A generalized Cartan decomposition for the double coset space $(U(n_1) \times U(n_2) \times U(n_3)) \setminus U(n) / (U(p) \times U(q))$

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Abstract. Motivated by recent developments on visible actions on complex manifolds, we raise a question whether or not the multiplication of three subgroups L, G' and H surjects a Lie group G in the setting that G/H carries a complex structure and contains $G'/G' \cap H$ as a totally real submanifold.

Particularly important cases are when G/L and G/H are generalized flag varieties, and we classify pairs of Levi subgroups (L,H) such that LG'H=G, or equivalently, the real generalized flag variety $G'/H\cap G'$ meets every L-orbit on the complex generalized flag variety G/H in the setting that (G,G')=(U(n),O(n)). For such pairs (L,H), we introduce a herringbone stitch method to find a generalized Cartan decomposition for the double coset space $L\backslash G/H$, for which there has been no general theory in the non-symmetric case. Our geometric results provides a unified proof of various multiplicity-free theorems in representation theory of general linear groups.

1. Introduction and statement of main results.

1.1. Our object of study is the double coset space $L \setminus G/H$, where $L \subset G \supset H$ are a triple of reductive Lie groups.

In the 'symmetric case' (namely, both (G, L) and (G, H) are symmetric pairs), the theory of the Cartan decomposition G = LBH or its variants gives an explicit description of the double coset decomposition $L \setminus G/H$ (e.g., [3], [4], [14], [15], [16], [17]). However, in the general case where one of the pairs (G, L) and (G, H) is non-symmetric, there is no known structure theory on the double cosets $L \setminus G/H$ even for a compact Lie group.

Motivated by the recent works of 'visible actions' (Definition 7.1) on complex manifolds [9], [11] and multiplicity-free representations (e.g. the classification of multiplicity-free tensor product representations of GL(n), see [8], [19]), we have come to realize the importance of understanding the double cosets $L\backslash G/H$ in the non-symmetric case such as

$$(G, L, H) = (U(n), U(n_1) \times U(n_2) \times \dots \times U(n_k), U(m_1) \times \dots \times U(m_l)), \tag{1.1}$$

where $n = n_1 + \dots + n_k = m_1 + \dots + m_l$.

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In this article, we initiate the study of the double cosets $L\backslash G/H$ in the 'non-symmetric and visible case' by taking (1.1) as a test case, and develop new techniques in finding an explicit decomposition for $L\backslash G/H$.

For this, first we single out triples that give rise to visible actions. Theorem A gives a classification of the triples (L, G, H) such that G has the decomposition G = LG'H where G' = O(n), or equivalently, any L-orbit on the **complex** generalized flag variety $G/H \simeq \mathscr{B}_{m_1,\ldots,m_l}(\mathbb{C}^n)$ (see (1.5)) intersects with its **real** form $\mathscr{B}_{m_1,\ldots,m_l}(\mathbb{R}^n)$. The proof uses an idea of invariant theory arising from quivers. The classification includes some interesting non-symmetric cases such as k = 3, l = 2 and $\min(n_1 + 1, n_2 + 1, n_3 + 1, m_1, m_2) = 2$. Then, the L-action on G/H (and likewise, the H-action on G/L) becomes visible in the sense of [9] (see Definition 7.1).

Second, we confine ourselves to these triples, and prove an analog of the Cartan decomposition

$$G = LBH$$

by finding an explicit subset B in G' such that generic points of B form a J-transversal totally real slice (Definition 7.1) for the L-action on G/H of minimal dimension (see Theorem B). The novelty of our method in the non-symmetric case is an idea of 'herringbone stitch' (see Section 3).

1.2. To explain the perspectives of our generalization of the Cartan decomposition, let us recall briefly classic results on the double cosets $L\backslash G/H$ in the symmetric case. A prototype is a theorem due to H. Weyl: let K be a connected compact Lie group, and T a maximal toral subgroup. Then,

any element of
$$K$$
 is conjugate to an element of T . (1.2)

We set $G := K \times K$, $A := \{(t, t^{-1}) : t \in T\}$ and identify K with the subgroup diag $(K) := \{(k, k) : k \in K\}$ of G. Then, the statement (1.2) is equivalent to the double coset decomposition:

$$G = KAK. (1.3)$$

In the above case, $(G, K) = (K \times K, \operatorname{diag}(K))$ forms a compact symmetric pair. More generally, the decomposition (1.3) still holds for a Riemannian symmetric pair (G, K) by taking $A \simeq \mathbf{T}^k$ (G/K): compact type) or $A \simeq \mathbf{R}^k$ (G/K): non-compact type) where $k = \operatorname{rank} G/K$. Such a decomposition is known as the Cartan decomposition for symmetric spaces.

A further generalization of the Cartan decomposition has been developed over the decades under the hypothesis that both (G,L) and (G,H) are symmetric pairs. For example, Hoogenboom [4] gave an analog of the Cartan decomposition for $L\backslash G/H = (U(l)\times U(m))\backslash U(n)/(U(p)\times U(q))$ (l+m=p+q=n) by finding a toral subgroup T^k as its representatives, where $k=\min(l,m,p,q)$. This result is generalized by Matsuki [16], showing that there exists a toral subgroup B in G such that

$$G = LBH \tag{1.4}$$

if G is compact (see Fact 2.1). Analogous decomposition also holds in the case where G is a non-compact reductive Lie group and L is its maximal compact subgroup, by taking a non-compact abelian subgroup B of dimension rank G/H (see Flensted-Jensen [3]).

1.3. Before explaining a new direction of study in the non-symmetric case, we pin down some remarkable aspects on the Cartan decomposition in the symmetric case from algebraic, geometric, and analytic viewpoints.

Algebraically, finding nice representatives of the double coset is relevant to the reduction theory, or the theory of normal forms. For example, the Cartan decomposition (1.3) for $(G, K) = (GL(n, \mathbf{R}), O(n))$ corresponds to the diagonalization of symmetric matrices by orthogonal transformations. The case $G = G' \times G'$, $L = H = \operatorname{diag}(G')$ with $G' = GL(n, \mathbf{C})$ is equivalent to the theory of Jordan normal forms.

Geometrically, (1.4) means that every L-orbit on the (pseudo-)Riemannian symmetric space G/H meets the flat totally geodesic submanifold $B/B \cap H$. The decomposition (1.4) is also used in the construction of a G-equivariant compactification of the symmetric space G/H (see [2] for a survey on various compactifications).

Analytically, the Cartan decomposition is particularly important in the analysis of asymptotic behavior of global solutions to G-invariant differential equations on the symmetric space G/H (e.g. [3], [4], [6]).

1.4. Now, we consider the non-symmetric case $L \subset G \supset H$. Unlike the symmetric case, we cannot expect the existence of an abelian subgroup B such that LBH contains an interior point of G in general, as is easily observed by the argument of dimensions (e.g. [6, Introduction]). Instead, we raise here the following question:

QUESTION 1.1. Does there exist a 'nice' subgroup G' such that LG'H contains an open subset of G?

For a compact G, one may strengthen Question 1.1 as follows:

QUESTION 1.1'. Does there exist a 'nice' subgroup G' such that G = LG'H?

The decomposition G = LG'H means that the double coset space $L \setminus G/H$ can be controlled by a subgroup G'.

What is a 'nice' subgroup G'? In contrast to the previous case that G/H carries a G-invariant Riemannian structure and that the abelian subgroup G' = B (see (1.4)) gives a flat totally geodesic submanifold of G/H, we are interested in the case that G/H carries a G-invariant complex structure and that the subgroup G' gives a totally real submanifold $G'/G' \cap H$ of G/H. In the latter case, the L-action on G/H is said to be previsible ([9, Definition 3.1.1]) if LG'H contains an open subset of G.

1.5. Let us state our main results. Suppose we are in the setting (1.1) and consider Question 1.1' for

$$G' := O(n)$$
.

In this setting, we shall give a necessary and sufficient condition for the multiplication map $L \times G' \times H \to G$ to be surjective.

In order to clarify its geometric meaning, let $\mathscr{B}_{m_1,\ldots,m_l}(\mathbb{C}^n)$ denote the complex (generalized) flag variety:

$$\{(V_1, \dots, V_l) : \{0\} = V_0 \subset V_1 \subset V_2 \subset \dots \subset V_{l-1} \subset V_l = \mathbf{C}^n,$$

$$\dim V_i = m_1 + \dots + m_i \quad (1 \le i \le l)\}. \tag{1.5}$$

Likewise, the real (generalized) flag variety $\mathscr{B}_{m_1,\ldots,m_l}(\mathbf{R}^n)$ is defined and becomes a totally real submanifold of $\mathscr{B}_{m_1,\ldots,m_l}(\mathbb{C}^n)$.

THEOREM A. Let $k, l \ge 2$ and $n = n_1 + \cdots + n_k = m_1 + \cdots + m_l$ be partitions of n by positive integers. Let

$$(G, L, H) = (U(n), U(n_1) \times U(n_2) \times \cdots \times U(n_k), U(m_1) \times \cdots \times U(m_l)).$$

We set $N := \min(n_1, \ldots, n_k)$ and $M := \min(m_1, \ldots, m_l)$. Then the following five conditions are equivalent:

- i) G = LG'H. Here, G' := O(n).
- ii) $\mathscr{B}_{m_1,\ldots,m_l}(\mathbf{R}^n) \times \mathscr{B}_{n_1,\ldots,n_k}(\mathbf{R}^n)$ meets every G-orbit on $\mathscr{B}_{m_1,\ldots,m_l}(\mathbf{C}^n) \times$ $\mathscr{B}_{n_1,\ldots,n_k}(\mathbb{C}^n)$ by the diagonal action.
- ii)' $\mathscr{B}_{m_1,\ldots,m_l}(\mathbf{R}^n)$ meets every L-orbit on $\mathscr{B}_{m_1,\ldots,m_l}(\mathbf{C}^n)$.
- ii)" $\mathscr{B}_{n_1,\ldots,n_k}(\mathbf{R}^n)$ meets every H-orbit on $\mathscr{B}_{n_1,\ldots,n_k}(\mathbf{C}^n)$.
- iii) One of the following conditions holds:
 - 0)
 - $k = 3, \quad N = 1, \quad l = 2,$
 - II) $k = 3, N \ge 2, l = 2, M = 2,$

 - III) $l = 2, \quad M = 1,$ l') $k = 2, \quad l = 3, \quad M = 1,$
 - II') k = 2, N = 2, l = 3, M > 2,
 - III') k = 2, N = 1.

REMARK 1.5.1. Both (G, L) and (G, H) are symmetric pairs if and only if (k, l)(2,2), namely, (G,L,H) is in Case 0.

Remark 1.5.2. The condition (ii) implies that the L-action on G/H is previsible (see Definition 7.1). We shall see in Section 7 that this action is (strongly) visible, too (see also [9, Corollary 17]).

Remark 1.5.3. A holomorphic action of a complex reductive group on a complex manifold D is called *spherical* if its Borel subgroup has an open orbit on D. We shall see in Section 8 that the condition (ii) in Theorem A is equivalent to:

iv)
$$\mathscr{B}_{m_1,\ldots,m_l}(\mathbb{C}^n) \times \mathscr{B}_{n_1,\ldots,n_k}(\mathbb{C}^n)$$
 is a spherical variety of $G_{\mathbb{C}} := GL(n,\mathbb{C})$.

See Littelmann [13] for the statement (iv) in the case k = l = 2, namely, Case 0 in (iii).

- REMARK 1.5.4. An isometric action of a compact Lie group L on a Riemannian manifold is called *polar* if there exists a submanifold that meets every L-orbit orthogonally. Among Cases $0 \sim \text{III}'$ in Theorem A, the L-action on G/H is polar if and only if (G, L, H) is in Case 0 (see [1]).
- **1.6.** Suppose one of (therefore, all of) the equivalent conditions in Theorem A is satisfied. As a finer structural result of the double coset decomposition $L\backslash G/H$, we shall construct a fairly simple subset B of G'=O(n) such that the multiplication map $L\times B\times H\to G$ is still surjective, according to Cases $0\sim \text{III}$ of Theorem A. We omit Cases I' $\sim \text{III'}$ below because these are essentially the same with Cases I $\sim \text{III}$. For Case I below, we may and do assume $n_1=1$ without loss of generalities.

Theorem B (generalized Cartan decomposition). Let

$$(G, L, H) = (U(n), U(n_1) \times \cdots \times U(n_k), U(p) \times U(q)).$$

Then, there exists $B \subset O(n)$ such that G = LBH, where B is of the following form:

$$B \simeq \begin{cases} \boldsymbol{T}^{\min(n_1, n_2, p, q)} & \text{(Case 0),} \\ \boldsymbol{T}^{\min(p, q, n_2, n_3)} \cdot \boldsymbol{T}^{\min(p, q, n_2 + 1, n_3 + 1)} & \text{(Case I),} \\ \boldsymbol{T}^2 \cdot \boldsymbol{T} \cdot \boldsymbol{T}^2 & \text{(Case III),} \\ \boldsymbol{\underline{T}} \cdot \cdots \cdot \boldsymbol{\underline{T}} & \text{(Case IIII).} \end{cases}$$

Here, $T^a \cdot T^b$ means a subset of the form $\{xy \in G : x \in T^a, y \in T^b\}$ for some toral subgroups T^a and T^b .

We note that B is no longer a subgroup of G in Cases I, II and III.

1.7. This article is organized as follows. First, we give a proof of Theorem B (generalized Cartan decomposition G = LBH) by constructing explicitly the subset B of O(n). This is done in Theorems 2.2 (Case 0), 3.1 (Case I), 4.1 (Case II), and 5.1 (Case III), respectively by using an idea of herringbone stitch. This also gives a proof of the implication (iii) \Rightarrow (i) in Theorem A. The remaining implications of Theorem A are proved in Section 6. An application to representation theory is discussed in Section 8.

Theorem A was announced and used in [8, Theorem 3.1] and [9, Theorem 16] and its proof was postponed until this article. Theorem B was presented in the Oberwolfach workshop on "Finite and Infinite Dimensional Complex Geometry and Representation Theory", organized by A. T. Huckleberry, K.-H. Neeb, and J. A. Wolf, February 2004. The author thanks the organizers for a wonderful and stimulating atmosphere of the workshop.

2. Symmetric case.

This section reviews a well-known fact on the Cartan decomposition for the symmetric case. The results here will be used in the non-symmetric case (Sections 3, 4, and 5) as a 'stitch' (see Diagram 3.1, for example). Theorem 2.2 corresponds to Theorem B in Case 0, which is proved here.

First, we recall from [4, Theorem 6.10], [15, Theorem 1] the following:

FACT 2.1. Let G be a connected, compact Lie group with Lie algebra \mathfrak{g} . Suppose that τ and θ are two involutive automorphisms of G, and that L and H are open subgroups of G^{τ} and G^{θ} , respectively. We take a maximal abelian subspace \mathfrak{b} in $\mathfrak{g}^{-\tau,-\theta}:=\{X\in\mathfrak{g}:\tau X=\theta X=-X\}$, and write B for the connected abelian subgroup with Lie algebra \mathfrak{b} . Then G=LBH.

Now, let us consider the setting:

$$(G, L, H) = (U(n), U(n_1) \times U(n_2), U(p) \times U(q)),$$
 (2.1)

where $n = n_1 + n_2 = p + q$. Then, both (G, L) and (G, H) are symmetric pairs. In fact, if we set $I_{p,q} := \operatorname{diag}(1, \ldots, 1, -1, \ldots, -1)$ and define an involution θ by $\theta(g) := I_{p,q}gI_{p,q}^{-1}$, then $H = G^{\theta}$. Likewise, $L = G^{\tau}$ if we set $\tau(g) := I_{n_1,n_2}gI_{n_1,n_2}^{-1}$.

We set

$$l := \min(n_1, n_2, p, q) \tag{2.2}$$

and define an abelian subspace:

$$\mathfrak{b} := \sum_{i=1}^{l} \mathbf{R}(E_{i,n+1-i} - E_{n+1-i,i}).$$

Then, \mathfrak{b} is a maximal abelian subspace in $\mathfrak{g}^{-\tau,-\theta}$, and $B:=\exp(\mathfrak{b})$ is a toral subgroup of O(n). Now, applying Fact 2.1, we obtain:

Theorem 2.2. G = LBH.

3. Non-symmetric case 1: $\min(n_1, n_2, n_3) = 1$.

In Sections 3, 4, and 5, we give an explicit decomposition formula for the double coset space $L\backslash G/H$ in Cases I, II, and III of Theorem B, respectively, and complete the proof of Theorem B, and therefore that of the implication (iii) \Rightarrow (ii) of Theorem A.

The distinguishing feature of these three sections is that we are dealing with the **non-symmetric pair** (G, L), for which there is no known general theory on the double coset decomposition $L \setminus G/H$ of a compact Lie group G. We shall introduce a method of herringbone stitch (see Diagram 3.1) consisting of symmetric triples $G_{2i+1} \subset G_{2i} \supset H_i$ and $L_i \subset G_{2i+1} \supset G_{2i+2}$ (i = 0, 1, 2, ...) such that the iteration of the double coset decomposition of $G_{2i+1} \setminus G_{2i}/H_i$ and $L_i \setminus G_{2i+1}/G_{2i+2}$ keeps on toward a finer structure

of $L\backslash G/H = L_0\backslash G_0/H_0$.

This section treats the most interesting case for Theorem B, namely,

$$(G, L, H) = (U(n), U(n_1) \times U(n_2) \times U(n_3), U(p) \times U(q))$$
(3.1)

where $\min(n_1, n_2, n_3) = 1$. Theorem 3.1 below corresponds to Case I of Theorem B.

Without loss of generality, we may and do assume $n_1 = 1$. Thus, $L = U(1) \times U(n_2) \times U(n_3)$ $(n_2 + n_3 = n - 1)$. We set

$$l := \min(2p, 2q, 2n_2 + 1, 2n_3 + 1). \tag{3.2}$$

A simple computation shows $\left[\frac{l}{2}\right] = \min(p, q, n_2, n_3)$ and $\left[\frac{l+1}{2}\right] = \min(p, q, n_2 + 1, n_3 + 1)$. We define two abelian subspaces:

$$\mathfrak{b}' := \sum_{i=1}^{\left[\frac{l+1}{2}\right]} \mathbf{R}(E_{i,n+1-i} - E_{n+1-i,i}),$$

$$\mathfrak{b}'' := \sum_{i=1}^{\lfloor \frac{l}{2} \rfloor} \mathbf{R}(E_{i+1,n+1-i} - E_{n+1-i,i+1}).$$

Then $B' := \exp \mathfrak{b}'$ and $B'' := \exp \mathfrak{b}''$ are toral subgroups of dimension $\left[\frac{l+1}{2}\right]$ and $\left[\frac{l}{2}\right]$, respectively. We define a subset of O(n) by

$$B := B''B'. \tag{3.3}$$

For the sake of simplicity, we shall write also $B = T^{\left[\frac{l}{2}\right]} \cdot T^{\left[\frac{l+1}{2}\right]}$. We note that B is a compact manifold of dimension $l = \left[\frac{l}{2}\right] + \left[\frac{l+1}{2}\right]$ because B is diffeomorphic to the homogeneous space $(B' \times B'')/(B' \cap B'')$ and $B' \cap B''$ is a finite subgroup.

We are ready to describe the double coset decomposition for $L\backslash G/H$ in the case (3.1).

Theorem 3.1 (generalized Cartan decomposition). G = LBH, where $B \simeq T^{\min(p,q,n_2,n_3)} \cdot T^{\min(p,q,n_2+1,n_3+1)}$

PROOF. First, for $i \geq 1$, we define one dimensional toral subgroups by

$$B_i := \exp \mathbf{R}(E_{i,n+1-i} - E_{n+1-i,i}),$$

 $C_i := \exp \mathbf{R}(E_{i+1,n+1-i} - E_{n+1-i,i+1}).$

Then, B_1, B_2, \cdots , and $B_{\lceil \frac{l+1}{2} \rceil}$ commute with each other, and we have

$$B' = B_1 B_2 \cdots B_{\left[\frac{l+1}{2}\right]} = B_{\left[\frac{l+1}{2}\right]} \cdots B_2 B_1.$$

Likewise, $B'' = C_1 C_2 \cdots C_{\left[\frac{1}{2}\right]}$.

For $m \geq 1$, we define an embedding of a one dimensional torus into G by

$$\iota_m: \mathbf{T} \to G, \quad a \mapsto \operatorname{diag}(\underbrace{a, \dots, a}_{[\frac{m+1}{2}]}, \underbrace{1, \dots, 1}_{n-m}, \underbrace{a, \dots, a}_{[\frac{m}{2}]}).$$

We write T_m for its image, and define a subgroup G_m of G by

$$G_m := T_m \times U(n-m).$$

Here, we regard U(n-m) as a subgroup of G by identifying with $\{I_{\lfloor \frac{m+1}{2} \rfloor}\} \times U(n-m) \times \{I_{\lfloor \frac{m}{2} \rfloor}\}$. $(I_m$ stands for the unit matrix of degree m.) It is convenient to set $T_0 = \{e\}$ and $G_0 = G$. Then, we have a decreasing sequence of subgroups:

$$G = G_0 \supset G_1 \supset G_2 \supset \cdots$$
.

The point of our definition of G_m is that

 G_{2i} commutes with all of $B_1, \ldots, B_i, C_1, \ldots, C_{i-1}$. G_{2i+1} commutes with all of $B_1, \ldots, B_i, C_1, \ldots, C_i$.

Next, for $i \geq 0$, we define the following subgroups:

$$H_i := H \cap G_{2i} \simeq T_{2i} \times U(p-i) \times U(q-i),$$

 $L_i := L \cap G_{2i+1} \simeq T_{2i+1} \times U(n_2-i) \times U(n_3-i).$

The following obvious properties play a crucial role in the inductive step below.

$$H = H_0 \supset H_1 \supset H_2 \supset \cdots; \quad H_i \text{ commutes with } B_1, \dots, B_i,$$
 (3.4)

$$L = L_0 \supset L_1 \supset L_2 \supset \cdots; \quad L_i \text{ commutes with } C_1, \dots, C_i.$$
 (3.5)

With these preparations, let us proceed the proof of Theorem 3.1 along a herringbone stitch consisting of triples (G_{2i+1}, G_{2i}, H_i) and $(L_i, G_{2i+1}, G_{2i+2})$ (i = 0, 1, 2, ...):

Diagram 3.1.

We claim that each triple has the following decomposition formula:

$$G_{2i} = G_{2i+1}B_{i+1}H_i, (3.6)$$

$$G_{2i+1} = L_i C_{i+1} G_{2i+2}. (3.7)$$

To see this, we first take away the trivial factor from G_{2i} and G_{2i+1} , respectively. Then, the following bijections hold for $i = 0, 1, \ldots$,

$$G_{2i+1} \backslash G_{2i} / H_i \simeq (U(1) \times U(n-2i-1)) \backslash U(n-2i) / (U(p-i) \times U(q-i)),$$

 $L_i \backslash G_{2i+1} / G_{2i+2} \simeq (U(n_2-i) \times U(n_3-i)) \backslash U(n-2i-1) / (U(n-2i-2) \times U(1)).$

Since the right-hand side is the double coset space by symmetric subgroups, we can apply Theorem 2.2. Thus, (3.6) and (3.7) have been proved.

By using (3.6) and (3.7) iteratively, together with the commutating properties (3.4) and (3.5), we obtain

$$G = G_0 = G_1 B_1 H_0$$

$$= (L_0 C_1 G_2) B_1 H$$

$$= L C_1 (G_3 B_2 H_1) B_1 H$$

$$= L C_1 G_3 B_2 B_1 H$$

$$= \cdots$$

$$= L C_1 \cdots C_i G_{2i} B_i \cdots B_1 H$$

$$= L C_1 \cdots C_i G_{2i+1} B_{i+1} \cdots B_1 H.$$
(3.8)

If $\min(p,q) \leq \min(n_2,n_3)$, then this equation terminates with $G_{2i} = H_i$ when i reaches $\min(p,q)$. Then, $i = \left\lfloor \frac{l}{2} \right\rfloor = \left\lfloor \frac{l+1}{2} \right\rfloor$, and we have $G = LB''B'H_iH = LBH$ from (3.8). If $\min(p,q) > \min(n_2,n_3)$, then this equation terminates with $G_{2i+1} = L_i$ when i reaches $\min(n_2,n_3)$. Then, $i = \left\lfloor \frac{l}{2} \right\rfloor$ and $i+1=\left\lfloor \frac{l+1}{2} \right\rfloor$, and we have $G = LL_iB''B'H = LBH$ from (3.9). Hence, we have completed the proof of Theorem.

4. Non-symmetric case 2: $\min(n_1, n_2, n_3) \geq 2$.

In this section we study the double coset space $L\backslash G/H$ in Case II of Theorem B, that is, the non-symmetric case:

$$(G, L, H) = (U(n), U(n_1) \times U(n_2) \times U(n_3), U(p) \times U(q)),$$

where $n = n_1 + n_2 + n_3 = p + q$, $\min(n_1, n_2, n_3) \ge 2$ and $\min(p, q) = 2$. Without loss of generality, we may and do assume p = 2.

We define three abelian subspaces:

$$\mathfrak{a}_1 := \mathbf{R}(E_{1,n} - E_{n,1}) + \mathbf{R}(E_{2,n-1} - E_{n-1,2}),$$

$$\mathfrak{a}' := \mathbf{R}(E_{n_1+1,n-1} - E_{n-1,n_1+1}),$$

$$\mathfrak{a}_2 := \mathbf{R}(E_{n_1+1,n} - E_{n,n_1+1}) + \mathbf{R}(E_{n_1+2,n-1} - E_{n-1,n_1+2}),$$

and correspondingly three toral subgroups by $A_1 := \exp \mathfrak{a}_1$, $A' := \exp \mathfrak{a}'$, and $A_2 := \exp \mathfrak{a}_2$. We then set

$$B := A_2 A' A_1. (4.1)$$

Note that B is a five dimensional subset of O(n), but is no more a subgroup.

Here is a generalized Cartan decomposition for $L\backslash G/H$ in the non-symmetric setting $\min(n_1, n_2, n_3) \geq 2$ and $\min(p, q) = 2$:

Theorem 4.1. G = LBH.

PROOF. The proof again uses herringbone 'stitch', of which each stitch is a special case of Theorem 3.1 or Theorem 2.2, respectively.

Step 1. We define a subgroup G_1 of G by

$$G_1 := U(n_1) \times U(n_2 + n_3).$$

Since both (G, H) and (G, G_1) are symmetric pairs, we have

$$G = G_1 A_1 H \tag{4.2}$$

by Theorem 2.2. We observe from (2.2) that A_1 is of dimension $\min(2, n-2, n_1, n_2 + n_3) = 2$.

Step 2. We define a subgroup H_1 of G by

$$H_1 := Z_{H \cap G_1}(A_1) \simeq \Delta(T^2) \times U(n_1 - 2) \times U(n_2 + n_3 - 2).$$

Here, $\Delta(T^2) := \{ \operatorname{diag}(a, b, 1, \dots, 1, b, a) : a, b \in T \}$. Then, taking away the first factor inclusion $U(n_1)$, we have

$$L\backslash G_1/H_1 \simeq (U(n_2) \times U(n_3))\backslash U(n_2 + n_3)/(U(n_2 + n_3 - 2) \times U(1) \times U(1)).$$

Applying Theorem 3.1 to the right-hand side, we obtain

$$G_1 = LA_2A'H_1. (4.3)$$

We note that A_2A' is of dimension $\min(2n_2, 2n_3, 2(n_2 + n_3 - 2) + 1, 3) = 3$, as explained in Section 3.

Combining (4.2) and (4.3), we obtain

$$G = G_1 A_1 H$$

$$= (LA_2 A' H_1) A_1 H$$

$$= LA_2 A' A_1 H$$

$$= LBH$$

because H_1 commutes with A_1 . Thus, we have shown Theorem 4.1.

5. Non-symmetric case 3: $\min(p, q) = 1$.

This section treats the double coset space $L\backslash G/H$ in Case III of Theorem B, that is, the non-symmetric case:

$$(G, L, H) = (U(n), U(n_1) \times \cdots \times U(n_k), U(1) \times U(n-1))$$

for an arbitrary partition $n = n_1 + \cdots + n_k$. In this case, although the pair (G, L) is non-symmetric, the symmetric pair (G, H) gives a very simple homogeneous space, namely, $G/H \simeq \mathbf{P}^{n-1}\mathbf{C}$. Thus, it is much easier to find an explicit decomposition G = LBH than the previous cases in Sections 3 and 4.

For $1 \le i \le k-1$, we set

$$H_i := -E_{1,n_1 + \dots + n_i + 1} + E_{n_1 + \dots + n_i + 1,1}$$

 $B_i := \exp(\mathbf{R}H_i) \quad (\simeq \mathbf{T}),$

and define a (k-1)-dimensional subset B in G' = O(n) by

$$B:=B_1\cdots B_{k-1}.$$

We note that B is not a group if $k \geq 3$. The subset B is contained in the subgroup O(k) of O(n) in an obvious sense.

Then, we have

Theorem 5.1.
$$G = LBH$$
, where $B = \underbrace{T \cdot \cdots \cdot T}_{k-1} (\subset O(n))$.

PROOF. We shall work on the L-action on $G/H \simeq \mathbf{P}^{n-1}\mathbf{C}$. First, we observe that the map

$$U(n_i) \times \mathbf{R} \to \mathbf{C}^{n_i}, \quad (h_i, a_i) \mapsto h_i^{t}(a_i, 0, \dots, 0)$$

is surjective for each i ($1 \le i \le k$). Therefore, the following map

$$U(n_1) \times \cdots \times U(n_k) \times \mathbf{P}^{k-1} \mathbf{R} \to \mathbf{P}^{n-1} \mathbf{C},$$

$$((h_1, \dots, h_k), [a_1 : \dots : a_k]) \mapsto [h_1^{t}(a_1, 0, \dots, 0) : \dots : h_k^{t}(a_k, 0, \dots, 0)]$$

$$(5.1)$$

is also surjective.

Next, an elementary matrix computation shows

$$\exp(\theta_1 H_1) \cdots \exp(\theta_{k-1} H_{k-1})^t (1, 0, \dots, 0) = {}^t (a_1, \dots, 0, a_2, \dots, 0, \dots, a_k, 0, \dots, 0),$$

where

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_{k-1} \\ a_k \end{pmatrix} = \begin{pmatrix} \cos\theta_1 \cos\theta_2 \cdots \cos\theta_{k-2} \cos\theta_{k-1} \\ \sin\theta_1 \cos\theta_2 \cdots \cos\theta_{k-2} \cos\theta_{k-1} \\ \sin\theta_2 \cdots \cos\theta_{k-2} \cos\theta_{k-1} \\ \vdots \\ \sin\theta_{k-2} \cos\theta_{k-1} \\ \sin\theta_{k-1} \end{pmatrix} \in \mathbf{R}^k \setminus \{0\}.$$

Hence, $B \cdot [1:0:\cdots:0] = \mathbf{P}^{k-1}\mathbf{R}$.

Combining with the surjective map $L \times \mathbf{P}^{k-1}\mathbf{R} \to G/H$, we have shown that the multiplication map $L \times B \times H \to G$ is surjective.

Now, Theorems 2.2, 3.1, 4.1 and 5.1 show that we have completed the proof of Theorem B.

6. Proof of Theorem A.

This section gives a proof of Theorem A.

Suppose we are in the setting of Theorem A. The equivalence (i) \Leftrightarrow (ii) (likewise, (i) \Leftrightarrow (ii)' and (i) \Leftrightarrow (ii)") is clear from the following natural identifications:

$$G'/G' \cap H \simeq \mathscr{B}_{m_1,\dots,m_l}(\mathbf{R}^n), \quad G/H \simeq \mathscr{B}_{m_1,\dots,m_l}(\mathbf{C}^n).$$

Further, Theorem B shows (iii) \Rightarrow (i).

Thus, the rest of this section is devoted to the proof of the implication (i) \Rightarrow (iii). We begin with a question about when the multiplication map

$$L \times G' \times H \to G, \quad (l, g', h) \mapsto lg'h$$
 (6.1)

is surjective, in the general setting that G = U(n), G' = O(n), and H is a Levi subgroup G. Our key machinery to find a necessary condition for the surjectivity of (6.1) is Lemma 6.3. Let us explain briefly the ideas of our strategy that manages the three non-commutative subgroups L, G' and H:

 $L \cdots$ finding L-invariants (invariant theory),

 $G' \cdots$ using the geometric property (G' gives real points in G/H),

 $H \cdots$ realizing H as the isotropy subgroup of the G-action.

For this, we take $J \in M(n, \mathbf{R})$ and consider the adjoint orbit:

$$G/G_J \simeq \{ \operatorname{Ad}(g)J : g \in G \} \subset M(n, \mathbb{C}),$$

where $Ad(g)J := gJg^{-1}$ and

$$G_J := \{ g \in G : gJ = Jg \}.$$

Later, we shall choose J such that H is conjugate to G_J by an element of G'. Here, we note that the surjectivity of the map (6.1) remains unchanged if we replace H with aHa^{-1} and L with bHb^{-1} $(a, b \in G')$. Then, the following observation:

$$G'G_J/G_J \simeq {\operatorname{Ad}(g)J : g \in G'} \subset M(n, \mathbf{R})$$

will be used in Lemma 6.1 ('management' of $G' \simeq O(n)$), while an invariant theory will be used in Lemma 6.2 ('management' of $L \simeq U(n_1) \times \cdots \times U(n_k)$).

LEMMA 6.1. Let $J \in M(n, \mathbf{R})$, G' = O(n), and L a subgroup of G = U(n). If there exists $q \in G$ such that

$$Ad(L)(Ad(g)J) \cap M(n, \mathbf{R}) = \emptyset, \tag{6.2}$$

then $G \supseteq LG'G_J$.

PROOF. First we observe that

$$Ad(G'G_J)J = Ad(G')J \subset M(n, \mathbf{R}).$$

Then, the condition (6.2) implies $\operatorname{Ad}(Lg)J \cap \operatorname{Ad}(G'G_J)J = \emptyset$, whence $Lg \cap G'G_J = \emptyset$. Therefore, $g \notin LG'G_J$.

Next, we fix a partition $n = n_1 + \cdots + n_k$, and find a sufficient condition for (6.2) in the setting:

$$L = U(n_1) \times \cdots \times U(n_k).$$

For this, we fix $l \geq 2$ and take a loop $i_0 \rightarrow i_1 \rightarrow \cdots \rightarrow i_l$ consisting of non-negative integers $1, \ldots, k$ such that

$$i_0 = i_l, \quad i_{a-1} \neq i_a \quad (a = 1, 2, \dots, l).$$
 (6.3)

Now, let us introduce a non-linear map:

$$A_{i_0\cdots i_l}: M(n, \mathbf{C}) \to M(n_{i_0}, \mathbf{C})$$

as follows: Let $P \in M(n, \mathbb{C})$, and we write P as $(P_{ij})_{1 \leq i,j \leq k}$ in block matrix form such that the (i, j)-block $P_{ij} \in M(n_i, n_j; \mathbb{C})$. We set $\widetilde{P}_{ij} \in M(n_i, n_j; \mathbb{C})$ by

$$\widetilde{P}_{ij} := \begin{cases} P_{ij} & (i < j), \\ P_{ji}^* & (i > j). \end{cases}$$

Then, $A_{i_0\cdots i_l}(P)$ is defined by

$$A_{i_0\cdots i_l}(P) := \widetilde{P}_{i_0i_1}\widetilde{P}_{i_1i_2}\cdots\widetilde{P}_{i_{l-1}i_l}. \tag{6.4}$$

LEMMA 6.2. If there exists a loop $i_0 \to i_1 \to \cdots \to i_l \ (= i_0)$ such that at least one of the coefficients of the characteristic polynomial $\det(\lambda I_{n_{i_0}} - A_{i_0 \cdots i_l}(P))$ is not real, then

$$Ad(L)P \cap M(n, \mathbf{R}) = \emptyset.$$

Later, we shall take P to be Ad(g)J and apply this lemma to the following loops:

1) $1 \rightarrow 2 \rightarrow 3 \rightarrow 1$,

$$A_{1231} = P_{12}P_{23}P_{13}^* (6.5)$$

2) $1 \rightarrow 3 \rightarrow 2 \rightarrow 4 \rightarrow 1$.

$$A_{13241} = P_{13}P_{23}^*P_{24}P_{14}^* (6.6)$$

3) $1 \rightarrow 4 \rightarrow 2 \rightarrow 4 \rightarrow 3 \rightarrow 4 \rightarrow 1$,

$$A_{1424341} = P_{14}P_{24}^*P_{24}P_{34}^*P_{34}P_{14}^* (6.7)$$

PROOF. For a block diagonal matrix $l = \begin{pmatrix} l_1 & & \\ & l_2 & & \\ & & l_k \end{pmatrix} \in L$, the transform $P \mapsto \operatorname{Ad}(l)P$ induces that of the (i,j)-block matrix:

$$P_{ij} \mapsto l_i P_{ij} l_j^{-1} \quad (1 \le i, j \le k).$$

Then P_{ij}^* is transformed as $P_{ij}^* \mapsto (l_i P_{ij} l_j^{-1})^* = l_j P_{ij}^* l_i^{-1}$. Hence, \widetilde{P}_{ij} is transformed as

$$\widetilde{P}_{ij} \mapsto l_i \widetilde{P}_{ij} l_j^{-1} \quad (1 \le i, j \le k),$$

and then $A_{i_0\cdots i_l}(P)$ is transformed as

$$A_{i_0\cdots i_l}(P) \mapsto l_{i_0}A_{i_0\cdots i_l}(P)l_{i_0}^{-1}.$$

Therefore, the characteristic polynomial of $A_{i_0\cdots i_l}(P)$ is invariant under the transformation $P \mapsto \operatorname{Ad}(l)P$. In particular, if $\operatorname{Ad}(L)P \cap M(n, \mathbf{R}) \neq \emptyset$, then $\det(\lambda I_{n_{i_0}} - A_{i_0\cdots i_l}(P)) \in \mathbf{R}[\lambda]$. By contraposition, Lemma 6.2 follows.

Here is a key machinery to show the implication (i) \Rightarrow (iii) in Theorem A:

LEMMA 6.3. Let $n = n_1 + \cdots + n_k$ be a partition, and $L = U(n_1) \times \cdots \times U(n_k)$ be the natural subgroup of G = U(n). Suppose J is of a block diagonal matrix:

$$J := \begin{pmatrix} J_1 & & & \\ & J_2 & & \\ & & \ddots & \\ & & & J_k \end{pmatrix} \in M(n, \mathbf{R}), \tag{6.8}$$

where $J_i \in M(n_i, \mathbf{R})$ $(1 \le i \le k)$. If there exist a skew Hermitian matrix $X \in \mathfrak{u}(n)$ and a loop $i_0 \to i_1 \to \cdots \to i_l \ (= i_0)$ (see (6.3)) such that

$$\det \left(\lambda I_{n_{i_0}} - A_{i_0 \cdots i_l}([X, J])\right) \notin \mathbf{R}[\lambda],$$

then the multiplication map $L \times G' \times G_J \to G$ is not surjective. Here, we recall G' = O(n).

PROOF. We set $P(\varepsilon) := \mathrm{Ad}(\exp(\varepsilon X))J$. In view of Lemmas 6.1 and 6.2, it is sufficient to show

$$\det (\lambda I_{n_{i_0}} - A_{i_0 \cdots i_l}(P(\varepsilon))) \notin \mathbf{R}[\lambda]$$

for some $\varepsilon > 0$. We set Q := [X, J]. The matrix $P(\varepsilon)$ depends real analytically on ε , and we have

$$P(\varepsilon) = J + \varepsilon Q + O(\varepsilon^2),$$

as ε tends to 0. In particular, the (i,j)-block matrix $P_{ij}(\varepsilon)$ ($\in M(n_i,n_j;\mathbf{C})$) satisfies

$$P_{ij}(\varepsilon) = \varepsilon Q_{ij} + O(\varepsilon^2) \quad (\varepsilon \to 0)$$

for $i \neq j$. Then, we have

$$\det (\lambda I_{n_{i_0}} - A_{i_0 \cdots i_l}(P(\varepsilon))) = \det (\lambda I_{n_{i_0}} - \varepsilon^l \widetilde{Q}_{i_0 i_1} \cdots \widetilde{Q}_{i_{l-1} i_l} + O(\varepsilon^{l+1}))$$

$$= \det (\lambda I_{n_{i_0}} - \varepsilon^l A_{i_0 \cdots i_l}(Q) + O(\varepsilon^{l+1}))$$

$$= \sum_{r=0}^{n_{i_0}} \lambda^{n_{i_0} - r} \varepsilon^{rl} h_r(\varepsilon), \tag{6.9}$$

where $h_r(\varepsilon)$ $(0 \le r \le n_{i_0})$ are real analytic functions of ε such that

$$\det (\lambda I_{n_{i_0}} - A_{i_0 \cdots i_l}(Q)) = \sum_{r=0}^{n_{i_0}} \lambda^{n_{i_0} - r} h_r(0).$$

From our assumption, this polynomial is not of real coefficients, namely, there exists r such that $h_r(0) \notin \mathbf{R}$. It follows from (6.9) that $\det(\lambda I_{n_{i_0}} - A_{i_0 \cdots i_l}(P(\varepsilon))) \notin \mathbf{R}[\lambda]$ for any sufficiently small $\varepsilon > 0$. Hence, we have shown Lemma.

For the applications of Lemma 6.3 below, we shall take a specific choice of a skew Hermitian matrix $X \in \mathfrak{u}(n)$. According to the partition $n = n_1 + \cdots + n_k$, we write $X = (X_{ij})_{1 \leq i,j \leq k}$ as a block form. We note that the (i,j) block of Q = [X,J] is given by

$$Q_{ij} = X_{ij}J_j - J_iX_{ij} . (6.10)$$

We also note that if $J \in M(n, \mathbf{R})$ is a diagonal matrix whose entries consist of non-negative integers $1, 2, \dots, l$ such that

$$\#\{1 \le a \le n : J_{aa} = i\} = m_i \quad (1 \le i \le l),$$

then G_J is conjugate to $U(m_1) \times U(m_2) \times \cdots \times U(m_l)$ by an element of G' = O(n). Since the surjectivity of (6.1) remains unchanged if we take the conjugation of H by G', we can apply Lemma 6.3 to study the surjectivity of (6.1) in the setting (1.1).

Now, we apply Lemma 6.3 to show the following four propositions:

PROPOSITION 6.4. Let $n = n_1 + n_2 + n_3 = m_1 + m_2 + m_3$ be partitions of n by positive integers. We define (natural) subgroups L and H of G = U(n) by

$$L := U(n_1) \times U(n_2) \times U(n_3),$$

 $H := U(m_1) \times U(m_2) \times U(m_3),$

and G' := O(n). Then, $G \supseteq LG'H$.

In the following three propositions, we set

$$(G, L, H) = (U(n), U(n_1) \times \cdots \times U(n_k), U(p) \times U(q))$$
 and $G' = O(n)$

where $n = n_1 + n_2 + \dots + n_k = p + q$.

Proposition 6.5. $G \supseteq LG'H$ if

$$\min(p,q) \ge 3, \quad k = 3 \quad and \quad \min(n_1, n_2, n_3) \ge 2.$$
 (6.11)

Proposition 6.6. $G \supseteq LG'H$ if

$$\min(p, q) = 2 \quad and \quad k \ge 4. \tag{6.12}$$

Proposition 6.7. $G \supseteq LG'H$ if

$$\min(p,q) \ge 3 \quad and \quad k \ge 4. \tag{6.13}$$

PROOF OF PROPOSITION 6.4. We consider the partition $n = n_1 + n_2 + n_3$ and the loop $1 \to 2 \to 3 \to 1$. We take $J = \text{diag}(j_1, \ldots, j_n) \in M(n, \mathbf{R})$ to be a diagonal matrix with the following two properties:

$$j_1 = 1$$
, $j_{n_1} = 2$, $j_{n_1+n_2+1} = 3$,
 $\#\{k: j_k = i\} = m_i \quad (1 \le i \le 3)$.

Then, the isotropy subgroup G_J is conjugate to H by an element of O(n). We fix $z \in \mathbb{C}$ and define a skew Hermitian matrix $X = (X_{ij})_{1 \le i,j \le 3} \in \mathfrak{u}(n)$ as follows:

$$X_{12} = \begin{pmatrix} 1 & 0 \end{pmatrix}, \ X_{23} = \begin{pmatrix} 1 & 0 \end{pmatrix}, \ X_{13} = \begin{pmatrix} z & 0 \end{pmatrix}.$$

Then it follows from (6.10) that Q = [X, J] has the following block entries:

$$Q_{12} = \begin{pmatrix} 1 & \\ & 0 \end{pmatrix}, \ Q_{23} = \begin{pmatrix} 1 & \\ & 0 \end{pmatrix}, \ Q_{13}^* = \begin{pmatrix} 2\overline{z} & \\ & 0 \end{pmatrix},$$

and therefore we have

$$A_{1231}(Q) = Q_{12}Q_{23}Q_{13}^* = \begin{pmatrix} 2\overline{z} & 0 \end{pmatrix}.$$

Thus, $\det(\lambda I_{n_1} - A_{1231}(Q)) = \lambda^{n_1} - 2\overline{z}\lambda^{n_1-1}$. This does not have real coefficients if we take $z \notin \mathbf{R}$. Hence, Proposition follows from Lemma 6.3.

PROOF OF PROPOSITION 6.5. We shall apply Lemma 6.3 with k=3 and the loop $1 \to 2 \to 3 \to 1$. In light of the assumption (6.11), an elementary consideration shows that there exist positive integers p_i, q_i $(1 \le i \le 3)$ satisfying the following equations:

We set

$$J_i := \begin{pmatrix} 1 & p_i & & \\ & \ddots & & \\ & & 1 & \\ & & & 0 & \\ & & & \ddots & \\ & & & & 0 \end{pmatrix} \in M(n_i, \mathbf{R}) \quad (1 \le i \le 3).$$

Then $G_J \simeq U(p_1 + p_2 + p_3) \times U(q_1 + q_2 + q_3) = H$, where J is defined as in (6.8). Now, let us take a specific choice of $X \in \mathfrak{u}(n)$ as follows: for $z \in \mathbb{C}$,

$$X_{12} := \begin{pmatrix} & 0 & 1 \\ 1 & & \end{pmatrix}, \ X_{23} := \begin{pmatrix} & 0 & 1 \\ 1 & & \end{pmatrix}, \ X_{13} := \begin{pmatrix} & 0 & 1 \\ z & & \end{pmatrix}.$$

This is possible because $n_i \geq 2$ (i = 1, 2, 3). Then the (i, j)-block of Q := [X, J] amounts to

$$Q_{12} = \begin{pmatrix} & & -1 \\ 1 & & \end{pmatrix}, \ Q_{23} = \begin{pmatrix} & & -1 \\ 1 & & \end{pmatrix}, \ Q_{13} = \begin{pmatrix} & & -1 \\ z & & \end{pmatrix}.$$

Associated to the loop $1 \rightarrow 2 \rightarrow 3 \rightarrow 1$, we have

$$A_{1231}(Q) = Q_{12}Q_{23}Q_{13}^* = \begin{pmatrix} & 0 & -\overline{z} \\ 1 & & \end{pmatrix}.$$

Hence, $\det(\lambda I_{n_1} - A_{1231}(Q)) = \lambda^{n_1} + \lambda^{n_1-2}\overline{z} \notin \mathbf{R}[\lambda]$ if we take $z \notin \mathbf{R}$. Now, Proposition 6.5 follows from Lemma 6.3.

Proof of Proposition 6.6. With the notation as in (6.8), we define J by setting k=4 and

$$J_1 = \begin{pmatrix} 1 & 0 \end{pmatrix}, \ J_2 = \begin{pmatrix} 1 & 0 \end{pmatrix}, \ J_3 = 0, \ J_4 = 0.$$

Then the isotropy subgroup G_J is conjugate to $H \simeq U(2) \times U(n-2)$ by an element of G' = O(n). We consider the loop $1 \to 3 \to 2 \to 4 \to 1$. Then it follows from (6.10) that

$$A_{13241}(Q) = Q_{13}Q_{23}^*Q_{24}Q_{14}^*$$

$$= (-J_1X_{13})(-J_2X_{23})^*(-J_2X_{24})(-J_1X_{14})^*$$

$$= \begin{pmatrix} (\vec{a}, \vec{b})(\vec{d}, \vec{c}) & 0 & \cdots & 0 \\ 0 & & & & 0 \\ \vdots & & & 0 & \end{pmatrix},$$

where $\vec{a}, \vec{b} \in \mathbb{C}^{n_3}$ denote the first row vectors of X_{13} , X_{23} and $\vec{c}, \vec{d} \in \mathbb{C}^{n_4}$ denote the first row vectors of X_{14} , X_{24} , respectively. Since n_1 , n_2 , n_3 and n_4 are positive integers, we can find $X \in \mathfrak{u}(n)$ such that $(\vec{a}, \vec{b})(\vec{d}, \vec{c}) \notin \mathbb{R}$.

Then

$$\det(\lambda I_{n_1} - A_{13241}(Q)) = \lambda^{n_1 - 1} (\lambda - (\vec{a}, \vec{b})(\vec{d}, \vec{c})) \notin \mathbf{R}[\lambda].$$

Thus Proposition 6.6 follows from Lemma 6.3.

PROOF OF PROPOSITION 6.7. Without loss of generality, we may and do assume $1 \le n_1 \le n_2 \le \cdots \le n_k$. We give a proof according to the following three cases:

Case 1) $k \geq 5$.

Case 2) $k = 4 \text{ and } n_3 > 1.$

Case 3) $k = 4 \text{ and } n_3 = 1.$

Case 1) Suppose $k \geq 5$. Then, $n_5 + \cdots + n_k > 1$. In fact, if it were not the case, we would have k = 5 and $n_5 = 1$, which would imply $n_1 = n_2 = \cdots = n_5 = 1$ and n = 5. But, this contradicts to the assumption $n = p + q \geq 3 + 3 = 6$. Now, we apply Proposition 6.5 to $L' = U(n_1 + n_2) \times U(n_3 + n_4) \times U(n_5 + \cdots + n_k)$ ($\supset L$), and conclude

$$G \supseteq L'G'H \supset LG'H$$
.

Case 2) Suppose k=4 and $n_3>1$. Then, $2 \le n_3 \le n_4$ and $2 \le n_1+n_2$. Then apply Proposition 6.5 to $L'=U(n_1+n_2)\times U(n_3)\times U(n_4)$ and we conclude that

$$G \supseteq L'G'H \supset LG'H$$
.

Case 3) Suppose k = 4 and $n_3 = 1$. Then,

$$k = 4$$
 and $n_1 = n_2 = n_3 = 1$. (6.14)

In the setting (6.8), we define J by setting

$$J_1 = J_2 = J_3 := (1) \in M(1, \mathbf{R})$$
 and $J_4 := \begin{pmatrix} 1 & & & & & \\ & \ddots & & & \\ & & & 1 & & \\ & & & & 0 & \\ & & & & \ddots & \\ & & & & & 0 \end{pmatrix}$.

Then, $G_J \simeq U(p) \times U(q) = H$.

Given $Y = (v_1, \ldots, v_p) \in M(q, p; \mathbf{C})$ $(v_1, \ldots, v_p \in \mathbf{C}^q)$, we define $X \in \mathfrak{u}(n)$ by

$$X := \begin{pmatrix} 0 & -Y^* \\ Y & 0 \end{pmatrix}.$$

Then, $Q := [X, J] = \begin{pmatrix} 0 & Y^* \\ Y & 0 \end{pmatrix}$. Associated to the partition $n = n_1 + n_2 + n_3 + n_4$ (= 1 + 1 + 1 + (n - 3)) and the loop $1 \to 4 \to 2 \to 4 \to 3 \to 4 \to 1$,

$$A_{1424341}(Q) = Q_{14}Q_{24}^*Q_{24}Q_{34}^*Q_{34}Q_{14}^*$$

$$= \begin{pmatrix} 0 \\ v_1 \end{pmatrix}^* \begin{pmatrix} 0 \\ v_2 \end{pmatrix} \begin{pmatrix} 0 \\ v_2 \end{pmatrix}^* \begin{pmatrix} 0 \\ v_3 \end{pmatrix} \begin{pmatrix} 0 \\ v_3 \end{pmatrix}^* \begin{pmatrix} 0 \\ v_1 \end{pmatrix}$$

$$= (v_2, v_1)(v_3, v_2)(v_1, v_3), \tag{6.15}$$

where 0 denotes the zero vector in C^{p-3} . Since $p \geq 3$ and $q \geq 3 \ (\geq 2)$, we can take

$$Y = (v_1, v_2, \dots, v_p) = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & z & 0 & 0 \\ & 0 & & 0 \end{pmatrix},$$

so that $(v_2, v_1)(v_3, v_2)(v_1, v_3) = 1 + z$. Thus,

$$\det (\lambda I_1 - A_{1424341}([X, J])) = \lambda - 1 - z \notin \mathbf{R}[\lambda]$$

if $z \notin \mathbf{R}$. Hence Proposition follows from Lemma 6.3.

Hence, the proof of Theorem A is now completed.

7. Visible actions on generalized flag varieties.

Suppose a Lie group L acts holomorphically on a connected complex manifold D with complex structure J.

DEFINITION 7.1 (see [9, Definitions 2.3, 3.1.1 and 3.3.1]). The action is previsible if there exists a totally real submanifold S such that

$$D' := L \cdot S \text{ is open in } D. \tag{7.1}$$

The previsible action is *visible* if

$$J_x(T_xS) \subset T_x(L \cdot x)$$
 for generic $x \in S$ (*J*-transversality), (7.2)

and is strongly visible if there exists an anti-holomorphic diffeomorphism σ of D' such that

$$\sigma|_S = \mathrm{id},\tag{7.3}$$

$$\sigma$$
 preserves each L-orbit on D' . (7.4)

A strongly visible action is visible ([9, Theorem 14]). Furthermore, we have:

Lemma 7.2. Suppose there exists an automorphism $\tilde{\sigma}$ of L such that

$$\sigma(g \cdot x) = \tilde{\sigma}(g) \cdot \sigma(x) \quad (g \in L, \ x \in L). \tag{7.5}$$

Then, a previsible action satisfying (7.3) is strongly visible.

PROOF. Any L-orbit on D' is of the form $L \cdot x$ for some $x \in S$. Then, by (7.3) and (7.5), we have $\sigma(L \cdot x) = \tilde{\sigma}(L) \cdot \sigma(x) = L \cdot x$. Hence, the condition (7.4) is fulfilled. \square

Now, let us consider the setting of Theorem A.

Example 7.3. We set

$$\tilde{\sigma}(g) := \overline{g} \text{ for } g \in G = U(n).$$

Then $\tilde{\sigma}$ stabilizes subgroups L and H in the setting (1.1) in particular, induces a Lie group automorphism, denoted by the same letter $\tilde{\sigma}$, of L, and an anti-holomorphic diffeomorphism, denoted by σ , of the homogeneous space

$$G/H \simeq \mathscr{B}_{m_1,\ldots,m_l}(\mathbf{C}^n).$$

The *L*-action on G/H satisfies the compatibility condition (7.5). Now, we consider the totally real submanifold $S := \mathcal{B}_{m_1,\ldots,m_l}(\mathbf{R}^n)$ in G/H. Since $\tilde{\sigma} = \mathrm{id}$ on G' = O(n) and $S \simeq G'/G' \cap H$, we have $\sigma|_S = \mathrm{id}$. Therefore, if S meets every L-orbit on G/H, then the L-action on G/H is not only previsible by definition but also is strongly visible by Lemma 7.2. Hence, the assertion in Remark 1.5.2 is proved.

8. Applications to representation theory.

This section gives a flavor of some applications of Theorem A to multiplicity-free theorems in representation theory.

In [10] (see also [12] and [9, Theorem 2]), we proved that the multiplicity-free property propagates from fibers to spaces of holomorphic sections of equivariant holomorphic bundles under a certain geometric condition. The key assumption there is strongly visible actions (Definition 7.1) on base spaces.

First of all, we observe that one dimensional representations are obviously irreducible, and therefore is multiplicity-free. Then, by [10], this multiplicity-free property propagates to the multiplicity-free property of the representation on the space $\mathcal{O}(G/H, \mathcal{L}_{\lambda})$ of holomorphic sections as an L-module for any G-equivariant holomorphic line bundle $\mathcal{L}_{\lambda} \to G/H$ if (G, L, H) satisfies (ii)' (or any of the equivalent conditions) in Theorem A. Then, by a theorem of Vinberg–Kimelfeld [20], this implies that $G/H \simeq \mathcal{B}_{m_1,\dots,m_l}(\mathbb{C}^n)$ is a spherical variety of $L_{\mathbb{C}} \simeq GL(n_1,\mathbb{C}) \times \dots \times GL(n_k,\mathbb{C})$, namely, a Borel subgroup of $L_{\mathbb{C}}$ has an open orbit on $\mathcal{B}_{m_1,\dots,m_l}(\mathbb{C}^n)$.

More generally, applying the propagation theorem of multiplicity-free property to higher dimensional fibers, we get from Theorem A a new geometric proof of a number of multiplicity-free results including:

• (Tensor product) The tensor product of two irreducible representations π_{λ} and π_{μ} of $GL(n, \mathbb{C})$ is multiplicity-free if the highest weight $\mu \in \mathbb{Z}^n$ is of the form,

$$(\underbrace{a,\ldots,a}_{p},\underbrace{b,\ldots,b}_{q}) \quad (a \ge b). \tag{8.1}$$

for some $a, b \in \mathbb{Z}$ $(a \ge b)$ and some p, q (p + q = n) and if one of the following conditions is satisfied:

- 1) $\min(p, q) = 1$.
- 1)' a b = 1.
- 2) $\min(p,q) = 2$ and λ is of the form

$$(\underbrace{x, \dots, x}_{n_1}, \underbrace{y, \dots, y}_{n_2}, \underbrace{z, \dots, z}_{n_3}) \quad (x \ge y \ge z)$$
(8.2)

- 2)' a b = 2 and λ is of the form (8.2).
- 3) λ is of the form (8.2) satisfying

$$\min(x-y, y-z, n_1, n_2, n_3) = 1.$$

Stembridge [19] gave a proof of this fact using a combinatorial method by a case-by-case argument. He proved also that this exhausts all multiplicity-free cases.

- (Restriction: $GL_n \downarrow GL_p \times GL_q$) The representation π_{λ} of $GL(n, \mathbb{C})$ is multiplicity-free when restricted to $GL(p, \mathbb{C}) \times GL(q, \mathbb{C})$ if one of the three conditions (1), (2), and (3) is satisfied.
- (Restriction: $GL_n \downarrow GL_{n_1} \times GL_{n_2} \times GL_{n_3}$) The irreducible representation π_{μ} of $GL(n, \mathbb{C})$ having highest weight μ of the form (8.1) is multiplicity-free when restricted to $GL(n_1, \mathbb{C}) \times GL(n_2, \mathbb{C}) \times GL(n_3, \mathbb{C})$ if $\min(a b, p, q) \leq 2$.

It is noteworthy that the above three multiplicity-free results ("triunity") are obtained from a single geometric result, Theorem A (see [8, Theorems 3.3, 3.4 and 3.6]). In particular, we get the equivalence (ii) \Leftrightarrow (iv) in Remark 1.5.3 by considering the $(G \times G)$ -equivariant line bundle $\mathcal{L}_{\lambda} \boxtimes \mathcal{L}_{\mu} \to G/L \times G/H$.

Besides, Theorem A gives a new geometric proof of yet more multiplicity-free theorems (see [9, Theorems 19, 20]):

- $(GL_p GL_q \text{ duality})$ The symmetric algebra $S(M(p,q; \mathbf{C})) \simeq S(\mathbf{C}^{pq})$ is multiplicity-free as a representation of $GL(p, \mathbf{C}) \times GL(q, \mathbf{C})$.
- (Kac [5]) $S(C^{pq})$ is still multiplicity-free as a representation of $GL(p-1, \mathbb{C}) \times GL(q, \mathbb{C})$.
- (Panyushev [18]) Let \mathcal{N} be a nilpotent orbit of $GL(n, \mathbb{C})$ corresponding to a partition $(2^p 1^{n-2p})$. Then the representation of $GL(n, \mathbb{C})$ on the space $\mathbb{C}[\mathcal{N}]$ of regular functions is multiplicity-free.

All of the examples discussed so far are finite dimensional. As we saw in [12], we can also expect from strongly visible actions yet more multiplicity-free theorems for infinite

dimensional representations for both continuous and discrete spectra. Applications of Theorem A (and its non-compact version) to infinite dimensional representations will be discussed in a future paper.

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