

## APPROXIMATION BY HÖLDER CONTINUOUS FUNCTIONS IN A SOBOLEV SPACE

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**ABSTRACT.** We prove that a function  $u \in W^{1,1}(\mathbf{R}^n)$  may be simultaneously approximated by a Hölder continuous function both pointwise and in the Sobolev norm.

**1. Introduction.** Given an open set  $\Omega \subset \mathbf{R}^n$  we denote by  $W^{1,p}(\Omega)$ ,  $p \geq 1$ , the Sobolev space consisting of all functions  $u \in L^p(\Omega)$  whose first order distributional partial derivatives also belong to  $L^p(\Omega)$ . The space  $W^{1,p}(\Omega)$  is a Banach space with respect to the norm

$$\|u\|_{1,p;\Omega} = \|u\|_p + \|Du\|_p.$$

A fundamental property of functions  $u \in W^{1,p}(\mathbf{R}^n)$  is quasicontinuity: any function  $u \in W^{1,p}(\mathbf{R}^n)$  has a representative (also denoted by  $u$ ) with the property that, for any  $\varepsilon > 0$  there exists a continuous function  $v$  defined on  $\mathbf{R}^n$  with the property that the set  $\{u \neq v\}$  has small  $p$ -capacity (see e.g., [1]). This is a strengthening of the classical Lusin theorem regarding the approximation of measurable functions continuous functions. Functions  $u \in W^{1,p}(\mathbf{R}^n)$  are identified up to a set with zero  $p$ -capacity with their quasicontinuous representatives.

Malý [8] observed that when  $p > 1$ , if the condition on the capacity is relaxed somewhat, then the approximator  $v$  may be chosen to be Hölder continuous, a property now commonly called *Hölder quasicontinuity*. In addition, Malý showed that the approximator  $v$  may be chosen in the space  $W^{1,p}(\mathbf{R}^n)$  with norm arbitrarily close to  $u$ . Hajlasz and Kinnunen [5], working with Hausdorff content in place of capacity, extended Malý's result to the Sobolev space  $M^{1,p}(X)$  of functions defined on a metric measure space  $X$ , and recently the result has been

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further extended to variable-exponent Sobolev spaces with exponent  $1 < p(x) < n$  by Harjulehto, Kinnunen and Tuhkanen [6].

Although the results mentioned above omit the case  $p = 1$ , Kinnunen and Tuominen [7] have extended the result in [5] to the Sobolev space  $M^{1,1}(X)$ . Since  $M^{1,1}(\mathbf{R}^n) \neq W^{1,1}(\mathbf{R}^n)$  this leaves a small gap concerning the Euclidean case. The purpose of this note is to supplement the above-mentioned results and obtain approximation by Hölder continuous functions in the space  $W^{1,1}(\mathbf{R}^n)$  as well.

It was proved in [9] that if  $u \in W^{1,1}(\mathbf{R}^n)$ , then for any  $\varepsilon > 0$  the continuous approximator satisfying  $v$  may be chosen so that  $\|u-v\|_{1,1} < \varepsilon$  in addition to the set  $\{u \neq v\}$  having 1-capacity less than  $\varepsilon$ . We adapt the methods developed in [5] and [9] to obtain the following main result.

**Theorem 1.1.** *Let  $u \in W^{1,1}(\mathbf{R}^n)$ , and let  $0 < \lambda < 1$ . Then, for any  $\varepsilon > 0$ , there exists a Hölder continuous function  $v \in W^{1,1}(\mathbf{R}^n)$  with exponent  $\lambda$  with the property that*

- (1)  $H_\infty^{n-1+\lambda}(\{x : \bar{u}(x) \neq v(x)\}) < \varepsilon$ , and
- (2)  $\|u - v\|_{1,1} < \varepsilon$ ,

where  $\bar{u}$  is the precise representative of  $u$ .

**2. Preliminaries.** Throughout the paper  $C_{a,b,c,\dots}$  will denote a constant whose precise value depends only on the parameters  $a, b, c, \dots$  but may change between occurrences.

**Definition 2.1.** Let  $\alpha \geq 0$ . The  $\alpha$ -dimensional Hausdorff content of a set  $E \subset \mathbf{R}^n$  is the quantity

$$H_\infty^\alpha(E) = \inf \left\{ \sum_{k=1}^{\infty} (\text{diam } E_k)^\alpha, E \subset \bigcup_{k=1}^{\infty} E_k \right\}.$$

In light of the elementary inequality,

$$\sum_{k=1}^{\infty} a_k^q \leq \left( \sum_{k=1}^{\infty} a_k \right)^q$$

whenever  $a_k \geq 0$  and  $q \geq 1$ , we have

$$(2.1) \quad H_{\infty}^{\alpha_2}(E)^{\alpha_1} \leq H_{\infty}^{\alpha_1}(E)^{\alpha_2},$$

whenever  $0 \leq \alpha_1 \leq \alpha_2$ . In particular, there is a constant  $c_n$  with the property that the Lebesgue outer measure satisfies  $|E| \leq c H_{\infty}^{\alpha}(E)^{n/\alpha}$  whenever  $0 \leq \alpha \leq n$ .

**Definition 2.2.** Let  $u \in L_{\text{loc}}^1(\mathbf{R}^n)$  and let  $x \in \mathbf{R}^n$ . For  $r > 0$ , we define

$$\bar{u}_r(x) = \oint_{B(x,r)} u(y) \, dy.$$

The precise representative of  $u$  is defined by

$$\bar{u}(x) = \lim_{r \rightarrow 0^+} \bar{u}_r(x)$$

at all points  $x \in \mathbf{R}^n$  where this limit exists.

It is well known that, if  $u \in W^{1,1}(\mathbf{R}^n)$ , then  $\bar{u}(x)$  exists for all  $x$  outside a set  $N$  with  $H_{\infty}^{n-1}(N) = 0$  and  $\bar{u}(x)$  is quasicontinuous. Moreover, we have the following uniform behavior (see, e.g., [4, pages 160–162]):

**Proposition 2.3.** *If  $u \in W^{1,1}(\mathbf{R}^n)$ , then for every  $\varepsilon > 0$ , there exists an open set  $U$  with  $H_{\infty}^{n-1}(U) < \varepsilon$  such that*

$$\lim_{r \rightarrow 0^+} \oint_{B(x,r)} |u(y) - \bar{u}(x)| \, dy = 0$$

*uniformly for  $x \in \mathbf{R}^n \setminus U$ .*

**Definition 2.4.** Let  $u \in L_{\text{loc}}^1(\mathbf{R}^n)$ , and let  $\lambda \geq 0$ . The fractional maximal function  $M^{\lambda}u$  is defined by

$$\sup_{r>0} r^{\lambda} \oint_{B(x,r)} |u(y)| \, dy.$$

The following weak-type estimate is well known.

**Proposition 2.5.** *If  $u \in L^1(\mathbf{R}^n)$  and  $t > 0$ , then the set  $\{x : M^\lambda u(x) > t\}$  is open and*

$$H_\infty^{n-\lambda}(\{x : M^\lambda u(x) > t\}) \leq \frac{C_{n,\lambda}}{t} \|u\|_1.$$

Proposition 2.5 is straightforward to prove using a covering argument and the observation that, for any point  $x$  with  $M^\lambda u(x) > t$ , there is a number  $r = r_x$  satisfying

$$r^{n-\lambda} < t^{-1} \int_{B(x,r)} |u(y)| \, dt.$$

The fractional maximal function is used in the following inequalities which may be proved as corollaries of the Bojarski-Hajlasz inequality [5, Theorem 2].

**Proposition 2.6.** *Suppose that  $u \in W^{1,1}(\mathbf{R}^n)$ . Then*

$$|\bar{u}(x) - \bar{u}(y)| \leq C_{n,\lambda} |x - y|^\lambda (M^{1-\lambda} |Du|(x) + M^{1-\lambda} |Du|(y))$$

and

$$\int_{B(x,r)} |u(y) - \bar{u}(x)| \, dy \leq C_{n,\lambda} r^\lambda M^{1-\lambda} |Du|(x)$$

at all points  $x$  where  $\bar{u}(x)$  is defined.

We denote by  $W_0^{1,1}(\Omega)$  the closure of  $C_0^\infty(\Omega)$  in the  $W^{1,1}(\Omega)$  norm. The following characterization of  $W_0^{1,1}(\Omega)$  was obtained in [9]:

**Proposition 2.7.** *Let  $\Omega \subset \mathbf{R}^n$  be an arbitrary open set, and let  $u \in W^{1,1}(\Omega)$ . Then  $u \in W_0^{1,1}(\Omega)$  if and only if*

$$\lim_{r \rightarrow 0^+} r^{-n} \int_{B(x,r) \cap \Omega} |f(y)| \, dy = 0$$

for  $H_\infty^{n-1}$ -almost every  $x \in \partial\Omega$ .

Given a function  $u : \Omega \rightarrow \mathbf{R}$ , denote by  $u^*$  its zero extension off  $\Omega$ :

$$(2.2) \quad u^*(x) = \begin{cases} u(x) & x \in \Omega, \\ 0 & x \notin \Omega. \end{cases}$$

We make the trivial observation that  $u \in W_0^{1,1}(\Omega)$  implies  $u^* \in W^{1,1}(\mathbf{R}^n)$ .

**3. Proof of Theorem 1.** Let  $u \in W^{1,1}(\mathbf{R}^n)$ ,  $0 < \lambda < 1$ , and  $\varepsilon > 0$  be given. Let  $\theta > 0$  be a quantity whose precise value will be specified later. Since

$$H_\infty^{n+1-\lambda}(\{x : M^{1-\lambda}|Du|(x) > T\}) < \frac{C_{\lambda,n}}{T} \|Du\|_1,$$

we may take  $T$  sufficiently large and refer to Proposition 2.3 and equation (2.1) to find an open set  $U$  with  $H^{n-1+\lambda}(U) < \theta$  such that  $\bar{u}(x)$  is defined and  $M^{1-\lambda}|Du(x)| \leq T$  for all  $x \in \mathbf{R}^n \setminus U$ . Define  $K = \mathbf{R}^n \setminus U$ . Then  $K$  is closed, and by Proposition 2.6, we have

$$(3.1) \quad |\bar{u}(x) - \bar{u}(y)| \leq C_{n,\lambda} T |x - y|^\lambda$$

for all  $x, y \in K$  and

$$(3.2) \quad \int_{B(x,r)} |u(y) - \bar{u}(x)| dy \leq C_{n,\lambda} T r^\lambda$$

for all  $x \in K$ . Since  $|U| \leq C_n \theta^{(n-1+\lambda)/n}$ , we may assume without loss of generality that  $|U| < 1$ . The definition of the approximator  $v$  will rely on a smoothing procedure introduced in [3].

**Proposition 3.1.** [3, Lemma 3.2] *There exists a function  $\delta \in C^\infty(U)$  with the property that*

$$(3.3) \quad C_n \text{dist}(x, \partial U) \leq \delta(x) \leq \text{dist}(x, \partial U)$$

for all  $x \in U$  and

$$(3.4) \quad \sup_{x \in U} |D\delta(x)| \leq C_n.$$

At this point, we fix a regularizing kernel  $\phi \in C_0^\infty(B(0,1))$  and a function  $\delta \in C^\infty(U)$  as in Proposition 3.1. For each  $\varepsilon > 0$  write  $\phi_\varepsilon(x) = \varepsilon^{-n} \phi(x/\varepsilon)$ . For each  $z \in U$ , define  $\psi_z(x) = \phi_{\delta(z)/2}(x - z)$ . We define a smoothing  $Su$  of  $u$  on  $U$  by

$$(3.5) \quad Su(z) = \int_{\mathbf{R}^n} \psi_z(x) u(x) dx, \quad z \in U.$$

We will require the following estimate on the  $W^{1,1}(U)$  norm of  $Su$ :

**Proposition 3.2.** [9, Lemma 4.5]  $Su \in C^\infty(U)$  and  $\|Su\|_{1,1;U} \leq C_n \|u\|_{1,1;U}$ .

We are now in a position to define the approximator  $v$ :

$$(3.6) \quad v(x) = \begin{cases} Su(x), & x \in U, \\ \bar{u}(x), & x \in K. \end{cases}$$

By construction, we have

$$H_\infty^{n-1+\lambda}(\{x : \bar{u}(x) \neq v(x)\}) < \theta,$$

which can be made arbitrarily small by choosing  $\theta$  sufficiently close to zero.

We may show that  $v$  is Hölder continuous with exponent  $\lambda$  by considering several cases. Throughout the argument, for any point  $\xi \in U$ , we denote by  $\xi'$  a point in  $K$  satisfying  $|\xi - \xi'| = \text{dist}(\xi, K)$ . We refer to a generic constant simply as  $C$ .

First, if  $x, y \in K$  then by (3.1) we have  $|v(x) - v(y)| \leq CT|x - y|^\lambda$ .

Second, if  $x \in U$  and  $y \in K$ , then  $|v(x') - v(y)| \leq CT|x' - y|^\lambda$  since  $x' \in K$ . By (3.5), we have

$$v(x') - v(x) = \int_{\mathbf{R}^n} \psi_z(w) [\bar{u}(x') - u(w)] dw$$

so that

$$|v(x') - v(x)| \leq C \int_{B(x', 2|x-x'|)} |\bar{u}(x') - u(w)| dw \leq CT|x - x'|^\lambda.$$

Since  $|x - x'| \leq |x - y|$ , we have  $|x' - y| \leq 2|x - y|$  so that

$$|x - x'|^\lambda + |x' - y|^\lambda \leq C|x - y|^\lambda.$$

The triangle inequality yields  $|v(x) - v(y)| \leq CT|x - y|^\lambda$ .

Third, if  $x \in U$ ,  $y \in U$ , and  $|x - x'| < 2|x - y|$ , then  $|y - x'| < 3|x - y|$ . Since

$$\begin{aligned} |v(x) - v(y)| &\leq |v(x) - v(x')| + |v(y) - v(x')| \\ &\leq CT(|x - x'|^\lambda + |y - x'|^\lambda), \end{aligned}$$

we have  $|v(x) - v(y)| \leq CT|x - y|^\lambda$ .

In the fourth and final case we consider  $x \in U$  and  $y \in U$  with  $2|x - y| \leq |x - x'|$ . In this case the line segment adjoining  $x$  and  $y$  lies entirely within  $U$ . For any point  $z \in U$  and real number  $a$  we have

$$v(z) - a = \int_{\mathbf{R}^n} \psi_z(x)[u(w) - a] dw$$

so that

$$Dv(z) = \int_{\mathbf{R}^n} D\psi_z(x)[u(w) - a] dw,$$

and therefore

$$|Dv(z)| \leq \int_{\mathbf{R}^n} |D\psi_z(w)||u(w) - a| dw.$$

In light of (3.3) and (3.4) we have  $|D\phi_z| \leq C_n\delta(z)^{-n-1}$ , so that

$$\begin{aligned} |Dv(z)| &\leq C\delta(z)^{-1} \int_{B(z, \delta(z)/2)} |u(w) - a| dw \\ &\leq C\delta(z)^{-1} \int_{B(z', 2|z - z'|)} |u(w) - a| dw. \end{aligned}$$

With the special choice  $a = v(z')$ , we may appeal to (3.2) to conclude that

$$|Dv(z)| \leq C\delta(z)^{-1+\lambda} M^{1-\lambda} |Du|(z') \leq CT\delta(z)^{-1+\lambda} \leq CT|z - z'|^{-1+\lambda}$$

for all  $z \in U$ . In particular, for any point  $z$  belonging to the line segment adjoining  $x$  and  $y$  and satisfying

$$|v(x) - v(y)| = |Dv(z)||x - y|$$

we have the estimate

$$|v(x) - v(y)| \leq CT|z - z'|^{-1+\lambda}|x - y|.$$

The geometry of the situation implies  $|x - y| \leq |z - z'|$ , since otherwise we would have  $|x - x'| \leq |x - z'| \leq |x - z| + |z - z'| < 2|x - y|$ . Thus,

$$|v(x) - v(y)| \leq CT|x - y|^\lambda,$$

as required.

By construction, we have  $v, u \in W^{1,1}(U)$ . Since

$$\begin{aligned} r^{-n} \int_{B(x,r) \cap U} |v(y) - u(y)| \, dy &\leq C_n \int_{B(x,r)} |v(y) - v(x)| \, dy \\ &\quad + C_n \int_{B(x,r)} |u(y) - \bar{u}(x)| \, dy \end{aligned}$$

for all  $x \in K$ , the fact that  $v$  is continuous and (3.2) holds on  $K$ , we obtain

$$\lim_{r \rightarrow 0^+} r^{-n} \int_{B(x,r) \cap U} |v(y) - u(y)| \, dy = 0$$

for all  $x \in \partial U$ . Proposition 2.7 implies that  $v - u \in W_0^{1,1}(U)$ , and consequently  $(v - u)^* \in W^{1,1}(\mathbf{R}^n)$ . It follows that

$$v = (v - u)^* + u \in W^{1,1}(\mathbf{R}^n).$$

Moreover,

$$\|u - v\|_{1,1} = \|u - v\|_{1,1;U} \leq \|u\|_{1,1;U} + \|v\|_{1,1;U} \leq C_n \|u\|_{1,1;U}$$

by Proposition 3.2. Since  $|U| \rightarrow 0$  as  $\theta \rightarrow 0$ , we may choose  $\theta$  sufficiently small to guarantee  $\|u - v\|_{1,1} < \varepsilon$ .

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