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FINITE MODEL PROPERTY FOR FIVE MODAL CALCULI IN THE NEIGHBOURHOOD OF S3

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That Lewis' system S3 is decidable was shown by Matsumoto in [9]. That it has the finite model property (f.m.p.) has been established only recently by Lemmon in [7]. First it is proved that a weaker system E3 has the f.m.p. and from this it is inferred that S3 also has the same property. There is one disadvantage to this method. It is not clear how to modify it to show that a system which is somewhat stronger (or weaker) than S3 also has the f.m.p. Given a *direct* proof this can be fairly easily done. Halldén, for example, has, in an obvious manner, extended the result from S2 to S6 (compare Theorem 5 of [10] with Theorem 13 of [5]). A similar extension from S3 to S7 is not readily available from Lemmon's treatment; and the same remark applies to weakening the result to, say, S3°.

In this paper I shall give a direct proof of the f.m.p. of $S3^{\circ}$ and extend it to the systems $R3^{\circ}$, S3.1, S7 and S8. The system $S3^{\circ}$ is due to Sobociński [13]; $R3^{\circ}$ due to Canty [2]; S3.1, S7 and S8 due to Halldén [5]. The name "S3.1" occurs in [6]; p. 345. In \$1 new axiomatizations of these systems will be given. The two important deductions of \$1, those of 1.2 and 2.1, are extracted from certain considerations of Lemmon [7], both algebraic and logistical (see pp. 195-196). In \$2 the f.m.p. will be established. The results of \$2 are simple consequences of the axiomatizations and the author's results of [12] and thorough acquaintance with [12] is presupposed. All the terminology and notation of \$2 is that of [12].

§1. AXIOMATICS. We suppose our systems to be N-K-M calculi with the usual definitions. The five systems mentioned are defined as follows:

- (1) $S3^\circ = \{S1^\circ; \mathbb{C}\mathbb{C}pq\mathbb{C}MpMq\};$
- (2) $R3^\circ = {S3^\circ; CLpp};$
- (3) $S3.1 = \{S3; M \& Lp LLp\};$
- (4) $S7 = {S3; MMp};$
- (5) $S8 = {S3; LMMp}.$

Now consider the following five theses:

V1 (MKMpNMKpNpMp;

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V2 CpMp;
V3 MNMMKpNp;
V4 MMKpNp;
V5 ΝΜΝΜΜΚpNp.

It is pointed out by Hughes and Cresswell in [6], p. 269 that S7 can be alternately axiomatized as $\{S3; V4\}$. (Their remark is for S2 and S6. But, of course, it carries over to S3 and S7.) Similarly, it is easy to see that $\{S8\} \leftrightarrows \{S3; V5\}$. Also, clearly $\{R3^\circ\} \leftrightarrows \{S3^\circ; V2\}$. We now prove that $\{S3^\circ\} \leftrightarrows \{S2^\circ; V1\}$ and $\{S3.1\} \leftrightarrows \{S3; V3\}$.

Theorem 1. $\{S3^\circ\} \leftrightarrows \{S2^\circ; V1\}$.

1.1. First we show that $\{S3^\circ\} \rightarrow \{V1\}$.

Z1	& & pq & M p M q	[S3°]
Z2	© <i>MKMpNMqMKpNq</i>	[<i>Z1</i> ; S1°]
V1	<u>ᢆ</u> © <i>ΜΚΜϷΝΜΚϷΝϷΜϷ</i>	$[Z2,q/KpNp;S1^{\circ}]$

1.2. Next we show that $\{S2^\circ; V1\} \rightarrow \{S3^\circ\}$.

Z1	©MKqNqMq	[S2°]
Z2	©MKpNpMq	[Z1;S1°]
Z3	©NMqNMKpNp	[<i>Z2</i> ; S1°]
Z4	©ΚΜϷΝΜqΚΜϷΝΜΚϷΝϷ	[<i>Z3</i> ; S1°]
Z5	©ΜΚΜϷΝΜqΜΚΜϷΝΜΚϷΝϷ	[Z4;S2°]
Z6	©MKMpNMqMp	[Z5; V1; S1°]
Z7	© <i>©pqCMpMq</i>	[S1°; cf.33.321 in [4]]
Z8	©NMKpNqANMpMq	[<i>Z</i> 7;S1°]
Z9	©KMpNMqMKpNq	[<i>Z</i> 8;S1°]
Z1 0	©KMpNMqKMKpNqNMq	[<i>Z9</i> ;S1°]
Z11	©MKMpNMqMKMKpNqNMq	[Z10;S2°]
Z12	©MKMpNMqMKpNq	[<i>Z6,p/KpNq</i> ; <i>Z11</i> ;S1°]
Z13	$\mathbb{C}\mathbb{C}pq\mathbb{C}MpMq$	[<i>Z12</i> ;S1°]

This completes the proof. There are a number of things to notice about the thesis V1: (1) Note its similarity to the condition for transitive algebras in [7], p. 196. (2) The proper axiom of $S3^{\circ}(S3)$ (Z13 above) when added to S1°(S1) gives us S3°(S3). In other words its addition to S2°(S2) makes the proper axiom of S2°(S2), CMKpqMp, non-independent. But V1 has to be added to $S2^{\circ}(S2)$ to give $S3^{\circ}(S3)$. Group V of [8], p. 494 verifies $S1^{\circ}(S1)$ and V1 but falsifies &MKpqMp. (3) In [1] Åqvist constructs a system S3.5. "S3.5 is put forward to stand to S5 as S3 stands to S4 and S2 to T" (See [3], p. 58). A similar system on the S1-side, i.e., a system which stands to S1 as S3 stands S2 and S4 to T can be constructed by adding V1 to S1. And we can call it S1.5. (4) V_1 can be thought of as a sort of incomplete form of the proper axiom of S4°(S4), ©MMpMp, since erasing NMKpNp from V1 gives us ©MMpMp. (5) In [8] mention is made of "T-principles" of S1, viz., theorems of S1 of the form $\mathbb{C}K\alpha T\beta$ where T is a theorem of S1 but $\mathbb{C}\alpha\beta$ is not. Apparently Lewis and Langford thought that only S1 has T-principles (See p. 151). However, it is noted by Hughes and Cresswell in [6], p. 230,

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n. 209 that S2 also has T-principles and their argument clearly shows that even S3 has these principles. Now V1 is a theorem of S3 which may well be called a T-principle but of a different sort than the ones mentioned above, i.e., S3 contains theorems of the form $\mathbb{S}MK\alpha T\beta$ where T is a theorem of S3 but $\mathbb{S}M\alpha\beta$ is not.

Theorem 2. $\{S3.1\} = \{S3; V3\}.$

2.1 First we show that $\{S3.1\} \rightarrow \{V3\}$.

Z1	©ΚΜΜΚ⊅Ν⊅ΝΜΚ⊅Ν⊅ΚΜΜΚ⊅Ν⊅ΝΜΚ⊅Ν⊅	[S1°]
Z2	<u>©'ΜΜΚ</u> <i>ϕ</i> Ν <i>ϕCNMKϕNϕKMMKϕNϕNKϕNϕ</i>	$[Z1; S1^\circ]$
Z3	ϾϺϺΚϼΝϼΑϺΚϼΝϼΚΜΜΚϼΝϼΝΜΚϼΝϼ	$[Z2; S1^\circ]$
Z4		$[S2^\circ; cf. Z2 \text{ of } 1.2 \text{ above}]$
Z5	©KMMKpNpNMKpNpMKMMKpNpNMKpNp	[S1]
Z6	<i>©ΑΜΚϷΝϷΚΜΜΚϷΝϷΝΜΚϷΝϷΜΚΜΜΚϷΝϷΝΜΚ</i>	bNp [$Z4; Z5; S1^\circ$]
Z7	© <i>ΜΜΚpNpMKMMKpNpNMKpNp</i>	[<i>Z6</i> ; S1°]
Z8	© <i>ΝΜΚΜΜΚϷΝϷΝΜΚϷΝϷΝΜΜΚϷΝϷ</i>	[<i>Z7</i> ; S1°]
Z9	© <i>ΜΝΜΚΜΜΚϷΝϷΝΜΚϷΝϷΜΝΜΚϷΝϷ</i>	[<i>Z8</i> ; S2°]
Z10	M© $LpLLp$	[S3.1]
Z11	Μ©ΜΜϷ	$[Z10,p/Np;S1^{\circ}]$
Z12	ΜΝΜΚΜΜΚϸΝϸΝΜΚϸΝϸ	$[Z11,p/KpNp;S1^\circ]$
V3	ΜΝΜΜΚϷΝϷ	[<i>Z12;Z9</i> ;S1°]

2.2 Next we show that $\{S3; V3\} \rightarrow \{S3.1\}$.

Z1	&LLq &LpLLp	[S3; cf. TS3.7 in [6], p. 235]
Z2	© <i>ΝΜΜΚϷΝϷ</i> © <i>LpLLp</i>	$[Z1,q/NKpNp;S1^\circ]$
Z3	© <i>MNMMK</i> pNpM©LpLLp	[<i>Z2</i> ; S2°]
Z4	M© L p LLp	[Z3;V3;S1°]

This completes the proof. Halldén in [5] proved two intersection results: (1) α is a theorem of S3 if and only if α is a theorem of both S4 and S7; (2) α is a theorem of S3 if and only if α is a theorem of both S3.1 and S8. It is well-known that $\{S4\} \leftrightarrows \{S3; NMMKpNp\}$ and we saw earlier that $\{S7\} \leftrightarrows \{S3; MMKpNp\}$. Also we have just shown that $\{S3.1\} \leftrightarrows \{S3; MNMMKpNp\}$ whereas $\{S8\} \leftrightarrows \{S3; NMNMKpNp\}$. It is interesting that in both cases we can find a thesis A such that the two intersecting calculi can be axiomatized by adding A and NA respectively to S3.

We therefore have the following alternative axiomatizations which we now write in a different notation:

(1) $S3^\circ = \{S2^\circ; \Diamond(\Diamond p \land \sim \Diamond(p \land \sim p)) \exists \Diamond p\};$

- (2) R3° = {S3°; $p \supset \Diamond p$ };
- (3) S3.1 = {S3; $\diamond \sim \diamond \diamond (p \land \sim p)$ };
- (4) S7 = {S3; $\Diamond \Diamond (p \land \sim p)$ };
- (5) S8 = {S3; $\sim \diamond \sim \diamond \diamond (p \land \sim p)$ }.

§2. FINITE MODEL PROPERTY. As in [12] we shall use matrices $\mathfrak{M} = \langle M, D, \cap, -, P \rangle$ in our investigation. As our stock of conditions on these matrices we list the following:

(A) $\langle M, \cap, -, P \rangle$ is a weak modal algebra; D is an additive ideal of M; (B) x = 0 if and only if $-P(x) \in D$; (C) (D) $PO \leq Px;$ (E) $P(Px \cap -P0) \leq Px;$ (F) $x \rightarrow Px \varepsilon D;$ (G) $x \leq Px;$ (H) $P - P P 0 \epsilon D;$

PPOεD; (I)

 (\mathbf{J}) - P - P P 0 ε D.

We omit the proof of the three theorems that follow:

Theorem 3. There exists a o-regular characteristic matrix for S3°(R3°, S3.1, S7, S8).

Theorem 4. $\mathfrak{M} = \langle M, D, \cap, -, P \rangle$ is a σ -regular S3°(R3°, S3.1, S7, S8)-matrix if and only if

- (A) (E); (A) (F); (1)
- (2)
- (3)
- (4)
- $\begin{array}{cccc} (A) & & & (I), \\ (A) & & & (H); \\ (A) & & & (G), (I); \\ (A) & & & (G), (J). \end{array}$ (5)

Theorem 5. $|_{S3^{\circ}(R3^{\circ}, S3.1, S7, S8)}A$ if and only if A is verified by all matrices $\mathfrak{M} = \langle M, D, \cap, -, P \rangle$ such that condition (1)((2), (3), (4), (5)) of Theorem 4 is satisfied.

Theorem 6. Let $\mathfrak{M} = \langle M, D, \cap, -, P \rangle$ be a σ -regular S3°(R3°, S3.1, S7, S8)matrix, and let a_1, \ldots, a_r be a finite sequence of elements of M. Then there is a finite σ -regular S3°(R3°, S3.1, S7, S8)-matrix $\mathfrak{M}_1 = \langle M_1, D_1, \cap_1, -_1, \mathsf{P}_1 \rangle$ with at most $2^{2^{r+4}}$ elements such that

- (i) for $1 \leq i \leq r$, $a_i \in M_1$;
- (*ii*) for x, y ε M_1 , $x \cap_1 y = x \cap y$;
- (*iii*) for $x \in M_1$, $-_1x = -x$;
- (iv) for $x \in M_1$ such that $P x \in M_1$, $P_1 x = P x$;
- for $x \in M_1$, if $x \in D_1$, then $x \in D$. (v)

Proof. See Theorem IV.1 [12] and Theorem IV.4 [12]. Include now in the construction of M_1 , PPO and P-PPO as well. This does not affect the proofs of the theorems but changes the " $2^{2^{r+2}}$ " in their statements to " $2^{2^{r+4}}$ ". It is clear that the only thing which remains to be shown is that \mathfrak{M}_1 satisfies conditions (D) ----- (J) given that A satisfies the corresponding conditions.

D: Let $P0 \leq Px$. But $P0 = P_10$ and $Px \leq P_1x$. So $P_10 \leq P_1x$.

We pause now and note that this shows that \mathfrak{M}_1 is a S2°-matrix given that \mathfrak{M} is one (see the axiomatization of S2° given in [11]). Also note that each of our systems contain S2°. We shall use this fact in what follows.

E: Let $P(Px \cap -P0) \leq Px$. Let x be covered by A_1, \ldots, A_n . Let $P_1x \cap -P_10$ be covered by B_1, \ldots, B_p . Let $A_1 = \{x_1, \ldots, x_s\}$. Then $P_1 x \leq PA_1$. Hence

 $P_1x \cap -P_10 \leq PA_1 \cap -P0 = (Px_1 \cup \ldots \cup Px_s) \cap -P0 = (Px_1 \cap -P0) \cup \ldots \cup (Px_s \cap -P0).$ Now proceeding exactly as in Theorem V. 10 [12] (observe that properties of S2°-matrices are used in the proof) we get, $P_1(P_1x \cap -P_10) \leq P_1x$.

F: Let $x \in M_1$ and $x \to P x \in D$. Now $P x \leq P_1 x$. Hence $x \cap -P_1 x \leq x \cap -P x$. Hence $-(x \cap -P x) \leq -(x \cap -P_1 x)$. By Definition II.5 [12] and Theorem III.6 [12], $(x \to P x) \to (x \to P_1 x) \in D$. By Definition II.14(ii) [12], $x \to P_1 x \in D$. Also, clearly, $x \to P_1 x \in M_1$. Therefore, $x \to P_1 x \in D_1$.

G: Let $x \leq Px$. But $Px \leq P_1x$. So $x \leq P_1x$.

H: Let $P - P P 0 \varepsilon D$. Now $P 0 = P_1 0$. Hence $P P 0 = P P_1 0$. Also $P_1 0 \varepsilon M_1$ and $P P_1 0 = P P 0 \varepsilon M_1$ (by construction). Hence by condition (iv) of the theorem, $P_1 P_1 0 = P P_1 0 = P P 0$. Hence $-P P 0 = -P_1 P_1 0$. So $P - P P 0 = P - P_1 P_1 0$. Again, $-P_1 P_1 0 \varepsilon M_1$ and $P - P_1 P_1 0 = P - P P 0 \varepsilon M_1$ (by construction). By condition (iv), $P_1 - P_1 P_1 0 = P - P_1 P_1 0 = P - P P 0$. Hence $P_1 - P_1 P_1 0 \varepsilon D$. And clearly $P_1 - P_1 P_1 0 \varepsilon M_1$. Therefore $P_1 - P_1 P_1 0 \varepsilon D_1$.

I: Let PPOED. We have $PO \leq P_1O$. Hence PPO $\leq PP_1O$ (by the algebraic variant of Becker's Rule, which, of course, holds in S2°-matrices). Also PP₁O $\leq P_1P_1O$. So PPO $\leq P_1P_1O$. By arguing as in (F), $P_1P_1O \in D_1$.

J: Let $-P - PP0 \varepsilon D$. The arguing as in (H), $P_1 - P_1 P_1 0 = P - PP0$. Hence $-P - PP0 = -P_1 - P_1 P_1 0$. So $-P_1 - P_1 P_1 0 \varepsilon D$. And $-P_1 - P_1 P_1 0 \varepsilon M_1$. Therefore, $-P_1 - P_1 P_1 0 \varepsilon D_1$.

This completes the proof of Theorem 6. It follows that our systems have the f.m.p. and so are decidable. For the systems $S3^{\circ}$, $R3^{\circ}$ and S3.1, the decidability results are new. It is known, however, that S7 and S8 are decidable (see [6], pp. 282-284), but the proof that they have the f.m.p. is new. And, of course, implicit in Theorem 6 is another proof that S3 has the f.m.p.

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