

ON AUTOMORPHISM GROUPS OF SOME CONTACT RIEMANNIAN MANIFOLDS

MAKOTO NAMBA

(Received September 25, 1967)

1. Introduction. Recently Dr. S. Tanno offered the author a conjecture that the dimension of the automorphism group of a contact Riemannian manifold of dimension $2n+1$ will not exceed $(n+1)^2$. It has been proved that the unit sphere S^{2n+1} with the standard Sasakian structure has the automorphism group of dimension $(n+1)^2$. ([3]). In this paper, we shall examine the conjecture for some kinds of contact Riemannian manifolds. Especially, we shall prove that the dimension of the automorphism group of Euclidean space E^{2n+1} with its standard contact metric structure is just $(n+1)^2$.

The author wishes to express his gratitude to Dr. S. Tanno for his suggestions.

2. Expressions in adapted local coordinate systems. A differentiable manifold M of dimension $2n+1$ is called a contact Riemannian manifold, [2], if it admits a vector field ξ , a 1-form η , a 1-1 tensor field Φ and a Riemannian metric G such that

$$(2.1) \quad \eta(\xi) = 1,$$

$$(2.2) \quad \Phi^2 + 1 = \xi \otimes \eta,$$

$$(2.3) \quad G(\xi, X) = \eta(X),$$

$$(2.4) \quad G(\Phi X, \Phi Y) = G(X, Y) - \eta(X)\eta(Y),$$

$$(2.5) \quad G(X, \Phi Y) = d\eta(X, Y) = \frac{1}{2} \{X\eta(Y) - Y\eta(X) - \eta[X, Y]\},$$

where X and Y are vector fields.

Let M be a contact Riemannian manifold of dimension $2n+1$ with ξ , η , Φ and G . A vector field X on M is called an infinitesimal automorphism if

$$(2.6) \quad L_X \eta = 0$$

and

$$(2.7) \quad L_X G = 0,$$

where L_X is the Lie derivative with respect to X . (2.6) indicates that X is an infinitesimal strict contact transformation and (2.7) indicates that X is a Killing vector field.

Let P be a point of M . As is well known, we can take a coordinate system $x^1, \dots, x^n, y^1, \dots, y^n, z$, called an adapted coordinate system such that

$$(2.8) \quad \eta = dz - \Sigma y^\alpha dx^\alpha$$

and

$$x^1(p) = \dots = x^n(p) = y^1(p) = \dots = y^n(p) = z(p) = 0.$$

We express above (2.1). (2.7) by means of this coordinate system. For convenience, we write $\partial_\alpha, \partial_{\alpha^*}, \partial_\Delta$ for $\frac{\partial}{\partial x^\alpha}, \frac{\partial}{\partial y^\alpha}, \frac{\partial}{\partial z}$ and indices vary from 1 to n . At first by direct calculations we can see

$$(2.9) \quad \xi = \partial_\Delta.$$

Put

$$(2.10) \quad \begin{aligned} \Phi(\partial_\alpha) &= \phi_\alpha^\beta \partial_\beta + \phi_\alpha^{\beta^*} \partial_{\beta^*} + \phi_\alpha^\Delta \partial_\Delta, \\ \Phi(\partial_{\alpha^*}) &= \phi_{\alpha^*}^\beta \partial_\beta + \phi_{\alpha^*}^{\beta^*} \partial_{\beta^*} + \phi_{\alpha^*}^\Delta \partial_\Delta, \\ \Phi(\partial_\Delta) &= 0 \end{aligned}$$

and

$$(2.11) \quad \begin{aligned} G(\partial_\alpha, \partial_\beta) &= g_{\alpha\beta}, & G(\partial_\alpha, \partial_{\beta^*}) &= g_{\alpha\beta^*}, \\ G(\partial_{\alpha^*}, \partial_{\beta^*}) &= g_{\alpha^*\beta^*}, & G(\partial_\alpha, \partial_\Delta) &= g_{\alpha\Delta}, \\ G(\partial_{\alpha^*}, \partial_\Delta) &= g_{\alpha^*\Delta}, & G(\partial_\Delta, \partial_\Delta) &= g_{\Delta\Delta}. \end{aligned}$$

Then (2.2) is equivalent to

$$(2.12) \quad \begin{aligned} \phi_\alpha^r \phi_r^\beta + \phi_{\alpha^*}^{r^*} \phi_{r^*}^\beta &= -\delta_\alpha^\beta && \text{Kronecker's delta,} \\ \phi_\alpha^r \phi_r^{\beta^*} + \phi_{\alpha^*}^{r^*} \phi_{r^*}^{\beta^*} &= 0, \\ \phi_{\alpha^*}^r \phi_r^\beta + \phi_{\alpha^*}^{r^*} \phi_{r^*}^\beta &= 0, \\ \phi_{\alpha^*}^r \phi_r^{\beta^*} + \phi_{\alpha^*}^{r^*} \phi_{r^*}^{\beta^*} &= -\delta_{\alpha^*}^{\beta^*}, \end{aligned}$$

$$\begin{aligned}\phi_\alpha^r \phi_r^d + \phi_\alpha^{r*} \phi_r^d &= -y^\alpha, \\ \phi_{\alpha^*}^r \phi_r^d + \phi_{\alpha^*}^{r*} \phi_r^d &= 0\end{aligned}$$

and (2.3), (2.5) are equivalent to

$$\begin{aligned}g_{\alpha\beta} &= -\frac{1}{2}\phi_\alpha^{\beta*} + y^\alpha y^\beta, \quad \phi_\alpha^{\beta*} = \phi_\beta^{\alpha*}, \\ g_{\alpha\beta^*} &= \frac{1}{2}\phi_\alpha^\beta = -\frac{1}{2}\phi_{\beta^*}^{\alpha*}, \\ (2.13) \quad g_{\alpha^*\beta^*} &= \frac{1}{2}\phi_{\alpha^*}^\beta, \quad \phi_{\alpha^*}^\beta = \phi_{\beta^*}^{\alpha^*}, \\ g_{\alpha d} &= -y^\alpha, \\ g_{\alpha^* d} &= 0, \\ g_{dd} &= 1.\end{aligned}$$

Thus

$$G = \begin{pmatrix} -\frac{1}{2}\phi_\alpha^{\beta*} + y^\alpha y^\beta & \frac{1}{2}\phi_\alpha^\beta & -y^\alpha \\ \frac{1}{2}\phi_\beta^{\alpha^*} & \frac{1}{2}\phi_{\alpha^*}^\beta & 0 \\ -y^\beta & 0 & 1 \end{pmatrix}.$$

Let $X = a^\alpha \partial_\alpha + a^{\alpha^*} \partial_{\alpha^*} + a^d \partial_d$ be a vector field. The condition $L_X \eta = 0$ is expressed as follows:

$$\begin{aligned}(2.14) \quad y^r \partial_\alpha a^r - \partial_\alpha a^d + a^{\alpha^*} &= 0, \\ y^r \partial_{\alpha^*} a^r - \partial_{\alpha^*} a^d &= 0, \\ y^r \partial_d a^r - \partial_d a^d &= 0.\end{aligned}$$

Differentiating (2.14), we obtain

$$\begin{aligned}(2.15) \quad \partial_d a^\alpha &= 0, \quad \partial_d a^{\alpha^*} = 0, \quad \partial_d a^d = 0 \\ \partial_\alpha a^{\beta^*} &= \partial_\beta a^{\alpha^*}, \\ \partial_{\alpha^*} a^\beta &= \partial_{\beta^*} a^\alpha, \\ \partial_\alpha a^\beta + \partial_{\beta^*} a^{\alpha^*} &= 0.\end{aligned}$$

(First three equations indicate that coefficients of X do not depend on z)
 The condition $L_X G = 0$ is expressed as follows :

$$\begin{aligned}
 & -\frac{1}{2} X \phi_{\alpha}^{\beta*} + a^{\alpha*} y^{\beta} + a^{\beta*} y^{\alpha} = \frac{1}{2} \phi_{\alpha}^{\beta*} \partial_{\alpha} a^r - \frac{1}{2} \phi_{\beta}^r \partial_{\alpha} a^{r*} \\
 & + \frac{1}{2} \phi_r^{\alpha*} \partial_{\beta} a^r - \frac{1}{2} \phi_{\alpha}^r \partial_{\beta} a^{r*} - y^r y^{\beta} \partial_{\alpha} a^r + y^{\beta} \partial_{\alpha} a^d \\
 & - y^r y^{\alpha} \partial_{\beta} a^r + y^{\alpha} \partial_{\beta} a^d, \\
 & \frac{1}{2} X \phi_{\alpha}^{\beta} = -\frac{1}{2} \phi_r^{\beta} \partial_{\alpha} a^r - \frac{1}{2} \phi_r^{\beta*} \partial_{\alpha} a^{r*} + \frac{1}{2} \phi_{\alpha}^r \partial_{\beta} a^r \\
 & - \frac{1}{2} \phi_{\alpha}^r \partial_{\beta} a^{r*} - y^{\alpha} (y^r \partial_{\beta} a^r - \partial_{\beta} a^d), \\
 (2.16) \quad & \frac{1}{2} X \phi_{\alpha}^{\beta*} = -\frac{1}{2} \phi_r^{\beta} \partial_{\alpha} a^r - \frac{1}{2} \phi_r^{\beta*} \partial_{\alpha} a^{r*} - \frac{1}{2} \phi_r^{\alpha} \partial_{\beta} a^r \\
 & - \frac{1}{2} \phi_r^{\alpha*} \partial_{\beta} a^{r*}, \\
 & -a^{\alpha*} = y^r \partial_{\alpha} a^r - \partial_{\alpha} a^d + \frac{1}{2} \phi_r^{\alpha*} \partial_{\alpha} a^r - \frac{1}{2} \phi_{\alpha}^r \partial_{\alpha} a^{r*} \\
 & - y^{\alpha} (y^r \partial_{\alpha} a^r - \partial_{\alpha} a^d), \\
 & 0 = y^r \partial_{\alpha} a^r - \partial_{\alpha} a^d - \frac{1}{2} \phi_r^{\alpha} \partial_{\alpha} a^{r*} - \frac{1}{2} \phi_r^{\alpha*} \partial_{\alpha} a^r, \\
 & y^r \partial_{\alpha} a^r = \partial_{\alpha} a^d.
 \end{aligned}$$

Connecting (2.14), (2.15) and (2.16), we conclude that the conditions that an infinitesimal strict contact transformation X is to be an infinitesimal automorphism are

$$\begin{aligned}
 (2.17) \quad & X \phi_{\alpha}^{\beta*} = -\phi_r^{\beta*} \partial_{\alpha} a^r + \phi_{\beta}^r \partial_{\alpha} a^{r*} - \phi_{\alpha}^{\alpha*} \partial_{\beta} a^r + \phi_{\alpha}^r \partial_{\beta} a^{r*}, \\
 & X \phi_{\alpha}^{\beta} = -\phi_r^{\beta} \partial_{\alpha} a^r - \phi_r^{\beta*} \partial_{\alpha} a^{r*} + \phi_{\alpha}^{\alpha*} \partial_{\beta} a^r - \phi_{\alpha}^r \partial_{\beta} a^{r*}, \\
 & X \phi_{\alpha}^{\beta*} = -\phi_r^{\beta} \partial_{\alpha} a^r - \phi_r^{\beta*} \partial_{\alpha} a^{r*} - \phi_{\alpha}^{\alpha} \partial_{\beta} a^r - \phi_{\alpha}^{\alpha*} \partial_{\beta} a^{r*}.
 \end{aligned}$$

By Libermann [1], there is a one-to-one correspondence between infinitesimal strict contact transformations and differentiable functions of $x^1, \dots, x^n, y^1, \dots, y^n$. This correspondence is given by

$$\begin{aligned}
 f & \longrightarrow X_f = (\partial_{\alpha^*} f) \partial_{\alpha} - (\partial_{\alpha} f) \partial_{\alpha^*} + (y^{\alpha} \partial_{\alpha^*} f - f) \partial_{\alpha}, \\
 X & \longrightarrow -\eta(X) = \Sigma a^{\alpha} y^{\alpha} - a^d.
 \end{aligned}$$

Substituting X_f for X in (2.17), we obtain

$$\begin{aligned}
 X_f \phi_\alpha^{\beta*} &= (-\phi_r^{\beta*} \partial_\alpha \partial_{r^*} - \phi_\beta^r \partial_\alpha \partial_r - \phi_r^{\alpha*} \partial_\beta \partial_{r^*} - \phi_\alpha^r \partial_\beta \partial_r) f, \\
 (2.18) \quad X_f \phi_\alpha^\beta &= (-\phi_r^\beta \partial_\alpha \partial_{r^*} + \phi_{r^*}^\beta \partial_\alpha \partial_r + \phi_\alpha^{r*} \partial_\beta \partial_{r^*} + \phi_\alpha^r \partial_\beta \partial_r) f, \\
 X_f \phi_{\alpha^*}^\beta &= (-\phi_r^\beta \partial_{\alpha^*} \partial_{r^*} + \phi_{r^*}^\beta \partial_{\alpha^*} \partial_r - \phi_r^\alpha \partial_\beta \partial_{r^*} + \phi_{r^*}^\alpha \partial_\beta \partial_r) f.
 \end{aligned}$$

3. Calculations of dimensions. We impose on Φ following conditions for the convenience of calculations. Let v be an everywhere non-zero function of $x^1, \dots, x^n, y^1, \dots, y^n, z$. Let

$$\begin{aligned}
 (3.1) \quad \phi_\alpha^{\beta*} &= -\delta_{\alpha\beta} v, \quad \phi_{\alpha^*}^\beta = \delta_{\alpha\beta} \frac{1}{v}, \quad \phi_\alpha^\beta = 0, \\
 \phi_{\alpha^*}^\beta &= 0, \quad \phi_{\alpha^*}^\alpha = \frac{1}{v} y^\alpha, \quad \phi_\alpha^\alpha = 0,
 \end{aligned}$$

and so

$$G = \begin{bmatrix} \frac{\delta_{\alpha\beta}}{2} v + y^\alpha y^\beta & 0 & -y^\alpha \\ 0 & \frac{\delta_{\alpha\beta}}{2v} & 0 \\ -y^\beta & 0 & 1 \end{bmatrix}.$$

By this (2.12) still holds and hence we have a contact Riemannian structure.

Remark 1. The case $v \equiv 1$ is just the standard contact Riemannian structure of E^{2n+1} .

Now (2.18), in this case, reduces to

$$\begin{aligned}
 (3.2) \quad -\delta_{\alpha\beta} X_f v &= v(\partial_\alpha \partial_\beta + \partial_\beta \partial_\alpha) f, \\
 0 &= (-\partial_\alpha \partial_\beta + v^2 \partial_{\alpha^*} \partial_{\beta^*}) f.
 \end{aligned}$$

CASE 1^o. When v is non-zero constant. In this case, (3.2) is

$$(3.3) \quad \begin{aligned} \partial_\alpha \partial_{\beta^*} f &= -\partial_\beta \partial_{\alpha^*} f, \\ \partial_\alpha \partial_\beta f &= v^2 \partial_{\alpha^*} \partial_{\beta^*} f. \end{aligned}$$

Differentiating the last equation and using the first equation,

$$\partial_\alpha \partial_\beta \partial_r f = v^2 \partial_\alpha \partial_{\beta^*} \partial_{r^*} f = -v^2 \partial_\beta \partial_{\alpha^*} \partial_{r^*} f = -\partial_\alpha \partial_\beta \partial_r f.$$

Hence $\partial_\alpha \partial_\beta \partial_r f = \partial_\alpha \partial_{\beta^*} \partial_{r^*} f = 0$. In the same way, $\partial_{\alpha^*} \partial_{\beta^*} \partial_{r^*} f = \partial_{\alpha^*} \partial_\beta \partial_r f = 0$. Thus, if we expand f in formal power series, terms of degree more than two vanish. On the other hand, if we put

$$\begin{aligned} f &= f_0 + f_\alpha x^\alpha + f_{\alpha^*} y^\alpha + \frac{1}{2} f_{\alpha\beta} x^\alpha x^\beta + f_{\alpha\beta^*} x^\alpha y^\beta + \frac{1}{2} f_{\alpha^*\beta^*} y^\alpha y^\beta, \\ f_{\alpha\beta} &= f_{\beta\alpha} \text{ and } f_{\alpha^*\beta^*} = f_{\beta^*\alpha^*}, \end{aligned}$$

then by (3.3), $f_{\alpha\beta^*} = -f_{\beta\alpha^*}$, $f_{\alpha\beta} = v^2 f_{\alpha^*\beta^*}$. As f_0 , f_α , f_{α^*} are arbitrary constants, the dimension of the space of such f 's is

$$1 + 2n + \frac{n(n+1)}{2} + \frac{n(n-1)}{2} = (n+1)^2.$$

Thus,

THEOREM 1. *The dimension of the automorphism group of Euclidean space E^{2n+1} with a contact Riemannian structure such that Φ is given by (3.1), where v is non-zero constant, is $(n+1)^2$.*

CASE 2^o. When v and ξv are everywhere non-zero functions. Differentiating the last equation of (3.2) by $\partial = \xi$, we obtain

$$0 = 2v\partial v \partial_{\alpha^*} \partial_{\beta^*} f.$$

By assumption $v \neq 0$ and $\partial v \neq 0$, $\partial_{\alpha^*} \partial_{\beta^*} f = 0$ and so $\partial_\alpha \partial_\beta f = 0$. These indicate that if we expand f in formal power series, terms including $x^\alpha x^\beta$ or $y^\alpha y^\beta$ vanish. On the other hand, if we put

$$f = f_0 + f_\alpha x^\alpha + f_{\alpha^*} y^\alpha + f_{\alpha\beta^*} x^\alpha y^\beta,$$

then

$$f_{\alpha\beta^*} = -f_{\beta\alpha^*} \quad \text{if } \alpha \neq \beta,$$

$$(3.4) \quad \begin{aligned} 2vf_{ss^*} = & -(f_{\alpha^*} + f_{r\alpha^*}x^r)\partial_\alpha v + (f_\alpha + f_{ar}y^r)\partial_{\alpha^*}v \\ & + (f_0 + f_\alpha x^\alpha)\partial_\alpha v, \quad s = 1, \dots, n, \end{aligned}$$

are the first equation of (3.2).

If we expand v in formal power series

$$v = v_0 + v_{1\alpha}z + v_\alpha x^\alpha + v_{\alpha^*}y^\alpha + \frac{1}{2}v_{2\alpha}z^2 + \dots,$$

then by above last condition,

$$2v_0f_{ss^*} = -f_{\alpha^*}v_\alpha + f_\alpha v_{\alpha^*} + f_0v_{1\alpha}, \quad s = 1, \dots, n.$$

But $v_0 \neq 0$, $f_{ss^*} = \frac{1}{2v_0}(-f_{\alpha^*}v_\alpha + f_\alpha v_{\alpha^*} + f_0v_{1\alpha})$, $s = 1, \dots, n$. Thus the dimension of the space of such f 's does not exceed $1 + 2n + \frac{n(n-1)}{2} = \frac{(n+1)(n+2)}{2}$ which is less than $(n+1)^2$.

THEOREM 2. *The dimension of the automorphism group of Euclidean space E^{2n+1} with a contact Riemannian structure such that Φ is given by (3.1), where v and ξv are everywhere non-zero analytic functions, does not exceed $\frac{(n+1)(n+2)}{2}$.*

In the case when v does not depend on $x^1, \dots, x^n, y^1, \dots, y^n$, but depends only on z and $\partial_\alpha v \neq 0$, the dimension is determined definitely. For, in this case, (3.4) reduce to

$$\begin{aligned} f_{\alpha\beta^*} &= -f_{\beta\alpha^*}, & \alpha &\neq \beta, \\ 2vf_{ss^*} &= f_0\partial_\alpha v + f_\alpha x^\alpha\partial_\alpha v, & s &= 1, \dots, n. \end{aligned}$$

Differentiating the last equation by x^α , $f_\alpha = 0$ and so $2vf_{ss^*} = \partial_\alpha v f_0$. If $f_{ss^*} \neq 0$, then $\frac{\partial_\alpha v}{2v}$ must be a constant. Hence,

$$v = Ae^{Bz} \text{ where } A \text{ and } B \text{ are non-zero constants.}$$

If v is not of this form, then $f_{ss^*} = 0$ and $f_0 = 0$,

$$f = f_0 + f_{\alpha^*}y^\alpha + \sum_{\alpha \neq \beta} f_{\alpha\beta^*}y^\alpha y^\beta + \frac{\partial_\alpha v}{2v} f_0 \left(\sum_{s=1}^n x^s y^s \right) \text{ if } v = Ae^{Bz},$$

and

$$f = f_{\alpha^*} y^\alpha + \sum_{\alpha \approx \beta} f_{\alpha\beta^*} y^\alpha y^\beta \quad \text{if } v \approx Ae^{Bz}.$$

Thus

THEOREM 3. *The dimension of the automorphism group of Euclidean space E^{2n+1} with a contact Riemannian structure such that Φ is given by (3.1), where $v = Ae^{Bz}$, A and B being non-zero constants, is $n(n+1)/2+1$. If v is not of the form Ae^{Bz} but still is an analytic function of z such that $\frac{\partial v}{\partial z}$ is everywhere non-zero, then the dimension is $n(n+1)/2$.*

CASE 3°. When v is an everywhere non-zero function such that $\xi v \equiv 0$. Though in this case calculations are a little difficult, we can see the dimension of automorphism group is still less than $(n+1)^2$. At first we expand v and f in formal power series:

$$v = v_0 + v_r x^r + v_{r^*} y^r + \frac{1}{2} v_{r\delta} x^r x^\delta + v_{r\delta^*} x^r y^\delta + \frac{1}{2} v_{r^*\delta^*} y^r y^\delta + \dots,$$

$$f = f_0 + f_r x^r + f_{r^*} y^r + \frac{1}{2} f_{r\delta} x^r x^\delta + f_{r\delta^*} x^r y^\delta + \frac{1}{2} f_{r^*\delta^*} y^r y^\delta + \dots.$$

Using these expansion, the first equation of (3.2) is expressed in this case as the following infinite number of equations;

$$(3.5) \quad \begin{aligned} f_{\alpha\beta^*} &= -f_{\alpha^*\beta}, \quad f_{\alpha\beta^*r} = -f_{\alpha^*\beta r}, \quad f_{\alpha\beta^*r^*} = -f_{\alpha^*\beta r^*}, \\ f_{\alpha\beta^*r} &= -f_{\alpha^*\beta r}, \quad f_{\alpha\beta^*r\delta^*} = -f_{\alpha^*\beta r\delta^*}, \quad f_{\alpha\beta^*r^*\delta^*} = -f_{\alpha^*\beta r^*\delta^*}, \\ &\dots \dots \dots \quad \text{for } \alpha \approx \beta, \end{aligned}$$

and

$$(3.6) \quad \begin{aligned} 2v_0 f_{ss^*} &= f_\alpha v_{\alpha^*} - f_{\alpha^*} v_\alpha, \\ 2v_0 f_{ss^*r} + 2v_r f_{ss^*} &= v_{\alpha^*} f_{\alpha r} - v_\alpha f_{\alpha^* r} + f_{\alpha^* r} f_\alpha - v_{\alpha r} f_{\alpha^*}, \\ 2v_0 f_{ss^*r^*} + 2v_{r^*} f_{ss^*} &= v_{\alpha^*} f_{\alpha r^*} - v_\alpha f_{\alpha^* r^*} + v_{\alpha^* r^*} f_\alpha - v_{\alpha r^*} f_{\alpha^*}, \\ &\dots \dots \dots, \text{ for } s = 1, \dots, n, \end{aligned}$$

(in general, $f_{ss^*} \dots = \frac{1}{2v_0}$ (a linear combination of f' 's of indices less than the left)),

and the last equation of (3.2) is expressed as follows;

$$\begin{aligned}
 f_{\alpha\beta} &= v_0^2 f_{\alpha^*\beta^*}, \\
 f_{\alpha\beta r} &= v_0^2 f_{\alpha^*\beta^*r} + 2v_0 v_r f_{\alpha^*\beta}, \\
 f_{\alpha\beta r^*} &= v_0^2 f_{\alpha^*\beta^*r^*} + 2v_0 v_{r^*} f_{\alpha^*\beta^*}, \\
 f_{\alpha\beta r\delta} &= v_0^2 f_{\alpha^*\beta^*r\delta} + 2(v_r v_\delta + v_0 v_{r\delta}) f_{\alpha^*\beta^*} + 2v_0 v_\delta f_{\alpha^*\beta^*r} + 2v_0 v_r f_{\alpha^*\beta^*\delta}, \\
 &\dots\dots\dots,
 \end{aligned}
 \tag{3.7}$$

(in general, $f_{\alpha\beta\dots} = v_0^2 f_{\alpha^*\beta^*\dots} +$ (a linear combination of f 's of indices less than the first term).)

By (3.6), we can see that coefficients of the expansion of f of the form $f_{ss^*\dots}$ are expressed by linear combinations of other coefficients of lower indices, and in (3.7), if $\beta \cong r$, then by (3.5)

$$\begin{aligned}
 f_{\alpha\beta r} \dots &= v_0^2 f_{\alpha^*\beta^*r} \dots + \text{lower terms} \\
 &= -v_0^2 f_{\alpha^*\beta^*r^*} \dots + \text{lower terms} \\
 &= -f_{\alpha\beta r} \quad + \text{lower terms.}
 \end{aligned}$$

Hence $f_{\alpha\beta r} \dots = \frac{1}{2}$ (a linear combination of f 's of indices less than the left),

and hence $f_{\alpha^*\beta^*r} \dots$ is also expressed by a linear combination of f 's of indices less than itself. In the same way, if $\beta \cong r$, $f_{\alpha^*\beta^*r^*} \dots$ and $f_{\alpha\beta r^*} \dots$ are expressed by linear combinations of f 's of indices less than itself.

Thus, the coefficients of the expansion of f except

$$f_0, f_\alpha, f_{\alpha^*}, f_{\alpha\beta} \text{ and } f_{\alpha\beta^*} (\alpha \cong \beta)$$

are all expressed by linear combinations of these. Hence

THEOREM 4. *The dimension of the automorphism group of Euclidean space E^{2n+1} with a contact Riemannian structure such that Φ is given by (3.1), where v is an everywhere non-zero analytic function such that $\xi v \equiv 0$, is less than $(n + 1)^2$.*

REMARK 2. Examining (3.5), (3.6) and (3.7) carefully, we can see that in Case 3^o, if $n > 1$ and if the dimension of the automorphism group is just $(n + 1)^2$, then v must be a constant. For $n = 1$, however, it does not hold.

Summarizing cases 1^o ~ 3^o in terms of manifolds,

THEOREM 5. *The dimension of the automorphism group of an analytic,*

complete, simply connected, contact Riemannian manifold M of dimension $2n + 1$ such that for every point of M there exists an adapted local coordinate system such that ϕ is given by (3.1), where

- 1^o) v is a non-zero constant, is just $(n + 1)^2$,
- 2^o) v and ξv are everywhere non-zero analytic functions, does not exceed $(n + 1)^2$,
- 3^o) v is an everywhere non-zero analytic function such that $\xi v \equiv 0$, does not exceed $(n + 1)^2$.

REMARK 3. As is easily seen by (2.14) and (2.16), ξ is always an infinitesimal strict contact transformation, and ξ is an infinitesimal automorphism if and only if $\phi_\alpha^\beta, \phi_\alpha^{\beta*}, \phi_{\alpha^*}^\beta$ do not depend on z . In this case, the manifold is called a K -contact manifold. Above Case 2^o treats the cases of non K -contact manifolds, while Case 3^o treats the cases of K -contact manifolds.

BIBLIOGRAPHY

- [1] P. LIBERMANN, Sur les automorphismes infinitésimaux des structures symplectiques et des structures de contact, Colloque de géométrie différentielle globale, (1958), 37-59.
- [2] S. SASAKI, Almost contact manifolds, Lecture note, 1965.
- [3] S. TANNO, The Automorphism Groups of contact Riemannian manifolds and Kählerian manifolds, (unpublished).

MATHEMATICAL INSTITUTE
TÔHOKU UNIVERSITY
SENDAI, JAPAN