# ON INFINITESIMAL HOLOMORPHICALLY PROJECTIVE TRANSFORMATIONS IN KÄHLERIAN MANIFOLDS 

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Recently, T. O$t s u k i$ and Y. Tashiro [9] ${ }^{1)}$ have studied holomorphically projective correspondences of Kählerian manifolds. Further, Y. Tashiro [11] has introduced the notion of such a correspondence of almost-complex manifolds endowed with a symmetric $\varphi$-connection, i. e. a symmetric affine connection with respect to which the almost-complex structure is covariant constant. He has defined the holomorphically projective curvature tensor $P_{k j i}{ }^{h}$ which is invariant under holomorphically projective correspondences, and characterized a Kählerian manifold of constant holomorphic sectional curvature by the condition $P_{k j i}{ }^{h}=0$. One of the present authors ${ }^{2}$ has introduced the notion of the holomorphically projective changes of a $\varphi$-connection of some type, called a half-symmetric $\varphi$-connection, and the notion of the infinitesimal holomorphically projective transformation, which will be briefly called an $H P$-transformation.

We shall devote this paper to $H P$-transformations in Kählerian manifolds of some types. In $\S 1$, we shall give some preliminary facts concerning Kählerian manifolds and infinitesimal transformations for the later use. We shall characterize in $\S 2$ the analytic $H P$-transformation as an infinitesimal transformation preserving holomorphically planar curves. In §3, we shall discuss the properties of analytic $H P$-transformations.
T. Sumitomo [10] and K. Yano and T. Nagano [13] have recently studied infinitesimal projective transformations in a Riemannian manifold and obtained valuable results. We shall consider analogous problems concerning $H P$ transformations. In §4, we shall deal with a Kählerian manifold admitting an analytic $H P$-transformation which leaves the covariant derivative of the holomorp hically projective curvature tensor. We shall prove in §5 that a Kählerian manifold which satisfies $\nabla_{k} R_{j i}=0$ and admits a non-trivial analytic $H P$-transformation is necessarily an Einstein one.

As will be proved in $\S 5$, the existence of a non-trivial analytic $H P$ transformation in a Kählerian manifold satisfying $\nabla_{k} R_{j i}=0$ reduces the manifold to an Einstein one. So, it might become a problem to investigate

[^0]$H P$-transformations in Kähler-Einstein manifold. We shall prove in $\S 6$ some theorems on $H P$-transformations in a Kähler-Einstein manifold, for example, that in a Kähler-Einstein manifold any analytic $H P$-transformation is uniquely decomposed as a sum of a Killing vector and a gradient analytic $H P$-transformation.

In the last $\S 7$, we shall discuss $H P$-tranformations in a compact Kählerian manifold having the constant holomorphic sectional curvature.

1. Preliminaries. We shall first give preliminary formulas on the Kählerian manifold and the infinitesimal transformation, isometric, affine, or holomorphically projective. Let us consider an $n(=2 m>2)$ real dimensional Kählerian manifold with local coordinates $\left\{x^{i}\right\}^{3}$ ). Then the (positive definite) Riemannian metric $g_{j i}$ and the complex structure $\boldsymbol{\varphi}_{i}{ }^{h}$ satisfy the following equations.

$$
\begin{gathered}
\boldsymbol{\varphi}_{j}^{r} \boldsymbol{\varphi}_{r}{ }^{i}=-\delta_{j}{ }^{i}, g_{r s} \boldsymbol{\varphi}_{j}^{r} \boldsymbol{\varphi}_{i}{ }^{s}=g_{j i}, \\
\nabla_{k} \varphi_{j}^{h}=0, \quad \nabla_{k} g_{j i}=0,
\end{gathered}
$$

where $\nabla_{k}$ denotes the operator of the covariant differentiation with respect to $\left\{\begin{array}{l}h i \\ j i\end{array}\right\}$.

Let $R_{k j i}{ }^{h}$ be the Riemannian curvature tensor and put $R_{j i}=R_{r j i}{ }^{r}, R_{k j t h}$ $=R_{k j i}{ }^{r} g_{r h}, R=R_{j i} g^{j i}$ and

$$
S_{j i}={\boldsymbol{\varphi}_{j}{ }^{r} R_{r i}, ~}_{\text {, }}
$$

then the following identities are valid ${ }^{4}$

$$
\begin{gather*}
R_{k j i}^{r} \boldsymbol{\varphi}_{r}^{h}=R_{k j r}{ }^{h} \boldsymbol{\varphi}_{i}^{r}, \quad R_{k j i r} \boldsymbol{\varphi}_{h}^{r}=R_{k j h r} \boldsymbol{\varphi}_{i}{ }^{r},  \tag{1.1}\\
R_{k j i h}=R_{k j t r} \boldsymbol{\varphi}_{i}{ }^{t} \boldsymbol{\varphi}_{h}^{r}, \\
R_{j i}=R_{t r} \boldsymbol{\varphi}_{j}{ }^{t} \boldsymbol{\varphi}_{i}{ }^{r},  \tag{1.2}\\
S_{j i}+S_{i j}=0, \quad S_{j i}=S_{t r} \boldsymbol{\varphi}_{j}^{t} \boldsymbol{\varphi}_{i}^{r}{ }^{r},  \tag{1.3}\\
S_{j i}=-\frac{1}{2} \boldsymbol{\varphi}^{t r} R_{t r j i} .
\end{gather*}
$$

The holomorphically projective curvature tensor ${ }^{5}$ ) $P_{k j i}{ }^{h}$ which will be briefly called $H P$-curvature tensor, $P$ is given by

[^1]$P_{k j i}{ }^{n}=R_{k j i}{ }^{h}+\frac{1}{n+2}\left(R_{k i} \delta_{j}{ }^{n}-R_{j i} \delta_{k}{ }^{h}+S_{k i} \varphi_{j}{ }^{h}-S_{j i} \varphi_{k}{ }^{h}+2 S_{k j} \varphi_{i}{ }^{h}\right)$.
We can obtain easily the following identities.
\[

$$
\begin{align*}
& P_{(k j) i}{ }^{h}=0, \quad P_{[k j i]}{ }^{h}=0,  \tag{1.5}\\
& P_{r j i}{ }^{r}=0,  \tag{1.6}\\
& P_{k j i}{ }^{r} \boldsymbol{\varphi}_{r}{ }^{h}=P_{k j r}{ }^{h} \boldsymbol{\varphi}_{i}{ }^{r}, \quad P_{r j i}{ }^{h} \boldsymbol{\varphi}_{k}{ }^{r}=P_{r k i}{ }^{h} \boldsymbol{\varphi}_{j}^{r}, \tag{1.7}
\end{align*}
$$
\]

from which we get

$$
\begin{align*}
& P_{k j r}^{r}=0,  \tag{1.8}\\
& P_{r j i}^{t} \boldsymbol{\varphi}_{t}^{r}=0, \quad P_{k j r}{ }^{t} \boldsymbol{\varphi}_{t}^{r}=0 .
\end{align*}
$$

A necessary and sufficient condition for $P_{k j i}^{h}=0$ is that the manifold is a space of constant holomorphic curvature ${ }^{6)}$, i.e. a space whose curvature tensor $R_{k j i}{ }^{h}$ takes the form

$$
\begin{equation*}
R_{k j i}{ }^{h}=k\left(g_{k i} \delta_{j}{ }^{h}-g_{j i} \delta_{k}{ }^{h}+\boldsymbol{\varphi}_{k i} \boldsymbol{\varphi}_{j}{ }^{h}-\boldsymbol{\varphi}_{j i} \boldsymbol{\varphi}_{k}{ }^{h}+2 \boldsymbol{\varphi}_{k j} \boldsymbol{\varphi}_{i}{ }^{h}\right), \tag{1.10}
\end{equation*}
$$

where we put

$$
k=-\frac{R}{n(n+2)}
$$

For a vector field $v^{i}$ and a tensor field $a_{i}{ }^{h}$, the following identities are known ${ }^{7)}$,
where $\underset{v}{\underset{\sim}{\mathcal{L}}}$ denotes the operator of Lie differentiation with respect to $v^{i}$.
A Killing vector or an infinitesimal isometry $v^{i}$ is defined by $\underset{v}{\mathcal{L}} g_{j i}=$ $\nabla_{j} v_{i}+\nabla_{i} v_{j}=0^{8)}$. An infinitesimal affine transformation $v^{i}$ is defined by

$$
\underset{v}{\mathscr{L}}\left\{\begin{array}{l}
h i
\end{array}\right\} \equiv \nabla_{j} \nabla_{i} v^{h}+R_{r j i}{ }^{h} v^{r}=0 .
$$

We shall say a vector field $v^{i}$ an infinitesimal holomorphically projective transformation or, for simplicity, an $H P$-transformation, if it satisfies

[^2]\[

\underset{v}{\underset{v}{f}}\left\{$$
\begin{array}{l}
h \\
j i
\end{array}
$$\right\}=\rho_{j} \delta_{i}^{h}+\rho_{i} \delta_{j}^{h}-\widetilde{\rho_{j}} \varphi_{i}^{h}-\widetilde{\rho_{i}}{\boldsymbol{\varphi}_{j}^{h},}^{h 9)}
\]

where $\rho_{i}$ is a certain vector and $\widetilde{\rho}_{i}=\phi_{i}{ }^{r} \rho_{r}$. In this case, we shall call $\rho_{i}$ the associated vector of the transformation. If $\rho_{i}$ vanishes, then the $H P$-transformation reduces to an affine one.

Contracting the last equation with respect to $h$ and $i$, we get $\nabla_{j} \nabla_{r} v^{r}=$ $(n+2) \rho_{j}$, which shows that the associated vector is gradient.

A vector field $v^{i}$ is called contravariant analytic or, for simplicity, analytic, if it satisfies

$$
\underset{v}{\mathcal{L}} \boldsymbol{\varphi}_{i}{ }^{h} \equiv-\boldsymbol{\varphi}_{i}^{r} \nabla_{r} v^{h}+\boldsymbol{\varphi}_{r}{ }^{h} \nabla_{i} v^{r}=0 .
$$

2. A geometrical interpretation of an analytic $H P$-transformation. In a differentiable manifold $M$, we consider a tensor valued function $V$ depending not only on a point $P$ of $M$ but also on $k$ vectors $u_{1}, \ldots \ldots, u_{k}$ at the point and denote it by $V\left(P, u_{1}, \ldots \ldots, u_{k}\right)$. We assume that the value of this function $V$ lies in the tensor space associated to the tangent space of $M$ at $P$ and that it depends differentiably on all its arguments.

Assuming the manifold $M$ to be affinely connected, we take an arbitrary curve $C: x^{i}=x^{i}(t)$ and denote its successive derivatives by

$$
\begin{equation*}
\frac{d x^{i}}{d t}, \frac{\delta^{2} x^{i}}{\delta t^{2}}, \ldots \ldots \tag{2.1}
\end{equation*}
$$

Then if we substitute (2.1) into the function $V$ instead of $u_{1}, u_{2}, \ldots \ldots, u_{k}$, we have a family of tensors

$$
V(C)=V\left(x, \frac{d x}{d t}, \ldots \ldots, \frac{\delta^{k} x}{\delta t^{k}}\right)
$$

along the curve $C$.
Let $v^{i}$ be an infinitesimal transformation, i. e. a vector field, and ' $x^{i}=x^{i}$ $+\varepsilon v_{i}$ be the infinitesimal point-transformation determined by $v^{i}, \varepsilon$ being an infinitesimal constant. Given a curve $C: x^{i}=x^{i}(t)$, the image ${ }^{\prime} C$ of $C$ is expressed by

$$
x^{i}=x^{i}(t)+\varepsilon v^{i}(x(t)) .
$$

We shall call the limiting value

$$
\underset{v}{\underset{L}{L}} V(C) \equiv \lim _{\epsilon \rightarrow 0} \frac{V\left(^{\prime} C\right)-{ }^{\prime} V(C)}{\varepsilon}
$$

[^3]the Lie derivative of $V(C)$ with respect to $v^{i}$, where we have denoted by ' $V(C)$ the family of tensors induced from $V(C)$ by the transformation ' $x^{k}$ $=x^{i}+\varepsilon v^{i}$.

In a Kählerian manifold, a curve $x^{t}=x^{i}(t)$ defined by

$$
\frac{d^{2} x^{h}}{d t^{2}}+\left\{\begin{array}{l}
h  \tag{2.2}\\
h i
\end{array}\right\} \frac{d x^{j}}{d t} \frac{d x^{i}}{d t}=\alpha \frac{d x^{h}}{d t}+\beta \boldsymbol{\varphi}_{j}{ }^{h} \frac{d x^{j}}{d t}
$$

is, by definition, a holomorphically planar curve ${ }^{10)}$ or an $H$-plane curve, where $\alpha$ and $\beta$ are certain functions of $t$.

Let $v^{i}$. be an infinitesimal transformation and assume that for any $\varepsilon$ the infinitesimal point-transformation ' $x^{i}=x^{i}+\varepsilon v^{i}$ maps any $H$-plane curve into an $H$-plane curve. Then we say that $v^{i}$ preserves the $H$-plane curves.

Now we ask for the condition that $v^{t}$ preserve the $H$-plane curves. For such a vector $v^{i}$, taking account of (2.2), we have

$$
\underset{v}{\mathscr{L}}\left[\frac{d^{2} x^{h}}{d t^{2}}+\left\{\begin{array}{l}
h  \tag{2.3}\\
{ }_{i}
\end{array}\right\} \frac{d x^{j}}{d t} \frac{d x^{i}}{d t}-\alpha \frac{d x^{h}}{d t}-\beta \boldsymbol{\varphi}_{j}{ }^{h} \frac{d x^{j}}{d t}\right]=\gamma \frac{d x^{h}}{d t}+\delta \boldsymbol{\varphi}_{j}{ }^{h} \frac{d x^{j}}{d t}
$$

along any $H$-plane curve, where $\gamma$ and $\delta$ are certain functions of $t$.
Denoting the Lie derivative of the Christoffel's symbols and the complex structure $\boldsymbol{\phi}_{i}{ }^{\prime}$, respectively, by
we have from (2.3)

$$
\begin{equation*}
t_{j i}{ }^{h} \dot{x}^{j} \dot{x}^{2}+a \dot{x}^{h}+b \boldsymbol{\varphi}_{j}{ }^{h} \dot{x}^{j}-\beta a_{j}{ }^{h} \dot{x}^{j}=0 \tag{2.4}
\end{equation*}
$$

where we have put

$$
a=-(\gamma+\underset{v}{\mathscr{L}} \alpha), \quad b=-\left(\delta+\underset{v}{\underset{v}{\mathscr{L}} \beta}, \quad \dot{x}^{i}=d x^{t} / d t .\right.
$$

Since the relation (2.4) holds for any $H$-plane curve $C$, it must hold identically for any values of $x^{i}$ and $\dot{x}^{i}$.

By means of the definition of the $H$-plane curves, we see further that the identity (2.4) holds for any value of the coefficient $\beta$.

Taking account of these arguments, we can easily see that the relation

$$
\begin{align*}
& a_{j}{ }^{h} \dot{x}^{j}=f \dot{x}^{h}+g{\varphi_{j}}{ }^{\circ} \dot{x}^{j},  \tag{2.5}\\
& t_{j i}{ }^{j} \dot{x}^{j} \dot{x}^{i}=p \dot{x}^{h}+q \varphi_{j}{ }^{h} \dot{x}^{j} \tag{2.6}
\end{align*}
$$

hold for any values $x^{i}$ and $\dot{x}^{i}$, where $f, g, p$ and $q$ are certain functions of $x^{i}$ and $\dot{x}^{i}$.

[^4]If we take account of Lemma 1 given in Appendix $I$, we obtain by means of (2.5)

$$
\begin{equation*}
a_{i}^{h} \equiv{\underset{v}{v}}^{\boldsymbol{q}_{i}}{ }^{h}=0 \tag{2.7}
\end{equation*}
$$

On the other hand, if we substitute (2.7) and $\nabla_{j} \varphi_{i}{ }^{h}=0$ into the identity
then we get

$$
\begin{equation*}
\boldsymbol{t}_{\boldsymbol{j} i}^{r} \boldsymbol{\varphi}_{r}{ }^{h}=\boldsymbol{t}_{\boldsymbol{j} r}{ }^{h} \boldsymbol{\varphi}_{i}{ }^{r} . \tag{2.8}
\end{equation*}
$$

From (2.6) and (2.8), taking account of Lemma 2 given in Appendix I, we have

$$
\begin{equation*}
t_{j i}{ }^{h}=\underset{v}{\mathscr{L}}\left\{{ }_{j i j}^{h}\right\}=\rho_{j} \delta_{i}{ }^{h}+\rho_{i} \delta_{j}{ }^{h}-\widetilde{\rho_{j}} \varphi_{i}{ }^{h}-\widetilde{\rho}_{i} \varphi_{j}{ }^{h}, \tag{2.9}
\end{equation*}
$$

where $\rho_{i}$ is a certain vector field. Therefore the infinitesimal transformation $v^{i}$ is an analytic $H P$-transformation.

Conversely, it is obvious that an analytic $H P$-transformation preserves the $H$-plane curves. Thus we have the following

THEOREM 2.1. In a Kählerian manifold, an infinitesimal transformation preserves the $H$-plane curves, if and only if it is an analytic HPtransformation.
3. Some properties of $H P$-transformations. Let $v^{i}$ be an $H P$-transformation, then it holds

$$
\underset{v}{\underset{\sim}{\mathscr{~}}}\left\{\begin{array}{l}
h i \tag{3.1}
\end{array}\right\} \equiv \nabla_{j} \nabla_{i} v^{h}+R_{r j i}{ }^{h} v^{r}=\rho_{j} \delta_{i}{ }^{h}+\rho_{i} \delta_{j}{ }^{h}-\widetilde{\rho}_{j} \varphi_{i}{ }^{h}-\widetilde{\rho}_{i} \varphi_{j}{ }^{h} .
$$

Transvecting (3.1) with $g^{j t}$, we have

$$
\begin{equation*}
\nabla^{r} \nabla_{r} v^{h}+R_{r}{ }^{h} v^{r}=0 \tag{3.2}
\end{equation*}
$$

Hence, by virtue of the well known theorem on an analytic vectors, ${ }^{11)}$ we have the following

THEOREM 3.1. In a compact Kählerian manifold, an HP-transformation is analytic.

In a compact Kählerian manifold $M$, it holds that $\int_{M}\left(R_{j i} v^{j} v^{i}\right) d \sigma \geqq 0$ for an analytic vector $v^{i}$, where $d \sigma$ denoted the volume element of $M$ and the equality holds when and only when $v^{i}$ is parallel. Therefore, if the Ricci's
11) Lichnerowicz, A. [4], Yano, K. [12].
form $R_{j i} \xi^{\xi} \xi^{i}$ is negative definite, then there exists no non-trivial $H P$-transformation provided that the manifold is compact.

Taking account of the identity (1.11), we have for a vector field $v^{i}$
which implies
because of $\nabla_{j} \varphi_{i}{ }^{h}=0$. If the vector field $v^{i}$ is an $H P$-transformation, it is easily verified that the right-hand side of the last equation vanishes. Thus we have the following theorem by virtue of Obata's theorem ${ }^{12}$.

THEOREM 3.2. In an irreducible Kählerian manifold admitting no quaternion structure, any HP-transformation is analytic.

It is known that in a Kählerian manifold admitting a quaternion structure the Ricci tensor vanishes identically ${ }^{133}$. Thus we have

THEOREM 3.3. In an irreducible Kählerian manifold having non-vanishing Ricci tensor, any HP-transformation is analytic.

Corollary 3.4. In an irreducible Kähler-Einstein manifold if its scalar curvature is non-vanishing, any HP-transformation is analytic.

In the following part of this section we shall give some formulas on analytic $H P$-transformations which will be useful in the later sections.

Let $v^{i}$ be an $H P$-transformation. Substituting (3.1) into the identity

$$
\nabla_{k} \mathscr{L}_{v}^{\mathcal{L}} g_{j i}-\underset{v}{\mathscr{f}} \nabla_{k} g_{j i}=g_{r i} \mathscr{V}_{v}\left\{\begin{array}{l}
r j \\
r
\end{array}\right\}+g_{j r} \mathscr{f}_{v}\left\{\begin{array}{c}
r i
\end{array}\right\},
$$

we find

$$
\begin{equation*}
\nabla_{k} \mathscr{V}_{v} g_{j i}=\rho_{j} g_{k i}+\rho_{i} g_{k j}-\bar{\rho}_{j} \boldsymbol{\varphi}_{k i}-\tilde{\rho}_{i} \boldsymbol{\varphi}_{k j}+2 \rho_{k} g_{j i}, \tag{3.3}
\end{equation*}
$$

which will be used in $\S 5$.
If we substitute (3.1) into (1.12), then we have

$$
\begin{equation*}
\underset{v}{\mathcal{L}} R_{k j i}{ }^{h}=\delta_{j}{ }^{h} \nabla_{k} \rho_{i}-\delta_{k}{ }^{h} \nabla_{j} \rho_{i}-\varphi_{j}{ }^{h} \nabla_{k} \tilde{\rho}_{i}+\varphi_{k}{ }^{h} \nabla_{j} \tilde{\rho}_{i}-\left(\nabla_{k} \tilde{\rho}_{j}-\nabla_{j} \tilde{\rho}_{k}\right) \operatorname{\varphi }_{i}{ }^{h} . \tag{3.4}
\end{equation*}
$$

Contracting the last equation with respect to $h$ and $k$, we find

$$
\begin{equation*}
\underset{v}{\mathcal{L}} R_{j i}=-n \nabla_{j} \rho_{i}-2{\varphi_{j}^{r}}^{r} \boldsymbol{\varphi}_{i}^{t} \nabla_{r} \rho_{i} . \tag{3.5}
\end{equation*}
$$

12) Obata, M. [8].
13) Obata, M. [8].

Now we shall assume that $v^{i}$ is an analytic $H P$-transformation. Then we have $\underset{v}{\underset{v}{f}} R_{j i}=\underset{v}{\mathcal{L}}\left(R_{r t} \boldsymbol{\varphi}_{j}^{r}{ }_{\boldsymbol{\varphi}_{i}}{ }^{t}\right)$ by virtue of (1.2). Hence from (3.5) it follows

$$
\begin{equation*}
\nabla_{j} \rho_{i}=\varphi_{j}{ }^{\tau} \varphi_{i}{ }^{t} \nabla_{r} \rho_{t} \tag{3.6}
\end{equation*}
$$

since $n>2$. The last equation also is written in the form

$$
\underset{\rho}{\mathscr{L}} \boldsymbol{\varphi}_{i}^{h} \equiv-\varphi_{i}^{r} \nabla_{r} \rho^{h}+\varphi_{r}^{h} \nabla_{i} \rho^{r}=0,
$$

which shows that $\rho^{i}$ is analytic. Moreover, according to (3.6) we have

$$
\begin{equation*}
\nabla_{j} \tilde{\rho}_{i}+\nabla_{i} \tilde{\rho}_{j}=\phi_{i}^{r}\left(\nabla_{j} \rho_{r}-\boldsymbol{\varphi}_{j}{ }^{t} \varphi_{r}^{s} \nabla_{t} \rho_{s}\right)=0, \tag{3.7}
\end{equation*}
$$

which means that $\tilde{\rho}^{i}$ is a Killing vector. Thus we get the following
THEOREM 3.5. If a vector $\rho_{i}$ is the associated vector of an analytic HP-transformation, then $\rho^{i}$ is analytic and $\tilde{\rho^{i}}$ is a Killing vector.

From (3.5) and (3.6) it follows

$$
\begin{equation*}
\underset{v}{\mathcal{E}} R_{j i}=-(n+2)_{\nabla_{j}} \rho_{i}, \tag{3.8}
\end{equation*}
$$

from which we have

$$
\begin{equation*}
\underset{v}{\underset{v}{f}} S_{j i}=(n+2)_{\nabla_{j}} \tilde{\rho}_{i} . \tag{3.9}
\end{equation*}
$$

On the other hand, from (3.4) and (3.7) we get
(3.10) $\quad \underset{v}{\mathcal{f}} R_{k j i}{ }^{h}=\delta_{j}{ }^{h} \nabla_{k} \rho_{i}-\delta_{k}{ }^{h} \nabla_{j} \rho_{i}-\varphi_{j}{ }^{h} \nabla_{k} \tilde{\rho}_{i}+{\varphi_{k}}^{h} \nabla_{j} \rho_{i}-2{\boldsymbol{\varphi}_{i}{ }^{h} \nabla_{k} \tilde{\rho}_{j} .}^{\text {. }}$

If we substitute (3.8) and (3.9) into (3.10), then we can verify

$$
\begin{equation*}
\underset{v}{£} P_{k j i}{ }^{h}=0 .{ }^{14)} \tag{3.11}
\end{equation*}
$$

In the next place, substituting (3.1) and (3.8) into the identity
we have
(3.12) $\underset{v}{£} \nabla_{k} R_{j i}=-(n+2)_{\nabla_{k} \nabla_{j} \rho_{i}}-R_{k i} \rho_{j}-R_{k j} \rho_{i}+S_{k i} \bar{\rho}_{j}+S_{k j} \widetilde{\rho}_{i}-2 R_{j i} \rho_{k i}$.

Hence if we put

$$
\begin{equation*}
P_{k j i}=\frac{1}{n+2}\left(\nabla_{k} R_{j i}-\nabla_{j} R_{k i}\right), \tag{3.13}
\end{equation*}
$$

14) Ishihara, S. [2].
it holds

$$
\begin{equation*}
\underset{v}{\mathcal{L}} P_{k j i}=P_{k j i}{ }^{\tau} \rho_{r} . \tag{3.14}
\end{equation*}
$$

4. An analytic $H P$-transformation which leaves invariant the covariant derivative of the $H P$-curvature tensor. In this section we shall show an analogous theorem to the one obtained by T. Sumitomo for an infinitesimal projective transformation in a Riemannian space ${ }^{155}$.

Let $v^{i}$ be an analytic $H P$-transformation. If we substitute (3.1) and (3.11) into the identity

$$
\begin{aligned}
& \underset{v}{£} \nabla_{l} P_{k j i}{ }^{h}-\nabla_{l}{\underset{v}{v}}_{£} P_{k j i}{ }^{n}
\end{aligned}
$$

then we obtain

$$
\underset{v}{£} \nabla_{l} P_{k j i}{ }^{h}=T_{l k j i}{ }^{n},
$$

where we have put

$$
\begin{aligned}
T_{l k j i}{ }^{h}=\delta_{l}{ }^{h} P_{k j i}{ }^{r} \rho_{r} & -2 \rho_{l} P_{k j i}{ }^{h}-\rho_{k} P_{l j i}{ }^{h}-\rho_{j} P_{k l i}{ }^{h}-\rho_{i} P_{k j i}{ }^{h} \\
& -\boldsymbol{\varphi}_{l}{ }^{h} P_{k j i}{ }^{r} \bar{\rho}_{r}+\boldsymbol{\varphi}_{l}{ }^{r}\left(\bar{\rho}_{k} P_{r j i}{ }^{h}+\bar{\rho}_{j} P_{k r i}{ }^{h}+\tilde{\rho}_{i} P_{k j r}{ }^{h}\right) .
\end{aligned}
$$

Now we shall assume that $\underset{v}{f} \nabla_{l} P_{k j i}^{h}=0$. Then we have

$$
\begin{equation*}
T_{l k j i}{ }^{h}=0 . \tag{4.1}
\end{equation*}
$$

Contracting this equation with respect to $h$ and $l$, we can verify

$$
P_{k j i}{ }^{r} \rho_{r}=0,
$$

by virtue of (1.5)~(1.9).
Substituting the last equation into (4.1) and taking account of $P_{k j i j}{ }^{r} \bar{\rho}_{r}=0$, we obtain the equation

$$
\begin{aligned}
2 \rho_{l} P_{k j i}^{h}+\rho_{k} P_{l j i}{ }^{h} & +\rho_{j} P_{k l i}^{h}+\rho_{i} P_{k j l}^{h} \\
& =\boldsymbol{\varphi}_{l}^{r}\left(\tilde{\rho}_{k} P_{r j i}^{h}+\tilde{\rho}^{l} P_{k r i}^{h}+\tilde{\rho}_{i} P_{k j r}{ }^{h}\right) .
\end{aligned}
$$

Transvecting this equation with $\rho^{l} P^{k j i}{ }_{h}=\rho^{l} P_{r s t h} g^{r k} g^{s j} g^{t i}$ and taking account of (1.5) $\sim(1.9)$, we obtain

$$
\left(\rho_{l} P_{k j i}{ }^{h}\right)\left(\rho^{l} P^{k j i}{ }_{h}\right)+2\left(\rho^{l} P_{l j i h}\right)\left(\rho_{r} P^{r j i h}\right)+\left(\rho^{l} P_{k j l l}\right)\left(\rho_{t} P^{k j t r}\right)=0,
$$

after some complicated calculation.
15) Sumitomo, T. [10], Yano, K. and Nagano, T. [13].

Since the each term in the left-hand side of the last equation is nonnegative, it must hold $\rho_{l} P_{k j i}{ }^{h}=0$, from which we get the following

THEOREM 4.1. If a Kählerian manifold admits an analytic non-affine HP-transformation which leaves invariant the covariant derivative of the HP-curvature tensor, then the manifold is a space of constant holomorpic curvature.

In a symmetric Kählerian manifold, i.e. in a Kählerian manifold satisfying $\nabla_{l} R_{k j i}^{h}=0$, the equation $\underset{v}{\underset{v}{f}} \nabla_{l} P_{k j i}^{h}=0$ trivially holds, so we have

Corollary 4.2. If a symmetric Kählerian manifold admits an analytic non-affine HP-transformation, then the manifold is a space of constant holomorphic curvature.
5. An analytic $H P$-transformation in a Kählerian manifold satisfying $\nabla_{k} R_{j i}=0$. In this section we shall obtain a theorem on an analytic HPtransformation in a Kählerian manifold satisfying $\nabla_{k} R_{j i}=0$. The method used here is analogous to the one used by T. Sumitomo [10] for an infinitesimal projective transformation in a Riemannian space.

At the first place, we have a well known ${ }^{16}$ )
Lemma 5.1. A necessary and sufficient condition for a Riemannian manifold to be an Einstein one is that the following equation holds:

$$
R_{j i} R^{j i}=\frac{R^{2}}{n}
$$

This follows from the identity $Z_{j i} Z^{j i}=R_{j i} R^{j t}-\frac{R^{2}}{n}$, where $Z_{j i}=R_{j i}$ $-(R / n) g_{j i}$.

Now consider a Kählerian manifold such that $\nabla_{k} R_{j i}=0$ and let $v^{i}$ be an analytic $H P$-transformation. Then, from (3.12) we have

$$
\begin{equation*}
(n+2)_{\nabla_{k} \nabla_{j}} \rho_{i}=-R_{k i} \rho_{j}-R_{k j} \rho_{i}+S_{k i} \tilde{\rho}_{j}+S_{k j} \tilde{\rho}_{i}-2 R_{j i} \rho_{k} . \tag{5.1}
\end{equation*}
$$

Transvecting this equation with $g^{k j}$, we get

$$
\begin{equation*}
\nabla^{r} \nabla_{r} \rho_{i}=-\frac{1}{n+2}\left(2 R_{i}^{r} \rho_{r}+R \rho_{i}\right) \tag{5.2}
\end{equation*}
$$

On the other hand, since $\rho^{i}$ is analytic, we have

$$
\nabla^{r} \nabla_{r} \rho_{i}+R_{i}^{r} \rho_{r}=0
$$

16) For example, Sumitomo, T. [10].

Compairing the last two equations, we find

$$
\begin{equation*}
R_{i}^{r} \rho_{r}=\frac{R}{n} \rho_{i}, \tag{5.3}
\end{equation*}
$$

which shows that $\rho^{i}$ is a Ricci's direction. Thus it follows

$$
\begin{equation*}
R^{i r} \nabla_{i} \rho_{r}=\frac{R}{n} \nabla_{i} \rho^{i} . \tag{5.4}
\end{equation*}
$$

Lemma 5.2. If a Kählerian manifold satisfying $\nabla_{k} R_{j i}=0$ is not an Einstein manifold, then the associated vector $\rho^{i}$ of an analytic HP-transformation satisfies $\nabla_{i} \rho^{i}=0$.

PROOF. By applying the Ricci's identity to $R_{j i}$, we find

$$
\begin{equation*}
R_{l k j}{ }^{r} R_{r i}+R_{l k i}{ }^{r} R_{j r}=0 . \tag{5.5}
\end{equation*}
$$

Transvecting this with $g^{k i}$, we have

$$
\begin{equation*}
R_{t t r j} R^{t r}=R_{l}{ }^{r} R_{j r} . \tag{5.6}
\end{equation*}
$$

From (5.5) it follows

$$
\left(\underset{v}{£} R_{l k j}{ }^{r}\right) R_{r i}+R_{l k j}{ }_{v} £_{v} R_{r i}+\left(\underset{v}{£} R_{l k i}{ }^{r}\right) R_{j r}+R_{l k i}{ }_{v} £_{v} R_{j r}=0 .
$$

If we transvect this equation with $R^{j k} g^{i l}$, then we get

$$
\left(R_{h}{ }^{k} R^{i j}+R_{t h} R^{t j} g^{i k}\right) \underset{v}{\mathscr{v}} R_{k j i}{ }^{h}=0
$$

by virtue of (5.6).
Now let $v^{i}$ be an analytic $H P$-transformation. If we substitute (3.10) into the last equation, then we can verify

$$
\begin{equation*}
\left(\nabla_{r} \rho^{r}\right) R_{j i} R^{j i}-R R_{j i} \nabla^{j} \rho^{i}=0, \tag{5.7}
\end{equation*}
$$

after some calculation.
From (5.4) and (5.7) it follows

$$
\left(R_{j i} R^{j i}-\frac{R^{2}}{n}\right) \nabla_{r} \rho^{r}=0,
$$

which implies together with Lemma 5.1 the lemma.
THEOREM 5.3. If a Kählerian manifold satisfying $\nabla_{k} R_{j \imath}=0$ admits an analytic non-affine HP-transformation, it is a Kähler-Einstein manifold.

PROOF. Since $\nabla_{k} R_{j i}=0, R_{j i} R^{j i}$ is constant, and so we have

$$
0=\underset{v}{\mathscr{L}}\left(R_{j i} R^{j i}\right)=\left(\underset{v}{£_{j i}} R_{j i}\right) R^{j i}+R_{j i} \mathscr{L}_{v}\left(R_{r t} g^{r j} g^{t i}\right)
$$

$$
=2\left[\left(\mathcal{f}_{v} R_{j \imath}\right) R^{j i}+R_{j}^{r} R_{r t}{\underset{v}{e}}^{\mathcal{E}} g^{j t}\right],
$$

where $v^{i}$ is a vector field.
Now let $v^{t}$ be an analytic non-affine $H P$-transformation. If we substitute (3.8) and (5.4) into the last equation, then we find

$$
-\frac{n+2}{n} R_{\nabla_{r}} \rho^{r}+R_{j}^{r} R_{r t} £_{v} g^{j t}=0 .
$$

If we assume that our manifold is not an Einstein one, then we have

$$
\begin{equation*}
R_{j}^{r} R_{r t} \mathscr{L}_{v} g^{j t}=0, \tag{5.8}
\end{equation*}
$$

by virtue of Lemma 5.2. By means of $\underset{v}{\mathcal{L}}\left(g^{j t} g_{t i}\right)=0$, (5.8) can be written in the form

$$
R^{j r} R_{r}{ }_{v}^{t} g_{j t}=0 .
$$

Operating $\nabla_{i}$ to the both sides and then substituting (3.3), we get

$$
\frac{1}{2}\left(\rho_{i} \rho^{i}\right)\left(R_{j r} R^{j r}\right)+\left(R_{j r} \rho^{j}\right)\left(R_{i}^{r} \rho^{i}\right)=0 .
$$

Since the each term of the left-hand side is non-negative, we have $\rho_{i} R_{j r}=0$, which contradicts to our assumption.
q. e. d.

## 6. A Kähler-Einstein manifold with non-vanishing scalar curvature.

We have given in the last section that the existence of an analytic non-affine $H P$-transformation in a Kählerian manifold satisfying $\nabla_{k} R_{j i}=0$ reduces the manifold to an Einstein one. In this section we shall devote ourselves to discuss such a transformation in a Kähler-Einstein manifold with $R \neq 0$.

We shall first prove the following
LEMMA 6.1. In a Kählerian manifold with positive (or negative) definite Ricci's form, any infinitesimal affine transformation is analytic and hence so is any Killing vector field.

Proof. When the given manifold $V$ is irreducible, the Ricci tensor being non-zero, the manifold admits no quaternion structure. Thus, taking account of Obata's theorem ${ }^{17)}$, we see that in $V$ any affine transformation is analytic.

When the given manifold is reducible, for any point there exists a neighbourhood $U$ of the point which is a Pythagorean product of irreducible Kählerian manifolds, say $V_{1}, V_{2}, \ldots \ldots, V_{p}$. In each of these Kählerian manifolds

[^5]$V_{1}, \ldots \ldots, V_{p}$ its Ricci's form is positive (or negative) definite, because of the assumption on the Ricci's form of $V$. Then, each of these manifolds $V_{1}, \cdots$, $V_{p}$ admits no quaternion structure.

Let $v^{t}$ be an infinitesimal affine transformation in the given $V$. In the neighbourhood $U, v^{i}$ is decomposed in such a way that $v^{i}=\sum_{\alpha=1}^{p} v_{(\alpha)}^{i}$, where $\boldsymbol{v}_{(\alpha)}{ }^{t}$ is an infinitesimal affine transformation in the Kählerian manifold $V_{\alpha}$ ( $\alpha=1, \ldots \ldots, p$ ). Since the manifold $V_{\alpha}$ is irreducible and has no quaternion structure, by means of Obata's theorem, $v_{(\alpha)}{ }^{i}$ is analytic. Accordingly, it is obvious that the given $v^{i}$ is analytic in $U$. This proves the lemma. q. e. d.

This lemma implies immediately the following
Lemma 6. 2. In a Kähler-Einstein manifold, if its scalar curvature does not vanish, any Killing vector is analytic.

We notice here that in an Einstein manifold with $R \neq 0$ any infinitesimal affine transformation is a Killing vector. In fact, for an infinitesimal affine transformation $v^{i}$ we have $\underset{v}{\underset{v}{e}} R_{j i}=0$. The manifold being Einsteinian, it follows $\underset{v}{\underset{v}{\mathcal{E}}} g_{j i}=(n / R) \underset{v}{\mathcal{E}} R_{j i}=0$.

By virtue of these lemmas we have the following
THEOREM 6.3. In a Kähler-Einstein manifold with non-vanishing scalar curvature, an HP-transformation is analytic if and only if its associated vector is analytic.

Proof. The associated vector of an analytic $H P$-transformation is analytic by means of Theorem 3.5. Conversely, we suppose that the associated vector $\rho_{i}$ of an $H P$-transformation $v^{2}$ is analytic. Then, it follows from (3.5) and (3.6)

$$
\underset{v}{\underset{v}{f} R_{j i}}=-(n+2)_{\nabla_{j}} \rho_{i} .
$$

The manifold being an Einstein one, this implies

$$
\begin{equation*}
\underset{v}{£} g_{j i}=\frac{1}{k} \nabla_{j} \rho_{i}, \quad k=-\frac{R}{n(n+2)} . \tag{6.1}
\end{equation*}
$$

Taking account of (6.1), if we put

$$
\begin{equation*}
p_{i}=v_{i}-\frac{1}{2 k} \rho_{i}, \tag{6.2}
\end{equation*}
$$

we have $\nabla_{j} p_{i}+\nabla_{i} p_{j}=0$, which means that the vector $p^{i}$ is a Killing one. According to Lemma 6,2, the vector $p^{i}$ is analytic. Therefore the given $H P$ -
transformation $v^{i}$ is analytic.
q. e. d.

Let $v^{i}$ be an analytic $H P$-transformation in a Kähler-Einstein manifold. Then from (3.8) we have (6.1). If we define a vector field $p^{i}$ by (6.2), we see that $p^{i}$ is a Killing vector. Next, if we put $q^{i}=(1 / 2 k) \widetilde{\rho^{i}}=-(1 / 2 k)$ $\boldsymbol{\varphi}_{r}{ }^{i} \rho^{r}$, then we have

$$
\begin{align*}
& \tilde{q^{i}}=-\frac{1}{2 k} \rho^{i}  \tag{6.3}\\
& v^{i}=p^{i}+\varphi_{r}^{i} q^{r} .
\end{align*}
$$

Thus we have, taking account of Theorem 3.5, the following
THEOREM 6. $4^{18}$. In a Kähler-Einstein manifold with $R \neq 0$, an analytic HP-transformation $v^{i}$ is uniquely decomposed in the form

$$
v^{i}=p^{i}+\boldsymbol{\varphi}_{r}{ }^{i} q^{r},
$$

where $p^{i}$ and $q^{i}$ are Killing vectors.
On Theorem 6. 4 we remark the following fact. The equation $\underset{u}{\mathscr{L}} \boldsymbol{\varphi}_{i}{ }^{h}=0$ is equivalent to

$$
\nabla_{j} u_{i}-\nabla_{i} u_{j}=\varphi_{j}^{r}\left(\nabla_{r} \tilde{u}_{i}+\nabla_{i} \tilde{u}_{r}\right) .
$$

Hence, in a Kählerian manifold, a necessary and sufficient condition in order that an analytic vector $u_{i}$ is gradient is that $\tilde{u}^{i}$ is a Killing vector.

Now, if $q^{i}$ is a Killing vector, taking account of Lemma 6.2, it is analytic, and hence so is $\tilde{q}^{i}$. If we put $u^{i}=\tilde{q}^{i}$ in the above arguments, we get $\nabla_{j} \widetilde{q}_{i}=\nabla_{i} \tilde{q}_{j}$. Thus $\boldsymbol{\varphi}_{r}{ }^{i} q^{r}$ in Theorem 6.4 is gradient analytic.

Thus the uniqueness follows from the fact that an Einstein manifold with $R \neq 0$ can not admit a non-trivial parallel vector field.

Next we have from (6.4)

If we substitute (3.1) and (6.3) into the last equation, we find

$$
\begin{equation*}
\nabla_{j} \nabla_{i} \rho^{h}+R_{r j i}{ }^{h} \rho^{r}=2 k\left(\rho_{j} \delta_{i}{ }^{h}+\rho_{i} \delta_{j}{ }^{h}-\tilde{\rho}_{j} \varphi_{i}{ }^{h}-\tilde{\rho}_{i} \varphi_{j}{ }^{h}\right) . \tag{6.5}
\end{equation*}
$$

Thus we have the following

[^6]Corollary 6.5. In a Kähler-Einstein manifold with $R \neq 0$, the associated vector of an analytic HP-transformation is a (gradient analytic) HPtransformation.

Let $L_{H}, L_{I}$ and $L^{\prime}$ be the Lie algebra consisting of all analytic $H P$ transformations, the Lie algebra consisting of all Killing vector fields and the vector space of all analytic gradient $H P$-transformations, respectively. Then Theorem 6.4 asserts that a direct sum $L_{H}=L_{I}+L^{\prime}$ holds good. After some computation, we can verify the following

Corollary 6.6. In a Kähler-Einstein manifold with $R \neq 0$, the following relations hold:

$$
\begin{gathered}
L_{H}=L_{I}+L^{\prime}(\text { direct sum }), \\
{\left[L_{I}, L_{I}\right] \subset L_{I}, \quad\left[L_{I}, L^{\prime}\right] \subset L^{\prime}, \quad\left[L^{\prime}, L^{\prime}\right] \subset L_{I} .}
\end{gathered}
$$

From (6.5) we have

$$
\begin{equation*}
\nabla_{j \nabla_{i}} \rho_{h}+R_{t j i h} \rho^{t}=2 k\left(g_{j h} \rho_{i}+g_{i h} \rho_{j}-\varphi_{j h} \tilde{\rho}_{i}-\varphi_{i h} \tilde{\rho}_{j}\right) . \tag{6.6}
\end{equation*}
$$

Let $v^{i}$ be non-affine and consider a geodesic $x^{i}=x^{i}(s)$ at a point on which $\rho_{i}\left(d x^{i} / d s\right) \neq 0$, where $s$ is the arc lengh. If we define a function $f(s)$ along the geodesic by $f(s)=\rho_{i}\left(d x^{i} / d s\right)$, then we have $f^{\prime \prime}(s)=4 k f(s)$ because of (6.6). Now we assume that $R<0$. Then we find $f(s)=A e^{3 \sqrt{ } \sqrt{s} s}+B e^{-2 \sqrt{\bar{k} s}}$, where $A$ and $B$ are constant. Thus we obtain

THEOREM 6.7. In a complete Kähler-Einstein manifold with $R<0$, the length of the associated vector of an analytic non-affine HP-transformation is not bounded.

Next, if we take the alternating part of (6.6) with respect to $i$ and $h$, we get

$$
\begin{equation*}
R_{t j i h} \rho^{t}=k\left(g_{t i} g_{j h}-g_{j i} g_{t h}+\boldsymbol{\varphi}_{t i} \boldsymbol{\varphi}_{j h}-\boldsymbol{\varphi}_{j i} \boldsymbol{\varphi}_{t h}+2 \boldsymbol{\varphi}_{t j} \boldsymbol{\varphi}_{i h}\right) \rho^{t}, \tag{6.7}
\end{equation*}
$$

from which, taking account of the theorem given in Appendix II, we obtain
THEOREM 6.8. If a Kähler-Einstein manifold with $R \neq 0$ admits an analytic non-affine HP-transformation, then its local homogeneous holonomy group at any point is the full unitary group $U(n / 2)$.

Let $\rho^{i}$ be an analytic gradient $H P$-transformation, then (6.7) is valid. Hence if $L^{\prime}$ is transitive ${ }^{19)}$ at each point of the manifold, then (1.10) holds

[^7]good. Therefore we get the following
THEOREM 6.9. In a Kähler-Einstein manifold with $R \neq 0$, if the vector space consisting of all analytic gradient HP-transformations is transitive at each point, then the manifold is a space of constant holomorphic curvature.

This theorem can also be proved in the following way. We consider a Kähler-Einstein manifold, then it holds $P_{k j i}=0$, where the tensor $P_{k j i}$ is defined by (3.13). Let $v^{i}$ be a non-affine analytic $H P$-transformation and $\rho_{i}$ be its associated vector. Then, from (3.14) it follows $P_{k j i}{ }^{r} \rho_{r}=0$. If the vector space $L^{\prime}$ is transitive at each point of the manifold, then we have $P_{k j i}{ }^{h}=0$. This proves that the manifold has constant holomorphic curvature.

Corollary 6.1. If a homogeneous Kähler-Einstein manifold with $R \neq 0$ admits an analytic non-affine HP-transformation, and if its linear isotropy group is irreducible, then it is a space of constant holomorphic curvature.

PROOF. Since the linear isotropy group of the manifold is irreducible, taking account of the formula $\left[L_{T}, L^{\prime}\right] \subset L^{\prime}$ which is given in Corollary 6.6, we see that the vector space $L^{\prime}$ is transitive at any point. Accordingly, Theorem 6.9 implies that the given manifold is of constant holomorphic curvature. q. e. d.
7. An $H P$-transformation in a compact space of constant holomorphic curvature. Let us consider a compact space of constant holomorphic curvature with $R>0^{20}$. Then the manifold being an Einstein one, an analytic vector $v$ is decomposed uniquely in the form

$$
v^{t}=p^{i}+\varphi_{r}^{\prime} q^{r 21)}
$$

where $p^{i}$ and $q^{i}$ are Killing vectors. Hence we have

$$
\underset{v}{\mathcal{E}}\left\{\begin{array}{l}
h i j  \tag{7.1}\\
h
\end{array}\right\}=-\underset{\tilde{q}}{\mathcal{L}}\left\{\begin{array}{l}
h i j
\end{array}\right\}=-\left(\nabla_{j} \nabla_{i} \tilde{q}^{h}+R_{r j i}{ }^{h} \tilde{q}_{q}^{r}\right) .
$$

Since $q^{t}$ is a Killing vector, we have

$$
\nabla_{j} \nabla_{i} q^{h}+R_{r j i}{ }^{h} q^{r}=0 .
$$

Substituting the last equation into (7.1), we find

$$
\underset{v}{\mathcal{E}}\left\{\begin{array}{l}
h i j
\end{array}\right\}=\left(-\boldsymbol{\varphi}_{t}{ }^{h} R_{r j i}{ }^{t}+\boldsymbol{\varphi}_{r}{ }^{t} R_{t j i}{ }^{n}\right) q^{r} .
$$

Next if we substitute (1.10) into the last equation, then we get

[^8]\[

\underset{v}{\mathcal{E}}\left\{$$
\begin{array}{l}
h \\
j i
\end{array}
$$\right\}=\rho_{j} \delta_{i}{ }^{h}+\rho_{i} \delta_{j}{ }^{h}-\check{\rho}_{j} \varphi_{i}{ }^{h}-\tilde{\rho}_{i} \varphi_{j}{ }^{h}, \quad \rho_{i}=-2 k \tilde{q}_{i},
\]

from which we see that $v^{i}$ is an $H P$-transformation. Thus on taking account of Theorem 3.1, we have

THEOREM 7.1. In a compact space of constant holomorphic curvature with $R>0$, a necessary and sufficient condition for a vector field to be analytic is that it is an HP-transformation.

This theorem can be also proved in the following way. Let $L_{H}$ and $A$ be the Lie algebras of all $H P$-transformations and of all analytic vector fields respectively. Then it follows $L_{H} \subset A$ from Theorem 3.1 and

$$
A=L_{I}+\widetilde{L}_{I},(\text { direct sum })
$$

from Matsushima's theorem ${ }^{22)}$ where $L_{I}$ denotes the Lie algebra of all Killing vector fields in the manifold and $\widetilde{L}_{I}$ is defined by $\widetilde{L}_{I}=\left\{\tilde{p}^{i} \mid p^{i} \in L_{I}\right\}$.

It is known that $\operatorname{dim} L_{I}=m^{2}+2 m^{22)}$, which implies

$$
\operatorname{dim} A=2\left(m^{2}+2 m\right)
$$

On the other hand, it is known ${ }^{24}$

$$
\operatorname{dim} L_{H}=2\left(m^{2}+2 m\right)
$$

Consequently, we have $\operatorname{dim} L_{H}=\operatorname{dim} A$, hence we get $L_{H}=A$.

## APPENDIX I

Consider an $n(=2 m>2)$ dimensional real vector space $V$ and let $e_{1}, \ldots$ $\ldots, e_{n}$ be a fixed base. We shall represent any quantities on $V$ in terms of their components with respect to the base $e_{i}$. Since $n$ is even, $V$ admits a complex structure, i.e. a tensor $\boldsymbol{\varphi}_{i}{ }^{h}$ such that $\boldsymbol{\varphi}_{i}{ }^{r} \boldsymbol{\varphi}_{r}{ }^{h}=-\delta_{i}{ }^{h}$. In the following we shall consider a fixed complex structure.

Lemma 1. Let $a_{j}{ }^{i}$ be a tensor on $V$ such that

$$
\begin{equation*}
\boldsymbol{\varphi}_{j}^{r} a_{r}^{i}+a_{j}^{r} \boldsymbol{\varphi}_{r}^{i}=0 . \tag{1}
\end{equation*}
$$

Moreover, if it satisfies the equation

$$
\begin{equation*}
a_{j}{ }^{i} y^{j}=a y^{i}+b \boldsymbol{\varphi}_{j}{ }^{i} y^{j} \tag{2}
\end{equation*}
$$

for any vector $y^{i}$, then $a_{j}{ }^{i}$ must be a zero tensor, where $a$ and $b$ are realvalued functions of $y^{i}$.
22) Matsushima, Y. [5].
23) Ishihara, S. [2].
24) Ishihara, S. [3].

PROOF. At the first place, we notice that $a_{j}{ }^{i}$ satisfies the relations

$$
a_{r}^{r}=0, \quad a_{r}{ }^{i} \varphi_{i}^{r}=0
$$

by virtue of (1). Next, for convenience, we shall introduce an Hermitian metric $g_{j i}{ }^{255}$. Then the equation $g_{r s} \boldsymbol{\varphi}_{j}{ }^{r} \boldsymbol{\varphi}_{i}{ }^{s}=g_{j i}$ holds true and $\boldsymbol{\varphi}_{j i}=\boldsymbol{\varphi}_{j}{ }^{r} g_{r i}$ is skew-symmetric with respect to $j$ and $i$.

Transvecting (2) with $y_{i}=g_{i r} y^{r}$, we have $a_{j}{ }^{i} y^{j} y_{i}=a y^{i} y_{i}$, and with $\boldsymbol{\varphi}_{i}{ }^{i} y_{t}$, we get $\varphi_{i}{ }^{t} y_{t} a_{j}{ }^{i} y^{j}=-b y^{i} y_{i}$. Making use of these equations, we can eliminate $a$ and $b$ in (2) and we have

$$
\begin{equation*}
t_{j h r}{ }^{i} y^{j} y^{h} y^{r}=0 \tag{3}
\end{equation*}
$$

where

$$
t_{j h r}^{i}=a_{j}^{i} g_{h r}-a_{j h} \delta_{r}^{i}+\varphi_{p j} a_{h}^{p} \varphi_{r}^{i}, \quad a_{j h}=a_{j}^{r} g_{r n} .
$$

Since (3) holds for arbitrary $y^{i}$, it follows $t_{(j h r)}^{i}=0$. If we write down this explicitely, it becomes the following equation:

$$
\begin{align*}
& 2\left(a_{j}^{i} g_{h r}+a_{h}^{i} g_{r j}+a_{r}^{i} g_{j h}\right)  \tag{4}\\
- & \left(a_{j l} \delta_{r}^{i}+a_{h r} \delta_{j}^{i}+a_{r j} \delta_{h}^{i}+a_{h j} \delta_{r}^{i}+a_{r h} \delta_{j}^{i}+a_{j r} \delta_{h}^{i}\right) \\
+ & \boldsymbol{\varphi}_{p j} a_{h}^{p} \boldsymbol{\varphi}_{r}^{i}+\boldsymbol{\varphi}_{p h} a_{r}^{p} \boldsymbol{\varphi}_{j}^{i}+\boldsymbol{\varphi}_{p r} a_{j}^{p} \boldsymbol{\varphi}_{h}{ }^{i} \\
+ & \boldsymbol{\varphi}_{p_{h}} a_{j}^{p} \boldsymbol{\varphi}_{r}^{i}+\boldsymbol{\varphi}_{p r} a_{h}^{p} \boldsymbol{\varphi}_{j}^{i}+\boldsymbol{\varphi}_{p j} a_{r}^{p} \boldsymbol{\varphi}_{h}{ }^{i}=0 .
\end{align*}
$$

By contraction with respect to $i$ and $j$ we have $(n-2)\left(a_{h r}+a_{r h}\right)=0$, which implies

$$
\begin{equation*}
a_{j t}+a_{i j}=0 \tag{5}
\end{equation*}
$$

On the other hand, transvecting (4) with $g^{l r} g_{i t}$, we have $n a_{j t}-2 a_{t j}=0$, after some calculation. Hence we obtain $a_{j i}=0$ on taking account of (5). This implies $a_{j}{ }^{i}=0$.
q. e. d.

LEmMA 2. Let $t_{j i}{ }^{h}$ be a tensor on $V$ such that

$$
\begin{align*}
t_{j i}{ }^{h} & =t_{t i}{ }^{h}  \tag{6}\\
t_{j i}{ }^{r} \boldsymbol{\varphi}_{r}{ }^{h} & =t_{j r}{ }^{h} \boldsymbol{\varphi}_{i}{ }^{r} . \tag{7}
\end{align*}
$$

Moreover, if it satisfies the equation

$$
\begin{equation*}
t_{j t}{ }^{h} y^{j} y^{i}=a y^{h}+b \boldsymbol{\varphi}_{j}^{h} y^{j} \tag{8}
\end{equation*}
$$

for any vector $y^{i}, a$ and $b$ being functions of $y^{i}$, then $t_{s i}{ }^{h}$ takes the following form:

25 ) It is always possible to introduce an Hermitian metric. See, Frölicher, A. [1].

$$
\begin{equation*}
t_{j i}{ }^{h}=\alpha_{j} \delta_{i}{ }^{h}+\alpha_{i} \delta_{j}{ }^{h}-\tilde{\alpha}_{j} \varphi_{i}{ }^{h}-\tilde{\alpha}_{i} \varphi_{j}{ }^{h} \tag{9}
\end{equation*}
$$

where $\alpha_{i}$ is a certain vector and $\tilde{\alpha}_{i}=\varphi_{i}{ }^{r} \alpha_{r}$.
PROOF. In the same manner as in the proof of Lemma 1 , we shall introduce an Hermitian metric $g_{j i}$.

From (6) and (7) it follows

$$
t_{j i}{ }^{h}+t_{c b}{ }^{h} \boldsymbol{\varphi}_{j}{ }^{c} \boldsymbol{\varphi}_{i}^{b}=0,
$$

from which we obtain the equation

$$
\begin{equation*}
g^{j i} t_{j i}^{h}=0 \tag{10}
\end{equation*}
$$

because of $g^{j i} \boldsymbol{\varphi}_{j}{ }^{c} \boldsymbol{\varphi}_{i}{ }^{b}=g^{c b}$.
From (8) we can easily obtain the relations

$$
t_{s i}{ }^{h} y_{n} y^{j} y^{i}=a y^{r} y_{r}, \quad t_{j i}{ }^{r} \boldsymbol{\varphi}_{r}{ }^{t} y_{t} y^{j} y^{i}=-b y^{r} y_{r}
$$

Making use of these relations, we can eliminate $a$ and $b$ in (8) and get

$$
\begin{equation*}
t_{j i r p}{ }^{n} y^{j} y^{i} y^{r} y^{p}=0 \tag{11}
\end{equation*}
$$

where

$$
t_{s i r p}{ }^{h}=t_{j i}{ }^{h} g_{r p}-t_{j t r} \delta_{p}{ }^{h}+t_{j t}{ }^{s} \boldsymbol{\varphi}_{s r} \boldsymbol{\varphi}_{p}{ }^{h}, \quad t_{j i r}=t_{j i}{ }^{s} g_{s r}
$$

Since (11) holds for arbitrary $y^{i}$, it follows $t_{\text {, Sirp) }}{ }^{h}=0$. Transvecting this with $g^{r p}$ and taking account of (6), (7) and (10), we can obtain

$$
\begin{equation*}
t_{j i}^{h}=\alpha_{j} \delta_{i}^{h}+\alpha_{i} \delta_{j}^{h}+\beta_{j} \varphi_{i}^{h}+\beta_{i} \varphi_{j}^{h}, \tag{12}
\end{equation*}
$$

where

$$
\alpha_{j}=\frac{1}{n+2} t_{j r}^{r}, \quad \beta_{j}=\frac{-1}{n+2} t_{j r}^{s} \varphi_{s}^{r}
$$

In the last place, substituting (12) into (7), we get $\beta_{j}=-\tilde{\alpha}_{i}$. q. e. d.
We can generalize Lemma 2 in the following form.
LEMMA 3. Let $t_{j i}{ }^{h}$ be a tensor on $V$ such that $t_{j i}{ }^{h}=t_{i j}{ }^{h}$. If it satisfies

$$
\begin{equation*}
t_{j i}{ }^{h} y^{j} y^{i}=a y^{h}+b \boldsymbol{\varphi}_{j}{ }^{h} y^{j} \tag{13}
\end{equation*}
$$

for any vector $y^{i}$, then $t_{j i}{ }^{h}$ takes the following form:

$$
t_{j i}{ }^{h}=\alpha_{j} \delta_{i}{ }^{h}+\alpha_{i} \delta_{j}^{h}+\beta_{j} \varphi_{i}{ }^{h}+\beta_{i} \varphi_{j}{ }^{h}
$$

where $a$ and $b$ are real-valued functions of $y^{i}$ and $\alpha_{i}, \beta_{i}$ are certain vectors.

Lemma 2 is a direct consequence of Lemma 3, but the proof of the latter is very complicated, so we shall only give the outline of it.

Multiplying the both sides of (13) with $y^{k} \boldsymbol{\varphi}_{c}{ }^{l}{ }^{c}$, we have

$$
t_{j i b}^{k k l} y^{j} y^{i} y^{b} y^{c}=\left(a \boldsymbol{\varphi}_{c}{ }^{l} \delta_{b}{ }^{k} \delta_{r}{ }^{h}+b \boldsymbol{\varphi}_{r}{ }^{h} \boldsymbol{\varphi}_{c}{ }^{c} \delta_{b}{ }^{k}\right) y^{c} y^{b} y^{r},
$$

where

$$
t_{j i b c}^{n k l}=t_{j i}{ }^{h} \delta_{b}{ }^{k} \boldsymbol{\varphi}_{c}{ }^{l}
$$

If we take the alternating part with respect to $h, k$ and $l$ of the above equation, we have

$$
t_{j i b c}^{n k \prime} y^{j} y^{i} y^{b} y^{c}=0
$$

which implies

$$
t_{(i, b c)}^{[h k!4]}=0 .
$$

By contraction, we get

$$
\begin{equation*}
t_{(j i b r)}^{\prime \prime k, r} \cdot=0 \tag{14}
\end{equation*}
$$

where the left-hand side is the sum of 72 terms because of the symmetry with respect to $i$ and $j$.

Transvecting (14) with $\boldsymbol{\varphi}_{k}{ }^{b}$ and putting $t_{j}=t_{j r}{ }^{r}, \rho_{j}=t_{j t}{ }^{k} \boldsymbol{\varphi}_{k}{ }^{t}$, we obtain after a complicated calculation

$$
\begin{equation*}
\left(n^{2}+2 n\right) t_{j i}{ }^{h}-8 \Phi_{3} \cdot \Phi_{2} t_{j i}{ }^{h}=A_{j} \delta_{i}{ }^{h}+A_{i} \delta_{j}{ }^{h}+B_{j} \varphi_{i}{ }^{h}+B_{i} \varphi_{j}{ }^{h}, \tag{15}
\end{equation*}
$$

where

$$
\begin{gathered}
A_{j}=\tilde{\rho}_{j}+(n+1) t_{j}, \quad B_{j}=\tilde{t}_{j}-(n+1) \rho_{j}, \\
\tilde{\rho}_{j}=\varphi_{j}^{r} \rho_{r}, \quad \tilde{t}_{j}=\boldsymbol{\varphi}_{j}^{r} t_{r} .
\end{gathered}
$$

and $\Phi_{2}, \Phi_{3}$ are the operators defined by

$$
\begin{align*}
& \Phi_{2} A_{j i}^{h}=\frac{1}{2}\left(A_{j i}^{h}+A_{j r}{ }^{t} \boldsymbol{\varphi}_{i}^{r} \boldsymbol{\varphi}_{t}^{h}\right)^{36)}, \\
& \Phi_{3} A_{j i}{ }^{h}=\frac{1}{2}\left(A_{j i}{ }^{h}-A_{r t}{ }^{h} \boldsymbol{\varphi}_{j}^{r} \boldsymbol{\varphi}_{i}^{t}\right) \tag{16}
\end{align*}
$$

These operators $\Phi_{2}$ and $\Phi_{3}$ satisfy the following identities ${ }^{277}$.
 form :

$$
\Phi_{2} A_{j i}^{h}=\stackrel{*}{=}{ }_{i t}^{r h} A_{j r}{ }^{t}, \Phi_{j} A_{j i}{ }^{h}=o_{j i}^{\prime t} A_{r t^{h}} .
$$

27) Obata, M. [7].

$$
\begin{equation*}
\Phi_{2} \cdot \Phi_{2}=\Phi_{2}, \quad \Phi_{3} \cdot \Phi_{3}=\Phi_{3}, \quad \Phi_{2} \bullet \Phi_{3}=\Phi_{3} \cdot \Phi_{2} \tag{17}
\end{equation*}
$$

After some calculation we get easily

$$
\Phi_{3} \cdot \Phi_{2}\left(A_{j} \delta_{i}^{h}+A_{i} \delta_{j}{ }^{h}+B_{j} \varphi_{i}{ }^{h}+B_{i} \varphi_{j}^{h}\right)=0
$$

Therefore, if we operate $\Phi_{3} \cdot \Phi_{2}$ to the both sides of (15), we get

$$
\left(n^{2}+2 n\right) \Phi_{3} \cdot \Phi_{2} t_{j t}{ }^{h}-8 \Phi_{3} \cdot \Phi_{2} \cdot \Phi_{3} \cdot \Phi_{2} t_{j t}{ }^{h}=0
$$

from which we obtain

$$
(n+4)(n-2) \Phi_{3} \cdot \Phi_{2} t_{j i}{ }^{h}=0
$$

by virtue of (17). Consequently, $\Phi_{3} \cdot \Phi_{2} t_{j i}{ }^{h}=0$ holds. Thus if we substitute the last equation into (15), we find

$$
t_{s i}{ }^{h}=\alpha_{j} \delta_{i}{ }^{h}+\alpha_{i} \delta_{j}^{h}+\beta_{j} \varphi_{i}{ }^{h}+\beta_{i} \varphi_{j}{ }^{h},
$$

where

$$
\begin{aligned}
& \alpha_{j}=\frac{1}{n(n+2)} A_{j}=\frac{1}{n(n+2)}\left\{\tilde{\rho}_{j}+(n+1) t_{j}\right\}, \\
& \beta_{j}=\frac{1}{n(n+2)} B_{j}=\frac{1}{n(n+2)}\left\{\tilde{t}_{j}-(n+1) \rho_{j}\right\} . \quad \quad \text { q.e.d. }
\end{aligned}
$$

We can also prove the following lemma according to Lemma 2.1 given in Ishihara, S . [2] and Lemma 3.

LEMMA 4. Let $t_{j i}{ }^{h}$ be a tensor on $V$ such that

$$
\Phi_{2} t_{j t}{ }^{h}=0^{28)}, \quad \Phi_{3} \cdot \Phi_{1}\left(t_{j t}{ }^{h}-t_{i j}{ }^{h}\right)=0
$$

If $t_{y t}{ }^{h}$ satisfies

$$
t_{j i}{ }^{h} y^{j} y^{j}=a y^{h}+b \boldsymbol{\varphi}_{j}{ }^{h} y^{j}
$$

for any vector $y^{i}$, then it takes the following form:

$$
t_{j t}^{h}=\rho_{j} \delta_{i}^{h}+\rho_{i} \delta_{j}^{h}-\tilde{\rho}_{j} \varphi_{i}^{h}-\tilde{\rho}_{i} \varphi_{j}^{h}+\sigma_{j} \delta_{i}^{h}+\tilde{\sigma}_{j} \varphi_{i}^{h}
$$

where $\rho_{j}$ and $\sigma_{j}$ are certain vectors and operator $\Phi_{1}$ defined by

$$
\Phi_{1} t_{j i}{ }^{h}=\frac{1}{2}\left(t_{j i}{ }^{h}-t_{j r}{ }^{t} \boldsymbol{\varphi}_{i}^{r} \boldsymbol{\varphi}_{t}{ }^{h}\right) .
$$

In an almost-complex manifold, an affine connection $\Gamma_{i i}^{h}$ is called a $\boldsymbol{\varphi}$ connection, if the almost-complex structure $\boldsymbol{\varphi}_{i}{ }^{h}$ is covariant constant with respect to $\Gamma_{j i}^{h}$, i. e. $\nabla_{j} \varphi_{i}{ }^{h}=0$, where $\nabla_{j}$ is defined by $\nabla_{j} v^{h}=\partial_{j} v^{h}+\Gamma_{j r}^{h} v^{r}$ for

[^9]a vector field $v^{t}$, for example. A $\varphi$-connection is said to be half-symmetric ${ }^{299}$, if its torsion tensor $S_{j i}{ }^{h}$ satisfies $\Phi_{3} \cdot \Phi_{1} S_{j i}{ }^{h}=0$.

By the same arguments as in $\S 2$, we can prove the following
THEOREM. In an almost-complex manifold endowed with a half-symmetric $\varphi$-connection $\Gamma_{j}^{h}$, in order that an infinitesimal transformation $v^{t}$ preserves the $H$-plane curves ${ }^{3}$, it is necessary and sufficient that it satisfies the following equations:

$$
\begin{gathered}
{\underset{v}{v}}^{\varphi_{i}}=0, \\
{\underset{v}{v}}^{~_{j i l}^{h}}=\rho_{j} \delta_{i}^{h}+\rho_{i} \delta_{j}^{h}-\check{\rho}_{j} \varphi_{i}^{h}-\tilde{\rho}_{i} \varphi_{j}^{h}+\sigma_{j} \delta_{i}^{h}+\check{\sigma}_{j} \varphi_{i}^{h}
\end{gathered}
$$

where $\rho_{j}$ and $\sigma_{j}$ are certain vector fields.

## Appendix II

Let $V$ be an $n(=2 m)$ dimensional real vector space and $\left(g_{j i}, \boldsymbol{\varphi}_{i}{ }^{h}\right)$ an Hermitian structure on it. Then $g_{j t}=g_{r s} \boldsymbol{\varphi}_{j}{ }^{r} \boldsymbol{\varphi}_{i}{ }^{s}$ holds, and so $\boldsymbol{\varphi}_{j t}=\boldsymbol{\varphi}_{j}{ }^{r} g_{r i}$ is skew-symmetric.

Consider a tensor $R_{k j t}{ }^{r}$ of type $(1,3)$ on $V$ and suppose that there exists a non-zero vector $\rho^{i}$ satisfying

$$
\begin{equation*}
\rho^{t} R_{t j t}{ }^{h}=\left(g_{t i} \delta_{j}^{h}-g_{j t} \delta_{t}{ }^{h}+\boldsymbol{\varphi}_{t i} \boldsymbol{\varphi}_{j}^{h}-\boldsymbol{\varphi}_{j t} \boldsymbol{\varphi}_{t}^{h}+2 \boldsymbol{\varphi}_{t j} \boldsymbol{\varphi}_{i}{ }^{h}\right) \rho^{t} . \tag{1}
\end{equation*}
$$

For a vector $\sigma^{i}$, we denote by $R(\sigma)$ the matrix whose $(i, h)$-element is $R(\sigma)_{i}{ }^{h}=\rho^{t} \sigma^{j} R_{t j i}{ }^{h}$. Then we have

$$
\begin{equation*}
R(\sigma)_{t}^{h}=\rho_{i} \sigma^{h}-\sigma_{t} \rho^{h}+\dot{\rho}_{t} \tilde{\sigma}^{h}-\tilde{\sigma}_{i} \tilde{\rho}^{h}+2{\boldsymbol{\varphi}_{i}}^{h} \rho^{i} \tilde{\sigma}_{t} \tag{2}
\end{equation*}
$$

where $\tilde{\rho}_{i}=\boldsymbol{\varphi}_{i}^{r} \rho_{r}$ and $\tilde{\sigma}^{i}=-\boldsymbol{\varphi}_{r}{ }^{i} \sigma^{r}$.
We shall prove the following
LEMMA. If we choose a suitable base in $V$, the Lie algebra generated by the matrices $R(\sigma), \sigma \in V$, contains all matrices of the following form:

$$
\left(\begin{array}{rr}
A & B \\
-B & A
\end{array}\right)
$$

where $A$ is a skew-symmetric ( $m, m$ )-matrix and $B$ is a symmetric ( $m, m$ )matrix.

PROOF. Since we can change the length of $\rho^{i}$ without loss of generality,
29) Ishibara, S. [2].
30) The definition of $H$-plane curves in an almost-complex manifold with a $\varphi$-connection bave given in [2] and [11].
it is possible to choose a base such that

$$
\begin{gathered}
\rho^{i}=\left(\delta_{\alpha 1}, \delta_{\bar{\alpha} \bar{i}}\right) \quad g_{j t}=\delta_{j t}, \\
\varphi_{\alpha \beta}=\varphi_{\bar{\alpha} \bar{\beta}}=0, \quad \varphi_{\alpha \bar{\beta}}=-\delta_{\alpha \beta}, \quad \varphi_{\bar{\alpha} \beta}=\delta_{\alpha \beta} .
\end{gathered}
$$

where indices $\alpha$ and $\beta$ run over $1,2, \ldots \ldots, m$ and $\bar{\alpha}=m+\alpha$.
In the following, we shall only use the lower indices, because the base in consideration is orthogonal. If we take $m-1$ vectors

$$
\sigma_{\gamma}=\left(\delta_{\alpha \gamma}, \delta_{\alpha \bar{\gamma}}\right), \quad \gamma=2, \ldots \ldots, m
$$

then we have

$$
\underset{\gamma}{\tilde{\sigma}_{i}}=\left(-\delta_{\alpha \gamma}, \delta_{\bar{\alpha} \bar{\gamma}}\right), \quad \rho=\left(-\delta_{\alpha 1}, \delta_{\bar{\alpha} \overline{1}}\right) .
$$

It is easily seen that $2 m$ vectors $\rho_{i}, \tilde{\rho}_{i}, \sigma_{\gamma}$ and $\tilde{\sigma}_{\gamma}$ are linearly independent.
We shall now put

$$
R_{1}^{*}=R(\grave{\rho}), \quad R_{\gamma}=R \underset{\gamma}{\boldsymbol{\sigma}}, \quad, \quad R_{\gamma}^{*}=R(\underset{\gamma}{\boldsymbol{\sigma}}),
$$

and use the following notations on ( $m, m$ )-matrixes :

$$
\begin{aligned}
& A_{\beta \alpha}=\left(a_{\mu}\right): a_{\beta \alpha}=-a_{\alpha \beta}=1, a_{\mu \lambda}=0 \text { for }(\mu, \lambda) \neq(\alpha, \beta),(\beta, \alpha) \\
& B_{\beta \alpha}=\left(b_{\mu \lambda}\right): b_{\beta \alpha}=b_{\alpha \beta}=1, b_{\mu \lambda}=0 \text { for }(\mu, \lambda) \neq(\alpha, \beta),(\beta, \alpha) \\
& C=\left(c_{\mu \lambda}\right): c_{11}=2, c_{\mathrm{e} \mathrm{\varepsilon}}=1 \text { for } \varepsilon=2, \ldots \ldots, m, c_{\mu \lambda}=0 \text { for } \mu \neq \lambda ; \\
& D_{\gamma}=\left(d_{\mu \lambda}\right):-d_{11}=d_{\gamma \gamma}=1, d_{\mu \lambda}=0 \text { for }(\mu, \lambda) \neq(1,1),(\gamma, \gamma)
\end{aligned}
$$

where $\alpha, \beta, \lambda$ and $\mu$ run over $1,2, \ldots \ldots, m$ and $\gamma=2, \ldots \ldots, m$.
Using this notation, we can obtain

$$
R_{\gamma}=2\left(\begin{array}{cc}
A_{1 \gamma} & 0  \tag{3}\\
0 & A_{1 \gamma}
\end{array}\right), R_{\gamma}^{*}=2\left(\begin{array}{cc}
0 & B_{1 \gamma} \\
-B_{1 \gamma} & 0
\end{array}\right), R_{1}^{*}=4\left(\begin{array}{rr}
0 & C \\
-C & 0
\end{array}\right)
$$

By some calculation we get for $\beta, \gamma=2, \ldots \ldots, m$

$$
\begin{array}{ll}
{\left[R_{\beta}, R_{\gamma}\right]=4\left(\begin{array}{cc}
A_{\beta \gamma} & 0 \\
0 & A_{\beta \gamma}
\end{array}\right)}  \tag{4}\\
{\left[R_{\beta,}^{*}, R_{\gamma}\right]=4\left(\begin{array}{cc}
0 & B_{\beta \gamma} \\
-B_{\beta \gamma} & 0
\end{array}\right)} \\
{\left[R_{\gamma}^{*}, R_{\gamma}\right]=8\left(\begin{array}{cc}
0 & D_{\gamma} \\
-D_{\gamma} & 0
\end{array}\right) .}
\end{array}
$$

Hence we find

$$
P=R_{1}^{*}-\frac{1}{2} \sum_{\gamma=2}^{m}\left[R_{\gamma}^{*}, R_{\gamma}\right]=4(m+1)\left(\begin{array}{cc}
0 & B_{11}  \tag{6}\\
-B_{11} & 0
\end{array}\right),
$$

from which it follows

$$
P+\frac{m+1}{2}\left[R_{\gamma}^{*}, R_{\gamma}\right]=4(m+1)\left(\begin{array}{cc}
0 & B_{\gamma \gamma}  \tag{7}\\
-B_{\gamma \gamma} & 0
\end{array}\right) .
$$

According to $(3) \sim(7)$, we see that the lemma is true.
q. e. d.

By means of the above lemma, we have the following
ThEOREM. In a Kählerian manifold of $n$ dimensions, if its curvature tensor $R_{k j i}{ }^{h}$ satisfies at a point the relation

$$
\begin{equation*}
\rho^{t} R_{t j t}{ }^{h}=\left(g_{t t} \delta_{j}^{h}-g_{j t} \delta_{t}^{h}+\boldsymbol{\varphi}_{t i} \boldsymbol{\varphi}_{j}^{h}-\boldsymbol{\varphi}_{j t} \boldsymbol{\varphi}_{t}^{h}+2 \boldsymbol{\varphi}_{t j} \boldsymbol{\varphi}_{t}{ }^{h}\right) \rho^{t} \tag{1}
\end{equation*}
$$

for a non-vanishing vector $\rho^{i}$, then the local homogeneous holonomy group of the manifold at any point coincides with the full unitary group $U(n / 2)$.

PROOF. We suppose that the relation (1) holds at a point $P$. We consider for fixed indices $j$ and $k$ a matrix $R(k j ; P)$ whose $(i, h)$-element is given by the value of $R_{k j t}{ }^{h}$ at the point $P$. Then, it follows from the above lemma that the Lie algebra generated by all the matrices $R(k j ; P)$ is equivalent to the Lie algebra of the full unitary group $U(n / 2)$. Therefore, taking account of Nijenhuis' theorem ${ }^{311}$, we see that the local homogeneous holonomy group of the manifold at the point $P$ contains the unitary group $U(n / 2)$. The manifold being Kählerian, it follows thus that the local homogeneous holonomy group of the manifold at $P$ coincides with $U(n / 2)$.
q. e. d.

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[^0]:    1) The number in brackets [] refers to the Bibliography at the end of the paper.
    2) Ishibara, S. [2].
[^1]:    3). In the present paper we shall restrict our attention to manifolds which are real representations of (complex) Kählerian manifolds, i. e. pseudo-Kählerian one. As to the notations, we follow Yano, K. [12]. We shall represents any quantit es in terms of their components with respect to natural frames $\partial / \partial x^{i}$. Indices run over $1,2, \ldots \ldots, n=2 m$.
    4) Yano, K. [12].
    5) Tashiro, Y. [11].

[^2]:    6) Tashiro, Y. [11].
    7) Yano, K. [12].
    8) We shall identify a contravariant vector $v^{i}$ with a covariant vector $v_{i}=g_{i r} v^{r}$. Hence we shall say $v_{i}$ is a Killing vector, or that $\rho^{i}$ is gradient, for example.
[^3]:    9) The definition of the $H P$-transformation is different from that given in Ishihara, S . [2].
[^4]:    10) Ishihara, S. [2], Otsuki, T. and Taskiro, Y. [9], Tashiro, Y. [11].
[^5]:    17) 

    Obata, M. [8].

[^6]:    18) In the compact case, this theorem is trivially contained in Matsushima's theorem on analytic vectors. [5].
[^7]:    19) Let $L$ be a vector space of vector fields in an $n$ dimensional manifold. Denoting bv $v(P)$ the value of a vector field $v$ at $P$, we consider the vector space $L_{P}=\{v(P) \mid v \in L\}$ of vectors at $P$. When $\operatorname{dim} L_{P}=n$, we say that the vector space $L$ is transitive at $P$.
[^8]:    20) In a compact Kähler-Einstein manifold with $R<0$ there exists no non trivial analytic vector.
    21) Matsushima, Y. [5].
[^9]:    28) This equation is equivalent to (7).
