# 47. Complex Hypersurfaces with Vanishing Bochner Curvature Tensor 

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1. Introduction. The purpose of this paper is to show the following :

Theorem. Let $M$ be a complex hypersurface of complex dimension $n(n \geqq 2)$ in a space of constant holomorphic sectional curvature $\tilde{c}$. If the Bochner curvature tensor of $M$ vanishes identically, then $M$ is of constant holomorphic sectional curvature $\tilde{c}$.
2. Preliminaries. Let $(\tilde{M}, J, g)$ be a Kaehlerian manifold of constant holomorphic sectional curvature $\tilde{c}$ of complex dimension $n+1$ ( $n \geqq 2$ ). Then the curvature tensor $\tilde{R}$ of $\tilde{M}$ is given by

$$
\begin{align*}
\tilde{R}(\tilde{X}, \tilde{Y}) \tilde{W} & =\frac{\tilde{c}}{4}\{g(\tilde{Y}, \tilde{W}) \tilde{X}-g(\tilde{X}, \tilde{W}) \tilde{Y}+g(J \tilde{Y}, \tilde{W}) J \tilde{X}  \tag{1}\\
& -g(J \tilde{X}, \tilde{W}) J \tilde{Y}+2 g(\tilde{X}, J \tilde{Y}) J \tilde{W}\},
\end{align*}
$$

where $\tilde{X}, \tilde{Y}$ and $\tilde{W}$ are vector fields on $\tilde{M}$. Let $M$ be a complex hypersurface of $\tilde{M}$ immersed by $\varphi: M \rightarrow \tilde{M}$ and $\xi$ a local field of unit vectors normal to $M$. Then, identifying, for each $x \in M$, the tangent space $T_{x}(M)$ with $\varphi_{*}\left(T_{x}(M) \subset T_{\varphi(x)}(\tilde{M})\right.$ by means of $\varphi_{*}$, we may put

$$
\begin{equation*}
\tilde{\nabla}_{X} \xi=-A X+s(X) J \xi \tag{2}
\end{equation*}
$$

$$
\begin{equation*}
\tilde{\nabla}_{X} Y=\nabla_{X} Y+h(X, Y) \xi+k(X, Y) J \xi \tag{3}
\end{equation*}
$$

where $\tilde{\nabla}$ denotes the covariant differentiation with respect to $g, X$ and $Y$ are vector fields in $M$ and $-A X$ (resp. $\nabla_{X} Y$ ) is the tangential part of $\tilde{V}_{X} \xi$ (resp. $\tilde{V}_{X} Y$ ). It is well known that the naturally induced metric is the Kaehlerian metric and the almost complex structure is the Kaehlerian structure on $M$. We denote them also by $g$ and $J$ respectively. Then the relations $h(X, Y)=g(A X, Y), k(X, Y)=g(J A X, Y)$ and $J A=-A J$ hold (for details, see [3]). The curvature tensor $R$ and the Ricci tensor $S$ of $M$ are given by

$$
\begin{gather*}
R(X, Y)=\tilde{R}(X, Y)+A X \wedge A Y+J A X \wedge J A Y  \tag{4}\\
S(X, Y)=-2 g\left(A^{2} X, Y\right)+\frac{n+1}{2} \tilde{c} g(X, Y) \tag{5}
\end{gather*}
$$

where $X \wedge Y$ is the endomorphism defined by $(X \wedge Y)(Z)=g(Z, Y) X$ $-g(X, Z) Y$. The Bochner curvature tensor $B$ of $M$ is, by definition, given by

$$
\begin{align*}
B(X, Y)= & R(X, Y)-\frac{1}{2 n+4}\left[R^{1} X \wedge Y+X \wedge R^{1} Y+R^{1} J X \wedge J Y\right. \\
& \left.+J X \wedge R^{1} J Y-2 g\left(J X, R^{1} Y\right) J-2 g(J X, Y) R^{1} \circ J\right] \\
& +\frac{\operatorname{trace} R^{1}}{(2 n+4)(2 n+2)}[X \wedge Y+J X \wedge J Y-2 g(J X, Y) J]
\end{align*}
$$

where $g\left(R^{1} X, Y\right)=S(X, Y)$. We assume the Bochner curvature tensor $B=0$. Then we have, from (6),

$$
\begin{align*}
R(X, Y) W= & \frac{1}{2 n+4}\left\{g(W, Y) R^{1} X-g\left(R^{1} X, W\right) Y+g\left(W, R^{1} Y\right) X\right. \\
& -g(X, W) R^{1} Y+g(W, J Y) R^{1} J X-g\left(R^{1} J X, W\right) J Y \\
& +g\left(W, R^{1} J Y\right) J X-g(J X, W) R^{1} J Y-2 g\left(J X, R^{1} Y\right) J W  \tag{7}\\
& \left.-2 g(J X, Y) R^{1} J W\right\}-\frac{\operatorname{trace} R^{1}}{(2 n+4)(2 n+2)} \\
& \{g(W, Y) X-g(X, W) Y+g(W, J Y) J X \\
& -g(J X, W) J Y-2 g(J X, Y) J W\} .
\end{align*}
$$

Substituting (1) and (7) into (4), we have

$$
\begin{aligned}
\frac{1}{2 n+4} & \left\{g(W, Y) R^{1} X-g\left(R^{1} X, W\right) Y+g\left(W, R^{1} Y\right) X-g(X, W) R^{1} Y\right. \\
& +g(W, J Y) R^{1} J X-g\left(R^{1} J X, W\right) J Y+g\left(W, R^{1} J Y\right) J X \\
& -g(J X, W) R^{1} J Y-2 g\left(J X, R^{1} Y\right) J W-2 g(J X, Y) R^{1} J W \\
& -\frac{\operatorname{trace} R^{1}}{(2 n+4)(2 n+2)}\{g(W, Y) X-g(X, W) Y+g(W, J Y) J X \\
& -g(J X, W) J Y-2 g(J X, Y) J W\} \\
= & \frac{\tilde{c}}{4}\{g(Y, W) X-g(X, W) Y+g(J Y, W) J X-g(J X, W) J Y \\
& +2 g(X, J Y) J W\}+g(A Y, W) A X-g(A X, W) A Y \\
& +g(J A Y, W) J A X-g(J A X, W) J A Y .
\end{aligned}
$$

Substituting $R^{1} X=-2 A^{2} X+\frac{n+1}{2} \tilde{c} X$ into (8), we have, after simplification,

$$
\begin{align*}
\left(\frac{\tilde{c}}{4}+\right. & \left.\frac{\operatorname{trace} R^{1}}{(2 n+4)(2 n+2)}-\frac{n+1}{2 n+4} \tilde{c}\right)\{g(Y, W) X-g(X, W) Y \\
& +g(J Y, W) J X-g(J X, W) J Y+2 g(X, J Y) J W\} \\
= & \frac{1}{2 n+4}\left\{-2 g(W, Y) A^{2} X+2 g\left(A^{2} X, W\right) Y-2 g\left(W, A^{2} Y\right) X\right.  \tag{9}\\
& +2 g(X, W) A^{2} Y-2 g(W, J Y) A^{2} J X+2 g\left(A^{2} J X, W\right) J Y \\
& -2 g\left(W, A^{2} J Y\right) J X+2 g(J X, W) A^{2} J Y+4 g\left(J X, A^{2} Y\right) J W \\
& \left.+4 g(J X, Y) A^{2} J W\right\}-g(A Y, W) A X+g(A X, W) A Y \\
& -g(J A Y, W) J A X+g(J A X, W) J A Y .
\end{align*}
$$

3. Proof of Theorem. We take an orthonormal basis $\left\{e_{1}, \cdots, e_{n}\right.$, $\left.J e_{1}, \cdots, J e_{n}\right\}$ of $T_{x}(M)$ such that $A e_{i}=\lambda_{i} e_{i}, A J e_{i}=-\lambda_{i} J e_{i}, g\left(J e_{i}, e_{j}\right)=0$ $(i, j=1, \cdots, n)$ and $0 \leqq \lambda_{1} \leqq \cdots \leqq \lambda_{n}$. Then, since trace $R^{1}=-2$ trace $A^{2}$
$+(n+1) n \tilde{c}$, (9) reduces to

$$
-\frac{\operatorname{trace} A^{2}}{2(n+1)(n+2)}\{g(Y, W) X-g(X, W) Y+g(J Y, W) J X
$$

$$
-g(J X, W) J Y+2 g(X, J Y) J W\}
$$

$$
\begin{align*}
= & \frac{1}{2 n+4}\left\{-2 g(W, Y) A^{2} X+2 g\left(A^{2} X, W\right) Y-2 g\left(W, A^{2} Y\right) X\right.  \tag{10}\\
& +2 g(X, W) A^{2} Y-2 g(W, J Y) A^{2} J X+2 g\left(A^{2} J X, W\right) J Y \\
& -2 g\left(W, A^{2} J Y\right) J X+2 g(J X, W) A^{2} J Y+4 g\left(J X, A^{2} Y\right) J W \\
& \left.+4 g(J X, Y) A^{2} J W\right\}-g(A Y, W) A X+g(A X, W) A Y \\
& -g(J A Y, W) J A X+g(J A X, W) J A Y .
\end{align*}
$$

Putting $X=e_{i}, Y=e_{j}, W=e_{k}$ in (10), we have

$$
\begin{aligned}
& -\frac{\operatorname{trace} A^{2}}{2(n+1)(n+2)}\left(\delta_{j k} e_{i}-\delta_{i k} e_{j}\right) \\
& \quad=\frac{1}{2 n+4}\left(-2 \delta_{j k} \lambda_{i}^{2} e_{i}+2 \delta_{i k} \lambda_{i}^{2} e_{j}-2 \delta_{k j} \lambda_{j}^{2} e_{i}+2 \delta_{i k} \lambda_{j}^{2} e_{j}\right) \\
& \quad-\lambda_{i} \lambda_{j} \delta_{j k} e_{i}+\lambda_{i} \lambda_{j} \delta_{i k} e_{j}
\end{aligned}
$$

Setting $j=k \neq i$, we have

$$
\begin{equation*}
\frac{\operatorname{trace} A^{2}}{2(n+1)(n+2)}=\frac{1}{n+2}\left(\lambda_{i}^{2}+\lambda_{j}^{2}\right)+\lambda_{i} \lambda_{j} \quad(i \neq j) \tag{11}
\end{equation*}
$$

from which we have

$$
\left(\lambda_{k}-\lambda_{j}\right)\left\{\lambda_{k}+\lambda_{j}+(n+2) \lambda_{i}\right\}=0 \quad(n \geqq 3)
$$

(for distinct $i, j$ and $k$ ).
Therefore the rank $A$ must be $0,2 n-2$ or $2 n$. But, if the rank $A \neq 0$, then the non-zero $\lambda_{i}$ 's must be equal to, say, $\lambda$, because of $0 \leqq \lambda_{1} \leqq \cdots$ $\leqq \lambda_{n}$. Hence, again by (11), we have

$$
\begin{aligned}
& \frac{n \lambda^{2}}{(n+1)(n+2)}=\frac{2 \lambda^{2}}{n+2}+\lambda^{2} \\
& \quad \text { (if the rank } A=2 n), \\
& \left\{\begin{array}{l}
\frac{(n-1) \lambda^{2}}{(n+1)(n+2)}=\frac{2 \lambda^{2}}{n+2}+\lambda^{2} \\
\frac{(n-1) \lambda^{2}}{(n+1)(n+2)}=\frac{\lambda^{2}}{n+2}
\end{array}\right.
\end{aligned}
$$

(if the rank $A=2 n-2$ ),
from which we have $\lambda=0$ in both cases. Hence $M$ is totally geodesic. Thus $M$ is of constant holomorphic sectional curvature $\tilde{c}$. If $n=2$, then we have, from (11),

$$
\frac{\lambda_{1}^{2}+\lambda_{2}^{2}}{12}=\frac{1}{4}\left(\lambda_{1}^{2}+\lambda_{2}^{2}\right)+\lambda_{1} \lambda_{2}
$$

from which we have $\lambda_{1}=\lambda_{2}=0$. Hence $M$ is of constant holomorphic sectional curvature $\tilde{c}$, which completes the proof.

## References

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[2] H. Takagi and Y. Watanabe: Kählerian manifolds with vanishing Bochner curvature tensor satisfying $R(X, Y) \cdot R=0$. Hokkaido Math. Jour. Vol. III, 129-132 (1974).
[3] B. Smyth: Differential geometry of complex hypersurfaces. Ann. of Math., 85, 246-266 (1967).

