## PAPERS COMMUNICATED

## 51. On the Geometry in Microscopic and Macroscopic Space.

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In the present paper I intend to construct a new geometry which will have its foundation on the proper qualities of geometry, and which, based on the common and actual physical demonstrations and observations, will express pure-mathematically the relations between the physical realities. Consequently, I have decided to give up the conventional and ordinary method of deriving the microscopic space from the macroscopic, and, reversing the process, to explain the macroscopic from the microscopic, the metrical conception of the latter being defined by the physical phenomena. I will now develop the theory of kinematic connections, ${ }^{1)}$ which seems to me quite natural to establish a unified field theory.

Consider the set of matrices $E_{\lambda}(\lambda=1,2,3,4,5)$ :

$$
\begin{array}{ll}
E_{1}=\left(\begin{array}{llll}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0
\end{array}\right) \quad E_{2}=\left(\begin{array}{llll}
0 & 0 & 0 & -i \\
0 & 0 & -i & 0 \\
0 & i & 0 & 0 \\
i & 0 & 0 & 0
\end{array}\right) \quad E_{3}=\left(\begin{array}{llll}
0 & 0 & 0 & 1 \\
0 & 0 & -1 & 0 \\
0 & -1 & 0 & 0 \\
1 & 0 & 0 & 0
\end{array}\right) \\
E_{4}=\left(\begin{array}{llll}
0 & 0 & -i & 0 \\
0 & 0 & 0 & i \\
i & 0 & 0 & 0 \\
0 & -i & 0 & 0
\end{array}\right) \quad E_{5}=\left(\begin{array}{llll}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & -1 & 0 \\
0 & 0 & 0 & -1
\end{array}\right) .
\end{array}
$$

Then we get

$$
\begin{equation*}
\frac{1}{2}\left(E_{\lambda} E_{\mu}+E_{\mu} E_{\lambda}\right)=\delta_{\lambda}^{\mu}, \tag{1}
\end{equation*}
$$

where the $\delta_{\lambda}^{\mu}$ denotes Kronecker's delta. Let us now consider the five independent real variables $x^{1}, x^{2}, x^{3}, x^{4}, x^{5}$ of which at least one is not zero. Also suppose that we have twenty-five real functions $p_{\mu}^{\cdot \lambda}$ of the variables, and, let $q_{\rho \mu}^{\lambda}$ be defined by equations
(2)

$$
p_{\nu}^{\cdot \lambda} q_{\cdot \lambda}^{\mu}=\delta_{\nu}^{\nu} .
$$

We now define the matrices $\alpha_{\lambda}$ and $\alpha^{\mu}$, by the following equations:

$$
\begin{equation*}
\alpha_{\lambda}=p_{\lambda}^{\cdot \mu} E_{\mu}, \quad \alpha^{\mu}=q_{\cdot \lambda}^{\mu} E^{\lambda} \quad(\lambda, \mu=1,2,3,4,5), \tag{3}
\end{equation*}
$$

where $E^{\lambda}=E_{\lambda}$. From (1), we have

$$
\begin{equation*}
\alpha_{(\lambda} \alpha_{\mu)}=\sum_{\omega=1}^{5} p_{\lambda}^{* \omega} p_{\mu}^{\omega \omega}, \tag{4}
\end{equation*}
$$

and

[^0]$$
\left.a^{(\lambda} \alpha^{\mu}\right)=\sum_{w=1}^{5} q_{\omega w}^{\lambda} q_{w}^{\mu},
$$
where
$$
\left.\alpha_{(\lambda} \alpha_{\mu}=\frac{1}{2}\left(\alpha_{\lambda} \alpha_{\mu}+\alpha_{\mu} \alpha_{\lambda}\right) \quad \text { and } \quad \alpha^{(\lambda} \alpha^{\mu}\right)=\frac{1}{2}\left(\alpha^{\lambda} \alpha^{\mu}+\alpha^{\mu} \alpha^{\lambda}\right) .
$$

From (3), we get

$$
\begin{equation*}
\left.\left(\alpha^{(\lambda} \alpha^{\mu)}\right)\left(\alpha_{(\lambda} \alpha_{\nu}\right)\right)=\delta_{\nu}^{\mu} \tag{5}
\end{equation*}
$$

In particular we put
(6) $\quad p_{i}^{.5}=0, \quad p_{5}^{.5}=1, \quad p_{5}^{* i}=\phi^{i}, \quad q_{55}^{i}=\varphi^{i},^{1)}$
then we obtain

$$
\begin{cases}\alpha_{i}=p_{i}^{j} E_{j}, & \alpha_{5}=\phi^{j} E_{j}+E_{5}  \tag{7}\\ \alpha_{i}=q_{. j}^{i} E^{j}+\varphi^{i} E_{5}, & \alpha^{5}=E^{5}\end{cases}
$$

and

As the kinematic transformation, we now consider the following equations:

$$
\left\{\begin{array}{l}
\overline{x^{5}}=x^{5}  \tag{9}\\
\bar{x}^{i}=\bar{x}^{i}\left(x^{1}, x^{2}, x^{3}, x^{4}, x^{5}\right)
\end{array}\right.
$$

We can now consider the special one of (9)

$$
\begin{equation*}
d \bar{x}^{\nu}=A_{\lambda}^{\nu} d x^{\lambda}, \quad A_{\lambda}^{\nu}=\frac{\partial \bar{x}^{\nu}}{\partial x^{\lambda}}, \tag{10}
\end{equation*}
$$

which satisfies the following conditions: if for the transformation (10), we put

$$
\begin{equation*}
\bar{\alpha}^{\mu}=A_{\lambda}^{\mu} \alpha^{\lambda}, \quad \alpha_{\nu}=A_{\nu}^{\mu} \bar{\alpha}_{\mu} \tag{11}
\end{equation*}
$$

then there exists a matrix $S$, which will satisfy the following equations:

$$
\begin{equation*}
S^{-1} \alpha^{\mu} S=A_{\nu}^{\nu} \alpha^{\nu}, \quad A_{\nu}^{\nu} S^{-1} \alpha_{\mu} S=\alpha_{\nu} . \tag{12}
\end{equation*}
$$

An infinitesimal transformation of (10) is defined by the equations:

$$
\begin{equation*}
\bar{x}^{\mu}=x^{\mu}+\eta^{\mu} \delta t ; \tag{13}
\end{equation*}
$$

then we get

$$
\begin{equation*}
\bar{\alpha}_{\mu}=\alpha_{\mu}+\varepsilon^{\rho} \xi_{\mu \rho}, \quad S=1+\varepsilon^{p} \Gamma_{\rho} . \tag{14}
\end{equation*}
$$

Accordingly, we obtain

$$
\begin{equation*}
\xi_{\mu \rho}=-\Gamma_{\rho} \alpha_{\mu}+\alpha_{\mu} \Gamma_{\rho} \tag{15}
\end{equation*}
$$

From (14) and (15), we have

$$
\begin{equation*}
\bar{\alpha}_{\mu}=\alpha_{\mu}+\varepsilon^{\rho}\left(-\Gamma_{\mathrm{p}} \alpha_{\mu}+\alpha_{\mu} \Gamma_{\mathrm{p}}\right) . \tag{16}
\end{equation*}
$$

Let us now introduce the functions $\Gamma_{\mu \nu}^{\lambda}$ satisfying the following equations:

1) Let us make the convention that Greek indices run over the range $1,2,3,4,5$, whereas the Latin indices take the values $1,2,3,4$ only.

$$
\begin{equation*}
\frac{\partial \alpha_{\mu}}{\partial x^{\rho}}-\Gamma_{\mu \nu}^{s} \alpha_{\sigma}+\Gamma_{\rho} \alpha_{\mu}-\alpha_{\mu} \Gamma_{\mathrm{p}}=0 . \tag{17}
\end{equation*}
$$

Putting

$$
\begin{equation*}
\alpha_{\mu ; p} \equiv \frac{\partial \alpha_{\mu}}{\partial x^{p}}-\Gamma_{\mu p}^{o} \alpha_{\sigma}+\Gamma_{\rho} \alpha_{\mu}-\alpha_{\mu} \Gamma_{p}, \tag{18}
\end{equation*}
$$

we will call $\Gamma_{\mu \nu}^{\lambda}$ and $\Gamma_{\lambda}$ the parameters of the covariant differentiation in macroscopic and microscopic space respectively.

Let us now consider the generalized Dirac's equation:

$$
\begin{equation*}
\alpha^{\mu} \psi_{j \downarrow}+N \psi=0, \tag{19}
\end{equation*}
$$

where $N$ is an arbitrary function. Using the solutions $\psi$ satisfying (19), we will introduce the equations:

$$
\begin{equation*}
a_{i} d x^{i} \psi=d s \psi, \tag{20}
\end{equation*}
$$

which define the metrics $d s \psi$ in the microscopic space. ${ }^{1)}$
By repeating the operator of the left hand side of (20), we have

$$
\left.\alpha_{(i} \alpha_{j}\right) d x^{i} d x^{j} \psi=d s^{2} \psi .
$$

We will now assume that the equation will be satisfied by any $\psi$. Then we have

$$
\begin{equation*}
g_{i j} d x^{i} d x^{j}=d s^{2}, \tag{21}
\end{equation*}
$$

where

$$
g_{i j}=\alpha_{i i} \alpha_{j)}
$$

We will consider that $g_{i j}$ define the gravitational potentials in the macroscopic space. Consequently we see that the metrics of the macroscopic space is defined by assuming the matrices $E_{\lambda}$ and $a_{i}$.

Also any ordered set of five independent real variables $x^{\lambda}$ which have defined the function $\psi$ may be thought of as homogeneous coordinates of a point in four dimensional manifold. Accordingly, the transformation (9) can be regarded as the kinematic one studied by the present author. ${ }^{2)}$

[^1]
[^0]:    1) T. Hosokawa: Kinematic Connections and their Application to Physics, Proc. 10 (1934), 49-52.
[^1]:    1) Y. Mimura: Relativistic Quantum Mechanics and Wave Geometry, Jour. of Science of the Hiroshima University, series A, 5 (1935), p. 102.
    2) T. Hosokawa: loc. cit., p. 49.
