

101. Open Basis and Continuous Mappings. II^{*)}

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Let X and Y be T_1 -spaces and let $f(X)=Y$ be a continuous mapping. f is said to be an S -mapping if the inverse image $f^{-1}(y)$ is separable¹⁾ for each point y of Y . By the *open S -image*, we mean the image of an open continuous S -mapping. V. I. Ponomarev [4] has recently obtained the following theorem: *a T_1 -space X has a point-countable open base if and only if X is an open S -image of a 0-dimensional metric space.*

In this note, we shall obtain an analogous theorem concerning the locally countable (star-countable) open base and we shall next investigate the open base of the inverse image space of an open continuous S -mapping.

1. We begin with proving the following theorem which is analogous to V. I. Ponomarev's theorem.

Theorem 1. *A T_1 -space X has a locally countable (star-countable) open base if and only if X is an open S -image of a locally separable 0-dimensional metric space.*

Proof. As the "if" part is easily seen from our previous note ([1], Theorem 10, Remark 3), we shall prove the "only if" part. Since it is easily verified that X has a star-countable open base if and only if X has a locally countable open base, we deal with the case of the star-countable open base. Let X have a star-countable open base $\mathfrak{A}=\{U_\alpha\}$, then X is decomposed in such a way that $X=\bigcup_{\gamma \in \Gamma} A_\gamma$, $A_\gamma = \bigcup \{U_\alpha \in \mathfrak{A}_\gamma\}$, $A_\gamma \cap A_{\gamma'} = \emptyset$ for $\gamma \neq \gamma'$, $\gamma, \gamma' \in \Gamma$ where each \mathfrak{A}_γ is a countable subfamily of \mathfrak{A} [2, 6]. Then each A_γ has a countable open base \mathfrak{A}_γ for each $\gamma \in \Gamma$. Let $\mathfrak{A}_\gamma = \{U_n^{(\gamma)} \mid n=1, 2, \dots\}$. For every point x of A_γ , $\{U_n^{(\gamma)} \mid x \in U_n^{(\gamma)}, U_n^{(\gamma)} \in \mathfrak{A}_\gamma\}$ is countable. Let us denote this collection by $\{U_{n_i(x)}^{(\gamma)} \mid i=1, 2, \dots\}$, then, since X is a T_1 -space, we have $\bigcap_{i=1}^{\infty} U_{n_i(x)}^{(\gamma)} = x$. If the intersection of all sets belonging to a countable subfamily $\{U_{n_i}^{(\gamma)}\}$ of \mathfrak{A}_γ is a single point, then we define $\xi = (n_1, n_2, \dots)$. Now let B_γ denote the set of all such ξ . We can define the topology

^{*)} This note is a continuation of our previous note [1].

1) A set A is said to be separable when there exists a countable subset B of A such that $\bar{B} \supset A$. By the definition due to V. I. Ponomarev, S -mapping means the continuous mapping such that the inverse image $f^{-1}(y)$ is perfectly separable for each point y of Y , but we define here in the weaker sense than this.

of B_γ as a subspace of Baire's zero-space.²⁾ Then B_γ is a separable 0-dimensional metric space. If $x \in A_\gamma$ and $\bigcap_{i=1}^{\infty} U_{n_i}^{(\gamma)} = x$, we define a mapping f_γ of B_γ onto A_γ by $f_\gamma(\xi) = x$ where $\xi = (n_1, n_2, \dots)$. To prove that f_γ is an open continuous mapping, it is sufficient to show that f_γ transforms the base for the neighborhood system of ξ to that of $f_\gamma(\xi)$ for any point ξ of B_γ . Let $V_n(\xi) = \left\{ \xi' \mid \rho(\xi, \xi') < \frac{1}{n}, \xi' \in B_\gamma \right\}$, then $\{V_n(\xi) \mid n=1, 2, \dots\}$ is a base for the neighborhood system of ξ . Let $f_\gamma(\xi) = x$ and let $U(x)$ be any neighborhood of x where $\xi = (n_1, n_2, \dots)$, then, since $\bigcap_{i=1}^{\infty} U_{n_i}^{(\gamma)} = x$, we can find n_k such that $U_{n_k}^{(\gamma)} \subset U(x)$. Then $f_\gamma(V_{k+1}(\xi)) \subset U_{n_k}^{(\gamma)} \subset U(x)$. Therefore f_γ is an open continuous mapping of B_γ onto A_γ . Moreover, since B_γ is separable, the inverse image $f_\gamma^{-1}(x)$ is separable for every point x of A_γ . Hence f_γ is an open continuous S -mapping. For each $\gamma \in \Gamma$, let C_γ is a topological space such that C_γ is homeomorphic to B_γ and let $C_\gamma \cap C_{\gamma'} = \phi$ for $\gamma \neq \gamma'$. We define the topology of $T = \bigcup_{\gamma \in \Gamma} C_\gamma$ as follows: for each point t of T such that $t \in C_\gamma$, the base for the open neighborhood system of t is that of t of the space C_γ . Then T is a locally separable 0-dimensional metric space. Let φ_γ be the above homeomorphism between C_γ and B_γ . We define a mapping f of T onto X as follows: if $t \in C_\gamma$, then $f(t) = f_\gamma \varphi_\gamma(t)$. Then it is easy to see that f is an open continuous S -mapping of T onto X . This completes the proof.

As an immediate consequence of Theorem 1, we get the following corollary.

Corollary 1. *A T_1 -space X is perfectly separable if and only if X is an open S -image of a separable 0-dimensional metric space.*

2. In this section, we deal with the open basis of inverse image spaces of open continuous S -mappings.

Theorem 2. *Let X be a topological space and let Y be a topological space with a locally countable (star-countable) open base. If $f(X) = Y$ is an open continuous S -mapping, then X has a locally countable (star-countable) open base if and only if X has a point-countable open base.*

Proof. As the "only if" part is obvious, we shall prove the "if" part. By the same argument as that of Theorem 1, we can decompose Y in such a way that $Y = \bigcup_{\gamma \in \Gamma} A_\gamma$ where $A_\gamma \cap A_{\gamma'} = \phi$ for $\gamma \neq \gamma'$

2) Let B be the set of all points x such that $x = (n_1, n_2, n_3, \dots)$ where each n_i is a positive integer. Let $x = (n_1, n_2, n_3, \dots)$ and $y = (m_1, m_2, m_3, \dots)$ be any points of B . If $n_i = m_i$ for $i < k$ and $n_k \neq m_k$, then we define the metric $\rho(x, y) = \frac{1}{k}$. When we define $\rho(x, y)$ for any two points x and y of B , B is said to be Baire's zero-space.

and each A_γ is perfectly separable open subspace of Y . Since f is an open continuous S -mapping, each $f^{-1}(A_\gamma)$ is separable ([8], Lemma 2). Then, since X has a point-countable open base, each $f^{-1}(A_\gamma)$ is perfectly separable. Since $X = \bigcup_{\gamma \in I} f^{-1}(A_\gamma)$ and $f^{-1}(A_\gamma) \cap f^{-1}(A_{\gamma'}) = \emptyset$ for $\gamma \neq \gamma'$, X has a star-countable open base. This completes the proof.

Corollary 2. *A topological space X has a locally countable (star-countable) open base if and only if the product space $X \times Y$ has a locally countable (star-countable) open base for any topological space Y with a locally countable (star-countable) open base.*

Proof. As the “if” part is obvious, we need only prove the “only if” part. Since X has a star-countable open base, X is decomposed in such a way that $X = \bigcup_{\gamma \in I} A_\gamma$ and $A_\gamma \cap A_{\gamma'} = \emptyset$ for $\gamma \neq \gamma'$ and each A_γ is a perfectly separable open subspace of X . Then $X \times Y = (\bigcup_{\gamma \in I} A_\gamma) \times Y = \bigcup_{\gamma \in I} (A_\gamma \times Y)$ and $(A_\gamma \times Y) \cap (A_{\gamma'} \times Y) = \emptyset$ for $\gamma \neq \gamma'$. Let f_γ be the projection of $A_\gamma \times Y$ onto Y , then it is easy to see that f_γ is an open continuous S -mapping. Then, by virtue of Theorem 2, $A_\gamma \times Y$ has a star-countable open base. Therefore $X \times Y$ has a star-countable open base. This completes the proof.

Theorem 3. *Let X be a regular T_1 -space and let Y be a locally separable metric space. If $f(X) = Y$ is an open continuous S -mapping, then X is a locally separable metric space if and only if X has a point-countable open base.*

Proof. As the “only if” part is obvious, we need only prove the “if” part. Since Y is a locally separable metric space, Y has a star-countable open base. Then, by virtue of Theorem 2, X has a star-countable open base. Therefore X is locally separable and locally metrizable. Since X has a star-countable open base, X is strongly paracompact. Hence X is metrizable by Nagata-Smirnov's theorem [3, 5]. This completes the proof.

As an immediate result of Theorem 3, we get the following theorem which includes the well-known theorem due to A. H. Stone ([8], Theorem 4).

Theorem 4. *Let X be a regular T_1 -space with a point-countable open base and let Y be a regular T_1 -space. If $f(X) = Y$ is an open continuous S -mapping, then Y is a locally separable metric space if and only if X is a locally separable metric space.*

In conclusion, we shall give an example which shows that we can not drop the assumption that X has a point-countable open base in Theorems 2, 3, and 4.

Example. Let $X = [0, 1]$ that is, the closed interval of the real line. We define the topology of X as follows: if $x \neq 1$ and $x \in X$,

then the collection of all semi-open intervals of the form $[x, y)$ with $x < y \leq 1$ is the base for the neighborhood system of x and if $x=1$, then the single point x is itself open (cf. [7]). It is easy to see that X is a separable normal T_1 -space but not perfectly separable. Hence X is not metrizable. Therefore X has no point-countable open base. Now let $Y=[0, 1]$ be the subspace of the real line, then Y is a separable metric space and hence Y has a star-countable open base. Let f be the projection of $X \times Y$ onto Y , then f is an open continuous S -mapping. On the other hand, it is easy to see that $X \times Y$ has no point-countable open base. In fact, suppose on the contrary that $X \times Y$ has a point-countable open base. Then, since $X \times Y$ is separable, $X \times Y$ is perfectly separable. Hence X is perfectly separable. This contradicts the fact that X is not perfectly separable.

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