# A Hasse diagram for rational toral ranks 

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#### Abstract

Let $X$ be a simply connected CW complex with finite rational cohomology. For the finite quotient set of rationalized orbit spaces of $X$ obtained by almost free toral actions, $\mathcal{T}_{0}(X)=\left\{\left[Y_{i}\right]\right\}$, induced by an equivalence relation based on rational toral ranks, we order as $\left[Y_{i}\right]<\left[Y_{j}\right]$ if there is a rationalized Borel fibration $Y_{i} \rightarrow Y_{j} \rightarrow B T_{\mathrm{Q}}^{n}$ for some $n>0$. It presents a variation of almost free toral actions on $X$. We consider about the Hasse diagram $\mathcal{H}(X)$ of the poset $\mathcal{T}_{0}(X)$, which makes a based graph $G \mathcal{H}(X)$, with some examples. Finally we will try to regard $G \mathcal{H}(X)$ as the 1-skeleton of a finite CW complex $\mathcal{T}(X)$ with base point $X_{\mathrm{Q}}$.


## 1 Introduction

Let $r_{0}(X)$ be the rational toral rank of a simply connected CW complex $X$ of $\operatorname{dim} H^{*}(X ; \mathbb{Q})<\infty$, i.e., the largest integer $r$ such that an $r$-torus $T^{r}=S^{1} \times \cdots \times$ $S^{1}$ (r-factors) can act continuously on a CW-complex $Y$ in the rational homotopy type of $X$ with all its isotropy subgroups finite (almost free action) [2], [4], [6]. Recall that the rationalized Borel space of almost free toral action $\left(E T^{n} \times{ }_{T^{n}}^{\mu} Y\right)_{\mathrm{Q}}$ is homotopy equivalent to the rationalization of the orbit space of $Y$ obtained by the action $\mu$. In a work of V.Puppe (for example see [8]), we can see a Hasse diagram of the cohomology algebras of the fixed point sets of circle actions on $X$, which are correspond to the rationalized Borel spaces, from a point of view of a deformation. We are interested in a rational variation of Borel spaces of toral actions with no-fixed point and the aim of this note is giving a framework for such an approach based on rational toral ranks.

[^0]Due to the rational homotopy theory of D.Sullivan, rationalized fibrations are equivalent to Koszul-Sullivan(KS) extensions. Remark that, when we give certain KS-extensions of the Sullivan minimal model $M(X)$ of $X$ [3], the existences of the free toral actions on complexes in the rational homotopy type of $X$, whose Borel fibrations induce the KS-extensions, are rationally guaranteed by a result of S.Halperin [6, Proposition 4.2] (see Proposition 2.1 below). We denote the homotopy set of rationalized Borel spaces of almost free toral actions $\mu$ on complexes $X_{\mu}$ in the rational homotopy type of $X$, which are given by certain KS-extensions (see §2), by $\mathcal{X}=\coprod_{n=0}^{r_{0}(X)} \mathcal{X}_{n}$ where $\mathcal{X}_{n}:=\left\{\left(E T^{n} \times_{T^{n}}^{\mu} X_{\mu}\right)_{\mathbb{Q}}\right\}$ for $n>0$ and $\mathcal{X}_{0}:=\left\{X_{\mathrm{Q}}\right\}$. For two elements $Y_{1}:=\left(E T^{m} \times T_{T^{m}}^{\mu_{1}} X_{1}\right)_{\mathrm{Q}}$ and $Y_{2}:=\left(E T^{n} \times{ }_{T^{n}}^{\mu_{2}} X_{2}\right)_{\mathrm{Q}}$ of $\mathcal{X}$ for $m<n$, we denote $Y_{1}<Y_{2}$ if there is a rationalized Borel fibration $Y_{1} \rightarrow Y_{2} \rightarrow B T_{\mathrm{Q}}^{n-m}$, which satisfies the homotopy commutative diagram


Here we put $Y_{1}:=X_{\mathrm{Q}}$ if $m=0$. Then $(\mathcal{X},<)$ is a strict partially ordered set (poset).

Definition 1.1. We give an equivalence relation of $\mathcal{X}$ by $Y_{1} \sim Y_{2}$ when $Y_{1}, Y_{2} \in \mathcal{X}_{n}$ for some $n$ and $r_{0}\left(Y_{1}\right)=r_{0}\left(Y_{2}\right)$. For the quotient set $\mathcal{T}_{0}(X):=\mathcal{X} / \sim=\left\{P_{i}\right\}_{i}$, we put $P_{i}<P_{j}$ if there are elements $Y_{i}, Y_{j} \in \mathcal{X}$ such that $\left[Y_{i}\right]=P_{i},\left[Y_{j}\right]=P_{j}$ and $Y_{i}<Y_{j}$ or if there is an element $P_{k} \in \mathcal{T}_{0}(X)$ with $P_{i}<P_{k}$ and $P_{k}<P_{j}$.

Notice that even if $T^{m}$ acts almost freely on $X$ and $r_{0}(X)=n(>m)$, then there does not always exist an almost free action of $T^{n-m}$ on a complex in the rational homotopy type of the Borel space $E T^{m} \times T^{m} X$. For example, when $X=$ $S^{3} \times S^{3} \times S^{7}$, we obtain $r_{0}(X)=3$ by standard $T^{3}$-action $\left(s_{1}, s_{2}, s_{3}\right) \cdot\left(z_{1}, z_{2}, z_{3}\right)=$ $\left(s_{1} z_{1}, s_{2} z_{2}, s_{3} z_{3}\right)$. But there exists a free $S^{1}$-action $\mu: S^{1} \times Y \rightarrow Y$ for a finite complex $Y$ with $Y_{\mathrm{Q}} \simeq X_{\mathrm{Q}}$ and $r_{0}\left(E S^{1} \times_{S^{1}}^{\mu} Y\right)=0$. It is also rationally given as the total space of a non-trivial fibration with fiber $\mathbb{C} P^{3}$ and base $S^{3} \times S^{3}$. See Example 3.5 below for detail. Thus we stand on our starting point.

Claim 1.2. The poset $\mathcal{T}_{0}(X)=\left(\left\{P_{i}\right\}_{i},<\right)$ is not totally ordered in general.
The poset $\mathcal{T}_{0}(X)$ makes a Hasse diagram of the sets $\left\{P_{i}\right\}_{i}$. We denote it as $\mathcal{H}(X)$. It is not a numerical but is a graphical (rational) homotopy invariant of spaces. Here we can put $i<j$ if $P_{i}<P_{j}$ and fix $P_{0}=\left[X_{\mathrm{Q}}\right], P_{1}=$ $\left[\left(E S^{1} \times{ }_{S^{1}} Y\right)_{\mathbb{Q}}\right]$ with $r_{0}\left(E S^{1} \times{ }_{S^{1}} Y\right)=r_{0}(X)-1, \cdots, P_{r_{0}(X)}=\left[\left(E T^{r_{0}(X)} \times{ }_{T^{r_{0}(X)}}\right.\right.$ $\left.Y)_{\mathbb{Q}}\right]$ with $r_{0}\left(E T^{r_{0}(X)} \times_{T^{r_{0}}(X)} Y\right)=0$ for a complex $Y$ in the rational homotopy of $X$. The subset $\left\{P_{1}, . ., P_{r_{0}(X)}\right\}$ always exists by the restrictions to $i_{r_{0}(X)}^{m}\left(T^{m}\right)=$ $\left\{\left(s_{1}, . ., s_{m}, 1, . ., 1\right) \mid s_{i} \in S^{1}\right\}$ of an almost free $T^{r_{0}(X)}$-action on $Y$ for $m=1, . ., r_{0}(X)$. We observe from the above definition

Lemma 1.3. (1) For $Y \in \mathcal{X}, r_{0}(Y)=n$ if and only if $n=\max \left\{k \mid[Y]=P_{i}<P_{i_{1}}<\right.$ $\left.\cdots<P_{i_{k}}, r_{0}\left(P_{i_{k}}\right)=0\right\}$. Then the path of length $n, P_{i} \rightarrow P_{i_{1}} \rightarrow \cdots \rightarrow P_{i_{n}}$, is unique in the graph. In particular, if $Y=X_{\mathrm{Q}}, P_{i}=P_{0}, P_{i_{j}}=P_{j}$ for $j=1, . ., n$.
(2) For $Y \in \mathcal{X}, Y \in \mathcal{X}_{n}$ if and only if $n=\max \left\{k \mid P_{0}<P_{i_{1}}<\cdots<P_{i_{k}}=[Y]\right\}$. Then $n=d\left(P_{0},[Y]\right)$, the distance between $P_{0}$ and $[Y]$ in the graph.

Our Hasse diagrams are restricted to certain forms. Of course, $\mathcal{T}_{0}(X)$ is a finite set. Especially, when $r_{0}(X)=n, n<\sharp \mathcal{T}_{0}(X) \leq(n+(n-1)+\cdots+2+1)+1=$ $\left(n^{2}+n\right) / 2+1\left(0<\sharp \mathcal{X}_{m} / \sim \leq n-m+1\right.$ for $\left.m \leq n\right)$. In particular, $\sharp \mathcal{T}_{0}(X)=$ $r_{0}(X)+1$ if and only if $\mathcal{T}_{0}(X)$ is totally ordered. For example, if $r_{0}(X)=3$ and $r_{0}\left(X^{\prime}\right)=4$ for some spaces $X$ and $X^{\prime}, 4 \leq \sharp \mathcal{T}_{0}(X) \leq 7$ and $5 \leq \sharp \mathcal{T}_{0}\left(X^{\prime}\right) \leq 11$ and $\mathcal{H}(X)$ and $\mathcal{H}\left(X^{\prime}\right)$ are certain sub-diagrams (see Remark 3.7 below) of the Hasse diagrams:

, respectively. If there exist such spaces, $r_{0}\left(P_{0}\right)=3, r_{0}\left(P_{1}\right)=2, r_{0}\left(P_{2}\right)=r_{0}\left(P_{4}\right)=$ $1, r_{0}\left(P_{3}\right)=r_{0}\left(P_{5}\right)=r_{0}\left(P_{6}\right)=0$ in the left hand and $r_{0}\left(P_{0}\right)=4, r_{0}\left(P_{1}\right)=3$, $r_{0}\left(P_{2}\right)=r_{0}\left(P_{5}\right)=2, r_{0}\left(P_{3}\right)=r_{0}\left(P_{6}\right)=r_{0}\left(P_{8}\right)=1, r_{0}\left(P_{4}\right)=r_{0}\left(P_{7}\right)=r_{0}\left(P_{9}\right)=$ $r_{0}\left(P_{10}\right)=0$ in the right hand. Here $r_{0}\left(P_{i}\right)$ means $r_{0}(Y)$ for some space $Y$ with $P_{i}=[Y]$.

We can describe a point $P_{i}=[Y]$ of $\mathcal{T}_{0}(X)$ by the double index (lattice point)

$$
\text { d.i. }\left(P_{i}\right):=(s, t) \quad ; \quad s+t \leq r_{0}(X)
$$

when

$$
Y \in \mathcal{X}_{t} \text { and } r_{0}(Y)=r_{0}(X)-s-t
$$

by Definition 1.1. If $P_{i} \neq P_{j}$ in $\mathcal{T}_{0}(X)$, d.i. $\left(P_{i}\right) \neq$ d.i. $\left(P_{j}\right)$. For example, in the above right diagram of $r_{0}(X)=4$, we see d.i. $\left(P_{0}\right)=(0,0)$, d.i. $\left(P_{1}\right)=(0,1)$, d.i. $\left(P_{2}\right)=(0,2)$, d.i. $\left(P_{3}\right)=(0,3)$, d.i. $\left(P_{4}\right)=(0,4)$, d.i. $\left(P_{5}\right)=(1,1)$, d.i. $\left(P_{6}\right)=$ $(1,2)$, d.i. $\left(P_{7}\right)=(1,3)$, d.i. $\left(P_{8}\right)=(2,1)$, d.i. $\left(P_{9}\right)=(2,2)$ and d.i. $\left(P_{10}\right)=(3,1)$. In general, when $r_{0}(X)>1$, if there is a circle action on $X$ that represents $P$ with d.i. $(P)=\left(r_{0}(X)-1,1\right)$, then it is a "bad" action in a meaning since the orbit space permits no almost free circle action.

Claim 1.4. (1) If $P_{i}<P_{j}$ for d.i. $\left(P_{i}\right)=(s, t)$ and d.i. $\left(P_{j}\right)=\left(s^{\prime}, t^{\prime}\right)$, then $s \leq s^{\prime}$ and $t<t^{\prime}$.
(2) If there is a point $P_{i}$ with d.i. $\left(P_{i}\right)=(s, t)$, then there are points $\left\{P_{j}\right\}$ with double indexes $(s, t+1), . .,\left(s, r_{0}(X)-s\right)$, too.

Notice that a Hasse diagram $\mathcal{H}$ can be seen as a connected, finite, non-directed, simple graph $G \mathcal{H}$ with base point corresponding to the minimal element in general. We say a graph with a base point as a based graph in this paper. Define $\phi: \mathcal{T}_{0}(X) \rightarrow \mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0}$ by $\phi(P):=$ d.i. $(P)$ and extend $\tilde{\phi}: G \mathcal{H}(X) \rightarrow \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0}$ by $\tilde{\phi}\left(P_{i} P_{j}\right)=$ d.i. $\left(P_{i}\right)-$ d.i. $\left(P_{j}\right)$, the line segment with extremal points d.i. $\left(P_{i}\right)$ and d.i. $\left(P_{j}\right)$. Then there is a commutative diagram


Note that $\tilde{\phi}$ is injective, that is, $\tilde{\phi}$ gives the realization of $\mathcal{H}(X)$ into $\mathbb{R}_{\geq 0} \times$ $\mathbb{R}_{\geq 0}$ induced by the above double indexes. We see $\mathcal{H}(X)=\mathcal{H}(Y)$ if and only if $\tilde{\phi} G \mathcal{H}(X)=\tilde{\phi} G \mathcal{H}(Y)$. On the other hand, we can reconstruct $\tilde{\phi} G \mathcal{H}(X)$ from $G \mathcal{H}(X)$ graphically (see $\S 4)$. Thus

Theorem 1.5. For some spaces $X$ and $Y, \mathcal{H}(X)=\mathcal{H}(Y)$ if and only if $G \mathcal{H}(X)$ and $G \mathcal{H}(Y)$ are isomorphic as based graphs.

There do not exist the following Hasse diagrams in our ones:

$\cdots$. For example, the graph

$$
A-B-C-D-E
$$

represents the totally ordered Hasse diagram of a space with rational toral rank 4 if we choose the base point as $A$ or $E$. Also it represents (2) of Example 3.5 if we choose the base point as $B$ or $D$. But if we choose the base point as $C$, the graph corresponds to non of our Hasse diagrams. Also the graph

represents our Hasse diagrams (a) or (b) below if we choose the base point as $A$ or $B$, respectively.
(a)

(b)

(c)


If we choose the base point as $F$, the Hasse diagram is given as (c), which is not ours since the points $G$ and $B$ must be a same one from Definition 1.1. Also we can check that the other points are not impossible to be realized as the minimal elements of our Hasse diagrams (the base point of $G \mathcal{H}$ ). Note that the author does not know whether or not exists a space (rational model) $X$ with $\mathcal{H}(X)=(a)$. The following question is essential.

Question 1.6. Find an example of two spaces (rational models) $X$ and $Y$ such that $\phi \mathcal{T}_{0}(X)=\phi \mathcal{T}_{0}(Y)$ in $\mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0}$ but $\mathcal{H}(X) \neq \mathcal{H}(Y)$.
Remark 1.7. Our definition of $(\mathcal{X} / \sim,>)$ in Definition 1.1 may be rough. But if we do not take the quotient, the poset $(\mathcal{X},>)$ seems very complicated. For example, even when $X=S^{3} \times S^{3}$, the Hasse diagram is

(it seems as a broom) where $H^{*}\left(S^{2} \times S^{3} ; \mathbb{Q}\right) \cong \mathbb{Q}\left[t_{1}\right] /\left(t_{1}^{2}\right) \otimes \Lambda(v)$ with $|v|=3$ and

$$
\left\{P_{i}\right\}_{i} \cong\left\{H^{*}\left(P_{i} ; \mathbf{Q}\right)\right\}_{i} \cong\left\{\left.\frac{\mathbb{Q}\left[t_{1}, t_{2}\right]}{\left(t_{1}^{2}+a_{i} t_{2}^{2}, t_{1} t_{2}\right)} \right\rvert\, a_{i} \in \mathbf{Q}^{*}\right\} \cong \mathbb{Q}^{*} / \mathbf{Q}^{* 2}
$$

which is an infinite set $\left(\mathbb{Q}^{*}=\mathbb{Q}-0\right.$ is the unite group of $\left.\mathbb{Q}\right)$. Note that $D_{1} u=t_{1}^{2}$, $D_{1} v=0, D_{2} u=t_{1}^{2}+a_{i} t_{2}^{2}$ and $D_{2} v=t_{1} t_{2}$ for $M(X)=(\Lambda(u, v), 0)$ (see §2).

Remark 1.8. For $Y \in \mathcal{X}, \mathcal{T}_{0}(Y) \equiv\left\{P_{i} \in \mathcal{T}_{0}(X) \mid[Y]=P_{i}\right.$ or $\left.[Y]<P_{i}\right\}$ as ordered sets. Thus $\mathcal{H}(Y)$ is a sub-Hasse diagram of $\mathcal{H}(X)$. Also for two spaces $X$ and $X^{\prime}, G \mathcal{H}(X \times$ $\left.X^{\prime}\right) \supset G \mathcal{H}(X) \vee G \mathcal{H}\left(X^{\prime}\right)$ as a subgraph with vertexes $\left\{P_{i}\right\}_{i}$ and edges $\left\{P_{i} P_{j}\right\}=\left\{P_{i}<\right.$ $P_{j} \mid$ there is no $P_{k}$ with $\left.P_{i}<P_{k}<P_{j}\right\}_{i, j}$. Here the right hand is the one point union $G \mathcal{H}(X) \amalg G \mathcal{H}\left(X^{\prime}\right) / \sim$ where $P_{r_{0}(X)} \sim P_{0}^{\prime}$ for $\mathcal{T}_{0}(X)=\left\{P_{i}\right\}_{i}$ and $\mathcal{T}_{0}\left(X^{\prime}\right)=\left\{P_{i}^{\prime}\right\}_{i}$. It is a grafting of one on the other. By using a Sullivan model, S.Halperin indicates that
rational toral rank does not preserve the product formula $r_{0}\left(X \times X^{\prime}\right)=r_{0}(X)+r_{0}\left(X^{\prime}\right)$ in general [7]([4, Ex.7.19]). Thus this embedding may be complicated in general (see Example 3.9 below).

Acknowledgement. The author would like to thank Katsuhiko Kuribayashi, Shizuo Kaji and the referee for their valuable suggestions and is grateful to Yves Félix for his encouragement.

## 2 A Halperin's result

Let $X$ be a simply connected CW complex of finite type and the Sullivan minimal model $M(X)=(\Lambda V, d)$. It is a free Q-commutative differential graded algebra with a Q-graded vector space $V=\bigoplus_{i \geq 2} V^{i}$ where $\operatorname{dim} V^{i}<\infty$ and a decomposable differential; i..e., $d\left(V^{i}\right) \subset\left(\Lambda^{+} V \cdot \Lambda^{+} V\right)^{i+1}$ and $d \circ d=0$. Here $\Lambda^{+} V$ is the ideal of $\Lambda V$ generated by elements of positive degree. Denote the degree of a homogeneous element $x$ of a graded algebra as $|x|$. Then $x y=(-1)^{|x||y|} y x$ and $d(x y)=d(x) y+(-1)^{|x|} x d(y)$. Note that $M(X)$ determines the rational homotopy type of $X, X_{\mathbb{Q}}$. In particular, $H^{*}(\Lambda V, d) \cong H^{*}(X ; \mathbb{Q})$. Refer [3] for detail.

If an $r$-torus $T^{r}$ acts on $X$ by $\mu: T^{r} \times X \rightarrow X$, there is the Borel fibration

$$
X \rightarrow E T^{r} \times_{T^{r}}^{\mu} X \rightarrow B T^{r},
$$

where $E T^{r} \times_{T^{r}}^{\mu} X$ is the orbit space of the action $g(e, x)=\left(e g^{-1}, g x\right)$ on the product $E T^{r} \times X$. It is rationally given by the KS extension (model)

$$
\left(\mathbb{Q}\left[t_{1}, \ldots, t_{r}\right], 0\right) \rightarrow\left(\mathbb{Q}\left[t_{1}, \ldots, t_{r}\right] \otimes \Lambda V, D\right) \rightarrow(\Lambda V, d) \quad(*)
$$

where with $\left|t_{i}\right|=2$ for $i=1, \ldots, r, D t_{i}=0$ and $D v \equiv d v$ modulo the ideal $\left(t_{1}, \ldots, t_{r}\right)$ for $v \in V$.

Proposition 2.1. [6, Proposition 4.2] Suppose that $X$ is a simply connected CW-complex with $\operatorname{dim} H^{*}(X ; Q)<\infty$. Put $M(X)=(\Lambda V, d)$. Then $r_{0}(X) \geq r$ if and only if there is a KS extension (*) satisfying $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, \ldots, t_{r}\right] \otimes \wedge V, D\right)<\infty$. Moreover, if $r_{0}(X) \geq r$, then $T^{r}$ acts freely on a finite complex $Y$ that has the same rational homotopy type as $X$ and $M\left(E T^{r} \times_{T^{r}} Y\right) \cong\left(\mathbb{Q}\left[t_{1}, \ldots, t_{r}\right] \otimes \wedge V, D\right)$.

Thus we can put

$$
\mathcal{X}_{n}=\left\{\left(\mathbb{Q}\left[t_{1}, \ldots, t_{n}\right] \otimes \Lambda V, D\right) \mid \operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, \ldots, t_{n}\right] \otimes \wedge V, D\right)<\infty\right\} / \cong
$$

for $M(X)=(\Lambda V, d)$. The KS extension of the fibration $Y_{1} \rightarrow Y_{2} \rightarrow B T_{\mathrm{Q}}^{n-m}$ in $\S 1$ is given by the homotopy commutative diagram

for $M\left(B T^{n-m}\right)=\left(\mathbb{Q}\left[t_{m+1}, . ., t_{n}\right], 0\right), M\left(Y_{1}\right)=\left(\mathbb{Q}\left[t_{1}, . ., t_{m}\right] \otimes \Lambda V, D_{1}\right)$ and $M\left(Y_{2}\right)=$ $\left(\mathbb{Q}\left[t_{1}, . ., t_{n}\right] \otimes \Lambda V, D_{2}\right)$. Then we simply write $\left[D_{1}\right]<\left[D_{2}\right]$.

Even if $r_{0}(X)>i$ and $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, \ldots, t_{i-1}\right] \otimes \wedge V, D\right)<\infty$, we may not be able to construct the KS extension

$$
\left(\mathbb{Q}\left[t_{i}\right], 0\right) \rightarrow\left(\mathbb{Q}\left[t_{1}, \ldots, t_{i}\right] \otimes \wedge V, D^{\prime}\right) \rightarrow\left(\mathbb{Q}\left[t_{1}, \ldots, t_{i-1}\right] \otimes \wedge V, D\right)
$$

satisfying $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, \ldots, t_{i}\right] \otimes \wedge V, D^{\prime}\right)<\infty$ in general (see Claim 1.2).

## 3 Examples of $r_{0}(X) \leq 4$

Refer the arguments of [4, 7.3.2] or [7] for the computations of toral ranks with minimal models. We put $M(X)=(\Lambda V, d)$. A manner to draw $\tilde{\phi} G \mathcal{H}(X)$ often is the following steps.
i) Estimate $r_{0}(X)$ by Proposition 2.1.
ii) $\operatorname{Dot} V=\left\{(s, t) \in \mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0} \mid s \geq 0, t>0, s+t \leq r_{0}(X)\right\}$.
iii) Check whether or not a point ' $P$ ' exists so that d.i. $(P)=\left(s, r_{0}(X)-s\right) \in V$ for $s=1, . ., r_{0}(X)-1$. If exists (then we say it a bud), next check the below $\cdots$. See Claim 1.4 (2).
iv) Check whether or not an edge ' $<$ ' exists between $P$ and $P^{\prime}$ with d.i. $(P)=$ $(s, t)$ and d.i. $\left(P^{\prime}\right)=\left(s^{\prime}, t+1\right)$ for $s<s^{\prime}$. See Claim 1.4 (1). In particular, the trunk $P_{0}-P_{1}-\cdots-P_{r_{0}(X)}$ always exists.

Example 3.1. When $X=S^{2 m+1} \times S^{2 n+1}$, the Hasse diagram of $\mathcal{T}_{0}(X)$ is totally ordered as (1) for any $m$ and $n$. Next put $M(X)=\left(\Lambda\left(v_{1}, v_{2}, v_{3}, v_{4}\right), d\right)$ with $d v_{1}=d v_{2}=d v_{4}=0, d v_{3}=v_{1} v_{2}$ and $\left|v_{1}\right|=\left|v_{2}\right|=3,\left|v_{3}\right|=5,\left|v_{4}\right|=9$. It is given by the total space of a non-trivial fibration $S^{5} \rightarrow X \rightarrow S^{3} \times S^{3} \times S^{9}$. Then $\mathcal{H}(X)$ is given as (2):

where $P_{1}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v_{1}=D v_{2}=D v_{4}=0 D v_{3}=v_{1} v_{2}+t^{3}$, $P_{2}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D\right)\right]$ with $D v_{1}=D v_{2}=0 D v_{3}=v_{1} v_{2}+t_{1}^{3}, D v_{4}=t_{2}^{5}$, $P_{3}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v_{1}=D v_{2}=0, D v_{3}=v_{1} v_{2}, D v_{4}=v_{1} v_{3} t+t^{5}$. Note that $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t, t^{\prime}\right] \otimes \Lambda V, D^{\prime}\right)=\infty$ for any KS extension $\left(\mathbb{Q}\left[t, t^{\prime}\right] \otimes \Lambda V, D^{\prime}\right)$ of it.

In general, $\mathcal{H}(X)$ is given as only (1) or $(2)$ if $r_{0}(X)=2$. Next we will consider the cases of $r_{0}(X)>2$.

A minimal model $(\Lambda V, d)$ is said to be pure if $d V^{\text {even }}=0$ and $d V^{\text {odd }} \subset \Lambda V^{\text {even }}$.

Lemma 3.2. For $m<n$, if $M(Y)=\left(\Lambda\left(u_{1}, . ., u_{m}, v_{1}, . ., v_{n}\right), d\right)$ with $\left|u_{i}\right|$ even and $\left|v_{1}\right|=\cdots=\left|v_{n}\right|$ odd is a pure model, then $r_{0}(Y)=n-m$.

Proof. From [1, Theorem 1], $r_{0}(Y) \leq n-m$. From [5, Lemma 8], there is a sub-basis $v_{1}^{\prime}, . ., v_{m}^{\prime}$ of $\mathbb{Q}\left(v_{1}, . ., v_{n}\right)$ such that $d v_{1}^{\prime}, . ., d v_{m}^{\prime}$ is a regular sequence, i.e., $\operatorname{dim} H^{*}\left(\Lambda\left(u_{1}, . ., u_{m}, v_{1}^{\prime}, . ., v_{m}^{\prime}\right), d\right)<\infty$. Then there is a sub-basis $v_{i_{1}}, . ., v_{i_{n-m}}$ with $\mathbb{Q}\left(v_{i_{1}}, . ., v_{i_{n-m}}\right) \oplus \mathbb{Q}\left(v_{1}^{\prime}, . ., v_{m}^{\prime}\right)=\mathbb{Q}\left(v_{1}, . ., v_{n}\right)$. For $j=1, . ., n-m$, put $D v_{i_{j}}=$ $d v_{i_{j}}+t_{j}^{a_{j}}$ with $a_{j}=\left(\left|v_{i_{j}}\right|+1\right) / 2$. Then $\left[t_{j}^{a_{j}}\right] \in \mathbb{Q}\left[u_{1}, . ., u_{m}\right] /\left(d v_{1}^{\prime}, . ., d v_{m}^{\prime}\right)$ and especially $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{i_{1}}, . ., t_{i_{n-m}}\right] \otimes \Lambda\left(u_{1}, . ., u_{m}, v_{1}, . ., v_{n}\right), D\right)<\infty$. From Proposition 2.1, $r_{0}(Y) \geq n-m$.

Theorem 3.3. If $X$ has the rational homotopy type of product of odd spheres with same dimensions, $X_{\mathrm{Q}} \simeq\left(S^{k} \times \cdots \times S^{k}\right)_{\mathrm{Q}}$ for some $k>1$, then $\mathcal{T}_{0}(X)$ is totally ordered.

Proof. Put $r_{0}(X)=n$. Suppose $A=\left(\mathbb{Q}\left[t_{1}, . ., t_{n-s}\right] \otimes \Lambda\left(v_{1}, . ., v_{n}\right), D\right)$ satisfies $\operatorname{dim} H^{*}(A)<\infty$. It is easy to check that $A$ is pure. From the above lemma, $r_{0}(A)=s$. Thus there is no point $P$ in $\mathcal{H}(X)$ such that d.i. $(P)=(s, n-s)$ for $s>0$. We have done from Claim 1.4 (2).

Theorem 3.4. Suppose that $1<n_{1} \leq n_{2} \leq n_{3} \leq n_{4}$ are odd.
(1) For $X=S^{n_{1}} \times S^{n_{2}} \times S^{n_{3}}$, there exists an element $P$ in $\mathcal{T}_{0}(X)$ with d.i. $(P)=$ $(2,1)$ if and only if $n_{1}+n_{2}<n_{3}$.
(2) For $X=S^{n_{1}} \times S^{n_{2}} \times S^{n_{3}} \times S^{n_{4}}$, there exists an element $P$ in $\mathcal{T}_{0}(X)$ with d.i. $(P)=(3,1)$ if and only if $n_{1}+n_{2}<n_{3}$ and $n_{1}+n_{3}<n_{4}$.

Proof. (1) Put $M(X)=\left(\Lambda\left(v_{1}, v_{2}, v_{3}\right), 0\right)$ with $\left|v_{i}\right|=n_{i}$. Then $D v_{1}=D v_{2}=0$, $D v_{3}=v_{1} v_{2} t^{\left(n_{3}-n_{1}-n_{2}+1\right) / 2}+t^{\left(n_{3}+1\right) / 2}$ if and only if $d . i .([D])=(2,1)$.
(2) Put $M(X)=\left(\Lambda\left(v_{1}, v_{2}, v_{3}, v_{4}\right), 0\right)$. Then there is a differential $D$ with $D v_{3}=$ $v_{1} v_{2} t^{\left(n_{3}-n_{1}-n_{2}+1\right) / 2}$ and $D v_{4}=v_{1} v_{3} t^{\left(n_{4}-n_{1}-n_{3}+1\right) / 2}+t^{\left(n_{4}+1\right) / 2}$ if and only if there exists a bud $P$ of d.i. $(P)=(3,1)$.

Example 3.5. Let $X$ be the product of three odd-spheres. Then $r_{0}(X)=3$. From Theorem 3.3, $\mathcal{T}_{0}\left(S^{3} \times S^{3} \times S^{3}\right)$ is given by the 4-points $\left\{P_{0}, P_{1}, P_{2}, P_{3}\right\}$ which is totally ordered as (1). But $\mathcal{T}_{0}\left(S^{3} \times S^{3} \times S^{7}\right)$ is given by the 5-points $\left\{P_{0}, P_{1}, P_{2}, P_{3}, P_{4}\right\}$ which is partially ordered as (2):
(1)

where $P_{1}=\left[\left(S^{2} \times S^{3} \times S^{7}\right)_{\mathbb{Q}}\right]\left(=\left[\left(S^{3} \times S^{3} \times \mathbb{C} P^{3}\right)_{\mathbb{Q}}\right]\right)$, $P_{2}=\left[\left(S^{2} \times S^{2} \times S^{7}\right)_{\mathbb{Q}}\right]$ $\left(=\left[\left(S^{2} \times S^{3} \times \mathbb{C} P^{3}\right)_{\mathrm{Q}}\right]\right)$ and $P_{3}=\left[\left(S^{2} \times S^{2} \times \mathbb{C} P^{3}\right)_{\mathrm{Q}}\right]$. Here $P_{4}=\left[Y_{\mathrm{Q}}\right]$ is given
by $M(Y)=(\mathbb{Q}[t] \otimes \Lambda(x, y, z), D)$ with $D x=D y=0$ and $D z=x y t+t^{4}$ for $M(X)=(\Lambda(x, y, z), 0)$ of $|x|=|y|=3$ and $|z|=7$. Then $H^{*}(Y ; \mathbb{Q}) \cong \Lambda(x, y) \otimes$ $\mathrm{Q}[t] /\left(x y t+t^{4}\right)$, which is finite dimensional. Note $r_{0}(Y)=0$ from Proposition 2.1. Indeed, suppose that there is a KS extension

$$
\left(\mathbb{Q}\left[t_{2}\right], 0\right) \rightarrow\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda(x, y, z), D^{\prime}\right) \rightarrow\left(\mathbb{Q}\left[t_{1}\right] \otimes \Lambda(x, y, z), D\right)=M(Y)
$$

We have $D^{\prime} \circ D^{\prime} \neq 0$ for any non-trivial differential $D^{\prime} x=f\left(t_{1}, t_{2}\right)$ and $D^{\prime} y=$ $g\left(t_{1}, t_{2}\right)$ in $\mathbb{Q}\left[t_{1}, t_{2}\right]$. Also if $D^{\prime} x=D^{\prime} y=0$ and $D^{\prime} z=x y t_{1}+t_{1}^{4}+a x y t_{2}+\sum a_{i j} t_{1}^{i} t_{2}^{j}$ $\left(a, a_{i j} \in \mathbb{Q}\right)$, then $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda(x, y, z), D^{\prime}\right)=\infty$ for any $a, a_{i j}$. Thus d.i. $\left(P_{4}\right)=(2,2-0-1)=(2,1)$.

Notice that there is not a point of $(1,2)$ from [7, Lemma 2.12].
Thus the set $\mathcal{T}_{0}(X)$ is more sensitive than the number $r_{0}(X)$ about degrees of the rational homotopy group of $X$.

Example 3.6. Put $M(X)=\left(\Lambda\left(v_{1}, v_{2}, v_{3}, v_{4}, v_{5}\right), d\right)$ with $d v_{1}=d v_{2}=d v_{4}=d v_{5}=$ $0, d v_{3}=v_{1} v_{2}$. If
(1) $\left|v_{1}\right|=\left|v_{2}\right|=3,\left|v_{3}\right|=5,\left|v_{4}\right|=9,\left|v_{5}\right|=15$ or
(2) $\left|v_{1}\right|=\left|v_{2}\right|=3,\left|v_{3}\right|=5,\left|v_{4}\right|=3,\left|v_{5}\right|=7$,
then $\mathcal{H}(X)$ is given as
(1) $P_{3}$
(2) $P_{3}$

$P_{0}$.

In (1), $P_{1}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v_{1}=D v_{2}=D v_{5}=0, D v_{4}=t^{5}, D v_{3}=v_{1} v_{2}$. $P_{2}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D\right)\right]$ with $D v_{1}=D v_{2}=D v_{5}=0, D v_{3}=v_{1} v_{2}+t_{2}^{3}, D v_{4}=$ $t_{1}^{5}$.
$P_{3}=\left[\left(\mathbf{Q}\left[t_{1}, t_{2}, t_{3}\right] \otimes \Lambda V, D\right)\right]$ with $D v_{1}=D v_{2}=0, D v_{3}=v_{1} v_{2}+t_{2}^{3}, D v_{4}=t_{1}^{5}$, $D v_{5}=t_{3}^{8}$.
$P_{4}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v_{1}=D v_{2}=D v_{5}=0, D v_{3}=v_{1} v_{2}, D v_{4}=v_{1} v_{3} t+t^{5}$. $P_{5}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D\right)\right]$ with $D v_{1}=D v_{2}=0, D v_{3}=v_{1} v_{2}, D v_{4}=v_{1} v_{3} t_{1}+t_{1}^{5}$, $D v_{5}=t_{2}^{8}$.
$P_{6}=[(\mathbf{Q}[t] \otimes \Lambda V, D)]$ with $D v_{1}=D v_{2}=D v_{4}=0, D v_{3}=v_{1} v_{2}, D v_{5}=v_{1} v_{3} t^{4}+$ $v_{2} v_{4} t^{2}+t^{8}$.

In (2), $P_{4}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v_{1}=D v_{2}=D v_{4}=0, D v_{3}=v_{1} v_{2}$, $D v_{5}=v_{1} v_{4} t+t^{4}$.
$P_{5}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D\right)\right]$ with $D v_{1}=D v_{2}=D v_{4}=0, D v_{3}=v_{1} v_{2}+t_{2}^{3}$, $D v_{5}=v_{1} v_{4} t_{1}+t_{1}^{4}$.

Remark 3.7. If $r_{0}(X)=3, \mathcal{H}(X)$ is given as one of Example 3.5, Example 3.6 or the diagrams:


Thus we see that $4 \leq \sharp\left\{\mathcal{H}(X) \mid r_{0}(X)=3\right\} \leq 8$.
Finally we give two examples with the same Hasse diagrams.
Example 3.8. Put $M\left(X_{1}\right)=\left(\Lambda\left(v_{1}, v_{2}, v_{3}, v_{4}, v_{5}, v_{6}\right), d\right)$ with $d v_{1}=d v_{2}=d v_{4}=$ $d v_{5}=d v_{6}=0, d v_{3}=v_{1} v_{2}$ and $\left|v_{1}\right|=\left|v_{2}\right|=3,\left|v_{3}\right|=5,\left|v_{4}\right|=9,\left|v_{5}\right|=13$, $\left|v_{6}\right|=17$. Then $\mathcal{H}\left(X_{1}\right)$ is given as

where $P_{4}=[(\mathbb{Q}[t] \otimes \wedge V, D)]$ with $D v_{1}=D v_{2}=0, D v_{3}=v_{1} v_{2}+t^{3}, D v_{4}=t^{5}$, $D v_{5}=t^{7}, D v_{6}=t^{9}$.
$P_{5}=[(\mathbf{Q}[t] \otimes \wedge V, D)]$ with $D v_{1}=D v_{2}=D v_{5}=D v_{6}=0, D v_{3}=v_{1} v_{2}$, $D v_{4}=v_{1} v_{3} t+t^{5}$.
$P_{8}=[(\mathbb{Q}[t] \otimes \wedge V, D)]$ with $D v_{1}=D v_{2}=D v_{4}=D v_{6}=0, D v_{3}=v_{1} v_{2}$, $D v_{5}=v_{2} v_{4} t+v_{1} v_{3} t^{4}+t^{7}$.
$P_{9}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \wedge V, D\right)\right]=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \wedge V, D^{\prime}\right)\right]=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \wedge V, D^{\prime \prime}\right)\right]$ with $D v_{1}=D v_{2}=0, D v_{3}=v_{1} v_{2}$ (same for $D^{\prime}$ and $D^{\prime \prime}$ ) and

$$
\begin{aligned}
D v_{4} & =v_{1} v_{3} t_{2}+t_{1}^{5}, D v_{5}=0, D v_{6}=v_{2} v_{5} t_{2}+t_{2}^{9} \\
D^{\prime} v_{4} & =v_{1} v_{3} t_{1}+t_{1}^{5}, D^{\prime} v_{5}=0, D^{\prime} v_{6}=v_{2} v_{5} t_{2}+t_{2}^{9} \\
D^{\prime \prime} v_{4} & =v_{1} v_{3} t_{1}+t_{2}^{5}, D^{\prime \prime} v_{5}=0, D^{\prime \prime} v_{6}=v_{2} v_{5} t_{1}+t_{1}^{9}
\end{aligned}
$$

Note that $P_{1}<P_{9}$ is given by $D, P_{5}<P_{9}$ by $D^{\prime}$ and $P_{8}<P_{9}$ by $D^{\prime \prime}$.
$P_{10}=[(\mathbf{Q}[t] \otimes \wedge V, D)]$ with $D v_{1}=D v_{2}=D v_{4}=D v_{5}=0, D v_{3}=v_{1} v_{2}$ and $D v_{6}=v_{1} v_{5} t+v_{2} v_{4} t^{3}+v_{1} v_{3} t^{5}+t^{9}$.

Example 3.9. Put $M\left(X_{2}\right)=\left(\Lambda\left(v_{1}, v_{2}, v_{3}, v_{4}, v_{5}, v_{6}, w_{1}, w_{2}, w_{3}, w_{4}, w_{5}, w_{6}, u, y, z, v\right), d\right)$ with $d v_{1}=\cdots=d v_{6}=d w_{1}=\cdots=d w_{6}=d u=d y=d z=0$,

$$
d v=v_{1} v_{2} v_{3} v_{4}+v_{1} v_{2} v_{5} v_{6}+w_{1} w_{2} w_{3} w_{4}+w_{1} w_{2} w_{5} w_{6}+u^{2}
$$

and $\left|v_{1}\right|=\cdots=\left|v_{6}\right|=\left|w_{1}\right|=\cdots=\left|w_{6}\right|=3,|u|=6,|y|=|z|=7,|v|=11$. We see $\operatorname{dim} H^{*}\left(X_{2} ; \mathbb{Q}\right)<\infty$ since $M\left(X_{2}\right)$ is the total space of a KS extension

$$
\left(\Lambda\left(v_{1}, \cdots, v_{6}, w_{1}, \cdots, w_{6}, y, z\right), 0\right) \rightarrow(\Lambda V, d) \rightarrow(\Lambda(u, v), \bar{d})=M\left(S^{6}\right)
$$

where $\bar{d} u=0$ and $\bar{d} v=u^{2}$. Remark the space $X_{1}$ in Example 3.8 is not a formal space but $X_{2}$ is formal [3]. Note that $r_{0}\left(X^{\prime}\right)=0$ for a space $X^{\prime}$ with $X_{2 Q} \simeq\left(X^{\prime} \times\right.$ $\left.S^{7} \times S^{7}\right)_{\mathrm{Q}}$, where $M\left(X^{\prime}\right)=\left(\Lambda\left(v_{1}, v_{2}, v_{3}, v_{4}, v_{5}, v_{6}, w_{1}, w_{2}, w_{3}, w_{4}, w_{5}, w_{6}, u, v\right), d\right)$.

Then $\mathcal{H}\left(X_{2}\right)$ is given as

where $P_{1}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ such that $D v_{i}=0$ for $i \neq 4, D v_{4}=t^{2}, D w_{i}=D u=$ $D z=0, D y=v_{2} v_{3} t, D v=d v-v_{1} y t$. $P_{4}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}, t_{3}, t_{4}\right] \otimes \Lambda V, D\right)\right]$ with

$$
\begin{gathered}
D v_{1}=D v_{2}=D v_{3}=D v_{5}=D w_{1}=D w_{2}=D w_{3}=D w_{5}=D u=0, \cdots(*) \\
D v_{4}=t_{1}^{2}, D v_{6}=t_{2}^{2}, D w_{4}=t_{3}^{2}, D w_{6}=t_{4}^{2} \\
D y=v_{2} v_{3} t_{1}+v_{1} v_{5} t_{2}, D z=w_{2} w_{3} t_{3}+w_{1} w_{5} t_{4} \\
D v=d v-v_{1} y t_{1}+v_{2} y t_{2}-w_{1} z t_{3}+w_{2} z t_{4} .
\end{gathered}
$$

Then $D \circ D=0$ and $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, t_{2}, t_{3}, t_{4}\right] \otimes \Lambda V, D\right)<\infty$. Thus $r_{0}\left(X_{2}\right) \geq 4$ and we deduce $r_{0}\left(X_{2}\right)<5$ by the direct (but complicated) calculations that $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, t_{2}, t_{3}, t_{4}, t_{5}\right] \otimes \Lambda V, D\right)=\infty$ for any $D$. Note the part $(*)$ of $P_{4}$ is applied for all differentials below.
$P_{5}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v=d v, D y=t^{4}, D v_{i}=D w_{i}=D u=D z=0$.
$P_{6}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D\right)\right]$ such that $D v_{i}=0$ for $i \neq 4, D v_{4}=t_{1}^{2}, D w_{i}=D u=0$,
$D y=v_{2} v_{3} t_{1}, D v=d v-v_{1} y t_{1}, D z=t_{2}^{4}$.
$P_{8}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v=d v-v_{1} y t+v_{2} y t-w_{1} z t, D y=v_{2} v_{3} t+v_{1} v_{5} t$, $D z=w_{2} w_{3} t, D v_{4}=D v_{6}=D w_{4}=t^{2}, D w_{6}=0$.
$P_{9}=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D\right)\right]=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D^{\prime}\right)\right]=\left[\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda V, D^{\prime \prime}\right)\right]$ with

$$
\begin{gathered}
D v_{4}=t_{1}^{2}, D v_{6}=D w_{4}=D w_{6}=t_{2}^{2}, D y=v_{2} v_{3} t_{1}+v_{1} v_{5} t_{2} \\
D z=w_{2} w_{3} t_{2}+w_{1} w_{5} t_{2}, D v=d v-v_{1} y t_{1}+v_{2} y t_{2}-w_{1} z t_{2}+w_{2} z t_{2} \\
D^{\prime} v_{i}=D^{\prime} w_{i}=D^{\prime} u=0, D^{\prime} y=t_{1}^{4}, D^{\prime} z=t_{2}^{4}, D^{\prime} v=d v \\
D^{\prime \prime} v_{4}=t_{2}^{2}, D^{\prime \prime} v_{6}=D^{\prime \prime} w_{4}=D^{\prime \prime} w_{6}=t_{1}^{2}, D^{\prime \prime} y=v_{2} v_{3} t_{2}+v_{1} v_{5} t_{1}, \\
D^{\prime \prime} z=w_{2} w_{3} t_{1}+w_{1} w_{5} t_{1}, D^{\prime \prime} v=d v-v_{1} y t_{2}+v_{2} y t_{1}-w_{1} z t_{1}+w_{2} z t_{1} .
\end{gathered}
$$

Note that $P_{1}<P_{9}$ is given by $D, P_{5}<P_{9}$ by $D^{\prime}$ and $P_{8}<P_{9}$ by $D^{\prime \prime}$.
$P_{10}=[(\mathbb{Q}[t] \otimes \Lambda V, D)]$ with $D v_{4}=D v_{6}=D w_{4}=D w_{6}=t^{2}, D y=v_{2} v_{3} t+v_{1} v_{5} t$,
$D z=w_{2} w_{3} t+w_{1} w_{5} t, D v=d v-v_{1} y t+v_{2} y t-w_{1} z t+w_{2} z t$.

## 4 Proof of Theorem 1.5

Let $G$ be a connected, non-directed, finite, simple(i.e., without multiple edges, loops), based graph with the vertex set $V(G)=\left\{v_{0}, v_{1}, . ., v_{N}\right\}$ of the base point $v_{0}$. For the set of distances $D_{0}=\left\{d\left(v_{0}, v_{i}\right) \mid v_{i} \in V(G)\right\}_{i}$ between the points of $G$ and $v_{0}$, put $n=\max D_{0}$. Suppose that a path of length $n$

$$
\begin{equation*}
l_{0}: v_{0} \rightarrow v_{i_{1}} \rightarrow \cdots \rightarrow v_{i_{n-1}} \rightarrow v_{i_{n}} \tag{0}
\end{equation*}
$$

with $d\left(v_{0}, v_{i_{n}}\right)=n$ is unique.
Then put $\psi\left(v_{0}\right):=(0,0)$ and

$$
\psi\left(v_{i_{u}}\right):=(0, u) \in \mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0}
$$

for $u=1, . ., n$.
Next put $D_{1}=\left\{d\left(v_{0}, v_{j}\right) \mid v_{j} \in V_{1}=V(G)-V\left(l_{0}\right)\right\}_{j}$ and the set of paths with length $n_{1}=\max D_{1}$ as

$$
L_{1}=\left\{l_{1, j}\right\}_{j}=\left\{v_{0} \rightarrow v_{j_{1}} \rightarrow \cdots \rightarrow v_{j_{n_{1}-1}} \rightarrow v_{j_{n_{1}}} \mid d\left(v_{0}, v_{j_{n_{1}}}\right)=n_{1}, v_{j_{n_{1}}} \in V_{1}\right\}_{j} .
$$

Here $V\left(l_{0}\right)=\left\{v_{0}, v_{i_{1}}, . ., v_{i_{n}}\right\}$. Suppose that (for some $c$ )

$$
\begin{equation*}
j_{m} \neq i_{m} \text { for } m>c \text { if } j_{c} \neq i_{c} \tag{1}
\end{equation*}
$$

For a path $l_{1, j}$ of $L_{1}$, if $v_{j_{c}}=v_{i_{c}}$ for $c=0, . ., m-1$ and $v_{j_{m}} \neq v_{i_{m}}$, put

$$
\psi\left(v_{j_{u}}\right):=\left(n-n_{1}, u\right) \in \mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0}
$$

for $u=m, m+1, . ., n_{1}$.
Next put $D_{2}=\left\{d\left(v_{0}, v_{k}\right) \mid v_{k} \in V_{2}=V(G)-\left(V\left(l_{0}\right) \cup V\left(L_{1}\right)\right)\right\}_{k}$ and the set of paths of with length $n_{2}=\max D_{2}$

$$
L_{2}=\left\{l_{2, k}\right\}_{k}=\left\{v_{0} \rightarrow v_{k_{1}} \rightarrow \cdots \rightarrow v_{k_{n_{2}-1}} \rightarrow v_{k_{n_{2}}} \mid d\left(v_{0}, v_{k_{n_{2}}}\right)=n_{2}, v_{k_{n_{2}}} \in V_{2}\right\}_{k} .
$$

Suppose that (for some $c$ )

$$
\begin{gathered}
k_{m} \neq i_{m} \text { for } m>c \text { if } k_{c} \neq i_{c} \text { and } \\
k_{m} \neq i_{m}, j_{m} \text { for } m>c \text { if } k_{c} \neq j_{c} . \quad \cdots(2)
\end{gathered}
$$

For a path $l_{2, k}$ of $L_{2}$, if $v_{k_{c}}=v_{i_{c}}$ or $v_{k_{c}}=v_{j_{c}}$ for $c=0, . ., m-1$ but $v_{k_{m}} \neq v_{i_{m}}$ and $v_{k_{m}} \neq v_{j_{m}}$, put

$$
\psi\left(v_{k_{u}}\right):=\left(n-n_{2}, u\right) \in \mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0}
$$

for $u=m, m+1, . ., n_{2}$.
Iterating this argument, we have an injection $\psi: V(G) \rightarrow \mathbb{Z}_{\geq 0} \times \mathbb{Z}_{\geq 0}$ and it is naturally extended to the map from the set of edges, $\tilde{\psi}: E(G) \rightarrow \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0}$ as $\tilde{\psi}\left(v_{a} v_{b}\right)=\psi\left(v_{a}\right)-\psi\left(v_{b}\right)$, the line segment with extremal points $\psi\left(v_{a}\right)$ and $\psi\left(v_{b}\right)$, for any edge $v_{a} v_{b}$ of $G$. Thus there is the embedding of $G$ into $\mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0}$


Notice that two graphs $G$ and $G^{\prime}$ satisfying (0),(1),(2),.. are isomorphic as based graphs if and only if $\tilde{\psi} G=\tilde{\psi} G^{\prime}$.

Proof of Theorem 1.5. If $G=G \mathcal{H}(X)$, the above conditions (0), (1), (2),.. are satisfied from Lemma 1.3. Thus the above map $\tilde{\psi}$ is defined and we see $\tilde{\psi} G \mathcal{H}(X)=$ $\tilde{\phi} G \mathcal{H}(X)$ in $\mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0}$. Suppose $\mathcal{H}(X) \neq \mathcal{H}(Y)$. Then $\tilde{\psi} G \mathcal{H}(X)=\tilde{\phi} G \mathcal{H}(X) \neq$ $\tilde{\phi} G \mathcal{H}(Y)=\tilde{\psi} G \mathcal{H}(Y)$. Thus $G \mathcal{H}(X)$ and $G \mathcal{H}(Y)$ are not isomorphic as based graphs.

## 5 Appendix

Recall an edge of $G \mathcal{H}(X)$ is represented by a rationalized Borel fibration

$$
Y_{\mathrm{Q}} \rightarrow\left(E S^{1} \times_{S^{1}} Y\right)_{\mathrm{Q}} \rightarrow B S_{\mathrm{Q}}^{1}
$$

where $Y_{\mathrm{Q}} \in \mathcal{X}_{n}$ and $\left(E S^{1} \times_{S^{1}} Y\right)_{\mathrm{Q}} \in \mathcal{X}_{n+1}$ for some $n$. It is given as

in $\tilde{\phi} G \mathcal{H}(X)$.
Definition 5.1. Suppose $Y_{Q} \in \mathcal{X}_{n}$. For two elements $Y_{1}=\left(E S^{1} \times_{S^{1}}^{\mu_{1}} Z_{1}\right)_{Q}$ and $Y_{2}=$ $\left(E S^{1} \times_{S^{1}}^{\mu_{2}} Z_{2}\right)_{\mathrm{Q}}$ of $\mathcal{X}_{n+1}$, we denote

$$
Y_{1} \underset{Y_{3}}{\sim} Y_{2}
$$

if there exists a homotopy commutative diagram of fiber inclusions of rationalized Borel fibrations over $B S_{Q}^{1}$

where $Z_{1 Q} \simeq Z_{2 Q} \simeq Z_{3 Q} \simeq Y_{\mathrm{Q}}$ and $\operatorname{dim} H^{*}\left(Y_{3} ; Q\right)<\infty$.
Note $Y_{3} \in \mathcal{X}_{n+2}$ and in general $r_{0}\left(Y_{1}\right) \neq r_{0}\left(Y_{2}\right)$. The Sullivan model is given as the DGA-homotopy commutative diagram of natural projections

with $\operatorname{dim} H^{*}\left(\mathbb{Q}\left[t_{1}, t_{2}\right] \otimes \Lambda W, D\right)<\infty$. Here $W=\mathbb{Q}\left(t_{3}, . ., t_{n+2}\right) \oplus V$ for $M(X)=$ $(\Lambda V, d)$ and $d_{W} \mid V=d$. Remark that Definition 5.1 is not an equivalence relation.
Definition 5.2. For edges (1-cells) $P_{a} P_{b}, P_{a} P_{d}, P_{b} P_{c}$ and $P_{d} P_{c}$ in $G \mathcal{H}(X)$, which is given as (a horizontal deformation of)

in $\tilde{\phi} G \mathcal{H}(X)$, we say that a 2-cell attaches on the 1-cycle $\square P_{a} P_{b} P_{c} P_{d}$ (or simply that $\square P_{a} P_{b} P_{c} P_{d}$ makes a leaf) and denote as $\partial e^{2}=\square P_{a} P_{b} P_{c} P_{d}$ if $Y_{1} \sim_{Y_{3}} Y_{2}$ for $\left[Y_{\mathrm{Q}}\right]=P_{a}$, $\left[Y_{1}\right]=P_{b},\left[Y_{2}\right]=P_{d}$ and $\left[Y_{3}\right]=P_{c}$.

The existence of a leaf may depend on the degree of certain freedom of $\{D\}$ that represent the upper right point $P_{c}$ of a cycle $\square P_{a} P_{b} P_{c} P_{d}$. In Example 3.8, we easily find that $\square P_{0} P_{5} P_{9} P_{8}$ makes a leaf by $D v_{1}=D v_{2}=D v_{4}=0, D v_{3}=v_{1} v_{2}$,

$$
\begin{gathered}
D v_{5}=v_{1} v_{4} t_{1}+t_{1}^{7} \text { and } \\
D v_{6}=v_{2} v_{4} t_{2}^{3}+v_{1} v_{3} t_{2}^{5}+t_{2}^{9}
\end{gathered}
$$

where $[D]=P_{9},\left[D_{1}\right]=P_{5}$ and $\left[D_{2}\right]=P_{8}$. Indeed, then the above DGA-diagram is commutative. But, in Example 3.9, the author can not find a differential $D$ that makes the above homotopy commutative diagram for the 1-cycle $\square P_{0} P_{5} P_{9} P_{8}$.

In general, if $G \mathcal{H}(X)$ contains (a horizontal deformation of)

as a sub-graph with $\partial e_{1}^{2}=\square P Q_{1} R Q_{2}, \partial e_{2}^{2}=\square P Q_{2} R Q_{3}$ and $\partial e_{3}^{2}=\square P Q_{1} R Q_{3}$, then $\mathcal{K}(X)$ contains

$$
\left(e_{1}^{2} \cup e_{2}^{2}\right) \cup_{\square P Q_{1} R Q_{3}} e_{3}^{2} \cong S^{2}
$$

Thus three pieces of leaf can make a 2 -sphere.
Remark 5.3. To append certain further informations of $\mathcal{X}$ on $\mathcal{T}_{0}(X)$, it may be suitable to regard $\left(\mathcal{T}_{0}(X)\right.$ as the 0 -skeleton and) the based graph $G \mathcal{H}(X)$ as the 1-skeleton of a finite CW complex $\mathcal{T}(X)$, which is obtained by generalizing Definition 5.2. When $\tilde{\phi} \mathcal{G H}(X)$ contains (a horizontal deformation of)

as a sub-graph, then a 3-cell of $\mathcal{T}(X)$ is given by the existence of the homotopy commutative diagram of natural projections

which represents the above sub-graph. Similarly we can construct higher dimensional CW-structure, which makes a complex $\mathcal{T}(X)$. It must be a topological homotopy invariant of spaces. (The complex $\mathcal{T}(X)$ is at most 2-dimensional if $r_{0}(X) \leq 5$.) If $\mathcal{T}(X)$ is compared to a plant, then the base point $X_{\mathrm{Q}}$ corresponds to the seed (that grows up to be the plant), and $B S_{Q^{2}}^{1}$, the water (that is necessary for its growth).

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[^0]:    Received by the editors March 2009 - In revised form in June 2010. Communicated by Y. Félix.
    2000 Mathematics Subject Classification : 55P62, 57 S99.
    Key words and phrases : rational toral rank, rational homotopy type, Sullivan minimal model.

