# ON HOMOTOPY 3-SPHERES ${ }^{1}$ 

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A homotopy 3 -sphere $M^{3}$ is a compact, simply connected 3 -manifold without boundary. After the work of Moise [6] and Bing [1] $M^{3}$ possesses a triangulation. The Poincaré conjecture [9] states that every homotopy 3 -sphere $M^{3}$ is a 3 -sphere. In this paper we prove three theorems, related to the Poincaré conjecture, about maps of a 3 -sphere $S^{3}$ onto $M^{3}$ and about 1- and 2 -spheres in $M^{3}$.

1. Theorems 1 and 2, concerning maps $S^{3} \rightarrow M^{3}$ and closed curves in $M^{3}$. From the work of Hurewicz [5], Part III, it follows that there exists a continuous map $\varphi: S^{3} \rightarrow M^{3}$ of degree 1 (where $S^{3}$ means a 3 -sphere). We shall prove that there exists an especially simple map of this kind. ${ }^{2}$

Theorem 1. If $M^{3}$ is a homotopy 3 -sphere then there exists a simplicial map $\gamma: S^{3} \rightarrow M^{3}$ of degree 1 such that the singularities of $\gamma$ (i.e. the closure of the set of those points $p \in M^{3}$ for which $\gamma^{-1}(p)$ consists of more than one point) lie in a ( polyhedral, compact) handlebody in $M^{3}$.

One might consider this result as a step towards a proof of the Poincaré conjecture. Indeed, if it were possible to restrict the singularities of $\gamma$ to a 3 -cell in $M^{3}$ instead of a handlebody the existence of a homeomorphism $S^{3} \rightarrow M^{3}$ would follow.

From Theorem 1 we may derive another aspect of the Poincaré problemby considering simple closed curves in $M^{3}$.

From the definition of simple connectedness it follows that every closed curve $C^{1} \subset M^{3}$ bounds a singular disk $D^{2} \subset M^{3}$. If $C^{1}$ is a tame, simple closed curve then one can find a $D^{2}$ which is also tame and possesses only "normal" singularities (see [7], [8]), i.e. double curves in which two sheets of $D^{2}$ pierce each other, triple points in which three sheets pierce each other, and branch points from each of which one or more double arcs originate; the triple points, the branch points, and the interiors of the double curves are disjoint from the boundary $D^{2}$ of $D^{2}$, but the double curves may have end points in $\cdot D^{2}$.

As Bing [2] has proved, $M^{3}$ is a 3 -sphere if (and only if) every tame, simple closed curve $C^{1} \subset M^{3}$ lies in a (compact) 3-cell in $M^{3}$. The statement that $C^{1}$ lies in a 3 -cell $D^{3} \subset M^{3}$ is equivalent to the statement that $C^{1}$ bounds a "knot projection cone" $D^{2}$ in $M^{3}$, i.e. a (tame) singular disk whose singularities are one branch point $P$ and double arcs originating from $P$, being pairwise

[^0]disjoint otherwise, and terminating in $\cdot D^{2}$. (A small neighborhood of a knot projection cone in $M^{3}$ is always a 3 -cell.) Hence one would prove the Poincaré conjecture if one could prove that every tame, simple closed curve $C^{1} \subset M^{3}$ bounds a knot projection cone in $M^{3}$. Theorem 2 of this paper (which may be considered as a corollary of Theorem 1) is a first step in this direction: it states that $C^{1}$ always bounds a knot projection cone $D^{2}$ with additional singularities that do not touch $\cdot D^{2}=C^{1}$.

Theorem 2. If $C^{1}$ is a tame, simple closed curve in a homotopy 3 -sphere $M^{3}$ then there is a (tame) singular disk $D^{2} \subset M^{3}$ with $\cdot D^{2}=C^{1}$ such that $D^{2}$ has the following singularities:
(a) One branch point $P$ of multiplicity $g$ ( $g$ may be zero) and $g$ double arcs $Q_{1}^{1}, \cdots, Q_{g}^{1}$ (in each of which two sheets of $D^{2}$ pierce each other), starting from $P$ and ending at $D^{2}$ with ${ }^{0} Q_{i}^{1} \subset{ }^{0} D^{2}$ such $^{3}$ that the $Q_{i}^{1}-P$ 's are pairwise disjoint.
(b) Closed double curves $R_{1}^{1}, \cdots, R_{h}^{1}$ ( $h$ may be zero) which may pierce themselves and the $Q_{i}^{1}$ 's in triple points of $D^{2}$, but which are disjoint from $\cdot D^{2}$.

In the special case $h=0, D^{2}$ is a knot projection cone; in the case $g=0$, $D^{2}$ is a so called Dehn disk (see [8]). In the latter case it follows from Dehn's lemma (stated by Dehn [3] and proved by Papakyriakopoulos [8]) that there exists a (tame) disk $D^{* 2}$ with $\cdot D^{* 2}=C^{1}$ and $h^{*}=0$ (and also $g^{*}=0$ ). Now the question arises whether it follows in the general case $(g \neq 0)$ that there exists a (tame, singular) disk $D^{* 2}$ with $D^{* 2}=C^{1}$ and $h^{*}=0$ (and $g^{*}$ arbitrary, not necessarily equal to $g$ ). An affirmative answer to this question would imply the Poincaré conjecture.

If one applies the methods for proving Dehn's lemma, as developed by Papakyriakopoulos [8] and later simplified by Shapiro and Whitehead [12], to this problem then one has to consider a small neighborhood $D^{3} \subset M^{3}$ of $D^{2}$, a covering of $D^{3}$, etc. Then all conclusions of the proof of Dehn's lemma in [12] apply to our problem as well, except in case (1) wherein the boundary $D^{3}$ of $D^{3}$ (or that of one of the neighborhoods in the coverings) consists of 2 -spheres only : for case (1) it follows easily in dealing with Dehn's lemma that $C^{1}$ bounds a nonsingular disk; however it seems to be difficult to prove for case (1) in dealing with our problem, $g \neq 0$, that $C^{1}$ bounds a knot projection cone. Nevertheless I hope that someone will be able to fill this gap in the proof of the Poincaré conjecture.
2. Theorem 3, concerning 2 -spheres in $M^{3}$. We obtain another aspect of the Poincaré problem if we consider 2 -spheres in $M^{3}$ instead of closed curves. If we remove the interior of a 3 -cell $C^{3}$ from $M^{3}$ we get a so called homotopy 3 -cell $M_{*}^{3}$. It follows from the Hurewicz theorem [5], Part II, that every 2 -sphere in $M_{*}^{3}$ may be homotopically deformed into one point.

Let us consider a 2 -sphere $F_{0}^{2} \subset M_{*}^{3}$, "topologically parallel" to the bound-

[^1]ary of $M_{*}^{3}$, i.e. such that $F_{0}^{2}+M_{*}^{3}$ bounds a 3 -annulus $F_{0}^{3} \subset M_{*}^{3}$. If one could prove that $F_{0}^{2}$ can be deformed ${ }^{4}$ into a 3 -cell $H^{3} \subset M_{*}^{3}$ not only by a homotopy but also by an isotopy whose image is tame at each level then the Poincaré conjecture would follow (since it would follow that $M_{*}^{3}$ is a 3 -cell). It follows from the work of Smale [13] on regular homotopy that $F_{0}^{2}$ can be deformed onto the boundary of a 3 -cell in $H^{3}$ in such a way that no branch points occur at any stage of the deformation. In order to go one step further in this direction we shall show that $F_{0}^{2}$ can be deformed into $H^{3}$ by especially simple homotopic deformations that take place in a special order.

First we have to define some special homotopic deformations. Let

$$
\alpha:{F^{\prime}}^{2} \rightarrow M_{*}^{3},
$$

with the image $\alpha\left(F^{\prime 2}\right) \subset{ }^{0} M_{*}^{3}$ denoted by $F^{2}$, be a continuous map, defining a (tame) 2 -sphere with canonical singularities (i.e. normal double curves and triple points, but without branch points, see [8]). Let $A^{\prime 2}$ be a disk in ${F^{\prime 2}}^{2}$ whose image $\alpha\left(A^{\prime 2}\right)$ is also a (nonsingular) disk $A^{2}$. Let

$$
A^{* 2} \subset{ }^{0} M_{*}^{3}
$$

be another tame disk with $A^{* 2} \cap A^{2}=A^{2}=A^{* 2}$ such that $A^{2}+A^{* 2}$ bounds a 3 -cell $K^{3} \subset M_{*}^{3}$. Now we consider a deformation $\delta$ that changes $\alpha$ into $\alpha^{*}$ such that

$$
\alpha^{*}\left|\left(F^{\prime 2}-{ }^{0} A^{\prime 2}\right)=\alpha\right|\left(F^{\prime 2}-{ }^{0} A^{\prime 2}\right)
$$

and $\alpha^{*} \mid A^{\prime 2}$ is a homeomorphism onto $A^{* 2}$. We call such a deformation nonessential if there exists an epi-homeomorphism

$$
\zeta: M_{*}^{3} \rightarrow M_{*}^{3} \quad \text { with } \quad \zeta\left(F^{2}\right)=\alpha^{*}\left(F^{\prime 2}\right)
$$

that is the identity outside a small neighborhood of $K^{3}$. We call $\delta$ an elementary deformation of type 1,2 , or 3 , respectively, if the surface defined by $\alpha^{*}$ has only normal singularities and one of the following conditions holds (see Fig. 1):

Type 1. Either case (a) ${ }^{-}\left({ }^{0} K^{3} \cap F^{2}\right)$ is a disk $B^{2}$ with $\cdot B^{2} \subset{ }^{0} A^{* 2}$; or case (b) ${ }^{-}\left({ }^{0} K^{3} \cap F^{2}\right)$ consists of two disks $B^{2}, C^{2}$ such that

$$
\cdot B^{2}, \cdot C^{2} \subset{ }^{0} A^{* 2}
$$

and $B^{2} \cap C^{2}$ is an are with

$$
{ }^{0}\left(B^{2} \cap C^{2}\right) \subset{ }^{0} K^{3}
$$

[^2]Type 2. ${ }^{-}\left({ }^{0} K^{3} \cap F^{2}\right)$ is a disk $B^{2}$ such that each of the intersections $B^{2} \cap A^{2}$ and $B^{2} \cap A^{* 2}$ consists of two disjoint arcs with

$$
{ }^{0}\left(\cdot B^{2} \cap A^{2}\right) \subset{ }^{0} A^{2} \text { and }{ }^{0}\left(\cdot B^{2} \cap A^{* 2}\right) \subset{ }^{0} A^{* 2} .
$$

Type 3. Either case (a) ${ }^{-}\left({ }^{0} K^{3} \cap F^{2}\right)$ is a disk $B^{2}$ with $\cdot B^{2} \subset{ }^{0} A^{2}$; or case (b) ${ }^{-}\left({ }^{0} K^{3} \cap F^{2}\right)$ consists of two disks $B^{2}, C^{2}$ such that $B^{2} \subset{ }^{0} A^{2}$ and each of the intersections $C^{2} \cap A^{2}, C^{2} \cap A^{* 2}, C^{2} \cap B^{2}$ is an arc with

$$
{ }^{0}\left(\cdot C^{2} \cap A^{2}\right) \subset{ }^{0} A^{2}, \quad{ }^{0}\left(\cdot C^{2} \cap A^{* 2}\right) \subset{ }^{0} A^{* 2}, \quad{ }^{0}\left(C^{2} \cap B^{2}\right) \subset{ }^{0} C^{2},{ }^{0} B^{2} .
$$

We remark that an elementary deformation of type 1 (a or b) changes the image sphere $F^{2}$ only in a small neighborhood (small with respect to $F^{2}$ ) of an arc (connecting a point in ${ }^{0} A^{2}$ to a point in ${ }^{0} B^{2}$ or in ${ }^{0} B^{2} \cap{ }^{0} C^{2}$, respectively); a deformation ${ }^{4}$ of type 2 changes $F^{2}$ in a small neighborhood of a disk (whose boundary intersects each $A^{2}$ and $B^{2}$ in one arc). According to this one might say that a deformation of type $i(i=1,2,3)$ is essentially $i$-dimensional.

Theorem 3. Let $M_{*}^{3}$ be a homotopy 3 -cell and $\alpha_{0}: F^{\prime 2} \rightarrow M_{*}^{3}$ an embedding of a 2-sphere, topologically parallel to $\cdot M_{*}^{3}$. Then $\alpha_{0}$ can be deformed step by step into maps $\alpha_{1}, \alpha_{2}, \alpha_{3}$ of ${F^{\prime 2}}^{2}$ into $M_{*}^{3}$ such that the following holds:
(a) $\quad \alpha_{i}(i=1,2,3)$ is obtained from $\alpha_{i-1}$ by a finite sequence of elementary deformations of type $i$ and non-essential deformations.
(b) The image $\alpha_{3}\left(F^{\prime 2}\right)$ lies in a 3 -cell $H^{3} \subset{ }^{0} M_{*}^{3}$.

The two essential points of this theorem (which are not immediate consequences of Smale's results [13]) are (1) the order in which the deformations take place and (2) that no deformations are used that move the surface over a triple point.

We remark without proof: If it were possible to avoid the deformations of type 1 b (i.e. to avoid triple points) or to avoid the deformations of type 2 then this would imply the Poincaré conjecture; this would hold even if $H^{3}$ were not a 3-cell, but homeomorphic to any compact subset of euclidean 3 -space with connected boundary.
3. Sketch of the proofs. The theorems are proved by considering deformations of singular 2 -spheres in a homotopy 3 -cell $M_{*}^{3}$. We start with an embedding

$$
\beta_{0}: F_{0}^{\prime 3} \rightarrow M_{*}^{3}
$$

of a 3 -annulus $F_{0}^{\prime 3}$ into $M_{*}^{3}$ such that one boundary sphere ${S^{\prime 2}}^{2}$ of $F_{0}^{\prime 3}$ is mapped onto ${ }^{\cdot} M_{*}^{3}$ and the other boundary sphere $F_{0}^{\prime 2}$ onto the 2 -sphere $F_{0}^{2}=\alpha_{0}\left(F^{\prime 2}\right)$. Now we deform $F_{0}^{2}$ into a 3 -cell $H^{3} \subset{ }^{0} M_{*}^{3}$ in the simplest way we can find. To do this we choose a simple cell-decomposition $\Gamma$ of the homotopy 3 -sphere $M^{3}=M_{*}^{3}+C^{3}\left(C^{3}\right.$ being a 3 -cell with $C^{3} \cap M_{*}^{3}=C^{3}={ }^{\prime} M_{*}^{3}$ ) into one vertex $E^{0}, r$ elements $E_{i}^{1}, E_{i}^{2}(i=1, \cdots, r)$ of each dimension 1 and 2 , and one open 3 -cell $E^{3}$ containing $C^{3}$. Then we choose a neighborhood $J^{3}$ of the 2 -skeleton $G^{2}$ of $\Gamma$, and we may assume that our initial 3 -annulus $\beta_{0}\left(F_{0}^{\prime 3}\right)$ is $M_{*}^{3}-{ }^{0} J^{3}$,
hence $F_{0}^{2}=J^{3}$. Now we use the fact that $M_{*}^{3}$ is simply connected by taking a collection of $r$ singular disks, bounded by the 1 -skeleton $G^{1}$ of $\Gamma$ (that consists of the $r$ loops $\bar{E}_{i}^{1}$ with the common vertex $E^{0}$ ); these disks with the boundary point $E^{0}$ in common form a "fan" $V^{2}$ with singularities. We can choose $V^{2}$ such that its only singularities are pairwise disjoint double arcs $A_{j}^{1}\left(j=1, \cdots, s\right.$, as depicted in Fig. 2). Now we contract $V^{2}$, changing it only within small neighborhoods $A_{j}^{3}$ of the $A_{j}^{1}$, s, onto a nonsingular fan $V_{*}^{2}$, a small neighborhood $H^{3}$ of which is a 3 -cell; that means we deform the 1 -skeleton $G^{1}$ into the 3 -cell $H^{3}$. We carry out corresponding deformations (see footnote 4) of the 2 -skeleton $G^{2}$ onto a "singular 2 -skeleton" $G_{*}^{2}$ and of its neighborhood $J^{3}$ onto a singular polyhedron $J_{*}^{3}$; and we change the map $\beta_{0}$ correspondingly into a map $\beta_{I}: F_{I}^{\prime 3} \rightarrow M^{3}$ with $\beta_{I}\left|{S^{\prime 2}}^{2}=\beta_{0}\right| S^{\prime 2}$. All the deformations of $G^{2}, J^{3}$ take place in the $A_{j}^{3}$ 's. $\quad H^{3}+\bigcup_{j=1}^{s} A_{j}^{3}$ is a handlebody $K^{3}$. The corresponding deformations of $F_{0}^{2}$ onto $F_{I}^{2}$ are of type 1a only.

Now we have to deform the rest of $F_{I}^{2}$ into $H^{3}$. First we remark that $J_{*}^{3}$ may be decomposed into a neighborhood $T_{*}^{3}$ of the deformed 1 -skeleton $\cdot V_{*}^{2}$ and into $r$ "prismatic", singular 3-cells $P_{\# i}^{3}$ (being prismatic neighborhoods of middle parts of the deformed $E_{i}^{2}$, s), such that $T_{*}^{3} \subset{ }^{0} H^{3}$. That means, that part of $F_{I}^{2}$ lying outside of $H^{3}$ lies in the "top" and "bottom" disks of the $P_{* i}^{3}$ 's. The boundaries of the top and bottom disks of $P_{\nless i}^{3}$ may be joined by an arc $W_{i}^{1} \subset F_{I}^{2} \cap{ }^{0} H^{3}$ and by an are $W_{P i}^{3} \subset \cdot P_{\# i}^{3}$; the so obtained 1 -spheres $W_{i}^{1}+W_{P i}^{1}$ bound singular disks $W_{i}^{2} \subset{ }^{0} H^{3}$. We can choose these $W_{i}^{2}$, such that their only singularities are double ares and that singular, prismatic neighborhoods $W_{i}^{3}$ of them fit properly to $F_{I}^{2}$ and to the $P_{* i}^{3}$ 's. Then we expand the singular 3 -annulus, defined by $\beta_{I}$, over these singular prisms $W_{i}^{3}$ (denoting the changed $\beta_{I}$ by $\beta_{I I}$ ); the corresponding deformation of $F_{I}^{2}$ onto a singular 2 -sphere $F_{I I}^{2}$ may be decomposed into deformations of type 1 ( $a$ and $b$ ) yielding a singular 2 -sphere $F_{1}^{2}$ (and a map $\alpha_{1}$ according to Theorem 3) and after them deformations of type 2 yielding $F_{I I}^{2}$. Now $F_{I I}^{2}$ contains "folds" around the $P_{* i}^{3}$ 's consisting of the top and bottom disks and joining disks (containing the $W_{P i}^{1}$ 's); so we can expand the singular 3 -annulus over the $P_{\# i}^{3}$ 's (denoting the changed $\beta_{I I}$ by $\beta:{F^{\prime \prime}}^{3} \rightarrow M_{*}^{3}$ with $\beta\left|{S^{\prime}}^{2}=\beta_{0}\right|{S^{\prime 2}}^{2}$ ). The corresponding deformation of $F_{1 I}^{2}$ yields $F_{3}^{2} \subset{ }^{0} H^{3}$ (and $\alpha_{3}$ ) and may be decomposed into deformations of type 2, yielding $F_{2}^{2}$ (and $\alpha_{2}$ ), and after them deformations of type 3 (a and b); this completes the proof of Theorem 3.

To prove Theorem 2 we observe that the complement $M_{*}^{3}-{ }^{0} K^{3}$ of the handlebody $K^{3}$ is covered one-to-one by $\beta$. So we deform the given curve $C^{1}$ isotopically into a curve $C_{0}^{1} \subset M_{*}^{3}-K^{3}$; then we choose a knot projection cone $D^{\prime 2}$ bounded by the $\operatorname{knot} \beta^{-1}\left(C_{0}^{1}\right)$ in the 3 -annulus $F^{\prime 3}$; we bring about by small deformations the situation in which $\beta\left(D^{\prime 2}\right)$ has only normal singularities. Then $D^{2}=\beta\left(D^{\prime 2}\right)$ has the demanded properties. Theorem 1 is proved by extending $\beta$ to a 3 -sphere $S^{3} \supset F^{\prime 3}$.

We remark: If it were possible to find the map

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\beta: F^{i^{3}} \rightarrow M_{*}^{3}
$$

( with $\left.\beta\left(\cdot F^{\prime 3}-{S^{\prime}}^{2}\right) \subset{ }^{0} H^{3}\right)$ such that $\beta \mid \beta^{-1}\left(M_{*}^{3}-H^{3}\right)$ is locally one-to-one then the Poincaré conjecture would follow by an easy conclusion. We would obtain such a map $\beta$ if it were possible to deform the 3 -annulus $\beta_{0}\left(F_{0}^{\prime 3}\right)$ onto $\beta\left(F^{\prime 3}\right)$ by "expansions" only. But in our procedure some of the very first deformations in the $A_{j}^{3,}$ s (and only these) are not expansions, so we get certain surfaces in $F^{\prime 3}$ such that $\beta$ is not locally one-to-one at (and only at) the points of these surfaces. ( $\beta$ maps these surfaces homeomorphically into $K^{3}$. Moreover it is possible to arrange our procedure such that these exceptional surfaces become disks.)

## I. Proof of Theorems 1 and 2

We prove Theorem 1 and 2 first. After this we shall prove Theorem 3 by consideration of some more details.
4. Preliminaries. Let $M^{3}$ be a homotopy 3 -sphere. After Moise [6] and Bing [1] there exists a triangulation of $M^{3}$. This means there exists a homotopy 3 -sphere, homeomorphic to $M^{3}$, that is a (straight-lined, finite) polyhedron in a euclidean space $\mathfrak{E}^{n}$ of sufficiently high dimension $n$. So we may assume for convenience and without loss of generality that $M^{3}$ itself is a polyhedron in $\mathbb{E}^{n}$. All point sets considered in the subsequent part of this paper are polyhedral in $\S^{n}$ in the sense of [10] (i.e. finite unions of straightlined, finite, convex, open cells in $\mathbb{E}^{n}$ ); they are denoted by capital roman letters, and their dimensions by upper indices. We use the notation $X, \bar{X},{ }^{0} X$ for the boundary, closure, interior of $X$, respectively, and $X-Y=$ $X-(X \cap Y)$ for the difference.

By a decomposition of $X$ we mean always a collection of finitely many pairwise disjoint point sets whose union is $X$. A decomposition $\Delta$ is called a cell-decomposition, if the elements of $\Delta$ are open cells such that for every two cells $A, B \in \Delta$ either $A \cap B=\emptyset$ or $A \subset \cdot B$ holds. We call a cell-decomposition $\Delta$ a straight-lined triangulation if its elements are open, straight-lined simplices in $\mathbb{E}^{n}$ such that the open faces of each element are also elements of $\Delta$; we call a cell-decomposition $\Theta$ a triangulation in general if for each element $A \epsilon \Theta$ the decomposition $\Theta(\bar{A})$ of $\bar{A}$, consisting of all those elements of $\Theta$ that lie in $\bar{A}$, is isomorphic to the decomposition of a simplex (of the same dimension as $A$ ) into its interior and its open faces.

By a (polyhedral) neighborhood of $X$ in $Y$ (as defined in [14]) we mean the closure of the simplex star of $X$ in a second barycentric subdivision $\Delta^{* *}$ of a (general) triangulation $\Delta$ of $Y$ such that $X$ is the union of elements of $\Delta$; the neighborhood is called small with respect to $Z|V| \cdots \mid W$ (see [4, Kap. I,2]) if $Z \cap Y, V \cap Y, \cdots, W \cap Y$ are unions of elements of $\Delta$.

By an arc, disk, or 3 -cell we mean, if not stated otherwise, a compact, nonsingular 1-, 2 -, or 3 -cell, respectively.

All maps considered in the subsequent part of this paper are simplicial maps in the sense of [11, p. 114]: a continous map $\alpha: A^{\prime} \rightarrow B$ is called sim-
plicial if there exist straight-lined triangulations $\Delta^{\prime}$ of $A^{\prime}$ and $\Delta$ of $B$ such that $\alpha$ maps each element of $\Delta^{\prime}$ linearly onto an element of $\Delta$.

Let $C^{3}$ be a 3 -cell in $M^{3}$ and denote the homotopy 3 -cell $M^{3}-{ }^{0} C^{3}$ by $M_{*}^{3}$.
5. A simple cell-decomposition $\Gamma$ of $M^{3}$. We can find a cell-decomposition $\Gamma$ of $M^{3}$ with the following properties:
(i) $\Gamma$ contains just one 0-dimensional element, say $E^{0}$, and just one 3-dimensional element, say $E^{3}$.
(ii) $C^{3} \subset E^{3}$.
(iii) $\Gamma$ contains $r$ elements, say $E_{1}^{1}, \cdots, E_{r}^{1}$, of dimension 1 and $r$ clements, say $E_{1}^{2}, \cdots, E_{r}^{2}$, of dimension 2 .
(iv) Each element $E_{i}^{1}$ lies at least 2 times in the boundary of $\bigcup_{j=1}^{r} E_{j}^{2}$ (i.e.: if $U^{3}$ is a neighborhood of a point of $E_{i}^{1}$ in $M^{3}$, which is small with respect to

$$
E_{1}^{1}|\cdots| E_{r}^{1} E_{1}^{2} \cdots \mid E_{r}^{2}
$$

then ${ }^{0} U^{3} \cap \bigcup_{j=1}^{r} E_{j}^{2}$ consists of at least 2 pairwise disjoint open disks).
Proof of the assertion. I may be found as follows:
Step 0. We take an arbitrary decomposition $\Gamma_{0}$ of $M^{3}$ into open cells.
Step 1. We delete, step by step, such 2 -dimensional elements of $\Gamma_{0}$ that separate two different 3 -dimensional elements; this yields finally a decomposition $\Gamma_{1}$ with only one 3-dimensional element (see [11]).

Step 2. Now we contract a maximal tree in the 1 -skeleton of $\Gamma_{1}$ into one point; this yields a decomposition $\Gamma_{2}$ with property (i).

Step 3. If a 1-dimensional element $E^{1} \epsilon \Gamma_{2}$ lies just once in the boundary of a 2-dimensional element $E^{2} \epsilon \Gamma_{2}$ and does not lie in the boundary of any other 2-dimensional element of $\Gamma_{2}$ then we delete both $E^{1}$ and $E^{2}$; repeating this operation as often as possible, we obtain a decomposition $\Gamma_{3}$ with properties (i) and (iv). $\Gamma_{3}$ possesses also property (iii) since the Euler characteristic of $M^{3}$ is zero (see [11]).

Step 4. To obtain $\Gamma$ we deform the 2-skeleton of $\Gamma_{3}$ isotopically such that the deformed 2 -skeleton lies in $M^{3}-C^{3}$.

Remark. In the case $r=0, M^{3}$ is obviously a 3 -sphere and we have nothing to prove. Therefore we may assume for the subsequent sections of this paper that $r \neq 0$. We denote the 1 -skeleton $\bigcup_{i=1}^{r} \bar{E}_{i}^{1}$ and the 2 -skeleton $\bigcup_{i=1}^{r} \bar{E}_{i}^{2}$ of $\Gamma$ by $G^{1}, G^{2}$, respectively.
6. The 1-skeleton $G^{1}$ of $\Gamma$ bounds a singular fan $V^{2}$. We assert: There exists a map

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\zeta: V^{\prime 2} \rightarrow M_{*}^{3}
$$

with the image $\zeta\left(V^{\prime 2}\right) \subset{ }^{0} M_{*}^{3}$ denoted by $V^{2}$, and with the following properties (see Fig. 2):
(i) $V^{\prime 2}$ consists of $r$ disks $V_{1}^{\prime 2}, \cdots, V_{r}^{\prime 2}$, possessing one common boundary
point $E^{\prime \prime}$, and otherwise being pairwise disjoint; $V^{\prime 2}$ is disjoint from $M^{3}, F^{\prime 2}$.
(ii) $\cdot V^{2}=G^{1}$.
(iii) The only singularities of $V^{2}$ are pairwise disjoint, normal, double $\operatorname{arcs} A_{1}^{1}, \cdots, A_{s}^{1}$ ( $s$ may be zero) such that each of the two connected components $A_{j}^{\prime 1}, A_{j}^{\prime \prime 1}$ of $\zeta^{-1}\left(A_{j}^{1}\right)$ possesses just one boundary point in ${ }^{\prime} V^{\prime 2}-E^{\prime 0}$ and otherwise lies in ${ }^{0} V^{\prime 2}$ (for all $j=1, \cdots, s$ ).
(iv) The arcs $A_{j}^{1}(j=1, \cdots, s)$ intersect $G^{2}-G^{1}$ at most in isolated piercing points, $V^{2}$ intersects $G^{2}-G^{1}$ at most in piercing curves whose intersection and self-intersection points are the piercing points $A_{j}^{1} \cap\left(G^{2}-G^{1}\right)$.
(v) $\zeta^{-1}\left(-\left\{V^{2} \cap\left[G^{2}-G^{1}\right]\right\}\right)$ is disjoint from $\cdot V^{\prime 2}-E^{\prime 0}$, i.e. a connected component of

$$
\zeta^{-1}\left(V^{2} \cap\left[G^{2}-G^{1}\right]\right)
$$

is either a 1 -sphere or an open are whose boundary lies in

$$
E^{\prime 0}+\bigcup_{j=1}^{s}\left[\left(A_{j}^{\prime 1}+\cdot A_{j}^{\prime \prime 1}\right) \cap^{0} V^{\prime 2}\right]
$$

(see Fig. 3).
Proof of the assertion. Step 0 . Since $M_{*}^{3}$ is simply connected there exists a map $\zeta_{0}: V^{\prime 2} \rightarrow M_{*}^{3}$ with properties (i) and (ii).

Step 1. From $\zeta_{0}$ we can obtain by small deformations (by a similar procedure as described in [7]) a map $\zeta_{I}: V^{\prime 2} \rightarrow M_{*}^{3}$, also with properties (i), (ii), such that the only singularities of $V_{I}^{2}=\zeta_{I}\left(V^{\prime 2}\right)$ are normal double curves, triple points, and branch points of multiplicity 1 (see [8]), and such that the triple points, the branch points, and the interiors of the double curves lie in ${ }^{0} V_{I}^{2}$, and that $E^{0}$ is no double point.

Step 2. Now we consider the set $D_{I}$ of all double points (not including the triple points) of $V_{I}^{2}$, and we remove, step by step, all those connected components $D_{I 1}^{1}, \cdots, D_{I d}^{1}$ of $D_{I}$ that are disjoint from $\cdot V_{I}^{2}$. To do this we can find an arc $C_{k}^{1} \subset V_{I}^{2}$ that joins a point of $\cdot V_{I}^{2}-\left(E^{0}+D_{I}\right)$ to a point of a component $D_{I k}^{1}$ (provided that $d \neq 0$ ) such that ${ }^{0} C_{k}^{1} \cap \bar{D}_{I},{ }^{0} C_{k}^{1} \cap \cdot V_{I}^{2}=\emptyset$; then we remove $D_{I k}^{1}$ (without introducing a new component of that kind) by a deformation of $\zeta_{I}$ (see Fig. 4) that changes $V_{I}^{2}$ only in a neighborhood of $C_{k}^{1}$, and so on. In this way we obtain finally after $d$ deformations a map $\zeta_{I I}: V^{\prime 2} \rightarrow M_{*}^{3}$.

Step 3. Now we can remove the triple points of $V_{I I}^{2}=\zeta_{I I}\left(V^{\prime 2}\right)$ by deformations of $\zeta_{I I}$ that change $V_{I I}^{2}$ only in neighborhoods of double arcs of $V_{I I}^{2}$ that join the triple points to $V_{I I}^{2}-E^{0}$. Further we can remove the branch points by cuts along those double arcs of $V_{I I}^{2}$ that join the branch points to $\cdot V_{I I}^{2}-E^{0}$. This yields a map

$$
\zeta_{I I I}: V^{\prime 2} \rightarrow M_{*}^{3}
$$

with $\zeta_{I I I}\left(V^{\prime 2}\right)$ denoted by $V_{I I I}^{2}$, such that the set $D_{I I I}$ of double points of $V_{I I I}^{2}$ consists of pairwise disjoint arcs $D_{I I I I}^{1}, \cdots, D_{I I I e}^{1}$.
Step 4. If one of the components of the inverse image of $D_{I I I k}^{1}-$ say $D_{I I I k}^{\prime 1}-$ is disjoint from $\cdot V^{\prime 2}$, then we choose an arc $C_{k}^{\prime 1} \subset V^{\prime 2}$, joining a point of ${ }^{0} D_{I I I k}^{\prime 1}$ to
a point of

$$
\cdot V^{\prime 2}-\left[E^{\prime 0}+\zeta_{I I I}^{-1}\left(\cdot D_{I I I}\right)\right]
$$

with ${ }^{0} C_{k}^{\prime 1} \cap \zeta_{I I I}^{-1}\left(D_{I I I}\right),{ }^{0} C_{k}^{\prime 1} \cap \cdot V^{\prime 2}=\emptyset$, and we remove $D_{I I I k}^{\prime 1}$ by a deformation of $\zeta_{I I I}$ (similar to Step 2) that changes $V_{I I I}^{2}$ only in a neighborhood of $\zeta_{I I I}\left(C_{k}^{\prime 1}\right)$; and so on. This yields finally a map

$$
\zeta_{I V}: V^{\prime 2} \rightarrow M_{*}^{3}
$$

with the properties (i), (ii), and (iii).
Step 5 . From $\zeta_{I V}$ we obtain by small deformations a map

$$
\zeta_{V}: V^{\prime 2} \rightarrow M_{*}^{3}
$$

with $\zeta_{V}\left(V^{\prime 2}\right)$ denoted by $V_{V}^{2}$, having the properties (i), $\cdots$, (iv).
Step 6 . From $\zeta_{V}$ we obtain, by deformations that change $V_{V}^{2}$ only in a small neighborhood of $\cdot V_{V}^{2}=G^{1}$, a map $\zeta: V^{\prime 2} \rightarrow M_{3}^{*}$ with the required properties.
7. Neighborhoods $A_{j}^{3}$ of the double arcs $A_{j}^{1}$ of $V^{2}$. Let $A_{1}^{3}, \ldots, A_{s}^{3}$ be pairwise disjoint neighborhoods of $A_{1}^{1}, \cdots, A_{s}^{1}$, respectively, in $M_{*}^{3}$, which are small with respect to $G^{2} \mid V^{2}$ (see Fig. 5a).
$A_{j}^{3} \cap G^{1}$ consists of two disjoint arcs; we denote them by $K_{j}^{1}, L_{j}^{1}$. The closures of the connected components of $\left(A_{j}^{3} \cap V^{2}\right)-A_{j}^{1}$ are two disks; we denote them by $V_{K j}^{2}, V_{L j}^{2}$ such that

$$
K_{j}^{1} \subset \cdot V_{K j}^{2}, \quad L_{j}^{1} \subset \cdot V_{L j}^{2}
$$

We choose a neighborhood $A_{j}^{2}$ of $A_{j}^{1}$ in $V_{K j}^{2}$, which is small with respect to $G^{2}$, and we denote the nonsingular fan ${ }^{-}\left(V^{2}-\bigcup_{j=1}^{s} A_{j}^{2}\right)$ by $V_{*}^{2}$.

We denote those connected components of $A_{j}^{3} \cap G^{2}$ that contain $K_{j}^{1}, L_{j}^{1}$, respectively, by $K_{j}^{2}, L_{j}^{2}$. The closures of the connected components of $K_{j}^{2}-K_{j}^{1}$ and $L_{j}^{2}-L_{j}^{1}$ are disks $K_{j 1}^{2}, \cdots, K_{j t_{j}}^{2}$ and $L_{j 1}^{2}, \cdots, L_{j u_{j}}^{2}$, respectively. Those connected components of $A_{j}^{3} \cap G^{2}$ that are different from $K_{j}^{2}, L_{j}^{2}$ are disks $N_{j 1}^{2}, \cdots, N_{j v_{j}}^{2}\left(v_{j}\right.$ may be zero). We arrange the notation such that the disks $K_{j 1}^{2}, \cdots, K_{j t_{j}}^{2}$ lie around $K_{j}^{1}$ in the order of the enumeration and such that $V_{K j}^{2}$ lies in this order between $K_{j t_{j}}^{2}$ and $K_{j 1}^{2}$.
8. A small neighborhood $J^{3}$ of the 2 -skeleton $G^{2}$ and its complementary 3 -annulus $F_{0}^{3}$. Let $T^{3}$ be a neighborhood of $G^{1}$ in $M_{*}^{3}$, which is small with respect to

$$
G^{2}\left|V^{2}\right| A_{1}^{3}|\cdots| A_{s}^{3}\left|A_{1}^{2}\right| \cdots \mid A_{s}^{2} ;
$$

Let $J^{3}$ be a neighborhood of $G^{2}$ in $M_{*}^{3}$, which is small with respect to

$$
T^{3}\left|V^{2}\right| A_{1}^{3}|\cdots| A_{s}^{3}\left|A_{1}^{2}\right| \cdots \mid A_{s}^{2}
$$

Then $M_{*}^{3}-{ }^{0} J^{3}$ is a 3 -annulus $F_{0}^{3}$.
We denote $T^{3} \cap J^{3}$ by $T_{J}^{3}$, and the two connected components of $T_{J}^{3} \cap A_{j}^{3}$ $(j=1, \cdots, s)$ by $T_{K j}^{3}, T_{L j}^{3}$ (see Fig. 5b) such that $K_{j}^{1} \subset T_{K j}^{3}$ and $L_{j}^{1} \subset T_{L j}^{3}$.

Further we denote the connected components of $J^{3} \cap A_{j}^{3}$ by $K_{j}^{3}, L_{j}^{3}, N_{j 1}^{3}, \cdots, N_{j v_{j}}^{3}$ where

$$
K_{j}^{2} \subset K_{j}^{3}, \quad L_{j}^{2} \subset L_{j}^{3}, \quad N_{j m}^{2} \subset N_{j m}^{3} \quad\left(m=1, \cdots, v_{j}\right)
$$

and the connected components of ${ }^{-}\left(K_{j}^{3}-T_{K j}^{3}\right)$ and $^{-}\left(L_{j}^{3}-T_{L j}^{3}\right)$ by $K_{j 1}^{3}, \cdots, K_{j t_{j}}^{3}$ and $L_{j 1}^{3}, \cdots, L_{j u_{j}}^{3}$, respectively, where

$$
K_{j k}^{2} \cap K_{j k}^{3} \neq \emptyset\left(k=1, \cdots, t_{j}\right) \quad \text { and } \quad L_{j 1}^{2} \cap L_{j 1}^{3} \neq \emptyset\left(1=1, \cdots, u_{j}\right)
$$

Those $t_{j}-1$ connected components of ${ }^{-}\left(A_{j}^{3}-K_{j}^{3}\right)$ that are disjoint from $V_{K j}^{2}$ are 3-cells $F_{K j 1}^{3}, \cdots, F_{K j t_{j}-1}^{3}$ in $F_{0}^{3}$ (see Fig. 5b).

The connected components of ${ }^{-}\left(J^{3}-T_{J}^{3}\right)$ are $r$ 3-cells; we denote them by $P_{1}^{3}, \cdots, P_{r}^{3}$ where $E_{i}^{2} \cap P_{i}^{3} \neq \emptyset(i=1, \cdots, r)$, and we denote the disks $E_{i}^{2} \cap P_{i}^{3}$ by $P_{i}^{2}$. Then $P_{i}^{3}$ can be represented as cartesian product $P_{i}^{2} \times I^{1}$, where $I^{1}$ is the interval $-1 \leqq x \leqq+1$, such that
(i) $\quad P_{i}^{2}$ is the central disk, i.e. $p \times 0=p$ for all $p \in P_{i}^{2}$;
(ii) the top and bottom disks are the connected components of $\cdot P_{j}^{3} \cap \cdot J^{3}$, i.e. $\left(P_{i}^{2} \times 1\right)+\left(P_{i}^{2} \times-1\right)=\cdot P_{i}^{3} \cap: J^{3}$;
(iii) the polyhedra $A_{j}^{3}, V^{2}, A_{j}^{2}$ intersect $P_{i}^{3}$ "prismatically", i.e.:
$A_{j}^{3} \cap P_{i}^{3}=\left(A_{j}^{3} \cap P_{i}^{2}\right) \times I^{1}, V^{2} \cap P_{i}^{3}=\left(V^{2} \cap P_{i}^{2}\right) \times I^{1}, A_{i}^{2} \cap P_{i}^{3}=\left(A_{i}^{2} \cap P_{i}^{2}\right) \times I^{1}$.
Let $F_{0}^{\prime 3}$ be a 3 -annulus, disjoint from $M^{3}, V^{\prime 2}, F^{\prime 2}$, and let

$$
\beta_{0}: F_{0}^{\prime 3} \rightarrow M_{*}^{3}
$$

be a homeomorphism with the image $\beta_{0}\left(F_{0}^{\prime 3}\right)=F_{0}^{3}$. We denote the boundary 2-spheres $\beta_{0}^{-1}\left(J^{3}\right)$ and $\beta_{0}^{-1}\left(\cdot M_{*}^{3}\right)$ of $F_{0}^{\prime 3}$ by $F_{0}^{\prime 2}$ and $S^{\prime 2}$, respectively. (We may bring about by isotopic deformations the situation in which $\beta_{0}\left(F_{0}^{\prime 2}\right)=\alpha_{0}\left(F^{\prime 2}\right)$ with $\alpha_{0}$ the embedding given in Theorem 3.)
9. Deformations in the $A_{j}^{3}$ 's that take $G^{1}$ onto the boundary of the nonsingular fan $V_{*}^{2}$. We denote the 3 -cell $K_{j}^{3}+\bigcup_{k=1}^{t_{j}-1} F_{K j k}^{3}$ (see Fig. 5b) by $Q_{j}^{3}$, and choose a neighborhood $Q_{* j}^{3}$ of ${ }^{-}\left(A_{j}^{3}-Q_{j}^{3}\right)$ in ${ }^{-}\left(A_{j}^{3}-Q_{j}^{3}\right)$, which is small with respect to $G^{2}\left|V^{2}\right| A_{j}^{2}\left|T^{3}\right| T_{J}^{3} \mid J^{3}$, such that (with respect to the product representation introduced in Sec. 8)

$$
{ }^{-}\left({ }^{0} Q_{* j}^{3} \cap P_{i}^{3}\right)={ }^{-}\left(Q_{* j}^{3} \cap P_{i}^{2}\right) \times I^{1} \quad(i=1, \cdots, r)
$$

Then we denote the 3 -cell ${ }^{-}\left[A_{j}^{3}-\left(Q_{j}^{3}+Q_{* j}^{3}\right)\right]$ by $O_{j}^{3}$ and the disks $\cdot O_{j}^{3} \cap Q_{j}^{3}$ and $\cdot O_{j}^{3} \cap Q_{* j}^{3}$ by $O_{j}^{2}$ and $O_{\# j}^{2}$, respectively.

Now we can find an epi-homeomorphism $\delta_{j}: Q_{j}^{3} \rightarrow Q_{j}^{3}+O_{j}^{3}$ with the following properties (see Fig. 5):
(i) $\delta_{j} \mid\left(\cdot Q_{j}^{3}-{ }^{0} O_{j}^{2}\right)=$ identity; $\delta_{j}\left(O_{j}^{2}\right)=O_{\# j}^{2}$.
(ii) $\delta_{j}\left(K_{j}^{1}\right)=\left(K_{j}^{1}-\cdot A_{j}^{2}\right)+{ }^{-}\left(\cdot A_{j}^{2}-K_{j}^{1}\right)$.
(iii) $\delta_{j}\left(K_{j k}^{2}\right)$ intersects $L_{j}^{1}$ in just one point and intersects each disk $O_{j}^{2}$, $V_{L j}^{2}, L_{j 1}^{2}, \cdots, L_{j u_{j}}^{2}, N_{j 1}^{2}, \cdots, N_{j v_{j}}^{2}$ in just one arc (for all $k=1, \cdots, t_{j}$ ); $\delta_{j}\left({ }^{0} K_{j k}^{2}\right)$ is disjoint from $V_{K j}^{2}$.
(iv) The neighborhood $\delta_{j}\left(T_{K j}^{3}\right)$ of $\delta_{j}\left(K_{j}^{1}\right)$ in $A_{j}^{3}$ is small with respect to $T_{L j}^{3}\left|V^{2}\right| L_{j 1}^{3}|\cdots| L_{j u_{j}}^{3}\left|N_{j 1}^{3}\right| \cdots \mid N_{j v_{j}}^{3}$ and intersects $O_{j}^{2}$ in just two disjoint disks.
(v) The intersections of $\delta_{j}\left(K_{j k}^{3}\right), \delta_{j}\left(K_{j_{k}}^{2}\right)\left(k=1, \cdots, t_{j}\right)$, and $\delta_{j}\left(T_{K j}^{3}\right)$ with $L_{j 1}^{3}\left(1=1, \cdots, u_{j}\right)$ and $N_{j m}^{3}\left(m=1, \cdots, v_{j}\right)$ (see also Fig. 6) can be written as cartesian products, using the product representation of the $P_{i}^{3}$ 's introduced in Sec. 8; the same holds for the polyhedra

$$
\begin{array}{ccc}
\delta_{j}^{-1}\left(L_{j 1}^{3} \cap \delta_{j}\left(K_{j k}^{3}\right)\right), & \delta_{j}^{-1}\left(L_{j 1}^{2} \cap \delta_{j}\left(K_{j k}^{3}\right)\right), & \delta_{j}^{-1}\left(N_{j m}^{3} \cap \delta_{j}\left(K_{j k}^{3}\right)\right), \\
\delta_{j}^{-1}\left(N_{j m}^{2} \cap \delta_{j}\left(K_{j k}^{3}\right)\right), & \delta_{j}^{-1}\left(T_{L j}^{3} \cap \delta_{j}\left(K_{j k}^{3}\right)\right), & \delta_{j}^{-1}\left(V_{L j}^{2} \cap \delta_{j}\left(K_{j k}^{3}\right)\right) .
\end{array}
$$

Let $\eta: J^{3} \rightarrow M_{*}^{3}$ be the map defined by
(a) $\left.\eta\right|^{-}\left(J^{3}-\bigcup_{j=1}^{s} K_{j}^{3}\right)=$ identity,
(b) $\quad \eta\left|K_{j}^{3}=\delta_{j}\right| K_{j}^{3}$ (for all $j=1, \cdots, s$ ),
and denote the images $\eta\left(J^{3}\right), \eta\left(G^{1}\right), \eta\left(G^{2}\right), \eta\left(T_{J}^{3}\right), \eta\left(P_{i}^{3}\right)$ by $J_{*}^{3}, G_{*}^{1}, G_{*}^{2}, T_{* J}^{3}, O_{* i}^{3}$, respectively. Obviously we have $G_{*}^{1}=V^{2}$.

Now we denote $\beta_{0}^{-1}\left(O_{j}^{2}\right)$ by ${O_{j}^{\prime 2}}^{2}$, and we choose $s$ pairewise disjoint 3 -cells $O_{1}^{\prime 3}, \cdots, O_{s}^{\prime 3}$ (see Fig. 7) that are disjoint from $M^{3}, V^{\prime 2}, F^{\prime 2},{ }^{0} F_{0}^{\prime 3}$ such that $\cdot O_{j}^{\prime 3} \cap \cdot F_{0}^{\prime 3}=O_{j}^{\prime 2}$; then we denote $F_{0}^{\prime 3}+\bigcup_{j=1}^{s} O_{j}^{\prime 3}$ by $F_{I}^{\prime 3}$, and we choose a map

$$
\beta_{I}: F_{I}^{\prime 3} \rightarrow M_{*}^{3}
$$

with the following properties:
(I) $\left.\beta_{I}\right|^{-}\left[F_{0}^{\prime 3}-\bigcup_{j=1}^{s} \bigcup_{k=1}^{t} t_{j=1}^{-1} \beta_{0}^{-1}\left(F_{K j k}^{3}\right)\right]=\left.\beta_{0}\right|^{-}\left[F_{0}^{\prime 3}-\bigcup_{j=1}^{s} \bigcup_{k=1}^{t_{j}-1} \beta_{0}^{-1}\left(F_{K j k}^{3}\right)\right]$.
(II) $\beta_{I} \mid \beta_{0}^{-1}\left(F_{K j k}^{3}\right)=\left[\delta_{j} \mid F_{K j k}^{3}\right] \cdot\left[\beta_{0} \mid \beta_{0}^{-1}\left(F_{K j k}^{3}\right)\right]$ for all $j=1, \cdots, s$; $k=1, \cdots, t_{j}$ ).
(III) $\beta_{I} \mid O_{j}^{\prime 3}$ is an epi-homeomorphism of $O_{j}^{\prime 3}$ onto $O_{j}^{3}$.

We remark that the map $\beta_{I}$ is locally one-to-one, except for the "reflection disks" $O_{j}^{\prime 2}$, i.e. if $p$ is a point of $F_{i}^{\prime 3}$ and if $U^{\prime 3}$ is a sufficiently small neighborhood of $p$ in $F_{I}^{\prime 3}$ then $\beta_{I} \mid U^{\prime 3}$ is a homeomorisphm if and only if $p \notin \bigcup_{j=1}^{s} O_{j}^{\prime 2}$.
10. $G_{\#}^{1}$ and its neighborhood $T_{* J}^{3}$ lie in a 3-cell $H^{3}$. Let $H^{3}$ be a neighbor$\operatorname{hood}$ of $V_{*}^{2}+T_{* J}^{3}$ in $M_{*}^{3}$, which is small with respect to

$$
G_{*}^{2}\left|V^{2}\right| J_{*}^{3}\left|A_{1}^{3}\right| \cdots\left|A_{s}^{3}\right| O_{1}^{2}|\cdots| O_{s}^{2}
$$

that intersects the $P_{\# i}^{3}$ 's prismatically, i.e.: $\eta^{-1}\left(H^{3} \cap P_{\# i}^{3}\right)(i=1, \cdots, r)$ can be written as cartesian product using the product representation of the $P_{i}^{3 \prime} s$ introduced in Sec. 8 (compare Fig. 11a).
11. Arcs $W_{i}^{1}$ in $\cdot J^{3} \cap T_{J}^{3}$ joining top and bottom disks of the prisms $P_{i}^{3}$. $T_{J}^{3}$ a handlebody of genus $r$. The intersection $: J^{3} \cap \cdot T_{J}^{3}$ is a 2 -sphere with $2 r$ holes, denoted by $T^{2}$.

We assert: There can be found $r$ pairwise disjoint $\operatorname{arcs} W_{1}^{1}, \cdots, W_{r}^{1} \subset T^{2}$ such that (for all $i=1, \cdots, r$ )
(i) ${ }^{0} W_{i}^{1} \subset{ }^{0} T^{2} ; \cdot W_{i}^{1}=p_{i} \times \cdot I^{1}$ (using the product representation of the $P_{i}^{3}$ 's introduced in Sec. 8) with $p_{i}$ an arbitrary point in $\cdot P_{i}^{2}-\bigcup_{j=1}^{s} A_{j}^{3}$; we denote the arc $p_{i} \times I^{1}$ by $W_{P i}^{1}$;
(ii) if $S_{i}^{1} \subset{ }^{0} T_{J}^{3}$ is a 1 -sphere, topologically parallel to $W_{i}^{1}+W_{P i}^{1}$, i.e.: such that there exists an annulus in $T_{J}^{3}$ with boundary curves $S_{i}^{1}$ and $W_{i}^{1}+W_{P i}^{1}$, then $S_{i}^{1}$ is homologous to $0 \bmod 2$ in $M_{*}^{3}-\left(W_{i}^{1}+W_{P i}^{1}\right)$.

We denote the arc $\eta\left(W_{i}^{1}\right)$ by $W_{\neq i}^{1}$. There exists just one connected component of $\beta_{I}^{-1}\left(W_{\circledast i}^{1}\right)$-we denote it by $W_{i}^{\prime 1}$-such that $\beta_{I}\left(W_{i}^{\prime 1}\right)=W_{\# i}^{1}$; and $W_{i}^{\prime 1} \subset \cdot F_{I}^{\prime 3}$.

Proof of the assertion. First we remark that the 1 -spheres $\cdot P_{1}^{2}, \cdots, \cdot P_{r}^{2}$ form a 1-dimensional homology basis $\bmod 2$ of $T_{J}^{3}$ (if we identify the chains $\bmod 2$ with the corresponding polyhedra). If $\cdot P_{1}^{2}, \cdots, \cdot P_{r}^{2}$ were homologously dependent $\bmod 2$ it would follow that there exists a surface in $T_{J}^{3}$ with boundary some of the $\cdot P_{i}^{2}$, s; this surface could be completed by the corresponding disks $P_{i}^{2}$ to a closed surface, non-separating in $M_{*}^{3}$; but this is impossible since $M_{*}^{3}$ is a homotopy 3-cell.

We choose an arbitrary system of pairwise disjoint arcs

$$
W_{1}^{*_{1}}, \cdots, W_{r}^{*_{1}} \subset T^{2}
$$

fulfilling condition (i). Now $W_{i}^{* 1}+W_{P i}^{1}(i=1, \cdots, r)$ is homologous mod 2 in $T_{J}^{3}$ to a linear combination $\sum_{k=1}^{r} c_{i k}^{\prime} \cdot P_{k}^{2}$ with coefficients $c_{i k}^{\prime}=0$ or 1 . If $c_{i i}^{\prime}=0$ then we take $W_{i}^{1}=W_{i}^{* 1}$. If $c_{i i}^{\prime} \neq 0$ then to obtain $W_{i}^{1}$ we take a small neighborhood $N_{i}^{2}$ of $\cdot P_{i}^{2} \times 1$ in $T^{2}$ and replace the arc $W_{i}^{* 1} \cap N_{i}^{2}$ by another arc in $N_{i}^{2}$ with the same boundary points such that $W_{i}^{1}+W_{P i}^{1}$ is homologous $\bmod 2$ to $W_{i}^{* 1}+W_{P i}^{1}+\cdot P_{i}^{2}$ in $T_{J}^{3}$. Now the $W_{i}^{1,}$ s fulfill condition (ii) also. For every $i=1, \cdots, r$ there exists a surface in $T_{J}^{3}$ whose boundary consists of $S_{i}^{1}$ and some of the $\cdot P_{k}^{2}$, s , except $\cdot P_{i}^{2}$, and whose interior lies in ${ }^{0} T_{J}^{3}$; this surface can be completed by the corresponding $P_{k}^{2}$,s to a surface $B_{i}^{2}$ in $M_{*}^{3}-\left(W_{i}^{1}+W_{P i}^{1}\right)$ that is bounded by $S_{i}^{1}$ only.
12. Singular disks $W_{\neq i}^{2}$ in $H^{3}$ corresponding to the arcs $W_{\neq i}^{1}$. Let $W_{1}^{\prime 2}, \cdots, W_{r}^{\prime 2}$ be $r$ pairwise disjoint disks that are disjoint from $M^{3},{ }^{0} F_{I}^{\prime 3}, F^{\prime 2}, V^{\prime 2}$ such that

$$
W_{i}^{\prime 2} \cap \cdot F_{I}^{\prime 3}=\cdot W_{i}^{\prime 2} \cap \cdot F_{I}^{\prime 3}=W_{i}^{\prime 1} \quad(\text { for all } i=1, \cdots, r)
$$

We denote $\cdot W_{i}^{\prime 2}-{ }^{0} W_{i}^{\prime 1}$ by $W_{P i}^{\prime 1}$, and $\bigcup_{i=1}^{r} W_{i}^{\prime 2}$ by $W^{\prime 2}$.
Now we assert: There exists a map $\vartheta: W^{\prime 2} \rightarrow H^{3}$, with the image $\vartheta\left(W^{\prime 2}\right) \subset{ }^{0} H^{3}$ denoted by $W_{*}^{2}$, and with the following properties:
(i) $\vartheta\left|W_{i}^{\prime \prime}=\beta_{I}\right| W_{i}^{\prime 1}$ and $\vartheta\left(W_{P i}^{\prime 1}\right)=W_{P i}^{1}($ for all $i=1, \cdots, r)$.
(ii) The only singularities of $W_{*}^{2}$ are pairwise disjoint, normal, double arcs $B_{1}^{1}, \cdots, B_{b}^{1}$ ( $b$ may be zero) such that each of the two connected components $B_{f}^{\prime 1}, B_{f}^{\prime \prime 1}$ of $\vartheta^{-1}\left(B_{f}^{1}\right)$ possesses just one boundary point in $\bigcup_{i=1}^{r}{ }^{0} W_{i}^{\prime 1}$ and otherwise lies in ${ }^{0} W^{\prime 2}$ (for all $f=1, \cdots, b$ ). $W^{2}$ intersects the $P_{\# i}^{3}$ 's prismatically.
(iii) There exists a neighborhood $U^{\prime 2}$ of $\cdot W^{\prime 2}$ in $W^{\prime 2}$ such that $\vartheta\left({ }^{0} U^{\prime 2}\right) \subset{ }^{0} T_{\# J}^{3}$.

Proof of the assertion. Step 0. Since $W_{\# i}^{1}+W_{P i}^{1} \subset{ }^{0} H^{3}$ (for all $\left.i=1, \cdots, r\right)$ there exists a map $\vartheta_{0}: W^{\prime 2} \rightarrow H^{3}$ with property (i).

Step 1. As in the proof of Sec. 6, steps 1 to 5 , we can derive from $\vartheta_{0}$ a map $\vartheta_{I}: W^{\prime 2} \rightarrow H^{3}$ with properties (i), (ii).

Step 2. We choose pairwise disjoint neighborhoods $N_{1}^{3}, \cdots, N_{r}^{3}$ of the 1 -spheres $W_{\# i}^{1}+W_{P i}^{1}$ in $H^{3}$, which are small with respect to $T_{* J}^{3} \mid \vartheta_{I}\left(W^{\prime 2}\right)$. The intersection $N_{i}^{3} \cap \vartheta_{I}\left(W_{i}^{\prime 2}\right)$ consists of a 1 -sphere $N_{i}^{1}$, topologically parallel to $W_{\# i}^{1}+W_{P i}^{1}$, and of an even number $n_{i}$ of meridian circles of $N_{i}^{3}$ each of which pierces $N_{i}^{1}$ in just one point. Now we choose an oriented 1 -sphere $X_{i}^{1}$ in $\cdot N_{i}^{3} \cap{ }^{0} T_{\# J}^{3}$, topologically parallel to $W_{\# i}^{1}+W_{P i}^{1}$, and an oriented meridian circle $Y_{i}^{1}$ of $N_{i}^{3}$ that intersects $X_{i}^{1}$ in just one point; we denote the homology classes of $X_{i}^{1}$ and $Y_{i}^{1}$ in $N_{i}^{3}$ by $\mathfrak{x}_{i}$ and $\mathfrak{y}_{i}$, respectively. Then the homology class $\mathfrak{n}_{i}$ of the properly oriented 1 -sphere $N_{i}^{1}$ is $\mathfrak{n}_{i}=\mathfrak{x}_{i}+w_{i} \mathfrak{\eta}_{i}$.

Now we need the fact that the coefficients $w_{i}$ are even numbers. To prove this we show that both $N_{i}^{1}$ and $X_{i}^{1}$ are homologous $0 \bmod 2$ in $M_{*}^{3}-\left(W_{\# i}^{1}+W_{P i}^{1}\right)$ :
(1) $\quad N_{i}^{1}$ bounds a 2-dimensional polyhedron $D_{i}^{2} \subset \vartheta_{I}\left(W_{i}^{\prime 2}\right)$ that intersects $W_{\# i}^{1}+W_{P i}^{1}$ in the even number $n_{i}$ of piercing points. From $D_{i}^{2}$ we remove $n_{i}$ disks, being the intersections of $D_{i}^{2}$ with a small neighborhood $U_{i}^{3}$ of $W_{* i}^{1}+W_{P i}^{1}$ in $N_{i}^{3}$, and replace them by $\frac{1}{2} n_{i}$ annuli in $\cdot U_{i}^{3}$ such that we obtain a 2 -dimensional polyhedron bounded by $N_{i}^{1}$ and disjoint from $W_{\# i}^{1}+W_{P i}^{1}$.
(2) $\quad\left(\eta \mid T_{J}^{3}\right)^{-1}\left(X_{i}^{1}\right)$ is a 1 -sphere $S_{i}^{1} \subset{ }^{0} T_{J}^{3}$ and there exists an annulus $B_{i}^{* 2}$ with boundary curves $S_{i}^{1}$ and $W_{i}^{1}+W_{P i}^{1}$ and with ${ }^{0} B_{i}^{* 2} \subset{ }^{0} T_{J}^{3}$. On the other hand $S_{i}^{1}$ bounds a surface $B_{i}^{2}$ in $J^{3}-\left(W_{i}^{1}+W_{P i}^{1}\right)$ as constructed in the proof of Sec. 11 which can be chosen disjoint from ${ }^{0} B_{i}^{* 2}$. We can bring about by small deformations the situation in which $\eta\left(B_{i}^{2}+B_{i}^{* 2}\right)$ has normal double curves but no branch points (since $\eta$ is locally one-to-one). Therefore (and since $\eta \mid B_{i}^{* 2}$ is one-to-one) $\eta\left(B_{i}^{2}\right)$ intersects the boundary curve $W_{\ngtr i}^{1}+W_{P i}^{1}$ of $\eta\left(B_{i}^{2}+B_{i}^{* 2}\right)$ in an even number of piercing points. From $\eta\left(B_{i}^{2}\right)$ we obtain, as in (1), a 2-polyhedron disjoint from $W_{* i}^{1}+W_{P i}^{1}$ with boundary $X_{i}^{1}$.

If $w_{i} \neq 0$ (for some $i=1, \cdots, r$ ) then we choose a point in ${ }^{0} W_{\nless i}^{1}$, which is no double point of $\vartheta_{I}\left(W^{\prime 2}\right)$, and a neighborhood $R_{i}^{3}$ of this point in $N_{i}^{3}$ which is small with respect to $\vartheta_{I}\left(W^{\prime 2}\right) \mid W_{* i}^{1}$. We denote the disk $R_{i}^{3} \cap \vartheta_{I}\left(W^{\prime 2}\right)$ by $W_{R i}^{2}$. In ${ }^{0} R_{i}^{3}$ we choose a disk $R_{i}^{2}\left(\right.$ see Fig. 8) such that $\cdot R_{i}^{2} \cap W_{\# i}^{1}$ is one arc $R_{i}^{1}$, such that ${ }^{0} R_{i}^{2} \cap^{0} W_{\mathrm{R} i}^{2}$ is an open arc one of whose boundary points lies in $\cdot R_{i}^{2}-R_{i}^{1}$ and the other one in $W_{R i}^{1}-R_{i}^{1}$, and such that $-\left[\cdot\left(W_{R i}^{2}+R_{i}^{2}\right) \cap{ }^{0} R_{i}^{3}\right]$ is an unknotted chord in $R_{i}^{3}$. Then we choose an epi-homeomorphism

$$
\lambda_{i}: R_{i}^{3} \rightarrow R_{i}^{3}
$$

with $\lambda_{i} \mid \cdot R_{i}^{3}=$ identity and $\lambda\left(-\left[\cdot\left(W_{R i}^{2}+R_{i}^{2}\right) \cap{ }^{0} R_{i}^{3}\right]\right)=W_{\# i}^{1} \cap R_{i}^{3}$ and a map

$$
\vartheta_{I I}: W^{\prime 2} \rightarrow H^{3}
$$

with

$$
\left.\vartheta_{I I}\right|^{-}\left[W^{\prime 2}-\vartheta_{I}^{-1}\left(W_{R i}^{2}\right)\right]=\left.\vartheta_{I}\right|^{-}\left[W^{\prime 2}-\vartheta_{I}^{-1}\left(W_{R i}^{2}\right)\right]
$$

and

$$
\vartheta_{I I}\left(\vartheta_{I}^{-1}\left(W_{\mathbf{R} i}^{2}\right)\right)=\lambda_{i}\left(W_{R i}^{2}+R_{i}^{2}\right) .
$$

Now let $N_{I I i}^{3}$ be a neighborhood of $W_{\nless i}^{1}+W_{P i}^{1}$ in $N_{i}^{3}$, being small with respect to $\vartheta_{I I}\left(W^{\prime 2}\right) \mid T_{\neq J}^{3}$. Then ${ }^{0} N_{I I i}^{3} \cap \vartheta_{I I}\left(W^{\prime 2}\right)$ consists of a 1 -sphere $N_{I I i}^{1}$, topologically parallel to $W_{\# i}^{1}+W_{P i}^{1}$, and of $n_{i}+2$ meridian circles of $N_{I I i}^{3}$. The homology class $\mathfrak{n}_{I I i}$ of the properly oriented $N_{I I i}^{1}$ in $N_{i}^{3}-{ }^{0} N_{I I i}^{3}$ is

$$
\mathfrak{n}_{I I i}=\mathfrak{x}_{I I i}+\left(w_{i} \pm 2\right) \mathfrak{y}_{I I i}
$$

with $\mathfrak{r}_{I I i}, \mathfrak{y}_{I I i}$ the homology classes of $X_{i}^{1}, Y_{i}^{1}$, respectively, in $N_{i}^{3}-{ }^{0} N_{I I i}^{3}$. The sign in the coefficient $w_{i} \pm 2$ depends on the choice of $R_{i}^{2}$ (see Fig. 8). So we can derive by $\frac{1}{2} \sum_{i=1}^{r} w_{i}$ operations of the kind described a map

$$
\vartheta_{*}: W^{\prime 2} \rightarrow H^{3}
$$

such that (under analogous notation) the curve $N_{* i}^{1}$ is homologous to $X_{* i}^{1}$ in $N_{i}^{3}-{ }^{0} N_{* i}^{3}($ for all $i=1, \cdots, r)$.

If $w_{i}=0$ (for all $\left.i=1, \cdots, r\right)$ then we choose $\vartheta_{*}=\vartheta_{I}$, etc.
Step 3. From $\vartheta_{*}$ we can obtain by deformations (that change $\vartheta_{*}\left(W^{\prime 2}\right)$ only in the $N_{* i}^{3}$ 's) a map $\vartheta: W^{\prime 2} \rightarrow H^{3}$ with the demanded properties (i), (ii), (iii).
13. Deformation over prismatic neighborhoods of the singular disks $W_{\# i}^{2}$. The map $\vartheta$ can be extended to a map $\tilde{\vartheta}: W^{\prime 3} \rightarrow H^{3}$, with $\tilde{\vartheta}\left(W^{\prime 3}\right) \subset{ }^{0} H^{3}$ denoted by $W_{*}^{3}$, such that (see Fig. 9) the following hold:
(i) $W^{\prime 3}$ may be represented as cartesian product $W^{\prime 2} \times I_{*}^{1}$ where $I_{*}^{3}$ means an interval $-1 \leqq x_{*} \leqq 1$, with $p \times 0=p$ for all $p \epsilon W^{\prime 2}$, and $W^{\prime 3}$ is disjoint from $M^{3},{F^{\prime 2}}^{2}, V^{\prime 2}$. We denote the components $W_{i}^{\prime 2} \times I^{1}$ of $W^{\prime 3}$ by $W_{i}^{\prime 3}$.
(ii) $W_{i}^{\prime 3} \cap F_{i}^{\prime 3}=\cdot W_{i}^{\prime 3} \cap \cdot F_{i}^{\prime 3}=W_{i}^{\prime 1} \times I_{*}^{1}$ with

$$
\tilde{\vartheta}\left|\left(\cdot W_{i}^{\prime 3} \cap \cdot F_{i}^{\prime 3}\right)=\beta_{I}\right|\left(\cdot W_{i}^{\prime 3} \cap \cdot F_{i}^{\prime 3}\right)
$$

(iii) $W_{*}^{3}$ and the $P_{* i}^{3}$ 's intersect each other prismatically, i.e.:

$$
\eta^{-1}\left(W_{\#}^{3} \cap P_{\# i}^{3}\right)=\left\{\left[\eta^{-1}\left(W_{\#}^{3} \cap P_{\# i}^{3}\right)\right] \cap P_{i}^{2}\right\} \times I^{1}
$$

and

$$
\tilde{\vartheta}^{-1}\left(W_{\#}^{3} \cap P_{* i}^{3}\right)=\left\{\left[\tilde{\vartheta}^{-1}\left(W_{*}^{3} \cap P_{\# i}^{3}\right)\right] \cap W^{2}\right\} \times I_{*}^{1}
$$

(using the product representations introduced in Sec. 8 and in (i), respectively).
(iv) If $p$ is a point of $W_{*}^{3}, \vartheta^{-1}(p)$ is either one or two points. The set $B$ of all double points of $W_{*}^{3}$ is disjoint from the disks $\tilde{\vartheta}\left(W_{P i}^{\prime 1} \times I_{*}^{1}\right)(i=1, \cdots, r)$ and is prismatic, i.e.

$$
\tilde{\vartheta}^{-1}(B)=\left[\tilde{\vartheta}^{-1}(B) \cap W^{\prime 2}\right] \times I_{*}^{1},
$$

(using the same product representation as in (i)).
We denote the 3 -annulus $F_{I}^{\prime 3}+W^{\prime 3}$ by $F_{I I}^{\prime 3}$ and we define a map

$$
\beta_{I I}: F_{I I}^{\prime 3} \rightarrow M_{*}^{3}
$$

such that $\beta_{I I}\left|F_{I}^{\prime 3}=\beta_{I}\right| F_{I}^{\prime 3}$ and $\beta_{I I} \mid W^{\prime 3}=\tilde{\vartheta}$.
14. Deformation over the prisms $P_{* i}^{3}$. In $F_{I I}^{\prime 3}-S^{\prime 2}$ there are $2 r$ pairwise disjoint disks $P_{+i}^{\prime 2}, P_{-i}^{\prime 2}(i=1, \cdots, r)$ mapping onto the top and bottom disks of the $P_{\# i}^{3}$ 's, i.e. such that $\beta_{I I}\left(P_{ \pm i}^{\prime 2}\right)=\eta\left(P_{i}^{2} \times \pm 1\right)$. Now we choose $r$ pairwise disjoint 3 -cells $P_{1}^{\prime 3}, \cdots, P_{r}^{\prime 3}$, disjoint from $M^{3}, F^{\prime 2}, V^{\prime 2}$, such that

$$
P_{i}^{\prime 3} \cap F_{I I}^{\prime 3}=\cdot P_{i}^{\prime 3} \cap \cdot F_{I I}^{\prime 3}=P_{+i}^{\prime 2}+P_{-i}^{\prime 2}+\left(W_{P i}^{\prime 1} \times I_{*}^{1}\right)
$$

(being a disk, for all $i=1, \cdots, r$ ); and we choose epi-homeomorphisms

$$
\varkappa_{i}: P_{i}^{\prime 3} \rightarrow P_{i}^{3}
$$

such that $\eta_{i} \cdot \varkappa_{i}\left|\left(\cdot P_{i}^{\prime 3} \cap \cdot F_{I I}^{\prime 3}\right)=\beta_{I I}\right|\left(\cdot P_{i}^{\prime 3} \cap \cdot F_{I I}^{\prime 3}\right)$. Finally we denote the 3 -annulus $F_{I I}^{\prime 3}+\bigcup_{i=1}^{r} P_{i}^{\prime 3}$ by $F^{\prime 3}$ and we define a map

$$
\beta: F^{\prime 3} \rightarrow M_{*}^{3}
$$

such that $\beta \mid F_{I I}^{\prime 3}=\beta_{I I}$ and $\beta \mid P_{i}^{\prime 3}=\eta_{i} \cdot \varkappa_{i}$.
We denote the handlebody $H^{3}+\mathrm{U}_{j=1}^{s} A_{j}^{3}$ by $K^{3}$ and $\beta^{-1}\left(K^{3} \cap \beta\left(F^{\prime 3}\right)\right)$ by $K^{\prime 3}$. We remark that $\beta\left(\cdot F^{\prime 3}-S^{\prime 2}\right) \subset{ }^{0} H^{3}$ and that

$$
\left.\beta\right|^{-}\left(F^{\prime 3}-K^{\prime 3}\right):^{-}\left(F^{\prime 3}-K^{\prime 3}\right) \rightarrow^{-}\left(M_{*}^{3}-K^{3}\right)
$$

is an epi-homeomorphism. Moreover $\beta$ is locally one-to-one, except on the $s$ surfaces ${ }^{-}\left(\cdot O_{j}^{\prime 3} \cap^{0} F^{\prime 3}\right)$; it is locally three-to-one on the $\operatorname{arcs}^{-}\left(\cdot O_{j}^{\prime 2} \cap^{0} F^{\prime 3}\right)$ and locally two-to-one otherwise on ${ }^{-}\left(\cdot O_{j}^{\prime 3} \cap^{0} F^{\prime 3}\right)$.
15. Conclusion. There can be found an epi-homeomorphism $\lambda: M^{3} \rightarrow M^{3}$ such that the image $C_{0}^{3}=\lambda\left(C^{1}\right)$ of the given curve $C^{1}$ lies in ${ }^{0} M_{*}^{3}-K^{3}$. Then we choose a knot projection cone $D^{\prime 2} \subset F^{\prime 3}$ with $\cdot D^{\prime 2}=\beta^{-1}\left(C_{0}^{1}\right)$. We can choose $D^{\prime 2}$ such that $\beta \mid D^{\prime 2}$ is locally one-to-one. Further we can bring about by small deformations the situation in which the singularities of the image $\beta\left(D^{\prime 2}\right)$ are normal. Then $D^{2}=\lambda^{-1}\left(\beta\left(D^{\prime 2}\right)\right)$ possesses the demanded properties. This proves Theorem 2.

We choose two disjoint 3 -cells $C^{\prime 3}, C^{\prime \prime 3}$ with

$$
C^{\prime 3} \cap F^{\prime 3}={S^{\prime 2}}^{2}=C^{\prime 3}, \quad C^{\prime \prime 3} \cap F^{\prime 3}=\cdot F^{\prime 3}-S^{\prime 2}=\cdot C^{\prime 3},
$$

an epi-homeomorphism

$$
\beta^{\prime}: C^{\prime 3} \rightarrow C^{3}
$$

with $\beta^{\prime}\left|{S^{\prime}}^{2}=\beta\right|{S^{\prime}}^{2}$, and a map

$$
\beta^{\prime \prime}: C^{\prime \prime 3} \rightarrow H^{3}
$$

with $\beta^{\prime \prime}\left|\left(\cdot F^{\prime 3}-S^{\prime 2}\right)=\beta\right|\left(\cdot F^{\prime 3}-S^{\prime 2}\right)$. Then $F^{\prime 3}+C^{\prime 3}+C^{\prime \prime 3}$ is a 3 -sphere $S^{3}$ and the map $\gamma: S^{3} \rightarrow M^{3}$, composed of $\beta, \beta^{\prime}, \beta^{\prime \prime}$, has the demanded properties. This proves Theorem 1.

## II. Proof of Theorem 3

We bring about (by isotopic deformations) the situation in which the 2 -sphere $J^{3}=\beta_{0}\left(F_{0}^{\prime 2}\right)$ (see Sec. 8 ) is equal to the image $F_{0}^{2}=\alpha_{0}\left(F^{\prime 2}\right)$ under the given
embedding $\alpha_{0}$. We denote the 2 -spheres

$$
\cdot F_{I}^{\prime 3}-S^{\prime 2}, \quad \cdot F_{I I}^{\prime 3}-S^{\prime 2}, \quad \cdot F^{\prime 3}-S^{2}
$$

by $F_{I}^{\prime 2}, F_{I I}^{\prime 2}, F_{I I I}^{\prime 2}$, respectively, and we choose epi-homeomorphisms $\mu_{0}, \mu_{I}$, $\mu_{I I}, \mu_{I I I}$ of $F^{\prime 2}$ onto $F_{0}^{\prime 2}, F_{I}^{\prime 2}, F_{I I}^{\prime 2}, F_{I I I}^{\prime 2}$, respectively, such that $\alpha_{0}=\left(\beta_{0} \mid F_{0}^{\prime 2}\right) \cdot \mu_{0}$ and

$$
\mu_{[i]}^{-1}\left|\left(F_{[i]}^{\prime 2} \cap F_{[i-1]}^{\prime 2}\right)=\mu_{[i-1]}^{-1}\right|\left(F_{[i]}^{\prime 2} \cap F_{[i-1]}^{\prime 2}\right) \quad(\text { for }[i]=I, I I, I I I)
$$

We denote the maps

$$
\left(\beta_{I} \mid F_{I}^{\prime 2}\right) \cdot \mu_{I}, \quad\left(\beta_{I I} \mid F_{I I}^{\prime 2}\right) \cdot \mu_{I I}, \quad\left(\beta \mid F_{I I I}^{\prime 2}\right) \cdot \mu_{I I I}
$$

defining singular 2 -spheres in $M_{*}^{3}$, by $\alpha_{I}, \alpha_{I I}, \alpha_{3}$, respectively. Now $\alpha_{3}$ fulfills already the condition (b) of Theorem 3, and it remains to show that the deformation from $\alpha_{0}$ to $\alpha_{3}$, which may be derived from the proof of Theorem 1, 2 , can be decomposed into a sequence of elementary deformations, according to condition (a).
16. Decomposing the deformations in the $A_{j}^{33}$ s. The deformation from $\alpha_{0}$ to $\alpha_{I}$, changing the 2 -sphere $F_{0}^{2}$ in the $A_{j}^{3}$ 's (see Sec. 9), can be decomposed into a sequence of $\sum_{j=1}^{s} t_{j} \cdot\left(u_{j}+2 v_{j}\right)$ elementary deformations of type 1a, intermixed with nonessential deformations, (see Fig. 5).

We denote the connected components of the (prismatic) intersections

$$
\eta\left(K_{j k}^{3}\right) \cap L_{j l}^{3} \quad\left(j=1, \cdots, s ; k=1, \cdots, t_{j} ; l=1, \cdots, u_{j}\right)
$$

under current enumeration by $C_{1}^{3}, \cdots, C_{c}^{3}$ and the connected components of

$$
\eta\left(K_{j k}^{3}\right) \cap N_{j m}^{3} \quad\left(m=1, \cdots, v_{j}\right)
$$

by $D_{1}^{3}, \cdots, D_{d}^{3}$. Further we denote that connected component of $\eta^{-1}\left(C_{g}^{3}\right)$ ( $g=1, \cdots, c$ ) that is different from $C_{g}^{3}$ by $C_{g}^{\prime 3}$, and that connected component of $\eta^{-1}\left(D_{h}^{3}\right)(h=1, \cdots, d)$ that is different from $D_{h}^{3}$ by $D_{h}^{\prime 3}$. Finally we denote the intersections of the $C_{g}^{3}, C_{g}^{\prime 3}, D_{h}^{3}, D_{h}^{\prime 3}$ s s with the $P_{i}^{2}$, (see Fig. 11a) by $C_{g}^{2}, C_{g}^{\prime 2}$, $D_{h}^{2}, D_{h}^{2}{ }_{h}$, respectively, and the intersections of the $K_{j k}^{3}, L_{j l}^{3}$ 's with the $P_{i}^{2}$ 's by $K_{P j k}^{2}, L_{P j l}^{2}$, respectively.
17. Decomposing the deformations over $W_{*}^{3}$. We can bring about by small deformations the situation in which the singular dises $W_{* i}^{2}$ and their prismatic neighbourhood $W_{*}^{3}$ (as constructed in Secs. 11, 12, 13) are in a "normal position" with respect to the singular 2 -sphere $F_{I}^{2}=\alpha_{I}\left(F^{\prime 2}\right)$ and to the singular disks $P_{\# i}^{2}$, etc., i.e. such that the following conditions hold:
(i) $F_{I}^{2}, H^{3}$, the $A_{j}^{3}$ 's, and the $P_{\# i}^{2}$ 's intersect $W_{*}^{3}$ prismatically with respect to the product representation introduced in Sec. 13.

We denote $\widetilde{\vartheta}\left(\vartheta^{-1}\left(p_{i}\right) \times I_{*}^{1}\right)$ by $P_{i}^{1}$ (Fig. 9$)$.
(ii) $\eta^{-1}\left(W_{*}^{2} \cap P_{\# i}^{2}\right)(i=1, \cdots, r)$ is disjoint from those connected components of $K_{P j k}^{2} \cap \eta^{-1}\left(H^{3} \cap P_{\# i}^{3}\right)$ and $L_{P j l}^{2} \cap \eta^{-1}\left(H^{3} \cap P_{\# i}^{3}\right)(j=1, \cdots, s$;
$\left.k=1, \cdots, t_{j} ; l=1, \cdots, u_{j}\right)$ that contain the $\operatorname{arcs} \cdot K_{P j k}^{2} \cap \cdot P_{i}^{2}, L_{P j l}^{2} \cap \cdot P_{i}^{2}$, respectively, in their boundaries (see Fig. 11a).

Now we carry out the deformation of $\alpha_{I}$ into $\alpha_{I I}$ in three steps:
Step 1. Let $B_{f}^{\prime 3}(f=1, \cdots, b)$ (see Fig. 10) be that connected component of $\widetilde{\vartheta}^{-1}\left(B^{3}\right)$ that contains $B_{f}^{\prime 1}$. We choose pairwise disjoint neighborhoods $B_{*_{f}^{\prime}}^{\prime 3}$ of the $B_{f}^{\prime 3}$ 's in $W^{\prime 3}$, which are small with respect to $\tilde{\vartheta}^{-1}\left(F_{I}^{2} \cap W_{\#}^{3}\right) \mid \tilde{\vartheta}^{-1}\left(B^{3}\right)$ and which are cartesian products in the product representation introduced in Sec. 13. Now we deform $F_{I}^{2}$ over the 3 -cells $\tilde{\vartheta}\left(B_{* f}^{\prime 3}\right)$ which can be done by a sequence of elementary deformations of type 1a. We denote the map so obtained from $\alpha_{I}$ by $\alpha_{I *}$ and ${ }^{-}\left(W^{\prime 2}-\bigcup_{f=1}^{b} B_{* f}^{\prime 3}\right)$ by $W_{*}^{\prime 2}$. Now we have to deform $F_{I *}^{2}=\alpha_{I *}\left(F^{\prime 2}\right)$ over the remaining nonsingular 3-cells $\tilde{\vartheta}\left(W_{*}^{\prime 2} \times I_{*}^{1}\right)$.

Step 2. In $W_{*}^{\prime 2}$ we choose pairwise disjoint $\operatorname{arcs} X_{1}^{1}, \cdots, X_{x}^{1}$ (see Fig. 10) with ${ }^{0} X_{m}^{1} \subset{ }^{0} W_{*}^{\prime 2}$ that join points of

$$
\cdot W_{*}^{\prime 2}-\bigcup_{i=1}^{r} W_{P i}^{\prime 1}
$$

to points of

$$
\vartheta^{-1}\left(F_{I *}^{2} \cap W_{\#}^{2}\right) \cap{ }^{0} W_{*}^{\prime 2}
$$

such that
(a) every double point of $\vartheta^{-1}\left(F_{I *}^{2} \cap W_{*}^{2}\right) \cap^{0} W_{*}^{\prime 2}$ is end point of one arc $X_{m}^{1}$,
(b) every connected component of $\vartheta^{-1}\left(F_{I *}^{2} \cap W_{*}^{2}\right) \cap^{0} W_{*}^{\prime 2}$ contains at least one end point of an arc $X_{m}^{1}$,
(c) the $X_{m}^{1}$ s intersect $\vartheta^{-1}\left(F_{I *}^{\gamma} \cap W_{*}^{2}\right) \cap^{0} W_{*}^{\prime 2}$ in isolated piercing points that are no double points of $\vartheta^{-1}\left(F_{I *}^{2} \cap W_{\#}^{2}\right) \cap^{0} W_{*}^{\prime 2}$,
(d) the points $\vartheta\left(\cdot X_{m}^{1} \cap \cdot W_{*}^{\prime 2}\right)$ are no double points of $F_{I *}^{2}$.

Now we choose pairwise disjoint neighborhoods $X_{m}^{2}$ of the $X_{m}^{1}$ 's in $W_{*}^{\prime 2}$, which are small with respect to $\vartheta^{-1}\left(F_{I *}^{2} \cap W_{*}^{2}\right)$. Then we deform $F_{I *}^{2}$ over the 3 -cells $\tilde{\vartheta}\left(X_{m}^{2} \times I_{*}^{1}\right)$ which can be done by a sequence of elementary deformations of type 1a and 1 b . According to the notation used in Theorem 3 we denote the map so obtained from $\alpha_{I *}$ by $\alpha_{1}$ and $\alpha_{1}\left(F^{\prime 2}\right)$ by $F_{1}^{2}$. Further we denote ${ }^{-}\left(W_{*}^{\prime 2}-\bigcup_{m=1}^{x} X_{m}^{2}\right)$ by $W_{* *}^{\prime 2}$.

Step 3. Finally we deform $F_{1}^{2}$ over the remaining 3-cells $\widetilde{\vartheta}\left(W_{* *}^{\prime 2} \times I_{*}^{1}\right)$. This can be done by a sequence of elementary deformations of type 2 (and may be nonessential deformations) since the curves $\vartheta^{-1}\left(F_{1}^{2} \cap W_{*}^{2}\right) n^{0} W_{* *}^{\prime 2}$ are nonsingular, pairwise disjoint, open arcs with boundary points in

$$
\cdot W_{* *}^{\prime 2}-\bigcup_{i=1}^{r} W_{P i}^{\prime 1}
$$

By this we obtain from $\alpha_{1}$ the map $\alpha_{I I}$.
18. Decomposing the deformations over the $P_{* i}^{3}$ 's. We carry out the deformation of $\alpha_{I I}$ into $\alpha_{3}$ in four steps (see Fig. 11).

Step 1. Let $Q_{i}^{1}$ be a neighborhood of a point $\epsilon \cdot P_{i}^{1}$ in $\cdot P_{i}^{2}-{ }^{0} P_{i}^{1}$ which is small
with respect to $\eta^{-1}\left(F_{1 I}^{2} \cap P_{\nless i}^{2}\right)$ and let $Y_{i}^{1}=\cdot P_{i}^{2}-{ }^{0} Q_{i}^{1}$. Further we choose a neighborhood $Y_{i}^{2}$ of $Y_{i}^{1}$ in $P_{i}^{2}$, which is small with respect to

$$
\eta^{-1}\left(H^{3} \cap P_{\# i}^{2}\right)\left|\eta^{-1}\left(F_{I I}^{2} \cap P_{\# i}^{2}\right)\right| \bigcup_{j, k=1}^{s, t j} K_{P j k}^{2}
$$

and intersecting the disks $C_{g}^{2}, C_{g}^{\prime 2}, D_{h}^{\prime 2}$ prismatically, i.e. such that

$$
\eta^{-1}\left(\eta\left(Y_{i}^{2} \times I^{1}\right)\right)=\left[\eta^{-1}\left(\eta\left(Y_{i}^{2} \times I^{1}\right)\right) \cap P_{i}^{2}\right] \times I^{1}
$$

(using the product representation introduced in Sec. 8). Then we deform $F_{I I}^{3}$ over the 3-cells $\eta\left(Y_{1}^{2} \times I^{1}\right)$ which can be done by a sequence of elementary deformations of type 2 (and may be nonessential deformations). We denote the map so obtained from $\alpha_{I I}$ by $\alpha_{I I *}$, and $\alpha_{I I *}\left({F^{\prime 2}}^{2}\right)$ by $F_{I I *}^{2}$, further ${ }^{-}\left(P_{i}^{2}-Y_{i}^{2}\right)$ by $P_{* i}^{2}$ (see Fig. 11b), the image $\eta\left(P_{* i}^{2}\right)$ by $P_{* * i}^{2}$, and the intersections of $K_{P j k}^{2}, L_{P j l}^{2}$ with the $P_{* i}^{2}$ 's by $K_{* j k}^{2}, L_{* j l}^{2}$, respectively. Further we denote the set of double points of

$$
\eta\left(\bigcup_{i=1}^{r} P_{* i}^{2} \times I^{1}\right)
$$

by $D_{*}$ and the connected components of

$$
\eta^{-1}\left(D_{*}\right) \cap \bigcup_{i=1}^{r} P_{* i}^{2}
$$

by $C_{* g}^{2}, C_{* g}^{\prime 2}, D_{* h}^{2}, D_{* h}^{\prime 2}$ such that
$C_{* g}^{2} \subset C_{g}^{2}, \quad C_{* g}^{\prime 2} \subset C_{g}^{\prime 2}, \quad D_{* h}^{2} \subset D_{h}^{2}$,

$$
D_{* h}^{\prime 2} \subset D_{h}^{\prime} \quad(g=1, \cdots, c ; h=1, \cdots, d)
$$

Step 2. We choose pairwise disjoint $\operatorname{arcs} Y_{i 1}^{1}, \cdots, Y_{i y_{1}}^{1}$ (see Fig. 11b) in $P_{*_{i}}^{2}$ with ${ }^{0} Y_{i f}^{1} \subset{ }^{0} P_{*_{i}}^{2}\left(f=1, \cdots, y_{i}\right)$ that join points of $Y_{1}^{2}$ to points in ${ }^{0} P_{* i}^{2}-\eta^{-1}\left(F_{1 I *}^{2} \cap P_{* * i}^{2}\right)$, and we choose pairwise disjoint neighborhoods $Y_{i f}^{2}$ of the $Y_{i f}^{1}$ 's in $P_{* i}^{2}$, which are small with respect to $\eta^{-1}\left(F_{I I *}^{2} \cap P_{* * i}^{2}\right) \mid \bigcup_{j, k=1}^{s, t}{ }_{j} K_{* j k}^{2}$ such that, with the notation $P_{* * i}^{2}={ }^{-}\left(P_{* i}^{2}-\bigcup_{f=1}^{y_{i}} Y_{i f}^{2}\right)$, the following hold:
(i) The arcs $Y_{i f}^{1}$ intersect the curves ${ }^{-}\left[\eta^{-1}\left(F_{I I *}^{2} \cap P_{* * i}^{2}\right) \cap{ }^{0} P_{* i}^{2}\right]$ in isolated piercing points that are no double points (and no boundary points) of that curves.
(ii) The arcs $Y_{i f}^{1}$ are disjoint from the disks $C_{* g}^{2}, C_{* g}^{\prime 2}, D_{* h}^{2}(g=1, \cdots, c$; $h=1, \cdots, d)$ and from the $\operatorname{arcs}^{-}\left(\cdot K_{* j k}^{2} \cap^{0} P_{* i}^{2}\right)\left(j=1, \cdots, s ; k=1, \cdots, t_{j}\right)$ and intersect the disks $D_{* h}^{\prime 2}$ prismatically, i.e. such that

$$
\eta\left(Y_{i f}^{1} \cap D_{* h}^{\prime 2}\right)=\left[\eta\left(Y_{i f}^{1} \cap D_{* h}^{\prime 2}\right) \cap D_{* h}^{2}\right] \times I^{1}
$$

using the product representation introduced in Sec. 8. The $Y_{i f}^{2}$ 's intersect the $D_{* h}^{\prime 2}$ 's also prismatically.
(iii) If $Z^{1}$ is a connected component of ${ }^{-}\left[\eta^{-1}\left(F_{I I *}^{2} \cap P_{* * i}^{2}\right) \cap^{0} P_{* * i}^{2}\right]$ then one of the following cases holds (see Fig. 12) :
case a. $Z^{1}$ is an arc (that is either disjoint from the disks $C_{* g}^{2}, C_{*_{g}}^{\prime 2}, D_{* h}^{2}$, $D_{* h}^{\prime 2}$ or lies in the boundary of one disk $C_{* g}^{2}, C_{* g}^{\prime 2}$, or $D_{* h}^{\prime 2}$ ).
case b. $Z^{1}$ consists of two arcs, piercing each other in one point, and is disjoint from the disks $C_{* g}^{2}, C_{* g}^{\prime 2}, D_{* h}^{2}, D_{* h}^{\prime 2}$.
case c. $Z^{1}$ consists of two $\operatorname{arcs} Z_{1}^{1}, Z_{2}^{1}$ lying in the boundary of one disk $D_{* h}^{\prime 2}$, and of one arc $Z_{3}^{1}$ that pierces $Z_{1}^{1}$ and $Z_{2}^{1}$ each in one point.
case d. $Z^{1}$ consists of the boundary of one disk $D_{* h}^{2}$ and of an arbitrary number of pairwise disjoint arcs that intersect $D_{* h}^{2}$ each in one arc (and $\cdot D_{* h}^{2}$ each in two points).
Then we deform $F_{I I *}^{2}$ over the 3 -cells $\eta\left(Y_{i f}^{2} \times I^{1}\right)(i=1, \cdots, r$; $f=1, \cdots, y_{i}$ ) which can be done by a sequence of elementary deformations of type 2 (and may be nonessential deformations). According to the notation used in Theorem 3 we denote the map so obtained from $\alpha_{\text {II* }}$ by $\alpha_{2}$ and $\alpha_{2}\left(F^{\prime 2}\right)$ by $F_{2}^{2}$. Further we denote the intersections of the disks $K_{* j k}^{2}$ with the $P_{* * i}^{2}$ 's by $K_{* * j k}^{2}$.

Step 3. Now we deform $F_{2}^{2}$ over the 3-cells $\eta\left(K_{* * j k}^{2} \times I^{1}\right)(j=1, \cdots, s ;$ $k=1, \cdots, t_{j}$ ) which can be done by a sequence of elementary deformations of type 3 a and 3 b and nonessential deformations. We denote the map so obtained from $\alpha_{2}$ by $\alpha_{2 *}$ and $\alpha_{2 *}\left({F^{\prime}}^{2}\right)$ by $F_{2 *}^{2}$.

Step 4. The remaining parts $\eta\left({ }^{-}\left[P_{* * i}^{2}-\bigcup_{j, k=1}^{s, t_{j}} K_{* * j k}^{2}\right] \times I^{1}\right)$ of the $P_{* i}^{3}$ 's are nonsingular 3 -cells, and we can deform $F_{2 *}^{2}$ over them by a sequence of elementary deformations of type 3 a and 3 b (and may be nonessential deformations). By this we obtain from $\alpha_{2 *}$ the map $\alpha_{3}$.
19. Conclusion. The maps $\alpha_{1}$ and $\alpha_{2}$, as obtained in Sec. 17, Step 2, and Sec. 18, Step 2, respectively, and the map $\alpha_{3}$ possess the demanded properties, and Theorem 3 is proved.

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    ${ }^{2}$ Theorem 1 is a consequence of a "monotonic mapping theorem" announced by Moise in [6a]; however the proof is different from Moise' proof.

[^1]:    ${ }^{3}$ We denote the interior of a (tame) point set $X$ by ${ }^{0} X$, the boundary by ${ }^{\circ} X$, and the closure by $\bar{X}$ or ${ }^{-} X$.

[^2]:    ${ }^{4}$ For convenience we shall use the word "deformation" not only for deformations of maps but also for deformations of polyhedra $X \subset M^{3}$ (i.e. for changes of $X$ into $X^{*}$ such that there can be found homotopic maps $\xi, \xi^{*}: X^{\prime} \rightarrow M^{3}$ with $\left.\xi\left(X^{\prime}\right)=X, \xi^{*}\left(X^{\prime}\right)=X^{*}\right)$. This is convenient since a surface with normal singularities, defined by a map

    $$
    \xi: X^{\prime 2} \rightarrow M^{3}
    $$

    is essentially determined by the image polyhedron $\xi\left(X^{\prime 2}\right)$.

