2-Type flat integral submanifolds in $S^7(1)$

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Abstract. This paper determines all flat, mass-symmetric, 3-dimensional 2-type submanifolds of the unit sphere $S^{7}(1)$ which are integral submanifolds of the canonical contact structure.

Key words: integral submanifolds, finite type submanifolds.

1. Introduction

In [5,6] Bang-Yen Chen introduced the notion of submanifolds of finite type. Let M be a submanifold of Euclidean space E^n and Δ the Laplacian of the induced metric. M is said to be of *finite type* if its position vector field x has a decomposition of the form

$$x = x_0 + x_1 + \dots + x_k$$

where x_0 is a constant vector and $\Delta x_i = \lambda_i x_i$. Assuming the λ_i to be distinct we say that M is of k-type.

The theory of finite type submanifolds has become an area of active research. The first results on this subject have been collected in the book [6]; for a recent survey, see [7]. In particular, there is the problem of classification of low type submanifolds which lie in a hypersphere. Far from being solved in general, there are many partial results which contribute to the solution of this problem. For instance, by the well-known result of Takahashi [10], 1-type submanifolds are characterized as being minimal in a sphere.

However, classification of even 2-type spherical submanifolds seems to be virtually impossible. A compact submanifold M^n of a hypersphere S^m of E^{m+1} is said to be mass-symmetric if the center of mass of M^n in E^{m+1} is the center of S^m in E^{m+1} . Note that the only 2-type surface in S^3 is the flat torus $S^1(a) \times S^1(b)$, $a \neq b$, while a 2-type mass-symmetric integral surface in S^5 is locally the product of a circle and a helix of order 4, or

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the product of two circles [1]. Integral finite type surfaces in S^5 are also studied in [3], where a weaker assumption is used. On the other hand the codimension seems to play a crucial role in the characterization of low type spherical submanifolds of codimension greater than 1 and hence it seems to be necessary to use extra conditions. In [7] B.-Y. Chen gives a list of open problems and conjectures concerning submanifolds of finite type. He also gives a good survey of what is known about the classification of 2-type (spherical) submanifolds with arbitrary codimension.

This paper provides a contribution in codimension greater than 1 by classifying 2-type, mass-symmetric, flat integral 3-dimensional submanifolds of the unit sphere $S^7(1) \subset E^8$.

It is well-known [4] that an odd-dimensional sphere S^{2n+1} carries a contact structure, i.e., a global 1-form η such that $\eta \wedge (d\eta)^n \neq 0$. A submanifold of a contact manifold M^{2n+1} with contact form η is an *integral submanifold* if it is an integral submanifold of the 2*n*-dimensional subbundle defined by $\eta = 0$. It is well known that the maximum dimension of an integral submanifold is only *n* and hence of dimension at most 3 in S^7 . Moreover, contact transformations map integral submanifolds to integral submanifolds and hence integral submanifolds are fundamental objects in the geometry of contact manifolds. For a general discussion of these ideas see [4, Chap. III] or [9].

Theorem Let $x: M \to S^7 \subset E^8$ be an isometric immersion of a flat 3dimensional mass-symmetric 2-type integral submanifold M into S^7 . Then M lies fully in $S^7 \subset E^8 \cong \mathbb{C}^4$ and the position vector x = x(u, v, w) of Min E^8 is given by

$$x = \frac{\lambda}{\sqrt{\lambda^2 + 1}} \cos \frac{u}{\lambda} e_1 + \frac{1}{\sqrt{\sigma_2(\sigma_1 + \sigma_2)}} \sin(\lambda u - \sigma_2 v) e_2$$
$$+ \frac{1}{\sqrt{\rho_1(\rho_1 + \rho_2)}} \sin(\lambda u + \sigma_1 v + \rho_1 w) e_3$$
$$+ \frac{1}{\sqrt{\rho_2(\rho_1 + \rho_2)}} \sin(\lambda u + \sigma_1 v - \rho_2 w) e_4$$
$$+ \frac{\lambda}{\sqrt{\lambda^2 + 1}} \sin \frac{u}{\lambda} e_5 + \frac{1}{\sqrt{\sigma_2(\sigma_1 + \sigma_2)}} \cos(\lambda u - \sigma_2 v) e_6$$
$$+ \frac{1}{\sqrt{\rho_1(\rho_1 + \rho_2)}} \cos(\lambda u + \sigma_1 v + \rho_1 w) e_7$$

$$+\frac{1}{\sqrt{\rho_2(\rho_1+\rho_2)}}\cos(\lambda u+\sigma_1 v-\rho_2 w)e_8$$

with $\rho_1 = \frac{1}{2} \left(\sqrt{4c(2c-a) + d^2} + d \right)$, $\rho_2 = \frac{1}{2} \left(\sqrt{4c(2c-a) + d^2} - d \right)$, $\sigma_1 = c$, $\sigma_2 = c - a$, where a, c, d, λ are constants such that $-1 \le \lambda < 0$, $1 + \lambda^2 + ac - c^2 = 0$, $a \ge 0$, $a^2 \ge d^2$ and $\{e_1, e_2, e_3, e_4, e_5 = -Je_1, e_6 = -Je_2, e_7 = -Je_3, e_8 = -Je_4\}$ is an orthonormal basis of \mathbb{C}^4 .

2. Preliminaries

First we briefly describe the Sasakian structure on S^7 . We consider the space \mathbb{C}^4 of 4-complex variables. Let J denote its natural complex structure, namely by identifying $z = (x_1 + i \ y_1, \ldots, x_4 + i \ y_4) \in \mathbb{C}^4$ with $(x_1, \ldots, x_4, \ y_1, \ldots, y_4) \in E^8$, $Jz = (-y_1, \ldots, -y_4, \ x_1, \ldots, x_4)$. We give the unit sphere $S^7 = \{z \in \mathbb{C}^4 : |z| = 1\}$ its usual contact structure. Define a tangent vector field ξ , a 1-form η and a (1, 1) tensor field φ on S^7 as follows:

Let \langle , \rangle denote the metric on S^7 induced from \mathbb{C}^4 (so S^7 has constant sectional curvature 1),

$$\xi = -Jz, \ \eta(X) = \langle X, \xi \rangle \text{ and } \varphi = s \circ J$$

where s denotes the orthogonal projection from $T_z \mathbb{C}^4$ onto $T_z S^7$ and X an arbitrary tangent vector field on S^7 . Using these definitions, we obtain for all tangent vector fields X and Y on S^7 that

$$\varphi^{2}X = -X + \eta(X)\xi,$$

$$\eta(\xi) = 1, \ \eta(X) = \langle X, \xi \rangle, \ d\eta(\xi, X) = 0,$$

$$d\eta(X, Y) = \langle X, \varphi Y \rangle,$$

$$N = -2d\eta \otimes \xi,$$

(2.1)

where N is the Nijenhuis tensor of φ given by $N(X,Y) = [\varphi X, \varphi Y] + \varphi^2[X,Y] - \varphi[\varphi X,Y] - \varphi[X,\varphi Y]$. It is well-known [4] that these formulas imply that $(\varphi, \xi, \eta, \langle, \rangle)$ determines a Sasakian structure on S^7 . Therefore, we also have

$$\nabla'_X \xi = -\varphi X, \ (\nabla'_X \varphi) Y = \langle X, Y \rangle \xi - \eta(Y) X$$
(2.2)

where ∇' denotes the Levi-Civita connection of \langle , \rangle . For more details see [4].

A Riemannian manifold M, isometrically immersed in S^7 , is called an integral submanifold if η restructed to M vanishes. Some authors call integral submanifolds, C-totally real submanifolds. A direct consequence of the definition is that $\varphi(TM) \subset T^{\perp}M$ (i.e., that M is an anti-invariant submanifold of S^7), in particular, $d\eta = 0$ on M.

In this paper we consider the unit hypersphere $S^7(1) \subset \mathbb{C}^4 \cong E^8$ centered at the origin and with the Sasakian structure $(\varphi, \xi, \eta, \langle, \rangle)$.

Let

$$x: M \to S^7(1) \tag{2.3}$$

be an immersion of a 3-dimensional integral submanifold M into $S^7(1)$. Denote by $\overline{\nabla}$ the usual Levi-Civita connection of E^8 and by ∇ , ∇' the induced connections on M and $S^7(1)$, respectively. Let H, h, A and D denote the mean curvature vector, the second fundamental form, the Weingarten maps and the normal connection of M in E^8 , respectively. Finally, denote by H', h', A' and D' the corresponding quantities for M in $S^7(1)$. Then we have H = H' - x and, for any vector ζ normal to M in $S^7(1)$, $A_{\zeta} = A'_{\zeta}$. If X_1, X_2, X_3 is a local orthonormal basis of vector fields on M, then $\xi_i = \varphi X_i, i = 1, 2, 3, \xi_0 = \xi, x$ form a basis of the normal space of M in E^8 . For convenience, we put $(e_1, \ldots, e_8) = (X_1, X_2, X_3, \xi_1, \xi_2, \xi_3, \xi_0, x)$, and denote by $\{w_i\}, i = 1, \ldots, 8$ the dual frame of $\{e_i\}$ and by $\{w_i^j\}, i, j = 1, \ldots, 8$ the corresponding connection forms. Thus we have $\overline{\nabla}e_i = \sum_{i=1}^8 w_i^j e_j$. If A_s is the Weingarten maps with respect to ξ_s , then from [4, pp. 102–103], we have $A_i X_j = A_j X_i, i, j = 1, 2, 3$ and $A_0 = 0$. Thus, by means of straightforward calculation and using the Gauss-Weingarten formulas we obtain for the tangent vector fields X_i on M

$$\varphi h'(X_i, X_j) = -A_{\varphi X_j} X_i,$$

$$\langle h(X_i, X_j), \varphi X_k \rangle = \langle h(X_i, X_k), \varphi X_j \rangle.$$
 (2.4)

On the other hand, using the Gauss-Weingarten formulas, (2.2) and (2.4) we obtain $\sum_{\ell=1}^{8} w_{3+j}^{\ell}(e_i)e_{\ell} = \delta_{ij}e_7 + \sum_{\ell=1}^{6} w_j^{\ell}(e_i)\varphi e_{\ell}$, i, j = 1, 2, 3. Thus

$$w_{3+i}^{3+j} = w_i^j, \ w_{3+j}^7(e_i) = \delta_{ij}, \ w_{3+j}^8 = w_7^8 = 0, \ i, j = 1, 2, 3.$$
 (2.5)

The sectional curvature $K(X_i, X_j)$ of M determined by an orthonormal pair X_i, X_j is given by

$$K(X_i, X_j) = 1 + \sum_{\ell=1}^{3} (\langle A_\ell X_i, X_i \rangle \langle A_\ell X_j, X_j \rangle - \langle A_\ell X_i, X_j \rangle^2). \quad (2.6)$$

The covariant derivative ∇h is defined by

$$\bar{\nabla}h(X_i, X_j, X_k) = D_{X_i}h(X_j, X_k) - h(\nabla_{X_i}X_j, X_k) - h(X_j, \nabla_{X_i}X_k).$$

We say that the submanifold M is *C*-parallel if the vector $\overline{\nabla}h$ is parallel to the characteristic vector field ξ .

3. 2-type Submanifolds

Let M be a 3-dimensional integral submanifold of $S^{7}(1)$. In what follows we will always work with an orthonormal basis on a component of an open dense subset $U \subset M$ constructed in the following way. Let $p \in M$. Consider the function $f: UM_p \to \mathbb{R}: u \to f(u) = \langle h(u, u), \varphi u \rangle$, where UM_p is the unit sphere in the tangent space M_p . Since UM_p is compact, f attains an absolute maximum at a unit vector X_1 . We deduce from (2.4) that $\langle h(X_1, X_1), \varphi w \rangle = 0$ for $w \in UM_p$ with $\langle X_1, w \rangle = 0$. So X_1 is an eigenvector of $A_{\varphi X_1}$. Hence, since $A_{\varphi X_1}$ is symmetric we can also choose X_2 and X_3 as eigenvectors of $A_{\varphi X_1}$. If X_2 and X_3 are both eigenvectors of $A_{\varphi X_1}$ with the same eigenvalue, we choose X_2 as the vector in which the function f restricted to $\{u \in UM_p : \langle u, X_1 \rangle = 0\}$ attains an absolute maximum. So, in this case, we find that $\langle h(X_2, X_2), \varphi X_3 \rangle = 0$. Furthermore, we may still assume that X_2 and X_3 satisfy the following two properties, see [2]. $\langle h(X_2, X_2), \varphi X_2 \rangle \geq 0$, $\langle h(X_2, X_2), \varphi X_2 \rangle^2 \geq \langle h(X_3, X_3), \varphi X_3 \rangle^2$. Then with respect to such an orthonormal basis $\{X_1, X_2, X_3\}$, we can write the Weingarten maps $A_i = A_{\xi_i}$ $(\xi_i = \varphi X_i \ i = 1, 2, 3)$ at the point $p \in M$ in the following way:

$$A_{1} = \begin{bmatrix} \lambda_{1} & 0 & 0 \\ 0 & \lambda_{2} & 0 \\ 0 & 0 & \lambda_{3} \end{bmatrix}, A_{2} = \begin{bmatrix} 0 & \lambda_{2} & 0 \\ \lambda_{2} & a & b \\ 0 & b & c \end{bmatrix}, A_{3} = \begin{bmatrix} 0 & 0 & \lambda_{3} \\ 0 & b & c \\ \lambda_{3} & c & d \end{bmatrix}.$$
(3.1)

If the eigenvalues of A_1 have constant multiplicity on a neighborhood of p we extend this basis differentiably about p and define the open dense set U by this property. Note that we have, from the above arguments,

$$\lambda_1, \ a \ge 0, \ a^2 \ge d^2 \quad \text{at} \quad p. \tag{3.2}$$

Also at the point p, since f attains an absolute maximum in the direction X_1 , we know that the function f_2 defined by $f_2(\theta) = f(\cos \theta X_1 + \sin \theta X_i)$, i = 2, 3 has a relative maximum at the origin. Hence $f_2''(0) \leq 0$, which implies that

$$\lambda_1 \ge 2\lambda_2, \ \lambda_1 \ge 2\lambda_3 \quad \text{at} \quad p.$$
 (3.3)

We remark that if $\lambda_2 = \lambda_3$ on a component of U we can choose the basis in such a way that b = 0 on this component.

We now consider the hypothesis that M is 2-type and mass-symmetric. Let Δ be the Laplacian of M associated with the induced metric. This Laplacian can be extended componentwise to E^8 -valued smooth maps u of M as follows:

$$\Delta u = \sum_{i=1}^{3} (\bar{\nabla}_{\nabla_{X_i} X_i} u - \bar{\nabla}_{X_i} \bar{\nabla}_{X_i} u).$$
(3.4)

The position vector x of M with respect to the origin of E^8 is given by the immersion (2.3) and can be written as follows:

$$x = x_1 + x_2, \ \Delta x_1 = \mu_1 x_1, \ \Delta x_2 = \mu_2 x_2$$
 (3.5)

where x_1, x_2 are non-constant E^8 -valued maps on M. Note that $A_x = -I$ and Dx = 0. Moreover, since $H = \sum_{i=1}^3 \frac{1}{3} (\operatorname{tr} A_i) \xi_i - x$ and $\Delta x = -3H$, by using (3.5) we find

$$\Delta H = (\mu_1 + \mu_2) \sum_{i=1}^{3} \alpha_i \xi_i + \left(\frac{\mu_1 \mu_2}{3} - (\mu_1 + \mu_2)\right) x \tag{3.6}$$

where $\alpha_i = \frac{1}{3}$ tr A_i , i = 1, 2, 3. On the other hand applying (3.4) to H we have, by direct computation

$$\Delta H = \sum_{i,j} [(\Delta \alpha_i)\xi_i + \alpha_i \Delta^D \xi_i + 2A_i \text{ grad } \alpha_i + \alpha_i (\nabla_{X_j} A_i) X_j - \alpha_i (\operatorname{tr} A_i A_j) \xi_j - 2D_{\operatorname{grad} \alpha_i} \xi_i + \alpha_i A_{D_{X_j} \xi_i} X_j + 3\alpha_i \xi_i - 3 \|H\|^2 x]$$
(3.7)

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where

$$\Delta^{D}\xi_{i} = \sum_{j=1}^{3} (D_{\nabla_{X_{j}}X_{j}}\xi_{i} - D_{X_{j}}D_{X_{j}}\xi_{i}).$$
(3.8)

Since Dx=0, we have that $D\xi_i$ is perpendicular to x. So $\langle \Delta^D \xi_i, x \rangle = 0$. Now combining (3.6) with (3.7) we obtain from the *x*-component that $||H||^2 = \frac{1}{3}(\mu_1 + \mu_2) - \frac{\mu_1\mu_2}{9}$. Thus M has constant mean curvature, (for this well-known result, see [6, p. 274]) and so we have

$$\alpha_1^2 + \alpha_2^2 + \alpha_3^2 = \text{const.}$$
(3.9)

Also, from the tangential component we have

$$\sum_{i,j=1}^{3} (2A_j \text{ grad } \alpha_j + \alpha_j (\nabla_{X_i} A_j) X_i + \alpha_j A_{D_{X_i} \xi_j} X_i) = 0.$$
(3.10)

Now using the Codazzi equation

$$(\nabla_{X_i} A_s) X_j - A_{D_{X_i} \xi_s} X_j - (\nabla_{X_j} A_s) X_i + A_{D_{X_j} \xi_s} X_i = 0$$
(3.11)

we obtain

grad tr
$$A_s - \sum_{i,j=1}^{3} (\operatorname{tr} A_i w_s^i(X_j) X_j + (\nabla_{X_j} A_s) X_j - A_{D_{X_j} \xi_s} X_j) = 0.$$

(3.12)

From (3.9),

$$\sum_{i=1}^{3} (\text{tr } A_i) \text{grad tr } A_i = 0.$$
 (3.13)

Using (3.12) we obtain

$$\sum_{i,j} \alpha_j (\nabla_{X_i} A_j) X_i = \sum_{i,j} \alpha_j A_{D_{X_i} \xi_j} X_i.$$

Thus (3.10) becomes $\sum_{i,j} (A_i \text{ grad } \alpha_i + \alpha_i A_{D_{X_j}\xi_i} X_j) = 0$, or

$$\sum_{i,j} A_i(\beta_i^j X_j) = 0$$
 (3.14)

where for convenience we have put

$$\beta_j^i = X_i \alpha_j - \sum_k \alpha_k w_j^k(X_i). \tag{3.15}$$

Now from (3.1) and (3.14) we obtain the following useful equations

$$\lambda_{1}\beta_{1}^{1} + \lambda_{2}\beta_{2}^{2} + \lambda_{3}\beta_{3}^{3} = 0,$$

$$\lambda_{2}\beta_{1}^{2} + \lambda_{2}\beta_{2}^{1} + a\beta_{2}^{2} + b\beta_{2}^{3} + b\beta_{3}^{2} + c\beta_{3}^{3} = 0,$$

$$\lambda_{3}\beta_{1}^{3} + b\beta_{2}^{2} + c\beta_{2}^{3} + \lambda_{3}\beta_{3}^{1} + c\beta_{3}^{2} + d\beta_{3}^{3} = 0.$$
(3.16)

We continue with some further calculations. Combining the ξ -component of (3.6) and (3.7) we obtain

$$\sum_{i=1}^{3} \langle \alpha_i \Delta^D \xi_i - 2D_{\text{grad } \alpha_i} \xi_i, \xi \rangle = 0$$

which by direct computation becomes

$$\sum_{i=1}^{3} \beta_i^i = 0. (3.17)$$

Also (3.13) gives

$$\sum_{i=1}^{3} \alpha_i \beta_i^j = 0, \ j = 1, 2, 3.$$
(3.18)

Finally, combining the ξ_i -components, i = 1, 2, 3, of (3.6) and (3.7) we have the following.

From the ξ_1 -component

$$\Delta \alpha_{1} + \sum_{i,j} [\alpha_{1}(1 + w_{1}^{2}(X_{i})^{2} + w_{1}^{3}(X_{i})^{2}) + \alpha_{2}(X_{i}w_{1}^{2}(X_{i}) - w_{1}^{2}(X_{j})w_{i}^{j}(X_{i}) + w_{1}^{3}(X_{i})w_{2}^{3}(X_{i})) + \alpha_{3}(X_{i}w_{1}^{3}(X_{i}) - w_{1}^{3}(X_{j})w_{i}^{j}(X_{i}) - w_{1}^{2}(X_{i})w_{2}^{3}(X_{i})) + 2(X_{i}\alpha_{j})w_{1}^{j}(X_{i}) - \alpha_{i} \text{tr } A_{i}A_{1}] = \alpha_{1}(\mu_{1} + \mu_{2} - 3). \quad (3.19)$$

From the ξ_2 -component

$$\Delta \alpha_2 + \sum_{i,j} [\alpha_1(w_1^2(X_j)w_i^j(X_i) - X_iw_1^2(X_i) + w_1^3(X_i)w_2^3(X_i)) + \alpha_2(1 + w_1^2(X_i)^2 + w_2^3(X_i)^2)$$

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+
$$\alpha_3(X_i w_2^3(X_i) - w_2^3(X_j) w_i^j(X_i) + w_1^2(X_i) w_1^3(X_i))$$

+ $2(X_i \alpha_j) w_2^j(X_i) - \alpha_i \text{ tr } A_i A_2] = \alpha_1(\mu_1 + \mu_2 - 3).$ (3.20)

From the ξ_3 -component

$$\begin{aligned} \Delta \alpha_3 + \sum_{i,j} [\alpha_1(X_i w_3^1(X_i) + w_1^3(X_j) w_i^j(X_i) - w_1^2(X_i) w_2^3(X_i)) \\ + \alpha_2(X_i w_3^2(X_i) + w_1^2(X_i) w_1^3(X_i) + w_2^3(X_j) w_i^j(X_i)) \\ + \alpha_3(1 + w_1^3(X_i)^2 + w_2^3(X_i)^2) \\ + 2(X_i \alpha_j) w_3^j(X_i) - \alpha_i \text{ tr } A_i A_3] &= \alpha_3(\mu_1 + \mu_2 - 3). (3.21) \end{aligned}$$

Now set

$$E_{1}(X_{i}) = X_{i}\lambda_{1}$$

$$E_{2}(X_{i}) = (\lambda_{1} - 2\lambda_{2})w_{1}^{2}(X_{i})$$

$$E_{3}(X_{i}) = (\lambda_{1} - 2\lambda_{3})w_{1}^{3}(X_{i})$$

$$E_{4}(X_{i}) = (\lambda_{2} - \lambda_{3})w_{2}^{3}(X_{i}) - bw_{1}^{2}(X_{i}) - cw_{1}^{3}(X_{i})$$

$$E_{5}(X_{i}) = X_{i}\lambda_{2} - aw_{1}^{2}(X_{i}) - bw_{1}^{3}(X_{i})$$

$$E_{6}(X_{i}) = X_{i}\lambda_{3} - cw_{1}^{2}(X_{i}) - dw_{1}^{3}(X_{i})$$

$$E_{7}(X_{i}) = X_{i}a + 3\lambda_{2}w_{1}^{2}(X_{i}) - 3bw_{2}^{3}(X_{i})$$

$$E_{8}(X_{i}) = X_{i}b + \lambda_{2}w_{1}^{3}(X_{i}) + (a - 2c)w_{2}^{3}(X_{i})$$

$$E_{9}(X_{i}) = X_{i}c + \lambda_{3}w_{1}^{2}(X_{i}) + (2b - d)w_{2}^{3}(X_{i})$$

$$E_{10}(X_{i}) = X_{i}d + 3\lambda_{3}w_{1}^{3}(X_{i}) + 3cw_{2}^{3}(X_{i}).$$
(3.22)

Applying the Codazzi equation (3.11) successively for all values of (s, i, j) we obtain $(i) = E_{i}(X_{i}) = E_{i}(X_{i}) = E_{i}(X_{i})$

and in addition

$$3\beta_1^i = E_1(X_i) + E_5(X_i) + E_6(X_i)$$

$$3\beta_2^i = E_2(X_i) + E_7(X_i) + E_9(X_i)$$

$$3\beta_3^i = E_3(X_i) + E_8(X_i) + E_{10}(X_i).$$
(3.24)

Thus by using (3.23) we observe that $\beta_i^j = \beta_j^i$, i, j = 1, 2, 3.

4. Proof of the Theorem

Now we assume that M is flat and continue with some more calculations. From (2.6) and (3.1) we obtain

$$1 + \lambda_1 \lambda_2 - \lambda_2^2 = 0$$

$$1 + \lambda_1 \lambda_3 - \lambda_3^2 = 0$$

$$1 + \lambda_2 \lambda_3 + ac + bd - b^2 - c^2 = 0$$
(4.1)

and from these $(\lambda_2 - \lambda_3)(\lambda_1 - \lambda_2 - \lambda_3) = 0$. If $\lambda_2 \neq \lambda_3$, then $\lambda_1 = \lambda_2 + \lambda_3$. But from (3.3) we obtain $\lambda_2 + \lambda_3 \geq 2\lambda_2$ and $\lambda_2 + \lambda_3 \geq 2\lambda_3$ at p. Thus $\lambda_2 = \lambda_3$, a contradiction. So $\lambda_2 = \lambda_3 = \lambda$ and then, from our initial discussion in Section 3, we have also b = 0. Now (4.1) becomes

$$1 + \lambda_1 \lambda - \lambda^2 = 0
 1 + \lambda^2 + ac - c^2 = 0.
 (4.2)$$

From these relations we have that $\lambda \neq 0$, $\lambda_1 \neq \lambda$, $\lambda_1 \neq 2\lambda$, $c \neq 0$ and $a \neq c$. Also using (3.3) we have $-1 \leq \lambda < 0$ at p.

Now from (3.16) and (3.17) we obtain $\beta_1^1 = 0$ and $\beta_3^3 = -\beta_2^2$. Also, since $\Sigma_i \alpha_i^2 \neq 0$ and $\beta_i^j = \beta_j^i$, from (3.18) we get

$$\beta_2^2 \left[(\beta_1^2)^2 - (\beta_1^3)^2 + \frac{c-a}{\lambda} \beta_1^3 \beta_2^3 \right] = 0.$$
(4.3)

Lemma 1 $\beta_2^2 = -\beta_3^3 = 0.$

Proof. Suppose $\beta_2^2 \neq 0$. Then from (4.3) we have

$$(\beta_1^2)^2 - (\beta_1^3)^2 + \frac{c-a}{\lambda}\beta_1^3\beta_2^3 = 0.$$
(4.4)

From (3.18) by using (3.16) we obtain

$$(c^{2} - a^{2} + d^{2})\beta_{2}^{2} - 2cd\beta_{2}^{3} = 0,$$

$$((3\lambda^{2} - 1)(c - a) + 2\lambda^{2}(a + c))\beta_{2}^{2} + 2\lambda^{2}d\beta_{2}^{3} = 0,$$

$$(\lambda^{2} - 1)d\beta_{2}^{2} + (2\lambda^{2}(a + c) - 2c(3\lambda^{2} - 1))\beta_{2}^{3} = 0.$$
(4.5)

If d = 0, from (4.5) we have a + c = 0 and $3\lambda^2 - 1 = 0$. Thus $\alpha_1 = \alpha_2 = \alpha_3 = 0$, a contradiction.

Thus $d \neq 0$, and from (4.5) we have $\beta_2^3 = \frac{c^2 - a^2 + d^2}{2cd}\beta_2^2$, while using (4.4) and (3.16) we obtain

$$d^2 = \frac{(a+c)^2(a-2c)}{a}$$

Also from (4.5) we obtain $\lambda^2 = \frac{a}{a-2c}$ and from (4.1) $a = \frac{2(c^2-1)}{c}$. Thus finally we have

$$\lambda^2 = 1 - c^2, \quad a = \frac{2(c^2 - 1)}{c}, \quad d^2 = \frac{(3c^2 - 2)^2}{c^2(1 - c^2)}$$
(4.6)

and from (3.9) we conclude that λ, a, c, d are constant.

Now from (3.15) we obtain

$$egin{aligned} &3eta_1^i = -rac{3c^2-2}{c}w_1^2(X_i) - dw_1^3(X_i),\ &3eta_2^i = -rac{3c^2-2}{\lambda}w_1^2(X_i) - dw_2^3(X_i),\ &3eta_3^i = -rac{3c^2-2}{\lambda}w_1^3(X_i) + rac{3c^2-2}{c}w_2^3(X_i). \end{aligned}$$

From (4.6) and (3.16) we obtain

$$\beta_1^2 = \frac{2-c^2}{2\lambda c}\beta_2^2, \quad \beta_2^3 = \frac{c(3c^2-2)}{2d(1-c^2)}\beta_2^2, \quad \beta_1^3 = \frac{(c^2-2)(3c^2-2)}{2\lambda c^2 d}\beta_2^2.$$

Now from (3.23, (i), (ii)) we get $w_1^2(X_1) = 0$, $w_1^3(X_1) = 0$ and then from (3.23, (iii), (vi)), $w_1^2(X_2) = w_1^3(X_3) = 0$. Thus we have $\beta_1^2 = -dw_1^3(X_2)$, $\beta_2^2 = -dw_2^3(X_2)$ and $\beta_2^3 = -\frac{3c^2-2}{\lambda}w_1^2(X_3) - dw_2^3(X_3)$. Therefore

$$w_1^3(X_2) = rac{2-c^2}{2\lambda c} w_2^3(X_2)$$

and

$$(3c^{2}-2)w_{1}^{2}(X_{3}) + \lambda dw_{2}^{3}(X_{3}) = \frac{\lambda c(3c^{2}-2)}{2(1-c^{2})}w_{2}^{3}(X_{2}).$$

$$(4.7)$$

Also $3\beta_1^3 = -\frac{3c^2-2}{c}w_1^2(X_3)$ and $3\beta_3^1 = \frac{3c^2-2}{c}w_2^3(X_1)$. Thus $w_2^3(X_1) = -w_1^2(X_3)$ and from $\beta_1^2 = \beta_2^1$ we get $w_2^3(X_1) = w_1^3(X_2)$. Then

$$w_1^2(X_3) = \frac{c^2 - 2}{2\lambda c} w_2^3(X_2).$$
(4.8)

From (3.22) we obtain $E_8(X_2) = -\frac{c^2+2}{2c}w_2^3(X_2)$ and $E_{10}(X_2) = 3\frac{c^2+2}{2c}w_2^3(X_2)$. Thus $E_{10}(X_2) = -3E_8(X_2)$. Now, using (3.23, (xiii), (xv)) we have $E_9(X_3) = -3E_7(X_3)$ or

$$10\lambda w_1^2(X_3) - dw_2^3(X_3) = 0. (4.9)$$

Finally from (4.6), (4.7) and (4.8) we have $(5c^4 - 12c^2 + 8)w_2^3(X_2) = 0$. But $5c^4 - 12c^2 + 8 \neq 0$. Thus $w_2^3(X_2) = 0$ and so $\beta_2^2 = 0$, a contradiction.

Lemma 2 λ, a, c, d are constant and $w_i^j = 0, i, j = 1, 2, 3$ on M.

Proof. We have $\beta_1^1 = \beta_2^2 = \beta_3^3 = 0$ and from (3.16) and (3.18) we get $\beta_1^2 = 0, \ d\beta_1^3 = 0, \ d\beta_2^3 = 0$ and

$$\lambda \beta_1^3 + c\beta_2^3 = 0, \quad (3\lambda^2 - 1)\beta_1^3 + \lambda(a+c)\beta_2^3 = 0. \tag{4.10}$$

We will examine two cases, $d \neq 0$ and d = 0.

Case I: $d \neq 0$

We have $\beta_1^3 = \beta_2^3 = 0$. Thus $\beta_i^j = 0, i, j, = 1, 2, 3$. From (3.15) we get

$$\frac{3\lambda^2 + 1}{\lambda^2} X_i \lambda = (a+c)w_1^2(X_i) + dw_1^3(X_i)$$
(4.11)

and from (3.23, (iv), (v))

$$(\lambda^{2} + 1)w_{1}^{2}(X_{3}) = \lambda c w_{1}^{3}(X_{1})$$

$$w_{1}^{2}(X_{3}) = w_{1}^{3}(X_{2}).$$
(4.12)

Now using (4.2), (4.11) and (4.12), from (3.23, (vii)) we obtain

$$(1 - \lambda^2)(\lambda^2 - 2c^2 + 1)w_1^2(X_3) = 0.$$
(4.13)

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We claim that $(1 - \lambda^2)(\lambda^2 - 2c^2 + 1) \neq 0$.

Indeed, let $\lambda^2 = 1$, or $\lambda = -1$ since λ is negative. Then from (4.2) we have $a = \frac{c^2-2}{c}$ and from (3.22) $E_1 = 0$. Now from (3.23, (i), (ii)) we get $w_1^2(X_1) = w_1^3(X_1) = 0$ and then from (4.12) and (3.23, (iii)) $w_1^2(X_3) = w_1^3(X_2) = w_1^2(X_2) = 0$. After these from (4.11) we also have $w_1^3(X_3) = 0$. Thus $w_1^2 = w_1^3 = 0$.

Now from (3.19) we obtain $(3\lambda^2 - 1)(4 - \lambda_1^2 - 2\lambda^2 - \mu_1 - \mu_2) - \lambda^2(a+c)^2 - \lambda^2 d^2 = 0$. This relation with (3.9) and (4.2) imply that a, c, d are constant. Now from (3.23, (x), (xiii), (xiv)) we get $w_2^3 = 0$. Thus $w_i^j = 0, i, j = 1, 2, 3$ and then (3.19), (3.20), (3.21) become

$$2 + ac + c^{2} + d^{2} + 2z = 0, \quad (a + c)(3 + a^{2} + c^{2} + z) + cd^{2} = 0,$$

$$3 + ac + 3c^{2} + d^{2} + z = 0$$

where $z = \mu_1 + \mu_2 - 3$.

We can easily see that this system together with (4.2) is impossible. Thus $\lambda^2 \neq 1$.

Suppose now that $\lambda^2 - 2c^2 + 1 = 0$. Then from (4.2) we get a + c = 0. Thus from (3.15) we have

$$X_{i}\lambda = \frac{\lambda^{2}d}{3\lambda^{2} + 1}w_{1}^{3}(X_{i}), \quad (3\lambda^{2} - 1)w_{1}^{2} = \lambda dw_{2}^{3},$$
$$X_{i}d = -\frac{3\lambda^{2} - 1}{\lambda}w_{1}^{3}(X_{i}). \quad (4.14)$$

Now from (3.23, (i), (ii), (iv), (v)) we get

$$X_{2}\lambda = -\lambda w_{1}^{2}(X_{1}), \quad X_{3}\lambda = -\lambda w_{1}^{3}(X_{1})$$

$$(\lambda^{2} + 1)w_{1}^{2}(X_{3}) = \lambda c w_{1}^{3}(X_{1}), \quad w_{1}^{2}(X_{3}) = w_{1}^{3}(X_{2})$$
(4.15)

By using (4.14) and (4.15), from (3.23, (x)) we obtain $(3\lambda^2 - 1)w_1^2(X_1) - \lambda dw_1^2(X_3) = 0$, while from (3.23, (ix), (xi)) we conclude that $(3\lambda^2 + 1)w_1^2(X_1) + \lambda dw_1^2(X_3) = 0$. From these two relations we have $w_1^2(X_1) = w_1^2(X_3) = 0$. Now from (4.15) we have $w_1^3(X_1) = w_1^3(X_2) = 0$ and from (3.23, (iii)) $w_1^2(X_2) = 0$. Thus $w_1^2 = 0$ and now from (4.14) we get $w_2^3 = 0$. Therefore (3.20) becomes $cd^2 = 0$, a contradiction.

Thus finally we have $(1 - \lambda^2)(\lambda^2 - 2c^2 + 1) \neq 0$ and from (4.13) we have $w_1^2(X_3) = 0$, while from (4.12) $w_1^3(X_1) = w_1^3(X_2) = 0$. Also from (4.11) and (3.23), (ii), (vi), (viii)) we find $w_1^3(X_3) = 0$, $w_1^2(X_1) = 0$ and $w_1^2(X_2) = 0$.

Thus we have $w_1^2 = w_1^3 = 0$. Now from (4.11), $\lambda = \text{const.}$ and from (3.19)

$$(\lambda_1 + 2\lambda)(4 - \lambda_1^2 - 2\lambda^2 - \mu_1 - \mu_2) - \lambda(a+c)^2 - \lambda d^2 = 0.$$

From this, (3.9) and (4.2) we conclude that a, c, d are constant.

Finally from (3.15) we obtain $w_2^3 = 0$.

Case II: d = 0

The determinant of (4.10) is $D = \frac{1}{c}(\lambda^4 + (1+c^2)\lambda^2 - c^2).$

If D = 0, using (3.9) and (4.2) we conclude that λ, a, c are constant. Thus from (3.15) we have

$$\beta_1^i = \alpha_2 w_2^1(X_i), \quad \beta_2^i = \alpha_1 w_1^2(X_i), \quad \beta_3^i = \alpha_1 w_1^3(X_i) + \alpha_2 w_2^3(X_i)$$

and since $\alpha_1^2 + \alpha_2^2 \neq 0$ we obtain $w_1^2(X_1) = w_1^2(X_2) = 0$. Now from (3.23, (ii), (iv)), $w_1^3(X_1) = 0$ and then $w_1^2(X_3) = 0$. So $w_1^2 = 0$. From (3.23, (vii), (viii)) we obtain $w_1^3(X_2) = w_1^3(X_3) = 0$. Thus $w_1^3 = 0$. Using $w_1^2 = w_1^3 = 0$, from (3.23, (ix), (xiii), (xiv)) we conclude that $w_2^3 = 0$.

Now suppose $D \neq 0$. In this case from (4.10) we have $\beta_i^j = 0$ for i, j = 1, 2, 3. Then from (3.15),

$$X_i \alpha_1 = \alpha_2 w_1^2(X_i), \ X_i \alpha_2 = \alpha_1 w_2^1(X_i), \ \alpha_1 w_1^3 + \alpha_2 w_2^3 = 0.$$
(4.16)

We assert that $\alpha_1 \neq 0$. Indeed, if for the moment we suppose that $\alpha_1 = 0$, then from (4.16) we have $w_1^2 = w_2^3 = 0$. Now from (3.23, (iv), (vii), (viii)) we obtain $w_1^3 = 0$ and from (3.19) we get $\lambda(a+c)^2 = 0$, a contradiction.

For α_2 we distinguish two subcases II₁, $\alpha_2 = 0$ and II₂, $\alpha_2 \neq 0$, which we examine separately.

II₁: $\alpha_2 = 0$.

In this case we have a + c = 0 and $\lambda = \text{const.}$ So from (4.1) we have that a, c are constant, while from (4.16) $w_1^2 = w_1^3 = 0$. Now from (3.23, (x), (xiii), (xiv)) we get $w_2^3 = 0$.

II₂: $\alpha_2 \neq 0$.

Now we have $\alpha_1 \alpha_2 \neq 0$. From (4.16) and (3.23, (i), (iii)) we obtain

$$(3\lambda^{2}+1)w_{1}^{2}(X_{1}) + \lambda(a+c)w_{1}^{2}(X_{2}) = 0,$$

$$\lambda((2\lambda^{2}+1)a - \lambda^{2}c)w_{1}^{2}(X_{1}) - (3\lambda^{2}+1)(\lambda^{2}+1)w_{1}^{2}(X_{2}) = 0.$$

The determinant of this system is

$$D = (3\lambda^2 + 1)^2(\lambda^2 + 1) + \lambda^2(a+c)((2\lambda^2 + 1)a - \lambda^2 c).$$

If D = 0, then using (3.9) and (4.2) we have that λ, a, c are constant. Now from (4.16) we have $w_1^2 = 0$ and from (3.23, (iii), (v), (vi)) we obtain $w_1^3 = 0$. Finally from (4.16) $w_2^3 = 0$. Now suppose $D \neq 0$. Then $w_1^3(X_1) = w_1^2(X_2) = 0$ and $X_1\lambda = X_2\lambda = 0$. Now from (3.23, (vi)) we have $w_1^3(X_3) = 0$. From (4.16) and (3.23, (ii), (iv)) we obtain

$$(3\lambda^2 + 1)w_1^3(X_1) + \lambda(a+c)w_1^2(X_3) = 0,$$

$$\lambda cw_1^3(X_1) - (\lambda^2 + 1)w_1^2(X_3) = 0.$$

If for the determinant $D_1 = (\lambda^2 + 1)(3\lambda^2 + 1) + \lambda^2 c(a+c)$, we have $D_1 = 0$, then from (3.9) and (4.2) we obtain $\lambda, a, c = \text{constant}$. So, from (4.16) and (3.23, (v)) we conclude that $w_1^3 = w_2^3 = 0$. If $D_1 \neq 0$, then $w_1^3(X_1) = w_1^2(X_3) = 0$. Thus $w_1^2 = 0$ and from (4.16) $\lambda = \text{constant}$ and a + c = const. Now from (4.2) we have a, c are constant. Again from (3.23, (v)) we have $w_1^3(X_2) = 0$. So $w_1^3 = 0$ and from (4.16) $w_2^3 = 0$, which completes the proof of the lemma.

Proof of the Theorem. From Lemma 2 we have that λ, a, c, d are constant and $w_i^j = 0$, i, j = 1, 2, 3. Thus from (3.22) we have $E_1 = E_2 = \ldots = E_{10} =$ 0. Now, according to [2], we have that M is C-parallel and the theorem follows from Proposition 5.2 of [2] which says that under these conditions the position vector is as in the statement of the Theorem and M lies fully in E^8 .

We close this paper with an auxiliary result for which we need the following definition (see [8, p. 20]).

Definition If $\gamma(s)$ is a curve in a Reimannian manifold N, parametrized by arc length s, we say that γ is a *Frenet curve of order* r when there exist orthonormal vector fields E_1, E_2, \ldots, E_r , along γ , such that:

$$\dot{\gamma} = E_1, \ \nabla_{\dot{\gamma}} E_1 = k_1 E_2, \ \nabla_{\dot{\gamma}} E_2 = -k_1 E_1 + k_2 E_3, \dots,$$

 $\nabla_{\dot{\gamma}} E_{r-1} = -k_{r-2} E_{r-2} + k_{r-1} E_r, \ \nabla_{\dot{\gamma}} E_r = -k_{r-1} E_{r-1}$

where $k_1, k_2, \ldots, k_{r-1}$ are positive C^{∞} functions of s. k_j is called the j-th curvature of γ .

So, for example, a geodesic is a Frenet curve of order 1; a circle is a Frenet curve of order 2 with k_1 a constant; a helix of order r is a Frenet curve of order r, such that $k_1, k_2, \ldots, k_{r-1}$ are constants.

Proposition Let M be a flat, 3-dimensional mass-symmetric 2-type integral submanifold of $S^7 \subset E^8$. Then M is locally the product of 3 curves. Any one of these curves is a helix of order 4, or a circle in E^8 .

Proof. According to Lemma 2, the Weingarten maps (3.1) of M have constant components and $w_i^j = 0$, i, j, = 1, 2, 3. Thus, by using the Gauss-Weingarten formulas we have

$$\bar{\nabla}_{X_1} X_1 = \lambda_1 \xi_1 - x, \quad \bar{\nabla}_{X_2} X_1 = \lambda \xi_2, \quad \bar{\nabla}_{X_3} X_1 = \lambda \xi_3, \bar{\nabla}_{X_2} X_2 = \lambda \xi_1 + a \xi_2 - x, \quad \bar{\nabla}_{X_3} X_2 = c \xi_3, \quad \bar{\nabla}_{X_i} x = X_i, \bar{\nabla}_{X_3} X_3 = \lambda \xi_1 + c \xi_2 + d \xi_3 - x, \quad \bar{\nabla}_{X_1} \xi_1 = -\lambda_1 X_1 + \xi, \bar{\nabla}_{X_2} \xi_1 = -\lambda X_2, \quad \bar{\nabla}_{X_3} \xi_1 = -\lambda X_3, \quad \bar{\nabla}_{X_2} \xi_2 = -\lambda X_1 - a X_2 + \xi, \bar{\nabla}_{X_3} \xi_2 = -c X_3, \quad \bar{\nabla}_{X_3} \xi_3 = -\lambda X_1 - c X_2 - d X_3 + \xi, \quad \bar{\nabla}_{X_i} \xi = -\xi_i.$$

$$(4.17)$$

Let $X_1 = E_1$. From (4.17) we obtain

$$\begin{split} \bar{\nabla}_{E_1} E_1 &= \lambda_1 \xi_1 - x = k_1 E_2, \text{ where } k_1 = \sqrt{1 + \lambda^2}, \ E_2 = \frac{1}{k_1} (\lambda \xi_1 - x), \\ \bar{\nabla}_{E_1} E_2 &= -k_1 X_2 + \frac{\lambda_1}{k_1} \xi = -k_1 E_1 + k_2 E_3, \ k_2 = \frac{\lambda_1}{k_1} \text{ and } E_3 = \xi, \\ \bar{\nabla}_{E_1} E_3 &= -\xi_1 = -k_2 E_2 + k_3 E_4, \ k_3 = \frac{1}{k_1} \text{ and } E_4 = -\frac{1}{k_1} (\xi_1 + \lambda_1 x), \\ \bar{\nabla}_{E_1} E_4 &= -k_3 E_3. \end{split}$$

Thus $k_4 = 0$ and an X_1 -curve of M is a helix of order 4 in E^8 . If $\lambda_1 = 0$, we have $k_2 = 0$ and the X_1 -curve is a circle.

Now we put $X_2 = E_1$. From (4.17) we obtain

$$\begin{split} \bar{\nabla}_{E_1} E_1 &= \lambda \xi_1 + a \xi_2 - x = k_1 E_2, \quad k_1 = \sqrt{\lambda^2 + a^2 + 1}, \\ E_2 &= \frac{1}{k_1} (\lambda \xi_1 + a \xi_2 - x). \\ \bar{\nabla}_{E_1} E_2 &= \frac{1}{k_1} (-\lambda a X_1 - k_1^2 X_2 + a \xi) = -k_1 E_1 + k_2 E_3, \\ k_2 &= \frac{\varepsilon a \sqrt{\lambda^2 + 1}}{k_1}, \quad E_3 = \frac{\varepsilon}{\sqrt{\lambda^2 + 1}} (-\lambda X_1 + \xi), \\ \text{where } \varepsilon &= \pm 1 \text{ according as } a > 0 \text{ or } a < 0. \end{split}$$

$$\begin{split} \bar{\nabla}_{E_1} E_3 &= -\varepsilon \sqrt{\lambda^2 + 1} \ \xi_2 = -k_2 E_2 + k_3 E_4, \quad k_3 = \varepsilon \varepsilon_1 \frac{1 + \lambda^2}{k_1} \\ E_4 &= \frac{\varepsilon_1}{k_1 \sqrt{\lambda^2 + 1}} (\lambda a \xi_1 - (\lambda^2 + 1) \xi_2 - ax), \\ \text{where } \varepsilon_1 &= \pm 1 \text{ according as } \varepsilon = \pm 1. \\ \bar{\nabla}_{E_1} E_4 &= -k_3 E_3. \end{split}$$

Thus $k_4 = 0$ and an X_2 -curve of M is a helix of order 4 in E^8 . If a = 0, we have $k_2 = 0$ and the curve is a circle.

Let now $X_3 = E_1$. In the same manner, from (4.17) we have

$$\begin{split} \bar{\nabla}_{E_1} E_1 &= \lambda \xi_1 + c \xi_2 + d \xi_3 - x = k_1 E_2, \quad k_1 = \sqrt{\lambda^2 + c^2 + d^2 + 1}, \\ E_2 &= \frac{1}{k_1} (\lambda \xi_1 + c \xi_2 + d \xi_3 - x). \\ \bar{\nabla}_{E_1} E_2 &= \frac{1}{k} (-\lambda d X_1 - c d X_2 - k_1^2 X_3 + d \xi) = -k_1 E_1 + k_2 E_3, \\ k_2 &= \frac{\varepsilon d}{k_1} \sqrt{\lambda^2 + c^2 + 1}, \\ E_3 &= \frac{\varepsilon}{\sqrt{\lambda^2 + c^2 + 1}} (-\lambda X_1 - c X_2 + \xi), \\ \text{where } \varepsilon = \pm 1 \text{ according as } d > 0 \text{ or } d < 0. \\ \bar{\nabla}_{E_1} E_3 &= -\varepsilon \sqrt{\lambda^2 + c^2 + 1} \xi_3 = -k_2 E_2 + k_3 E_4, \\ k_3 &= \frac{\varepsilon \varepsilon_1}{k_1} (\lambda^2 + c^2 + 1), \\ E_4 &= \frac{\varepsilon_1}{k_1 \sqrt{\lambda^2 + c^2 + 1}} (\lambda d \xi_1 + c d \xi_2 - (\lambda^2 + c^2 + 1) \xi_3 - d x), \\ \text{where } \varepsilon_1 &= \pm 1 \text{ according as } \varepsilon = \pm 1. \\ \bar{\nabla}_{E_1} E_4 &= -k_3 E_3. \end{split}$$

Thus an X_3 -curve is a helix of order 4. If d = 0, the curve is a circle.

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