

# An entropy solution for some degenerate or singular obstacle parabolic problems with $L^1$ —data via a sequence of penalized equations

E. Azroul      H. Redwane      M. Rhoudaf

## Abstract

We give an existence result of the obstacle parabolic degenerate or singular problem associated to the equation,  $\frac{\partial u}{\partial t} + A(u) = f$  in  $Q_T$ , where  $A$  is a classical Leray-Lions operator acting from the weighted Sobolev space  $L^p(0, T, W_0^{1,p}(\Omega, w))$  into its dual  $L^{p'}(0, T, W^{-1,p'}(\Omega, w^*))$ , while the datum  $f$  is assumed to lie in  $L^1(Q_T)$ . The proof is based on the penalization methods.

## 1 Introduction

In this paper, we investigate the problem of existence of solutions of the obstacle problems associated to the following initial-boundary value problem:

$$(P_e) \begin{cases} \frac{\partial u}{\partial t} - \operatorname{div}(a(x, t, u, \nabla u)) = f & \text{in } Q_T = \Omega \times (0, T) \\ u = 0 & \text{on } \Sigma = \partial\Omega \times (0, T) \\ u(0) = u_0 & \text{in } \Omega, \end{cases}$$

where  $\Omega$  is an open bounded subset of  $\mathbb{R}^N$ ,  $N \geq 1$ ,  $T > 0$ , and we have set  $Q_T$  the cylinder  $\Omega \times (0, T)$  and  $\Sigma$  its lateral surface.

We assume that  $-\operatorname{div}(a(x, t, u, \nabla u))$  is a Leray-Lions operator defined from the weighted Sobolev space  $L^p(0, T, W_0^{1,p}(\Omega, w))$  into its dual  $L^{p'}(0, T, W^{-1,p'}(\Omega, w^*))$

---

Received by the editors September 2009.

Communicated by P. Godin.

2000 *Mathematics Subject Classification* : Primary 47A15; Secondary 46A32, 47D20.

*Key words and phrases* : Weighted Sobolev spaces, degenerated obstacle, penalized equations.

where  $w = \{w_i, 0 \leq i \leq N\}$  is collection of weight functions on  $\Omega$ ,  $1 \leq p \leq \infty$ ,  $w^* = \{w_i^{1-p'}, 0 \leq i \leq N\}$ , and where  $a(x, t, s, \xi) : Q_T \times \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}^N$  is a Carathodory function satisfy some suitable hypotheses (see assumption  $(H_2)$ ). The data  $f \in L^1(Q_T)$ ,  $u_0 \in L^1(\Omega)$  and  $u_0 \geq 0$ .

More precisely, this paper deals with the existence of a solution to the obstacle degenerate or singular parabolic problem associated to  $(P_e)$  in the sense of entropy solution:

$$(P_u) \left\{ \begin{array}{l} u \geq \psi \text{ a.e. in } Q_T \\ T_k(u) \in L^p(0, T, W_0^{1,p}(\Omega, w)), u \in C([0, T], L^1(\Omega)) \\ \int_{\Omega} S_k(u - \varphi)(\tau) dx + \int_{Q_\tau} \frac{\partial \varphi}{\partial t} T_k(u - \varphi) dx dt \\ \quad + \int_{Q_\tau} a(x, t, u, \nabla u) \nabla T_k(u - \varphi) dx dt \\ \leq \int_{Q_\tau} f T_k(u - \varphi) dx dt + \int_{\Omega} S_k(u_0 - \varphi(x, 0)) dx \quad \forall \tau \in [0, T], \forall k > 0 \\ \varphi \in K_\psi \cap L^\infty(Q_T) \cap C([0, T], L^1(\Omega)) \text{ such that } \frac{\partial \varphi}{\partial t} \in L^{p'}(W^{-1,p'}(\Omega, w^*)). \end{array} \right.$$

where  $S_k(t) = \int_0^t T_k(s) ds$ ,  $K_\psi = \{u \in L^p(0, T, W_0^{1,p}(\Omega, w)), u \geq \psi \text{ a.e. in } Q_T\}$ . and  $\psi \in L^\infty(\Omega) \cap W_0^{1,p}(\Omega, w)$ .

The aim of our work is to investigate the relationship between the obstacle problem  $(P_u)$  and some penalized sequence of approximate equations. More precisely letting  $\{f_\epsilon\}$  and  $u_0^\epsilon$  be a standard approximation of  $f$  and  $u_0$  (that is  $f_\epsilon \rightarrow f$  in  $L^1(Q)$  and  $u_0^\epsilon \rightarrow u_0$  in  $L^1(\Omega)$ ), and considering the following penalized sequence of approximate equations:

$$(P_\epsilon^\epsilon) \left\{ \begin{array}{ll} \frac{\partial u_\epsilon}{\partial t} - \operatorname{div}(a(x, t, u_\epsilon, \nabla u_\epsilon)) - \frac{1}{\epsilon} T_\epsilon(u_\epsilon - \psi)^- = f_\epsilon & \text{in } Q_T \\ u_\epsilon = 0 & \text{on } \Sigma \\ u_\epsilon(0) = u_0^\epsilon & \text{in } \Omega. \end{array} \right.$$

We study the possibility to find a solution of  $(P_u)$  as a limit of a subsequence  $\{u_\epsilon\}$  of solutions of  $(P_\epsilon^\epsilon)$ .

The penalized term  $\frac{1}{\epsilon} T_\epsilon(u_\epsilon - \psi)^-$  introduced in  $(P_\epsilon^\epsilon)$  play a crucial role in the proof of our main result, in particular this term allows to prove that the solution  $u$  of  $(P_u)$  belongs in the convex set  $K_\psi$  (that is  $u \geq \psi$ ).

A priori estimates of  $T_k(u_\epsilon)$  are obtained in the general settings  $L^p(0, T, W_0^{1,p}(\Omega, w))$ . For the passage to the limit, we prove the strong converge of the truncation of  $u_\epsilon$  and the almost everywhere convergence of  $\nabla u_\epsilon$ . The model example is an equation,

$$\frac{\partial u}{\partial t} - \Delta_{p,w} u = f,$$

where  $\Delta_{p,w}$  is the so-called degenerate or singular  $p$ -Laplacian operator, that is  $\Delta_{p,w}(u) = -\operatorname{div}(w(x)|\nabla u|^{p-2}\nabla u)$ , where  $w(x)$  is some weight function defined on  $\Omega$  (see section 3 for more details).

In this context of degenerate or singular parabolic problems, existence results for

$(P_e)$  have been proved in [2] when the data  $f$  belongs to  $L^p(0, T, W^{-1,p'}(\Omega))$  and  $u_0$  is in  $L^2(\Omega)$ , while the strongly nonlinear variational case is investigated in [3]. For the nondegenerated cases, we refer the reader to ([14], [25], [26]).

Let us mention that our paper can be seen as a continuation of the works ([2], [3]) and as a generalization of the works ([14], [25], [26]).

## 2 Abstract framework

Let  $\Omega$  be a bounded open subset of  $\mathbb{R}^N$ ,  $p$  be a real number such that  $1 < p < \infty$  and  $w = \{w_i(x), 1 \leq i \leq N\}$  be a vector of weight functions, i.e., every component  $w_i(x)$  is a measurable function which is strictly positive a.e. in  $\Omega$ . Further, we suppose in all this section that, there exists

$$r_0 > \max(N, p) \text{ such that } w_i^{\frac{r_0}{r_0-p}} \in L^1_{loc}(\Omega) \quad (2.1)$$

and

$$w_i^{\frac{-1}{p-1}} \in L^1_{loc}(\Omega) \quad (2.2)$$

for any  $0 \leq i \leq N$ .

We denote by  $W^{1,p}(\Omega, w)$  the space of all real-valued functions  $u \in L^p(\Omega, w_0)$  such that the derivatives in the sense of distributions fulfill

$$\frac{\partial u}{\partial x_i} \in L^p(\Omega, w_i) \text{ for all } i = 1, \dots, N.$$

Which is a Banach space under the norm,

$$\|u\|_{1,p,w} = \left[ \int_{\Omega} |u(x)|^p w_0 \, dx + \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u(x)}{\partial x_i} \right|^p w_i(x) \, dx \right]^{\frac{1}{p}}. \quad (2.3)$$

The condition (2.1) implies that  $C_0^\infty(\Omega)$  is a subset of  $W^{1,p}(\Omega, w)$  and consequently, we can introduce the subspace  $W_0^{1,p}(\Omega, w)$  of  $W^{1,p}(\Omega, w)$  as the closure of  $C_0^\infty(\Omega)$  with respect to the norm (2.3). Moreover, the condition (2.2) implies that  $W^{1,p}(\Omega, w)$  as well as  $W_0^{1,p}(\Omega, w)$  are reflexive Banach spaces.

We recall that the dual space of weighted Sobolev spaces  $W_0^{1,p}(\Omega, w)$  is equivalent to  $W^{-1,p'}(\Omega, w^*)$ , where  $w^* = \{w_i^* = w_i^{1-p'}, i = 0, \dots, N\}$  and where  $p'$  is the conjugate of  $p$ , i.e.,  $p' = \frac{p}{p-1}$ . For more details about the weighted Sobolev spaces, we refer the reader to [18].

Now we turn out to give some fundamental results which allow to study the parabolic problems in a general settings of weighted Sobolev spaces.

In order to deal with time derivative, we introduce a time mollification of a function  $u$  belonging in some weighted Lebesgue space. Thus we define for all  $\mu \geq 0$  and all  $(x, t) \in Q_T$  :  $u_\mu = \mu \int_{-\infty}^t \tilde{u}(x, s) \exp(\mu(s-t)) \, ds$  where  $\tilde{u}(x, s) = u(x, s) \chi_{(0,T)}$ .

**Proposition 2.1.** (cf. [3])

1) If  $u \in L^p(Q_T, w_i)$ , then,  $u_\mu$  is measurable in  $Q_T$ ,  $\frac{\partial u_\mu}{\partial t} = \mu(u - u_\mu)$  and

$$\left( \int_Q |u_\mu|^p w_i(x) dx dt \right)^{\frac{1}{p}} \leq \left( \int_Q |u|^p w_i(x) dx dt \right)^{\frac{1}{p}},$$

$$\text{i.e., } \|u_\mu\|_{L^p(Q_T, w_i)} \leq \|u\|_{L^p(Q_T, w_i)}.$$

2) If  $u \in W_0^{1,p}(Q_T, w)$ , then  $u_\mu \rightarrow u$  in  $W_0^{1,p}(Q_T, w)$  as  $\mu \rightarrow +\infty$ .

3) If  $u_n \rightarrow u$  in  $W_0^{1,p}(Q_T, w)$ , then  $(u_n)_\mu \rightarrow u_\mu$  in  $W_0^{1,p}(Q_T, w)$ .

Now, we give some imbedding and compactness results in weighted Sobolev Spaces which allow in particular to extend in the settings of weighted Sobolev spaces, some trace results and the Aubin's and Simon's results [27].

Let  $V = W_0^{1,p}(\Omega, w)$ ,  $H = L^2(\Omega, \sigma)$  (where  $\sigma$  is a weight function on  $\Omega$  such that  $\sigma \in L^1(\Omega)$  and  $\sigma^{-1} \in L^1(\Omega)$ ) and let  $V^* = W^{-1,p'}(\Omega, w^*)$ , with  $(2 \leq p < \infty)$ . Let  $X = L^p(0, T, V)$ . The dual space of  $X$  is  $X^* = L^{p'}(0, T, V^*)$  where  $\frac{1}{p'} + \frac{1}{p} = 1$  and denoting the space  $W_p^1(0, T, V, H) = \{v \in X : v' \in X^*\}$  endowed with the norm

$$\|u\|_{W_p^1} = \|u\|_X + \|u'\|_{X^*}, \quad (2.4)$$

which is a Banach space. Here  $u'$  stands for the generalized derivative of  $u$ , i.e.,

$$\int_0^T u'(t) \varphi(t) dt = - \int_0^T u(t) \varphi'(t) dt \text{ for all } \varphi \in C_0^\infty(0, T).$$

**Lemma 2.2.** The Banach space  $H$  is an Hilbert space and its dual  $H'$  can be identified with him self, i.e.,  $H' \simeq H$ .

*Proof.* Indeed, let

$$\begin{aligned} F : H \times H &\rightarrow \mathbb{R} \\ (f, g) &\mapsto \int_\Omega f g \sigma dx. \end{aligned}$$

Remark that  $F$  is a symmetric bilinear form, which is also continuous and defined positively, since

$$\int_\Omega f g \sigma dx = \int_\Omega f \sigma^{\frac{1}{2}} g \sigma^{\frac{1}{2}} dx \leq \left( \int_\Omega |f|^2 \sigma dx \right)^{\frac{1}{2}} \left( \int_\Omega |g|^2 \sigma dx \right)^{\frac{1}{2}}.$$

Then, the Banach space  $H$  is an Hilbert space. Finally by a standard argument, we can identified  $H$  with its dual  $H'$  i.e.,  $H' \simeq H$ . ■

**Lemma 2.3.** (cf. [3])

The evolution triple  $V \subseteq H \subseteq V^*$  is verified.

**Lemma 2.4.** (cf. [3])

Assume that,  $\frac{\partial u_n}{\partial t} = h_n + k_n$  in  $D'(\Omega)$ , where  $h_n$  and  $k_n$  are bounded respectively in  $L^{p'}(0, T, W^{1,p'}(\Omega, w^*))$  and in  $L^1(Q_T)$ .

If  $u_n$  is bounded in  $L^p(0, T, W_0^{1,p}(\Omega, w))$ , then  $u_n \rightarrow u$  in  $L_{loc}^p(Q_T, \sigma)$ .

**Lemma 2.5.** (cf. [3])

Let  $g \in L^r(Q_T, \gamma)$  and let  $g_n \in L^r(Q_T, \gamma)$ , with  $\|g_n\|_{L^r(Q_T, \gamma)} \leq c, 1 < r < \infty$ . If  $g_n(x) \rightarrow g(x)$  a.e in  $Q_T$ , then  $g_n \rightharpoonup g$  in  $L^r(Q_T, \gamma)$ , where  $\rightharpoonup$  denotes weak convergence and  $\gamma$  is a weight function on  $Q_T$ .

**Lemma 2.6.** (cf. [29]) Let  $V \subseteq H \subseteq V^*$  be an evolution triple. Then the imbedding

$$W_p^1(0, T, V, H) \hookrightarrow C([0, T], H)$$

is continuous.

### 3 Basic assumptions and Main results

We suppose in all our considerations that, there exists

$$r_0 > \max(N, p) \text{ such that } w_i^{\frac{r_0}{r_0-p}} \in L_{loc}^1(\Omega) \text{ and } w_i^{\frac{-1}{p-1}} \in L_{loc}^1(\Omega),$$

for any  $0 \leq i \leq N$ . Now we state our basic assumptions:

**Assumption (H<sub>1</sub>).** For  $2 \leq p < \infty$ , we suppose that the expression:

$$|||u||| = \left( \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^p w_i(x) dx \right)^{\frac{1}{p}} \quad (3.1)$$

is a norm on  $W_0^{1,p}(\Omega, w)$  which is equivalent to (2.3) and that there exists a weight function  $\sigma$  on  $\Omega$  such that,

$$\sigma \in L^1(\Omega) \text{ and } \sigma^{-1} \in L^1(\Omega). \quad (3.2)$$

and for which the Hardy inequality,

$$\left( \int_{\Omega} |u(x)|^p \sigma dx \right)^{\frac{1}{p}} \leq c \left( \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^p w_i(x) dx \right)^{\frac{1}{p}}, \quad (3.3)$$

holds for every  $u \in W_0^{1,p}(\Omega, w)$  with a constant  $c > 0$  independent of  $u$ . Moreover, the imbedding

$$W_0^{1,p}(\Omega, w) \hookrightarrow L^p(\Omega, \sigma) \quad (3.4)$$

expressed by the inequality (3.3) is assumed compact.

Now we give some examples in which the abstract hypothesis (H<sub>1</sub>) is satisfied:

*Remark 3.1.* Assume that  $w_0(x) \equiv 1$  and there exists  $\nu \in ]\frac{N}{p}, +\infty[ \cap [\frac{1}{p-1}, +\infty[$  such that

$$w_i^{\frac{N}{N-1}}, w_i^{-\nu} \in L^1(\Omega) \text{ for all } i = 1, \dots, N. \quad (3.5)$$

Then, it's easily seen that the assumptions (3.5) imply that,

$$\|u\| = \left( \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^p w_i(x) dx \right)^{\frac{1}{p}} \quad (3.6)$$

is a norm defined on  $W_0^{1,p}(\Omega, w)$  and it's equivalent to (2.3) and that, the imbedding

$$W_0^{1,p}(\Omega, w) \hookrightarrow L^p(\Omega) \quad (3.7)$$

is compact [see [18], pp 46].

Thus the hypotheses  $(H_1)$  is satisfied for  $\sigma \equiv 1$ .

*Remark 3.2.* If we use the special weight functions  $w$  and  $\sigma$  expressed in terms of the distance to the boundary  $\partial\Omega$ . Denote  $d(x) = \text{dist}(x, \partial\Omega)$  and set  $w(x) = \sigma(x) = d^\lambda(x)$ . In this case, the Hardy inequality reads

$$\left( \int_Q |u|^p w(x) dx dt \right)^{\frac{1}{p}} \leq c \left( \int_Q |\nabla u|^p w(x) dx dt \right)^{\frac{1}{p}}$$

for

$$\lambda < (p-1) \frac{(N-1)}{N}. \quad (3.8)$$

The condition (3.8) is sufficient for the compact imbedding (3.4) holds (see for example [17],[18]).

**Assumption  $(H_2)$ .** Let  $a = (a_i)_{1 \leq i \leq N}$  be a family of Carathodory functions defined on  $Q \times \mathbb{R} \times \mathbb{R}^N$  such that for a.e.  $(x, t) \in Q$  and all  $s \in \mathbb{R}, \xi \in \mathbb{R}^N$

$$|a_i(x, t, s, \xi)| \leq \beta w_i^{\frac{1}{p}}(x) [c_1(x, t) + \sigma^{\frac{1}{p'}} |s|^{p-1} + \sum_{j=1}^N w_j^{\frac{1}{p'}}(x) |\xi_j|^{p-1}], \quad (3.9)$$

for  $1 \leq i \leq N$

$$[a(x, t, s, \xi) - a(x, t, s, \eta)](\xi - \eta) > 0 \text{ for all } \xi \neq \eta \in \mathbb{R}^N \quad (3.10)$$

$$a(x, t, s, \xi) \cdot \xi \geq \alpha \sum_{i=1}^N w_i |\xi_i|^p, \quad (3.11)$$

where  $c_1(x, t)$  is a positive function in  $L^{p'}(Q)$ , and  $\alpha, \beta$  are strictly positive constants.

**Assumption  $(H_3)$ .** Let  $K_\psi = \{u \in W_0^{1,p}(\Omega, w); u \geq \psi \text{ a.e. in } \Omega\}$ . where  $\psi : \Omega \rightarrow \overline{\mathbb{R}}$  is a measurable function on  $\Omega$  such that

$$K_\psi \cap L^\infty(\Omega) \neq \emptyset. \quad (3.12)$$

We suppose that

$$f \in L^1(\Omega), \quad (3.13)$$

and

$$u_0 \in L^1(\Omega) \text{ and } u_0 \geq 0 \text{ a.e. in } \Omega. \quad (3.14)$$

We recall that, for  $k > 1$  and  $s$  in  $\mathbb{R}$ , the truncation is defined as

$$T_k(s) = \begin{cases} s & \text{if } |s| \leq k \\ k \frac{s}{|s|} & \text{if } |s| > k. \end{cases}$$

Now, we recall the following lemmas:

**Lemma 3.3.** *Assume that  $(H_1)$  holds. Let  $F : \mathbb{R} \rightarrow \mathbb{R}$  be uniformly Lipschitzian, with  $F(0) = 0$ . Let  $u \in W_0^{1,p}(\Omega, w)$ . Then  $F(u) \in W_0^{1,p}(\Omega, w)$ . Moreover, if the set  $D$  of discontinuity points of  $F'$  is finite, then*

$$\frac{\partial(F \circ u)}{\partial x_i} = \begin{cases} F'(u) \frac{\partial u}{\partial x_i} & \text{a.e. in } \{x \in \Omega : u(x) \notin D\} \\ 0 & \text{a.e. in } \{x \in \Omega : u(x) \in D\}. \end{cases}$$

*Proof.* See [13] (see also [5]). ■

From the previous lemma, we deduce the following.

**Lemma 3.4.** *Assume that  $(H_1)$  holds. Let  $u \in W_0^{1,p}(\Omega, w)$ , and let  $T_k(u)$  be the usual truncation ( $k \in \mathbb{R}^+$ ), then  $T_k(u) \in W_0^{1,p}(\Omega, w)$ . Moreover, we have*

$$T_k(u) \rightarrow u \text{ strongly in } W_0^{1,p}(\Omega, w).$$

*Proof.* See [13] (see also [5]). ■

The following lemma generalizes to the weighted case the analogous Lemma 5 in [12]. For that, we use the method of [12] and [23] which gives the strong convergence of  $u_n$ .

**Lemma 3.5.** *Assume that  $(H_1)$  and  $(H_2)$  are satisfied and let  $(u_n)$  be a sequence in  $L^p(0, T, W_0^{1,p}(\Omega, w))$  such that  $u_n \rightharpoonup u$  weakly in  $L^p(0, T, W_0^{1,p}(\Omega, w))$  and*

$$\int_Q [a(x, t, u_n, \nabla u_n) - a(x, t, u_n, \nabla u)] [\nabla u_n - \nabla u] \, dxdt \rightarrow 0. \quad (3.15)$$

*Then,  $u_n \rightarrow u$  in  $L^p(0, T, W_0^{1,p}(\Omega, w))$ .*

*Proof.* See [3]. ■

## 4 Existence result

This section is devoted to establish the existence theorem.

**Theorem 4.1.** *Let  $u_0 \in L^1(\Omega)$  such that  $u_0 \geq 0$ . Assume that  $(H_1)$ ,  $(H_2)$  and  $(H_3)$  hold true. Then there exists at last one solution  $u \in C([0, T]; L^1(\Omega))$  such that  $u(x, 0) = u_0$  a.e. and for all  $\tau \in ]0, T]$ ,*

$$\left\{ \begin{array}{l} T_k(u) \in L^p(0, T, W_0^{1,p}(\Omega, w)), u \geq \psi \text{ a.e. in } \Omega, \\ \int_{\Omega} S_k(u(\tau) - \varphi(\tau)) dx + \langle \frac{\partial \varphi}{\partial t}, T_k(u - \varphi) \rangle_{Q_\tau} + \int_{Q_\tau} a(x, t, u, \nabla u) \nabla T_k(u - \varphi) dx dt \\ \leq \int_{Q_\tau} f T_k(u - \varphi) dx dt + \int_{\Omega} S_k(u_0 - \varphi(x, 0)) dx \\ \forall k > 0 \text{ and } \forall \varphi \in K_\psi \cap L^\infty(Q) \text{ such that } \frac{\partial \varphi}{\partial t} \in L^{p'}(0, T, W^{-1,p'}(\Omega, w^*)) \end{array} \right.$$

where  $Q_\tau = \Omega \times ]0, \tau[$ .

*Proof.* The proof is divided into 3 steps.

### Step 1: A priori estimates

Consider the approximate problem

$$(P_\epsilon) \left\{ \begin{array}{l} \frac{\partial u_\epsilon}{\partial t} - \operatorname{div}(a(x, t, u_\epsilon, \nabla u_\epsilon)) - \frac{1}{\epsilon} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- = f_\epsilon \\ u_\epsilon \in L^p(0, T, W_0^{1,p}(\Omega, w)), u_\epsilon(x, 0) = u_0^\epsilon \end{array} \right.$$

where  $f_\epsilon \rightarrow f$  strongly  $L^1(Q)$ ,  $u_0^\epsilon \rightarrow u_0$  strongly  $L^1(\Omega)$ .

Thanks to [3], there exists at least one solution of the problem  $(P_\epsilon)$ .

By choosing  $T_\gamma(u_\epsilon - T_\beta(u_\epsilon))$ ,  $\beta \geq \|\psi\|_\infty$  as test function in  $(P_\epsilon)$ , we get

$$\begin{aligned} & \langle \frac{\partial u_\epsilon}{\partial t}, T_\gamma(u_\epsilon - T_\beta(u_\epsilon)) \rangle + \int_{\{\beta \leq |u_\epsilon| \leq \beta + \gamma\}} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla u_\epsilon dx dt \\ & - \int_Q \frac{1}{\epsilon} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- T_\gamma(u_\epsilon - T_\beta(u_\epsilon)) dx dt = \int_Q f_\epsilon T_\gamma(u_\epsilon - T_\beta(u_\epsilon)) dx dt \end{aligned} \quad (4.1)$$

On the one hand, we have

$$\langle \frac{\partial u_\epsilon}{\partial t}, T_\gamma(u_\epsilon - T_\beta(u_\epsilon)) \rangle = \int_{\Omega} S_\gamma^\beta(u_\epsilon(T)) dx - \int_{\Omega} S_\gamma^\beta(u_\epsilon^0) dx \quad (4.2)$$

where  $S_\gamma^\beta(s) = \int_0^s T_\gamma(t - T_\beta(t)) dt$ . Since  $a$  satisfies (3.11) and by using the fact that  $\int_{\Omega} S_\gamma^\beta(u_\epsilon(T)) dx \geq 0$  and  $|\int_{\Omega} S_\gamma^\beta(u_\epsilon^0) dx| \leq \gamma \|u_\epsilon^0\|$ , we get  $\forall \epsilon > 0$ :

$$\begin{aligned} & \alpha \int_{\{\beta \leq |u_\epsilon| \leq \beta + \gamma\}} \sum_{i=1}^N \left| \frac{\partial u_\epsilon}{\partial x_i} \right|^p w_i(x) dx dt \\ & - \frac{1}{\epsilon} \int_Q T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- T_\gamma(u_\epsilon - T_\beta(u_\epsilon)) dx dt \leq c\gamma, \end{aligned} \quad (4.3)$$



where  $c$  is a constant which varies from line to line and which depends only the data. It follows that

$$-\int_Q \frac{1}{\epsilon} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- \frac{T_\gamma(u_\epsilon - T_\beta(u_\epsilon))}{\gamma} dx dt \leq c$$

since  $-\int_Q \frac{1}{\epsilon} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- \frac{T_\gamma(u_\epsilon - T_\beta(u_\epsilon))}{\gamma} dx dt \geq 0$ , for every  $\beta \geq \|\psi\|_\infty$ , we deduce by Fatou's lemma as  $\gamma \rightarrow 0$  that

$$\int_Q \frac{1}{\epsilon} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- \leq c. \quad (4.4)$$

Using in  $(P_\epsilon)$  the test function  $T_\epsilon(u_\epsilon)\chi_{(0,\tau)}$ , we get for every  $\tau \in (0, T)$ ,

$$\begin{aligned} \int_\Omega S_k(u_\epsilon(\tau)) dx + \int_{Q_\tau} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) \nabla T_k(u_\epsilon) dx dt \\ - \frac{1}{\epsilon} \int_Q T_{\frac{1}{\epsilon}}((u_\epsilon - \psi)^-) T_k(u_\epsilon) dx dt \leq ck, \end{aligned}$$

which gives thanks to (4.4):

$$\int_\Omega S_k(u_\epsilon(\tau)) dx + \int_{Q_\tau} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) dx dt \leq ck. \quad (4.5)$$

Then,

$$\alpha \int_Q \sum_{i=1}^N \left| \frac{\partial T_k(u_\epsilon)}{\partial x_i} \right|^p w_i(x) dx dt \leq ck, \quad \forall k \geq 1. \quad (4.6)$$

Hence,  $T_k(u_\epsilon)$  is bounded in  $L^p(0, T, W_0^{1,p}(\Omega, w))$ .

Let  $k > 0$  large enough and  $B_R$  be a ball of  $\Omega$ , we have,

$$\begin{aligned} k \text{ meas}(\{|u_\epsilon| > k\} \cap B_R \times [0, T]) = \\ \int_0^T \int_{\{|u_\epsilon| > k\} \cap B_R} |T_k(u_\epsilon)| dx dt \leq \int_0^T \int_{B_R} |T_k(u_\epsilon)| dx dt \\ \leq \left( \int_Q |T_k(u_\epsilon)|^p w_0 dx dt \right)^{\frac{1}{p}} \times \left( \int_0^T \int_{B_R} w_0^{1-p'} dx dt \right)^{\frac{1}{p'}} \end{aligned}$$

then, thanks to  $(H_1)$ , we deduce that,

$$k \text{ meas}(\{|u_\epsilon| > k\} \cap B_R \times [0, T]) \leq c \left( \int_Q \sum_{i=1}^N \left| \frac{\partial T_k(u_\epsilon)}{\partial x_i} \right|^p w_i(x) dx dt \right)^{\frac{1}{p}} \leq c k^{\frac{1}{p}} \quad (4.7)$$

which implies that,  $\text{meas}(\{|u_\epsilon| > k\} \cap B_R \times [0, T]) \leq \frac{c_1}{k^{1-\frac{1}{p}}}$ ,  $\forall k \geq 1$ . So, we have,

$$\lim_{k \rightarrow +\infty} (\text{meas}(\{(x, t) \in Q : |u_\epsilon| > k\} \cap B_R \times [0, T])) = 0 \quad (4.8)$$

uniformly with respect to  $\epsilon$ .

Consider now a function nondecreasing  $\xi_k \in C^2(\mathbb{R})$  such that

$$\begin{cases} \xi_k(s) = s & \text{for } |s| \leq \frac{k}{2} \\ \xi_k(s) = k & \text{for } |s| \geq k. \end{cases}$$

Multiplying the approximate equation by  $\xi'_k(u_\epsilon)$ , we get

$$\begin{aligned} \frac{\partial}{\partial t}(\xi_k(u_\epsilon)) - \operatorname{div}(a(x, t, u_\epsilon, \nabla u_\epsilon) \xi'_k(u_\epsilon)) + a(x, t, u_\epsilon, \nabla u_\epsilon) \xi''_k(u_\epsilon) \\ - \frac{1}{\epsilon} T_{\frac{1}{\epsilon}}((u_\epsilon - \psi)^-) \xi'_k(u_\epsilon) = f_\epsilon \xi'_k(u_\epsilon), \end{aligned}$$

in the sense of distribution.

This implies, thanks to (4.6) and the fact that  $\xi'_k$  has compact support, that  $\xi_k(u_\epsilon)$  is bounded in  $L^p(0, T, W_0^{1,p}(\Omega, w))$ , while its time derivative  $\frac{\partial}{\partial t}(\xi_k(u_\epsilon))$  is bounded in  $L^{p'}(0, T, W^{-1,p'}(\Omega, w^*)) + L^1(Q_T)$ , hence lemma 3.3 allows us to conclude that  $\xi_k(u_\epsilon)$  is compact in  $L^p_{loc}(Q_T, \sigma)$ .

Thus, for a subsequence, it also converges in measure and almost everywhere in  $Q_T$  since we have, for every  $\lambda > 0$

$$\begin{aligned} \operatorname{meas}(\{|u_\epsilon - u_\eta| > \lambda\} \cap B_R \times [0, T]) &\leq \operatorname{meas}(\{|u_\epsilon| > \frac{k}{2}\} \cap B_R \times [0, T]) \\ &+ \operatorname{meas}(\{|u_\eta| > \frac{k}{2}\} \cap B_R \times [0, T]) + \operatorname{meas}(\{|\xi_k(u_\epsilon) - \xi_k(u_\eta)| > \lambda\} \cap B_R \times [0, T]). \end{aligned} \quad (4.9)$$

Let  $\sigma > 0$ , then, by (4.8) and the fact that  $\xi_k(u_\epsilon)$  is compact in  $L^p_{loc}(Q_T, \sigma)$ , there exists  $k(\sigma) > 0$  such that,  $\operatorname{meas}(\{|u_\epsilon - u_\eta| > \lambda\} \cap B_R \times [0, T]) \leq \sigma$  for all  $\epsilon, \eta \leq \epsilon_0(k(\sigma), \lambda, R)$ . This proves that  $(u_\epsilon)$  is a Cauchy sequence in measure in  $B_R \times [0, T]$ , thus converges almost everywhere to some measurable function  $u$ . Then for a subsequence denoted again  $u_\epsilon$ , we can deduce from (4.6) that,

$$T_k(u_\epsilon) \rightharpoonup T_k(u) \text{ weakly in } L^p(0, T, W_0^{1,p}(\Omega, w)). \quad (4.10)$$

and then, the compact imbedding (3.4) gives,

$$T_k(u_\epsilon) \rightarrow T_k(u) \text{ strongly in } L^p(Q_T, \sigma) \text{ and a.e. in } Q_T. \quad (4.11)$$

## Step 2: About the gradient of approximate solutions.

In the sequel and throughout the paper, we will denote  $\alpha(\epsilon, \mu, s)$  all quantities (possibly different) such that,  $\lim_{s \rightarrow \infty} \lim_{\mu \rightarrow \infty} \lim_{\epsilon \rightarrow +0} \alpha(\epsilon, \mu, s) = 0$ . Taking now  $T_\eta(u_\epsilon - (T_k(u))_\mu)$ ,  $\eta > 0$  as test function in  $(P_\epsilon)$ , we get

$$\begin{aligned} \left\langle \frac{\partial u_\epsilon}{\partial t}, T_\eta(u_\epsilon - (T_k(u))_\mu) \right\rangle + \int_Q a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla T_\eta(u_\epsilon - (T_k(u))_\mu) \\ - \frac{1}{\epsilon} \int_{Q_T} T_{\frac{1}{\epsilon}}((u_\epsilon - \psi)^-) T_\eta(u_\epsilon - (T_k(u))_\mu) dx dt \leq c\eta, \end{aligned}$$

which implies that,

$$\begin{aligned} \left\langle \frac{\partial u_\epsilon}{\partial t}, T_\eta(u_\epsilon - (T_k(u))_\mu) \right\rangle + \int_{Q_T} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla T_\eta(u_\epsilon - (T_k(u))_\mu) dx dt \\ \leq \frac{\eta}{\epsilon} \int_{Q_T} T_{\frac{1}{\epsilon}}((u_\epsilon - \psi)^-) dx dt + c\eta \end{aligned}$$

and by (4.4)

$$\left\langle \frac{\partial u_\epsilon}{\partial t}, T_\eta(u_\epsilon - T_k(u)_\mu) \right\rangle + \int_{Q_T} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla T_\eta(u_\epsilon - (T_k(u)_\mu)) \leq c\eta. \quad (4.12)$$

The first term of the left-hand side of the last inequality reads as,

$$\begin{aligned} \left\langle \frac{\partial u_\epsilon}{\partial t}, T_\eta(u_\epsilon - T_k(u)_\mu) \right\rangle &= \left\langle \frac{\partial u_\epsilon}{\partial t} - \frac{\partial T_k(u)_\mu}{\partial t}, T_\eta(u_\epsilon - T_k(u)_\mu) \right\rangle \\ &\quad + \left\langle \frac{\partial T_k(u)_\mu}{\partial t}, T_\eta(u_\epsilon - T_k(u)_\mu) \right\rangle. \end{aligned} \quad (4.13)$$

The second term of the last equality can be written as,

$$\begin{aligned} &\left\langle \frac{\partial u_\epsilon}{\partial t} - \frac{\partial T_k(u)_\mu}{\partial t}, T_\eta(u_\epsilon - T_k(u)_\mu) \right\rangle \\ &= \int_\Omega S_\eta(u_\epsilon(T) - T_k(u)_\mu(T)) \, dx - \int_\Omega S_\eta(u_0^\epsilon) \, dx \geq -\eta \int_\Omega |u_0^\epsilon| \, dx \geq -\eta c. \end{aligned} \quad (4.14)$$

The third term can be written as,

$$\left\langle \frac{\partial T_k(u)_\mu}{\partial t}, T_\eta(u_\epsilon - T_k(u)_\mu) \right\rangle = \mu \int_{Q_T} (T_k(u) - T_k(u)_\mu)(T_\eta(u_\epsilon - T_k(u)_\mu)) \quad (4.15)$$

thus by letting  $\epsilon \rightarrow 0$  and by using Lebesgue theorem,

$$\lim_{\epsilon \rightarrow 0} \int_{Q_T} (T_k(u) - T_k(u)_\mu)(T_\eta(u_\epsilon - T_k(u)_\mu)) = \int_{Q_T} (T_k(u) - T_k(u)_\mu)(T_\eta(u - T_k(u)_\mu)).$$

Consequently,

$$\left\langle \frac{\partial u_\epsilon}{\partial t}, T_\eta(u_\epsilon - T_k(u)_\mu) \right\rangle \geq \alpha(\epsilon, \mu) - \eta c \quad (4.16)$$

on the other hand,

$$\begin{aligned} &\int_{Q_T} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla T_\eta(u_\epsilon - T_k(u)_\mu) \, dx \, dt \\ &= \int_{\{|u_\epsilon - T_k(u)_\mu| < \eta\}} a(x, t, u_\epsilon, \nabla u_\epsilon) (\nabla u_\epsilon - \nabla T_k(u)_\mu) \, dx \, dt \\ &= \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)_\mu) \, dx \, dt \\ &\quad + \int_{\{|u_\epsilon| > k\} \cap \{|u_\epsilon - T_k(u)_\mu| < \eta\}} a(x, t, u_\epsilon, \nabla u_\epsilon) (\nabla u_\epsilon - \nabla T_k(u)_\mu) \, dx \, dt \end{aligned}$$

which implies, by using the fact that

$$\int_{\{|u_\epsilon| > k\} \cap \{|u_\epsilon - T_k(u)_\mu| < \eta\}} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla u_\epsilon \, dx \, dt \geq 0,$$

that

$$\begin{aligned} &\int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)_\mu) \, dx \, dt \\ &\leq c\eta + \int_{\{|u_\epsilon| > k\} \cap \{|u_\epsilon - T_k(u)_\mu| < \eta\}} a(x, t, u_\epsilon, \nabla u_\epsilon) |\nabla T_k(u)_\mu| \, dx \, dt. \end{aligned} \quad (4.17)$$

Since  $a(x, t, T_{k+\eta}(u_\epsilon), \nabla T_{k+\eta}(u_\epsilon))$  is bounded  $\prod_{i=1}^N L^{p'}(Q_T, w_i^*)$ , there exists some  $h_{k+\eta} \in \prod_{i=1}^N L^{p'}(Q_T, w_i^*)$  such that,  $a(x, t, T_{k+\eta}(u_\epsilon), \nabla T_{k+\eta}(u_\epsilon)) \rightharpoonup h_{k+\eta}$  weakly in  $\prod_{i=1}^N L^{p'}(Q_T, w_i^*)$ . Consequently,

$$\begin{aligned} & \int_{\{|u_\epsilon| > k\} \cap \{|u_\epsilon - T_k(u)_\mu| < \eta\}} a(x, t, u_\epsilon, \nabla u_\epsilon) |\nabla T_k(u)_\mu| \, dx \, dt \\ &= \int_{\{|u| > k\} \cap \{|u - T_k(u)_\mu| < \eta\}} h_{k+\eta} |\nabla T_k(u)_\mu| \, dx \, dt + \alpha(\epsilon) \end{aligned}$$

thanks to proposition 2.1, one easily has,

$$\int_{\{|u| > k\} \cap \{|u - T_k(u)_\mu| < \eta\}} h_{k+\eta} |\nabla T_k(u)_\mu| \, dx \, dt = \alpha(\mu).$$

Hence,

$$\begin{aligned} & \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)_\mu) \, dx \, dt \quad (4.18) \\ & \leq c\eta + \alpha(\epsilon, \mu). \end{aligned}$$

On the other hand, note that

$$\begin{aligned} & \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)_\mu) \, dx \, dt \\ &= \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)) \, dx \, dt \\ &+ \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u) - \nabla T_k(u)_\mu) \, dx \, dt \quad (4.19) \end{aligned}$$

the last integral tends to 0 as  $\epsilon \rightarrow 0$  and  $\mu \rightarrow \infty$ . Indeed, we have that

$$\begin{aligned} & \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u) - \nabla T_k(u)_\mu) \, dx \, dt \\ & \rightarrow \int_{\{|T_k(u) - T_k(u)_\mu| < \eta\}} h_k (\nabla T_k(u) - \nabla T_k(u)_\mu) \, dx \, dt \text{ as } \epsilon \rightarrow 0. \end{aligned}$$

It is obviously that,  $\int_{\{|T_k(u) - T_k(u)_\mu| < \eta\}} h_k (\nabla T_k(u) - \nabla T_k(u)_\mu) \, dx \, dt \rightarrow 0$  as  $\mu \rightarrow \infty$ . We deduce then that,

$$\int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)) \, dx \, dt \leq c\eta + \alpha(\epsilon, \mu). \quad (4.20)$$

Let  $A_\epsilon = \left( [a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) - a(x, t, T_k(u_\epsilon), \nabla T_k(u))] [\nabla T_k(u_\epsilon) - \nabla T_k(u)] \right)$ , then for any  $0 < \theta < 1$ , we write

$$I_\epsilon = \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| \leq \eta\}} A_\epsilon^\theta \, dx \, dt + \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| > \eta\}} A_\epsilon^\theta \, dx \, dt$$

since,  $a(x, T_k(u_\epsilon), \nabla T_k(u_\epsilon))$  is bounded in  $\prod_{i=1}^N L^{p'}(Q_T, w_i^{1-p'})$ , while  $\nabla T_k(u_\epsilon)$  is bounded in  $\prod_{i=1}^N L^p(Q_T, w_i)$ , then by applying the Hölder's inequality, we obtain,

$$I_\epsilon \leq c \left( \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} A_\epsilon \, dx \, dt \right)^\theta + c_2 \operatorname{meas}\{(x, t) \in Q_T : |T_k(u_\epsilon) - T_k(u)_\mu| > \eta\}^{1-\theta} \quad (4.21)$$

on the other hand, we have,

$$\begin{aligned} & \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} A_\epsilon \, dx \, dt \\ &= \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)) \, dx \, dt \\ & \quad - \int_{\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}} a(x, t, T_k(u_\epsilon), \nabla T_k(u)) (\nabla T_k(u_\epsilon) - \nabla T_k(u)) \, dx \, dt \\ &= I_\epsilon^1 + I_\epsilon^2 \end{aligned} \quad (4.22)$$

using (4.20), we have,

$$I_\epsilon^1 \leq c\eta + \alpha(\epsilon, \mu). \quad (4.23)$$

Concerning  $I_\epsilon^2$  the second term of the right hand side of the (4.22), it is easy to see that

$$I_\epsilon^2 = \alpha(\epsilon) \quad (4.24)$$

because for all  $i = 1, \dots, N$ , we have,  $a_i(x, t, T_k(u_\epsilon), \nabla T_k(u)) \rightarrow a_i(x, t, T_k(u), \nabla T_k(u))$  strongly in  $L^{p'}(Q_T, w_i^{1-p'})$ , while  $\frac{\partial T_k(u_\epsilon)}{\partial x_i} \rightharpoonup \frac{\partial T_k(u)}{\partial x_i}$  weakly in  $L^p(Q_T, w_i)$ .

Combining (4.21), (4.22), (4.23) and (4.24) we get,

$$I_\epsilon \leq c \operatorname{meas}\{|T_k(u_\epsilon) - T_k(u)_\mu| < \eta\}^\theta + c(\alpha(\epsilon, \mu, \eta))^{1-\theta}$$

and by passing to the limit sup over  $\epsilon, \mu$  and  $\eta$

$$\begin{aligned} & \lim_{\epsilon \rightarrow 0} \int_{Q_T} \left( [a(x, t, T_k(u_\epsilon), \nabla T_k(u_\epsilon)) - a(x, t, T_k(u), \nabla T_k(u))] \right. \\ & \quad \left. [\nabla T_k(u_\epsilon) - \nabla T_k(u)] \right)^\theta = 0 \end{aligned}$$

by Theorem 3.3 of [15] (see also [8], [9]), there exist a subsequence also denoted by  $u_\epsilon$  such that,

$$\nabla u_\epsilon \longrightarrow \nabla u \text{ a.e. in } Q_T. \quad (4.25)$$

### Step 3: Passage to the limit

Let  $\varphi \in K_\psi \cap L^\infty(\bar{Q})$ , choosing  $T_k(u_\epsilon - \varphi)_{\chi_{(0,\tau)}}$  as test function in  $(P_\epsilon)$ , we get,

$$\begin{aligned} & \left\langle \frac{\partial u_\epsilon}{\partial t}, T_k(u_\epsilon - \varphi) \right\rangle_{Q_\tau} + \int_{Q_\tau} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla T_k(u_\epsilon - \varphi) \, dx \, dt \\ & \quad - \frac{1}{\epsilon} \int_{Q_\tau} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- T_k(u_\epsilon - \varphi) \, dx \, dt \\ & = \int_{Q_\tau} f_\epsilon T_k(u_\epsilon - \varphi) \, dx \, dt \end{aligned} \quad (4.26)$$

since,  $-\frac{1}{\epsilon} \int_{Q_\tau} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- T_k(u_\epsilon - \varphi) \, dx \, dt \geq 0$  and  $\frac{\partial u_\epsilon}{\partial t} = \frac{\partial}{\partial t}(u_\epsilon - \varphi) + \frac{\partial \varphi}{\partial t}$ , we get

$$\begin{aligned} \int_{\Omega} S_k(u_\epsilon(\tau) - \varphi(\tau)) \, dx + \left\langle \frac{\partial \varphi}{\partial t}, T_k(u_\epsilon - \varphi) \right\rangle_{Q_\tau} \\ + \int_{Q_\tau} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla T_k(u_\epsilon - \varphi) \, dx \, dt \\ \leq \int_{Q_\tau} f_\epsilon T_\epsilon(u_\epsilon - \varphi) \, dx \, dt + \int_{\Omega} S_k(u_\epsilon(0) - \varphi(0)) \, dx. \end{aligned} \quad (4.27)$$

**Lemma 4.2.** Assume that the assumptions of Theorem 4.1 hold true. Let  $u^\epsilon$  be a sequence of solutions of  $(P_\epsilon)$  converges to  $u$  a.e. in  $Q$ . Then the sequence  $u_\epsilon$  is a Cauchy sequence in  $C([0, T], L^1(\Omega))$ , moreover,  $u \in C([0, T], L^1(\Omega))$  and  $u_\epsilon$  converges to  $u$  in  $C([0, T], L^1(\Omega))$ .

*Proof.* See Appendix. ■

Because of  $u_\epsilon \rightarrow u$  in  $C([0, T], L^1(\Omega))$ , then  $\forall \tau \leq T$ ,  $u_\epsilon(t) \rightarrow u(t)$  in  $L^1(\Omega)$ , thus

$$\int_{\Omega} S_k(u_\epsilon(\tau) - \varphi(\tau)) \, dx \rightarrow \int_{\Omega} S_k(u - \varphi) \, dx \quad (4.28)$$

and

$$\int_{\Omega} S_k(u_\epsilon(0) - \varphi(0)) \, dx \rightarrow \int_{\Omega} S_k(u_0 - \varphi(0)) \, dx.$$

Let  $M = k + \|\varphi\|_\infty$ , then, we can write,

$$\begin{aligned} \int_{Q_T} a(x, t, u_n, \nabla u_n) \nabla T_k(u_n - \varphi) \, dx \, dt \\ = \int_{Q_T} a(x, t, T_M(u_n), \nabla T_M(u_n)) \nabla T_k(u_n - \varphi) \, dx \, dt, \end{aligned}$$

by Fatou's lemma and the convergence of  $a(x, t, T_M(u_n), \nabla T_M(u_n))$  to  $a(x, t, T_M(u), \nabla T_M(u))$  weakly in  $\prod_{i=1}^N L^{p'}(Q, w_i^{1-p'})$ , it possible to conclude that

$$\int_{Q_T} a(x, t, T_M(u), \nabla T_M(u)) \nabla T_k(u - \varphi) \, dx \, dt \quad (4.29)$$

$$\leq \liminf_{\epsilon \rightarrow 0} \int_{\Omega} a(x, t, T_M(u_\epsilon), \nabla T_M(u_\epsilon)) \nabla T_k(u_\epsilon - \varphi) \, dx \, dt.$$

Moreover, since  $\frac{\partial \varphi}{\partial t} \in L^{p'}(0, T, W^{-1, p'}(\Omega, w^*))$  and  $\nabla T_k(u_\epsilon - \varphi) \rightharpoonup \nabla T_k(u - \varphi)$

weakly in  $\prod_{i=1}^N L^p(Q_T, w_i)$ , we get,

$$\int_{Q_\tau} \frac{\partial \varphi}{\partial t} T_k(u_\epsilon - \varphi) \, dx \, dt \rightarrow \int_{Q_\tau} \frac{\partial \varphi}{\partial t} T_k(u - \varphi) \, dx \, dt \quad (4.30)$$

$$\int_Q f_\epsilon T_k(u_\epsilon - \varphi) \, dx \, dt \rightarrow \int_Q f T_k(u - \varphi) \, dx \, dt. \quad (4.31)$$

Finally, by (4.27)-(4.31) we get,

$$\begin{aligned} \int_\Omega S_k(u_\epsilon(\tau) - \varphi(\tau)) \, dx + \left\langle \frac{\partial \varphi}{\partial t}, T_k(u - \varphi) \right\rangle_{Q_\tau} + \int_{Q_\tau} a(x, t, u, \nabla u) \nabla T_k(u - \varphi) \, dx \, dt \\ \leq \int_{Q_\tau} f T_k(u - \varphi) \, dx \, dt + \int_\Omega S_k(u(0) - \varphi(0)) \, dx. \end{aligned}$$

By Step 1, Step 2 and Step 3, the proof of Theorem 4.1 is complete.  $\blacksquare$

## 5 Appendix

In this appendix we give the proof of Lemma 4.2.

*Proof.* Note that  $T_l(u) \in K_\psi$ , for every  $l \geq \|\psi\|_\infty$ . Let  $\eta_i \geq 0$  converges to  $u_0$  in  $L^1(\Omega)$  and  $v_\mu^{i,l} = (T_l(u))_\mu + e^{-\mu t} T_l(\eta_i)$ . Using the admissible test function  $T_k(u_\epsilon - v_\mu^{i,l})$  in  $(P_\epsilon)$  leads to

$$\begin{aligned} \left\langle \frac{\partial u_\epsilon}{\partial t}, T_k(u_\epsilon - v_\mu^{i,l}) \right\rangle_{Q_\tau} + \int_{Q_\tau} a(x, t, u_\epsilon, \nabla u_\epsilon) \nabla T_k(u_\epsilon - v_\mu^{i,l}) \, dx \, dt \\ - \frac{1}{\epsilon} \int_{Q_\tau} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- T_k(u_\epsilon - v_\mu^{i,l}) \, dx \, dt = \int_{Q_\tau} f_\epsilon T_k(u_\epsilon - v_\mu^{i,l}) \, dx \, dt \end{aligned} \quad (5.1)$$

since  $\frac{\partial u_\epsilon}{\partial t} = \frac{\partial}{\partial t}(u_\epsilon - v_\mu^{i,l}) + \frac{\partial}{\partial t}(v_\mu^{i,l}) = \frac{\partial}{\partial t}(u_\epsilon - v_\mu^{i,l}) + \mu(T_l(u) - v_\mu^{i,l})$  we deduce,

$$\begin{aligned} \left\langle \frac{\partial u_\epsilon}{\partial t}, T_k(u_\epsilon - v_\mu^{i,l}) \right\rangle_{Q_\tau} &= \left\langle \frac{\partial}{\partial t}(u_\epsilon - v_\mu^{i,l}), T_k(u_\epsilon - v_\mu^{i,l}) \right\rangle_{Q_\tau} \\ &\quad + \mu \int_{Q_\tau} (T_l(u) - v_\mu^{i,l}) T_k(u_\epsilon - v_\mu^{i,l}) \, dx \, dt. \end{aligned}$$

Remark that, for every  $\tau \in [0, T]$  and when  $\epsilon$  tends to 0

$$\mu \int_{Q_\tau} (T_l(u) - v_\mu^{i,l}) T_k(u_\epsilon - v_\mu^{i,l}) \, dx \, dt \rightarrow \mu \int_{Q_\tau} (T_l(u) - v_\mu^{i,l}) T_k(u - v_\mu^{i,l}) \, dx \, dt \geq 0.$$

On the other hand, by using Lebesgue's convergence theorem and the fact that,

$$- \int_{Q_\tau} \frac{1}{\epsilon} T_{\frac{1}{\epsilon}}(u_\epsilon - \psi)^- T_k(u_\epsilon - v_\mu^{i,l}) \, dx \, dt \geq 0, \text{ we deduce by (5.1) that}$$

$$\begin{aligned} \left\langle \frac{\partial}{\partial t}(u_\epsilon - v_\mu^{i,l}), T_k(u_\epsilon - v_\mu^{i,l}) \right\rangle_{Q_\tau} + \int_{Q_\tau} a(x, t, u_\epsilon, \nabla v_\mu^{i,l}) \nabla T_k(u_\epsilon - v_\mu^{i,l}) \, dx \, dt \\ \leq \alpha(\epsilon, \mu, i, l) \end{aligned}$$

for every  $\tau \in [0, T]$ .

Since for all  $j = 1, \dots, N$  : we have  $a_j(x, t, T_{2k+l}(u_\epsilon), \nabla v_\mu^{i,l}) \rightarrow a_j(x, t, T_{k+2l}(u), \nabla v_\mu^{i,l})$  strongly in  $L^{p'}(Q, w_j^{1-p'})$  while  $\frac{\partial}{\partial x_j} T_k(u_\epsilon - v_\mu^{i,l}) \rightharpoonup \frac{\partial}{\partial x_j} T_k(u - v_\mu^{i,l})$  weakly in  $L^p(Q, w_j)$ , we have,

$$\left\langle \frac{\partial}{\partial t} (u_\epsilon - v_\mu^{i,l}), T_k(u_\epsilon - v_\mu^{i,l}) \right\rangle_{Q_\tau} \leq \alpha(\epsilon, \mu, i, l). \quad (5.2)$$

In view of the definition  $S_k(z) = \int_0^z T_k(s) ds$  and using Lebesgue's convergence theorem, we deduce that  $\int_\Omega S_k(u_\epsilon(\tau) - v_\mu^{i,l}(\tau)) dx \leq \alpha(\epsilon, \mu, i, l)$ . Which implies, by writing,

$$\int_\Omega S_k\left(\frac{u_\epsilon - u_\lambda}{2}\right) dx \leq \frac{1}{2} \left( \int_\Omega S_k(u_\epsilon(\tau) - v_\mu^{i,l}(\tau)) dx + \int_\Omega S_k(u_\lambda(\tau) - v_\mu^{i,l}(\tau)) dx \right),$$

that

$$\int_\Omega S_k\left(\frac{u_\epsilon - u_\lambda}{2}\right) dx \leq \alpha(\epsilon, \lambda). \quad (5.3)$$

Finally, by Hölder's inequality, we have,

$$\begin{aligned} \int_\Omega |u_\epsilon - u_\lambda| dx &= \int_{\{|u_\epsilon - u_\lambda| \leq 1\}} |u_\epsilon - u_\lambda| dx + \int_{\{|u_\epsilon - u_\lambda| > 1\}} |u_\epsilon - u_\lambda| dx \\ &\leq \left( \int_{\{|u_\epsilon - u_\lambda| \leq 1\}} |u_\epsilon - u_\lambda|^2 dx \right)^{\frac{1}{2}} \text{meas}(\Omega)^{\frac{1}{2}} + \int_{\{|u_\epsilon - u_\lambda| > 1\}} |u_\epsilon - u_\lambda| dx \\ &\leq \text{meas}(\Omega)^{\frac{1}{2}} \left( \int_{\{|u_\epsilon - u_\lambda| \leq 1\}} 2S_1(u_\epsilon - u_\lambda) dx \right)^{\frac{1}{2}} + \int_{\{|u_\epsilon - u_\lambda| > 1\}} 2S_1(u_\epsilon - u_\lambda) dx \end{aligned}$$

since  $\left(\frac{|y|^2}{2}\right)_{\chi_{\{|y| \leq 1\}}} = S_1(y)_{\chi_{\{|y| \leq 1\}}}$  and  $\left(\frac{|y|}{2}\right)_{\chi_{\{|y| > 1\}}} \leq \left(\frac{|y|}{2} + \frac{|y| - 1}{2}\right)_{\chi_{\{|y| > 1\}}} = S_1(y)_{\chi_{\{|y| > 1\}}}$ . Due to (5.3) we deduce that,  $\int_\Omega |u_\epsilon(\tau) - u_\lambda(\tau)| dx \leq \alpha(\epsilon, \lambda)$ , not depending on  $\tau$ , and thus  $(u_\epsilon)$  is a Cauchy sequence in  $C([0, T], L^1(\Omega))$ , and since  $u_\epsilon \rightarrow u$ , a.e. in  $Q$ , we deduce that  $u_\epsilon \rightarrow u$ , a.e. in  $C([0, T], L^1(\Omega))$ . ■

### Acknowledgment

The authors would like to thank the anonymous referee for his/her valuable suggestions and comments.

### References

- [1] R. ADAMS, *Sobolev spaces*, AC, Press, New York, (1975)
- [2] L. AHAROUCH, E. AZROUL and M. RHOUDAF, *Existence result for variational degenerated parabolic problems via pseudo-monotonicity*. EJDE, conf 14, ISSN: 1072-6691, pp. 9-20, (2006).
- [3] L. AHAROUCH, E. AZROUL and M. RHOUDAF, *Strongly nonlinear variational parabolic problems in Weighted Sobolev spaces*, AJMAA, vol 5, Issue 2, Art 13, pp. 1-25, (2008).



- [4] E. AZROUL, H. REDWANE and M. RHOUDAF, *Existence of a renormalized solution for a class of nonlinear parabolic equations in Orlicz spaces*, Port. Math. 66, no. 1, 29–63, (2009)
- [5] Y. AKDIM, E. AZROUL and A. BENKIRANE, *Existence Results for Quasilinear Degenerated Equations Via Strong Convergence of Truncations*, Revista Matematica Complutense 17, , N.2, (2004) pp 359-379.
- [6] Y. AKDIM, E. AZROUL and A. BENKIRANE, *Existence of Solution for quasilinear degenerated Elliptic Unilateral Problems*, Ann. Math. Blaise pascal vol 10 (2003) pp 1-20.
- [7] Y. AKDIM, E. AZROUL and A. BENKIRANE, *Existence of solution for quasilinear degenerated elliptic equation*, Electronic J. Diff. Equ. Vol 2001 , N71, (2001) pp 1-19.
- [8] D. BLANCHARD and F. MURAT *Renormalized solutions of nonlinear parabolic problems with  $L^1$  data, Existence and uniqueness*, Proc. Roy. Soc. Edinburgh Sect. Vol A127, (1997) pp 1137-1152.
- [9] D. BLANCHARD, F. MURAT and H. REDWANE, *Existence and Uniqueness of a Renormalized Solution for a Fairly General Class of Nonlinear Parabolic Problems*, J. Differential Equations. Vol 177, (2001) pp 331-374.
- [10] H. BREZIS and F.E. BROWDER, *Strongly nonlinear parabolic initial-boundary value problems* , Proc. Nat Acad. Sci. U. S. A. 76 (1976). pp. 38-40.
- [11] J. BERKOVITS and V. MUSTONEN, *Topological degree for perturbation of linear maximal monotone mappings and applications to a class of parabolic problems*, Rend. Mat. Roma, Ser, VII, 12 (1992), pp. 597-621.
- [12] L. BOCCARDO, F. MURAT and J.P. PUEL, *Existence of bounded solutions for nonlinear elliptic unilateral problems*, Ann. Mat. Pura Appl. (4) 152 (1988), 183-196.
- [13] L. BOCCARDO and F. MURAT, *Strongly nonlinear Cauchy problems with gradient dependt lower order nonlinearity*, Pitman Research Notes in Mathematics, 208 (1988), pp. 347-364.
- [14] L. BOCCARDO and F. MURAT, *Almost everywhere convergence of the gradients of solutions to elliptic and parabolic equations*, Nonlinear analysis, T.M.A., 19 (1992), n 6, pp. 581-597.
- [15] L. BOCCARDO, A. DALL'AGLIO, T. GALLOUËT and L. ORSINA, *Nonlinear parabolic equations with measure data*, Journal of Functional Analysis, 147 (1997), n 1, pp. 237-358.
- [16] A. DALL'AGLIO and A. ORSINA, *Non linear parabolic equations with natural growth condition and  $L^1$  data*. Nolinear Anal., T.M.A., 27 n1 (1996). pp. 59-73.
- [17] P. DRABEK, A. KUFNER and L. MUSTONEN, *Pseudo-monotonicity and degenerated or singular elliptic operators*, Bull. Austral. Math. Soc. Vol. 58 (1998), 213-221.
- [18] P. DRABEK, A. KUFNER and F. NICOLSI, *Non linear elliptic equations, singular and degenerated cases*, University of West Bohemia, (1996).

- [19] A. KUFNER, *Weighted Sobolev Spaces*, John Wiley and Sons, (1985).
- [20] R. LANDES, *On the existence of weak solutions for quasilinear parabolic initial-boundary value problems*, Proc. Roy. Soc. Edinburgh sect. A. 89 (1981), 217-137.
- [21] R. LANDES and V. MUSTONEN, *A strongly nonlinear parabolic initial-boundary value problems*, Ark. f. Math. 25. (1987).
- [22] R. LANDES and V. MUSTONEN, *On parabolic initial-boundary value problems with critical growth for the gradient*, Ann. Inst. H. Poincaré11 (2) (1994) 135-158.
- [23] J. LERAY and J.L. LIONS, *Quelques resultats de Višik sur les problèmes elliptiques nonlinéaires par les méthodes de Minty-Browder*, Bull. Soc. Math. France 93 (1995), 97-107.
- [24] J.L. LIONS, *quelques methodes de résolution des problèmes aux limites non linéaires*, Dunod et Gauthiers-Villars, 1969.
- [25] A. PORRETTA *Existence results for nonlinear parabolic equations via strong convergence of truncations*, Ann. Mat. Pura. Appl. (1999), pp. 143-172.
- [26] J. M. RAKOTOSON *A Compactness lemma for quasilinear problems: application to parabolic equations* J. Funct. Anal. 106 (1992), pp. 358-374.
- [27] J. SIMON *Compact sets in the space  $L^p(0, T, B)$* , Ann. Mat. Pura. Appl. 146 (1987), pp. 65-96.
- [28] M. Rhoudaf *Existence results for Strongly nonlinear degenerated parabolic equations via strong convergence of truncations with  $L^1$ -data* thèse de Doctorat. Univ. Sidi Mohamed Ben Abdella. Fès, Maroc (2006).
- [29] E. ZEIDLER, *nonlinear functional analysis and its applications, II A and II B*, Springer-Verlag. New York-Heidlberg, (1990).

Département de Mathématiques et Informatique,  
 Faculté des Sciences Dhar-Mahraz.  
 B.P. 1796 Atlas Fès, Morocco  
 email:azroul\_elhoussine@yahoo.fr

Faculté des Sciences Juridiques, conomiques et Sociales, Université Hassan 1.  
 B.P. 784, Settat, Morocco  
 email:redwane\_hicham@yahoo.fr

Département des Mathématiques, Faculté des Sciences et Techniques de Tanger.  
 B.P. 416, Tanger, Morocco  
 email:rhoudaf\_mohamed@yahoo.fr