

NON-LINEAR CONNECTION IN VECTOR BUNDLES

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Introduction.

The differential geometry of tangent bundle of Riemannian or Finslerian manifold has been studied by various authors. (Cf. Bibliography in Yano and Ishihara [6].) An almost complex structure induced on the tangent bundle of a differentiable manifold by a linear connection of the base manifold played an important role in these papers.

On the other hand, a vector bundle, or more precisely a hypertangent bundle, with a non-linear connection whose fibre has dimension larger than that of the underlying manifold admits a structure F characterized by the equation $F^3 + F = 0$. Such a structure first studied by Yano [2] contains as a special case an almost complex structure as well as an almost contact structure. Recently, Yano and Ishihara [6] studied such a structure induced on submanifolds in an almost complex space.

We consider, in this paper, a vector bundle $\mathcal{V}(M, \pi, Y, G)$, or $\mathcal{V}(M)$ simply, on a differentiable manifold M , where we denote by π the projection from the bundle space \mathcal{V} to the base space M , by Y the fibre which is an m -dimensional vector space and by G the group of the bundle which is a Lie subgroup of $GL(m)$. We assume, in the sequel, that $\dim M = n$ and the dimension of each fibre of $\mathcal{V}(M)$ is $m > n$. (In the case where $m = n$, see Kandatu [1], Yano and Ishihara [5].)

In §1, non-linear connection is defined as a distribution in $\mathcal{V}(M)$ or as an operator on the set of all cross-sections on M .

We discuss, in §2, vectors in $\mathcal{V}(M)$ and then we introduce a special frame of reference which is suitable for our present theme.

The last §3 is devoted to the study of the structure F stated above. We also refer, in this section, the almost complex structure induced by F on the integral manifold of the distribution defined by the characteristic vectors corresponding to the characteristic roots other than zero.

§1. Non-linear connection in $\mathcal{V}(M)$.

Let M be a differentiable manifold of dimension n and Y be a vector space of dimension m which is larger than n . We denote by $\mathcal{V}(M)$ the differentiable vector

Received January 24, 1966.

bundle over M with fibre Y . (Differentiability is always assumed to be C^∞ .) We introduce a local coordinate system in $\pi^{-1}(U)$, where π is the bundle projection and U an open neighbourhood of M . We denote by φ_U the coordinate function, that is, φ_U is a diffeomorphism from $U \times Y$ to $\pi^{-1}(U)$. For $p \in U$ and $y \in Y$ we define

$$\varphi_U(p, y) = (\xi^1, \dots, \xi^n, \eta^1, \dots, \eta^m),^{1)}$$

where (ξ^1, \dots, ξ^n) are local coordinates of p in U and (η^1, \dots, η^m) cartesian coordinates of y in the vector space Y . If we denote by $\{y_k\}$ the basis of Y , then

$$(1.1) \quad \mathbf{Z}_\epsilon^U(p) \stackrel{\text{def}}{=} \varphi_U(p, y_\epsilon), \quad p \in U$$

form basis of Y_p , where Y_p is the fibre over p .

For $U \cap U' \neq \emptyset$, we denote the coordinate transformation by

$$g_{U'U}: U \cap U' \rightarrow GL(m).$$

The law of transformation of the frame $\mathbf{Z}_\epsilon^U(p)$ at p is given by

$$(1.2) \quad \mathbf{Z}_\epsilon^{U'}(p) = \mathbf{Z}_\epsilon^U A_\epsilon'^{(g_{U'U}(p))}, \quad p \in U \cap U'; \text{ and } A_\epsilon' \text{ is a non-singular real } m \times m \text{ matrix,}$$

if we take account of (1.1). The facts above show that the law of coordinate transformation on ${}^c\mathcal{V}(M)$ is expressed as follows with respect to the local coordinate system (ξ^i, η^r) :

$$(1.3) \quad \xi^{i'} = \xi^{i'}(\xi), \quad \eta^{r'} = M_\epsilon'^{(r)}(\xi) \eta^\epsilon,$$

where $M_\epsilon'^{(r)}(\xi)$ is a non-singular real $m \times m$ matrix.

The fibre over a point p is the integral manifold through p of the distribution expressed by pfaffian equations

$$(1.4) \quad \omega^i \stackrel{\text{def}}{=} d\xi^i = 0.$$

We shall define a non-linear connection which is given as a distribution complementary to the distribution (1.4). First, let ${}^c\mathcal{V}(M)$ be a vector bundle over M whose fibre cY consists of all non-zero vectors of Y . Clearly ${}^c\mathcal{V}(M)$ is a sub-bundle of $\mathcal{V}(M)$. The bundle projection ${}^c\mathcal{V} \rightarrow M$ is denoted by ${}^c\pi$ and the fibre of ${}^c\mathcal{V}(M)$ over $p \in M$ by ${}^cY_p = {}^c\pi^{-1}(p)$. Now we define a bundle transformation $R_a: {}^c\mathcal{V} \rightarrow {}^c\mathcal{V}$, a being a non-zero real number, by $R_a(\sigma) = a\sigma$, where σ is an arbitrary element of ${}^c\mathcal{V}$. More explicitly, if σ belongs to $\pi^{-1}(U)$ and is expressed by the local coordinates (ξ, η) , then the local coordinates of $R_a(\sigma)$ is given by $(\xi, a\eta)$. Then $\pi \circ R_a$ is the identity mapping of M . The set of all such bundle transformations R_a forms a

1) We use, in this paper, different kinds of indices. Small roman indices i, j, k, \dots run over the range $1, 2, \dots, n$ and large roman ones A, B, C, \dots the range $1, 2, \dots, n+m$. On the other hand, greek indices in the latter half of alphabet $\kappa, \lambda, \mu, \dots$ run over the range $1, 2, \dots, m$.

group and we denote it by D . The group D is a group of bundle transformations of the subbundle ${}^{\circ}\mathcal{V}(M)$. A *non-linear connection* in ${}^{\circ}\mathcal{V}(M)$ is defined as a differentiable distribution Π satisfying the following conditions.

$$(1.5) \quad \begin{aligned} (a) \quad T_{\sigma}({}^{\circ}\mathcal{V}) &= T_{\sigma}({}^{\circ}Y_p) + \Pi_{\sigma} \quad (\text{direct sum}), \\ (b) \quad dR_a(\Pi_{\sigma}) &= \Pi_{R_a(\sigma)} \quad \text{for any real number } a \neq 0, \end{aligned}$$

where $T_{\sigma}(\quad)$ means the tangent space at σ of the space in parentheses and Π_{σ} is the value of the distribution Π at σ . (1.5) (a) says that $\dim \Pi = n$.

Π regarded as a distribution in ${}^{\circ}\mathcal{V}(M)$ has singularities along the 0-cross-section. We consider (1.5) outside of the 0-cross-section and call Π a non-linear connection in ${}^{\circ}\mathcal{V}(M)$.

Now we shall express the non-linear connections with respect to the local coordinate system (ξ, η) in $\pi^{-1}(U)$. We see, from (1.5) (a) that equations of Π is of the form

$$(1.6) \quad \omega^{\epsilon} = F^{\epsilon}_{\mathfrak{J}}(\xi, \eta) d\xi^{\mathfrak{J}} + d\eta^{\epsilon} = 0,$$

where $F^{\epsilon}_{\mathfrak{J}}(\xi, \eta)$ are uniquely determined in $\pi^{-1}(U)$ except the domain containing $\eta = (0, \dots, 0)$.

Condition (1.5) (b) requires that $F^{\epsilon}_{\mathfrak{J}}(\xi, \eta)$ are homogeneous functions of degree one with respect to the arguments η , i.e.

$$F^{\epsilon}_{\mathfrak{J}}(\xi, a\eta) = a F^{\epsilon}_{\mathfrak{J}}(\xi, \eta) \quad (a \neq 0).$$

$F^{\epsilon}_{\mathfrak{J}}(\xi, \eta)$ are called *components of non-linear connection*.

We sometimes call Π_{σ} the *horizontal plane at σ* and Π the *horizontal plane field*.

Under the coordinate transformation (1.3) $F^{\epsilon}_{\mathfrak{J}}(\xi, \eta)$ are transformed in to $F^{\epsilon'}_{\mathfrak{J}'}(\xi', \eta')$ by the following law:

$$(1.7) \quad F^{\epsilon'}_{\mathfrak{J}'} \frac{\partial \xi^{\mathfrak{J}'}}{\partial \xi^{\mathfrak{k}}} = M^{\epsilon'}_{\mathfrak{k}} F^{\epsilon}_{\mathfrak{k}} - \frac{\partial M^{\epsilon'}_{\mathfrak{k}}}{\partial \xi^{\mathfrak{k}}} \eta^{\epsilon}.$$

This is easily verified by the use of (1.5) (a).

A non-linear connection on ${}^{\circ}\mathcal{V}$ is defined in other ways. We shall give one of them in below.

Let \mathfrak{F} be the set of all C^{∞} -functions on M and \mathfrak{X} the set of all C^{∞} -cross-sections on M regarded as a vector space over the ring \mathfrak{F} . We denote by $\tilde{\mathfrak{X}}$ the sub-space of \mathfrak{X} consisting of all C^{∞} -cross-sections $M \rightarrow \mathfrak{Q}$, where \mathfrak{Q} is the bundle space of the tangent bundle $\mathfrak{Q}(M)$ of M .

DEFINITION 1.1. A non-linear connection is defined as an operator

$$\nabla: \mathfrak{X} \times \tilde{\mathfrak{X}} \rightarrow \mathfrak{X}$$

which assigns $\nabla(V, v) \in \mathfrak{X}$, denoted by $\nabla_v V$ to $(V, v) \in \mathfrak{X} \times \tilde{\mathfrak{X}}$ and satisfies following conditions:

$$(i) \quad \nabla_{fv} V = f \nabla_v V,$$

$$(ii) \quad \nabla_{(v+v')} V = \nabla_v V + \nabla_{v'} V$$

and

$$(iii) \quad \nabla_v(fV) = f \nabla_v V + (vf)V,$$

where $f \in \mathfrak{F}$, $v, v' \in \tilde{\mathfrak{X}}$ and $V \in \mathfrak{X}$. We further assume, by denoting V_p the value of V at $p \in M$, that

(iv) if $V_p = 0$, then $(\nabla_v V)_p = (\tilde{\nabla}_v V)_p$, where $\tilde{\nabla}$ is an arbitrarily given linear connection on ${}^c\mathcal{V}$, and that

$$(v) \quad \text{if } V_p = V'_p, \text{ then } (\nabla_v(V - V'))_p = (V_v V)_p - (\nabla_v V')_p.$$

If such an operator is defined in each of coverings $\{U\}$ of M and ∇ defined on U and ∇' on U' coincide on $U \cap U' \neq \emptyset$, then one can define $\tilde{\nabla}$ on M which induces ∇ on U and ∇' on U' .

We see, as a direct result of Definition 1.1, that a linear connection is a non-linear connection.

Now if we represent ∇ in the local coordinate system (ξ, η) , then the equivalency of two definitions of a non-linear connection follows automatically.

We shall use, as the basis in $\pi^{-1}(U)$, the basis $Z_i^U(p)$ on Y_p and the basis $d\varphi_U(\partial/\partial\xi^i)_p$ for an arbitrary point $p \in M$, where $d\varphi_U$ denotes the differential of φ_U and $\partial/\partial\xi^i$ are the basis of the tangent space M at p . These basis are denoted by $e_A = \{e_1, \dots, e_n, e_{n+1}, \dots, e_{n+m}\}$, where $e_i = d\varphi_U(\partial/\partial\xi^i)$ and $e_{n+i} = Z_i^U(p)$. Let there be given ∇ on U . Conditions (ii) and (iii) show that it is sufficient to express $\nabla_{e_i} V$ in order to express ∇ . We may put, by the condition (iv),

$$(1.8) \quad \nabla_{e_i} V = \left\{ \frac{\partial V^B}{\partial \xi^i} + \tilde{F}_i^B(\xi, V) \right\} e_B.$$

The quantities \tilde{F}_i^B appearing in (1.8) seem to depend on p and V , but conditions (iv) and (v) show that \tilde{F}_i^B are function of p and $V(p)$. Then we can write them as $\tilde{F}_i^B(\xi, \eta)$, where $(\xi, \eta) = V(p)$. Condition (i) requires that $\tilde{F}_i^B(\xi, \eta)$ are homogeneous functions of degree 1 with respect to η , i.e.

$$\tilde{F}_i^B(\xi, a\eta) = a \tilde{F}_i^B(\xi, \eta)$$

for any real number $a \neq 0$.

A vector field V is said to be *horizontal in the second sense* if $\nabla_{e_i} V$ is a linear combination of e_j , that is

$$\left(\frac{\partial V^B}{\partial \xi^i} + \tilde{F}_i^B(\xi, \eta) \right) e_B = \phi_i^j e_j,$$

which is equivalent to

$$(1.9) \quad \frac{\partial V^\kappa}{\partial \xi^i} + \tilde{\Gamma}^{\kappa}_{i^*}(\xi, \eta) = 0.$$

Now, we can define a horizontal plane field H by the condition that $H_\sigma \in H$ is the set of all vector fields which are horizontal at σ .

On the other hand, if there is given a non-linear connection in the first sense, then an operator $\tilde{F}: \mathfrak{X} \times \tilde{\mathfrak{X}} \rightarrow \mathfrak{X}$ is defined by

$$\tilde{F}_{e_i} V \stackrel{\text{def}}{=} \left(\frac{\partial V^\kappa}{\partial \xi^i} + \Gamma^{\kappa}_{i^*} \right) e_\kappa + \frac{\partial V^j}{\partial \xi^i} e_j,$$

where $\Gamma^{\kappa}_{i^*}$ are given in (1.6).

We conclude this section by the following theorem which will be obtained by a straightforward calculation.

THEOREM. *The non-linear connection is integrable if and only if*

$$(1.10) \quad K_{kj\lambda^*} \eta^\lambda = 0,$$

$K_{kj\lambda^*}$ being defined by

$$(1.11) \quad 2K_{kj\lambda^*} = \partial_{[k} \Gamma^{\kappa}_{j]\lambda} - \Gamma^{\kappa}_{[k} \partial_{|\alpha|} \Gamma^{\kappa}_{j]\lambda} + \Gamma^{\kappa}_{[k|\alpha|} \Gamma^{\kappa}_{j]\lambda},$$

where $\Gamma^{\kappa}_{j\lambda} = \partial \Gamma^{\kappa}_{j^*} / \partial \eta^\lambda$.

§2. Vectors in ${}^c\mathcal{V}(M)$.

DEFINITION 2.1. A *horizontal vector* $'V$ is, by definition, a vector which is tangent to the distribution H .

Then $'V$ has the following components

$$'V = \begin{pmatrix} V^i \\ -\Gamma^{\kappa}_{j^*} V^j \end{pmatrix}.$$

We can easily see that V^i are components of a tangent vector V of the manifold M . This fact gives the reason that we call such a vector $'V$ a *horizontal lift* of V .

A *vertical vector* $''V$ is, by definition, a vector which is tangent to a fibre of ${}^c\mathcal{V}(M)$.

Then we have

$$''V = \begin{pmatrix} 0 \\ V^\kappa \end{pmatrix}.$$

A special vertical vector " V " whose components are zero except " V^{i*} "²⁾ and " $V^{i*}=w^i$ " are components of a tangent vector w of M is called a *vertical lift* of the vector w .

We suppose, in the rest of this paper, that ${}^c\mathcal{V}(M)$ is a hypertangent bundle, that is, ${}^c\mathcal{V}(M)$ has a sub-bundle $\tilde{\mathcal{L}}(M)$ which is isomorphic to the tangent bundle $\mathcal{L}(M)$ of M . We choose the natural frame $e_i=\partial/\partial\xi^i$ in $T_p(M)$, the tangent space of M at $p\in M$. Then, denoting by ι the isomorphism of $\mathcal{L}(M)$ to $\tilde{\mathcal{L}}(M)$, we have the image $\iota(e_i)$ of e_i denoted by C_{i*} on the fibre at p in $\mathcal{L}(M)$. We choose $C_x(x, y, \dots=2n+1, \dots, n+m)$ on the fibre at p in ${}^c\mathcal{V}(M)$ in such a way that C_x are complement to C_{i*} . We denote by B_i the horizontal lifts of e_i .

In the sequel, we use the special frame of reference given by

$$A^\alpha=(B_i, C_{i*}, C_x)^{3)}$$

and their inverse

$$A^\alpha=(B^i, C^{i*}, C^x).$$

The components of their special frame become

$$B_i=\begin{pmatrix} \delta_i^h \\ -\Gamma_i^k \\ 0 \end{pmatrix}, \quad C_{i*}=\begin{pmatrix} 0 \\ \delta_{i*}^{j*} \\ 0 \end{pmatrix}, \quad C_x=\begin{pmatrix} 0 \\ \delta_x^y \\ 0 \end{pmatrix},$$

$$B^i=(\delta_h^i, 0), \quad C^{i*}=(\delta_h^i, \Gamma_h^{i*}, 0), \quad C^x=(0, \Gamma_h^x).$$

If we represent a vector V with respect to the adapted frame A_α , then we have

$$V=V^i B_i + V^{i*} C_{i*} + V^x C_x.$$

It can be easily verified that $V^i B_i$ is a horizontal vector and that $V^{i*} C_{i*}$ is a vertical vector. We call them a *horizontal part* and a *vertical part* of the vector V respectively.

§3. The structure F in ${}^c\mathcal{V}(M)$.

Under the notations in §2 we define a linear transformation F in ${}^c\mathcal{V}(M)$ by the following conditions:

$$(3.1) \quad \begin{cases} FB_i = C_{i*}, \\ FC_{i*} = -B_i, \\ FC_x = 0. \end{cases}$$

2) The range of the indices i^*, j^*, \dots is the first n parts of the range of the indices κ, λ, \dots . We often write $i^*=n+i$ and use it to mean that it corresponds to i .

3) We shall use the indices $\alpha, \beta, \gamma, \dots$ instead of the indices A, B, C, \dots in the case where we are using the special frame above.

Since $\mathcal{V}(M)$ is a hypertangent bundle, so we can make correspondence between the distribution defined by \mathbf{C}_* and that defined by \mathbf{B}_* .

Direct computations show that

$$(3.2) \quad F^3 + F = 0.$$

Thus we have

PROPOSITION 3.1. *There always exists, in a hypertangent bundle with a non-linear connection, a structure F satisfying (3.2) and of rank $2n$.*

The components of F with respect to the adapted frame \mathbf{A}_α are given by

$$(3.3) \quad \begin{pmatrix} 0 & -E_n & 0 \\ E_n & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix},$$

where E_n denotes $n \times n$ unit matrix.

We shall need the components of the non-holonomic object which are important when we are using a frame of reference such as \mathbf{A}_α which is not the natural one associated with the coordinate system. They are

$$\Omega_{\gamma\beta}^\alpha = -\Omega_{\beta\gamma}^\alpha = A^\alpha_A (X_\gamma A_\beta^A - X_\beta A_\gamma^A),$$

where $X_\alpha = A_\alpha^A \partial_A$.

The only non-vanishing components of $\Omega_{\gamma\beta}^\alpha$ are

$$(3.4) \quad \begin{cases} \Omega_{j\lambda}^\epsilon = \Gamma_{j\lambda}^\epsilon, \\ \Omega_{kj}^\epsilon = -\Gamma_{kjl}^\epsilon \eta^\lambda. \end{cases}$$

The components of Nijenhuis tensor constructed from F are given by

$$N_{\gamma\beta}^\alpha = F_\gamma^\epsilon F_\beta^\delta \Omega_{\epsilon\delta}^\alpha - F_\epsilon^\alpha F_\beta^\delta \Omega_{\gamma\delta}^\epsilon - F_\gamma^\epsilon F_\delta^\alpha \Omega_{\epsilon\beta}^\delta + F_\delta^\epsilon F_\epsilon^\alpha \Omega_{\gamma\beta}^\delta$$

with respect to the frame \mathbf{A}_α .

A simple calculation, taking account of (3.3) and (3.4), gives

$$\begin{aligned} N_{kj}^{h*} &= N_{k*j}^{h*} = -N_{kj*}^{h*} = \Gamma_{kj*}^{h*} - \Gamma_{jk*}^{h*}, \\ N_{kj*}^{h*} &= N_{kj}^{h*} = -N_{k*j*}^{h*} = K_{kjl}^{h*} \eta^\lambda, \\ N_{kj*}^{x*} &= \Gamma_{jk*}^{x*}, \\ N_{k*j*}^{x*} &= -K_{kjl}^{x*} \eta^\lambda, \\ N_{kx}^{h*} &= -\Gamma_{kx}^{h*}. \end{aligned}$$

PROPOSITION 3.2. *A necessary and sufficient condition that F is integrable is that*

$$\Gamma_{kj^*}^{h^*} - \Gamma_{jk^*}^{h^*} = 0,$$

$$K_{kj\lambda}{}^\mu \eta^\lambda = 0,$$

$$\Gamma_{jk^*}^x = 0,$$

$$\Gamma_{kx}^{h^*} = 0.$$

If we denote by L_1 the $2n$ -dimensional distribution defined by \mathbf{B}_i and \mathbf{C}_i , then the almost complex structure is introduced from F on L_1 . The distribution determined by \mathbf{C}_x is denoted by L_2 , that is, L_2 is spanned by the characteristic vectors of F corresponding to the characteristic root 0, then $\dim L_2 = m - n$.

We define tensors l and m as follows

$$l = -F^2 \quad \text{and} \quad m = F^2 + I,$$

where I is a unit tensor. It is easily verified that l and m are complementary projection tensors, that is, $l + m = I$, $l^2 = l$, $m^2 = m$ and $lm = ml = 0$.

Yano and Ishihara [4] proved the following two theorems.

THEOREM ([4]). *A necessary and sufficient condition for the distribution L_1 to be integrable is that one of the following condition is satisfied:*

$$(i) \quad N_{FE}{}^D l_C{}^F l_B{}^E m_D{}^A = 0,$$

$$(ii) \quad N_{CB}{}^D m_D{}^A = 0.$$

If we write down the integrability condition of L_1 with respect to the adapted frame \mathbf{A}_α , we have

$$\Gamma_{ji^*}^x = 0 \quad \text{and} \quad K_{ji\lambda}{}^x \eta^\lambda = 0.$$

THEOREM ([4]). *A necessary and sufficient condition that L_1 is integrable and besides the almost complex structure introduced on L_1 is integrable is that*

$$N_{FE}{}^A l_C{}^F l_B{}^E = 0.$$

If we express this condition with respect to the adapted frame \mathbf{A}_α , then we have

$$\Gamma_{ji^*}^{h^*} - \Gamma_{ij^*}^{h^*} = 0, \quad K_{ji\lambda}{}^\mu \eta^\lambda = 0 \quad \text{and} \quad \Gamma_{jk^*}^x = 0.$$

Now let us consider infinitesimal transformations which preserve the structure F . First of all we calculate the Lie derivative of F with respect to a vector field V and represent it in the adapted frame \mathbf{A}_α . Then we have

$$(\mathcal{L}_V F)_\beta^\alpha = V^\epsilon X_\epsilon F_\beta^\alpha - F_\beta^\epsilon X_\epsilon V^\alpha + F_\epsilon^\alpha X_\beta V^\epsilon + (\Omega_{\epsilon\delta}^\alpha F_\beta^\delta - \Omega_{\epsilon\beta}^\delta F_\delta^\alpha) V^\epsilon.$$

PROPOSITION 3.3. *If the horizontal lift $'V$ of a vector field v on M preserves the structure F , then we have*

$$K_{ji\lambda}{}^\mu \eta^\lambda v^j = 0, \quad I_{ji}^x = 0$$

and

$$\partial_i v^h + \Gamma_{ji}^{h*} v^j = 0,$$

where v^i are the components of the vector v and ∂_i denotes the partial derivative with respect to ξ^i .

PROPOSITION 3.4. *If the vertical lift $''V$ of a vector field v on M preserves the structure F , then we have*

$$I_{ij}^x v^j = 0$$

and

$$\partial_i v^h + \Gamma_{ij}^{h*} v^j = 0.$$

Next we consider the case in which the distribution L_1 is integrable. In such a case there exists an almost complex structure F induced by F . If $'V$ (or $''V$) is tangent to the integral manifold of L_1 and $\mathcal{L}_V F = 0$ (or $\mathcal{L}_V F = 0$), then $'V$ (or $''V$) is an almost analytic vector.

Together with Propositions 3.3 and 3.4, we have

PROPOSITION 3.5. *A necessary and sufficient condition for the horizontal lift $'V$ of a vector v on M which is tangent to the integral manifold of L_1 to be almost analytic is that*

$$K_{jh\lambda}{}^i \eta^\lambda v^h = 0$$

and

$$\partial_j v^i + \Gamma_{jh}^i v^h = 0.$$

For the vertical lift $''V$ the above conditions should be

$$\partial_j v^i + \Gamma_{jh}^i v^h = 0.$$

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