ON GENERATING SUBGROUPS OF THE AFFINE GROUP ON THE PLANE BY PAIRS OF INFINITESIMAL TRANSFORMATIONS*

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ABSTRACT. Let G be a Lie group with Lie algebra g and let X and Y be elements of g. If every element of G can be written as a product of elements taken alternately from $\exp(tX)$ and $\exp(tY)$, X and Y are said to generate G. A classification will be obtained here of all Lie subgroups of the affine group acting on the plane; for each such group, necessary and sufficient conditions will be found that a pair of elements in the Lie algebra generate the group. All but three subgroups of the affine group can be so generated.

I. Introduction. The real affine group A(2) acting on the plane is the set of all transformations from R^2 to R^2 of the form $v \rightarrow Av + l$, where $A \in GL(2, R)$ and $l \in R^2$. From now on denote such a transformation by $\langle A, l \rangle$. Then $\langle A, l \rangle \circ \langle B, m \rangle = \langle AB, l + Am \rangle$. The Lie algebra a(2) of A(2) consists of all $\langle A, l \rangle$ with $A \in M_2(R)$ and $l \in R^2$; $[\langle A, l \rangle, \langle B, m \rangle] = \langle AB - BA, Am - Bl \rangle$. We shall determine all Lie subalgebras of a(2) up to conjugacy, and thereby all connected Lie subgroups of A(2) up to conjugacy.

A connected Lie group G is generated by a pair of one-parameter subgroups if every element of G can be written as a finite product of elements chosen alternately from the two one-parameter subgroups. This happens just in case the Lie algebra of G is generated by the corresponding pair of infinitesimal transformations, because the set of all such finite products is an arcwise connected subgroup of G and so a Lie subgroup by Yamabe's theorem [4]. It is known that all connected subgroups of the Moebius group $w = (\alpha z + \beta)/(\nu z + \zeta)$, α , β , ν , and ζ complex, can be generated by an appropriate pair of infinitesimal transformations with the exception of the group $w = \alpha z + \beta$, $\alpha > 0$ [2]. This group is also a subgroup of A(2); we will show that all subgroups of A(2), with the exception of this group and two others, can be generated by a suitable pair of infinitesimal transformations.

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II. Subalgebras of $M_2(\mathbf{R})$.

THEOREM 1. Let g be a subalgebra of $M_2(\mathbf{R})$. Then g is conjugate to precisely one of the following:

 $(1) \{0\} \qquad (2) R \begin{pmatrix} 1 & 0 \\ 0 & \lambda \end{pmatrix} \text{ where } |\lambda| \leq 1$ $(3) R \begin{pmatrix} \lambda & -1 \\ 1 & \lambda \end{pmatrix} \text{ where } 0 \leq \lambda \qquad (4) R \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ $(5) R \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \qquad (6) \left\{ \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} \right\}$ $(7) \left\{ \begin{pmatrix} a & b \\ 0 & a \end{pmatrix} \right\} \qquad (8) \left\{ \begin{pmatrix} a & -b \\ b & a \end{pmatrix} \right\}$ $(9) \left\{ \begin{pmatrix} \lambda a & b \\ 0 & (\lambda + 1)a \end{pmatrix} \right\} \text{ where } \lambda \in R \qquad (10) \left\{ \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \right\}$ $(11) \mathfrak{sl}(2, R) \qquad (12) M_2(R).$

PROOF. The rational canonical form theorem implies that each onedimensional g is conjugate to an algebra listed in (2) through (5).

LEMMA. If $g \subset M_2(R)$ is isomorphic to $R \oplus R$, g contains the identity matrix I.

PROOF. Suppose not and let e and f generate g. Choose $h \in M_2(R)$ so $\{e, f, I, h\}$ is a basis for $M_2(R)$. Then $\mathfrak{sl}(2, R) = [M_2(R), M_2(R)]$ is generated by [e, h] and [f, h], although it is three dimensional.

Assume that g is isomorphic to $R \oplus R$ and choose e so e and I generate g; after suitable conjugation we may suppose that e is one of the matrices listed in (2) through (5); after subtracting a suitable multiple of I, we may suppose that e is one of $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$. Thus g is conjugate to 6, 7, or 8; no two of these algebras are conjugate because every matrix in 6 is diagonalizable and every matrix in 7 has at least one real eigenvalue.

If g is two dimensional and non-abelian, g has a basis $\{e, f\}$ so [e, f] = e. Notice that tr e = 0; after suitable conjugation, then, $e = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \text{ or } \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$. Let $f = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$; [e, f] is then $\begin{pmatrix} 0 & 2b \\ -2c & 0 \end{pmatrix}$, $\begin{pmatrix} -b-c & a-d \\ b+c \end{pmatrix}$; or $\begin{pmatrix} c & d-a \\ -c \end{pmatrix}$; this can equal e only if $e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ and $f = \begin{pmatrix} a & b \\ 0 & a+1 \end{pmatrix}$, so g is conjugate to an algebra listed in (9). Distinct λ 's give distinct conjugacy classes of algebras, for if g is conjugate to $\{ \begin{pmatrix} \lambda a & b \\ 0 & (\lambda+1)a \end{pmatrix} \}$, g contains an element with two distinct eigenvalues one unit apart, and these eigenvalues must be λ and $\lambda + 1$.

Suppose dim g = 3 and $I \notin g$. Then $g \oplus RI = M_2(R)$ and $\mathfrak{sl}(2, R) = [M_2(R), M_2(R)] \subset [g, g] \subset g$, so $\mathfrak{sl}(2, R) = g$.

Finally suppose dim g = 3 and $I \in g$. Then $\mathfrak{sl}(2, R) \cap g$ is a two dimensional Lie algebra and so conjugate to one of 6, 7, 8, 9; since any algebra conjugate to $\mathfrak{sl}(2, R) \cap g$ is contained in $\mathfrak{sl}(2, R)$, $\mathfrak{sl}(2, R) \cap g$ is conjugate to $\begin{pmatrix} -a/2 & b \\ a & d \end{pmatrix}$ and g is conjugate to 10.

THEOREM 2. Every connected Lie subgroup of GL(2, R) is conjugate to precisely one of the following:

 $(1) \{I\} \qquad (2) \left\{ \begin{pmatrix} e^{t} & 0\\ 0 & e^{\lambda t} \end{pmatrix} \right\} \text{ where } |\lambda| \leq 1$ $(3) \left\{ e^{\lambda t} \begin{pmatrix} \cos t & -\sin t\\ \sin t & \cos t \end{pmatrix} \right\} \qquad (4) \left\{ \begin{pmatrix} 1 & t\\ 0 & 1 \end{pmatrix} \right\}$ $(5) \left\{ e^{t} \begin{pmatrix} 1 & t\\ 0 & 1 \end{pmatrix} \right\} \qquad (6) \left\{ \begin{pmatrix} a & 0\\ 0 & b \end{pmatrix} \right| \ a > 0, b > 0 \right\}$ $(7) \left\{ \begin{pmatrix} a & b\\ 0 & a \end{pmatrix} \right| \ a > 0 \right\} \qquad (8) \left\{ a \begin{pmatrix} \cos t & -\sin t\\ \sin t & \cos t \end{pmatrix} \right| \ a > 0 \right\}$ $(9) \left\{ \begin{pmatrix} a^{\lambda} & b\\ 0 & a^{\lambda+1} \end{pmatrix} \right| \ a > 0 \right\} \qquad (10) \left\{ \begin{pmatrix} a & b\\ 0 & d \end{pmatrix} \right| \ a > 0, d > 0 \right\}$

(9)
$$\left\{ \begin{pmatrix} a^{\lambda} & b \\ 0 & a^{\lambda+1} \end{pmatrix} \middle| a > 0 \right\}$$
 (10) $\left\{ \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \middle| a > 0, d > 0 \right\}$
where $\lambda \in B$

(11)
$$\left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \middle| ad - bc = 1 \right\}$$
 (12) $\left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \middle| ad - bc > 0 \right\}$

PROOF. An immediate consequence of Theorem 1.

III. Subalgebras of a(2). Let g be a subalgebra of a(2); define $g_0 = \{A \in M_2(R) \mid \text{there exists } l \in R^2 \text{ such that } \langle A, l \rangle \in g\}$ and $V = \{l \in R^2 \mid \langle 0, l \rangle \in g\}$. Then g_0 is a subalgebra of $M_2(R)$ and V is a subspace of R^2 ; $g_0(V) \subset V$ because $[\langle A, l \rangle, \langle 0, m \rangle] = \langle 0, Am \rangle$. The following sequence is exact:

$$0 \to V \to g \to g_0 \to 0$$

Notice that conjugation of $\langle A, \mathfrak{l} \rangle \in a(2)$ by $\langle B, m \rangle \in A(2)$ yields $\langle BAB^{-1}, B\mathfrak{l} - BAB^{-1}m \rangle$. In particular g_0 becomes Bg_0B^{-1} and V becomes BV.

THEOREM 3. The pair $\{g_0, V\}$ is conjugate to precisely one of the following:

(a) $\{g_0, \{0\}\}\$ where g_0 is one of the algebras listed in Theorem 1

(b) $\{g_0, R^2\}$ where g_0 is one of the algebras listed in Theorem 1

(c) $\{g_0, R(_0^1)\}$ where g_0 is one of $\{0\}, R(_{0-1}^{1-0}), R(_{0-1}^{1-0}), R(_{0-0}^{0-1}),$ $\begin{array}{c} R(\begin{smallmatrix} 1 & 1 \\ 0 & 1 \end{smallmatrix}), \{(\begin{smallmatrix} a & 0 \\ 0 & b \end{smallmatrix})\}, \{(\begin{smallmatrix} \lambda a & b \\ 0 & (\lambda + 1)a \end{smallmatrix})\}, \{(\begin{smallmatrix} a & b \\ 0 & a \end{smallmatrix})\}, \{(\begin{smallmatrix} a$

PROOF. We can assume that g_0 is one of the algebras listed in Theorem 1. The condition $g_0(V) \subset V$ puts no restriction on V if dim V $= 0 \text{ or } 2; \text{ when dim } V = 1, V \text{ can be arbitrary if } g = \{0\} \text{ or } R(\begin{smallmatrix} 1 & 0 \\ 0 & 1 \end{smallmatrix}), V = R(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}) \text{ or } R(\begin{smallmatrix} 1 \\ 1 \end{smallmatrix}) \text{ if } g = R(\begin{smallmatrix} 1 & 0 \\ 0 \end{smallmatrix}), -1 \leq \lambda < 1 \text{ or } \{(\begin{smallmatrix} a & b \\ 0 \end{smallmatrix})\}, V = R(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}), V = R(I) \end{smallmatrix}), V = R(I)$ wise no one-dimensional V will work. When $g_0 = \{0\}$ or $R(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, $Bg_0B^{-1} = g_0$ for all B; applying an appropriate B to V we can assume $V = R({}^{1}_{0}). \quad \text{If} \quad g_{0} = \{ ({}^{1}_{0} {}^{b}_{b}) \} \quad \text{or} \quad R({}^{1}_{0} {}^{-1}_{-1}), \quad ({}^{0}_{1} {}^{1}_{0})g_{0}({}^{0}_{1} {}^{-1}_{0})^{-1} = g_{0} \text{ and}$ $\binom{0}{1} \binom{1}{0} R\binom{1}{0} = R\binom{0}{1}$; thus V can be taken to be $R\binom{1}{0}$. If $g_0 = R\binom{1}{0} \binom{0}{\lambda}$ for $|\lambda| < 1$ and $Bg_0 B^{-1} = g_0$, $B = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}$ so $R \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $R \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ are not conjugate.

Choose a subspace V_1 of R^2 so $V \oplus V_1 = R^2$. Whenever $A \in g_0$, there is a unique $\varphi(A) \in V_1$ so $\langle A, \varphi(A) \rangle \in g$. Clearly $g = \{\langle A, \varphi(A) \rangle$ $+ l \rangle | A \in g_0, l \in V \}.$

Notice that $\varphi: g_0 \to V_1$ is linear. Let $P: \mathbb{R}^2 \to V_1$ be the obvious map. Then $\varphi([A, B]) = P\{A\varphi(B) - B\varphi(A)\}$ projection since $[\langle A, \varphi(A) \rangle, \langle B, \varphi(B) \rangle] = \langle [A, B], A\varphi(B) - B\varphi(A) \rangle.$

Conjugation of g by $\langle I, m \rangle$ leaves g_0 and V fixed and converts $\langle A, \varphi(A) \rangle$ to $\langle A, \varphi(A) - Am \rangle$. Hence we may replace $\varphi(A)$ by $P\{\varphi(A) - Am\}$ and obtain a conjugate algebra.

If $g_0 = \{0\}, \varphi = 0$. If $g_0 = Re$ where $e = \begin{pmatrix} 1 & 0 \\ 0 & \lambda \end{pmatrix}$ $0 < |\lambda| \le 1, \begin{pmatrix} \lambda & -1 \\ 1 & \lambda \end{pmatrix}$ $0 \leq \lambda$ or $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$, *m* can be found so $\varphi(e) = em$ since det $e \neq 0$. Thus after conjugation $\varphi = 0$. If $I \in g_0$ we can suppose $\varphi(I) = 0$ since I is nonsingular; whenever $A \in g_0$, $0 = \varphi([I, A]) = P\{\varphi(A)\} = \varphi(A)$, so $\varphi = 0$. If $g_0 = \mathfrak{sl}(2, R)$, $\varphi = 0$ unless $V = \{0\}$ and $V_1 = R^2$. In this case let $e = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, $f = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $g = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$; as usual we may $2\varphi(f) = \varphi[e, f] = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \varphi(f),$ $\varphi(e) = 0.$ Then assume so $\varphi(f) = 0$. Similarly $-2\varphi(g) = \varphi[e, g] = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}\varphi(g)$, so $\varphi(g) = 0$ and $\varphi = 0$. If $g_0 = \{ \begin{pmatrix} \lambda a & b \\ 0 & (\lambda+1)a \end{pmatrix} \}$, let $e = \begin{pmatrix} \lambda & 0 \\ 0 & \lambda+1 \end{pmatrix}$, $f = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$. Suppose $\lambda \neq 0, -1$, or -2. Then $\det(\begin{pmatrix} \lambda & 0 \\ 0 & \lambda+1 \end{pmatrix} \neq 0$ and we can suppose $\varphi(e) = 0; \quad -\varphi(f) = \varphi[e, f] = P\{ \begin{pmatrix} \lambda & 0 \\ 0 & \lambda+1 \end{pmatrix} \varphi(f) \}. \quad \text{If} \quad V = \{0\} \text{ and }$ $\varphi(f) = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$, $\begin{pmatrix} (1+\lambda)v_1 \\ (2+\lambda)v_2 \end{pmatrix} = 0$ so $v_1 = v_2 = 0$ and $\varphi = 0$. If V = R(0) let $V_1 = R({}^0_1)$ and $\varphi(f) = ({}^0_v)$; then $-({}^0_v) = ({}^0_{(\lambda+1)v})$ and v = 0, so $\varphi = 0$. In short, φ can be taken to be zero unless $g_0 = R({}^0_1 {}^0_0)$, $R({}^0_0 {}^1_0)$, $\{({}^0_0 {}^a_a)\}, \{({}^0_0 {}^a_b)\}, \text{ or } \{({}^{2a}_{0} {}^a_a)\}$. The following five lemmas complete the classification.

LEMMA 1. Let $g_0 = R(\begin{smallmatrix} 1 & 0 \\ 0 & 0 \end{smallmatrix})$. If $V = R(\begin{smallmatrix} 0 \\ 1 \end{pmatrix}$ or R^2 , φ can be taken to be zero. If $V = \{0\}$ or $R(\begin{smallmatrix} 1 \\ 0 \\ 0 \end{smallmatrix})$, $\varphi(\begin{smallmatrix} 1 & 0 \\ 0 \\ 0 \end{smallmatrix})$ can be taken to be 0 or $(\begin{smallmatrix} 0 \\ 1 \\ 0 \end{smallmatrix})$.

PROOF. If $Bg_0B^{-1} = g_0$, $B = \begin{pmatrix} a & 0 \\ 0 & d \end{pmatrix}$; such a *B* preserves all possible *V*. Conjugation of $\langle \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$, $\varphi(\begin{smallmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \rangle$ by $\langle \begin{pmatrix} a & 0 \\ 0 & d \end{pmatrix}$, $m \rangle$ yields $\langle \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} \delta & 0 \\ 0 & d \end{pmatrix} \varphi(\begin{smallmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} m \rangle$. Clearly *a*, *d*, and *m* can be chosen to make the second part of this expression equal 0 or $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$. We are interested in the projection of this term on V_1 ; since $V_1 = R^2$, $R(_1^0)$, $R(_0^1)$, and $\{0\}$ when $V = \{0\}$, $R(_0^1)$, $R(_1^0)$, and R^2 , the lemma follows.

LEMMA 2. Let $g_0 = R({}^0_0 {}^1_0)$. If $V = R^2$, $\varphi = 0$. If $V = \{0\}$ or $R({}^0_0), \varphi({}^0_0 {}^1_0)$ can be taken to be 0 or $({}^0_1)$.

PROOF. If $Bg_0B^{-1} = g_0$, $B = \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$; such a *B* preserves all possible *V*. Conjugation of $\langle \begin{pmatrix} 0 & b \\ 0 & d \end{pmatrix}$, $\varphi \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \rangle$ by $\langle \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$, $m \rangle$ yields $\langle \begin{pmatrix} 0 & a/d \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} a & b \\ 0 & 0 \end{pmatrix} \varphi \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & a/d \\ 0 & 0 \end{pmatrix} m \rangle$. Clearly a = d and m can be chosen to make the second part of this expression equal 0 or $\binom{0}{1}$.

LEMMA 3. Let $g_0 = \{\begin{pmatrix} 0 & b \\ 0 & a \end{pmatrix}\}$. If $V = R(\begin{smallmatrix} 1 \\ 0 \end{pmatrix}$ or R^2 , φ can be taken to be zero. If $V = \{0\}$, $\varphi(\begin{smallmatrix} 0 & b \\ 0 & a \end{pmatrix}$ can be taken to be 0 or $\begin{pmatrix} a \\ 0 \end{pmatrix}$.

PROOF. Let $e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $f = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$, $\varphi(e) = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$, $\varphi(f) = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$. If $V = \{0\}$, $\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \varphi(e) = \varphi[e, f] = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} w_1 \\ w_2 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} w_2 \\ -v_2 \end{pmatrix}$, so $v_1 = w_2$ and $v_2 = 0$. If $V = R(\frac{1}{0})$, let $V_1 = R(\frac{0}{1})$; then $v_1 = w_1 = 0$ and $\begin{pmatrix} 0 \\ -v_2 \end{pmatrix} = \varphi(e) = \varphi[e, f] = P\{\begin{pmatrix} w_2 \\ -v_2 \end{pmatrix}\} = \begin{pmatrix} 0 \\ -v_2 \end{pmatrix}$, so $v_2 = 0$.

If $Bg_0B^{-1} = g_0$, $B = \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$; such a *B* preserves all possible *V*. Conjugation of $\langle e, \varphi(e) \rangle$ and $\langle f, \varphi(f) \rangle$ by $\langle \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}, m \rangle$ yields $\langle \begin{pmatrix} 0 & a/d \\ 0 & d \end{pmatrix}, \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \varphi(e) - \begin{pmatrix} 0 & a/d \\ 0 & d \end{pmatrix} m \rangle$ and $\langle \begin{pmatrix} 0 & b/d \\ 0 & d \end{pmatrix}, \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \varphi(f) - \begin{pmatrix} 0 & b/d \\ 0 & d \end{pmatrix} \varphi(f) - \begin{pmatrix} 0 & b/d \\ 0 & d \end{pmatrix} \varphi(f) = 0$, the projection of $\begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \varphi(e) - \begin{pmatrix} 0 & a/d \\ 0 & d \end{pmatrix} m$ is automatically zero; clearly a = d, b = 0, and *m* can be chosen to make the projection of $\begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \varphi(f) - \begin{pmatrix} 0 & b/d \\ 0 & d \end{pmatrix} \varphi(f)$. If $V = \{0\}$, let $\tilde{\varphi}$ be the conjugate of φ ;

$$\begin{split} \tilde{\varphi}(e) &= \frac{d}{a} \tilde{\varphi} \begin{pmatrix} 0 & a/d \\ 0 & 0 \end{pmatrix} = \frac{d}{a} \left\{ \begin{pmatrix} ab \\ 0d \end{pmatrix} \begin{pmatrix} v_1 \\ 0 \end{pmatrix} \\ & - \begin{pmatrix} 0 & a/d \\ 0 & 0 \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} \right\} = \begin{pmatrix} dv_1 - m_2 \\ 0 \end{pmatrix}, \end{split}$$

$$\begin{split} \tilde{\varphi}(f) &= \tilde{\varphi} \begin{pmatrix} 0 & b/d \\ 0 & 1 \end{pmatrix} - \frac{b}{d} \tilde{\varphi}(e) = \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \begin{pmatrix} w_1 \\ v_1 \end{pmatrix} \\ &- \begin{pmatrix} 0 & b/d \\ 0 & 1 \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} - \begin{pmatrix} bv_1 - b/d m_2 \\ 0 \end{pmatrix} = \begin{pmatrix} aw_1 \\ dv_1 - m_2 \end{pmatrix}. \end{split}$$

Clearly a, d, and m_2 can be chosen to make $\tilde{\varphi}(e) = 0$ and $\tilde{\varphi}(f)$ either 0 or $\binom{1}{0}$.

LEMMA 4. Let $g_0 = \{\begin{pmatrix} a & b \\ 0 & 0 \end{pmatrix}\}$. If $V = \{0\}$ or R^2 , φ can be taken to be zero. If $V = R(\begin{smallmatrix} 1 \\ 0 \end{pmatrix}, \varphi(\begin{smallmatrix} a & b \\ 0 & 0 \end{pmatrix}$ can be taken to be 0 or $(\begin{smallmatrix} 0 \\ a \end{pmatrix}$.

PROOF. Let $e = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$, $f = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$, $\varphi(e) = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$, $\varphi(f) = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$. If $V = \{0\}$, $-\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = -\varphi(e) = \varphi[e, f] = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} w_1 \\ w_2 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} w_2 & v_2 \\ v_2 \end{pmatrix}$, so $w_2 = v_2 = 0$. Conjugation by $\langle I, \begin{pmatrix} w_1 \\ v_1 \end{pmatrix} \rangle$ converts $\langle e, \varphi(e) \rangle$ and $\langle f, \varphi(f) \rangle$ to $\langle e, 0 \rangle$ and $\langle f, 0 \rangle$, so φ can be taken to be zero. If $V = R\begin{pmatrix} 1 \\ 0 \end{pmatrix}$, let $V_1 = R\begin{pmatrix} 0 \\ 1 \end{pmatrix}$; then $v_1 = w_1 = 0$ and $-\begin{pmatrix} 0 \\ v_2 \end{pmatrix} = \varphi[e, f] = P\{\begin{pmatrix} w_2 \\ 0 \end{pmatrix}\} = 0$, so $v_2 = 0$. If $Bg_0B^{-1} = g_0$, $B = \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$. Conjugation of $\langle e, 0 \rangle$ and $\langle f, \varphi(f) \rangle$ by $\langle \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$, $\begin{pmatrix} m_1 \\ m_2 \end{pmatrix} \rangle$ yields $\langle \begin{pmatrix} 0 & a/d \\ 0 & d \end{pmatrix}, \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} \rangle$ and $\langle \begin{pmatrix} 1 & -b/a \\ 0 & d \end{pmatrix}, \begin{pmatrix} w_2 \\ 0 & d \end{pmatrix} = \begin{pmatrix} 0 & -b/d \\ 0 & d \end{pmatrix}$; we are only interested in the projection of the second parts of these expressions on R(1), so $\tilde{\varphi}(e) = 0$, $\tilde{\varphi}(f) = \begin{pmatrix} 0 \\ dw_2 \end{pmatrix}$. Clearly d can be chosen so $\tilde{\varphi}(f) = 0$ or $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

LEMMA 5. Let $g_0 = \{ \begin{pmatrix} 2a & b \\ 0 & a \end{pmatrix} \}$. If $V = R^2$, φ is zero. If $V = \{0\}$ or $R({}^1_0), \varphi({}^{2a}_0 {}^b_a)$ can be taken to be 0 or $({}^0_b)$.

PROOF. Let $e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $f = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$. Since f is non-singular, $\varphi(f)$ can be taken to be zero; let $\varphi(e) = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$. If $V = \{0\}, -\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = -\varphi(e) = \varphi[e, f] = -\begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$, $\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} -2v_1 \\ -v_2 \end{pmatrix}$, so $v_1 = 0$. If $V = R(\frac{1}{2})$, let $V_1 = R(\frac{1}{2})$; then $v_1 = 0$.

If $Bg_0B^{-1} = g_0$, $B = \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$. Conjugation of $\langle e, \varphi(e) \rangle$ and $\langle f, 0 \rangle$ by $\langle \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}, \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} \rangle$ yields respectively

$$\left\langle \begin{pmatrix} 0 & a/d \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \begin{pmatrix} 0 \\ v_2 \end{pmatrix} - \begin{pmatrix} 0 & a/d \\ 0 & 0 \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} \right\rangle,$$
$$\left\langle \begin{pmatrix} 2 & -b/d \\ 0 & 1 \end{pmatrix}, - \begin{pmatrix} 2 & -b/d \\ 0 & 1 \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} \right\rangle.$$

If $V = \{0\}$,

$$\tilde{\varphi}(e) = \begin{pmatrix} \frac{bd}{a}v_2 - m_2\\ \frac{d^2}{a}v_2 \end{pmatrix} \quad , \quad \tilde{\varphi}(f) = \begin{pmatrix} -2m_1 + \frac{b^2}{a}v_2\\ \frac{bd}{a}v_2 - m_2 \end{pmatrix}$$

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Clearly *a*, *b*, *d*, *m*₁, and *m*₂ can be chosen so $\tilde{\varphi}(e) = 0$ or $\binom{0}{1}$ and $\tilde{\varphi}(f) = 0$. If $V = R\binom{1}{0}$, we are only interested in the projections of the above expressions on $R\binom{0}{1}$, so $\tilde{\varphi}(e) = \binom{0}{(d^2/a)v_2}$ and $\tilde{\varphi}(f) = \binom{0}{(bd/a)v_2 - m_2}$; clearly *a*, *b*, *d*, and *m*₂ can be chosen so $\tilde{\varphi}(e) = 0$ or $\binom{0}{1}$ and $\tilde{\varphi}(f) = 0$.

Combining the above results, we obtain:

THEOREM 4. Let g be a subalgebra of a(2). Then g is conjugate to precisely one of the following:

A. $\{\langle A, 0 \rangle \mid A \in g_0\}$ or $\{\langle A, l \rangle \mid A \in g_0, l \in R^2\}$ where g_0 is one of the following

1. $\{0\}$ 2. $R\begin{pmatrix}1 & 0\\ 0 & \lambda\end{pmatrix}$ where $|\lambda| \leq 1$ 3. $R\begin{pmatrix}\lambda & -1\\ 1 & \lambda\end{pmatrix}$ where $0 \leq \lambda$ 4. $R\begin{pmatrix}0 & 1\\ 0 & 0\end{pmatrix}$ 5. $R\begin{pmatrix}1 & 1\\ 0 & 1\end{pmatrix}$ 6. $\{\begin{pmatrix}a & 0\\ 0 & b\end{pmatrix}\}$ 7. $\{\begin{pmatrix}a & b\\ 0 & a\end{pmatrix}\}$ 8. $\{\begin{pmatrix}a & -b\\ b & a\end{pmatrix}\}$ 9. $\{\begin{pmatrix}\lambda a & b\\ 0 & (\lambda + 1)a\end{pmatrix}\}$ where $\lambda \in R$ 10. $\{\begin{pmatrix}a & b\\ 0 & d\end{pmatrix}\}$ 11. $\mathfrak{S}(2, R)$ 12. $M_2(R)$.

B. $\{\langle A, l \rangle \mid A \in g_0, l \in V\}$ where $\{g_0, V\}$ is one of

13. 0, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ 14. $R\begin{pmatrix} 1&0\\0&\lambda \end{pmatrix}$, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ where $|\lambda| \leq 1$ 15. $R\begin{pmatrix} 1&0\\0&\lambda \end{pmatrix}$, $R\begin{pmatrix} 0\\1 \end{pmatrix}$ where $|\lambda| < 1$ 16. $R\begin{pmatrix} 0&1\\0&0 \end{pmatrix}$, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ where $|\lambda| < 1$ 17. $R\begin{pmatrix} 1&1\\0&1 \end{pmatrix}$, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ 18. $\left\{ \begin{pmatrix} a&0\\0&b \end{pmatrix} \right\}$, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ 19. $\left\{ \begin{pmatrix} a&b\\0&a \end{pmatrix} \right\}$, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ 20. $\left\{ \begin{pmatrix} \lambda a&b\\0&(\lambda+1)a \end{pmatrix} \right\}$, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ 21. $\left\{ \begin{pmatrix} a&b\\0&d \end{pmatrix} \right\}$, $R\begin{pmatrix} 1\\0 \end{pmatrix}$ where $\lambda \in R$ С.

22.
$$\left\{ \left\langle \begin{pmatrix} r & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ r \end{pmatrix} \right\rangle \middle| r \in R \right\}$$

23.
$$\left\{ \left\langle \begin{pmatrix} 0 & r \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ r \end{pmatrix} \right\rangle \middle| r \in R \right\}$$

24.
$$\left\{ \left\langle \begin{pmatrix} 0 & r \\ 0 & s \end{pmatrix}, \begin{pmatrix} s \\ 0 \end{pmatrix} \right\rangle \middle| r, s \in R \right\}$$

25.
$$\left\{ \left\langle \begin{pmatrix} 2r & s \\ 0 & r \end{pmatrix}, \begin{pmatrix} 0 \\ s \end{pmatrix} \right\rangle \middle| r, s \in R \right\}$$

26.
$$\left\{ \left\langle \begin{pmatrix} r & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} s \\ r \end{pmatrix} \right\rangle \middle| r, s \in R \right\}$$

27.
$$\left\{ \left\langle \begin{pmatrix} 0 & r \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} s \\ r \end{pmatrix} \right\rangle \middle| r, s \in R \right\}$$

28.
$$\left\{ \left\langle \begin{pmatrix} r & s \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} t \\ r \end{pmatrix} \right\rangle \middle| r, s, t \in R \right\}$$

29.
$$\left\{ \left\langle \begin{pmatrix} 2r & s \\ 0 & r \end{pmatrix}, \begin{pmatrix} t \\ s \end{pmatrix} \right\rangle \middle| r, s, t \in R \right\}$$

THEOREM 5. Let G be a connected Lie subgroup of A(2). Then G is conjugate to precisely one of the following:

A. $\{\langle A, 0 \rangle \mid A \in G_0\}$ or $\{\langle A, \ell \rangle \mid A \in G_0, \ell \in \mathbb{R}^2\}$ where G_0 is one of the following, 1 {1}

1.
$$\{1\}$$

3. $\left\{e^{\lambda t}\begin{pmatrix}\cos t & -\sin t\\\sin t & \cos t\end{pmatrix}\right\}$
where $\lambda \ge 0$
5. $\left\{e^{t}\begin{pmatrix}1 & t\\0 & 1\end{pmatrix}\right\}$
5. $\left\{e^{t}\begin{pmatrix}1 & t\\0 & 1\end{pmatrix}\right\}$
7. $\left\{\begin{pmatrix}a & b\\0 & a\end{pmatrix} \mid a > 0\right\}$
9. $\left\{\begin{pmatrix}a^{\lambda} & b\\0 & a^{\lambda+1}\end{pmatrix} \mid a > 0\right\}$
where $\lambda \in \mathbb{R}$
11. $\left\{\begin{pmatrix}a & b\\c & d\end{pmatrix} \mid ad - bc = 1\right\}$
2. $\left\{\begin{pmatrix}e^{t} & 0\\0 & e^{\lambda t}\end{pmatrix}\right\}$
4. $\left\{\begin{pmatrix}1 & t\\0 & 1\end{pmatrix}\right\}$
6. $\left\{\begin{pmatrix}1 & t\\0 & 1\end{pmatrix}\right\}$
6. $\left\{\begin{pmatrix}a & 0\\0 & b\end{pmatrix} \mid a > 0, b > 0\right\}$
8. $\left\{a\begin{pmatrix}\cos t & -\sin t\\\sin t & \cos t\end{pmatrix} \mid a > 0\right\}$
10. $\left\{\begin{pmatrix}a & b\\0 & d\end{pmatrix} \mid a > 0, d > 0\right\}$
11. $\left\{\begin{pmatrix}a & b\\c & d\end{pmatrix} \mid ad - bc = 1\right\}$
12. $\left\{\begin{pmatrix}a & b\\c & d\end{pmatrix} \mid ad - bc \neq 0\right\}$

B.
$$\{\langle A, L \rangle \mid A \in G_0, L \in V\}$$
 where $\{G_0, V\}$ is one of
13. $\{I\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$ 14. $\{\begin{pmatrix} e^t & 0\\ 0 & e^{At} \end{pmatrix}\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$ where $|\lambda| \leq 1$
15. $\{\begin{pmatrix} e^t & 0\\ 0 & e^{At} \end{pmatrix}\}, R\begin{pmatrix} 0\\ 1 \end{pmatrix}$ 16. $\{\begin{pmatrix} 1 & t\\ 0 & 1 \end{pmatrix}\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$
where $|\lambda| < 1$
17. $\{e^t \begin{pmatrix} 1 & t\\ 0 & 1 \end{pmatrix}\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$
18. $\{\begin{pmatrix} a & 0\\ 0 & b \end{pmatrix} \mid a > 0, b > 0\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$
19. $\{\begin{pmatrix} a & b\\ 0 & a \end{pmatrix} \mid a > 0\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$
20. $\{\begin{pmatrix} a^{A} & b\\ 0 & a \end{pmatrix} \mid a > 0\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$
20. $\{\begin{pmatrix} a & b\\ 0 & a^{\lambda+1} \end{pmatrix} \mid a > 0\}, R\begin{pmatrix} 1\\ 0 \end{pmatrix}$ where $\lambda \in R$
21. $\{\begin{pmatrix} e^t & 0\\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0\\ t \end{pmatrix} \mid t \in R\}$
23. $\{\langle \begin{pmatrix} 1 & t\\ 0 & t \end{pmatrix}, \begin{pmatrix} u\\ 0 \end{pmatrix} \rangle \mid t, u \in R\}$
24. $\{\langle \begin{pmatrix} 1 & t\\ 0 & t \end{pmatrix}, \begin{pmatrix} u\\ 0 \end{pmatrix} \rangle \mid t, u \in R\}$
25. $\{\langle \begin{pmatrix} e^t & 0\\ 0 & 1 \end{pmatrix}, \begin{pmatrix} u\\ t \end{pmatrix} \rangle \mid t, u \in R\}$
26. $\{\langle \begin{pmatrix} e^t & 0\\ 0 & 1 \end{pmatrix}, \begin{pmatrix} u\\ t \end{pmatrix} \rangle \mid t, u \in R\}$
27. $\{\langle \begin{pmatrix} 1 & t\\ 0 & 1 \end{pmatrix}, \begin{pmatrix} v\\ t \end{pmatrix} \rangle \mid t, u \in R\}$
28. $\{\langle \begin{pmatrix} e^t & u\\ 0 & 1 \end{pmatrix}, \begin{pmatrix} v\\ t \end{pmatrix} \rangle \mid t, u, v \in R\}$
29. $\{\langle \begin{pmatrix} t^2 & tu\\ 0 & t \end{pmatrix}, \begin{pmatrix} v\\ 0 \end{pmatrix} \rangle \mid t > 0, u, v \in R\}$
W. Comparison of a schedulence of $M(R)$ here noise of infinitesimal

IV. Generation of subalgebras of $M_2(\mathbf{R})$ by pairs of infinitesimal transformations.

THEOREM 6. Let X, $Y \in M_2(R)$. a. If X and Y have no common complex eigenvector and tr $X \neq 0$ or tr $Y \neq 0$, X and Y generate $M_2(R)$

b. If X and Y have no common complex eigenvector and tr X = tr Y= 0, X and Y generate $\mathfrak{A}(2, \mathbb{R})$

c. If X and Y have a common complex eigenvector and X, Y, [X, Y] are linearly independent, X and Y generate a subalgebra conjugate to $\{(\begin{smallmatrix} a & b \\ b & d \end{bmatrix}\}$

d. Otherwise X and Y generate a subalgebra of dimension ≤ 2

e. All subalgebras of $M_2(R)$ can be generated by appropriate X and Y.

PROOF. If g is an algebra listed in Theorem 1 other than $\mathfrak{A}(2, R)$ and $M_2(R)$, there is a complex vector v such that $Av = \lambda v$ for all $A \in g$. Consequently if X and Y have no common complex eigenvector, they generate a subalgebra conjugate to $\mathfrak{A}(2, R)$ or $M_2(R)$. But both of these subalgebras are self-conjugate. The rest of the theorem follows immediately.

REMARK. If g is a subalgebra of $M_2(R)$ and X and Y belong to g, the above theorem gives a satisfactory necessary and sufficient condition that X and Y generate g, since the generation problem is trivial when dim $g \leq 2$.

V. Generation of subalgebras of a(2) by pairs of infinitesimal transformations. Let g be a subalgebra of a(2), X and Y elements of g. We seek a simple necessary and sufficient condition that X and Y generate g. The problem is trivial when dim $g \leq 2$; if dim g = 3, X and Y generate g just in case X, Y, and [X, Y] are linearly independent. When $g \rightarrow g_0$ is an isomorphism, the problem was solved in the previous section. Referring to Theorem 4, we are left with algebras 6 through 12 when $V = R^2$ and 21.

THEOREM 7. Let $g = \{\langle A, \mathfrak{l} \rangle \mid A \in g_0, \mathfrak{l} \in R^2\}$ where $g_0 = R(\begin{smallmatrix} \Lambda & -1 \\ \lambda \end{smallmatrix}) 0 \leq \lambda, \{(\begin{smallmatrix} a & -b \\ b & -a \end{smallmatrix})\}, \mathfrak{sl}(2, R), or M_2(R).$ Let $X = \langle A, \mathfrak{l} \rangle$ and $Y = \langle B, m \rangle$ belong to g. Then X and Y generate g if and only if

(1) A and B generate g_0

(2) The equations $Av = \ell$ and Bv = m cannot be simultaneously solved for v; equivalently A is nonsingular and $m \neq BA^{-1}\ell$ or B is non-singular and $\ell \neq AB^{-1}m$ or A and B are singular and one of $\ell \notin$ range A, $m \notin$ range B.

Moreover, such a pair always exists.

PROOF. The first condition is obviously necessary. If v satisfies the second condition, conjugation of X and Y by $\langle I, v \rangle$ produces $\langle A, 0 \rangle$ and $\langle B, 0 \rangle$, so X and Y generate a subalgebra conjugate to $\{\langle A, 0 \rangle | A \in g_0\}$.

Conversely, suppose 1 and 2 hold; then X and Y generate a sub-

algebra \tilde{g} such that $\tilde{g}_0 = g_0$. If $\tilde{V} = R^2$, $\tilde{g} = g$; otherwise $\tilde{V} = \{0\}$ by Theorem 3. Then \tilde{g} is conjugate to $\{\langle A, 0 \rangle \mid A \in g_0\}$ by Theorem 4. Let $\langle C, w \rangle \in A(2)$ induce this conjugation; then X and Y become $\langle CAC^{-1}, Cl - CAC^{-1}w \rangle$ and $\langle CBC^{-1}, Cm - CBC^{-1}w \rangle$, so $Cl - CAC^{-1}w = 0$, $Cm - CBC^{-1}w = 0$; since C is nonsingular, $A(C^{-1}w) = l$, $B(C^{-1}w) = m$.

If A is nonsingular, the vector v obviously exists just in case $m = BA^{-1}v$. If A and B generate g_0 and both are singular, g_0 must be $\mathfrak{A}(2, R)$ or $M_2(R)$, so A and B must have rank 1 and Ker $A \cap$ Ker $B = \{0\}$. Suppose $\mathfrak{l} \in$ range A and $m \in$ range B. Let $Av = \mathfrak{l}$ and suppose that v_1 generates Ker A; then $A(v + \lambda v_1) = \mathfrak{l}$; since $v_1 \notin$ Ker B, Bv_1 generates the range of B and λ exists such that $B(v + \lambda v_1) = m$.

The existence of a generating pair is clear.

THEOREM 8. Let $g = \{\langle \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}, k \rangle | k \in \mathbb{R}^2 \}$. Let $X = \langle A, k \rangle$ and $Y = \langle B, m \rangle$ belong to g. Then X and Y generate g if and only if

(1) A and B are linearly independent,

(2) $Am - B\ell$ belongs to neither $\mathbf{R}({}_0^1)$ nor $\mathbf{R}({}_1^0)$.

Moreover, g can always be generated by such a pair.

PROOF. These conditions are necessary. For example, suppose $Am - Bl \in R({}^{0}_{1})$. Then the subspace of g generated by X, Y, and $[X, Y] = \langle 0, Am - Bl \rangle$ is a subalgebra, so X and Y generate an algebra of dimension at most 3.

Conversely suppose the above conditions hold. Then X and Y generate an algebra \tilde{g} with $\tilde{g}_0 = \{ \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} \}$; it is enough to prove that $\tilde{V} = R^2$. At any rate \tilde{V} is invariant under \tilde{g}_0 and so equal to $\{0\}$, $R(_0^1)$, $R(_0^1)$, or R^2 . But $[\langle A, \mathfrak{l} \rangle, \langle B, m \rangle] = \langle 0, Am - B\mathfrak{l} \rangle$ and $Am - B\mathfrak{l} \notin R(_0^1)$ or $R(_0^1)$.

The above conditions are satisfied by $X = \langle \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, 0 \rangle$ and $Y = \langle \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \rangle$.

THEOREM 9. Let $g = \{\langle A, \mathfrak{l} \rangle \mid A \in g_0, \mathfrak{l} \in \mathbb{R}^2\}$ where $g_0 = \{\begin{pmatrix} a & b \\ 0 & a \end{pmatrix}\}$ or $\{\begin{pmatrix} a & b \\ 0 & d \end{pmatrix}\}$. Let $X = \langle A, \mathfrak{l} \rangle$ and $Y = \langle B, m \rangle$ belong to g. Then X and Y generate g if and only if

- (1) A and B generate g_0 ,
- (2) $Am Bl \notin R(_0^1)$.

Moreover, g can always be generated by such a pair.

PROOF. These conditions are necessary. Indeed suppose $Am - B\& \in R\begin{pmatrix} 1\\ 0 \end{pmatrix}$. If $g_0 = \{ \begin{pmatrix} a & b \\ 0 & a \end{pmatrix} \}$, the subspace generated by X, Y, and $\langle 0, \begin{pmatrix} 1\\ 0 \end{pmatrix} \rangle$ is a subalgebra of dimension at most 3. If $g_0 = \{ \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \}$, the subspace generated by X, Y, $\langle \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, 0 \rangle$ and $\langle 0, \begin{pmatrix} 1\\ 0 \end{pmatrix} \rangle$ is a subalgebra of dimension at most 4.

Conversely suppose 1 and 2 hold; then X and Y generate an algebra \tilde{g} with $\tilde{g}_0 = g_0$. It is enough to prove that $\tilde{V} = R^2$; at any rate, \tilde{V} is invariant under g_0 and so $\{0\}, R({}^1_0)$, or R^2 . If $g_0 = \{{}^a_{(0)}{}^b_{a}\}, Am - B\& \in \tilde{V}$, so \tilde{V} is not $\{0\}$ or $R({}^1_0)$. If $g_0 = \{{}^a_{(0)}{}^b_{a}\}, \tilde{g}$ contains $\langle {}^1_{(0)}{}^0_{(0)}\}, \langle {}^s_{2}\rangle$ and $[X, Y] = \langle {}^0_{(0)}{}^0_{(0)}, \langle {}^t_{12}\rangle \rangle$ for some s_1, s_2, t, t_1 , and t_2 ; we are assuming $t_2 \neq 0$. Thus \tilde{g} contains the bracket of these two elements, $\langle 0, {}^t_{12}\rangle - {}^t_{(02)}\rangle$, and \tilde{V} is not $\{0\}$ or $R({}^1_0)$.

If $g_0 = \langle \begin{pmatrix} a & b \\ 0 & a \end{pmatrix} \rangle$, the conditions are satisfied by $X = \langle \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, 0 \rangle$ and $Y = \langle \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \rangle$. If $g_0 = \{\begin{pmatrix} a & b \\ 0 & a \end{pmatrix} \}$ the conditions are satisfied by $X = \langle \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}, 0 \rangle$ and $Y = \langle \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rangle$.

THEOREM 10. Let $g = \{\langle ({}^{\lambda a}_{0}, {}^{b}_{\lambda+1)a}, \mathfrak{l} \rangle \mid a, b \in R, \mathfrak{l} \in R^2\}$ for $\lambda \in R$. Let $X = \langle A, \mathfrak{l} \rangle$ and $Y = \langle B, m \rangle$ belong to g. Then X and Y generate g if and only if

(1) A and B are linearly independent,

(2) $(A - \beta)m - (B + \alpha)\ell \notin R(\frac{1}{0})$ where $[A, B] = \alpha A + \beta B$. Moreover g can be generated by such a pair unless $\lambda = -2$.

PROOF. If $(A - \beta)m - (B - \alpha) \& \in \mathbb{R}(\frac{1}{2})$, the subspace generated by X, Y, and $(0, (\frac{1}{2}))$ is a subalgebra of dimension at most 3.

Conversely suppose these conditions hold and let X and Y generate \tilde{g} ; then $\tilde{g}_0 = \{ \begin{pmatrix} \lambda^a \\ 0 \\ \lambda + 1 \end{pmatrix} \}$ and it is sufficient to show that $\tilde{V} = R^2$; since \tilde{V} is invariant under \tilde{g}_0 , $\tilde{V} = \{0\}$, $R(\frac{1}{6})$, or R^2 . But \tilde{g} contains $[X, Y] - \alpha X - \beta Y = \{0, (A - \beta)m - (B + \alpha)k\}$, so $\tilde{V} = R^2$.

If $\lambda \neq -2$, let $X = \langle \begin{pmatrix} \lambda & 0 \\ 0 & \lambda+1 \end{pmatrix}, 0 \rangle$, $Y = \langle \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rangle$ and notice that the above conditions hold. If $\lambda = -2$. notice that

$$\left[\begin{pmatrix} 2a & b \\ 0 & a \end{pmatrix}, \begin{pmatrix} 2c & d \\ 0 & c \end{pmatrix}\right] = \begin{pmatrix} 0 & ad - bc \\ 0 & 0 \end{pmatrix} = -c \begin{pmatrix} 2a & b \\ 0 & a \end{pmatrix} + a \begin{pmatrix} 2c & d \\ 0 & c \end{pmatrix}$$

and

$$\left\{ \begin{pmatrix} 2a & b \\ 0 & a \end{pmatrix} - a \right\} \begin{pmatrix} m_x \\ m_y \end{pmatrix} - \left\{ \begin{pmatrix} 2c & d \\ 0 & c \end{pmatrix} - c \right\} \begin{pmatrix} \ell_x \\ \ell_y \end{pmatrix}$$
$$= \begin{pmatrix} am_x + bm_y - c\ell_x - d\ell_y \\ 0 \end{pmatrix}.$$

THEOREM 11. Let $g = \{\langle \begin{pmatrix} a & b \\ 0 & d \end{pmatrix}, \begin{pmatrix} e \\ 0 \end{pmatrix} \rangle\}$. Let $X = \langle A, l \rangle$ and $Y = \langle B, m \rangle$ belong to g. Then X and Y generate g if and only if

- (1) A and B generate $\{\begin{pmatrix} a & b \\ 0 & d \end{pmatrix}\}$,
- (2) $Am B\ell \neq 0$.

Moreover, g can always be generated by such a pair.

PROOF. If Am - Bk = 0, the subspace generated by X, Y, and $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, 0) is a subalgebra of dimension at most 3.

Conversely suppose these conditions hold and let X and Y generate \tilde{g} ; then $\tilde{g}_0 = \{ \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} \}$ and it is enough if $\tilde{V} \neq \{0\}$. But \tilde{g} contains $\langle \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} s \\ 0 \end{pmatrix} \rangle$ and $[X, Y] = \langle \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} s \\ 0 \end{pmatrix} \rangle$ for some s, t, u; we are assuming $u \neq 0$. Thus \tilde{g} contains the bracket of these two elements, $\langle 0, \begin{pmatrix} u \\ 0 \end{pmatrix} \rangle$, and $\tilde{V} \neq \{0\}$.

The conditions are satisfied by $X = \langle \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, 0 \rangle$ and $Y = \langle \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$, $\begin{pmatrix} 1 \\ 0 \end{pmatrix} \rangle$.

THEOREM 12. Every connected subgroup of A(2) not conjugate to $\{\langle \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}, \& \rangle \mid a > 0, \& \in \mathbb{R}^2\}, \{\langle \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} c \\ 0 \end{pmatrix} \mid a > 0, b, c \in \mathbb{R}\}, or \{\langle \begin{pmatrix} a^2 & b \\ 0 & a \end{pmatrix}, \& \rangle \mid a > 0, b \in \mathbb{R}, \& \in \mathbb{R}^2\}$ can be generated by an appropriate pair of infinitesimal transformations.

PROOF. It suffices to consider the three dimensional g on the list in Theorem 4. Every non-abelian three dimensional Lie algebra can be generated by appropriate X and Y except the Lie algebra $\{\langle \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}, k \rangle | a \in R, k \in R^2\}$ [1]; we should show that only two algebras on our list are isomorphic to this algebra. It is easier to proceed directly; we already know that 1 through 12 can be generated if $V = \{0\}$. If $V = R^2$ pick $X = \langle 0, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \rangle$; let $Y = \langle \begin{pmatrix} 1 & 0 \\ 0 \end{pmatrix}, 0 \rangle$ in case 2 if $\lambda \neq 1$, $\langle \begin{pmatrix} A & -1 \\ 1 & \lambda \end{pmatrix}, 0 \rangle$ in case 3 if $\lambda \neq 1$, $\langle \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, 0 \rangle$ in case 4, and $\langle \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, 0 \rangle$ in case 5. In case 3 when $\lambda = 1$ let $X = \langle 0, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rangle$, $Y = \langle \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix}$ in case 18 let $X = \langle \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rangle$. In case 20 when $\lambda \neq -1$ let $X = \langle \begin{pmatrix} 0 & 0 \\ 0 & \lambda + 1 \end{pmatrix}, 0 \rangle$, $Y = \langle \begin{pmatrix} 0 & 0 \\ 0 & \lambda + 1 \end{pmatrix}, 0 \rangle$. In case 28 let $X = \langle \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rangle$, in case 29 let $X = \langle \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}, \langle 1 \rangle \rangle$.

REMARK. Notice that the only subgroup of A(2) conjugate to $G = \{\langle \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}, k \rangle \mid a > 0, k \in \mathbb{R}^2 \}$ is G itself.

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