# AN EXTENSION OF THE PLANCHEREL FORMULA TO UNIMODULAR GROUPS 

Haruo Sunouchi

(Received June 12, 1952)

Several extensions of the Plancherel formula to unimodular locally compact groups have been proposed under some restricted conditions by R. Godement, F. I. Mautner, I. E.Segal and the Russian mathematicians. ${ }^{1)}$ These of Mautner [7,8] and Segal [12] were estabiished by the use of the reduction theory of J. von Neumann [10], therefore the separability conditions of groups seem to be essential, and their results are somewhat measure-theoretic. On the other hand, Godement [3] has obtained a Plancherel formula by the method analogous to abelian groups, that is, by constructing the Radon measure on the set of characters. His method seems to be more elegant. But he assumed that $\mathbf{R}^{5}$ (the definition will be stated belcw) is of the finite class, and this condition is considerabiy strong (cf. [3; Theorem 6]).

The object of this paper is to give an extension of the Plancherel formula to arbitrary unimodular locally compact groups mostly along the Godement method Our main tool is the 4 -operation of arbitrary rings of operators defined in the previous papers [13, 14]. In Godement's paper [3]. the algebra $\mathbf{L}$ of continuous functions with compact supports on the group played an essential role. We replace this algebra $L$ by the algebra $\left(\mathbf{R}_{0}^{P}\right)_{F}$ of the bounded linear operators defined by the bounded elements with some properties. But in the case of the abelian groups, our results do not coincide to the well-known Plancherel formula Therefore, if $\boldsymbol{R}^{*}$ is of the finite class, the Godement method is more natural than ours for this purpose. But it is interest that, if we assume $R^{s}$ being of the finite class, we obtain the factor decomposition of $\mathbf{R}^{⿶}$ as shown in the previous paper [15].

This method of the factor decomposition of rings of operators will give a suggestion for the general one.

As remarked in the previous paper [15], in the double unitary representation of a group by a central Radon measure of the positive type (the definitions will be given below, §1), our $\mathbf{R}_{0}^{S}$ is the maximal Hilbert algebra introduced by H. Nakano ${ }^{2}$;man can easily see that our treatments are also

[^0]available to the arbitrary maximal Hilbert algebras, but we shall not discuss them explicitly.

Finally, we are very much indebted to Professor M. Kondo in the Tokyo Metropolitan University for his many valuable suggestions. The author extends his hearty thanks to him.

## 1. Double unitary representations.

Let $G$ be a unimodular locally compact group, which need not be separable. Following Godement [3],

Definition 1.1. A double unitary representation (abr. d. u. r.) of $G$ is a structure $\left\{\underset{\sim}{\mathfrak{S}}, U_{s}, V_{s}, S\right\}$ satisfying the foliowing conditions;
a) $\mathfrak{h}$ is a Hilbert space,
b) $s \rightarrow U_{s}, s \rightarrow V_{s}$ are two continuous unitary representations of $G$ on $\mathscr{\xi}$, such that

$$
\begin{array}{ll}
U_{s} V_{t}=V_{t} U_{s} & \text { for } s, t \in G, \\
V_{t} \text { such that } & \text { for } t \in G .
\end{array}
$$

c) $S$ is an involution in $\mathfrak{5 ू}^{3}$ such that

In the sequel we shall discuss only the foilowing case : let $\mu$ be a central Radon measure of the positive type on $G$, that is, $\mu$ is a Radon measure satisfying

$$
\begin{array}{lr}
\int f * g(s) d \mu(s)=\int g * f(s) d \mu(s) & \text { for } f, g \in \mathbf{L} \\
\int \widetilde{f} * f(s) d \mu(s) \geqq 0 & \text { for } f \in \mathbf{L} \tag{1.2}
\end{array}
$$

where $L$ is an algebra of continuous functions with compact supports on $G$. $\widetilde{f}(s)=f\left(s^{-1}\right) ; f * g(s)=\int f(t) g\left(t^{-1} s\right) d t$; $d t$ is a Haar measure on $G$. Then it is known that we can define a d.u.r. of $G$ by such a measure ([3;p.16]). For the latter use we shall sketch the construction.

Put

$$
\begin{equation*}
\mathbf{u}(\mu)=\left[f \in \mathbf{L} ; \int \widetilde{J} * f(s) d \mu(s)=0\right] \tag{1.3}
\end{equation*}
$$

then, as $\mathbf{u}(\mu)$ is a two-sided ideal in the algebra $\mathbf{L}$, we obtain a quotient algebra $\mathbf{L}(\mu)=\mathbf{L} / \mathbf{u}(\mu)$. Denote the canonical mapping of $\mathbf{L}$ on $\mathbf{L} / \mathbf{u}(\mu)$ by $f \rightarrow \mathbf{f}(\mu)$. The expression:

$$
\begin{equation*}
<\mathbf{f}(\mu), \mathbf{g}(\mu)>=\int \widetilde{g} * f\left(s^{\prime}, \boldsymbol{d} \mu(\boldsymbol{s})\right. \tag{1.4}
\end{equation*}
$$

is an inner product on $\mathbf{L}(\mu)$, therefore, by completion with this inner product we obtain a Hilbert space $\mathscr{S}(\mu)$ in which $L(\mu)$ is dense. If we define the involution $S$ and unitary operators $U_{s}(\mu), V_{s}(\mu)$ by

[^1]\[

$$
\begin{array}{cl}
\operatorname{Sf}(\mu)=\widetilde{\mathbf{f}}(\mu) & \text { for } f \in \mathbf{L},  \tag{1.5}\\
U_{s}(\mu) \mathbf{f}(\mu)=\varepsilon_{s} * \mathbf{f}(\mu), \quad V_{s}(\mu) \mathbf{f}(\mu)=\mathbf{f} * \varepsilon_{s}^{-1}(\mu) & \text { for } f \in \mathbf{L},
\end{array}
$$
\]

where $\varepsilon_{s} * f(t)=f\left(s^{-1} t\right), f * \varepsilon_{s^{-1}}(t)=f(t s)$, then it may be clear that the structure $\left\{\mathscr{S}(\mu), U_{s}(\mu), V_{s}(\mu), S\right\}$ is a d.u.r. The above obtained d.u.x. will be called a d.u.r. by $\mu$, and hereafter we omit the notation ( $\mu$ ). If $\mu=\varepsilon$ (that is, a measure +1 on the unit $e$ of $G$ ), we say the above d. u.r. is regular. Mautner and Segal discussed only the regular case.

The d. u. r. by $\mu$ is studied by Godement in detail, so refer to [3; Chap I. §1.]. The principal results ${ }^{4)}$ [3; Theorem 1] can be stated as follows:

Theorem 1.1. In the d. u.r. $\left\{\mathfrak{y}, U_{s}, V_{s}, S\right\}$ by $\mu$, let $\mathbf{R}^{s}$ and $\mathbf{R}^{d}$ be the $W *$-algebras ${ }^{5}$ ) generated in $\mathfrak{g}$ by $U_{s}$ and $V_{s}$, respectively; then we obtain $\left(\mathbf{R}^{s}\right)^{\prime}=\mathbf{R}^{d}, \quad\left(\mathbf{R}^{d}\right)^{\prime}=\mathbf{R}^{s}$.

Therefore, denote by $\mathbf{R}^{4}$ the set of all bounded linear operators commute with $U_{s}, V_{s}$, then we obtain $\mathbf{R}=\mathbf{R}^{s} \cap \mathbf{R}^{d}$, that is, $\mathbf{R}^{4}$ is the center of $\mathbf{R}^{\text {s }}$ and $\mathbf{R}^{d}$.

Definition 1.2. If we define the $U_{f}$ and $V_{f}$ by

$$
\begin{equation*}
U_{f}=\int U_{s} f(s) d s, \quad V_{f}=\int V_{s} f\left(s^{-1}\right) d s, \quad \text { for } f \in \mathbf{L} \tag{1.7}
\end{equation*}
$$

then it is well-known that these $U_{f}, V_{f}$ are the bounded linear operators on $\mathfrak{J}$ and that they satisfy the relation:

$$
\begin{equation*}
U_{f} \mathbf{g}=V_{g} \mathbf{f}=f * \mathbf{g} \quad \text { for } \mathbf{g}(g \in \mathbf{L}) \tag{1.8}
\end{equation*}
$$

Therefore we can define the operator $U_{x}, V_{x}$ for any $\mathbf{x} \in \mathfrak{y}$ by

$$
\begin{equation*}
U_{x} \mathbf{f}=V_{f} \mathbf{x}, \quad V_{x} \mathbf{f}=U_{f} \mathbf{x}, \quad \text { for } \mathbf{f}(f \in \mathbf{L}) ; \tag{1.9}
\end{equation*}
$$

if these operators $U_{x}$ and $V_{x}$ are bounded, then we say that $\mathbf{x}$ is a bounded element.

For the bounded elements of $\mathfrak{5}$, the following facts are known (cf. [3; Chap I. § 1]):

Lemma 1.1. $1^{\circ}$. If $\mathbf{x}$ is bounded, then $S \mathrm{x}$ is also bounded and

$$
\begin{equation*}
V_{S x}=V_{x}^{*}, \quad U_{s x}=U_{s x^{*}}^{*} . \tag{1.10}
\end{equation*}
$$

$2^{\circ} U_{x}$ and $V_{x}$ are related by
(1.11) $\quad V_{S x}=S U_{x S}, \quad U_{S x}=S V_{x} S$.
$3^{\circ} U_{x} \in \mathbf{R}^{s}, V_{x} \in \mathbf{R}^{d}$; if $A \in \mathbf{R}^{s}$ (or $\in \mathbf{R}^{d}$ ), then $A \mathbf{x}$ is also bounded and
$A U_{x}=U_{A x}, \quad\left(A V_{x}=V_{\Delta x}\right)$
$U_{x} A=U_{S d^{*} S x}, \quad\left(V_{x} A=V_{S A^{*} S x}\right)$.
$4^{\circ}$ Let $\mathbf{R}_{0}^{c}\left(\mathbf{R}_{0}^{\prime}\right)$ be the set of all $U_{x}\left(V_{x}\right)$ for the bounded $\mathbf{x}$, then $\mathbf{R}_{0}^{c}\left(\mathbf{R}_{0}^{\prime \prime}\right)$

[^2]is a two-sided ideal in $\mathbf{R}^{s}\left(\mathbf{R}^{d}\right)$ and (strongly) dense in $\mathbf{R}^{s}\left(\mathbf{R}^{d}\right)$.
$5^{\circ}$ For the bounded $\mathbf{x}, \mathbf{y}$, the product:
\[

$$
\begin{equation*}
\mathbf{x} * \mathbf{y}=U_{x} \mathbf{y}=V_{y} \mathbf{x} \tag{1.14}
\end{equation*}
$$

\]

is well-defined and $\mathbf{x} * \mathbf{y}$ is also a bounded element in $\mathfrak{\xi}$, satisfying

$$
\begin{equation*}
U_{x x y}=U_{x} U_{y}, \quad V_{x y}=V_{y} V_{x} . \tag{1.15}
\end{equation*}
$$

In this meaning, we shall call this $\mathbf{R}_{0}^{s}$, or $\mathscr{S}_{0}$, the set of corresponding elements of $\mathfrak{y}$, the bounded algebra of the d.u.r.

Definition 1.3. If $\mathbf{e} \in \mathfrak{H}$ is bounded and $U_{s}$ is a projection, we call $U_{e}$ -a bounded projection in the d. u.r. ${ }^{6)}$ As be easily seen, $U_{b}$ is a projection if and only if $\mathrm{Se}=\mathbf{e}$ and $\mathbf{e} * e=\mathbf{e}$. This suggests the following definitions: an bounded element $\mathbf{x}$ is called self-adjoint (abr.s.a.) if $S \mathbf{x}=\mathbf{x}$, and idempotent if $\mathbf{x} * \mathbf{x}=\mathbf{x}$.

Lemma 1.2. If $P$ is a non-zero projection in $\mathbf{R}^{s}$, then there exists a nonzero s.a. bounded element in the range of $P$.

Proof. As $P \neq 0$ and $\mathbf{L}$ is dense in $\mathfrak{h}$, there exists an element $\mathbf{f} \in \mathrm{L}$ such that $P \mathbf{f} \neq 0$. By $3^{\circ}$ and $5^{\circ}$ of Lemma 1.1, $P \mathbf{f}, S P f$ and so $P \mathbf{f} * S P f$ are bounded. $P \mathbf{f} * S P \mathbf{f}$ is the required one. Because, $P \mathbf{f} * S P \mathbf{f}=U_{p r} S P \mathbf{f}=$ $P U_{f} S P \mathbf{f}$, implies $P \mathbf{f} * S P \mathbf{f}$ is in the range of $P$. By the equation $S(P \mathbf{f} * S P \mathbf{f})$ $=S U_{P j}(S S) S P \mathbf{f}=V_{P f} P \mathbf{f}=P \mathbf{f} * S P \mathbf{f}$, it is s. a. ${ }^{`}$ Finally we shall show that it is non-zero. If we assume that $P \mathbf{f} * S P \mathbf{f}$ be zero, then $V_{P_{j} s P_{j}} g=0$ for any $\mathbf{g} \in \mathbf{L}$, therefore we have

$$
\left.<V_{P^{\prime} \leftrightarrow S P f} \mathbf{g}, \mathbf{g}\right\rangle=<V_{P f} \mathbf{g}, V_{P f} g>=0 \quad \text { for } \mathbf{g} \in \mathbf{L} ;
$$

it is easily seen that this implies $P \mathbf{f}=0$, thus we obtain the contradiction.
Then we have the following theorem by the quite similar manner to [12; Theorem 2]; we omit the proof.

Theorem 1.2. Every projection in $\mathbf{R}^{s}$ is the least upper bound of the bounded projections which it bounds.

Lemma 1.2. For any bounded element $\mathbf{x}, U_{x}$ is approximated uniformlv by the linear combinations of bounded projections, say $U_{p_{n}}$. And the same time, $\mathbf{x}$ is approximated (strongly) by the linear combinations of the corresponbing s. a. idempotent elements.

This lemma was given by Segal in the proof of [12; Theorem 4].
2. 4-operations in $\mathbf{W}^{*}$-algebras.

We consider a general $W^{*}$-algebra $\mathbf{M}$ on a Hilbert space $\mathfrak{F}$, and denote its center by $\mathbf{M M}^{\xi}$. The 4 -operation in a $W^{*}$-algebra $\mathbf{M}$ has been introduced by Dixmier [1] under the condition that $\mathbf{M}$ is of the finite class, and this notion is extended to an arbitrary $W^{*}$-algebra in the previous papers [13, 14].

We say that a projection $P \in \mathbf{M}$ is finite if a projection $Q \in \mathbf{M}, \quad P \sim$ $Q \leqq P$ implies $Q=P$, and infinite in the other case. If the unit element
6) This is no others than the finite projection in the termniology of Segal [12].
$I \in \mathbf{M}$ is finite, $\mathbf{M}$ is said to be of the finite class, and otherwise of the infinite class. As mentioned in the previous paper [13], $\mathbf{M}$ is generally a direct sum of three $W^{*}$-algebras, $\mathbf{M M}^{\gamma}, \mathbf{M}^{i}$ and $\mathbf{I M}^{p i}$, say; $\mathbf{M M}^{j}$ is of the finite class, $\mathbf{I} \mathbf{M}^{i}$ and $\mathbf{I M}^{p i}$ are of the infinite class; in $\mathbf{M}^{i}$, every central projection is infinite but contains a finite projection in it, and $\mathbf{M}^{p_{i}}$ is the other case. Especially $\mathbf{I M}^{p i}$ is called of the purely infinite class. Hereafter we assume that $\mathbf{M}$ contains no direct summand of the purely infinite class.

By a central envelope $Z$ of a projection $P \in \mathbf{M} \mathbf{M}$, we mean the least central projection containing $P$. Then there exists a system of finite projections $E_{\alpha}$ such that corresponding central envelopes $Z_{\alpha}$ are mutually. orthogonal and span the unit $I$. Denote $E=\Sigma \oplus E_{\varkappa}$, then $E$ is also finite [14; Lemma 1.1]; we shall call this $E$ the generalised unit of $\mathbf{M}$. In general, any projection $P \in \mathbf{M}$ is decomposed in a following way with respect to the generalised unit $E[14 ;$ Lemma 1.2]:

$$
\begin{equation*}
P=\sum_{\alpha \in A_{1}} \oplus E_{1}^{\alpha} \oplus F_{1} \oplus \sum_{\alpha \in A_{2}} \oplus E_{z}^{\alpha} \oplus F_{z} \oplus \cdots \oplus \sum_{\alpha \in A_{\mu}} \oplus E_{\mu}^{\alpha} \tag{2.1}
\end{equation*}
$$

where $E_{\mu}^{\alpha} \sim E_{\mu}^{3}, E_{\nu}^{\alpha}<E_{\mu}^{\star}<E \quad(\nu>\mu)$, and $F_{\mu} \prec E_{\mu}^{\alpha}$ has no comparable part to the remainders. If the above expression (2.1) ends up with finite terms and every $\mathrm{A}_{i}$ is finite, we say $P$ is $E$-finite; if a operator $A \in \mathbf{M}$ be contained in some $E$-finite projection $P$, that is, $A P=P A=A$, then we say $A$ is $E$ finite. With these definitions the results in the previous paper [14; Theorem 2] can be stated as follows:

Theorem 2.1. For any $E$-finite $A \in \mathbf{M}$, we can define a mapping $A \rightarrow A^{\prime}$ $\in \mathbf{M}^{\prime}$ satisfying the following properties:
(i) $A \in \mathbf{M}^{4}$ implies $A^{4}=A$,
(ii) $(\alpha A)^{2}=\alpha A^{4}$,
(iii) $(A+B)^{4}=A^{4}+B^{\prime}$,
(iv) $(A B)^{\prime}=(B A)^{\prime}$,
(iv) For any (not necessarily $E$-finite) $C \in \mathbf{M}^{4},(C A)^{4}=C A^{4}$,
(v) If $A$ is s.a. and $A \geqq 0$, then $A^{\xi}$ is s.a. and $A^{4} \geqq 0$,
(v) If $A$ is s.a., $A \geqq 0$ and $A^{\xi}=0$, then $A=0$,
(vi) $\left(A^{*}\right)^{4}=\left(A^{\xi}\right)^{*}$,

But this 4 -operation depends on the choice of the generalised unit of $\mathbf{M}$; if there exists another finite projection $E^{\prime} \in \mathbf{M}$, of which central envelope spans the unit $I$, we can define another mapping $A \rightarrow A^{\text {/' }}$ for any $E^{\prime}$-finite operator $A$ with respect to this $E^{\prime}$. Suppose that $E^{\prime}$ be $E$-finite, then any $E^{\prime}$-finite operator becomes also $E$-finite; two operations $A^{4}$ and $A^{4,}$ are related by

$$
\begin{equation*}
A^{\xi \prime}=\left(E^{\prime \prime}\right)^{-1} A^{\xi} . \tag{2.2}
\end{equation*}
$$

We have defined the $\xi$-operation for any finite (not necessarily $E$-finite) operators in [14], but we shall not use this generalized notion in this paper.

Now return to the case of the d.u.r. of $G$ by $\mu$. When $\mathbf{R}^{\text {i }}$ is of the finite class, there exist the interesting relations between the $\xi$-operation of $\mathbf{R}^{s}$ and the elements of Hilbert space or the structure of $G$; these facts are discussed in detail by Godement [3; Chap. I]. Finally we shall note an important

Lemma 2.1. Any bounded projection in $\mathbf{R}^{\text {s }}$ is finite in the sense of the $W^{*}$-algebra.

Proof. Let $U_{e}$ be a bounded projection in $\mathbf{R}^{s}$, and let $P$ be a projection in $\mathbf{R}^{s}$ such that $P \leqq U_{\theta}, P \sim U_{g}$. Then there exists a partially isometric operator $W \in \mathbf{R}^{s}$ such that $W W^{*}=P$, and $W^{*} W=U_{e} . \quad P=W W^{*} U_{e}=U_{W W^{*} ;}$ evidently this implies $W W^{*} e \neq 0$. As $W$ and $W^{*}$ are partially isometric, $\|\mathrm{e} \mid=\| W W^{*} \mathrm{e} \| ; W W^{*} \mathrm{e}$ is an image of e by the projection $W W^{*}=P$, so that $\mathrm{e}=W W^{*} \mathrm{e}$ or we have $P=U_{\rho}$. This completes the proof.

Thus we can see that $\mathbf{R}^{s}$ has no direct summand of the purely infinite class, by Theorem 1.2, and that the above theorem is available for $\mathbf{R}$.
3. Traces on $*$-algebras.

By $*$-algebra we shall mean, as usual, an algebra which has an operation $A^{*}$ satisfying $1^{\circ}(\alpha A+\beta B)^{*}=\bar{\alpha} A^{*}+\beta B^{*}, \quad 2^{\circ} \quad(A B)^{*}=B^{*} A^{*}$, $3^{\circ} \quad A^{* *}=A$.

Definition 3.1. A linear functional $\sigma$ on a $*$-algebra $\mathbf{A}$ is called a state if $\sigma\left(A^{*} A\right) \geqq 0$ for $A \in \mathbf{A}$, and a trace if it is a state and satisfies $\sigma(A B)=\sigma(B A)$ for $A, B \in \mathbf{A}$. A trace (or state) is said to be bounded if there exists a constant $M$ such that (3.1) $\quad|\sigma(A)| \leqq M \sigma\left(A^{*} A\right), \quad$ for $A \in \mathbf{A}$.

The double unit rry representations of $a *-a!g 2 b r a$ by the trace (for the definition of the d.u.r. ${ }^{\text {¹ }}$ of a $*$-algebra, see [15; Definition 3.1]) have been already discussed by Nakamura [9]. He treated only a $C^{*}$-algebra with the unit element, but most part of his results holds true in the case of a $k$-algebra with a trace. (cf. also [2; Chap. II]).

Next we shall prove the following generalization of Lemma 15 of [3], which is also interest in the theory of the $W^{*}$-algebras.

Theorem 3.1. Lot $\mathbf{M}$ be a $W^{*}$-algebra without a part of the purely ininite class, and let $\mathbf{M}_{F}$ be a *-algebra generated by the $E$-finite operators in $\mathbf{M}$. Then there exists a maximal two-sided ideal in $\mathbf{M}_{F} ;$ moreover, there exists a one-to-one correspondence between the maximal two-sided ideals and the maximal ideals in $\mathbf{M}^{\dagger}$.

First, we shall prove some lemmas.
Lemma 3.1. Let m be a two-sided ideal in $\mathbf{M}_{F}$, and let $\mathrm{m}^{4}$ be the image of m by the 4 -operation, then $\mathrm{m}^{4}$ is an ideal in $\mathbf{M}^{4}$.
7) It must be noted here that in this case, $U_{A}$ is not necessarily a unitary operator, but it satisfies only the relation $U_{A^{*}}=U_{A^{*}}$.

Proof. If $A, B \in \mathrm{~m}^{4}$, then $A+B \in \mathrm{~m}^{4}, \alpha A \in \mathrm{~m}^{4}$ are evident. Let $T \in \mathbf{M}^{\xi}, A \in \mathbf{m}$. then $T A^{\xi}=(T A)^{4}$ by Theorem 2.1. (iv $\beta$ ), and $T A$ $\in \mathbf{M}_{F}$, so $T A^{4} \in \mathbf{m}^{4}$. Thus it is sufficient to prove that $\mathbf{m}^{4} \neq \mathbf{M}^{\xi}$. Suppose $\mathbf{m}^{4}=\mathbf{M}^{\xi}$, then it implies that the unit $I \in \mathrm{~m}^{4}$, or it implies that there exists a projection $E^{\prime} \in \mathrm{m}$ such that $E^{\prime} \sim E$, by the definition of the 4 -operation. But, generally, if a projection $P$ is contained in a two-sided ideal m , and if a projection $Q \sim P$, then $Q \in \mathrm{~m}$. Indeed, denote by $W$ the partially isometric operator which gives the equivalence $Q \sim P$, then $W$ and its adjoint $W^{*}$ are contained in $\mathbf{M}_{F}$ because $W$ and $W^{*}$ are contained in an $E$-finitep rojection $P \cup Q$. Thus we obtain $Q=Q Q=W W^{*} W W^{*}=W P W^{*} \in \mathrm{~m}$. By this fact, any $E$-finite projection is contained in m and we obtain $\mathbf{m}=\mathbf{M}_{F}$; this is a contradiction.

## Lemma 3.2. Let n be an ideal in $\mathbf{M}^{4}$, then

$$
\begin{equation*}
\mathbf{m}=\left\{A \in \mathbf{M}_{F} ;(A T)^{夕} \in \mathbf{n} \quad \text { for all } T \in \mathbf{M}_{F}\right\} \tag{3.2}
\end{equation*}
$$

is a two-sided ideal in $\mathbf{M M}_{F}$.
Proof. If $A, B \in \mathrm{~m}$, then $A+B, \alpha A \in \mathrm{~m}$ are evident. Let $A \in \mathrm{~m}$, $S \in \mathbf{M}_{F}$, then we obtain $A S, S A \in \mathbf{m}$; because, for any $T \in \mathbf{M}_{F}, \quad(A S T)^{4}$ $\in \mathrm{n}$ and $(S A T)^{\xi}=(A T S)^{\xi} \in \mathbf{n} . \mathbf{m}^{\prime} \neq \mathbf{M}_{F}$ is as follows: the unit $I \notin \mathbf{n}$, so that for the generalized unit $E, I=E^{\xi}=(E E)^{\xi} \notin \mathrm{n}$, therefore we obtain $E \notin \mathrm{~m}$.

Proof of the theorem. Let $\mathbf{n}$ be a maximal ideal in $\mathbf{I M}^{4}$, then $m$, given by (3.2) is a two-sided ideal in $\mathbf{I M}_{F}$. Let there exists a two-sided ideal $\mathbf{m}^{\prime}$ containing $\mathbf{m}$, then $\left(\mathbf{M}^{\prime}\right)^{4}$ is an ideal in $\mathbf{M}^{\prime}$ by Lemma 3.1. Suppose a maximal ideal $n_{1}$ in $\mathbf{M}^{4}$ containing ( $\left.m^{\prime}\right)^{4}$, and denote by $m_{1}$ the two-sided ideal in $\mathbf{M}_{F}$ given by (3.2) for $\mathbf{n}_{1}$. Then $\mathbf{m} \subseteq \mathbf{m}^{\prime} \subseteq \mathbf{m}_{1}$ is clear, so that $\mathbf{n} \subseteq \mathbf{n}_{1}$ and we have $\mathbf{n}=\mathbf{n}_{1}$ as n is maximal. Therefore we obtain $\mathbf{m}=\mathbf{m}^{\prime}$, that is, $\mathbf{m}$ is maximal. Thus we see that there is a maximal twosided ideal in $\mathbf{M}_{F}$, and it corresponds to the maximal ideal in $\mathbf{M}^{\xi}$.

Conversely, let $\mathbf{m}$ be a maximal ideal in $\mathbf{M}_{F}$, and suppose that the corresponding $\mathbf{m}^{4}$ is not maximal in $\mathbf{M}^{4}$. Then there is a maximal ideal $\mathbf{n}$ containing $\mathrm{m}^{4}$ properly. Consider the two-sided ideals $\mathrm{m}^{\prime}$ and $\mathrm{m}_{1}$ in $\mathbf{M}_{F}$, given by (3.2) for $\mathrm{m}^{4}$ and n , respectively, then clearly $\mathrm{m}_{1} \supseteq \mathrm{~m}^{\prime} \supseteq \mathrm{m}$. But there exists a $A \in \mathbf{M}_{F}$ such that $A^{4} \in \mathbf{n}-\mathbf{m}^{4}$, therefore there exists a $B$ $\in \mathbf{M}^{4}$ such that $B A^{y} \notin \mathbf{m}^{4}$, this implies $A \in \mathbf{m}_{1}-\mathbf{m}^{\prime}$; this fact contradicts the maximality of m . Thus we obtained the proof.

By the above argument, we see that $A$ is contained in the maximal $m$ if and only if $(A T)^{4} \in \mathbf{m}^{4}$ for all $T \in \mathbf{M}_{F}$.

As we have defined the $\xi$-operation for the $*$-algebra $\mathbf{M}_{F}$ in $\S 2$, put

$$
\begin{equation*}
f(A)=f^{\prime}\left(A^{\varphi}\right) \quad \text { for } A \in \mathbf{M}_{F} \tag{3.3}
\end{equation*}
$$

where $f^{\prime}$ is a trace on $\mathbf{M}^{\prime}$, then we obtain a trace on $\mathbf{M}_{F}$.
Now let $\mathbf{m}$ be a maximal two-sided ideal in $\mathbf{M}_{F}$, then $\mathbf{m}^{4}$ is a maximal ideal in $\mathbf{M}^{\dagger} \cdot$ it is well-known that in $\mathbf{I M}^{\xi}$ there exists the one-to-one cor-
respondence between the maximal ideals and the characters, and they are related by the condition: $A \in \mathbf{m}^{\prime}$ if and only if $\mathcal{X}^{\prime}(A)=0$, for a character $\chi^{\prime}$. Therefore, by the above remark, we obtain that $A \in \mathrm{~m}$ if and only if $\chi^{\prime}\left((A T)^{\xi}\right)=0$ for all $T \in \mathbf{M}_{F} ;$ by (3.3), $\mathrm{A} \in \mathrm{m}$ is equivalent to $\chi(A T)=0$ for all $T \in \mathbf{M}_{F}$. That is, $A \in \mathbf{m}$ is equivalent to $\chi\left(A^{*} A\right):=0$, by the Schwarz inequality. Thus, the maximal two-sided ideal in $\mathbf{I M}_{F}$ is characterised by the trace, introduced by the character of $\mathbf{M M}^{\boldsymbol{y}}$. In this sense, we shall call such a trace a character of $\mathbf{M}_{\mathrm{F}}$. Then the following theorem is obtained:

ThEOREM 3.2. There exists a one-to-one correspondence between the characters $\chi$ of $\mathbf{M}_{F}$ and the characters $\chi^{\prime}$ of $\mathbf{M}^{\xi}$, and they are re'ated by

$$
\begin{equation*}
\chi(A)=\chi^{\prime}\left(A^{\psi}\right) \tag{3.4}
\end{equation*}
$$

4. An extension of the Plancherel formula.

Consider again the d.u.r. of $G$ by the central Radon measure of the positive type $\mu$. Because $\mathbf{R}^{s}$ has no part of the purely infinite class, as remarked in $\S 2, \mathbf{R}^{s}$ is a direct sum of two $W^{*}$-algebras : of the finite class $\left(\mathbf{R}^{s}\right)^{r}$ and of the infinite class $\left(\mathbf{R}^{s}\right)^{i}$. As the generalized unit $E$ of $\mathbf{R}^{s}$, we take $E=I^{f} \oplus \Sigma \oplus U_{e_{\alpha}}$, where $I^{j}=Z_{0}$ is the unit element of $\left(\mathbf{R}^{s}\right)^{f}$, and $U_{s}{ }^{\alpha}$ are the bounded projection defined by $\mathrm{e}_{\alpha}$; the possibility of this choice is due to Theorem 1.2. Let the corresponding central envelopes be $Z_{\alpha}$, then the unit element $I^{i}$ of $\left(\mathbf{R}^{s}\right)^{i}$ is spanned by $Z_{\alpha}$. This system $\left\{Z_{0} ; U_{e_{\alpha}}, Z_{\alpha}\right\}$ will be called the defining system of the 4 operation. In $\left(\mathbf{R}^{s}\right)^{f}$, we can also take some system of bounded projections $U_{e_{\beta}}$ such that $\Sigma \oplus U_{e_{\beta}} \oplus \Sigma \oplus U_{e_{\alpha}}=E$, and define a 4 -operation with respect to this system, then we can discuss the both parts by the unified method. But such 4 -operation has some pathological properties as shown in $[14 ; \S 3]$, so it is preferable to treat as heer.

As be well-known. the set of all characters of $\mathbf{R}^{\text {y }}$ is a compact (totallydisconnected) space $\bar{\Omega}$ in the weak topology; by the above partition $I^{f}$ and $I^{i}$ of the unit $I$ the space $\bar{\Omega}$ is decomposed into the direct sum of two compact spaces $\bar{\Omega}^{r}$ and $\bar{\Omega}^{i}$, say. By Theorem 3.2, there is the one-to-one correspondences between the characters of $\mathbf{R}_{F}^{s}$, generated by the $E$-finite operators in $\mathbf{R}^{s}$, and the characters of $\mathbf{R}^{3}$. If we introduce the weak topology in the set of the characters of $\mathbf{R}_{F}^{s}$, then by (3.3), we obtain a homeomorphism between them, because $\bar{\Omega}$ is compact; denote by $\overline{\mathbf{X}}$ the set of characters of $\mathbf{R}_{F}^{s}$, then $\overline{\mathbf{X}}$ becomes compact and $\overline{\mathbf{X}}=\overline{\mathbf{X}} \oplus \nmid \overline{\mathbf{X}}$, each of which corresponds to $\bar{\Omega}^{f}$ and $\overline{\Omega^{i}}$, respectively. In each $\mathbf{R}_{\alpha}^{s}=Z_{\alpha} \mathbf{R}^{s}(\alpha \neq 0)$, any $E$-finite operator is defined by a bounded element in 5 , but this is not the case in $\left(\mathbf{R}^{s}\right)^{f}$. Therefore it is convenient to introduce the $*$-algebra $\left(\mathbf{R}_{0}^{s}\right)_{F}$, generated by the $E$ finite operators in $\mathbf{R}_{0}^{\mathrm{c}}$, (see, §1); we shail denote by $\left(\mathscr{ぬ}_{0}\right)_{F}$ the set of the corresponding element of $\mathfrak{J}$ to the operators in $\left(\mathbf{R}_{0}^{\mathrm{j}}\right)_{F}$. It is clear that $\left(\mathbf{R}_{0}^{\mathrm{s}}\right)^{f}$ $=\left(\mathbf{R}_{0}^{s}\right)_{F}^{f}$ and $\left(\mathbf{R}^{s}\right)^{i}=\left(\mathbf{R}_{0}^{s}\right)_{r}$. Now let us contract the character $\chi$ in $\overline{\mathbf{X}}$ to $\left(\mathbf{R}_{0}^{\delta}\right)_{F}$
and consider this as a trace $\sigma_{X}$ on $\left(\mathbf{R}_{0}^{c}\right)_{F}$; if we introduce also the weak topology in the set of the traces on $\left(\mathbf{R}_{0}^{\mathrm{j}}\right)_{F}$, then the mapping $\chi \rightarrow \sigma_{X}$ is continuous, and $\overline{\mathbf{X}}$ is compact, so that the image $\widetilde{\mathbf{X}}$ of $\overline{\mathbf{X}}$ is also compact; omit the trace $\sigma \equiv 0$ on $\left(\mathbf{R}_{0}^{s}\right)_{F}$, then we obtain a locally compact space $\mathbf{X}$.
Clearly, $\mathbf{X}=\mathbf{X}^{j} \oplus \mathbf{X}^{i}$, and $\mathbf{X}^{i}=\overline{\mathbf{X}^{i}}$; thus we obtain a locally compact space, which plays a role of the dual object of the Plancherel formula.

As $\sigma \in \mathbf{X}$ is a trace on the $*$-algebra $\left(\mathbf{R}_{0}^{s}\right)_{F}$, we obtain a d.u.r. as stated in §3. That is, $\mathbf{u}(\sigma)=\left\{U_{x} ; \sigma\left(U_{x}{ }^{*} U_{x}\right)=0\right\}$ is a two-sided ideal in $\left(\mathbf{R}_{0}^{\mathrm{j}}\right)_{F}$, therefore we obtain a canonical mapping $U_{x} \rightarrow \mathrm{x}(\sigma)$ to the quotient algebra. Put

$$
\begin{equation*}
<\mathbf{x}(\sigma), \mathbf{y}(\sigma)>=\sigma\left(U_{y}^{*} U_{x}\right), \tag{4.1}
\end{equation*}
$$

this is an inner product on the quotient algebra; by completion with this inner product we obtain a Hilbert space $\mathfrak{(}(\sigma)$. To construct the d.u. r., it is sufficient to put

$$
\begin{align*}
& U_{x}(\sigma) \mathbf{y}(\sigma)=\mathbf{x} * \mathbf{y}(\sigma), \quad V_{x}(\sigma) \mathbf{y}(\sigma)=\mathbf{y} * \mathbf{x}(\sigma),  \tag{4.2}\\
& S(\mathbf{x}(\sigma))=(\mathbf{S} \mathbf{x})(\sigma) . \tag{4.3}
\end{align*}
$$

These reasons are quite analogous to the one sketched in $\S 1$ for the d.u.r. of the group; for detail, see Nakamura [9]. Thus we can correspond to each $\sigma \in \mathbf{X}$ a Hilbert space $\check{5}(\sigma)$. Since we have introduced in $\mathbf{X}$ the weak topology, for each $U_{x} \in\left(\mathbf{R}_{0}^{*}\right)_{F}, \sigma\left(U_{x}\right)$ is a continuous function with respect to $\sigma$ : the vector-function $\mathbf{x}(\sigma)$, defined on $\mathbf{X}$ to $\mathfrak{S}(\sigma)$, is continuous; by the construction mentioned above, the set of $\mathbf{x}(\sigma)$ is dense in each $\mathfrak{y}(\sigma)$, so that the vectorfunctions $\mathbf{x}(\sigma)$ form a fundamental family of the continuous vector-functions $\Lambda$ in the sense of Godement [2; Chap. III].

If $\sigma \in \mathbf{X}$ approches to the infinity, then evidently $\mathbf{x}(\sigma) \rightarrow 0$; thus the vector-function $\mathbf{x}(\sigma)$ has an analogous property with the ordinary Fourier transform. Now our object is to generalize the Plancherel theorem in the following form:

Theorem 4.1. Let $G$ be a unimodular locally compact group, and let a d.u.r. $\left\{\underset{\mathrm{J}}{\mathrm{J}}, U_{s}, V_{s}, S\right\}$ be constructed by a central Radon measure of the positive type $\mu$ on $G$. Then there exist a locally compact space $\mathbf{X}$ and a measure $\hat{\mu}$ on X , possessing the following properties:
a) for any $\mathbf{x}, \mathbf{y} \in\left(\mathfrak{g}_{0}\right)_{F}$,

$$
\begin{equation*}
<\mathbf{x}, \mathbf{y}>=\int_{\mathbf{x}}\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)>d \hat{\mu}(\sigma), \tag{4.4}
\end{equation*}
$$

b) $\mathfrak{~}$ is isomorphic to $\mathrm{L}_{\mathrm{A}}^{2}$.

Here we shall freely use the notion of the continuous sums of the Hilbert spaces proposed by Godement [2] ${ }^{8}$, but some generalizations are necessary.

[^3]Definition 4.1. We call the fundamental family of the continuous vectorfunctions (la famille fondamentale de champs de vecteurs continus) the set $\Lambda$ of the vector-functions on $\mathbf{X}$, satisfying the following axioms: $\left(\Lambda_{1}\right): \Lambda$ is a linear subspace of the space of all the vector-functions defined on $\mathbf{X} ;\left(\Lambda_{2}\right)$ : for any $\mathbf{X} \in \Lambda$, the scalar function $\|\mathbf{x}(\sigma)\|$ is continuous on $\mathbf{X}$; $\left(\Lambda_{3}\right)$; for any $\sigma \in \mathbf{X}$, the $\mathbf{x}(\sigma)(\mathbf{x} \in \Lambda)$ are dense in $\mathfrak{S}(\sigma)$. And we say that a vector-function $\mathbf{x}$ on X is continuous in a point $\sigma_{0}$, if for any $\varepsilon>0$, there exist a neighborhood $V$ of $\sigma_{0}$ and a $\mathbf{y} \in \Lambda$ such that $\|\mathbf{x}(\sigma)-\mathbf{y}(\sigma)\|<\varepsilon$ for any $\sigma \in V$.

Definition 4.2. ${ }^{\text {g }}$ We say that a vector-function $\mathbf{x}$ is squarely-summable (with respect to $\Lambda$ and $\hat{\mu}$ ), if $\int_{\mathbf{X}}\langle\mathbf{x}(\sigma), \mathbf{x}(\sigma)>d \hat{\mu}(\sigma)<+\infty$ and for any $\varepsilon>0$, there exists a continuous $\mathbf{y}$ such that $\left(\int_{\mathrm{x}}\|\mathbf{x}(\sigma)-\mathbf{y}(\sigma)\|^{2} \boldsymbol{d} \hat{\mu}(\sigma)\right)^{1 / 2}<\varepsilon$. The set of these vector-functions, modulo the null-set, and defined the norm by

$$
\begin{equation*}
\|\mathbf{x}\|=\left(\int_{\mathbf{X}}\langle\mathbf{x}(\sigma), \mathbf{x}(\sigma)>\hat{d} \hat{\mu}(\sigma))^{1 / 2}\right. \tag{4.5}
\end{equation*}
$$

will be denoted by $L_{\Lambda}^{2}$. Then we can easily see that $L_{\Lambda}^{\prime}$ forms a Hilbert space with the above norm.

## 5. Proof of Theorem 4.1.

The aim of our proof is to construct a Radon measure $\tilde{\mu}_{\alpha}$ on each compact (or locally compact) set $\Gamma_{\alpha}$, which gives the required formula with respect to the elements of $\left(\mathscr{\aleph}_{0}\right)_{F}$; and then to extend these measures $\hat{\mu}_{\alpha}$ to a measure $\hat{\mu}$ on the whole space $\mathbf{X}$ and to all elements of $\mathfrak{y}$. Here $\Gamma_{a}$ denotes the subset of $\mathbf{X}$, which corresponds to the defining system $Z_{\alpha}$. In the part of the finite class, this problem is reduced to the theorem 3.1 of [15], because $Z_{0} \mathfrak{\oiiint}_{0}$ is a maximal Hilbert algebra of the finite class. Therefore $\bar{i}_{t}$ is sufficient to consider only the part of the infinite class. We will reduce the proof to the case of the finite class: this is an analogous procedure to the construction of the $\zeta$-operation in a $W^{*}$-algebra of the infinite class, discussed in [14].

Let $F(\sigma)$ be a continuous function on $\mathbf{X}^{\text {}}$, then it corresponds to an operator $U_{F} \in \mathbf{R}^{4}$, because $\mathbf{X}^{6}$ is isomorphic to the Boolean space of ( $\left.\mathbf{R}^{4}\right)^{\prime}$; moreover we can take a $U_{x} \in\left(\mathbf{R}_{0}^{s}\right)_{F}$ such that $F(\sigma)=\sigma\left(U_{x}\right)$ on $\Gamma_{\alpha}$ by the definition of the $\psi$-operation. As shown in Lemma 1 of [13], $Z_{\alpha} \mathbf{R}^{\prime \prime}$ is
 $A=A$, and this is a $W^{*}$-algebra of the finite class on the Hilbert space $U_{i_{\alpha}} \mathfrak{H}$. Now we shall show

[^4]Lemma 5.1. A necessary and sufficient condition that a $U_{x}$ should be in$\mathbf{R}_{\left(U_{i} e_{\alpha}\right)}$ is that $\mathbf{x}$ should be in $U_{e_{\alpha}} V_{o_{\alpha}} \mathfrak{H}$.

Proof. Assume that $\mathbf{x} \in U_{e_{\alpha}} V_{e_{\alpha}} \cdot \mathfrak{V}$, then $U_{e_{\alpha}} V_{\rho_{\alpha}} \mathbf{x}=\mathbf{x}$, or $U_{e_{\alpha}} V_{t \alpha} U_{x},=U_{x}$, this implies $U_{e \alpha} U_{x x}=U_{x}$ and $U_{x} U_{e \alpha}=U_{e_{\alpha}} U_{t_{e_{\alpha}}} V_{e_{\alpha}} x=U_{e_{\alpha}} U_{x}=U_{x}$, that is, $U_{x}$ $\in \mathbf{R}_{\left(V_{\alpha}\right)}$. Conversely if $U_{x} \in \mathbf{R}^{s}{ }_{\left(U_{\alpha}\right)}$, then clearly we obtain $U_{e_{\alpha}} \mathbf{x}=\mathbf{x}$, and $V_{\sigma_{\alpha}} \mathbf{x}=\mathbf{x}$; this complete the proof.

The above lemma shows that the elements $\mathbf{x}$ corresponding to $U_{x} \in$
 can apply the results of [15] to the part of $U_{e_{\alpha}} V_{e_{\alpha}} \mathfrak{H}$; as the 4 -operation is defined in $\left(U_{e_{\alpha}} V_{e_{\alpha}} \mathfrak{J}\right)_{0}$, for each $\sigma\left(U_{x}^{4}\right), \mathbf{x} \in\left(U_{e_{\alpha}} V_{e_{\alpha}} \mathfrak{J}\right)$, if we take a real $\sigma\left(U_{y}^{\xi}\right), \mathbf{y} \in\left(U_{e_{\alpha}} V_{e_{\alpha}} \mathfrak{\mathfrak { g }}\right)$, such that $\sigma\left(U_{x}^{\natural}\right)=\sigma\left(U_{x}^{\natural}\right) \sigma\left(U_{y}^{\xi}\right)$ and put

$$
\begin{equation*}
I_{\alpha}\left(\sigma\left(U_{x}^{\xi}\right)\right)=\left\langle\mathbf{x}^{\xi}, \mathbf{y}^{\prime}\right\rangle \tag{5.1}
\end{equation*}
$$

where $\mathbf{x}^{\xi}$ is the projection of $\mathbf{x}$ to $\left(U_{e} V_{e_{\alpha}} \mathfrak{W}\right)^{\frac{y}{c}}$ ([15; Theorem 2.1]), we obtain. a Radon measure $\hat{\mu}_{a}$ on $\Gamma_{a}$ such that

$$
\begin{equation*}
I_{\alpha}\left(\sigma\left(U_{x}^{y}\right)\right)=\int_{\Gamma_{\alpha}} \sigma\left(U_{x}^{\xi}\right) d \hat{\mu}_{\alpha}(\sigma)=\left\langle\mathbf{X}^{\xi}, \mathbf{y}\right\rangle \tag{5.2}
\end{equation*}
$$

or by the same reasons to [15], we obtain
Lemma 5.2. For $\mathbf{x}, \mathbf{y} \in\left(U_{e_{\alpha}} V_{e_{\alpha}} \mathfrak{W}\right)_{0}$ and $U_{F} \in Z_{\alpha} \mathbf{R}^{\xi}$,

$$
\begin{equation*}
<\mathbf{x}, U_{F} \mathbf{y}>=\int_{\Gamma_{\alpha}}<\mathbf{x}(\sigma), \mathbf{y}(\sigma)>\overline{F(\sigma)} d \hat{\mu}_{\alpha}(\sigma) . \tag{5.3}
\end{equation*}
$$

But there exists an $\mathbf{x}^{\prime}$ not necessarily in $U_{e_{\alpha}} V_{e_{\alpha}} \mathfrak{F}$, but $\sigma(U)_{x}^{\xi}=\sigma\left(U_{\neq 1}^{\xi}\right)$ on $\Gamma_{\alpha}$. Therefore we will assume that if $U_{x} \in \mathbf{R}^{{ }_{(P)}}, \quad P \leqq U_{e_{\alpha}}$, then a $U_{y}$, required in (5.1), should be taken in the same $\mathbf{R}^{s}{ }_{(P)}$. In this assumption, we have

Lemma 5.3. The positive linear functional $I_{\alpha}$ on the space of the continuous functions of $\Gamma_{\alpha}$ is well-defined by the relation (5.1).

Proof. First, let $E$-finite projections $P$ and $P_{1}$ be equivalent with the partially isometric operator $W$; let $U_{x}$ and $U_{x_{1}}$ be contained in $P$ and $P_{1}$ respectively, and assume $U_{x}^{\xi}=U_{x_{1}}^{\xi}$. Then, if we denote the $\mathbf{x}^{\prime}$ and $\mathbf{x}_{1}^{4}$ the images of the 4 -operation defined in $P S P S \mathscr{I}$ and $P_{1} S P_{1} S \mathscr{F}$ resp., we have $\mathbf{x}^{4}=W^{*} S W^{*} S \mathbf{x}_{1}^{4}$. In fact by [13; Lemma 1], we have $U_{x y}=P U_{x}^{\psi}$ and $U_{x_{1}{ }^{\dagger}}=P_{1} U_{x 1}^{\xi}=P_{1} U_{x}^{\xi}$. Therefore, $W^{*} U_{x_{1} \xi} \quad W=W^{*} P_{1} W U_{x 4}=P U_{x \xi}=U_{x 4}$. Evidently, this implies $\mathbf{x}^{4}=W^{*} S W^{*} S \mathbf{x}_{1}{ }^{\prime}$. As $W^{*} S W^{*} S$ is partially isometric, and as it is sufficient to consider the above case by the definition of the 4 -operation [14; §2], we obtain the proof.

Summarizing the mentioned above, we see
Lemma 5.4. Let $\mathbf{x}, \mathbf{y} \in\left(5_{0}\right)_{r}$, and let $F$ be a continuous function on $\mathbf{X}$, then we have a unique Radon measure $\hat{\mu}_{a}$ on $\Gamma_{a}$ such that

$$
\begin{equation*}
<Z_{\alpha}, U_{F} \mathbf{y}>=\int_{\mathrm{T}_{\alpha}}\left\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)>\overline{F(\sigma)} d \dot{\mu}_{\alpha}(\sigma)\right. \tag{5.4}
\end{equation*}
$$

Now we shall extend the Radon measure $\mu_{x}$ constructed above on each $\Gamma_{a}$ to a regular measure $\hat{\mu}$ on the whole space $\mathbf{X}$. But this will be done by the well-known extension theorem of measures ${ }^{10}$; let $S$ be a ring, generated by the compact sets contained in some $\Gamma_{\alpha}$, that is, $S \in S$ if and only if $S$ is the following form: $S=\bigcup_{\iota=1}^{u} S_{a}, S_{a, \imath} \subseteq \mathrm{I}_{a}$ and compact; if we put

$$
\begin{equation*}
\hat{\mu}(S)=\sum_{i=1}^{n} \hat{\mu}_{a}\left(S_{\alpha, l}\right), \tag{5.5}
\end{equation*}
$$

then $\hat{\mu}$ becomes a $\sigma$-finite measure on $\mathbf{S}$, so that we have a unique $\sigma$-finite measure $\hat{\mu}$ on the $\sigma$-finite ring $\overline{\mathbf{S}}$, generated by $\mathbf{S}$.

Let x be a bounded element in $\mathfrak{g}$, then it is evident that the set of $\alpha \in \mathrm{A}$ such that $Z_{\alpha} \mathrm{x} \neq 0$ is at most countable, say $\alpha_{i} ; \mathrm{x}=\sum_{i=1}^{\infty} Z_{\alpha_{i}} \mathrm{x}$. Furthermore, let $U_{x}$ be $E$-finite, and denote $\varphi_{\mathrm{r}_{a}}(\sigma)$ the characteristic function of $\Gamma_{\alpha}$, then we can easily see that $\varphi_{\Gamma_{a}}(\sigma) \sigma\left(U_{x}\right)=\sigma\left(Z_{\alpha} U_{x}\right)=\sigma\left(U_{Z_{\alpha^{x}}}\right)$, so that $\alpha \in \mathrm{A}$ such that $\varphi_{\Gamma_{a}}(\sigma) \sigma\left(U_{x}\right) \equiv 0$ are at most countable. Hence $\sigma\left(U_{x}\right)$ becomes measurable for the above $\hat{\mu}$, and

$$
\begin{gather*}
\int_{\mathbf{X}} \sigma\left(U_{y}{ }^{*} U_{v}\right) \overline{F(\sigma)} d \hat{\mu}(\sigma)=\sum_{i=1}^{\infty} \int_{\Gamma_{\alpha_{i}}} \sigma\left(U_{y} * U_{x}\right) \overline{F(\sigma)} d \hat{\mu}_{\alpha_{l}}(\sigma)  \tag{5.6}\\
\left.=\sum_{i=1}^{\infty}\left\langle Z_{\alpha_{i}} \mathbf{x}, U_{r} \mathbf{Y}\right\rangle=<\mathbf{x}, U_{t} \mathbf{Y}\right\rangle
\end{gather*}
$$

Thus we obtain
Lemma 5.5. For bounded $\mathbf{x}, \mathbf{y} \in \mathfrak{I}$, which give the $E$-finite operators $U_{x}$ and $U_{y}$, we have

$$
\begin{equation*}
<\mathbf{x}, U_{F} \mathbf{Y}>=\int_{\mathbf{x}}\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)\rangle \overline{F(\sigma)} d \hat{\mu}(\sigma) \tag{5.7}
\end{equation*}
$$

But there exist bounded elements of $\mathfrak{S}$, which give the not necessarily $E$-finite operators. First we note

Lemma 5.6. Any s.a. idempotent element $\mathrm{e} \in \mathfrak{\ddagger}$ is the (strong) limit of the elements of $\left(\mathfrak{g}_{0}\right)_{F}$

Proof. It is sufficient to consider in the part of the infinite class. As $U_{e}$ is a bounded projection, it is finite in the sense of $W^{*}$-algebras (Lemma 2.1); $U_{\theta}$ is decomposed in the following form by [14; Theorem 1]:

[^5]\[

$$
\begin{equation*}
U_{e}=\sum_{i=1}^{\infty} Q_{i} U_{e}=\sum_{i=1}^{\infty} U_{Q_{i},} \tag{5.8}
\end{equation*}
$$

\]

where $Q_{i}$ are the central projections such that $I=\sum_{i=1}^{\infty} \oplus Q_{i}$, and every $U_{Q_{i}-}$ is $E$-finite. The (5.8) means that $\mathrm{e}=\sum_{i=1}^{\infty} Q_{i} \mathrm{e}$, because $\mathrm{e}=U_{e} \mathrm{e}=\sum_{i=1}^{\infty} Q_{i} U_{e} \mathrm{e}$ $=\sum_{i=1}^{\infty} Q_{i} \mathrm{e}$, and the fact that $U_{Q_{i} e}$ is $E$-finite, implies $Q_{i} \mathrm{e} \in\left(\mathfrak{H}_{\mathrm{G}}\right)_{F}$ Thus the proof is completed.

Combining the above lemma and Lemma 1.3, we see that every bounded element $\mathbf{x}$ is the (strong) limit of some elements $\mathbf{y}_{n} \in\left(\mathfrak{S}_{0}\right)_{E}$, that is, $\left(\mathfrak{F}_{0}\right)_{F}$ is dense in $\mathfrak{F}$.

Consider now the linear subspace $\mathfrak{M}$ of $\mathfrak{H}$, constructed by the elements of the form:

$$
\begin{equation*}
\mathbf{x}=U_{r_{1}} \mathbf{x}_{1}+\ldots \ldots+U_{F_{n}} \mathbf{x}_{n}, \quad \mathbf{x}_{i} \in\left(\mathfrak{B}_{0}\right)_{r}, \quad F_{i} \in \mathbf{L}(\mathbf{X}), \tag{5.9}
\end{equation*}
$$

then by (5.7), we can associate to such an $\mathbf{x}$ a vector-function

$$
\begin{equation*}
\mathbf{x}(\sigma)=F_{1}(\sigma) \mathbf{x}_{1}(\sigma)+\ldots+F_{n}(\sigma) \mathbf{x}_{n}(\sigma) \tag{5.10}
\end{equation*}
$$

Evidently, this vector-function is continuous and has a compact support on. $\mathbf{X}$; by the formula (5.7) and the fact that the correspondence $F \rightarrow U_{F}$ is. multiplicative, we have

$$
\begin{equation*}
<\mathbf{x}, \mathbf{y}>=\int_{\mathbf{x}}\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)>d \hat{\mu}(\sigma) \tag{5.11}
\end{equation*}
$$

for any $\mathbf{x}, \mathbf{y} \in \mathfrak{M}$.
On the other hand, any continuous vector-function on $\mathbf{X}$ is the uniform limit of the vector-functions of the form (5.10) on every compact set of $\mathbf{X}$. ${ }^{11)}$ Therefore the vector-functions (5.10) are dense in $L_{i}^{2}$; so that we have the isomorphism between the closure of $\mathfrak{M}$ in $\mathfrak{F}$ and the space $\mathrm{L}_{\mathbb{A}}^{2}$. It remains. to prove that $\mathfrak{M}$ is dense in $\mathfrak{H}$ and that this isomorphism gives the transformation $\mathbf{x}$ to $\mathbf{x}(\sigma)$ for $\mathbf{x} \in\left(\check{\jmath}_{0}\right)_{F}$, defined previously in $\S 4$.

If $F(\sigma) \in \mathbf{L}(\mathbf{X})$ converges to 1 uniformly on every compact set, then

$$
\begin{aligned}
\lim & \left\langle U_{l} \mathbf{x}, \mathbf{y}\right\rangle=\lim \int_{\mathrm{x}}\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)\rangle F(\sigma) d^{\prime} \mu(\sigma) \\
& =\int_{\mathrm{x}}\left\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)>d \hat{\mu}(\sigma)=\langle\mathbf{x}, \mathbf{y}\rangle \quad \text { for } \mathbf{x}, \mathbf{y} \in\left(\mathfrak{H}_{0}\right)_{F} .\right.
\end{aligned}
$$

Therefore, $\mathbf{x} \in\left(\mathfrak{S}_{0}\right)_{F}$ is the weak limit of the elements of the forms $U_{r} \mathbf{x}$; $\left(\mathfrak{S}_{0}\right)_{F}$ is dense in $\mathfrak{J}$ (Lemma 5.6) and $\mathfrak{M}$ is the linear subspace of $\mathfrak{g}$, so weobtain the first part of the above statesments. So that the vector-function.

[^6]$F(\sigma) \mathbf{x}(\sigma)$ converges uniformly to $\mathbf{x}(\sigma)$ on $\mathbf{X}$, therefore the above isomorphism transforms $\mathbf{x}$ to $\mathbf{x}(\sigma)$. Thus the proof is completed.

## 6. Some remarks.

Firstly, as mentioned in $\S 2$, our 4 -operation depends on the choice of the generalised unit element, or the defining system of the $\xi$-operation. We discuss here these circumstances.

Let $E^{\prime}$ be such another, and assume that $E^{\prime}$ be $E$-finite. Then any $E^{\prime}$ finite operator $A$ is also $E$-finite; we obtain by (2.2)

$$
\begin{equation*}
\sigma_{E^{\prime}}(A)=\sigma_{E}\left(E^{\prime}\right)^{-1} \sigma_{E}(A), \tag{6.1}
\end{equation*}
$$

where $\sigma_{E}$ and $\sigma_{E^{\prime}}$ is the one, defined by the same character of $\mathbf{R}^{4}$, as described in $\S \S 3$ and 4 . It should be noted that $\sigma_{E}\left(E^{\prime}\right)^{-1}$ may be infinite for some $\sigma$, but $\sigma_{E}\left(E^{\prime}\right)^{-1} \sigma_{E}(A)$ is well-defined, because $A$ is contained in some $E^{\prime}$-finite projection (see [14; §3]) ; and it is clear that the dual space $\mathbf{X}$ is uniquely determined for any generalized unit element (§4). By the relation (6.1) and the uniqueness of the Radon measure and the extension of the $\sigma$-finite measure, we obtain the following formula for any $\mathbf{x}, \mathbf{y}$, which define the $E^{\prime}$-finite operators $U_{x x}$ and $U_{y}$, respectively:

$$
\begin{equation*}
<\mathbf{x}, \mathbf{y}\rangle=\int_{\mathbf{x}}\left\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)>\sigma\left(E^{\prime}\right) d \dot{\mu}(\sigma)\right. \tag{6.2}
\end{equation*}
$$

But this formula gives the isomorphism of $\mathfrak{j}$ and $\mathrm{L}_{\mathrm{N}}^{2}$ for the measure $\sigma\left(E^{\prime}\right)$ $d \hat{\mu}(\sigma)$, thus we obtain

Theorem 6.1. If wz take a fixed generalized unit element $E$ of $\mathbf{R}^{s}$ as the basis, then for any another generalized unit element, which is E-fnite, our Plancherel formula becomes in the following form:

$$
\begin{equation*}
<\mathbf{x}, \mathbf{y}>=\int_{\mathbf{x}}\langle\mathbf{x}(\sigma), \mathbf{y}(\sigma)>\boldsymbol{a}(\sigma) d \hat{\mu}(\sigma), \tag{6.3}
\end{equation*}
$$

where $a(\sigma)$ is a (generalized) continuous function on $\mathbf{X}$, which depends only on the generalized unit element; the dual locally compact space $\mathbf{X}$ and the measure $\hat{\mu}$ are unique.

But arbitrary two generalized unit elements are not necessarily comparable; in this case we do not know the unicity of the measure $\hat{\mu}$ in the above sense.

Next, let us assume that $\mathbf{R}^{s}$ be of the finite class, then the decomposition obtained in Theorem 4.1 gives the irreducible one of the $W^{*}$-algebras $\mathbf{R}^{s}$ or $\mathbf{R}^{d}$, proved in [15]. Because $U_{s} \in \mathbf{R}^{s}, V_{s} \in \mathbf{R}^{d}$, we obtain the unitary operators $U_{s}(\sigma)$ and $V_{s}(\sigma)$. We can easily verify that the system $\left\{\mathscr{S}(\sigma), U_{s}\right.$ $\left.(\sigma), V_{s}(\sigma), S\right\}$ becomes the d.u.r. of the given group $G$. Moreover, if we assume that $G$ is separable, then the Hilbert space $\mathfrak{H}$ becomes separable, and $\mathbf{R}^{s}$ is also separable in the weak topology. Denote the $W^{*}$-algebras
generated by $U_{s}(\sigma)$ and $V_{s}(\sigma)$ ，by $\mathbf{R}^{s}(\sigma)$ and $\mathbf{R}^{\prime \prime}(\sigma)$ ，respectively，and consider a decomposable operator $A \sim T_{A}(\sigma)$ ，permutable with $\mathbf{R}^{s}(\sigma)$ ，then $A \in \mathbf{R}^{d}$ ， that is，$U_{A}(\sigma)=T_{A}(\sigma)$ ，a．e．and $U_{A}(\sigma) \in \overline{\mathbf{R}^{a}(\sigma)}$ ，where $\overline{\mathbf{R}^{\prime \prime}(\sigma)}$ denotes the $W^{*}$－algebra generated by the image of the elements in $\mathbf{R}^{d}$ ．This fact impiies $\mathbf{R}^{\prime}(\sigma)^{\prime}=\overline{\mathbf{R}^{c}(\sigma)}$ ，a．e．Similarly $\mathbf{R}^{d}(\sigma)^{\prime}=\overline{\mathbf{R}^{s}(\sigma)}$ ，a．e．By these facts and the Theorem 5.2 of［15］，we obtain

Theorem 6．2．Assume that $\mathbf{R}^{s}$ be of the finite class，and $G$ be seprable． Then the doub＇e unitary representations，obtained by the decomposition in Theorem 4．1，is irreducib．e a．e．

## Bibliography

［1］J．Dixmier，Les anneaux d＇opérateurs de classe finie，Ann．Ecole Norm．Sup ， 66 （1949），209－251．
〔2〕 R．Godement，Sur la théorie des représentations unitaires，Ann．of Math．，53（1951）， 68－124．
［3］R．Godement，Mémoire sur la théorie des caractères dans les groupes localement compacts unimodulaires，Journ．de Liouville，30（1951），1－110
〔4〕M Kondo，Sur les sommes directes des espaces linéaires，Proc．Im．p．Acad．Tokyo， 20（1944），425－431．
［5］M．Kondo，Sur la réductibilité des anneaux des opérateurs，Proc．Acad．Tokyo， 20 （1944），432－438．
［6］W．Mackfy，Functions on locally compact groups，Bull．Amer．Math．Soc．， 56 （1950），385－412．
〔7］F．I．MAUTNER，Unitary representations of locally compact groups，I．Ann．of Math．，5（1950），1－25．
〔8〕 F I．MAUTNER，Unitary representations of locally compact groups，II．Ann．of Math．，52（1950），528－556．
$19]$ M NAKAMURA，The two－sided representations of an operator algebra，Proc Japan Acad．，27（1951），172－176．
［10］J．von Neumann，On rings of operators，Reduction theory，Ann．of Math．， 50 （1949），401－485．
［11］I．E．SFgAL，The two－sided regular representation of a unimodular locally compact group，Ann．of Math．，51（1950）293－298．
〔12〕 I．E．Segal，An extension of Plancherel＇s formula to separable unimodular groups， Ann of Math．52（1950），272－292．
〔13〕 H．SunOUCHI，On rings of operators of infinite classes，Proc．Japan Acad．， 28 （1952），9－13．
〔14］H．SunOUCHI，On rings of operators of infinite classes．II．in Proc．Japan Acad． 28（1952）330－325．
〔15］H Sunouchi，The irreducible docompositions of the maximal Hilbert algebras of the finite classes．This volum，2כ7－215．

Added in Proof．（Jan．31，1953）．After our papers were presented to the editors，Dixmier has published an elegant account of the 4 －operation and traces on an arbitrary $W^{*}$－algebra：Applications 4 dans les anneaux d＇opérateurs，Comp．Math．， 10 （1952）1－55．

Mathematical Insititute，Tôhoku University，Sendai．


[^0]:    1) Numbers in brackets refer to the bibliography at the end of the paper. As for the com.plete bibliography related to this topic, see Mackey [6]. As the Russian papers are not yet available in this country, we omit them.
    2) For the notions of Hilbert algebras, see [15] or H. Nakano, Hilbert algebras, Tôhoku Math. Journ., 2(1950), 4-23, O. Takenouchi, On the maximal Hilbert algebras, ibid 3(1951), 123-131.
[^1]:    3) The involution $S$ is such an operator on $\mathscr{S}$ that $S(\mathbf{x}+\mathbf{y})=S \mathbf{x}+S \mathbf{y}, S(\alpha \mathbf{x})=\bar{c} \boldsymbol{i} \mathbf{x}$ $S S \mathbf{x}=\mathbf{x}, \quad\langle S \mathbf{x}, S \mathbf{y}\rangle=\langle\mathbf{y}, \mathbf{x}\rangle$.
[^2]:    4) As we use only these fundamental properties in this paper, our treatment is also available to the maximal Hilbert algebras; see [15].
    5) By $W^{*}$-algebra we shall mean a weakly closed operator algebra in a Hilbert space, and by $C^{*}$-algebra a uniformly closed one, in the terminology of Segal [11].
[^3]:    8) The notion of the continuous sum of Banach spaces was already discussed by Kondo [4.5] and his results are stronger than Godement's in some points, but the latters seems to be more suited to our purposes.
[^4]:    9) Godement considered only the Radon measure $\hat{\mu}$ on $X$, but our measure $\hat{\mu}$ is not necessarily a Radon measure. So we need this formally generalized definition.
[^5]:    10) See Halmos, Measure Theory. (1950). Especially Theorem A of p. 54.
[^6]:    11) See [2;Chap. III prop.6]. This proposition does not depend on the measure.
