix} & 1 & 0 \\ & 1 & \cdot \\ 0 & 0 & \cdot \\ & \cdot & 0 \\ & & \cdot \\ & & \cdot \\ 1 & 1 & 0 & \cdots & \cdots & 0 & \cdot \\ & & & 0 & & & \cdot \\ 0 & \cdots & \cdots & \cdots & \cdots & \cdots & 0 & 1 \end{pmatrix} \quad (j=1, \dots, n),$$

$\tilde{E}_1 \cdots$  an  $(n+4) \times (n+4)$  matrix with the same property as  $E_3$  in §3,

*and*

$$\tilde{F}_1 = {}^t(f, f, 0, \dots, 0).$$

**PROOF.** By simple calculations, we have Proposition 4.1.

Q.E.D.

**PROPOSITION 4.2.** *For  $U$  in (4.1), the following inequality holds,*

$$(4.4) \quad \frac{d}{dt}(\tilde{M}_1 e^{-\mu t} U, e^{-\mu t} U) \leq C_1 \langle e^{-\mu t} U, e^{-\mu t} U \rangle - C_2 \langle\langle e^{-\mu t} u_y, e^{-\mu t} u_y \rangle\rangle \\ + C_3 \langle\langle e^{-\mu t} h \rangle\rangle_1^2 + \frac{C_4}{\mu} (e^{-\mu t} f, e^{-\mu t} f)$$

for all  $\mu \geq \mu_1$  where  $\mu_1$ ,  $C_1$ ,  $C_2$ ,  $C_3$  and  $C_4$  are positive constants.

**PROOF.** By Proposition 4.1, we have

$$\begin{aligned} \frac{d}{dt}(\tilde{M}_1 e^{-\mu t} U, e^{-\mu t} U) &= -2\mu(\tilde{M}_1 e^{-\mu t} U, e^{-\mu t} U) \\ &\quad + \left( e^{-\mu t} \left( \tilde{A}_1 U_x + \tilde{A}_{10} U_y + \sum_{j=1}^n \tilde{A}_{1j} U_{w_j} + \tilde{E}_1 U + \tilde{F}_1 \right), e^{-\mu t} U \right) \\ &\quad + \left( e^{-\mu t} U, e^{-\mu t} \left( \tilde{A}_1 U_x + \tilde{A}_{10} U_y + \sum_{j=1}^n \tilde{A}_{1j} U_{w_j} + \tilde{E}_1 U + \tilde{F}_1 \right) \right) \\ &\leq C_1 \langle e^{-\mu t} U, e^{-\mu t} U \rangle - C_2 \langle \langle e^{-\mu t} u_y, e^{-\mu t} u_y \rangle \rangle + C_3 \langle \langle e^{-\mu t} h \rangle \rangle_1^2 + \frac{C_4}{\mu} (e^{-\mu t} f, e^{-\mu t} f) \end{aligned}$$

for all  $\mu \geq \mu_1$  where  $\mu_1$ ,  $C_1$ ,  $C_2$ ,  $C_3$  and  $C_4$  are positive constants.

O.E.D.

Secondly, we use the same vector  $U$  in (4.1) for the solution  $u$  of the problem (P.2) under the condition (A.I) which belongs to  $\mathcal{H}_{2,u}[(\mathbf{R}_+^1)^3 \times \mathbf{R}^n]$ .

**PROPOSITION 4.3.** *For  $U$  in (4.1), the following inequality holds,*

$$(4.5) \quad \langle\!\langle A_{x,w,\mu}^{-1/2} U \rangle\!\rangle_{0,\mu,t}^2 \leq C \left\{ \frac{1}{\mu} \|U(t)\|_{0,\mu}^2 + \frac{1}{\mu} \|U(0)\|_{0,\mu}^2 + \|U\|_{0,\mu,t}^2 + \frac{1}{\mu} \langle U \rangle_{0,\mu,t}^2 + \frac{1}{\mu^2} \|\tilde{F}_1\|_{0,\mu,t}^2 \right\}$$

for all  $t \in \mathbf{R}_+^1$  and all  $\mu \geq \mu_2$  where  $C$  and  $\mu_2$  are positive constants.

**PROOF.**  $U$  satisfies the equation (4.2). We set  $U(t, x, y, w) = 0$  ( $x < 0$ ). Then, by the Fourier transform of (4.2) with respect to  $(x, w)$ , we get

$$(4.6) \quad \tilde{M}_1 \hat{U}_t = i\xi \tilde{A}_1 \hat{U} - \tilde{A}_1 \hat{U}(t, 0, y, \zeta) + \tilde{A}_{10} \hat{U}_y + i \left( \sum_{j=1}^n \tilde{A}_{1j} \zeta_j \right) \hat{U} + \widehat{\tilde{E}_1 U} + \widehat{\tilde{F}_1},$$

where

$\xi$  is the dual variable of  $x$ ,  $\zeta = (\zeta_1, \dots, \zeta_n)$  is the dual vector of  $w = (w_1, \dots, w_n)$ ,

$$\hat{p} = \int_{\mathbf{R}^{n+1}} e^{-i(x \cdot \xi + w \cdot \zeta)} p(x, w) dx dw \quad \text{and} \quad \hat{U} = \int_{\mathbf{R}^n} e^{-iw \cdot \zeta} U(t, 0, y, w) dw.$$

We set

$$(4.7) \quad V = e^{-\mu t} (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} \hat{U},$$

where  $|\zeta|^2 = |\zeta_1|^2 + \dots + |\zeta_n|^2$ . Then, by (4.6) and (4.7), we obtain

$$(4.8) \quad \begin{aligned} V_y &= \tilde{A}_{10}^{-1} \tilde{M}_1 V_t + \mu \tilde{A}_{10}^{-1} \tilde{M}_1 V - \tilde{A}_{10}^{-1} i \left( \tilde{A}_1 \xi + \sum_{j=1}^n \tilde{A}_{1j} \zeta_j \right) V \\ &\quad + e^{-\mu t} \tilde{A}_{10}^{-1} \tilde{A}_1 (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} \hat{U}(t, 0, y, \zeta) \\ &\quad - \tilde{A}_{10}^{-1} e^{-\mu t} (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} \{ \widehat{\tilde{E}_1 U} + \widehat{\tilde{F}_1} \} \end{aligned}$$

and  $\tilde{A}_{10}^{-1} \tilde{M}_1$  is an Hermite matrix. Therefore, we have

$$\begin{aligned} -\frac{d}{dy} [V, V] &= -[V_y, V] - [V, V_y] \\ &= - \left[ \tilde{A}_{10}^{-1} \tilde{M}_1 V_t + \mu \tilde{A}_{10}^{-1} \tilde{M}_1 V - \tilde{A}_{10}^{-1} i \left( \tilde{A}_1 \xi + \sum_{j=1}^n \tilde{A}_{1j} \zeta_j \right) V \right. \\ &\quad \left. + e^{-\mu t} \tilde{A}_{10}^{-1} \tilde{A}_1 (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} \hat{U}(t, 0, y, \zeta) \right. \\ &\quad \left. - \tilde{A}_{10}^{-1} e^{-\mu t} (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} \{ \widehat{\tilde{E}_1 U} + \widehat{\tilde{F}_1} \}, V \right] \\ &\quad - \left[ V, \tilde{A}_{10}^{-1} \tilde{M}_1 V_t + \mu \tilde{A}_{10}^{-1} \tilde{M}_1 V - \tilde{A}_{10}^{-1} i \left( \tilde{A}_1 \xi + \sum_{j=1}^n \tilde{A}_{1j} \zeta_j \right) V \right. \end{aligned}$$

$$\begin{aligned}
& + e^{-\mu t} \tilde{A}_{10}^{-1} \tilde{A}_1 (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} \hat{U}(t, 0, y, \zeta) \\
& - \tilde{A}_{10}^{-1} e^{-\mu t} (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} \{\widehat{\tilde{E}_1 V} + \widehat{\tilde{F}_1}\} \Big] \\
= & - \frac{d}{dt} [\tilde{A}_{10}^{-1} \tilde{M}_1 V, V] - 2\mu [\tilde{A}_{10}^{-1} \tilde{M}_1 V, V] \\
& + \left\{ \left[ e^{-\mu t} \tilde{A}_{10}^{-1} i \left( \tilde{A}_1 \xi + \sum_{j=1}^n \tilde{A}_{1j} \zeta_j \right) (\xi^2 + |\zeta|^2 + \mu^2)^{-1/2} \hat{U}, e^{-\mu t} \hat{U} \right] \right. \\
& \quad \left. + \left[ e^{-\mu t} \hat{U}, e^{-\mu t} \tilde{A}_{10}^{-1} i \left( \tilde{A}_1 \xi + \sum_{j=1}^n \tilde{A}_{1j} \zeta_j \right) (\xi^2 + |\zeta|^2 + \mu^2)^{-1/2} \hat{U} \right] \right\} \\
& - [e^{-\mu t} \tilde{A}_{10}^{-1} \tilde{A}_1 (\xi^2 + |\zeta|^2 + \mu^2)^{-1/2} \hat{U}(t, 0, y, \zeta), e^{-\mu t} \hat{U}] \\
& - [e^{-\mu t} \hat{U}, e^{-\mu t} \tilde{A}_{10}^{-1} \tilde{A}_1 (\xi^2 + |\zeta|^2 + \mu^2)^{-1/2} \hat{U}(t, 0, y, \zeta)] \\
& + [e^{-\mu t} \tilde{A}_{10}^{-1} (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} (\widehat{\tilde{E}_1 U} + \widehat{\tilde{F}_1}), V] \\
& + [V, e^{-\mu t} \tilde{A}_{10}^{-1} (\xi^2 + |\zeta|^2 + \mu^2)^{-1/4} (\widehat{\tilde{E}_1 U} + \widehat{\tilde{F}_1})].
\end{aligned}$$

Therefore, we obtain

$$\begin{aligned}
(4.9) \quad \langle\langle A_{x,w,\mu}^{-1/2} U \rangle\rangle_{0,\mu,t}^2 & = \int_0^t \int_{-\infty}^{\infty} \int_{\mathbb{R}^n} \int_{-\infty}^{\infty} \left\{ -\frac{d}{dy} [V, V] \right\} dy d\xi d\xi dt \\
& \leq C \left\{ \frac{1}{\mu} \|U(t)\|_{0,\mu}^2 + \frac{1}{\mu} \|U(0)\|_{0,\mu}^2 + \|U\|_{0,\mu,t}^2 + \frac{1}{\mu} \langle U \rangle_{0,\mu,t}^2 + \frac{1}{\mu^2} \|\tilde{F}_1\|_{0,\mu,t}^2 \right\}
\end{aligned}$$

for all  $t \in \mathbb{R}_+^1$  and all  $\mu \geq \mu_2$  where  $C$  and  $\mu_2$  are positive constants.

Q.E.D.

Thirdly, we consider the problem (P.3) under the condition (A.II).

We set

$$(4.10) \quad U = \begin{pmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ U_5 \\ \vdots \\ \vdots \\ U_{n+4} \\ U_{n+5} \end{pmatrix} = \begin{pmatrix} u_t - u_x + \sqrt{2}^{-1} u_y + \sqrt{2}^{-1} u_z \\ u_t + u_x + \sqrt{2}^{-1} u_y + \sqrt{2}^{-1} u_z \\ u_y \\ u_z \\ u_{w_1} \\ \vdots \\ \vdots \\ u_{w_n} \\ u \end{pmatrix},$$

for the solution  $u$  of the problem (P.3) which belongs to  $\mathcal{H}_{2,\mu}[(R_+^1)^4 \times R^n]$ .

**PROPOSITION 4.4.** *For  $U$  in (4.10), we have*

$$(4.11) \quad \begin{cases} \tilde{M}_2 U_t = \tilde{A}_2 U_x + \tilde{A}_{20} U_y + \tilde{A}_{200} U_z + \sum_{j=1}^n \tilde{A}_{2j} U_{w_j} + \tilde{E}_2 U + \tilde{F}_2 \\ (t, x, y, z, w) \in (\mathbf{R}_+^1)^4 \times \mathbf{R}^n \end{cases}$$

*and*

$$(4.12) \quad \begin{cases} U|_{y=0} = {}^t \left( h_t - h_x + \frac{u_y}{\sqrt{2}} + \frac{h_z}{\sqrt{2}}, h_t + h_x + \frac{u_y}{\sqrt{2}} + \frac{h_z}{\sqrt{2}}, u_y, h_z, h_{w_1}, \dots, h_{w_n}, h \right) \\ U|_{z=0} = {}^t \left( k_t - k_x + \frac{k_y}{\sqrt{2}} + \frac{u_z}{\sqrt{2}}, k_t + k_x + \frac{k_y}{\sqrt{2}} + \frac{u_z}{\sqrt{2}}, k_y, u_z, k_{w_1}, \dots, k_{w_n}, k \right), \end{cases}$$

*where*

$$\tilde{M}_2 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & -1 & 1 \\ & & & 0 \\ & & & 2 \\ & & & . \\ & 0 & & . \\ & & & . \\ & & & 2 \\ & & & 1 \end{pmatrix},$$

$$\tilde{A}_2 = \text{diag}(-1, 1, 0, 0, \dots, 0, 1),$$

$$\tilde{A}_{20} = \begin{pmatrix} 0 & 1/\sqrt{2} & 1/2 & -1/2 \\ 1/\sqrt{2} & 0 & 1/2 & -1/2 \\ 1/2 & 1/2 & -1/\sqrt{2} & 1/\sqrt{2} \\ -1/2 & -1/2 & 1/\sqrt{2} & -1/\sqrt{2} \\ & & & 0 \\ & & & -\sqrt{2} \\ & & & \\ & & 0 & \\ & & & -\sqrt{2} \\ & & & 1 \end{pmatrix},$$

$$\tilde{A}_{200} = \begin{pmatrix} 0 & 1/\sqrt{2} & -1/2 & 1/2 \\ 1/\sqrt{2} & 0 & -1/2 & 1/2 \\ -1/2 & -1/2 & -1/\sqrt{2} & 1/\sqrt{2} \\ 1/2 & 1/2 & 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 0 \\ -\sqrt{2} \\ 0 \\ -\sqrt{2} \end{pmatrix},$$

$\tilde{E}_2$  ... an  $(n+5) \times (n+5)$  matrix with the same property as  $E_3$  in §3,

*and*

$$\tilde{F}_2 = {}^t(f, f, 0, \dots, 0).$$

**PROOF.** By simple calculations we obtain Proposition 4.4.

Q.E.D.

**PROPOSITION 4.5.** *For  $U$  in (4.10), the following inequality holds,*

$$(4.13) \quad \frac{d}{dt}(\tilde{M}_2 e^{-\mu t} U, e^{-\mu t} U) \\ \leq C_1 \langle e^{-\mu t} U, e^{-\mu t} U \rangle - C_2 \langle \langle e^{-\mu t} u_y, e^{-\mu t} u_y \rangle \rangle - C_3 \langle \langle \langle e^{-\mu t} u_z, e^{-\mu t} u_z \rangle \rangle \rangle \\ + C_4 \langle \langle e^{-\mu t} h \rangle \rangle_1^2 + C_5 \langle \langle \langle e^{-\mu t} k \rangle \rangle \rangle_1^2 + \frac{C_6}{\mu} (e^{-\mu t} f, e^{-\mu t} f)$$

for all  $\mu \geq \mu_3$  where  $\mu_3, C_1, C_2, C_3, C_4, C_5$  and  $C_6$  are positive constants.

**PROOF.** By the same method as the one in the proof of Proposition 4.2, and Proposition 4.4, we have Proposition 4.5. Q.E.D.

### §5. The proof of Main Theorem 1.

In this section, we shall prove Main Theorem 1.

Firstly, we consider  $U$  which is defined by (3.9) for the solution  $u \in \mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^3 \times \mathbf{R}^n]$  of the problem (P.1) under the condition (A.I). By Theorem 3.2, we obtain

$$\begin{aligned}
 (5.1) \quad & \frac{d}{dt}(M_3 e^{-\mu t} U, e^{-\mu t} U) \\
 &= -2\mu(M_3 e^{-\mu t} U, e^{-\mu t} U) + (e^{-\mu t} M_3 U_t, e^{-\mu t} U) + (e^{-\mu t} U, e^{-\mu t} M_3 U_t) \\
 &= -2\mu(M_3 e^{-\mu t} U, e^{-\mu t} U) \\
 &\quad + \left( e^{-\mu t} \left( A_3 U_x + A_{30} U_y + \sum_{j=1}^n A_{3j} U_{w_j} + E_3 U + F_3 \right), e^{-\mu t} U \right) \\
 &\quad + \left( e^{-\mu t} U, e^{-\mu t} \left( A_3 U_x + A_{30} U_y + \sum_{j=1}^n A_{3j} U_{w_j} + E_3 U + F_3 \right) \right) \\
 &\leq -C_1 \mu(e^{-\mu t} U, e^{-\mu t} U) + \frac{C_2}{\mu} (e^{-\mu t} F_3, e^{-\mu t} F_3) \\
 &\quad - \langle A_3 e^{-\mu t} U, e^{-\mu t} U \rangle - \langle A_{30} e^{-\mu t} U, e^{-\mu t} U \rangle
 \end{aligned}$$

where  $C_1$  and  $C_2$  are positive constants.

Now, we set

$$(5.2) \quad P_{31} = \begin{pmatrix} 1 & -\frac{1-c}{\sqrt{\delta_0}} & -\frac{2b}{1+c} & -\frac{2d_1}{1+c} & \dots & -\frac{2d_n}{1+c} & 0 \\ & 0 & & & & & \\ & & 0 & & & & \\ & & & 0 & & & \\ & & & & 0 & & \\ & & & & & 0 & \\ & & & & & & 0 \end{pmatrix}$$

and

$$(5.3) \quad Q_{31} = \begin{pmatrix} 1 & 0 & 0 & & & & & \\ 0 & 1 & 0 & & & & & \\ 0 & 0 & 0 & & & & & \\ \hline & 0 & & & & & & \\ & & 1 & & & & & \\ & & & \ddots & & & & \\ & & & & 0 & & & \\ & & & & & \ddots & & \\ & & & & & & \ddots & \\ & & & & & & & 1 \end{pmatrix}$$

where  $P_{31}$  and  $Q_{31}$  are  $(n+4) \times (n+4)$  matrices. Then, we have

$$P_3(U - P_{31}U)|_{x=0} = 0 \quad \text{and} \quad Q_3(U - Q_{31}U)|_{y=0} = 0.$$

Using  $G_3$  and  $H_3$  which are defined in (3.13), we get

$$(5.4) \quad \begin{cases} U - P_{31}U|_{x=0} \in \text{Ker } P_3 \\ P_{31}U|_{x=0} = {}^t(G_3, 0, \dots, 0) = G_{31} \end{cases}$$

and

$$(5.5) \quad \begin{cases} U - Q_{31}U|_{y=0} \in \text{Ker } Q_3 \\ Q_{31}U|_{y=0} = {}^t(\tilde{h}_t - \tilde{h}_x - \tilde{\gamma}\tilde{h}, \theta_{30}(\tilde{h}_t + \tilde{h}_x + \tilde{\gamma}\tilde{h}), 0, \tilde{h}_{w_1}, \dots, \tilde{h}_{w_n}, \tilde{h}) = H_{31} \end{cases}$$

Then, by (3.14) and (5.4), we obtain

$$(5.6) \quad \begin{aligned} \langle A_3 e^{-\mu t} U, e^{-\mu t} U \rangle &= \langle A_3 e^{-\mu t} (I - P_{31}) U, e^{-\mu t} (I - P_{31}) U \rangle \\ &\quad + 2 \operatorname{Re} \langle A_3 e^{-\mu t} U, e^{-\mu t} G_{31} \rangle - \langle A_3 e^{-\mu t} G_{31}, e^{-\mu t} G_{31} \rangle \\ &\geq C_3 \langle e^{-\mu t} U, e^{-\mu t} U \rangle - C_4 \langle e^{-\mu t} G_{31}, e^{-\mu t} G_{31} \rangle \end{aligned}$$

where  $C_3$  and  $C_4$  are positive constants. Similarly, by (3.14) and (5.5), we have

$$(5.7) \quad \begin{aligned} \langle\langle A_{30} e^{-\mu t} U, e^{-\mu t} U \rangle\rangle &= \langle\langle A_{30} e^{-\mu t} (I - Q_{31}) U, e^{-\mu t} (I - Q_{31}) U \rangle\rangle \\ &\quad + 2 \operatorname{Re} \langle\langle A_{30} e^{-\mu t} U, e^{-\mu t} H_{31} \rangle\rangle - \langle\langle A_{30} e^{-\mu t} H_{31}, e^{-\mu t} H_{31} \rangle\rangle \\ &\geq -\delta_1 \langle\langle e^{-\mu t} v_{1y}, e^{-\mu t} v_{1y} \rangle\rangle - C_5 \langle\langle e^{-\mu t} H_{31}, e^{-\mu t} H_{31} \rangle\rangle \end{aligned}$$

where  $\delta_1$  is a sufficiently small positive constant, and  $C_5$  is a positive constant.

Thus, by (5.1), (5.6) and (5.7), we get

$$(5.8) \quad \begin{aligned} \frac{d}{dt} (M_3 e^{-\mu t} U, e^{-\mu t} U) &\leq -C_1 \mu (e^{-\mu t} U, e^{-\mu t} U) + \frac{C_2}{\mu} (e^{-\mu t} F_3, e^{-\mu t} F_3) \\ &\quad - C_3 \langle e^{-\mu t} U, e^{-\mu t} U \rangle + \delta_1 \langle\langle e^{-\mu t} v_{1y}, e^{-\mu t} v_{1y} \rangle\rangle \\ &\quad + C_4 \langle e^{-\mu t} G_{31}, e^{-\mu t} G_{31} \rangle + C_5 \langle\langle e^{-\mu t} H_{31}, e^{-\mu t} H_{31} \rangle\rangle. \end{aligned}$$

Nextly, for  $V$  in (3.10), we have the following inequality by Theorem 3.3 and the same method as the above one,

$$(5.9) \quad \begin{aligned} \frac{d}{dt} (M_4 e^{-\mu t} V, e^{-\mu t} V) &\leq -C'_1 \mu (e^{-\mu t} V, e^{-\mu t} V) + \frac{C'_2}{\mu} (e^{-\mu t} F_4, e^{-\mu t} F_4) \\ &\quad - C'_3 \langle e^{-\mu t} V, e^{-\mu t} V \rangle + \delta_2 \langle\langle e^{-\mu t} v_{2y}, e^{-\mu t} v_{2y} \rangle\rangle \\ &\quad + C'_4 \langle e^{-\mu t} G_{41}, e^{-\mu t} G_{41} \rangle + C'_5 \langle\langle e^{-\mu t} H_{41}, e^{-\mu t} H_{41} \rangle\rangle \end{aligned}$$

where

$$(5.10) \quad \begin{cases} G_{41} = {}^t(G_4, 0, \dots, 0) \\ H_{41} = {}^t(\tilde{h}_t - \tilde{h}_x - \tilde{\gamma}\tilde{h}, \theta_{40}(\tilde{h}_t + \tilde{h}_x + \tilde{\gamma}\tilde{h}), 0, \tilde{h}_{w_1}, \dots, \tilde{h}_{w_n}, \tilde{h}) \end{cases}$$

$C'_j$  ( $j = 1, \dots, 5$ ) is a positive constant and  $\delta_2$  is a sufficiently small positive constant.

**LEMMA 5.1.** *Let  $u$  be the solution of the problem (P.1) which belongs to  $\mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^3 \times \mathbf{R}^n]$ . Then, there exist positive constants  $C$  and  $\tilde{\mu}_1$  such that the following inequality holds for all  $t \in \mathbf{R}_+^1$  and all  $\mu \geq \tilde{\mu}_1$ ,*

$$(5.11) \quad \begin{aligned} & \| \mu u(t) \|_{0,\mu}^2 + \mu \| \mu u \|_{0,\mu,t}^2 + \langle \mu u \rangle_{0,\mu,t}^2 + \langle \langle \mu u \rangle \rangle_{0,\mu,t}^2 \\ & \leq C \{ \| u(0) \|_{1,\mu}^2 + \mu \| u_t \|_{0,\mu,t}^2 + \mu \| u_x \|_{0,\mu,t}^2 + \mu \| u_y \|_{0,\mu,t}^2 \}. \end{aligned}$$

**PROOF.** See [7].

Q.E.D.

**PROOF OF MAIN THEOREM 1.** By Proposition 4.2, (5.8), (5.9) and Lemma 5.1, we have Main Theorem 1. Q.E.D.

## §6. The proof of Main Theorem 2.

In this section, we shall prove Main Theorem 2.

Firstly, we consider  $U$  which is defined by (3.9) for the solution  $u \in \mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^3 \times \mathbf{R}^n]$  of the problem (P.2) under the condition (A.I). By Theorem 3.4 and the same method as the one in §5, we obtain

$$(6.1) \quad \begin{aligned} \frac{d}{dt} (M_3 e^{-\mu t} U, e^{-\mu t} U) & \leq -C_1 \mu (e^{-\mu t} U, e^{-\mu t} U) + \frac{C_2}{\mu} (e^{-\mu t} F_3, e^{-\mu t} F_3) \\ & \quad - \langle A_3 e^{-\mu t} U, e^{-\mu t} U \rangle - \langle \langle A_{30} e^{-\mu t} U, e^{-\mu t} U \rangle \rangle \end{aligned}$$

where  $C_1$  and  $C_2$  are positive constants. Now, we set

$$(6.2) \quad P_{51} = P_{31} \quad (\text{for } P_{31}, \text{ see (5.2)})$$

and

$$(6.3) \quad Q_{51} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & & \end{pmatrix},$$

where  $P_{51}$  and  $Q_{51}$  are  $(n+4) \times (n+4)$  matrices. Then, we obtain

$$P_3(U - P_{51}U)|_{x=0} = 0 \quad \text{and} \quad Q_5(U - Q_{51}U)|_{y=0} = 0.$$

By  $G_3$  and  $H_5$  which are defined in (3.31), we have

$$(6.4) \quad \begin{cases} (U - P_{51}U)|_{x=0} \in \text{Ker } P_3, \quad (U - Q_{51}U)|_{y=0} \in \text{Ker } Q_5 \\ P_{51}U|_{x=0} = {}^t(G_3, 0, \dots, 0) = G_{51} \\ Q_{51}U|_{y=0} = {}^t(0, 0, H_5, 0, \dots, 0) = H_{51}. \end{cases}$$

Then, by (3.32) and (6.4), we get

$$(6.5) \quad \langle A_3 e^{-\mu t} U, e^{-\mu t} U \rangle \geq C_3 \langle e^{-\mu t} U, e^{-\mu t} U \rangle - C_4 \langle e^{-\mu t} G_{51}, e^{-\mu t} G_{51} \rangle$$

where  $C_3$  and  $C_4$  are positive constants. Similarly, we have

$$\begin{aligned} (6.6) \quad & \langle\langle A_{30} e^{-\mu t} U, e^{-\mu t} U \rangle\rangle = \langle\langle A_{30} e^{-\mu t} (I - Q_{51}) U, e^{-\mu t} (I - Q_{51}) U \rangle\rangle \\ & + 2\operatorname{Re} \langle\langle A_{30} e^{-\mu t} U, e^{-\mu t} H_{51} \rangle\rangle - \langle\langle A_{30} e^{-\mu t} H_{51}, e^{-\mu t} H_{51} \rangle\rangle \\ & \geq -\delta_3 \mu \langle\langle \Lambda_{x,w,\mu}^{-1/2} e^{-\mu t} U, \Lambda_{x,w,\mu}^{-1/2} e^{-\mu t} U \rangle\rangle \\ & - \frac{C_5}{\mu} \langle\langle \Lambda_{x,w,\mu}^{1/2} e^{-\mu t} H_{51}, \Lambda_{x,w,\mu}^{1/2} e^{-\mu t} H_{51} \rangle\rangle \end{aligned}$$

where  $\delta_3$  is a sufficiently small positive constant and  $C_5$  is a positive constant. Thus, by (6.1), (6.5) and (6.6), we obtain

$$\begin{aligned} (6.7) \quad & \frac{d}{dt} (M_3 e^{-\mu t} U, e^{-\mu t} U) \leq -C_1 \mu (e^{-\mu t} U, e^{-\mu t} U) + \frac{C_2}{\mu} (e^{-\mu t} F_3, e^{-\mu t} F_3) \\ & - C_3 \langle e^{-\mu t} U, e^{-\mu t} U \rangle + \delta_3 \mu \langle\langle \Lambda_{x,w,\mu}^{-1/2} e^{-\mu t} U, \Lambda_{x,w,\mu}^{-1/2} e^{-\mu t} U \rangle\rangle \\ & + C_4 \langle e^{-\mu t} G_{51}, e^{-\mu t} G_{51} \rangle + \frac{C_5}{\mu} \langle\langle \Lambda_{x,w,\mu}^{1/2} e^{-\mu t} H_{51}, \Lambda_{x,w,\mu}^{1/2} e^{-\mu t} H_{51} \rangle\rangle. \end{aligned}$$

Nextly, for  $V$  in (3.10), we have the following inequality by Theorem 3.5 and the same method as the above one,

$$\begin{aligned} (6.8) \quad & \frac{d}{dt} (M_4 e^{-\mu t} V, e^{-\mu t} V) \leq -C'_1 \mu (e^{-\mu t} V, e^{-\mu t} V) + \frac{C'_2}{\mu} (e^{-\mu t} F_4, e^{-\mu t} F_4) \\ & - C'_3 \langle e^{-\mu t} V, e^{-\mu t} V \rangle + \delta_4 \mu \langle\langle \Lambda_{x,w,\mu}^{-1/2} e^{-\mu t} V, \Lambda_{x,w,\mu}^{-1/2} e^{-\mu t} V \rangle\rangle \\ & + C'_4 \langle e^{-\mu t} G_{61}, e^{-\mu t} G_{61} \rangle + \frac{C'_5}{\mu} \langle\langle \Lambda_{x,w,\mu}^{1/2} e^{-\mu t} H_{61}, \Lambda_{x,w,\mu}^{1/2} e^{-\mu t} H_{61} \rangle\rangle \end{aligned}$$

where

$$(6.9) \quad G_{61} = {}^t(G_4, \dots, 0), \quad H_{61} = {}^t(0, 0, H_6, 0, \dots, 0),$$

$C'_j$  ( $j=1, \dots, 5$ ) is a positive constant and  $\delta_4$  is a sufficiently small positive constant.

LEMMA 6.1. Let  $u \in \mathcal{H}_{2,\mu}[(R^1_+)^3 \times R^n]$  be the solution of the problem (P.2). Then, there exist positive constants  $C$  and  $\tilde{\mu}_2$  such that the following inequality holds for all  $t \in R^1_+$  and all  $\mu \geq \tilde{\mu}_2$ ,

$$\begin{aligned} (6.10) \quad & \| \mu u(t) \|_{0,\mu}^2 + \mu \| \mu u \|_{0,\mu,t}^2 + \langle \mu u \rangle_{0,\mu,t}^2 + \mu \langle\langle \Lambda_{x,w,\mu}^{-1/2} \mu u \rangle\rangle_{0,\mu,t}^2 \\ & \leq C \{ \| u(0) \|_{1,\mu}^2 + \mu \| u_t \|_{0,\mu,t}^2 + \mu \| u_x \|_{0,\mu,t}^2 + \mu \| u_y \|_{0,\mu,t}^2 \}. \end{aligned}$$

PROOF. See [16].

Q.E.D.

PROOF OF MAIN THEOREM 2. By (6.7), (6.8), Proposition 4.3 and Lemma 6.1, we

have Main Theorem 2.

Q.E.D.

### §7. The proof of Main Theorem 3.

In this section, we shall prove Main Theorem 3.

**LEMMA 7.1.** *Let  $u$  be the solution of the problem (P.3) which belongs to  $\mathcal{H}_{2,\mu}[(\mathbf{R}_+^1)^4 \times \mathbf{R}^n]$ . Then, there exist positive constants  $C$  and  $\tilde{\mu}_3$  such that the following inequality holds for all  $t \in \mathbf{R}_+^1$  and all  $\mu \geq \tilde{\mu}_3$ :*

$$(7.1) \quad \begin{aligned} & \| \|\mu u(t)\|_0^2 + \mu \| \mu u \|_{0,\mu,t}^2 + \langle \mu u \rangle_{0,\mu,t}^2 + \langle \langle \mu u \rangle \rangle_{0,\mu,t}^2 + \langle \langle \langle \mu u \rangle \rangle \rangle_{0,\mu,t}^2 \\ & \leq C \{ \|u(0)\|_1^2 + \mu \|u_t\|_{0,\mu,t}^2 + \mu \|u_x\|_{0,\mu,t}^2 + \mu \|u_y\|_{0,\mu,t}^2 + \mu \|u_z\|_{0,\mu,t}^2 \}. \end{aligned}$$

**PROOF.** By the same method as the one in [7], we have Lemma 7.1. Q.E.D.

**PROOF OF MAIN THEOREM 3.** By the same method as the one in §5, Theorem 3.7, Theorem 3.8, Proposition 4.4 and Lemma 7.1, we obtain Main Theorem 3. Q.E.D.

### Appendix. On a result in [27].

We state a result in [27] which is used in §3.

We treat the mixed problem

$$(P) \quad \left\{ \begin{array}{l} L[u] = \frac{\partial^2 u}{\partial t^2} - 2 \sum_{j=1}^n h_j(t, x) \frac{\partial^2 u}{\partial t \partial x_j} - \sum_{i,j=1}^n a_{ij}(t, x) \frac{\partial^2 u}{\partial x_i \partial x_j} \\ \quad + a_0(t, x) \frac{\partial u}{\partial t} + \sum_{j=1}^n a_j(t, x) \frac{\partial u}{\partial x_j} + d(t, x)u = f(t, x) \\ u(0, x) = u_0(x), \quad u_t(0, x) = u_1(x) \\ B[u]|_{x_1=0} = a_{11}(t, 0, x')^{-1/2} \left\{ a_{11}(t, 0, x') \frac{\partial u}{\partial x_1} + \sum_{j=2}^n a_{1j}(t, 0, x') \frac{\partial u}{\partial x_j} \right. \\ \quad \left. + h_1(t, 0, x') \frac{\partial u}{\partial t} \right\} + \sum_{j=2}^n b_j(t, x') \frac{\partial u}{\partial x_j} - c(t, x') \left( 1 + \frac{h_1(t, 0, x')^2}{a_{11}(t, 0, x')} \right)^{1/2} \\ \quad \cdot \left\{ \frac{\partial u}{\partial t} - \left( 1 + \frac{h_1(t, 0, x')^2}{a_{11}(t, 0, x')} \right)^{-1} \sum_{j=2}^n \left( h_j(t, 0, x') - \frac{h_1(t, 0, x')}{a_{11}(t, 0, x')} a_{1j}(t, 0, x') \right) \frac{\partial u}{\partial x_j} \right\} \\ \quad + \gamma(t, x')u|_{x_1=0} = g(t, x') \\ (t, x) = (t, x_1, x') \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^{n-1} \end{array} \right.$$

where  $x = (x_1, x_2, \dots, x_n)$ ,  $x' = (x_2, \dots, x_n)$ ,  $n \geq 2$ , the coefficients  $h_j$  and  $a_{ij}$  ( $a_0$ ,  $a_j$  and  $d$ ) belong to  $\mathcal{B}^1(\mathbf{R} \times \overline{\mathbf{R}_+^n})$  ( $\mathcal{B}^0(\mathbf{R} \times \overline{\mathbf{R}_+^n})$ ) and are constant outside a compact set in  $\mathbf{R} \times \overline{\mathbf{R}_+^n}$ ,

the coefficients  $b_j$ ,  $c$  and  $\gamma$  belong to  $\mathcal{B}^1(\mathbf{R} \times \mathbf{R}^{n-1})$  and are constant outside a compact set in  $\mathbf{R} \times \mathbf{R}^{n-1}$ .

We assume the following conditions for the problem (P):

(C.1) The operator  $L$  is regularly hyperbolic on  $\mathbf{R} \times \overline{\mathbf{R}_+^n}$  and  $a_{11}(t, x) > 0$  on  $\mathbf{R} \times \overline{\mathbf{R}_+^n}$ .

$$(C.2) \quad |1 + c(t, x')| - |1 - c(t, x')| \\ > 2 \left\{ \sup_{\eta'} |\operatorname{Re} b(t, x', \eta')|^2 + \sup_{\eta'} |\operatorname{Im} b(t, x', \eta')|^2 \right\}^{1/2}$$

for all  $(t, x', \eta') \in \mathbf{R} \times \mathbf{R}^{n-1} \times (\mathbf{R}^{n-1} - \{0\})$  where

$$(1) \quad \begin{cases} b(t, x', \eta') = \sum_{j=2}^n b_j(t, x') \eta'_j / d(t, x', \eta') \\ d(t, x', \eta') = \left[ \sum_{i,j=2}^n a_{ij}(t, 0, x') \eta_i \eta_j - \frac{1}{a_{11}(t, 0, x')} \left( \sum_{j=2}^n a_{1j}(t, 0, x') \eta_j \right)^2 \right. \\ \quad \left. + \left( 1 + \frac{h_1(t, 0, x')^2}{a_{11}(t, 0, x')} \right)^{-1} \left\{ \sum_{j=2}^n \left( h_j(t, 0, x') - \frac{h_1(t, 0, x')}{a_{11}(t, 0, x')} a_{1j}(t, 0, x') \right) \eta_j \right\}^2 \right]^{1/2} \\ \eta' = (\eta_2, \dots, \eta_n) \in \mathbf{R}^{n-1} - \{0\}. \end{cases}$$

**REMARK.** In (C.1), the condition  $a_{11}(t, x) > 0$  on  $\mathbf{R} \times \overline{\mathbf{R}_+^n}$  is replaced by the condition  $a_{11}(t, 0, x') > 0$  on  $\overline{\mathbf{R}_+^1} \times \mathbf{R}^{n-1}$ .

By the treatment in the framework of  $L^2$ -theory, we have only to consider the following two cases respectively:

$$(I) \quad |1 - c(t, x')| < \frac{1}{2} \inf_{(t, x') \in \mathbf{R} \times \mathbf{R}^{n-1}} \left\{ 1 - \frac{2}{|1 + c(t, x')|} \left( \sum_{j=2}^n |\tilde{b}_j(t, x')|^2 \right)^{1/2} \right\},$$

$$(II) \quad |1 - c(t, x')| > \frac{1}{4} \inf_{(t, x') \in \mathbf{R} \times \mathbf{R}^{n-1}} \left\{ 1 - \frac{2}{|1 + c(t, x')|} \left( \sum_{j=2}^n |\tilde{b}_j(t, x')|^2 \right)^{1/2} \right\}$$

for all  $(t, x') \in \mathbf{R} \times \mathbf{R}^{n-1}$  where

$$\sigma(L) = \tilde{\xi}^2 + \tilde{d}(\eta')^2 - \tilde{\tau}^2,$$

$$\tilde{\xi} = \frac{1}{\sqrt{a_{11}(t, x)}} \left\{ a_{11}(t, x) \xi + \sum_{j=2}^n a_{1j}(t, x) \eta_j + h_1(t, x) \tau \right\},$$

$$\tilde{\tau} = \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{1/2} \left\{ \tau - \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{-1} \sum_{j=2}^n \left( h_j(t, x) - \frac{h_1(t, x)}{a_{11}(t, x)} a_{1j}(t, x) \right) \eta_j \right\},$$

$$\begin{aligned} \bar{d}(\eta') &= \left[ \sum_{i,j=2}^n a_{ij}(t, x) \eta_i \eta_j - \frac{1}{a_{11}(t, x)} \left( \sum_{j=2}^n a_{1j}(t, x) \eta_j \right)^2 \right. \\ &\quad \left. + \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{-1} \left\{ \sum_{j=2}^n \left( h_j(t, x) - \frac{h_1(t, x)}{a_{11}(t, x)} a_{1j}(t, x) \right) \eta_j \right\}^2 \right]^{1/2}, \\ \bar{d}(\eta')^2 &= {}^t \eta' M \eta' = {}^t \zeta' \cdot \zeta' \quad (\eta' = {}^t(\eta_2, \dots, \eta_n), \quad M > 0, \quad \zeta' = {}^t(\zeta_2, \dots, \zeta_n)), \end{aligned}$$

$${}^t N M N = \begin{pmatrix} \alpha_2(t, x) & & 0 & \\ & \ddots & & \\ & & \ddots & \\ 0 & & & \alpha_n(t, x) \end{pmatrix} > 0,$$

$$\zeta' = \begin{pmatrix} \zeta_2 \\ \vdots \\ \zeta_n \end{pmatrix} = \begin{pmatrix} \sqrt{\alpha_2} & & 0 & \\ & \ddots & & \\ & & \ddots & \\ 0 & & & \sqrt{\alpha_n} \end{pmatrix} N^{-1} \cdot \eta',$$

$$\tilde{\zeta}' = \begin{pmatrix} \tilde{\zeta}_2 \\ \vdots \\ \tilde{\zeta}_n \end{pmatrix} = \left. \begin{pmatrix} \sqrt{\alpha_2} & & 0 & \\ & \ddots & & \\ & & \ddots & \\ 0 & & & \sqrt{\alpha_n} \end{pmatrix} N^{-1} \right|_{x_1=0} \cdot \eta',$$

$$\sum_{j=2}^n b_j(t, x') \eta_j = \sum_{j=2}^n \tilde{b}_j(t, x') \tilde{\zeta}_j, \quad b(t, x', \eta') = \left( \sum_{j=2}^n \tilde{b}_j \tilde{\zeta}_j \right) / \sqrt{\tilde{\zeta}_2^2 + \dots + \tilde{\zeta}_n^2}$$

and

$$|1 + c(t, x')| - |1 - c(t, x')| > 2 \left( \sum_{j=2}^n |\tilde{b}_j(t, x')|^2 \right)^{1/2}.$$

We set

$$(2) \quad Q_0 = \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{1/2} \left\{ \frac{\partial}{\partial t} - \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{-1} \right. \\ \left. \cdot \sum_{j=2}^n \left( h_j(t, x) - \frac{h_1(t, x)}{a_{11}(t, x)} a_{1j}(t, x) \right) \frac{\partial}{\partial x_j} \right\},$$

$$(3) \quad Q_1 = \frac{1}{\sqrt{a_{11}(t, x)}} \left\{ a_{11}(t, x) \frac{\partial}{\partial x_1} + \sum_{j=2}^n a_{1j}(t, x) \frac{\partial}{\partial x_j} + h_1(t, x) \frac{\partial}{\partial t} \right\} + \gamma(t, x'),$$

$$(4) \quad Q_j = \sum_{l=2}^n p_{jl}(t, x) \frac{\partial}{\partial x_l} \quad (j=2, \dots, n)$$

where

$$(5) \quad \begin{pmatrix} p_{22}(t, x) & \cdots & p_{2n}(t, x) \\ \vdots & \ddots & \vdots \\ p_{n2}(t, x) & \cdots & p_{nn}(t, x) \end{pmatrix} = \begin{pmatrix} \sqrt{\alpha_2} & & 0 \\ & \ddots & \\ 0 & & \sqrt{\alpha_n} \end{pmatrix} N^{-1}.$$

Then, we have

$$(6) \quad L = Q_0 \cdot Q_0 - Q_1 \cdot Q_1 - \sum_{j=2}^n Q_j \cdot Q_j + (\text{lower order operator}).$$

$$\text{Case (I): } |1 - c(t, x')| < \frac{1}{2} \inf_{(t, x') \in \mathbb{R} \times \mathbb{R}^{n-1}} \left\{ 1 - \frac{2}{|1 + c(t, x')|} \left( \sum_{j=2}^n |\tilde{b}_j(t, x')|^2 \right)^{1/2} \right\}$$

for all  $(t, x') \in \mathbb{R} \times \mathbb{R}^{n-1}$ .

We set

$$(7) \quad u = \begin{pmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ \vdots \\ U_{n+1} \\ U_{n+2} \end{pmatrix} = \begin{pmatrix} Q_0 u - Q_1 u \\ z_1(Q_0 u + Q_1 u) \\ Q_2 u \\ Q_3 u \\ \vdots \\ Q_n u \\ u \end{pmatrix}$$

where  $u$  is the solution of the problem (P),

$$(8) \quad z_1 = \frac{\sqrt{\varepsilon_0}}{1 + c(t, x')}$$

and

$$(9) \quad \varepsilon_0 = \frac{1}{2} \inf_{(t, x') \in \mathbb{R} \times \mathbb{R}^{n-1}} \left\{ 1 - \frac{2}{|1 + c(t, x')|} \left( \sum_{j=2}^n |\tilde{b}_j(t, x')|^2 \right)^{1/2} \right\}.$$

Now, we state our result in [27].

**THEOREM A.** *The problem (P) under the conditions (C.1) and (C.2) is transformed into the system:*

$$(10) \quad \begin{cases} \tilde{M}_1 U_t = \tilde{A}_{11} U_{x_1} + \sum_{j=2}^n \tilde{A}_{1j} U_{x_j} + \tilde{E}_1 U + \tilde{F}_1(t, x) \\ U(0, x) = U_0(x) \\ \tilde{P}_1 U|_{x_1=0} = \tilde{G}_1(t, x') \\ (t, x) = (t, x_1, x') \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^{n-1} \end{cases}$$

where

$$\begin{aligned} \tilde{M}_1 &= \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{1/2} \text{diag}(1, 1, 1 + |z_1|^2, \dots, 1 + |z_1|^2, 1) \\ &\quad - \frac{h_1(t, x)}{\sqrt{a_{11}(t, x)}} \text{diag}(-1, 1, 1 - |z_1|^2, \dots, 1 - |z_1|^2, 1), \\ \tilde{A}_{11} &= \sqrt{a_{11}(t, x)} \text{diag}(-1, 1, 1 - |z_1|^2, \dots, 1 - |z_1|^2, 1), \\ \tilde{A}_{1j} &= \frac{a_{1j}(t, x)}{a_{11}(t, x)} \tilde{A}_{11} + \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{-1/2} \left( h_j(t, x) - \frac{h_1(t, x)}{a_{11}(t, x)} a_{1j}(t, x) \right) \\ &\quad \cdot \text{diag}(1, 1, 1 + |z_1|^2, \dots, 1 + |z_1|^2, 1) \\ &+ \sum_{l=2}^n p_{lj} \begin{pmatrix} 0 & \cdot & \cdot & \cdot & 0 & 1 & 0 \\ 0 & \cdot & \cdot & \cdot & 0 & z_1 & \cdot \\ \cdot & & & & \cdot & 0 & \cdot \\ \cdot & & & & \cdot & \cdot & \cdot \\ \cdot & & & & \cdot & \cdot & \cdot \\ & & & & & & 0 \\ 0 & \cdot & \cdot & \cdot & 0 & 0 & \cdot \\ 1 & \bar{z}_1 & 0 & \cdot & 0 & 0 & \cdot \\ & & & & & & \cdot \\ & & & & & 0 & \cdot \\ 0 & \cdot & \cdot & \cdot & \cdot & \cdot & 0 & 1 \end{pmatrix} \\ &\quad (j=2, \dots, n), \end{aligned}$$

$\tilde{\tilde{E}}_1$  is an  $(n+2) \times (n+2)$  matrix which has the property that for  $\tilde{\tilde{E}}_1 = (e_{ij})$ ,  $e_{ij}$  belongs to  $\mathcal{B}^0(\mathbf{R} \times \mathbf{R}_+^n)$  and is a constant outside a compact set in  $\mathbf{R} \times \overline{\mathbf{R}_+^n}$ ,

$$\tilde{\tilde{F}}_1 = {}^t(f, z_1 f, 0, \dots, 0),$$

$$\tilde{\tilde{P}}_1 = \left( 1, -\frac{1-c(t, x')}{\sqrt{\varepsilon_0}}, -\frac{2}{1+c} \tilde{b}_2, \dots, -\frac{2}{1+c} \tilde{b}_n, 0 \right),$$

$$\tilde{\tilde{G}}_1 = -\frac{2g(t, x')}{1+c(t, x')}$$

and there is a positive constant  $C$  such that

$$(11) \quad [\tilde{\tilde{A}}_{11} U, U] \geq C[U, U] \quad \text{for all } U \in \text{Ker } \tilde{\tilde{P}}_1.$$

$$\text{Case (II): } |1-c(t, x')| > \frac{1}{4} \inf_{(t, x') \in \mathbf{R} \times \mathbf{R}^{n-1}} \left\{ 1 - \frac{2}{|1+c(t, x')|} \left( \sum_{j=2}^n |\tilde{b}_j(t, x')|^2 \right)^{1/2} \right\}$$

$$\text{for all } (t, x') \in \mathbf{R} \times \mathbf{R}^{n-1}.$$

For the solution  $u$  of the problem (P), we use the same vector  $U$  as in (7) where  $z_1$  is replaced by  $z_2$ :

$$(12) \quad z_2(t, x') = \sqrt{\frac{1-c(t, x')}{1+c(t, x')}} \quad (\sqrt{1}=1).$$

Then, we have

**THEOREM B.** *The problem (P) under the conditions (C.1) and (C.2) is transformed into the system:*

$$(13) \quad \begin{cases} \tilde{\tilde{M}}_2 U_t = \tilde{\tilde{A}}_{21} U_{x_1} + \sum_{j=2}^n \tilde{\tilde{A}}_{2j} U_{x_j} + \tilde{\tilde{E}}_2 U + \tilde{\tilde{F}}_2 \\ U(0, x) = U_0(x) \\ \tilde{\tilde{P}}_2 U|_{x_1=0} = \tilde{\tilde{G}}_2(t, x') \\ (t, x) = (t, x_1, x') \in \mathbf{R}_+^1 \times \mathbf{R}_+^1 \times \mathbf{R}^{n-1} \end{cases}$$

where

$$\begin{aligned} \tilde{\tilde{M}}_2 &= \left( 1 + \frac{h_1(t, x)^2}{a_{11}(t, x)} \right)^{1/2} \text{diag}(1, 1, 1+|z_2|^2, \dots, 1+|z_2|^2, 1) \\ &\quad - \frac{h_1(t, x)}{\sqrt{a_{11}(t, x)}} \text{diag}(-1, 1, 1-|z_2|^2, \dots, 1-|z_2|^2, 1), \end{aligned}$$

$$\tilde{\tilde{A}}_{21} = \sqrt{a_{11}(t, x)} \text{diag}(-1, 1, 1-|z_2|^2, \dots, 1-|z_2|^2, 1),$$

$$\tilde{\tilde{A}}_{2j} = \frac{a_{1j}(t, x)}{a_{11}(t, x)} \tilde{\tilde{A}}_{21} + \left(1 + \frac{h_1(t, x)^2}{a_{11}(t, x)}\right)^{-1/2} \left(h_j(t, x) - \frac{h_1(t, x)}{a_{11}(t, x)} a_{1j}(t, x)\right) \\ \cdot \text{diag}(1, 1, 1 + |z_2|^2, \dots, 1 + |z_2|^2, 1)$$

$$\begin{array}{c} (l+1) \text{ column} \\ \left( \begin{array}{ccccccccc} 0 & \cdot & \cdot & \cdot & \cdot & 0 & 1 & & 0 \\ 0 & \cdot & \cdot & \cdot & \cdot & 0 & z_2 & & \cdot \\ \cdot & & & & & \cdot & 0 & & \cdot \\ \cdot & & & & & \cdot & \cdot & & \cdot \\ \cdot & & & & & \cdot & \cdot & & \cdot \\ \cdot & & & & & \cdot & \cdot & & \cdot \\ + \sum_{l=2}^n p_{lj} & 0 & 0 & \cdot & \cdot & 0 & 0 & & \cdot \\ (l+1) \text{ row} & 1 & \bar{z}_2 & 0 & \cdot & 0 & 0 & & \cdot \\ & & & & & & & & \cdot \\ & & & & & & & & 0 \\ 0 & \cdot & 0 & 1 \end{array} \right) \end{array}$$

$$(j=2, \dots, n),$$

$\tilde{\tilde{E}}_2 \cdots$  an  $(n+2) \times (n+2)$  matrix which the same property as  $\tilde{\tilde{E}}_1$ ,

$$\tilde{\tilde{F}}_2 = {}^t(f, z_2 f, 0, \dots, 0),$$

$$\tilde{\tilde{P}}_2 = \left(1, -z_2, -\frac{2}{1+c} \tilde{b}_2, \dots, -\frac{2}{1+c} \tilde{b}_n, 0\right),$$

$$\tilde{\tilde{G}}_2 = -\tilde{\tilde{G}}_1,$$

and there exists a positive constant  $C$  such that

$$(14) \quad [\tilde{\tilde{A}}_{21} U, U] \geq C[U, U] \quad \text{for all } U \in \text{Ker } \tilde{\tilde{P}}_2.$$

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