Tohoku Math. J. 55 (2003), 543–549

SOME HOMOLOGICAL INVARIANTS OF THE MAPPING CLASS GROUP OF A THREE-DIMENSIONAL HANDLEBODY

SUSUMU HIROSE

(Received December 5, 2001, revised September 17, 2002)

Abstract. We show that, if $g \ge 2$, the virtual cohomological dimension of the mapping class group of a three-dimensional handlebody of genus g is equal to 4g - 5 and its Euler number is equal to 0.

1. Introduction. A genus g handlebody H_g is an oriented 3-manifold which is constructed from 3-ball by attaching g 1-handles. The mapping class group \mathcal{H}_g of H_g is defined to be the group of isotopy classes of orientation-preserving diffeomorphisms of H_g . This group \mathcal{H}_g is a subgroup of the mapping class group \mathcal{M}_g of a surface ∂H_g , that is, $\mathcal{M}_g = \pi_0(\text{Diff}^+(\partial H_g))$, where $\text{Diff}^+(\partial H_g)$ is the group of orientation preserving diffeomorphisms of ∂H_g . Throughout this paper, we assume $g \ge 2$.

The cohomological dimension of a group G, cd(G), is defined to be the largest number n for which there exists a G-module M with $H^n(G, M)$ nonzero. We remark that if $G_1 \subset G_2$, then $cd(G_1) \leq cd(G_2)$. Also, when G has torsion, cd(G) is infinite. However, if G has finite index torsion-free subgroups (we call G virtually torsion-free), we define the virtual cohomological dimension of G, vcd(G), to be the cohomological dimension of a finite index torsion-free subgroup \hat{G} . A theorem of Serre [13] states that this number is independent of the choice of \hat{G} . For the virtual cohomological dimensions of \mathcal{M}_g and \mathcal{H}_g , Harer [5] showed that $vcd(\mathcal{M}_g) = 4g - 5$, and McCullough [11] showed that $vcd(\mathcal{H}_2) = 3$ and, if $g \geq 3$, $3g - 2 \leq vcd(\mathcal{H}_g) \leq 4g - 5$. In this paper, we prove the following result.

THEOREM 1.1. If $g \ge 2$, the virtual cohomological dimension of \mathcal{H}_g is equal to 4g-5.

McCullough [12] informed the author that Hatcher has obtained (not published) this result by investigating the action of \mathcal{H}_g on the disk complex defined by McCullough [11]. In this paper, by making an essential use of the construction of Mess given in [9], we prove the result and give an explicit description of a subgroup of \mathcal{H}_q that attains vcd(\mathcal{H}_q).

We also give some remarks on the relationship between \mathcal{H}_g and the outer automorphism group of the free group of rank g. We denote by F_g the free group of rank g and by $Out(F_g)$ its outer automorphism group. There is a natural homomorphism from \mathcal{H}_g to $Out(F_g)$ defined

²⁰⁰⁰ Mathematics Subject Classification. Primary 57N10; Secondary 57N05, 20F38.

Key words and phrases. Virtual cohomological dimension, Euler number, 3-dimensional handlebody, mapping class group.

S. HIROSE

by the action of diffeomorphisms on the fundamental group of H_g , which is a surjection [4]. Culler and Vogtmann [3] showed that $vcd(Out(F_g)) = 2g - 3$. This fact indicates that the kernel of the above surjection is, in some sense, big. In fact, McCullough [10] showed that the kernel of the above surjection is not finitely generated.

For any finitely generated abelian group *A*, we define the *rank* of *A* by $\operatorname{rk}_{\mathbb{Z}}(A) = \dim_{\mathbb{Q}}(\mathbb{Q} \otimes_{\mathbb{Z}} A)$. For a torsion-free group *G* of finite homological type, we define the *Euler characteristic* $\chi(G)$ (see [2]) by

$$\chi(G) = \sum_{i} (-1)^{i} \operatorname{rk}_{\mathbb{Z}}(H_{i}(G)) \,.$$

For a group G of finite homological type which may have torsion, we choose a torsion-free subgroup \hat{G} of finite index, and define $\chi(G)$ by

$$\chi(G) = \frac{\chi(\hat{G})}{(G:\hat{G})},$$

where $(G : \hat{G})$ denotes the index of \hat{G} in G. Since, \mathcal{H}_g is of type VFL [11], we can define $\chi(\mathcal{H}_g)$. Then we show the following result.

THEOREM 1.2. $\chi(\mathcal{H}_q) = 0.$

Harer and Zagier [6] calculated $\chi(\mathcal{M}_g)$, which turned out to be quite different from $\chi(\mathcal{H}_g)$. This result indicates considerable difference between \mathcal{M}_g and \mathcal{H}_g .

Finally, the author would like to express his gratitude to Professors T. Akita, N. Ivanov, N. Kawazumi, J. McCarthy and D. McCullough for their helpful comments. A part of this paper was written while the author stayed at Michigan State University as a visiting scholar sponsored by the Japanese Ministry of Education, Culture, Sports, Science and Technology. He is grateful to the Department of Mathematics, Michigan State University, for its hospitality.

2. Proof of Theorem 1.1. In general, for an oriented C^{∞} -manifold A and its subset B, by Diff⁺(A) we denote the group of all orientation preserving diffeomorphisms of A, by Diff⁺(A, fix B) the group of elements of Diff⁺(A) whose restriction to Bare the identity map, and by Diff⁺(A, B) the group of elements of Diff⁺(A) which preserve B as a set. For a disk D in ∂H_g , we define $\mathcal{H}_{g,1} = \pi_0(\text{Diff}^+(H_g, \text{fix } D))$, and $\mathcal{M}_{g,1} = \pi_0(\text{Diff}^+(\partial H_g, \text{fix } D))$. For the center p of the disk D, we define $\mathcal{H}_g^1 = \pi_0(\text{Diff}^+(H_g, \text{fix } \{p\}))$, and $\mathcal{M}_g^1 = \pi_0(\text{Diff}^+(\partial H_g, \text{fix } \{p\}))$. Let D_1, D_2, \ldots, D_g be the cocores of 1-handles which are used to construct H_g . These disks D_1, D_2, \ldots, D_g are properly embedded disks in H_g . Let E_1, \ldots, E_{g-1} and C be properly embedded disks as indicated in Figure 1.

We introduce some specific elements of \mathcal{H}_g . For a disk D properly embedded in H_g , let N be a regular neighborhood of D in H_g . We parametrize N by $\phi : [-1, 1] \times D^2 \to N$ such that $\phi(\{0\} \times D^2) = D$ and $\phi([-1, 1] \times \partial D^2)$ is an annulus in ∂H_g . Let ψ be a diffeomorphism of $[-1, 1] \times D^2$ defined by $\psi(t, r, \theta) = (t, r, \theta + (1 - t)\pi)$, where (r, θ) is a polar coordinate of D^2 . The map $\delta_D : H_g \to H_g$, defined by $\delta_D(x) = \phi \circ \psi \circ \phi^{-1}(x)$ if

THREE-DIMENSIONAL HANDLEBODY

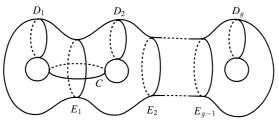


FIGURE 1

 $x \in N$, = x if $x \notin N$, is an orientation preserving diffeomorphism of H_g , which we call *a disk twist* about *D*. The isotopy class of δ_D , denoted by d_D , is an element of \mathcal{H}_g , which we call *a disk twist* about *D*. For an annulus *A* properly embedded in H_g , let $\phi : [-1, 1] \times S^1 \times [0, 1] \rightarrow N$ be a parametrization of a regular neighborhood *N* of *A* in H_g such that $\phi|_{\{0\} \times S^1 \times [0, 1]}$ is a parametrization of *A*, and let ψ be the diffeomorphism on $[-1, 1] \times S^1 \times [0, 1]$ defined by $\psi(t, \theta, s) = (t, \theta + (1 - t)\pi, s)$, where θ is a polar coordinate of S^1 . We define $\alpha_A \in \text{Diff}^+(H_g)$, which we call *an annulus twist* about *A*, in the same manner as the definition of δ_D . The isotopy class of α_A , denoted by a_A , is an element of \mathcal{H}_g , which is called *an annulus twist* about *A*.

We now introduce the following terminologies for later use. Let N be a regular neighborhood of ∂H_g in H_g , and A be an annulus in ∂H_g . We parametrize N as $\phi : [0, 1] \times \partial H_g \rightarrow N$ such that $\phi(\{0\} \times \partial H_g) = \partial H_g$ and $\phi|_{\{0\} \times \partial H_g}$ is an identity map. The set $A' = \phi(\partial A \times [0, 1] \cup A \times \{1\})$ is an annulus properly embedded in H_g . We say that "we *push* A *into* H_g " if we obtain A' from A. Similarly, for a disk D in ∂H_g , we say that "we *push* D *into* H_g " if we obtain a disk D' from D in the same manner as above.

Mess [9] discovered certain subgroups B_g , $B_{g,1}$, called *Mess subgroups*, of the mapping class groups \mathcal{M}_g , $\mathcal{M}_{g,1}$, respectively, which are defined in a recursive manner as follows (this definition is quoted from §6.3 of [8]):

Step 0: Let B_2 be the subgroup of \mathcal{M}_2 generated by Dehn twists about any three pairwise disjoint and pairwise nonisotopic simple closed curves C_0 , C_1 , C_2 in ∂H_2 .

Step 1_g: We assume that B_g $(g \ge 2)$ is already defined. There is a surjection from Diff⁺ $(\partial H_g, \text{fix } D)$ to Diff⁺ (∂H_g) defined by forgetting the disk D, which induces a surjection $f : \mathcal{M}_{g,1} \to \mathcal{M}_g$. Let $B_{g,1}$ be the preimage of B_g under f.

Step 2_g : By restricting each diffeomorphism, we obtain a homomorphism ρ : Diff⁺ $(\partial H_g, \text{fix } D) \rightarrow \text{Diff}^+(\partial H_g \setminus \text{int } D, \text{fix } \partial D)$. We consider an embedding $\partial H_g \setminus \text{int } D$ into ∂H_{g+1} and identify $\partial H_g \setminus \text{int } D$ with its image. By extending each diffeomorphism of $\partial H_g \setminus \text{int } D$, whose restriction on ∂D is the identity, across the complement of $\partial H_g \setminus \text{int } D$ in ∂H_{g+1} , we obtain a homomorphism ι : Diff⁺ $(\partial H_g \setminus \text{int } D, \text{fix } \partial D) \rightarrow \text{Diff}^+(\partial H_{g+1})$. The composition $\iota \circ \rho$ induces a homomorphism $i: \mathcal{M}_{g,1} \rightarrow \mathcal{M}_{g+1}$. In the complement of $\partial H_g \setminus \text{int } D$ in ∂H_{g+1} , we choose a nontrivial simple closed curve C that is not isotopic into $\partial H_g \setminus \text{int } D$ and consider the Dehn twist $t \in \mathcal{M}_{g+1}$ about this curve. Let T be the infinite cyclic group generated by t. We define B_{g+1} as the group generated by $i(B_{g,1})$ and T.

S. HIROSE

Mess [9] showed the following result (see also Corollary 6.3B of [8]).

PROPOSITION 2.1. The cohomological dimension of B_q is equal to 4g - 5.

We will first show the following lemma, which is remarked by Mess [9, p. 4] without a proof.

LEMMA 2.2. \mathcal{H}_q contains a subgroup isomorphic to B_q .

REMARK 2.3. The definition of B_g involves some choices. This lemma means that, with some good choices, B_g is realized as a subgroup of \mathcal{H}_g .

PROOF. Along the steps of the definition of B_g , we will check that B_2 , $B_{g,1}$, B_{g+1} can be constructed as subgroups of \mathcal{H}_2 , $\mathcal{H}_{g,1}$, \mathcal{H}_{g+1} , respectively. In each step, we use the same notation as used in definitions of B_g and $B_{g,1}$.

Step 0: We choose $C_0 = \partial D_1$, $C_1 = \partial C$, $C_2 = \partial D_2$. Then $B_2 \subset \mathcal{H}_2$.

Step 1_g: We assume that $B_g \subset \mathcal{H}_g$. Let g_1, \ldots, g_n be generators of B_g . For each g_i , we can choose an element \tilde{g}_i of $\mathcal{H}_{g,1}$ such that $f(\tilde{g}_i) = g_i$. By the definition, $B_{g,1}$ is generated by the kernel of f and $\tilde{g}_1, \ldots, \tilde{g}_n$. In order to obtain generators for the kernel of f, we consider the following two short exact sequences:

(S1)
$$1 \longrightarrow \mathbf{Z} \longrightarrow \mathcal{M}_{q,1} \xrightarrow{\alpha} \mathcal{M}_{q}^{1} \longrightarrow 1$$
,

(S2)
$$1 \longrightarrow \pi_1(\partial H_g, p) \xrightarrow{\beta} \mathcal{M}_g^1 \xrightarrow{\gamma} \mathcal{M}_g \longrightarrow 1.$$

The group Z in (S1) is an infinite cyclic group generated by the Dehn twist d about ∂D . The homomorphism α is induced by the homomorphism from Diff⁺ $(\partial H_q, \text{ fix } D)$ to Diff⁺(∂H_q , fix{p}) defined by collapsing D into a point p. The sequence (S2) is introduced by Birman [1]. The homomorphism γ is induced by the homomorphism from Diff⁺(∂H_g , fix $\{p\}$ to Diff⁺ (∂H_g) defined by forgetting the point p. The group $\pi_1(\partial H_g, p)$ is generated by simple loops in ∂H_g with base point p. Let l_1, \ldots, l_{2g} be simple loops in ∂H_g , whose homotopy classes generate $\pi_1(\partial H_g, p)$. For each l_i , let L_i be an annulus in ∂H_g , which is a regular neighborhood of l_i such that $L_i \supset D \ni p$. ∂L_i consists of two simple closed curves l_i^1 and l_i^2 in ∂H_q . The homomorphism β is defined so that it maps a homotopy class of l_i (denote by $[l_i]$ for short) to that of $\lambda_i = (+\text{Dehn twist about } l_i^1) \times (-\text{Dehn twist about } l_i^2)$, which is also an element of Diff⁺(∂H_a , fix D), and α (an element of $\mathcal{M}_{a,1}$ represented by λ_i = $\beta([l_i])$. Let \tilde{l}_i be an element of $\mathcal{M}_{q,1}$ represented by λ_i . The kernel of f is generated by d and $\tilde{l}_1, \ldots, \tilde{l}_{2q}$, since it is equal to α^{-1} (the kernel of γ) = α^{-1} (the image of β). Let D' be a disk in H_g obtained by pushing D into H_g , and $\delta_{D'}$ be the disk twist about D'. Let L'_i be an annulus obtained by pushing L_i into H_g , and $\alpha_{L'_i}$ be the annulus twist about L'_i . The diffeomorphisms $\delta_{D'}$ and $\alpha_{L'}$ are elements of Diff⁺(H_q , fix D), whose restrictions to ∂H_q represent d and \tilde{l}_i , respectively. This fact shows that the kernel of f is included in $\mathcal{H}_{q,1}$. Hence, $B_{q,1} \subset \mathcal{H}_{q,1}$.

Step 2_g : It is easy to see that $i(B_{g,1}) \subset \mathcal{H}_{g+1}$. If we choose $C = \partial D_{g+1}$, then $t \in \mathcal{H}_{g+1}$. Therefore, $B_{g+1} \subset \mathcal{H}_{g+1}$.

Along the line of the proof of Theorem 6.4.A in [8], we will prove Theorem 1.1.

THREE-DIMENSIONAL HANDLEBODY

PROOF OF THEOREM 1.1. There is a natural homomorphism $\mathcal{M}_g \to \operatorname{Aut}(H_1(\partial H_g, \mathbb{Z}/3\mathbb{Z}))$ defined by the action of diffeomorphisms on $H_1(\partial H_g, \mathbb{Z}/3\mathbb{Z})$. Let Γ be the kernel of this homomorphism. It is a classical result that Γ is torsion-free (see, e.g., Ivanov [7, Corollary 1.5]). Therefore, Γ , $\mathcal{H}_g \cap \Gamma$ and $B_g \cap \Gamma$ are finite index torsion-free subgroups of \mathcal{M}_g , \mathcal{H}_g and B_g , respectively. By the definition of virtual cohomological dimension, $\operatorname{vcd}(\mathcal{M}_g) = \operatorname{cd}(\Gamma)$, $\operatorname{vcd}(\mathcal{H}_g) = \operatorname{cd}(\mathcal{H}_g \cap \Gamma)$ and $\operatorname{vcd}(B_g) = \operatorname{cd}(B_g \cap \Gamma)$. By Harer [5, Theorem 4.1], $\operatorname{vcd}(\mathcal{M}_g) = 4g - 5$, and hence, $\operatorname{cd}(\Gamma) = 4g - 5$. By Proposition 2.1, $\operatorname{vcd}(B_g) = \operatorname{cd}(B_g) = 4g - 5$, and hence, $\operatorname{cd}(\mathcal{H}_g \cap \Gamma) \leq \operatorname{cd}(\Gamma)$. These facts show the theorem.

3. Proof of Theorem 1.2. McCullough defined a *disk complex* L in [11] and used it to estimate $vcd(\mathcal{H}_g)$. We here review the definition of L. By a *disk* in H_g , we mean a properly embedded 2-disk in H_g . A disk D is called *essential* when ∂D does not bound a 2-disk in ∂H_g . The disk complex L of H_g is a simplicial complex whose vertices are the isotopy classes of essential disks in H_g , and whose simplices are defined by the rule that a collection of n + 1 distinct vertices spans an *n*-simplex if and only if it admits a collection of representatives which are pairwise disjoint. McCullough showed the following Theorem in [11, Theorem 5.3].

THEOREM 3.1 ([11]). The disk complex L of H_g is contractible.

We use the following Propositions regarding Euler characteristics of groups (see, e.g., [2, Proposition §IX 7.3]).

PROPOSITION 3.2. Let $1 \to G' \to G \to G'' \to 1$ be a short exact sequence of groups, where G' and G'' are of finite homology type. If G is virtually torsion-free, then G is of finite homological type and $\chi(G) = \chi(G')\chi(G'')$.

PROPOSITION 3.3. Let X be a contractible simplicial complex on which G act simplicially. For each simplex σ of X, let $G_{\sigma} = \{g \in G \mid g\sigma = \sigma\}$. If X has only finitely many cells mod G, and, for each simplex σ of X, G_{σ} is of finite homological type, then

$$\chi(G) = \sum_{\sigma \in \mathcal{E}} (-1)^{\dim \sigma} \chi(G_{\sigma}) \,,$$

where \mathcal{E} is a set of representatives for the cells of $X \mod G$.

For each simplex $\sigma = \langle D_0, \ldots, D_n \rangle$ of L, Proposition 6.5 of [11] shows that $G_{\sigma} = \pi_0 \text{Diff}^+(H_g, D_0 \cup \cdots \cup D_n)$. For the same simplex σ , let Γ_{σ} be the graph defined as follows. The vertices of Γ_{σ} correspond to the components of $H_g \setminus D_0 \cup \cdots \cup D_n$. Each edge corresponds to one of D_0, \ldots, D_n and connects the vertices corresponding to the components attached along this disk. Let $H_g/D_0 \cup \cdots \cup D_n$ be the space obtained from H_g by collapsing each D_i to one point, and δ be a homomorphism from G_{σ} to $\pi_0 \text{Diff}^+(H_g/D_0 \cup \cdots \cup D_n, D_0/D_0 \cup \cdots \cup D_n/D_n)$ which is induced by collapsing each D_i to one point. Let \mathbb{Z}^{n+1} denote the free abelian group generated by disk twists about D_0, \ldots, D_n . Then we have the following exact

S. HIROSE

sequence:

(S3)

$$1 \longrightarrow \mathbf{Z}^{n+1} \longrightarrow G_{\sigma} \stackrel{\delta}{\longrightarrow} \pi_0 \mathrm{Diff}^+(H_g/D_0 \cup \cdots \cup D_n, D_0/D_0 \cup \cdots \cup D_n/D_n) \longrightarrow 1.$$

Let ε be the natural homomorphism from $\pi_0 \text{Diff}^+(H_g/D_0 \cup \cdots \cup D_n, D_0/D_0 \cup \cdots \cup D_n/D_n)$ to the group of automorphisms of Γ_{σ} . Let A_{σ} be the image of ε , which is a finite group, since the group of automorphisms of Γ_{σ} is a finite group. By H'_g we denote the 3-manifold obtained by cutting H_g along D_0, \ldots, D_n , and by $D_0^1, D_0^2, \ldots, D_n^1, D_n^2$ the disks on $\partial H'_g$ obtained as a result of cutting, and by $H'_g/D_0^1 \cup D_0^2 \cup \cdots \cup D_n^1 \cup D_n^2$ the space obtained from H'_g by collapsing each D_j^i ($i = 1, 2, j = 0, \ldots, n$) to one point. Then we obtain the following exact sequence:

$$1 \longrightarrow \pi_0 \text{Diff}^+(H'_g/D_0^1 \cup D_0^2 \cup \dots \cup D_n^1 \cup D_n^2,$$
(S4)
$$fix \ D_0^1/D_0^1 \cup D_0^2/D_0^2 \cup \dots \cup D_n^1/D_n^1 \cup D_n^2/D_n^2)$$

$$\longrightarrow \pi_0 \text{Diff}^+(H_g/D_0 \cup \dots \cup D_n, D_0/D_0 \cup \dots \cup D_n/D_n) \xrightarrow{\varepsilon} A_{\sigma} \longrightarrow 1.$$

Since $\chi(\mathbf{Z}^{n+1}) = \chi((S^1)^{n+1}) = 0$, by applying Proposition 3.2 to (S3) and (S4), we obtain $\chi(G_{\sigma}) = 0$. Theorem 1.2 now follows from the above observation together with Theorem 3.1 and Proposition 3.3.

REFERENCES

- J. S. BIRMAN, Mapping class groups and their relationship to braid groups, Comm. Pure and Appl. Math. 22 (1969), 213–238.
- [2] K. S. BROWN, Cohomology of groups, Grad. Texts in Math. 87, Springer-Verlag, New York-Berlin, 1982.
- [3] M. CULLER AND K. VOGTMANN, Moduli of graphs and automorphisms of free groups, Invent. Math. 84 (1986), 91–119.
- [4] H. B. GRIFFITHS, Automorphisms of a 3-dimensional handlebody, Abh. Math. Sem. Univ. Hamburg 26 (1964), 191–210.
- [5] J. L. HARER, The virtual cohomological dimension of the mapping class group of an orientable surface, Invent. Math. 84 (1986), 157–176.
- [6] J. L. HARER AND D. ZAGIER, The Euler characteristic of the moduli space of curves, Invent. Math. 85 (1986), 457–485.
- [7] N. V. IVANOV, Subgroups of Teichmüller modular groups, Transl. Math. Monogr. 115, American Mathematical Society, Providence, RI, 1992.
- [8] N. V. IVANOV, Mapping class groups, Handbook of geometric topology, 523–633, North-Holland, Amsterdam, 2002.
- [9] G. MESS, Unit tangent bundle subgroups of the mapping class groups, preprint (1990).
- [10] D. MCCULLOUGH, Twist groups of compact 3-manifolds, Topology 24 (1985), 461-474.
- [11] D. MCCULLOUGH, Virtually geometrically finite mapping class groups of 3-manifolds. J. Differential Geom. 33 (1991), 1–65.
- [12] D. MCCULLOUGH, private communication.
- [13] J.-P. SERRE, Cohomology des groupes discrets, Prospects in Mathematics (Proc. Sympos., Princeton Univ., Princeton, N. J., 1970), 77–169, Ann. Math. Studies 70, Princeton Univ. Press, Princeton, N. J., 1971.

THREE-DIMENSIONAL HANDLEBODY

DEPARTMENT OF MATHEMATICS FACULTY OF SCIENCE AND ENGINEERING SAGA UNIVERSITY SAGA, 840–8502 JAPAN

E-mail address: hirose@ms.saga-u.ac.jp