# 163. Regularity of Solutions of Hyperbolic Mixed Problems with Characteristic Boundary 

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§1. Introduction. At first we recall the following well-known property of a solution of a hyperbolic Cauchy problem which is $L^{2}$-well posed: If the initial value is in $H^{r}\left(R^{n}\right)$, then the solution is also in $H^{r}\left(R^{n}\right)$ for any time $>0$. We call this "The property of having finite $r$ norm is persistent".

The author proved in [2] that, for a mixed problem to a first order hyperbolic system, if this mixed problem is $L^{2}$-well posed and the boundary is not characteristic for the equation, then the property of having finite $r$-norm is persistent.

In this note we discuss whether the persistent property holds or not in the case where the boundary is characteristic for the equation. Let $\Omega$ be a sufficiently smooth domain in $R^{n}, M=\partial / \partial t-L\left(t, x ; D_{x}\right)$ be a first order hyperbolic system whose coefficients are $N \times N$ matrices in $\mathscr{B}([0, T] \times \Omega)$ and $P(t, x)$ be an $N \times N$ matrix defined on $[0, T] \times \partial \Omega$. Let us consider the mixed problem
(P) $\left\{\begin{array}{lll}(1.1) & M[u(t, x)]=f(t, x) & \text { in }[0, T] \times \Omega \\ (1.2) & u(0, x)=\varphi(x) & \text { on } \Omega \\ (1.3) & P(t, x) u(t, x)=0 & \text { on }[0, T] \times \partial \Omega .\end{array}\right.$

Definition. The mixed problem ( P ) is said to be $L^{2}$-well posed if for any initial data $\varphi(x) \in D_{0}=\left\{u(x) \in H^{1}(\Omega) ;\left.P(0, x) u\right|_{\partial \Omega}=0\right\}$ and any second member $f(t, x) \in \mathcal{E}_{t}^{0}\left(H^{1}(\Omega)\right) \cap \mathcal{E}_{t}^{1}\left(L^{2}(\Omega)\right)^{1)}$ there exists a unique solution $u(t, x)$ of (P) in $\mathcal{E}_{t}^{1}\left(L^{2}(\Omega)\right) \cap \mathcal{E}_{t}^{0}(\mathscr{D}(L(t))$ ) satisfying the following energy inequality

$$
\begin{equation*}
\|u(t)\| \leqq c(T)\left(\|\varphi\|+\int_{0}^{t}\|f(s)\| d s\right), \quad t \in[0, T] \tag{1.4}
\end{equation*}
$$

where $c(T)$ is a positive constant which depends only on $T$.
We remark that $\mathscr{D}(L(t))$ is the closure of $D_{t}=\left\{u(x) \in H^{1}(\Omega)\right.$; $\left.\left.P(t) u\right|_{\partial \Omega}=0\right\}$ by the norm $\|u\|_{L(t)}=\|u\|+\|L(t) u\|$. At first we state

Theorem 1. In the case where $\Omega=R_{+}^{2}=\left\{(x, y) ; x>0, y \in R^{1}\right\}$, $L=\left[\begin{array}{rr}-2 & 0 \\ 0 & 0\end{array}\right] \partial / \partial x+\left[\begin{array}{ll}0 & 1 \\ 1 & 0\end{array}\right] \partial / \partial y$ and $P=\left[\begin{array}{ll}1 & 0\end{array}\right]$, the mixed problem $(\mathrm{P})$ is $L^{2}$-well posed, but the property of having finite r-norm is not persistent. More precisely, if the initial value $\varphi(x, y) \in H^{m}\left(R_{+}^{2}\right)$ satisfies

[^0]$\left.P\left(L^{k} \varphi\right)\right|_{x=0}=0(k=0,1, \cdots, m-1)$ and $f(t, x, y) \equiv 0$, then the solution $u(t, x, y)={ }^{t}\left(u_{1}, u_{2}\right)$ has the following properties
(i) $u_{1}(t, x, y) \in \mathcal{E}_{t}^{p}\left(H^{[(m+1-p) / 2]}\left(R_{+}^{2}\right)\right)$ and $u_{2}(t, x, y) \in \mathcal{E}_{t}^{p}\left(H^{[(m-p) / 2\rfloor}\left(R_{+}^{2}\right)\right)$ for any $p=0,1, \cdots, m$,
(ii) moreover, if we suppose more strictly that $\varphi(0, y) \notin H^{m}\left(R^{1}\right)$, then $u_{1}(t, x, y) \notin H^{[(m+1) / 2]+1}\left(R_{+}^{2}\right)$ and $u_{2}(t, x, y) \notin H^{[m / 2]+1}\left(R_{+}^{2}\right)$ for any $t>0$.

The above results can be extended to the following form. Let us consider

$$
\begin{equation*}
L\left(t, x ; D_{x}\right)=\sum_{i=1}^{n} A_{i}(t, x) \frac{\partial}{\partial x_{i}}+B(t, x) \tag{1.5}
\end{equation*}
$$

where $A_{i}(i=1, \cdots, n)$ and $B$ are $N \times N$ matrices, and assume that the boundary $\partial \Omega$ of $\Omega$ is compact and sufficiently smooth. For simplicity, we assume the following conditions
(C.1) $\quad A_{i}(i=1, \cdots, n)$ are Hermitian matrices,
(C.2) the boundary matrix $A_{B}=\sum_{i=1}^{n} A_{i}(t, x) \nu_{i}(x)$ is singular, but its rank is constant on $\partial \Omega$ where $\vec{n}=\left(\nu_{1}, \nu_{2}, \cdots, \nu_{n}\right)$ is the exterior unit normal to $\partial \Omega$,
(C.3) $P(t, x)$ is an $N \times N$ matrix, $\operatorname{rank} P=l=$ constant and $\operatorname{Ker} P(t)$ is maximally non-positive for $L(t)$ on $\partial \Omega$, i.e., we assume that

$$
u \cdot \overline{A_{B} u} \leqq 0, \quad u \in \operatorname{Ker} P, \quad t \geqq 0, \quad x \in \partial \Omega,
$$

and that $\operatorname{Ker} P$ is not properly contained in any other subspace having this property.

Then we have
Theorem 2. Assume that the data $\varphi(x) \in H^{m}(\Omega)$ and the second member $f(t, x) \in \mathcal{E}_{t}^{m}\left(L^{2}\right) \cap \mathcal{E}_{t}^{m-1}\left(H^{1}\right) \cap \cdots \cap \mathcal{E}_{t}^{0}\left(H^{m}\right)$ satisfy the compatibility conditions (1.6) of order $(m-1)$ :

$$
\begin{equation*}
\left.\sum_{i=1}^{k}\binom{k}{i} \frac{\partial^{i} P}{\partial t^{i}}(0, x) \cdot \varphi^{(k-i)}(x)\right|_{\partial \Omega}=0, \quad k=0,1, \cdots, m-1, \tag{1.6}
\end{equation*}
$$

where $\varphi^{(0)}(x)=\varphi(x)$ and $\varphi^{(p+1)}(x)(p \geqq 0)$ is defined successively by the formula

$$
\begin{align*}
\varphi^{(p+1)}(x)= & \sum_{i=1}^{p}\binom{p}{i}\left(\sum_{j=1}^{n} \frac{\partial^{i} A_{j}}{\partial t^{i}}(0, x) \frac{\partial}{\partial x_{j}}+\frac{\partial^{i} B}{\partial t^{i}}(0, x)\right) \\
& \times \varphi^{(p-i)}(x)+\frac{\partial^{p} f}{\partial t^{p}}(0, x) . \tag{1.7}
\end{align*}
$$

Then there exists a unique solution $u(t, x)$ of $(P)$ in $\mathcal{E}_{t}^{p}\left(H^{[(m-p) / 2]}(\Omega)\right)$ ( $p=0,1, \cdots, m$ ), and it does not necessarily belong to $H^{[m / 2]+1}(\Omega)$ for any $t>0$.

Remark. In Maxwell equation, we pose $\vec{n} \times\left.\vec{E}\right|_{\partial \Omega}=0$ as the boundary condition where $\vec{n}$ is the exterior normal of the boundary and $\vec{E}$ is the electric field vector. Then this mixed problem satisfies the conditions (C.1), (C.2) and (C.3). However in this case the property of having finite $r$-norm is persistent.

Theorem 3. In the case where $\Omega=R_{+}^{2}, L=\left[\begin{array}{rr}-a & 0 \\ 0 & 0\end{array}\right] \partial / \partial x+\left[\begin{array}{ll}a_{1} & \bar{c} \\ c & a_{2}\end{array}\right]$ $\times \partial / \partial y\left(a>0 ; a_{1}, a_{2} \in R\right)$ and $P=[10]$, the necessary and sufficient condition in order that the property of having finite r-norm be persistent is $c=0$.
§2. Proof of Theorem 1. Since the $L^{2}$-well posedness is obvious in view of [1], we prove the latter of this theorem. If $\varphi(x, y)={ }^{t}\left(\varphi_{1}, \varphi_{2}\right)$ is in $H^{1}\left(R_{+}^{2}\right)$ and $\varphi_{1}(0, y)=0$, then the solution $u(t, x, y)$ is given by $u(t)$ $=e^{L t} \varphi$, which is in $\mathcal{E}_{t}^{1}\left(L^{2}\right) \cap \mathcal{E}_{t}^{0}(\mathscr{D}(L))$. Since the coefficients of $L$ is constant, $\partial u / \partial y(t, x, y)=e^{L t}(\partial \varphi / \partial y) \in \mathcal{E}_{t}^{0}\left(L^{2}\right)$. From the equation it follows

$$
\frac{\partial u_{1}}{\partial x}=\frac{1}{2}\left\{\frac{\partial u_{2}}{\partial y}-\frac{\partial u_{1}}{\partial t}\right\} \in \mathcal{E}_{t}^{0}\left(L^{2}\right)
$$

Hence $u_{1}(t, x, y)$ is in $\mathcal{E}_{t}^{0}\left(H^{1}\left(R_{+}^{2}\right)\right)$. Our purpose is to show that $u_{2}(t, x, y)$ does not belong to $H^{1}\left(R_{+}^{2}\right)$ for any $t>0$. Let us prove this by contradiction. For this we construct the solution $u(t, x, y)$ concretely by using Fourier-Laplace transform. We extend the definition domain of $u$ to $R_{+}^{1} \times R^{2}$ by $u(t, x, y)=0$ for $x<0$, and denote by $\tilde{u}(t, \xi, \eta)$ the image of Fourier transform of $u(t, x, y)$, i.e.,

$$
\begin{equation*}
\tilde{u}(t, \xi, \eta)=\int_{R^{2}} e^{-i\left(x \xi+y_{\eta}\right)} u(t, x, y) d x d y . \tag{2.1}
\end{equation*}
$$

Then it follows

$$
\begin{gather*}
\tilde{u}_{1}(t, \xi, \eta)=\frac{i \eta}{a} \sin a t \cdot e^{-i \xi t} \tilde{\varphi}_{2}(\xi, \eta) \\
\quad+\left(\cos a t-\frac{i \xi}{a} \sin a t\right) e^{-i \xi t} \tilde{\varphi}_{1}(\xi, \eta),  \tag{2.2}\\
\tilde{u}_{2}(t, \xi, \eta)=\frac{i \eta}{a} \sin a t \cdot e^{-i \xi t} \tilde{\varphi}_{1}(\xi, \eta) \\
+\left\{\left(\cos a t-\frac{i \xi}{a} \sin a t\right)+\frac{2 i \xi}{a} \sin a t\right\} e^{-i \xi t} \tilde{\varphi}_{2}(\xi, \eta)
\end{gather*}
$$

where $a=\sqrt{\xi^{2}+\eta^{2}}$. $\quad$ Since

$$
\begin{aligned}
\frac{\partial u_{2}}{\partial x} & (t, x, y)=\int_{0}^{t} \frac{\partial^{2} u_{2}}{\partial s \partial x}(s, x, y) d s+\frac{\partial \varphi_{2}}{\partial x}(x, y) \\
& =\frac{1}{2} \int_{0}^{t}\left\{\frac{\partial^{2} u_{2}}{\partial y^{2}}(s, x, y)-\frac{\partial^{2} u_{1}}{\partial s \partial y}(s, x, y)\right\} d s+\frac{\partial \varphi_{2}}{\partial x}(x, y) \\
& =\frac{1}{2} \int_{0}^{t} \frac{\partial^{2} u_{2}}{\partial y^{2}}(s, x, y) d s-\frac{1}{2}\left\{\frac{\partial u_{1}}{\partial y}(t, x, y)-\frac{\partial \varphi_{1}}{\partial y}(x, y)\right\}+\frac{\partial \varphi_{2}}{\partial x}(x, y)
\end{aligned}
$$

the necessary and sufficient condition in order that $u_{2}(t, x, y)$ be in $H^{1}\left(R_{+}^{2}\right)$ is

$$
\begin{equation*}
\int_{0}^{t} \frac{\partial^{2} u_{2}}{\partial y^{2}}(s, x, y) d s \in L^{2}\left(R_{+}^{2}\right), \quad \text { i.e., } \quad \int_{0}^{t}(i \eta)^{2} \tilde{u}_{2}(s, \xi, \eta) d s \in L^{2}\left(R^{2}\right) \tag{2.4}
\end{equation*}
$$

Substituting (2.3) into (2.4), we get

$$
\begin{align*}
\int_{0}^{t}(i \eta)^{2} \tilde{u}_{2}(s, \xi, \eta) d s= & \frac{(i \eta)^{3}}{a} \cdot \tilde{\varphi}_{1}(\xi, \eta) \cdot \int_{0}^{t} \sin a s \cdot e^{-i \xi s} d s \\
& +(i \eta)^{2} \cdot \tilde{\varphi}_{2}(\xi, \eta) \cdot \int_{0}^{t}\left(\cos a s-\frac{i \xi}{a} \sin a s\right) e^{-i \epsilon s} d s  \tag{2.5}\\
& +\frac{(2 i \xi)(i \eta)^{2}}{a} \tilde{\varphi}_{2}(\xi, \eta) \cdot \int_{0}^{t} e^{-i \xi s} \sin a s d s \\
= & I_{1}+I_{2}+I_{3} .
\end{align*}
$$

The terms $I_{1}$ and $I_{2}$ are easily proved to be in $L^{2}\left(R^{2}\right)$, therefore the term $I_{3}$ must be in $L^{2}\left(R^{2}\right)$. Since

$$
\int_{0}^{t} e^{-i \xi s} \sin a s d s=\frac{1}{a+|\xi|}\left(1-\cos a t \cdot e^{-i \xi t}\right)-\frac{i \xi}{a+|\xi|} \int_{0}^{t} e^{(\operatorname{sign} \xi \cdot a-\xi) s i} d s
$$

we get the following (2.6) in order to be $I_{3} \in L^{2}\left(R^{2}\right)$

$$
\begin{equation*}
\frac{(i \xi)^{2}(i \eta)^{2}}{a(a+|\xi|)} \tilde{\varphi}_{2}(\xi, \eta) \cdot \int_{0}^{t} e^{(\operatorname{sign} \xi \cdot a-\xi) s i} d s \in L^{2}\left(R^{2}\right) \tag{2.6}
\end{equation*}
$$

Taking account of the identity

$$
i \xi \cdot \tilde{\varphi}_{2}(\xi, \eta)=\frac{\partial \widetilde{\varphi}_{2}}{\partial x}(\xi, \eta)+\tilde{\varphi}_{2}(0, \eta), \quad \tilde{\varphi}_{2}(0, \eta)=\int_{R 1} e^{-i y \eta} \varphi_{2}(0, y) d y
$$

we see that (2.6) is equivalent to

$$
\begin{equation*}
\tilde{F}(t, \xi, \eta)=\frac{(i \xi)(i \eta)^{2}}{a(a+|\xi|)} \tilde{\varphi}_{2}(0, \eta) \cdot \int_{0}^{t} e^{(\operatorname{sign} \varepsilon \cdot a-\xi) s i} d s \in L^{2}\left(R^{2}\right) . \tag{2.7}
\end{equation*}
$$

If we put $l(t, \eta)=2\left(\eta^{2} t^{2}-\pi^{2} / 16\right) / \pi t$, then for $|\xi| \geqq l(t, \eta)$

$$
\begin{equation*}
\left|\int_{0}^{t} e^{(s \operatorname{sign} \xi \cdot a-\xi) s i} d s\right| \geqq \frac{t}{\sqrt{2}} \tag{2.8}
\end{equation*}
$$

Hence it follows

$$
\int_{R^{1}} \frac{\xi^{2}}{a^{2}(a+|\xi|)^{2}}\left|\int_{0}^{t} e^{(\mathrm{sign} \xi \cdot a-\xi) s i} d s\right|^{2} d \xi \geqq \frac{c t^{2}}{\sqrt{l^{2}+t^{2}}}
$$

where $c=1 / 16 \int_{0}^{\infty} t^{2}\left(1+t^{2}\right)^{-2} d t$. Therefore if we take $\varphi_{2}(x, y)$ as $\varphi_{2}(0, y)$ $\notin H^{1}\left(R^{1}\right)$, then $\tilde{F}(t, \xi, \eta)$ does not belong to $L^{2}\left(R^{2}\right)$ for any $t>0$. This is a contradiction. Thus Theorem 1 is proved in the case $m=1$. For general $m$ we can prove by induction.
§3. Proof of Theorem 2. We can prove as in [2] that this mixed problem has a finite propagation speed. Thus by the local transformation we can reduce to the case

$$
\Omega=R_{+}^{n}=\left\{\left(x_{1}, \cdots, x_{n}\right) ;\left(x_{1}, \cdots, x_{n-1}\right) \in R^{n-1}, x_{n}>0\right\} .
$$

Moreover, applying an appropriate transformation of unknown functions, we have only to consider the following fairly simple mixed problem

where (A.1) $A_{i}(i=1, \cdots, n)$ are $N \times N$ Hermitian matrices and $A_{n}$
$=\left[\begin{array}{cc}\tilde{A}_{n} & 0 \\ 0 & 0\end{array}\right]$ where $\tilde{A}_{n}$ is an $r \times r$ non-singular matrix, (A.2) $P=\left[E_{l} O\right]$ is an $l \times N$ matrix where $E_{l}$ is an $l \times l$ unit matrix, (A.3) $\operatorname{Ker} P$ is maximally non-positive for $L(t)$. We remark that (A.3) assures $l \leqq r$. Here we treat the mixed problem (M) when $L(t)$ is independent of $t$. When $L(t)$ depends on $t$, we can prove Theorem 2 by using energy inequalities and Cauchy's polygonal line as in [2]. Using Theorem 3.2 of LaxPhillips [1], we see that $L$ generates a semi-group $T(t)$ in $L^{2}\left(R_{+}^{n}\right)$, from which the $L^{2}$-well posedness is proved. We pass to the problem of regularity. Let us put $v_{1}={ }^{t}\left(u_{1}, \cdots, u_{r}\right), v_{2}={ }^{t}\left(u_{r+1}, \cdots, u_{N}\right), g_{1}={ }^{t}\left(f_{1}, \cdots\right.$, $f_{r}$ ) and $g_{2}={ }^{t}\left(f_{r+1}, \cdots, f_{N}\right)$, then there exist first order differential operators $L_{i j}(i, j=1,2)$ such that

$$
\begin{equation*}
\partial v_{i} / \partial t=L_{i 1} v_{1}+L_{i 2} v_{2}+g_{i}, \quad i=1,2 \tag{3.4}
\end{equation*}
$$

We see from (A.1) that $L_{12}, L_{21}$ and $L_{22}$ don't contain the derivative with respect to $x_{n}$. First we consider the case $m=1$. Then the solution $u(t, x)$ is given by

$$
u(t, x)=T(t) \varphi+\int_{0}^{t} T(t-s) f(s) d s
$$

which is in $\mathcal{E}_{t}^{1}\left(L^{2}\right) \cap \mathcal{E}_{t}^{0}(\mathscr{D}(L))$. Let us put $U(t, x)={ }^{t}{ }^{t} u,{ }^{t} \partial u / \partial t,{ }^{t} \partial u / \partial x_{1}$, $\left.\cdots, t \partial u / \partial x_{n-1}\right)$, then $U(t, x)$ satisfies

$$
\left\{\begin{array}{l}
\partial U / \partial t=\tilde{L} U+F(t, x)  \tag{3.5}\\
U(0, x)=\Phi(x) \\
\left.\tilde{P} U\right|_{x_{n}=0}=0
\end{array}\right.
$$

where

$$
\begin{gathered}
\tilde{L}=\left[\begin{array}{lll}
L & & \\
& \ddots & \\
& & L
\end{array}\right]+\text { lower order, } \quad \tilde{P}=\left[\begin{array}{l}
P \\
\\
\\
\\
\\
\\
\\
\\
\\
\\
\\
\hline(x)={ }^{t}\left({ }^{t} \varphi,{ }^{t}(L \varphi+f(0)), \frac{{ }^{t} \partial \varphi}{\partial x_{1}}, \cdots, \frac{{ }^{t} \partial \varphi}{\partial x_{n-1}}\right)
\end{array}, ~\right.
\end{gathered}
$$

and

$$
\begin{aligned}
\boldsymbol{F}(t, x)={ }^{t}\left({ }^{t} f, \frac{{ }^{t} \partial f}{\partial t},\right. & \left(\frac{\partial f}{\partial x_{1}}-\frac{\partial A_{n}}{\partial x_{1}}\left[\begin{array}{cc}
\tilde{A}_{n}^{-1} & 0 \\
0 & 0
\end{array}\right] f\right), \\
& \left.\cdots,{ }^{t}\left(\frac{\partial f}{\partial x_{n-1}}-\frac{\partial A_{n}}{\partial x_{n-1}}\left[\begin{array}{cc}
\tilde{A}_{n}^{-1} & 0 \\
0 & 0
\end{array}\right] f\right)\right) .
\end{aligned}
$$

As $\Phi(x) \in L^{2}\left(R_{+}^{n}\right)$ and $F(t, x) \in \mathcal{E}_{t}^{0}\left(L^{2}\right)$, we see from (3.5) that $U(t, x)$ is in $\mathcal{E}_{t}^{0}\left(L^{2}\right)$. Therefore it follows from (3.4) that $\partial v_{1} / \partial x_{1}$ is in $\mathcal{E}_{t}^{0}\left(L^{2}\right)$. Hence $v_{1}(t, x)$ is in $\mathcal{E}_{t}^{0}\left(H^{1}\right)$.

Next we pass to the case $m=2$. Since in (3.5) $\Phi(x) \in H^{1}\left(R_{+}^{n}\right)$ and $\boldsymbol{F}(t, x) \in \mathcal{E}_{t}^{0}\left(H^{1}\right) \cap \mathcal{E}_{t}^{1}\left(L^{2}\right)$, we can apply the result obtained now to (3.5). Therefore, if we put $V_{i}={ }^{t}\left(v_{i},{ }^{t} \partial v_{i} / \partial t,{ }^{t} \partial v_{i} / \partial x_{1}, \cdots,{ }^{t} \partial v_{i} / \partial x_{n-1}\right)(i=1,2)$, $V_{1}(t, x)$ is in $\mathcal{E}_{t}^{1}\left(L^{2}\right) \cap \mathcal{E}_{t}^{0}\left(H^{1}\right)$. Hence in (3.5) $L_{21} v_{1}+g_{2}$ is in $\mathcal{E}_{t}^{1}\left(L^{2}\right) \cap \mathcal{E}_{t}^{0}\left(H^{1}\right)$. Since $v_{2}$ is free of boundary condition and $L_{22}$ generates a semi-group in $L^{2}\left(R_{+}^{n}\right), v_{2}(t, x)$ is also in $\mathcal{E}_{t}^{1}\left(L^{2}\right) \cap \mathcal{E}_{t}^{0}\left(H^{1}\right)$, which implies the required
result in the case $m=2$. For general $m$ we can prove this theorem by induction. The method used here is essentially the same as in [2].

The detailed proof will be given in a forthcoming paper.

## References

[1] P. D. Lax and R. S. Phillips: Local boundary conditions for dissipative symmetric linear differential operators. Comm. Pure Appl. Math., 13, 427-456 (1960).
[2] M. Tsuji: Analyticity of solutions of hyperbolic mixed problems (to appear).


[^0]:    1) $\mathcal{E}_{t}^{k}(E)$ is the set of $E$-valued functions of $t$ which are $k$-times continuously differentiable.
