# 70. On the Theory of Hypersurfaces in the Path-space of the Third Order. 

By Yasuro Tomonaga.
Mathematical Institute, Tokyo Imperial University.
(Comm. by S. Kakeya, m.i.A., July, 12, 1943.)
§0. The theory of path-space of the third order has been developed by Prof. H. Hombu ${ }^{1)}$. In the present note, we shall deal with the theory of hypersurfaces in such a space. In an $n$-dimensional manifold $V_{n}$ referred to a coordinate system $x^{\lambda}(\lambda=1,2, \ldots, n)$, let us consider a system of paths, defined by the differential equations of the third order,

$$
\begin{equation*}
T^{\lambda}=x^{(3) \lambda}+H^{\lambda}\left(x, x^{(1)}, x^{(2)}\right)=0 . \tag{0.1}
\end{equation*}
$$

In order that our system of paths admits of projective parameters, it is necessary that
(a) $H_{(1)}^{\lambda} x^{(1) \nu}+2 H_{(2)}^{\lambda} x^{(2) \nu}=3 H^{\lambda}$,
(b) $H_{(2)}^{\lambda}, x^{(1) \nu}=-3 x^{(2) \lambda}$.

The base connections of our $V_{n}$ are defined by
(a) $\delta x^{(1) \lambda}=d x^{(1) \lambda}+\frac{1}{3} H_{(2) \nu}^{(\lambda)} d x^{\nu}$,
(b) $\delta x^{(2) \lambda}=d x^{(2) \lambda}+\frac{2}{3} H_{(2) \nu}^{(\lambda)} d x^{(1) \nu}+\frac{1}{3} H_{(1) \nu}^{\lambda} d x^{\nu}$.

We see that $\frac{\delta x^{(1) \lambda}}{d t}=0$ (along any curve) and $\frac{\delta x^{(2) \lambda}}{d t}=0$ (along paths).

The covariant derivative of a vector $v^{\lambda}$ in $V_{n}$ is given by

$$
\begin{equation*}
\dot{\partial} v^{2}=d v^{2}+w_{\mu}^{2} v^{\mu}, \tag{0.4}
\end{equation*}
$$

(a) ${\underset{(0)}{\Gamma_{\mu \nu}^{\lambda}}=\frac{1}{3} H_{(2) \mu(1) \nu}^{\lambda}-\frac{2}{9} H_{(2) \mu(2) \sigma}^{\lambda} H_{(2) \nu}^{\sigma},}^{\sigma}$
(b) $\underset{(1)^{\prime}}{\stackrel{*}{\mu_{\nu}}}=\frac{2}{3} H_{(2) \mu(2) \nu}^{\lambda}$.

The equation (0.4) can be also written as follows:

$$
\delta v^{\lambda}=\Gamma_{\nu}^{(0)} v^{\lambda} \cdot d x^{\nu}+\nabla_{\nu}^{(1)} v^{\lambda} \cdot \delta x^{(1) \nu}+\nabla_{\nu}^{(2)} v^{\lambda} \cdot \delta x^{(2) \nu},
$$

where

$$
\begin{equation*}
\nabla_{\nu}^{(0)} v^{\lambda}=\bar{\Gamma}_{\nu}^{(0)} v^{\lambda}+\stackrel{\Gamma_{(0)}^{\lambda}}{*} v^{\mu}, \quad \nabla_{\nu}^{(1)} v^{\lambda}=\bar{\Gamma}_{\nu}^{(1)} v^{\lambda}+{\underset{(1)}{\mu}}_{*}^{*} v^{\mu}, \quad \nabla_{\nu}^{(2)} v^{\lambda}=\bar{\nabla}_{\nu}^{(2)} v^{\lambda}, \tag{0.6}
\end{equation*}
$$

1) H. Hombu: Projektive Transformation eines Systems der gewöhnlichen Differentialgleichungen dritter Ordnung. Proc. 13 (1937), 187-190, Die projektive Theorie der "paths" 3-ter Ordnung. Proc. 14 (1938), 36-40.
(a) $\left.\bar{\nabla}_{\nu}^{(0)}=\frac{\partial}{\partial x^{\nu}}-\frac{1}{3} H_{(2) \nu}^{\mu} \frac{0}{\partial x^{(1) \mu}}-\left(\frac{1}{3} H_{(1) \nu}^{\mu}-\frac{2}{9} H_{(2),}^{\mu} H_{(2) \nu}^{( }\right)\right) \frac{\partial}{\partial x^{(2) \mu}}$,
(b) $\quad \bar{\nu}_{\nu}^{(1)}=\frac{\partial}{\partial x^{(1) \nu}}-\frac{2}{3} H_{(2) \nu}^{\mu} \frac{\partial}{\partial x^{(2) \mu}}$,
(c) $\overline{\bar{\Gamma}}_{\nu}^{(2)}=\frac{\partial}{\partial x^{(2) \nu}}$.

Then, the curvature and torsion tensors of our $V_{\boldsymbol{n}}$ are given by


$$
\begin{aligned}
& +R_{\mu \sigma \pi}^{\lambda(0)(1)}\left[d_{1}^{\sigma} \delta x_{2}^{(1) \pi}\right]+R_{\mu \sigma \pi}^{\lambda(0) 2}\left[d x_{2}^{\sigma} \delta x^{(2) \pi}\right]
\end{aligned}
$$

where




(e) $R_{\mu \sigma \pi}^{\lambda(\alpha)(2)}=\bar{\Gamma}_{\pi}^{(2)} \stackrel{*}{\left.i_{1}\right)_{\sigma}^{\prime}}$,
and

(b) ${ }_{21}^{\delta \delta x^{(1) \lambda}}-{ }_{12}^{\delta \delta x^{(1) \lambda}}=S_{\mu \sigma(1)}^{(0)(0) \lambda}{ }_{1}^{\left(x^{\mu}\right.} d x^{\sigma}+S_{\mu(1)}^{(0)(2)}\left[d x_{1}^{\mu} x_{2}^{(2) \sigma}\right]$

$$
+S_{\mu_{\sigma}(1)}^{(1)(1)}\left[d x_{2}^{\mu} \delta x^{(1) \rho}\right],
$$


$+S_{\mu(2)}^{(0)(2)}\left[d_{1} x_{2}^{\mu} \delta x^{(1) \rho}\right]$,
where
(0.11)
(a) $S_{\mu_{0}(0)}^{(0)(0) \lambda}=\stackrel{*}{\Gamma_{(0)}} \stackrel{*}{\mu \sigma}-\stackrel{*}{(0)}{ }_{(0)}{ }^{\wedge}$,
(b) $S_{\mu \sigma(0)}^{(0)(1) \lambda}=\stackrel{*}{\Gamma_{(1)} \lambda} \lambda$,
(c) $S_{\mu(1))}^{(0)(0) \lambda}=\frac{1}{3} \bar{\nabla}_{\dot{\sigma}}^{(0)} H_{(2) \mu}^{\lambda}-\frac{1}{3} \bar{\nabla}_{\mu}^{(0)} H_{(2),}^{\lambda}$,

(e) $S_{\mu(2)}^{(0)(0) \lambda}=\frac{1}{3} \bar{\Gamma}_{\sigma}^{(0)} H_{(1) \mu}^{\lambda}-\frac{2}{9} H_{(2) \sigma}^{\pi} \bar{\nabla}_{\mu}^{(0)} H_{(2) \pi}^{\lambda}-\frac{1}{3} \bar{F}_{\mu}^{(0)} H_{(1) \sigma}^{\lambda}$

$$
+\frac{2}{9} H_{(2), \mu}^{\pi} \bar{r}_{4}^{(2)} H_{(2) \pi}^{\lambda},
$$

(f) $S_{\mu \sigma(2)}^{(1)(1) \lambda}=S_{\mu(0)}^{(0)(0) \lambda}$,
(g) $S_{\left.\mu_{\sigma}(2)\right)}^{(0)(1) \lambda}=\frac{1}{3} \bar{\nabla}_{\sigma}^{(1)} H_{(1) \mu}^{\lambda}-\frac{2}{3} \bar{\nabla}_{\mu}^{(0)} H_{(2) \sigma}^{\lambda}-\frac{2}{9} H_{(2) \mu}^{\tau} \overline{\bar{F}}_{\sigma}^{(1)} H_{(2) \tau}^{\lambda}$,
(h) $S_{\mu(1)}^{(0)(1) i}=S_{\mu(0)}^{(00 X(0) \lambda}$.
§1. Let us consider a hypersurface $V_{n-1}$ immersed in the $V_{n}$ whose parametric representation is

$$
x^{\lambda}=x^{\lambda}\left(y^{\mathbf{i}}, y^{\dot{2}}, \ldots, y^{\dot{n}-\mathbf{i}}\right)
$$

In our $V_{n-1}$, we take a system of paths with projective parameter defined by

$$
T^{i}=y^{(3) i}+H^{i}\left(y, y^{(1)}, y^{(2)}\right)=0, \quad(i=\dot{1}, \dot{2}, \ldots, \dot{n}-\dot{1})
$$

The quantities of $V_{n-1}$ corresponding to that of $V_{n}$ are derived from $H^{i}$ in the same way as last paragraph. If we put

$$
\begin{equation*}
\Im^{\lambda}=H^{\lambda}-\xi_{i}^{\lambda} H^{i}+3 \xi_{j k}^{\lambda} y^{(2) j} y^{(1) k}+\xi_{j k h}^{\lambda} y^{(1) j} y^{(1) k} y^{(1) k} \tag{1.1}
\end{equation*}
$$

where

$$
\xi_{i}^{\lambda}=\frac{\partial x^{\lambda}}{\partial y^{i}}, \quad \xi_{j k}^{\lambda}=\frac{\partial^{2} x^{\lambda}}{\partial y^{j} \partial y^{k}}, \quad \xi_{j k h}^{\lambda}=\frac{\partial^{3} x^{\lambda}}{\partial y^{j} \partial y^{k} \partial x^{h}},
$$

then $\mathfrak{S}^{\lambda}$ is a vector of $V_{n}$ and scalar of $V_{n-1}$.
According to the assumption on $H^{\lambda}$ and $H^{i}, \Im^{\lambda}$ must satisfy the following relations:
(a) $\mathfrak{F}_{(1) s}^{\lambda} y^{(1) s}+2 \mathfrak{Y}_{(2) s}^{\lambda} y^{(2) s}=3 \mathfrak{S}^{\lambda}$,
(b) $\Im_{(2) s}^{\lambda} y^{(1) s}=0$.

We have from (1.1)
(1.3) (a) $\Im_{(1) s}^{\lambda}=H_{(1) \nu}^{\lambda} \xi_{s}^{\nu}+2 H_{(2) \nu}^{\lambda}, \xi_{i s}^{\nu} y^{(1) i}-\xi_{i}^{2} H_{(1) s}^{i}+3 \xi_{i s}^{\lambda} y^{(2) i}+\xi_{s i k}^{\lambda} y^{(1) j} y^{(1) k}$,
(b) $\mathfrak{Y}_{(2) s}^{\lambda}=H_{(2)}^{\lambda}, \xi_{s}^{\nu}-\xi_{i}^{\lambda} H_{(2) s}^{i}+3 \xi_{i s}^{\lambda} y^{(1) i}$.

Now we get
(a) $\bar{V}_{l}^{(0)} \Phi=\xi_{l}^{\lambda} \overline{\bar{L}}_{\lambda}^{(1)} \varphi+\frac{1}{3} \Im_{(2) l}^{\lambda} \overline{\bar{V}}_{\lambda}^{(1)} \Phi+\frac{1}{3}\left(\bar{V}_{l}^{(1)} \mathcal{J}^{\lambda}\right) \bar{\Gamma}_{\lambda}^{(2)} \Phi$,
(b) $\overline{\tilde{r}}_{l}^{(1)} \Phi=\xi_{l}^{\lambda} \overline{\bar{D}}_{\lambda}^{(1)} \varphi+\frac{2}{3} \Im_{(2) l}^{\lambda} \bar{J}_{\lambda}^{(2)} \Phi$,
(c) $\overline{\bar{D}}_{l}^{(2)} \Phi=\xi_{l}^{1} \bar{D}_{\lambda}^{(2)} \Phi$,
(\$) being an arbitrary quantity of $V_{\mu}$.
On our hypersurface $V_{n-1}, x^{(1) \lambda}$ and $x^{(2) \lambda}$ being expressed as $x^{(1) \lambda}=$ $\xi_{i}^{\lambda} y^{(1) i}, x^{(2) \lambda}=\xi_{i}^{\hat{i}} y^{(2) i}+\xi_{i j}^{\lambda} y^{(1) i} y^{(1))}$, it can be readily proved that
(a) $\delta x^{(1) \lambda}=\xi_{i}^{\lambda} \delta y^{(1) i}+\frac{1}{3} \Im_{(2) i}^{\lambda} d y^{i}$,
(b) $\delta x^{(2) \lambda}=\xi_{i}^{\lambda} \delta y^{(2) i}+\frac{2}{3} \Im_{(2)}^{\lambda} \delta y^{(1) i}+\frac{1}{3}\left(\bar{V}_{j}^{(1)} \mathfrak{Y}^{\lambda}\right) d y^{i}$.

Then we have from (1.5)

$$
\begin{equation*}
\delta \xi_{i}^{\lambda}=F_{j_{k}}^{\lambda} d y^{k}+\frac{2}{3} \Im_{(2) j(2) k}^{\lambda} \delta y^{(1) k}, \tag{1.6}
\end{equation*}
$$

where

Furthermore we get from (1.3) and (1.4)

$$
\begin{equation*}
F_{j k}^{\lambda}=\frac{1}{3} \bar{\nabla}_{k}^{(1)} \Im_{(2) j}^{\lambda} \tag{1.9}
\end{equation*}
$$

If we have a vector $v^{\lambda}$ tangent to the hypersurface $V_{n-1}$, then $v^{\lambda}$ being expressed as $v^{\lambda}=\xi_{i}^{\lambda} v^{i}$, we have along $V_{n-1}$

$$
\begin{equation*}
\delta v^{\lambda}=\xi_{i}^{\lambda} \delta v^{i}+v^{j}\left(F_{j k}^{\lambda} d y^{k}+\frac{2}{3} \mathfrak{S}_{(2) j(2) k}^{\lambda} \delta y^{(1) k}\right) \tag{1.10}
\end{equation*}
$$

Definition 1. If we have $\mathfrak{J}^{2}=0$ at every point of $V_{n-1}$, such a $V_{n-1}$ is called totally geodesic $V_{n-1}$.

Then it is evident from (1.1), that any path of a totally geodesic $V_{n-1}$ immersed in $V_{n}$ is also a path of $V_{n}$.

Definition 2. If we have $\mathfrak{J}_{(2) k}^{\lambda}=0$ at every point on $V_{n-1}$, such a $V_{n-1}$ is called semi-geodesic $V_{n-1}$.

From (1.9) and (1.2), it can be proved that semi-geodesic $V_{n-1}$ has following properties:
(a) $\delta \xi_{j}^{\lambda}=0$,
(b) With respect to $x_{3}^{(1)}, \mathfrak{J}^{\lambda}$ are homogenous of degree 3.

That is to say: When a vector of semi-geodesic $V_{n-1}$ is displaced parallelly to itself in $V_{n}$ along $V_{n-1}$, it moves also parallelly to itself in $V_{n-1}$.

We have from (1.7) and (1.8) the next fundamental relations,

$$
\begin{equation*}
\xi_{j}^{\mu} w_{\mu}^{\lambda}=\xi_{i}^{\lambda} w_{j}^{i}-\xi_{j k}^{\lambda} d y^{k}+F_{j_{k}}^{\lambda} d y^{k}+\frac{2}{3} \Im_{(2) j(2) k}^{\lambda} \delta y^{(1) k} . \tag{1.11}
\end{equation*}
$$

§ 2. With use of (1.6) and (1.10), we obtain the integrability conditions of (1.11) as follows:

$$
\begin{align*}
& \text { (a) } \stackrel{*}{R_{\mu \circ \pi}^{\lambda(0) 0} \xi_{j}^{\mu} \xi_{k}^{a} \xi_{h}^{\pi}}+\frac{1}{9} R_{\mu \sigma \pi}^{\lambda(1)(1)} \mathcal{J}_{(2) k}^{(2)} \mathcal{F}_{(2) h}^{\pi} \xi_{j}^{\mu}  \tag{2.1}\\
& +\frac{1}{3} R_{\mu \sigma \pi}^{\lambda(0)(1) \xi_{j}^{\mu}\left(\xi_{k}^{\sigma} \mathfrak{S}_{(2) h}^{\pi}-\xi_{h}^{\sigma} \mathfrak{Y}_{(2) k}^{\pi}\right)} \\
& +\frac{1}{3} R_{\mu \sigma \pi}^{\lambda(0)(2) \xi_{j}^{\mu}\left(\xi_{k}^{a} \bar{V}_{h}^{(1)} \mathcal{S}^{\pi}-\xi_{h}^{\sigma} \bar{\sigma}_{k}^{(1)} \mathfrak{Y}^{\pi}\right)} \\
& +\frac{1}{9} R_{\mu \sigma \pi}^{\chi(1) 2)} \xi_{j}^{\mu}\left(\Im_{(2) k}^{\sigma} \bar{F}_{h}^{(1)} \mathcal{J}^{\pi}-\Im_{(2) h}^{\sigma} \overline{\bar{F}}_{k}^{(1)} \mathfrak{J}^{n}\right)
\end{align*}
$$

No. 7.] On the Theory of Hypersurfaces in the Path-space of the Third Order.

$$
\begin{aligned}
& =\xi_{i}^{\lambda} R_{j k h}^{i(0)(0)}+\nabla_{h}^{(0)} F_{j k c}^{\lambda}-\nabla_{k}^{(0)} F_{j h}^{\lambda}+F_{j a}^{\lambda} S_{k k k}^{(0)(0) a} \\
& +\frac{2}{3} \mathcal{J}_{(2) \dot{(2) a}}^{\lambda} S_{k h(1)}^{(0)(0) a}
\end{aligned}
$$

(b) $R_{\mu \sigma \pi}^{\alpha(1)(1) \xi_{j} \xi_{j} \xi_{h}^{\pi}}+\frac{2}{3} R_{\mu \sigma \pi}^{\alpha(1)(2) \xi_{j}^{\mu}\left(\xi_{k} \mathcal{V}_{(2) h}^{\pi}-\xi_{h}^{\sigma} \mathcal{Y}_{(2) k}^{\pi}\right)}$

$$
=\xi_{i}^{\lambda} R_{j k h}^{i(1)(1)}+\frac{2}{3}\left(\nabla_{h}^{(1)} \mathfrak{J}_{(2) j(2) k}^{\lambda}-\nabla_{k}^{(1)} \mathfrak{J}_{(2) j(2) h}^{\lambda}\right)
$$

(c) $R_{\mu \sigma \pi}^{\mu(1)(1) \xi_{j}^{\mu} \xi_{k}^{\sigma} \xi_{h}^{\pi}}+\frac{1}{3} R_{\mu \sigma \pi}^{\lambda(1)(1) \xi_{j}^{\mu} \mathfrak{Y}_{(2) k}^{\sigma} \xi_{h}^{\pi}+\frac{2}{3} R_{\mu \sigma \pi}^{\lambda(0)(2)} \xi_{j}^{\mu} \xi_{k}^{\sigma} \mathfrak{V}_{(2) h}^{\pi}}$

$$
\begin{aligned}
& -\frac{1}{3} R_{\mu \sigma \pi}^{\lambda(1)(2) \xi_{j}^{\mu} \xi_{h}^{\sigma} \bar{F}_{k}^{(1)} \mathfrak{J}^{\pi}+\frac{2}{9} R_{\mu \sigma \pi}^{\lambda(1)(2)} \xi_{j}^{\mu} \mathfrak{Y}_{(2) k}^{\sigma} \mathcal{Y}_{(2) \pi}^{\pi}} \\
& =\dot{\zeta}_{i}^{\lambda} R_{j k h}^{j 0 \kappa(1)}+\nabla_{k}^{(1)} F_{j h}^{\lambda}-\frac{2}{3} \nabla_{k}^{(0)} \mathfrak{J}_{(2) \dot{j}(2) h}^{\lambda}+F_{j a}^{\lambda} S_{k h(0)}^{(0)(1) a} \\
& +\frac{2}{3} \Im_{(2) j(2) a}^{\lambda} S_{k h(1)}^{(0)(1) a},
\end{aligned}
$$

(d) $R_{\mu \sigma \pi}^{(10)(2) \xi_{j}^{\mu} \xi_{k} \xi_{h}^{\pi}}+\frac{1}{3} R_{\mu \sigma \pi}^{\lambda(1)(2) \xi_{i}^{\mu} \Psi_{(2) k}^{\sigma} \xi_{h}^{\pi}}$

$$
=\xi_{i}^{\lambda} R_{j k h}^{i(0)(2)}+\nabla_{h}^{(2)} F_{j k}^{\lambda}+\frac{2}{3} \Im_{(2) j(2) a}^{\lambda} S_{k h(1)}^{(0)(2) a},
$$

where

The integrability conditions of (1.5) are
(a) $S_{\mu \sigma(0)}^{(0)(0) \lambda} \xi_{j}^{\mu} \xi_{k}^{\sigma}+\frac{1}{3}\left(\xi_{j}^{\mu} \mathcal{Y}_{(2) k}^{\sigma}-\xi_{k}^{\mu} \mathcal{Y}_{(2) j}^{\sigma}\right) S_{\mu \sigma(0)}^{(0)(1) \lambda}=\xi_{i}^{2} S_{j k(0)}^{(0)}(0) i+F_{j k}^{\lambda}-F_{k j}^{\nu}$,
(b) $S_{\mu \sigma(0)}^{(0)(1)} \xi_{j}^{\mu} \xi_{k}^{G}=\xi_{i}^{\lambda} S_{j k(0)}^{(0)(1) i}+\frac{2}{3} \mathfrak{J}_{(2) \dot{x}(2) k}^{\lambda}$,
(c) $S_{\mu \sigma(1)}^{(0)(1) \lambda \xi_{j}^{\mu} \xi_{k}^{\sigma}}+\frac{1}{3} S_{\mu \sigma(1)}^{(0)(1)} \xi_{j}^{\mu} \Im_{(2) k}^{\sigma}-\frac{1}{3} S_{\mu \sigma(1)}^{(0)(1) \lambda} \xi_{k}^{\mu} \mathfrak{Z}_{(2) j}^{\sigma}$

$$
\begin{aligned}
& -1 S_{j \sigma(1)}^{(0)(2)} \xi_{k}^{\mu} \overline{\bar{j}}_{j}^{(1)} \mathfrak{J}^{\sigma}+\frac{1}{3} S_{\mu \sigma(1)}^{(0)(2) \lambda \xi_{j}^{\mu} \bar{\nabla}_{k}^{(1)} \mathfrak{J}^{\sigma}} \\
& =\xi_{i}^{\lambda} S_{j k(1)}^{(0)(0) i}+\frac{1}{3} \mathfrak{J}^{\lambda}(2) i S_{j k(0)}^{(0)(0) i}+\frac{1}{3} \nabla_{k}^{(0)} \mathfrak{J}_{(2) j}^{\lambda}-\frac{1}{3} \nabla_{j}^{(0)} \mathfrak{J}_{(2) k}^{\lambda},
\end{aligned}
$$

(d) $S_{\mu \sigma(2)}^{(0 \times 0)} \xi_{j}^{\mu \xi_{k}^{\sigma}}+\frac{1}{3} S_{\mu \sigma(2)}^{(0)(1) \lambda} \xi_{j}^{\mu} \mathfrak{Y}_{(2) k}^{\sigma}-\frac{1}{3} S_{\mu(2)}^{(0)(1) \lambda} \xi_{k}^{\mu} \mathfrak{Z}_{(2) j}^{\sigma}$

$$
+\frac{1}{9} S_{\mu \sigma(2)}^{(1)(1) \lambda} \mathfrak{J}_{(2) j}^{\mu} \Im_{(2) k}^{\sigma}=\xi_{i}^{\lambda} S_{j k(2)}^{(0)(0) i}+\frac{2}{3} \mathfrak{J}_{(2) i}^{\lambda} S_{j k(1)}^{(0)(0) i}
$$

$$
+\frac{1}{3}\left(\bar{\Gamma}_{i}^{(1)} \mathcal{U}^{i}\right) S_{j k(0)}^{(0)(0) i}+\frac{1}{3} \nabla_{k}^{(0)} \overline{\bar{V}}_{j}^{(1)} \mathcal{J}^{2}-\frac{1}{3} \nabla_{j}^{(0)} \overline{\bar{V}}_{k}^{(0)} \dot{\mathscr{J}}^{\lambda},
$$

(e) $S_{\mu \sigma(2)}^{(0)(1) \lambda} \xi_{j}^{\mu} \xi_{k}^{\sigma}+\frac{1}{3} S_{\mu(2)}^{(1)(1), ~} \mathfrak{Y}_{(2) j}^{\mu} \xi_{k}^{\sigma}-\frac{1}{3} S_{\mu \sigma(2)}^{(1)(1) \lambda} \mathfrak{J}_{(2) k}^{\mu} \xi_{j}^{\sigma}$

$+\frac{1}{3} \nabla_{k}^{(1)} \bar{F}_{j}^{(1)} \mathfrak{Y}^{\lambda}+\frac{1}{3}\left(\bar{F}_{i}^{(1)} \mathfrak{Y}^{\lambda}\right) S_{j k(0)}^{(0)(1) i}$.
§3. The equations of (2.2) or (2.1) correspond to the equations of Gauss and Codazzi in Riemannian geometry. Let us consider the geometric meaning of them. At first, we must go back to $\S 0$ and consider the classification of spaces.

Definition 3. If $\stackrel{*}{\boldsymbol{R}_{\mu \sigma \pi}^{\chi(\alpha)}(\theta)}=0$, at every point of $V_{n}$, such $a V_{n}$ is called 0-flat.

Definition 4. If $R_{\mu \sigma \pi}^{\lambda(1)(1)}=0$, at every point of $V_{n}$, such $a V_{n}$ is called 1-flat.

Then, we have from (0.8) the following theorems:
Theorem 1. In order that $\underset{21}{\delta \partial} v^{\lambda}-\delta \partial v^{\lambda}=0$ for an arbitrary $v^{\lambda}$ and vanishing $\delta x^{(1) \lambda}, \delta x^{(2) \lambda}$, it is necessary and sufficient that $V_{n}$ is 0 -flat.

Definition 5. If $S_{\mu(0)}^{(0)(0) \lambda}=0$, at every point of $V_{n}$, such $a V_{n}$ is called 0 -symmetric.

Definition 6. If $S_{\mu(1)}^{(0)(0) \lambda}=0$, at every point of $V_{n}$, such $a V_{n}$ is called 1-symmetric.

Definition 7. If $S_{\mu(2)}^{(0)(0) \lambda}=0$, at every point of $V_{n}$, such $a V_{n}$ is called 2-symmetric.

Then we have from (0.10) the following theorems:
Theorem 3. In order that $\delta d x^{\lambda}-\delta d x^{\lambda}=0$, for vanishing $\delta x^{(1) \lambda}$, it is necessary and sufficient that $V_{n}$ is 0 -symmetric.
 it is necessary and sufficient that $V_{n}$ is 1 -symmetric.
 is necessary and sufficient that $V_{n}$ is ${ }_{2}{ }^{12}$-symmetric.

Remark. If $V_{n}$ is 0 -flat, it is also 1 -symmetric. If $V_{n}$ is 0 symmetric, it is also 1 -flat, because we have after some calculation

By means of these theorems and (2.1) or (2.2), we have the following results.

Theorem 6. (i) The totally geodesic $V_{n-1}$ immersed in the 0-flat $V_{u}$ is also 0-flat.
(ii) The totally geodesic $V_{n-1}$ immersed in the 1-symmetric $V_{n}$ is also 1-symmetric.

No. 7.] On the Theory of Hypersurfaces in the Path-space of the Third Order.
(iii) The totally geodesic $V_{n-1}$ immersed in the 2-symmetric $V_{n}$ is also 2-symmetric.
(iv) The semi-geodesic $V_{n-1}$ immersed in the 1-flat $V_{n}$ is also 1-flat.
(v) The semi-geodesic $V_{n-1}$ immersed in the 0 -symmetric $V_{n}$ is also 0 -symmetric.

In conclusion I wish to express my cordial thanks to Prof. K. Yano for his kind guidance and many benefical suggestions.

