# ON NORMAL $(f, g, u, v, \lambda)$-STRUCTURES ON SUBMANIFOLDS OF CODIMENSION 2 IN AN EVEN-DIMENSIONAL EUCLIDEAN SPACE 

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## § 0. Introduction.

It is well known that a hypersurface of an almost Hermitian manifold admits an almost contact metric structure naturally induced on it.

The study of hypersurfaces of a Euclidean space and of a Kählerian manifold on which the induced almost contact metric structure satisfies certain conditions has been started by one of the present authors [4,5].

On the other hand Blair [1, 2], Goldberg [3], Ludden [1, 2], Yamaguchi [8] and the present authors [6,9] started the study of hypersurface of an almost contact manifold and of submanifolds of codimension 2 of an almost complex manifold.

These submanifolds admit, under certain conditions, what we call ( $f, g, u, v, \lambda$ )structure. An even-dimensional sphere of codimension 2 of an even-dimensional Euclidean space is a typical example of a manifold which admits this kind of structure.

In a previous paper [9], we have studied the $(f, g, u, v, \lambda)$-structure and given characterizations of even-dimensional sphere.

In the present paper, we study submanifolds of codimension 2 in an evendimensional Euclidean space which admit a normal ( $f, g, u, v, \lambda$ )-structure.

In §1, we consider submanifolds of codimension 2 of an even-dimensional Euclidean space regarded as a flat Kählerian manifold. In the next section, we deal with ( $f, g, u, v, \lambda$ )-structure induced on a submanifold of codimension 2 of an even-dimensional Euclidean space.

In $\S 3$, we find differential equations which $f, g, u, v$ and $\lambda$ satisfy. $\S 4$ is devoted to the study of relations between the structure equations of the submanifold and the induced ( $f, g, u, v, \lambda$ )-structure.

In $\S 5$ we prove a series of lemmas which are valid for normal ( $f, g, u, v, \lambda$ )structures and in $\S 6$ we study properties of the mean curvature vector of the submanifold with normal ( $f, g, u, v, \lambda$ )-structure.

In the last $\S 7$, we study hypersurfaces of an odd-dimensional Euclidean space and determine all the hypersurfaces admitting a normal ( $f, g, u, v, \lambda$ ) -structure.

Our main theorem appears at the end of $\S 7$.

[^0]
## § 1. Submanifolds of codimension 2 of an even-dimensional Euclidean space.

Let $E$ be a ( $2 n+2$ )-dimensional Euclidean space and denote by $X$ the position vector representing a point of $E$. Since $E$ is even-dimensional, $E$ can be regarded as a flat Hermitian manifold, and hence there exists a tensor field $F$ of type (1,1) with constant components such that

$$
\begin{equation*}
F^{2}=-I \tag{1.1}
\end{equation*}
$$

and

$$
\begin{equation*}
(F X) \cdot(F Y)=X \cdot Y \tag{1.2}
\end{equation*}
$$

for any vectors $X$ and $Y$, where $I$ denotes the identity transformation and a dot the inner product in the Euclidean space $E$.

We consider an orientable submanifold $M$ of codimension 2 of $E$ covered by a system of coordinate neighborhoods $\left\{U ; x^{h}\right\}$, where here and throughout the paper the indices $h, i, j, k, \cdots$ run over the range $\{1,2, \cdots, 2 n\}$.

We put

$$
\begin{equation*}
X_{i}=\partial_{i} X, \quad \partial_{i}=\partial / \partial x^{i}, \tag{1.3}
\end{equation*}
$$

then $X_{\imath}$ are $2 n$ linearly independent vector fields tangent to the submanifold $M$ and

$$
\begin{equation*}
g_{j i}=X_{j} \cdot X_{\imath} \tag{1.4}
\end{equation*}
$$

give components of the fundamental metric tensor of $M$ regarded as a Riemannian manifold referred to the coordinate system $\left\{U ; x^{h}\right\}$. We denote by $C$ and $D$ two mutually orthogonal unit normals to the submanifold $M$ such that $X_{v}, C, D$ form the positive orientation of $E$. Then we have

$$
\begin{align*}
X_{i} \cdot C=0, & X_{i} \cdot D=0 \\
C \cdot C=1, & C \cdot D=0, \quad D \cdot D=1 . \tag{1.5}
\end{align*}
$$

Now the vectors $X_{\imath}, C$ and $D$ being linearly independent, the transforms $F X_{2}$ of $X_{\imath}$ by $F$ can be expressed as

$$
F X_{i}=f_{i}{ }^{h} X_{h}+u_{i} C+v_{i} D,
$$

where $f_{\imath}{ }^{h}$ are components of a tensor field of type (1.1) and $u_{\imath}$ and $v_{i}$ are components of 1 -forms in $M$.

As to the transform $F C$ of $C$ by $F$, we have

$$
\begin{aligned}
(F C) \cdot X_{2} & =\left(F^{2} C\right) \cdot\left(F X_{2}\right)=-C \cdot\left(F X_{2}\right)=-u_{i}, \\
(F C) \cdot C & =\left(F^{2} C\right) \cdot(F C)=-C \cdot(F C)=0
\end{aligned}
$$

by virtue of (1.2) and consequently

$$
F C=-u^{h} X_{h}+\lambda D,
$$

where

$$
u^{h}=u_{i} g^{i n},
$$

$g^{i n}$ being contravariant components of the metric tensor and $\lambda$ a function of $M$.
As to the transform $F D$ of $D$ by $F$, we have

$$
\begin{aligned}
&(F D) \cdot X_{\imath}=\left(F^{2} D\right) \cdot\left(F X_{\imath}\right)=-D \cdot\left(F X_{2}\right)=-v_{i}, \\
&(F D) \cdot C=\left(F^{2} D\right) \cdot(F C)=-D \cdot(F C)=-\lambda, \\
&(F D) \cdot D=\left(F^{2} D\right) \cdot(F D)=-D \cdot(F D)=0,
\end{aligned}
$$

and consequently

$$
F D=-v^{h} X_{h}-\lambda C,
$$

where

$$
v^{h}=v_{i} g^{i h} .
$$

Thus we have

$$
F X_{i}=f_{i}{ }^{h} X_{h}+u_{i} C+v_{i} D,
$$

$$
\begin{align*}
& F C=-u^{h} X_{h}+\lambda D,  \tag{1.6}\\
& F D=-v^{h} X_{h}-\lambda C .
\end{align*}
$$

We note here that the 1 -forms $u_{i}$ and $v_{i}$ depend on the choice of unit normals $C$ and $D$ but the function $\lambda=(F C) \cdot D$ does not depend on the choice of $C$ and $D$. In fact, if we choose another set of mutually orthogonal unit normals $C^{\prime}$ and $D^{\prime}$, we have

$$
\begin{aligned}
& C^{\prime}=C \cos \theta-D \sin \theta, \\
& D^{\prime}=C \sin \theta+D \cos \theta,
\end{aligned}
$$

and consequently

$$
\begin{aligned}
\left(F C^{\prime}\right) \cdot D^{\prime} & =(F C \cos \theta-F D \sin \theta)(C \sin \theta+D \cos \theta) \\
& =(\lambda D \cos \theta+\lambda C \sin \theta)(C \sin \theta+D \cos \theta) \\
& =\lambda .
\end{aligned}
$$

## § 2. (f, $g, u, v, \lambda)$-structure on a submanifold of codimension 2.

Now applying the operator $F$ to the first equation of (1.6) and taking account of (1.6), we find

$$
\begin{gathered}
F^{2} X_{\imath}=f_{\imath}^{t} F X_{t}+u_{i} F C+v_{i} F D, \\
-X_{\imath}=f_{\imath}^{t}\left(f_{t}^{h} X_{h}+u_{t} C+v_{t} D\right)+u_{i}\left(-u^{h} X_{h}+\lambda D\right)+v_{i}\left(-v^{h} X_{h}-\lambda C\right),
\end{gathered}
$$

from which

$$
\begin{aligned}
& f_{\imath}^{t} f_{t}^{h}=-\delta_{i}^{h}+u_{i} u^{h}+v_{i} v^{h}, \\
& u_{t} f_{\imath}^{t}=\lambda v_{i}, \quad v_{t} f_{\imath}^{t}=-\lambda u_{i} .
\end{aligned}
$$

Applying the operator $F$ to the second equation of (1.6), we find

$$
\begin{gathered}
F^{2} C=-u^{i} F X_{i}+\lambda F D, \\
-C=-u^{i}\left(f_{i}^{h} X_{h}+u_{i} C+v_{i} D\right)+\lambda\left(-v^{h} X_{h}-\lambda C\right),
\end{gathered}
$$

from which

$$
f_{i}{ }^{h} u^{i}=-\lambda v^{h}, \quad u_{i} u^{i}=1-\lambda^{2}, \quad v_{i} u^{i}=0 .
$$

Applying also the operator $F$ to the last equation of (1.6), we find

$$
\begin{gathered}
F^{2} D=-v^{i} F X_{i}-\lambda F C \\
-D=-v^{i}\left(f_{i}^{h} X_{h}+u_{i} C+v_{i} D\right)-\lambda\left(-u^{h} X_{h}+\lambda D\right),
\end{gathered}
$$

from which

$$
f_{i}{ }^{h} v^{2}=\lambda u^{h}, \quad u_{i} v^{i}=0, \quad v_{i} v^{2}=1-\lambda^{2} .
$$

Thus summing up, we have

$$
\begin{gather*}
f_{i}^{t} f_{t}^{h}=-\delta_{i}^{h}+u_{i} u^{h}+v_{i} v^{h}, \\
u_{t} t_{2}{ }^{t}=\lambda v_{i}, \quad v_{t} f_{\imath}^{t}=-\lambda u_{i},  \tag{2.1}\\
f_{i}{ }^{h} u^{i}=-\lambda v^{h}, \quad f_{\imath}^{h} v^{i}=\lambda u^{h}, \\
u_{i} u^{2}=1-\lambda^{2}, \quad u_{i} v^{i}=0, \quad v_{i} v^{2}=1-\lambda^{2} .
\end{gather*}
$$

Now, substituting the first equation of (1.6) into

$$
\left(F X_{j}\right) \cdot\left(F X_{\imath}\right)=X_{j} \cdot X_{\imath},
$$

we find

$$
\left(f_{j}^{t} X_{t}+u_{j} C+v_{j} D\right)\left(f_{\imath}^{s} X_{s}+u_{i} C+v_{i} D\right)=g_{j i}
$$

that is,

$$
\begin{equation*}
f_{j}^{t} f_{i}^{s} g_{t s}=g_{j i}-u_{j} u_{i}-v_{j} v_{i} \tag{2.2}
\end{equation*}
$$

If we put

$$
\begin{equation*}
f_{i t}=f_{\imath}^{s} g_{t s} \tag{2.3}
\end{equation*}
$$

we find, from the first equation of (2.1),

$$
f_{j}^{t} f_{t i}=-g_{j i}+u_{j} u_{i}+v_{j} v_{i},
$$

and from (2.2)

$$
f_{j}^{t} f_{i t}=g_{j i}-u_{j} u_{i}-v_{j} v_{i} .
$$

From these two equations, we find

$$
\begin{equation*}
f_{j}^{t}\left(f_{t i}+f_{i t}\right)=0 \tag{2.4}
\end{equation*}
$$

Transvecting (2.4) with $f_{s}{ }^{3}$ and taking account of the first equation of (2.1), we find

$$
\left(-\delta_{s}^{t}+u_{s} u^{t}+v_{s} v^{t}\right)\left(f_{t i}+f_{i t}\right)=0
$$

from which

$$
\begin{equation*}
f_{s i}+f_{i s}=0 \tag{2.5}
\end{equation*}
$$

because of the second and the third equations of (2.1). Thus the tensor $f_{i t}$ defined by (2.3) is skew-symmetric.

We call an $(f, g, u, v, \lambda)$-structure the set of $f, g, u, v$, and $\lambda$ satisfying (2.1) and (2. 2).

## $\S 3$. Differential equations which $f, g, u, v$ and $\lambda$ satisfy.

We denote by $\left\{{ }_{j}{ }_{i}\right\}$ the Christoffel symbols formed with $g_{j i}$ and by $\nabla_{\imath}$ the operator of covariant differentiation with respect to $\left\{{ }_{j}{ }_{i}\right\}$. Then the equations of Gauss of $M$ are

$$
\nabla_{\jmath} X_{\imath}=\partial_{j} X_{\imath}-\left\{\begin{array}{c}
h  \tag{3.1}\\
j
\end{array}\right\} X_{h}=h_{j i} C+k_{j i} D
$$

where

$$
h_{j i}=h_{i j} \quad \text { and } \quad k_{j i}=k_{i j}
$$

are the second fundamental tensors of $M$ with respect to the normals $C$ and $D$ respectively.

The equations of Weingarten are

$$
\begin{equation*}
\nabla_{i} C=\partial_{i} C=-h_{i}{ }^{h} X_{h}+l_{i} D, \tag{3.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{i} D=\partial_{i} D=-k_{i}{ }^{h} X_{h}-l_{i} C, \tag{3.3}
\end{equation*}
$$

where

$$
\begin{equation*}
h_{i}{ }^{h}=h_{i t} g^{t h}, \quad k_{i}{ }^{h}=k_{i t} g^{t h} \tag{3.4}
\end{equation*}
$$

and $l_{2}$ are components of the third fundamental tensor with respect to the normals $C$ and $D$. The $l_{\imath}$ define the connection induced in the normal bundle of $M$.

Now applying the operator $\nabla_{\rho}$ of covariant differentiation to the first equation of (1.6) and taking account of $\nabla_{j} F=0$, we find

$$
\begin{gathered}
F \nabla_{j} X_{i}=\left(\nabla_{j} f_{i}^{h}\right) X_{h}+f_{i}{ }^{h} \nabla_{j} X_{h}+\left(\nabla_{j} u_{i}\right) C+u_{i}\left(\nabla_{j} C\right)+\left(\nabla_{j} v_{i}\right) D+v_{i}\left(\nabla_{j} D\right), \\
F\left(h_{j i} C+k_{j i} D\right)=\left(\nabla_{j} f_{i}^{h}\right) X_{h}+f_{i}^{t}\left(\nabla_{j} X_{t}\right)+\left(\nabla_{j} u_{i}\right) C+u_{i}\left(\nabla_{j} C\right)+\left(\nabla_{j} v_{i}\right) D+v_{i}\left(\nabla_{j} D\right),
\end{gathered}
$$

or

$$
\begin{aligned}
& h_{j i}\left(-u^{h} X_{h}+\lambda D\right)+k_{j i}\left(-v^{h} X_{h}-\lambda C\right) \\
= & \left(\nabla_{\jmath} f_{i}{ }^{h}\right) X_{h}+f_{i}^{t}\left(h_{j t} C+k_{j t} D\right)+\left(\nabla_{j} u_{i}\right) C+u_{i}\left(-h_{j}{ }^{h} X_{h}+l_{j} D\right)+\left(\nabla_{j} v_{i}\right) D+v_{i}\left(-k_{j}{ }^{h} X_{h}-l_{j} C\right),
\end{aligned}
$$

from which

$$
\begin{aligned}
\nabla_{J} f_{i}{ }^{h} & =-h_{j i} u^{h}+h_{j}{ }^{h} u_{i}-k_{j i} v^{h}+k_{j}{ }^{h} v_{i}, \\
\nabla_{j} u_{i} & =-h_{j t} f_{\imath}{ }^{t}-\lambda k_{j i}+l_{j} v_{i}, \\
\nabla_{j} v_{i} & =-k_{j t} f_{i}{ }^{t}+\lambda h_{j i}-l_{j} u_{i} .
\end{aligned}
$$

Applying the operator $\nabla_{2}$ to the second equation of (1.6), we find

$$
\begin{aligned}
F \nabla_{i} C & =-\left(\nabla_{i} u^{h}\right) X_{h}-u^{h} \nabla_{\imath} X_{h}+\left(\nabla_{i} \lambda\right) D+\lambda\left(\nabla_{i} D\right), \\
F\left(-h_{i}{ }^{h} X_{h}+l_{i} D\right) & =-\left(\nabla_{i} u^{h}\right) X_{h}-u^{h}\left(\nabla_{i} X_{h}\right)+\left(\nabla_{i} \lambda\right) D+\lambda\left(\nabla_{i} D\right),
\end{aligned}
$$

or

$$
\begin{aligned}
& -h_{i}{ }^{t}\left(f_{t}{ }^{h} X_{h}+u_{t} C+v_{t} D\right)+l_{i}\left(-v^{h} X_{h}-\lambda C\right) \\
= & -\left(\nabla_{i} u^{h}\right) X_{h}-u^{t}\left(h_{i t} C+k_{i t} D\right)+\left(\nabla_{i} \lambda\right) D+\lambda\left(-k_{i}{ }^{h} X_{h}-l_{i} C\right),
\end{aligned}
$$

from which

$$
\begin{aligned}
\nabla_{i} u^{h} & =h_{i}^{t} f_{t}^{h}-\lambda k_{i}^{h}+l_{i} v^{h}, \\
\nabla_{i} \lambda & =-h_{i}{ }^{t} v_{t}+k_{i t} u^{t} .
\end{aligned}
$$

Applying the operator $\nabla_{2}$ to the last equation of (1.6), we find

$$
\begin{aligned}
F \nabla_{i} D & =-\left(\nabla_{i} v^{h}\right) X_{h}-v^{t}\left(\nabla_{\imath} X_{t}\right)-\left(\nabla_{i} \lambda\right) C-\lambda\left(\nabla_{i} C\right), \\
F\left(-k_{i}^{t} X_{t}-l_{i} C\right) & =-\left(\nabla_{i} v^{h}\right) X_{h}-v^{t}\left(\nabla_{\imath} X_{t}\right)-\left(\nabla_{i} \lambda\right) C-\lambda\left(\nabla_{i} C\right),
\end{aligned}
$$

or

$$
\begin{aligned}
& -k_{i}{ }^{t}\left(f_{t}^{h} X_{h}+u_{t} C+v_{t} D\right)-l_{i}\left(-u^{h} X_{h}+\lambda D\right) \\
= & -\left(\nabla_{i} v^{h}\right) X_{h}-v^{t}\left(h_{i t} C+k_{i t} D\right)-\left(\nabla_{i} \lambda\right) C-\lambda\left(-h_{i}^{h} X_{h}+l_{i} D\right),
\end{aligned}
$$

from which

$$
\begin{aligned}
\nabla_{i} v^{h} & =k_{i}{ }^{t} f_{t}{ }^{h}+\lambda h_{i}{ }^{h}-l_{i} u^{h}, \\
\nabla_{i} \lambda & =-h_{i t} v^{t}+k_{i}^{t} u_{t} .
\end{aligned}
$$

Thus, summing up, we have

$$
\begin{align*}
\nabla_{j} f_{i}{ }^{h} & =-h_{j i} u^{h}+h_{j}{ }^{h} u_{i}-k_{j i} v^{h}+k_{j}{ }^{h} v_{i}, \\
\nabla_{j} u_{i} & =-h_{j t} f_{i}-\lambda k_{j i}+l_{j} v_{i}, \\
\nabla_{j} v_{i} & =-k_{j t} f_{i}{ }^{t}+\lambda h_{j i}-l_{j} u_{i},  \tag{3.5}\\
\nabla_{i} \lambda & =-h_{i t} v^{t}+k_{i t} u^{t} .
\end{align*}
$$

## $\S$ 4. Normal $(f, g, u, v, \lambda)$-structure.

We now compute

$$
\begin{equation*}
S_{j i}^{h}=N_{j i}^{h}+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h} \tag{4.1}
\end{equation*}
$$

where

$$
\begin{equation*}
N_{j i}^{h}=f_{j}{ }^{t} \nabla_{t} f_{i}^{h}-f_{\imath}^{t} \nabla_{t} f_{j}^{h}-\left(\nabla_{J} f_{2}^{t}-\nabla_{\imath} f_{j}^{t}\right) f_{t}^{h} \tag{4.2}
\end{equation*}
$$

is the Nijenhuis tensor formed with $f_{2}{ }^{h}$.
Substituting (3.5) into (4.1), we find

$$
\begin{aligned}
S_{j i}^{h}= & f_{j}{ }^{t}\left(-h_{t i} u^{h}+h_{t}{ }^{h} u_{i}-k_{t i} v^{h}+k_{t}{ }^{h} v_{i}\right) \\
& -f_{i}{ }^{t}\left(-h_{t j} u^{h}+h_{t}{ }^{h} u_{j}-k_{t j} v^{h}+k_{t}^{h} v_{j}\right) \\
& -\left(h_{j}{ }^{t} u_{i}-h_{i}{ }^{t} u_{j}+k_{j}{ }^{t} v_{i}-k_{i}{ }^{t} v_{j}\right) f_{t}^{h} \\
& -\left(h_{j t} f_{\imath}{ }^{t}-h_{i t} f_{j}^{t}-l_{j} v_{i}+l_{i} v_{j}\right) u^{h} \\
& -\left(k_{j t} f_{i}{ }^{t}-k_{i t} f_{j}{ }^{t}+l_{j} u_{i}-l_{i} u_{j}\right) v^{h},
\end{aligned}
$$

that is,

$$
\begin{align*}
S_{j i}{ }^{h}= & \left(f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{t}{ }^{h}\right) u_{i}-\left(f_{\imath}{ }^{t} h_{t}{ }^{h}-h_{i}{ }^{t} f_{t}{ }^{h}\right) u_{j} \\
& +\left(f_{j}{ }^{t} k_{t}{ }^{h}-k_{j}{ }^{t} f_{t}^{h}\right) v_{i}-\left(f_{\imath}{ }^{t} k_{t}{ }^{h}-k_{i}{ }^{t} f_{t}^{h}\right) v_{j}  \tag{4.3}\\
& +\left(l_{j} v_{i}-l_{i} v_{j}\right) u^{h}-\left(l_{j} u_{i}-l_{i} u_{j}\right) v^{h} .
\end{align*}
$$

When the tensor $S_{j i}{ }^{h}$ vanishes identically, the ( $f, g, u, v, \lambda$ )-structure is said to be normal.

Now the equations of Gauss of the submanifold $M$ are

$$
\begin{equation*}
K_{k j i}{ }^{h}=h_{k}{ }^{h} h_{j i}-h_{j}{ }^{h} h_{k i}+k_{k}{ }^{h} k_{j i}-k_{j}{ }^{h} k_{k v}, \tag{4.4}
\end{equation*}
$$

where

$$
K_{k j i^{h}}=\partial_{k}\left\{\begin{array}{c}
h \\
j
\end{array}\right\}-\partial_{j}\left\{\begin{array}{c}
h \\
k
\end{array}\right\}+\left\{\begin{array}{c}
h \\
k
\end{array}\right\}
$$

are components of the curvature tensor of $M$, the equations of Codazzi are

$$
\begin{align*}
& \nabla_{k} h_{j i}-\nabla_{j} h_{k i}-l_{k} k_{j i}+l_{j} k_{k i}=0, \\
& \nabla_{k} k_{j i}-\nabla_{j} k_{k i}+l_{k} h_{j i}-l_{j} h_{k i}=0, \tag{4.5}
\end{align*}
$$

and the equations of Ricci are

$$
\begin{equation*}
\nabla_{j} l_{i}-\nabla_{i} l_{j}+h_{j}{ }^{t} k_{t i}-h_{i}{ }^{t} k_{t \jmath}=0 \tag{4.6}
\end{equation*}
$$

In the sequel, we assume that the connection induced in the normal bundle of $M$ has no curvature, that is, we can choose $C$ and $D$ in such a way that we have $l_{2}=0$, and we say in this case that the connection induced in the normal bundle is trivial.

In this case, we have, from (4.5),

$$
\begin{equation*}
\nabla_{k} h_{j i}-\nabla_{j} h_{k i}=0, \quad \nabla_{k} k_{j i}-\nabla_{j} k_{k i}=0, \tag{4.7}
\end{equation*}
$$

which say that the tensors $\nabla_{k} h_{j i}$ and $\nabla_{k} k_{j i}$ are both symmetric in all the three indices, and, from (4. 6),

$$
\begin{equation*}
h_{\jmath}{ }^{t} k_{t i}-h_{i}{ }^{t} k_{t \jmath}=0, \tag{4.8}
\end{equation*}
$$

or

$$
\begin{equation*}
h_{\jmath}{ }^{t} k_{t}{ }^{i}-k_{\jmath}{ }^{t} h_{t}{ }^{i}=0, \tag{4.9}
\end{equation*}
$$

which says that $h_{i}{ }^{h}$ and $k_{i}{ }^{h}$ are commutative as linear transformations in the tangent space of $M$.

Now for the normal ( $f, g, u, v, \lambda$ )-structure of $M$ such that the connection induced in the normal bundle is trivial, we have, from (4.3),

$$
\begin{equation*}
\left(f_{j}^{t} h_{t}^{h}-h_{j}{ }^{t} f_{t}^{h}\right) u_{i}-\left(f_{i}{ }^{t} h_{t}^{h}-h_{i}{ }^{t} f_{t}{ }^{h}\right) u_{j}+\left(f_{j}{ }^{t} k_{t}{ }^{h}-k_{j}{ }^{t} f_{t}^{h}\right) v_{i}-\left(f_{l}{ }^{t} k_{t}{ }^{h}-k_{i}{ }^{t} f_{t}^{h}\right) v_{j}=0 . \tag{4.10}
\end{equation*}
$$

Since 1 -forms $u_{i}, v_{i}$ and $l_{i}$ depend on the choice of unit normals $C$ and $D$, the tensor $S_{j i}{ }^{h}$ also depends on the choice of the normals. However, the left hand side of (4.10) does not depend on the choice of $C$ and $D$. In fact, if we choose another set of mutually orthogonal unit normals $C^{\prime}$ and $D^{\prime}$, we have

$$
\begin{align*}
& C^{\prime}=C \cos \theta-D \sin \theta, \\
& D^{\prime}=C \sin \theta+D \cos \theta . \tag{4.11}
\end{align*}
$$

Then the second fundamental tensors $h_{j i}{ }^{\prime}$ and $k_{j i}{ }^{\prime}$ with respect to $C^{\prime}$ and $D^{\prime}$ are defined by

$$
\begin{equation*}
\nabla_{j} X_{i}=h_{j i}{ }^{\prime} C^{\prime}+k_{j i}{ }^{\prime} D^{\prime} . \tag{4.12}
\end{equation*}
$$

Substituting (4.11) into (4.12) and comparing the resulting equation with (3.1), we get

$$
\begin{align*}
& h_{j i}^{\prime}=h_{j i} \cos \theta-k_{j i} \sin \theta, \\
& k_{j i}^{\prime}=h_{j i} \sin \theta+k_{j i} \cos \theta . \tag{4.13}
\end{align*}
$$

On the other hand (4.11) and the first equation of (1.16) show that

$$
\begin{align*}
u_{i}^{\prime} & =u_{i} \cos \theta-v_{i} \sin \theta, \\
v_{i}^{\prime} & =u_{i} \sin \theta+v_{i} \cos \theta \tag{4.14}
\end{align*}
$$

Consequently we have

$$
\begin{aligned}
& \left(f_{j}^{t} h_{t}^{\prime h}-h_{j}^{\prime t} f_{t}^{h}\right) u_{i}^{\prime}-\left(f_{2}^{t} h_{t}^{\prime h}-h_{i}^{\prime t} f_{t}^{h}\right) u_{j}^{\prime}+\left(f_{j}^{t} k_{t}^{\prime h}-k_{j}^{\prime t} f_{t}^{h}\right) v_{i}^{\prime}-\left(f_{2}^{t} k_{t}^{\prime h}-k_{i}^{\prime t} f_{t}^{h}\right) v_{j}^{\prime} \\
& =\left(f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{t}{ }^{h}\right) u_{i}-\left(f_{i}{ }^{t} h_{t}{ }^{h}-h_{i}{ }^{t} f_{t}{ }^{h}\right) u_{j}+\left(f_{j}{ }^{t} k_{t}{ }^{h}-k_{j}{ }^{t} f_{t}{ }^{h}\right) v_{i}-\left(f_{2}{ }^{t} k_{t}{ }^{h}-k_{i}{ }^{t} f_{t}{ }^{h}\right) v_{j} .
\end{aligned}
$$

This shows that the conditions imposed on $M$ are of intrinsic character.

## § 5. Some lemmas on normal (f, $\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}, \lambda)$-structure.

As we have seen in $\S 4$, the condition imposed on the submanifold $M$ does not depend on the choice of unit normals $C$ and $D$.

The main purpose of the following discussions is to determine submanifolds of codimension 2 of $E$ which satisfy (4.10).

Assuming that the function $\lambda\left(1-\lambda^{2}\right)$ does not vanish almost everywhere on $M$, we prove following series of lemmas.

Lemma 5.1. For the normal ( $f, g, u, v, \lambda$ )-structure of $M$ such that the connection induced in the normal bundle is trivial, we have

$$
\begin{equation*}
f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{t}{ }^{h}=a u_{j} u^{h}+b\left(u_{j} v^{h}+v_{j} u^{h}\right)+c v_{j} v^{h} \tag{5.1}
\end{equation*}
$$

and

$$
\begin{equation*}
f_{j}{ }^{t} k_{t}{ }^{h}-k_{j}{ }^{t} f_{t}^{h}=b u_{j} u^{h}+c\left(u_{j} v^{h}+v_{j} u^{h}\right)+d v_{j} v^{h}, \tag{5.2}
\end{equation*}
$$

$a, b, c$, and $d$ being scalars of $M$.
Proof. We put

$$
\begin{equation*}
P_{j}{ }^{h}=f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{t}{ }^{h}, \quad Q_{j}{ }^{h}=f_{j}{ }^{t} k_{t}{ }^{h}-k_{j}{ }^{t} f_{t}{ }^{h} \tag{5.3}
\end{equation*}
$$

and note that

$$
\begin{equation*}
P_{j i}=f_{j}^{t} h_{t i}+f_{i}^{t} h_{t j}, \quad Q_{j i}=f_{j}^{t} k_{t i}+f_{i}^{t} k_{t j} \tag{5.4}
\end{equation*}
$$

are both symmetric with respect to $j$ and $i$.
Then equation (4.10) can be written as

$$
\begin{equation*}
P_{j}{ }^{h} u_{i}-P_{i}{ }^{h} u_{j}+Q_{j}{ }^{h} v_{i}-Q_{i}{ }^{h} v_{j}=0, \tag{5.5}
\end{equation*}
$$

from which, by transvection with $u^{i}$,

$$
P_{j}{ }^{h}\left(1-\lambda^{2}\right)-\left(P_{i}{ }^{h} u^{i}\right) u_{j}-\left(Q_{i}{ }^{h} u^{i}\right) v_{j}=0
$$

by virtue of (2.1), that is, $P_{j}{ }^{h}$ is of the form

$$
\begin{equation*}
P_{j}^{h}=u_{j} P^{h}+v_{j} Q^{h} \tag{5.6}
\end{equation*}
$$

and consequently $P_{j i}$ is of the form

$$
\begin{equation*}
P_{j i}=u_{j} P_{i}+v_{j} Q_{i} . \tag{5.7}
\end{equation*}
$$

Since $P_{j i}$ is symmetric, we have, from (5.7),

$$
\begin{equation*}
u_{j} P_{i}-u_{i} P_{j}+v_{j} Q_{i}-v_{i} Q_{j}=0, \tag{5.8}
\end{equation*}
$$

from which we see that $P_{\imath}$ must be of the form

$$
\begin{equation*}
P_{i}=a u_{i}+b v_{i} \tag{5.9}
\end{equation*}
$$

and $Q_{i}$ of the form

$$
\begin{equation*}
Q_{i}=d u_{i}+c v_{i} . \tag{5.10}
\end{equation*}
$$

Substituting (5.9) and (5.10) into (5.8), we find

$$
u_{j}\left(a u_{i}+b v_{i}\right)-u_{i}\left(a u_{j}+b v_{j}\right)+v_{j}\left(d u_{i}+c v_{i}\right)-v_{i}\left(d u_{j}+c v_{j}\right)=0,
$$

or

$$
(b-d)\left(u_{j} v_{i}-u_{i} v_{j}\right)=0 .
$$

from which, $u_{i}$ and $v_{i}$ being orthogonal to each other, we have

$$
b=d \text {, }
$$

and consequently we have

$$
P_{i}=a u_{i}+b v_{i}, \quad Q_{i}=b u_{i}+c v_{i},
$$

or

$$
P^{h}=a u^{h}+b v^{h}, \quad Q^{h}=b u^{h}+c v^{h} .
$$

Substituting these into (5.6), we obtain

$$
\begin{equation*}
P_{j}{ }^{h}=a u_{j} u^{h}+b\left(u_{j} v^{h}+v_{j} u^{h}\right)+c v_{j} v^{h} . \tag{5.11}
\end{equation*}
$$

Similarly, we have

$$
\begin{equation*}
Q_{j}{ }^{h}=\bar{a} u_{j} u^{h}+\bar{b}\left(u_{j} v^{h}+v_{j} u^{h}\right)+\bar{d} v_{j} v^{h} . \tag{5.12}
\end{equation*}
$$

Substituting these into (5.5), we find

$$
\left(u_{j} v_{i}-u_{i} v_{j}\right)\left\{(b-\bar{a}) u^{h}+(c-\bar{b}) v^{h}\right\}=0
$$

from which

$$
\begin{equation*}
\bar{a}=b, \quad \bar{b}=c . \tag{5.13}
\end{equation*}
$$

Equations (5.11), (5.12) and (5.13) prove the lemma.
Lemma 5.2. For the normal ( $f, g, u, v, \lambda$ )-structure of $M$ such that the connection induced in the normal bundle is trivial, we have

$$
\begin{array}{ll}
h_{i}{ }^{h} u^{i}=\alpha u^{h}+\beta v^{h}, & h_{i}{ }^{h} v^{i}=\beta u^{h}+\gamma v^{h}, \\
k_{i}{ }^{h} u^{2}=\bar{\alpha} u^{h}+\bar{\beta} v^{h}, & k_{i}{ }^{h} v^{2}=\bar{\beta} u^{h}+\bar{\gamma} v^{h} . \tag{5.14}
\end{array}
$$

Proof. Transvecting (5.1) with $f_{k^{3}}$, we find

$$
\left(-\delta_{k}^{t}+u_{k} u^{t}+v_{k} v^{t}\right) h_{t}{ }^{h}-f_{k}{ }^{j} h_{j}{ }^{t} f_{t}^{h}=a \lambda v_{k} u^{h}+b \lambda\left(v_{k} v^{h}-u_{k} u^{h}\right)-c \lambda u_{k} v^{h}
$$

by virtue of (2.1), or

$$
-h_{k h}+u_{k}\left(u^{t} h_{t h}\right)+v_{k}\left(v^{t} h_{t h}\right)+h_{t s} f_{k}^{t} f_{h}^{s}=a \lambda v_{k} u_{h}+b \lambda\left(v_{k} v_{h}-u_{k} u_{h}\right)-c \lambda u_{k} v_{h},
$$

from which, taking the skew-symmetric part,

$$
u_{k}\left(u^{t} h_{t h}\right)-u_{h}\left(u^{t} h_{t k}\right)+v_{k}\left(v^{t} h_{t h}\right)-v_{h}\left(v^{t} h_{t k}\right)=-\lambda(a+c)\left(u_{k} v_{h}-u_{h} v_{k}\right)
$$

This equation shows that $u^{t} h_{t h}$ and $v^{t} h_{t h}$ should be respectively of the form

$$
u^{t} h_{t h}=\alpha u_{h}+\beta v_{h}, \quad v^{t} h_{t h}=\beta u_{h}+\gamma v_{h},
$$

that is,

NORMAL $(f, g, u, v, \lambda)$-STRUCTURES

$$
h_{i}{ }^{h} u^{\imath}=\alpha u^{h}+\beta v^{h}, \quad h_{i}{ }^{h} v^{\imath}=\beta u^{h}+\gamma v^{h} .
$$

The other two equations will be proved in a similar way. We note here that $\alpha, \beta, \gamma$ and $\bar{\alpha}, \bar{\beta}, \bar{\gamma}$ are given by

$$
\begin{array}{lll}
\left(1-\lambda^{2}\right) \alpha=h_{j i} u^{\jmath} u^{2}, & \left(1-\lambda^{2}\right) \beta=h_{j i} u^{\jmath} v^{2}, & \left(1-\lambda^{2}\right) \gamma=h_{j i} v^{v} v^{2}, \\
\left(1-\lambda^{2}\right) \bar{\alpha}=k_{j i} u^{\jmath} u^{2}, & \left(1-\lambda^{2}\right) \bar{\beta}=k_{j i} u^{\jmath} v^{2}, & \left(1-\lambda^{2}\right) \bar{\gamma}=h_{j i} v^{v} v^{2} .
\end{array}
$$

Lemma 5.3. In Lemma 5. 2, we have

$$
\begin{equation*}
2 \beta=\bar{\alpha}-\bar{\gamma}, \quad 2 \bar{\beta}=\gamma-\alpha . \tag{5.15}
\end{equation*}
$$

Proof. In (4.10), we contract with respect ot $h$ and $i$, then we obtain

$$
\begin{equation*}
f_{J}^{t}\left(h_{t}{ }^{2} u_{i}\right)-h_{J}{ }^{t}\left(f_{t}{ }^{2} u_{i}\right)+f_{J}{ }^{t}\left(k_{t}{ }^{2} v_{i}\right)-k_{J}{ }^{t}\left(f_{t}{ }^{v} v_{i}\right)=0 \tag{5.16}
\end{equation*}
$$

because of

$$
f_{\imath}^{t} h_{t}{ }^{2}=f^{i t} h_{t i}=0, \quad f_{\imath}^{t} k_{t}{ }^{2}=f^{i t} k_{t i}=0
$$

Substituting (2.1) and (5.14) into (5.16), we find

$$
f_{j}{ }^{t}\left(\alpha u_{t}+\beta v_{t}\right)-\lambda h_{j}{ }^{2} v_{t}+f_{j}\left(\bar{\beta} u_{t}+\bar{\gamma} v_{t}\right)+\lambda k_{j}{ }^{t} u_{t}=0,
$$

and consequently

$$
\alpha \lambda v_{j}-\beta \lambda u_{j}-\lambda\left(\beta u_{j}+\gamma v_{j}\right)+\bar{\beta} \lambda v_{j}-\bar{\gamma} \lambda u_{j}+\lambda\left(\bar{\alpha} u_{j}+\bar{\beta} v_{j}\right)=0,
$$

or

$$
-\lambda(2 \beta+\bar{\gamma}-\bar{\alpha}) u_{j}+\lambda(2 \bar{\beta}+\alpha-\gamma) v_{j}=0,
$$

from which

$$
2 \beta=\bar{\alpha}-\bar{\gamma}, \quad 2 \bar{\beta}=\gamma-\alpha .
$$

Lemma 5.4. In Lemma 5.2, we have

$$
\begin{equation*}
\beta=0, \quad \bar{\beta}=0 \tag{5.17}
\end{equation*}
$$

and consequently

$$
\alpha=\gamma, \quad \bar{\alpha}=\bar{\gamma} .
$$

Proof. Transvecting the first equation

$$
h_{i}{ }^{h} w^{2}=\alpha u^{h}+\beta v^{h}
$$

of (5.14) with $k_{h}{ }^{t}$ and using (5.14), we obtain

$$
\begin{aligned}
k_{h}{ }^{t} h_{i}{ }^{h} u^{2} & =\alpha\left(\bar{\alpha} u^{t}+\bar{\beta} v^{t}\right)+\beta\left(\bar{\beta} u^{t}+\bar{\gamma} v^{t}\right), \\
& =(\alpha \bar{\alpha}+\beta \bar{\beta}) u^{t}+(\alpha \bar{\beta}+\beta \bar{\gamma}) v^{t} .
\end{aligned}
$$

Also transvecting the third equation

$$
k_{i}{ }^{h} u^{2}=\bar{\alpha} u^{h}+\bar{\beta} v^{h}
$$

of (5.14) with $h_{h}{ }^{t}$ and using (5.14), we obtain

$$
\begin{aligned}
h_{h}{ }^{t} k_{i}{ }^{h} u^{i} & =\bar{\alpha}\left(\alpha u^{t}+\beta v^{t}\right)+\bar{\beta}\left(\beta u^{t}+\gamma v^{t}\right) \\
& =(\alpha \bar{\alpha}+\beta \bar{\beta}) u^{t}+(\bar{\alpha} \beta+\bar{\beta} \gamma) v^{t} .
\end{aligned}
$$

Thus, $h_{i}{ }^{h}$ and $k_{i}{ }^{h}$ being commutative,

$$
\alpha \bar{\beta}+\beta \bar{\gamma}=\bar{\alpha} \beta+\bar{\beta} \gamma,
$$

or

$$
(\gamma-\alpha) \bar{\beta}+(\bar{\alpha}-\bar{\gamma}) \beta=0
$$

or using (5.15),

$$
2 \bar{\beta}^{2}+2 \beta^{2}=0,
$$

from which the lemma follows.
Combining Lemma 5. 2 and Lemma 5.4, we have
Lemma 5.5. For the normal ( $f, g, u, v, \lambda$ )-structure of $M$ such that the connection induced in the normal bundle is trivial, we have

$$
\begin{array}{ll}
h_{i}{ }^{h} u=\alpha u^{h}, & h_{i}{ }^{h} v^{2}=\alpha v^{h}, \\
k_{i}{ }^{h} u^{i}=\bar{\alpha} u^{h}, & k_{i}{ }^{h} v^{2}=\bar{\alpha} v^{h} . \tag{5.18}
\end{array}
$$

We also have
Lemma 5.6. For the normal ( $f, g, u, v, \lambda$ )-structure of $M$ such that the connection induced in the normal bundle is trivial, $h_{i}{ }^{h}$ and $k_{i}{ }^{h}$ commute with $f_{i}{ }^{h}$.

Proof. Transvecting (4.10) with $u^{i}$ and using (2.1) and (5.18), we obtain

$$
\left(f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{t}{ }^{h}\right)\left(1-\lambda^{2}\right)+\left(\lambda h_{t}{ }^{h} v^{t}+\alpha f_{t}{ }^{h} u^{t}\right) u_{j}+\left(\lambda k_{t}{ }^{h} v^{t}+\bar{\alpha} f_{t}{ }^{h} u^{t}\right) v_{j}=0,
$$

or

$$
\left(f_{J}{ }^{t} h_{t}{ }^{h}-h_{J}{ }^{t} f_{t}^{h}\right)\left(1-\lambda^{2}\right)=0,
$$

that is,

$$
f_{J}{ }^{t} h_{t}{ }^{h}=h_{J}{ }^{t} f_{t}{ }^{h} .
$$

Similarly we can prove

$$
f_{J}{ }^{t} k_{t}{ }^{h}=k_{J}{ }^{t} f_{t}{ }^{h} .
$$

Lemma 5.7. For the normal ( $f, g, u, v, \lambda$ )-structure of $M$ such that the connection induced in the normal bundle is trivial, we have

$$
\begin{equation*}
h_{i}{ }^{t} h_{t}{ }^{h}=\alpha h_{i}{ }^{h}, \quad k_{i}{ }^{t} k_{t}{ }^{h}=\bar{\alpha} k_{i}{ }^{h} . \tag{5.19}
\end{equation*}
$$

Proof. Differentiating

$$
h_{j i} u^{i}=\alpha u_{j}
$$

covariantly, we obtain

$$
\left(\nabla_{k} h_{j i}\right) u^{2}+h_{j i}\left(\nabla_{k} u^{i}\right)=\left(\nabla_{k} \alpha\right) u_{j}+\alpha\left(\nabla_{k} u_{j}\right),
$$

or using (3.5)

$$
\left(\nabla_{k} h_{j i}\right) u^{2}+h_{j i}\left(h_{k}{ }^{t} f_{t}{ }^{2}-\lambda k_{k}{ }^{i}\right)=\left(\nabla_{k} \alpha\right) u_{j}+\alpha\left(-h_{k t} f_{j}^{t}-\lambda k_{k j}\right)
$$

and consequently taking skew-symmetric part

$$
h_{j i} h_{k}{ }^{t} f_{t}{ }^{2}-h_{k i} h_{j}{ }^{t} f_{t}{ }^{2}=\left(\nabla_{k} \alpha\right) u_{j}-\left(\nabla_{j} \alpha\right) u_{k}-\alpha h_{k t} f_{j}+\alpha h_{j t} J_{k}{ }^{t}
$$

because of

$$
\nabla_{k} h_{j i}-\nabla_{j} h_{k i}=0, \quad h_{j i} k_{k}{ }^{2}=h_{k i} k_{j}{ }^{2}
$$

But $h_{k}{ }^{t}$ and $f_{t}{ }^{2}$ commute and consequently

$$
\begin{equation*}
2 h_{j i} h_{k}{ }^{t} f_{t}{ }^{2}=\left(\nabla_{k} \alpha\right) u_{j}-\left(\nabla_{j} \alpha\right) u_{k}-2 \alpha h_{k t} f_{j}^{t}, \tag{5.20}
\end{equation*}
$$

from which, transvecting with $u^{k}$,

$$
2 h_{j i} \alpha u^{t} f_{t^{2}}=\left(u^{k} \nabla_{k} \alpha\right) u_{j}-\left(\nabla_{j} \alpha\right)\left(1-\lambda^{2}\right)-2 \alpha^{2} u_{t} f_{j}^{\prime},
$$

or

$$
-2 \alpha \lambda h_{j i} v^{2}=\left(u^{k} \nabla_{k} \alpha\right) u_{j}-\left(\nabla_{j} \alpha\right)\left(1-\lambda^{2}\right)-2 \alpha^{2} \lambda v_{j}
$$

that is,

$$
\begin{equation*}
\left(\nabla_{j} \alpha\right)\left(1-\lambda^{2}\right)=\left(u^{k} \nabla_{k} \alpha\right) u_{j} . \tag{5.21}
\end{equation*}
$$

Thus, $\nabla_{j} \alpha$ being proportional to $u_{j}$, we find from (5.20)

$$
h_{j i} h_{k}{ }^{t} f_{t}{ }^{2}=-\alpha h_{k t} f_{j}^{t},
$$

or

$$
h_{j i} f_{k}^{t} h_{t}{ }^{i}=\alpha h_{j t} f_{k}^{t},
$$

since $h_{k}{ }^{t}$ and $f_{t}{ }^{2}$ commute.
Transvecting this equation with $f_{h}{ }^{k}$, we find

$$
\left(h_{j i} h_{t}{ }^{i}\right)\left(-\delta_{h}^{t}+u_{h} u^{t}+v_{h} v^{t}\right)=\alpha h_{j t}\left(-\delta_{h}^{t}+u_{h} u^{t}+v_{h} v^{t}\right),
$$

or using (5.18)

$$
h_{j i} h_{h}{ }^{2}=\alpha h_{j h},
$$

or

$$
h_{i}{ }^{t} h_{t}{ }^{h}=\alpha h_{i}{ }^{h} .
$$

Similarly, we can prove

$$
k_{i}{ }^{t} k_{t}{ }^{h}=\bar{\alpha} k_{i}{ }^{h} .
$$

Lemma 5. 8. In Lemma 5.5 and Lemma 5.7, $\alpha$ and $\bar{\alpha}$ are both constants.
Proof. Differentiating the second equation of (5.18) covariantly and taking account of (3.5), we find

$$
\left(\nabla_{j} h_{i}{ }^{h}\right) v_{h}-h_{i}{ }^{h}\left(k_{j t} f_{h}{ }^{t}-\lambda h_{j h}\right)=\left(\nabla_{j} \alpha\right) v_{i}-\alpha\left(k_{j t} f_{i}{ }^{t}-\lambda h_{j i}\right),
$$

from which, taking the skew-symmetric part

$$
h_{j}{ }^{h} k_{i t} f_{h}{ }^{t}-h_{i}{ }^{h} k_{j t} f_{h}{ }^{t}=\left(\nabla_{j} \alpha\right) v_{i}-\left(\nabla_{i} \alpha\right) v_{j}+\alpha\left(k_{i t} f_{j}{ }^{t}-k_{j t} f_{i}{ }^{t}\right),
$$

because of the equation of Codazzi (4.7).
Transvecting the above equation with $v^{3}$ and making use of (2.1) and (5.18), we obtain

$$
\begin{equation*}
\left(1-\lambda^{2}\right) \nabla_{j} \alpha=\left(v^{k} \nabla_{k} \alpha\right) v_{j} . \tag{5.22}
\end{equation*}
$$

Thus, $\nabla_{j} \alpha$ is proportional to $v_{j}$, but (5.21) shows that $\nabla_{j} \alpha$ is proportional to $u_{j}$. $u_{\jmath}$ and $v_{\jmath}$ being orthogonal to each other, we have $\nabla_{j} \alpha=0$ and hence $\alpha=$ const.

## §6. The mean curvature vector.

The mean curvature vector of the submanifold $M$ is defined to be

$$
\begin{equation*}
\frac{1}{2 n} g^{j i} \nabla_{j} X_{\imath}=\frac{1}{2 n} h_{i}{ }^{2} C+\frac{1}{2 n} k_{i}{ }^{i} D \tag{6.1}
\end{equation*}
$$

and the mean curvature $H$ of the submanifold $M$ is defined to be the length of the mean curvature vector, that is,

$$
\begin{equation*}
H^{2}=\frac{1}{4 n^{2}}\left[\left(h_{i}\right)^{2}+\left(k_{i}\right)^{2}\right] . \tag{6.2}
\end{equation*}
$$

If the mean curvature vector vanishes identically on $M$, then $M$ is said to be minimal.

A necessary and sufficient condition for $M$ to be minimal is that

$$
\begin{equation*}
h_{i}{ }^{2}=0, \quad k_{i}{ }^{i}=0 . \tag{6.3}
\end{equation*}
$$

We have
Lemma 6.1. Suppose that the submanifold $M$ is such that the connection induced in the normal bundle is trivial and the ( $f, g, u, v, \lambda$ )-structure induced on $M$ is normal. Then the mean curvature of $M$ is constant.

Proof. Let $\alpha^{\prime}$ be an eigenvalue of $h_{i}{ }^{h}$ at a point of $M$ and $p^{2}$ the eigenvector corresponding to $\alpha^{\prime}$ at the point. Then we have

$$
h_{i}{ }^{h} p^{i}=\alpha^{\prime} p^{h}
$$

Applying this $h_{h}{ }^{3}$ and taking account of (5.19), we find

$$
\alpha \alpha^{\prime} p^{\jmath}=\alpha^{\prime 2} p^{\jmath}
$$

from which

$$
\alpha^{\prime}=\alpha \quad \text { or } \quad \alpha^{\prime}=0 .
$$

Thus the only eigenvalue of ${h_{i}}^{h}$ is $\alpha$ or 0 . Moreover, by Lemma 5.8, $\alpha$ being constant, the eigenvalues of $h_{i}{ }^{h}$ are constant.

Similarly we can show that $k_{i}{ }^{h}$ has only two constant eigenvalues $\bar{\alpha}$ and 0 .
Now, let $r$ and $s$ be multiplicities of the eigenvalues $\alpha$ of $h_{i}{ }^{h}$ and of $\bar{\alpha}$ of $k_{i}{ }^{h}$ respectively. Then, $\alpha$ and $\bar{\alpha}$ being constant, $r$ and $s$ are also constant. So we have

$$
h_{i}{ }^{2}=r \alpha, \quad k_{i}{ }^{2}=s \bar{\alpha} .
$$

Substituting this into (6. 2), we obtain

$$
\begin{equation*}
H^{2}=\frac{1}{4 n^{2}}\left(r^{2} \alpha^{2}+s^{2} \bar{\alpha}^{2}\right)=\text { const. } \tag{6.4}
\end{equation*}
$$

This lemma shows that, in the sequel, we have to consider only two cases. One of these is the case where the submanifold is minimal and the another is the case where the mean curvature vector does not vanish everywhere on $M$.

Suppose first that the submanifold $M$ is minimal. Then from Lemma 5.7 we find

$$
h_{j i} h^{j i}=0, \quad k_{j i} k^{j i}=0,
$$

from which

$$
\begin{equation*}
h_{j i}=0, \quad k_{j i}=0 . \tag{6.5}
\end{equation*}
$$

Thus equations of Weingarten give

$$
\nabla_{j} C=0, \quad \nabla_{j} D=0,
$$

and consequently, the unit normals $C$ and $D$ being constant vectors, $M$ is a $2 n$ dimensional plane. Thus we have

Theorem 6.1. Let $M$ of codimension 2 of $E$ be such that the connection induced on the normal bundle of $M$ is trivial and the ( $f, g, u, v, \lambda$ )-structure on $M$ is normal. If $M$ is minimal, then $M$ is a plane of codimension 2.

Suppose next that the mean curvature vector does not vanish everywhere on $M$, and choose the first unit normal $C$ along the direction of the mean curvature vector and choose the second unit normal $D$ in such a way that $X_{i}, C, D$ form the positive orientation of $E$.

Then the 1 -forms $u_{i}$ and $v_{i}$ are completely determined when $M$ is given. We say that such an ( $f, g, u, v, \lambda$ )-structure is intrinsic.

Since the first unit normal $C$ is chosen in the direction of the mean curvature vector, we see, from (6.1), that

$$
\begin{equation*}
k_{i}{ }^{i}=0 . \tag{6.6}
\end{equation*}
$$

Thus if $M$ is such that the connection induced in the normal bundle is trivial and the ( $f, g, u, v, \lambda$ )-structure induced on $M$ is normal, then we have, from (5.19),

$$
k_{j i} k^{j i}=0,
$$

from which

$$
\begin{equation*}
k_{j i}=0 . \tag{6.7}
\end{equation*}
$$

Thus, equations of Gauss and Weingarten become respectively

$$
\nabla_{j} X_{i}=h_{j i} C, \quad \nabla_{j} C=-h_{j}{ }^{h} X_{h} \quad \nabla_{j} D=0,
$$

from which $D$ is a constant vector and consequently

$$
\nabla_{j}(X \cdot D)=0,
$$

that is,

$$
X \cdot D=\text { const }
$$

which shows that $M$ lies in a ( $2 n+1$ )-dimensional plane. Thus we have

Theorem 6.2. Let $M$ of codimension 2 be such that the connection induced in the normal bundle of $M$ is trivial and the mean curvature vector does not vanish everywhere. If the ( $f, g, u, v, \lambda$ )-structure induced on $M$ is normal, then there exists a (2n+1)-dimensional plane $E^{2 n+1}$ such that $M$ is a hypersurface of it.

## § 7. Hypersurfaces of an odd-dimensional Euclidean space.

By theorem 6.2, there exists a $(2 n+1)$-dimensional plane $E^{\prime}$ such that the submanifold $M$ under consideration is a hypersurface of it. So, in this section, we regard $M$ as a hypersurface of a $(2 n+1)$-dimensional Euclidean space $E^{\prime}$, which is of course in a ( $2 n+2$ )-dimensional Euclidean space $E$.

We consider a linear coordinate system in $E^{\prime}$ consisting of $2 n+1$ linearly independent vectors $E_{\lambda}, E_{\lambda}$ and $D$ forming a linear coordinate system of $E$, where here and in the sequel the indices $\kappa, \lambda, \mu, \nu, \cdots$ run over the range $\{1,2, \cdots, 2 n+1\}$. We put

$$
\begin{equation*}
g_{\mu \lambda}=E_{\mu} \cdot E_{\lambda}, \tag{7.1}
\end{equation*}
$$

all the $g_{\mu \lambda}$ being constant. We also have

$$
\begin{equation*}
E_{\lambda} \cdot D=0 . \tag{7.2}
\end{equation*}
$$

Now, $F$ being a complex structure of the ( $2 n+2$ )-dimensional Euclidean space $E$, we can put

$$
\begin{align*}
F E_{\lambda} & =\varphi_{k}{ }^{\mu} E_{\mu}+\eta_{2} D, \\
F D & =-\eta^{\mu} E_{\mu}, \tag{7.3}
\end{align*}
$$

where

$$
\begin{equation*}
\eta^{s}=\eta_{2} g^{2 x}, \tag{7.4}
\end{equation*}
$$

$g^{\lambda_{k}}$ being contravariant components of $g_{\mu \lambda}$.
From the first equation of (7.3), we find

$$
F^{2} E_{\lambda}=\varphi_{\lambda}{ }^{\mu}\left(\varphi_{\mu}{ }^{k} E_{\kappa}+\eta_{\mu} D\right)-\eta_{\lambda} \eta^{k} E_{\kappa},
$$

from which, $F^{2}$ being equal to $-I$,

$$
\begin{aligned}
\varphi_{2}^{\mu} \varphi_{\mu}{ }^{k} & =-\delta_{\lambda}^{E}+\eta_{\lambda} \eta^{k}, \\
\varphi_{\lambda}{ }^{\mu} \eta_{\mu} & =0 .
\end{aligned}
$$

From the second equation of (7.3), we find

$$
F^{2} D=-\eta^{2}\left(\varphi_{k}{ }^{\kappa} E_{k}+\eta_{\lambda} D\right),
$$

from which

$$
\varphi_{2}{ }^{\kappa} \eta^{2}=0, \quad \eta_{\lambda} \eta^{2}=1 .
$$

Moreover, from the first equation of (7.3), we have

$$
\left(F E_{\mu}\right) \cdot\left(F E_{\lambda}\right)=\left(\varphi_{\mu}{ }^{\nu} E_{\nu}+\eta_{\mu} D\right) \cdot\left(\varphi_{k}{ }^{{ }^{k}} E_{k}+\eta_{\lambda} D\right),
$$

from which, $\left(F E_{\mu}\right) \cdot\left(F E_{\lambda}\right)$ being equal to $E_{\mu} \cdot E_{\lambda}=g_{\mu \lambda}$,

$$
g_{\mu \lambda}=\varphi_{\mu}{ }_{\mu} \varphi_{\lambda}{ }_{\lambda}{ }^{5} g_{\nu \kappa}+\eta_{\mu} \eta_{\lambda .} .
$$

Summing up, we have

$$
\begin{align*}
\varphi_{\lambda}{ }^{\mu} \varphi_{\mu}{ }^{k} & =-\delta_{\lambda}^{k}+\eta_{\lambda} \eta^{k}, \\
\varphi_{2}{ }^{\mu} \eta_{\mu} & =0, \quad \varphi_{\lambda}{ }^{k}{ }^{k}{ }^{2}=0, \quad \eta_{\lambda} \eta^{2}=1,  \tag{7.5}\\
\varphi_{\mu}{ }^{2} \varphi_{\lambda}{ }^{k} g_{\nu k} & =g_{\mu \lambda}-\eta_{\mu} \eta_{\lambda},
\end{align*}
$$

that is, $\left(\varphi_{\alpha}{ }^{k}, \eta_{\lambda}, g_{\mu \lambda}\right)$ defines an almost contact metric structure of the $(2 n+1)$ dimensional Euclidean space $E^{\prime}$.

Now we consider a $2 n$-dimensional submanifold $M$ in $E^{\prime}$ in $E$ and represent it by the position vector

$$
X=X(x)=X^{\kappa}(x) E_{\mathrm{k}},
$$

the origin of the coordinate system being on $E^{\prime}$.
The vectors $X_{2}$ tangent to $M$ and the unit normal vector $C$ to $M$ can be expressed as

$$
\begin{equation*}
X_{i}=B_{i}{ }^{\kappa} E_{\mathrm{k}}, \quad C=C^{\mathrm{k}} E_{\mathrm{x}}, \tag{7.6}
\end{equation*}
$$

respectively, where

$$
B_{i}{ }^{\varepsilon}=\partial_{i} X^{k}
$$

Applying the operator $F$ to the both sides of the first equation of (7.6), we find

$$
\begin{gathered}
F X_{\imath}=B_{i}{ }^{\kappa} F E_{k}, \\
f_{\imath}{ }^{h} X_{h}+u_{i} C+v_{i} D=B_{i}{ }^{\lambda}\left(\varphi_{\imath}{ }^{\kappa} E_{k}+\eta_{\lambda} D\right),
\end{gathered}
$$

or

$$
f_{\imath}{ }^{h} B_{h}{ }^{\kappa} E_{k}+u_{i} C^{\kappa} E_{k}+v_{i} D=B_{i}{ }^{2}\left(\varphi_{k}{ }^{\kappa} E_{k}+\eta_{k} D\right)
$$

by virtue of (1.6), (7.3) and (7.6), from which

$$
\begin{aligned}
\varphi_{\lambda}{ }^{\kappa} B_{i}{ }^{2} & =f_{i}{ }^{h} B_{h}{ }^{\kappa}+u_{i} C^{\kappa}, \\
\eta_{\lambda} B_{i}{ }^{2} & =v_{i} .
\end{aligned}
$$

Applying the operator $F$ to the both sides of the second equation of (7.6), we find

$$
\begin{gathered}
F C=C^{\lambda} F E_{\lambda}, \\
-u^{i} X_{i}+\lambda D=C^{\lambda}\left(\varphi_{\lambda}{ }^{k} E_{k}+\eta_{\lambda} D\right),
\end{gathered}
$$

or

$$
-u^{i}\left(B_{i}{ }^{\kappa} E_{k}\right)+\lambda D=C^{\lambda}\left(\varphi_{\lambda}{ }^{\kappa} E_{k}+\eta_{\lambda} D\right),
$$

by virtue of (1.6), (7.3) and (7.6), from which

$$
\begin{aligned}
\varphi_{\lambda}{ }^{*} C^{\lambda} & =-u^{i} B_{i}{ }^{\kappa}, \\
\eta_{\lambda} C^{2} & =\lambda .
\end{aligned}
$$

Summing up, we have

$$
\varphi_{2}{ }^{{ }^{k} B_{i}{ }^{2}=f_{i}{ }^{h} B_{h}{ }^{\kappa}+u_{i} C^{\kappa}, ~}
$$

$$
\begin{align*}
& \varphi_{\lambda}{ }^{k} C^{\lambda}=-u^{i} B_{i}{ }^{k}  \tag{7.7}\\
& \eta_{2} B_{i}{ }^{2}=v_{i}, \quad \eta_{\lambda} C^{\lambda}=\lambda .
\end{align*}
$$

It will be easily verified that, $\varphi_{\lambda}{ }^{\kappa}, \eta_{\lambda}, g_{\mu \lambda}$ defining an almost contact metric structure, $f_{i}{ }^{h}, g_{j i}, u_{i}, v_{i}, \lambda$ define an ( $f, g, u, v, \lambda$ )-structure.

Now the equations of Gauss and Weingarten of $M$ in $E^{\prime}$ are respectively

$$
\begin{equation*}
\nabla_{j} X_{\imath}=h_{j i} C, \tag{7.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{j} C=-h_{j}{ }^{i} X_{i}, \tag{7.9}
\end{equation*}
$$

or

$$
\begin{equation*}
\nabla_{j} B_{i}{ }^{\varepsilon}=h_{j i} C^{x} \tag{7.10}
\end{equation*}
$$

and

$$
\nabla_{j} C^{x}=-h_{j}{ }^{i} B_{i}{ }^{\boldsymbol{E}} .
$$

Differenting the first equation of (7.7) covariantly, we find

$$
\varphi_{\lambda}{ }^{\star} h_{j i} C^{2}=\left(\nabla_{j} f_{i}{ }^{h}\right) B_{h}{ }^{\kappa}+f_{\imath}{ }^{t} h_{j i} C^{\kappa}+\left(\nabla_{j} u_{i}\right) C^{\kappa}-u_{i} h_{j}{ }^{t} B_{t}{ }^{\kappa},
$$

from which, taking account of the second equation of (7.7),

$$
\begin{aligned}
\nabla_{j} f_{i}{ }^{h} & =-h_{j i} u^{h}+h_{j}{ }^{h} u_{i}, \\
\nabla_{j} u_{i} & =-h_{j t} f_{i}^{t} .
\end{aligned}
$$

Differentiating the second equation of (7.7) covariantly and taking account of (7.7), we find

$$
\varphi_{i}{ }^{k}\left(-h_{j}{ }^{t} B_{t}{ }^{k}\right)=-\left(\nabla_{j} u^{i}\right) B_{i}{ }^{k}-u^{i} h_{j i} C^{k},
$$

or

$$
-h_{j}{ }^{t}\left(f_{t}{ }^{h} B_{h}{ }^{\kappa}+u_{l} C^{k}\right)=-\left(\nabla_{j} u^{i}\right) B_{i}{ }^{\kappa}-u^{i} h_{j i} C^{\kappa},
$$

from which

$$
\nabla_{j} u^{2}=h_{j}{ }^{t} f_{t^{2}} .
$$

Differentiating the third equation of (7.7) covariantly, we find

$$
\eta_{2} h_{j i} C^{2}=\nabla_{j} v_{i},
$$

from which

$$
\nabla_{j} v_{i}=\lambda h_{j i} .
$$

Finally differentiating the last equation of (7.7) covariantly, we find

$$
\eta_{\lambda}\left(-h_{j}{ }^{h} B_{h_{h}}{ }^{2}\right)=\nabla_{j} \lambda,
$$

from which

$$
\nabla_{j} \lambda=-h_{j t} v^{t}
$$

Summing up, we have

$$
\begin{align*}
\nabla_{j} f_{i}{ }^{h} & =-h_{j i} u^{h}+h_{j}{ }^{h} u_{i}, \\
\nabla_{j} u_{i} & =-h_{j t} f_{\imath}^{t}, \\
\nabla_{j} v_{i} & =\lambda h_{j i},  \tag{7.12}\\
\nabla_{j} \lambda & =-h_{j t} v^{t} .
\end{align*}
$$

We assumed that ( $f, g, u, v, \lambda$ )-structure on $M$ is normal, that is,

$$
\begin{equation*}
S_{j i}{ }^{h}=f_{j}{ }^{t} \nabla_{t} f_{2}^{h}-f_{\imath}{ }^{t} \nabla_{t} f_{j}{ }^{h}-\left(\nabla_{j} f_{\imath}{ }^{t}-\nabla_{\imath} f_{j}{ }^{t}\right) f_{t}^{h}+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h}=0 . \tag{7.13}
\end{equation*}
$$

As we have seen in $\S 6$, the only eigenvalue of the tensor $h_{i}{ }^{h}$ is $\alpha$ or 0 . We denote the eigenspaces corresponding to the eigenvalues $\alpha$ and 0 by $V_{\alpha}$ and $V_{0}$ respectively. Since the multiplicity $r$ of $\alpha$ is constant, $V_{\alpha}(x)$ at $x$ and $V_{0}(x)$ at $x, x \in M$, define respectively $r$ - and $(2 n-r)$-dimensional distributions $D_{\alpha}$ and $D_{0}$ over $M$. They are complementary in the sense that they are mutually orthogonal and their Whiteney sum is $T(M)$.

Lemma 7.1. The distributions $D_{\alpha}$ and $D_{0}$ are both integrable.
Proof. Let $p^{h}$ and $q^{h}$ be two arbitrary eigenvectors of $h_{i}{ }^{h}$ with constant eigenvalue $\alpha \neq 0$, then we have

$$
h_{i}{ }^{h} p^{2}=\alpha p^{h}, \quad h_{i}{ }^{h} q^{2}=\alpha q^{h},
$$

from which

$$
\begin{aligned}
& \left(\nabla_{j} h_{i}{ }^{h}\right) p^{2}+h_{i}{ }^{h}\left(\nabla_{j} p^{i}\right)=\alpha\left(\nabla_{j} p^{h}\right), \\
& \left(\nabla_{j} h_{i}{ }^{h}\right) q^{2}+h_{i}{ }^{h}\left(\nabla_{j} q^{i}\right)=\alpha\left(\nabla_{j} q^{h}\right) .
\end{aligned}
$$

Thus

$$
h_{i}{ }^{h}\left(p^{j} \nabla_{j} q^{2}-q^{j} \nabla_{j} p^{i}\right)=\alpha\left(p^{j} \nabla_{j} q^{h}-q^{j} \nabla_{j} p^{h}\right)
$$

by virtue of the equations of Codazzi, that is, if $p^{h}$ and $q^{h}$ belong to $D_{\alpha}$, then [ $p, q]^{h}$ also belongs to $D_{\alpha}$. Consequently the distribution $D_{\alpha}$ spanned by eigenvectors of ${h_{i}}^{h}$ with eigenvalue $\alpha \neq 0$ is integrable.

Similarly we can also prove that the distribution $D_{0}$ spanned by eigenvectors of $h_{i}{ }^{h}$ with eigenvalue 0 is integrable.

Lemma 7. 2. Each integral manifold of $D_{\alpha}$ is totally geodesic in $M$ and so is each integral manifold of $D_{0}$.

Proof. Let $p^{h}$ and $q^{h}$ be two arbitrary vectors belonging to the distribution $D_{\alpha}$. Then we have

$$
\begin{equation*}
h_{i}{ }^{h} p_{h}=\alpha p_{i}, \quad h_{i}{ }^{h} q_{h}=\alpha q_{i} . \tag{7.14}
\end{equation*}
$$

Differentiating the first equation of (7.14) covariantly, we obtain

$$
\left(\nabla_{j} h_{i}{ }^{h}\right) p_{h}+h_{i}{ }^{h}\left(\nabla_{j} p_{h}\right)=\alpha \nabla_{j} p_{i},
$$

from which

$$
h_{i}{ }^{h}\left(\nabla_{j} p_{h}\right)-h_{j}{ }^{h}\left(\nabla_{2} p_{h}\right)=\alpha\left(\nabla_{j} p_{i}-\nabla_{\imath} p_{j}\right)
$$

by virtue of the equations of Codazzi. Transvecting this equation with $q^{j}$ and taking account of (7.14), we have

$$
h_{i}{ }^{h}\left(q^{j} \nabla_{j} p_{h}\right)-\alpha q^{h}\left(\nabla_{\imath} p_{n}\right)=\alpha q^{j}\left(\nabla_{j} p_{i}-\nabla_{\imath} p_{j}\right),
$$

from which

$$
h_{i}{ }^{h}\left(q^{j} \nabla_{j} p_{h}\right)=\alpha\left(q^{j} \nabla_{j} p_{i}\right),
$$

or

$$
h_{i}{ }^{h}\left(q^{j} \nabla_{j} p^{i}\right)=\alpha\left(q^{j} \nabla_{j} p^{h}\right),
$$

which shows that if $p^{h}$ and $q^{h}$ are two arbitrary vectors belonging to the distribution $D_{\alpha}$, then $q^{j} \nabla_{j} p^{h}$ also belongs to the distribution $D_{\alpha}$. Thus each integral manifold of $D_{\alpha}$ is totally geodesic in $M$.

Similarly we can prove that each integral manifold of $D_{0}$ is totally geodesic in $M$.

Moreover, if $p^{2}$ and $w^{2}$ belong respectively to $D_{0}$ and $D_{\alpha}$, we have

$$
\left(w^{j} \nabla_{j} h_{i}{ }^{h}\right) p^{2}=w^{j} \nabla_{j}\left(h_{i}{ }^{h} p^{i}\right)-h_{i}{ }^{h} w^{j} \nabla_{j} p^{2}=-h_{i}{ }^{h} w^{j} \nabla_{j} p^{2}
$$

and

$$
\left(p^{j} \nabla_{j} h_{i}{ }^{h}\right) w^{i}=p^{j} \nabla_{j}\left(h_{i}{ }^{h} w^{i}\right)-h_{i}{ }^{h} p^{j} \nabla_{j} w^{2}=\alpha p^{j} \nabla_{j} w^{h}-h_{i}{ }^{h} p^{j} \nabla_{j} w^{2},
$$

that is,

$$
\begin{equation*}
\left(w^{j} \nabla_{j} h_{i}^{h}\right) p^{2}=-\alpha\left(w^{j} \nabla_{j} p^{i}\right)_{\alpha}, \tag{7.15}
\end{equation*}
$$

and

$$
\begin{align*}
\left(p^{j} \nabla_{j} h_{i}{ }^{h}\right) w^{i} & =\alpha\left(p^{j} \nabla_{j} w^{h}\right)-\alpha\left(p^{j} \nabla_{j} w^{h}\right)_{\alpha}  \tag{7.16}\\
& =\alpha\left(p^{j} \nabla_{j} w^{h}\right)_{0},
\end{align*}
$$

vector of the form $q^{h}$ being written as $\left(q^{h}\right)_{\alpha}+\left(q^{h}\right)_{0}$, where $\left(q^{h}\right)_{\alpha}$ and $\left(q^{h}\right)_{0}$ respectively denote the $D_{\alpha}$ and $D_{0}$ components of $q^{h}$. Hence we get

$$
-\left(w^{j} \nabla_{j} p^{i}\right)_{\alpha}=\left(p^{j} \nabla_{j} w^{h}\right)_{0},
$$

because of the equation of Codazzi.
Consequently we have

$$
\begin{equation*}
\left(w^{j} \nabla_{j} p^{i}\right)_{\alpha}=0, \quad \text { that is, } \quad w^{j} \nabla_{j} p^{i} \in D_{0}, \tag{7.17}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(p^{j} \nabla_{j} w^{h}\right)_{0}=0, \quad \text { that is, } \quad p^{j} \nabla_{j} w^{2} \in D_{\alpha} . \tag{7.18}
\end{equation*}
$$

Thus we see that the distributions $D_{0}$ and $D_{\alpha}$ are parallel. So, using de Rham's decomposition theorem [7], we have

Lemma 7.3. If the submanifold $M$ is complete, then $M$ is a product of $M_{\alpha}$ and $M_{0}, M_{\alpha}$ corresponding to the integral manifold of $D_{\alpha}$ and $M_{0}$ to that of $D_{0}$.

Lemma 7.4. The $M_{\alpha}$ is totally umbilical in $E^{\prime}$ and $M_{0}$ is totally geodesic in $E^{\prime}$.
Proof. We represent $M_{\alpha}$ by

$$
\begin{equation*}
x^{h}=x^{h}\left(u^{a}\right), \tag{7.19}
\end{equation*}
$$

where $u^{a}$ are local coordinates on $M_{\alpha}$. Thus we have

$$
\begin{equation*}
X^{\mathrm{k}}=X^{\mathrm{k}}(x(u)), \tag{7.20}
\end{equation*}
$$

from which

$$
\begin{equation*}
B_{b}{ }^{k}=B_{b}{ }^{h} B_{h}{ }^{\kappa}, \tag{7.21}
\end{equation*}
$$

where

$$
B_{b}{ }^{\kappa}=\partial_{b} X^{k}, \quad B_{b}{ }^{h}=\partial_{b} x^{h} \quad\left(\partial_{b}=\partial / \partial u^{b}\right) .
$$

From (7.21), we find by covariant differentiation

$$
\nabla_{c} B_{b}{ }^{\kappa}=B_{c}{ }^{j} B_{b}{ }^{i} \nabla_{j} B_{i}{ }^{\kappa}
$$

because of $\nabla_{c} B_{b}{ }^{2}=0$, from which

$$
\nabla_{c} B_{b}{ }^{\kappa}=B_{c}{ }^{j} B_{b}{ }^{i} h_{j i} C^{\kappa}
$$

or

$$
\begin{equation*}
\nabla_{c} B_{b}{ }^{\kappa}=\alpha g_{c b} C^{x}, \tag{7.22}
\end{equation*}
$$

because $B_{b}{ }^{h}$ are eigenvectors of $h_{j}{ }^{h}$ with eigenvalue $\alpha$. Equation (7.22) shows that $M_{\alpha}$ is totally umbilical in $E^{\prime}$.

We can similarly prove that $M_{0}$ is totally geodesic in $E^{\prime}$.
Lemma 7.5. The $M_{\alpha}$ is a sphere and $M_{0}$ is a plane.
Proof. The $M_{0}$ being totally geodesic in $E^{\prime}$, it is a plane. Thus $M_{\alpha}$ is a hypersurface of a Euclidean space.

For the covariant derivative of $C^{\kappa}$ along $M_{\alpha}$, we have

$$
\begin{aligned}
\nabla_{c} C^{\kappa} & =B_{c}{ }^{j}\left(\nabla_{j} C^{\kappa}\right) \\
& =-B_{c}{ }^{j} h_{j}{ }^{2} B_{i}{ }^{\kappa} \\
& =-\alpha B_{c}{ }^{s} B_{j}{ }^{\kappa},
\end{aligned}
$$

$B_{c}{ }^{3}$ being an eigenvector of $h_{j}{ }^{2}$ with eigenvalue $\alpha$, from which

$$
\nabla_{c} C^{\kappa}+\alpha B_{c}{ }^{\kappa}=0
$$

and consequently

$$
C^{x}+\alpha X^{x}=A^{\kappa}
$$

$A^{\varepsilon}$ being a constant vector. This equation shows that $M_{\alpha}$ lies on a sphere. Thus, $M_{\alpha}$ being the intersection of a plane and a sphere, $M_{\alpha}$ is itself a sphere.

From these lemmas, we have
Theorem 7.1. Let $M$ be a $2 n$-dimensional complete differentiable hypersurface in a ( $2 n+1$ )-dimensional Euclidean space $E^{\prime}$. If the ( $\left.f, g, u, v, \lambda\right)$-structure induced on $M$ is normal, then $M$ is a product of a sphere and a plane.

Combining Theorems 6.1, 6.2 and Theorem 7.1, we obtain
Theorem 7.2. Let a complete differentiable submanifold $M$ of codimension 2 of an even-dimensional Euciidean space be such that the connection induced in the normal bundle of $M$ is trivial. If the ( $f, g, u, v, \lambda$ )-structure induced on $M$ is normal, then $M$ is a sphere, a plane, or a product of a sphere and a plane.

As a special case of Theorem 7.2, we have from (4.3)
Theorem 7.3. Let a complete differentiable submanifold $M$ of codimension 2 of an even-dimensional Euclidean space be such that the connection induced in the normal bundle of $M$ is trivial. If the linear transformations $h_{j}{ }^{2}$ and $k_{j}{ }^{2}$ which are defined by the second fundamental tensors of $M$ commute with $f_{j}{ }^{2}$, then $M$ is a sphere, a plane, or a product of a sphere and a plane.

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