

# Orientation reversing involution

By

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## § 1. Introduction

In this note we discuss the following problem from the bordism point of view. "Which manifold admits an orientation reversing involution?"

Let  $\Omega_*$  be the oriented cobordism group. Then we shall have

**Theorem.** *An element  $x$  of  $\Omega_*$  has a representative which admits an orientation reversing involution if and only if  $x$  is a torsion element of  $\Omega_*$ .*

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## § 2. Proof of the theorem

If an oriented closed manifold  $M^n$  admits an orientation reversing diffeomorphism, then  $2[M^n] = 0$  in  $\Omega_n$ , that is  $[M^n]$  is a torsion element of  $\Omega_n$ . Therefore we have only to prove that each torsion element of  $\Omega_n$  has a representative which admits an orientation reversing involution.

Let us first recall from Wall [4] that the algebra  $W_*$  of un-oriented cobordism classes represented by a manifold with the first Stiefel-Whitney class  $w_1$  reduced integral is a polynomial algebra over  $Z_2$  on classes  $X_{2k-1}$ ,  $X_{2k}$ ,  $X_{2^j}$  with  $k$  not a power of 2. There is a homomorphism  $\partial: W_{n+1} \rightarrow \Omega_n$  obtained by sending the class of  $M$  into the class of the submanifold  $N$  of  $M$  dual to  $w_1$ , and Wall has shown that image  $\partial$  is precisely the set of torsion elements of  $\Omega_*$ .

Using Wall's representative manifolds, one has that the classes  $X_{2k-1}$  and  $X_{2^j}^2$  contain orientable manifolds. It follows that  $\partial X_{2^j}^2 = 0$  and  $\partial X_{2k-1} = 0$ . Since  $\partial$  is a derivation, for any monomial

$$Y = \prod_{\alpha} X_{2^j}^{2^{\alpha}} \cdot \prod_{\beta} X_{2k_{\beta-1}} \cdot \prod_{\gamma} X_{2k_{\gamma}},$$

one has that

$$\partial X = \prod_{\alpha} X_{2^j}^{2^{\alpha}} \cdot \prod_{\beta} X_{2k_{\beta-1}} \cdot \partial \left\{ \prod_{\gamma} X_{2k_{\gamma}} \right\}.$$

Thus, it suffices to show that each class  $\partial \{X_{2k_1} \cdots X_{2k_r}\}$  contains a representative manifold on which  $Z_2$  acts in the desired fashion.

First consider the case  $r=1$ . Then  $\partial X_{2k} = X_{2k-1}$  is representable by a Dold manifold  $P(2m+1, 2n)$  (see [2]). The Dold manifold  $P(2m+1, 2n)$  is obtained from  $S^{2m+1} \times \mathbf{CP}(2n)$  by identifying the points

$$(z_0, \dots, z_m, \eta_0, \dots, \eta_{2n}) \quad \text{and} \quad (-z_0, \dots, -z_m, \bar{\eta}_0, \dots, \bar{\eta}_{2n})$$

where  $z_i, \eta_j \in \mathbf{C}$ . Define a map

$$T: S^{2m+1} \times \mathbf{CP}(2n) \rightarrow S^{2m+1} \times \mathbf{CP}(2n)$$

by

$$T(z_0, \dots, z_m, \eta_0, \dots, \eta_{2n}) = (\bar{z}_0, z_1, \dots, z_m, \eta_0, \dots, \eta_{2n}).$$

This preserves identifications to give an involution

$$T: P(2m+1, 2n) \rightarrow P(2m+1, 2n).$$

Consider a neighborhood of a fixed point  $(0, z_1, \dots, z_m, \eta_0, \dots, \eta_{2n})$  of  $T$ . Then  $T$  reverses the orientation locally. Since  $T$  is a diffeomorphism, we can easily deduce that  $T$  reverses the orientation globally.

Next we consider the case  $r > 1$ . Recall that a representative for  $X_{2k}$  is obtained as follows:  $P(2m+1, n)$  has an involution

$$\tau: P(2m+1, n) \rightarrow P(2m+1, n)$$

induced by the involution

$$(z_0, \dots, z_m, \eta_0, \dots, \eta_n) \rightarrow (z_0, \dots, z_{m-1}, \bar{z}_m, \eta_0, \dots, \eta_n).$$

Then let  $Q(2m+1, n)$  be formed from  $S^1 \times P(2m+1, n)$  by identifying  $(t, u)$  and  $(-t, \tau(u))$ . As noted by Wall [4],  $Q(2m+1, n)$  represents  $X_{2k}$  (for properly chosen  $m$  and  $n$ ).

Let  $N_i = Q(2m_i + 1, n_i)$  represent  $X_{2k_i}$ ,  $i = 1, \dots, r$ . Define an involution  $T_1$  on  $N_1$  by setting  $T_1(t, z_0, \dots, z_{m_1}, \eta_1, \dots, \eta_{n_1}) = (t, \bar{z}_0, z_1, \dots, z_{m_1}, \eta_1, \dots, \eta_{n_1})$ . It is easy to see that  $T_1$  is well-defined. Remark that even if  $m_1 = 0$ , the map  $T_1$  is well-defined. Let  $\pi_i: N_i \rightarrow S^1$  be the projection induced by  $(t, u) \rightarrow t^2$ . Then  $\pi_i$  is a fibration and realizes  $w_1(N_i)$ . Now let  $P: N_1 \times \dots \times N_r \rightarrow S^1$  be the map defined by  $P(v_1, \dots, v_r) = \pi_1(v_1) \cdots \pi_r(v_r)$ . This is the composition of the bundle maps

$$\pi_1 \times \dots \times \pi_r: N_1 \times \dots \times N_r \rightarrow S^1 \times \dots \times S^1$$

and

$$\mu: S^1 \times \dots \times S^1 \rightarrow S^1$$

where  $\mu$  is the multiplication. Thus  $P$  is transverse regular on  $1 \in S^1$ . In addition,  $P$  realizes  $w_1$ , so

$$V = \{(v_1, \dots, v_r) \in N_1 \times \dots \times N_r \mid \pi_1(v_1) \cdots \pi_r(v_r) = 1\}$$

represents  $\partial(X_{2k_1} \cdots X_{2k_r})$ . This construction of  $V$  is due to Anderson [1] and Stong [3]. Obviously  $T_1 \times id \times \dots \times id$  induces an involution  $T$  on  $V$ .

Consider a neighborhood of a fixed point  $(t(1), 0, \dots, 0, 1, \eta_1(1), \dots, \eta_{n_1}(1)) \times \dots \times (t(r), z_1(r), \dots, z_{m_r}(r), \eta_1(r), \eta_1(r), \dots, \eta_{n_r}(r))$  of  $T$  where  $t^2(1) \cdots t^2(r) = 1$ . Then  $T$  reverses the orientation locally.

Since  $T$  is a diffeomorphism, we can easily deduce that  $T$  reverses the orientation globally. Thus  $\partial(X_{2k_1} \cdots X_{2k_r})$  is represented by  $V$  on which  $Z_2$  acts in the desired manner. This completes the proof of the theorem.

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References

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