# Energy Inequalities and the Cauchy Problem for a Pseudo-Differential System 

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Let $\vec{A}(t)$ be an $N \times N$ matrix of pseudo-differential operators of order $\leqq 1$ which depend on a parameter $t$. Here the term "pseudo-differential operator" will be understood as described in the preceding paper [10], which has been designed to be the introductory part of the present paper. Certain pseudocommutativity relations are assumed for $\vec{A}(t)$. Let us write $L=D_{t}+\vec{A}(t)$, $D_{t}=\frac{1}{i} \frac{\partial}{\partial t}$. Here we study the Cauchy problem which consists in finding a solution $\vec{u}=\left(u_{1}, u_{2}, \cdots, u_{N}\right), u_{j} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, to the equation

$$
L \vec{u}=\vec{f} \quad \text { in } R_{n+1}^{+}=R_{t}^{+} \times\left(R_{n}\right)_{x}
$$

with initial condition

$$
\mathscr{D}_{L^{2}-\lim _{t \downarrow 0}^{\prime}} \vec{u}=\vec{\alpha},
$$

when $\vec{f}=\left(f_{1}, f_{2}, \cdots, f_{N}\right), f_{j} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $\vec{\alpha}=\left(\alpha_{1}, \alpha_{2}, \cdots, \alpha_{N}\right), \alpha_{j} \in\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ are arbitrarily given. It was shown in [10] that if a solution $\vec{u}$ exists, then $\vec{f}$ must admit the $\mathscr{D}_{L^{\prime}}{ }^{2}$-canonical extension. The energy inequalities of Friedrichs-Lewy type are assumed for $L$. Even if $L$ is a system of differential operators, our treatments will give rise to some simplification and refinement to our related paper [9].

In Section 1 we shall show the approximation theorems, which are the analogues of the results [9] established for a system of differential operators. Sections 2 and 3 are devoted to the studies of the uniqueness and existence theorems for the Cauchy problem. In Section 4 we consider the pseudodifferential system with constant coefficients. The discussions are made here about the well-posedness in the $L^{2}$ norm and its connection with the energy inequalities. In Section 5 a characterization of regular hyperbolicity of a pseudo-differential operator is given. This is an analogue of our recent result established in [9] for a differential operator. Section 6 is concerned with generalization of S. Kaplan's result [11] about the Cauchy problem for parabolic equation. The method developed in Sections 2 and 3 will much simplify his treatments. In the final section the Cauchy problem for ordinary differential operators is considered. It is shown that the method developed in Sections 2, 3 and 4 also lead to generalization of basic theorem in [1].

## 1. Approximation theorem

Let $R_{n+1}=R \times R_{n}$ be an ( $n+1$ )-dimensional Euclidean space with generic points $(t, x), x=\left(x_{1}, \cdots, x_{n}\right)$ and $\Xi_{n+1}=\Xi \times \Xi_{n}$ be its dual with point $(\tau, \xi), \xi$ $=\left(\xi_{1}, \cdots, \xi_{n}\right)$. We write $|x|=\left(\sum_{j=1}^{n} x_{j}^{2}\right)^{1 / 2}$ and for an $n$-tuple $p=\left(p_{1}, \cdots, p_{n}\right)$ of non-negative integers we write $|p|=p_{1}+\cdots+p_{n}, x^{p}=x_{1}^{p_{1}} \cdots x_{n}^{p_{n}}, D_{x}^{p}=D_{1}^{p_{1} \cdots} D_{n}^{p_{n}}$ with $D_{j}=\frac{1}{i} \frac{\partial}{\partial x_{j}}$. By $D_{t}$ we mean $\frac{1}{i} \frac{\partial}{\partial t}$. The Fourier transform, $\hat{\phi}, \phi \epsilon$ $\mathscr{S}\left(R_{n}\right)$, is defined by $\hat{\phi}(\xi)=\int \phi(x) e^{-i\langle x, \xi\rangle} d x$, which is extended by continuity to a temperate distribution $u \in \mathscr{S}^{\prime}\left(R_{n}\right)$ by the formula $\left.<\hat{u}, \phi>=<u, \hat{\phi}\right\rangle$, where $\langle x, \xi\rangle=\sum_{j=1}^{n} x_{j} \xi_{j}$.

We shall continue to employ the notations in our preceding paper [10]. We have considered there the spaces $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)=\mathscr{D}_{t}^{\prime} \varepsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x},\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)\left(\bar{R}_{n+1}^{+}\right)$and have shown that these spaces are reflexive, ultrabornological and Souslin. Let $A(t)$ be an $\mathrm{OP}_{r}$-valued $C^{\infty}$ function of $t \in R_{t}$, that is, $A(t) \epsilon \mathbb{C}_{(r)}^{\infty}$ in the notation used in [10]. For any $u \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ (resp. $\left.\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)\right), A(t) u$ is well defined, belongs to the space $\mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ (resp. $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{\left.L^{2}\right)_{x}}\right)\right)$ and the map $u \rightarrow A(t) u$ is continuous. If $\vec{A}(t)$ is an $N \times N$ matrix of operators $A_{i j}(t) \in \mathfrak{G}_{(r)}^{k}$, then we shall also write $\vec{A}(t) \in \mathfrak{§}_{(r)}^{k}$. If, for a vector distribution $\vec{u}=\left(u_{1}, \cdots, u_{N}\right)$, each component $u_{j}$ belongs to the same space $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, then we shall write $\vec{u} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$. When confusion appears impossible, we shall use a similar abbreviation.

Let $\Lambda$ and $S$ be operators with symbols $|\xi|$ and $\left(1+|\xi|^{2}\right)^{1 / 2}$ respectively. We shall denote by $\lambda\left(D_{x}\right)$ the operator with symbol $\lambda(\xi)$. Let us consider $\vec{A}(t) \epsilon \bigoplus_{(r)}^{k}$. In what follows, we assume that for any $T>0$ and any real $\lambda$ there exists a constant $C_{\lambda, T}$ such that
(*) $\left\|\left(S^{-\lambda} \vec{A}(t) S^{\lambda}-\vec{A}(t)\right) \vec{\chi}\right\|_{(0)} \leqq C_{\lambda, T}\|\vec{\chi}\|_{(r-1)}, 0 \leqq t \leqq T, \vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right)$,
where we mean by $\|\vec{x}\|_{(r)}$ the norm defined by $\|\vec{x}\|_{(r)}^{2}=\sum_{j=1}^{N}\left\|x_{j}\right\|_{(r)}^{2}$ and $\left\|x_{j}\right\|_{(r)}=$ $\left(\frac{1}{(2 \pi)^{n}} \int\left|\hat{\chi}_{j}(\xi)\right|^{2}\left(1+|\xi|^{2}\right)^{r} d \xi\right)^{1 / 2}$. As shown in Section 4 in [10], a singular integral operator in the sense of $A . P$. Calderón [3] has the pseudo-commutativity (*). For a differential operator with constant coefficients, the commutativity in question is trivially satisfied. For any real $s$ we can find a constant $C_{\lambda, T}^{(s)}$ such that $\left\|\left(S^{-\lambda} \vec{A}(t) S^{\lambda}-\vec{A}(t)\right) \vec{\chi}\right\|_{(s)} \leqq C_{\lambda, T}^{(s)}\|\vec{\chi}\|_{(s+r-1)}$ and the adjoint operator $\vec{A}^{*}(t)$ has also the property (*). In fact, for any $\vec{\chi}_{1}, \vec{\chi}_{2} \in C_{0}^{\infty}\left(R_{n}\right)$ the inequalities

$$
\begin{aligned}
\left|\left(\vec{\chi}_{1},\left(S^{-\lambda} \vec{A}^{*}(t) S^{\lambda}-\vec{A}^{*}(t)\right) \vec{\chi}_{2}\right)\right| & =\left|\left(\left(S^{\lambda} \vec{A}(t) S^{-\lambda}-\vec{A}(t)\right) \vec{\chi}_{1}, \vec{\chi}_{2}\right)\right| \\
& \leqq\left\|\left(S^{\lambda} \vec{A}(t) S^{-\lambda}-\vec{A}(t)\right) \vec{\chi}_{1}\right\|_{(-r+1)}\left\|\vec{\chi}_{2}\right\|_{(r-1)}
\end{aligned}
$$

$$
\leqq C_{-\lambda, T}^{(-r+1)}\left\|\vec{\chi}_{1}\right\|_{(0)}\left\|\vec{\chi}_{2}\right\|_{(r-1)}
$$

imply $\left\|\left(S^{-\lambda} \vec{A}^{*}(t) S^{\lambda}-A^{*}(t)\right) \vec{\chi}_{2}\right\|_{(0)} \leqq C_{-\lambda, T}^{(-r+1)}\left\|\vec{\chi}_{2}\right\|_{(r-1)}$.
To prove the approximation theorem below (Theorem 1) we shall need the following two lemmas. For any $\varepsilon>0$ we put $S_{\varepsilon}=1+\varepsilon \Lambda$. Then we have

Lemma 1. For any $x \in \mathscr{H}_{(s)}\left(R_{n}\right), S_{\varepsilon}^{-1} \chi$ belongs to the space $\mathscr{H}_{(s+1)}\left(R_{n}\right)$ and it converges in $\mathscr{H}_{(s)}\left(R_{n}\right)$ to $x$ as $\varepsilon \downarrow 0$.

Proof. For a fixed $\varepsilon, \frac{\left(1+|\xi|^{2}\right)^{1 / 2}}{1+\varepsilon|\xi|}$ is bounded and we can write

$$
\left(1+|\xi|^{2}\right)^{(s+1) / 2}\left(S_{\varepsilon}^{-1} x\right)^{\wedge}=\frac{\left(1+|\xi|^{2}\right)^{1 / 2}}{1+\varepsilon|\xi|}\left(1+|\xi|^{2}\right)^{s / 2} \hat{\chi}(\xi)
$$

and therefore $S_{\varepsilon}^{-1} \chi \in \mathscr{H}_{(s+1)}\left(R_{n}\right)$. If we write

$$
\begin{aligned}
\left(1+|\xi|^{2}\right)^{s / 2}\left(S_{\varepsilon}^{-1} x-x\right)^{\wedge} & =\left(\frac{1}{1+\varepsilon|\xi|}-1\right)\left(1+|\xi|^{2}\right)^{s / 2} \hat{\chi}(\xi) \\
& =-\frac{\varepsilon|\xi|}{1+\varepsilon|\xi|}\left(1+|\xi|^{2}\right)^{s / 2} \hat{\chi}(\xi)
\end{aligned}
$$

then $0 \leqq \frac{\varepsilon|\xi|}{1+\varepsilon|\xi|} \leqq 1$ and $\frac{\varepsilon|\xi|}{1+\varepsilon|\xi|}$ converges to 0 for any fixed $\xi$ as $\varepsilon \downarrow 0$. Thus we see that $\left\|S_{\varepsilon}^{-1} x-x\right\|_{(s)}$ converges to 0 as $\varepsilon \downarrow 0$.

Remark. Evidently $\left\|S_{\varepsilon}^{-1} x\right\|_{(s)} \leqq\|x\|_{(s)}$ and we see from the BanachSteinhaus theorem that $S_{\varepsilon}^{-1} \chi$ converges to $\chi$ in $\mathscr{H}_{(s)}\left(R_{n}\right)$ uniformly when $\chi$ varies in a compact subset of $\mathscr{H}_{(s)}\left(R_{n}\right)$.

Lemma 2. Let $A(t) \in \mathfrak{c}_{(r)}$. Then we have
(i) For any $T>0$ and $\varepsilon$ with $0<\varepsilon \leqq 1$, there exists a constant $C_{T}^{(s)}$ such that

$$
\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{(s)} \leqq C_{T}^{(s)}\|\vec{\chi}\|_{(s+r-1)}, 0 \leqq t \leqq T, \vec{\chi} \in \mathscr{H}_{(s+r-1)}\left(R_{n}\right)
$$

(ii) For any $\vec{\chi} \in \mathscr{H}_{(s+r-1)}\left(R_{n}\right),\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{(s)}$ converges to 0 as $\varepsilon \downarrow 0$.

Proof. We may assume $\vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right)$, for $C_{0}^{\infty}\left(R_{n}\right)$ is dense in $\mathscr{H}_{(s+r-1)}\left(R_{n}\right)$ and $\vec{\chi} \rightarrow\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{(s)}$ is semi-continuous from below.
(i) For each $t, 0 \leqq t \leqq T$, the operator $\vec{B}(t)=S \vec{A}(t)-\vec{A}(t) S$ is of order $\leqq r$. Putting $R=\Lambda-S$, we have $|\hat{R}(\xi)| \leqq \frac{1}{\left(1+|\xi|^{2}\right)^{1 / 2}}$ and therefore the operator $R \vec{A}(t)-\vec{A}(t) R$ is of order $\leqq r-1$. Thus the operator $\vec{B}_{1}(t)=\Lambda \vec{A}(t)-\vec{A}(t) \Lambda$ is of order $\leqq r$ and we can write $S_{\varepsilon} \vec{A}(t)-\vec{A}(t) S_{\varepsilon}=\varepsilon \vec{B}_{1}(t)$. Putting $\vec{\Gamma}_{\varepsilon}(t)=$ $\vec{A}(t)-S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}$, for any $\vec{\chi} \in \mathscr{H}_{(s)}\left(R_{n}\right)$ we have

$$
\vec{\Gamma}_{\varepsilon}(t) \vec{\chi}=\frac{\varepsilon}{1+\varepsilon \Lambda} \vec{B}_{1}(t) \vec{\chi}=\frac{\varepsilon\left(1+\Lambda^{2}\right)^{1 / 2}}{1+\varepsilon \Lambda} S^{-1} \vec{B}_{1}(t) \vec{\chi}
$$

where $\frac{\varepsilon\left(1+|\xi|^{2}\right)^{1 / 2}}{1+\varepsilon|\xi|} \leqq 1$ and $S^{-1} \vec{B}_{1}(t)$ is of order $\leqq r-1$. Thus we obtain

$$
\left\|\left(\vec{A}(t)-S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}\right) \vec{\chi}\right\|_{(s)}=\left\|\vec{\Gamma}_{\varepsilon} \vec{\chi}\right\|_{(s)} \leqq\left\|S^{-1} \vec{B}_{1}(t) \vec{\chi}\right\|_{(s)} \leqq C_{T}^{(s)}\|\vec{\chi}\|_{(s+r-1)}
$$

where $C_{T}^{(s)}$ is a constant.
(ii) $\frac{\varepsilon\left(1+|\xi|^{2}\right)^{1 / 2}}{1+\varepsilon|\xi|}$ converges pointwise to 0 as $\varepsilon \downarrow 0$. If we let $\varepsilon \downarrow 0$ in (i), we see by the Banach-Steinhaus theorem that $\lim _{\varepsilon \downarrow 0}\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{(s)}$ $=0$ for any $\vec{\chi} \in \mathscr{H}_{(s)}\left(R_{n}\right)$.

For any real numbers $\sigma, s$ we shall denote by $\widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$the space of $u \in \mathscr{D}^{\prime}\left(R_{n+1}^{+}\right)$such that $\phi u$ belongs to the space $\mathscr{H}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)[5, \mathrm{p} .51]$ when $\phi$ is taken arbitrarily in $C_{0}^{\infty}(R)$. The topology in $\breve{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$is defined by the semi-norms $\widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right) \ni u \rightarrow\|\phi u\|_{(\sigma, s)}$. By $\widetilde{\mathscr{H}}_{(\sigma, s)}^{*}\left(\bar{R}_{n+1}^{+}\right)$we mean the adjoint space of $\widetilde{\mathscr{H}}_{(-\sigma,-s)}\left(\bar{R}_{n+1}^{+}\right)$, which consists of all $v \in \mathscr{\mathscr { H }}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$with support $\subset[0, T] \times R_{n}$ for some $T>0$. It is to be noticed that $\widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\stackrel{\check{\mathscr{H}}}{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$may be identified for $|\sigma|<\frac{1}{2}$ (cf. Proposition 7 in [8, p. 416]) and that in the space $\widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$the following conditions are equivalent (cf. Theorem 1 in [8, p. 410]):
(i) $\sigma>\frac{1}{2}$.
(ii) For any $u \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), u$ has the $\mathscr{D}_{L^{2}}^{\prime}$-boundary value $\mathscr{D}_{L^{2}}^{\prime} \lim _{t \downarrow 0} u$ [10, p. 375].
(iii) For any $u \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), u$ has the distributional boundary value $\lim _{t \downarrow 0} u$ [7, p. 12].
and similarly the following conditions are equivalent (cf. Theorem 2 in $[8$, p. 413]):
(i ) $\sigma>-\frac{1}{2}$.
(ii) For any $u \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), u$ has the $\mathscr{D}_{L^{2}}^{\prime}$-canonical extension over $t=0$ [10, p. 379].
(iii) For any $u \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), u$ has the canonical extension over $t=0$ [7, p. 12].

Let $\vec{u} \in \mathscr{H}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$and assume that $\vec{A}(t) \in \bigoplus_{(r)}^{l}$ with $l \geqq|\sigma|$. Then $\vec{A}(t) \vec{u}$ $\epsilon \widetilde{\mathscr{H}}_{(\sigma, s-r)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{u} \rightarrow \vec{A}(t) \vec{u}$ is a continuous map of $\widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$into $\widetilde{\mathscr{H}}_{(\sigma, s-r)}\left(\bar{R}_{n+1}^{+}\right)$(cf. Proposition 14 in [10, p. 385]). From the equality $S^{j} \vec{\Gamma}_{\varepsilon}(t) \vec{\chi}$ $=\frac{\varepsilon\left(1+\Lambda^{2}\right)^{1 / 2}}{1+\varepsilon \Lambda} S^{j-1} \vec{B}_{1}(t) \vec{\chi}$ for any $\vec{\chi} \in C_{0}^{\infty}\left(R_{n+1}\right)$ we have $\left\|S^{j} \vec{\Gamma}_{\varepsilon}(t) \vec{\chi}\right\|_{(0, s)} \leqq$
$C_{T}^{(s)}\|\vec{x}\|_{(0, s+r-1+j)}$. In the same way as in the proof of Proposition 14 in [10, p. 385], we have immediately the following

Corollary 1. Let $\vec{A}(t) \in \mathbb{C}_{(r)}^{l}$ with $l \geqq|\sigma|$. Then
(i) For any $T>0$ and $\varepsilon$ with $0<\varepsilon \leqq 1$, there exists a constant $C_{T}^{(\sigma, s)}$ such that

$$
\begin{aligned}
\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{(\sigma, s)} & \leqq C_{T}^{(\sigma, s)}\|\vec{\chi}\|_{(\sigma, s+r-1)} \\
0 & \leqq t \leqq T, \vec{\chi} \in \widetilde{\mathscr{H}}_{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)
\end{aligned}
$$

(ii) For any $\vec{\chi} \in \widetilde{\mathscr{H}}_{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right),\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{(\sigma, s)}$ converges to 0 as $\varepsilon \downarrow 0$.

Let $\vec{A}(t) \in \mathfrak{C}_{(r)}$ with any fixed real $r$. With the aid of Lemmas 1 and 2 we can show the following

Theorem 1 (Approximation theorem). Let $\vec{u} \in \widetilde{\mathscr{H}}_{(0, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)$and assume that

$$
\left\{\begin{array}{l}
L \vec{u} \equiv D_{t} \vec{u}+\vec{A}(t) \vec{u}=\vec{f} \in \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right), \\
\mathscr{D}_{L^{2-}}^{\prime} \lim _{t \downarrow 0} \vec{u}=\vec{\alpha} \in \mathscr{H}_{(s)}\left(R_{n}\right) .
\end{array}\right.
$$

Then there exists a sequence $\left\{\vec{\psi}_{j}\right\}, \vec{\psi}_{j} \in C_{0}^{\infty}\left(R_{n+1}\right)$ such that
(i) $\vec{\psi}_{j} \rightarrow \vec{u}$ in $\widetilde{\mathscr{H}}_{(0, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)$,
(ii) $L \vec{\psi}_{j} \rightarrow \vec{f}$ in $\widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$,
(iii) $\quad \vec{\psi}_{j}(0, \cdot) \rightarrow \vec{\alpha}$ in $\mathscr{H}_{(s)}\left(R_{n}\right)$ as $j \rightarrow \infty$.

Proof. Put $\vec{u}_{\varepsilon}=S_{\varepsilon}^{-1} \vec{u}, \vec{f}_{\varepsilon}=S_{\varepsilon}^{-1} \vec{f}$ and $\vec{\alpha}_{\varepsilon}=S_{\varepsilon}^{-1} \alpha$ for $\varepsilon>0$. Then $\vec{u}_{\varepsilon} \epsilon$ $\widetilde{\mathscr{H}}_{(0, s+r)}\left(\bar{R}_{n+1}^{+}\right), \vec{f}_{\varepsilon} \in \widetilde{\mathscr{H}}_{(0, s+1)}\left(\bar{R}_{n+1}^{+}\right), \vec{\alpha}_{\varepsilon} \in \mathscr{H}_{(s+1)}\left(\bar{R}_{n}\right)$ and we can write

$$
L\left(\vec{u}_{\varepsilon}\right)=\vec{f}_{\varepsilon}+\vec{\Gamma}_{\varepsilon}\left(\vec{u}_{\varepsilon}\right),
$$

where $\vec{\Gamma}_{\varepsilon}\left(\vec{u}_{\varepsilon}\right)=\vec{A}(t) \vec{u}_{\varepsilon}-S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon} \vec{u}_{\varepsilon} \in \widetilde{\mathscr{H}}_{(0, s+1)}\left(R_{n+1}^{+}\right)$and $\lim _{t \downarrow 0} \vec{u}_{\varepsilon}=\vec{\alpha}_{\varepsilon}$. Furthermore, we see from Lemmas 1 and 2 that

$$
\begin{equation*}
\vec{u}_{\varepsilon} \rightarrow \vec{u} \quad \text { in } \quad \tilde{\mathscr{H}}_{(0, s+r-1)}\left(\bar{R}_{n+1}^{+}\right), \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\vec{f}_{\varepsilon} \rightarrow \vec{f} \quad \text { in } \quad \tilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right), \tag{2}
\end{equation*}
$$

$$
\begin{equation*}
\vec{\Gamma}_{\varepsilon}\left(\vec{u}_{\varepsilon}\right) \rightarrow 0 \quad \text { in } \quad \tilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right), \tag{3}
\end{equation*}
$$

$$
\begin{equation*}
\vec{\alpha}_{\varepsilon} \rightarrow \vec{\alpha} \quad \text { in } \quad \mathscr{H}_{(s)}\left(R_{n}\right) \tag{4}
\end{equation*}
$$

as $\varepsilon \downarrow 0$. We note here $D_{t} \vec{u}_{\varepsilon}=\vec{f}_{\varepsilon}+\vec{\Gamma}_{\varepsilon}\left(\vec{u}_{\varepsilon}\right)-\vec{A}(t) \vec{u}_{\varepsilon} \in \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$.
For sufficiently small $\varepsilon_{0}>0$ if we put $\vec{v}^{1}=\vec{u}_{\varepsilon_{0}} \in \mathscr{\mathscr { H }}_{(0, s+r)}\left(\bar{R}_{n+1}^{+}\right), \vec{f}^{1}=\vec{f}_{\varepsilon_{0}}+$ $\vec{\Gamma}_{\varepsilon_{0}}\left(\vec{u}_{\varepsilon_{0}}\right) \in \widetilde{\mathscr{H}}_{(0, s+1)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{\alpha}^{1}=\vec{\alpha}_{\varepsilon_{0}} \in \mathscr{H}_{(s+1)}\left(R_{n}\right)$, then $L \vec{v}^{1}=\vec{f}^{1}, \lim _{t \downarrow 0} \vec{v}^{1}=\vec{\alpha}^{1}$ and we have

$$
\begin{array}{lll}
\vec{v}_{\varepsilon}^{1} \rightarrow \vec{v}^{1} & \text { in } & \tilde{\mathscr{H}}_{(0, s+r)}\left(\bar{R}_{n+1}^{+}\right), \\
\vec{f}_{\varepsilon}^{1}+\vec{\Gamma}_{\varepsilon}\left(\vec{v}_{\varepsilon}^{1}\right) \rightarrow \vec{f}^{1} & \text { in } & \tilde{\mathscr{H}}_{(0, s+1)}\left(\bar{R}_{n+1}^{+}\right), \\
\vec{\alpha}_{\varepsilon}^{1} \rightarrow \vec{\alpha}^{1} & \text { in } & \mathscr{H}_{(s+1)}\left(R_{n}\right) \tag{7}
\end{array}
$$

as $\varepsilon \downarrow 0$ and moreover $D_{t} \vec{v}_{\varepsilon}^{1} \in \widetilde{\mathscr{H}}_{(0, s+1)}\left(\bar{R}_{n+1}^{+}\right)$.
Determine $\vec{v}^{k}, k=2,3, \cdots$, successively, by $\vec{v}^{k}=\vec{v}_{\varepsilon_{0}}^{k-1}, \vec{f}^{k}=\vec{f}_{\varepsilon_{0}}^{k-1}+\vec{\Gamma}_{\varepsilon_{0}}\left(\vec{v}_{\varepsilon_{0}}^{k-1}\right)$ and $\vec{\alpha}^{k}=\vec{\alpha}_{\varepsilon_{0}}^{k-1}$. Then $\vec{v}^{k} \in \widetilde{\mathscr{H}}_{(0, s+r-1+k)}\left(\bar{R}_{n+1}^{+}\right), L \vec{v}^{k}=\vec{f}^{k} \in \widetilde{\mathscr{H}}_{(0, s+k)}\left(\bar{R}_{n+1}^{+}\right)$and $\lim _{t \downarrow 0} \vec{v}^{k}=$ $\vec{\alpha}^{k} \in \mathscr{H}_{(s+k)}\left(R_{n}\right) \subset \mathscr{H}_{(s)}\left(R_{n}\right)$ and we have $D_{t} \vec{v}^{k} \in \widetilde{\mathscr{H}}_{(0, s+k-1)}\left(\bar{R}_{n+1}^{+}\right)$. Thus $\vec{v}^{k} \epsilon$ $\widetilde{\mathscr{H}}_{(1, s+r+k-2)}\left(\bar{R}_{n+1}^{+}\right)$for $r \leqq 1$ and $\vec{v}^{k} \in \widetilde{\mathscr{H}}_{(1, s+k-1)}\left(\bar{R}_{n+1}^{+}\right)$for $r>1$.

Let us take $k$ so that $k>2-r$ (resp. $k \geqq r$ ) in the case where $r \leqq 1$ (resp. $r>1)$. There exists a sequence $\left\{\vec{\psi}_{j}\right\}, \vec{\psi}_{j} \in C_{0}^{\infty}\left(R_{n+1}\right)$, such that $\vec{\psi}_{j}$ converges in $\widetilde{\mathscr{H}}_{(1, s+r+k-2)}\left(\bar{R}_{n+1}^{+}\right)$(resp. in $\left.\widetilde{\mathscr{H}}_{(1, s+k-1)}\left(\bar{R}_{n+1}^{+}\right)\right)$to $\vec{v}^{k}$ for $r \leqq 1$ (resp. for $r>1$ ). Then $\vec{\psi}_{j}, L \vec{\psi}_{j}$ and $\vec{\psi}_{j}(0, \cdot)$ converge in $\widetilde{\mathscr{H}}_{(0, s+r-1)}\left(\bar{R}_{n+1}^{+}\right), \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\widetilde{\mathscr{H}}_{(s)}\left(R_{n}\right)$ to $\vec{v}^{k}, L \vec{v}^{k}$ and $\vec{v}^{k}(0, \cdot)$ respectively as $j \rightarrow \infty$.

Let $\sigma>-\frac{1}{2}$ and suppose $\vec{A}(t) \epsilon \mathfrak{C}_{(r)}^{l}$ with $l \geqq|\sigma|$. In the same way as in the proof of the theorem we can prove the following

Corollary 2. Let $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)$and assume that

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \epsilon \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), \\
\mathscr{D}_{L^{2}-1 \lim _{t \downarrow 0}} \vec{u}=\vec{\alpha} \in \mathscr{H}_{(\nu)}\left(R_{n}\right)
\end{array}\right.
$$

for any real ע. Then there exists a sequence $\left\{\vec{\psi}_{j}\right\}, \vec{\psi}_{j} \in C_{0}^{\infty}\left(R_{n+1}\right)$, such that
(i) $\quad \vec{\psi}_{j} \rightarrow \vec{u} \quad$ in $\quad \tilde{\mathscr{H}}_{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)$,
(ii) $L \vec{\psi}_{j} \rightarrow \vec{f}$ in $\tilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$,
(iii) $\quad \vec{\psi}_{j}(0, \cdot) \rightarrow \vec{\alpha} \quad$ in $\quad \mathscr{H}_{(\nu)}\left(R_{n}\right)$
as $j \rightarrow \infty$.
Let $\sigma, s$ be any real numbers and $r$ a fixed positive real number. According to S. Kaplan [11] we shall use the notation $\mathscr{K}^{(\sigma, s)}$ to denote the space $\mathscr{B}_{2, k}$ $[5, \mathrm{p} .36]$, where $k=k_{\sigma, s}=\left(\tau^{2}+\lambda^{2 r}(\xi)\right)^{\sigma / 2 r} \lambda^{s}(\xi), \lambda(\xi)=\left(1+|\xi|^{2}\right)^{1 / 2} . \mathscr{K}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$, $\mathscr{\mathscr { K }}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), \widetilde{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$and the like will have obvious meanings. We shall denote the norm in $\mathscr{K}^{(\sigma, s)}$ by $\|\cdot\|_{\sigma, s}$. Then we see from Proposition 5 in [8,
p. 413] that the canonical extension $u_{\sim}$ exists for every $u \epsilon \widetilde{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$if and only if $\sigma>-\frac{r}{2}$ and from Corollary 1 in [8, p. 412] that $\lim _{t \downarrow 0} u$ exists for every $u \in \widetilde{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$if and only if $\sigma>\frac{r}{2}$ and $\lim _{t \downarrow 0} u \in \mathscr{H}_{(\sigma+s-r / 2)}\left(R_{n}\right)$. In this case the trace map $u \rightarrow u(0, \cdot)$ of $\widetilde{\mathscr{K}}^{(\sigma, s)}$ into $\mathscr{H}_{(\sigma+s-r / 2)}\left(R_{n}\right)$ is an epimorphism (cf. Theorem 1 in [6, p. 21]). It is also to be noticed that $\mathscr{K}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\dot{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$may be identified for $|\sigma|<\frac{r}{2}$ (cf. Proposition 7 in [8, p. 416]). In the same way as in the proof of Proposition 14 in [10, p. 385] we can prove that $\left(A(t) \in \mathfrak{c}_{(r)}^{l}, l r \geqq|\sigma|\right.$, is a continuous linear map of $\widetilde{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$into $\widetilde{\mathscr{K}}^{(\sigma, s-r)}\left(\bar{R}_{n+1}^{+}\right)$for any real numbers $\sigma$, s. Similarly we have the following

Corollary $1^{\prime}$. Let $A(t) \epsilon \bigoplus_{(r)}^{l}$ with $l r \geqq|\sigma|$. Then
(i) For any $T>0$ and $\varepsilon$ with $0<\varepsilon \leqq 1$, there exists a constant $C_{T}^{(\sigma, s)}$ such that

$$
\begin{gathered}
\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{\sigma, s} \leqq C_{T}^{(\sigma, s)}\|\vec{\chi}\|_{\sigma, s+r-1} \\
0 \leqq t \leqq T, \vec{\chi} \in \widetilde{\mathscr{K}}^{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)
\end{gathered}
$$

(ii) For any $\vec{\chi} \in \widetilde{\mathscr{K}}^{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right),\left\|\left(S_{\varepsilon}^{-1} \vec{A}(t) S_{\varepsilon}-\vec{A}(t)\right) \vec{\chi}\right\|_{\sigma, s}$ converges to 0 $a s \varepsilon \downarrow 0$.

Corollary $2^{\prime}$. Let $\sigma>-\frac{r}{2}$ and $\vec{A}(t) \in \mathfrak{§}_{(r)}^{l}$ with $l r \geqq|\sigma|$. Let $\vec{u} \epsilon$ $\widetilde{\mathscr{K}}^{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)$and assume that

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \in \widetilde{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), \\
\mathscr{D}_{L^{2}}^{\prime}-\lim _{t \downarrow 0} \vec{u}=\vec{\alpha} \in \mathscr{H}_{(\nu)}\left(R_{n}\right)
\end{array}\right.
$$

for any real $\nu$. Then there exists a sequence $\left\{\vec{\psi}_{j}\right\}, \vec{\psi}_{j} \in C_{0}^{\infty}\left(R_{n+1}\right)$, such that
(i) $\vec{\psi}_{j} \rightarrow \vec{u}$ in $\widetilde{\mathscr{K}}^{(\sigma, s+r-1)}\left(\bar{R}_{n+1}^{+}\right)$,
(ii) $L \vec{\psi}_{j} \rightarrow \vec{f}$ in $\quad \widetilde{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$,
(iii) $\quad \vec{\psi}_{j}(0, \cdot) \rightarrow \vec{\alpha} \quad$ in $\quad \mathscr{H}_{(\nu)}\left(R_{n}\right)$
as $j \rightarrow \infty$.

## 2. Uniqueness and existence theorems for the Cauchy problem (I)

For the sake of simplicity we assume $A(t) \epsilon \mathbb{G}_{(1)}^{\infty}$ in this and next sections. Let $H$ be a slab $[0, T] \times R_{n}, T>0$, and denote by $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ the set of distributions $\epsilon \mathscr{D}^{\prime}(\dot{H})$ which can be extended to distributions $\epsilon \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$.

The quotient topology is induced in $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$. Similarly for $\mathscr{D}^{\prime}(H)$ and $\mathscr{D}^{\prime}((-\infty, T])$.

Consider the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \quad \text { in } \quad \dot{H},  \tag{8}\\
u_{0} \equiv \mathscr{D}_{L^{2}-\lim _{t \downarrow 0}} \vec{u}=\vec{\alpha}
\end{array}\right.
$$

for given $\vec{f} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ and $\vec{\alpha} \epsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$. If a solution $\vec{u} \epsilon \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ exists, then $\vec{f}$ must have the $\mathscr{D}_{L^{2}}{ }^{2}$-canonical extension $\vec{f}_{\sim}$ over $t=0$ and $\vec{u}_{\sim}$ satisfies the equation

$$
L\left(\vec{u}_{\sim}\right)=\vec{f}_{\sim}-i \delta_{t} \otimes \vec{\alpha} .
$$

Conversely, if $\vec{v} \in \mathscr{D}^{\prime}((-\infty, T])\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ vanishing for $t<0$ is a solution of $L \vec{v}=\vec{f}_{\sim}-i \delta_{t} \otimes \vec{\alpha}$, that is,
(9) $\quad\left(\left(\vec{v}, L^{*} \vec{w}\right)\right)=\left(\left(\vec{f}_{\sim}, \vec{w}\right)\right)-i\left(\vec{\alpha}, \vec{w}_{0}\right), \quad \vec{w} \in C_{0}^{\infty}\left((-\infty, T) \times R_{n}\right)$,
where ((,)) means the scalar product between $\mathscr{D}^{\prime}((-\infty, T])\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $\mathscr{D}((-\infty, T)) \widehat{\otimes}_{l}\left(\mathscr{D}_{L^{2}}\right)_{x}$, then the restriction $\vec{u} \mid H \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ is a solution of the Cauchy problem (8) (cf. Corollary 3 in [10, p. 393]). The equation (9) implies Green's formula:

$$
\left(\left((L \vec{u})_{\sim}, \vec{w}\right)\right)-\left(\left(\vec{u}, L^{*} \vec{w}\right)\right)=i\left(\vec{u}_{0}, \vec{w}_{0}\right) .
$$

Let $\vec{f} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H), \vec{\alpha}, \vec{\beta} \in\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ and assume that $\vec{f}$ has a two-sided $\mathscr{D}_{L^{2}}^{\prime}$-canonical extension $\vec{f}_{\sim}^{\sim}$. The problem to find a solution $\vec{u} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ of the equation $L \vec{u}=\vec{f}$ in $\dot{H}$ with the conditions $\vec{u}_{0}=\vec{\alpha}, \vec{u}_{T} \equiv \mathscr{D}_{L^{2}}^{\prime 2} \lim _{t \uparrow T} \vec{u}=\vec{\beta}$ is reduced to the problem of finding $\vec{v} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ with supp $\vec{v} \subset H$ such that

$$
\begin{equation*}
\left(\left(\vec{v}, L^{*} \vec{w}\right)\right)=\left(\left(\vec{f}_{\sim}^{\sim}, \vec{w}\right)\right)-i\left(\vec{\alpha}, \vec{w}_{0}\right)+i\left(\vec{\beta}, \vec{w}_{T}\right), \vec{w} \in C_{0}^{\infty}\left(R_{n+1}\right) \tag{10}
\end{equation*}
$$

where $(()$,$) means the scalar product between \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $\mathscr{D}_{t} \otimes\left(\mathscr{D}_{L^{2}}\right)_{x}$. The equation (10) implies Green's formula:

$$
\left(\left((L \vec{u})_{\sim}^{\sim}, \vec{w}\right)\right)-\left(\left(\vec{u}_{\sim}^{\sim}, L^{*} \vec{w}\right)\right)=-i\left\{\left(\vec{u}_{T}, \vec{w}_{T}\right)-\left(\vec{u}_{0}, \vec{w}_{0}\right)\right\} .
$$

In Sections 2 and 3, $L$ will be assumed to admit the inequality :

$$
\begin{gathered}
\left(E_{(0)}^{2} \uparrow\right)_{T}:\|\vec{\phi}(t, \cdot)\|_{(0)}^{2} \leqq C_{T}\left(\|\vec{\phi}(0, \cdot)\|_{(0)}^{2}+\int_{0}^{t}\left\|L \vec{\phi}\left(t^{\prime}, \cdot\right)\right\|_{(0)}^{2} d t^{\prime}\right), \\
0 \leqq t \leqq T, \quad \vec{\phi} \in C_{0}^{\infty}\left(R_{n+1}\right),
\end{gathered}
$$

where $C_{T}$ is a constant. We shall agree to write $\left(E_{(0)}^{2} \uparrow\right)$ if $\left(E_{(0)}^{2} \uparrow\right)_{T}$ holds true for every $T>0$.

We shall often need the following lemma (cf. Lemma 4 in [9, p. 78]).

Lemma 3. Let $r(t)$ and $\rho(t)$ be two real-valued functions defined in the interval $0 \leqq t \leqq T$ and suppose that $r$ is continuous and $\rho$ is non-decreasing. Then the inequality

$$
r(t) \leqq C\left(\rho(t)+\int_{0}^{t} r\left(t^{\prime}\right) d t^{\prime}\right)(C>0 \text { is a constant })
$$

implies

$$
r(t) \leqq C e^{C t} \rho(t)
$$

Let $s$ be arbitrarily chosen. If we apply the inequality $\left(E_{(0)}^{2} \uparrow\right)_{T}$ to $S^{s} \vec{\phi}$ instead of $\vec{\phi}$, then the pseudo-commutativity ( $*$ ) and Lemma 3 yield the following inequality :

$$
\begin{gathered}
\left(E_{(s)}^{2} \uparrow\right)_{T}:\|\vec{\phi}(t, \cdot)\|_{(s)}^{2} \leqq C_{T}^{(s)}\left(\|\vec{\phi}(0, \cdot)\|_{(s)}^{2}+\int_{0}^{t}\left\|L \vec{\phi}\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime}\right) \\
0 \leqq t \leqq T, \quad \vec{\phi} \in C_{0}^{\infty}\left(R_{n+1}\right)
\end{gathered}
$$

where $C_{T}^{(s)}$ is a constant. We can also apply Lemma 3 to conclude that if $\left(E_{(0)}^{2} \uparrow\right)_{T}$ holds for $L$ and $\vec{B}(t) \in \mathbb{C}_{(0)}$, then so does for $L^{1}=L+\vec{B}(t)$.

Let us denote by $\mathscr{E}_{t}^{0}\left(\mathscr{H}_{(s)}\right)$ the space of $\mathscr{H}_{(s)}\left(R_{n}\right)$-valued continuous functions of $t$ defined on $[0, \infty)$. Then we have

Proposition 1. Suppose ( $E_{(0)}^{2} \uparrow$ ) holds for L. If, for a given $\vec{u} \epsilon$ $\widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right), \quad L \vec{u}=\vec{f} \in \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\lim _{t \downarrow 0} \vec{u}=\vec{\alpha} \in \mathscr{H}_{(s)}\left(R_{n}\right)$ hold, then $\vec{u} \in$ $\mathscr{E}_{t}^{0}\left(\mathscr{H}_{(s)}\right)$ and $\vec{u}$ satisfies the inequality $\left(E_{(s)}^{2} \uparrow\right)$, that is,

$$
\|\vec{u}(t, \cdot)\|_{(s)}^{2} \leqq C_{T}^{(s)}\left(\|\vec{\alpha}\|_{(s)}^{2}+\int_{0}^{t}\left\|\vec{f}\left(t^{\prime}, \cdot\right)\right\|_{(s)} d t^{\prime}\right)
$$

In particular, if $\vec{f}=0$ and $\vec{\alpha}=0$, then $\vec{u}=0$.
Proof. In virtue of Theorem 1 there exists a sequence $\left\{\vec{\phi}_{k}\right\}, \vec{\phi}_{k} \in C_{0}^{\infty}\left(R_{n+1}\right)$, with properties mentioned there and we have

$$
\begin{aligned}
&\left\|\vec{\phi}_{k}(t, \cdot)-\vec{\phi}_{k^{\prime}}(t, \cdot)\right\|_{(s)}^{2} \leqq C_{T}^{(s)}\left(\left\|\vec{\phi}_{k}(0, \cdot)-\vec{\phi}_{k^{\prime}},(0, \cdot)\right\|_{(s)}^{2}+\right. \\
&\left.\quad+\int_{0}^{t}\left\|L \vec{\phi}_{k}\left(t^{\prime}, \cdot\right)-L \vec{\phi}_{k^{\prime}}\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime}\right)
\end{aligned}
$$

which means that $\left\{\vec{\phi}_{k}(t, \cdot)\right\}$ is a Cauchy sequence in $\mathscr{E}_{t}^{0}\left(\mathscr{H}_{(s)}\right)$. Let $\vec{v}$ be the limit of $\left\{\vec{\phi}_{k}\right\}$. Clearly $\vec{v}$ coincides with $\vec{u}$ as a distribution and $\vec{u}$ satisfies $\left(E_{(s)}^{2} \uparrow\right)$ and the proposition is proved.

Let $u \in \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$. Then $u$ may be considered as an $\mathscr{H}_{(s)}\left(R_{n}\right)$-valued measurable function $u(t, \cdot)$ defined for almost everywhere $t \in(0, \infty)$ and $\int_{0}^{T}\|u(t, \cdot)\|_{(s)}^{2} d t<+\infty$ for any $T>0$. Thus almost all points $t_{0} \in(0, \infty)$ are Lebesgue points of $u(t, \cdot)$ :

$$
\lim _{h \downarrow 0} \frac{1}{2 h} \int_{t_{0}-h}^{t_{0}+h}\left\|u\left(t^{\prime}, \cdot\right)-u\left(t_{0}, \cdot\right)\right\|_{(s)} d t^{\prime}=0
$$

Let $t_{0}$ be a Lebesgue point of $u(t, \cdot)$. For any $\phi \in C_{0}^{\infty}\left(R_{t}\right)$ such that $\phi \geqq 0$, $\int \phi(t) d t=1$ and $\operatorname{supp} \phi \subset[-1,1]$, we have for any small $\varepsilon>0$

$$
\begin{aligned}
& \left\|\frac{1}{\varepsilon} \int \phi\left(\frac{t-t_{0}}{\varepsilon}\right) u(t, \cdot) d t-u\left(t_{0}, \cdot\right)\right\|_{(s)} \\
= & \left\|\frac{1}{\varepsilon} \int \phi\left(\frac{t-t_{0}}{\varepsilon}\right)\left(u(t, \cdot)-u\left(t_{0}, \cdot\right)\right) d t\right\|_{(s)} \\
\leqq & \frac{\sup \phi}{\varepsilon} \int_{t_{0}-\varepsilon}^{t_{0}+\varepsilon}\left\|u(t, \cdot)-u\left(t_{0}, \cdot\right)\right\|_{(s)} d t .
\end{aligned}
$$

Thus we see that $u\left(t_{0}, \cdot\right)$ is the section of $u$ for $t=t_{0}$.
If $\vec{u} \in \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$and $L \vec{u}=\vec{f} \in \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$, then $\vec{u}$ may be considered as an $\mathscr{H}_{(s)}$-valued continuous function of $t \in(0, \infty)$. In fact, let $t_{0}>0$ be a sufficiently small Lebesgue point of $\vec{u}(t, \cdot)$. Then $\lim _{t \downarrow t_{0}} \vec{u}$ exists in $\mathscr{H}_{(s)}\left(R_{n}\right)$ and therefore $\vec{u}$ is an $\mathscr{H}_{(s)}\left(R_{n}\right)$-valued continuous function of $t \in\left[t_{0}, \infty\right)$, where $t_{0}$ can be chosen arbitrarily small.

For any $\sigma$, $s$ we denote by $\mathscr{H}_{(\sigma, s)}(H)$ the space of all distributions $u \in \mathscr{D}^{\prime}(H)$ such that there exists a distribution $U \in \mathscr{H}_{(\sigma, s)}\left(R_{n+1}\right)$ with $U=u$ in $\dot{H}$. The norm of $u$ is defined by $\|u\|_{(\sigma, s)}=\inf \|U\|_{(\sigma, s)}$, the infimum being taken over all such $U$.

In the following Propositions 2 through 7 we assume that $\left(E_{(0)}^{2} \uparrow\right)_{T}$ holds for $L$.

Proposition 2. If $\vec{u} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H), L \vec{u}=0$ in $\dot{H}$ and $\mathscr{D}_{L^{2}-}^{\prime-\lim _{t \downarrow 0}} \vec{u}=0$, then $\vec{u}=0$ in $\xrightarrow[H]{h}$.

Proof. Since $\vec{u} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ there exist integers $k, l$ such that $\vec{u} \in \mathscr{H}_{(k, l)}(H)$. Suppose that $k<0$. From the relation $D_{t} \vec{u}=-\vec{A}(t) \vec{u} \in \mathscr{H}_{(k, l-1)}(H)$ it follows that $\vec{u} \in \mathscr{H}_{(k+1, l-1)}(H)$. Repeating this procedure, we see that $\vec{u} \epsilon$ $\mathscr{H}_{(0, l-k)}(H)$, and applying Proposition 1 we can conclude that $\vec{u}=0$ in $\dot{H}$.

Proposition 3. For any given $\vec{g} \in \mathscr{H}_{(0, s)}(H)$ and $\vec{\beta} \in \mathscr{H}_{(s)}\left(R_{n}\right)$, s being a real number, the Cauchy problem:

$$
\left\{\begin{array}{l}
L^{*} \vec{v}=\vec{g} \text { in } \dot{H},  \tag{11}\\
\lim _{t \downarrow T} \vec{v}=\vec{\beta}
\end{array}\right.
$$

has a solution $\vec{v} \in \mathscr{H}_{(0, s)}(H)$ such that $\vec{r}=\lim _{t \downarrow 0} \vec{v}$ exists in $\mathscr{H}_{(s)}\left(R_{n}\right)$ and such that the inequality

$$
\|\vec{r}\|_{(s)}+\int_{0}^{T}\|\vec{v}(t, \cdot)\|_{(s)} d t \leqq C_{T}\left(\|\vec{\beta}\|_{(s)}+\int_{0}^{T}\|\vec{g}(t, \cdot)\|_{(s)} d t\right)
$$

holds, where $C_{T}$ is a constant.
Proof. Consider the space $\boldsymbol{H}_{(-s)}=\mathscr{H}_{(-s)}\left(R_{n}\right) \times \mathscr{H}_{(0,-s)}(H)$ and its subspace $A=\left\{(\vec{u}(0, \cdot), L \vec{u}): \vec{u} \in C_{0}^{\infty}(H)\right\}$. Then the map

$$
l: A \ni(\vec{u}(0, \cdot), L \vec{u}) \rightarrow \int_{0}^{T}(\vec{u}(t, \cdot), \vec{g}(t, \cdot)) d t-i\left(\vec{u}_{T}, \vec{\beta}\right)
$$

is continuous. In fact, from the energy inequality $\left(E_{(-s)}^{2} \uparrow\right)_{T}$ for $L$ we have

$$
\begin{aligned}
& \left|\int_{0}^{T}(\vec{u}(t, \cdot), \vec{g}(t, \cdot)) d t-i\left(\vec{u}_{T}, \vec{\beta}\right)\right| \\
& \leqq \max _{0 \leqq t \leq T}\|\vec{u}(t, \cdot)\|_{(-s)} \int_{0}^{T}\|\vec{g}(t, \cdot)\|_{(s)} d t+\left\|\vec{u}_{T}\right\|_{(-s)}\|\beta\|_{(s)} \\
& \leqq \sqrt{C_{T}^{(-s)}}\left(\|\vec{u}(0, \cdot)\|_{(-s)}^{2}+\int_{0}^{T}\|L \vec{u}(t, \cdot)\|_{(-s)}^{2} d t\right)^{1 / 2}\left(\|\vec{\beta}\|_{(s)}+\int_{0}^{T}\|\vec{g}(t, \cdot)\|_{(s)} d t\right)
\end{aligned}
$$

which implies the inequality

$$
\|l\| \leqq \sqrt{C_{T}^{(-s)}}\left(\|\vec{\beta}\|_{(s)}+\int_{0}^{T}\|\vec{g}(t, \cdot)\|_{(s)} d t\right)
$$

Thus there exists $(i \vec{f}, \vec{v}) \in \boldsymbol{H}_{(s)}$ such that

$$
\begin{equation*}
\int_{0}^{T}(L \vec{u}(t, \cdot), \vec{v}(t, \cdot)) d t-i\left(\vec{u}_{0}, \vec{r}\right)=\int_{0}^{T}(\vec{u}(t, \cdot), \vec{g}(t, \cdot)) d t-i\left(\vec{u}_{T}, \vec{\beta}\right) \tag{12}
\end{equation*}
$$

and

$$
\left(\|\vec{\gamma}\|_{(s)}^{2}+\int_{0}^{T}\|\vec{v}(t, \cdot)\|_{(s)}^{2} d t\right)^{1 / 2} \leqq \sqrt{C_{T}^{(-s)}}\left(\|\vec{\beta}\|_{(s)}+\int_{0}^{T}\|g(t, \cdot)\|_{(s)} d t\right)
$$

From Green's formula (12) we see that $\|\vec{v}\|$ is a solution of the Cauchy problem (11), which completes the proof.

We shall say that $(\mathrm{CP})_{(s)}$ holds for $L$ if the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \quad \text { in } H,  \tag{13}\\
\lim _{t \downarrow 0} \vec{u}=\vec{\alpha}
\end{array}\right.
$$

has a solution $\vec{u} \in \mathscr{H}_{(0, s)}(H)$ for any given $\vec{f} \in \mathscr{H}_{(0, s)}(H)$ and $\vec{\alpha} \epsilon \mathscr{H}_{(s)}\left(\boldsymbol{R}_{n}\right)$. Then we have the following

Proposition 4. If $(\mathrm{CP})_{(s)}$ holds for $L$, then so does it for $L^{1}=L+\vec{B}(t)$, $\vec{B}(t) \epsilon \sqsubseteq_{(0)}$.

Proof. Let (CP) $)_{(s)}$ hold for $L$ and consider the Cauchy problem:

$$
\left\{\begin{array}{l}
L^{1} \vec{u}=\vec{h} \quad \text { in } \dot{H}, \\
\lim _{t \downarrow 0} \vec{u}=\vec{r}
\end{array}\right.
$$

for any given $\vec{h} \in \mathscr{H}_{(0, s)}(H)$ and $\vec{r} \in \mathscr{H}_{(s)}\left(R_{n}\right)$.
Let $\vec{v}^{0} \in \mathscr{H}_{(0, s)}(H)$ be chosen so that

$$
\left\{\begin{array}{l}
L \vec{v}^{0}=\vec{h} \quad \text { in } \dot{H}, \\
\lim _{t \downarrow 0} \vec{v}^{0}=\vec{r}
\end{array}\right.
$$

If there exists a $\vec{w} \in \mathscr{H}_{(0, s)}(H)$ such that

$$
\left\{\begin{array}{l}
L \vec{w}=-\vec{B}(t) \vec{w}-\vec{B}(t) \vec{v}^{0} \\
\lim _{t \downarrow 0} \vec{w}=0
\end{array}\right.
$$

then $\vec{u}=\vec{v}^{0}+\vec{w}$ will be the solution to be found. The method of successive approximation will be successful to this end.

Put $\vec{w}^{0}=0$ and determine $\vec{w}^{l} \in \mathscr{H}_{(0, s)}(H)$ successively by

$$
\left\{\begin{array}{l}
L \vec{w}^{l+1}=-\vec{B}(t) \vec{w}^{l}-\vec{B}(t) \vec{v}^{0} \\
\lim _{t \downarrow 0} \vec{w}^{l+1}=0
\end{array}\right.
$$

Then $L\left(\vec{w}^{l+1}-\vec{w}^{l}\right)=-\vec{B}(t)\left(\vec{w}^{l}-\vec{w}^{l-1}\right)$ and we have from $\left(E_{(s)}^{2} \uparrow\right)_{T}$ for $L$

$$
\begin{aligned}
\left\|\left(\vec{w}^{l+1}-\vec{w}^{l}\right)(t, \cdot)\right\|_{(s)}^{2} & \leqq C_{s, T} \int_{0}^{t}\left\|\left(\vec{w}^{l}-\vec{w}^{l-1}\right)\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime} \\
& \leqq C_{s, T}^{l} \int_{0}^{t} \frac{\left(t-t^{\prime}\right)^{l-1}}{(l-1)!}\left\|\vec{w}^{1}(t, \cdot)\right\|_{(s)}^{2} d t \\
& \leqq \frac{\left(C_{s, T} T\right)^{l}}{l!} \sup _{0 \leqq t^{\prime} \leqq T}\left\|\vec{w}^{1}\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2}, 0 \leqq t \leqq T
\end{aligned}
$$

and therefore $\left\|\left(\vec{w}^{l+l^{\prime}}-\vec{w}^{l}\right)(t, \cdot)\right\|_{(s)} \leqq C_{s, T}^{\prime}$, where $C_{s, T}^{\prime}$ is a constant independent of $l, l^{\prime}$. Thus $\left\{\vec{w}^{l}\right\}$ is a Cauchy sequence in $\mathscr{E}_{t}^{0}\left(\mathscr{H}_{(s)}\right), t \in[0, T)$. If we put $\vec{w}=\lim _{l \rightarrow \infty} \vec{w}^{l}$, then $\vec{w}$ will be the solution as desired.

Proposition 5. If $(\mathrm{CP})_{(s)}$ holds for some $s$, then it does also for any $s$.
Proof. Let $(\mathrm{CP})_{(s)}$ hold for $L$. This means that the set $A=\{(\vec{\phi}(0, \cdot), L \vec{\phi})$ : $\left.\vec{\phi} \in C_{0}^{\infty}(H)\right\}$ is dense in $\boldsymbol{H}_{(s)}=\mathscr{H}_{(s)} \times \mathscr{H}_{(0, s)}(H)$. Let $s^{\prime}$ be any real number. Then the map $\left[S^{s^{\prime}-s}\right]:(\vec{\alpha}, \vec{f}) \rightarrow\left(S^{s^{\prime}-s} \vec{\alpha}, S^{s^{\prime}-s} \vec{f}\right)$ is an isomorphism of $\boldsymbol{H}_{(s)}$ onto
$\boldsymbol{H}_{\left(s^{\prime}\right)}$ and $\left[S^{s^{\prime}-s}\right](A)$ is also dense in $\boldsymbol{H}_{\left(s^{\prime}\right)}$. If we put $\vec{\psi}=S^{s^{\prime}-s} \vec{\phi}, \vec{\phi} \in C_{0}^{\infty}(H)$, then we have

$$
\begin{aligned}
\left(S^{s^{\prime}-s}(\vec{\phi}(0, \cdot)), S^{s^{\prime}-s} L \vec{\phi}\right) & =\left(\vec{\psi}(0, \cdot), S^{s^{\prime}-s} L S^{s-s^{\prime}} \vec{\psi}\right) \\
& =(\vec{\psi}(0, \cdot), L \vec{\psi}+\vec{B}(t) \vec{\psi}),
\end{aligned}
$$

where $\vec{B}(t)=S^{s^{\prime}-s} L S^{s-s^{\prime}}-L=S^{s^{\prime}-s} \vec{A}(t) S^{s-s^{\prime}}-\vec{A}(t)$ is of order $\leqq 0$. Thus $(\mathrm{CP})_{\left(s^{\prime}\right)}$ holds for $L^{1}=L+\vec{B}(t)$ and therefore so does it for $L$.

Proposition 6. If for any $\vec{f} \in \mathscr{H}_{(0, s)}(H)$ and $\vec{\alpha} \in \mathscr{H}_{(s)}\left(R_{n}\right)$ the Cauchy problem (8) has a solution $\vec{u} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$, then $\vec{u} \in \mathscr{H}_{(0, s)}(H)$

Proof. There exist integers $k, l$ such that $\vec{u} \in \mathscr{H}_{(k, l)}(H)$. Suppose that $k<0$. Then from the equation $D_{t} \vec{u}=\vec{f}-\vec{A}(t) \vec{u}$ we see that $D_{t} \vec{u} \in \mathscr{H}_{\left(k, s_{1}\right)}(H)$, $s_{1}=\min (s-k, l-1)$ and therefore $\vec{u} \in \mathscr{H}_{\left(k+1, s_{2}\right)}(H), s_{2}=\min \left(l-1, s_{1}\right)$. Repeating this procedure, we can find $s^{\prime}$ such that $\vec{u} \in \mathscr{H}_{\left(0, s^{\prime}\right)}(H)$. For any $(\vec{\alpha}, \vec{f}) \in \boldsymbol{H}_{(s)}$ $=\mathscr{H}_{(s)}\left(R_{n}\right) \times \mathscr{H}_{(0, s)}(H)$ a solution of the Cauchy problem (13) belongs to the space $\bigcup_{m=-\infty}^{\infty} \mathscr{H}_{(0, m)}(H)$. Since a solution is unique in $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ for $\vec{f}$ and $\vec{\alpha}$, we see from the closed graph theorem that $(\vec{\alpha}, \vec{f}) \rightarrow \vec{u}$ is a continuous map of $\boldsymbol{H}_{(s)}$ into $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{\left.\left.L^{2}\right)_{x}\right)}\right)(H)\right.$. The space $\mathscr{H}_{(s)}\left(R_{n}\right)$ and $\mathscr{H}_{(0, s)}(H)$ are both of type $(\boldsymbol{F})$. Thus by Theorem A in A. Grothendieck [4, p. 16] there exists a fixed $m$ such that the corresponding solution $\vec{u}$ belonging to the space $\mathscr{H}_{(0, m)}(H)$ for every $(\vec{\alpha}, \vec{f}) \in \boldsymbol{H}_{(s)}$.

Suppose that $m<s$. For any $\vec{g} \in \mathscr{H}_{(0, m)}(H)$ and $\vec{\beta} \in \mathscr{H}_{(m)}\left(R_{n}\right)$ there exist sequences $\left\{\vec{g}_{j}\right\},\left\{\vec{\beta}_{j}\right\}, \vec{g}_{j} \in C_{0}^{\infty}(H), \vec{\beta}_{j} \in C_{0}^{\infty}\left(R_{n}\right)$ such that $\vec{g}_{j}, \vec{\beta}_{j}$ converge to $\vec{g}, \vec{\beta}$ in $\mathscr{H}_{(0, m)}(H), \mathscr{H}_{(m)}\left(R_{n}\right)$ as $j=\infty$ respectively. Denote by $\vec{v}_{j}$ a unique solution $\epsilon \mathscr{H}_{(0, m)}(H)$ of the Cauchy problem (13) associated with $\vec{g}_{j}$ and $\vec{\beta}_{j}$. Owing to $\left(E_{(m)}^{2} \uparrow\right)_{T},\left\{\vec{v}_{j}\right\}$ is a Cauchy sequence in $\mathscr{E}_{t}^{0}\left(\mathscr{H}_{(m)}\right), t \in[0, T)$, and therefore $\vec{v}_{j}$ has the limit $\vec{v} \in \mathscr{H}_{(0, m)}(H)$ and $\vec{v}$ is a solution of the Cauchy problem (13) associated with $\vec{g}$ and $\vec{\beta}$. In virtue of Proposition 5, it follows that $\vec{u} \epsilon$ $\mathscr{H}_{(0,-s)}(H)$, which was to be proved.

Proposition 7. (CP $)_{(s)}$ holds for $L$ if and only if the conditions that $\vec{w} \in \mathscr{H}_{(0, s)}(H), L^{*} \vec{w}=0$ in $\dot{H}$ and $\lim _{t \uparrow T} \vec{w}=0$ imply $\vec{w}=0$ in $\dot{H}$.

Proof. Let $(\mathrm{CP})_{(s)}$ hold for $L$ and $\vec{w} \in \mathscr{H}_{(0,-s)}(H)$ and assume that $L^{*} \vec{w}=0$ in ${ }_{H}^{H}$ with $\lim _{t \uparrow T} \vec{w}=0$. For any $\vec{f} \in C_{0}^{\infty}(\vec{H})$ let $\vec{u} \in \mathscr{H}_{(0, s)}(H)$ be a solution of $L \vec{u}=\vec{f}$. Since $\left(E_{(s)}^{2} \uparrow\right)_{T}$ holds for $L$, there exists a sequence $\left\{\vec{\phi}_{j}\right\}, \vec{\phi}_{j} \in C_{0}^{\infty}(H)$, vanishing near $t=0$ and we have $\int_{0}^{T}\left(L \vec{\phi}_{j}(t, \cdot), \vec{w}(t, \cdot)\right) d t=0$. Thus $\vec{w}=0$ in $\dot{H}$.

To prove the converse, it suffices to show that $A=\left\{(\vec{\phi}(0, \cdot), L \vec{\phi}): \vec{\phi} \in C_{0}^{\infty}(H)\right\}$ is dense in $\boldsymbol{H}_{(s)}=\mathscr{H}_{(s)}\left(R_{n}\right) \times \mathscr{H}_{(0, s)}(H)$. Let $(i \vec{\beta}, \vec{w}) \in \boldsymbol{H}_{(-s)}$ such that

$$
\int_{0}^{T}(L \vec{\phi}(t, \cdot), \vec{w}(t, \cdot)) d t-i\left(\vec{\phi}_{0}, \vec{\beta}\right)=0, \quad \vec{\phi} \in C_{0}^{\infty}(H)
$$

which implies $L^{*} \vec{w}=0$ in $\dot{H}$ and $\lim _{t \uparrow T} \vec{w}=0$. Thus we see that $\vec{w}=0$ in $\dot{H}$ and $\vec{\beta}=0$, completing the proof.

Proposition 8. Let $(\mathrm{CP})_{(s)}$ hold for $L$. Then the energy inequality $\left(E_{(0)}^{2} \uparrow\right)_{T}$ implies the following:

$$
\begin{gathered}
\left(E_{(0)}^{1} \uparrow\right)_{T}:\|\vec{\phi}(t, \cdot)\|_{(0)} \leqq C_{T}^{\prime}\left(\|\vec{\phi}(0, \cdot)\|_{(0)}+\int_{0}^{t}\left\|L \vec{\phi}\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}\right) \\
0 \leqq t \leqq T, \quad \vec{\phi} \in C_{0}^{\infty}\left(R_{n+1}\right)
\end{gathered}
$$

Proof. From the fact that (CP) $)_{(s)}$ holds for $L$ in any slab $H_{1}=\left[0, T_{1}\right]$ $\times R_{n}, 0<T_{1} \leqq T$, we see by the preceding proposition that the conditions $\vec{w} \in \mathscr{H}_{(0,-s)}\left(H_{1}\right), L^{*} \vec{w}=0$ in $\dot{H}_{1}$ and $\lim _{t \uparrow T_{1}} \vec{w}=0$ imply $\vec{w}=0$. in $\dot{H}_{1}$, and therefore by Proposition 3 we can conclude that $\left(E_{(s)}^{1} \uparrow\right)_{T}$ holds for $L$. In virtue of the pseudo-commutativity (*) and Lemma 3 we see that $\left(E_{(s)}^{1} \uparrow\right)_{T}$ implies $\left(E_{\left(s^{\prime}\right)}^{1} \uparrow\right)_{T}$ for any $s^{\prime}$, completing the proof.

We shall say that $(\mathrm{CP})_{(s)}$ holds for $L$ if the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \quad \text { in } R_{n+1}^{+},  \tag{14}\\
\lim _{t \downarrow 0} \vec{u}=\vec{\alpha}
\end{array}\right.
$$

has a solution $\vec{u} \in \mathscr{H}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$for any given $\vec{g} \in \mathscr{H}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{\alpha} \in \mathscr{H}_{(s)}\left(R_{n}\right)$.
Consider the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \quad \text { in } R_{n+1}^{+}  \tag{15}\\
\mathscr{D}_{L^{2}-\lim _{t \downarrow 0}^{\prime}} \vec{u}=\vec{\alpha}
\end{array}\right.
$$

for given $\vec{\alpha} \epsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ and $\vec{f} \epsilon \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, which has the $\mathscr{D}_{L^{2}}^{\prime}$-canonical extension $\vec{f}_{\sim}$. For the Cauchy problem (15) we can prove with necessary modifications the analogues of Propositions 2 through 8, which were obtained for the slab $H$.

Theorem 2. Suppose ( $E_{(0)}^{2} \uparrow$ ) holds for $L$. Then
(1) A solution of the Cauchy problem (15) is unique in $\mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$.
(2) For any given $\vec{g} \in \widetilde{\mathscr{H}}_{(0, s)}^{*}\left(\bar{R}_{n+1}^{+}\right)$, the equation $L^{*} \vec{w}=\vec{g}$ in $R_{n+1}^{+}$has a solution $\vec{w} \in \widetilde{\mathscr{H}}_{(0, s)}^{*}\left(\bar{R}_{n+1}^{+}\right)$such that $\vec{r}=\lim _{t \downarrow 0} \vec{w}$ exists in $\mathscr{H}_{(s)}\left(R_{n}\right)$ and

$$
\|\vec{\gamma}\|_{(s)}+\int_{0}^{\infty}\|\vec{w}(t, \cdot)\|_{(s)} d t \leqq C_{s} \int_{0}^{\infty}\|\vec{g}(t, \cdot)\|_{(s)} d t
$$

with a constant $C_{s}$.
(3) The following conditions are equivalent:
(i) (CP) $)_{(s)}$ holds for some real s.
(ii) (CP) $)_{(s)}$ holds for every real s.
(iii) (CP) $)_{(s)}$ holds for $L^{1}=L+\vec{B}(t)$ with $\vec{B}(t) \in \mathbb{C}_{(0)}$.
(iv) If $\vec{w} \in \widetilde{\mathscr{H}}_{(0, s)}^{*}\left(\bar{R}_{n+1}^{+}\right)$and $L \vec{w}=0$ in $R_{n+1}^{+}$, then $\vec{w}=0$.

If each of these conditions is satisfied, then the energy inequality $\left(E_{(s)}^{1} \uparrow\right)$ holds true for any s.

Let $k$ be a non-negative integer and $s$ a real number. Along the same line as in the proofs of Proposition 5 and Corollary 3 in [9, p. 89, p. 90] we can obtain

Proposition 9. Suppose $\left(E_{(0)}^{2} \uparrow\right)$ and (CP) $)_{(0)}$ hold for L. Then for any $\vec{f} \in \widetilde{\mathscr{H}}_{(k, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{\alpha} \in \mathscr{H}_{(k+s)}\left(R_{n}\right)$ the Cauchy problem (14) has a unique solution $\vec{u} \in \mathscr{H}_{(k+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{u}$ has the following properties:
(i) $\left(\vec{u}, \cdots, D_{t}^{k} \vec{u}\right) \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(k+s)}\right) \times \cdots \times \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(s)}\right)$,

$$
\begin{array}{r}
\sum_{j=0}^{k}\left\|D_{t}^{j} \vec{u}(t, \cdot)\right\|_{(k+s-j)}^{2} \leqq C_{T}\left(\|\vec{\alpha}\|_{(k+s)}^{2}+\sum_{j=0}^{k-1}\left\|D_{t}^{j} \vec{f}(0, \cdot)\right\|_{(k+s-1-j)}^{2}+\right.  \tag{ii}\\
\left.+\sum_{j=0}^{k} \int_{0}^{t}\left\|D_{t}^{j} \vec{f}\left(t^{\prime}, \cdot\right)\right\|_{(k+s-j)}^{2} d t^{\prime}\right), \quad 0 \leqq t \leqq T
\end{array}
$$

for any $T>0$.
Applying the interpolation theorem for the Hilbert scales and proceeding along the same lines as in the proof of Corollary 4 in [9, p. 96] we can obtain

Proposition 10. Suppose $\left(E_{(0)}^{2} \uparrow\right)$ and (CP) $)_{(0)}$ hold for L. Then for any $\vec{f} \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{\alpha} \in \mathscr{H}_{(\sigma+s)}\left(R_{n}\right), \sigma$ being a non-negative number, the Cauchy problem (14) has a unique solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$and $(\vec{\alpha}, \vec{f}) \rightarrow \vec{u}$ is a continuous map of $\mathscr{H}_{(\sigma+s)}\left(R_{n}\right) \times \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$into $\tilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$.

Next we show the following
Theorem 3. Suppose $\left(E_{(0)}^{2} \uparrow\right)$ and (CP) $)_{(0)}$ hold for L. Let $\sigma=k+\sigma^{\prime}$ with non-negative integer $k$ and $-\frac{1}{2}<\sigma^{\prime} \leqq \frac{1}{2}$. Then for any $\vec{f} \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{\alpha} \in \mathscr{H}_{(\sigma+s)}\left(R_{n}\right)$ the Cauchy problem (15) has a unique solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$ and $\vec{u}$ has the following properties:
(i) $\left(\vec{u}, \cdots, D_{t}^{k} \vec{u}\right) \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(\sigma+s)}\right) \times \cdots \times \mathscr{E}_{t}^{0}\left(\mathscr{H}_{\left(\sigma^{\prime}+s\right)}\right)$,
(ii) $(\vec{\alpha}, \vec{f}) \rightarrow \vec{u}$ is a continuous map of $\mathscr{H}_{(\sigma+s)}\left(R_{n}\right) \times \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$into $\widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$.

Proof. As shown in Theorem 2 a solution of the Cauchy problem (15) is unique in $\mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$. We shall first consider the case $\sigma \geqq 0$. Owing to Proposition 9 and Corollary 3, there exists a solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$ and $\vec{u}$ has the property (ii). We have only to show that $\left(\vec{u}, \ldots, D_{t}^{k} \vec{u}\right) \epsilon$ $\mathscr{E}_{t}^{0}\left(\mathscr{H}_{(\sigma+s)}\right) \times \cdots \times \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(s)}\right)$. Clearly $\vec{u} \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(\sigma+s)}\right)$ and $\vec{f} \epsilon \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(\sigma+s-1 / 2)}\right)$ for $\sigma>\frac{1}{2}$ and therefore $D_{t} \vec{u}=\vec{f}-\vec{A}(t) \vec{u} \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(\sigma+s-1)}\right)$. Repeating this process, we see that (i) holds true.

Next, consider the case $-\frac{1}{2}<\sigma<0$. The canonical extension $\vec{f}_{\sim}$ belongs to the space $\stackrel{\circ}{\mathscr{\mathscr { H }}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$. If we put

$$
\vec{g}=\frac{\vec{f}_{\sim}}{D_{t}-i \lambda\left(D_{x}\right)}, \text { i.e. } \quad D_{t} \vec{g}-i \lambda\left(D_{x}\right) \vec{g}=\vec{f}_{\sim}
$$

where $\lambda(\xi)=\left(1+|\xi|^{2}\right)^{1 / 2}$ and $\lambda\left(D_{x}\right) \in \mathfrak{C}_{(1)}^{\infty}$, then $\vec{g} \in \stackrel{\circ}{\mathscr{\mathscr { H }}}_{(\sigma+1, s)}\left(\bar{R}_{n+1}^{+}\right), \frac{1}{2}<\sigma+1<1$. From Corollary 3 in [8, p. 419] we see that $\lim _{t \downarrow 0} g$ exists and equals 0 . The Cauchy problem (15) can be written in the form

$$
\left\{\begin{array}{l}
D_{t}(\vec{u}-\vec{g})+\vec{A}(t)(\vec{u}-\vec{g})=-i \lambda\left(D_{x}\right) \vec{g}-\vec{A}(t) \vec{g} \quad \text { in } R_{n+1}^{+} \\
\mathscr{D}_{L^{2}-\lim _{t \downarrow 0}}(\vec{u}-\vec{g})=\vec{\alpha}
\end{array}\right.
$$

where $-i \lambda\left(D_{x}\right) \vec{g}-\vec{A}(t) \vec{g} \in \dot{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right), \sigma+1>\frac{1}{2}$. Thus there exists a unique solution $\vec{v}=\vec{u}-\vec{g} \in \widetilde{\mathscr{H}}_{(\sigma+2, s-2)}\left(\bar{R}_{n+1}^{+}\right) \cap \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(\sigma+s)}\right)$ and therefore $\vec{u}=\vec{v}+\vec{g}$ $\epsilon \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right) \cap \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(\sigma+s)}\right)$. In view of the closed graph theorem it follows that $(\vec{\alpha}, \vec{f}) \rightarrow \vec{u}$ is a continuous map of $\mathscr{H}_{(\sigma+s)}\left(R_{n}\right) \times \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$into $\widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. This completes the proof of the theorem.

We shall close this section with some remarks on energy inequalities.
Proposition 11. If the following inequality for $L$ :

$$
\left(\tilde{E}_{(0)}^{2} \uparrow\right)_{T}:\left\|\vec{\phi}\left(t_{1}, \cdot\right)\right\|_{(0)}^{2} \leqq C_{T}\left(\left\|\vec{\phi}\left(t_{0}, \cdot\right)\right\|_{(0)}^{2}+\int_{t_{0}}^{t_{1}}\|L \vec{\phi}(t, \cdot)\|_{(0)}^{2} d t\right), \vec{\phi} \in C_{0}^{\infty}\left(R_{n+1}\right)
$$

holds for any $t_{0}, t_{1}, 0 \leqq t_{0} \leqq t_{1} \leqq T$ with a constant $C_{T}$, then the condition that $\vec{w} \in \mathscr{H}_{(0, s)}(H), L^{*} \vec{w}=0$ in $\vec{H}$ and $\lim _{t \uparrow T} \vec{w}=0$ imply $\vec{w}=0$ in $\dot{H}$ is equivalent to saying that the inequality for $L^{*}$ :

$$
\left(E_{(0)}^{1} \downarrow\right)_{T}:\left\|\vec{\phi}\left(t_{0}, \cdot\right)\right\|_{(0)} \leqq C_{t}^{\prime}\left(\left\|\vec{\phi}\left(t_{1}, \cdot\right)\right\|_{(0)}+\int_{t_{0}}^{t_{1}}\left\|L^{*} \vec{\phi}(t, \cdot)\right\|_{(0)} d t\right), \vec{\phi} \in C_{0}^{\infty}\left(R_{n+1}\right)
$$

holds for any $t_{0}, t_{1}, 0 \leqq t_{0} \leqq t_{1} \leqq T$, where $C_{T}^{\prime}$ is a constant.
If this is the case, then ( $\left.\tilde{E}_{(0)}^{1} \uparrow\right)$ holds true for $L$.

Proof. We may take $s=0$. Suppose a solution of the Cauchy problem for $L^{*}$ is unique in $\mathscr{H}_{(0,0)}(H)$. Then it is unique in $\mathscr{H}_{(0,0)}\left(H_{1}\right), H_{1}=\left[0, t_{1}\right] \times R_{n}$. We shall first show that it is also unique in $\mathscr{H}_{(0,0)}\left(H^{\prime}\right), H^{\prime}=\left[t_{0}, t_{1}\right] \times R_{n}$. Let $\vec{w} \in \mathscr{H}_{(0,0)}\left(H^{\prime}\right), L^{*} \vec{w}=0$ in $H^{\prime}$ and $\lim _{t \uparrow t_{1}} \vec{w}=0$. Let $t_{0}^{\prime}$ be a Lebesgue point of the $\mathscr{H}_{(0)}\left(R_{n}\right)$-valued function $\vec{w}(t, \cdot)$ defined on $\left(t_{0}, t_{1}\right)$. Then $\vec{w}$ has the section $\vec{w}\left(t_{0}^{\prime}, \cdot\right)=\vec{\beta} \in \mathscr{H}_{(0)}\left(R_{n}\right)$ for $t=t_{0}^{\prime}$. The Cauchy problem $L^{*} \vec{w}_{1}=0$ in $\left(0, t_{0}^{\prime}\right) \times R_{n}$ with initial condition $\lim _{t \uparrow t_{0}^{\prime}} \vec{w}_{1}=\vec{\beta}$ has a unique solution $\vec{w}_{1} \epsilon \mathscr{H}_{(0,0)}\left(\left[0, t_{0}^{\prime}\right] \times R_{n}\right)$. If we put $\vec{W}=\vec{w}$ in $\left[t_{0}^{\prime}, t_{1}\right) \times R_{n}$ and $\vec{W}=\vec{w}_{1}$ in $\left(0, t_{0}^{\prime}\right] \times R_{n}$, then $L^{*} \vec{W}=0$ in $\left(0, t_{1}\right) \times R_{n}$ and $\lim _{t \uparrow t_{1}} \vec{W}=0$. Our assumption implies $\vec{W}=0$ and therefore $\vec{w}=0$.

Thus, replacing $0, T$ by $t_{0}, t_{1}$ in the proof of Proposition 3, and repeating the same procedure as given there, we see that for given $\vec{g} \in \mathscr{H}_{(0,0)}\left(H^{\prime}\right)$ and $\vec{\beta} \in \mathscr{H}_{(0)}\left(R_{n}\right)$ the Cauchy problem $L^{*} \vec{v}=\vec{g}$ in $\dot{H}^{\prime}$ with initial condition $\lim _{t \uparrow t_{1}} \vec{v}=\vec{\beta}$ has a unique solution $\vec{v} \in \mathscr{H}_{(0,0)}\left(H^{\prime}\right)$ and $\vec{v}$ satisfies the following:

$$
\|\vec{\gamma}\|_{(0)}+\int_{t_{0}}^{t_{1}}\|\vec{v}(t, \cdot)\|_{(0)} d t \leqq C_{T}^{\prime}\left(\|\vec{\beta}\|_{(0)}+\int_{t_{0}}^{t_{1}}\|\vec{g}(t, \cdot)\|_{(0)} d t\right)
$$

where $\vec{r}=\lim _{t \downarrow t_{0}} \vec{v}$ and $C_{T}^{\prime}$ is a constant. As a result, we can conclude that $\left(E_{(0)}^{1} \downarrow\right)_{T}$ holds true for any $\vec{\phi} \in C_{0}^{\infty}\left(R_{n+1}\right)$.

The converse is trivial, since the approximation theorem holds for $L^{*}$.
Proposition 12. Suppose $\left(E_{(0)}^{2} \uparrow\right)_{T}$ holds for $L$ and $L^{*}$. Then
(i) $\left(\tilde{E}_{(0)}^{1} \uparrow\right)_{T}$ holds for $L$ and $L^{*}$.
(ii) $(\mathrm{CP})_{(0)}$ holds for $L$ if and only if $\left(\tilde{E}_{(0)}^{1} \downarrow\right)_{T}$ holds for $L^{*}$.

Proof. (i) Let $t_{0}, t_{1}$ be any two points such that $0 \leqq t_{0} \leqq t_{1} \leqq T$. Then Proposition 3 implies that for any given $\vec{\beta} \in \mathscr{H}_{(0)}\left(R_{n}\right)$ the Cauchy problem

$$
\left\{\begin{array}{l}
L^{*} \vec{v}=0 \quad \text { in } \dot{H}_{1}, \\
\lim _{t \uparrow t_{1}} \vec{v}=\vec{\beta}
\end{array}\right.
$$

where $H_{1}=\left[0, t_{1}\right] \times R_{n}$, has a solution $\vec{v} \in \mathscr{H}_{(0,0)}\left(H_{1}\right)$ such that $\|\vec{v}(0, \cdot)\|_{(0)} \leqq$ $C_{1}\|\vec{\beta}\|_{(0)}$ with a constant $C_{1}$ independent of $t_{1}$. From the fact that $\left(E_{(0)}^{2} \uparrow\right)_{T}$ holds for $L^{*}$ it follows that

$$
\|\vec{v}(t, \cdot)\|_{(0)} \leqq C\|\vec{v}(0, \cdot)\|_{(0)} \leqq C_{2}\|\vec{\beta}\|_{(0)}, \quad 0 \leqq t \leqq t_{1} .
$$

From Green's formula

$$
\int_{t_{0}}^{t_{1}}\left(L \vec{u}\left(t^{\prime}, \cdot\right), \vec{v}\left(t^{\prime}, \cdot\right)\right) d t^{\prime}=-i\left\{\left(\vec{u}\left(t_{1}, \cdot\right), \vec{\beta}\right)-\left(\vec{u}\left(t_{0}, \cdot\right), \vec{v}\left(t_{0}, \cdot\right)\right)\right\}
$$

for any $\vec{u} \in C_{0}^{\infty}\left(R_{n+1}\right)$, we have

$$
\begin{aligned}
& \left|\left(\vec{u}\left(t_{1}, \cdot\right), \vec{\beta}\right)\right| \leqq C_{3}\left\{\left\|\vec{u}\left(t_{0}, \cdot\right)\right\|_{(0)}\left\|\vec{v}\left(t_{0}, \cdot\right)\right\|_{(0)}+\right. \\
& \left.\quad+\int_{t_{0}}^{t_{1}}\left\|L \vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(0)}\left\|\vec{v}\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}\right\} \\
& \leqq C_{4}\|\vec{\beta}\|_{(0)}\left\{\left\|\vec{u}\left(t_{0}, \cdot\right)\right\|_{(0)}+\int_{t_{0}}^{t_{1}}\left\|L \vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}\right\},
\end{aligned}
$$

where $C_{2}, C_{3}$ and $C_{4}$ are constants independent of $t_{0}$ and $t_{1}$. This implies that we have with a constant $C_{T}$

$$
\left\|\vec{u}\left(t_{1}, \cdot\right)\right\|_{(0)} \leqq C_{T}\left(\left\|\vec{u}\left(t_{0} \cdot,\right)\right\|_{(0)}+\int_{t_{0}}^{t_{1}}\left\|L \vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}\right)
$$

Combining (i) with Proposition 11 leads to (ii), which completes the proof.

## 3. Uniqueness and existence theorems for the Cauchy problem (II)

Let $\sigma, s$ be any real numbers and write $\sigma=k+\sigma^{\prime}$ with integer $k$ and $-\frac{1}{2}<\sigma^{\prime} \leqq \frac{1}{2}$. Then we have the following

Proposition 13. Suppose $\left(E_{(0)}^{2} \uparrow\right)$ and (CP) $)_{(0)}$ hold for L. Then
(i) For any $\vec{\alpha} \in \mathscr{H}_{(\sigma+s)}\left(R_{n}\right)$ and $\vec{f} \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$, where $\vec{f}$ is assumed to have the $\mathscr{D}_{L}^{\prime}$-canonical extension $\vec{f}_{-} \epsilon \stackrel{\mathscr{\mathscr { H }}}{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$, the Cauchy problem (15) has a unique solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$.
(ii) Let $\vec{u} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and assume that $\mathscr{D}_{L^{2}}^{\prime-l_{t} \lim ^{\prime} \vec{u}}$ exists, $L \vec{u}=\vec{f}$
 some real $\sigma$, s. Then $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. In particular, if $\vec{\alpha}=0$ then $\vec{u} \epsilon$ $\dot{\mathscr{\mathscr { H }}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$.

Proof. Consider the case $k \geqq 0$. In Theorem 2 we have shown that there exists a solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$for the Cauchy problem (I5). Since a solution of the Cauchy problem (15) is unique in $\mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ we have only to show that if $\alpha=0$ then $\vec{u}_{\sim} \in \dot{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. Suppose $\vec{\alpha}=0$. Then $\lim _{t \downarrow 0}\left(\vec{u}, \cdots, D_{t}^{k} \vec{u}\right)=0$. In fact, if $k=0$ then $\lim _{t \downarrow 0} \vec{u}=\mathscr{D}_{L^{2}}^{\prime}-\lim _{t \downarrow 0} \vec{u}=0$. Let $k>0$. $\stackrel{t \downarrow 0}{T h e n}$ the condition $\vec{f}_{\sim} \epsilon \stackrel{\circ}{\mathscr{\mathscr { H }}}_{\left(k+\sigma^{\prime}, s\right)}\left(\bar{R}_{n+1}^{+}\right)$implies $\lim _{t \downarrow 0}^{t \downarrow 0}\left(\vec{f}, \cdots, D_{t}^{k-1} \vec{f}\right)=$ $\underset{\substack{\mathscr{D}^{2} \\ t \downarrow 0}}{L_{0}^{2-1}}\left(\vec{f}, \cdots, D_{t}^{k-1} \vec{f}\right)=0$ (cf. Theorem 3 in $[8, \mathrm{p} .419]$ ). Since $\lim _{t \downarrow 0} \vec{A}(t) \vec{u}=$ $\lim _{t \downarrow 0} \vec{A}^{\prime}(t) \vec{u}=\cdots=0$, it follows from the equation $D_{t} \vec{u}=\vec{f}-\vec{A}(t) \vec{u}$ that $\lim _{t \downarrow 0} D_{t} \vec{u}=0$. Then from the equation $D_{t}^{2} \vec{u}=D_{t} \vec{f}+i \vec{A}^{\prime}(t) \vec{u}+\vec{A}(t) D_{t} \vec{u}$ we obtain $\lim _{t \downarrow 0} D_{t}^{2} \vec{u}=0$.

Repeating this procedure, we see that $\lim _{t \downarrow 0}\left(\vec{u}, \cdots, D_{t}^{k} \vec{u}\right)=0$. In the case where $\sigma^{\prime}<\frac{1}{2}$, by Theorem 3 in $\left[8\right.$, p. 419] we have $\left.\vec{u}_{\sim} \in \stackrel{\check{\mathscr{H}}}{(\sigma+1, s-1)} \bar{R}_{n+1}^{+}\right)$. Let $\sigma^{\prime}=\frac{1}{2}$. Then $\quad \vec{u}_{\sim} \epsilon \stackrel{\mathscr{\mathscr { H }}}{(\sigma+1-\varepsilon, s-1+\varepsilon)}\left(\bar{R}_{n+1}^{+}\right)\left(\stackrel{\ddot{\mathscr{H}}}{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), \quad 0<\varepsilon<1, \quad\right.$ and therefore $\left(D_{t}-i \lambda\left(D_{x}\right)\right) \vec{u}_{\sim}=\vec{f}_{\sim}-\vec{A}(t) \vec{u}_{\sim}-i \lambda\left(D_{x}\right) \vec{u}_{\sim} \epsilon \stackrel{\mathscr{\mathscr { H }}}{(\sigma, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. Consequently $\vec{u}_{\sim} \epsilon$ $\stackrel{\ddot{\mathscr{H}}}{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$.

Consider the case where $k \leqq 0$. We shall reason by descending induction over $k$. Assume that the results are valid for any $k+1$. Let $\vec{f}_{\dot{\mathscr{C}}} \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$ with $\vec{f}_{\sim} \epsilon \dot{\mathscr{\mathscr { H }}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right), \sigma=k+\sigma^{\prime}$ and $\vec{\alpha} \in \mathscr{H}_{(\sigma+s)}\left(R_{n}\right)$. Let $\vec{g} \in \dot{\mathscr{\mathscr { H }}}_{(\sigma+1, s)}\left(\bar{R}_{n+1}^{+}\right)$be such that

$$
D_{t} \vec{g}-i \lambda\left(D_{x}\right) \vec{g}=\vec{f}_{\sim}
$$

Then it follows from Corollary 3 in $[10, \mathrm{p} .393]$ that $\mathscr{D}_{L^{2}-1 \lim _{t \downarrow 0}} \vec{g}=0$. The Cauchy problem (15) can be written in the form

$$
\left\{\begin{array}{l}
D_{t}(\vec{u}-\vec{g})+\vec{A}(t)(\vec{u}-\vec{g})=-i \lambda\left(D_{x}\right) \vec{g}-\vec{A}(t) \vec{g} \quad \text { in } R_{n+1}^{+} \\
\mathscr{D}_{L^{2}}^{\prime} \lim _{t \downarrow 0}(\vec{u}-\vec{g})=\vec{\alpha}
\end{array}\right.
$$

where $-i \lambda\left(D_{x}\right) \vec{g}-\vec{A}(t) \vec{g} \in \dot{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. Then there exists a solution $\vec{v}=\vec{u}-\vec{g} \in \widetilde{\mathscr{H}}_{(\sigma+2, s-2)}\left(\bar{R}_{n+1}^{+}\right)$and therefore $\vec{u}=\vec{v}+\vec{g} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. In particular, if $\vec{\alpha}=0$ then $\vec{v} \in \stackrel{\mathscr{H}}{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. Thus the proof is complete.

Proposition 14. Suppose $\left(E_{(0)}^{2} \uparrow\right)$ and (CP) $)_{(0)}$ hold for L. For any given $\vec{h} \in \stackrel{\dot{\mathscr{H}}}{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$there exists a unique solution $\vec{v} \in \dot{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$of $L \vec{v}=\vec{h}$.

Proof. First we let $\sigma>-\frac{1}{2}$. The problem to find a solution $\vec{v} \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+} \varepsilon$ $\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ for $L \vec{v}=\vec{h}$ is equivalent to the one to find a solution $\vec{u} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ of the Cauchy problem $L \vec{u}=\vec{f}, \vec{f}=\vec{h} \mid R_{n+1}^{+} \in \widetilde{\mathscr{H}}_{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$, with initial condition $\mathscr{D}_{L^{2}-1 \lim _{t \downarrow 0}} \vec{u}=0$. Thus we see that there exists a solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$ and $\vec{u}_{\sim} \in \dot{\mathscr{\mathscr { H }}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$. Moreover we can conclude that $\vec{v}$ is unique in $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$.

Let $\sigma \leqq-\frac{1}{2}$. We can then show the existence of a solution $\vec{v} \epsilon$ $\dot{\mathscr{\mathscr { H }}}_{(\sigma+1, s-1)}\left(\bar{R}_{n+1}^{+}\right)$by proceeding along the same line as in the proof of Proposition 13. And the proof is now complete.

Theorem 4. Suppose $\left(E_{(0)}^{2} \uparrow\right)^{-}$and $(\mathrm{CP})_{(0)}$ hold for $L$. Then for any $\vec{h} \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ there exists a unique solution $\vec{v} \in\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ of $L \vec{v}=\vec{h}$ and $\vec{h} \rightarrow \vec{v}$ is a continuous map of $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ onto itself.

Proof. Let $\left\{t_{j}\right\}$ be a sequence of real numbers such that $t_{0}<0<t_{1}<t_{2}<\cdots$ and $\lim _{j \rightarrow \infty} t_{j}=\infty$ and put $U_{j}=\left(t_{j}, t_{j+2}\right)$. Then $\left\{U_{j}\right\}_{j=0,1, \ldots}$ is an open covering
of $\left(t_{0}, \infty\right)$. We can choose a partition of unity $\left\{\phi_{j}\right\}$ subordinate to the covering. Then $\vec{h}=\sum_{j=0}^{\infty} \phi_{j} \vec{h}$. Consider the equations

$$
L \vec{v}_{j}=\phi_{j} \vec{h}, \quad j=0,1, \cdots,
$$

where $\phi_{j} \vec{h} \in \dot{\mathscr{\mathscr { H }}}_{\left(\sigma_{j}, s_{j}\right)}\left(\bar{R}_{n+1}^{+}\right)$for some real numbers $\sigma_{j}, s_{j}$. In virtue of Proposition 14 it follows that there exists a solution $\vec{v}_{j} \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$. From our assumption that $\left(E_{(0)}^{2} \uparrow\right)$ holds for $L$ we see that $\vec{v}_{j}$ vanishes for $t<t_{j}$. Thus $\vec{v}=\sum_{j=0}^{\infty} \vec{v}_{j}$ is well defined in the space $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $\vec{v}$ is unique in $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$.

Let us consider the map

$$
l:\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right) \ni \vec{v} \rightarrow L \vec{v} \in\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right),
$$

which is linear, continuous and onto. Since the space $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ is ultrabornological and Souslin (Corollary 1 in [10, p.374]), we see from Corollary in $[16, \mathrm{p} .604]$ that $l$ is an epimorphism. Thus the proof is complete.

Now we can state the following theorem which is an immediate consequence of Theorem 4 and the discussions given just before Lemma 3.

Theorem 5. Suppose $\left(E_{(0)}^{2} \uparrow\right)$ and (CP) i0) hold for L. Then for any $\vec{\alpha} \in\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ and $\vec{f} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, where $\vec{f}$ is assumed to have the $\mathscr{D}_{L_{2}}^{\prime}$-canonical extension $\vec{f}_{\sim} \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, the Cauchy problem (15) has a unique solution $\vec{u} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $\left(\vec{\alpha}, \vec{f}_{\sim}\right) \rightarrow \vec{u}$ is a continuous map under the topology of $\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x} \times\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and the topology of $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$.

## 4. Pseudo-differential operators with constant coefflcients

Let $A_{i j} \in \mathrm{OP}_{r}, i, j=1,2, \cdots, N$, such that $\frac{\partial}{\partial x_{k}}\left(A_{i j} \phi\right)=A_{i j}\left(\frac{\partial}{\partial x_{k}} \phi\right), k=1,2, \ldots, N$, hold for any $\phi \in C_{0}^{\infty}\left(R_{n}\right)$. Then there exist distributions $T_{A_{i j}} \in \mathscr{D}^{\prime}\left(R_{n}\right)$, with which we can write $A_{i j} u=T_{A_{i j}} *^{\prime} u, u \in\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$, where by $*^{\prime}$ we mean the partial convolution with respect to the variable $x$. By taking $\delta$ as $u$ we see that $T_{A_{i j}} \epsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$. We shall denote by $\vec{A}$ (resp. $\left.\vec{T}_{A}\right)$ the $N \times N$ matrix with entries $A_{i j}\left(\right.$ resp. $\left.T_{A_{i j}}\right)$. Then we can write $\vec{A} \vec{u}=\vec{T}_{A^{*}} \vec{u}$. The map $l: \hat{\vec{u}} \rightarrow\left(1+|\xi|^{2}\right)^{-\frac{r}{2}} \times$ $\hat{\vec{T}}_{A}(\xi) \hat{\vec{u}}$ is a bounded operator of $L^{2}\left(\Xi_{n}\right)$ into itself and its norm is given by the formula

$$
\|l\|=\text { ess. sup }\left|\left(1+|\xi|^{2}\right)^{-\frac{r}{2}} \hat{\vec{T}}_{A}(\xi)\right|
$$

where we mean by $|\vec{X}|$ the operator norm of a matrix $\vec{X}$. Thus $\hat{\vec{T}}_{A_{i j}}(\xi)$ is a locally summable function for $i, j=1,2, \cdots, N$ and

$$
\left|\hat{\vec{T}}_{A}(\xi)\right| \leqq C\left(1+|\xi|^{2}\right)^{\frac{r}{2}}
$$

with a constant $C=\|l\|$.
In this section we shall deal with the operator $L=D_{t}+\vec{A}$, where $\vec{A} \in \mathrm{OP}_{r}$ is a convolution operator given above.

Proposition 15. If $\vec{u} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ satisfies $L \vec{u}=0$ in $R_{n+1}^{+}$and $\mathscr{D}_{L^{2}-\lim _{t \downarrow 0}^{\prime}} \vec{u}=0$, then $\vec{u}=0$ in $R_{n+1}^{+}$.

Proof. By Proposition 9 we see that $\vec{u}$ may be considered as a $\mathscr{D}_{L^{2}}^{\prime}$-valued $C^{\infty}$ function of $t$. If we write $\vec{A} \vec{u}=\vec{T}_{A} *^{\prime} \vec{u}$ with a $\vec{T}_{A} \epsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ such that $\left|\hat{\vec{T}}_{A}(\xi)\right| \leqq C\left(1+|\xi|^{2}\right)^{r / 2}$, then the Fourier transformation of $D_{t} \vec{u}+\vec{A}(t) \vec{u}$ with respect to $x$ is written in the form

$$
D_{t} \hat{\vec{u}}(t, \xi)+\hat{\vec{T}}_{A}(\xi) \hat{\vec{u}}(t, \xi)=0 .
$$

Since $e^{i \hat{T}_{A}(\xi) t}$ is a locally summable function of $\xi$, $e^{i \dot{T}_{A}(\xi) t} \hat{\hat{u}}$ is well defined as $\mathscr{D}^{\prime}\left(\Xi_{n}\right)$-valued $C^{\infty}$ function of $t$ and $D_{t}\left(e^{i \tilde{T}_{A}(\xi) t} \hat{u}\right)=0$ and therefore $\vec{U}(\xi)=$ $e^{i \hat{T}_{A}(\xi) t} \hat{\vec{u}}(t, \xi) \in \mathscr{D}^{\prime}\left(\Xi_{n}\right)$. On the other hand, from $\mathscr{D}_{L^{2}}^{\prime} \lim _{t \downarrow 0} u=0$ we see that $\lim _{t \downarrow 0} \vec{u}=\lim _{t \downarrow 0} \hat{\vec{u}}=0$. Thus $\vec{U}(\xi)=0$ as a distribution. Thus we can conclude that $\vec{u}=0$ as a distribution.

We shall say the Cauchy problem for $L$ is well posed in the $L^{2}$ norm if for any $\vec{\alpha} \in C_{0}^{\infty}\left(R_{n}\right)$ the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{u}=0 \quad \text { in } \quad(0, T) \times R_{n} \\
\lim _{t \downarrow 0} \vec{u}=\vec{\alpha}
\end{array}\right.
$$

has a unique solution $\vec{u} \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(0)}\right), 0 \leqq t \leqq T$, and

$$
\|\vec{u}(t, \cdot)\|_{(0)} \leqq C_{T}\|\vec{u}(0, \cdot)\|_{(0)}, \quad 0 \leqq t \leqq T
$$

where $T>0$ is arbitrary.
Then the Cauchy problem for $L$ is well posed in the $L^{2}$ norm if and only if

$$
\left|e^{-i \hat{\mathscr{T}}_{A}(\xi) t}\right| \leqq C_{T}, \quad 0 \leqq t \leqq T
$$

If we put $k=\left(\log C_{T}\right) / T$, then

$$
\left|e^{-i \hat{T}_{A}(\xi) t}\right| \leqq C_{T} e^{k t}, \quad 0 \leqq t<\infty
$$

and therefore

$$
\left|e^{-\left(i \hat{T}_{A}(\xi)+k I\right) t}\right| \leqq C_{T}, \quad 0 \leqq t<\infty
$$

In [17, p. 411] G. Strang gave a necessary and sufficient condition in order that a Kowalewski system may be strongly hyperbolic. In connection
with his studies we shall show the following
Proposition 16. The following conditions are equivalent:
(1) The Cauchy problem for $L$ is well posed in the $L^{2}$ norm.
(2) $\left(E_{(0)}^{1} \uparrow\right)$ holds for $L$ and $\left(E_{(0, \downarrow}^{1} \downarrow\right)$ holds for $L^{*}$.
(3) $\left(E_{(0)}^{2} \uparrow\right)$ holds for $L$ and $\left(E_{(0)}^{2} \downarrow\right)$ holds for $L^{*}$.
(4) $\left(E_{(0)}^{2} \uparrow\right)$ holds for $L$.

Proof Since the implications $(2) \Rightarrow(3),(3) \Rightarrow(4)$ are trivial, we have only to show the implications $(1) \Rightarrow(2)$ and $(4) \Rightarrow(1)$.
(1) $\Rightarrow(2)$. For any $\vec{u} \in C_{0}^{\infty}\left(R_{n+1}\right)$ if we put $\vec{f}=L \vec{u}$, then we have

$$
D_{t} \hat{\vec{u}}(t, \xi)+\hat{\vec{T}}_{A}(\xi) \hat{\vec{u}}(t, \xi)=\hat{\vec{f}}(t, \xi),
$$

and therefore

$$
\hat{\vec{u}}(t, \xi)=e^{-i \hat{F}_{A}(\xi) t} \hat{\vec{u}}(0, \xi)+i \int_{0}^{t} e^{-i \dot{f}_{A}(\xi)\left(t-t^{\prime}\right)} \dot{\vec{f}}\left(t^{\prime}, \xi\right) d t^{\prime}
$$

which implies that ( $E_{(0)}^{1} \uparrow$ ) holds for $L$ and similarly $\left(E_{(0)}^{1} \downarrow\right)$ holds for $L^{*}$.
$(4) \Rightarrow(1)$. Consider the set $\left.A=\left\{(\vec{\phi}(0, \cdot), L \vec{\phi}): \vec{\phi} \in C_{0}^{\infty}{ }_{(n+1}\right)\right\}$. Then the set $A$ is dense in $\mathscr{H}_{(0)}\left(R_{n}\right) \times \widetilde{\mathscr{H}}_{(0,0)}\left(\bar{R}_{n+1}^{+}\right)$. In fact, let $(-i \vec{\beta}, \vec{w})$ be any element of $\mathscr{H}_{(0)}\left(R_{n}\right) \times \widetilde{\mathscr{H}}_{(0,0)}^{*}\left(\bar{R}_{n+1}^{+}\right)$such that

$$
\int_{0}^{\infty}(L \vec{\phi}(t, \cdot), \vec{w}(t, \cdot)) d t-i(\vec{\phi}(0, \cdot), \vec{\beta})=0 .
$$

This means that $L^{*} \vec{w}=0$ in $R_{n+1}^{+}$, and therefore the preceding proposition implies $\vec{w}=0$ and $\vec{\beta}=0$. Thus there exists a sequence $\left\{\vec{\phi}_{j}\right\}, \vec{\phi}_{j} \in C_{0}^{\infty}\left(R_{n+1}\right)$, such that $L \vec{\phi}_{j} \rightarrow 0$ in $\widetilde{\mathscr{H}}_{(0,0)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{\phi}_{j}(0, \cdot) \rightarrow \vec{\alpha}$. In virtue of $\left(E_{(0)}^{2} \uparrow\right)$ we see that $\left\{\vec{\phi}_{j}(t, \cdot)\right\}$ is a Cauchy sequence in $\mathscr{E}_{t}^{0}\left(\mathscr{H}_{(0)}\right)$. If we put $\vec{u}=\lim _{j \rightarrow \infty} \vec{\phi}_{j}$, then $\vec{u} \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(0)}\right)$ and for any $T>0$ we have $\|\vec{u}(t, \cdot)\|_{(0)} \leqq C_{T}\|\vec{\alpha}\|_{(0)}, 0 \leqq t \leqq T$.

Let $\mathfrak{F}$ be a family of $N \times N$ matrices $\vec{M}(\xi)$ of measurable functions of $\xi$. As an analogue of a result of H.-O. Kreiss [12, p. 71; 13, p.113], we can show the following

Proposition 17. The following conditions are equivalent:
(1) $\left|e^{\vec{M}(\xi) t}\right| \leqq C$ for all $t \geqq 0$ and $\vec{M} \in \mathfrak{F}$ a.e. on $\Xi_{n}$.
(1)' For any complex number $s$ with $\operatorname{Re} s>0$ there exists a constant $C$ such that for all $\vec{M} \in \mathfrak{F}$

$$
(\vec{M}(\xi)-s I)^{-1} \leqq C / \operatorname{Re} s \text { a.e. on } \Xi_{n} .
$$

(2) There exist a constant $C$ and a matrix $\vec{S}$, whose entries are measurable functions of $\xi$, such that for all $\vec{M} \in \mathfrak{F}$

$$
|\vec{S}(\xi)|,\left|\vec{S}^{-1}(\xi)\right| \leqq C
$$

and

$$
S M S^{-1}=\left(\begin{array}{ccccc}
x_{1} & b_{12} \ldots \ldots \cdots \cdots & b_{1 N} \\
0 & x_{2} & b_{23} \ldots \cdots \cdots & b_{2 N} \\
\ldots \ldots \ldots \ldots \ldots \cdots \cdots \cdots \cdots \\
0 \ldots \ldots \ldots \cdots \cdots & 0 & x_{N}
\end{array}\right) \quad \text { a.e. on } \Xi_{n}
$$

where $0 \geqq \operatorname{Re} x_{1} \geqq \operatorname{Re} x_{2} \geqq \cdots \geqq \operatorname{Re} x_{N}$ and $\left|b_{i j}\right| \leqq C\left|\operatorname{Re} x_{i}\right|$.
(3) There exist a constant $C$ and a positive definite Hermitian matrix $\vec{H}(\xi)$ such that for all $\vec{M} \in \mathfrak{F}$

$$
|\vec{H}(\xi)|,\left|\vec{H}^{-1}(\xi)\right| \leqq C \text { and } \vec{H} \vec{M}+\vec{M}^{*} \vec{H} \leqq 0 \quad \text { a.e. on } \Xi_{n} .
$$

The proposition with $\vec{M}(\xi)$ replaced by $-i \vec{T}_{A}(\xi)-k I$ yields the following
Corollary 3. The following conditions are equivalent:
(1) $\left|e^{-\left(i \dot{T}_{A}(\xi)+k I\right) t}\right| \leqq C$ for $t \geqq 0$ and a.e. on $\Xi_{n}$.
(2) There exist a constant $C$ and a matrix $\vec{S}$ such that

$$
|S(\xi)|,\left|S^{-1}(\xi)\right| \leqq C
$$

and

$$
\vec{S} \hat{\vec{T}}_{A} \vec{S}^{-1}=\left(\begin{array}{cccc}
x_{1} b_{12} \ldots \ldots \ldots \cdots & b_{1 N} \\
0 x_{2} b_{23} \ldots \ldots \ldots & b_{2 N} \\
\ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \\
0 \ldots \ldots \ldots \ldots \ldots & 0 & x_{N}
\end{array}\right) \quad \text { a.e. on } \Xi_{n}
$$

where $k \geqq \operatorname{Im} x_{1} \geqq \cdots \geqq \operatorname{Im} x_{N}$ and $\left|b_{i j}\right| \leqq C\left(\left|\operatorname{Im} x_{i}-k\right|\right)$.
(3) There exist a constant $C$ and a positive definite Hermitian matrix $\vec{H}(\xi)$ such that

$$
|\vec{H}(\xi)|,\left|\vec{H}^{-1}(\xi)\right| \leqq C \text { and }-i\left(\vec{H}(\xi) \hat{\vec{T}}_{A}(\xi)-\hat{\vec{T}}_{A}^{*}(\xi) \vec{H}(\xi)\right) \leqq k C \quad \text { a.e. on } \Xi_{n} .
$$

Proposition 18. Suppose $\hat{\vec{T}}_{A}(\xi)$ is positive homogeneous of degree $r>0$, that is, $\hat{\vec{T}}_{A}(\lambda \xi)=\lambda^{r} \hat{\vec{T}}_{A}(\xi)$ for $\lambda>0$. For the operator $L=D_{t}+\vec{A}(t)$, the energy inequality $\left(E_{0, ~ 2}^{2} \uparrow \downarrow\right)$ holds if and only if the eigenvalues $\chi_{j}$ of the matrix $\hat{\vec{T}}_{A}(\xi)$ are real and $\hat{T}_{A}(\xi)$ is symmetrizable.

Proof. Suppose ( $E_{(0)}^{2} \uparrow$ ) holds for $L$. Let $\chi_{j}(\xi), j=1,2, \cdots, N$, be the eigenvalues of $\hat{T}_{A}(\xi)$. From that $\left(E_{(0)}^{2} \uparrow\right)$ holds for $L$ it follows by Corollary 3 (2) that $k \geqq \operatorname{Im} \chi_{j}(\xi)$ and $\chi_{j}(\lambda \xi)=\lambda^{r} \chi_{j}(\xi)$, and therefore $\frac{k}{\lambda^{r}} \geqq \operatorname{Im} \chi_{j}(\xi)$. On the other hand, that ( $E_{(0)}^{2} \downarrow$ ) holds for $L$ means that ( $E_{(0)}^{2} \downarrow$ ) holds for $L^{1}=D_{t}-\vec{A}$. In the same way as above, we can conclude that $0 \geqq-\operatorname{Im} \chi_{j}(\xi)$, and therefore $\operatorname{Im} x_{j}(\xi)=0$ for $j=1,2, \cdots, N$.

From the relation $\left|e^{-i \dot{\vec{T}}_{A}(\xi) t}\right| \leqq C_{T}, 0 \leqq t \leqq T$, together with the fact that $\hat{\vec{T}}_{A}(\xi)$ is positive homogeneous of degree $r$, we may take $k=0$, and by Corollary 3 (2) we can conclude that $b_{i j}=0$ for any $i, j$. Taking $\vec{H}(\xi)=\vec{S}^{*}(\xi) \vec{S}(\xi)$, we see that $\vec{H}(\xi)$ is a positive definite Hermitian matrix, $\vec{H}(\xi), \vec{H}^{-1}(\xi)$ are bounded and $\vec{H}(\xi) \hat{\vec{T}}_{A}(\xi)$ is Hermitian.

The converse is well known [3, p. 111].
Let $\vec{A} \in \mathrm{OP}_{r}, r>0$ and $\chi_{j}(\xi), j=1,2, \cdots, N$, be the characteristic roots of the matrix $\hat{\vec{T}}_{A}(\xi)$. If there exist constants $C>0$ and $C_{0}$ such that

$$
\operatorname{Im} \chi_{j}(\xi) \leqq-C|\xi|^{r}+C_{0}
$$

then the Cauchy problem for the operator $L=D_{t}+\vec{A}$ is well posed in the $L^{2}$ norm. In fact, we have for any $T>0$

$$
\begin{aligned}
\left|e^{-i \hat{T}_{A}(\xi) t}\right| & \leqq\left(1+2 t\left|\hat{\vec{T}}_{A}(\xi)\right|+\cdots+(2 t)^{N-1}\left|\hat{\vec{T}}_{A}(\xi)\right|^{N-1}\right) e^{t \max _{j} \operatorname{Im} x_{j}(\xi)} \\
& \leqq C_{1}\left(1+t|\xi|^{r}+\cdots+\left(t|\xi|^{r}\right)^{N-1}\right) e^{-C t|\xi|^{r}} \\
& \leqq C_{2}, \quad 0 \leqq t \leqq T .
\end{aligned}
$$

For example, the Cauchy problem for the operator $D_{t}-i \lambda^{r}\left(D_{x}\right), \lambda(\xi)=$ $\left(1+|\xi|^{2}\right)^{1 / 2}$ is well posed in the $L^{2}$ norm.

Let us consider a pseudo-differential operator with the form:

$$
P(D)=D_{t}^{m}+\sum_{j=1}^{m} A_{j} D_{t}^{m-j}
$$

where $A_{j}$ are convolution operators such that $A_{j} \in \mathrm{OP}_{r_{j}}$. For any given $\vec{\alpha}=\left(\alpha_{0}, \ldots, \alpha_{m-1}\right), \alpha_{j} \in\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ and $f \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, where $f$ is assumed to have the $\mathscr{D}_{L^{2}}^{\prime 2}$-canonical extension $f_{\sim} \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, the problem to find a solution $u \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ of the Cauchy problem

$$
\left\{\begin{array}{l}
P(D) u=f \quad \text { in } R_{n+1}^{+},  \tag{16}\\
\mathscr{D}_{L^{2}-\lim _{t \downarrow 0}^{\prime}}\left(u, D_{t} u, \cdots, D_{t}^{m-1} u\right)=\vec{\alpha}
\end{array}\right.
$$

is reduced to the problem to find $w \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ such that

$$
P w=f_{\sim}+\sum_{k=0}^{m-1} D_{t}^{k} \delta \otimes r_{k}
$$

where $\gamma_{k}=-i\left(\alpha_{m-k-1}+\sum_{\nu=1}^{m-k-1} A_{m-\nu-k} \alpha_{\nu-1}\right)([9, \mathrm{p} .82])$ and $u=\left(w \mid R_{n+1}^{+}\right)_{\sim}$. We shall use the notation $\Gamma(\vec{\alpha})=\left(\gamma_{0}, \cdots, \gamma_{m-1}\right)$.

On the other hand, by the Calderón transformation

$$
v_{j}=S^{m-j} D_{t}^{j-1} u, j=1,2, \cdots, m
$$

the Cauchy problem (16) can be written in the form

$$
\left\{\begin{array}{l}
L \vec{v} \equiv D_{t} \vec{v}+\vec{A} \vec{v}=\vec{f} \quad \text { in } R_{n+1}^{+}  \tag{17}\\
\mathscr{D}_{L^{2}}^{\prime-} \lim _{t \downarrow 0} \vec{v}=\vec{\beta}
\end{array}\right.
$$

where $\vec{f}=(0, \cdots, 0, f), \vec{\beta}=\left(S^{m-1} \alpha_{0}, \cdots, \alpha_{m-1}\right)$,
and $\vec{A} \in \mathrm{OP}_{r}, r=\max \left(1, r_{j}+(1-j)\right)$.
Let us denote by [ $\left.E_{(0)}^{2} \uparrow\right]$ the following energy inequality :

$$
\begin{aligned}
& {\left[E_{(0)}^{2} \uparrow\right]: \sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi(t, \cdot)\right\|_{(m-1-j)}^{2} \leqq C_{T}\left(\sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi(0, \cdot)\right\|_{(m-1-j)}^{2}+\right.} \\
& \left.\quad+\int_{0}^{t}\left\|P \phi\left(t^{\prime}, \cdot\right)\right\|_{(0)}^{2} d t^{\prime}\right), 0 \leqq t \leqq T, \phi \in C_{0}^{\infty}\left(R_{n+1}\right)
\end{aligned}
$$

with a constant $C_{T}$. We shall use the notations $\left[E_{(0)}^{2} \downarrow\right],\left[E_{(0)}^{1} \uparrow\right],\left[E_{(0)}^{1} \uparrow\right]$ and the like with obvious meanings. If $\left[E_{(0)}^{2} \uparrow\right]$ holds for $P$, then $\left[E_{(0)}^{2} \downarrow\right]$ holds for $P^{*}=D_{t}^{m}+\sum_{j=0}^{m-1} \bar{A}_{j} D_{t}^{m-j}$. In fact, if we put $\psi(t)=\bar{\phi}(-t)$ for any $\phi \in C_{0}^{\infty}\left(R_{n+1}\right)$, then $\overline{P^{*}(D)} \phi=P(D) \psi$ and

$$
\begin{aligned}
\sum_{j=0}^{m-1}\left\|D_{t}^{j} \psi(t, \cdot)\right\|_{(m-1-j)}^{2} & \leqq C_{T}\left(\sum_{j=0}^{m-1}\left\|D_{t}^{j} \psi(0, \cdot)\right\|_{(m-1-j)}^{2}+\right. \\
& \left.+\int_{0}^{t}\left\|P(D) \psi\left(t^{\prime}, \cdot\right)\right\|_{(0)}^{2} d t^{\prime}\right), \quad 0 \leqq t \leqq T
\end{aligned}
$$

which implies

$$
\begin{aligned}
\sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi(-t, \cdot)\right\|_{(m-1-j)}^{2} \leqq C_{T}( & \sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi(0, \cdot)\right\|_{(m-1-j)}^{2}+ \\
& \left.+\int_{-t}^{0}\left\|P^{*}(D) \phi\left(t^{\prime}, \cdot\right)\right\|_{(0)}^{2} d t^{\prime}\right)
\end{aligned}
$$

Similarly if $\left[E_{(0)}^{1} \uparrow\right]$ holds for $P$, then $\left[E_{(0)}^{1} \downarrow\right]$ holds for $P^{*}$.
Proposition 19. Suppose $\left[E_{(0)}^{2} \uparrow\right]$ holds true for $P$. For any $f \epsilon$ $\widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$and $\vec{\alpha} \in \mathscr{H}_{(m-1)}\left(R_{n}\right) \times \cdots \times \mathscr{H}_{(0)}\left(R_{n}\right)$ the Cauchy problem (16) has a unique solution $u \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $u$ has the properties

$$
\begin{equation*}
D_{t}^{j} u \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(s+m-1-j)}\right), j=0,1, \ldots, m-1 \tag{i}
\end{equation*}
$$

(ii)

$$
\begin{aligned}
\sum_{j=0}^{m-1}\left\|D_{t}^{j} u(t, \cdot)\right\|_{(m+s-1-j)}^{2} & \leqq C_{T}^{(s)}\left(\sum_{j=0}^{m-1}\left\|\alpha_{j}\right\|_{(m+s-1-j)}^{2}+\right. \\
& \left.+\int_{0}^{t}\left\|f\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime}\right)
\end{aligned}
$$

with a constant $C_{T}^{(s)}$.
Proof. Uniqueness of a solution is trivial by Proposition 15. It is sufficient to show that the set $A=\left\{\left(\Gamma\left(\vec{\phi}_{0}\right), P \vec{\phi}\right): \phi \in C_{0}^{\infty}\left(R_{n+1}\right)\right\}, \vec{\phi}_{0}=(\phi(0, \cdot), \cdots$, $\left.D_{t}^{m-1} \phi(0, \cdot)\right)$, is dense in $\left(\mathscr{H}_{(s+m-1)}\left(R_{n}\right) \times \cdots \times \mathscr{H}_{(s)}\left(R_{n}\right)\right) \times \widetilde{\mathscr{H}}_{(0, s)}\left(\bar{R}_{n+1}^{+}\right)$. Let $\vec{\beta} \in \mathscr{H}_{(0)}\left(R_{n}\right) \times \cdots \times \mathscr{H}_{(-m+1)}\left(R_{n}\right)$ and $w \in \widetilde{\mathscr{H}}_{(0,-s)}^{*}\left(\bar{R}_{n+1}^{+}\right)$such that

$$
\int(P \phi(t, \cdot), w(t, \cdot)) d t+\left(\Gamma\left(\vec{\phi}_{0}\right), \vec{\beta}\right)=0, \quad \phi \in A
$$

Then $P^{*} w=0$ in $R_{n+1}^{+}$, and therefore $w=0$ and $\beta=0$.
If for any $\vec{\alpha} \in C_{0}^{\infty}\left(R_{n+1}\right)$ the Cauchy problem:

$$
\left\{\begin{array}{l}
P(D) u=0 \quad \text { in }(0, T) \times R_{n} \\
\lim _{t \downarrow 0}\left(u, D_{t} u, \cdots, D_{t}^{m-1} u\right)=\alpha,
\end{array}\right.
$$

where $T>0$ is arbitrary, has a unique solution $u \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(m-1)}\right)$ such that $D_{t}^{j} u \in \mathscr{E}_{t}^{0}\left(\mathscr{H}_{(m-1-j)}\right), j=0,1, \ldots, m-1$, and

$$
\sum_{j=0}^{m-1}\left\|D_{t}^{j} u(t, \cdot)\right\|_{(m-1-j)}^{2} \leqq C_{T}\left(\sum_{j=0}^{m-1}\left\|D_{t}^{j} u(0, \cdot)\right\|_{(m-1-j)}^{2}\right), \quad 0 \leqq t \leqq T
$$

with a constant $C_{T}$, then we shall say that $P$ satisfies the property $(W)$.
Let $L$ be the operator associated with $P$ by the Calderón transformation. Then we have the following

Theorem 6. The following conditions are equivalent:
(1) $P$ satisfies the property $(W)$.
(2) $\left[E_{(0)}^{1} \uparrow\right]$ holds for $P$ and $\left[E_{(0) \downarrow}^{1} \downarrow\right]$ holds for $P^{*}$.
(3) $\left[E_{(0)}^{2} \uparrow\right]$ holds for $P$.
(4) The Cauchy problem for $L$ is well posed in the $L^{2}$ norm.
(5) $\quad\left(E_{(0)}^{1} \uparrow\right)$ holds for $L$ and $\left(E_{(0)}^{1} \downarrow\right)$ holds for $L^{*}$.
(6) $\left(E_{(0)}^{2} \uparrow\right)$ holds for $L$.

Proof. The conditions (4), (5) and (6) are equivalent by Proposition 16 and the equivalences of (2) and (5), (3) and (6) are trivial by the definition. The implication $(3) \Rightarrow(1)$ is an immediate consequence of the preceding proposition. We have only to show the implication (1) $\Rightarrow$ (4). Let $\vec{\alpha}=\left(\alpha_{0}, \cdots\right.$, $\left.\alpha_{m-1}\right) \in C_{0}^{\infty}\left(R_{n}\right)$. Then $\left(S^{-m+1} \alpha_{0}, S^{-m+2} \alpha_{1}, \cdots, \alpha_{m-1}\right) \epsilon\left(\mathscr{D}_{L^{2}}\right)_{x}$, where $C_{0}^{\infty}\left(R_{n}\right)$ is dense in $\left(\mathscr{D}_{L^{2}}\right)_{x}$. Since the property $(W)$ holds also true of the initial data
$\left(S^{-m+1} \alpha_{0}, \cdots, \alpha_{m-1}\right) \epsilon\left(\mathscr{D}_{L^{2}}\right) x$, the Cauchy problem for $L$ is well posed in the $L^{2}$ norm.

Now let us consider the case where $A_{j}$ can be written in the form

$$
A_{j}=A_{j}^{0} \Lambda^{j}+B_{j}, \quad j=1,2, \ldots, m
$$

where $\hat{T}_{A_{j}^{0}}(\xi)$ are positive homogeneous of degree $0, \hat{T}_{A_{j}^{0}}(\xi)$ continuous on $|\xi|=1$ and $B_{j}$ of order $\leqq j-1$. We put

$$
P_{0}(D)=D_{t}^{m}+\sum_{j=1}^{m} A_{j}^{0} \Lambda^{j} D_{t}^{m-j}
$$

Then we have the following
Proposition 20. [ $\left.E_{(0)}^{2} \uparrow \downarrow\right]$ holds for $P(D)$ if and only if the roots of the polynomial $P_{0}(\tau, \xi)$ of $\tau$ are real and distinct.

Proof. Suppose [ $\left.E_{(0)}^{2} \uparrow \downarrow\right]$ holds for $P(D)$. Then $\left(E_{(0)}^{2} \downarrow \uparrow\right)$ holds for $L$. $L$ can be written in the form $L=\vec{A}^{0} \Lambda+\vec{B}$, where $\hat{\vec{T}}_{A^{0}}(\xi)$ is positive homogeneous of degree $0, \hat{T}_{A^{0}}(\xi)$ continuous on $|\xi|=1$ and $\vec{B}$ of order $\leqq 0$. Thus we see by Lemma 3 that ( $\left.E_{(0) \uparrow \downarrow}^{2} \uparrow\right)$ holds also for $L_{0}=\vec{A}^{0} \Lambda$. Observe that $P_{0}(\tau, \xi)$ is the minimal polynomial of the matrix $\hat{\vec{T}}_{A^{0}}(\xi)$. In virtue of Proposition 18 we see that the roots are real and distinct.

Conversely, suppose the roots of $P_{0}(\tau, \xi)=0$ are real and distinct. Then by necessary modifications of the proofs of Theorems 24 and 25 in A.P. Calderón [3, p. 109, p. 110] there exists a positive definite Hermitian matrix $\vec{H}(\xi)$ such that $\vec{H}(\xi) \hat{\vec{T}}_{A^{0}}(\xi)=\hat{\vec{T}}_{A^{0}}(\xi) \vec{H}(\xi)$. Applying Corollary 3 and Lemma 3 we see that $\left[E_{(0) \downarrow \uparrow]}^{2}\right.$ holds for $P$.

Corollary 4. In the case where the coefficients of the operators $A_{j}^{0}, j=$ $1,2, \ldots, m$, are real, $\left[E_{(0)}^{2} \uparrow\right]$ holds for $P$ if and only if the roots of $P_{0}(\tau, \xi)=0$ are real and distinct.

## 5. A characterization of regular hyperbolicity

In our previous paper [9, p. 101] it is shown that a differential operator $P(D)=D_{t}^{m}+\sum_{j=0}^{m-1} \sum_{j+|p| \leqslant m} a_{j, p}(t, x) D_{t}^{j} D_{x}^{p}, a_{j, p} \in \mathscr{B}$, is regularly hyperbolic if and only if, for any fixed $T>0, P(D)$ satisfies the energy inequality:

$$
\begin{aligned}
{\left[\tilde{E}_{(0)}^{1} \uparrow\right]: } & \sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi\left(t_{1}, \cdot\right)\right\|_{(m-1-j)} \leqq C_{T}\left(\sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi\left(t_{0}, \cdot\right)\right\|_{(m-1-j)}+\right. \\
& +\int_{t_{0}}^{t_{1}}\|P(D) \phi(t, \cdot)\|_{(0)} d t, \quad 0 \leqq t_{0} \leqq t_{1} \leqq T, \quad \phi \in C_{0}^{\infty}\left(R_{n+1}\right)
\end{aligned}
$$

where $C_{T}$ is a constant.
The aim of this section is to generalize this result to a pseudo-differential operator.
T. Bałabon [1] has investigated the Cauchy problem for a pseudo-differential operators with the form:

$$
P(D)=D_{t}^{m}+\sum_{j=1}^{m} A_{j}(t) D_{t}^{m-j}
$$

where $A_{j}(t)=A_{j}\left(t, x, D_{x}\right)$ is a pseudo-diffenertial operator of order $j$ in the sense of J.J. Kohn and L. Nirenberg, which depends smoothly on $t$ and its asymptotic expansion has only operators of integral order.

Let $\mathfrak{B}$ be the space of all $B_{\infty}$ singular integral operators in the sense of A.P. Calderón $[3,14]$ with semi-norms $\left\{p_{m}\right\}_{m}=0,1, \ldots$ :

$$
p_{m}: \quad K \rightarrow\|K\|_{m}=\max _{0 \leqq|\alpha| \leqq 2 n}\left\{\sup _{|\varsigma|=1}\left\|\left(\frac{\partial}{\partial \varsigma}\right)^{\alpha} \sigma(K)(x, \varsigma)\right\|_{m}\right\},
$$

where $\|K\|_{m}$ is the norm of $B_{m}$ singular integral operator $K$.
Consider a pseudo-differential operator with the form

$$
P(D)=D_{t}^{m}+\sum_{j=1}^{m} A_{j}(t) D_{t}^{m-j}, A_{j}(t)=A_{j}^{0}(t) \Lambda^{j}+B_{j}(t)
$$

where $A_{j}^{0}(t)=A_{j}^{0}\left(t, x, D_{x}\right)$ are $\mathfrak{B}$-valued continuous functions of $t \in R_{t}$ and $B_{j}(t) \in \mathbb{C}_{(j-1)}$. We shall give a characterization of the regular hyperbolicity of $P(D)$ by making use of the energy inequalities.

We shall denote by $P^{0}(D)$ the principal part of $P(D)$ :

$$
P^{0}(D)=D_{t}^{m}+\sum_{j=1}^{m} A_{j}^{0}(t) \Lambda^{j} D_{t}^{m-j}
$$

and we put

$$
P_{\left(t_{0}, x_{0}\right)}^{0}(D)=D_{t}^{m}+\sum_{j=1}^{m} A_{j}^{0}\left(t_{0}, x_{0}, D_{x}\right) \Lambda^{j} D_{t}^{m-j}
$$

where the point $\left(t_{0}, x_{0}\right)$ is fixed. Let $T$ be any fixed positive number.
Proposition 21. Suppose the following energy inequality $\left[\tilde{E}_{(0)}^{1} \uparrow\right]$ holds for $P(D)$ :

$$
\begin{aligned}
{\left[\tilde{E}_{(0)}^{1} \uparrow\right]: } & \sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi\left(t_{1}, \cdot\right)\right\|_{(m-1-j)} \leqq C_{T}\left(\sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi\left(t_{0}, \cdot\right)\right\|_{(m-1-j)}+\right. \\
& +\int_{t_{0}}^{t_{1}}\left\|(P \phi)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}, \quad 0 \leqq t_{0} \leqq t_{1} \leqq T, \quad \phi \in C_{0}^{\infty}\left(R_{n+1}\right)
\end{aligned}
$$

where $C_{T}$ is a constant. Then $\left[E_{(0)}^{1} \uparrow\right]$ holds for $P_{\left(t_{0}, x_{0}\right)}^{0}(D)$ with a constant independent of $\left(t_{0}, x_{0}\right) \in[0, T] \times R_{n}$.

Proof. Let $\left(t_{0}, x_{0}\right) \in[0, T) \times R_{n}$. For any fixed $\tilde{t} \in(0, T]$ we take $\lambda$ so large that $t_{0}<t_{1}=t_{0}+\frac{\tilde{t}}{\lambda} \leqq T$. Let $\phi_{\lambda}(t, x)=u\left(\lambda\left(t-t_{0}\right), \lambda\left(x-x_{0}\right)\right)$ for any $u \in C_{0}^{\infty}\left(R_{n+1}\right)$. Then we have

$$
\begin{align*}
\sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi_{\lambda}\left(t_{1}, \cdot\right)\right\|_{(m-1-j)} \leqq C_{T}( & \sum_{j=0}^{m-1}\left\|D_{t}^{j} \phi_{\lambda}\left(t_{0}, \cdot\right)\right\|_{(m-1-j)}+  \tag{18}\\
& \left.+\int_{t_{0}}^{t_{1}}\left\|\left(P(D) \phi_{\lambda}\right)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}\right)
\end{align*}
$$

where

$$
\begin{aligned}
& \left\|D_{t}^{j} \phi_{\lambda}\left(t_{1}, \cdot\right)\right\|_{(m-1-j)}^{2}=\sum_{|p| \leqq m-1-j} \lambda^{2(j+|p|-n \mid 2)}\binom{m-1-j}{p}\left\|D_{t}^{j} D_{p}^{x} u(\tilde{t}, \cdot)\right\|_{(0)}^{2} \\
& \left\|D_{j}^{t} \phi_{\lambda}\left(t_{0}, \cdot\right)\right\|_{(m-1-j)}^{2}=\sum_{|p| \leqq m-1-j} \lambda^{2(j+|p|-n \mid 2)}\binom{m-1-j}{p}\left\|D_{t}^{j} D_{x}^{p} u(0, \cdot)\right\|_{(0) \cdot}^{2} .
\end{aligned}
$$

Moreover, we can write

$$
P(D) \phi_{\lambda}=D_{t}^{m} \phi_{\lambda}+\sum_{j=1}^{m} A_{j}^{0}(t) \Lambda^{j} D_{t}^{m-j} \phi_{\lambda}+\sum_{j=1}^{m} B_{j}(t) D_{t}^{m-j} \phi_{\lambda}
$$

where

$$
\begin{aligned}
A_{j}^{0}(t) \Lambda^{j} D_{t}^{m-j} \phi_{\lambda} & =\frac{1}{(2 \pi)^{2}} \lambda^{m-n} \int \sigma\left(A_{j}^{0}\right)(t, x, \xi)\left|\frac{\xi}{\lambda}\right|^{j} D_{t}^{m-j} \hat{u}\left(\lambda\left(t-t_{0}\right), \frac{\xi}{\lambda}\right) e^{i<x-x_{0}, \xi>} d \xi \\
& =\frac{\lambda^{m}}{(2 \pi)^{n}} \int \sigma\left(A_{j}^{0}\right)(t, x, \xi)|\xi|^{j} D_{t}^{m-j} \hat{u}\left(\lambda\left(t-t_{0}\right), \xi\right) e^{i<\lambda\left(x-x_{0}\right), \xi>} d \xi \\
& =\lambda^{m}\left(A_{j}^{0}\left(\frac{\cdot}{\lambda}+t_{0}, \frac{\cdot}{\lambda}+x_{0}, D_{x}\right) \Lambda^{j} D_{t}^{m-j} u\right)\left(\lambda\left(t-t_{0}\right), \lambda\left(x-x_{0}\right)\right),
\end{aligned}
$$

and therefore

$$
\begin{aligned}
&\left\|\left(P(D) \phi_{\lambda}\right)(t, \cdot)\right\|_{(0)} \leqq \lambda^{m-(n / 2)} \|\left(P_{0}\left(\frac{t}{\lambda}+t, \frac{x}{\lambda}+x_{0}\right)\right. \\
&(D) u)\left(\lambda\left(t-t_{0}\right), \cdot\right) \|_{(0)}+ \\
&+C_{1} \lambda^{m-1-\frac{n}{2}} \sum_{j=1}^{m}\left\|\left(\lambda^{-2}+|\xi|^{2}\right)^{\frac{j-1}{2}} D_{t}^{m-j} \hat{u}\left(\lambda\left(t-t_{0}\right), \cdot\right)\right\|_{(0)}
\end{aligned}
$$

where $C_{1}$ is a constant independent of $u$ but depends on $B_{j}$. Thus we have

$$
\begin{gathered}
\int_{t_{0}}^{t_{1}}\left\|\left(P(D) \phi_{\lambda}\right)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t \leqq \lambda^{m-1-n / 2} \int_{0}^{t}\left\|\left(P_{\left(\frac{t}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}\right)}(D) u\right)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}+ \\
+C_{1} \lambda^{m-2-n / 2} \sum_{j=1}^{m} \int_{0}^{t}\left\|\left(\lambda^{-2}+|\xi|^{2}\right)^{\frac{j-1}{2}} D_{t}^{m-j} \hat{u}\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}
\end{gathered}
$$

In the case where $n \geqq 2$ we can expand the operator $A_{j}^{0}\left(\frac{t^{\prime}}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}\right.$, $\left.D_{x}\right) f$ in the form

$$
\begin{aligned}
A_{0}^{j}\left(\frac{t^{\prime}}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}, D_{x}\right) f & =a_{0}^{j}\left(\frac{t^{\prime}}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}\right) f \\
+ & \sum_{m=1}^{\infty} \sum_{l=1}^{d(m)} a_{l m}^{j}\left(\frac{t^{\prime}}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}\right) G_{l m} f
\end{aligned}
$$

where $\left\{G_{l m}\right\}$ be a system of Giraud operators associated with a complete orthonormal system of spherical harmonics of degree $m$ and $d(m)=g(m)-g(m-2)$, $g(m)=\binom{m+n-1}{n-1}$, and we set $g(-1)=g(-2)=0$. Since sup $\left\lvert\, a_{0}^{j}\left(\frac{t}{\lambda}+t_{0}\right.$, \right. $\left.\frac{x}{\lambda}+x_{0}\right) \left.\left|\leqq C^{\prime}, \sup \right| a_{l m}^{j}\left(\frac{t}{\lambda}+t_{0}, \frac{x}{\lambda}+x_{0}\right) \right\rvert\, \leqq C^{\prime} m^{-\frac{3}{2} n}\left\|A_{j}^{0}\right\|_{0},\left\|G_{l m} f\right\|_{(0)} \leqq C^{\prime} m^{\frac{n-2}{2}}$ $\gamma_{m}\|f\|_{(0)}$ with $\gamma_{m}=-i^{m}(2 \sqrt{\pi})^{-n} \Gamma(m)\left(\Gamma\left(\frac{m+n}{2}\right)\right)^{-1}$ and $d(m) \leqq C^{\prime} m^{n-2}$, where $C^{\prime}$ is a constant independent of $\left(t_{0}, x_{0}\right)[3,14]$, we obtain with a constant $C^{\prime \prime}$ independent of ( $t_{0}, x_{0}$ )

$$
\begin{align*}
\| A_{j}^{o}\left(\frac{t}{\lambda}+t_{0},\right. & \left.\frac{x}{\lambda}+x_{0}, D_{x}\right) \Lambda_{j} D_{t}^{m-j} u\left(t^{\prime}, \cdot\right) \|_{(0)}  \tag{19}\\
& \leqq C^{\prime \prime}\left(1+\sum_{m=1}^{\infty} m^{-3}\right)\left\|A_{j}^{0}\right\|_{0}\left\|D_{t}^{m-j} u\left(t^{\prime}, \cdot\right)\right\|_{(j)}
\end{align*}
$$

In the case where $n=1$ we can write

$$
\begin{aligned}
A_{j}^{0}\left(\frac{t^{\prime}}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}, D_{x}\right) f & =a_{0}^{j}\left(\frac{t^{\prime}}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}\right) f+ \\
& +a_{1}^{j}\left(\frac{t^{\prime}}{\lambda}+t_{0}, \frac{x^{\prime}}{\lambda}+x_{0}\right) \lim _{\varepsilon \downarrow 0} \int_{|x-y|>\varepsilon} \frac{f(y)}{x-y} d y
\end{aligned}
$$

where $a_{0}^{j}(t, \cdot)$ and $a_{1}^{j}(t, \cdot)$ are $B_{\infty}$-valued continuous function of $t$. Thus the estimate (19) remains valid.

Dividing both sides of (18) by $\lambda^{m-1-(n / 2)}$, letting $\lambda \rightarrow \infty$ and applying Lebesgue's convergence theorem we obtain the estimate

$$
\begin{gather*}
\sum_{j=0}^{m-1}\left\|\left(\Lambda^{m-1-j} D_{t}^{j} u\right)(\tilde{t}, \cdot)\right\|_{(0)} \leqq C_{T}\left(\sum_{j=0}^{m-1}\left(\Lambda^{m-1-j} D_{t}^{j} u\right)(0, \cdot) \|_{(0)}+\right.  \tag{20}\\
\left.+\int_{0}^{i}\left\|P_{\left(t_{0}, x_{0}\right)}^{0}(D) u\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}\right)
\end{gather*}
$$

where $C_{T}$ is a constant independent of ( $t_{0}, x_{0}$ ) and $u$.
If we take $u(t, x) e^{i\left\langle x, \xi_{0}\right\rangle}, \xi_{0}=(1,0, \ldots, 0)$, instead of $u(t, x)$, then we get
$\hat{u}\left(t, \xi-\xi_{0}\right)$ as the partial Fourier transform and we have

$$
\begin{gather*}
\sum_{j=0}^{m-1}\left\|\left(\Lambda\left(D_{x}+\xi_{0}\right)\right)^{m-1-j} D_{t}^{j} u(\tilde{t}, \cdot)\right\|_{(0)} \leqq C_{T}\left(\sum_{j=0}^{m-1}\left(\Lambda\left(D_{x}+\xi_{0}\right)\right)^{m-1-j} D_{t}^{j} u(\tilde{t}, \cdot) \|_{(0)}+\right.  \tag{21}\\
\left.+\int_{0}^{\tilde{t}}\left\|\left(P_{\left(t_{0}, x_{0}\right)}^{0}(D) u e^{i<x, \xi_{0}>}\right)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}\right)
\end{gather*}
$$

where $\Lambda\left(D_{x}+\xi_{0}\right)$ is defined by $\left(\Lambda\left(D_{x}+\xi_{0}\right) u\right)^{\wedge}=\left|\xi+\xi_{0}\right| \hat{u}$.
It is evident that

$$
\begin{aligned}
& \left(P_{\left(t_{0}, x_{0}\right)}^{0}(D) u e^{\left.i<x, \xi_{0}\right\rangle}\right)^{\wedge} \\
= & D_{t}^{m} \hat{u}\left(t, \xi-\xi_{0}\right)+\sum_{j=1}^{m} \sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi\right)|\xi|^{j} D_{t}^{m-j} \hat{u}\left(t, \xi-\xi_{0}\right) \\
= & D_{t}^{m} \hat{u}\left(t, \xi-\xi_{0}\right)+\sum_{j=1}^{m} \sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi-\xi_{0}\right)\left|\xi-\xi_{0}\right|^{j} D_{t}^{m-j} \hat{u}\left(t, \xi-\xi_{0}\right)+ \\
& +\sum_{j=1}^{m} \sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi\right)\left(|\xi|^{j}-\left|\xi-\xi_{0}\right|^{j}\right) D_{t}^{m-j} \hat{u}\left(t, \xi-\xi_{0}\right)+ \\
& +\sum_{j=1}^{m}\left(\sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi\right)-\sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi-\xi_{0}\right)\right)\left|\xi-\xi_{0}\right|^{j} D_{t}^{m-j} \hat{u}\left(t, \xi-\xi_{0}\right) .
\end{aligned}
$$

From the following estimates:

$$
\left|\sigma\left(A_{j}^{o}\right)\left(t_{0}, x_{0}, \xi\right)\left(|\xi|^{j}-\left|\xi-\xi_{0}\right|^{j}\right)\right| \leqq C_{2}\left(1+\left|\xi-\xi_{0}\right|^{2}\right)^{(j-1) / 2}
$$

and

$$
\begin{aligned}
& \left|\sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi\right)-\sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi-\xi_{0}\right)\right|\left|\xi-\xi_{0}\right|^{j} \\
= & \left|\sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \frac{\xi}{|\xi|}\right)-\sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \frac{\xi-\xi_{0}}{\left|\xi-\xi_{0}\right|}\right)\right|\left|\xi-\xi_{0}\right|^{j} \\
\leqq & C_{3}\left|\frac{\xi}{|\xi|}-\frac{\xi-\xi_{0}}{\left|\xi-\xi_{0}\right|}\right|\left|\xi-\xi_{0}\right|^{j} \\
\leqq & 2 C_{3} \frac{\left|\xi-\xi_{0}\right|^{j}}{|\xi|+\left|\xi-\xi_{0}\right|} \leqq C_{4}\left(1+\left|\xi-\xi_{0}\right|^{2}\right)^{(j-1) / 2},
\end{aligned}
$$

we obtain

$$
\begin{aligned}
& \left.\mid P_{\left(t_{0}, x_{0}\right)}^{0}(D) u e^{i<x, \xi_{0}>}\right)^{\wedge} \mid \\
\leqq & \left.\left|D_{t}^{m} u\left(t, \xi-\xi_{0}\right)+\sum_{j=1}^{m} \sigma\left(A_{j}^{0}\right)\left(t_{0}, x_{0}, \xi\right)\right| \xi\right|^{j} D_{t}^{m-j} \hat{u}\left(t, \xi-\xi_{0}\right) \mid \\
& +\left(C_{2}+C_{4}\right) \sum_{j=1}^{m}\left(1+\left|\xi-\xi_{0}\right|^{2}\right)^{(j-1) / 2}\left|D_{t}^{m-j} \hat{u}\left(t, \xi-\xi_{0}\right)\right|,
\end{aligned}
$$

and therefore

$$
\begin{align*}
& \int_{0}^{\tau}\left\|\left(P_{\left(t t_{0}, x_{0}\right)}^{0}(D) u e^{i<x, \xi_{0}>}\right)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}  \tag{22}\\
\leqq & \int_{0}^{\tau}\left\|\left(P_{\left(t_{0}, x_{0}\right)}^{0}(D) u\right)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}+C_{T}^{0} \sum_{j=1}^{m-1} \int_{0}^{\tau}\left\|D_{t}^{j} u\left(t^{\prime}, \cdot\right)\right\|_{(m-1-j)} d t^{\prime},
\end{align*}
$$

where $C_{2}, C_{3}, C_{4}$ and $C_{T}^{0}$ are constants independent of ( $t_{0}, x_{0}$ ).
There exists a constant $C_{5}$ such that

$$
\begin{aligned}
\frac{1}{C_{5}^{2}}\left(1+|\xi|^{2}\right)^{m-1-j} & \leqq|\xi|^{2(m-1-j)}+\left|\xi+\xi_{0}\right|^{2(m-1-j)} \\
& \leqq C_{5}^{2}\left(1+|\xi|^{2}\right)^{m-1-j}
\end{aligned}
$$

Thus we obtain the following estimate from (20), (21) and (22)

$$
\begin{aligned}
& \frac{1}{C_{5}} \sum_{j=0}^{m-1}\left\|S^{m-1-j} D_{t}^{j} u(\tilde{t}, \cdot)\right\|_{(0)} \leqq C_{T}\left\{C_{2} \sum_{j=0}^{m-1}\left\|S^{m-1-j} D_{t}^{j} u(0, \cdot)\right\|_{(0)}\right. \\
& \quad+2 \int_{0}^{\tau}\left\|\left(P_{\left(t_{0}, x_{0}\right)}^{0}(D) u\right)\left(t^{\prime}, \cdot\right)\right\|_{(0)} d t^{\prime}+C_{T}^{0} \sum_{j=0}^{m-1} \int_{0}^{\tilde{t}}\left\|D_{t}^{j} u\left(t^{\prime}, \cdot\right)\right\|_{(m-1-j)} d t^{\prime}
\end{aligned}
$$

By Lemma 3 we see that $\left[\tilde{E}_{(0)}^{1} \uparrow\right]$ holds for $P_{\left(t_{0} x_{0}\right)}^{0}(D)$ with a constant independent of $\left(t_{0}, x_{0}\right) \in[0, T) \times R_{n}$ and $u$. By letting $t_{0} \uparrow T$, we see that $\left[E_{(0)}^{1} \uparrow\right]$ holds for $P_{\left(T, x_{0}\right)}^{0}(D)$ with the same constant. Thus the proof is complete.

Let $\lambda_{j}(t, x, \xi), j=1,2, \cdots, m$, be the roots of the algebraic equation $P^{0}(t, x, \tau, \xi)=0$ with respect to $\tau$. If (i) $\lambda_{j}(t, x, \xi)$ are real for $j=1,2, \ldots, m$ and (ii) there exists a positive constant $d_{T}$ depending on $T$ such that $\left|\lambda_{j}(t, x, \xi)-\lambda_{k}(t, x, \xi)\right| \geqq d_{T}, j \neq k$, hold for $t \epsilon[0, T], x \in R_{n}$ and $\xi \in \Xi_{n}$ with $|\xi|=1$, then $P$ is said to be regularly hyperbolic.

Theorem 7. $P$ is regularly hyperbolic if $\left[\tilde{E}_{(0)}^{1} \uparrow \downarrow\right]$ holds for $P(D)$. The converse holds true when there exists a constant $C_{T}$ such that

$$
\left\|A_{j}^{0}(t)-A_{j}^{0}\left(t^{\prime}\right)\right\|_{0} \leqq C_{T}\left|t-t^{\prime}\right|, \quad 0 \leqq t, t^{\prime} \leqq T
$$

Proof. Suppose [ $\left.\tilde{E}_{(0)}^{1} \uparrow \downarrow\right]$ hold for $P(D)$. Then, it follows from the preceding proposition that $\left[E_{(0)}^{1} \uparrow \downarrow\right]$ holds for $P_{\left(t_{0}, x_{0}\right)}^{0}(D),\left(t_{0}, x_{0}\right) \in[0, T] \times R_{n}$, with a constant independent of $\left(t_{0}, x_{0}\right)$. Owing to Theorem $6,\left(E_{(0)}^{1} \uparrow \downarrow\right)$ holds for $L_{\left(t_{0}, x_{0}\right)}^{0}(D)$, the system of linear operators corresponding to $P_{\left(t_{0}, x_{0}\right)}^{0}(D)$ under the Calderon transformation, and therefore from Proposition 18 we see that for any fixed ( $t_{0}, x_{0}$ ) the roots $\lambda_{j}\left(t_{0}, x_{0}, \xi\right), j=1,2, \cdots, m$, are real and distinct.

For any $\xi^{\prime}, \xi^{\prime \prime} \in \Xi_{n}$ on $|\xi|=1$ we denote by $l$ the spherical distance between $\xi^{\prime}, \xi^{\prime \prime}$ and $\xi(s), 0 \leqq s \leqq l \leqq \pi$, a point on an arc of a great circle with end points $\xi^{\prime}, \xi^{\prime \prime}$. Writing $\sigma\left(A_{j}\right)=\hat{A}_{j}(t, x, \xi)$, we have

$$
\begin{aligned}
\left|\hat{A}_{j}\left(t, x, \xi^{\prime \prime}\right)-\hat{A}_{j}\left(t, x, \xi^{\prime}\right)\right|= & \left|\int_{0}^{l} \sum_{k=1}^{n} \frac{\partial}{\partial \xi_{k}} \hat{A}_{j}(t, x, \xi(s)) \frac{\partial \xi_{k}}{\partial s} d s\right| \\
& \leqq \int_{0}^{l}\left(\sum_{k=1}^{n}\left\|\frac{\partial}{\partial \xi_{k}} \hat{A}_{j}(t, x, \xi(s))\right\|^{2}\right)^{1 / 2} d s \leqq M l
\end{aligned}
$$

where $M$ is a constant and $l \leqq \pi\left|\xi^{\prime}-\xi^{\prime \prime}\right|$.
Let us consider the set

$$
\mathfrak{S}=\left\{\left(\hat{A}_{1}^{0}(t, x, \cdot), \cdots, \hat{A}_{m}^{0}(t, x, \cdot)\right): t \in[0, T], x \in R_{n}\right\},
$$

where $\hat{A}_{j}^{0}(t, x, \cdot)$ are continuous functions of $\xi \in \Xi_{n}$ on $|\xi|=1$ with parameter $(t, x)$, and equip $\mathfrak{S}$ with the uniform convergence topology. Since the set $\mathfrak{S}$ is equicontinuous and uniformly bounded, its closure $\overline{\mathfrak{S}}$ is compact. For any $\left(\hat{B}_{1}, \ldots, \hat{B}_{m}\right) \in \overline{\mathbb{S}}$ the polynomial $Q(\tau, \xi)=\tau^{m}+\sum_{j=1}^{m} \hat{B}_{j}(\xi) \tau^{m-j}$ in $\tau$ have simple zeros only. Let $\Delta_{Q}$ be its discriminant. Since it is a continuous function of $\left(\hat{B}_{1}, \cdots, \hat{B}_{m}\right) \in \overline{\mathcal{S}}$ and $\xi \in \Xi_{n}$ with $|\xi|=1$, it follows that $\Delta_{Q}(\xi) \geqq d_{T}>0$ for a constant $d_{T}$ depending on $T$.

Conversely, suppose $P$ is regularly hyperbolic. By means of the Calderón transformation $v_{j}=S^{m-j} D_{t}^{j-1} u, j=1,2, \cdots, m$, we are reduced to consider the system of linear operators

$$
L \vec{v} \equiv D_{t} \vec{v}+\vec{A}^{0}(t) \Lambda \vec{v}+\vec{B}(t) \vec{v}, \quad \vec{v}=\left(v_{1}, \cdots, v_{m}\right)
$$

where the eigenvalues of the matrix $\hat{\vec{A}}^{0}(t, x, \xi)$ are $\lambda_{j}(t, x, \xi), j=1,2, \cdots, m$. Owing to Theorem 25 in [3, p. 110], we see that there exists an $N \times N$ matrix $\vec{N}(t)$ whose elements are continuous linear operators of the space $\mathscr{H}_{(0)}\left(R_{n}\right)$ into itself for every $t$ and which satisfies the following properties:
(i) $\vec{N}(t)$ is a positive definite Hermitian matrix and $t \rightarrow \vec{N}(t)$ is continuous.
(ii) $\left\|\left(\vec{N}(t) \vec{A}^{0}(t) S-S \vec{A}^{0 *}(t) \vec{N}(t)\right) \vec{x}\right\|_{(0)} \leqq M\|\vec{\chi}\|_{(0)}, 0 \leqq t \leqq T, \vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right)$ with a constant $M$.

By Proposition 22 below (which will be proved in the next section) we see that ( $E_{(0)}^{1} \uparrow \downarrow$ ) holds for $L$ and therefore $\left[E_{(0)}^{1} \uparrow \downarrow\right]$ holds for $P(D)$. Thus the proof is complete.

Corollary 5. Assume that $\hat{A}_{j}^{0}(t, x, \xi), j=1,2, \cdots, m$, are real. If $\left[\tilde{E}_{(0)}^{1} \uparrow\right]$ holds for $P(D)$, then $P$ is regularly hyperbolic.

If $A_{j}^{0}(t)$ is $\mathfrak{B}$-valued $C^{m-j}$ function of $t$ and $B_{j}(t) \epsilon \underbrace{m-j}_{(j-1)}$ for each $j$, then we can consider the formal adjoint operator $P^{*}(D)$. Suppose [ $\left.E_{(0)}^{2} \uparrow\right]$ holds for $P(D)$ and $P^{*}(D)$. Then in the same way as in the proof of Proposition 8 in $[9$, p. 100$]$ we can show that $\left[\tilde{E}_{(0)}^{1} \uparrow\right]$ holds for $P(D)$ and $\left[\tilde{E}_{(0)}^{1} \downarrow\right]$ for $P_{\left(t 0_{0}, x_{0}\right)}^{*}(D)$. Thus we have the following

Corollary 6. If $\left[E_{(0)}^{2} \uparrow\right]$ holds for $P(D)$ and $P^{*}(D)$, then $P$ is regularly hyperbolic.

## 6. A generalization of Kaplan's treatment on parabolic operators

Let $\vec{A}(t) \in \mathfrak{C}_{(r)}$. We shall first give a sufficient condition in order that ( $\tilde{E}_{(0)}^{1} \uparrow \downarrow$ ) may hold for $L=D_{t}+\vec{A}(t)$.

Proposition 22. Let $\vec{H}(t), 0 \leqq t \leqq \infty$, be an $N \times N$ positive definite matrix whose elements are continuous linear operators of the space $\mathscr{H}_{(0)}\left(R_{n}\right)$ into itself for each $t$ and suppose that for any $T>0$
(i) There exists a constant $\gamma_{T}$ such that

$$
\frac{1}{r_{T}}\|\vec{\chi}\|_{(0)}^{2} \leqq(\vec{H}(t) \vec{\chi}, \vec{\chi}) \leqq r_{T}\|\vec{\chi}\|_{(0)}^{2}, \quad 0 \leqq t \leqq T, \quad \vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right)
$$

(ii) $\vec{H}(t)$ is locally Lipsitzian:

$$
\left\|\left(\vec{H}(t)-\vec{H}\left(t^{\prime}\right)\right) \vec{\chi}\right\|_{(0)} \leqq C_{T}\|\vec{\chi}\|_{(0)}\left|t-t^{\prime}\right|, \quad 0 \leqq t, t^{\prime} \leqq T, \quad \vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right)
$$

(iii) There exists a constant $C_{T}$ such that

$$
\left\|\left(\vec{H}(t) \vec{A}(t)-\vec{A}^{*}(t) \vec{H}(t)\right) \vec{\chi}\right\|_{(0)} \leqq C_{T}\|\vec{x}\|_{(0)}, \quad 0 \leqq t \leqq T, \quad \vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right) .
$$

Then ( $\tilde{E}_{(0)}^{1} \uparrow \downarrow$ ) holds for $L$.
Proof. For any $\vec{u} \in C_{0}^{\infty}\left(R_{n+1}\right)$ we put $\vec{f}=L \vec{u}, h^{2}(t)=(\vec{H}(t) \vec{u}(t, \cdot), \vec{u}(t, \cdot))$ and consider Dini's derivates $D_{ \pm}\left(h^{2}(t)\right)$. Then we have

$$
\begin{aligned}
& D_{ \pm}\left(h^{2}(t)\right) \leqq C_{T}\|\vec{u}(t, \cdot)\|_{(0)}^{2}+\left|\left(\vec{H}(t) D_{t} \vec{u}(t, \cdot), \vec{u}(t, \cdot)\right)-\left(\vec{H}(t) \vec{u}(t, \cdot), D_{t} \vec{u}(t, \cdot)\right)\right| \\
& \leqq C_{T}\|\vec{u}(t, \cdot)\|_{(0)}^{2}+\left|\left(\left(\vec{H}(t) \vec{A}(t)-\vec{A}^{*}(t) \vec{H}(t)\right) \vec{u}(t, \cdot), \vec{u}(t, \cdot)\right)\right|+ \\
& \quad+2\|\vec{f}(t, \cdot)\|_{(0)}\|\vec{H}(t) \vec{u}(t, \cdot)\|_{(0)} \\
& \leqq\left(C_{T}+C_{T}^{\prime}\right)\|\vec{u}(t, \cdot)\|_{(0)}^{2}+2\|\vec{f}(t, \cdot)\|_{(0)}\|\vec{H}(t) \vec{u}(t, \cdot)\|_{(0)} \\
& \leqq r_{T}\left(C_{T}+C_{T}^{\prime}\right) h^{2}(t)+2\left(\gamma_{T}\right)^{1 / 2}\|\vec{f}(t, \cdot)\|_{(0)} h(t)
\end{aligned}
$$

with a constant $C_{T}^{\prime}$. Put $2 C=\gamma_{T}\left(C_{T}+C_{T}^{\prime}\right)$. From the fact that $D_{-} h^{2}=2 h D_{-} h$ for $h(t)>0$ and $D_{-} h^{2} \leqq 0$ for $h(t)=0$ we obtain

$$
D_{-}\left(e^{-C t} h\right) \leqq e^{-C t}\left(\gamma_{T}\right)^{1 / 2}\|\vec{f}(t, \cdot)\|_{(0)}
$$

and therefore

$$
\begin{aligned}
\left\|\vec{u}\left(t_{1}, \cdot\right)\right\|_{(0)} \leqq r_{T} e^{c\left(t_{1}-t_{0}\right)}\left\|\vec{u}\left(t_{0}, \cdot\right)\right\|_{(0)}+\gamma_{T} \int_{t_{0}}^{t_{1}} e^{-c\left(t-t_{1}\right)}\|\vec{f}(t, \cdot)\|_{(0)} d t & \\
& 0 \leqq t_{0} \leqq t_{1} \leqq T
\end{aligned}
$$

On the other hand, from the inequality

$$
-D_{+} h(t) \leqq C\left(h(t)+\left(\gamma_{T}\right)^{1 / 2}\|\vec{f}(t, \cdot)\|_{(0)}\right)
$$

we obtain

$$
\left\|\vec{u}\left(t_{0}, \cdot\right)\right\|_{(0)} \leqq r_{T} e^{C\left(t_{1}-t_{0}\right)}\|\vec{u}(t, \cdot)\|_{(0)}+\gamma_{T} \int_{t_{0}}^{t_{1}} e^{C\left(t-t_{0}\right)}\|\vec{f}(t, \cdot)\|_{(0)} d t,
$$

which completes the proof.
Proposition 23. If we assume in Proposition 22 that

$$
\vec{H}^{-1}(t)\left(\left(\mathscr{D}_{L^{2}}\right)\right) \subset \mathscr{H}_{(r)}\left(R_{n}\right) \quad \text { for each } t, 0 \leqq t<\infty
$$

then $\left(\tilde{E}_{(0)}^{1} \uparrow \downarrow\right)$ holds for $L^{*}$.
Proof. From the condition (i), it follows that $\vec{H}^{-1}(t)$ exists and has the property (i). For any $t, t^{\prime}$ with $0 \leqq t, t^{\prime} \leqq T$, we obtain

$$
\begin{aligned}
\left\|\left(\vec{H}^{-1}(t)-\vec{H}^{-1}\left(t^{\prime}\right)\right) \vec{\chi}\right\|_{(0)} & =\left\|\left(\vec{H}^{-1}(t)\left(\vec{H}\left(t^{\prime}\right)-\vec{H}(t)\right) \vec{H}^{-1}\left(t^{\prime}\right)\right) \vec{\chi}\right\|_{(0)} \\
& \leqq C_{T} \gamma_{T}^{2}\left|t^{\prime}-t\right|\|\vec{\chi}\|_{(0)} .
\end{aligned}
$$

If we put $\vec{\phi}(t, \cdot)=\vec{H}^{-1}(t) \vec{\chi} \in \mathscr{H}_{(r)}\left(R_{n}\right)$ for any $\vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right)$, then we have

$$
\begin{aligned}
\left\|\left(\vec{H}^{-1}(t) \vec{A}^{*}(t)-\vec{A}(t) \vec{H}^{-1}(t)\right) \vec{\chi}\right\|_{(0)} & =\left\|\vec{H}^{-1}(t)\left(\vec{A}^{*}(t) \vec{H}(t)-\vec{H}(t) \vec{A}(t)\right) \vec{\phi}(t, \cdot)\right\|_{(0)} \\
& \leqq \gamma_{T} C_{T}\|\vec{\phi}(t, \cdot)\|_{(0)} \\
& \leqq \gamma_{T}^{2} C_{T}\|\vec{\chi}\|_{(0)} .
\end{aligned}
$$

Applying the preceding proposition, we see that ( $\tilde{E}_{(0)}^{1} \uparrow \downarrow$ ) holds for $L^{*}$.
Let $\vec{A}(t)$ be an element of $\mathfrak{G}_{(r)}, r>0$, satisfying the pseudo-commutativity (*) and assume there exists an $N \times N$ positive definite matrix $\vec{H}(t), 0 \leqq t \leqq \infty$, whose elements are continuous linear operators of $\mathscr{H}_{(-r / 2)}\left(R_{n}\right)$ into itself for each $t$, and assume $\vec{H}(t)$ has the following properties: (i) There exists a constant $r_{T}$ such that $\frac{1}{\gamma_{T}}\|\vec{\chi}\|_{(0)}^{2} \leqq(\vec{H}(t) \vec{\chi}, \vec{\chi}) \leqq \gamma_{T}\|\vec{\chi}\|_{(0)}^{2}, 0 \leqq t \leqq T$, for $\vec{\chi} \in C_{0}^{\infty}\left(\boldsymbol{R}_{n}\right)$. (ii) There exists a constant $C_{T}$ such that $\left\|\left(\vec{H}(t)-\vec{H}\left(t^{\prime}\right)\right) \vec{\chi}\right\|_{(0)} \leqq C_{T}\|\vec{\chi}\|_{(0)}\left|t-t^{\prime}\right|$, $0 \leqq t, t^{\prime} \leqq T$, for $\vec{\chi} \epsilon C_{0}^{\infty}\left(R_{n}\right)$ and (iii) $(\vec{H}(t) \vec{A}(t) \vec{\chi}, \vec{\chi})$ is coercive in the sense:

$$
\operatorname{Im}(\vec{H}(t) \vec{A}(t) \vec{\chi}, \vec{\chi}) \leqq \mu_{0}\|\vec{\chi}\|_{(0)}^{2}-\mu_{1}\|\vec{\chi}\|_{(r / 2)}^{2}, 0 \leqq t \leqq T, \vec{\chi} \in C_{0}^{\infty}\left(R_{n}\right)
$$

with constants $\mu_{1}=\mu_{1}(T)$ and $\mu_{0}=\mu_{0}(T)>0$.
S. Kaplan [11] has investigated the Cauchy problem for the parabolic operator with the form:

$$
\frac{\partial}{\partial t}-M(t)=\frac{\partial}{\partial t}-\sum_{\mid \alpha \leqq \leqq 2 m} a_{\alpha}(t, x) D_{x}^{\alpha}, \quad a_{\alpha} \in \mathscr{B}\left(R_{n+1}\right)
$$

and $M(t)$ is assumed to be uniformly strongly elliptic, where $m$ is a positive
integer. The operator $M(t)$ satisfies the condition (iii)' with $N=1, H(t)=1$ and $r=2 m$.

We shall first note that the following energy inequality holds true for $L=D_{t}+\vec{A}(t)$.

Theorem 8. For any $\vec{u} \in \mathscr{H}_{(0, s+r)}(H), H=[0, T] \times R_{n}$, there exists a constant $C_{T}$ such that

$$
\begin{align*}
\left\|\vec{u}\left(t_{1}, \cdot\right)\right\|_{(s+r / 2)}^{2} & +\int_{t_{0}}^{t_{1}}\|\vec{u}(t, \cdot)\|_{(s+r)}^{2} d t \leqq C_{T}\left(\left\|\vec{u}\left(t_{0}, \cdot\right)\right\|_{(s+r / 2)}^{2}+\right.  \tag{23}\\
& \left.+\int_{t_{0}}^{t_{1}}\|L \vec{u}(t, \cdot)\|_{(s)}^{2} d t\right), \quad 0 \leqq t_{0} \leqq t_{1} \leqq T
\end{align*}
$$

Proof. For any $\vec{u} \in C_{0}^{\infty}\left(R_{n+1}\right)$, if we put $\vec{f}=L \vec{u}$, then we have

$$
\begin{aligned}
& D_{-}(\vec{H}(t) \vec{u}(t, \cdot), \vec{u}(t, \cdot)) \\
& \quad \leqq K\|\vec{u}(t, \cdot)\|_{(0)}^{2}+i\left\{\left(\vec{H}(t) D_{t} \vec{u}(t, \cdot), \vec{u}(t, \cdot)\right)-\left(\vec{H}(t) \vec{u}(t, \cdot), D_{t} \vec{u}(t, \cdot)\right)\right\} \\
& =K\|\vec{u}(t, \cdot)\|_{(0)}^{2}+2 \operatorname{Im}(\vec{u}(t, \cdot), \vec{H}(t) \vec{f}(t, \cdot))+2 \operatorname{Im}(\vec{H}(t) \vec{A}(t) \vec{u}(t, \cdot), \vec{u}(t, \cdot)) \\
& \quad \leqq 2|(\vec{H}(t) \vec{f}(t, \cdot), \vec{u}(t, \cdot))|-2 \mu_{1}\|\vec{u}(t, \cdot)\|_{(r / 2)}^{2}+\left(2 \mu_{0}+K\right)\|\vec{u}(t, \cdot)\|_{(0)}^{2}
\end{aligned}
$$

with a constant $K$. Putting $h^{2}(t)=(\vec{H}(t) \vec{u}(t, \cdot), \vec{u}(t, \cdot))$, we obtain

$$
\begin{aligned}
h^{2}\left(t_{1}\right)-h^{2}\left(t_{0}\right) & \leqq 2 \int_{t_{0}}^{t_{1}}|(\vec{H}(t) \vec{f}(t, \cdot), \vec{u}(t, \cdot))| d t- \\
& -2 \mu_{1} \int_{t_{0}}^{t_{1}}\|\vec{u}(t, \cdot)\|_{(r / 2)}^{2} d t+\left(2 \mu_{0}+K\right) \int_{t_{0}}^{t_{1}}\|\vec{u}(t, \cdot)\|_{(0)}^{2} d t,
\end{aligned}
$$

and therefore if we put $\vec{v}=S^{-s-r / 2} \vec{u}$, then we can write

$$
\begin{gathered}
\frac{1}{r}\left\|\vec{v}\left(t_{1}, \cdot\right)\right\|_{(s+r / 2)}^{2}-\gamma_{T}\left\|\vec{v}\left(t_{0}, \cdot\right)\right\|_{(s+r / 2)}^{2} \leqq 2 \int_{t_{0}}^{t_{1}}\left|\left(\vec{H}(t) L S^{s+r / 2} \vec{v}, S^{s+r / 2} \vec{v}\right)\right| d t- \\
-2 \mu_{1} \int_{t_{0}}^{t_{1}}\|\vec{v}(t, \cdot)\|_{(s+r)}^{2} d t+\left(2 \mu_{0}+K\right) \int_{t_{0}}^{t_{1}}\|\vec{v}(t, \cdot)\|_{(s+r / 2)}^{2} d t
\end{gathered}
$$

where

$$
\begin{aligned}
& \left|\left(\vec{H}(t) L S^{s+r / 2} \vec{v}, S^{s+r / 2} \vec{v}\right)\right| \\
& \leqq\left|\left(\vec{H}(t) S^{s+r / 2} L v, S^{s+r / 2} \vec{v}\right)\right|+\left|\left(\vec{H}(t)\left(\vec{A}(t) S^{s+r / 2}-S^{s+r / 2} \vec{A}(t)\right) \vec{v}, S^{s+r / 2} \vec{v}\right)\right| \\
& \leqq C_{1}\|(L \vec{v})(t, \cdot)\|_{(s)}\|\vec{v}(t, \cdot)\|_{(s+r)}+C_{2}\|\vec{v}(t, \cdot)\|_{(s+r-1)}\|\vec{v}(t, \cdot)\|_{(s+r)} .
\end{aligned}
$$

For any given $\varepsilon>0$ there exists a constant $C(\varepsilon)$ such that

$$
\|\vec{v}(t, \cdot)\|_{(s+r-1)}^{2} \leqq \varepsilon^{2}\|\vec{v}(t, \cdot)\|_{(s+r)}^{2}+C(\varepsilon)\|\vec{v}(t, \cdot)\|_{(s)}^{2} .
$$

Applying the Schwarz inequality, we have the estimate with a constant $C^{\prime}(\varepsilon)$

$$
\begin{aligned}
2 \int_{t_{0}}^{t_{1}} \mid\left(\vec{H}(t) L S^{s+r / 2} \vec{v},\right. & \left.S^{s+r / 2} \vec{v}\right) \mid d t \leqq 3 \varepsilon \int_{t_{0}}^{t_{1}}\|\vec{v}(t, \cdot)\|_{(s+r)}^{2} d t+ \\
& +C^{\prime}(\varepsilon) \int_{t_{0}}^{t_{1}}\|L \vec{v}(t, \cdot)\|_{(s)}^{2} d t+C^{\prime}(\varepsilon) \int_{t_{0}}^{t_{1}}\|\vec{v}(t, \cdot)\|_{(s)}^{2} d t
\end{aligned}
$$

Taking $\varepsilon=\frac{1}{3} \mu_{1}$ and applying Lemma 3 in Section 2, we obtain the inequality with a constant $C_{T}$ such that

$$
\begin{aligned}
&\left\|\vec{v}\left(t_{1}, \cdot\right)\right\|_{(s+r / 2)}^{2}+\int_{t_{0}}^{t_{1}}\|\vec{v}(t, \cdot)\|_{(s+r)}^{2} d t \leqq C_{T}\left(\left\|\vec{v}\left(t_{0}, \cdot\right)\right\|_{(s+r / 2)}^{2}+\right. \\
&+\int_{t_{0}}^{t_{1}}\|L \vec{v}(t, \cdot)\|_{(s)}^{2} d t
\end{aligned}
$$

which will yield the estimate (23) since $C_{0}^{\infty}(H)$ is dense in $\mathscr{H}_{(0, s+r)}(H)$. Thus the proof is complete.

By modifying the method developed in Sections 2 and 3 we shall show the uniqueness and existence theorems for the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \quad \text { in } \dot{H},  \tag{24}\\
\mathscr{D}_{L^{2}-1}^{\prime-\lim _{t \downarrow 0}} \vec{u}=\vec{\alpha}
\end{array}\right.
$$

for any preassigned $\vec{\alpha} \epsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ and $\vec{f} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$, where $\vec{f}$ is assumed to have the $\mathscr{D}_{L^{2}}^{\prime}$-canonical extension $\vec{f}_{\sim}$.

From now on, we assume that $\vec{A}(t) \epsilon \mathfrak{๒}_{(r)}^{\infty}$.
Theorem 9. If $\vec{u} \in \mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$ and $\vec{u}$ is a solution of the Cauchy problem $L \vec{u}=0$ in $\dot{H}$ with initial condition $\mathscr{D}_{L^{2}-\lim _{t \downarrow 0}} \vec{u}=0$, then $\vec{u}=0$.

Proof. There exists real numbers $\sigma, s$ such that $\vec{u} \in \mathscr{K}^{(\sigma, s)}(H)$. From the equation $D_{t} \vec{u}=-\vec{A}(t) \vec{u} \in \mathscr{K}^{(\sigma, s-r)}(H)$ we see that $\vec{u} \in \mathscr{K}^{(\sigma+r, s-r)}(H)$. Thus we may assume that $\sigma \geqq 0$. From the energy inequality in the preceding theorem we can conclude that $\vec{u}=0$.

We shall say that (CP) ${ }_{(s)}^{\prime}$ holds for $L$ if the Cauchy problem (24) has a solution $\vec{u} \in \mathscr{H}_{(0, s+r)}(H)$ for any given $\vec{f} \in \mathscr{H}_{(0, s)}(H)$ and $\vec{\alpha} \in \mathscr{H}_{(s+r / 2)}\left(R_{n}\right)$. Then, in the same way as in the proof of Propositions 4 and 5 we have

Proposition 4'. If ( CP$)_{(s)}^{\prime}$ holds for $L$, then it also holds for $L^{1}=L+\vec{B}(t)$, $\vec{B}(t) \in \mathfrak{S}_{(r-1)}$.

Proposition 5'. If (CP) $)_{(s)}^{\prime}$ holds for some $s$, then it does for any s.
Next we shall show an analogue of Proposition 7.

Proposition 7'. (CP)'s holds for $L$ if and only if the conditions that $\vec{w} \in \mathscr{K}_{(0,-s)}(H), L^{*} \vec{w}=0$ in $\dot{H}$ and $\mathscr{D}_{L^{2-}}^{\prime-\lim _{t \uparrow T}} \vec{w}=0$ imply $\vec{w}=0$ in $\dot{H}$.

Proof. Let (CP) $)_{(s)}^{\prime}$ hold for $L$ and $\vec{w} \in \mathscr{H}_{(0,-s)}(H)$ and assume that $L^{*} \vec{w}=0$ in $\dot{H}$ with $\mathscr{D}_{L^{2}-\lim _{t \uparrow T}} \vec{w}=0$. For any $\vec{f} \in C_{0}^{\infty}(\mathscr{H})$, let $\vec{u} \in \mathscr{H}_{(0, s+r)}(H)$ be a solution of $L \vec{u}=\vec{f}$. From the fact that the energy inequality (23) holds true, there exists a sequence $\left\{\vec{\phi}_{j}\right\}, \vec{\phi}_{j} \in C_{0}^{\infty}(H)$ vanishing near $t=0$ and we have $\int_{0}^{T}\left(L \vec{\phi}_{j}(t, \cdot), \vec{w}(t, \cdot)\right) d t=0 . \quad$ Thus $\vec{w}=0$ in $\vec{H}$.

To prove the converse, we first show that $A=\left\{(\vec{\phi}(0, \cdot), L \vec{\phi}): \vec{\phi} \in C_{0}^{\infty}(H)\right\}$ is dense in $\mathscr{H}_{(s+r / 2)}\left(R_{n}\right) \times \mathscr{H}_{(0, s)}(H)$. Let $(i \vec{\beta}, \vec{w}) \in \mathscr{H}_{(-s-r / 2)}\left(R_{n}\right) \times \mathscr{H}_{(0,-s)}(H)$ such that

$$
\int_{0}^{T}(L \vec{\phi}(t, \cdot), \vec{w}(t, \cdot)) d t-i\left(\vec{\phi}_{0}, \vec{\beta}\right)=0, \quad \vec{\phi} \in C_{0}^{\infty}(H),
$$

which implies $L^{*} \vec{w}=0$ in $\dot{H}$, and $\mathscr{D}_{L^{2}-1 \lim _{t \downarrow 0}} \vec{w}=0$. Thus we see that $\vec{w}=0$ in $H^{\prime}$ and $\vec{\beta}=0$. For any $\vec{f} \in \mathscr{H}_{(0, s)}(H)$ and $\vec{\alpha} \in \mathscr{H}_{(s+r / 2)}\left(R_{n}\right)$ there exists a sequence $\left\{\vec{\phi}_{j}\right\}, \vec{\phi}_{j} \in C_{0}^{\infty}(H)$, such that $\vec{\phi}_{j}(0, \cdot), L \vec{\phi}_{j}$ converge in $\mathscr{H}_{(s+r / 2)}\left(R_{n}\right), \mathscr{H}_{(0, s)}(H)$ to $\vec{\alpha}$, $\vec{f}$ respectively as $j \rightarrow \infty$. From the energy inequality (23) we see that $\left\{\vec{\phi}_{j}\right\}$ is a Cauchy sequence in $\mathscr{H}_{(0, s+r)}(H)$. Let $\vec{u}$ be the limit of the sequence $\left\{\vec{\phi}_{j}\right\}$. Then $\vec{u}$ satisfies the equation $L \vec{u}=\vec{f}$ in $\vec{H}$ with $\mathscr{D}_{L^{2}}^{\prime 2} \lim _{t \downarrow 0} \vec{u}=\vec{\alpha}$. From the fact that $\vec{u} \in \mathscr{H}_{(0, s+r)}(H)$ and $D_{t} \vec{u} \in \mathscr{H}_{(0, s)}(H)$ we see that $\vec{u} \in \mathscr{K}^{(r, s)}(H)$.

Proposition 24. Suppose (CP) ${ }_{(0)}$ holds for L. For any $\vec{f} \in \mathscr{K}^{(k r, s)}(H), k$ being any non-negative integer, and $\vec{\alpha} \in \mathscr{H}_{((k+1 / 2) r+s)}\left(R_{n}\right)$ there exists a unique solution $\vec{u} \in \mathscr{K}^{((k+1) r, s)}(H)$ of the Cauchy problem (24). Furthermore $\vec{u}$ satisfies the inequality

$$
\begin{align*}
& \sum_{j=0}^{k}\left\|D_{t}^{j} \vec{u}(t, \cdot)\right\|_{(s+(k-j+1 / 2) r)}^{2}+\sum_{j=0}^{k} \int_{0}^{t}\left\|D_{t}^{j} \vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(s+(k-j+1) r)}^{2} d t^{\prime}  \tag{25}\\
& \leqq C_{T}\left(\|\vec{\alpha}\|_{(s+(k+1 / 2) r)}^{2}+\sum_{j=0}^{k-1}\left\|D_{t}^{j} \vec{f}(0, \cdot)\right\|_{(s+(k-1 / 2) r)}^{2}+\right. \\
& \left.\quad+\sum_{j=0}^{k} \int_{0}^{t}\left\|D_{t}^{j} \vec{f}\left(t^{\prime}, \cdot\right)\right\|_{(s+(k-j) r)}^{2} d t^{\prime}\right)
\end{align*}
$$

with a constant $C_{T}$.
Proof. If $k=0$ this result is already shown in Theorem 8 and Proposition $7^{\prime}$. Let $\vec{f} \in \mathscr{K}^{(r, s)}(H)$ and $\vec{\alpha} \in \mathscr{H}_{(s+(3 / 2) r)}\left(R_{n}\right)$. Then the Cauchy problem (24) has a unique solution $\vec{u} \in \mathscr{K}^{(2 r, s)}(H)$. Furthermore $\vec{u}$ satisfies the inequality:

$$
\begin{align*}
\|\vec{u}(t, \cdot)\|_{(s+(3 / 2) r)}^{2}+\int_{0}^{t}\left\|\vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(s+2 r)}^{2} d t \leqq & C_{1}\left(\|\vec{u}(0, \cdot)\|_{(s+(3 / 2) r)}^{2}+\right.  \tag{26}\\
& \left.+\int_{0}^{t}\left\|L u\left(t^{\prime}, \cdot\right)\right\|_{(s+r)}^{2} d t^{\prime}\right)
\end{align*}
$$

Put $\vec{v}=D_{t} \vec{u}$. Then $\vec{v} \in \mathscr{K}^{(r, s)}(H)$ and we have $L \vec{v}=D_{t} \vec{f}+i \vec{A}^{\prime}(t) \vec{u} \in \mathscr{H}_{(0, s)}(H)$, and therefore

$$
\begin{aligned}
\|\vec{v}(t, \cdot)\|_{(s+r / 2)}^{2} & +\int_{0}^{t}\left\|\vec{v}\left(t^{\prime}, \cdot\right)\right\|_{(s+r)}^{2} d t \leqq C_{2}\left(\|\vec{v}(0, \cdot)\|_{(s+r / 2)}^{2}+\right. \\
& \left.+\int_{0}^{t}\left\|D_{t} \vec{f}\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime}+\int_{0}^{t}\left\|\vec{A}^{\prime}\left(t^{\prime}\right) \vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime}\right)
\end{aligned}
$$

where $C_{2}$ is a constant. Applying Lemma 3 in Section 2, we obtain with a constant $C_{3}$

$$
\begin{align*}
&\|\vec{v}(t, \cdot)\|_{(s+r / 2)}^{2}+\int_{0}^{t}\left\|\vec{v}\left(t^{\prime}, \cdot\right)\right\|_{(s+r)}^{2} d t^{\prime} \leqq C_{3}\left(\|\vec{v}(0, \cdot)\|_{(s+r / 2)}^{2}+\right.  \tag{27}\\
&\left.+\int_{0}^{t}\left\|D_{t} \vec{f}\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime}\right)
\end{align*}
$$

From (26) and (27) we have with a constant $C_{T}$

$$
\begin{aligned}
& \|\vec{u}(t, \cdot)\|_{(s+(3 / 2) r)}^{2}+\left\|D_{t} \vec{u}(t, \cdot)\right\|_{(s+r / 2)}^{2}+\int_{0}^{t}\left\|\vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(s+2 r)}^{2} d t+ \\
& +\int_{0}^{t}\left\|D_{t} \vec{u}\left(t^{\prime}, \cdot\right)\right\|_{(s+r)}^{2} d t \leqq C_{T}\left(\|\vec{u}(0, \cdot)\|_{(s+(3 / 2) r)}^{2}+\|\vec{f}(0, \cdot)\|_{(s+r / 2)}^{2}+\right. \\
& \left.\quad+\int_{0}^{t}\left\|\vec{f}\left(t^{\prime}, \cdot\right)\right\|_{(s+r)}^{2} d t^{\prime}+\int_{0}^{t}\left\|D_{t} \vec{f}\left(t^{\prime}, \cdot\right)\right\|_{(s)}^{2} d t^{\prime}\right)
\end{aligned}
$$

Repeating this procedure, we obtain the inequality (25).
We note here that $\mathscr{K}^{(k r, s)}(H), k$ being non-negetive integer, has the equivalent norm

$$
\left(\sum_{j=0}^{k} \int_{0}^{T} D_{t}^{j}\left\|u\left(t^{\prime}, \cdot\right)\right\|_{(s+(k-j) r)}^{2} d t^{\prime}\right)^{1 / 2}
$$

With the aid of the interpolation theorem for the Hilbert scales, we can show

Corollary 7, Suppose (CP) ${ }_{(0)}$, holds for $L$. For any $\vec{f} \in \mathscr{K}^{(\sigma, s)}(H), \sigma \geqq 0$ and $\vec{\alpha} \in \mathscr{H}_{(\sigma+s+r / 2)}\left(R_{n}\right)$ there exists a unique solution of the Cauchy problem (24) and $(\vec{\alpha}, \vec{f}) \rightarrow \vec{u}$ is a continuous map of $\mathscr{H}_{(\sigma+s+r / 2)}\left(R_{n}\right) \times \mathscr{K}^{(\sigma, s)}(H)$ into $\mathscr{K}^{(\sigma+r, s)}(H)$.

We shall denote by $\mathscr{\mathscr { K }}^{(\sigma, s)}\left(H_{-}\right)$the space which is a restriction of the space $\dot{\mathscr{K}}^{(\sigma, s)}\left(\bar{R}_{n+1}^{+}\right)$to $(-\infty, T] \times R_{n}$ and similarly for $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)\left(H_{-}\right)$. By Proposition 7 in [8, p. 416] we see that for every $\vec{u} \in \mathscr{K}^{(\sigma, s)}(H)$ with $|\sigma|<\frac{r}{2}$ its canonical extension $\vec{u}_{\sim}$ over $t=0$ belongs to the space $\mathscr{\mathscr { K }}^{(\sigma, s)}\left(H_{-}\right)$.

Proposition 25. Suppose (CP) ${ }_{(0)}^{\prime}$ holds for L. For any $\vec{f} \in \mathscr{K}^{(\sigma, s)}(H)$, $-\frac{r}{2}<\sigma<0$ and $\vec{\alpha} \in \mathscr{H}_{(\sigma+s+r / 2)}\left(R_{n}\right)$ there exists a unique solution $\vec{u} \in \mathscr{K}^{(\sigma+r, s)}(H)$ of the Cauchy problem (24).

Proof. For any given $\vec{f} \in \mathscr{K}^{\left(\sigma_{s}\right)}(H)$ we shall consider $\vec{g}$ satisfying the equation

$$
D_{t} \vec{g}-i \lambda^{r}\left(D_{x}\right) \vec{g}=\vec{f}_{\sim}
$$

Then $\vec{g} \in \mathscr{K}^{(\sigma+r, s)}\left(H_{-}\right)$and therefore $\mathscr{D}_{L^{2-}}^{\prime} \lim _{t \downarrow 0} \vec{g}=0$. The Cauchy problem (24) can be written in the form

$$
\left\{\begin{array}{l}
D_{t}(\vec{u}-\vec{g})+\vec{A}(t)(\vec{u}-\vec{g})=-i \lambda^{r}\left(D_{x}\right) \vec{g}-\vec{A}(t) \vec{g} \quad \text { in } H,  \tag{28}\\
\mathscr{D}_{L^{2}-\lim _{t \downarrow 0}}(\vec{u}-\vec{g})=\vec{\alpha},
\end{array}\right.
$$

where $-i \lambda^{r}\left(D_{x}\right) \vec{g}-\vec{A}(t) \vec{g} \in \dot{\mathscr{K}}^{(\sigma+r, s-r)}\left(H_{-}\right), \frac{r}{2}<\sigma+r<r$. Thus there exists a unique solution $\vec{v}=\vec{u}-\vec{g} \in \widetilde{K}^{(\sigma+2 r, s-r)}(H)$ and therefore $\vec{u}=\vec{v}+\vec{g} \in \mathscr{K}^{(\sigma+r, s)}(H)$.

Let $\sigma, s$ be any real numbers and write $\sigma=k r+\sigma^{\prime}$ with integer $k$ and $-\frac{r}{2}<\sigma^{\prime} \leqq \frac{r}{2}$. We are now prepared to show the following theorem, a generalization of a result of S. Kaplan [11, p. 180].

Theorem 10. Suppose (CP) ${ }_{(0)}^{\prime}$ holds for L. For any $\vec{\alpha} \epsilon \mathscr{H}_{(\sigma+s+r / 2)}\left(R_{n}\right)$ and $\vec{f} \in \mathscr{K}^{(\sigma, s)}(H)$ with $\vec{f}_{\sim} \in \mathscr{K}^{(\sigma, s)}\left(H_{-}\right)$, there exists a unique solution $\vec{u} \in \mathscr{K}^{(\sigma+r, s)}(H)$ of the Cauchy problem (24). In particular, if $\vec{\alpha}=0$ then $\vec{u}_{\sim} \in \mathscr{K}^{(\sigma+r, s)}\left(H_{-}\right)$.

Proof. Consider the case $k \geqq 0$. In Corollary 7 we have shown that there exists a solution $\vec{u} \in \mathscr{K}^{(\sigma+r, s)}(H)$. Since a solution of the Cauchy problem is unique in $\mathscr{D}_{t}^{\prime}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)(H)$, we have only to show that if $\vec{\alpha}=0$ then $\vec{u}_{\sim} \epsilon$ $\mathscr{K}^{(\sigma+r, s)}\left(H_{-}\right)$. Suppose $\vec{\alpha}=0$. Then $\lim _{t \downarrow 0}\left(\vec{u}, \cdots, D_{t}^{k} \vec{u}\right)=0$. In fact, if $k=0$ then $\lim _{t \downarrow 0} \vec{u}=\mathscr{D}_{L^{2}}^{\prime-} \lim _{t \downarrow 0} \vec{u}=0$. Let $k>0$. Then the condition $\vec{f}_{\sim} \in \dot{\mathscr{K}}^{\left(k r+\sigma^{\prime}, s\right)}\left(H_{-}\right)$ implies $\lim _{t \downarrow 0}\left(f, \cdots, D_{t}^{k-1} \vec{f}\right)=\mathscr{D}_{L}^{\prime} \lim _{t \downarrow 0}\left(\vec{f}, \cdots, D_{t}^{k-1} \vec{f}\right)=0$ (cf. Theorem 3 in [8, p. 419]). In the same way as in the proof of Proposition 13 we can prove that $\lim _{t \downarrow 0}\left(\vec{u}, \cdots, D_{t}^{k} \vec{u}\right)=0$. In the case $\sigma^{\prime}<\frac{r}{2}$, Theorem 3 in [8, p. 419] implies immediately $\vec{u} \in \mathscr{\mathscr { K }}^{(\sigma+r, s)}\left(H_{-}\right)$. Let $\sigma^{\prime}=\frac{r}{2}$. Then $\vec{u}_{\sim} \epsilon \dot{\mathscr{K}}^{(\sigma+r-\varepsilon, s+\varepsilon)}\left(H_{-}\right) \subset$ $\dot{\mathscr{K}}^{(\sigma, s+r)}\left(H_{-}\right), 0<\varepsilon \leqq r$. Combining with the relation $D_{t}\left(\vec{u}_{\sim}\right)=\vec{f}_{\sim}-\vec{A}(t) \vec{u}_{\sim} \epsilon$ $\mathscr{\mathscr { K }}^{(\sigma, s)}\left(H_{-}\right)$shows that $\vec{u}_{\sim} \in \dot{\mathscr{K}}^{(\sigma+r, s)}\left(H_{-}\right)$.

Consider the case where $k<0$. We shall reason by descending induction over $k$. Assume that the results hold true of any $k+1$. Let $\vec{f}_{\sim} \in \dot{\mathscr{K}}^{(\sigma, s)}\left(H_{-}\right)$,
$\sigma=k r+\sigma^{\prime}$, and $\vec{\alpha} \in \mathscr{H}_{(\sigma+s+r / 2)}\left(R_{n}\right)$. Let $\vec{g} \in \mathscr{\mathscr { K }}^{(\sigma+r, s)}\left(H_{-}\right)$be a solution of the equation

$$
D_{t} \vec{g}-i \lambda^{r}\left(D_{x}\right) \vec{g}=\vec{f}_{\sim}
$$

Then $\mathscr{D}_{L^{2}-l_{t \downarrow 0}^{\prime}} \vec{g}=0$. The Cauchy problem (24) can be written in the form (28) and $-i \lambda^{r}\left(D_{x}\right) \vec{g}-\vec{A}(t) \vec{g} \in \dot{\mathscr{K}}^{(\sigma+r, s-r)}\left(H_{-}\right)$, and therefore there exists a solution $\vec{v}=\vec{u}-\vec{g} \epsilon \mathscr{K}^{(\sigma+2 r, s-r)}(H)$ and $\vec{u}=\vec{v}+\vec{g} \in \mathscr{K}^{(\sigma+r, s)}(H)$. Especially, if $\vec{\alpha}=0$ then $\vec{u}_{\sim} \in \dot{\mathscr{K}}^{(\sigma+r, s)}\left(H_{-}\right)$.

Along the same line as in the proof of the preceding theorem we can prove the following

Proposition 26. Suppose (CP) ${ }_{(0)}^{\prime}$ holds for L. For any $\vec{h} \in \mathscr{K}^{(\sigma, s)}\left(H_{-}\right)$ there exists a unique solution $\vec{v} \in \mathscr{K}^{(\sigma+r, s)}\left(H_{-}\right)$of $L \vec{v}=\vec{h}$.

The following theorems are the analogues of Theorems 4 and 5 and can be proved in a similar way, so the proofs are omitted.

Theorem 11. Suppose (CP) ${ }_{(0)}^{\prime}$ holds for L. Then for any $\vec{h} \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ there exists a unique solution $\vec{v} \in\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ of $L \vec{v}=\vec{h}$ and $\vec{h} \rightarrow \vec{v}$ is a continuous map of $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ onto itself.

Theorem 12. Suppose (CP) ${ }_{(0)}^{\prime}$ holds for $L$. Then for any $\vec{\alpha} \epsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$ and $\vec{f} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, which has the $\mathscr{D}_{L^{2}}^{\prime}$-canonical extension $\vec{f}_{-} \epsilon\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$, the Cauchy problem (24) has a unique solution $\vec{u} \in \mathscr{D}^{\prime}\left(R_{t}^{+}\right)\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and $\left(\vec{\alpha}, \vec{f}_{\sim}\right) \rightarrow \vec{u} \sim$ is a continuous map under the topology of $\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x} \times\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$ and the topology of $\left(\mathscr{D}_{t}^{\prime}\right)_{+}\left(\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}\right)$.

## 7. Notes on a system of ordinary differential operators

Let $L$ be a system of ordinary differential operators of the form $L=D_{t}+\vec{A}(t)$, where $\vec{A}(t)$ is an $N \times N$ matrix of $C^{\infty}$ functions on $R_{t}$ and consider the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{u}=\vec{f} \text { in } R^{+}  \tag{29}\\
\lim _{t \downarrow 0} \vec{u}=\vec{\alpha}
\end{array}\right.
$$

for any preassigned $\vec{f} \in \mathscr{D}^{\prime}\left(R^{+}\right)$and $\vec{\alpha} \in \boldsymbol{C}^{N}$. If $\vec{u} \in \mathscr{D}^{\prime}\left(R^{+}\right)$exists, then $\bar{f}$ has the canonical extension $\vec{f}_{\sim} \in \mathscr{D}_{+}^{\prime}$ and

$$
\begin{equation*}
L\left(\vec{u}_{\sim}\right)=\vec{f}_{\sim}-i \vec{\alpha} \delta . \tag{30}
\end{equation*}
$$

Conversely, if $\vec{v} \in \mathscr{D}_{+}^{\prime}$ satisfies the equation (30), then the restriction $\vec{u}=\vec{v} \mid R^{+}$is a solution of the Cauchy problem (29) and $\vec{v}=\vec{u}_{-}$, where by $\mathscr{D}_{+}^{\prime}$ we
mean the closed subspace of $\mathscr{D}^{\prime}(R)$ with support $\subset \bar{R}^{+}$.
Now we shall show that our considerations in the present paper can also be applied to the Cauchy problem for ordinary differential system as a special case.

For any $\vec{\phi} \in C_{0}^{\infty}(R)$

$$
\vec{\phi}\left(t_{1}\right)=\vec{\phi}\left(t_{0}\right)+\int_{t_{0}}^{t_{1}} \vec{\phi}^{\prime}(t) d t
$$

whence for any $T>0$

$$
\left|\vec{\phi}\left(t_{1}\right)\right| \leqq\left|\vec{\phi}\left(t_{0}\right)\right|+\int_{t_{0}}^{t_{1}}|L \vec{\phi}(t)| d t+\max _{0 \leqq t \leqq T}|\vec{A}(t)| \int_{t_{0}}^{t_{1}}|\vec{\phi}(t)| d t, \quad 0 \leqq t_{0} \leqq t_{1} \leqq T .
$$

By Lemma 3 in Section 2, we can find a constant $C_{T}$ such that

$$
\begin{equation*}
\left|\vec{\phi}\left(t_{1}\right)\right| \leqq C_{T}\left(\left|\vec{\phi}\left(t_{0}\right)\right|+\int_{t_{0}}^{t_{1}}|L \vec{\phi}(t)| d t\right), \quad 0 \leqq t_{0} \leqq t_{1} \leqq T, \quad \vec{\phi} \in C_{0}^{\infty}(R) \tag{31}
\end{equation*}
$$

Similarly, for the formal adjoint $L^{*}$ of $L$ we have

$$
\begin{equation*}
\left|\vec{\phi}\left(t_{0}\right)\right| \leqq C_{T}\left(\left|\vec{\phi}\left(t_{1}\right)\right|+\int_{t_{0}}^{t_{1}}\left|L^{*} \vec{\phi}(t)\right| d t\right), \quad 0 \leqq t_{0} \leqq t_{1} \leqq T, \quad \vec{\phi} \in C_{0}^{\infty}(R) \tag{32}
\end{equation*}
$$

We shall first show the following
Theorem 12. If $\vec{u} \in \mathscr{D}^{\prime}\left(R^{+}\right)$satisfies $L \vec{u}=0$ in $t>0$ and $\lim _{t \downarrow 0} \vec{u}=0$, then $\vec{u}=0$.

Proof. In the same way as in the proof of Proposition 8 in [7, p. 22] we see that $\vec{u} \in \mathscr{E}_{t}^{\infty}\left(R^{+}\right)$. By the energy inequality (31) we have immediately $\vec{u}=0$ in $R^{+}$.

In what follows we shall show the existence theorems for the Cauchy problem (29).

Proposition 27. Let $\sigma>-\frac{1}{2}$. For any $\vec{\alpha} \in \boldsymbol{C}^{N}$ and $\vec{f} \in \widetilde{\mathscr{H}}_{(\sigma)}\left(\bar{R}^{+}\right)$there exists a unique solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1)}\left(\bar{R}^{+}\right)$of the Cauchy problem (29).

Proof. (1) Let $\sigma=k$ be a non-negative integer. First consider the case $k=0$. The set $A=\left\{(\vec{\phi}(0), L \vec{\phi}): \vec{\phi} \in C_{0}^{\infty}\left(\bar{R}^{+}\right)\right\}$is dense in $\boldsymbol{C}^{N} \times \widetilde{\mathscr{H}}_{(0)}\left(\bar{R}^{+}\right)$. In fact, let $(i \vec{\beta}, \vec{w}) \in \boldsymbol{C}^{N} \times \widetilde{\mathscr{H}}_{(0)}^{*}\left(\bar{R}^{+}\right)$such that

$$
(L \vec{\phi}, \vec{w})-i(\vec{\phi}(0), \vec{\beta})=0, \quad \vec{\phi} \in C_{0}^{\infty}\left(\bar{R}^{+}\right)
$$

Then we see that $L^{*} \vec{w}=0$ in $R^{+}$. By the energy inequality (32) we conclude that $\vec{w}=0$ in $R^{+}$and therefore $\vec{\beta}=0$.

For any $\vec{\alpha} \in \boldsymbol{C}^{N}$ and $\vec{f} \in \widetilde{\mathscr{H}}_{(k)}\left(\bar{R}^{+}\right)$there exists a sequence $\left\{\vec{\phi}_{j}\right\}, \vec{\phi}_{j} \in C_{0}^{\infty}\left(\bar{R}^{+}\right)$, such that $\vec{\phi}_{j}(0), L \vec{\phi}_{j}$ converge in $\boldsymbol{C}^{N}$ and $\tilde{\mathscr{H}}_{(k)}\left(\bar{R}^{+}\right)$to $\vec{\alpha}, \vec{f}$ respectively as $j \rightarrow \infty$.

By the energy inequality (31) we see that $\vec{\phi}_{j}$ is a Cauchy sequence in $\mathscr{E}_{t}^{0}\left(\bar{R}^{+}\right)$. Let $\vec{u}$ be the limit of $\vec{\phi}_{j}$. Then $\vec{u} \in \mathscr{E}_{t}^{0}\left(\bar{R}^{+}\right)$is a solution of the Cauchy problem (24). From the equation $D_{t} \vec{u}=\vec{f}-\vec{A}(t) \vec{u} \in \mathscr{H}_{(0)}\left(\bar{R}^{+}\right)$we see that $\vec{u} \in \mathscr{H}_{(1)}\left(\bar{R}^{+}\right)$.

Let $k=1$ and $\vec{f} \in \mathscr{H}_{(1)}\left(\bar{R}^{+}\right)$. Then $\vec{v}=D_{t} \vec{u} \in \tilde{\mathscr{H}}_{(0)}\left(\bar{R}^{+}\right)$and $L \vec{v}=D_{t} \vec{f}+i A^{\prime}(t) \vec{u}$ $\epsilon \mathscr{H}_{(0)}\left(\bar{R}^{+}\right)$, and therefore $\vec{v} \in \widetilde{\mathscr{H}}_{(1)}\left(\bar{R}^{+}\right)$, which implies $\vec{u} \in \widetilde{\mathscr{H}}_{(2)}\left(\bar{R}^{+}\right)$.

In the case where $\sigma=k \geqq 2$, repeating this procedure, we see that $\vec{u} \in \widetilde{\mathscr{H}}_{(k+1)}\left(\bar{R}^{+}\right)$.
(2) Let $\sigma$ be a non-negative real number. For any $\vec{\alpha} \epsilon C^{N}$ and $\vec{f} \epsilon$ $\widetilde{\mathscr{H}}_{(\sigma)}\left(\bar{R}^{+}\right)$there exists a solution $\vec{u} \in \mathscr{H}_{(k+1)}\left(\bar{R}^{+}\right)$of the Cauchy problem (29), where $k=[\sigma]$. Since $D_{t} \vec{u}=\vec{f}-\vec{A}(t) \vec{u} \in \widetilde{\mathscr{H}}_{(\sigma)}\left(\bar{R}^{+}\right)$we see that $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1)}\left(\bar{R}^{+}\right)$.
(3) Let $\sigma$ be such that $-\frac{1}{2}<\sigma<0$. For any $\vec{f} \in \widetilde{\mathscr{H}}_{(\sigma)}\left(\bar{R}^{+}\right)$if we define $\vec{g}$ by the equation $\left(D_{+}-i\right) \vec{g}=\vec{f}_{\sim}$, then $\vec{g} \in \dot{\mathscr{H}}_{(\sigma+1)}\left(\bar{R}^{+}\right)$and $\lim _{t \downarrow 0} \vec{g}=0$. The Cauchy problem (29) can be written in the form

$$
\left\{\begin{array}{l}
D_{t}(\vec{u}-\vec{g})+\vec{A}(t)(\vec{u}-\vec{g})=-i \vec{g}-\vec{A}(t) \vec{g} \\
\lim _{t \downarrow 0}(\vec{u}-\vec{g})=\vec{\alpha}
\end{array}\right.
$$

where $-i \vec{g}-\vec{A}(t) \vec{g} \epsilon \stackrel{\dot{\mathscr{H}}}{(\sigma+1)}\left(\bar{R}^{+}\right)$. Thus there exists a solution $\vec{v}=\vec{u}-\vec{g} \epsilon$ $\widetilde{\mathscr{H}}_{(\sigma+2)}\left(\bar{R}^{+}\right)$and therefore $\vec{u}=\vec{v}+\vec{g} \in \widetilde{\mathscr{H}}_{(\sigma+1)}\left(\bar{R}^{+}\right)$. Thus the proof is complete.

In the same way as in the proof of Proposition 13 we can prove the following

Proposition 28. Let $\sigma$ be any real number. For any $\vec{\alpha} \epsilon \boldsymbol{C}^{N}$ and $\vec{f} \epsilon$ $\widetilde{\mathscr{H}}_{(\sigma)}\left(\bar{R}^{+}\right)$with $\vec{f}_{\sim} \in \dot{\mathscr{H}}_{(\sigma)}\left(\bar{R}^{+}\right)$there exists a unique solution $\vec{u} \in \widetilde{\mathscr{H}}_{(\sigma+1)}\left(\bar{R}^{+}\right)$. In particular, if $\vec{\alpha}=0$ then $u \in \stackrel{\dot{\mathscr{H}}}{(\sigma+1)}\left(\bar{R}^{+}\right)$.

As an extension of Theorem 37 in E. Berz [2, p. 32] we have
Proposition 29. Let $\sigma$ be any real number. For any $\vec{h} \in \dot{\mathscr{H}}_{(\sigma)}\left(\bar{R}^{+}\right)$there exists a unique solution $\vec{v} \in \dot{\mathscr{H}}_{(\sigma+1)}\left(\bar{R}^{+}\right)$.

The following two theorems are the analogues of Theorems 4 and 5 and these can be proved in a similar way.

Theorem 13. For any $\vec{h} \in \mathscr{D}_{+}^{\prime}$, there exists a unique solution $\vec{v} \in \mathscr{D}_{+}^{\prime}$ of the equation $L \vec{u}=\vec{h}$ and $\vec{h} \rightarrow \vec{v}$ is a continuous map of $\mathscr{D}_{+}^{\prime}$ onto itself.

Theorem 14. For any $\vec{\alpha} \in \boldsymbol{C}^{N}$ and $\vec{f} \in \mathscr{D}^{\prime}\left(R^{+}\right)$with the canonical extension
 $\left(\vec{\alpha}, \vec{f}_{\sim}\right) \rightarrow \vec{u} \sim$ is a continuous map under the topology $\boldsymbol{C}^{N} \times \mathscr{D}_{+}^{\prime}$ and the topology $\mathscr{D}^{\prime}{ }^{+}$.

Let us consider an ordinary differential operator

$$
P(D)=D_{t}^{m}+\sum_{j=1}^{m} a_{j}(t) D_{t}^{m-j}, \quad a_{j} \in C^{\infty}(R) .
$$

Substituting $u_{j}=D_{t}^{j-1} u, j=1,2, \cdots, m$, then we obtain the equivalent system:

$$
\left\{\begin{array}{l}
D_{t} u_{j}-u_{j+1}=0 \text { for } j=1,2, \cdots, m-1 \\
D_{t} u_{m}+\sum_{j=1}^{m} a_{j}(t) u_{m-j+1}=f
\end{array}\right.
$$

Thus we have
Corollary 8. For any $h \in \mathscr{D}_{+}^{\prime}$, there exists a unique solution $v \in \mathscr{D}_{+}^{\prime}$ of the equation $P v=h$.

Corollary 9. For any $\left(\alpha_{0}, \ldots, \alpha_{m-1}\right) \in \boldsymbol{C}^{m}$ and $f \in \mathscr{D}^{\prime}\left(R^{+}\right)$with the canonical extension $f_{\sim}$, there exists a unique solution $u \in \mathscr{D}^{\prime}\left(R^{+}\right)$of the Cauchy problem:

$$
\left\{\begin{array}{l}
P u=f \text { in } R^{+}, \\
\lim _{t \downarrow 0}\left(u, D_{t} u, \cdots, D_{t}^{m-1} u\right)=\left(\alpha_{0}, \alpha_{1}, \cdots, \alpha_{m-1}\right) .
\end{array}\right.
$$

We can prove an analogue of Theorem 37 in E. Berz [2, p. 32].
Proposition 30. Let $l$ be a non-negative integer such that $l \leqq m$ and let $h \in \mathscr{D}_{+}^{\prime}$. Then the unique solution $v \in \mathscr{D}_{+}^{\prime}$ of $P v=h$ is a canonical distribution and $\lim _{t \downarrow 0}\left(v \mid R^{+}\right)=\cdots=\lim _{t \downarrow 0} D_{t}^{m-1-l}\left(v \mid R^{+}\right)=0$ when $l<m$, if and only if $h$ can be written in the form $h=D_{t}^{l} g$, where $g \in \mathscr{D}_{+}^{\prime}$ is a canonical distribution.

Prooe. Let $h$ be written in the form $h=D_{t}^{l} g, g \in \mathscr{D}_{+}^{\prime}$ being canonical. Suppose $l=0$. Then, in virtue of Corollary 1 in [7, p. 19], the restriction $u=v \mid R^{+}$is a solution of the Cauchy problem:

$$
\left\{\begin{array}{l}
P u=h \quad \text { in } R^{+}, \\
\lim _{t \downarrow 0}\left(u, D_{t} u, \cdots, D_{t}^{m-1} u\right)=0
\end{array}\right.
$$

and $v=u_{\sim}$.
By the induction on $l$ we shall prove the $v$ is a canonical distribution and $\lim _{t \downarrow 0}\left(u, \cdots, D_{t}^{m-1-l} u\right)=0$. Let $l>0$ and suppose the assertion is true for $l-1$, $0<l<m$. Consider the equation $P w=D_{t}^{l-1} g$. Then $w \in \mathscr{D}_{+}^{\prime}$ is canonical and $\lim _{t \downarrow 0}\left(w \mid R^{+}\right)=\cdots=\lim _{t \downarrow 0} D_{t}^{m-l}\left(w \mid R^{+}\right)=0$, and therefore $w, \cdots, D_{t}^{m-1-l} w$ are canonical. If we put $v=D_{t} w+\chi$, then

$$
P \chi=-i \sum_{j=1}^{m} a_{j}^{\prime}(t) D_{t}^{m-j} w .
$$

Thus $x \in \mathscr{D}_{+}^{\prime}$ is canonical and $\lim _{t \downarrow 0}\left(x \mid R^{+}\right)=\cdots=\lim _{t \downarrow 0} D_{t}^{m-l}\left(x \mid R^{+}\right)=0$ and therefore $v=D_{t} w+x$ is canonical and $\lim _{t \downarrow 0}\left(u, \cdots, D_{t}^{m-1-l} u\right)=0$ for $l<m$.

Conversely, let $v$ be canonical and $\lim _{t \downarrow 0}\left(u, \cdots, D_{t}^{m-1-l} u\right)=0$ when $l<m$. Put $Y_{k}=\frac{1}{(k-1)!} t^{k-1}$. Owing to the relation (16) in [10, p. 392], we have

$$
(-i)^{l} D_{t}^{m-l} v+\sum_{j=1}^{m} \sum_{k=1}^{l}(-i)^{k}\binom{l}{k} Y_{k} *\left(D_{t}^{k} a_{j}\left(Y_{l} * D_{t}^{m-j} v\right)\right)=Y_{l} * h .
$$

Since $v$ is canonical and $\lim _{t \downarrow 0}\left(u, \cdots, D_{t}^{m-1-t} u\right)=0, l<m$, we see that $v, D_{t} v, \cdots$, $D_{t}^{m-1} v$ are canonical and therefore the left hand side of the equation is canonical. Thus $Y_{l} * h$ is a canonical distribution, which implies that we can write $h=D_{t}^{l} g$, with a canonical $g$. The proof is thus complete.

Proposition 31. Let $\left\{\vec{u}_{\iota}\right\}_{\iota \in I}$ be a directed set in $\mathscr{E}_{t}^{0}\left(\bar{R}^{+}\right)$and put $\vec{f}_{\iota}=L \vec{u}_{\iota}$ in $\mathscr{D}^{\prime}\left(R^{+}\right)$. If $\vec{f}_{c}$ can be written in the form $\vec{f}_{c}=D_{t} \vec{g}_{c}$ in $R^{+}$, where $\vec{g}_{\iota} \in \mathscr{E}_{t}^{0}\left(\bar{R}^{+}\right)$ and $\vec{g}_{\iota}(0)=0$, and if $\vec{u}_{\iota}(0), \vec{g}_{،}$ converge in $\boldsymbol{C}^{N}, \mathscr{E}_{t}^{0}\left(\vec{R}^{+}\right)$to $\vec{\alpha}$, $\vec{g}$ respectively, then $\vec{u}_{\iota}$ converges in $\mathscr{E}_{t}^{0}\left(\bar{R}^{+}\right)$to $\vec{u}$ and $\vec{u}$ satisfies the equation $L \vec{u}=\vec{f}$ in $R^{+}$and $\vec{u}(0)=\vec{\alpha}$, where $\vec{f}=D_{t} \vec{g}$.

Proof. Consider the Cauchy problem:

$$
\left\{\begin{array}{l}
L \vec{v}_{\iota}=\vec{g}_{\iota} \text { in } R^{+} \\
\lim _{t \downarrow 0} \vec{v}_{\iota}=0
\end{array}\right.
$$

There exists a unique solution $\vec{v}_{\iota} \in \mathscr{E}_{t}^{1}\left(\bar{R}^{+}\right)$and $\vec{v}_{\iota}$ converges in $\mathscr{E}_{t}^{1}\left(\bar{R}^{+}\right)$to $\vec{v}$ when c run through $I$. Then $\vec{v}$ is a solution of the Cauchy problem $L \vec{v}=\vec{g}$ in $R^{+}$with $\vec{v}(0)=0$. On the other hand, from the equation $D_{t} \vec{v}_{\iota}=\vec{g}_{\iota}-\vec{A}(t) \vec{v}_{\iota}$ we have $D_{t} \vec{v}_{\iota}(0)=0$. If we put $\vec{u}_{\iota}=D_{t} \vec{v}+\vec{w}_{t}$, then

$$
\left\{\begin{array}{l}
L \vec{w}_{\imath}=i \vec{A}^{\prime}(t) \vec{v}_{\imath} \quad \text { in } \quad R^{+} \\
\lim _{t \downarrow 0} \vec{w}_{\imath}=\vec{u}(0)
\end{array}\right.
$$

where $\vec{A}^{\prime}(t) \vec{v} \in \mathscr{E}_{t}^{1}\left(\bar{R}^{+}\right)$. Thus there exists a unique solution $\vec{w}_{\iota} \in \mathscr{E}_{t}^{2}\left(\bar{R}^{+}\right)$. Since $\vec{u}_{\iota}(0), \vec{A}(t) \vec{v}_{\iota}$ converge in $\boldsymbol{C}^{N}, \mathscr{E}_{t}^{1}\left(\vec{R}^{+}\right)$to $\alpha, \vec{A}(t) \vec{v}$ respectively, $\vec{w}_{\iota}$ converges in $\mathscr{E}_{t}^{2}\left(\bar{R}^{+}\right)$to $\vec{w}$. Consequently $\vec{u}_{t}=D_{t} \vec{v}_{\iota}+\vec{w}_{\iota}$ converges in $\mathscr{E}_{t}^{0}\left(\bar{R}^{+}\right)$to $\vec{u}=D_{t} \vec{v}+\vec{w}$ and $\vec{u}$ satisfies $L \vec{u}=\vec{f}$ in $R^{+}$and $\vec{u}(0)=\vec{\alpha}$, completing the proof.

Consider the Cauchy problem

$$
\left\{\begin{array}{l}
L \vec{v}=\vec{h} \text { in } R,  \tag{33}\\
\vec{v}(0)=\vec{\alpha}
\end{array}\right.
$$

for any preasigned $\vec{\alpha} \in C^{N}$ and $\vec{h} \in \mathscr{D}^{\prime}(R)$, where $\vec{v}(0)$ is the value of $\vec{v}$ in the sense of S. Łojasiewicz. By Theorem 5 in [10, p. 392] and Theorem 14, if $\vec{h} \in \mathscr{D}^{\prime}(R)$ has no mass on $t=0$ and the restrictions $\vec{h}_{1}=\vec{h} \mid R^{+}$and $\vec{h}_{2}=\vec{h} \mid R^{-}$ have the canonical extensions $\vec{h}_{1 \sim}$ and $\vec{h}_{2}^{\sim}$ over $t=0$, then, owing to Theorem 5 in $\left[10\right.$, p. 392] and Theorem 14, there exists a unique solution $\vec{v} \in \mathscr{D}^{\prime}(R)$ of the Cauchy problem (33), and $\vec{v}_{1}=\vec{v}\left|R^{+}, \vec{v}_{2}=\vec{v}\right| R^{-}$satisfy the equations

$$
\begin{aligned}
L\left(\vec{v}_{1 \sim}\right) & =\vec{h}_{1 \sim}-i \vec{\alpha} \delta, \\
L\left(\vec{v}_{2}^{\tilde{2}}\right) & =\vec{h}_{2}^{\tilde{2}}+i \vec{\alpha} \delta,
\end{aligned}
$$

Thus we have the following
Theorem 15. Let $\left\{\vec{v}_{\iota}\right\}_{\iota \in I}$ be a directed set in $\mathscr{E}_{t}^{0}(R)$ and put $\vec{h}_{\iota}=L \vec{v}_{\iota}$ in $\mathscr{D}^{\prime}(R)$. If $\vec{h}_{\iota}$ can be written in the form $\vec{h}_{\iota}=D_{t} \vec{g}_{\iota}$, where $\vec{g}_{\iota} \in \mathscr{E}_{t}^{0}(R)$ and $\vec{g}_{\iota}(0)=0$, and if $\vec{v}_{\iota}(0)$, $\vec{g}_{،}$ converge in $\boldsymbol{C}^{N}, \mathscr{E}_{t}^{0}(R)$ to $\vec{\alpha}, \vec{g}$ respectively, then $\vec{v}_{\iota}$ converges in $\mathscr{E}_{t}^{0}(R)$ to $\vec{v}$ and $\vec{v}$ satisfies the equation $L \vec{v}=\vec{h}$ and $\vec{v}(0)=\vec{\alpha}$, where $\vec{h}=D_{t} \vec{g}$.

Let us again consider the differential operator $P(D)$. The discussions made for a system will allow to show the following

Theorem 16. Let $\left\{v_{\iota}\right\}_{\iota \in I}$ be a directed set in $\mathscr{E}_{t}^{0}(R)$ and put $h_{\iota}=P v_{\iota}$ in $\mathscr{D}^{\prime}(R)$. If the values $\left(v_{\iota}(0), D_{t} v_{\iota}(0), \cdots, D_{t}^{m-1} v_{\iota}(0)\right)=\vec{\alpha}_{\iota}$ exist and if $h_{\iota}$ can be written in the form $h_{\iota}=D_{t}^{l} g_{\iota}, 0 \leqq l \leqq m$, where $g_{\iota} \in \mathscr{E}_{t}^{0}(R)$ and $\left(g_{\iota}(0), D_{t} g_{\iota}(0)\right.$, $\left.\cdots, D_{t}^{l-1} g_{\iota}(0)\right)=0$, then $v_{\iota}$ belongs to the space $\mathscr{E}_{t}^{m-l}(R)$. If $\vec{\alpha}_{t}, g_{،}$ converge in $\boldsymbol{C}^{m}, \mathscr{E}_{t}^{0}(R)$ to $\vec{\alpha}, g$ respectively, then $v$, converges in $\mathscr{E}_{t}^{m-l}(R)$ to $v$ and $v$ satisfies the equation $P v=h$ and $\left(v(0), D_{t} v(0), \cdots, D_{t}^{m-1} v(0)\right)=\vec{\alpha}$.

Proof. Since the values $\left(g_{\imath}(0), \cdots, D_{t}^{l-1} g_{\iota}(0)\right)$ exist, $D_{t}^{j} g_{،}$ has no mass on $t=0$ and the restrictions $\left(D_{t}^{j} g_{i}\right)\left|R^{+},\left(D_{t}^{j} g_{\imath}\right)\right| R^{-}$have the canonical extensions over $t=0$ for each $j, 0 \leqq j \leqq l$. Put $v_{\iota}^{+}=v_{\iota}\left|R^{+}, v_{\iota}^{-}=v_{\iota}\right| R^{-}, h_{\iota}^{+}=h_{\iota} \mid R^{+}$and $h_{\iota}^{-}=$ $h_{\iota} \mid R^{-}$and consider the Cauchy problems

$$
\left\{\begin{array} { l } 
{ P v _ { \iota } ^ { + } = h _ { \iota } ^ { + } \quad \text { in } R ^ { + } , } \\
{ \operatorname { l i m } _ { t \downarrow 0 } ( v _ { \iota } ^ { + } , \ldots , D _ { t } ^ { m - 1 } v _ { \iota } ^ { + } ) = \vec { \alpha } _ { \iota } , }
\end{array} \quad \left\{\begin{array}{l}
P v_{\iota}^{-}=h_{\iota}^{-} \text {in } R^{-} \\
\lim _{t \uparrow 0}\left(v_{\iota}^{-}, \ldots, D_{t}^{m-1} v_{\iota}^{-}\right) \vec{\alpha}_{\iota}
\end{array}\right.\right.
$$

The reasonings made in the proofs of Propositions 30, 31 will show that $v_{\iota}=$ $v_{\iota}^{+}+v_{\iota}^{-} \in \mathscr{E}_{t}^{m-l}(R)$ and that $v_{\iota}$ converges in $\mathscr{E}_{t}^{m-l}(R)$ to $v$, which satisfies $P v=h$ and $\left(v(0), D_{t} v(0), \cdots, D_{t}^{m-l} v(0)\right)=0$. This completes the proof.

In closing this paper let us add a comment on the coerciveness considered in Section 6. Let us consider the operator $L=D_{t}+\vec{A}$, where $\vec{A}$ is an $N \times N$ matrix of convolution operators and $\vec{A} \in \mathrm{OP}_{r}, r>0$, and assume that $L$ is parabolic in the sense of I. G. Petrowski. If we let $\chi_{j}(\xi)$ be the characteristic roots of $\hat{\vec{T}}_{A}(\xi)$, where $\vec{A} \vec{u}=\vec{T}_{A} * \vec{u}$ with $\vec{u} \epsilon\left(\mathscr{D}_{L^{2}}^{\prime}\right)_{x}$, then there exist constants $C>0$ and $C_{0}$ such that

$$
\begin{equation*}
\operatorname{Im} x_{j}(\xi) \leqq-C|\xi|^{r}+C_{0}, \quad \xi \in \Xi_{n} . \tag{34}
\end{equation*}
$$

We shall show that $L$ satisfies the energy inequality (23) in Section 6.
The inequality (34) is equivalent to the inequality

$$
\begin{equation*}
\operatorname{Im} \chi_{j}(\xi) \leqq-C^{\prime}\left(1+|\xi|^{2}\right)^{r / 2}+C_{1} \tag{35}
\end{equation*}
$$

with constants $C^{\prime}>0$ and $C_{1}$. Let us consider an $N \times N$ matrix $\vec{B}=\left(\frac{i}{2} C^{\prime} S^{r}\right) \vec{E}$ with an $N \times N$ unit matrix $\vec{E}$. Then the operator $\tilde{L}=L+\vec{B}=D_{t}+\vec{A}$ is also parabolic. As noted in Section 4, $\tilde{L}$ is well posed in the $L^{2}$ norm. Owing to Corollary 3 in Section 4 it follows that there exists a positive definite Hermitian matrix $\vec{H}(\xi)$ such that

$$
-i\left(\vec{H}(\xi) \hat{\vec{T}}_{\hat{A}}(\xi)-\hat{\vec{T}}_{\vec{A}}^{*}(\xi) \vec{H}(\xi)\right) \leqq C_{2} \quad \text { a.e. on } \Xi_{n}
$$

with a constant $C_{2}$. Since $\hat{\vec{T}}_{\tilde{A}}(\xi)=\hat{\vec{T}}_{A}(\xi)+i \frac{C^{\prime}}{2}\left(1+|\xi|^{2}\right)^{r / 2}$, we have

$$
\begin{aligned}
\operatorname{Im}(\vec{H} L \vec{u}, \vec{u})= & -\frac{i}{2}\{(\vec{H} L \vec{u}, \vec{u})-(\vec{u}, \vec{H} L \vec{u})\} \\
= & -\frac{i}{2}\left(\left(\vec{H} \vec{A}-\vec{A}^{*} \vec{H}\right) \vec{u}, \vec{u}\right) \\
& \leqq C_{2}\|\vec{u}\|^{2}-C^{\prime}\left(\vec{H} \vec{u}, S^{r} \vec{u}\right) \\
= & C_{2}\|\vec{u}\|^{2}-C^{\prime}\left(\vec{H} S^{r / 2} \vec{u}, S^{r / 2} \vec{u}\right) \\
& \leqq C_{2}\|\vec{u}\|^{2}-C^{\prime \prime}\|\vec{u}\|_{(r / 2)}^{2}, \quad \vec{u} \in C_{0}^{\infty}\left(R_{n}\right)
\end{aligned}
$$

with a constant $C^{\prime \prime}$. In virtue of Proposition 22 we see that $L$ satisfies the energy inequality (23).

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