A CHARACTERIZATION OF CONTACT TRANSFORMATIONS

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1. Introduction. Let M^{2n+1} be a contact manifold with a contact form η [2], [3]. By definition, η satisfies the relation

(1)
$$\eta \wedge \overbrace{d\eta \wedge \cdots \wedge d\eta}^{n} \neq 0,$$

where d means the exterior differentiation and \wedge means the exterior multiplication. The Pfaffian equation

$$(2) \qquad \eta = 0$$

determines in M^{2n+1} a 2*n*-dimensional distribution D which we shall call the *contact distribution*. We say that a tangent vector X of M^{2n+1} belongs to the distribution D if and only if

$$\eta(X) = 0$$

is satisfied.

An r-dimensional submanifold F in M^{2n+1} is said to be an *integral submanifold* (of the contact distribution D) if and only if every tangent vector of F at every point p of F belongs to D. An integral submanifold of dimension r in M^{2n+1} is said to be a maximal integral submanifold if it is not a pure subset of any other integral submanifold of dimension r.

A diffeomorphism of M^{2n+1} is said to be a *contact transformation* [3] of M^{2n+1} if and only if

$$(4) f_*\eta = \sigma\eta$$

holds good, where f_* is the dual map of f which acts on the vector space of 1-forms of M^{2n+1} and σ is a function over M^{2n+1} which does not vanish at any point of M^{2n+1} .

The purpose of this paper is to prove Theorem B which characterizes contact transformations. Theorem A on the highest dimension of integral submanifold of D is given as a preliminary of Theorem B.

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THEOREM A. Let M^{2n+1} be a contact manifold. Then the highest dimension of integral submanifolds of the contact distribution D is equal to n.

THEOREM B. A diffeomorphism f of a contact manifold M^{2n+1} transforms every integral submanifold of D of the highest dimension to another such if and only if f is a contact transformation of M^{2n+1} .

2. Proof of Theorem A. First we shall show the existence of *n*-dimensional integral submanifolds of *D*. By virtue of a theorem of E. Cartan [1] every point p of M^{2n+1} has a neighborhood U with local coordinates $(x^{\alpha}, y^{\alpha}, z)$ $(\alpha=1, 2, \dots, n)$ such that the contact form η can be written as

(5)
$$\eta = dz - \sum y^{\alpha} dx^{\alpha}$$

in U. We call such local coordinates as adapted local coordinates for brevity. In U, we can give as an example a piece of *n*-dimensional integral submanifold F of D containing p defined by $x^{\alpha} = x_0^{\alpha}$, $z = z_0$ where $(x_0^{\alpha}, y_0^{\alpha}, z_0)$ are local coordinates of p.

A maximal integral submanifold of dimension n which contains F as a pure subset gives an example of a global integral submanifold of dimension n.

Secondly, we shall show that there exists no integral submanifold of D whose dimension is higher than n. To prove it, we introduce a contact metric structure (ϕ, ξ, η, g) associated to the contact form [3]. They satisfy the relations

(6)
$$\begin{cases} \phi_{j}^{i}\xi^{j} = 0, \quad \phi_{j}^{i}\eta_{i} = 0, \\ \xi^{i}\eta_{i} = 1, \quad \phi_{j}^{i}\phi_{k}^{j} = -\delta_{k}^{i} + \xi^{i}\eta_{k} \\ \eta_{i} = g_{ij}\xi^{j} \\ g_{ij}\phi_{h}^{i}\phi_{k}^{j} = g_{hk} - \eta_{h}\eta_{k}. \end{cases}$$

Suppose F were an integral submanifold of dimension r and

(7)
$$x^i = x^i(u^1, u^2, \cdots, u^r)$$
 $(i, j = 1, 2, \cdots, 2n+1)$

were a local parametric representation of F. Then, as every tangent vector of F belongs to D, we have

(8)
$$\eta_i X^i_{\lambda} = 0 \qquad \left(X^i_{\lambda} = \frac{\partial x^i}{\partial u^{\lambda}}\right) \qquad (\lambda, \mu = 1, \cdots, r),$$

where $\eta = \eta_i dx^i$. Differentiating the last equation with respect to u^{μ} , and subtracting the equation obtained by interchanging λ and μ from the last equation, we have

(9)
$$\phi_{ij} X_{\lambda}^{i} X_{\mu}^{j} = 0$$
,

where ϕ_{ij} is given by

(10)
$$\phi_{ij} = g_{ih} \phi_j^h = \frac{\partial \eta_j}{\partial x^i} - \frac{\partial \eta_i}{\partial x^j}.$$

As (9) can be written as

$$g_{ih}(\phi_j^h X_\mu^j) X_\lambda^i = 0,$$

the vector X_{λ}^{i} and $\phi_{j}^{i}X_{\mu}^{j}$ are othogonal. On the other hand we can easily see from (6)₅ and (6)₁ that ξ^{i} are orthogonal to X_{λ}^{i} and $\phi_{j}^{i}X_{\mu}^{j}$. Hence (2r+1)vectors ξ^{i} , X_{λ}^{i} , $\phi_{j}^{i}X_{\mu}^{j}$ are linearly independent. Therefore we see that $r \leq n$.

3. Integral element. We consider adapted local coordinates $(x^{\alpha}, y^{\alpha}, z)$ around a point p of M^{2n+1} and suppose $(x_0^{\alpha}, y_0^{\alpha}, z_0)$ are coordinates of p. Then, we have the following

LEMMA 1. In order that r sets of values $(a_{\lambda}^{\alpha}, b_{\lambda}^{\alpha}, c_{\lambda})$ $(\lambda, \mu = 1, 2, \dots, r)$ are components of linearly independent tangent vectors at p of an integral submanifold of dimension r through p, it is necessary and sufficient that

(11)
$$c_{\lambda} = \sum y_0^{\alpha} a_{\lambda}^{\alpha},$$

(12)
$$\sum a^{\alpha}_{\lambda} b^{\alpha}_{\mu} = \sum a^{\alpha}_{\mu} b^{\alpha}_{\lambda},$$

 $\eta_i = (-y^{\alpha}, 0, 1)$,

are satisfied.

PROOF. As

(13)

	(1	if	j=n+i	$(1 \leq i \leq n),$
(14)	$\phi_{ij} = \left\{ \right.$	-1	if	i=n+j	$(1 \leq i \leq n),$ $(1 \leq j \leq n),$
		0	otherwise		

in adapted local coordinates, the necessity of the lemma is clear from (8) and (9).

To prove the sufficiency, we put

(15)
$$\begin{cases} x^{\alpha} = x_{0}^{\alpha} + \sum a_{\lambda}^{\alpha} u^{\lambda}, \\ y^{\alpha} = y_{0}^{\alpha} + \sum b_{\lambda}^{\alpha} u^{\lambda}, \\ z = z_{0} + \sum c_{\lambda} u^{\lambda} + \frac{1}{2} \sum c_{\lambda \mu} u^{\lambda} u^{\mu}, \end{cases}$$

where

(16)
$$c_{\lambda\mu} = \sum a_{\lambda}^{\alpha} b_{\mu}^{\alpha} = \sum a_{\mu}^{\alpha} b_{\lambda}^{\alpha} .$$

Then, we can easily see that

(17)
$$\frac{\partial z}{\partial u^{\lambda}} = \sum y^{\alpha} \frac{\partial x^{\alpha}}{\partial u^{\lambda}}$$

is satisfied identically is u^{λ} . Hence, (15) gives an integral submanifold of D admitting $(a_{\lambda}^{\alpha}, b_{\lambda}^{\alpha}, c_{\lambda})$ as tangent vectors at $p(u^{\lambda} = 0)$. Q.E.D.

[N. B.] The integral submanifolds which have $(a_{\lambda}^{\alpha}, b_{\lambda}^{\alpha}, c_{\lambda})$ as tangent vectors at p are not unique, because the condition to be an integral submanifold is too weak.

In the proof of Theorem A, we saw that if X_{λ}^{i} ($\lambda = 1, 2, \dots, r$) are tangent vectors of an integral submanifold of D at a point p, then X_{λ}^{i} satisfy (8) and (9).

Conversely, if X_{λ}^{i} ($\lambda=1, 2, \dots, r$) are linearly independent tangent vectors of M^{2n+1} at a point p satisfying (8) and (9), then there exists an integral submanifold F^{r} which has these vectors as tangent vectors. This can be easily seen by taking adapted local coordinates around p and applying Lemma 1. Hence, we see that the following lemma is true.

LEMMA 2. In order that r linearly independent vectors X_{λ}^{i} ($\lambda = 1, 2, \cdots$ \cdot, r) at a point p of M^{2n+1} are tangent vectors of an integral submanifold of dimension r of the distribution D, it is necessary and sufficient that (8) and (9) hold at p.

We say that an r-space determined by r linearly independent vectors X_{λ}^{i} at a point p of M^{2n+1} satisfying (8) and (9) as an r-dimensional *integral* element of D.

4. Proof of Theorem B.

LEMMA 3. Let X be a tangent vector of a contact manifold M^{2n+1}

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belonging to the contact distribution D at a point p of M^{2n+1} . Then, there exists an r-dimensional integral submanifold F of D through p $(1 \le r \le n)$ such that X is a tangent vector of F at p.

PROOF. We take a neighborhood containing p and adapted local coordinates $(x^{\alpha}, y^{\alpha}, z)$. Suppose $(x_0^{\alpha}, y_0^{\alpha}, z_0)$ are coordinates of the point p and $(a_1^{\alpha}, b_1^{\alpha}, c_1)$ are components of the vector X with respect to the adapted coordinates. As X belongs to the distribution D there exists a relation

$$(18) c_1 = \sum y_0^{\alpha} a_1^{\alpha}$$

First, suppose $a_1^{\alpha} \neq 0$ and we will show that we can take (r-1) vectors $(a_{\rho}^{\alpha}, b_{\rho}^{\alpha}, c_{\rho})$ $(p = 2, \dots, r)$ so that they and $(a_1^{\alpha}, b_1^{\alpha}, c_1)$ together span an *r*-dimensional integral element of *D*. To do so, we take $a_2^{\alpha}, \dots, a_r^{\alpha}$ so that

(19)
$$\operatorname{rank} (a_{\lambda}^{\alpha}) = r \qquad (\lambda = 1, 2, \cdots, r),$$

and define c_2, \dots, c_r by (11) for $\lambda = 2, \dots, r$. Then, (11) holds good for $\lambda = 1, 2, \dots, r$.

We determine $b_2^{\alpha}, \dots, b_r^{\alpha}$ inductively. Assuming that $b_1^{\alpha}, \dots, b_{\sigma}^{\alpha}$ $(1 \leq \sigma \leq r-1)$ is already determined, we take $b_{\sigma+1}^{\alpha}$ as a set of solutions of

(20)
$$\begin{cases} \sum a_1^{\alpha} x^{\alpha} = \sum a_{\sigma+1}^{\alpha} b_1^{\alpha}, \\ \cdots \\ \sum a_{\sigma}^{\alpha} x^{\alpha} = \sum a_{\sigma+1}^{\alpha} b_{\sigma}^{\alpha}, \end{cases}$$

as these equations admit solutions by (19). Then we can see that the constants a^{α}_{λ} , b^{α}_{λ} , c_{λ} thus determined satisfy (12) for λ , $\mu=1, 2, \dots, r$. So $(a^{\alpha}_{\lambda}, b^{\alpha}_{\lambda}, c_{\lambda})$ define an *r*-dimensional integral element containing *X*.

Secondly, if $a_1^{\alpha}=0$ then we have $c_1=0$ by (18). In this case $(0, b_{\lambda}^{\alpha}, 0)$ such that rank $(b_{\lambda}^{\alpha})=r$ determine an r-dimensional integral element containing X.

Hence, in any case there exists an integral submanifold of demension r of D which satisfies the required property by § 3.

[N. B.] The case r=n of Lemma 3 is used in the proof of Theorem B.

LEMMA 4. If a diffeomorphism f of a contact manifold M^{2n+1} with a contact form η transforms every tangent vector X belonging to the contact distribution D again to such one, then f is a contact transformation. **PROOF.** We put f(p) = q, $X_p \in D$ and

$$(21) X_q = f' X_p,$$

where f' is the induced map of the tangent space M_p at p onto the tangent space M_q at q by f. Then, as X_q belongs to D by assumption,

(22)
$$0 = \eta(X_q) = \eta(f' X_p) = (f_* \eta)(X_p),$$

where f_* is the dual map of f which acts on the vector space of 1-forms at q. As the last equation holds good for every tangent vector X_p of M_p belonging to D we see that the relation

$$(23) f_* \eta = \sigma \eta$$

holds good at p. As p is a general point of M^{2n+1} , (23) shows that f is a contact transformation of M^{2n+1} .

PROOF OF THEOREM B. We put f(p) = q and take an arbitrary tangent vector X_p of M_p belonging to D. By Lemma 3, there exists an *n*-dimensional integral submanifold F of D such that $p \in F$ and X_p is a tangent vector of F at p. Now, by assumption f transforms F to an *n*-dimensional integral submanifold fF of D. As $X_q = f' X_p$ is a tangent vector of fF, X_q belongs to D. Hence, by Lemma 4, f is a contact transformation of M^{2n+1} .

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