# Regular points and Green functions in Markov processes 

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## § 0. Introduction.

Our aim of this paper is to investigate the regular points of multi-dimensional standard processes having an adequate Green function $G(x, y)$ with the condition (S);
$(S)$. There exists $\alpha \in(0, d)(d \geqq 3)$ such that for any compact set $K$ given, there exist $\delta>0$ and $C_{1} C_{2} \in(0, \infty)$ such that

$$
C_{1}|x-y|^{-\alpha} \geqq G(x, y) \geqq C_{2}|x-y|^{-\alpha}
$$

for $|x-y|<\delta$ and $x, y \in K$.
In case $d=2$, we include the following case:

$$
C_{1} \log \frac{1}{|x-y|} \geqq G(x, y) \geqq C_{2} \log \frac{1}{|x-y|} .
$$

In § 1, for an adequate Green function with the condition $(S)$, we shall construct a standard process in Dynkin's sense with

$$
E_{x}\left(\int_{0}^{\zeta} f\left(x_{t}\right) d t\right)=G f(x)
$$

by modifying Ray's theory. [Th. 1.1.]
In $\S 2$ and $\S 3$, we shall apply the result of $\S 1$ to the uniformly elliptic operators of the forms
i)

$$
D^{s} u=\sum_{i \cdot j=1}^{d} \frac{\partial}{\partial x_{i}}\left(a_{i j} \frac{\partial u}{\partial x_{j}}\right),
$$

where $\left\{a_{i j}\right\}$ are bounded, measurable and symmetric,
ii).

$$
D^{*} u=\sum_{i \cdot j=1} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}}\left(a_{i j} \cdot u\right)-\sum_{i=1}^{d} \frac{\partial}{\partial x_{i}}\left(a_{i} \cdot u\right),
$$

where $\left\{a_{i j}\right\},\left\{a_{i}\right\}$ are bounded Hölder continuous, and in addition W. Littman's condition ( $L$ ) is assumed:

$$
\begin{equation*}
-\int_{\Omega} D v(x) d x \geqq 0 \tag{L}
\end{equation*}
$$

for every non-negative $C^{2}$-function $v$ with compact support in a ball $\Omega$, where $D$ is a formal adjoint operator of $D^{*}$. The continuity of the paths of the process connected with $D^{s}$ will be proved in $\S 2$.

In $\S 4$ if the standard process having a Green function with the property $(S)$ satisfies an additional condition $(R)$ :

$$
\begin{equation*}
P_{x}\left(\sigma_{A}<\zeta\right)=\int_{\bar{A}} G(x, y) \mu_{A}(d y), \tag{R}
\end{equation*}
$$

we shall prove the Wiener test (Th. 4.1) by the same idea as in Ito-Mckean [7] and in S. Watanabe [18] and using this we can see that given two processes with the Green functions satisfying the condition ( $S$ ) with the same index $\alpha$, a point is regular for one if and only if it is so for the other. [Th. 4.2.]

In $\S 5$, by verifying the condition $(R)$, we shall show that a point is regular for the canonical diffusion processes connected with $D$, its dual processes connected with $D^{*}$ and minimal diffusion processes connected with $D^{s}$, if and only if it is regular for the Brownian motion. This result corresponds to that of R.M. Hervé [4] in the case of the differential operator $D$ and of W. Littman, J. Stampacchia and F. Weinberger [11] in the case of the differential operator $D^{s}$.

When the coefficients of $D$ are assumed to be only continuous, the above result does not always hold, as is shown by an example in §7. In addition we shall show that no such example exists for the 3 -dimensional rotationinvariant process connected with $D$ with continuous coefficients.

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## § 1. Construction of a multi-dimensional standard process from a Green

 function.Let us first introduce some preliminary notions and notations.
Let $\Omega$ denote a domain in the $d$-dimensional space $R^{d}(d \geqq 2)$. We shall consider the following space of functions defined on $\Omega$.
$C_{k}$ is the space of continuous functions with compact support in $\Omega$.
$C_{0}$ is the space of continuous functions vanishing at infinity (with respect to the one-point compactification of $\Omega$ ).
Definition 1.1. A function $G(x, y): \Omega \times \Omega \rightarrow(0, \infty]$ is called a Green function if it satisfies the following four conditions.
(G. 1). $G(x, x)=\infty$ and $G(x, y)$ is continuous in $(x, y)$ as far as $x \neq y$.
(G. 2). $f \in C_{k}$ implies $G f(x) \equiv \int G(x, y) f(y) d y \in C_{0}$.
(G.3). $G f(x), f \in C_{k}$ separate any two points on $\Omega$.
(G.4). (the weak principle of the positive maximum). If $m \equiv \sup _{x \in \Omega} G f(x)$ is strictly positive, $m$ equals $\sup _{x \in S} G f(x)$, where $\left.S=\overline{\{x ; f(x)>0}\right\}$.

We shall often impose the condition (S) on the singularity of $G(x, y)$ on $x=y$.

Theorem 1.1. Given a Green function $G(x, y)$ satisfying the condition (S), we can construct a unique standard Markov process (in Dynkin's sense) $X$ $=\left(x_{t}, \zeta, M_{t}, P_{x}\right)$ with

$$
\begin{equation*}
E_{x}\left(\int_{0}^{\zeta} f\left(x_{t}\right) d t\right)=G f(x) . \tag{1.1}
\end{equation*}
$$

Proof. Using a standard method (see D. B. Ray [13], G. Lion [10]) we can construct a family of linear operators $\left\{G^{\lambda}\right\}_{\gg 0}$ satisfying the following conditions
(1.1. A) $G^{\lambda}$ maps $C_{0}$ into $C_{0}$,
(1.1. B) $\left\|\lambda G^{\lambda}\right\| \leqq 1$,*
(1.1. C) $\lambda ; \mu>0,(\mu-\lambda) G^{\lambda} G^{\mu}=G^{\lambda}-G^{\mu}$, (resolvent equation),
(1.1. $D) ~ G f=G^{\lambda}(\lambda G f+f)=G^{\lambda} f+\lambda G G^{\lambda} f, f \in C_{K}$;
$G^{\lambda}, \lambda>0$ are called resolvent operators. Using the separation assumption (G.3), we can see that for any $f \in C_{0}$ there exists a bounded measurable function $\hat{f}$ such that

$$
\begin{equation*}
\lim _{k \uparrow \infty} k G^{k} f=\hat{f} . \tag{1.2}
\end{equation*}
$$

Furthermore, in case $f$ belongs to $\overline{G\left(C_{K}\right)}=\overline{\left\{G f, f \in C_{K}\right\}}$ we have

$$
\begin{equation*}
\hat{f}=f . \tag{1.3}
\end{equation*}
$$

Therefore by applying Ray's theory [13] (cf. also H. Kunita-H. Nomoto [8]), we can construct a Markov process which may have branching points. Note that there exist positive measures of total mass $\leqq 1,\{\mu(x, d y), x \in \Omega\}$ such that

$$
\begin{equation*}
\hat{f}=\lim _{k \uparrow \infty} k G^{k} f(x)=\int_{\Omega} f(y) \mu(x, d y), \quad f \in C_{0} . \tag{1.4}
\end{equation*}
$$

$\mu(x, E)$ is called the branching measure at $x$ and $x$ is called a branching point if $\mu\left(x,\{x\}^{c}\right)>0$.

We shall later use the following property of the branching measure.
If $A$ is the set of all branching points,

$$
\begin{equation*}
\mu(x, A)=0 \quad \text { for every } x \tag{1.5}
\end{equation*}
$$

Furthermore, if $x \in \Omega-A$, we have $\hat{f}(x)=f(x)$ as was proved by G. Lion [10].
To see that there is no branching point we shall prove,

[^0]
## Proposition 1.

$$
\begin{equation*}
\lim _{k \rightarrow \infty} k G^{k} f(x)=f(x), \quad x \in \Omega, \quad f \in C_{0} . \tag{1.6}
\end{equation*}
$$

Proof. Now assume that there exists a point $x_{0} \in \Omega$ belonging to $A$. Let $U\left(x_{0}\right)$ be a neighborhood $\left\{x ;\left|x-x_{0}\right|<r\right\}$ of $x_{0}$ and $g(x)$ be a continuous function such that

$$
\begin{align*}
g(x)=1, & x \in Q, \\
0 \leqq g(x) \leqq 1, & x \in Q^{\prime}-Q,  \tag{1.7}\\
g(x)=0, & x \in \Omega-Q^{\prime},
\end{align*}
$$

where $Q=\left\{x ;\left|x-x_{0}\right|<r^{\prime}\right\}$ and $Q^{\prime}=\left\{x ;\left|x-x_{0}\right|<2 r^{\prime}\right\}\left(2 r^{\prime}<r\right)$. Then we can select a sufficiently large compact set $K$ such that

$$
\begin{equation*}
\int_{\Omega-K} \int_{\Omega} G(x, y) g(y) d y \mu\left(x_{0}, d y\right)<\frac{1}{3} \int G\left(x_{0}, y\right) g(y) d y \tag{1.8}
\end{equation*}
$$

for sufficiently small any $r^{\prime}$. Indeed, by the condition ( $S$ ) we have

$$
\int_{\Omega} G\left(x_{0}, y\right) g(y) d y \geqq \mathrm{const} \int_{\Omega}\left|x_{0}-y\right|^{-\alpha} g(y) d y \geqq \mathrm{const} \int_{Q}\left|x_{0}-y\right|^{-\alpha} d y
$$

and

$$
\sup _{x \in Q^{\prime}} \int G(x, y) g(y) d y \leqq \sup _{x \in Q^{\prime}} \operatorname{const} \int_{Q^{\prime}}|x-y|^{-\alpha} d y=\operatorname{const} \int_{Q^{\prime}}\left|x_{0}-y\right|^{-\alpha} d y .
$$

Hence, if we choose a large compact set $K$ such that $\mu\left(x_{0}, \Omega-K\right)$ is sufficienly small, noting that there exists an absolute constant $M$ such that

$$
1 \leqq \frac{\int_{Q^{2}}\left|x_{0}-y\right|^{-\alpha} d y}{\int_{Q}\left|x_{0}-y\right|^{-\alpha} d y}<M
$$

we have by the weak principle of the positive maximum the left-hand side of

$$
\begin{equation*}
\leqq \sup _{x \in \Omega-K} \int_{\Omega} G(x, y) g(y) d y \mu\left(x_{0}, \Omega-K\right) \leqq \sup _{x \in Q^{Q}} \int_{\Omega} G(x, y) g(y) d y \mu\left(x_{0}, \Omega-K\right) \tag{1.8}
\end{equation*}
$$

$<$ the right-hand side of (1.8).
Using (G.1) and (S) we can obtain constants $C_{1}, C_{2}>0$ depending only on $K$ such that

$$
C_{1} \cdot\left|x_{1}-x_{2}\right|^{-\alpha} \geqq G\left(x_{1}, x_{2}\right)>C_{2} \cdot\left|x_{1}-x_{2}\right|^{-\alpha}, x_{1}, x_{2} \in K,
$$

by change $C_{1}$ and $C_{2}$ in the condition (S). Furthermore, by (1.5), it holds $\mu\left(x_{0},\left\{x_{0}\right\}\right)=0$, so we can select $U\left(x_{0}\right)$ sufficiently small such that

$$
\begin{equation*}
\mu\left(x_{0}, U\left(x_{0}\right)\right)<\frac{C_{2}}{C_{1}} \frac{1}{3 M}, \tag{1.9}
\end{equation*}
$$

where $M$ is an absolute constant which depends only on the dimension $d$ and will be determined later. Hereafter we shall fix $K$ and $U\left(x_{0}\right)$. By choosing $r^{\prime}$ sufficiently small, we have

$$
\begin{equation*}
\sup _{K-U\left(x_{0}\right) \equiv x} \int_{\Omega} G(x, y) g(y) d y<\frac{1}{3} \int_{\Omega} G\left(x_{0}, y\right) g(y) d y . \tag{1.10}
\end{equation*}
$$

Indeed it holds

$$
\begin{gathered}
\sup _{x \in K-U\left(x_{0}\right)} \int_{\Omega} G(x, y) g(y) d y<C_{1}\left(r-2 r^{\prime}\right)^{-\alpha}\left|Q^{\prime}\right|, \\
\int_{\Omega} G\left(x_{0}, y\right) g(y) d y>C_{2}\left(2 r^{\prime}\right)^{-\alpha}|Q| .
\end{gathered}
$$

As $r^{\prime}$ is sufficiently small, we have $\frac{1}{3} C_{2}\left(2 r^{\prime}\right)^{-\alpha}|Q|>C_{1}\left(r-2 r^{\prime}\right)^{-\alpha}\left|Q^{\prime}\right|$. So we obtain (1.10). In the following, we shall show that there exists a constant $M$ depending only on the dimension $d$ such that

$$
\begin{equation*}
\frac{\sup _{x \in U\left(x_{0}\right)} \int_{\Omega} G(x, y) g(y) d y}{\int_{\Omega} G\left(x_{0}, y\right) g(y) d y}>\frac{C_{1}}{C_{2}} M . \tag{1.11}
\end{equation*}
$$

Indeed we have

$$
\begin{aligned}
& \text { the left-hand side of }(1.11)<\frac{C_{1} \sup _{x \in U\left(x_{0}\right)} \int_{\Omega}|x-y|^{-\alpha} g(y) d y}{C_{2} \int_{\Omega}\left|x_{0}-y\right|^{-\alpha} g(y) d y} \\
& \quad<\frac{C_{1} \sup _{x \in U\left(x_{0}\right)} \int_{Q^{\prime}}|x-y|^{-\alpha} d y}{C_{2} \int_{Q}\left|x_{0}-y\right|^{-\alpha} d y}=\frac{C_{1} \int_{Q^{\prime}}\left|x_{0}-y\right|^{-\alpha} d y}{C_{2} \int_{Q}\left|x_{0}-y\right|^{-\alpha} d y} \leqq \frac{C_{1}}{C_{2}} M .
\end{aligned}
$$

From (1.9), (1.11), (1.10) and (1.8), we obtain

$$
\begin{aligned}
& \int_{\Omega} \int_{\Omega} G(x, y) g(y) d y \mu\left(x_{0}, d x\right)=\int_{U\left(x_{0}\right)} \int_{\Omega} G(x, y) g(y) d y \mu\left(x_{0}, d x\right) \\
& \quad+\int_{K-U\left(x_{0}\right)} \int_{\Omega} G(x, y) g(y) d y \mu\left(x_{0}, d x\right)+\int_{\Omega-K} \int_{\Omega} G(x, y) g(y) d y \mu\left(x_{0}, d x\right) \\
& \quad<\frac{C_{1}}{C_{2}} M \int_{\Omega} G\left(x_{0}, y\right) g(y) d y \cdot \frac{C_{2}}{C_{1}} \frac{1}{3 M}+\frac{1}{3} \int_{\Omega} G\left(x_{0}, y\right) g(y) d y \\
& \quad+\frac{1}{3} \int_{\Omega} G\left(x_{0}, y\right) g(y) d y=\int_{\Omega} G\left(x_{0}, y\right) g(y) d y
\end{aligned}
$$

in contradiction with (1.3). Hence we have $A=\phi$.
To see that the process obtained above is a standard process we need only prove

Proposition 2. If we set

$$
G\left(C_{0}\right)=\left\{G^{\lambda} f ; f \in C_{0}, \lambda>0\right\},
$$

$G\left(C_{0}\right)$ is dense in $C_{0}$ with respect to the uniform norm.
Proof. From the results of D. B. Ray [13] (cf. G. Lion [10]), when $f$ belongs to the following function class;

$$
E_{\lambda}=\left\{f \in C_{0}, \text { non-negative, } \forall k \geqq 0, k G^{k+\lambda} f \leqq f\right\} \text {, }
$$

$k G^{k} f$ increases to $f$ monotonically as $k \uparrow \infty$. By (1.1. $A$ ) $k G^{k} f \in C_{0}$ and by Proposition $1 \hat{f}=f \in C_{0}$, and so by the Dini's theorem, we have $\lim _{k \uparrow \infty} k G^{k} f(x)=f(x)$, uniformly in $x$. Therefore, for any $f \in \tilde{E}=\left\{f \in C_{0}, f=f_{1}-f_{2}, f_{i} \in \bigcup_{\lambda>0} E\right\}$, we see that the convergence is uniform. To complete the proof of our proposition, we have only to note that $\tilde{E}$ is dense in $C_{0}$, which is shown in [10].

By the above results we can apply the Hille-Yosida theorem to construct a semi-group $\left\{T_{t}\right\}_{t \geqq 0}$ which is strong continuous and sub-Markov on $C_{0}$ such that

$$
G^{\lambda} f=\int_{0}^{\infty} e^{-\lambda t} T_{t} f d t
$$

The transition probability $P(t, x, \Gamma)$ corresponding to this semi-group is continuous in the sense that

$$
\lim _{t \downarrow 0} P(t, x, U)=1, U \text { open set } \ni x
$$

by Dynkin [2], lemma 2.10. Following Dynkin [2], Th. 3.7, we can construct a bounded Markov process whose almost all paths are right continuous and have left limits. Furthermore, by Dynkin [2], Th. 3.10, it is strong Markov, so that by Dynkin [2] Th. 3.13, we find that it has quasi-left-continuity. Thus the process obtained above is a standard process.

Remark. Under the condition ( $S$ ), ( $G .3$ ) is satisfied necessarily. For any two points $x_{0}, y_{0}$ such that $\left|x_{0}-y_{0}\right|=r$, let $Q, Q^{\prime}$ be sufficiently small balls

$$
Q=\left\{y ; x_{0}-y \mid<r^{\prime}\right\} \quad \text { and } \quad Q^{\prime}=\left\{y ;\left|x_{0}-y\right|<2 r^{\prime}\right\}\left(2 r^{\prime}<r\right) .
$$

Then we can construct a potential $G g(x)=\int_{\Omega} G(x, y) g(y) d y$ which separates $x_{\sigma}$ and $y_{0}$ by choosing an adequate function $g(x)$ having the form (1.7).

## § 2. A diffusion process connected with the self-adjoint elliptic operator of second order.

In this section we shall consider the following differential operator in the $d$-dimensional space $R^{d}(d \geqq 3)$

$$
D^{s} u=\sum_{i \cdot j=1}^{d} \frac{\partial}{\partial x_{i}}\left(a_{i j} \frac{\partial u}{\partial x_{j}}\right)
$$

where $\left\{a_{i j}\right\}$ are symmetric with respect to $i \cdot j$, bounded and measurable, $D^{s}$ is assumed to be uniformly elliptic. For this operator on a ball $\Omega, \mathrm{W}$. Littman, G. Stampacchia and F. Weinberger [12] have shown that there exists a Green function $G(x, y)$ having the condition (S) with $\alpha=d-2$, which is a weak solution of $-D^{s} G=\delta_{y}$ in the sense of [12]. (G.1)~(G.3) are proved in [12], P. 64~P. 67. (G. 4) is proved as follows.

For any $f \in C_{K}(\Omega), G f(x)$ is a solution of $-D^{s} G f(x)=f(x)$, so we have by the definition

$$
\Sigma \int_{\Omega} a_{i j} \frac{\partial}{\partial \bar{x}_{i}} G f(x) \cdot \phi_{x_{i}} d x=\int_{\Omega} f \cdot \phi d x
$$

where $\phi \in H_{0}^{1,2}(\Omega)$. Let $S$ be $\left.S=\overline{\{x ; f(x)>0}\right\}$ and $\phi$ be a non-negative function with compact support in $\Omega-S$ belonging to $C^{\infty}(\Omega)$. Then we have

$$
\int_{\Omega} \sum_{i, j=1}^{d} a_{i j} \frac{\partial}{\partial x_{i}} G f(x) \cdot \phi_{x_{j}} d x=\int_{\Omega} f(x) \cdot \phi(x) d x=\int_{\Omega-S} f(x) \cdot \phi(x) d x \leqq 0
$$

Hence $G f$ is a $D^{s}$-subsolution in $\Omega-S$, and so we can apply G. Stampacchia's maximum theorem [16] to $G f-m$ where $m=\sup _{x \in S} G f(x)$, which is clearly non positive on $\partial(\Omega-S)$. Then $G f \leqq m$ on $\Omega-S$, and so

$$
m \geqq G f(x), \quad \forall x \in \Omega
$$

From this Green function we can construct a standard process by Theorem 1.3. We call this process the minimal process associated with $D^{s}$ and is denoted by $X^{s}$.

We are going to prove the continuity of the sample paths of this process. Let us first observe the following fact for a standard process in general.

Lemma 2.1. If for an arbitrary ball $Q \subset \Omega$ and a point $x_{0} \in \Omega-\bar{Q}$, there exist functions $f_{1}, f_{2}$ with compact supports in $\Omega-\bar{Q}$, measurable, such that $G f_{1}$, $G f_{2}$ are bounded measurable and
i) $G f_{1}(x) \geqq G f_{2}(x)$ for $x \in \Omega$
ii) $G f_{1}(x)=G f_{2}(x) \quad$ for $x \in Q$
iii) $G f_{1}(x)>G f_{2}(x)$ for some neighborhood $U\left(x_{0}\right)$ of $x_{0}$, then the harmonic measure concentrates on the boundary of $Q$, that is,

$$
P_{x}\left(x_{\tau} \in \Omega-\bar{Q}\right)=0
$$

where $\tau_{Q}=\inf \left(t \geqq 0, x_{t} \notin Q\right)$.
Proof. By Dynkin's formula we have

$$
\begin{equation*}
E_{x} G f_{i}\left(x_{\tau_{Q}}\right)=G f_{i}(x) \quad \text { for } x \in Q, i=1,2 \tag{2.1}
\end{equation*}
$$

Now we suppose that the harmonic measure $P_{x}\left(x_{\tau_{Q}} \in d y\right)$ has strictly positive mass on a neighborhood $U\left(x_{0}\right)$ of $x_{0}$. Then we have

$$
E_{x} G f_{1}\left(x_{\tau_{Q}}\right)>E_{x} G f_{2}\left(x_{\tau_{Q}}\right) .
$$

This contradicts (2.1).
TheOrem 2.1. There exists a continuous standard process $X=\left(x_{t}, \zeta, M_{t}, P_{x}\right)$ on $\Omega$ whose generator is $D^{s}$.

Proof. We have only to show the continuity of the sample paths. For any ball $Q \in \Omega$ and any point $x_{0} \in \Omega-\bar{Q}$, let us consider the following function $g_{a}(x)$ ( $a$; positive constant) which is used in $[12]$ for other purpose,

$$
g_{a}(x)=\left\{\begin{array}{l}
-\frac{1}{2 a} \sum_{i \cdot j=1}^{d} a_{i j} \frac{\partial}{\partial x_{i}} G_{x_{0}}(x) \cdot-\frac{\partial}{\partial x_{j}} G_{x_{0}}(x), a \leqq G_{x_{0}}(x) \leqq 3 a, \\
0, \quad \text { otherwise },
\end{array}\right.
$$

where $G_{x_{0}}(x)=G\left(x, x_{0}\right)$. Then we have

$$
\int_{\Omega} G(x, y) g_{a}(y) d y=\left\{\begin{array}{l}
G_{x_{0}}(x), \quad G_{x_{0}}(x) \leqq a, \\
G_{x_{0}}(x)-\frac{1}{4 a}\left(G_{x_{0}}(x)-a\right)^{2}, \quad a \leqq G_{x_{0}}(x) \leqq 3 a, \\
2 a, \quad G_{x_{0}}(x) \geqq 3 a .
\end{array}\right.
$$

If we fix a sufficiently large compact subset $K$ of $\Omega$ in the condition (S), there exists a constant $C>0$ such that

$$
C r^{2-d}>G\left(x, x_{0}\right) \quad \text { for any } x \in \bar{Q},
$$

where $r$ denotes the distance between $x_{0}$ and $Q$. Hence if we select a constant $a$ such that $a \geqq C r^{2-d}$, we have $g_{a}(x)=0$ in $Q$. Let us set $f_{1}(x)=g_{3 a}(x)$ and $f_{2}(x)=g_{a}(x)$, then $f_{1}$ and $f_{2}$ satisfies the conditions i), ii), iii) in lemma 2.1, so we have

$$
P_{x}\left(x_{\tau_{Q}} \in \Omega-\bar{Q}\right)=0
$$

for each ball $Q$. This means that almost all sample paths are continuous from Courrege and Priouret [1] and R. Kondo [unpublished].

## § 3. The dual process of the canonical diffusion process.

Let us consider the following differential operator $D^{*}$ in $R^{d}$

$$
D^{*} u=\sum_{i \cdot j}^{d} \frac{\partial}{\partial x_{i} \partial x_{j}}\left(a_{i j} \cdot u\right)-\sum_{i=1}^{d} \frac{\partial}{\partial x_{i}}\left(a_{i} \cdot u\right)
$$

where $\left\{a_{i j}\right\},\left\{a_{j}\right\}$ are Hölder continuous and bounded and $\left\{a_{i j}\right\}$ is strictly positive definite. $D^{*}$ is the formal adjoint operator of the strictly elliptic operator $D$

$$
D u=\sum_{i \cdot j}^{d} a_{i j} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}} u+\sum_{i=1}^{d} a_{i} \frac{\partial u}{\partial x_{i}} .
$$

The Markov process whose generator is $D$ is called a (minimal) canonical diffusion process $X$ [2]. Hereafter we shall assume W. Littman's condition

$$
\begin{equation*}
-\int_{\Omega} D v(x) d x \geqq 0 \tag{L}
\end{equation*}
$$

for every non-negative $C^{2}$-function $v$ with compact support in $\Omega$.
Let us set

$$
G^{*}(x, y)=G^{\Omega}(y, x)
$$

where $G^{\Omega}(x, y)$ is the Green function in a ball $\Omega$ of $D$.
THEOREM 3.1. There exists a standard Markov process $X^{*}$ in a ball in the sense of theorem 1.1 with respect to $G^{*}(x, y)$.

Proof. It is sufficient to prove that $G^{*}(x, y)$ is the Green function with the condition (S). The property ( $G .1$ ) is obvious, because it is true for $G(y, x)$. The property (G.4) is proved by using the following W. Littman's theorem [11], theorem B. p. 210. Let $Q$ be a smooth domain in $\Omega$.
W. Littman's theorem: if under the condition ( $L$ )

$$
\begin{equation*}
\int_{\Omega} u(x) D v(x) d x \geqq 0 \tag{3.1}
\end{equation*}
$$

holds for all non-negative $v$ in $C^{2}(Q)$ with compact support in $Q$ where $u$ is locally integrable in $Q$, and if, in addition, for some compact subdomain $Q^{\prime} \subset Q$ we have

$$
0 \leqq M \equiv \underset{x \in Q}{\operatorname{ess} \sup } u(x)=\underset{x \in Q^{\prime}}{\operatorname{ess} \sup } u(x)
$$

then $u=M$ almost everywhere in $Q$.
Indeed, let $u(x)$ be $\int G^{*}(x, y) f(y) d y$, where $f \in C_{K}$, and let $S$ be $\overline{\{x ; f(x)>0\}}$. Then for any smooth domain $Q \subset \Omega-S$ and any non-negative $C^{2}$-function $v$ with compact support in $Q$ we have

$$
\begin{aligned}
\int_{Q} \int_{\Omega} G^{*}(x, y) f(y) d y D v(x) d x & =\int_{\Omega} f(y) d y \int_{\Omega} G^{\Omega}(y, x) D v(x) d x \\
=-\int_{\Omega} f(y) v(y) d y & =-\int_{Q} f(y) v(y) d y \geqq 0
\end{aligned}
$$

Hence, if we set $m=\sup _{x \in S} u(x)$, then $u(x)-m \vee o$ satisfies (3.1) by the condition (L). Suppose $A=\sup _{x \in \Omega} u(x)>m \vee 0$, then this supremum is attained at some point $z$ in $\Omega-S$ because $u \in C_{0}(\Omega)$. ( $u \in C_{0}(\Omega)$ follows from (G.2) which is proved later without using (G.4).) Let $z$ be such a point. Then for any smooth domain $Q$ inside $\Omega-S$ and containing $z$ the hypothesis of Littman's
theorem is satisfied, and hence $u=A$ inside $Q$, that is, $u=A$ on the part of $\partial S$. But this contradicts $u \in C_{0}(\Omega)$.

To verify the condition (S), it suffices to prove it for the Green function $G(x, y)$ in $R^{d}$ of the operator $D$. We can show this by using a theorem in $D$. Gilbarg and J. Serrin [3], which is an extension of the so-called maximum principle, but here we shall prove it, using the estimate of the fundamental solution $p(t, x, y)$ in $R^{d}$ of $D p=\frac{\partial p}{\partial t}$ with $\lim _{|x| \rightarrow \infty} p(t, x, y)=0$ :

$$
\begin{gathered}
G(x, y)=\int_{0}^{\infty} p(t, x, y) d t, x, y \in R^{d}, \\
p(t, x, y) \leqq M t^{-d / 2} e^{-\frac{\alpha(y-x) 2}{t}}, \\
p(t, x, y) \geqq M_{1} t^{-d / 2} e^{-\frac{\alpha_{1} 1 y-x \mid 2}{t}}-M_{2} t^{-\frac{d}{2}+2} e^{-\frac{\alpha_{2}|y-x| 2}{t}},
\end{gathered}
$$

where $M, \alpha, M_{1}, M_{2}, \alpha_{1}, \alpha_{2}, \lambda$ are positive constants [6]. The proof is as follows. We define $p_{1}(t, x, y), p_{2}(t, x, y)$ by $p_{1}(t, x, y)=M_{1} t^{-d / 2} e^{-\alpha_{1}|y-x|^{2 / h}}, p_{2}(t, x, y)$ $\left.=M_{2} t-\alpha / 2\right)+\lambda e^{-\alpha_{2}|y-x| 2 / t}$, and choose constants $\delta, r_{1}, C_{2}^{\prime}$ such that

$$
\delta=\left(\frac{1}{4} \frac{\alpha_{2}}{\alpha_{1}} \frac{M_{1}}{M_{2}}\right)^{1 / \lambda}
$$

$$
\begin{align*}
r_{1} & =\left(\frac{\delta^{(d / 2)-1}}{2\left(\frac{2}{d-2}\right) \alpha / \Gamma\left(\frac{d}{2}\right)}\right)^{1 / d-2}  \tag{3.2}\\
C_{2}^{\prime} & =\frac{1}{4} \frac{M_{1}}{\alpha_{1}} \Gamma(d / 2) .
\end{align*}
$$

Then, from the following estimate,

$$
\begin{aligned}
& \int_{0}^{\infty} p_{1}(t, x, y) d t=M_{1} \frac{\Gamma(d / 2)}{\alpha_{1}} \frac{1}{|x-y|^{d-2}} \\
& \int_{\delta}^{\infty} p_{1}(t, x, y) d t<M_{1} \int_{\delta}^{\infty} t^{-d / 2} d t=M_{1}\left(\frac{2}{d-2}\right) \delta^{-d / 2+1}
\end{aligned}
$$

we have

$$
\int_{0}^{\delta} p_{1}(t, x, y) d t>M_{1} \frac{\Gamma(d / 2)}{\alpha} \frac{1}{|x-y|^{d-2}}-M_{1}\left(\frac{2}{d-2}\right) \delta^{-\frac{d}{2}+1}
$$

and from (3.2) we have

$$
\int_{0}^{\delta} p_{1}(t, x, y) d t \geqq \frac{1}{2}-M_{1} \frac{\Gamma(d / 2)}{\alpha_{1}} \frac{1}{|x-y|^{d-2}}, \quad \text { for }|x-y|<r_{1} .
$$

Hence, noting $p(t, x, y) \geqq p_{1}(t, x, y)-p_{2}(t, x, y)$, we have for $|x-y|<r_{1}$

$$
\begin{aligned}
& \int_{0}^{\infty} p(t, x, y) d t \geqq \int_{0}^{\delta} p(t, x, y) d t \\
& \quad \geqq \frac{1}{2} M_{1} \frac{\Gamma(d / 2)}{\alpha_{1}} \frac{1}{|x-y|^{d-2}}-\delta^{\lambda} \int_{0}^{\infty} t^{-d / 2} e^{-\frac{\alpha_{2}|y-x|^{2}}{t} d t} \cdot M_{2} \\
& \quad=\frac{1}{2} M_{1} \frac{\Gamma(d / 2)}{\alpha_{1}} \frac{1}{|x-y|^{d-2}}-\delta^{\lambda} M_{2} \frac{\Gamma(d / 2)}{\alpha_{2}} \frac{1}{|x-y|^{d-2}} \\
& \quad=\frac{1}{4} M_{1} \frac{\Gamma(d / 2)}{\alpha} \frac{1}{|x-y|^{d-2}}=C_{2}^{\prime} \frac{1}{|x-y|^{d-2}} .
\end{aligned}
$$

It is obvious that $C_{1} \frac{1}{|x-y|^{a-2}} \geqq G(x, y), C_{1}>0$. Therefore the condition ( $S$ ) is satisfied for $\alpha=d-2(d \geqq 3)$.

To prove the property ( $G .2$ ) we have only to show

$$
\lim _{x \rightarrow a} G^{*}(x, y)=\lim _{x \rightarrow a} G(y, x)=0, \quad a \in \partial \Omega .
$$

In the following we shall use the notion "(super) harmonic (X) in $G$ " for brevity, which means " (super) harmonic in an open set $G$ with respect to a Markov process $X$ " according to Dynkin's book [2]. Noting that $G^{\Omega}(x, y)$ $=G(x, y)-E_{x} G\left(x_{\tau \Omega}, y\right)$, we have only to show for $x \in \Omega$

$$
\begin{equation*}
\lim _{y_{m} \rightarrow y} E_{x} G\left(x_{\tau \Omega}, y_{m}\right)=G(x, y), y_{m} \in \Omega, y \in \partial \Omega . \tag{3.3}
\end{equation*}
$$

First, by Fatou's lemma we have

$$
\begin{align*}
& \frac{\lim _{y_{m} \rightarrow y}}{} E_{x} G\left(x_{\tau \Omega}, y_{m}\right) \geqq E_{x} \underline{l i m}_{y_{m} \rightarrow y} G\left(x_{\tau \Omega}, y_{m}\right)  \tag{3.4}\\
& =E_{x} G\left(x_{\tau \Omega}, y\right), y_{m} \in \Omega, y \in \partial \Omega, x \in \Omega .
\end{align*}
$$

On the other hand, as $G(x, y)$ is superharmonic ( $X$ ) in $x$, we have

$$
\begin{equation*}
\varlimsup_{y_{m} \rightarrow y} E_{x} G\left(x_{\tau \Omega}, y_{m}\right) \leqq \varlimsup_{y_{m} \rightarrow y} G\left(x, y_{m}\right)=G(x, y), x \in \Omega . \tag{3.5}
\end{equation*}
$$

Therefore, if we can prove $E_{x} G\left(x_{\tau_{\Omega}}, y\right)=G(x, y)$, we obtain (3.3) from (3.4) and (3.5). Let $y \in \partial \Omega$ and let 0 be a center of $\Omega$. If we choose a sequence $\left\{y_{n}\right\}$ on the half line $\overrightarrow{0 Y} \cap \bar{\Omega}^{\mathrm{c}}$ which converges to $y$ as $m$ tends to infinity, we have

$$
G\left(u, y_{n}\right) \leqq \frac{C_{1}}{\left|u-y_{n}\right|^{d-2}} \leqq \frac{C_{1}}{|u-y|^{d-2}} \leqq \frac{C_{1}}{C_{2}} G(u, y)
$$

for all $u \in \partial \Omega$ by the property $(S)$ of $G(x, y)$, and $G\left(u, y_{n}\right)$ converges $G(u, y)$ as $n$ tends to infinity. Hence, noting $E_{x}\left(G\left(x_{\tau \Omega}, y\right)<\infty\right.$ by (3.4) and (3.5), we have by Lebesgue's convergence theorem

$$
\begin{equation*}
\lim _{n \rightarrow \infty} E_{x} G\left(x_{\tau_{\Omega} \Omega}, y_{n}\right)=E_{x} G\left(x_{\tau_{\Omega} \Omega}, y\right) . \tag{3.6}
\end{equation*}
$$

Noting that $E_{x} G\left(x_{\tau \Omega}, y_{n}\right)=G\left(x, y_{n}\right), x \in \Omega$, because $G(x, y)$ is harmonic ( $X$ ) in
$R^{d}-\{y\}$, we get $E_{x} G\left(x_{\tau \Omega}, y\right)=G(x, y)$. Thus (3.3) was proved. The property ( $G .3$ ) follows from the remark of $\S 1$.

Remark. Let $A^{*}$ be the strong infinitesimal operator of $X^{*}$. Then a function $u(x) \in C_{0}(\Omega)$ such that

$$
A^{*} u(x)=-f(x) \text { in } \Omega \text { for } f \in C_{0}(\Omega)
$$

is a weak solution of $D^{*} u(x)=f(x)$ in W. Littman's sense, that is: $u(x)$ is locally integrable in $\Omega$ and it satisfies

$$
\int_{\Omega} u(x) D v(x) d x=-\int_{\Omega} f(x) v(x) d x
$$

for all $v$ in $C^{2}(\Omega)$ with compact support in $\Omega$.

## §4. Wiener test and regular points.

Throughout this section, we shall assume that we are given a Green function $G(x, y)$ which satisfies the condition ( $S$ ) and the standard process $X=\left(x_{t}, \zeta, M_{t}, P_{x}\right)$ corresponding to $G$ by Theorem 1.1. In addition we shall assume the following condition ( $R$ ).
(R). If $A$ is an analytic set with compact closure, there exists a finite measure $\mu_{A}$ concentrating on $\bar{A}$ such that

$$
P_{x}\left(\sigma_{A}<\zeta\right)=\int_{\bar{A}} G(x, y) \mu_{A}(d y),
$$

where $\sigma_{A}=\inf \left(t>0, x_{t} \in A\right)=\zeta$ if $x_{t} \notin A$ for every $t>0$.
The condition ( $R$ ) corresponds to the so-called Riesz's representation theorem. We shall discuss the validity of $(R)$ in $\S 5$. A point $x$ is said to be a regular point of an analytic set $B$ for the process $X$, if it holds

$$
P_{x}\left(\sigma_{B}=0\right)=1
$$

for the probability law $P_{x}$ of the path of the process $X$ starting at $x$.
Our aim of this section is to prove the following results:
Theorem 4.1. The Wiener test which determines whether a point is regular or not holds for the above standard process $X=\left(x_{t}, \zeta, M_{t}, P_{x}\right)$, that is: let $B$ be an analytic set and let $x$ be its boundary point and set

$$
B_{k}=\left\{y ; \frac{1}{2^{k}}<|y-x| \leqq \frac{1}{2^{k-1}}\right\} \cap B .
$$

Then, $x$ is a regular point of $B$ for the process $X$, if and only if

$$
\begin{equation*}
\sum_{k=1}^{\infty} 2^{k \alpha} C\left(B_{k}\right)=\infty, \tag{4.1}
\end{equation*}
$$

where $C\left(B_{k}\right)=\mu_{B_{k}}(\bar{B})\left(\right.$ capacity of $\left.B_{k}\right)$.

Theorem 4.2. Let $X_{1}^{\alpha}$ and $X_{2}^{\alpha}$ be two standard processes corresponding to the Green functions $G_{1}$ and $G_{2}$ which satisfy the condition (S) for the same $\alpha$ and assume the condition ( $R$ ). Then a point $x \in \Omega$ is a regular point of an analytic set $B \subset \Omega$ for the process $X_{1}^{\alpha}$, if and only if it is a regular point of $B$ for the process $X_{2}^{\alpha}$.

To prove Theorem 4.1 we shall first prepare several lemmas.
Lemma 4.1. Let $0_{n}$ be a sequence of balls with the common center $z$ such that $0_{n} \downarrow z$ as $n \uparrow \infty$. Then

$$
\begin{equation*}
\lim _{n \rightarrow \infty x \in \Omega-0_{1}} P_{x}\left(\sigma_{0_{n}}<\zeta\right)=0 . \tag{4.2}
\end{equation*}
$$

Proof. We fix a compact set $K \subset \Omega$ which contains every $0_{n}$. Then by the conditions ( $S$ ) and ( $R$ ), we have

$$
C_{2} r_{n}^{-\alpha} \mu_{0_{n}}\left(\overline{0}_{n}\right) \leqq \int_{\overline{0}_{n}} G(z, y) \mu_{0_{n}}(d y)=P_{z}\left(\sigma_{0_{n}}<\zeta\right) \leqq 1,
$$

where $r_{n}$ is the radius of $\overline{0}_{n}$. Hence we have $\mu_{0_{n}}\left(0_{n}\right) \downarrow 0$ as $n \uparrow \infty$. On the otherhand, it holds

$$
\sup _{x \in \Omega-0_{1}} P_{x}\left(\sigma_{0_{n}}<\zeta\right) \leqq C_{1}\left|r_{1}-r_{n}\right|^{-\alpha} \mu_{0_{n}}\left(\overline{0}_{n}\right)+a \mu_{0_{n}}\left(\overline{0}_{n}\right)
$$

where $a$ is a constant such that $\sup _{\substack{x \in Q_{B} K \\ y \in \overline{0}_{1}}} G(x, y)=a$. Hence we have

$$
\sup _{x \in \Omega-0_{1}} P_{x}\left(\sigma_{0_{n}}<\zeta\right)<\frac{C_{1}\left|r_{1}-r_{n}\right|^{-\alpha}}{C_{2} r_{n}^{-\alpha}}+a \mu_{0_{n}}\left(\overline{0}_{n}\right) \rightarrow 0 \text { as } n \rightarrow \infty .
$$

Remark 1. We see easily that a point $x$ is not a regular point of $\{x\}$ for $X$.

Lemma 4.2. A point $x$ is a regular point of $B$ for $X$, if and only if

$$
\begin{equation*}
P_{x}\left(\overline{(i m}_{k \uparrow \infty} B_{k}^{*}\right)>0, \tag{4.3}
\end{equation*}
$$

where $B_{k}^{*}=\left\{\sigma_{B_{k}}<\zeta\right\}$.
Proof. i) Suppose that $x$ is not a regular point of $B$ for $X$ and that (4.3) holds. Noting that

$$
P_{x}\left\{\bigcup_{n=1}^{\infty}\left(0<\forall t<\sigma_{0_{n}^{c}}, x_{t} \notin B\right)\right\}=P_{x}\left(\sigma_{B}>0\right)^{*)},
$$

where $0_{n}=\left\{y:|y-x|<\frac{1}{2^{n}}\right\} \cap \Omega$, we see that for any given $\varepsilon>0$ there exists a number $n_{0}$ such that

$$
\begin{equation*}
P_{x}\left(0<\forall t<\sigma_{0_{n_{0}}^{c}}, x_{t} \oplus B\right) \geqq 1-\varepsilon^{* *)} . \tag{4.4}
\end{equation*}
$$

[^1]On the other hand, it holds that

$$
\begin{aligned}
& P_{x}\left(\sigma_{G_{n}}<\zeta\right)=P_{x}\left(0<\forall t<\sigma_{0_{n 0}}^{c}, x_{t} \notin B, \sigma_{G_{n}}<\zeta\right)+P_{x}\left(0<\exists t<\sigma_{0_{n_{0}}^{c}}, x_{t} \in B, \sigma_{G}<\zeta\right) \\
& \quad=E_{x}\left(P_{x_{\sigma_{0}^{c}}}\left(\sigma_{G_{n}}<\zeta\right), 0<\forall t<\sigma_{0_{n 0}^{c}}, x_{t} \oplus B\right)+P_{x}\left(0<\exists t<\sigma_{0_{n_{0}}^{c}}, x_{t} \in B, \sigma_{G n}<\zeta\right)
\end{aligned}
$$

for each $n>n_{0}$ where $G_{n}=\left\{y ;|y-x| \leqq \frac{1}{2^{n}}\right\} \cap B$. Hence, by (4.4) and lemma 4.1, we have

$$
\begin{equation*}
P_{x}\left(\sigma_{G_{n}}<\zeta\right)=\sup _{z \in \Omega-0_{n_{0}}} P_{z}\left(\sigma_{G_{n}}<\zeta\right)+\varepsilon \leqq 2 \varepsilon \tag{4.5}
\end{equation*}
$$

for sufficiently large $n$. As $\varepsilon$ is arbitrary, (4.5) contradicts (4.3). Hence $x$ is a regular point of $B$ for $X$, if (4.3) holds.
ii) Suppose that

$$
P_{x}\left(\overline{\lim }_{n \rightarrow \infty} B_{n}^{*}\right)=0 .
$$

Then we can easily show that $x$ is not a regular point of $B$ for $X$.
The following Lamperti's lemma [9] is used to prove the next lemma.
Let the sequence of events $\left\{E_{k}, k=1,2, \cdots\right\}$ satisfy the following conditions,
i)

$$
\sum_{k=1}^{\infty} P_{x}\left(E_{k}\right)=\infty
$$

ii) there exist positive constants $N$ and $C$ such that $P_{x}\left(E_{n} \cap E_{m}\right) \leqq$ $C P_{x}\left(E_{n}\right) P_{x}\left(E_{m}\right)$ for all $n>m>N$. Then $P_{x}\left(\varlimsup_{k \rightarrow \infty} E_{k}\right)>0$.

Lemma 4.3. $A$ point $x$ is a regular point of $B$ for $X$, if and only if

$$
\begin{equation*}
\sum_{k=1}^{\infty} P_{x}\left(B_{k}^{*}\right)=\infty \tag{4.7}
\end{equation*}
$$

Proof. We first notice that $\phi(r)=r^{-\alpha}$ posseses the following properties;
$\alpha) \phi(r)$ is continuous except at $r=0$.
$\beta) \quad \phi(r) \uparrow \infty$ as $r \downarrow 0$.
r) There exists a positive constant $M$ independent of $r$ such that

$$
\begin{equation*}
\frac{\phi\left(\frac{r}{2}\right)}{\phi(r)} \leqq M \tag{4.8}
\end{equation*}
$$

i) If $\sum_{k=1}^{\infty} P_{x}\left(B_{k}^{*}\right)<\infty$, we have

$$
P_{x}\left(\overline{\lim _{k \uparrow \infty}} B_{k}^{*}\right)=0
$$

by Borel-Cantelli lemma. Hence $x$ is not a regular point of $B$.
ii) If $\sum_{k=1}^{\infty} P_{x}\left(B_{k}^{*}\right)=\infty$, either $\sum_{k=1}^{\infty} P_{x}\left(B_{2 k}^{*}\right)$ or $\sum_{k=1}^{\infty} P_{x}\left(B_{2 k+1}^{*}\right)$ diverges. We sup-
pose that the former diverges. When $k>j$, we have

$$
\begin{aligned}
& P_{x}\left(B_{2 k}^{*} \cap B_{2 j}^{*}\right)=P_{x}\left(\sigma_{B_{2 k}}<\zeta, \sigma_{B_{2 j}}<\zeta\right) \\
& =P_{x}\left(\sigma_{B_{2 k}}<\sigma_{B_{2 j}}<\zeta\right)+P_{x}\left(\sigma_{B_{2} j}<\sigma_{B_{2 k}}<\zeta\right) \\
& =E_{x}\left(P_{x_{\sigma_{B_{2 k}}}}\left(\sigma_{B_{2 j} j}<\zeta\right), \sigma_{B_{22} k}<\sigma_{B_{2 j}}, \sigma_{B_{2 k}}<\zeta\right) \\
& +E_{x}\left(P_{x_{\sigma_{B_{2 j}}}}\left(\sigma_{B_{2} k}<\zeta\right), \sigma_{B_{2 j}}<\sigma_{B_{2} k}, \sigma_{B_{2} j}<\zeta\right) \\
& \leqq E_{x}\left(P_{x_{\sigma_{B_{2}}}}\left(\sigma_{B_{2 j}}<\zeta\right), \sigma_{B_{2 k}}<\zeta\right)+E_{x}\left(P_{x_{\sigma_{B_{2}}}}\left(\sigma_{B_{2 k}}<\zeta\right), \sigma_{B_{2} j}<\zeta\right) .
\end{aligned}
$$

Noting that the distance between $B_{2 j}$ and $B_{2 k}$ exceeds $\frac{1}{2^{2 j+1}}, \frac{1}{2^{2 k-1}}$, we get by the condition ( $R$ )

$$
\begin{align*}
P_{y}\left(B_{2 k}^{*}\right) & =\int_{\bar{B}_{2 k}} G(y, z) \mu_{B_{2 k}}(d z)  \tag{4.9}\\
& \leqq C_{1} \int_{\bar{B}_{2 k}} \phi(|y-z|) \mu_{B_{2 k}}(d z) \leqq C_{1} \phi\left(\frac{1}{2^{2 j+1}}\right) C\left(B_{2 k}\right)
\end{align*}
$$

for each $y \in \bar{B}_{2 j}$. Similarly we have

$$
\begin{equation*}
P_{y}\left(B_{2 j}^{*}\right) \leqq C_{1} \phi\left(\frac{1}{2^{2 j+1}}\right) C\left(B_{2 j}\right) \tag{4.10}
\end{equation*}
$$

for each $y \in \bar{B}_{2 k}$. On the other hand it holds

$$
\begin{equation*}
P_{x}\left(B_{2 k}^{*}\right)>C_{2} \phi\left(\frac{1}{2^{2 k-1}}\right) C\left(B_{2 k}\right) \geqq C_{2} \phi\left(\frac{1}{2^{2 j-1}}\right) C\left(B_{2 k}\right) \tag{4.11}
\end{equation*}
$$

and similarly

$$
\begin{equation*}
P_{x}\left(B_{2 j}^{*}\right)>C_{2} \phi\left(\frac{1}{2^{2 j-1}}\right) C\left(B_{2 j}\right) . \tag{4.12}
\end{equation*}
$$

Therefore, we have by (4.9) and (4.11)

$$
\begin{equation*}
P_{y}\left(B_{2 k}^{*}\right)<\frac{C_{1}}{C_{2}} \frac{\phi\left(\frac{1}{2^{2 j-1}}\right)}{\phi\left(\frac{1}{2^{2 j-1}}\right)} P_{x}\left(B_{2 k}^{*}\right) \tag{4.13}
\end{equation*}
$$

for each $y \in \bar{B}_{2 j}$. Similarly we have by (4.10) and (4.12)

$$
P_{y}\left(B_{2 j}^{*}\right)<\frac{C_{1}}{C_{2}} \frac{\phi\left(\frac{1}{2^{2 j+1}}\right)}{\phi\left(\frac{1}{2^{2 j-1}}\right)} P_{x}\left(B_{2 j}^{*}\right), \text { for each } y \in \bar{B}_{2 k} .
$$

Hence by (4.9) and (4.1) we obtain

$$
P_{x}\left(B_{2 j}^{*} \cap B_{2 k}^{*}\right) \leqq 2 \frac{C_{1}}{C_{2}} M^{2} P_{x}\left(B_{2 j}^{*}\right) P_{x}\left(B_{2 k}^{*}\right) .
$$

$\left\{B_{2 k}^{*}\right\}$ satisfies ii) of Lamperti's lemma and so

$$
P_{x}\left(\overline{\overline{(l i m}_{k \uparrow \infty}} B_{k}^{*}\right)>0 .
$$

By lemma 4.2, we see that $x$ is a regular point of $B$ for $X$.
Proof of Theorem 4.1. By using the computation in Lemma 2.3, we get

$$
\frac{C_{2}}{M^{-}} \phi\left(\frac{1}{2^{k}}\right) C\left(B_{k}\right) \leqq P_{x}\left(B_{k}^{*}\right) \leqq C_{1} \phi\left(\frac{1}{2^{k}}\right) C\left(B_{k}\right) .
$$

Hence (4.1) is equivalent to (4.7). This proves the Theorem.
In the sequel we shall prove Theorem 4.2. Let $C_{i}(i=1,2)$ be the capacity of $X_{i}^{\alpha}(i=1,2)$.

Lemma 4.4. Let $A$ be an open set with compact closure, and $K$ be a compact set containing $\bar{A}$ in the condition (S). Then there exist positive constants depending only on $K$ such that

$$
k_{2} C_{1}(S)<C_{2}(A)<k_{1} C_{1}(G)
$$

for an open set $G \supset \bar{A}$ and a compact set $S \subset A$.
Proof. If we set

$$
\begin{aligned}
& L^{*}=\left\{\text { measure } \mu, \int G_{1}(x, y) \mu(d y) \leqq 1\right. \\
& \text { on } \left.K \text {, support of } \mathrm{f}_{\bar{s}}^{\Downarrow} \mu \bar{A}\right\} \text {, then we have } \\
& \quad \mu(\bar{A})=\int_{\bar{A}} P_{x}^{1}\left(\sigma_{G}<\zeta\right) \mu(d x)
\end{aligned}
$$

for every $\mu \in L^{*}$ and an open set $G$ such that $K \supset G \supset \bar{A}$. Noting the conditions ( $R$ ) and ( $S$ ), we obtain

$$
\begin{align*}
\mu(\bar{A}) & \leqq \int_{\bar{A}} \int_{\bar{G}} G_{1}(x, y) \mu_{G}^{1}(d y) \mu(d x)  \tag{4.14}\\
& \leqq \frac{C_{1}}{C_{2}} \int_{\bar{G}} \int_{\bar{A}} G_{1}(y, x) \mu(d x) \mu_{G}^{1}(d y) \\
& \leqq \int_{\bar{G}} \frac{C_{1}}{C_{2}} \mu_{G}^{1}(d y) \leqq \frac{C_{1}}{C_{2}} C_{1}(G) .
\end{align*}
$$

On the other hand, we can show that there exist constants $k_{1}^{\prime}, k_{2}^{\prime}>0$ such that

$$
\begin{equation*}
1 / k_{1}^{\prime} G_{1}(x, y)<G_{2}(x, y)<1 / k_{2}^{\prime \prime} G_{1}(x, y), x, y \in K \tag{4.15}
\end{equation*}
$$

from the condition (S). Therefore, $1 / k_{1}^{\prime} \mu_{A}^{2}(d y)$ belongs to $L^{*}$ and so it holds $C_{2}(A)<k_{1}^{\prime} \frac{C_{1}}{C_{2}} C_{1}(G)$ by (4.14). Hence we have

$$
\begin{equation*}
C_{2}(A) \leqq k_{1} C_{1}(G) \tag{4.16}
\end{equation*}
$$

for any open set $G \supset \bar{A}$. If we set

$$
L^{* *}=\left\{\text { measure } \mu ; \int G_{1}(x, y) \mu(d y) \geqq 1 \text { inside } A \text {, support of } \mu \subseteq \bar{A}\right\},
$$

then we have for every $\mu \in L^{* *}$ and a compact set $S \subset A$

$$
\mu(\bar{A}) \geqq \int_{\bar{A}} P_{x}^{1}\left(\sigma_{s}<\zeta\right) \mu(d x),
$$

and by the same reason as in (4.14), we get

$$
\begin{aligned}
\mu(\bar{A}) & \geqq \int_{\bar{A}} \int_{S} G_{1}(x, y) \mu_{S}^{1}(d y) \mu(d x) \\
& \geqq \frac{C_{2}}{C_{1}} \int_{S} \mu_{S}^{1}(d y)>\frac{C_{2}}{C_{1}} C_{1}(S) .
\end{aligned}
$$

As $1 / k_{2}^{\prime} \mu_{A}^{2}(d y)$ belongs to $L^{* *}$ by (4.15), we see

$$
\begin{equation*}
C_{2}(A) \geqq k_{2} C_{1}(S) \tag{4.17}
\end{equation*}
$$

where $k_{2}=\frac{C_{2}}{C_{1}} k_{2}^{\prime}$. The conclusion follows from (4.16) and (4.17).
Proof of Theorem 4.2. As we may assume that $X_{i}^{\alpha}(i=1,2)$ is a standard process in a bounded domain $\Omega, E_{x}(\zeta)=\int_{\Omega} G(x, y) d y$ is finite, and so we have $P_{x}(\zeta<\infty)=1$, (remark $\zeta \leqq \tau_{\Omega}$ ). Hence we can take open sets $G_{k}, \hat{G}_{k}$, $\hat{\hat{G}_{k}}$ for each $B_{k}$ such that $\bar{B}_{k} \subset G_{k}, \bar{G}_{k} \subset \hat{G}_{k}, \overline{\hat{G}}_{k} \subset \hat{\hat{G}}_{k}$

$$
\begin{align*}
& P_{x}^{1}\left(\sigma_{B_{k}}<\zeta\right)+\frac{1}{2^{k}}>P_{x}^{1}\left(\sigma \hat{\hat{G}}_{k}<\zeta\right)>P_{x}^{1}\left(\sigma_{B_{k}}<\zeta\right),  \tag{4.19}\\
& P_{x}^{2}\left(\sigma_{B_{k}}<\zeta\right)+\frac{1}{2^{k}}>P_{x}^{2}\left(\sigma_{\hat{\sigma}_{k}}<\zeta\right)>P_{x}^{2}\left(\sigma_{B_{k}}<\zeta\right),
\end{align*}
$$

and, if we denote the distance between $Q$ and $R$ by $|Q, R|$,

$$
\begin{align*}
& \phi\left(\left|x, \hat{\hat{G}}_{k}\right|\right)<2 \phi\left(-\frac{1}{2^{k}}\right), \\
& \phi\left(\sup _{y \in \hat{\hat{G}}_{k}}|x-y|\right)>\frac{1}{2} \phi\left(\frac{1}{2^{k-1}}\right) . \tag{4.20}
\end{align*}
$$

For each $G_{k}$ which satisfies (4.19), $\sum_{k=1}^{\infty} P_{x}^{i}\left(B_{k}^{*}\right)$ diverges, if and only if $\sum_{k=1}^{\infty} P_{x}^{i}\left(\sigma_{G_{k}}<\zeta\right)$ $(i=1,2)$ diverges. Furthermore, from (4.20) we can see that $\sum_{k}^{\infty} \phi\left(\frac{1}{2^{k}}\right) C_{i}\left(G_{k}\right)$ diverges, if and only $\sum_{k}^{\infty} P_{x}^{i}\left(\sigma_{G_{k}}<\zeta\right)$ diverges. As it follows from lemma 4.4 that

$$
\sum_{k}^{\infty} \phi\left(1 / 2^{k}\right) C_{1}\left(G_{k}\right)=\infty \Rightarrow \sum_{k}^{\infty} \phi\left(1 / 2^{k}\right) C_{2}\left(\hat{G}_{k}\right)=\infty \Rightarrow \sum_{k}^{\infty} \phi\left(1 / 2^{k}\right) C_{1}\left(\hat{\hat{G}_{k}}\right)=\infty,
$$

we obtain

$$
\begin{equation*}
\sum_{k}^{\infty} P_{x}^{1}\left(B_{k}^{*}\right)=\infty \Rightarrow \sum_{k}^{\infty} P_{x}^{2}\left(\sigma_{\hat{G}_{k}}<\zeta\right)=\infty \Rightarrow \sum_{k}^{\infty} P_{x}^{1}\left(\sigma_{\hat{\hat{G}}}^{k}<(\zeta \zeta)=\infty .\right. \tag{4.21}
\end{equation*}
$$

Hence by (4.19) and (4.21) we have

$$
\sum_{k}^{\infty} P_{x}^{1}\left(B_{k}^{*}\right)=\infty \Leftrightarrow \sum_{k}^{\infty} P_{x}^{2}\left(B_{k}^{*}\right)=\infty .
$$

This means that $x$ is a regular point of $B$ for $X_{1}^{\alpha}$, if and only if $x$ is a regular point of $B$ for $X_{2}^{\alpha}$.

## § 5. Regular points for the multi-dimensional standard processes connected with the differential operator of second order.

In this section we are concerned with the canonical diffusion process $X$ connected with $D$, its dual process constructed by theorem 3.1 and the minimal diffusion process $X^{s}$ connected with the self-adjoint operator $D^{s}$ in $\S 2$.

Our aim is to prove the following theorem.
Theorem 5.1. Let $B$ be an analytic set with compact closure. Then a point is a regular point of $B$ for $X, X^{*}$ or $X^{s}$, if and only if $x$ is a regular point of $B$ for the Brownian motion,

Proof. To prove this by theorem 4.2, we have only to show that the condition $(R)$ is satisfied. For $X^{*}$ and $X^{s}$, the condition $(R)$ is easily verified by using Hunt's theory because of their dual property (under the condition ( $L$ ), the dual process of $X^{*}$ is $X$ and the dual process of $X^{s}$ is $X^{s}$ itself). But without the condition ( $L$ ), it is not obvious in the case of a canonical diffusion process. Hence we need to prove the following lemma.

Lemma 5.1. Let $X$ be a canonical diffusion process in $R^{d}(d \geqq 3)$. Then the condition $(R)$ is satisfied for $X$, that is:

$$
P_{x}\left(\sigma_{A}<\infty\right)=\int_{\bar{A}} G(x, y) \mu_{A}(d y), \text { for every }
$$

analytic set $A$ with compact closure, where $\mu_{A}$ is a uniquely determined measure concentrating on $\bar{A}$.

Proof. Remark that $P_{x}\left(\sigma_{A}<\infty\right)$ is $X$-excessive (see. Dynkin [2]) and harmonic ( $X$ ) in $R^{d}-\bar{A}$. First we have for every open set $Q$ with compact closure

$$
\begin{equation*}
P_{x}\left(\sigma_{A}<\infty\right)=g(x)+\int_{Q} G(x, y) \mu(d y), x \in Q, \tag{5.1}
\end{equation*}
$$

where $g(x)$ is harmonic ( $X$ ) in $R^{d}$ and $\mu$ is a measure on $Q$.
Indeed, the proof of (5.1) follows the same lines as that of Schur [14], if we prove the following proposition.

Proposition 5.1. Choose an open ball $Q$ containing a fixed point $x$ and let $\left\{T_{t}^{Q}\right\}$ be a semi-group of a stopped canonical diffusion process $X^{Q}$ on $Q$ (see, Dynkin [2]). Then

$$
h_{s}(x, y) \equiv T_{s}^{Q} G_{y}(x)
$$

is continuous in $y$.
Proof. Since $h_{s}(x, y)=T_{s}^{Q}\left[G_{y}(x)-E_{x} G_{y}\left(x_{\tau_{Q}}\right)\right]+T_{s}^{Q}\left[E_{x} G_{y}\left(x_{\tau_{Q}}\right)\right]$, we shall show that the rigth-hand side is continous.
i) We first prove that $T_{s}^{Q}\left[E_{x} G_{y}\left(x_{\tau_{\Omega}}\right)\right]$ is continuous in $y$. If we fix a point $x \in Q$, we have

$$
\begin{aligned}
& T_{s}^{Q}\left[E_{x} G_{y}\left(x_{\tau Q}\right)\right]=E_{x}^{Q}\left[E_{x_{s}} G_{y}\left(x_{\tau_{Q}}\right), s<\tau_{Q}\right] \\
& \quad+E_{x}^{Q}\left[G\left(x_{\tau_{Q}}, y\right), s \geqq \tau_{Q}\right]=E_{x}\left[E_{x_{s}} G\left(x_{\tau Q}, y\right), s<\tau_{Q}\right] \\
& \quad+E_{x}\left[G\left(x_{\tau Q}, y\right), s \geqq \tau_{Q}\right]=E_{x}\left[G\left(x_{\tau_{Q}}, y\right)\right] .
\end{aligned}
$$

Hence it suffices to show that $E_{x} G\left(x_{\tau_{Q}}, y\right)$ is continuous. If we fix a point $y \in R^{d}-\bar{Q}$, then $G(\cdot, y)$ is harmonic ( $X$ ) in $R^{d}-y$, and so we have $G(x, y)$ $=E_{x} G\left(x_{\tau Q}, y\right)$, where $x \in Q$ and $y \in R^{d}-\bar{Q}$. Therefore $E_{x} G\left(x_{\tau_{Q}}, y\right)$ is continuous in $R^{d}-\bar{Q}$. From (3.6), we have

$$
\lim _{y_{m} \rightarrow y} E_{x} G\left(x_{\tau Q}, y_{m}\right)=E_{x} G\left(x_{\tau q}, y\right)=G(x, y),
$$

where $y_{m} \in R^{d}-\bar{Q}, y \in \partial Q$. Thus $E_{x} G\left(x_{\tau Q}, y\right)$ is continuous in $R^{d}-Q$. If $y_{1}, y_{2}$ belong to $Q$, we have

$$
\left|E_{x}\left\{G\left(x_{\tau}, y_{1}\right)-G\left(x_{\tau Q}, y_{2}\right)\right\}\right| \leqq \sup _{z \in \partial Q}\left|G\left(z, y_{1}\right)-G\left(z, y_{2}\right)\right| \rightarrow 0 \text { as } y_{1} \rightarrow y_{2}
$$

as and from (3.2) we obtain

$$
\lim _{y_{m} \rightarrow y} E_{x} G\left(x_{\tau_{Q}}, y_{m}\right)=G(x, y), y_{m} \in Q, y \in \partial Q .
$$

Therefore $E_{x} G\left(x_{\tau Q}, y\right)$ is continuous in $R^{d}$.
ii) For each $x, y \in Q$, we have

$$
\begin{gathered}
T_{S\left[G_{y}(x)-E_{x} G_{y}\left(x_{\tau}\right)\right.}=T_{\xi}\left[G_{y}^{Q}(x)\right]=\int G^{Q}(z, y) P^{Q}(s, x, z) d z \\
=\int_{0}^{\infty} P^{Q}(t+s, x, y) d t=\int_{s}^{\infty} P^{Q}(t, x, y) d t .
\end{gathered}
$$

When $y \in Q^{c}$, we see that $G_{y}(x)=E_{x} G_{y}\left(x_{\cdot Q}\right)$ and for an arbitrary sequence $\left\{y_{m}\right\}$ in $Q$ such that $y_{m} \rightarrow y \in \partial Q$, we have $\lim _{m \rightarrow \infty}\left\{G\left(x, y_{m}\right)-E_{x} G_{y_{m}}\left(x_{\tau}\right)\right\}=0$. Thus $T_{s}^{\ell}\left[G_{y}(x)-E_{x} G_{y}\left(x_{\tau q}\right)\right]$ is continuous in $R^{d}$. We have proved the lemma.

Hence Schur's argument [15] carries over to the present case of the canonical diffusion process, if only we prove the following proposition.

Proposition 5.2. Let $Q$ be a bounded domain with sufficiently smooth
boundary and $\mu_{i}, i=1,2$ be finite measures with the same compact support in $Q$. Then if

$$
\int_{Q} G^{Q}(x, y) \mu_{1}(d y)=\int_{Q} G^{Q}(x, y) \mu_{2}(d y)
$$

holds for all $x \in Q$, we have

$$
\mu_{1}=\mu_{2}
$$

Proof. It suffices to show that for any open set $\omega \subset Q$, we have

$$
\int_{\omega} G^{Q}(x, y) \mu_{1}(d y)=\int_{\omega} G^{Q}(x, y) \mu_{2}(d y)
$$

Let $h(x)=\int_{Q} G^{Q}(x, y) \mu_{1}(d y)=\int_{Q} G^{Q}(x, y) \mu_{2}(d y)$ and $h_{\omega}$ be defined as $\inf _{f \in G} f(x)$ where $H=\left\{f\right.$; positive superharmonic $\left(X_{Q}\right)$ in $Q, f-h$; superharmonic $\left(X_{Q}\right)$ in $\left.\omega\right\}$. If we set $I_{\omega}^{i}(x)=\int_{\omega} G^{Q}(x, y) \mu_{i}(d y)(i=1,2)$, we have

$$
I_{\omega}^{i}=h_{\omega} \quad(i=1,2)
$$

following Hervé [4] Prop. |7.|. As the proof is short, we repeat it here:
$h-I_{\omega}^{i}$ is harmonic $\left(X_{Q}\right)$ in $\omega$, so $I_{\omega}$ belongs to $H$. Hence we have $I_{\omega}^{i} \geqq h_{\omega}$. Let $K$ be a compact set included in $\omega$. Then for any $h^{\prime} \in G, h^{\prime}-I_{K}$ is superharmonic ( $X_{Q}$ ) in $Q-K$. As $h^{\prime}-h$ is superharmonic $\left(X_{Q}\right)$ in $\omega, h^{\prime}-I_{R}=h^{\prime}-h$ $+I_{D-K}$ is superharmonic $\left(X_{Q}\right)$ in $\omega$. Hence $h^{\prime}-I_{K}$ is superharmonic $\left(X_{Q}\right)$ in $Q$. Noting $\liminf _{x \rightarrow a} h^{\prime}-I_{K} \geqq 0, x \in Q, a \in \partial Q$, we have $h^{\prime} \geqq I_{K}$.

Thus, we have proved the theorem.
Remark. When $d=2$, theorem 5.1 is hold by taking $G^{Q}(x, y)$ ( $Q$;sufficiently smooth bounded domain) instead of $G(x, y)$.

## §6. Regular points for some isotropic diffusions.

In this section we shall treat a uniformly elliptic differential operator on a closed ball $\bar{\Omega}$ with radius $h$ such that

$$
\begin{equation*}
D u(x)=\sum_{i, j=1}^{a} a_{i j}(x) \frac{\partial^{2}}{\partial x_{i} \partial x_{j}} u(x), \tag{6.1}
\end{equation*}
$$

where $x=\left(x_{1}, x_{2}, \cdots, x_{d}\right) \in \bar{\Omega}$ and the coefficients $a_{i j}$ are bounded continuous and symmetric. H. Tanaka [16] has shown that there exists a continuous standard process $X=\left(x_{t}, \zeta, M_{t}, P_{x}\right)$ with semigroup $\left\{T_{t}\right\}$ such that

$$
\lim _{t \rightarrow 0} t^{-1}\left\|T_{t} f(x)-f(x)\right\|=\sum_{i, j=1}^{d} a_{i j}(x) \frac{\partial_{f}^{2}(x)}{\partial x_{i} \partial x_{j}}, \text { for each } f \in C^{2}
$$

with compact support in $\Omega$.
In what follows we shall treat this process. We shall assume $d=2$ or 3
for simplicity.
By isotropy it is meant that transition probabilities are invariant under all orthogonal transformations $\{g\}$ that leave the origin fixed; that is

$$
P(t, x, E)=P(t, g x, g E)
$$

The following lemma was proved in a little different form by Wentzell in the case of the differential operator such that

$$
D=\sum_{i, j=1}^{d} a_{i j} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}}+\sum_{i=1}^{d} b_{i} \frac{\partial}{\partial x_{i}},
$$

where $x=\left(x_{1}, \cdots, x_{d}\right)$. In the case of (6.1) we get more detailed results.
Lemma 6.1. Assume that the process $X$ defined above is isotropic. In case $d=3$,

$$
\begin{align*}
f(r, \theta, \varphi)=a(r) \frac{\partial^{2} f}{\partial r^{2}} & +\frac{2 b(r)}{r} \frac{\partial f}{\partial r}+\frac{b(r)}{r^{2}}\left(\frac{\partial^{2} f}{\partial \theta^{2}}\right.  \tag{6.2}\\
& \left.+\frac{1}{\sin ^{2} \theta} \frac{\partial^{2} f}{\partial \varphi^{2}}+\frac{\cos \theta}{\sin \theta} \frac{\partial f}{\partial \theta}\right),
\end{align*}
$$

where $x=\left(x_{1}, x_{2}, x_{3}\right)=(r, \theta, \varphi)^{*} \neq(0, \theta, \varphi)$

$$
a_{i j}(x)=\delta_{i j} b(r)+\{a(r)-b(r)\} \frac{x_{i} x_{j}}{r^{2}} .
$$

In case $d=2$, under the assumptions of isotropy and reflection invariance, we have

$$
\begin{equation*}
f(r, \theta)=a(r) \frac{\partial^{2} f}{\partial r^{2}}+\frac{b(r)}{r} \frac{\partial f}{\partial r}+\frac{b(r)}{r^{2}} \frac{\partial^{2} f}{\partial \theta^{2}}, \tag{6.3}
\end{equation*}
$$

where $x=\left(x_{1}, x_{2}\right)=(r, \theta) \neq(0, \theta)$

$$
a_{i j}(x)=\delta_{i j} b(r)+\{a(r)-b(r)\} \frac{x_{i} x_{j}}{r^{2}}
$$

Moreover, by the continuity and boundedness of the cofficients $a_{i j}$ and uniform ellipticity, we can show that $a(r)$ and $b(r)$ are positive bounded continuous function of $r$ on $[0, h)$, and

$$
\lim _{r \rightarrow 0}\{a(r)-b(r)\}=0 .
$$

When the operator $D$ is expressed by polar coordinates, the form of infinitesimal operator is given by (6.2) and (6.3) except at the origin. Hence, in order to see the behaviour of the process $X$ at the origin, it is necessary to investigate the boundary conditions of the radial process $X_{r}$ on $[0, h$ ), which is defined by $X_{r}(t)=\left|x_{t}\right|$. It is known that the infinitesimal operator $A_{r}$ of $X_{r}$

[^2]has a form
\[

$$
\begin{equation*}
A_{r} f(r)=a(r) \frac{\partial^{2} f}{\partial r^{2}}+\frac{(d-1)}{r} b(r) \frac{\partial f}{\partial r}, \tag{6.4}
\end{equation*}
$$

\]

for $f \in c^{2}(0, h)$.
Theorem 6.1. Consider the radial process $X_{r}$ defined above on $[0, h)$. Then the boundary 0 can be neither " natural" nor " exit" in Feller's sense.

Proof. If we assume that it is natural or exit, we find that the point 0 is a trap with respect to the original process $X$, as 0 is a reflecting barrier. Hence we have $A f(0)=0$ for every function $f \in D(A)^{*}$. On the other hand, a function $f(x)=x_{1}^{2}+x_{2}^{2}+x_{3}^{2}$ where $x=\left(x_{1}, x_{2}, x_{3}\right)$ belongs to $D(A)$, obviously and $D f(0)=2\left(a_{11}(0)+a_{22}(0)+a_{33}(0)\right)>0$ by uniform ellipticity of $D$. This yields a contradiction.

When $d=2$, we shall show by an example that there exists a process $X$ whose radial process $X_{r}$ has a regular boundary 0 . Consider the operator $D$ on the disk $\Omega$ with radius $e^{-3}$ such that

$$
\begin{gather*}
D=\sum_{i, j=1}^{d} a_{i j} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}}, \quad x=\left(x_{1}, x_{2}\right),  \tag{6.5}\\
a_{i j}(x)=\delta_{i j}+\left(\frac{\log r}{2+\log r}-1\right){\frac{x_{i} x_{j}}{r^{2}}}^{* *)}
\end{gather*}
$$

Then the generator of $X_{r}$ has the form

$$
D_{r}=\frac{\log r}{2+\log r} \frac{1}{r(\log r)^{2}}-\frac{\partial}{\partial r}\left\{r(\log r)^{2} \frac{\partial}{\partial r}\right\} .
$$

Hence it holds

$$
\begin{aligned}
& \sigma=\int_{0}^{c^{-3}} \int_{y}^{e^{-3}}(2+\log x) \frac{x(\log x)^{2}}{\log x} d x \frac{d y}{y(\log y)^{2}}<\infty, \\
& \mu=\int_{0}^{e^{-3}} \int_{y}^{e^{-3}} \frac{d x}{x(\log x)^{2}} \frac{y(\log y)^{2}}{\log y}(2+\log y) d y<\infty,
\end{aligned}
$$

which shows that the boundary 0 is regular in Feller's sense. This example illustrates the following important remark; the point 0 is a regular point of the set $\{0\}$ for the original process $X$ which corresponds to (6.5). In the case of Brownian motion, this never occurs. Hence we see that the Hölder continuity of $a_{i j}$ plays an essential role in the proof of Theorem 5.1. However, in case $d=3$, we cannot construct such type of counter examples, as is shown by the following.

Theorem 6.2. In case $d=3$, the boundary 0 is always entrance.
Proof. Keeping (6.4) in mind, we see that the boundery 0 is entrance, if

[^3]and only if $\sigma=\infty$ and $\mu<\infty$ where
\[

$$
\begin{aligned}
& \sigma=\iint_{0<y<x<c} d m(x) d s(y), \\
& \mu=\iint_{0<y<x<c} d s(x) d m(y), \\
& s(x)=\int_{c}^{x} e^{-B(y)} d y \\
& m(x)=\int_{c}^{x} \frac{1}{a(y)} e^{B(y)} d y, \\
& B(x)=\int_{c}^{x} \frac{2 b(y)}{y a(y)} d y \\
& c: \text { some fixed constant in }(0, h) .
\end{aligned}
$$
\]

By Theorem 6.1, 0 cannot be natural nor exit. Hence it suffices to show $6=\infty$. Without loss of generality we may assume

$$
\frac{1}{2}<\frac{b(r)}{a(r)}<\frac{3}{2},
$$

for any $r \in(0, c]$, because $c$ can be chosen sufficiently small. (It is here that we use the properties of $a(r)$ and $b(r)$ mentioned in Lemma 6.1.) Hence, noting $x<c$, we have

$$
3 \log x-3 \log c \leqq B(x) \leqq 2 \frac{1}{2} \int_{c}^{x} \frac{1}{y} d y
$$

Therefore, it holds that

$$
\begin{aligned}
\sigma & \geqq \iint_{0<y<x<c} d m(x) e^{-\log y+\log c} d y \\
& \geqq e^{\log c} \int_{0}^{c} \int_{y}^{c} \frac{1}{M}-e^{3 \log x-3 \log c} d x e^{-\log y} d y \\
& =\frac{e^{-2 \log c}}{M} \int_{0}^{c} \frac{1}{4}\left(c^{4}-y^{4}\right) \frac{1}{y} d y=\infty,
\end{aligned}
$$

where $M$ is an upper bound of $a(r)$. This completes the proof of Theorem 6.2.

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[^0]:    * $\|\cdot\|$ is the norm of $C_{0}:\|f\|=\sup _{x}|f(x)|$.

[^1]:    *) Notice that $P_{x}\left(\sigma_{0}{ }_{n}^{c} \downarrow 0\right)=1$ and see remark 1.
    ${ }^{* *} P_{x}\left(\sigma_{B}>0\right)=1$ if $x$ is not a regular point of $B$ by Blumenthal's $0-1$ law.

[^2]:    *) ( $r$ ) is a point on the radial coordinate space ( $0, h$ ).
    $(\theta, \varphi)$ is a point on the spherical coordinate space $S^{n-1}$.

[^3]:    *) $D(A)$ denotes the domain of definitions of $A$.
    **) Remark that $D$ is uniformly elliptic in $\Omega$.

