## SOME RESULTS ON NONLINEAR HEAT EQUATIONS FOR MATERIALS OF FADING MEMORY TYPE

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1. Introduction. In this paper we consider a model for the heat conduction for a material covering an $n$-dimensional bounded set $\Omega$ with boundary $\partial \Omega, n=1,2,3$.

$$
\left\{\begin{array}{l}
\frac{d}{d t}\left(b_{0} u(t, x)+\int_{0}^{t} \beta(t-s) u(s, x) d s\right)=c_{0} \Delta u(t, x), \quad t>0, x \in \Omega  \tag{1.1}\\
u(0, x)=x, \quad x \in \Omega
\end{array}\right.
$$

where $u(t, x)$ is the temperature of the point $x$ at time $t$ (we assume that the temperature is 0 for $x \in \partial \Omega$ ), $b_{0}$ is the specific heat and $c_{0}$ the thermal conductivity. We assume that the specific heat has a term of fading memory type $\int_{0}^{t} \beta(t-s) u(s, x) d s$, whereas the thermal conductivity is constant. Concerning the kernel $\beta$ we assume only that it is locally integrable in $[0, \infty[$; this will allow us to consider kernels as $\left.\beta(t)=e^{-\omega t} t^{\alpha-1}, \omega \geq 0, \alpha \in\right] 0,1[$.

Model (1.1) (including also a memory term for the thermal conductivity) has been introduced in [7] and studied in [1] and [5].

We write problem (1.1) in abstract form in the Banach space $X=$ $C(\bar{\Omega})$,

$$
\left\{\begin{array}{l}
\frac{d}{d t}(u(t)+(\beta * u)(t))=A u(t), \quad t>0  \tag{1.2}\\
u(0)=x
\end{array}\right.
$$

where $u(t)=u(t, \cdot)$ and $A$ is the realization in $C(\bar{\Omega})$ of the Laplace operator $\Delta$ with Dirichlet boundary conditions.

In order to study (1.2), we assume that $A$ generates an analytic semigroup and that $\beta$ is Laplace transformable with Laplace transform $\hat{\beta}(\lambda)$ analytic in a sector $S_{\omega, \theta}=\{\lambda \in \mathbf{C} \backslash\{0\}:|\arg (\lambda-\omega)|<\theta\}$ with $\omega \in \mathbf{R}$ and $\theta \in] \pi / 2, \pi[$. Then the Laplace transform $\hat{u}(\lambda)$ of $u$ is given formally by

$$
\begin{equation*}
\hat{u}(\lambda):=F(\lambda) x=R(\lambda+\lambda \hat{\beta}(\lambda), A) x \tag{1.3}
\end{equation*}
$$

[^0]In Section 2, by proceeding as in $[\mathbf{3}]$ and [6], we solve problem (1.2) by means of a resolvent operator $R(t)$ obtained by inverting its formal Laplace transform $F(\lambda)$. We remark that if $\beta \in W_{\mathrm{loc}}^{1,1}(0, \infty)$, then problem (1.2) can be easily studied as a perturbation of heat equation. The main difference of our results with respect to $[\mathbf{3}]$ and $[\mathbf{6}]$ is that when $\beta$ is not regular there is also a lack of regularity for $R(t) x$. Indeed it can happen that, even if $x \neq 0$ is very regular (say $x \in D\left(A^{\infty}\right)$ ), $R(\cdot) x$ is not differentiable in 0 . For this reason we introduce in Section 3 a new notion of strict solution in order to study the inhomogeneous problem

$$
\left\{\begin{array}{l}
\frac{d}{d t}(u(t)+(\beta * u)(t))=A u(t)+f(t), \quad t>0  \tag{1.4}\\
u(0)=x
\end{array}\right.
$$

where $f:[0, T] \rightarrow X$ is continuous.
In Section 4, assuming, in addition, that $\beta$ is nonnegative and nonincreasing and that $\left\|e^{t A}\right\| \leq e^{\omega t}$, for some $\omega \leq 0$, we prove the estimate

$$
\begin{equation*}
\|R(t)\| \leq s_{\omega+\beta}(t) \tag{1.5}
\end{equation*}
$$

where $s_{\omega+\beta}$ is the solution of the integral equation

$$
\begin{equation*}
s_{\omega+\beta}(t)+\int_{0}^{t}(\omega+\beta)(t-\sigma) s_{\omega+\beta}(\sigma) d \sigma=1 \tag{1.6}
\end{equation*}
$$

This result enables us to solve (see Section 5) the semilinear problem,

$$
\left\{\begin{array}{l}
\frac{d}{d t}(u(t)+(\beta * u)(t))=A u(t)+F(u(t)), \quad t>0  \tag{1.7}\\
u(0)=x
\end{array}\right.
$$

where $F: X \rightarrow X$ is locally Lipschitz and such that

$$
\begin{equation*}
\|x\| \leq\|x-\delta F(x)\|, \quad \forall \delta>0, \quad \forall x \in X \tag{1.8}
\end{equation*}
$$

We recall that nonlinear integrodifferential equations of this type have been discussed, when $\beta$ is regular, by several authors (see $[\mathbf{2}, \mathbf{1}]$ and the references quoted therein). But in the above papers it is assumed that the nonlinear term is monotone; moreover, only the existence of weak solutions is stated.

We have also studied the positivity of the solutions. More precisely, under the hypotheses of Section 4 we can show that, if $Q$ is a closed convex cone in $X$ such that $e^{t A}(Q) \subset Q$ and if $x \in Q$, then the solution of (1.4) remains on $Q$. A similar result holds for problem (1.7).

Finally, in Section 6, we have discussed the physical example (1.1) also when a nonlinear perturbation term occurs. In a subsequent paper we shall consider the more general case in which also a memory term related to conductivity appears.
2. Construction of the resolvent $\mathbf{R}(\mathbf{t})$. Let $X$ be a complex Banach space (norm $\|\cdot\|$ ), $A: D(A) \subset X \rightarrow X$ a closed linear operator and $\beta:[0, \infty[\rightarrow \mathbf{R}$ a Laplace transformable function. We shall denote by $\rho(A)$ the resolvent set of $A$, by $\sigma(A)$ the spectrum of $A$, by $R(\lambda, A)$ the resolvent of $A$ and by $\hat{\beta}(\lambda)$ the Laplace transform of $\beta$. For any $\theta \in] 0, \pi\left[\right.$ we shall denote by $S_{\omega, \theta}$ the sector

$$
S_{\omega, \theta}=\{\lambda \in \mathbf{C} \backslash\{0\}:|\arg (\lambda-\omega)|<\theta\}
$$

We are here concerned with the Volterra integrodifferential equation

$$
\left\{\begin{array}{l}
\frac{d}{d t}(u(t)+(\beta * u)(t))=A u(t), \quad t>0  \tag{2.1}\\
u(0)=x
\end{array}\right.
$$

where $x \in X$ and $(\beta * u)(t)=\int_{0}^{t} \beta(t-s) u(s) d s$. We assume
$\exists M>0, \omega \in \mathbf{R}, \theta \in] \pi / 2, \pi[$ and $\alpha \in] 0,1[$ such that
(i) $\rho(A) \supset S_{\omega, \theta}$ and $\|R(\lambda, A)\| \leq M /|\lambda-\omega|, \quad \forall \lambda \in S_{\omega, \theta}$
(ii) There exists an analytic extension of $\hat{\beta}(\lambda)$ in $S_{\omega, \theta}$ (still denoted by $\hat{\beta}(\lambda))$ such that $\|\hat{\beta}(\lambda)\| \leq M /|\lambda-\omega|^{\alpha}, \quad \forall \lambda \in S_{\omega, \theta}$.

We fix once and for all a maximal analytic extension of $\hat{\beta}(\lambda)$ (still denoted by $\hat{\beta}(\lambda))$ and we denote by $\Omega$ its domain of definition. Set

$$
\begin{equation*}
\rho_{F}=\{\lambda \in \Omega ; \lambda+\lambda \hat{\beta}(\lambda) \in \rho(A)\} \tag{2.3}
\end{equation*}
$$

and

$$
\begin{equation*}
F(\lambda)=R(\lambda+\lambda \hat{\beta}(\lambda), A), \quad \forall \lambda \in \rho_{F} \tag{2.4}
\end{equation*}
$$

Let us remark that we do not assume that $D(A)$ is dense in $X$ and that $\beta$ is right differentiable at 0 . Examples of kernels fulfilling hypotheses (2.2) are $\left.\beta(t)=e^{-\omega t} t^{\alpha-1}, \omega \geq 0, \alpha \in\right] 0,1[$.

LEMMA 2.1. Assume (2.2). Then there exists an $r>0$ such that, setting $\omega_{\theta}=\omega+r \sec \theta$, one has $\rho_{F} \supset S_{\omega_{\theta}, \theta}$ and

$$
\begin{equation*}
F(\lambda)=R(\lambda, A)[1+\lambda \hat{\beta}(\lambda) R(\lambda, A)]^{-1}, \quad \forall \lambda \in S_{\omega_{\theta}, \theta} \tag{2.6}
\end{equation*}
$$

Finally, there exists $M_{1}>0$ such that

$$
\begin{equation*}
\|A F(\lambda)\| \leq M_{1}, \quad \forall \lambda \in S_{\omega_{\theta}, \theta} \tag{2.7}
\end{equation*}
$$

Proof. Given $y \in X$ and $\lambda \in S_{\omega, \theta}$, consider the equation

$$
\begin{equation*}
\lambda x+\lambda \hat{\beta}(\lambda) x-A x=y \tag{2.8}
\end{equation*}
$$

Setting $\lambda x-A x=z(2.8)$ reduces to

$$
\begin{equation*}
z+\lambda \hat{\beta}(\lambda) R(\lambda, A) z=y \tag{2.9}
\end{equation*}
$$

By (2.2) there exists an $r>0$ such that

$$
\begin{equation*}
\|\lambda \hat{\beta}(\lambda) R(\lambda, A)\| \leq \frac{1}{2}, \quad \forall \lambda \in S_{\omega_{\theta}, \theta} \tag{2.10}
\end{equation*}
$$

Now (2.5) and (2.6) follow by a standard fixed point argument.
It remains to prove (2.7). Recalling (2.6),

$$
\begin{align*}
A F(\lambda) & =(\lambda+\lambda \hat{\beta}(\lambda)) F(\lambda)-1  \tag{2.11}\\
& =\lambda F(\lambda)+\lambda \hat{\beta}(\lambda) R(\lambda, A)[1+\lambda \hat{\beta}(\lambda) R(\lambda, A)]^{-1}-1
\end{align*}
$$

so that (2.7) follows from (2.5) and (2.10).

We now set

$$
\begin{equation*}
R(t)=\frac{1}{2 \pi i} \int_{\gamma} e^{\lambda t} F(\lambda) d \lambda, \quad t>0 \tag{2.12}
\end{equation*}
$$

where $\gamma=\gamma^{-} \cup \gamma^{+}, \gamma^{ \pm}=\left\{\lambda \in \mathbf{C}: \lambda=\omega_{\theta}+\rho e^{ \pm i \theta}, \rho \geq 0\right\}$ is oriented counterclockwise.

The following result is proved as in $[\mathbf{3 , 6}]$.

Proposition 2.2. Assume (2.2) and let $R(t)$ be defined by (2.12). Then the following statements hold
(i) There exists $K>0$ such that

$$
\begin{align*}
& \|R(t)\| \leq K e^{\omega_{\theta} t}, \quad t \geq 0  \tag{2.13}\\
& \left\|R^{\prime}(t)\right\| \leq \frac{K}{t} e^{\omega_{\theta} t}, \quad t \geq 0 \tag{2.14}
\end{align*}
$$

(ii) We have

$$
\begin{equation*}
\lim _{t \rightarrow 0} R(t) x=x, \quad \forall x \in \overline{D(A)} \tag{2.15}
\end{equation*}
$$

Thus $R(\cdot) x, \beta * R(\cdot) x \in C([0, \infty[; X)$, for all $x \in \overline{D(A)}$.
(iii) $R$ is analytic in the sector $S_{0, \theta-\pi / 2}$.
(iv) For all $t>0$ and $x \in X, R(t) x \in D(A)$ and $A R(\cdot)$ is analytic in the sector $S_{0, \theta-\pi / 2}$.
(v) For all $t>0$,

$$
\begin{equation*}
R^{\prime}(t)+\int_{0}^{t} \beta(s) R^{\prime}(t-s) d s=A R(t) \tag{2.16}
\end{equation*}
$$

Proposition 2.3. If $x \in D(A)$ and $A x \in \overline{D(A)}$ we have

$$
\begin{equation*}
\lim _{t \rightarrow 0} \frac{d}{d t}(R(t) x+(\beta * R(\cdot) x)(t))=A x \tag{2.17}
\end{equation*}
$$

Thus $R(\cdot) x+(\beta * R)(\cdot) x \in C^{1}([0, \infty[; X)$ and $A R(\cdot) x \in C([0, \infty[; X)$.

Proof. From Proposition 2.2,

$$
\frac{d}{d t}(R(t) x+(\beta * R(\cdot) x)(t))=A R(t) x=R(t) A x, \quad t>0
$$

Since $A x \in \overline{D(A)},(2.17)$ follows from (2.15). ㅁ

Proposition 2.4. If $x \in D(A)$, then $R(\cdot) x+(\beta * R)(\cdot) x$ is Lipschitz continuous. Moreover, there is a $K^{\prime}>0$ such that

$$
\begin{equation*}
\left|R^{\prime}(t) x\right| \leq K^{\prime} t^{\alpha-1}|x| \tag{2.18}
\end{equation*}
$$

Proof. Let $x \in D(A)$; if $t>0$, by (2.16), we have

$$
\frac{d}{d t}(R(t) x+(K * R(\cdot) x)(t))=A R(t) x=R(t) A x
$$

Thus, by $(2.16), R(\cdot) x+(\beta * R)(\cdot) x$ is Lipschitz continuous. Moreover,

$$
\begin{aligned}
R^{\prime}(t) x & =\frac{1}{2 i \pi} \int_{\gamma} \lambda e^{\lambda t} F(\lambda) x d \lambda=\frac{1}{2 i \pi} \int_{\gamma} e^{\lambda t}(\lambda F(\lambda)-I) x d \lambda \\
& =\frac{1}{2 i \pi} \int_{\gamma} e^{\lambda t}(A F(\lambda) x-\lambda \hat{K}(\lambda) F(\lambda) x) d \lambda \\
& =R(t) A x-\frac{1}{2 i \pi} \int_{\gamma} e^{\lambda t} \lambda \hat{K}(\lambda) F(\lambda) x d \lambda
\end{aligned}
$$

The first term is bounded near 0 by (2.13). Concerning the second one,

$$
\left\|\frac{1}{2 i \pi} \int_{\gamma} e^{\lambda t} \lambda \hat{K}(\lambda) F(\lambda) x d \lambda\right\| \leq M \frac{e^{\omega_{0} t}}{\pi} \int_{0}^{\infty} e^{\rho t \cos \eta} \rho^{-\alpha} d \rho\|x\|
$$

and the conclusion follows. $\square$

Proposition 2.5. Assume (2.2), let $z \in X$ and set $v(t)=$ $\int_{0}^{t} R(s) z d s$. Then
(i) For all $T>0, v \in L^{\infty}(0, T: D(A)) \cap W^{1, \infty}(0, T: X)$.
(ii) If $z \in \overline{D(A)}$, then $v \in C(0, T: D(A)) \cap C^{1}(0, T: X)$.

Proof. Let $\rho>\omega$, then, by taking the Laplace transforms, one can check the identity

$$
v(t)=R(\rho, A)\{\rho v(t)-R(t) z-(\beta * R(\cdot) z)(t)\}
$$

and the conclusion follows. $\square$

We now want to characterize those elements $x$ of $X$ such that $R(\cdot) x$ is Hölder continuous. This problem is connected with the asymptotic behavior of $\|\lambda F(\lambda) x-x\|$, as the following lemma shows.

Proposition 2.6. Assume (2.2) and let $R(t)$ be defined by (2.12). Let $x \in D(A)$, and $\gamma \in] 0,1[$, then the following assertions are equivalent:
(i) $\forall \eta \in] 0, \theta\left[\right.$, there exists a constant $K_{1}(\eta)>0$ such that

$$
\begin{equation*}
\left\|R\left(r e^{ \pm i \eta}\right) x-x\right\| \leq K_{1}(\eta) e^{\omega_{\theta} r \cos \eta} r^{\gamma}, \quad \forall r>0 \tag{2.19}
\end{equation*}
$$

(ii) $\forall \eta \in] 0, \theta\left[\right.$, there exists a constant $K_{2}(\eta)>0$ such that

$$
\begin{equation*}
\left\|R^{\prime}\left(r e^{ \pm i \eta}\right) x\right\| \leq K_{2}(\eta) e^{\omega_{\theta} r \cos \eta} r^{\gamma-1}, \quad \forall r>0 \tag{2.20}
\end{equation*}
$$

(iii) $\forall \eta \in] 0, \theta\left[\right.$, there exists a constant $K_{3}(\eta)>0$ such that
$\|\lambda F(\lambda) x-x\| \leq K_{3}(\eta)|\lambda-\omega|^{-\gamma}, \quad$ for $\lambda=\omega_{\theta}+\rho e^{ \pm i(\pi / 2+\eta)}, \quad \forall \rho>0$
where the constants $K_{i}(\eta), i=1,2,3$, are increasing in $\eta$.

Proof. (i) $\Rightarrow$ (iii). It is sufficient to prove (iii) for $\lambda=\omega_{\theta}+$ $\rho e^{ \pm i(\pi / 2+\eta-\varepsilon)}, \forall \rho>0$, with $\left.\varepsilon \in\right] 0, \eta[$ and $\eta \in] 0, \theta[$. Set

$$
I_{ \pm i \eta}:=\left\{z \in \mathbf{C}: z=r e^{ \pm i \eta}, r>0\right\}
$$

We consider the case $\lambda=\omega+\rho e^{i(\pi / 2+\eta-\varepsilon)}$, the other case being similar. First we define

$$
\begin{equation*}
Q(\lambda) x=\int_{I_{ \pm \eta}} e^{-\lambda z} R(z) x d z, \quad x \in X \tag{2.22}
\end{equation*}
$$

$Q(\lambda)$ is well defined and analytic on the sector $S_{0, \eta+\pi / 2}$; thus, $Q(\lambda) x=$ $F(\lambda) x$. It follows that

$$
\lambda F(\lambda) x-x=\frac{1}{2 i \pi} \int_{I_{ \pm \eta}} \lambda e^{-\lambda z}(R(z) x-x) d z
$$

which yields (iii) by a simple computation.
(iii) $\Rightarrow$ (ii). We consider only the case $z=r e^{i \eta}$, the other case being similar. Let $\eta \in] 0, \theta[, r>0$, and $x$ satisfying (2.21). From Proposition 2.2, we have, for $r>0$,

$$
R^{\prime}\left(r e^{i \eta}\right) x=\frac{1}{2 i \pi} \int_{\gamma} \lambda e^{\lambda z} F(\lambda) x d \lambda=\frac{1}{2 i \pi} \int_{\gamma} e^{\lambda z}(\lambda F(\lambda) x-x) d \lambda
$$

and (ii) follows.
$(\mathrm{ii}) \Rightarrow(\mathrm{i})$. We only consider the case $z=r e^{i \eta}$. We have

$$
\begin{aligned}
\left|R\left(r e^{i \eta}\right) x-x\right| & =\lim _{\varepsilon \rightarrow 0}\left|\int_{\varepsilon}^{r} R^{\prime}\left(r e^{i \eta}\right) x d r\right| \\
& \leq \lim _{\varepsilon \rightarrow 0}(r-\varepsilon) K_{2}(\eta) e^{\omega_{\theta} r \cos \eta} r^{\gamma-1}
\end{aligned}
$$

and the proof is complete.

The next proposition states a relation among the assumptions of Proposition 2.5 and real interpolation spaces $D_{A}(\gamma, \infty)$ introduced in [4]. Let us recall the definition of $\left.D_{A}(\gamma, \infty), \gamma \in\right] 0,1[$; we set

$$
\begin{equation*}
\left.\|x\|_{\gamma, \eta}=\operatorname{Sup}_{\rho>0}\left\{\left\|\lambda^{\gamma} R(\lambda, A) x\right\| ; \lambda=\omega_{\theta}+\rho e^{ \pm i \eta}\right\}, \quad \eta \in\right] 0, \theta[. \tag{2.23}
\end{equation*}
$$

It is well known that the norms $\left\{\|x\|_{\gamma, \eta} ; \eta \in\right] 0, \theta[ \}$ are equivalent.

Proposition 2.7. Assume (2.2), and let $R(t)$ be defined by (2.12). Let $x \in \overline{D(A)}$, and $\gamma \in] 0, \alpha]$; then the following assertions are equivalent:
(i) $x \in D_{A}(\gamma, \infty)$.
(ii) $\forall \eta \in] 0, \theta\left[\right.$, there exists a constant $K_{3}(\eta)>0$ such that (2.21) holds.

Proof. (i) $\Rightarrow$ (ii). Let $x \in D_{A}(\gamma, \infty), \lambda=\omega_{\theta}+\rho e^{ \pm i \eta}$. Then

$$
\begin{align*}
\lambda F(\lambda) x-x & =A F(\lambda) x-\lambda \hat{\beta}(\lambda) F(\lambda) x \\
& =[1+\lambda \hat{\beta}(\lambda) R(\lambda, A)]^{-1} A R(\lambda, A) x-\lambda \hat{\beta}(\lambda) F(\lambda) x \tag{2.24}
\end{align*}
$$

Thus there exists a constant $C>0$ such that

$$
\|\lambda F(\lambda) x-x\| \leq C\left\{|\lambda|^{\gamma}\|x\|_{\gamma, \eta}+\frac{1}{|\lambda-\omega|^{\alpha}}\|x\|\right\}
$$

Since $\gamma \leq \alpha$, this completes the proof of the first implication.
$(\mathrm{ii}) \Rightarrow(\mathrm{i})$. By $(2.24)$, we have

$$
\begin{equation*}
R(\lambda, A) x=[1+\lambda \hat{\beta}(\lambda) R(\lambda, A)]\{\lambda F(\lambda) x-x+\lambda \hat{\beta}(\lambda) F(\lambda) x\} \tag{2.25}
\end{equation*}
$$ and now the conclusion follows easily.

We end this section with an approximation result which will be used later. Let $A_{n}$ be the Yosida approximation of $A$, i.e., $A_{n}=n J_{n}-n$, where $J_{n}=n R(n, A)$. Set

$$
\begin{align*}
\rho_{F_{n}} & =\left\{\lambda \in \Omega ; \lambda+\lambda \hat{\beta}(\lambda) \in \rho\left(A_{n}\right)\right\}  \tag{2.26}\\
F_{n}(\lambda) & =R\left(\lambda+\lambda \hat{\beta}(\lambda), A_{n}\right), \quad \forall \lambda \in \rho_{F_{n}}  \tag{2.27}\\
R_{n}(t) & =\frac{1}{2 \pi i} \int_{\gamma} e^{\lambda t} F_{n}(\lambda) d \lambda, \quad t>0 \tag{2.28}
\end{align*}
$$

Proposition 2.8. Assume (2.2), and let $R(t)$ be defined by (2.12) and $R_{n}(t)$ by (2.28). Then

$$
\begin{equation*}
\left\|R_{n}(t)\right\| \leq K e^{\omega_{\theta} t}, \quad t \geq 0 \tag{2.29}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{n \rightarrow \infty} R_{n}(t)=R(t), \quad \forall t>0 \text { in } \mathcal{L}(X) \tag{2.30}
\end{equation*}
$$

uniformly on bounded sets of $] 0, \infty[$.
3. The nonhomogeneous problem. We are here concerned with the problem

$$
\left\{\begin{array}{l}
\frac{d}{d t}(u(t)+(\beta * u)(t))=A u(t)+f(t), \quad t>0  \tag{3.1}\\
u(0)=x
\end{array}\right.
$$

where $x \in X, f \in C([0, T] ; X)$ and $A$ and $\beta$ verify (2.2).
We denote by $R(t)$ the resolvent defined by (2.12). We say that $u \in C([0, T] ; X)$ is a mild solution of problem (3.1) if it satisfies the integral equation

$$
\begin{equation*}
u(t)=R(t) x+\int_{0}^{t} R(t-s) f(s) d s, \quad t \geq 0 \tag{3.2}
\end{equation*}
$$

We want now to define a strict solution of (3.1). Remark that if $A=0$ and $f=0$, it is not in general true that $u(t)=R(t) x$ is of class $C^{1}$. Thus the following definition seems to be natural.

Definition. $u$ is called a strict solution of (3.1) if $u \in C([0, T] ; D(A))$, $u+\beta * u \in C^{1}([0, T] ; X)$ and fulfills (3.1).

Proposition 3.1. Assume (2.2), and let $f \in C^{\delta}([0, T] ; X)$, for some $\delta \in] 0,1[, x \in D(A), A x+f(0) \in \overline{D(A)}$. Then the mild solution $u$ to (3.1) is a strict solution.

Proof. Set

$$
\begin{equation*}
u(t)=u_{1}(t)+u_{2}(t)+u_{3}(t)+u_{4}(t) \tag{3.3}
\end{equation*}
$$

where

$$
\begin{align*}
& u_{1}(t)=R(t) x  \tag{3.4}\\
& u_{2}(t)=\int_{0}^{t} R(t-s)[f(s)-f(t)] d s  \tag{3.5}\\
& u_{3}(t)=\int_{0}^{t} R(s)[f(t)-f(0)] d s  \tag{3.6}\\
& u_{4}(t)=\int_{0}^{t} R(s) f(0) d s \tag{3.7}
\end{align*}
$$

Since

$$
\begin{equation*}
u_{4}(t)=A^{-1}[R(t) f(0)+(\beta * R)(\cdot) f(0)(t)-f(0)] \tag{3.8}
\end{equation*}
$$

we have
(3.9)

$$
\begin{aligned}
& A\left(u_{1}(t)+u_{4}(t)\right) \\
& \quad=R(t)(A x+f(0))+(\beta * R)(\cdot) f(0)(t)-f(0) \in C([0, T] ; X)
\end{aligned}
$$

By Proposition 2.3,

$$
R(\cdot) x+(\beta * R)(\cdot) x \in C^{1}([0, \infty[; X), \text { and } A R(\cdot) x \in C([0, \infty[; X)
$$

Thus we have only to check that $v$ is a strict solution of (3.1) with $x=0$. Set

$$
\begin{equation*}
v_{n}(t)=\int_{0}^{t} R_{n}(t-s) f(s) d s \tag{3.10}
\end{equation*}
$$

where $R_{n}(t)$ is defined in (2.28). We have

$$
\begin{align*}
\frac{d}{d t}\left(v_{n}(t)\right) & =\left(1-R_{n}(t)\right) f(t)+\int_{0}^{t} \frac{d}{d t} R_{n}(t-s)[f(s)-f(t)] d s  \tag{3.11}\\
& =: z_{n}(t)+w_{n}(t)
\end{align*}
$$

Now $z_{n}(t)=f(t)-R_{n}(t)[f(t)-f(0)]+R_{n}(t) f(0) ;$ since $f(0) \in$ $\overline{D(A)} R(\cdot), f(0)$ is continuous in $[0, T]$ by Proposition (2.2); moreover, it is easy to check that $R(\cdot)(f(\cdot)-f(0))$ is also continuous in $[0, T]$. So,

$$
\begin{align*}
\lim _{n \rightarrow \infty} z_{n}(t)= & (1-R(t)) f(t) \quad \text { in } C([0, T] ; X)  \tag{3.12}\\
& (1-R(\cdot)) f(\cdot) \in C([0, T] ; X)
\end{align*}
$$

Moreover, by recalling (2.14) and using the hypothesis $f \in C^{\delta}([0, T] ; X)$, one sees that there exists a constant $C$ such that

$$
\left\|\frac{d}{d t} R_{n}(t-s)[f(s)-f(t)]\right\| \leq C|t-s|^{\delta-1}
$$

It follows that

$$
\begin{equation*}
\lim _{n \rightarrow \infty} w_{n}(t)=\int_{0}^{t} \frac{d}{d t} R(t-s)[f(s)-f(t)] d s=: w(t) \quad \text { in } C([0, T] ; X) \tag{3.13}
\end{equation*}
$$

and so $v \in C^{1}([0, T] ; X)$. Since $v(0)=0$, we also have $\beta * v \in$ $C^{1}([0, T] ; X)$, and, consequently, $v \in C^{1}([0, T] ; D(A))$. This implies that $u$ is a strict solution of (3.1).
4. Some additional properties of $\mathbf{R}(\mathbf{t})$. In this section, we prove some additional estimates for the resolvent $\|R(t)\|$, which will be used in the next section. Also, we consider a closed convex cone $Q$ in $X$ and give sufficient conditions in order that $R(t)(Q) \subset Q$.

We assume, besides (2.2),

$$
\left\{\begin{array}{l}
\text { (i) } \exists \omega \leq 0 \text { such that }\left\|e^{t A}\right\| \leq e^{\omega t}, \text { for all } t \geq 0,  \tag{4.1}\\
\text { (ii) } \beta \text { is nonnegative and nonincreasing. }
\end{array}\right.
$$

For any kernel $K$ we denote by $s_{K}$ the solution of the integral equation

$$
\begin{equation*}
s_{K}+K * s_{K}=1 \tag{4.2}
\end{equation*}
$$

It is well known (see for instance [1]) that, if $K$ is nonnegative and nonincreasing, then $s_{K}(t) \geq 0$ for all $t \geq 0$.

Proposition 4.1. Assume (2.2) and (4.1). Let $R(t)$ be defined by (2.12). Then the following estimate holds:

$$
\begin{equation*}
\|R(t)\| \leq s_{\beta+\omega}(t), \quad \forall t \geq 0 \tag{4.3}
\end{equation*}
$$

where $s_{\beta+\omega}$ is defined in (4.2).

If, moreover, $e^{t A}(Q) \subset Q$, then $R(t)(Q) \subset Q, \forall t \geq 0$.

Proof. In view of Proposition 2.7, it suffices to prove that

$$
\begin{equation*}
\left\|R_{n}(t)\right\| \leq s_{[n \omega /(n+\omega)+\beta]}(t) \quad \forall t \geq 0 \tag{4.4}
\end{equation*}
$$

where $R_{n}(t)$ is defined by (2.28).
Let $x \in X$, and let $u_{n}(t)=R_{n}(t) x$; then $R_{n}(t) x$ is the solution of the problem

$$
\left\{\begin{array}{l}
n u_{n}(t)+\frac{d}{d t}\left(u_{n}(t)+\left(\beta * u_{n}\right)(t)\right)=n J_{n} u_{n}(t), \quad t>0  \tag{4.5}\\
u_{n}(0)=x
\end{array}\right.
$$

which is equivalent to

$$
\begin{equation*}
u_{n}+(\beta+n) * u_{n}=x+1 * n J_{n} u_{n} \tag{4.6}
\end{equation*}
$$

and also to

$$
\begin{equation*}
u_{n}=s_{n+\beta} x+s_{n+\beta} * n J_{n} u_{n} . \tag{4.7}
\end{equation*}
$$

Since $s_{n+\beta} \geq 0$, it follows that

$$
\begin{equation*}
\left\|u_{n}(t)\right\| \leq s_{n+\beta}(t)\|x\|+\frac{n^{2}}{n+\omega} \int_{0}^{t} s_{n+\beta}(t-s)\left\|u_{n}(s)\right\| d s \tag{4.8}
\end{equation*}
$$

which implies, by a classical argument,

$$
\begin{equation*}
\left\|u_{n}(t)\right\| \leq \phi_{n}(t)\|x\| \tag{4.9}
\end{equation*}
$$

where $\phi_{n}$ is the solution to the integral equation

$$
\begin{equation*}
\phi_{n}-\frac{n^{2}}{n+\omega} s_{n+\beta} * \phi_{n}=s_{n+\beta} \tag{4.10}
\end{equation*}
$$

Since the Laplace transform of $\phi_{n}$ and $s_{n}$ are given, respectively, by

$$
\begin{equation*}
\hat{\phi}_{n}(\lambda)=\frac{\hat{s}_{n+\beta}(\lambda)}{1-\frac{n^{2}}{n+\omega} \hat{s}_{n+\beta}(\lambda)} \tag{4.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\hat{s}_{n}(\lambda)=\frac{1}{\lambda+n+\lambda \hat{\beta}(\lambda)} \tag{4.12}
\end{equation*}
$$

we have

$$
\begin{equation*}
\hat{\phi}_{n}(\lambda)=\frac{1}{\lambda+\frac{n \omega}{n+\omega}+\lambda \hat{\beta}(\lambda)}=\hat{s}_{[n \omega /(n+\omega)+\beta]}(\lambda), \tag{4.13}
\end{equation*}
$$

which implies (4.4). Finally, to prove the last statement it suffices to remark that, by (4.6), it follows that $u_{n}(t) \in Q$, for all $t \geq 0$, since $J_{n}(Q) \subset Q$. $\square$
5. Semilinear equations. Let $X$ be a complex Banach space and $Q$ a closed convex cone in $X$. For any $r>0$ we shall denote by $B_{r}$ the ball $B_{r}=\{z \in X ;\|z\| \leq r\}$. Let $A: D(A) \subset X \rightarrow X$ be a closed linear operator, $\beta:[0, \infty[\rightarrow \mathbf{R}$ a Laplace transformable function and $F: X \rightarrow X$ a nonlinear mapping.

We are concerned here with the semilinear problem

$$
\left\{\begin{array}{l}
\frac{d}{d t}(u(t)+(\beta * u)(t))=A u(t)+F(u(t)), \quad t>0  \tag{5.1}\\
u(0)=x
\end{array}\right.
$$

We assume (2.2), (4.1) (with $\omega=0$, for simplicity) and, concerning $F$,
(i) For all $r>0$, there exists $M_{r}>0$ such that

$$
\begin{equation*}
\|F(x)-F(y)\| \leq M_{r}\|x-y\|, \quad \forall x, y \in B_{r} \tag{5.2}
\end{equation*}
$$

(ii) For all $\delta>0$ and all $x \in X,\|x\| \leq\|x-\delta F(x)\|$. (iii) $F(0)=0$.

We say that $u \in C([0, T] ; X)$ is a mild solution of problem (5.1) if $u$ fulfills the integral equation

$$
\begin{equation*}
u(t)=R(t) x+\int_{0}^{t} R(t-s) F(u(s)) d s \tag{5.3}
\end{equation*}
$$

where the resolvent $R(t)$ is defined by (2.12).

In the following lemma, we gather, for later use, some properties of the nonlinear mapping $F$.

LEMMA 5.1. Let $F$ be a mapping in $X$ such that hypotheses (5.2) are fulfilled. For any $r>0$, set $\delta_{r}=M_{2 r} / 2$. Then, if $\left.\delta \in\right] 0, \delta_{r}[$, the mapping $1-\delta F: B_{2 r} \rightarrow X$ is one-to-one and $(1-\delta F)\left(B_{2 r}\right) \supset B_{r}$. Define a mapping $J_{\delta, r}: B_{r} \rightarrow X$, for all $r>0$ and $\left.\delta \in\right] 0, \delta_{r}[$, by setting

$$
\begin{equation*}
J_{\delta, r}(x)=(1-\delta F)^{-1}(x), \quad x \in B_{r} \tag{5.4}
\end{equation*}
$$

Then

$$
\begin{equation*}
\left\|J_{\delta, r}(x)\right\| \leq\|x\|, \quad \forall x \in B_{r} \tag{5.5}
\end{equation*}
$$

$$
\begin{equation*}
\lim _{\delta \rightarrow 0} J_{\delta, r}(x)=x, \quad \forall x \in B_{r} \tag{5.6}
\end{equation*}
$$

Proof. The first statement follows from (5.2)(i) and the Contraction Principle. Moreover, (5.5) follows from (5.2)(ii) and (5.3) is easily checked. $\quad$.

We set, finally,

$$
\begin{equation*}
\left.F_{\delta, r}(x)=F\left(J_{\delta, r}(x)\right)=\frac{1}{\delta}\left(J_{\delta, r}(x)-x\right), \quad x \in B_{r}, \delta \in\right] 0, \delta_{r}[ \tag{5.7}
\end{equation*}
$$

By (5.5), it follows that

$$
\begin{equation*}
\lim _{\delta \rightarrow 0} F_{\delta, r}(x)=F(x), \quad \forall x \in B_{r} \tag{5.8}
\end{equation*}
$$

We prove the main result of this section:

THEOREM 5.2. Assume (2.2), (4.1) (with $\omega=0$ ) and (5.2). Then problem (5.1) has a unique mild solution $u$. If, moreover, $J_{\delta, r}(Q) \subset Q$ for $\delta \in] 0, \delta_{r}[$ and $x \in Q$, then $u(t) \in Q$ for all $t \geq 0$.

Proof. Fix $r>0$, let $x \in B_{r}$ and $\left.\delta \in\right] 0, \delta_{r}[$. Consider the approximating problem

$$
\left\{\begin{array}{l}
\frac{d}{d t}\left(u_{\delta}(t)+\left(\beta * u_{\delta}\right)(t)\right)=A u_{\delta}(t)+F_{\delta, r}\left(u_{\delta}(t)\right), \quad t>0  \tag{5.9}\\
u_{\delta}(0)=x
\end{array}\right.
$$

which is equivalent to

$$
\begin{equation*}
u_{\delta}(t)=R_{\delta}(t) x+\frac{1}{\delta} \int_{0}^{t} R_{\delta}(t-s) J_{\delta, r}\left(u_{\delta}(s)\right) d s \tag{5.10}
\end{equation*}
$$

where $R_{\delta}$ is the resolvent operator of problem (2.1) with $A$ replaced by $A-1 / \delta$. By standard arguments, equation (5.10) has a unique solution in a maximal interval $\left[0, \tau_{\delta}[\right.$. By (4.3) and (5.5),

$$
\begin{equation*}
\left\|u_{\delta}(t)\right\| \leq s_{\beta+1 / \delta}(t)\|x\|+\frac{1}{\delta} \int_{0}^{t} s_{\beta+1 / \delta}(t-s)\left\|u_{\delta}(s)\right\| d s \tag{5.11}
\end{equation*}
$$

Then

$$
\begin{equation*}
\left\|u_{\delta}(t)\right\| \leq \psi_{\delta}(t)\|x\| \tag{5.12}
\end{equation*}
$$

where $\psi_{\delta}$ is the solution to the integral equation

$$
\begin{equation*}
\psi_{\delta}(t)=s_{\beta+1 / \delta}(t)+\frac{1}{\delta} \int_{0}^{t} s_{\beta+1 / \delta}(t-s) \psi_{\delta}(s) d s \tag{5.13}
\end{equation*}
$$

As is easily checked, $\psi_{\delta}(t)=s_{\beta}(t)$, so that

$$
\begin{equation*}
\left\|u_{\delta}(t)\right\| \leq s_{\beta}(t)\|x\| \tag{5.14}
\end{equation*}
$$

This implies that the solution $u_{\delta}$ of (5.10) is global.
Now, it remains to prove that there exists the limit $\lim _{\delta \rightarrow 0} u_{\delta}(t)=$ $u(t)$ and that $u$ is the required solution. For this purpose we consider the solution $u(t)$ of equation (5.3) in its existence maximal interval $[0, \tau[$; by (5.8) and the Contraction Principle (depending on the parameter $\delta$ ), it follows that

$$
\begin{equation*}
\lim _{\delta \rightarrow 0} u_{\delta}(t)=u(t) \tag{5.15}
\end{equation*}
$$

uniformly in all intervals $\left[0, t_{1}\right] \subset[0, \tau[$. Thus we obtain the a priori estimate

$$
\begin{equation*}
\|u(t)\| \leq s_{\beta}(t)\|x\|, \quad \text { for all } t \in[0, \tau[ \tag{5.16}
\end{equation*}
$$

and problem (3.1) has a global solution.
Let us now assume that $n J_{\delta, r}(Q) \subset Q$; then, by (5.10), it follows that $u_{\delta}(t) \in Q$ for all $t \geq 0$ and $\delta>0$. Thus, by (5.15), we have $u(t) \in Q$ for all $t \geq 0$, and the proof is complete.

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