

Some Examples Related to Duality Theorem in Linear Programming

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The duality problems in linear programming may read as follows. Suppose an $m \times n$ matrix $A = (a_{ij})$, a column vector $\mathbf{b} = (b_1, \dots, b_m)$ and a row vector $\mathbf{c} = (c_1, \dots, c_n)$ are given.

The primal problem: Find a column vector $\mathbf{u} = (u_1, \dots, u_n)$ which maximizes the linear form $\mathbf{c}\mathbf{u}$ subject to the conditions $A\mathbf{u} \leq \mathbf{b}$ and $\mathbf{u} \geq 0$.

The dual problem: Find a row vector $\mathbf{v} = (v_1, \dots, v_m)$ which minimizes the linear form $\mathbf{v}\mathbf{b}$ subject to the conditions $\mathbf{v}A \geq \mathbf{c}$ and $\mathbf{v} \geq 0$.

In each problem a vector satisfying the required conditions is called feasible, and if it attains the maximum or minimum it is called optimal.

These problems can be represented by the following tableau:

| | | | | | | | | |
|-------------|----------|---------|----------|---------|----------|---|--------|--------|
| (≥ 0) | u_1 | \dots | u_j | \dots | u_n | \leq | | |
| v_1 | a_{11} | \dots | a_{1j} | \dots | a_{1n} | b_1 | | |
| . | . | \dots | . | \dots | . | . | | |
| v_i | a_{i1} | \dots | a_{ij} | \dots | a_{in} | b_i | | |
| . | . | \dots | . | \dots | . | . | | |
| v_m | a_{m1} | \dots | a_{mj} | \dots | a_{mn} | b_m | | |
| $\forall i$ | c_1 | \dots | c_j | \dots | c_n | <table style="border: none; width: 100%; height: 100%;"> <tr> <td style="text-align: right; padding-right: 5px;">\min</td> </tr> <tr> <td style="text-align: left; padding-left: 5px;">\max</td> </tr> </table> | \min | \max |
| \min | | | | | | | | |
| \max | | | | | | | | |

By taking inner products of the row of u 's with the rows of A and the row of c 's, we obtain the constraints $A\mathbf{u} \leq \mathbf{b}$ and the linear form $\mathbf{c}\mathbf{u}$ of the primal; the inner products of the column of v 's with the columns of A and the column of b 's yield the dual constraints $\mathbf{v}A \geq \mathbf{c}$ and the linear form $\mathbf{v}\mathbf{b}$.

Associated with these problems is the following well-known theorem:

The Duality Theorem. If the primal is feasible and if $\sup \mathbf{c}\mathbf{u} < \infty$, then there exist optimal solutions in the dual as well as in the primal, and moreover the extremal values of the linear forms coincide, i.e., $\max \mathbf{c}\mathbf{u} = \min \mathbf{v}\mathbf{b}$.

In the foregoing paper [1], M. Ohtsuka investigated the problems in a very general situation, and obtained extensions of the duality theorem. We refer necessary notions and notations to [1]. We shall show in the present paper that the conditions imposed in Ohtsuka's Theorems 2 and 3 are in a way necessary. Actually, even if $\mathcal{A} \neq \emptyset$, $-\infty < M < \infty$ and \emptyset, f and g are

all continuous and non-negative, we have examples where respectively

1. There exist no optimal measures in the primal.
2. Though an optimal measure exists in the primal, $\mathcal{M}' = \emptyset$.
3. There exists an optimal measure in the primal and $\mathcal{M}' \neq \emptyset$, $M = M'$, nevertheless there exist no optimal in the dual.
4. Though there exist optimal measures both in the primal and the dual, nevertheless $M < M'$.

Examples shall be given by the tableaux which are so explanatory that further explanations will be superfluous.

1. $X = \{1\}$, $Y = \{N, \omega\}$: the Alexandroff one point compactification of the discrete space N of all natural numbers.

| | u_1 | u_2 | \dots | u_n | \dots | u_ω | \leq |
|-----------|---|---|---------|---|---------|------------|---|
| v | 1 | $\frac{1}{2}$ | \dots | $\frac{1}{n}$ | \dots | 0 | 1 |
| \forall | $\frac{1}{1}\left(1 - \frac{1}{1}\right)$ | $\frac{1}{2}\left(1 - \frac{1}{2}\right)$ | \dots | $\frac{1}{n}\left(1 - \frac{1}{n}\right)$ | \dots | 0 | $\begin{array}{l} \min \\ \max \end{array}$ |

2. $X = Y = \{N, \omega\}$

| | u_1 | u_2 | \dots | u_n | \dots | u_ω | \leq |
|------------|-------|-----------------|---------|-----------------|---------|------------|---|
| v_1 | 1 | | | | | | 1 |
| v_2 | | $\frac{1}{2^2}$ | | | 0 | | $\frac{1}{2^3}$ |
| \vdots | | \ddots | | | | | \vdots |
| v_n | | | | $\frac{1}{n^2}$ | | | $\frac{1}{n^3}$ |
| \vdots | | 0 | | \ddots | | | \vdots |
| v_ω | | | | | | 0 | 0 |
| \forall | 1 | $\frac{1}{2}$ | \dots | $\frac{1}{n}$ | \dots | 0 | $\begin{array}{l} \min \\ \max \end{array}$ |

3. $X = \{N, \omega\}, Y = \{1\}$

| | u | \leq |
|------------|---------------|---|
| v_1 | 1 | 1 |
| v_2 | $\frac{1}{2}$ | $\frac{1}{2^2}$ |
| \vdots | \vdots | \vdots |
| v_n | $\frac{1}{n}$ | $\frac{1}{n^2}$ |
| \vdots | \vdots | \vdots |
| v_ω | 0 | 0 |
| \forall | 1 | $\begin{array}{l} \min \\ \max \end{array}$ |

4. $X = Y = \{N, \omega\}$

| | u_1 | u_2 | \dots | u_n | \dots | u_ω | \leq |
|------------|----------|---------------|---------------------|---------------|----------|------------|---|
| v_1 | \dots | $\frac{1}{n}$ | \dots | 0 | \dots | 0 | 1 |
| v_2 | \dots | $\frac{1}{n}$ | $\frac{1}{2^2}$ | \dots | 0 | 0 | $\frac{1}{2^2}$ |
| \vdots | \vdots | \vdots | \vdots | \vdots | \vdots | \vdots | \vdots |
| v_n | \dots | $\frac{1}{n}$ | $\frac{1}{n^n}$ | \dots | 0 | 0 | $\frac{1}{n^n}$ |
| v_{n+1} | \dots | $\frac{1}{n}$ | $\frac{1}{(n+1)^n}$ | \dots | 0 | 0 | $\frac{1}{(n+1)^{(n+1)}}$ |
| \vdots | \vdots | \vdots | \vdots | \vdots | \vdots | \vdots | \vdots |
| v_k | \dots | $\frac{1}{n}$ | $\frac{1}{k^n}$ | \dots | 0 | 0 | $\frac{1}{k^k}$ |
| \vdots | \vdots | \vdots | \vdots | \vdots | \vdots | \vdots | \vdots |
| v_ω | \dots | 0 | \dots | 0 | \dots | 0 | 0 |
| \forall | 1 | $\frac{1}{2}$ | \dots | $\frac{1}{n}$ | \dots | 0 | $\begin{array}{l} \min \\ \max \end{array}$ |

Reference

[1] M. Ohtsuka: *A generalization of duality theorem in the theory of linear programming*, this journal.

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