# ANALYSIS OF TRUNCATION ERROR OF APPROXIMATIONS BASED ON THE PADÉ TABLE AND CONTINUED FRACTIONS 

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1. Introduction. In the study and application of continued fractions

$$
\begin{equation*}
f=K\left(a_{n} / b_{n}\right)=\frac{a_{1}}{b_{1}}+\frac{a_{2}}{b_{2}}+\cdots \tag{1}
\end{equation*}
$$

it is important to have realistic estimates of the truncation error $\left|f-f_{n}\right|$ when (1) is approximated by its $n$th approximant $f_{n}$. Truncation error bounds are of two main types: (a) A priori bounds are expressed directly in terms of the elements $a_{n}, b_{n}$ or parameters associated with these elements. (b) A posteriori bounds are generally of the form

$$
\begin{equation*}
\left|f-f_{n}\right| \leqq M_{n}\left|f_{n}-f_{n-1}\right| \tag{2}
\end{equation*}
$$

and are obtained only after calculating the approximants $f_{1}, f_{2}, \cdots, f_{n}$. (There are also asymptotic estimates of the truncation error as given by $[4,15]$; however, such estimates will not be dealt with here.) Bounds of a priori type can be found in $[5,6,8,9,10,12,14,17$ and $18]$ and of a posteriori type in $[1,2,3,6,7,9,11,13,16]$. Most of the known truncation error bounds for continued fractions have been obtained either by studying inclusion regions for the approximants (Section 2) or by showing that the approximants form simple sequences (Section 3). In some cases both of these approaches have been used (Section 2). This paper provides a brief summary of the two approaches and reviews some of the main results. Proofs are omitted; however, proofs, application, and numerical examples may be found in references cited. These results have a strong connection with Padé tables. As an illustration of this connection we note that in a normal Pade table the approximants of the corresponding continued fraction of the form

$$
\frac{a_{0}}{1}+\frac{a_{1} z}{1}+\frac{a_{z} z}{1}+\cdots\left(\text { complex } a_{n} \neq 0\right)
$$

[^0]fill the stairlike sequence of squares $[0,0],[1,0],[1,1],[2,1]$, [2, 2], $\cdots$ ([19], Theorem 96.1).

The following definitions and terminology are used. An (infinite) continued fraction is a triple of sequences $\left[\left\{a_{n}\right\}_{1}^{\infty},\left\{b_{n}\right\}_{1}^{\infty},\left\{f_{n}\right\}_{1}^{\infty}\right]$ where $a_{1}, a_{2}, \cdots$, and $b_{1}, b_{2}, \cdots$ are complex numbers, $a_{n} \neq 0$, and where $f_{n}$ is an element of the extended complex plane defined as follows: If $s_{n}$ denotes the linear fractional transformation (l.f.t.)

$$
\begin{equation*}
s_{n}(z)=a_{n} /\left(b_{n}+z\right), n=1,2, \cdots \tag{3a}
\end{equation*}
$$

and

$$
\begin{equation*}
S_{1}(z)=s_{1}(z) ; S_{n}(z)=S_{n-1}\left(s_{n}(z)\right), n=2,3, \cdots \tag{3b}
\end{equation*}
$$

then

$$
\begin{equation*}
f_{n}=S_{n}(0), n=1,2, \cdots . \tag{3c}
\end{equation*}
$$

The $a_{n}$ and $b_{n}$ are called elements of the continued fraction and $f_{n}$ is called the $n$th approximant. An infinite continued fraction is said to converge if its sequence of approximants converges; $f=\lim f_{n}$ is called its value. For convenience the infinite continued fraction [ $\left.\left\{a_{n}\right\},\left\{b_{n}\right\},\left\{f_{n}\right\}\right]$ may also be denoted by each of the three expressions in (1); in addition the expressions in (1) are used to denote the value of the continued fraction when it exists. The $n$th approximant may also be represented by $f_{n}=K_{k=1}^{n}\left(a_{k} / b_{k}\right)$. A finite continued fraction is a triple of finite sequences $\left[\left\{a_{n}\right\}_{1}^{N},\left\{b_{n}\right\}_{1}^{N},\left\{f_{n}\right\}_{1}^{N}\right]$, where the approximants $f_{n}$ are defined as in (3). Its value is given by $f_{N}=$ $K_{k=1}^{N}\left(a_{n} / b_{n}\right)$, which may also be used to denote the continued fraction itself.
2. Inclusion Regions. Consider the problem: Given the first $n$ pairs of elements $\left(a_{1}{ }^{*}, b_{1}{ }^{*}\right), \cdots,\left(a_{n}{ }^{*}, b_{n}{ }^{*}\right)$ of a continued fraction $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ that belongs to a certain class $K$ of continued fractions, what can be said about the truncation error when $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ is approximated by its $n$th approximant? For this problem it is natural to study inclusion regions defined as follows:

Definition 1. For each $n=1,2,3, \cdots$ let $D_{n}$ be a subset of the complex, $2 n$ dimensional, Cartesian space $C^{2 n}$. Let $K$ denote the class consisting of:
(A) All finite continued fractions $K_{n=1}^{N}\left(a_{n} / b_{n}\right)$, such that

$$
\begin{equation*}
\left(a_{1}, b_{1}, \cdots, a_{n}, b_{n}\right) \in D_{n}, n=1, \cdots, N, N=1,2, \cdots, \tag{4}
\end{equation*}
$$ and

(B) all infinite continued fractions $K\left(a_{n} / b_{n}\right)$, such that
(i) $\left(a_{1}, b_{1}, \cdots, a_{n}, b_{n}\right) \in D_{n}, n=1,2, \cdots$.

Let $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ be a given continued fraction contained in the class $K$. For each $n=1,2,3, \cdots$ let $\Phi_{n}$ be the set consisting of the values of all finite continued fractions in $K$ of the form

$$
\begin{equation*}
K_{k=1}^{n+m}\left(a_{k} / b_{k}\right), m \geqq 0, \text { such that }\left(a_{k}, b_{k}\right)=\left(a_{k}^{*}, \mathrm{~b}_{\mathrm{k}}^{*}\right), k=1, \cdots, n . \tag{6}
\end{equation*}
$$

Then every closed set of complex numbers $\Omega_{n}$ containing $\Phi_{n}$ is called an $n$th inclusion region for $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ relative to the class $K$. The closure of $\Phi_{n}$ is called the best $n$th inclusion region for $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ relative to the class $K$.

Remark. As can be seen the closure of $\Phi_{n}$ contains the $n$th approximant of $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ as well as all possible values of continued fractions in $K$ having the first $n$ pairs of elements $\left(a_{1}{ }^{*}, b_{1}{ }^{*}\right), \cdots,\left(a_{n}{ }^{*}, b_{n}{ }^{*}\right)$. Moreover, every closed set containing the above points must contain $\Phi_{n}$. Thus we obtain,

Theorem 1. Let $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ be a convergent continued fraction belonging to a class $K$ as described in Definition l. Let $f_{n}$ be the $n$th approximant of $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ and $f=\lim f_{n}$. If $\left\{\Omega_{n}\right\}$ is a sequence of inclusion regions for $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ relative to class $K$, then

$$
\begin{equation*}
\left|f-f_{n}\right| \leqq \text { diameter } \Omega_{n} \tag{7}
\end{equation*}
$$

In studies made so far $\left\{\Omega_{n}\right\}$ has been a nested sequence of compact subsets of $C$ such that diameter $\Omega_{n} \rightarrow 0$. Clearly the error bounds in (7) can be best (on the basis of what is given) only if the $\Omega_{n}$ are best inclusion regions and $f_{n}$ lies on the boundary of $\Omega_{n}$. In no case can the error bound be less than half the diameter of $\Omega_{n}$.

The first error bounds for continued fractions (with complex elements) based on inclusion regions were obtained by Thron [18] in 1958. For the class of continued fractions $K\left(a_{n} / 1\right)$ with elements contained in the bounded subset of a parabolic region

$$
\left|a_{n}\right|-\operatorname{Re}\left(a_{n} e^{-2 i \alpha}\right) \leqq \frac{1}{2} \cos 2 \alpha,-\pi / 2<\alpha<\pi / 2
$$

Thron obtained a nested sequence of circular (disk) inclusion regions. His sharp estimates of the diameters of these disks provided a priori error bounds. More recently Thron's result has been extended by Snell and the author [12] to include variable parabolic regions and increased speed of convergence of the error bounds. An example is given by

Theorem 2 [12]. Let $\left\{P_{n}\right\}$ be a sequence of complex numbers $P_{n}=p_{n} e^{i \psi_{n}}$ such that

$$
\begin{equation*}
\left|P_{n}-1 / 2\right| \leqq 1 / 2-\epsilon, 0<\epsilon<1 / 2, n=0,1, \cdots . \tag{8}
\end{equation*}
$$

Let $\left\{E_{n}\right\}$ be the sequence of parabolic regions defined by
$(9) E_{n}=\left\{\zeta:|\zeta|-\operatorname{Re}\left[\zeta \exp \left(-i\left(\psi_{n}+\psi_{n-1}\right)\right)\right] \leqq 2 k p_{n-1}\left(\cos \psi_{n}-p_{n}\right)\right\}$,
where $0 \leqq k<1$. If $K\left(a_{n} / 1\right)$ is a continued fraction with elements satisfying

$$
\begin{equation*}
a_{n} \in E_{n}, 0<\left|a_{n}\right| \leqq M, n=1,2, \cdots \tag{10}
\end{equation*}
$$

for some constant $M>0$, then $K\left(a_{n} / 1\right)$ converges to $a$ value $f$ and

$$
\begin{equation*}
\left|f-f_{n}\right| \leqq \frac{\left|a_{1}\right|\left(\cos \psi_{1}-p_{1}\right)}{\left[1+\epsilon^{2}(1-k) / M\right]^{n-1}}, n=2,3, \cdots \tag{11}
\end{equation*}
$$

Remarks. (1) The right side of (11) estimates the diameter of the $n$th circular (disk) inclusion region. A decrease in the parameter $k$ reduces the element regions $E_{n}$ but increases the rate of convergence of the error bounds in (11).
(2) Thron's approach illustrated above has also been employed by Lange [14] for continued fractions $K\left(a_{n} / 1\right)$ with twin-elementregions and by Hillam [10], Sweezy and Thron [17] and Field and Jones [5] for continued fractions $K\left(1 / b_{n}\right)$ with the $b_{n}$ contained in regions which are complements of open circular disks. In these cases the $n$th approximant of the continued fraction is in the interior of the $n$th inclusion region and hence resulting error bounds are best possible. Examples of best inclusion regions and best error bounds for continued fractions will be given in the next section on simple sequences.

## 3. Simple Sequences.

Definition 2. A sequence of complex numbers $\left\{w_{n}\right\}$ is called a simple sequence if there exists a positive number $C$ (called a simple sequence constant) such that

$$
\begin{equation*}
\left|w_{n+m}-w_{n}\right| \leqq C\left|w_{n}-w_{n-1}\right|, m \geqq 0, n \geqq 2 \tag{12}
\end{equation*}
$$

Simple sequences generalize real number sequences with the nesting property

$$
\begin{equation*}
w_{2 n-2} \leqq w_{2 n} \leqq w_{2 n+1} \leqq w_{2 n-1}, n \geqq 2 \tag{13}
\end{equation*}
$$

A simple sequence may not converge (e.g. $w_{n}=(-1)^{n}$ ) and, moreover,
a convergent sequence may not be simple (e.g., $w_{n}=1 / n$, which does not converge fast enough to be simple). However, knowledge of a simple sequence constant provides an immediate a posteriori truncation error bound as shown by

Theorem 3. If $\left\{w_{n}\right\}$ is a simple sequence converging to $w$, with simple sequence constant $C$, then

$$
\begin{equation*}
\left|w-w_{n}\right| \leqq C\left|w_{n}-w_{n-1}\right|, n \geqq 2 . \tag{14}
\end{equation*}
$$

Most of the known a posteriori error bounds for continued fractions have been obtained in this way. Simple sequence constants for these cases are given in Table 1. The left column of Table 1 contains references (in brackets) and author's initials used hereafter to identify a particular result.

Perhaps the first known examples of continued fractions with simple sequences of approximants are those of the form $K\left(a_{n} / 1\right)$ with $a_{n}>0$ and $K\left(1 / b_{n}\right)$ with $b_{n}>0$; in such cases the approximants are positive real numbers satisfying (13) with simple sequence constant $C=1$. These results are obtainable as special cases of HP in Table 1, with $z$ real and positive. The first examples with complex elements $a_{n}, b_{n}$ were obtained in Blanch [2] in 1964, using comparison relations for continued fractions ( $B_{1}$ and $B_{2}$ in Table 1). An improvement of these results by Merkes [16] in 1966 was made from an analysis based on chain sequences ( $M$ in Table 1). In the same year Henrici and Pfluger [9] developed error bounds ( $H P$ in Table 1) for $S$-fractions (or series of Stieltjes) by considering inclusion regions $\Omega_{n}$ as follows: For an arbitrary but fixed S-fraction let $\Gamma_{n}$ denote the circle passing through the approximants $f_{n-2}, f_{n-1}, f_{n}$ and let $\Gamma_{n}{ }^{*}$ denote the union of $\Gamma_{n}$ and its interior. (If $z$ is not real, the points $f_{n-1}, f_{n}, f_{n+1}$ are not collinear and so $\Gamma_{n}$ is a non-degenerate circle. In the limiting case that $z$ is real and positive, the lens-shaped inclusion region $\Omega_{n}$ becomes a real line segment and the situation reduces to (13)). Then $\Omega_{n}$ is the lens-shaped region $\Gamma^{*}{ }_{n-1} \cap \Gamma_{n}{ }^{*}$ (see Figure 1). For each $n \geqq 3$, they proved the following results relative to the class of all $S$-fractions (finite or infinite) having the given set of first $n$ elements $a_{1}{ }^{*}, \cdots, a_{n}{ }^{*}$ : (1) $\Omega_{n}$ is the best $n$th inclusion region in the sense of Definition 1. (2) $\Omega_{n+1} \subset \Omega_{n}$. (3) $\Omega_{n}$ is convex. (4) $\Gamma_{n}$ and $\Gamma_{n-1}$ intersect in an angle (interior to $\Omega_{n}$ ) of magnitude $|\arg z|$, independent of $n$. From these facts it was shown that $\left\{f_{n}\right\}$ is a simple sequence with constant $C(z)$ given in Table $1(\mathrm{HP})$ and diameter $\Omega_{n+1}=C(z)\left|f_{n}-f_{n-1}\right|$. Thus both the ideas of simple sequences and inclusion regions were employed.

Using a modification of the method of HP, Jefferson [11] obtained best inclusion regions for the class of $T$-fractions in Table 1 (J) and showed that the approximants form simple sequences. A generalization of HP and J was obtained by Thron and the author [13] (see Table 1, JT); it applies also to continued fractions of Gauss, to large classes of $J$-fractions, to continued fractions $K\left(1 / b_{n}\right)$ where $\left|\arg b_{n}\right| \leqq(\pi / 2)-\epsilon, \epsilon>0$ or $b_{n}=0$, and to other examples. They developed inclusion regions $\Omega_{n}$ as follows: Let $\theta$ be a given real number such that $0<|\theta|<\pi$ and let $\left\{\gamma_{n}\right\}$ be a given sequence of real numbers. Let $K$ denote the class of all (finite or infinite) continued fractions $K\left(a_{n} / b_{n}\right)$ satisfying the conditions in Table 1 (JT). Let $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ be an arbitrary but fixed infinite continued fraction in $K$, with $n$th approximant $f_{n}$. For each $n \geqq 1$ let $\Gamma_{n}$ denote the circle defined by

$$
\Gamma_{n}: w=S_{n}\left(t e^{i \gamma n}\right),-\infty \leqq t \leqq \infty
$$

where $\left\{S_{n}\right\}$ is the sequence of l.f.t.'s (3b) associated with $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$. It is shown that there exists a sequence $\left\{\zeta_{n}\right\}$ such that each $\Gamma_{n}$ passes through $f_{n-1}=S_{n}(\infty), \zeta_{n}, f_{n}=S_{n}(0)$ and $\zeta_{n-1}$ in the given order. Then $\Omega_{n}$ is defined as the closed, lens-shaped region bounded on one side by the arc of $\Gamma_{n}$ with end points $f_{n-1}, \zeta_{n-1}$ passing through $\zeta_{n}$ and $w_{n}$ and on the other side by the arc of $\Gamma_{n-1}$ with the same end points $f_{n-1}, \zeta_{n-1}$ and not passing through $f_{n-2}$ or $\zeta_{n-2}$ unless $\zeta_{n-1}=$ $f_{n-2}$ or $f_{n-1}=\zeta_{n-2}$ (see Figure 2). For each $n \geqq 2$ they proved the following: (1) $\Omega_{n}$ is an $n$th inclusion region for $K\left(a_{n}{ }^{*} / b_{n}{ }^{*}\right)$ relative to the class $K$. (2) $\Omega_{n+1} \subset \Omega_{n}$. (3) $\Omega_{n}$ is convex. (4) $\Gamma_{n}$ and $\Gamma_{n-1}$ intersect in an angle (interior to $\Omega_{n}$ ) of magnitude $|\boldsymbol{\theta}|$, independent of $n$. From this it was shown that $\left\{f_{n}\right\}$ is a simple sequence with constant $C(\theta)$ given in Table $1(\mathrm{JT})$ and diameter $\Omega_{n}=C(\boldsymbol{\theta})\left|\zeta_{n-1}-f_{n-1}\right| \leqq$ $C(\theta)\left|f_{n}-f_{n-1}\right|$. It was further shown that the conditions imposed on the $a_{n}, b_{n}$ in Table 1 ( JT ) are invariant in form under equivalence transformations of continued fractions. The inclusion regions $\Omega_{n}$ could not be shown to be best in the sense of Definition 1, without assuming more about the structure of the class $K$.

We conclude with some remarks on subclasses of S-fractions (or series of Stieltjes) which represent functions $f(z)$ holomorphic at the origin. For such cases smaller inclusion regions and sharper error estimates than those of HP have been obtained. In 1968 Common [3] obtained such bounds for real values of $z$ and Baker [1] extended this to complex $z$ by considering best inclusion regions. However, Baker's analysis did not provide a simple method to calculate error bounds, since it did not show that the lens-shaped inclusion regions
$\Omega_{n}$ were convex (a property that greatly simplifies the calculation of diameter $\Omega_{n}$ ). This was done in an independent study at about the same time by Gragg [6] for the case with $f(z)$ holomorphic for $|z|<1$. In a second paper Gragg [7] extended his analysis to include functions holomorphic in the complex plane cut along an arbitrary finite interval of the real axis.

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Table 1. Simple Sequences $\left\{f_{n}\right\}$ from Continued Fractions

|  | $f_{n}=n$th Approximant of: | $C=$ Simple Sequence Constant |
| :---: | :---: | :---: |
| $\begin{gathered} B_{1} \\ {[2]} \end{gathered}$ | $\left.\left\|\frac{a_{1}}{1}+\frac{a_{2}}{1}+\cdots, \quad\right\| a_{n} \right\rvert\, \leqq \frac{1}{4}-\epsilon, 0<\epsilon<1 / 4$ | $C=(1 / 2 \epsilon)-1$ |
| $\begin{gathered} B_{2} \\ {[2]} \end{gathered}$ | $\frac{1}{b_{1}}+\frac{1}{b_{2}}+\cdots, \quad\left\|b_{n}\right\| \geqq 2+\epsilon, \epsilon>0$ | $C=d /(1-d), d=1+\frac{\epsilon}{2}-\left[\left(1+\frac{\epsilon}{2}\right)^{2}-1\right]^{1 / 2}$ |
| $\binom{M}{[16]}$ | $\left.\left\|\frac{a_{1}}{b_{1}}+\frac{a_{2}}{b_{2}}+\cdots, \quad\right\| \frac{a_{n}}{b_{n} b_{n-1}} \right\rvert\, \leqq r(1-r), 0<r<1 / 2$ | $C=r /(1-2 r)$ |
| $\begin{array}{\|c} \mathrm{HP} \\ {[9]} \\ \hline \end{array}$ | $\left\|\begin{array}{l} \frac{a_{1}}{z}+\frac{a_{2}}{1}+\frac{a_{3}}{(\text { S-fraction })} \end{array}+\frac{a_{4}}{1}+\cdots, \quad a_{n}>0,\|\arg z\|<\pi\right.$ | $C(z)= \begin{cases}1, & \arg z \mid \leqq \pi / 2 \\ \tan [(1 / 2) \arg z] \pi / 2<\|\arg z\|<\pi\end{cases}$ |
| $\begin{gathered} J \\ {[11]} \end{gathered}$ | $\begin{aligned} & \begin{array}{l} 1+d_{0} z+\frac{z}{(T \text {-fraction })} \end{array}+\frac{z}{1+d_{1} z}+d_{2} z \end{aligned}+\cdots, \begin{aligned} & d_{n}>0, \\ & \arg z \mid<\pi \end{aligned}$ | $C(z)= \begin{cases}1, & \|\arg z\| \leqq \pi / 2 \\ \sec [(1 / 2) \arg z], \pi / 2<\|\arg z\|<\pi\end{cases}$ |
| $\left\|\begin{array}{c} \mathrm{JT} \\ {[13]} \end{array}\right\|$ | $\begin{array}{ll} \frac{a_{1}}{b_{1}}+\frac{a_{2}}{b_{2}}+\cdots, & \gamma_{0}, \theta \text { real, } 0<\|\theta\|<\pi \\ \gamma_{n}=\arg a_{n}-\gamma_{n-1}-\theta(\bmod 2 \pi) \\ b_{n} e^{-i \gamma_{n}} \in & D[0, \theta], \quad 0<\theta<\pi \\ \text { where } & D[\theta, 0],-\pi<\theta<0 \\ D[\alpha, \beta] \equiv\{z: z=0 \text { or } \alpha \leqq \arg z \leqq \beta\} . \end{array}$ | $C(\theta)= \begin{cases}1, & 0<\|\theta\|<\pi / 2 \\ \sec (\|\theta\|-\pi / 2), \pi / 2<\|\theta\|<\pi .\end{cases}$ |



Figure 1. Schematic diagram of best inclusion regions $\Omega_{n}$ for S-fractions.


Figure 2. Schematic diagram for lens-shaped inclusion regions for class of continued fractions in Table 1 (JT).


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