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## **ON CONTACT METRIC MANIFOLDS**

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1. Introduction. Blair has proven ([1]) that there are no contact metric manifolds of vanishing curvature and of dimension  $\geq 5$ . Generalizing this result we prove in the present paper that any contact metric manifold of constant sectional curvature and of dimension  $\geq 5$  has the sectional curvature equal to 1 and is a Sasakian manifold. Moreover we give some restrictions on the scalar curvature in contact metric manifolds which are conformally flat or of constant  $\phi$ -sectional curvature.

2. Preliminaries. Throughout this paper we use the notations and terminology of [1], [2].

Let *M* be a (2n+1)-dimensional contact metric manifold and  $(\phi, \xi, \eta, g)$  be its contact metric structure. Thus, we have

$$egin{aligned} \phi^2 &= -I + \eta \otimes \xi \;,\;\; \phi \xi = 0 \;,\;\; \eta \circ \phi = 0 \;,\;\; \eta (\xi) = 1 \;, \ g(\phi X, \, \phi \, Y) &= g(X, \; Y) - \eta (X) \eta (Y) \;,\;\; g(X, \; \xi) = \eta (X) \;, \ arPsi (X, \; Y) &= g(X, \; \phi \, Y) = d \eta (X, \; Y) \;. \end{aligned}$$

Define an operator h by  $h = (1/2) \mathscr{L}_{\xi} \phi$ , where  $\mathscr{L}$  denotes Lie differentiation. The vector field  $\xi$  is Killing if and only if h vanishes. Blair has shown ([1], [2]) that h and  $\phi h$  are symmetric operators, h anti-commutes with  $\phi$  (i.e.,  $\phi h + h\phi = 0$ ),  $h\xi = 0$  and  $\eta \circ h = 0$ . Using a  $\phi$ -basis, i.e., an orthonormal frame  $\{E_i, E_{i+n} = \phi E_i, E_{2n+1} = \xi\}$   $(i = 1, \dots, n)$ , one can easily verify that tr h = 0 and tr  $\phi h = 0$ . In [1], [2] the following general formulas for a contact metric manifold were obtained

$$(2.2)$$
  $(1/2)(R_{\xi X}\xi - \phi R_{\xi \phi X}\xi) = h^2 X + \phi^2 X$  ,

(2.3)  $g(Q\xi, \xi) = 2n - \operatorname{tr} h^2$ ,

where  $R_{xy} = [V_x, V_y] - V_{[x,y]}$  is the curvature transformation and Q is the Ricci curvature operator. Finally, we note that  $d\Phi = d^2\eta = 0$  implies

(2.4) 
$$(\nabla_x \phi)(Y, Z) + (\nabla_y \phi)(Z, X) + (\nabla_z \phi)(X, Y) = 0.$$

3. Auxiliary results. First of all, using (2.1) we can easily obtain the following relations

$$\begin{array}{ll} (3.1) & (\mathcal{F}_{\scriptscriptstyle X}\varPhi)(\phi\,Y,\,Z) - (\mathcal{F}_{\scriptscriptstyle X}\varPhi)(\,Y,\,\phi Z) = \, -\eta(\,Y)g(X + hX,\,\phi Z) \\ & -\eta(Z)g(X + hX,\,\phi\,Y) \;, \end{array}$$

(3.2) 
$$(\nabla_{\mathcal{X}} \Phi)(\phi Y, \phi Z) + (\nabla_{\mathcal{X}} \Phi)(Y, Z) = \eta(Y)g(X + hX, Z)$$
$$-\eta(Z)g(X + hX, Y) .$$

LEMMA 3.1. Any contact metric manifold satisfies the conditions .3)  $(\nabla_{\phi,r}\phi)\phi Y + (\nabla_{r}\phi)Y = 2q(X, Y)\xi - \eta(Y)(X + hX + \eta(X)\xi)$ ,

(3.3) 
$$(\mathcal{V}_{\phi_X}\phi)\phi Y + (\mathcal{V}_X\phi)Y = 2g(X, Y)\xi - \eta(Y)(X + hX)$$

(3.4)(a) 
$$\sum_{i=1}^{N-1} (\nabla_{E_i} \phi) E_i = 2n\xi$$
,

(3.4)(b) 
$$\sum_{i=1}^{2n+1} (\nabla_{E_i} \phi) \phi E_i = 0 ,$$

where  $\{E_1, \dots, E_{2n+1}\}$  is an orthonormal frame.

**PROOF.** Making use of the identity (2.4) we can write

$$\begin{split} (\mathcal{F}_{\scriptscriptstyle X} \varPhi)(\,Y,\,Z) \,+\, (\mathcal{F}_{\scriptscriptstyle Y} \varPhi)(Z,\,X) \,+\, (\mathcal{F}_{\scriptscriptstyle Z} \varPhi)(X,\,Y) \\ &+\, (\mathcal{F}_{\phi_{\scriptscriptstyle X}} \varPhi)(\phi\,Y,\,Z) \,+\, (\mathcal{F}_{\phi_{\scriptscriptstyle Y}} \varPhi)(Z,\,\phi X) \,+\, (\mathcal{F}_{\scriptscriptstyle Z} \varPhi)(\phi X,\,\phi Y) \\ &+\, (\mathcal{F}_{\phi_{\scriptscriptstyle X}} \varPhi)(\,Y,\,\phi Z) \,+\, (\mathcal{F}_{\scriptscriptstyle Y} \varPhi)(\phi Z,\,\phi X) \,+\, (\mathcal{F}_{\phi_{\scriptscriptstyle Z}} \varPhi)(\phi X,\,Y) \\ &-\, (\mathcal{F}_{\scriptscriptstyle X} \varPhi)(\phi\,Y,\,\phi Z) \,-\, (\mathcal{F}_{\phi_{\scriptscriptstyle Y}} \varPhi)(\phi Z,\,X) \,-\, (\mathcal{F}_{\phi_{\scriptscriptstyle Z}} \varPhi)(X,\,\phi\,Y) = 0 \;. \end{split}$$

Hence in virtue of (3.1) and (3.2) we obtain

which is equivalent to (3.3). Choose a  $\phi$ -basis. As from (3.3) follows  $\mathcal{V}_{\varepsilon}\phi = 0$ , we can find (3.4) (a), (b) by using (3.3).

LEMMA 3.2. The curvature tensor of a contact metric manifold satisfies the relations

$$(3.5) \quad g(R_{\xi X}Y, Z) = -(\nabla_X \Phi)(Y, Z) - g(X, (\nabla_Y \phi h)Z) + g(X, \nabla_Z \phi h)Y) ,$$

$$(3.6) \quad g(R_{\varepsilon X}Y,Z) - g(R_{\varepsilon X}\phi Y,\phi Z) + g(R_{\varepsilon \phi X}Y,\phi Z) + g(R_{\varepsilon \phi X}\phi Y,Z) \\ = 2(\mathcal{F}_{hX}\Phi)(Y,Z) - 2\eta(Y)g(X+hX,Z) + 2\eta(Z)g(X+hX,Y) .$$

PROOF. Let X, Y, Z be tangent vectors at a point  $m \in M$ . By the same letters we denote their extensions to local vector fields. From (2.1) we have

$$R_{\scriptscriptstyle YZ} \xi = - ( {\it V}_{\scriptscriptstyle Y} \phi) Z + ( {\it V}_{\scriptscriptstyle Z} \phi) Y - ( {\it V}_{\scriptscriptstyle Y} \phi h) Z + ( {\it V}_{\scriptscriptstyle Z} \phi h) Y$$
 .

This yields (3.5) in virtue of (2.4). Denote

248

$$\begin{split} A(X, Y, Z) &= -(\mathcal{V}_{x} \boldsymbol{\varPhi})(Y, Z) + (\mathcal{V}_{x} \boldsymbol{\varPhi})(\phi Y, \phi Z) - (\mathcal{V}_{\phi x} \boldsymbol{\varPhi})(Y, \phi Z) \\ &- (\mathcal{V}_{\phi x} \boldsymbol{\varPhi})(\phi Y, Z) , \end{split}$$

$$egin{aligned} B(X,\ Y,\ Z) &= -g(X, (arPsi_{{}_Y}\phi h)Z) + g(X, (arPsi_{\phi_Y}\phi h)\phi Z) - g(\phi X, (arPsi_{{}_Y}\phi h)\phi Z) \ &- g(\phi X, (arPsi_{\phi_Y}\phi h)Z) \;. \end{aligned}$$

In view of (3.5) the left hand side of (3.6) equals A(X, Y, Z) + B(X, Y, Z) - B(X, Z, Y). By (3.2) and (3.3) we obtain

$$A(X, Y, Z) = 2g(X, Y)\eta(Z) - 2g(X, Z)\eta(Y)$$
.

Rewrite B in the following form

$$egin{aligned} B(X,\ Y,\ Z) &= -g(X,(arPsi_{_Y}\phi)hZ) + g(X,h(arPsi_{_Y}\phi)Z) + g(X,h\phi(arPsi_{_{\phi_Y}}\phi)Z) \ &+ g(X,\phi(arPsi_{_{\phi_Y}}\phi)hZ) + \eta(X)\eta((arPsi_{_{\phi_Y}}h)Z) \;. \end{aligned}$$

We have

$$(3.7) \qquad \phi({\it V}_{\phi_X}\phi)\,Y = 2\eta(\,Y)X - g(X + hX,\,\,Y)\xi - \eta(X)\eta(\,Y)\xi + ({\it V}_x\phi)\,Y \,.$$
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In fact

$$egin{aligned} \phi(ec{
aligned}_{\phi_X}\phi)\,Y &= (ec{
aligned}_{\phi_X}\phi^2)\,Y - (ec{
aligned}_{\phi_X}\phi)\phi\,Y \ &= (ec{
aligned}_{\phi_X}\eta)(\,Y)\xi + \eta(\,Y)ec{
aligned}_{\phi_X}\xi \,- (ec{
aligned}_{\phi_X}\phi)\phi\,Y \,, \end{aligned}$$

from which, by (2.1) and (3.3), we find (3.7). Moreover, remembering (2.1), we get

$$\eta((\nabla_{\phi_Y} h)Z) = -(\nabla_{\phi_Y} \eta)(hZ) = g(-Y + hY, hZ)$$
.

Thus, we obtain in virtue of (3.7)

 $B(X,\ Y,\ Z)=2g(hX,\ (\mathbb{P}_Y\phi)Z)+2\eta(Z)g(hX,\ Y)-2\eta(X)g(Y,\ hZ)\ .$  Therefore

which in view of (2.4) equals the right hand side of (3.6). Thus the proof is complete.

Denote by S the scalar curvature of M and define  $S^* = \sum_{i,j=1}^{2n+1} g(R_{E_iE_j}\phi E_j, \phi E_i)$ , where  $\{E_i\}$  is an orthonormal frame.

LEMMA 3.3. For any contact metric manifold M we have

 $(3.8) S^* - S + 4n^2 = \operatorname{tr} h^2 + (1/2)\{||\nabla \phi||^2 - 4n\} \ge 0.$ 

Moreover M is Sasakian if and only if  $||\nabla \phi||^2 = 4n$  or equivalently  $S^* - S + 4n^2 = 0$ .

**PROOF.** Let  $\{E_1, \dots, E_{2n+1}\}$  be a frame in  $M_m$ . By the same letters we denote local extension vector fields of this frame which are orthonormal and covariant constant at  $m \in M$ . Now (3.4) (a) and (2.1) become

(3.9) 
$$\sum_{i,j=1}^{2n+1} g((\nabla_{E_j} \nabla_{E_i} \phi) E_i, \phi E_j) = -4n^2$$

because tr h = 0. On the other hand, by (3.4) (b), we obtain

$$(3.10) \qquad -\sum_{i,j=1}^{2n+1} g((\nabla_{E_i} \nabla_{E_j}, \phi) E_i, \phi E_j) = \sum_{i,j=1}^{2n+1} g((\nabla_{E_i} \phi) E_j, (\nabla_{E_j} \phi) E_i) .$$

But the right hand side of (3.10) can be transformed as follows

$$\begin{split} \sum_{i,j,k=1}^{2^{n+1}} & g((\overline{\Gamma}_{E_i}\phi)E_j, \, E_k)g((\overline{\Gamma}_{E_j}\phi)E_i, \, E_k) \\ & = (1/2)\sum_{i,j,k=1}^{2^{n+1}} \{g((\overline{\Gamma}_{E_i}\phi)E_j, \, E_k)\}^2 = (1/2)\sum_{i,j=1}^{2^{n+1}} ||(\overline{\Gamma}_{E_i}\phi)E_j||^2 = (1/2) ||\overline{\Gamma}\phi||^2 \end{split}$$

in virtue of (2.4). Considering (3.9), (3.10) and the last relation we get

$$\sum_{i,\,j=1}^{2n+1} g((R_{EjE_i}\phi)E_i,\,\phi E_j) = (1/2) ||
abla \phi||^2 - 4n^2 \;.$$

Hence  $S^* - S + g(Q\xi, \xi) = (1/2) || \nabla \phi ||^2 - 4n^2$ , which with the help of (2.3) proves the equality part of (3.8).

Recall that *M* is Sasakian if and only if  $(\mathcal{V}_X \phi) Y = g(X, Y)\xi - \eta(Y)X$ . Consequently, we always have, for a contact metric manifold *M*,

$$\sum_{i,j=1}^{2n+1} || ({m arphi}_{E_i} \phi) E_j - g(E_i,\,E_j) \xi + \eta(E_j) E_i ||^2 \ge 0$$
 ,

where equality holds if and only if M is Sasakian. By using (3.4) (a) it can be easily shown that the last condition is equivalent to  $||F\phi||^2 - 4n \ge 0$ , where equality holds only in the Sasakian case. Note that from the symmetry of the operator h it follows that tr  $h^2 \ge 0$  and tr  $h^2 = 0$  if and only if h = 0. Recall also that on a Sasakian manifold the vector field  $\xi$  is Killing. Therefore, if M is Sasakian, then h vanishes. The above remarks complete the proof of our lemma.

## 4. Main results.

THEOREM 4.1. If a contact metric manifold M is of constant sectional curvature and dim  $M \ge 5$ , then the sectional curvature of M is equal to 1 and M is Sasakian.

**PROOF.** Let c be the constant sectional curvature of M, i.e.,  $R_{XY}Z = c\{g(Y, Z)X - g(X, Z)Y\}$ . Under this assumption, from (2.2) we obtain  $h^2X = (c-1)\phi^2X$ , hence tr  $h^2 = 2n(1-c)$ . Moreover, (3.6) yields

250

(4.1) 
$$(\nabla_{hx} \Phi)(Y, Z) = (1 - c) \{ \eta(Y)g(X, Z) - \eta(Z)g(X, Y) \}$$
  
+  $\eta(Y)g(hX, Z) - \eta(Z)g(hX, Y) .$ 

Now let us suppose that  $c \neq 1$ . Taking in (4.1) hX instead of X, we have

$$({\it V}_{\scriptscriptstyle X}\phi)\,Y=g(X+\,hX,\,\,Y)\xi-\eta(\,Y)(X+\,hX)$$
 ,

as  $\mathcal{V}_{\epsilon}\phi = 0$ . From this we find  $||\mathcal{V}\phi||^2 = 4n(2-c)$ . The last relation and equalities S = 2n(2n+1)c,  $S^* = 2nc$  applied to (3.8) give n = 1, a contradiction. Therefore c = 1. But in this case, by Lemma 3.3, the manifold M is Sasakian.

THEOREM 4.2. Let M be a conformally flat contact metric manifold with dim  $M \ge 5$ . Then the scalar curvature S of M satisfies  $S \le 2n(2n+1)$ . Moreover, M is Sasakian if and only if S = 2n(2n + 1).

PROOF. Conformal flatness yields

(4.2) 
$$R_{XY}Z = (1/(2n-1)) \left\{ g \left( QY - \frac{S}{2n}Y, Z \right) X - g \left( QX - \frac{S}{2n}X, Z \right) Y + g(Y, Z) QX - g(X, Z) QY \right\}.$$

Using the relations (2.3) and (4.2) we compute  $S^* = (1/(2n-1))\{S - 2(2n - \operatorname{tr} h^2)\}$ . Then, from (3.8) one can obtain

$$(4.3) \quad (2n-1)\{||
abla \phi ||^2 - 4n\} + 2(2n-3) ext{ tr } h^2 = 2(2n-2)\{2n(2n+1) - S\} \ ,$$
 which completes the proof.

REMARK 4.1. Any 3-dimensional contact metric manifold M satisfies the condition (4.2) and therefore (4.3), i.e.,  $||\nabla \phi||^2 - 4n = 2 \operatorname{tr} h^2$ . This shows that M is Sasakian if and only if the vector field  $\xi$  is Killing (cf. [6], [3]).

REMARK 4.2. As is known, any conformally flat contact metric manifold with Killing structure vector field  $\xi$  is of constant curvature (cf. [5], [4]). Then by Theorem 4.2 any conformally flat contact metric manifold M with dim  $M \ge 5$  and the scalar curvature S = 2n(2n + 1) is of constant sectional curvature.

In the next theorem we consider a contact metric manifold of constant  $\phi$ -sectional curvature, that is, a manifold M such that at any point  $m \in M$  the sectional curvature  $K(X, \phi X)$  (denote it by  $H_m$ ) is independent of the choice of the tangent vector  $X \in M_m$ ,  $0 \neq X \perp \xi$ . By H we denote the  $\phi$ -sectional curvature of M, i.e.,  $H: M \to R$ ,  $H(m) = H_m$ .

THEOREM 4.3. Let M be a contact metric manifold of constant  $\phi$ -sectional curvature. Then the scalar curvature S and the  $\phi$ -sectional curvature H satisfy the inequality  $n(n + 1)H + 3n^2 + n \ge S$ . Equality holds if and only if M is Sasakian.

PROOF. By our assumption we have  $g(R_{X\phi X}X, \phi X) + H_m ||X||^4 = 0$  at any point  $m \in M$  and for any  $X \in M_m$ ,  $X \perp \xi$ . It is clear that this condition implies

(4.4) 
$$g(R_{\phi X \phi^2 X} \phi X, \phi^2 X) + H_m ||\phi X||^4 = 0$$

at any point  $m \in M$  and for any  $X \in M_m$ . Set

$$P(X, Y, Z, W) = g(R_{\phi_X \phi^2 Y} \phi Z, \phi^2 W) + H_m g(\phi X, \phi Z) g(\phi Y, \phi W)$$

The tensor P satisfies P(X, Y, Z, W) = P(Z, W, X, Y). Therefore (4.4) is equivalent to

$$\begin{array}{ll} (4.5) \quad P(X,\ Y,\ Z,\ W) + P(X,\ Y,\ W,\ Z) + P(Y,\ X,\ Z,\ W) + P(Y,\ X,\ W,\ Z) \\ \quad + P(X,\ W,\ Y,\ Z) + P(X,\ W,\ Z,\ Y) + P(W,\ X,\ Y,\ Z) + P(W,\ X,\ Z,\ Y) \\ \quad + P(X,\ Z,\ Y,\ W) + P(X,\ Z,\ W,\ Y) + P(Z,\ X,\ Y,\ W) \\ \quad + P(Z,\ X,\ W,\ Y) = 0 \ . \end{array}$$

Choosing a  $\phi$ -basis, taking  $X = W = E_i$ ,  $Y = Z = E_j$  into (4.5) and summing over i and j we obtain

$$\sum_{i,j=1}^{2n+1} \{ P(E_i, E_j, E_j, E_i) + P(E_i, E_j, E_i, E_j) + P(E_i, E_i, E_j, E_j) \} = 0$$
 ,

which by the definition of P, the first Bianchi identity and (2.3) gives

 $4n(n + 1)H - 3S^* - S + 2(2n - \operatorname{tr} h^2) = 0$ .

Comparing the last identity with (3.8) we obtain

$$n(n+1)H+3n^2+n-S=(5/4) ext{ tr } h^2+(3/8)\{||
abla \phi||^2-4n\}$$
 ,

which completes the proof.

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252

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