# A refinement of Foreman's four-vertex theorem and its dual version

Gudlaugur Thorbergsson and Masaaki Umehara

**Abstract** A strictly convex curve is a  $C^{\infty}$ -regular simple closed curve whose Euclidean curvature function is positive. Fix a strictly convex curve  $\Gamma$ , and take two distinct tangent lines  $l_1$  and  $l_2$  of  $\Gamma$ . A few years ago, Brendan Foreman proved an interesting four-vertex theorem on semiosculating conics of  $\Gamma$ , which are tangent to  $l_1$  and  $l_2$ , as a corollary of Ghys's theorem on diffeomorphisms of  $S^1$ . In this paper, we prove a refinement of Foreman's result. We then prove a projectively dual version of our refinement, which is a claim about semiosculating conics passing through two fixed points on  $\Gamma$ . We also show that the dual version of Foreman's four-vertex theorem is almost equivalent to the Ghys's theorem.

# 1. Introduction

The well-known four-vertex theorem asserts that for a given convex curve  $\Gamma$  in the Euclidean plane  $\mathbb{R}^2$ , there exist at least four distinct points  $p_1, p_2, p_3, p_4$  on  $\Gamma$  such that the osculating circles  $C_1, C_2, C_3, C_4$  at these four points meet the curve  $\Gamma$  with multiplicity greater than or equal to 4 (cf. [4]). The definition of multiplicity of intersection points (resp., order of contact) of two regular curves is given in [8]. The order of contact is by definition one less than the multiplicity of intersection points.

Moreover, Kneser [3] showed that one can take  $C_1, C_2$  to be inscribed and  $C_3, C_4$  to be circumscribed. (In [3], the assertion is proved for any simple closed regular curve.) Bose [1] improved this by showing that the number of the inscribed osculating circles  $s^+$  (resp., the number of the circumscribed osculating circles  $s^-$ ) satisfies the following so-called *Bose formula* for a given generic convex curve

(1.1) 
$$s^+ - t^+ = 2$$
 (resp.,  $s^- - t^- = 2$ ),

where  $t^+$  (resp.,  $t^-$ ) is the number of inscribed triple tangent circles (resp., the number of circumscribed triple tangent circles). (See Fact 2.1 and [10] for details and its history.) Moreover, the authors proved in [7] that the four points

Received February 20, 2012. Accepted March 22, 2012.

Kyoto Journal of Mathematics, Vol. 52, No. 4 (2012), 743-758

DOI 10.1215/21562261-1728848, © 2012 by Kyoto University

<sup>2010</sup> Mathematics Subject Classification: Primary 53A04, 53A20, 53C75.

Umehara was partially supported by the Grant-in-Aid for Scientific Research (A) No. 22244006 from the Japan Society for the Promotion of Science.

 $p_1, p_2, p_3, p_4$  in Kneser's theorem can be chosen so that

$$(1.2) p_1 \prec p_3 \prec p_2 \prec p_4 (\prec p_1),$$

where  $\prec$  means the cyclic order on  $\Gamma$ . The result in (1.2) also holds for simple closed curves as in the case of (1.1).

A variant of the four-vertex theorem is known for diffeomorphisms of  $S^1(=\mathbf{P}^1)$ : let f be a diffeomorphism of the real projective line  $\mathbf{P}^1$ . Then for each point p there exists a unique projective transformation  $T_p \in \mathrm{PSL}(2, \mathbf{R})$  whose 2-jet at p coincides with that of f. Let us call  $T_p$  the osculating map of f at p. Then the following assertion holds.

# FACT (GHYS'S THEOREM)

For each diffeomorphism f of  $\mathbf{P}^1$ , there exist four distinct points  $p_1, p_2, p_3, p_4$  on  $\mathbf{P}^1$ , where  $T_{p_j}$  has the same 3-jet as f at  $p_j$  for each  $j = 1, \ldots, 4$ . In particular, the Schwarzian derivative of f vanishes at  $p_j$ .

Such a point  $p_j$  is called a *projective point* of f. In [7], the authors showed that one can take these four points  $p_j$  (j = 1, ..., 4) on  $\mathbf{P}^1$  so that each  $f \circ T_{p_j}^{-1}$  has a connected fixed-point set, and they gave refinements of Ghys's theorem along the lines of (1.1) and (1.2). We call such a point  $p_j$  a *clean projective point*. The original four-vertex theorem for convex curves can be proved via Ghys's theorem (see [6]).

Since convexity is invariant under projective transformations, we may assume that a convex curve  $\Gamma$  lies in a certain affine plane  $\mathbf{R}^2 (\subset \mathbf{P}^2)$ . In the projective plane  $\mathbf{P}^2$ , the curve  $\Gamma$  bounds a closed contractible domain  $\overline{D}_{\Gamma}$ , which coincides with the interior domain bounded by  $\Gamma$  in the affine plane  $\mathbf{R}^2$ . Instead of osculating circles, one can consider osculating conics and "sextactic points." For any five distinct points on a strictly convex curve  $\Gamma$ , there exists a unique regular conic  $\omega$  passing through the five points. Letting the five points all converge to p, the conic converges to a uniquely defined regular conic that is called the *osculating* conic of  $\Gamma$  at p. The osculating conic meets  $\Gamma$  with multiplicity at least five in p. If it meets with multiplicity at least six at p, then p is called a *sextactic point*. A strictly convex curve has at least six sextactic points (see [4]). This assertion was improved in [5], where it was shown that three of these sextactic points can be chosen so that the corresponding osculating conics are inscribed and the other three such that the corresponding osculating conics are circumscribed. A modern proof of this formula can be found in [8] and a refinement is given in [9,Theorem 1.2].

We now fix a strictly convex curve  $\Gamma$  and two distinct tangent lines  $l_1$  and  $l_2$  of  $\Gamma$ . Let  $\Omega(l_1, l_2)$  be the set of regular conics which are tangent to both  $l_1$  and  $l_2$ . For each point p on the curve  $\Gamma$ , there is a unique conic  $\omega_p \in \Omega(l_1, l_2)$  which meets  $\Gamma$  at p with multiplicity three. (If p lies on  $l_1$  or  $l_2$ , then the conic  $\omega_p$  should meet  $\Gamma$  at p with multiplicity at least four.) The conic  $\omega_p$  is called the

 $\Omega(l_1, l_2)$ -osculating conic of  $\Gamma$  at p. A point p on the curve  $\Gamma$  is called an  $\Omega(l_1, l_2)$ vertex if  $\omega_p$  hyperosculates at p; that is,  $\omega_p$  meets  $\Gamma$  at p with multiplicity at least four (resp., at least five) if p does not lie on  $l_1$  or  $l_2$  (resp., if p lies on  $l_1$ or  $l_2$ ).

A few years ago, Foreman [2] gave an elegant application of Ghys's theorem which we call in this paper *Foreman's theorem*. It says that *there exist four distinct*  $\Omega(l_1, l_2)$ -*vertices on*  $\Gamma$ . It is interesting because of the following reasons.

(i) The conics  $\omega_{p_i}$  can neither be inscribed nor circumscribed.

(ii) Foreman showed that the convex curve  $\Gamma$  induces a diffeomorphism  $f_{\Gamma}$  on  $\mathbf{P}^1$ , and the four distinct projective points in Ghys's theorem correspond to the desired four points  $p_1, p_2, p_3, p_4$  on  $\Gamma$ . However, even if  $p_j$  is a clean projective point, it is not clear whether or not the conic  $\omega_{p_j}$  has such a global separation property.

We will consider the question of whether Foreman's theorem allows a refinement analogous to the two formulas (1.1) and (1.2). In fact, one can accomplish this as follows. We fix a base point b on  $\Gamma$  that neither lies on  $l_1$  nor on  $l_2$ . The convex curve  $\Gamma$  is divided into two closed arcs by the two lines  $l_1$  and  $l_2$ . We denote by  $\Gamma^+$  (resp.,  $\Gamma^-$ ) the one of these two arcs that passes through b(resp., does not pass through b). We call  $\Gamma^+$  the *future part* and  $\Gamma^-$  the *past part*. We then define two sets  $\Omega^+(l_1, l_2)$  and  $\Omega^-(l_1, l_2)$  as follows: a conic  $\omega \in \Omega(l_1, l_2)$ belongs to  $\Omega^+(l_1, l_2)$  (resp.,  $\Omega^-(l_1, l_2)$ ) if one can divide  $\omega \in \Omega(l_1, l_2)$  into two closed arcs  $\omega^+$  and  $\omega^-$  bounded by  $l_1$  and  $l_2$  such that

$$\Gamma^+ \subset \mathbf{P}^2 \setminus D_\omega, \quad \omega^- \subset \mathbf{P}^2 \setminus D_\Gamma, \qquad (\text{resp.}, \ \Gamma^- \subset \mathbf{P}^2 \setminus D_\omega, \quad \omega^+ \subset \mathbf{P}^2 \setminus D_\Gamma).$$

The sets  $\Omega^+(l_1, l_2)$  and  $\Omega^-(l_1, l_2)$  do not depend on the order of two lines  $l_1, l_2$ , but depend on the base point b. If we put b on  $\Gamma^-$ , then  $\Omega^-(l_1, l_2)$  changes into  $\Omega^+(l_1, l_2)$ . In Figure 1, the curve  $\Gamma$  and the conic  $\omega$  are indicated by a simple closed curve and a circle, respectively. Namely, they are not indicated as the real conic and the convex curve, but instead they are "cartoons" which show more clearly how  $\omega$  meets  $\Gamma$ . We frequently use this kind of figure for the sake of

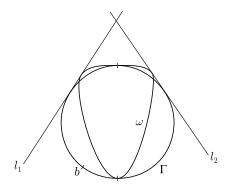


Figure 1. A conic in  $\Omega^+(l_1, l_2)$ 

simplicity. Since the conics belonging to  $\Omega^+(l_1, l_2)$  or  $\Omega^-(l_1, l_2)$  are special, the union of these two subsets is only a proper subset of  $\Omega(l_1, l_2)$ . An  $\Omega(l_1, l_2)$ -vertex p is called a *clean*  $\Omega^+(l_1, l_2)$ -*vertex* (resp., a *clean*  $\Omega^-(l_1, l_2)$ -*vertex*) if  $\omega_p$  belongs to  $\Omega^+(l_1, l_2)$  (resp.,  $\Omega^-(l_1, l_2)$ ) and the intersection  $\omega_p \cap \Gamma$  is a connected closed subset of  $\Gamma$ . The following result is our refinement of Foreman's theorem.

# THEOREM 1.1

Let  $l_1$  and  $l_2$  be two distinct tangent lines of a strictly convex curve  $\Gamma$ . There exist four distinct points  $p_1, p_2, p_3, p_4$  on  $\Gamma$  satisfying  $p_1 \prec p_2 \prec p_3 \prec p_4$  and the following properties:

- (1)  $p_i$  is a clean  $\Omega^+(l_1, l_2)$ -vertex for i = 1, 3;
- (2)  $p_j$  is a clean  $\Omega^-(l_1, l_2)$ -vertex for j = 2, 4.

Moreover, an analogue of the formula (1.1) holds.

This theorem is proved in Section 1 by using the intrinsic circle systems introduced in [10] and [7].

The real projective plane  $\mathbf{P}^2$  has its dual projective plane  $\mathbf{P}^2_*$ . Under this duality, lines in  $\mathbf{P}^2$  correspond to points in  $\mathbf{P}^2_*$ . A strictly convex curve  $\Gamma$  in  $\mathbf{P}^2$  has a (unique) dual curve  $\Gamma^*$  in  $\mathbf{P}^2_*$  which is also strictly convex. Then two distinct tangent lines  $l_1$  and  $l_2$  to  $\Gamma$  correspond to two distinct points  $o_1$  and  $o_2$  on  $\Gamma^*$ . The dual version of Foreman's four-vertex theorem is then as follows. Take two distinct points  $o_1$  and  $o_2$  on  $\Gamma$ . Let  $\Omega(o_1, o_2)$  be the set of regular conics passing through both  $o_1$  and  $o_2$ . For each point p on  $\Gamma$ , we define the  $\Omega(o_1, o_2)$ osculating conic at p as in the case of  $\Omega(\ell_1, \ell_2)$ . (If p coincides with  $o_1$  or  $o_2$ , then the conic  $\omega_p$  should meet  $\Gamma$  at p with multiplicity at least four.) A point p on the curve  $\Gamma$  is called an  $\Omega(o_1, o_2)$ -vertex if the  $\Omega(o_1, o_2)$ -osculating conic hyperosculates at p.

We now fix a base point b such that  $b \neq o_i$  (i = 1, 2). The convex curve  $\Gamma$  is divided into two closed arcs by  $o_1, o_2$ . We denote by  $\Gamma^+$  (resp.,  $\Gamma^-$ ) the one of these two arcs that passes through b (resp., does not pass through b). We call  $\Gamma^+$  the *future part* and  $\Gamma^-$  the *past part*. We define two subsets  $\Omega^+(o_1, o_2)$  and  $\Omega^-(o_1, o_2)$  as follows. A conic  $\omega \in \Omega(o_1, o_2)$  belongs to  $\Omega^+(o_1, o_2)$  (resp.,  $\Omega^-(o_1, o_2)$ ) if one can divide  $\omega \in \Omega(o_1, o_2)$  into two closed arcs  $\omega^+$  and  $\omega^-$  bounded by  $o_1$  and  $o_2$  such that (see Figure 2)

$$\Gamma^+ \subset \mathbf{P}^2 \setminus D_\omega, \quad \omega^- \subset \mathbf{P}^2 \setminus D_\Gamma, \qquad (\text{resp.}, \ \Gamma^- \subset \mathbf{P}^2 \setminus D_\omega, \quad \omega^+ \subset \mathbf{P}^2 \setminus D_\Gamma).$$

By definition,  $\Omega^{\pm}(o_1, o_2)$  does not depend on the order of  $o_1, o_2$ . However, if we put the base point b on  $\Gamma^-$ , then  $\Omega^+(o_1, o_2)$  changes into  $\Omega^-(o_1, o_2)$ .

An  $\Omega(o_1, o_2)$ -vertex p is called a *clean*  $\Omega^+(o_1, o_2)$ -vertex (resp., a *clean*  $\Omega^-(o_1, o_2)$ -vertex) if the  $\Omega(o_1, o_2)$ -osculating conic  $\omega_p$  belongs to  $\Omega^+(o_1, o_2)$  (resp.,  $\Omega^-(o_1, o_2)$ ) and the intersection  $\omega_p \cap \Gamma$  is a connected closed subset of  $\Gamma$ . The following is the dual version of Theorem 1.1.

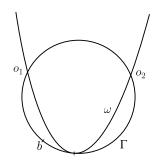


Figure 2. A conic in  $\Omega^+(o_1, o_2)$ 

## THEOREM 1.2

There exist four distinct points  $p_1, p_2, p_3, p_4$  on  $\Gamma$  satisfying  $p_1 \prec p_2 \prec p_3 \prec p_4$  and the following properties:

- (1)  $p_i$  is a clean  $\Omega^+(o_1, o_2)$ -vertex for i = 1, 3;
- (2)  $p_j$  is a clean  $\Omega^-(o_1, o_2)$ -vertex for j = 2, 4.

Moreover, an analogue of (1.1) holds. In particular, there exist four distinct  $\Omega(o_1, o_2)$ -vertices on  $\Gamma$ .

In Section 3, we show that the set of  $\Omega(o_1, o_2)$ -vertices on  $\Gamma^*$  corresponds under the duality exactly to the set of  $\Omega(l_1, l_2)$ -vertices on  $\Gamma$ , which proves the last assertion of the theorem. However, to prove all assertions of Theorem 1.2, we cannot use duality, since clean  $\Omega(l_1, l_2)$ -vertices on  $\Gamma$  might not correspond to clean  $\Omega(o_1, o_2)$ -vertices on  $\Gamma^*$  in general. We give two distinct proofs: one uses a method similar to the one in the proof of Theorem 1.1, and the other is an application of the refinement of Ghys's theorem given in [7], whereas Theorem 1.1 does not follow directly from it.

In Section 4, we also consider the case that l is a tangent line and o is a point on a strictly convex curve  $\Gamma$ . We get similar results on  $\Omega(l, o)$ -vertices as in the case of  $\Omega(l_1, l_2)$  and  $\Omega(o_1, o_2)$ .

## 2. Proof of Theorem 1.1

Before giving a proof of Theorem 1.1, we recall fundamental properties of intrinsic circle systems: we denote by  $\prec$  the cyclic order of  $S^1$ . A family of nonempty closed subsets  $F = \{F_p\}_{p \in S^1}$  is called an *intrinsic circle system* on  $S^1$  if it satisfies the following three conditions:

- $({\rm I1}) \ p \in F_p \ {\rm for \ each} \ p \in S^1. \ {\rm If} \ q \in F_p, \ {\rm then} \ F_p = F_q; \\$
- (I2) If  $p' \in F_p$ ,  $q' \in F_q$  and  $p \prec q \prec p' \prec q'$ , then  $F_p = F_q$  holds;

(I3) Let  $\{p_n\}$  and  $\{q_n\}$  be two sequences in  $S^1$  converging to p and q in  $S^1$ , respectively. Suppose that  $q_n \in F_{p_n}$  for each  $n = 1, 2, 3, \ldots$  Then  $q \in F_p$  holds.

We call  $F_p$  the *intrinsic* F-circle at p. Fix an intrinsic circle system F. We indicate by  $p \sim q$  that  $F_p = F_q$  holds. It is clear that  $\sim$  is an equivalence relation

on  $S^1$ . We denote by [p] the equivalence class of p, and we denote by r([p]) the number of connected components of  $F_p$  which does not depend on the choice of p. A point  $p \in S^1$  is called an F-vertex if r([p]) = 1. Set

$$S:=\big\{[p]\in F/\sim; r([p])=1\big\}, \qquad T:=\big\{[p]\in F/\sim; r([p])\geq 3\big\},$$

and

(2.1) 
$$s := \sum_{[p] \in S} r(p), \qquad t := \sum_{[p] \in T} (r(p) - 2).$$

Then the following assertion is proved in [10, Theorem 2.7].

#### FACT 2.1 (THE ABSTRACT BOSE FORMULA)

If s is finite, then so is t. Moreover the identity s - t = 2 holds.

If we let  $C_p$  denote a maximal inscribed circle tangent to a given convex curve  $\Gamma$  at a point p, then the family of subsets of  $S^1 := \Gamma$  defined by  $F_p := C_p \cap \Gamma$  for  $p \in S^1$  is a typical example of an intrinsic circle system. In this case, F-vertices are clean; that is, the osculating circles are inscribed at F-vertices.

A pair of intrinsic circle systems  $(F^+, F^-)$  on  $S^1$  is called *compatible* if an  $F^+$ -vertex (resp.,  $F^-$ -vertex) is never an  $F^-$ -vertex (resp.,  $F^+$ -vertex), and  $F^+$ -vertices (resp.,  $F^-$ -vertices) cannot accumulate to an  $F^-$ -vertex (resp., an  $F^+$ -vertex). The following assertion holds (see [7]).

#### FACT 2.2 (THE THEOREM OF FOUR SIGN CHANGES OF CLEAN VERTICES)

Let  $(F^+, F^-)$  be a compatible pair of intrinsic circle systems on  $S^1$ . Then there exist four points  $p_1, p_2, p_3, p_4$  on  $S^1$  satisfying (1.2) so that  $p_1, p_3$  are  $F^+$ -vertices and  $p_2, p_4$  are  $F^-$ -vertices.

In [7], the refinements of the four-vertex theorem for plane curves and Ghys's theorem are both proved by constructing compatible pairs of intrinsic circle systems.

Let  $l_1$  and  $l_2$  be two distinct tangent lines on  $\Gamma$ . To prove Theorem 1.1, it is sufficient to construct a compatible pair of intrinsic circle systems  $(F^+, F^-)$ after identifying  $S^1$  with  $\Gamma$ . For this purpose, we will prove the following.

## **PROPOSITION 2.3**

For each p on  $\Gamma$ , there exists a unique conic  $\omega_p^1$  in  $\Omega^+(l_1, l_2)$  (resp.,  $\omega_p^2$  in  $\Omega^-(l_1, l_2)$ ) such that

- (1)  $\omega_p^1$  (resp.,  $\omega_p^2$ ) is the  $\Omega(l_1, l_2)$ -osculating conic at p, or
- (2)  $\{p\}$  is a proper subset of  $F_p^+$  (resp.,  $F_p^-$ ), where

$$\begin{split} F_p^+ &:= \left( (\omega_p^1)^+ \cap \Gamma^+ \right) \cup \left( (\omega_p^1)^- \cap \Gamma^- \right), \\ F_p^- &:= \left( (\omega_p^2)^+ \cap \Gamma^+ \right) \cup \left( (\omega_p^2)^- \cap \Gamma^- \right). \end{split}$$

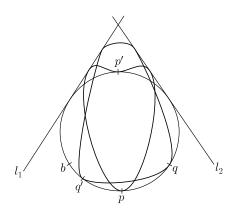


Figure 3. A typical arrangement

Once the proposition is proved,  $(F^+, F^-)$  gives a compatible pair of intrinsic circle systems on  $\Gamma$ . In fact, if  $F_p^+$  is connected, then  $\omega_p^1$  coincides with the  $\Omega(l_1, l_2)$ -osculating conic at p. Hence,  $F^+$ -vertices (resp.,  $F^-$ -vertices) correspond to clean  $\Omega^+(l_1, l_2)$ -vertices (resp., clean  $\Omega^-(l_1, l_2)$ -vertices). By the uniqueness of  $\omega_p^1$ , the three axioms (I1–I3) and the compatibility condition are all proved using the fact that two conics having more than four common points must coincide.

We have indicated a typical impossible case of two conics in  $\Omega^+(l_1, l_2)$  in Figure 3, where we find six intersections between the two conics. Since the roles of  $\Gamma^+$  and  $\Gamma^-$  interchange if we move the base point b between  $\Gamma^+$  and  $\Gamma^-$ , we may assume that p lies on  $\Gamma^+$ . Since the uniqueness of  $\omega_p^1$  and  $\omega_p^2$  follows from the fact that there is a unique conic passing through five given points, it is sufficient to show the existence of  $\omega_p^1$  and  $\omega_p^2$  as in Proposition 2.3. (To prove the uniqueness when  $p \in l_1$  or  $p \in l_2$ , we also need the fact that  $\omega_p$  must meet  $\Gamma$  at pwith multiplicity at least three.) Fix a point p on  $\Gamma$  arbitrarily. We first consider the case that p neither lies on  $l_1$  nor on  $l_2$ . We denote by m the tangent line of  $\Gamma$  at p. Let A (resp., B) be the point where  $l_1$  (resp.,  $l_2$ ) meets  $\Gamma$ . By a suitable projective transformation of  $\mathbf{P}^2$ , we may assume that  $l_1$  is the line  $\{y = 1\}, l_2$  is the x-axis, and m is the y-axis in the affine plane  $(\mathbf{R}^2; x, y)$  contained in  $\mathbf{P}^2$ . Then A, B can be placed on the right-hand side of the y-axis (see Figure 4). Take a conic  $\omega_0 \in \Omega^+(l_1, l_2)$  so that  $\omega_0$  is tangent to the y-axis at p from the left. Let c(t) =(x(t), y(t)) be a parameterization of the conic  $\omega_0$  such that c(0) = p and c(t+1) = c(t+1)c(t) for  $t \in \mathbf{R}$ . Define a family of conics by  $c_{\lambda}(t) := (\lambda x(t), y(t))$ , where  $\lambda \in [0, \infty)$ . Denote by  $C_{\lambda}$  the image of the curve  $c_{\lambda}$ . By definition,  $C_1$  coincides with  $\omega_0$ .

# LEMMA 2.4

The family  $\{C_{\lambda}\}_{\lambda \in (0,\infty)}$  satisfies the following properties.

(a) There exist positive constants  $\varepsilon$  and  $\delta$  such that  $c_{\lambda}([-\varepsilon,\varepsilon])$  lies in  $\overline{D}_{\Gamma}$  if  $\lambda > \delta$  and  $c_{\lambda}([-\varepsilon,\varepsilon])$  lies in  $\mathbf{P}^2 \setminus D_{\Gamma}$  if  $\lambda < 1/\delta$ .

- (b) If  $\lambda$  is sufficiently large,  $C_{\lambda}$  belongs to  $\Omega^+(l_1, l_2)$ .
- (c) If  $\lambda$  is sufficiently small,  $C_{\lambda}$  belongs to  $\Omega^{-}(l_1, l_2)$ .

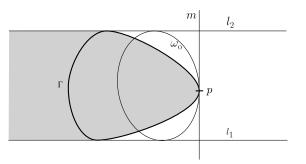


Figure 4. The figure after the projective transformation

## Proof

In Figure 4, the convex domain  $A_+(\Gamma)$  is marked in gray. The Euclidean curvature of  $C_{\lambda}$  at p is equal to  $\lambda \kappa_0$ , where  $\kappa_0$  is the curvature of  $\omega_0$  at p. In particular, there exist positive constants  $\varepsilon$  and  $\delta$  such that  $c_{\delta}([-\varepsilon, \varepsilon])$  lies in  $\overline{D}_{\Gamma}$  and  $c_{1/\delta}([-\varepsilon, \varepsilon])$ lies in  $\mathbf{P}^2 \setminus D_{\Gamma}$ . If  $\lambda > \delta$  (resp.,  $\lambda < 1/\delta$ ), then  $c_{\lambda}([-\varepsilon, \varepsilon])$  lies on the left-hand side of  $c_{\delta}$  (resp., right-hand side of  $c_{1/\delta}$ ). Hence assertion (a) follows.

Next, we prove (b) (resp., (c)). It is obvious that  $C_{\lambda}^{-}$  (resp.,  $C_{1/\lambda}^{-}$ ) does not meet  $\Gamma^{-}$  for sufficiently large  $\lambda$ . So if (b) (resp., (c)) fails, then for each positive integer n, there exists a positive number  $\lambda_n$  and point  $q_n \neq p$  on  $C_{\lambda_n}^+$  (resp.,  $C_{1/\lambda_n}^-$ ) such that  $q_n \in \Gamma^+$  and  $\{\lambda_n\}$  diverges to  $\infty$ . Since  $\Gamma^+$  is compact, we may assume that the sequence  $\{q_n\}$  converges to a point  $q_{\infty} \in \Gamma^+$ . Since the x-component of  $c_{\lambda_n}(t)$  ( $t \notin \mathbb{Z}$ ) (resp.,  $c_{1/\lambda_n}(t)$ ) diverges to  $\infty$  (resp., converges to 0) when  $n \to \infty$ , we get  $q_{\infty} = p$ . This is a contradiction, since  $q_n$  must lie on the left-hand side (resp., right-hand side) of  $\Gamma$  by (a).

We now come to the proof of Proposition 2.3. By (b) and (c), we can set

$$\lambda_1 := \inf \left\{ \lambda \in (0, \infty); C_\lambda \in \Omega^+(l_1, l_2) \right\},\$$
$$\lambda_2 := \sup \left\{ \lambda \in (0, \infty); C_\lambda \in \Omega^-(l_1, l_2) \right\}.$$

Then by definition,  $C_{\lambda_1} \in \Omega^+(l_1, l_2)$  (resp.,  $C_{\lambda_2} \in \Omega^-(l_1, l_2)$ ). If the osculating  $\Omega(l_1, l_2)$ -conic  $\omega_p$  of  $\Gamma$  at p coincides with  $C_{\lambda_1}$  (resp.,  $C_{\lambda_2}$ ), then we are in case (1) of Proposition 2.3. So we may assume  $C_{\lambda_1} \neq \omega_p$  (resp.,  $C_{\lambda_2} \neq \omega_p$ ). If  $\{p\}$  is a proper subset of

$$\Lambda_1 := (C^+_{\lambda_1} \cap \Gamma^+) \cup (C^-_{\lambda_1} \cap \Gamma^-)$$
  
(resp.,  $\Lambda_2 := (C^+_{\lambda_2} \cap \Gamma^+) \cup (C^-_{\lambda_2} \cap \Gamma^-)$ ),

then we are in case (2) after setting  $\omega_p^1 = C_{\lambda_1}$  (resp.,  $\omega_p^2 = C_{\lambda_2}$ ). Thus we may assume that  $\Lambda_1 = \{p\}$  (resp.,  $\Lambda_2 = \{p\}$ ). Since  $C_{\lambda_1}$  (resp.,  $C_{\lambda_2}$ ) is not an osculating conic, the curvature of  $C_{\lambda_1}$  (resp.,  $C_{\lambda_2}$ ) at p must be greater than (resp., less than) that of osculating  $\Omega(l_1, l_2)$ -conic at p and then  $C_{\lambda_1}$  (resp.,  $C_{\lambda_2}$ ) lies on the left-hand side (resp., right-hand side) of  $\Gamma$  around p. Then for a sufficiently small  $\varepsilon > 0, C_{\lambda_1-\varepsilon}$  (resp.,  $C_{\lambda_2+\varepsilon}$ ) must also belong to  $\Omega^+(l_1, l_2)$  (resp.,  $\Omega^-(l_1, l_2)$ ), which contradicts the definition of  $\lambda_1$ , and proves Proposition 2.3 whenever p is not on  $l_1 \cup l_2$ .

Next, we consider the case that p lies on  $l_1$  or  $l_2$ . After a suitable replacement of b, we may assume without loss of generality that p lies on  $l_1$ . Take a sequence  $\{p_n\}_{n=1}^{\infty}$  on  $\Gamma \setminus \{p\}$  converging to p. Then there exists a conic  $\omega_{p_n}^1 \in \Omega^+(l_1, l_2)$ and  $\omega_{p_n}^2 \in \Omega^+(l_1, l_2)$  satisfying one of the two properties of Proposition 2.3. If there exists a subsequence  $\{\omega_{p_{i_n}}^1\}_{n=1}^{\infty}$  such that  $\omega_{p_{i_n}}^1$  is the  $\Omega(l_1, l_2)$ -osculating conic, then  $\{\omega_{p_{i_n}}^1\}_{n=1}^{\infty}$  converges to the  $\Omega(l_1, l_2)$ -osculating conic at p, and the limit conic must satisfy (1). So we may assume that each  $\omega_{p_n}^1$  is not equal to the  $\Omega(l_1, l_2)$ -osculating conic at  $p_n$ . Then there exists a point  $q_n$  on  $\Gamma$  so that  $q_n \in F_{p_n}^+$ . Since  $\Gamma$  is compact, we may assume that  $\{q_n\}$  converges to a point  $q \in \Gamma$ . If  $q \neq p$ , then the limit of  $\{\omega_{p_n}^1\}_{n=1}^{\infty}$  must converge to the  $\Omega(l_1, l_2)$ -osculating conic at pand satisfy (1). Finally, we can apply the same argument for  $\omega_{p_n}^2 \in \Omega^-(l_1, l_2)$ and can prove the limiting conic satisfies case (1) and case (2) of Proposition 2.3 which completes the proof.

# 3. The dual version

Let  $\gamma(t)$  be a closed strictly convex curve in  $\mathbf{P}^2$ . Then it can be lifted to a spherical curve  $\tilde{\gamma}: S^1 \to S^2$  whose image is contained in an open hemisphere. If we denote by

$$\tilde{\pi}: S^2 \to \mathbf{P}^2$$

the canonical covering projection, then  $\pi \circ \tilde{\gamma} = \gamma$  holds. We denote by  $\tilde{n}(t) \in T_{\tilde{\gamma}(t)}S^2$  the unit normal vector of the curve  $\tilde{\gamma}$  pointing into the interior domain. This provides us with a map

$$\tilde{n}: S^1 \to S^2 (\subset \mathbf{R}^3),$$

such that  $\tilde{n}(t)$  is orthogonal to  $\tilde{\gamma}(t)$  and  $\tilde{\gamma}(t)(:=d\tilde{\gamma}/dt)$  in  $\mathbb{R}^3$ . We set

$$\gamma_* = \tilde{\pi} \circ \tilde{n} : S^1 \to \mathbf{P}^2.$$

Then  $\gamma_*(t)$  is also a closed strictly convex curve. Using the canonical inner product on  $\mathbf{R}^3$ , one can identify the dual vector space of  $\mathbf{R}^3$  with  $\mathbf{R}^3$ . Then the correspondence  $\gamma \mapsto n$  realizes the duality of convex curves between  $\mathbf{P}^2$  and  $\mathbf{P}_*^2$ . In fact, the tangent lines of (resp., the points on)  $\gamma$  correspond to the points on (the tangent lines of)  $\gamma_*(t)$ . Without loss of generality, the convex curve  $\gamma$  lies in the affine plane  $\mathbf{R}^2 = \{[x, y, 1] \in \mathbf{P}^2; x, y \in \mathbf{R}\}$ . Then we can write  $\gamma(t) := (x(t), y(t))$ . Without loss of generality, we may also assume that the origin is contained in the interior domain. Then we can choose a parameter t so that

$$x(t)\dot{y}(t) - y(t)\dot{x}(t) > 0$$

for each t. Then the dual of  $\gamma(t)$  in  $\mathbf{P}^2_*$  is given by

$$\gamma_* = \frac{1}{x\dot{y} - y\dot{x}}(-\dot{y}, \dot{x}).$$

In particular, if  $l := \gamma$  is a line such that  $\dot{\gamma}$  is a constant unit vector  $e := (\cos \theta, \sin \theta)$ , then

(3.1) 
$$\frac{1}{d}(-\sin\theta,\cos\theta) \quad \text{where } d := \det(\gamma,e)$$

is called the *dual point* of the line l, where d is the signed distance of the line l from the origin.

#### **PROPOSITION 3.1**

Let  $\gamma_i$  (i = 1, 2) be strictly convex curves in  $\mathbb{R}^2$  that meet at a point p with multiplicity  $m \geq 2$ . Let  $p^*$  be the dual point corresponding to the common tangent line at p. Then their dual curves meet at  $p^*$  with the same multiplicity m.

## Proof

Since the two curves meet at p with multiplicity m, the (m-1)-th jet of  $\gamma_1(t)$  at t = 0 coincides with that of  $\gamma_2(t)$ . The crucial point is that the curvature function of the dual curve  $\gamma_i^*$  (i = 1, 2) of  $\gamma_i$  is given by the formula

$$\kappa_i^* = -\frac{\det(\gamma_i, \dot{\gamma}_i)^3}{|\gamma_i|^3 \det(\dot{\gamma}_i, \ddot{\gamma}_i)},$$

which involves only the 2-jet of the curve  $\gamma_i$ . (The same phenomenon occurs in the proof of the Foreman theorem; see the formula for  $\kappa(t)$  in [2].) Now the assertion follows from the lemma in the appendix.

Let  $(\Gamma^*, o_1, o_2)$  be the dual of  $(\Gamma, l_1, l_2)$ . By Proposition 3.1, the  $\Omega(l_1, l_2)$ -vertices of  $\Gamma$  correspond one-to-one to the  $\Omega(o_1, o_2)$ -vertices of  $\Gamma^*$ . This is analogous to the correspondence between the  $\Omega(l_1, l_2)$ -vertices of  $\Gamma$  and the projective points of the associated diffeomorphism on  $S^1$  found by Foreman. We get the following corollary.

# COROLLARY 3.2

Let  $\Gamma$  be a strictly convex curve, and let  $o_1, o_2$  be two distinct points on  $\Gamma$ . Then there exist at least four distinct  $\Omega(o_1, o_2)$ -vertices on  $\Gamma$ ; namely, the last assertion of Theorem 1.2 holds.

We fix a strictly convex curve  $\Gamma$  and distinct points  $o_1, o_2$  on  $\Gamma$ . To prove the whole statement of Theorem 1.2, we need to construct a compatible pair of intrinsic circle systems. For each  $\omega \in \Omega^+(o_1, o_2)$  (resp.,  $\omega \in \Omega^-(o_1, o_2)$ ), we denote by  $G^+(\omega)$  (resp.,  $G^-(\omega)$ ) the subset of  $\Gamma^+$  (resp.,  $\Gamma^-$ ), where  $\omega^+$  (resp.,  $\omega^-$ ) meets  $\Gamma^+$  (resp.,  $\Gamma^-$ ) with multiplicity more than one.

#### **PROPOSITION 3.3**

For each p on  $\Gamma$ , there exists a unique conic  $\omega_p^1$  (resp.,  $\omega_p^2$ ) in  $\Omega^+(o_1, o_2)$  (resp.,  $\Omega^-(o_1, o_2)$ ) such that

(1)  $\omega_p^1$  (resp.,  $\omega_p^2$ ) is the  $\Omega(o_1, o_2)$ -osculating conic, or

A refinement of Foreman's four-vertex theorem

(2) 
$$\{p\}$$
 is a proper subset of  $F_p^+$  (resp.,  $F_p^-$ ), where  
 $F_p^+ := G^+(\omega_p^1) \cup G^-(\omega_p^1), \qquad F_p^- := G^+(\omega_p^2) \cup G^-(\omega_p^2).$ 

Proof

The uniqueness of  $\omega_p^1$  and  $\omega_p^2$  is proved using the fact that two conics having more than four points in common must coincide. (To prove the uniqueness when  $p = o_1$  or  $p = o_2$ , we also need the fact that  $\omega_p$  must meet  $\Gamma$  at p with multiplicity at least three.) So it is sufficient to prove the existence of  $\omega_p^1$  and  $\omega_p^2$ .

We first consider the case  $p \neq o_1, o_2$ . Let *m* be the tangent line of  $\Gamma$  at *p*. By a suitable projective transformation, we may assume that  $\Gamma$  lies in the affine plane ( $\mathbf{R}^2; x, y$ ) such that p = (0, -1),  $o_1 = (-1, 0)$ ,  $o_2 = (1, 0)$ , and *m* coincides with the line y = -1 such that  $\Gamma$  is tangent to y = -1 at (0, -1). Then the family of conics passing through  $o_1, o_2$  and tangent to the line y = -1 at (0, -1) is given by

$$C_{\lambda}: x^2 + \lambda y^2 + (\lambda - 1)y - 1 = 0.$$

If  $\lambda < -1$ , then  $\omega^+$  of this conic does not pass through p, since  $C_{\lambda}$  is a hyperbola which is tangent to the line y = -1 from below. Hence  $C_{\lambda}$  for  $\lambda < -1$  cannot be a candidate for  $\omega_p^1$  or  $\omega_p^2$ . So we consider a family of conics  $\{C_{\lambda}\}_{\lambda>-1}$  in  $\Omega(o_1, o_2)$ . If  $\lambda$  tends to -1, then  $C_{\lambda}$  collapses to the union of two lines (x-y-1)(x+y+1) = 0, and if  $\lambda$  goes to  $\infty$ , then  $C_{\lambda}$  collapses to a pair of parallel lines y = 0, 1. Using this property, one can easily show that there exists a constant  $\delta$  such that  $C_{\lambda} \in \Omega^+(o_1, o_2)$  if  $(-1 <)\lambda < -1 + 1/\delta$  and  $C_{\lambda} \in \Omega^-(o_1, o_2)$  if  $\lambda > \delta$ . So we can set

$$\lambda_1 := \sup \{ \lambda \in (-1, \infty); C_\lambda \in \Omega^+(o_1, o_2) \}, \\ \lambda_2 := \inf \{ \lambda \in (-1, \infty); C_\lambda \in \Omega^-(l_1, l_2) \}.$$

Then it can be proved that

$$\omega_p^1 := C_{\lambda_1}, \qquad \omega_p^2 := C_{\lambda_2}$$

satisfy the properties in Proposition 3.3. Finally, the case  $p = o_1$  or  $p = o_2$  can be proved by taking a limit  $p_n \to p$  as in the proof of Proposition 2.3.

## Proof of Theorem 1.2

We let  $F^+$  and  $F^-$  be the families of closed subsets of  $\Gamma$  as in part (2) of Proposition 3.3. It can be directly checked that  $(F^+, F^-)$  gives a compatible pair of intrinsic circle systems on  $\Gamma$  by using the fact that two conics having more than four points in common must coincide. Now the assertion follows from Fact 2.1 and Fact 2.2.

We now suggest a different proof of Theorem 1.2. We can identify the pencils of lines through  $o_1$  and  $o_2$  with  $\mathbf{P}^1(o_i)$  (i = 1, 2). For each point  $p \in \Gamma$ , there exists a unique line  $\varphi_i(p) \in \mathbf{P}^1(o_i)$  passing through  $o_i$  and p (see Fig. 5). (If  $p = o_i$ , then  $\varphi_i(p)$  should be the tangent line of  $\Gamma$  at  $o_i$ .) Then, we get a diffeomorphism  $f_{\Gamma}$ :

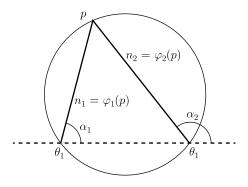


Figure 5. The correspondence  $f_{\Gamma}$ 

 $\mathbf{P}^1(o_1) \to \mathbf{P}^1(o_2)$  given by  $f_{\Gamma} = \varphi_2 \circ (\varphi_1)^{-1}$ . The following gives rise to another proof of Theorem 1.2.

## THEOREM 3.4

The map  $f_{\Gamma}$  can be identified with the diffeomorphism given in [2] for the dual convex curve  $\Gamma^*$ . In particular,  $f_{\Gamma}$  is a projective transformation if and only if  $\Gamma$ is a conic. Moreover, a conic  $\omega \in \Omega(o_1, o_2)$  meets  $\Gamma$  at p with multiplicity  $m(\geq 1)$ if and only if the osculating map  $T_{f_{\Gamma}}$  has the same (m-1)-jet as  $T_{\omega}$  at  $\varphi_1(p)$ . Furthermore, the intrinsic circle system associated to  $f_{\Gamma}$  given in [7] coincides exactly with that induced by Proposition 3.3.

# Proof

Without loss of generality, we may assume that  $\Gamma$  lies in  $\mathbb{R}^2$  with the origin inside of  $\Gamma$ , and  $o_i = (x_i, -1)$  (i = 1, 2). Let m be the line through  $o_1$  and  $o_2$ . Under duality,  $o_1$  and  $o_2$  correspond to two tangent lines  $l_1$  and  $l_2$  of  $\Gamma^*$ , respectively. Then the dual point M on  $\Gamma^*$  of the line m is the intersection point of  $l_1$  and  $l_2$ . Let  $n_1$  (resp.,  $n_2$ ) be a line whose angle with m is  $\alpha_i$ . Then  $n_i$  (i = 1, 2) is an element of  $P^1(o_i)$  which can be expressed by the homogeneous coordinates  $[\cos \alpha_i, \sin \alpha_i]$ . By (3.1) the dual point  $N_i$  of  $n_i$  lies on the line  $l_i$  whose signed Euclidean distance from M is proportional to  $1/(x_i + \cot \alpha_i)$  which is just a projective action of the inhomogeneous coordinate  $\cot \alpha_i$  of  $n_i$  in  $P^1(o_i)$ .

Suppose now that  $n_1$  meets  $n_2$  at a point p on  $\Gamma$ ; namely,  $n_i = \varphi_i(p)$  holds for i = 1, 2. Then the dual of p is just the tangent line of  $\Gamma^*$  passing through  $N_1 \in l_1$  and  $N_2 \in l_2$ . Thus,  $f_{\Gamma}$  is just equal to the diffeomorphism given by Foreman [2] for the dual convex curve  $\Gamma^*$ .

Since  $\Gamma$  is a conic if and only if  $\Gamma^*$  is, the second assertion follows. By replacing  $\Gamma$  by  $\omega \in \Omega(o_1, o_2)$ , we get a diffeomorphism  $f_{\omega}$ . If  $\omega$  coincides with the  $\Omega(o_1, o_2)$ -osculating conic at p,  $f_{\omega}$  is equal to the osculating map of  $f_{\Gamma}$  at  $\varphi_1(p)$ . The last assertion can easily be proved using the two facts that the intersections between  $\omega$  and  $\Gamma$  correspond to the fixed points of  $f_{\Gamma} \circ f_{\omega}^{-1}$  and that minimal

(resp., maximal) projective points of  $f_{\Gamma}$  correspond to the points where  $\Omega(o_1, o_2)$ osculating conic lies locally on the left-hand side (resp. right-hand side) of  $\Gamma$ .

# 4. The case of $\Omega(l, o)$

Let l and o be a tangent line and a point on a strictly convex curve  $\Gamma$  such that o does not lie in l. Let  $\Omega(l, o)$  be the set of regular conics passing through o and having contact with l. For each point p on  $\Gamma$ , we can define the  $\Omega(l, o)$ -osculating *conic* at p as in the case of  $\Omega(l_1, l_2)$  and  $\Omega(o_1, o_2)$ . A point p on the curve  $\Gamma$  is called an  $\Omega(l, o)$ -vertex if  $\omega_p(l, o)$  hyperosculates at p. We now fix a base point b on  $\Gamma$  such that  $b \neq o$  and  $b \notin l$ . The convex curve  $\Gamma$  is divided into two closed arcs by l and o. We denote by  $\Gamma^+$  (resp.,  $\Gamma^-$ ) the one of these two arcs that passes through b (resp., does not pass through b). We call  $\Gamma^+$  the future part and  $\Gamma^-$  the past part. By definition,  $\Gamma^+$  and  $\Gamma^-$  both meet l (resp., o) at one of their boundary points. We then define two subsets  $\Omega^+(l,o)$  and  $\Omega^-(l,o)$  as follows. A conic  $\omega \in \Omega(l, o)$  belongs to  $\Omega^+(l, o)$  (resp.,  $\Omega^-(l, o)$ ) if one can divide  $\omega \in \Omega(l, o)$  into two closed arcs  $\omega^+$  and  $\omega^-$  bounded by l and o such that

$$\Gamma^+ \subset \mathbf{P}^2 \setminus D_\omega, \quad \omega^- \subset \mathbf{P}^2 \setminus D_\Gamma, \qquad (\text{resp.}, \ \Gamma^- \subset \mathbf{P}^2 \setminus D_\omega, \quad \omega^+ \subset \mathbf{P}^2 \setminus D_\Gamma).$$

If we put b on  $\Gamma^-$ , then the roles of  $\Gamma^+$  and  $\Gamma^-$  are interchanged. In this section, we prove the following theorem.

# THEOREM 4.1

Let l and  $o(\notin l)$  be a tangent line and a point on a strictly convex curve  $\Gamma$ . Then, there exist four distinct points  $p_1, p_2, p_3, p_4$  on  $\Gamma$  satisfying  $p_1 \prec p_2 \prec p_3 \prec p_4$  and the following properties:

- (1)  $p_i$  is a clean  $\Omega^+(l, o)$ -vertex for i = 1, 3,
- (2)  $p_j$  is a clean  $\Omega^-(l, o)$ -vertex for j = 2, 4.

Moreover, an analogue of formula (1.1) holds.

To prove the theorem, it is sufficient to show the existence of a compatible pair of intrinsic circle systems. For this purpose, it is sufficient to show that the following proposition holds. For each  $\omega \in \Omega^+(l, o)$  (resp.,  $\omega \in \Omega^-(l, o)$ ), we denote by  $G^+(\omega)$ (resp.,  $G^{-}(\omega)$ ) the subset of  $\Gamma^{+}$  (resp.,  $\Gamma^{-}$ ) where  $\omega^{+}$  (resp.,  $\omega^{-}$ ) meets  $\Gamma^{+}$  (resp.,  $\Gamma^{-}$ ) with multiplicity more than one.

## **PROPOSITION 4.2**

For each p on  $\Gamma$ , there exists a unique conic  $\omega_p^1$  (resp.,  $\omega_p^2$ ) in  $\Omega^+(l,o)$  (resp.,  $\Omega^{-}(l,o)$ ) such that

- (1)  $\omega_p^1$  (resp.,  $\omega_p^2$ ) is the  $\Omega(l, o)$ -osculating conic, or (2)  $\{p\}$  is a proper subset of  $F_p^+$  (resp.,  $F_p^-$ ), where

$$F_p^+ := G^+(\omega_p^1) \cup G^-(\omega_p^1), \qquad F_p^- := G^+(\omega_p^2) \cup G^-(\omega_p^2).$$

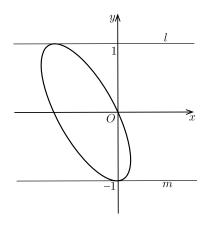


Figure 6. A conic belonging to  $\Omega(l, o)$ 

The uniqueness of  $\omega_p^1$  and  $\omega_p^2$  is proved using the fact that two conics having more than four points in common must coincide. So it is sufficient to prove the existence of  $\omega_p^1$  and  $\omega_p^2$ .

We consider the case  $p \neq o$  and p does not lie in l. (The case p = o or  $p \in l$  can be proved by taking a limit  $p_n \to p$  as in the proof of Proposition 2.3.) Let m be the tangent line of  $\Gamma$  at p. By a suitable projective transformation, we may assume that  $\Gamma$  lies in the affine plane ( $\mathbf{R}^2; x, y$ ) such that o = (0,0), l equal to y = 1, and m coincides with the line y = -1 such that  $\Gamma$  is tangent to the line m (i.e., y = -1) at (0, -1). We fix a conic  $\omega_0$  passing through (0,0) which is tangent to y = 1 and is tangent to y = -1 at (0, -1) (see Fig. 6). Let c(t) = (x(t), y(t)) be a parameterization of the conic  $\omega_0$  such that c(0) = p and c(t+1) = c(t) for  $t \in \mathbf{R}$ . We set  $c_{\lambda} = (\lambda x(t), y(t))$  ( $\lambda \in \mathbf{R}$ ), and we denote its image by  $C_{\lambda}$ . Now, Proposition 4.2 can be proved by applying the following lemma as in the proof of Proposition 3.3.

#### LEMMA 4.3

The family  $\{C_{\lambda}\}_{\lambda \in (0,\infty)}$  satisfies the following properties.

(a) The velocity vector of  $c_{\lambda}$  at (0,0) tends to be horizontal if  $\lambda \to \infty$  and to be vertical if  $\lambda \to 0$ .

(b) There exist positive constants  $\varepsilon$  and  $\delta$  such that  $c_{\lambda}([-\varepsilon,\varepsilon])$  lies in  $\overline{D}_{\Gamma}$  if  $\lambda < 1/\delta$  and  $c_{\lambda}([-\varepsilon,\varepsilon])$  lies in  $\mathbf{P}^2 \setminus D_{\Gamma}$  if  $\lambda > \delta$ .

- (c) If  $\lambda$  is sufficiently large,  $C_{\lambda}$  belongs to  $\Omega^{-}(l, o)$ .
- (d) If  $\lambda$  is sufficiently small,  $C_{\lambda}$  belongs to  $\Omega^+(l, o)$ .

#### Proof

Assertion (a) follows from the fact that the tangent line of  $\omega_0$  at (0,0) is not vertical. Assertion (b) follows from the fact that the (Euclidean) curvature of  $C_{\lambda}$  is equal to  $\lambda^{-2}\kappa_0$ , where  $\kappa_0$  is the curvature of  $\omega_0$  at (0,-1), as in the proof of (a) of Lemma 2.4.

Next, we prove (c) (resp., (d)). It is obvious that  $C_{\lambda}^{+}$  and  $C_{1/\lambda}^{+}$  do not meet  $\Gamma^{-}$  for sufficiently large  $\lambda$ . So if (c) (resp., (d)) fails, for each positive integer n, there exist a positive number  $\lambda_n$  and a point  $q_n \neq p$  on  $C_{\lambda}^{+}$  (resp.,  $C_{1/\lambda}^{-}$ ) such that  $q_n \in \Gamma^+$  and  $\{\lambda_n\}$  diverges to  $\infty$ . Since  $\Gamma^+$  is compact, we may assume that the sequence  $\{q_n\}$  converges to a point  $q_{\infty} \in \Gamma^+$ . Since the *x*-component of  $c_{\lambda_n}(t)$  ( $t \notin \mathbf{Z}$ ) (resp.,  $c_{1/\lambda_n}(t)$ ) diverges to  $\infty$  (resp., converges to 0) when  $n \to \infty$ , we can conclude that  $q_{\infty} = p$  or  $q_{\infty} = o$ . However, this contradicts (a) or (b).

## Appendix: A criterion for multiplicity

The following lemma is needed to prove Proposition 1.2.

## LEMMA A.4

Let  $\gamma_i(t)$  (i = 1, 2) be a pair of regular curves satisfying  $\gamma_1(0) = \gamma_2(0)(=:p)$  and  $\dot{\gamma}_1(0) = \dot{\gamma}_2(0)$ . We denote by  $\kappa_i(t)$  (i = 1, 2) the Euclidean curvature function of  $\gamma_i(t)$ . Then  $\gamma_1$  meets  $\gamma_2$  at p with multiplicity at least n + 2 if

$$(*)_j \qquad \qquad \frac{d^j \kappa_1(0)}{dt^j} = \frac{d^j \kappa_2(0)}{dt^j}$$

*holds for* j = 0, 1, ..., n - 1 *and*  $n \ge 1$ *.* 

#### Proof

We introduce arc-length parameter s on  $\gamma_i$  (i = 1, 2) so that s = 0 corresponds to p. We prove the assertion by induction. If n = 0,  $(*)_0$  implies that the first two derivatives of  $\gamma_1(s)$  and  $\gamma_2(s)$  at s = 0 coincide. The chain rule implies that  $d^k \kappa_i / ds^k$  (i = 1, 2) can be expressed in terms of  $d^j \kappa_i / dt^j$   $(0 \le j \le k)$  and the first k derivatives of  $\gamma_i(t)$ . We now suppose that  $(*)_j$   $(j = 0, \ldots, k - 1)$  implies the first k + 1 derivatives of  $\gamma_1(s)$  at s = 0 coincide with those of  $\gamma_2(s)$ . Then, as a consequence,  $d^k \kappa_1(0) / ds^k$  is equal to  $d^k \kappa_2(0) / ds^k$ , which implies that the first k + 2 derivatives of  $\gamma_1(s)$  and  $\gamma_2(s)$  coincide for s = 0. This proves the assertion.

## References

- R. C. Bose, On the number of circles of curvature perfectly enclosing or perfectly enclosed by a closed convex oval, Math. Z. 35 (1932), 16–24.
- B. Foreman, Ghys's theorem and semi-osculating conics of planar curves, Amer. Math. Monthly 114 (2007), 351–356.
- [3] H. Kneser, Neuer Beweis des Vierscheitelsatzes, Christiaan Huygens 2 (1922/23), 315–318.
- S. Mukhopadhyaya, New methods in the geometry of a plane arc I, Bull. Calcutta Math. Soc. 1 (1909), 31–37.
- [5] \_\_\_\_\_, Extended minimum number theorems of cyclic and sextactic points on a plane convex oval, Math. Z. **33** (1931), 648–662.

## Gudlaugur Thorbergsson and Masaaki Umehara

758

- [6] V. Ovsienko and S. Tabachnikov, Projective differential geometry old and new. From the Schwarzian derivative to the cohomology of diffeomorphism groups, Cambridge Tracts in Math. 165, Cambridge Univ. Press, Cambridge, 2005.
- G. Thorbergsson and M. Umehara, A unified approach to the four vertex theorems II, Differential and symplectic topology of knots and curves, Amer. Math. Soc. Transl. (Series 2) 190, Amer. Math. Soc., Providence, 1999, 229–252.
- [8] \_\_\_\_\_, Sectactic points on a simple closed curve, Nagoya Math. J. 167 (2002), 55–94.
- [9] \_\_\_\_\_, A global theory of flexes of periodic functions, Nagoya Math. J. 173 (2004), 85–138.
- M. Umehara, A unified approach to the four vertex theorems I, Differential and symplectic topology of knots and curves, Amer. Math. Soc. Transl. (Series 2)
   190, Amer. Math. Soc., Providence, 1999, 185–228.

*Thorbergsson*: Mathematisches Institut, Universität zu Köln, Weyertal 86-90, 50931 Köln, Germany; gthorbergsson@mi.uni-koeln.de

*Umehara*: Department of Mathematical and Computing Sciences, Tokyo Institute of Technology, 2-12-1-W8-34, O-okayama Meguro-ku, Tokyo 152-8552, Japan; umehara@is.titech.ac.jp