# ON SOME PROPERTIES OF $\pi$-STRUCTURES ON DIFFERENTIABLE MANIFOLD 

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D. C. Spencer [1]" considered under the name "complex almost-product structure" the structure on the $n$-dimensional differentiable manifold $V_{n}$ defined by giving two differentiable distributions $T_{1}, T_{2}$ which assign two complemented subspaces of dimension $\geqq 1$ in the complexified tangent space $T_{x}^{c}$ at each point $x \in V_{n}$. G. Legrand [2] called such structure as a $\pi$-structure and studied it by generalizing most properties of the almost complex structure which can be regarded as a special case of it [3].

In the following, we assume that on the manifold a structure is defined by giving $r(2 \leqq r \leqq n)$ differentiable distributions $T_{1}, \ldots \ldots, T_{r}$ which assign $r$ complemented subspaces of dimension $\geqq 1$ in the complexified tangent space $T_{x}^{c}\left(T_{r}^{c}\right.$ $=T_{1}+\ldots \ldots+T_{r}$ : direct sum) at each point $x \in V_{n}$. We call such structure as an $r$ - $\pi$-structure if we want to express the number of the distributions explicitly. Whereas we call it simply as a $\pi$-structure if we need not (or can not) express the number $r$ definitely. We generalize some properties of $\pi$-structure in the sense of Legrand to the $r$ - $\pi$-structure.

In this note we assume that the differentiable manifold $V_{n}$ as well as the distributions $T_{1}, \ldots \ldots, T_{r}$ are of class $C^{\infty}$ unless we state it explicitly. It is also assumed that the manifold is arc-wise connected and the second countability axiom is satisfied.

1. Fundamental tensor of the $\pi$-structure. Suppose the differentiable manifold $V_{n}$ has a $\pi$-structure defined by $r$ differentiable distributions $T_{1}, \ldots \ldots, T_{r}$. Let the projection operations from $T_{x}^{C}$ to $T_{\alpha}$ be denoted as $\Re_{\alpha}$, then we have

$$
\begin{gather*}
\mathfrak{F}_{\alpha}^{2}=\mathfrak{F}_{\alpha}, \quad \mathfrak{R}_{\alpha} \mathfrak{F}_{\beta}=0 \quad(\alpha \neq \beta),  \tag{1.1}\\
\mathfrak{P}_{1}+\ldots \ldots+\mathfrak{B}_{r}=\mathfrak{J}, \tag{1.2}
\end{gather*}
$$

where $\mathfrak{J}$ denotes the identity transformation and the Greek indices vary from 1 to $r$. Define a transformation $\mathfrak{F}$ on $T_{x}^{c}$ by the following:

$$
\begin{equation*}
\mathfrak{F} v=\lambda \sum_{\alpha} w_{\alpha} \Re_{a} v, \tag{1.3}
\end{equation*}
$$

1) Numbers in bracket refer to the reference at the end of the paper.
where $v$ is any vector in $T_{x}^{c}, \lambda$ is a non zero complex constant and $w_{\alpha}(\alpha=1, \ldots$ $\ldots, r$ ) are the $r$-th power roots of unity. It is obvious that

$$
\begin{equation*}
\mathfrak{F}^{s} v=\lambda^{s} \sum_{a} w_{a}^{s} \mathbb{B}_{a} v \quad(1 \leqq s \leqq r) \tag{1.4}
\end{equation*}
$$

thus we have

$$
\begin{equation*}
\mathfrak{F}^{r} v=\lambda^{r} v, \quad \text { i. e., } \quad \mathfrak{F}^{r}=\lambda^{r} \widetilde{\mathcal{S}} . \tag{1.5}
\end{equation*}
$$

On the manifold there exists a complex tensor field which induces $\mathfrak{F}$ at each $T_{x}^{c}$. Let this tensor field be denoted as $F_{j}^{i}$, then we have from (1.5) the following :

$$
\begin{equation*}
\stackrel{r}{F_{j}{ }^{i} \equiv F_{h_{1}}{ }^{i} F_{h_{2}}{ }_{1}^{h_{1}} F_{h_{3}}{ }^{h_{2}} \ldots \ldots F_{j}^{h_{r-1}}=\lambda^{r} \delta_{j}{ }^{i} .} \tag{1.6}
\end{equation*}
$$

Conversely, if the manifold has a non trivial tensor $F_{;}{ }^{i}$ satisfying (1.6), and $\mathfrak{F}$ be the transformation induced at $T_{x}^{c}$ by $F_{j}^{l}$, then it is obvious that the proper values of $\mathfrak{F}$ are among $\lambda w_{a}(\alpha=1, \ldots \ldots, r)$. If $\mathfrak{F}$ has actually $s(s \geqq 2$, because $F_{j}{ }^{i}$ is non trivial) of them as its proper values, then the number $s$ and the proper values do not vary when the point $x$ varies on the manifold, because of the differentiability of the considered tensor field $F_{j}^{i}$ and the connectedness of the manifold. Consequently the manifold has $s$ differentiable distributions constituted of $s$ proper subspaces in $T_{x}^{c}$ at each point $x$. Thus we have

THEOREM 1. 1. The manifold is endowed with $a \pi$-structure if and only if the manifold has a non trivial tensor field $F_{;}^{i}$ satisfying (1.6) for some $r: 2 \leqq r \leqq n$.

A tensor satisfying (1.6) is said to be degenerate if the number of its different proper values $s<r$. An example of degenerate tensor of the type (1.6) is given by :

$$
\begin{equation*}
\underset{1}{F_{j}^{i}}=\left(\cos \frac{\pi}{r}\right) \delta_{j}^{i}+\left(\sin \frac{\pi}{r}\right) \phi_{j}^{i 2)}, \tag{1.7}
\end{equation*}
$$

where $\phi_{j}{ }^{i}$ is assumed to be a tensor defining an almost complex structure on the manifold, i. e., it is a real tensor such that ${ }^{2}{ }_{j}{ }^{i} \equiv \phi_{l}{ }^{i} \phi_{j}{ }^{h}=-\delta_{j}{ }^{i}$. It is obvious that ${\underset{1}{j}}^{r}{ }^{i}=-\delta_{j}^{i}$ and ${\underset{1}{j}}^{F_{j}}$ has only two different proper values.

Now, if the manifold has an $r$ - $\pi$-structure, then the tensor $F_{j}{ }^{i}$ defined by (1.3) is non degenerate. For, from (1.2) and (1.4) we have
2) I was informed by Mr. Hatakeyama of the construction of a tensor $F_{j}{ }^{i}$ satisfying $\stackrel{r}{F_{j}}=-\delta_{j}{ }^{i}$ starting from the tensor defining an almost complex structure.

$$
\begin{equation*}
\Re_{\alpha} v=\frac{1}{r} \sum_{s=0}^{r-1} \frac{1}{\left(\lambda w_{\alpha}\right)^{s}} \mathfrak{F}^{s} v \tag{1.8}
\end{equation*}
$$

from which it follows that

$$
\begin{equation*}
\mathfrak{F} v_{a}=\left(\lambda w_{a}\right) v_{\alpha}, \quad \text { where } \quad v_{\alpha} \equiv \mathfrak{F}_{a} v \in T_{a} \tag{1.9}
\end{equation*}
$$

From (1.9) and $\operatorname{dim} T_{\alpha} \equiv n_{\alpha}>0$, it follows that $\lambda w_{a}(\alpha=1, \ldots \ldots, r)$ is actually a proper value of $\mathfrak{F}$.

Conversely if the manifold has a non degenerate tensor field $F_{g}^{l}$ satisfying (1.6), then the $r$ proper subspaces corresponding to the $r$ different proper values at each point induce $r$ differentiable distributions which define an $r$ - $\pi$-structure. Thus we have:

THEOREM 1.2. For the manifold to have an $r-\pi$-structure, it is necessary and sufficient that the manifold has a non degenerate tensor $F_{j}{ }^{i}$ satisfying (1.6).

The tensor corresponding to the $r-\pi$-structure insisted in the above theorem is called the fundamental tensor of the $r-\pi$-structure as it plays an important role in the study of $r$ - $\pi$-structure.

In the sequel, the following notations are used for the convenience sake:

$$
\begin{equation*}
F_{h_{1}}^{i} F_{h_{2}}^{h_{1}} \ldots \ldots F_{j}^{n_{s}-1} \equiv \stackrel{s}{F_{j}^{i}}, \quad F_{j}^{i} \equiv \stackrel{1}{F_{j}^{i}} \quad \text { and } \quad \stackrel{0}{F}_{j}^{i} \equiv \delta_{j}^{i} . \tag{1.10}
\end{equation*}
$$

By use of these notations (1.5) is expressed as

$$
\begin{equation*}
\stackrel{r}{F_{j}^{i}}=\lambda^{r} \delta_{j}^{i} . \tag{1.5}
\end{equation*}
$$

Moreover, if we define the following for a tensor satisfying (1.6):

$$
\begin{equation*}
\bar{F}_{j}^{s}=\frac{1}{\lambda^{a r}} \stackrel{a r-s}{F} ; \quad(a, s: \text { positive integers, } r>a r-s \geqq 0) \tag{1.11}
\end{equation*}
$$

then we have

$$
{\stackrel{s}{F_{h}}{ }^{\imath} \stackrel{\iota}{F_{i}^{h}}=\lambda^{r^{s}+t-r}{ }_{j}^{i} .}^{c}
$$

2. Adapted bases for an $r$ - $\pi$-structure. In the sequel, we assume that the indices take the following ranges:

$$
\begin{gathered}
1 \leqq a_{1}, b_{1}, c_{1}, \ldots \ldots \leqq n_{1}, \\
n_{1}+1 \leqq a_{2}, b_{2}, c_{2}, \ldots \ldots \leqq n_{1}+n_{2}, \\
\ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \\
n_{1}+\ldots \ldots+n_{r-1}+1 \leqq a_{r}, b_{r}, c_{r}, \ldots \ldots \leqq n_{1}+n_{2}+\ldots \ldots+n_{r},
\end{gathered}
$$

whereas

$$
\begin{aligned}
& 1 \leqq i, j, k, \ldots \ldots \leqq n \\
& 1 \leqq \alpha, \beta, \gamma, \ldots \ldots \leqq r .
\end{aligned}
$$

Moreover, we assume that $\bar{a}_{\alpha}, \bar{b}_{\alpha}, \bar{c}_{\alpha}, \ldots \ldots,(1 \leqq \alpha \leqq r)$ take all integers $\left[\left(n-n_{\alpha}\right)\right.$ in number] between 1 and $n$ except for $n_{\alpha}$ integers between $n_{1}+\ldots \ldots+n_{\alpha-1}+1$ and $n_{1}+\ldots \ldots+n_{\alpha-1}+n_{\alpha}$.

A basis ( $e_{i}$ ) in $T_{x}^{c}$ is called an adapted basis at $x$ if $e_{i_{\alpha}} \in T_{\alpha}$ for all $\alpha=$ $1, \ldots \ldots, r$. Since $T_{\alpha}$ is the proper subspace corresponding to the proper value $\lambda w_{a}$ of $\mathfrak{F}$, the tensor $F^{i}{ }^{i}$ satisfying (1.5)' has the following components with respect to such an adapted basis:

$$
\begin{equation*}
F_{b_{\alpha}}^{a_{\alpha}}=\lambda w_{a} \delta_{b_{\alpha},}^{\tau_{\alpha}^{\alpha}} \quad F_{b_{\beta}^{\alpha}}^{a}=0 \quad \text { for } \quad \alpha \neq \beta . \tag{2.1}
\end{equation*}
$$

More generally, we have

$$
\begin{equation*}
\stackrel{s}{F_{b_{\alpha}}^{a_{\alpha}}}=\left(\lambda w_{a}\right)^{s} \delta_{b_{\alpha}^{\alpha}}^{\alpha_{\alpha}}, \quad \stackrel{s^{a}{ }_{b}^{\alpha} \alpha}{b_{\beta}}=0 \quad \text { for } \quad \alpha \neq \beta, 1 \leqq s \leqq r . \tag{2.2}
\end{equation*}
$$

The transformation from an adapted basis to any other adapted basis is expressed as follows:

$$
\begin{equation*}
e_{b^{\prime} 1}=A_{b^{\prime} 1}^{a_{1}} e_{a_{1}}, \quad e_{b^{\prime}, 2}=A_{b^{\prime}{ }_{2}^{\prime}}^{a_{2}} e_{a_{2}}, \ldots \ldots, e_{b_{r}^{\prime} r}=A_{b_{r}^{\prime} r}^{a_{r}^{\prime}} e_{a_{r}} \tag{2.3}
\end{equation*}
$$

where

$$
\begin{equation*}
A_{1}=\left(A_{b^{\prime}, 1}^{a_{1}}\right), \quad A_{2}=\left(A_{b^{\prime}}^{2}\right), \ldots \ldots, \quad A_{r}=\left(A_{b_{r}^{\prime}}^{a_{r}}\right) \tag{2.4}
\end{equation*}
$$

is respectively an $n_{1} \times n_{1}, n_{2} \times n_{2}, \ldots \ldots, n_{r} \times n_{r}$ non singular matrix.
Let $\left(\theta^{t}\right)$ and $\left(\theta^{i^{\prime}}\right)$ be respectively the dual cobasis of $\left(e_{i}\right)$ and $\left(e_{i^{\prime}}\right)$, then we have

$$
\begin{equation*}
\theta^{a_{1}}=A_{b^{\prime} 1}^{a_{1}} \theta^{b^{\prime} 1}, \quad \theta^{q_{2}}=A_{b^{\prime} 2}^{a_{2}} \theta^{b^{\prime} 2}, \quad \ldots \ldots, \quad \theta^{a_{r}}=A_{b_{r}^{r}}^{a_{r}} \theta^{b^{p_{r}} r} \tag{2.5}
\end{equation*}
$$

Denote $E_{\pi}\left(V_{n}\right)$ as the set of all adapted bases relative to all points in $V_{n}$, and $p$ as the mapping which assigns each adapted basis in $T_{x}^{c}$ to $x$. Then $E_{\pi}\left(V_{n}\right)$ is a principal fibre space having $p$ as projection and a subgroup $G\left(n_{1}, n_{2}, \ldots \ldots, n_{r}\right)$ of $G L(n, C)$ as structure group. Here $G\left(n_{1}, n_{2}, \ldots \ldots, n_{r}\right)$ is the group which consists of all matrices of the following form :

$$
\left(\begin{array}{llll}
A_{1} & & &  \tag{2.6}\\
& A_{2} & & \\
& & \cdot & \\
0 & & & \\
& & \\
& & A_{r}
\end{array}\right)
$$

where $A_{1} \in G L\left(n_{1}, C\right), \ldots \ldots, A_{r} \in G L\left(n_{r}, C\right)$, hence
$G\left(n_{1}, n_{2}, \ldots \ldots, n_{r}\right) \cong G L\left(n_{1}, C\right) \times G L\left(n_{2}, C\right) \times \ldots \ldots \times G L\left(n_{r}, C\right)$.
3. Torsion of $r-\pi$-structure. Assume that $V_{n}$ has an $r-\pi$-structure. Consider a local section of $E_{\pi}\left(V_{n}\right)$ of class $C^{\infty}$ in each neighborhood of $V_{n}$, then at every point of the neighborhood $U$ there is associated an adapted basis ( $e_{i}$ ). Let ( $\theta^{i}$ ) be the dual cobasis of $\left(e_{i}\right)$, then we have

$$
\begin{equation*}
d \theta^{t}=\frac{1}{2} C_{j_{k} \theta^{j}}^{\theta^{j}} \wedge \theta^{k} \tag{3.1}
\end{equation*}
$$

where

$$
\begin{equation*}
C_{{ }_{j k}}^{i}+C_{k j}^{i}=0 . \tag{3.2}
\end{equation*}
$$

Let $U^{\prime}$ be any other neighborhood and $\left(\theta^{l^{\prime}}\right), C^{i^{\prime} k^{\prime} k^{\prime}}$ are defined by the same way, then for any $x \in U \cap U^{\prime}$ we have (2.5). If we put

$$
\begin{equation*}
A_{b^{\prime} \beta}^{a_{\alpha}}=0 \quad \text { for } \quad \alpha \neq \beta \tag{3.3}
\end{equation*}
$$

then (2.5) is expressed as follows :

$$
\begin{equation*}
\theta^{i}=A_{i^{\prime}}{ }^{\prime} \theta^{t^{\prime}} \tag{3.4}
\end{equation*}
$$

from which we have

$$
\begin{equation*}
d \theta^{t}=d A_{i^{\prime}}{ }^{i} \wedge \theta^{t^{\prime}}+A_{i^{\prime}}{ }^{i} d \theta^{i^{\prime}} \tag{3.5}
\end{equation*}
$$

Substitute (3.1) and the corresponding formula for $\left(\theta^{i}\right)$, and then make use of (3.4), we have

$$
\begin{equation*}
\frac{1}{2} C_{j k}{ }^{i} A_{j^{\prime}}{ }^{\prime} A_{k^{\prime}}{ }^{k} \theta^{j^{\prime}} \wedge \theta^{k^{\prime}}=d A_{j^{\prime}}{ }^{i} \wedge \theta^{j^{\prime}}+\frac{1}{2} A_{i^{\prime}}{ }^{i} C_{j^{\prime} k^{\prime} \theta^{\prime}}^{\theta^{\prime}} \wedge \theta^{k^{\prime}} \tag{3.6}
\end{equation*}
$$

Let $i$ take the integers in the range of $a_{\alpha}$, and then compare the term $\theta^{b^{\prime} \beta}$ $\wedge \theta^{c^{\prime} \gamma}(\beta \neq \alpha, \gamma \neq \alpha)$ in the both sides, we have

$$
C_{b_{\beta^{\prime} \gamma} \gamma}^{a_{\alpha}} A_{b^{\prime} \beta^{\prime}}^{b_{\beta}} A_{c^{\prime} \gamma \gamma}^{c}=A_{a_{\alpha}^{\prime}}^{\alpha_{\alpha}} C_{b^{\prime} \beta^{c^{\prime} \gamma}}^{\alpha^{\prime}} \quad(\beta \neq \alpha, \gamma \neq \alpha),
$$

that is,

$$
\begin{equation*}
C_{b^{\prime} \beta^{\prime} c^{\prime}{ }_{\gamma}}^{a^{\prime}{ }_{c}}=A_{a_{\alpha}}^{a^{\prime}{ }_{\alpha}} A_{b_{\beta}}^{b_{\beta}} A_{c_{\gamma}}^{c_{\gamma}} C_{b_{\beta^{\prime} \gamma}}^{a_{\alpha}} . \tag{3.7}
\end{equation*}
$$

Hence, if we define $t_{j k}{ }^{i}$ as follows :

$$
\begin{equation*}
t_{\bar{b}_{\alpha_{\alpha}}^{\bar{c}}}^{a_{\alpha}}=C_{\bar{b}_{\alpha} \bar{c}_{\alpha}}^{\alpha_{\alpha}} ; t_{j k}{ }^{i}=0 \text { for other indices, } \tag{3.8}
\end{equation*}
$$

then $t_{y c}{ }^{i}$ is a tensor. We call this tensor the torsion tensor of the $r$ - $\pi$-structure and call the following form the torsion form of the $r-\pi$-structure :

$$
\begin{equation*}
T^{i}=\frac{1}{2} t_{j k}^{i} \theta^{j} \wedge \theta^{k} \tag{3.9}
\end{equation*}
$$

4. Integrability of the $r$ - $\pi$-structure. By definition an $r$ - $\pi$-structure defined by $r$ distributions $T_{1}, \ldots \ldots, T_{r}$ is said to be integrable if at each point of $V_{n}$ there exist a neighborhood and $n$ complex valued functions $z^{t}$ of the local coordinates in the neighborhood such that each $T_{\alpha}$ is expressed by $d z^{\bar{a}} \alpha=0$ at every point in the neighborhood.

Suppose that the considered $r$ - $\pi$-structure is integrable, then as $T_{a}$ is expressed by $d z^{\bar{a}_{\alpha}}=0, \theta^{t}=d z^{t}$ may be regarded as the dual cobasis of the adapted basis given by a local section of $E_{\pi}\left(V_{n}\right)$ on the neighborhood. Hence (3.1) and consequently the following relations hold for $\theta^{i}=d z^{i}$ :

$$
\begin{equation*}
d \theta^{a}{ }_{\alpha}=\frac{1}{2} C_{b_{\alpha} c_{\alpha}}^{a_{\alpha}} \theta^{b} \alpha \wedge \theta^{\rho_{\alpha}}+C_{b_{\alpha_{\alpha}}{ }^{\bar{c}}}^{a_{\alpha}} \theta^{b_{\alpha}} \wedge \theta^{\bar{\natural} \alpha}+T^{a_{a}} \quad(\alpha=1, \ldots \ldots, r), \tag{4.1}
\end{equation*}
$$

where

$$
\begin{equation*}
T^{a_{\alpha}}=\frac{1}{2} C_{\bar{b}_{\alpha} \bar{c}_{\alpha}}^{a_{\alpha}} \theta^{\overline{b_{\alpha}} \alpha} \wedge \theta^{\bar{c}} . \tag{4.2}
\end{equation*}
$$

On the other hand, let $\bar{T}_{s}$ be the direct sum of all $T_{\alpha}$ 's except for $T_{s}$, then $\bar{T}_{s}$ is expressed by $d z^{\alpha_{s}}=0$ in the considered neighborhood. Thus the distribution given by $\bar{T}_{s}$ is integrable, and $d \theta^{v^{2}}$ belong to the ideal defined by $\theta^{\alpha_{s}}=d z^{\alpha^{2}}$. Therefore from (4.1) we have $T^{a,}=0$, that is the torsion tensor of the $r-\pi$ structure vanishes.

Conversely, assume that the torsion tensor of the $r-\pi$-structure vanishes and moreover, that both the considered manifold and the $r$ - $\pi$-structure are of class $C^{\omega}$. Under this situation, both the real and imaginary part of the tensor $F_{j}^{i}$ are real analytic functions of the local coordinates $x^{i}$. Since $T_{a}$ is spanned by the proper vectors of $\mathfrak{F}$ corresponding to the proper value $\lambda w_{a}$, it is expressed by the following equations in the local coordinates:

$$
\begin{equation*}
\left(F_{j}^{i}-\lambda w_{a} \delta_{j}^{i}\right) d x^{j}=0 \tag{4.3}
\end{equation*}
$$

As $T_{\alpha}$ is $n_{\alpha}$-dimensional, this system is of rank $n-n_{\alpha} \equiv \bar{n}_{\alpha}$. Hence (4.3) is equivalent with a system which consists of $\bar{n}_{\alpha}$ independent equations, say :

$$
\begin{equation*}
S_{\alpha}: \quad B_{i}^{\bar{a}} \alpha d x^{i}=0 \tag{4.4}
\end{equation*}
$$

As $T_{1} \cap T_{2}=\{0\}$, the system

$$
\begin{equation*}
S_{1}+S_{2}: \quad B_{i}^{\bar{a}_{1}} d x^{i}=0, B_{i}^{\overline{a_{2}}} d x^{i}=0 \tag{4.5}
\end{equation*}
$$

has zero vector as its only solution. Thus the system $S_{1}+S_{2}$ is of rank $n$. Consequently we can select $n_{1}$ forms $\theta^{a_{1}}$ out of $S_{2}$ such that the system consisting
of $B_{i}^{\bar{i}_{1}} d x^{i}$ and $\theta^{\tau_{1}}$ is independent. Let $\left(e_{i}\right)$ be the dual basis of this system and $\left\langle e_{b_{1}}, \theta^{{x_{1}}_{1}}\right\rangle=\delta_{b_{1}}^{{ }^{{ }_{1}}}$, then $\left\langle e_{b_{1}}, B_{i}^{a_{1}} d x^{i}\right\rangle=0$, hence $e_{b_{1}}$ form a basis of $T_{1}$. As $\left\langle e_{\bar{b}_{1}}, \theta^{a_{1}}\right\rangle=0$ and $T_{s}(s>1)$ is spanned by some vectors in ( $e_{\bar{b}_{1}}$ ), it follows that $\theta^{a_{1}}$ are linear combinations of forms in $S_{s}(s>1)$. As $\theta^{1_{1}}$ are linear combinations of forms in $S_{2}$ and the system made up by $S_{2}$ and $S_{1}$ is of rank $n$, we can select $n_{2}$ forms $\theta^{x_{2}}$ out of $S_{1}$ such that the system ( $S_{2}, \theta^{a_{2}}$ ) is linearly independent. By labeling the indices of $e_{\bar{b}_{1}}$ adequately we have $\left.<e_{b_{2}}, \theta^{a_{2}}\right\rangle=\delta_{b_{2}}^{a_{2}},<e_{b_{2}}, B_{i}^{\bar{a}_{2}}$ $d x^{i}>=0$ and $<e_{\bar{b}_{2}}, \theta^{a_{2}}>=0$. Thus $e_{b 2}$ form a basis of $T_{2}$ and $\theta^{x 2}$ are linear combinations of forms in $S_{t}(t \neq 2)$. As the rank of the system $\left(S_{3}, S_{1}\right)$ is also $n$ and $\theta^{\tau_{1}}, \theta^{\tau_{2}}$ are linear combinations of the forms in $S_{3}$, we can select $n_{3}$ forms $\theta^{a_{3}}$ out of $S_{1}-\left(\theta^{a_{2}}\right)$ and then continue the same processes as above. At last we can split up the system $S_{1}$ in $(r-1)$ subsystems $\left(\theta^{x^{2}}\right),\left(\theta^{\alpha_{z}}\right), \ldots \ldots,\left(\theta^{x} r\right)$ such that ( $\theta^{a_{0}}$ ) are linear combinations of the forms in $S_{t}(t \neq s)$ and each system forms the dual cobasis in $T_{2}, \ldots \ldots, T_{r}$. Thus ( $\theta^{\bar{u}_{r}}$ ) are linear combinations of forms in $S_{s}$ and the rank of the system is $n-n_{s}$, hence the system ( $\theta^{a^{\bar{s}}}$ ) is equivalent with $S_{s}$. Now as we assume that the torsion tensor of the $r-\pi$-structure $t_{j k}^{i}=0$, we have from (4.1) and (4.2) that
from which it follows that $d \theta^{a} \alpha$ are contained in the ideal defined by $\left(\theta^{a} \alpha\right)$. I. e., the system

$$
\begin{equation*}
\theta^{a^{\alpha}}=0 \tag{4.7}
\end{equation*}
$$

is completely integrable (This means that the distribution $\overline{T_{\alpha}}$ is integrable). Therefore, there exist $n_{\alpha}$ complex valued functions $z^{a}{ }_{\alpha}$ of class $C^{\omega}$ such that the system $\theta^{a}{ }_{\alpha}=0$ is equivalent with the system $d z^{{ }^{a} \alpha}=0(\alpha=1, \ldots \ldots, r)$. As the system $\left(F_{j}^{i}-\lambda w_{\alpha} \delta_{j}^{i}\right) d x^{j}=0$ is equivalent with $S_{\alpha}$ which is in turn equivalent with ( $\theta^{\bar{a}}=0$ ), which is again equivalent with $d z^{\bar{a}}{ }_{\alpha}=0$, it follows that the $T_{\alpha}$ is expressed by $d z^{\bar{a}} \alpha=0$, i. e. the considered $r-\pi$-structure is integrable. Thus we have

THEOREM 4.1. If the $r$ - $\pi$-structure is integrable, then the torsion tensor of the $r-\pi$-structure $t_{j k}^{i}=0$. Conversely if $t_{j k}^{i}=0$ and moreover both the manifold and the considered $r$ - $\pi$-structure are of class $C^{\omega}$, then the $r$ - $\pi$-structure is integrable.

From the course of the above proof, it is also evident that the definition of the integrability of an $r$ - $\pi$-structure stated above is equivalent to the one made by Walker [4].
5. A formula on torsion form of the $r-\pi$-structure. Assume that the manifold is endowed with an $r-\pi$-structure $(2 \leqq r \leqq n$ ). We generalize the operations $C$ and $M$ considered by Lichnerowicz [3] and Legrand [2] as follows :

Let $v_{1}, \ldots \ldots, v_{t}$ be any $t$ vectors of $T_{x}^{C}$ and $\varphi$ be a $t$-form, then define

$$
\begin{gather*}
\stackrel{s}{C} \varphi\left(v_{1}, \ldots \ldots, v_{t}\right)=\varphi\left(\mathfrak{F}^{s} v_{1}, \ldots \ldots, \mathfrak{F}^{s} v_{t}\right),  \tag{5.1}\\
\stackrel{s}{M} \varphi\left(v_{1}, \ldots \ldots, v_{t}\right)=\sum_{k=1}^{t} \varphi\left(v_{1}, \ldots \ldots, v_{k-1}, \mathfrak{F}^{s} v_{k}, v_{k+1}, \ldots \ldots, v_{t}\right),  \tag{5.2}\\
\\
(1 \leqq s<r) .
\end{gather*}
$$

If $\boldsymbol{\varphi}_{i_{1}} \cdots \cdots i_{t}$ are components of $\boldsymbol{\rho}$ with respect to a basis at a point $x$, then the components of $\stackrel{s}{C} \varphi$ and $\stackrel{s}{M} \varphi$ are respectively as follows:

$$
\begin{align*}
& (\stackrel{s}{C} \boldsymbol{\varphi})_{i_{1} \cdots \cdots i_{i}}=\stackrel{s}{F_{i_{1}}{ }^{j_{1}} \ldots \ldots .{\stackrel{s}{F_{i}}}^{s_{t}} \boldsymbol{\rho}_{f_{1}} \cdots \cdots j_{t}},  \tag{5.3}\\
& (\stackrel{s}{M} \boldsymbol{\varphi})_{i_{1}} \cdots \cdots i_{t}=\sum_{k=1}^{t}{ }^{s}{ }_{F_{k}}{ }^{h} \boldsymbol{\varphi}_{i_{1}} \cdots \cdots i_{k-1 i_{k+1}} \cdots \cdots \iota_{t} . \tag{5.4}
\end{align*}
$$

Let $\left(\theta^{i}\right)$ be the dual cobasis of an adapted basis at $x$, then we say that the form

$$
\varphi=\frac{1}{t!} \boldsymbol{\varphi}_{i_{1} \ldots \ldots i_{t}} \theta^{i_{1}} \wedge \ldots \ldots \wedge \theta^{t_{t}}
$$

is pure of the type $\left(p_{1}, \ldots \ldots, p_{r}\right)$ if the only non zero term in the above expression is the term which is of degree $p_{a}$ with respect to $\theta^{\boldsymbol{a} \alpha}(\alpha=1, \ldots \ldots, r)$. It is evident that this definition is independent of the adapted basis used at $x$. Let $\boldsymbol{\varphi}_{p_{1}, p_{2}, \ldots, p_{r}}$ be pure of the type ( $p_{1}, p_{2}, \ldots \ldots, p_{r}$ ), then from (2.2), (5.3) and (5.4) it follows that

$$
\begin{gather*}
\stackrel{s}{\boldsymbol{C}} \boldsymbol{\varphi}_{p_{1}, p_{2}, \ldots, p_{r}}=w_{1}^{s p_{1}} w_{2}^{s p_{2}} \ldots \ldots . w_{r}^{s p_{r}} \lambda^{s\left(p_{1}+p_{2}+\ldots+p_{r}\right)} \boldsymbol{\varphi}_{p_{1}, p_{2}, \ldots, p_{r},}  \tag{5.5}\\
\stackrel{s}{M} \boldsymbol{\varphi}_{p_{1}, p_{2}, \ldots, p_{r}}=\left(p_{1} w_{1}^{s}+p_{2} w_{2}^{s}+\ldots \ldots+p_{r} w_{r}^{s}\right) \lambda^{r} \boldsymbol{\varphi}_{p_{1}, p_{2}, \ldots, p_{r}} . \tag{5.6}
\end{gather*}
$$

As we shall concern principally with 2 -forms in the sequel, we list here some relations on the operations $\stackrel{s}{C}$ and $\stackrel{s}{M}$ which hold only when applied on 2 -forms. Let $\boldsymbol{\varphi}$ be a 2 -form with components $\boldsymbol{\varphi}_{p q}$, then

$$
\begin{gather*}
(\stackrel{\mathrm{s}}{(M)})_{s k}=\left(\delta_{j}^{p} \stackrel{s}{F}_{k}^{q}+\delta_{k}^{q}{ }^{s}{ }_{j}^{p}\right) \boldsymbol{\varphi}_{p q},  \tag{5.7}\\
(\stackrel{s}{C} \boldsymbol{\varphi})_{s k}=\stackrel{s}{F}_{j}^{p}{ }^{s}{ }^{s}{ }_{k}^{q} \boldsymbol{\varphi}_{p q} . \tag{58}
\end{gather*}
$$

Hence

$$
\begin{equation*}
(\stackrel{s t-s}{C M})_{t k}=\left(\stackrel{s}{F_{j}^{p}}{ }_{j}^{t}{ }_{k}^{q}+\stackrel{s}{F_{k}}{ }^{q} \stackrel{t}{F_{j}^{p}}\right) \boldsymbol{\varphi}_{p q} . \tag{5.9}
\end{equation*}
$$

From these relations we have immediately

$$
\left\{\begin{align*}
\stackrel{0}{M} & =2, & \stackrel{0}{C}=1,  \tag{5.10}\\
\stackrel{a r+b}{M} & =\lambda^{a r} \stackrel{b}{M}, & \stackrel{a r+b}{C}=\lambda^{2 a r} \stackrel{b}{C}, \\
\stackrel{a r}{M} & =2 \lambda^{a r}, & \stackrel{a r}{C}=\lambda^{2 a r},
\end{align*}\right.
$$

where $a$ is any positive integer and $0 \leqq b<r$. Moreover, we have

$$
\begin{equation*}
\stackrel{s}{M} \stackrel{t}{M}=\stackrel{s+t}{M}+\stackrel{s}{C} \stackrel{t-s}{M}, \tag{5.11}
\end{equation*}
$$

hence

$$
\begin{equation*}
(\stackrel{s}{M})^{2}=\stackrel{2 s}{M}+2 \stackrel{s}{C}, \quad \stackrel{s}{C}=\frac{1}{2}\left\{(\stackrel{s}{M})^{2}-\stackrel{2 s}{M}\right\} \tag{5.12}
\end{equation*}
$$

and

$$
\begin{equation*}
\stackrel{s}{C} M\left(\stackrel{s}{M} \stackrel{u^{u+s}}{M}-\frac{2 s+u}{M} .\right. \tag{5.13}
\end{equation*}
$$

From the last relation we have

$$
\begin{equation*}
\stackrel{s}{C} M=\lambda^{r} \stackrel{u+s-r}{C} \stackrel{r-u}{M} \quad \text { for } \quad u+s \geqq r, u>r, s ; \tag{5.14}
\end{equation*}
$$

and

$$
\begin{equation*}
\stackrel{s}{C} \stackrel{r-s}{M}=\lambda^{r} \stackrel{s}{M} . \tag{5.15}
\end{equation*}
$$

Now assume that the manifold is endowed with an $r$ - $\pi$-structure, and let $T^{i}$ be the torsion form of the structure. Denote

$$
\begin{equation*}
\boldsymbol{\varphi} \circ T \equiv \boldsymbol{\varphi}_{i} T^{i}=\frac{1}{2} \boldsymbol{\varphi}_{i} t_{j k}^{i} \theta^{j} \wedge \theta^{k} \tag{5.16}
\end{equation*}
$$

for any 1 -form $\boldsymbol{\varphi}$, then we have the following :

$$
\begin{equation*}
r^{2} \lambda^{r} d \boldsymbol{\rho}+\sum_{t=1}^{r}\left(-r M^{t}+\frac{1}{2}-\frac{1}{\lambda^{2 r}} \cdot \sum_{s=0}^{r-1} \stackrel{s}{C} \stackrel{t+2 r-2 s}{M}\right) d \stackrel{r-t}{C} \boldsymbol{\varphi}=r^{2} \lambda^{r} \boldsymbol{\varphi} \circ T . \tag{5.17}
\end{equation*}
$$

If we extend the definition of $\stackrel{s}{M}$ so as (5.7) to hold also for negative integer, then instead of (5.17) we have

$$
\begin{equation*}
r^{2} \lambda^{r} d \varphi+\sum_{t=1}^{r}\left(-r \stackrel{t}{M}+\frac{1}{2} \sum_{s=0}^{r-1} \stackrel{s}{C} \stackrel{t-2 s}{M}\right) d \stackrel{r-t}{C} \boldsymbol{\varphi}=r^{2} \lambda^{r} \varphi \circ T \tag{5.18}
\end{equation*}
$$

PROOF. Let $\varphi$ be a pure form of the type ( $1,0, \ldots \ldots, 0$ ), say $\boldsymbol{\varphi} \equiv \boldsymbol{\varphi}_{1,0, \ldots, 0}$ $=\boldsymbol{\varphi}_{a_{1}} \theta^{a_{1}}$, then by (3.1), $d \boldsymbol{\rho}=d \varphi_{a_{1}} \theta^{a_{1}}+\varphi_{a_{1}} d \theta^{a_{1}}$ is the sum of the pure form
of the type $\boldsymbol{\varphi}_{2,0, \ldots, 0}\left[\right.$ i. e., $\left.p_{1}=2, p_{2}=\ldots \ldots=p_{r}=0\right]$; pure forms of the type $\boldsymbol{\varphi}_{1,0, \ldots, 0,1,0, \ldots, 0}$ [i. e., $p_{1}=1, p_{2}=\ldots \ldots=p_{r}=0$ except for an integer $s(2 \leqq s \leqq r)$ and $p_{s}=1$ ]; pure forms of the type $\psi_{0, \ldots, 0,2,0, \ldots, 0}$ [i. e., $p_{1}=\ldots \ldots=p_{r}=0$ except for an integer $s(2 \leqq s \leqq r)$ and $\left.p_{s}=2\right]$ and pure forms of the type $\psi_{0, \ldots, 0,1,0, \ldots, 0,1,0, \ldots, 0}$ i. e., $p_{1}=\ldots \ldots=p_{r}=0$ except for two integers $s, t, s \neq t(2 \leqq s$, $t \leqq r$ ) and $\left.p_{s}=p_{t}=1\right]$. Whereas $\varphi \circ T$ is the sum of pure forms of the type $\psi_{0, \ldots, 0,2,0, \ldots, 0}$ and pure forms of the type $\psi_{0, \ldots, 0,1,0, \ldots, 0 .}$ As $\varphi=\boldsymbol{\varphi}_{1,0, \ldots, 0}$ is a pure form, with respect to the adapted basis given by the local section, we have

$$
\begin{equation*}
d^{r-t} \boldsymbol{C} \boldsymbol{\varphi}=w_{1}^{(r-t)} \lambda^{(r-t)} d \varphi . \tag{5.19}
\end{equation*}
$$

Therefore the coefficients of

$$
\begin{cases}\varphi_{2,0, \cdots, 0} ; & \varphi_{1,1,0, \cdots, 0} ;  \tag{5.20}\\ \boldsymbol{\psi}_{0,2,0, \cdots, 0} ; & \psi_{0,1,1,0, \cdots, 0}\end{cases}
$$

in $\frac{1}{2} \stackrel{s}{C} \stackrel{t-2 s}{M} d \stackrel{r-t}{C} \varphi$ are respectively the following:

$$
\begin{cases}\lambda^{r} ; & \frac{1}{2}\left\{\left(\frac{w_{2}}{w_{1}}\right)^{s}+\left(\frac{w_{2}}{w_{1}}\right)^{t}\left(\frac{w_{1}}{w_{2}}\right)^{s}\right\} \lambda^{r} ;  \tag{5.21}\\ \left(\frac{w_{2}}{w_{1}}\right)^{t} \lambda^{r} ; & \frac{1}{2}\left\{\left(\frac{w_{2}}{w_{1}}\right)^{t}\left(\frac{w_{3}}{w_{2}}\right)^{s}+\left(\frac{w_{3}}{w_{1}}\right)^{t}\left(\frac{w_{2}}{w_{3}}\right)^{s}\right\} \lambda^{r}\end{cases}
$$

Taking the summation $\sum_{t=1}^{r} \sum_{s=0}^{r-1}$ of each term in (5.21), we get the following


$$
\left\{\begin{align*}
r^{2} \lambda^{r} ; & 0 ;  \tag{5.22}\\
0 ; & 0
\end{align*}\right.
$$

On the other hand the coefficients of the four forms of (5.20) in $-r \stackrel{t}{M} d \stackrel{r-t}{C} \boldsymbol{\varphi}$ are respectively

$$
\begin{cases}-2 r \lambda^{r} ; & -r\left\{1+\left(\frac{w_{2}}{w_{1}}\right)^{t}\right\} \lambda^{r} ;  \tag{5.23}\\ -2 r\left(\frac{w_{2}}{w_{1}}\right)^{t} \lambda^{r} ; & -r\left\{\left(\frac{w_{2}}{w_{1}}\right)^{t}+\left(\frac{w_{3}}{w_{1}}\right)^{t}\right\} \lambda^{r}\end{cases}
$$

Taking the summation $\sum_{i=1}^{r}$ of each term in (5.23) we get the following respective coefficient of the forms of (5.20) in $\sum_{t=1}^{r}(-r) \stackrel{t}{M} \stackrel{r-t}{d C} \boldsymbol{\varphi}$ :

$$
\left\{\begin{array}{cc}
-2 r^{2} \lambda^{r} ; & -r^{2} \lambda^{r} ;  \tag{5.24}\\
0 ; & 0 .
\end{array}\right.
$$

From (5.22) and (5.24) it follows immediately that the respective coefficients of the forms of ( 5.20 ) in the left hand side of ( 5.18 ) are respectively

$$
\left\{\begin{array}{rr}
0 ; & 0 ;  \tag{5.25}\\
r^{2} \lambda^{r} ; & r^{2} \lambda^{r} .
\end{array}\right.
$$

Whereas the corresponding coefficients in $\varphi \circ T$ are respectively

$$
\begin{cases}0 ; & 0 ;  \tag{5.26}\\ 1 ; & 1 .\end{cases}
$$

Therefore, the relation (5.18) holds for $\varphi \equiv \boldsymbol{\varphi}_{1,0}, \cdots, 0$ because we can get similar results for the other forms appearing in both sides of (5.18). It is easily seen by the same way that ( 5.18 ) holds also for any other pure forms $\boldsymbol{\varphi}_{0, \cdots, 0,1,0}$, $\cdots, 0$ [i. e., $p_{1}=\ldots \ldots=p_{r}=0$ except for an integer $s(2 \leqq s \leqq r)$ and $\left.p_{s}=1\right]$. Thus we have the relation (5.18) for any 1 -form.
6. Components of the torsion tensor of an $r-\pi$-structure. Let $\boldsymbol{\rho}$ be any 1 -form, then as $(\stackrel{s}{C} \boldsymbol{\varphi})_{i}=\stackrel{s}{F_{i}}{ }^{m} \boldsymbol{\varphi}_{m}$, we have

$$
\begin{equation*}
d \stackrel{s}{C} \varphi=\stackrel{s}{\circ} \circ \varphi+\stackrel{s}{\mathscr{G}}, \tag{6.1}
\end{equation*}
$$

where we have put

$$
\begin{equation*}
\stackrel{s}{\mathfrak{f}}_{j k}^{m}=\frac{1}{2}\left(\partial_{j} \stackrel{s}{F}_{k}^{m}-\partial_{k} \stackrel{s}{F}_{j}^{m}\right), \quad(\stackrel{s}{\mathfrak{f}} \circ \varphi)_{f k}=\frac{1}{2}\left(\partial_{j} \stackrel{s}{F}_{k}^{m}-\partial_{k} \stackrel{s}{F}_{j}^{m}\right) \boldsymbol{\varphi}_{m}, \tag{6.2}
\end{equation*}
$$

$$
\begin{equation*}
\stackrel{s}{\mathscr{E}}_{j k}=\frac{1}{2}\left(\stackrel{s}{F}_{k}^{m} \partial_{j} \boldsymbol{\varphi}_{m}-\stackrel{s}{F}_{j}^{m} \partial_{k} \boldsymbol{\varphi}_{m}\right) . \tag{6.3}
\end{equation*}
$$

Moreover, if we put
then we have

Putting (6.1) in the left hand side of (5.18) and then make use of (6.5). we have

$$
\begin{align*}
& A \equiv r^{2} \lambda^{r} d \boldsymbol{\varphi}+\sum_{t=1}^{r}\left(-r \stackrel{i}{M}^{t}+\frac{1}{2} \sum_{s=0}^{r-1} \stackrel{s}{C}^{t-2 s}\right) \stackrel{r-t}{d C} \boldsymbol{\varphi} \\
& =r^{2} \lambda^{r} d \boldsymbol{\varphi}+\left(-r \stackrel{r}{M}+\frac{1}{2} \sum_{s=0}^{r-1} C^{s-2 s}\right) d \boldsymbol{\varphi}  \tag{6.6}\\
& +\sum_{t=1}^{r-1}\left(-r M^{i}+\frac{1}{2} \sum_{s=0}^{r-1} \stackrel{s}{M}^{t-2 s}\right)^{r-t} \stackrel{G}{t}^{t} \\
& +\sum_{t=1}^{r-1}\left(-r M^{t}+\frac{1}{2} \sum_{s=0}^{r-1} C^{s-2 s}\right)^{r-t} \stackrel{\rightharpoonup}{f}^{r} \circ \rho .
\end{align*}
$$

As it is shown below, we have

$$
\begin{equation*}
\left.B \equiv \sum_{t=1}^{r-1}\left(-r M^{t}+\frac{1}{2} \sum_{s=0}^{r-1} \stackrel{s}{C} M^{t-2 s}\right)\right)^{r-t}=-r^{2} \lambda^{r} d \varphi-\left(-r M^{r}+\frac{1}{2} \sum_{s=0}^{r-1} \stackrel{s}{C} M^{t-2 s}\right) d \varphi, \tag{6.7}
\end{equation*}
$$ we get

$$
\begin{equation*}
A=\sum_{t=1}^{r-1}\left(-r M^{t}+\frac{1}{2} \sum_{s=0}^{r-1} \stackrel{s}{C} M^{t-2 s}\right)^{r-t} \stackrel{\varphi}{f} \circ . \tag{6.8}
\end{equation*}
$$

From (6.8), (5.18), (5.7) and (5.9) we have

$$
\begin{align*}
& t_{j k}^{l}=\frac{1}{r^{2} \lambda^{r}} \sum_{t=1}^{r-1}\left\{-r\left(\delta_{j}^{p} F_{k}^{q}+\delta_{k}^{q}{ }_{i}^{t}{ }_{i}^{p}\right)\right. \tag{6.9}
\end{align*}
$$

The proof of (6.7) is as follows: Making use of (6.5) we have

$$
B=-r(r-1) \lambda^{r} d \varphi-r \sum_{t=1}^{r-1} \mathfrak{( t , r - t )} \mathfrak{\mathscr { E }}+\frac{1}{2}(r-1) \sum_{s=0}^{r-1}\left(s, \mathscr{S}^{(s, s)}+\frac{1}{2} \sum_{t=1}^{r-1} \sum_{s=0}^{r-1} \mathfrak{g}^{(t-s, r-t+s)}\right.
$$

It is shown below that

Hence we have

$$
\begin{align*}
& +\frac{1}{2}(r-1) \sum_{u=1}^{r-1}(u, r-u) . \tag{6.11}
\end{align*}
$$

As $\stackrel{(0, r)}{5}=\stackrel{(r, 0)}{5}=\lambda^{r}{ }^{(0,0)}{ }_{5}{ }^{(0)}=\lambda^{r} d \boldsymbol{\varphi}$, from (6.5) and (6.11) we have

$$
\begin{aligned}
B & =-(r-1)^{2} \lambda^{r} d \boldsymbol{\rho}-\sum_{t=1}^{r-1} \stackrel{(t, r-t)}{S_{L}} \\
& =-r^{2} \lambda^{r} d \boldsymbol{\varphi}+r \stackrel{r}{r} d \boldsymbol{\rho}-\frac{1}{2} \sum_{s=0}^{r-1} C^{s} M^{r-2 s} d \varphi
\end{aligned}
$$

Finally, the proof of (6.10) is as follows:

$$
\begin{aligned}
& \left.C=\sum_{t=1}^{r-1} \sum_{s^{\prime}=t-r+1}^{t} \begin{array}{c}
\left(s^{\prime}, r-s^{\prime}\right) \\
s_{j}
\end{array} \quad \text { (putting } s^{\prime}=t-s \text { in } C\right) \\
& =\sum_{t=1}^{r-1}\left(\sum_{s^{\prime}=1}^{t}{\left.\stackrel{(s}{s}, r-s^{\prime}\right)}_{s_{2}}+\sum_{s^{\prime}=t-r+1}^{0}\binom{\left(s^{\prime}, r-s^{\prime}\right)}{s_{2}}\right. \text {. }
\end{aligned}
$$

Since

$$
\begin{aligned}
& \sum_{s^{\prime}=t-r+1}^{0}{ }_{\substack{\left(s^{\prime}, r-s^{\prime}\right) \\
5}}=\sum_{s^{\prime \prime}=1}^{r-t}{ }_{5}^{\left(t-r+s^{\prime}, 2 r-t-s^{\prime \prime}\right)} \quad \text { (putting } s^{\prime}=t-r+s^{\prime \prime} \text { in left hand side) } \\
& =\sum_{s^{\prime \prime}=1}^{r-1}{\stackrel{\left(t+s^{\prime \prime}\right.}{\left.S^{\prime \prime}, r-t-s^{\prime \prime}\right)}}^{S^{\prime}} \sum_{u=t+1}^{r}\left(\begin{array}{c}
(u, r-u) \\
S^{2}
\end{array}\left(u=t+s^{\prime \prime}\right)\right. \text {, }
\end{aligned}
$$

we have

$$
\begin{aligned}
& =\sum_{t=1}^{r-1}\left(\sum_{u=1}^{r} \underset{\substack{(u, r-u) \\
5}}{ }\right)=(r-1) \sum_{u=1}^{r} \underset{\mathcal{S}}{(u, r-u)}
\end{aligned}
$$

7. An application of the relation (5.18). Let the infinitesimal transformation defined by the vector field $X$ be denoted by $X \cdot f$ where $f$ is a function. Let $u, v$ be any two vector fields, $\varphi$ be any 1 -form, then it is known that the following relation holds:

$$
\begin{equation*}
d \boldsymbol{\varphi}(u, v)=u \cdot \boldsymbol{\varphi}(v)-v \cdot \boldsymbol{\varphi}(u)-\boldsymbol{\varphi}([u, v]), \tag{7.1}
\end{equation*}
$$

where $[u, v]$ is the Poisson's bracket of the two vector fields $u, v$. Making use
of this formula we have

$$
\begin{equation*}
d^{r-t} \boldsymbol{C} \boldsymbol{\varphi}(u, v)=u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} v\right)-v \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} u\right)-\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}[u, v]\right), \tag{7.2}
\end{equation*}
$$

from which we have moreover the following:

$$
\begin{align*}
\stackrel{t}{M} \stackrel{r-t}{C} \boldsymbol{\varphi}(u, v) & =\stackrel{{ }^{r-t} C}{C} \boldsymbol{\varphi}\left(\mathfrak{F}^{t} u, v\right)+\stackrel{r}{C}_{C-t}^{C}\left(u, \mathfrak{F}^{t} v\right) \\
& =\mathscr{F}^{t} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} v\right)-\mathfrak{F}^{t} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} u\right)  \tag{7.3}\\
& +\lambda^{r}\{d \boldsymbol{\varphi}(u, v)+\boldsymbol{\varphi}([u, v])\} \\
& -\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}\left[\mathfrak{F}^{t} u, v\right]\right)-\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}\left[u, \mathfrak{F}^{t} v\right]\right) .
\end{align*}
$$

Hence

$$
\begin{align*}
& \stackrel{s}{s t-2 s} M d C \\
& \overbrace{}^{-t} \boldsymbol{\varphi}(u, v)=\stackrel{t-2 s}{M-t} C \boldsymbol{\varphi}\left(\mathfrak{F}^{s} u, \mathfrak{F}^{s} v\right) \\
&=\mathfrak{F}^{t-s} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-(t-s)} v\right)-\mathfrak{F}^{t-s} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-(t-s)} u\right)  \tag{7.4}\\
&+\mathfrak{F}^{s} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} v\right)-\mathfrak{F}^{s} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} u\right) \\
&-\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}\left[\mathfrak{F}^{t-s} u, \mathfrak{F}^{s} v\right]\right)-\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}\left[\mathfrak{F}^{s} u, \mathfrak{F}^{t-s} v\right]\right) .
\end{align*}
$$

Since the value $T(u, v)$ of the torsion form of an $r$ - $\pi$-structure for the vector fields $u, v$ defines a vector field, we have from (5.18) the following:

$$
\begin{align*}
r^{2} \lambda^{r} \varphi(T(u, v))=r^{2} \lambda^{r} d \varphi(u, v) & +\sum_{t=1}^{r}(-r){ }^{t} M^{r-t} C \varphi(u, v)  \tag{7.5}\\
& +\frac{1}{2} \sum_{t=1}^{r} \sum_{s=0}^{r-1} C^{s} M d C \varphi(u, v) .
\end{align*}
$$

Putting (7.3) and (7.4) in the right hand side of the above formula, we have

$$
\begin{align*}
r^{2} \lambda^{r} \boldsymbol{\varphi}(T(u, v)) & =\sum_{t=1}^{r}(-r)\left\{\mathfrak{F}^{t} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} v\right)-\mathfrak{F}^{t} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} u\right)\right\}-r^{2} \lambda^{r} \boldsymbol{\varphi}([u, v]) \\
& +r \sum_{t=1}^{r}\left\{\boldsymbol{\phi}\left(\mathfrak{F}^{r-t}\left[\mathfrak{F}^{t} u, v\right]\right)+\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}\left[u, \mathfrak{F}^{t} v\right]\right)\right\} \\
& +\frac{1}{2} \sum_{t=1}^{r} \sum_{s=0}^{r-1}\left\{\mathfrak{F}^{t-s} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-(t-s)} v\right)-\mathfrak{F}^{t-s} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-(t-s)} u\right)\right\}  \tag{7.6}\\
& +\frac{1}{2} \sum_{t=1}^{r} \sum_{s=0}^{r-1}\left\{\mathfrak{F}^{s} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} v\right)-\mathfrak{F}^{s} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} u\right)\right\} \\
& -\frac{1}{2} \sum_{t=1}^{r} \sum_{s=0}^{r-1}\left\{\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}\left[\mathfrak{F}^{t-s} u, \mathfrak{F}^{s} v\right]\right)+\boldsymbol{\varphi}\left(\mathfrak{F}^{r-t}\left[\mathfrak{F}^{s} u, \mathfrak{F}^{t-s} v\right]\right)\right\} .
\end{align*}
$$

It is seen immediatley that

$$
\begin{align*}
\frac{1}{2} \sum_{t=1}^{r} \sum_{s=0}^{r-1}\left\{\mathfrak{F}^{s} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} v\right)\right. & \left.-\mathfrak{F}^{s} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} u\right)\right\}  \tag{7.7}\\
& =\frac{1}{2} r \sum_{s=1}^{r}\left\{\mathfrak{F}^{s} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} v\right)-\mathfrak{F}^{s} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-s} u\right)\right\} .
\end{align*}
$$

As it is shown below that

$$
\begin{align*}
D & \equiv \frac{1}{2} \sum_{t=1}^{r} \sum_{s=0}^{r-1}\left\{\mathfrak{F}^{t-s} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-(t-s)} v\right)-\mathfrak{F}^{t-} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-(t-s)} u\right)\right\}  \tag{7.8}\\
& =\frac{1}{2} r \sum_{t=1}^{r}\left\{\mathfrak{F}^{t} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} v\right)-\mathfrak{F}^{t} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t} u\right)\right\},
\end{align*}
$$

from (7.6), (7.7) and (7.8) we have the following

$$
\begin{align*}
r^{2} \lambda^{r} T(u, v)= & -r^{2} \lambda^{r}[u, v]+r \sum_{t=1}^{r}\left\{\mathscr{F}^{r-t}\left[\mathfrak{F}^{t} u, v\right]+\mathfrak{F}^{r-t}\left[u, \mathscr{F}^{t} v\right]\right\}  \tag{7.9}\\
& -\frac{1}{2} \sum_{t=1}^{r} \sum_{s=0}^{r-1}\left\{\mathfrak{F}^{r-t}\left[\mathfrak{F}^{t-s} u, \mathfrak{F}^{s} v\right]+\mathfrak{F}^{r-t}\left[\mathfrak{F}^{s} u, \mathfrak{F}^{t-s} v\right]\right\}
\end{align*}
$$

To prove (7.8), put $t^{\prime}=t-s$, then we have

$$
\begin{aligned}
D & =\frac{1}{2} \sum_{t^{\prime}=1}^{r} \sum_{s=0}^{r-t^{\prime}}\left\{\mathfrak{F}^{t^{\prime}} u \cdot \boldsymbol{\rho}\left(\mathfrak{F}^{r-t^{\prime}} v\right)-\mathfrak{F}^{t^{\prime}} v \cdot \boldsymbol{\rho}\left(\mathfrak{F}^{r-t^{\prime}} u\right)\right\} \\
& +\frac{1}{2} \sum_{t^{\prime}=-(r-2)}^{0} \sum_{s=1-t^{\prime}}^{r-1}\left\{\mathfrak{F}^{t^{\prime}} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t^{\prime}} v\right)-\mathfrak{F}^{t^{\prime}} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t^{\prime}} u\right)\right\} .
\end{aligned}
$$

If we put $t^{\prime \prime}=t^{\prime}+r$, then the last term of the above formula turns out to be

$$
\begin{aligned}
& \frac{1}{2} \sum_{t^{\prime \prime}=2}^{r} \sum_{s=r+1-t^{\prime \prime}}^{r-1}\left\{\mathfrak{F}^{t^{\prime \prime}-r} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{2 r-t^{\prime \prime}} v\right)-\mathfrak{F}^{t^{\prime \prime}-r} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{2 r-t^{\prime \prime}} u\right)\right\} \\
& \quad=\frac{1}{2} \sum_{t^{\prime \prime}=2}^{r}\left(t^{\prime \prime}-1\right)\left\{\mathfrak{F}^{t^{\prime \prime}} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t^{\prime \prime}} v\right)-\mathfrak{F}^{t^{\prime \prime}} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t^{\prime \prime}} u\right)\right\} \\
& \quad=\frac{1}{2} \sum_{t^{\prime \prime}=1}^{r}\left(t^{\prime \prime}-1\right)\left\{\mathfrak{F}^{t^{\prime \prime}} u \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t^{\prime \prime}} v\right)-\mathfrak{F}^{t^{\prime \prime}} v \cdot \boldsymbol{\varphi}\left(\mathfrak{F}^{r-t^{\prime \prime}} u\right)\right\} .
\end{aligned}
$$

Hence we have (7.8).
For giving an application of (7.9), we first calculate some formulas to be used :

From (1.4) we have
and

$$
\begin{aligned}
\mathfrak{F}^{r-t}\left[\mathfrak{F}^{t} u, v\right] & =\lambda^{r} \sum_{\beta=1}^{r} \sum_{\alpha=1}^{r}\left(\frac{w_{\alpha}}{w_{\beta}}\right)^{t} \mathfrak{F}_{\beta}\left[\mathfrak{F}_{\alpha} u, v\right] \\
\mathfrak{F}^{r-t}\left[\mathfrak{F}^{t-s} u, \mathfrak{F}^{s} v\right] & =\lambda^{r} \sum_{\gamma=1}^{r} \sum_{\beta=1}^{r} \sum_{\alpha=1}^{r}\left(\frac{w_{\beta}}{w_{\gamma}}\right)^{t}\left(\frac{w_{\alpha}}{w_{\beta}}\right)^{s} \Re_{\gamma}\left[\Re_{\beta} u, \Re_{\alpha} v\right] .
\end{aligned}
$$

From these two formulas we have respectively

$$
\begin{gather*}
\sum_{t=1}^{r} \mathfrak{F}^{r-t}\left[\mathfrak{F}^{t} u, v\right]=r \lambda^{r} \sum_{\alpha=1}^{r} \mathfrak{F}_{\alpha}\left[\mathfrak{F}_{\alpha} u, v\right],  \tag{7.10}\\
\sum_{t=1}^{r} \sum_{s=0}^{r-1} \mathfrak{F}^{r-t}\left[\mathfrak{F}^{t-s} u, \mathfrak{F}^{s} v\right]=r^{2} \lambda^{r} \sum_{\alpha=1}^{r} \mathfrak{F}_{\alpha}\left[\mathfrak{F}_{\alpha} u, \mathfrak{F}_{\alpha} v\right] . \tag{7.11}
\end{gather*}
$$

It is obvious that

$$
\begin{equation*}
[u, v]=\sum_{\alpha=1}^{r} \mathfrak{F}_{\alpha}[u, v] . \tag{7.12}
\end{equation*}
$$

Substitute (7.10), (7.11) and (7.12) in (7.9), we have

$$
\begin{align*}
r^{2} \lambda^{r} T(u, v) & =r^{2} \lambda^{r} \sum_{a=1}^{r}\left\{-\mathfrak{\Re}_{\alpha}[u, v]+\mathfrak{F}_{\alpha}\left[\Re_{\alpha} u, v\right]+\Re_{\alpha}\left[u, \Re_{\alpha} v\right]-\Re_{\alpha}\left[\Re_{\alpha} u, \Re_{\alpha} v\right]\right\}  \tag{7.13}\\
& =r^{2} \lambda^{r} \sum_{\alpha=1}^{r} \Re_{\alpha}\left\{-\Re_{\alpha}[u, v]+\Re_{\alpha}\left[\Re_{\alpha} u, v\right]+\Re_{\alpha}\left[u, \Re_{\alpha} v\right]-\left[\Re_{\alpha} u, \Re_{\alpha} v\right]\right\} .
\end{align*}
$$

Let $N\left(P_{\alpha}\right)$ be the Nijenhuis tensor of the projection tensor ${\underset{\alpha}{\alpha}}_{P_{j}^{i}}$ induced by $\mathfrak{P}_{\alpha}$. As it is known that

$$
\begin{equation*}
N\left(P_{\alpha}\right)(u, v)=-\mathfrak{B}_{\alpha}\left[\mathfrak{B}_{\alpha} u, v\right]-\mathfrak{B}_{\alpha}\left[u, \mathfrak{B}_{\alpha} v\right]+\mathfrak{B}_{\alpha}[u, v]+\left[\mathfrak{F}_{\alpha} u, \mathfrak{B}_{\alpha} v\right], \tag{7.14}
\end{equation*}
$$

we have from (7.13) the following

$$
\begin{equation*}
T(u, v)=-\sum_{\alpha=1}^{r} \mathfrak{\Re}_{\alpha} N\left(P_{\alpha}\right)(u, v) . \tag{7.15}
\end{equation*}
$$

8. $\pi$-connections on the differentiable manifold endowed with an $r$ -$\pi$-structure. Let $V_{n}$ be a differentiable manifold having an $r-\pi$-structure. By definition a $\pi$-connection on $V_{n}$ is an infinitesimal connection defined on the principal fibre space $E_{\pi}\left(V_{n}\right)$. Let $E_{c}\left(V_{n}\right)$ be the principal fibre space consisting of all complex bases at all points of $V_{n}$, and having $G L(n, C)$ as its structure group. It is evident that $E_{\pi}\left(V_{n}\right)$ can be seen as a subspace of $E_{c}\left(V_{n}\right)$, so a local section in $E_{\pi}\left(V_{n}\right)$ can also be regarded as a local section in $E_{c}\left(V_{n}\right)$. Thus a $\pi^{-}$ connection can also be regarded as a complex linear connection, that is an infinite-
simal connection on $E_{c}\left(V_{n}\right)$. If a complex linear connection is determined by complex valued Pfaff forms ( $\omega_{j}^{i}$ ) with respect to the local section in $E_{\pi}\left(V_{n}\right)$, we say that ( $\omega_{j}^{i}$ ) defines a connection relative to the adapted basis of the $r-\pi$ structure. A complex linear connection ( $\omega_{j}$ ) defined relative to the adapted bases of the $r$ - $\pi$-structure can be regarded as a $\pi$-connection if and only if the values of the forms ( $\omega_{j}{ }^{t}$ ) belong to the Lie algebra of the structure group $G\left(n_{1}, n_{2}, \ldots\right.$ $\left.\ldots, n_{r}\right)$ of $E_{\pi}\left(V_{n}\right)$, that is to say, the following condition are satisfied:

$$
\begin{equation*}
\omega_{\bar{a}_{\alpha}}^{a_{\alpha}}=0 \quad(\alpha=1,2, \ldots \ldots, r) . \tag{8.1}
\end{equation*}
$$

Let $\nabla F_{j}{ }^{i}$ be the absolute differential of the tensor $F_{j}{ }^{i}$ with respect to the connection ( $\omega_{j}^{i}$ ), then we have

$$
\begin{equation*}
\nabla F_{j}^{i}=d F_{j}^{i}+\omega_{k}{ }^{i} F_{j}^{k}-\omega_{j}^{k} F_{k}{ }^{i} . \tag{8.2}
\end{equation*}
$$

Referring to an adapted basis of the $r$ - $\pi$-structure and then make use of (2.1) we have

$$
\begin{align*}
& \nabla F_{b_{\alpha}}^{a_{\alpha}}=\lambda w_{\alpha} \omega_{b_{\alpha}}^{a_{\alpha}}-\lambda w_{a} \omega_{b_{\alpha}}^{a_{\alpha}}=0, \\
& \nabla F_{b_{\beta}}^{a_{\alpha}}=\lambda w_{\beta} \omega_{b_{\beta}}^{a_{\alpha}}-\lambda w_{a} \omega_{b_{\beta}}^{a_{\alpha}}=\lambda\left(w_{\beta}-w_{\alpha}\right) \omega_{b_{\beta}}^{a_{\alpha}}  \tag{8.3}\\
& \quad(\alpha, \beta=1,2, \ldots \ldots, r ; \alpha \neq \beta) .
\end{align*}
$$

Therefore (8.1) is equivalent to

$$
\begin{equation*}
\nabla F_{j}^{i}=0 \tag{8.4}
\end{equation*}
$$

Thus we have the following :
THEOREM 8.1. A complex linear connection can be regarded as a $\pi$ connection if and only if the absolute differential of the tensor $F_{j}^{i}$ (the fundamental tensor of the $r$ - $\pi$-structure) with respect to the considered connection vanishes.

From (1.3) and (1.8) we have the following for the tensor fields $P_{\alpha_{j}}{ }^{i}$ induced by $\mathfrak{B}_{\alpha}$ :

$$
\begin{aligned}
F_{j}^{i} & =\lambda \sum_{\alpha=1}^{r} w_{\alpha} P_{\alpha j}^{i}, \\
P_{\alpha j}^{i} & =\frac{1}{r} \sum_{s=0}^{r-1} \frac{1}{\left(\lambda w_{a}\right)^{s}} \bar{F}_{j}^{s} .
\end{aligned}
$$

Hence (8.4) is equivalent with the following :

$$
\begin{equation*}
\nabla P_{\alpha_{j}}^{i}=0 \quad(\alpha=1, \ldots \ldots, r) \tag{8.5}
\end{equation*}
$$

From (8.6) we can see easily that a $\pi$-connection is the connection with respect to which each of the considered $r$-distributions is parallel (See Fukami [5]).

LEMMA. Let $\left(\omega_{j}^{i}\right)$ be any complex linear connection defined relative to the adapted basis of the $r$ - $\pi$-structure, then the following forms ( $\pi_{j}^{*}$ ) determine a $\pi$-connection:

$$
\begin{equation*}
\pi_{b_{\alpha}}^{a_{\alpha}}=\omega_{b_{\alpha}^{\alpha}}^{a}, \quad \pi_{\bar{a}_{\alpha}}^{a_{\alpha}}=0 ; \quad(\alpha=1, \ldots \ldots, r) . \tag{8.6}
\end{equation*}
$$

For the proof, the only thing must be shown is that ( $\pi_{i}^{i}$ ) defines a complex linear connection. But this is easily seen from its transformation rule with respect to the adapted basis.

The connection ( $\pi_{j}^{i}$ ) stated in the above lemma is called the $\pi$-connection induced by the complex linear connection ( $\omega_{g}$ ). Let

$$
\begin{equation*}
\omega_{j}^{t}=\gamma_{j k}^{i} \theta^{k}, \quad \pi_{j}^{t}=l_{j k}^{i} \theta^{k}, \tag{8.7}
\end{equation*}
$$

where ( $\theta^{t}$ ) is the dual cobasis of the adapted basis at each point defined by the considered local section.

Put

$$
\begin{equation*}
\tau_{j k}^{i}=l_{j_{k}}^{i}-\boldsymbol{\gamma}_{j k}^{i} \tag{8.8}
\end{equation*}
$$

then $\tau_{j k}^{l}$ is a tensor, and we have the following with respect to the adapted basis:

$$
\begin{equation*}
\underset{\tau_{\beta^{k}}}{a_{\alpha}}=-\gamma_{\hat{o}_{\beta^{k}},}^{a_{\alpha}} \quad \tau_{b_{\alpha^{k}}}^{a_{\alpha}}=0 \quad(\alpha \neq \beta) . \tag{8.9}
\end{equation*}
$$

As the covariant derivatives $\nabla_{k} F_{j}^{i}$ of $F_{j}^{i}$ with respect to the connection ( $\omega_{j}^{i}$ ) are defined by the following:

$$
\begin{equation*}
\nabla F_{j}^{i}=\nabla_{k} F_{j}^{i} \theta^{k} \tag{8.10}
\end{equation*}
$$

from (8.3) we have

$$
\begin{equation*}
\nabla_{k} F_{b_{\alpha}}^{a}=0, \quad \nabla_{k} F_{b_{\beta}}^{a_{\alpha}}=\lambda\left(w_{\beta}-w_{\alpha}\right) \gamma_{v_{\beta^{k}}}^{\alpha_{\alpha}} \quad(\alpha \neq \beta) \tag{8.11}
\end{equation*}
$$

Making use of (2.2) we have generally

From the above formulas we have
hence

$$
\begin{equation*}
\frac{1}{r \lambda^{r}} \sum_{s=1}^{r-1}\left(\nabla_{k}{\stackrel{s}{b_{\beta}^{c}}}_{c_{\alpha}^{\alpha}}^{r-s_{\alpha_{\alpha}}} F_{c_{\alpha}}^{a_{\alpha}}=-\gamma_{b_{\beta}^{k}}^{a_{\alpha}^{\alpha}}=\tau_{b_{\beta^{k}}^{a}}^{a_{\alpha}} \quad(\alpha \neq \beta ; \alpha, \beta=1, \ldots \ldots, r) .\right. \tag{8.13}
\end{equation*}
$$

From (8.12) we have moreover,

Therefore, it is evident that the tensor $\tau_{j k}^{i}$ has the following components in the local coordinate system :

$$
\begin{equation*}
\left.\tau_{j k}^{l}=\frac{1}{r} \frac{1}{\lambda^{r}} \sum_{s=1}^{r-1}\left(\nabla_{k} \stackrel{s}{F}_{s}^{s}\right)\right)_{l}^{r-s} . \tag{8.15}
\end{equation*}
$$

Thus we have the following:
THEOREM 8.2. Let $\gamma_{j k}^{i}$ be the parameters of a linear connection in the local coordinate system, then the following are parameters of $a \pi$-connection:

$$
\begin{equation*}
l_{j k}^{i}=\gamma_{j k}^{i}+\frac{1}{r} \frac{1}{\lambda^{r}} \sum_{s=1}^{r-1}\left(\nabla_{k} \stackrel{s}{F_{j}^{l}}\right) \stackrel{r-s}{F_{l}^{i}} . \tag{8.16}
\end{equation*}
$$

This connection is the $\pi$-connection induced by the linear connection $\gamma_{j k}^{i}$ (Tachibana [6]).

Next, let $\bar{\pi}_{j}^{t}$ be any $\pi$-connection and let $\bar{\pi}_{j}^{t}=\bar{l}_{j k}^{t} \theta^{k}$. Put

$$
\begin{equation*}
\sigma_{j k}^{i}=\overline{l_{j k}^{i}}-l_{j k}^{i}, \tag{8.17}
\end{equation*}
$$

then $\sigma_{j k}^{i}$ is a tensor. As $\bar{\pi} s_{\beta}^{a}=\pi{ }_{o_{\beta}}^{a_{\alpha}}=0$, we have following with respect to the adapted basis :

$$
\begin{equation*}
\sigma_{b_{\beta^{k}}}^{a_{\alpha}}=0 \tag{8.18}
\end{equation*}
$$

This is also the sufficient condition for $\bar{\pi}_{j}{ }^{t}$ and $\pi_{j}{ }^{t}$ be both the $\pi$-connection.
Since
with respect to adapted bases, we have

Hence it follows that

Thus if (8.18) is satisfied we have

From (8.21) and (8.22) it is evident that if $\sigma_{j k}^{i}$ satisfies (8.18), then its components with respect to a local coordinate system are as follows:

$$
\begin{equation*}
\frac{1}{r}\left(\sigma_{i k k}^{i}+\frac{1}{\lambda^{r}} \sum_{s=1}^{r-1} \stackrel{r}{F}_{j-s}^{F_{j}^{d}} \sigma_{d k}^{c} \stackrel{s}{F}_{c}^{i}\right) . \tag{8.23}
\end{equation*}
$$

Conversely, for any tensor $\sigma_{j k}^{i}$ the tensor having (8.23) as its components satisfies (8.18). Thus we have

THEOREM 8.3. Let $\gamma_{j k}^{i}$ be the parameters of a linear connection in the local coordinate system, then any $\pi$-connection can be expressed as follows:

$$
\begin{equation*}
\boldsymbol{\gamma}_{j k}^{\prime}+\frac{1}{r} \frac{1}{\lambda^{r}} \sum_{s=1}^{r-1}\left(\nabla_{k} \stackrel{s}{F_{j}^{l}}\right)^{r-s}{ }_{l}^{i}+\frac{1}{r}\left(\sigma_{j k}^{i}+\frac{1}{\lambda^{r}} \sum_{s=1}^{r-1}{ }^{r-s}{ }_{j}^{d} \sigma_{d k}^{c}{ }^{c}{ }_{F}^{s}{ }_{c}^{i}\right), \tag{8.24}
\end{equation*}
$$

where $\sigma_{j k}^{i}$ is a tensor [6].

## 9. Distinguished $\pi$-connections.

LEMMA. Let $\omega_{j}^{i}=\gamma_{j k}^{i} \theta^{k}$ be any complex linear connection defined relative to the adapted basis of the $\pi$-structure, then the following forms ( $\hat{\pi}_{j}{ }^{i}$ ) determine a $\pi$-conneciion:

For the proof, the only thing must be shown is that $\gamma_{\hat{\sigma}_{\alpha}{ }^{3}{ }^{3}{ }^{a}}$ define a tensor. But this is easily seen.

Now assume that $\omega_{j}^{i}=\boldsymbol{\gamma}_{j k}^{i} \theta^{k}$ is a symmetric linear connection (complex or real) defined relative to the adapted basis. Then as it is without torsion, we have

$$
\begin{aligned}
& d \theta^{i} \alpha=\theta^{j} \wedge \omega_{j}{ }^{,{ }^{\alpha} \alpha}
\end{aligned}
$$

Let $T^{i}$ be the torsion form of the considered $r$ - $\pi$-structure, we have

Let $\widehat{\mathfrak{F}}^{\mathbf{a}}$ be the torsion form of the $\pi$-connection $\left(\hat{\pi}_{j}{ }^{i}\right.$ ), then we have

$$
\begin{equation*}
\widehat{\mathfrak{S}}^{a_{\alpha}}=d \theta^{a}{ }_{\alpha}-\theta^{b}{ }^{b} \wedge \hat{\boldsymbol{\pi}}_{b_{\alpha}}^{a_{\alpha}} . \tag{9.4}
\end{equation*}
$$

Substituting (9.1) in the above formula, we have

$$
\begin{equation*}
\widehat{\mathfrak{S}}^{a_{\alpha}} \alpha=d \theta^{\alpha} \alpha-\theta^{b} \alpha \wedge \omega_{b_{\alpha}}^{a}-\gamma_{5_{\alpha_{\alpha}}{ }^{b}}^{a_{\alpha}} \theta^{5} \alpha \wedge \theta^{b} \alpha \tag{9.5}
\end{equation*}
$$

Then from (9.2), (9.3) and (9.5) we get

$$
\begin{equation*}
\widehat{\mathfrak{s}}^{a_{\alpha}}=T^{a_{\alpha}}, \quad \alpha=1, \ldots \ldots, r . \tag{9.6}
\end{equation*}
$$

Thus we have
THEOREM 9.1. There exists a $\pi$-connection having the torsion tensor of the considered $r$ - $\pi$-structure as its torsion tensor. Hence the $r$ - $\pi$-structure is without torsion if and only if there exists a symmetric $\pi$-connection.

The connection insisted in the above theorem is called the distinguished $\pi$ connection for the simplicity of statements.

Since $\pi$-connection is a connection with respect to which each of the $r$ distributions of the $\pi$-structure is parallel, we have from Theorem 4.1 and Theorem 9.1 the following:

COROLLARY. For an $r$ - $\pi$-structure, there exists a connection making each of the distributions parallel and moreover which is symmetric if the $\pi$-structure is integrable (See Walker [4]).

We are now in the stage of obtaining the parameters of the distinguished $\pi$-connection $\hat{\pi}_{j}^{i}=\hat{l}_{j k}^{i} \theta^{k}$ defined in (9.1). From (9.1) we have
where $\pi_{j}^{i}=l_{j k}^{i} \theta^{k}$ is the $\pi$-connection induced by the symmetric connection $\omega_{i}{ }_{i}$. Let $\mathfrak{\Im}^{i}$ be the torsion form of the $\pi$-connection $\pi_{j}{ }^{i}$, then we have

$$
\mathfrak{S}^{i}=\left(\pi_{j}^{i}-\omega_{j}^{i}\right) \wedge \theta^{j}=-\tau_{\mu k}^{i} \theta^{j} \wedge \theta^{k}
$$

From (8.9)

$$
\begin{equation*}
\mathfrak{S}^{a_{\alpha}}=\frac{1}{2}\left(\gamma_{b_{\beta} c_{\gamma}}^{a_{\alpha}}-\gamma_{c_{\gamma^{\prime} \beta}}^{a_{\alpha}}\right) \theta^{b_{\beta}} \wedge \theta^{c} \gamma+\sum_{\beta} \gamma_{o_{\beta}{ }^{c} \alpha}^{a_{\alpha}} \theta^{b_{\beta}} \wedge \theta^{c} \alpha,(\alpha \neq \beta, \alpha \neq \gamma) . \tag{9.9}
\end{equation*}
$$

Let $S_{j_{k}}^{\ell}$ be the torsion tensor of the $\pi$-connection $\left(\pi_{j}{ }^{\prime}\right)$, that is,

$$
\begin{equation*}
\mathfrak{s}^{t}=-S_{j k}^{i} \theta^{j} \wedge \theta^{k}, \quad\left(S_{j k}^{i}=-S_{k j}^{i}\right) \tag{9.10}
\end{equation*}
$$

then we have

$$
\left\{\begin{array}{l}
S_{b_{\beta^{\prime} \gamma}}^{a}=-\frac{1}{2}\left(\gamma_{b_{\beta}{ }^{c} \gamma}^{a_{\alpha}}-\gamma_{c_{\gamma_{\beta}}}^{a_{\alpha}}\right), \quad S_{b_{\beta^{c} \alpha}}^{a_{\alpha}}=-\frac{1}{2} \gamma_{b_{\beta}{ }^{c} \alpha^{\prime}}^{a_{\alpha}}  \tag{9.11}\\
S_{b_{\alpha^{c} \alpha}}^{a_{\alpha}}=0, \quad(\alpha \neq \beta, \alpha \neq \gamma) .
\end{array}\right.
$$

On the other hand, since (8.21) holds for any tensor $\sigma_{j k}^{i}$, it follows that

From these formulas, it is evident that the parameters of the distinguished connection in the local coordinates are as follows (because $\hat{l}_{j k}^{i}-l_{j k}^{i}$ is a tensor):

$$
\begin{equation*}
\hat{l}_{j k}^{l}=l_{j k}^{i}-\frac{2}{r}\left(S_{j k}^{i}+\frac{1}{\lambda^{r}} \sum_{s=1}^{r-1}{ }^{r-s}{ }_{s}^{d}{ }_{d a k}^{c} \stackrel{s}{F_{c}}{ }^{\iota}\right) \tag{9.13}
\end{equation*}
$$

Thus we have the following :
THEOREM 9.2. Let $l_{j k}^{i}$ be the $\pi$-connection induced by a symmetric connection and let $S_{j k}^{i}$ be its torsion tensor, then the connection defined in (9.13) is a distinguished $\pi$-connection (in the local coordinates).

From (9.3) we have the following expression for the torsion tensor $t_{j \boldsymbol{k}}^{i}$ $\left(T^{t}=\frac{1}{2} t_{i k}^{i} \theta^{j} \wedge \theta^{k}\right)$ of the $r-\pi$-structure:

$$
\begin{equation*}
t_{0_{\beta} c_{\gamma}}^{\alpha}=\left(\gamma_{v_{\beta} c_{\gamma}}^{a}-\gamma_{c_{\gamma^{\prime} \beta}}^{a}\right), \quad t_{b_{\alpha}{ }^{c} \beta}^{a}=0 \quad(\alpha \neq \beta, \alpha \neq \gamma) . \tag{9.14}
\end{equation*}
$$

Again from (8.21) we have

Therefore, from these formulas and (9.11), (9.14) we get

Hence it is evident that the torsion tensor of the $r-\pi$-structure has the following components in the local coordinates:

$$
\begin{equation*}
-\frac{r}{2} t_{j k}^{i}=(r-2) S_{j k}^{i}-\frac{1}{\lambda^{r}} \sum_{t=1}^{r-1}\left(\stackrel{t}{j}_{j}^{p} \delta_{k}^{q}+\delta_{j}{ }^{p} F_{k}^{t}\right) S_{p q}^{p} F_{h}^{r-t}, \tag{9.17}
\end{equation*}
$$

where $S_{j k}^{\ell}$ is the torsion tensor of the $\pi$-connection induced by a symmetric connection.
10. Some other expressions of the torsion tensor of $r$ - $\pi$-structure. Let $\nabla_{p}{ }_{p}{ }_{q}{\underset{q}{m}}^{m}$ be the covariant derivatives of the tensor $\stackrel{r-t}{F_{q}^{m}}$ with respect to the linear connection $\Gamma_{j k}^{i}$, then we have
where

$$
\begin{equation*}
S_{p q}^{h}=\frac{1}{2}\left(\Gamma_{p q}^{l}-\Gamma_{q p}^{h}\right) \tag{10.2}
\end{equation*}
$$

is the torsion tensor of the connection $\Gamma_{p q}^{\prime \prime}$.
Put (10.1) in (6.9), then by some straightforward calculation we have

$$
\begin{align*}
t_{j k}^{m} & =\frac{1}{r^{2} \lambda^{r}} \sum_{t=1}^{r-1}\left\{-r\left(\delta_{j}{ }^{p} F_{k}{ }^{q}+\delta_{k}{ }^{q} F_{j}^{t} F^{p}\right)+\frac{1}{2} \sum_{s=0}^{r-1}{ }^{s} F_{j}^{s}{ }_{j}^{s} F_{k}^{k_{1}}\left(\delta_{j_{1}}^{t-2 s} F_{k_{1}}^{q}\right.\right. \\
& \left.\left.+\delta_{k_{1}}^{t-2 s} F_{j_{1}}^{p}\right)\right\}\left(\nabla_{p} F_{q}{ }^{r-t}-\nabla_{q}{ }^{r-t} F_{p}{ }^{m}\right)+\frac{2}{r^{2} \lambda^{r}} \sum_{t=1}^{r-1}\left\{-r\left(\delta_{j}{ }^{p} F_{k}{ }^{q}{ }^{q}+\delta_{k}{ }^{q} F_{j}^{t}{ }^{p}\right)\right. \tag{10.3}
\end{align*}
$$

Thus, if $\Gamma_{j k}^{i}$ is symmetric we have

By some straightforward calculation, the right hand side of the above formula can also be written as follows:

If $\Gamma_{j k}^{i}$ is a $\pi$-connection, we have

$$
\begin{equation*}
+\frac{1}{r^{3} \lambda^{r}}\left\{(r-1)(2 r-1) \lambda^{r} S_{j k}^{m}+r \sum_{t=1}^{r-1} F_{j}^{t}{ }^{p}{ }^{r-t} F_{k}{ }^{G} S_{p q}^{m}-\sum_{t=1}^{r-1} \sum_{s=1}^{r-1} F_{j}^{t-s} F_{k}^{r-t+s} F_{k q}{ }^{q} S_{p q}^{m}\right\} \tag{10.6}
\end{equation*}
$$

As it can be seen by some simple calculations, the right hand side of the above formula can also be written as follows:

Or more simply,

$$
\begin{equation*}
t_{j k}^{m}=\frac{2(r-1)^{2}}{r^{2}} \Phi \Phi^{\prime} S_{j k p}^{m} \tag{10.8}
\end{equation*}
$$

where the operations $\Phi$ and $\Phi^{\prime}$ are defined as follows:

$$
\begin{align*}
& \left.+\frac{1}{2} \sum_{t=1}^{r-2} \sum_{s=t+1}^{r-1}\left(\stackrel{s}{F_{j}}{ }^{t-s} F_{k}{ }^{q}+\stackrel{s}{F_{k}}{ }_{k}{ }^{t-s}{ }_{j}{ }_{j}{ }^{p}\right)\right\}\left(\nabla_{p} \stackrel{F}{F}_{q}{ }^{m}-\nabla_{q}{ }_{a} F_{p}{ }^{m}\right) . \tag{10.5}
\end{align*}
$$

$$
\begin{align*}
& t_{j k}^{m}=\frac{1}{r^{2} \lambda^{r}} \sum_{t=1}^{r-1}\left\{-r\left(\delta_{j}{ }^{p}{ }^{t}{ }_{k}{ }^{q}+\delta_{k}{ }^{q}{ }^{t}{ }_{j}{ }^{p}\right)\right. \\
& \left.+\frac{1}{2} \sum_{s=0}^{r-1}{ }^{s}{ }_{j}^{j_{j}}{ }^{s} F_{k}^{k_{1}}\left(\delta_{j_{1}}^{v} F_{k_{1}}^{p}+\delta_{k_{1}}^{q} F_{j_{1}}^{t-2 s}\right)\right\}\left(\nabla_{p}{ }_{p}^{r-t}{ }_{q}{ }^{m}-\nabla_{q}{ }_{q}^{r-t}{ }_{p}{ }^{m}\right) . \tag{10.4}
\end{align*}
$$

$$
\begin{aligned}
& \left.+\frac{1}{2} \sum_{s=0}^{r=1} F_{F_{1}^{\prime}}^{s} F_{k}^{s k_{1}}\left(\delta_{j_{1}}^{t-2 s} F_{k_{1}}^{s}+\delta_{k_{1}}^{q} F_{j_{1}}^{t-2 s}\right)\right\} S_{p_{1}}^{r} F_{h}^{r-t}{ }^{m}+\frac{1}{r^{2} \lambda^{r}}\left\{(r-1)(2 r-1) \lambda^{r} S_{j k}^{m}\right.
\end{aligned}
$$

$$
\begin{align*}
& \Phi S_{j k}^{m}=S_{j k}^{m}-\frac{1}{r-1} \frac{1}{\lambda^{r}} \sum_{s=1}^{r-1} \stackrel{F}{k}_{k_{1}}^{s} S_{j k_{1}}^{h} F_{h}^{r-s}{ }^{m}  \tag{10.9}\\
& \Phi^{\prime} S_{j k}^{m}=S_{j k}^{m}-\frac{1}{r-1} \frac{1}{\lambda^{r}} \sum_{s=1}^{r-1} F_{j}^{s} S_{j_{1 k}}^{n} \stackrel{r-s}{r-s} F_{h}^{m} . \tag{10.10}
\end{align*}
$$

Finally we add a remark: Denote

$$
\begin{equation*}
\varphi \circ \stackrel{s}{N} \equiv \stackrel{s}{C} d \varphi+d \stackrel{s}{C} \stackrel{s}{M} \varphi-\stackrel{s}{M} d \stackrel{s}{C} \varphi ; \quad s=1, \ldots \ldots, r-1, \tag{10.11}
\end{equation*}
$$

where $\varphi$ is any 1 -form. Then it can be easily seen that for the cases $r=3,4$, $5,6, \varphi \circ T$ can be expressed by $\varphi \circ N^{s}(s=1, \ldots \ldots, r-1)$. For example, we have

But the same does not hold good generally. For example, it is easily shown that for the case $r=7, \varphi \circ T$ can not be expressed by the same way.
11. Characteristic forms of $r$ - $\pi$-structure. Groups of holonomy. Following Legrand [2] we can define the characteristic forms of $r-\pi$-structure and obtain some analogous results. Let $\left(\pi_{j}^{l}\right)$ be a $\pi$-connection defined relative to the adapted bases of the considered local section. Its curvature forms are as follows:

$$
\begin{equation*}
\Omega_{j}^{i}=d \pi_{j}^{i}+\pi_{k}^{i} \wedge \pi_{j}^{k} \tag{11.1}
\end{equation*}
$$

where $\pi_{a_{\alpha}}^{a_{\alpha}}=0(\alpha=1, \ldots \ldots, r)$. Put

$$
\begin{equation*}
\psi_{\alpha}=\lambda w_{\alpha} \Omega_{a_{\alpha}}^{a_{\alpha}} \quad(\alpha=1, \ldots \ldots, r) \tag{11.2}
\end{equation*}
$$

then it is easily seen that each of the 2 -forms $\psi_{a}$ (called the characteristic forms of the $\pi$-connection) is closed and that the cohomology class of the characteristic form $\psi_{x}$ is independent of the $\pi$-connection used. Moreover, it is also easily seen that $\frac{1}{w_{1}} \psi_{1}+\cdots \cdots+\frac{1}{w_{r}} \psi_{r}$ is homologous to zero.

It is trivial that for the manifold having an $r-\pi$-structure the group of holonomy with respect to an adapted basis is the subgroup of $G\left(n_{1}, n_{2}, \ldots \ldots, n_{r}\right)$. In relation to the characteristic forms of the $\pi$-connection, the following theorem is easily proved:

THEOREM 11.1. For the restricted homogeneous group of holonomy to be a subgroup of $S_{\alpha} G\left(n_{1}, \ldots \ldots, n_{r}\right)$, it is necessary and sufficient that the $\alpha$-th characteristic form $\psi_{\alpha}$ vanishes on $V_{n}$.

In the statement of the above theorem, $S_{\alpha} G\left(n_{1}, \ldots \ldots, n_{r}\right)$ means a group consisting of the elements of the form :

$$
\left(\begin{array}{cccc}
A_{1} & & & \\
A_{2} & & & 0 \\
& \cdot & \cdot & \\
0 & & & A_{r}
\end{array}\right)
$$

in which the determinant of $A_{\alpha}$ ( $\alpha$ : fixed) is equal to 1 .
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