# LOCALLY INVERTIBLE OPERATORS AND EXISTENCE PROBLEMS IN DIFFERENTIAL SYSTEMS 

Athanassios G. Kartsatos

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1. Introduction. Consider the boundary value problem

$$
(* *)
$$

$$
\begin{gathered}
x^{\prime}+A(t) x=F(t, x) \\
L x=r,
\end{gathered}
$$

where $A$ is an $n \times n$ matrix, $F$ is an $n$-vector, $L$ is a bounded linear operator defined on the space of continuous $n$-vector-valued functions on an interval $[a, b]$, under the sup-norm, and $r$ is a vector in $R^{n}$.

The existence of a solution to the problem ( $(*),(* *)$ ) is shown here under quite general assumptions on the matrix $A$ and the vector $F$, which include the following two: the homogeneous problem corresponding to (*), (**) has only the zero solution, and the vector $F(t, u)$ is continuously differentiable in the neighborhood of a certain vector $u_{0} \in R^{n}$.

The method followed here is based on the fact that certain (in general nonlinear) operator $T$ associated with the problem ((*), (**)) is Fréchet differentiable in a neighborhood of a point in its domain. This operator satisfies the conditions of Theorem I, p. 61, in Miranda's monograph [8] (cf. preliminaries, Theorem A). Thus, it is locally invertible (cf. Definition 2.3), and this implies the existence of solutions to the problem ((*), (**)).

Extensions of the above considerations to second order systems are also considered. In Section 4 it is shown that this method works also for boundary value problems on infinite intervals, or other existence problems.

For work related to the present paper, the reader is referred, for example, to the book of Falb and Jong [2], the papers [10], [11], [12] of Urabe, and the dissertation of McCandless [7].
2. Preliminaries. We start with certain notations and definitions, and (for the sake of completeness) we state the above mentioned theorem in Miranda's monograph [8].

In what follows $R=(-\infty, \infty), R_{+}=[0, \infty)$, and $J=[a, b]$, where $a, b$ are two fixed real numbers. The symbol $\|\cdot\|$ will denote the norm
in $R^{n}$ and the corresponding norm for $n \times n$ real matrices $U=\left[u_{i j}\right], i=$ $1,2, \cdots, n, j=1,2, \cdots, n$. If $E$ is a subset of $R$, then by $C\left[E, R^{n}\right]$ we denote the space of all bounded and continuous functions on $E$ with values $R^{n}$. C $\left[E, R^{n}\right]$ will always be considered with the norm

$$
\begin{equation*}
\|f\|_{E}=\sup _{t \in E}\|f(t)\| \tag{2.1}
\end{equation*}
$$

under which it is a Banach space. By $C_{c}$ we denote the space of all functions $f \in C\left[R_{+}, R^{n}\right]$ such that $\lim _{t \rightarrow \infty} f(t)$ exists and is a finite vector. $C_{c}$ is a closed subspace of $C\left[R_{+}, R^{n}\right]$.

Definition 2.1. Let $B_{1}, B_{2}$ be Banach spaces with norms $\|\cdot\|_{1},\|\cdot\|_{2}$ respectively. Let $S$ be an open subset of $B_{1}$. Let $f: S \rightarrow B_{2}, u \in S$ be such that there exists a linear operator $D(u): B_{1} \rightarrow B_{2}$ with the property

$$
\begin{equation*}
f(u+h)-f(u)=D(u) h+w(u, h), \tag{2.2}
\end{equation*}
$$

for every $h \in B_{1}$, where

$$
\begin{equation*}
\lim _{\|h\|_{1} \rightarrow 0}\|w(u, h)\|_{2} /\|h\|_{1}=0 \tag{2.3}
\end{equation*}
$$

Then $D(u) h$ is the "Fréchet differential of $f$ at $u$ with increment $h$. ."
It can be shown that if the Fréchet differential of $f$ at $u \in S$ exists, and $f$ is continuous at $u \in S$, then its "Fréchet derivative" $D(u)$ at the point $u \in S$ is a bounded linear operator on $B_{1}$ into $B_{2}$.

Definition 2.2. Assume that $B_{1}, B_{2}, S, f$ are as in Definition 2.1, and that $f$ is continuous and Fréchet differentiable at every point of $S$. Moreover, assume that for every $\varepsilon>0$ there exists $\delta(\varepsilon)>0$ such that
(i) If $u_{1}, u_{2} \in S$ with $\left\|u_{1}-u_{2}\right\|_{1} \leqq \delta(\varepsilon)$, then

$$
\begin{equation*}
\left\|\left[D\left(u_{1}\right)-D\left(u_{2}\right)\right] h\right\|_{2} \leqq \varepsilon\|h\|_{1}, \quad h \in B_{1} ; \tag{2.4}
\end{equation*}
$$

(ii) $\|w(u, h)\|_{2} \leqq \varepsilon\|h\|_{1}$ for every $u \in S$ and $h \in B_{1}$ with $\|h\| \leqq \delta(\varepsilon)$.

Then $f$ is said to be " $C$-differentiable on $S$ ".
Definition 2.3. Let $B_{1}, B_{2}, S, f$ be as in Definition 2.1, and let $u_{0} \in S$ with $f\left(u_{0}\right)=v_{0} \in B_{2}$. Then $f$ is said to be "locally invertible" at $\left(u_{0}, v_{0}\right)$ if there exist numbers $\alpha>0, \beta>0$ such that for any $v_{1} \in B_{2}$ with $\| v_{1}-$ $v_{0} \|_{2} \leqq \beta$, the equation $f(u)=v_{1}$ has a unique solution with the property $\left\|u-u_{0}\right\|_{1} \leqq \alpha$.

Now we are ready for the following
Theorem A. Let $f: S \rightarrow B_{2}$ be C-differentiable on $S$. Moreover, let $D\left(u_{0}\right): B_{1} \rightarrow B_{2}$ be one to one and onto for some $u_{0} \in S$. Then the function $f$ is locally invertible at $\left(u_{0}, f\left(u_{0}\right)\right)$.

For a proof of this theorem the reader is referred to Miranda [8].
In what follows, we shall denote the Fréchet derivative of $f$ at $u_{0}$ by $f^{\prime}\left(u_{0}\right)$. Now let $B_{1}, B_{2}, S$ be as in Definition 2.1 and let $u_{0} \in S$. Then if $f: S \rightarrow B_{2}$ is Fréchet differentiable at $u_{0}$ and $T: B_{2} \rightarrow B_{2}$ is a bounded linear operator, then the Fréchet derivative of $T f$ at $u_{0}$ exists and equals $T f^{\prime}\left(u_{0}\right)$. This follows easily from the definition of the Fréchet differential.

Now assume that the $n \times n$ matrix $A(t)$ in (*) is continuous on $J$. Then $X(t)$ will denote the fundamental matrix of solutions of

$$
\begin{equation*}
x^{\prime}+A(t) x=0 \tag{2.5}
\end{equation*}
$$

with $X(0)=I$ (the $n \times n$ identity matrix). Now let $L$ in (**) be a bounded linear operator mapping $C\left[J, R^{n}\right]$ into $R^{n}$. Moreover, denote by $\tilde{L}$ the $n \times n$ matrix whose columns are the values of $L$ on the corresponding columns of $X(t)$. Assume that $\tilde{L}$ is nonsingular with inverse $\tilde{L}^{-1}$. Then any solution of $((*),(* *))$ (with $F(t, u)$ continuous on $J \times R^{n}$ ) satisfies the equation

$$
\begin{gather*}
x(t)=X(t) \tilde{L}^{-1}(r-L p(\cdot ; x))+p(t ; x),  \tag{2.6}\\
p(t ; x)=\int_{0}^{t} X(t) X^{-1}(s) F(s, x(s)) d s \tag{2.7}
\end{gather*}
$$

For a proof of this fact the reader is referred to Opial [9]. Let $V$ be an open subset of $R^{n}$ and assume that $F(t, u)$ is continuous on $J \times R^{n}$ and continuously differentiable in $V$ with respect to $u$. Let $F_{x}(t, u)=$ [ $\left(\partial F_{i} / \partial x_{j}\right)(t, u)$ ] denote the Jacobian matrix of $F$ at the point $(t, u) \in J \times$ $U$. Now let $G=\left\{u \in C\left[J, R^{n}\right] ; u(t) \in U, t \in J\right\}$, and $x_{0} \in G$. Then the Fréchet derivative at $x_{0}$ of the operator $Q: G \rightarrow C\left[J, R^{n}\right]$ with $[Q u](t)=F(t, u(t))$, is given by

$$
\begin{equation*}
\left[Q^{\prime}\left(x_{0}\right) h\right](t)=F_{x}\left(t, x_{0}(t)\right) h(t), \quad t \in J \tag{2.8}
\end{equation*}
$$

for any $h \in C\left[J, R^{n}\right]$. For a proof of this fact in the case of a real valued function $F$ the reader is referred to Ladas and Lakshmikantham [6, p. 12]. The reader is also referred to the dissertation of McCandless [7], where a good treatment has been given of the Fréchet differentiability in Banach spaces.

Now assume that $F(t, u)$ is defined and continuous on $R_{+} \times R^{n}$ and that it is continuously differentiable in $u$ for any $t \in R_{+}$. Moreover, assume that the set $\left\{F(t, u(t)) ; t \in R_{+}\right\}$is bounded for any $u \in C\left[R_{+}, R^{n}\right]$. Then the operator $Q$ with $[Q u](t)=F(t, u(t))$ maps the space $C\left[R_{+}, R^{n}\right]$ into itself. Another assumption that we make on $F$ is the following: for every bounded set $K$ in $R^{n}$ and every $\varepsilon>0$ there exists $\delta=\delta(\varepsilon, K)$ such that for each $u_{1}, u_{2} \in K$ with $\left\|u_{1}-u_{2}\right\| \leqq \delta,\left\|F_{x}\left(t, u_{1}\right)-F_{x}\left(t, u_{2}\right)\right\| \leqq \varepsilon$
for every $t \in R_{+}$. We shall show that the Frechet derivative of the operator $Q$ defined above is given, at $x_{0} \in C\left[R_{+}, R^{n}\right]$, by

$$
\begin{equation*}
\left[Q^{\prime}\left(x_{0}\right) h\right](t)=F_{x}\left(t, x_{0}(t)\right) h(t), \quad t \in R_{+} \tag{2.9}
\end{equation*}
$$

for any $h \in C\left[R_{+}, R^{n}\right]$. In fact, we have, for some functions $\theta_{i}, i=1,2$, $\cdots, n$ with $0 \leqq \theta_{i} \leqq 1$,

$$
\begin{align*}
& \sup _{t \in R_{+}}\left\|F\left(t, x_{0}(t)+h(t)\right)-F(t, x(t))-\frac{\partial F}{\partial x}\left(t, x_{0}(t)\right) h(t)\right\|  \tag{2.10}\\
& \quad \leqq \sup _{t \in R_{+}}\left\|\left[\frac{\partial F_{i}}{\partial x_{j}}\left(t, x_{0}(t)+\theta_{i} h(t)\right)\right]-\left[\frac{\partial F_{i}}{\partial x_{j}}\left(t, x_{0}(t)\right)\right]\right\| \cdot\|h\|_{R_{+}} .
\end{align*}
$$

Since $\left\|x_{0}(t)+\theta_{i} h(t)\right\| \leqq\left\|x_{0}\right\|_{R_{+}}+\|h\|_{R_{+}}<\infty$, dividing the above inequality by $\|h\|_{R_{+}}$, and taking the limit of both members of the resulting inequality as $\|h\|_{R_{+}} \rightarrow 0$, our assertion follows.

Similarly, it can be shown that the above hold for $C_{c}$, or $C\left[R, R^{n}\right]$ under analogous assumptions on $F(t, u)$.
3. Problems on finite intervals. In what follows, the notations and definitions of Section 2 will be used without further mention.

Theorem 3.1. For the equation

$$
\begin{equation*}
x(t)=f(t)-X(t) \tilde{L}^{-1} L p(\cdot ; x)+p(t ; x) \tag{3.1}
\end{equation*}
$$

assume the following:
( i ) there exists an open set $U \subseteq R^{n}$ such that $\boldsymbol{F}(t, u)$ and its Jacobian $F_{x}(t, u)$ are defined and continuous on $J \times U$. Moreover, for every $\varepsilon>0$ there exists $\delta(\varepsilon)>0$ such that $u_{2}, u_{2} \in U$ and $\left\|u_{1}-u_{2}\right\| \leqq \delta(\varepsilon)$ imply $\left\|F_{x}\left(t, u_{1}\right)-F_{x}\left(t, u_{2}\right)\right\| \leqq \varepsilon$ for every $t \in J ;$
(ii) let $x_{0} \in C\left[J, R^{n}\right]$, with $x_{0}(t) \in U$ for $t \in J$, be fixed, and let $f_{0} \in$ $C\left[J, R^{n}\right]$ be given by

$$
\begin{equation*}
x_{0}(t)=f_{0}(t)-X(t) \tilde{L}^{-1} L p\left(\cdot ; x_{0}\right)+p\left(t ; x_{0}\right) ; \tag{3.2}
\end{equation*}
$$

(iii) let the equation

$$
\begin{equation*}
x(t)=f(t)-X(t) \widetilde{L}^{-1} L q\left(\cdot ; x_{0}, x\right)+q\left(t ; x_{0}, x\right) \tag{3.3}
\end{equation*}
$$

have a unique solution $x \in C\left[J, R^{n}\right]$ for every $f \in C\left[J, R^{n}\right]$, where

$$
\begin{equation*}
q\left(t ; x_{0}, x\right)=\int_{0}^{t} X(t) X^{-1}(s) F_{x}\left(s, x_{0}(s)\right) x(s) d s \tag{3.4}
\end{equation*}
$$

Then there exist two constants $\alpha>0, \beta>0$ such that for every $f \in C\left[J, R^{n}\right]$ with $\left\|f-f_{0}\right\| \leqq \beta$ there exists a unique solution to the equation

$$
\begin{equation*}
x(t)=f(t)-X(t) L^{-1} L p(\cdot ; x)+p(t ; x) \tag{3.5}
\end{equation*}
$$

with the property $\left\|x-x_{0}\right\| \leqq \alpha$.
Proof. Let $G=\left\{x \in C\left[J, R^{n}\right] ; x(t) \in U, t \in J\right\}$, and fix $x_{0} \in G$. Now consider the operator $T: G \rightarrow C\left[J, R^{n}\right]$ with

$$
\begin{equation*}
[T x](t)=x(t)+X(t) \tilde{L}^{-1} L p(\cdot ; x)-p(t ; x) \tag{3.6}
\end{equation*}
$$

It is easy to see that the operator $T$ is Fréchet differentiable on $G$, being the composition of an integral operator (which is linear and bounded) and the operator $Q: G \rightarrow C\left[J, R^{n}\right]$ with $(Q x)(t)=F(t, x(t)), t \in J$. Its Fréchet derivative at $x_{0}$ and with increment $h$ is given by

$$
\begin{equation*}
\left[T^{\prime}\left(x_{0}\right) h\right](t)=h(t)+X(t) \tilde{L}^{-1} L q\left(\cdot ; x_{0}, h\right)-q\left(t ; x_{0}, h\right) \tag{3.7}
\end{equation*}
$$

Now let $f \in C\left[J, R^{n}\right]$ and consider $T^{\prime}\left(x_{0}\right) h=f$. Then $h(t), t \in C\left[J, R^{n}\right]$ is the unique solution of the linear equation (3.3). Thus, $T^{\prime}\left(x_{0}\right)$ is one-to-one and onto. Let $\varepsilon>0$ be given. Then there exists $\delta_{1}(\varepsilon)>0$ such that $u_{1}, u_{2} \in U$ with $\left\|u_{1}-u_{2}\right\| \leqq \delta_{1}(\varepsilon)$ implies

$$
\begin{equation*}
\left\|F_{x}\left(\cdot, u_{1}\right)-F_{x}\left(\cdot, u_{2}\right)\right\|_{J} \leqq \varepsilon / 2 \mu \tag{3.8}
\end{equation*}
$$

where $\mu=\max \left\{\mu_{1}, \mu_{2}\right\}$ with

$$
\begin{gather*}
\mu_{1}=\sup _{t \in J}\left\{\|X(t)\|\left\|\tilde{L}^{-1}\right\|\|L\| \int_{0}^{t}\left\|X(t) X^{-1}(s)\right\| d s\right\}  \tag{3.9}\\
\mu_{2}=\sup _{t \in J}\left\{\int_{0}^{t}\left\|X(t) X^{-1}(s)\right\| d s\right\}  \tag{3.10}\\
\text { Thus, if } u_{1}, u_{2} \in G \text { with }\left\|u_{1}-u_{2}\right\|_{J} \leqq \delta_{1}(\varepsilon)
\end{gather*}
$$ we obtain

$$
\begin{equation*}
\left\|T\left(u_{1}\right) h-T\left(u_{2}\right) h\right\|_{J} \leqq \varepsilon\|h\|_{J} \tag{3.11}
\end{equation*}
$$

for any $h \in C\left[J, R^{n}\right]$. Moreover, it follows as in (2.17) and (2.18) that if

$$
\begin{equation*}
T(x+h)-T x=T^{\prime}(x) h+w(x, h) \tag{3.12}
\end{equation*}
$$

for every $x \in G, h \in C\left[J, R^{n}\right]$, then there exists $\delta_{2}(\varepsilon)>0$ such that

$$
\begin{align*}
\sup _{t \in J} & \|w(x, h)(t)\|  \tag{3.13}\\
& \leqq \sup _{t \in J}\left\|\left[\frac{\partial F_{i}}{\partial x_{j}}\left(t, x(t)+\theta_{i} h(t)\right)-\frac{\partial F_{i}}{\partial x_{j}}(t, x(t))\right]\right\| \cdot\|h\|_{J} \\
& \leqq \varepsilon\|h\|_{J}
\end{align*}
$$

for any $h \in C\left[J, R^{n}\right]$ with $\|h\|_{J} \leqq \delta_{2}(\varepsilon)$. If we let $\delta(\varepsilon)=\min \left\{\delta_{1}(\varepsilon), \delta_{2}(\varepsilon)\right\}$ we see that the operator $T$ is $C$-differentiable on $G$, and that the rest of the assumptions of Theorem A are satisfied. This completes the proof.

The above theorem has the following important

COROLLARY 3.1. Let the assumptions of Theorem 3.1 be satisfied, and assume that the number $\beta$ in the conclusion of the same theorem is such that $\left\|f_{0}\right\|_{J}<\beta$. Then there exist positive numbers $\alpha, \mu$ such that for each $r \in R^{n}$ with $\|r\| \leqq \mu$ there exists a unique solution of the problem ((*), (**)) satisfying $\left\|x-x_{0}\right\|_{J} \leqq \alpha$.

Proof. Let $\varepsilon>0$ be such that $\left\|f_{0}\right\|_{J}+\varepsilon<\beta$. Then since

$$
\begin{equation*}
\lim _{\|r\| \rightarrow 0} \sup _{t \in J}\left\|X(t) \widetilde{L}^{-1} r-f_{0}(t)\right\|=\left\|f_{0}\right\|_{J} \tag{3.14}
\end{equation*}
$$

there exists $\delta(\varepsilon)>0$ such that

$$
\begin{equation*}
\sup _{t \in J}\left\|X(t) \tilde{L}^{-1} r-f_{0}(t)\right\| \leqq\left\|f_{0}\right\|_{J}+\varepsilon<\beta \tag{3.15}
\end{equation*}
$$

whenever $\|r\| \leqq \delta(\varepsilon)=\mu$. Thus, for every $r \in R^{n}$ with $\|r\| \leqq \mu$ the equation (2.13) has a unique solution inside $G_{0}=\left\{x \in C\left[J, R^{n}\right] ;\left\|x-x_{0}\right\|_{J} \leqq\right.$ $\alpha\}$. This completes the proof.

It is evident from the above corollary that to ensure a unique solution of $((*),(* *))$ for sufficiently small $\|r\|$, it suffices to find an approximate solution $x_{0}(t)$, satisfying

$$
\begin{equation*}
x_{0}^{\prime}(t)+A(t) x_{0}(t)=F\left(t, x_{0}(t)\right)+\lambda(t), \tag{3.16}
\end{equation*}
$$

and such that $\left\|f_{0}\right\|_{J}<\beta$, where

$$
f_{0}(t)=-X(t) \widetilde{L}^{-1} L \phi(\cdot ; \lambda)+\phi(t ; \lambda)
$$

with

$$
\phi(t ; \lambda)=\int_{0}^{t} X(t) X^{-1}(s) \lambda(s) d s
$$

We also wish to point out that the solutions obtained by Theorem 3.1 and its corollary can be obtained by Newton's method. This follows from the proof of Theorem A, where a contraction mapping is involved.

Let us now consider the following boundary value problem:

$$
\begin{align*}
x^{\prime \prime} & =F(t, x)  \tag{3.17}\\
x(a) & =x(b)=0 . \tag{3.18}
\end{align*}
$$

Here $F$ is assumed to be defined and continuous on $J \times R^{n}$. Then finding a solution of the above problem amounts to finding a solution $x(t), t \in J$ of the integral equation

$$
\begin{align*}
x(t)= & \frac{1}{a-b}\left[(b-t) \int_{a}^{t}(s-a) F(s, x(s)) d s\right.  \tag{3.19}\\
& \left.+(t-a) \int_{t}^{b}(b-s) F(s, x(s)) d s\right]
\end{align*}
$$

We state the following theorem, whose proof can be carried out as in Theorem 3.1 and its corollary.

Theorem 3.2. Assume that Hypothesis (i) of Theorem 3.1 is satisfied. Furthermore, fix $x_{0} \in C\left[J, R^{n}\right]$ with $x_{0}(t) \in U$ for every $t \in J$, and let $f_{0} \in C\left[J, R^{n}\right]$ be given by

$$
\begin{align*}
x_{0}(t)= & f_{0}(t)+\frac{1}{a-b}\left[(b-t) \int_{a}^{t}(s-a) F\left(s, x_{0}(s)\right) d s\right.  \tag{3.20}\\
& +(t-a) \int_{t}^{b}(b-s) F\left(s, x_{0}(s)\right) d s
\end{align*}
$$

Let the equation

$$
\begin{align*}
x(t)= & f(t)+\frac{1}{a-b}\left[(b-t) \int_{a}^{t}(s-a) F_{x}\left(s, x_{0}(s)\right) x(s) d s\right.  \tag{3.21}\\
& \left.+(t-a) \int_{t}^{b}(b-s) F_{x}\left(s, x_{0}(s)\right) x(s) d s\right]
\end{align*}
$$

have a unique solution $x \in C\left[J, R^{n}\right]$ for every $f \in C\left[J, R^{n}\right]$. Then there exist two positive numbers $\alpha, \beta$ such that for every $f \in C\left[J, R^{n}\right]$ with $\left\|f-f_{0}\right\|_{J} \leqq \beta$, there exists a unique solution $x \in C\left[J, R^{n}\right]$ of the equation

$$
\begin{align*}
x(t)= & f(t)+\frac{1}{a-b}\left[(b-t) \int_{a}^{t}(s-a) F(s, x(s)) d s\right.  \tag{3.22}\\
& \left.+(t-a) \int_{t}^{b}(b-s) F(s, x(s)) d s\right]
\end{align*}
$$

with the property $\left\|x-x_{0}\right\|_{J} \leqq \alpha$. Moreover, if $\left\|f_{0}\right\|_{J} \leqq \beta$, then the problem ((3.17), (3.18)) has a unique solution $x(t)$ satisfying $\left\|x-x_{0}\right\|_{J} \leqq \alpha$.
4. Problems on infinite intervals. It is evident that Theorem 3.1 and Corollary 3.1 can be extended to problems of the form ( $(*),(* *))$. We formulate below such a result and omit its proof, which follows as before. Moreover, we formulate a theorem concerning the existence of bounded solutions of the equation (*) on the whole axis $R$.

Theorem 4.1. For the problem ((*), (**)) assume the following:
(i) $\lim _{t \rightarrow \infty} X(t)=X(\infty)$ exists and is a finite matrix. Moreover,

$$
\sup _{t \in R_{+}} \int_{0}^{t}\left\|X(t) X^{-1}(s)\right\| d s<+\infty
$$

(ii) $T: C_{c} \rightarrow R^{n}$ is a bounded linear operator such that $\widetilde{L}^{-1}$ exists;
(iii) $F(t, u): R_{+} \times R^{n} \rightarrow R^{n}$ is continuous, and continuously differentiable in $u$. Moreover, for every $\varepsilon>0$ there exists $\delta(\varepsilon)>0$ such that for every $u_{1}, u_{2} \in R^{n}$ with $\left\|u_{1}-u_{2}\right\| \leqq \delta(\varepsilon)$,

$$
\begin{equation*}
\left\|F_{x}\left(t, u_{1}\right)-F_{x}\left(t, u_{2}\right)\right\| \leqq \varepsilon, \quad t \in R_{+} . \tag{4.1}
\end{equation*}
$$

(iv) for every $u \in C\left[R_{+}, R^{n}\right]$, the set $\left\{F(t, u(t)) ; t \in R_{+}\right\}$is bounded; moreover,

$$
\int_{0}^{\infty}\left\|X^{-1}(s) F(s, u(s))\right\| d s<+\infty ;
$$

(v) for every $f \in C_{c}$ the equation (3.3) has a unique solution $x \in C_{c}$, where $q$ is given by (3.4) and $x_{0} \in C_{c}$ is fixed and such that

$$
\int_{0}^{\infty}\left\|X^{-1}(s) F_{x}(s, u(s))\right\| d s<+\infty
$$

for every $u$ in some neighborhood of $x_{0}$.
Then if $f_{0}$ is given by (3.2), there exist two constants $\alpha>0, \beta>0$ such that for every $f \in C\left[J, R^{n}\right]$ with $\left\|f-f_{0}\right\|_{R_{+}} \leqq \beta$, there exists a unique solution $x \in C_{c}$ to the equation (3.5) with $\left\|x-x_{0}\right\|_{R_{+}} \leqq \alpha$. Moreover, if $\left\|f_{0}\right\|_{R_{+}}<\beta$, then the problem $((*),(* *))$ has a solution for $\|r\|$ sufficiently small.

Now assume that $P_{1}, P_{2}$ are $n \times n$ projections, $P_{1}+P_{2}=I$. The following theorem ensures the existence of a solution to the integral equation

$$
\begin{align*}
x(t)= & \int_{-\infty}^{t} X(t) P_{1} X^{-1}(s) F(s, x(s)) d s  \tag{4.2}\\
& -\int_{t}^{\infty} X(t) P_{2} X^{-1}(s) F(s, x(s)) d s
\end{align*}
$$

In connection with (4.2) we shall consider the equations

$$
\begin{align*}
x_{0}(t)= & f_{0}(t)+\int_{-\infty}^{t} X(t) P_{1} X^{-1}(s) F\left(s, x_{0}(s)\right) d s  \tag{4.3}\\
& -\int_{t}^{\infty} X(t) P_{2} X^{-1}(s) F\left(s, x_{0}(s)\right) d s \\
x(t)= & f(t)+\int_{-\infty}^{t} X(t) P_{1} X^{-1}(s) F_{x}\left(s, x_{0}(s)\right) x(s) d s  \tag{4.4}\\
& -\int_{t}^{\infty} X(t) P_{2} X^{-1}(s) F_{x}\left(s, x_{0}(s)\right) x(s) d s
\end{align*}
$$

Theorem 4.2. For the system (*) assume the following:
(i) $\sup _{t \in R_{+}}\left[\int_{-\infty}^{t}\left\|X(t) P_{1} X^{-1}(s)\right\| d s+\int_{t}^{\infty}\left\|X(t) P_{2} X^{-1}(s)\right\| d s\right]<+\infty$;
(ii) $F(t, u)$ satisfies (iii) of Theorem 4.1 with $R_{+}$replaced by $R$;
(iii) for every $u \in C\left[R, R^{n}\right]$, the set $\{F(t, u(t)) ; t \in R\}$ is bounded;
(iv)

$$
\begin{aligned}
\sup _{t \in R_{+}} & {\left[\int_{-\infty}^{t}\left\|X(t) P_{1} X^{-1}(s) F_{x}(s, u(s))\right\| d s\right.} \\
& \left.+\int_{t}^{\infty}\left\|X(t) P_{2} X^{-1}(s) F_{x}(s, u(s))\right\| d s\right]<+\infty
\end{aligned}
$$

for every $u$ in some neighborhood of $x_{0} \in C\left[R, R_{+}\right]$, and the equation (4.4) has a unique solution in $C\left[R, R^{n}\right]$ for every $f \in C\left[R, R^{n}\right]$.

Then there exist two constants $\alpha, \beta>0$ such that, if $f_{0} \in C\left[R, R^{n}\right]$ is given by (4.3), then for every $f \in C\left[R, R^{n}\right]$ with $\left\|f-f_{0}\right\|_{R} \leqq \beta$, there exists a unique solution to the equation

$$
\begin{align*}
x(t)= & f(t)+\int_{-\infty}^{t} X(t) P_{1} X^{-1}(s) F(s, x(s)) d s  \tag{4.5}\\
& -\int_{t}^{\infty} X(t) P_{2} X^{-1}(s) F(s, x(s)) d s
\end{align*}
$$

satisfying $\left\|x-x_{0}\right\|_{R} \leqq \alpha$. Moreover, if $\left\|f_{0}\right\| \leqq \beta$, the system (*) has a unique solution $x \in C\left[R, R^{n}\right]$ such that $\left\|x-x_{0}\right\|_{R} \leqq \alpha$. This is given by (4.5), where $f(t) \equiv 0, \quad t \in R$.
5. Remarks. The assumed uniqueness of the solutions of the integral equations (3.3), (3.21), can be ensured by considering sufficiently small intervals $J$, in which case we obtain contraction mappings. Similarly, small enough integrals in (v) of Theorem 4.1 and (iv) of Theorem 4.2, ensure the uniqueness of solutions of (3.3), (4.4) respectively. Corollary (3.1) overlaps in the case $T x=x(0)-x(\omega)=0$ ( $\omega$-periodicity) with a result of Urabe [10]. For initial value problems connected to Fréchet derivatives, the reader is referred to Alekseev [1]. For boundary value problems on infinite intervals related papers are those of Kartsatos [3-5].

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Department of Mathematics
University of South Florida
tampa, Florida
U.S.A.

