## LIAPOUNOV EXPONENTS OF STOCHASTIC FLOWS


#### Abstract

By Ming Liao Auburn University We obtain a formula for Liapounov exponents of stochastic flows generated by stochastic differential equations on compact manifolds. As an application, the exponents of a class of stochastic flows on spheres are determined explicitly.


1. Introduction. Consider an SDE (stochastic differential equation) on a compact d-dimensional manifold M ,

$$
\begin{equation*}
d x_{t}=\sum_{i=1}^{k} X_{i}\left(x_{t}\right) \cdot d w_{t}^{i}+X_{0}\left(x_{t}\right) d t \tag{1}
\end{equation*}
$$

where $X_{0}, X_{1}, \ldots, X_{k}$ are smooth vector fields on $M, w_{t}=\left(w_{t}^{1}, \ldots, w_{t}^{k}\right)$ is Brownian motion on $R^{k}$ and $\circ d$ denotes the Stratonovich stochastic differential. We will use $P$ to denote the probability measure associated with Brownian motion $\mathrm{w}_{\mathrm{t}}$.

Let $\phi_{\mathrm{t}}$ denote the stochastic flow generated by (1). The reader is referred to Arnold [1] or Elworthy [7] for the general theory of such stochastic flows. We will assume that the SDE (1) is nondegenerate enough so that it has a unique stationary measure $\rho$ on M . This assumption is satisfied if the Lie algebra generated by $X_{0}, X_{1}, \ldots, X_{k}$ spans the tangent space at every point of $M$. Recall that a stationary measure $\rho$ is a probability measure on $M$ satisfying $\rho(\mathrm{dx})=\int_{\mathrm{M}} \rho(\mathrm{dy}) \mathrm{P}\left(\phi_{\mathrm{t}}(\mathrm{y}) \in \mathrm{dx}\right)$ for any $\mathrm{t} \geq 0$.

Equip M with a Riemannian metric. Let $\mathrm{D} \phi_{\mathrm{t}}$ denote the differential map of $\phi_{\mathrm{t}}$. By a version of Oseledec's multiplicative ergodic theorem (see [5]), for $\rho \times \mathrm{P}$-almost all ( $\mathrm{x}, \omega$ ), there is a filtration of the tangent space $\mathrm{T}_{\mathrm{x}} \mathrm{M}$ : $T_{x} M=V_{1} \supset V_{2}(\omega) \supset \cdots \supset V_{r}(\omega) \supset V_{r+1}=\{0\}$, where $V_{i}(\omega)$ are subspaces, such that $\forall v \in V_{i}-V_{i+1}, 1 \leq i \leq r$, the limit $\mu_{i}=\lim _{t \rightarrow \infty}(1 / \mathrm{t}) \log \left\|\mathrm{D} \phi_{\mathrm{t}}(\mathrm{v})\right\|$ exists, where the norm $\|\cdot\|$ is given by the Riemannian metric. We may assume $\mu_{1}>\mu_{2}>\cdots>\mu_{r}$. These numbers are called the Liapounov exponents of the stochastic flow $\phi_{t}$, which are nonrandom and independent of the Riemannian metric on $M$. The number $d_{i}=\operatorname{dim}\left(V_{i}\right)-\operatorname{dim}\left(V_{i+1}\right)$ is called the multiplicity of the exponent $\mu_{\mathrm{i}}$. Sometimes it is convenient to list the Liapounov exponents as $\lambda_{1} \geq \lambda_{2} \geq \cdots \geq \lambda_{\mathrm{d}}$, where an exponent of multiplicity k repeats $k$ times in this list.

Extending a formula of Khas'minskii for linear stochastic differential equations, Carverhill [6] obtained a formula for the top Liapounov exponent
$\mu_{1}$. This formula is extended by Baxendale [4] to express the sums of the exponents. More recently, Arnold and Imkeller [2] derived a formula for the complete set of Liapounov exponents for linear SDE's using anticipative calculus. In this paper, we will obtain a formula for all the Liapounov exponents of SDE's on compact manifolds based on a different idea. Our method uses results from linear algebra and Itô's formula, and seems simpler than the approach in [2]. Arnold and Imkeller also obtained the Oseledec spaces, which are not discussed here.

As an application, we will consider a class of stochastic flows on the ( $n-1$ )-dimensional sphere $S^{n-1}$ constructed as follows. Think of $S^{n-1}$ as the unit sphere embedded in $\mathrm{R}^{n}$. Let $\mathrm{x}_{1}, \mathrm{x}_{2}, \ldots, \mathrm{x}_{\mathrm{n}}$ be Cartesian coordinates on $R^{n}$, let $Y_{j}$ be the vector field on $S^{n-1}$ obtained by orthogonal projection of the coordinate vector field $\partial / \partial X_{j}$ on $R^{n}$ and let $Y_{j_{1} j_{2} \cdots j_{m}}=X_{j_{1}} X_{j_{2}} \cdots x_{j_{m-1}} Y_{j_{m}}$. Consider an SDE on $\mathrm{S}^{\mathrm{n-1}}$ of the following form:

$$
\begin{equation*}
d x_{t}=\sum_{j_{1}=1}^{n} \cdots \sum_{j_{m}=1}^{n} Y_{j_{1} \cdots j_{m}}\left(x_{t}\right) \circ d w_{t}^{j_{1} \cdots j_{m}}, \tag{2}
\end{equation*}
$$

where $w_{t}=\left(w_{t}^{\left.j_{1} \cdots j_{m}\right\}}\right.$ is an $n^{m}$-dimensional Brownian motion. We will see that the Liapounov exponents of the stochastic flow $\phi_{\mathrm{t}}$ generated by (2) can be expressed in terms of $n$ and $m$ in surprisingly simple formulas. The one-point motion of $\phi_{\mathrm{t}}$ is Brownian motion on $\mathrm{S}^{\mathrm{n-1}}$. We will also see that $\phi_{\mathrm{t}}$ becomes unstable in the sense that its top exponent is positive when $n$ and $m$ are sufficiently large.

We note that, when $\mathrm{m}=1$ or $2, \phi_{\mathrm{t}}$ is finite dimensional in the sense that it is contained in a finite-dimensional transformation group on $\mathrm{S}^{\mathrm{n}-1}$ (one can see this by checking the dimension of the Lie algebra generated by the vector fields involved). Its Liapounov exponents can be determined using the group structure, as in [3] and [9]. However, for $\mathrm{m} \geq 3, \phi_{\mathrm{t}}$ is infinite dimensional.
2. A matrix-valued process. A frame $u=\left(u_{1}, u_{2}, \ldots, u_{d}\right)$ at $x \in M$ is an ordered set of $d$ linearly independent vectors in $T_{x} M$, which can be identified with the linear map: $\mathrm{R}^{\mathrm{d}} \rightarrow \mathrm{T}_{\mathrm{x}} \mathrm{M}$ by sending $\xi \in \mathrm{R}^{\mathrm{d}}$ into $\mathrm{u} \xi=$ $\sum_{j} \mathrm{u}_{\mathrm{j}} \xi_{\mathrm{j}}$. Let $\mathrm{O}(M)$ be the bundle of orthonormal frames on $M$ and let $\pi: \mathrm{O}(\mathrm{M}) \rightarrow \mathrm{M}$ be the natural projection.

Let $G=G L(d, R)_{+}$be the group of $d \times d$ real matrices of positive determinant and let $S$ be the subgroup of upper triangular matrices with positive diagonal elements. Fix $x \in M$ and $u \in O(M)$ with $\pi(u)=x$. The frame $D \phi_{t}(u)=\left(D \phi_{t}\left(u_{1}\right), \ldots, D \phi_{t}\left(u_{d}\right)\right)$ at $x_{t}=\phi_{t}(x)$ in general is not orthonormal, but, by performing a Gram-Schmidt orthogonalization procedure to the ordered set of vectors in $D \phi_{t}(u)$, we obtain an $O(M)$-valued process $u_{t}$ with $\mathrm{u}_{0}=\mathrm{u}$ such that

$$
\begin{equation*}
\mathrm{D} \phi_{\mathrm{t}}(\mathrm{u})=\mathrm{u}_{\mathrm{t}} \mathrm{~s}_{\mathrm{t}} \tag{3}
\end{equation*}
$$

where $s_{t}$ is an $S$-valued process with $s_{0}=I_{d}$, the $d \times d$ identity matrix. We note that $u_{t}$ is a diffusion process on $\mathrm{O}(\mathrm{M})$.

Let $K=S O(d)$, the group of $d \times d$ orthogonal matrices of determinant 1 . Any $\mathrm{g} \in \mathrm{G}$ has a Cartan decomposition $\mathrm{g}=$ ha $^{+} \mathrm{k}$, where $\mathrm{h}, \mathrm{k} \in \mathrm{K}$ and $\mathrm{a}^{+}$is a diagonal matrix with positive and descending diagonal elements. Although the choices for h and k are not quite unique, $\mathrm{a}^{+}$is uniquely determined by g . Let $s_{t}=h_{t} a_{t}^{+} k_{t}$ be the Cartan decomposition of the process $s_{t}$. The diagonal elements $\alpha_{\mathrm{t}}^{1} \geq \alpha_{\mathrm{t}}^{2} \geq \cdots \geq \alpha_{\mathrm{t}}^{\mathrm{d}}$ of $\mathrm{a}_{\mathrm{t}}^{+}$are the factors by which the length of a tangent vector is changed under $\mathrm{D} \phi_{\mathrm{t}}$. It is natural to expect that the Liapounov exponents $\lambda_{j}$ are the limiting exponential rates of $\alpha_{\mathrm{t}}^{j}$ as $\mathrm{t} \rightarrow \infty$ in the sense that $\lambda_{\mathrm{j}}=\lim _{\mathrm{t} \rightarrow \infty}(1 / \mathrm{t}) \log \alpha_{\mathrm{t}}^{\mathrm{j}}$. This fact, whose proof is nontrivial can be considered as a part of Oseledec's multiplicative theorem; see [10] (the condition there is verified in [5]). Let

$$
\begin{equation*}
\Lambda=\lim _{\mathrm{t} \rightarrow \infty} \frac{1}{\mathrm{t}} \log \mathrm{a}_{\mathrm{t}}^{+} . \tag{4}
\end{equation*}
$$

Then $\Lambda=\operatorname{diag}\left\{\lambda_{1}, \lambda_{2}, \ldots, \lambda_{d}\right\}$.
We will let $A$ be the subgroup of diagonal matrices with positive diagonal elements and let N be the subgroup of upper triangular matrices with all the diagonal elements equal to 1 . Then $\mathrm{S}=\mathrm{AN}$. We have the I wasawa decomposition $G=K A N$ in the sense that any $g \in G$ can be uniquely decomposed as $g=$ zan with $z \in K, a \in A$ and $n \in N$. Since $s_{t}$ is in $S$ and $S=A N$, its I wasawa decomposition $s_{t}=a_{t} n_{t}$ does not have a K-component. We note that $s_{t}$ depends on the Brownian path $w$ and the initial frame $u$. We may write $s_{t}(u, w)$ to indicate this dependence.

Because $O(M)$ is compact, the diffusion process $u_{t}$ has at least a stationary measure. We will assume that it has a smooth stationary measure $\bar{\rho}$ on $\mathrm{O}(\mathrm{M})$. This means that $\bar{\rho}$ has a smooth density under local coordinates on $\mathrm{O}(\mathrm{M})$. By the following lemma, it is easy to see that, for $\bar{\rho} \times \mathrm{P}$-almost all (u,w),

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{1}{t} \log a_{t}(u, w)=\lim _{t \rightarrow \infty} \frac{1}{t} \log a_{t}^{+}(u, w) . \tag{5}
\end{equation*}
$$

Lemma 1. There is a subset 1 of $K$ of measure 0 such that if $g_{j}$ is a sequencein $G$ with Cartan decomposition $g_{j}=h_{j} \mathrm{a}_{\mathrm{j}}^{+} \mathrm{k}_{\mathrm{j}}$ and I wasawa decomposition $g_{j}=z_{j} a_{j} n_{j}$ satisfying:
(i) $\lim _{j \rightarrow \infty}(1 / \mathrm{j}) \log \mathrm{a}_{\mathrm{j}}^{+}$exists, and
(ii) the sequence $\mathrm{k}_{\mathrm{j}}$ has a limiting point not contained in I,
then $\lim _{j \rightarrow \infty}(1 / j) \log a_{j}^{+}=\lim _{j \rightarrow \infty}(1 / j) \log a_{j}$.
The lemma is a consequence of a more general result for semisimple Lie groups; see Corollary (2.4) in [8]. Here we present an elementary proof. By assumption, the diagonal elements of $a_{j}^{+}$have limiting exponential rates $\lambda_{1} \geq \lambda_{2} \geq \cdots \geq \lambda_{\mathrm{d}}$ as $\mathrm{i} \rightarrow \infty$ in the sense that $\mathrm{a}_{\mathrm{j}}^{+}=\operatorname{diag}\left\{\exp \left(\mu_{\mathrm{j} 1}\right)\right.$, $\left.\exp \left(\mu_{\mathrm{j} 2}\right), \ldots, \exp \left(\mu_{\mathrm{jd}}\right)\right\}$ with $\lim _{\mathrm{j} \rightarrow \infty} \mu_{\mathrm{ji}} / \mathrm{j}=\lambda_{\mathrm{i}}$. Without loss of generality, we may assume $\mathrm{k}_{\infty}=\lim _{\mathrm{j} \rightarrow \infty} \mathrm{k}_{\mathrm{j}}$ exists. Let $\mathrm{b}_{\mathrm{j}}=\mathrm{a}_{\mathrm{j}}^{+} \mathrm{k}_{\mathrm{j}}$. By performing a

Gram-Schmidt orthogonalization procedure on the column vectors of the matrix $b_{j}$, one sees that there is an upper triangular matrix $t_{j}$ such that $b_{j} t_{j} \in K$. Hence $a_{j} n_{j}=t_{j}^{-1}$. It suffices to show that the diagonal elements of $t_{j}$ have limiting exponential rates $-\lambda_{1}, \ldots,-\lambda_{d}$, unless $\mathrm{k}_{\infty}$ is contained in some subset of $K$ of measure 0 . To prove this, we will construct $t_{j}$ as a product of upper triangular matrices following the Gram-Schmidt orthogonalization procedure.

Note that the element of $\mathrm{b}_{\mathrm{j}}$ at place $(\mathrm{p}, \mathrm{q})$ is $\left(\mathrm{b}_{\mathrm{j}}\right)_{\mathrm{pq}}=\exp \left(\mu_{\mathrm{j}}\right)\left(\mathrm{k}_{\mathrm{j}}\right)_{\mathrm{pq}}$, which has a limiting exponential rate $\lambda_{p}$ unless $\left(k_{\infty}\right)_{p q}=0$. If $k_{\infty}$ is not contained in $\left\{k \in K ; k_{11}=0\right\}$, a subset of $K$ of measure 0 , then, by performing a column reduction on $b_{j}$, we may reduce its first column to a vector of unit length and change the rest of the first row to 0 . This can be achieved by multiplying $b_{j}$ on the right by the following upper triangular matrix $t_{j}^{(1)}$. Let $c_{1 j}$ be the norm of the first column vector of $b_{j}$, let $\left\{c_{1 j}^{-1},-\left(\mathrm{k}_{\mathrm{j}}\right)_{12} /\left(\mathrm{k}_{\mathrm{j}}\right)_{11}, \ldots,-\left(\mathrm{k}_{\mathrm{j}}\right)_{1 \mathrm{~d}} /\left(\mathrm{k}_{\mathrm{j}}\right)_{11}\right\}$ be the first row of $\mathrm{t}_{j}^{(1)}$, let $\left\{\mathrm{c}_{1 j}^{-1}, 1, \ldots, 1\right\}$ be the diagonal of $\mathrm{t}_{j}^{(1)}$ and let all the other elements of $t_{j}^{(1)}$ be 0 . We note that $\mathrm{C}_{1 j}$ has a limiting exponential rate $\lambda_{1}$.

For $p, q \geq 2$,

$$
\left(\mathrm{b}_{\mathrm{j}} \mathrm{t}_{\mathrm{j}}^{(1)}\right)_{\mathrm{pq}}=-\exp \left(\mu_{\mathrm{jp}}\right)\left[\left(\mathrm{k}_{\mathrm{j}}\right)_{\mathrm{p} 1}\left(\mathrm{k}_{\mathrm{j}}\right)_{1 \mathrm{q}} /\left(\mathrm{k}_{\mathrm{j}}\right)_{11}\right]+\exp \left(\mu_{\mathrm{jp}}\right)\left(\mathrm{k}_{\mathrm{j}}\right)_{\mathrm{pq}},
$$

which has a limiting exponential rate $\lambda_{\mathrm{p}}$ unless $\mathrm{k}_{\mathrm{\infty}} \in \mathrm{I}_{\mathrm{pq}}=\{\mathrm{k} \in \mathrm{K}$; $\left.-\left(k_{p 1} k_{1 q} / k_{11}\right)+k_{p q}=0\right\}$, a subset of $K$ of measure 0 .

If $k_{\infty}$ is not contained in $I_{22}$, we can now perform column reduction on the matrix $b_{j} t_{j}^{(1)}$ to get a new matrix whose first column is the same as that of $b_{j} \mathrm{t}_{\mathrm{j}}^{(1)}$, whose second column is orthogonal to the first one and has unit length and whose elements in the second row to the right of the diagonal are all 0. This amounts to multiplying the matrix $\mathrm{b}_{\mathrm{j}} \mathrm{t}_{\mathrm{j}}^{(1)}$ by an upper triangular matrix $t_{\mathrm{j}}^{(2)}$ whose diagonal is $\operatorname{diag}\left\{1, \mathrm{c}_{2 j}^{-1}, 1, \ldots, 1\right\}$, where $\mathrm{c}_{2 j}$ has a limiting exponential rate $\lambda_{2}$ and whose elements off the diagonal, second row and second column are 0 . Unless $k_{\infty}$ belongs to a set of measure $0,\left(b_{j} t_{j}^{(1)} t_{j}^{(2)}\right)_{p q}$ has a limiting exponential rate $\lambda_{\mathrm{p}}$ for $\alpha, \beta \geq 3$. We can continue in this way to obtain upper triangular matrices $t_{j}^{(3)}, \ldots, t_{j}^{(d)}$ such that $b_{j} t_{j}^{(1)} \ldots t_{j}^{(d)} \in K$ and $t_{j}=t_{j}^{(1)} \cdots t_{j}^{(d)}$ has the desired property.

We may take the subset I of K in Lemma 1 as the union of all the subsets of K of measure 0 appearing in the above construction. Note that I is independent of the sequence $g_{j}$.
3. A general formula. As before, let $\phi_{\mathrm{t}}$ be the stochastic flow on M generated by the SDE (1). For a tangent vector e at $x \in M$, $D \phi_{t}(e)$ is a diffusion process in the tangent bundle TM and satisfies the following SDE:

$$
\begin{equation*}
\mathrm{dD} \phi_{\mathrm{t}}(\mathrm{e})=\sum_{\mathrm{i}=1}^{\mathrm{k}} \delta \mathrm{X}_{\mathrm{i}}\left(\mathrm{D} \phi_{\mathrm{t}}(\mathrm{e})\right) \cdot \mathrm{d} \mathrm{w}_{\mathrm{t}}^{\mathrm{i}}+\delta \mathrm{X}_{0}\left(\mathrm{D} \phi_{\mathrm{t}}(\mathrm{e})\right) \mathrm{dt}, \tag{6}
\end{equation*}
$$

where $\delta \mathrm{X}$ is the natural lift to TM of the vector field X on M . We note that,
for $\mathrm{e} \in \mathrm{TM}, \delta \mathrm{X}(\mathrm{e}) \in \mathrm{T}_{\mathrm{e}} \mathrm{TM}$ is the tangent vector to the curve $\mathrm{s} \mapsto \mathrm{D} \psi_{\mathrm{s}}(\mathrm{e})$ at $\mathrm{s}=0$, where $\psi_{\mathrm{s}}$ is the flow of the vector field X on M .

A tangent vector $V \in T_{e} T M$ is called vertical if it is tangent to the curve $s \mapsto e+s Y$ in $T_{x} M \subset T M$ at $s=0$ for some $Y \in T_{x} M$. For simplicity, we may identify $Y \in T_{x} M$ with $V \in T_{e} T M$ as above. Using the Riemannian connection on $M$, any tangent vector $W$ on $T M$ can be uniquely decomposed as $\mathrm{W}=\mathrm{W}^{\mathrm{h}}+\mathrm{W}^{\mathrm{v}}$, where $\mathrm{W}^{\mathrm{h}}$ is horizontal and $\mathrm{W}^{\mathrm{v}}$ is vertical. We can show that $(\delta \mathrm{X})^{\mathrm{v}}(\mathrm{e})=\nabla_{\mathrm{e}} \mathrm{X}=\nabla \mathrm{X}(\mathrm{e})$ for any vector field X on M , where the covariant differentiation $\nabla$ is given by the Riemannian connection.

Let $\mathrm{u}=\left(\mathrm{u}_{1}, \ldots, \mathrm{u}_{\mathrm{d}}\right)$ be an orthonormal frame at $\mathrm{x} \in \mathrm{M}$. We may write $(\delta X)^{\mathrm{v}}(\mathrm{u})=\nabla \mathrm{X}(\mathrm{u})=\left(\nabla \mathrm{X}\left(\mathrm{u}_{1}\right), \ldots, \nabla \mathrm{X}\left(\mathrm{u}_{\mathrm{d}}\right)\right)$. Recall $\mathrm{D} \phi_{\mathrm{t}}(\mathrm{u})=\mathrm{u}_{\mathrm{t}} \mathrm{s}_{\mathrm{t}}$. We have $d D \phi_{t}(u)=\left(\circ d u_{t}\right) s_{t}+u_{t} \circ d s_{t}$. We may substitute $u$ for $e$ in (6) to get the following SDE on $L(M)$, the bundle of linear frames on $M$ :

$$
\begin{equation*}
\mathrm{du}_{\mathrm{t}}+\mathrm{u}_{\mathrm{t}}\left(\circ \mathrm{ds}_{\mathrm{t}}\right) \mathrm{s}_{\mathrm{t}}^{-1}=\sum_{\mathrm{i}} \delta \mathrm{X}_{\mathrm{i}}\left(\mathrm{u}_{\mathrm{t}}\right) \circ \mathrm{dw}_{\mathrm{t}}^{\mathrm{i}}+\delta \mathrm{X}_{0}\left(\mathrm{u}_{\mathrm{t}}\right) \mathrm{dt} \tag{7}
\end{equation*}
$$

For $u \in O(M)$ and a vector field $X$ on $M$, let $\tilde{X}(u)$ be the $d \times d$ matrix defined by

$$
\begin{equation*}
\tilde{\mathrm{X}}(\mathrm{u})_{\alpha \beta}=\left\langle\mathrm{u}_{\alpha}, \nabla \mathrm{X}\left(\mathrm{u}_{\beta}\right)\right\rangle, \tag{8}
\end{equation*}
$$

$\underset{\sim}{w}$ were $\langle\cdot, \cdot\rangle$ is the Riemannian inner product on $T_{\pi(u)} M$. We may write $\tilde{\mathrm{X}}(\mathrm{u})=\mathrm{u}^{-1} \nabla \mathrm{X}(\mathrm{u})$ in the sense that $\forall \xi \in \mathrm{R}^{\mathrm{d}}, \tilde{\mathrm{X}}(\mathrm{u}) \xi=\mathrm{u}^{-1} \nabla \mathrm{X}(\mathrm{u} \xi)$. We note that, for $k \in K, \tilde{X}(u k)=k^{-1} \tilde{X}(u) k$.

Let $\mathrm{H}: \mathrm{TM} \rightarrow \mathrm{TO}(\mathrm{M})$ be the horizontal lift. We note that, for $\mathrm{u} \in \mathrm{O}(\mathrm{M})$ with $\pi(u)=x$ and $Y \in T_{x} M, H(Y)(u)$ is the tangent vector to the curve $s \mapsto u(s)$ in $O(M)$ at $s=0$, where $u(s)$ is the parallel displacement of $u$ along a curve $Z_{s}$ in $M$ with $\left.(d / d s) Z_{s}\right|_{s=0}=Y$.

Let $G, K, A, N$ and $S$ be respectively the Lie algebras of $G, K, A, N$ and S. We have $G=K \oplus S=K \oplus A \oplus N$. For $Y \in G$, let $Y=Y_{K}+Y_{S}=Y_{K}+$ $Y_{A}+Y_{N}$ be such decompositions. From (7), by separating the components in the tangent spaces of $\mathrm{L}(\mathrm{M})$ and using $\delta \mathrm{X}^{\mathrm{v}}(\mathrm{u})=\nabla \mathrm{X}(\mathrm{u})=\mathrm{uX}(\mathrm{u})$ and $\delta \mathrm{X}^{\mathrm{h}}(\mathrm{u})$ $=H(X(\pi(u)))(u)$, we may write down the SDE's satisfied by $u_{t}$ and $s_{t}$ as follows. Recall that $x_{t}=\phi_{\mathrm{t}}(\mathrm{x})$. Then

$$
\begin{align*}
d u_{t}= & \sum_{i=1}^{k}\left\{H\left(X_{i}\left(x_{t}\right)\right)\left(u_{t}\right)+u_{t}\left[\tilde{X}_{i}\left(u_{t}\right)\right]_{K}\right\} \circ d w_{t}^{i}  \tag{9}\\
& +\left\{H\left(X_{0}\left(x_{t}\right)\right)\left(u_{t}\right)+u_{t}\left[\tilde{X}_{0}\left(u_{t}\right)\right]_{k}\right\} d t \\
d s_{t}= & \sum_{i=1}^{k}\left[\tilde{X}_{i}\left(u_{t}\right)\right]_{S} s_{t} \circ d w_{t}^{i}+\left[\tilde{X}_{0}\left(u_{t}\right)\right]_{S} s_{t} d t . \tag{10}
\end{align*}
$$

Since $s_{t}=a_{t} n_{t}$, we have $d s_{t}=\left(\circ d a_{t}\right) n_{t}+a_{t} \circ d n_{t}$ and $\left(\circ d s_{t}\right) s_{t}^{-1}=$ $\left(\circ d a_{t}\right) a_{t}^{-1}+A d\left(a_{t}\right)\left[\left(\circ d n_{t}\right) n_{t}^{-1}\right]$, where $A d(g) Y=g Y g^{-1}$ for $g \in G$ and $Y \in$ $G$. Since $A d(a) Y \in N$ for $a \in A$ and $Y \in N$, it follows from (10) and the
uniqueness of the I wasawa decomposition of $\left(\circ \mathrm{ds}_{t}\right) \mathrm{s}_{\mathrm{t}}^{-1}$ that

$$
\begin{align*}
& d n_{t}=\sum_{i=1}^{k}\left\{\operatorname{Ad}\left(a_{t}^{-1}\right)\left[\tilde{X}_{i}\left(u_{t}\right)\right]_{N}\right\} n_{t} \circ d w_{t}^{i}+\left\{\operatorname{Ad}\left(a_{t}^{-1}\right)\left[\tilde{X}_{0}\left(u_{t}\right)\right]_{N}\right\} n_{t} d t,  \tag{11}\\
& d a_{t}=\sum_{i=1}^{k}\left[\tilde{X}_{i}\left(u_{t}\right)\right]_{A} a_{t} \circ d w_{t}^{i}+\left[\tilde{X}_{0}\left(u_{t}\right)\right]_{A} a_{t} d t \tag{12}
\end{align*}
$$

and

$$
\begin{equation*}
d \log a_{t}=\sum_{i=1}^{k}\left[\tilde{X}_{i}\left(u_{t}\right)\right]_{A} \circ d w_{t}^{i}+\left[\tilde{X}_{0}\left(u_{t}\right)\right]_{A} d t . \tag{13}
\end{equation*}
$$

Given a vector field $X$ on $M$, let $Z=[\tilde{X}(u)]_{k}$. We may regard $u Z$ as the tangent vector to the curve $s \rightarrow u e^{s Z}$ in $O(M)$ at $s=0$. As a vector field on $\mathrm{O}(\mathrm{M}), \mathrm{uZ}$ acts on $\tilde{X}(\mathrm{u})$ as follows:

$$
(u Z) \tilde{X}(u)=\left.\frac{d}{d s} \tilde{X}\left(u e^{s z}\right)\right|_{s=0}=\left.\frac{d}{d s} e^{-s z} \tilde{X}(u) e^{s z}\right|_{s=0}=-[Z, \tilde{X}(u)],
$$

where $[X, Y]=X Y-Y X$ for $X, Y \in G$. It follows from (9) and (13) that

$$
\begin{aligned}
\log a_{t}=m_{t}+\int_{0}^{t} & \left\{\frac{1}{2} \sum_{i} H\left(X_{i}\left(x_{s}\right)\right) \tilde{X}_{i}\left(u_{s}\right)\right. \\
& \left.-\frac{1}{2} \sum_{i}\left[\left[\tilde{X}_{i}\left(u_{s}\right)\right]_{k}, \tilde{X}_{i}\left(u_{s}\right)\right]+\tilde{X}_{0}\left(u_{s}\right)\right\}_{A} d s,
\end{aligned}
$$

where $m_{t}=\int_{0}^{t} \sum_{i}\left[\tilde{X}_{i}\left(u_{s}\right)\right]_{A} d w_{s}^{i}$ (the Itô integral). Recall that $\Lambda$ defined by (4) is a diagonal matrix with the Liapounov exponents arranged in descending order along the diagonal. By (5) and the ergodic theory, we have proved the following result.

Theorem 1. Let $\bar{\rho}$ be a smooth stationary measure of $u_{t}$. Then

$$
\begin{equation*}
\Lambda=\int_{O(M)}\left\{\frac{1}{2} \sum_{i=1}^{\mathrm{k}} \mathrm{H}\left(\mathrm{X}_{\mathrm{i}} \circ \pi\right) \tilde{X}_{\mathrm{i}}-\frac{1}{2} \sum_{\mathrm{i}=1}^{\mathrm{k}}\left[\left[\tilde{X}_{\mathrm{i}}\right]_{\mathrm{K}}, \tilde{X}_{\mathrm{i}}\right]+\tilde{X}_{0}\right\}_{\mathrm{A}} \bar{\rho}(\mathrm{du}) . \tag{14}
\end{equation*}
$$

Remark 1. A Liapounov exponent is called simple if its multiplicity is equal to 1 . If all the exponents are simple, then $\Lambda$ has strictly descending diagonal elements. In this case, we can show that, for $\bar{\rho} \times \mathrm{P}$-almost all ( $\mathrm{u}, \mathrm{w}$ ), $\lim _{t \rightarrow \infty} n_{t}(u, w)$ exists. To show this, we need only to observe that in (11), $\operatorname{Ad}\left(a_{t}^{-1}\right)\left[\tilde{X}_{i}\left(u_{t}\right)\right]_{N}$ has a negative limiting exponential rate as $t \rightarrow \infty$. Hence an argument similar to the one used in [11] shows the convergence of $n_{t}$. Moreover, with a proper choice of the component $k_{t}$ in the Cartan decomposition $s_{t}=h_{t} a_{t}^{+} k_{t}, \lim _{t \rightarrow \infty} k_{t}(u, w)$ exists for $\bar{\rho} \times P$-almost all ( $\left.u, w\right)$. This follows from the convergence of $n_{t}$ and Corollary 2 in [8].
4. A special case. We may write $\bar{\rho}(\mathrm{du})=\int_{\mathrm{M}} \bar{\rho}_{\mathrm{x}}(\mathrm{du}) \rho(\mathrm{dx})$, where $\bar{\rho}_{\mathrm{x}}$ is a smooth probability measure on the fiber $\pi^{-1}(x)$. Given an orthonormal frame $u$ at $x$, this fiber can be identified with $K=S O(d)$ via the map $k \rightarrow u k$. $A$ measure on $\pi^{-1}(\mathrm{x})$ will be called a Haar measure if it is a Haar measure on K via the above identification. We will now simplify the formula (14) under the assumption that $\bar{\rho}_{\mathrm{x}}$ is the normalized Haar measure for any $\mathrm{x} \in \mathrm{M}$.

We define an inner product on G by $\langle\mathrm{X}, \mathrm{Y}\rangle=\operatorname{Trace}\left(\mathrm{XY}{ }^{*}\right)$ for $\mathrm{X}, \mathrm{Y} \in \mathrm{G}$, where $Y^{*}$ is the transpose of the matrix $Y$. This is just the standard Euclidean inner product when $X$ and $Y$ are viewed as $d^{2}$-dimensional vectors. Let $\|X\|=\sqrt{\langle X, X\rangle}$ be the norm of $X$. Let $P$ be the space of symmetric matrices of trace 0 and let $R$ be the one-dimensional space spanned by the identity matrix $I_{n}$. Then $G=R \oplus K \oplus P$. For $Y \in G$, we will use $Y_{p}$ to denote its P -component under this decomposition. We note that $Y_{k}$ has been defined to be the $K$-component of $Y$ under the I wasawa decomposition, which is, in general, different from the K -component of Y under the above decomposition. Let $\mathrm{H}_{\mathrm{d}}$ be the diagonal matrix defined by

$$
\begin{equation*}
H_{d}=\operatorname{diag}\{d-1, d-3, \ldots,-(d-3),-(d-1)\}, \tag{15}
\end{equation*}
$$

let $d k$ be the normalized Haar measure on $K$ and let $p=\operatorname{dim}(P)$.
Lemma 2. For any $X \in G$,

$$
\int_{K}\left[[\operatorname{Ad}(k) X]_{K}, \operatorname{Ad}(k) X\right]_{A} d k=-\frac{1}{p}\left\|X_{P}\right\|^{2} H_{d} .
$$

A more general result is proved in Section 4 of [9]. We provide a proof of Lemma 2 here for the reader's convenience.

We may assume that the $R$-component of $X$ is 0 in the decomposition $G=F \oplus K \oplus P$ because it will not affect the value of $\left[[\operatorname{Ad}(k) X]_{K}, \operatorname{Ad}(k) X\right]_{A}$. There are an orthonormal basis $\left\{Z_{1}, Z_{2}, \ldots, Z_{q}\right\}$ of $K$ and an orthonormal basis $\left\{Y_{1}, Y_{2}, \ldots, Y_{q}, Y_{q+1}, \ldots, Y_{p}\right\}$ of $P$ such that $\left\{Y_{q+1}, \ldots, Y_{p}\right\}$ forms a basis of $A,\left[Y_{j}\right]_{k}=-Z_{j}$ for $1 \leq j \leq q$ and $\left[Z_{i}, Y_{j}\right]_{A}=\delta_{i j} H_{i}^{\prime}$ for $1 \leq i, j \leq q$, where $H_{i}^{\prime} \in A$ with $H_{d}=\sum_{i=1}^{q} H_{i}^{\prime}$. To see the existence of such bases, let $Y_{i j}$ be the symmetric matrix which has 1 at places ( $\mathrm{i}, \mathrm{j}$ ) and ( $\mathrm{j}, \mathrm{i}$ ), and 0 elsewhere; let $\mathrm{Z}_{\mathrm{ij}}$ be the skew-symmetric matrix which has 1 at ( $\mathrm{i}, \mathrm{j}$ ), -1 at ( $\mathrm{j}, \mathrm{i}$ ) and 0 elsewhere; and let $\mathrm{H}_{\mathrm{ij}}$ be the diagonal matrix which as 1 at $(\mathrm{i}, \mathrm{i}),-1$ at $(\mathrm{j}, \mathrm{j})$ and 0 elsewhere. Then we may let $\left\{Z_{1}, \ldots, Z_{q}\right\}$ be $\left\{Z_{i j} / \sqrt{2} ; i<j\right\}$, let $\left\{Y_{1}, \ldots\right.$, $\left.\mathrm{Y}_{\mathrm{q}}\right\}$ be $\left\{\mathrm{Y}_{\mathrm{ij}} / \sqrt{2} ; \mathrm{i}<\mathrm{j}\right\}$ and let $\left\{\mathrm{Y}_{\mathrm{q}+1}, \ldots, \mathrm{Y}_{\mathrm{p}}\right\}$ be $\left\{\mathrm{H}_{12} / \sqrt{2}, \mathrm{H}_{13} / \sqrt{2}, \ldots, \mathrm{H}_{1 \mathrm{~d}} /\right.$ $\sqrt{2}\}$. In this case, $\left\{\mathrm{H}_{\mathrm{i}}^{\prime} ; 1 \leq \mathrm{i} \leq \mathrm{q}\right\}$ is given by $\left\{\mathrm{H}_{\mathrm{ij}} ; \mathrm{i}<\mathrm{j}\right\}$. Because $\left[\mathrm{H}_{\mathrm{ij}}\right.$, $\left.Z_{i j}\right]=2 Y_{i j}$, if we set $Z_{j}=H_{j}^{\prime}=0$ for $q+1 \leq j \leq p$, the relations $\left[Y_{j}\right]_{k}=-Z_{j}$ and $\left[Z_{i} Y_{j}\right]_{A}=\delta_{i j} H_{i}^{\prime}$ hold for all $1 \leq i, j \leq p$.

Let $X=Y+Z$ with $Y \in P$ and $Z \in K$. We now show that

$$
\begin{equation*}
\left[[\operatorname{Ad}(k) X]_{k}, \operatorname{Ad}(k) X\right]_{A}=[\operatorname{Ad}(k)[Z, Y]]_{A}-\sum_{j=1}^{q}\left\langle\operatorname{Ad}(k) Y, Y_{j}\right\rangle^{2} H_{j}^{\prime} . \tag{16}
\end{equation*}
$$

Since $[K, K] \subset K$,

$$
\begin{align*}
& {\left[[\operatorname{Ad}(k) X]_{K}, \operatorname{Ad}(k) X\right]_{A}} \\
& \quad=\left[[\operatorname{Ad}(k) X]_{K}, \operatorname{Ad}(k) Y\right]_{A}  \tag{17}\\
& \quad=[\operatorname{Ad}(k) Z, \operatorname{Ad}(k) Y]_{A}+\left[[\operatorname{Ad}(k) Y]_{K}, \operatorname{Ad}(k) Y\right]_{A} \\
& \quad=[\operatorname{Ad}(k)[Z, Y]]_{A}+\left[[\operatorname{Ad}(k) Y]_{K}, \operatorname{Ad}(k) Y\right]_{A} .
\end{align*}
$$

Define $a_{i j}=a_{i j}(k)$ by $\operatorname{Ad}(k) Y_{i}=\sum_{j} a_{i j} Y_{j}$. Let $Y=\sum_{j} y_{j} Y_{j}$. We have

$$
\begin{aligned}
{\left[[\operatorname{Ad}(k) Y]_{K}, \operatorname{Ad}(k) Y\right]_{A} } & =-\sum_{i, j, v, w} y_{v} y_{w} a_{v i} a_{w j}\left[Z_{i}, Y_{j}\right]_{A} \\
& =-\sum_{v, w, j} y_{v} y_{w} a_{v j} a_{w j} H_{j}^{\prime}
\end{aligned}
$$

Since

$$
\left\langle A d(k) Y, Y_{j}\right\rangle=\sum_{v, i} y_{v} a_{v i}\left\langle Y_{i}, Y_{j}\right\rangle=\sum_{v} y_{v} a_{v j}
$$

we see that

$$
\left[[\operatorname{Ad}(k) Y]_{k}, \operatorname{Ad}(k) Y\right]_{A}=-\sum_{j}\left\langle\operatorname{Ad}(k) Y, Y_{j}\right\rangle^{2} H_{j}^{\prime}
$$

This combined with (17) implies (16).
We note that, for any $Y \in P, \int_{K} \operatorname{Ad}(k) Y d k=0$. To show this, we may assume $Y$ is a traceless diagonal matrix because $\operatorname{Ad}(k) Y=k Y k^{-1}$ is such a matrix for some $k \in K$, and the Haar measure $d k$ is translation invariant. Let $Y=\operatorname{diag}\left\{y_{1}, y_{2}, \ldots, y_{d}\right\}$. We have

$$
\int_{K} \operatorname{Ad}(\mathrm{k}) \mathrm{Ydk}=\int_{\mathrm{K}} \mathrm{kYk}{ }^{-1} \mathrm{dk}=\sum_{\mathrm{i}, \alpha, \beta} \mathrm{y}_{\mathrm{i}} \int \mathrm{k}_{\alpha \mathrm{i}} \mathrm{k}_{\beta \mathrm{i}} \mathrm{dk}=\frac{1}{\mathrm{~d}} \sum_{\mathrm{i}} \mathrm{y}_{\mathrm{i}}=0
$$

because $\int_{K} \mathrm{k}_{\alpha \mathrm{i}} \mathrm{k}_{\beta \mathrm{i}} \mathrm{dk}=(1 / \mathrm{d}) \delta_{\alpha \beta}$. This proves our claim.
Now Lemma 2 follows from (16) and Lemma 3 below. Before stating Lemma 3, we note that, for any nonzero $Y \in P$, the linear span of $\mathrm{O}_{Y}=$ $\{\operatorname{Ad}(k) Y ; k \in K\}$ is $P$. To see this, we observe that $O_{Y}$ is the set of symmetric matrices with the same eigenvalues as those of $Y$. We may assume $Y \in A$. It suffices to show that, for any nonzero $Y \in A$, the set of diagonal matrices obtained by permuting the diagonal entries of $Y$ spans $A$. This reduces our claim to the elementary fact that, given any nonzero vector lying in the hyperplane $x_{1}+x_{2}+\cdots+x_{d}=0$, by permuting its components, we will get enough vectors to span the whole hyperplane.

Lemma 3. For any $Y, Y^{\prime} \in P$ with $\|Y\|=\left\|Y^{\prime}\right\|=1, \int_{K}\left\langle\operatorname{Ad}(k) Y, Y^{\prime}\right\rangle^{2} d k=$ $1 / p$, where $p=\operatorname{dim}(P)$.

To prove Lemma 3, let $S$ be the unit sphere in $P$ and fix $Y \in S$. Consider the function $\psi(W)=\int_{K}\langle\operatorname{Ad}(k) Y, W\rangle^{2} d k$ defined on $S$. We will show that $\psi$ is a constant on $S$. If not, let $a$ and $b$ be respectively its minimal and
maximal values. Choose $\mathrm{W}_{1}$ such that $\psi\left(\mathrm{W}_{1}\right)=\mathrm{a}$. Let $\mathrm{S}_{1}$ be the intersection of S and the orthogonal complement of $\mathrm{W}_{1}$ in P . Any $\mathrm{W} \in \mathrm{S}$ can be expressed as $\mathrm{W}=\mathrm{xW}_{1}+\mathrm{yW} \mathrm{W}_{2}$ for some $\mathrm{W}_{2} \in \mathrm{~S}_{1}$ and $\mathrm{x}^{2}+\mathrm{y}^{2}=1$. We have

$$
\begin{aligned}
0 & =\left.\frac{d}{d t} \psi\left(\sqrt{1-t^{2}} W_{1}+t W_{2}\right)\right|_{t=0} \\
& =2 \int_{K}\left\langle\operatorname{Ad}(k) Y, W_{y}\right\rangle\left\langle\operatorname{Ad}(k) Y, W_{2}\right\rangle d k .
\end{aligned}
$$

It follows that

$$
\psi\left(\mathrm{xW}_{1}+\mathrm{y} \mathrm{~W}_{2}\right)=\mathrm{x}^{2} \psi\left(\mathrm{~W}_{1}\right)+\mathrm{y}^{2} \psi\left(\mathrm{~W}_{2}\right) .
$$

This is less than the maximal value b if $\mathrm{x} \neq 0$. Therefore, b can only be obtained on $\mathrm{S}_{1}$. If $\psi\left(\mathrm{W}_{2}\right)=\mathrm{b}$, then, by the invariance of the Haar measure $\mathrm{dk}, \psi=\mathrm{b}$ along the orbit of $\mathrm{W}_{2}$ under $\operatorname{Ad}(\mathrm{K})$. Hence this orbit is orthogonal to $W_{1}$. Since the linear span of $\left\{\operatorname{Ad}(k) W_{2} ; k \in K\right\}$ is equal to $P$, this is impossible. Therefore, $\psi$ must be a constant.

Let $\mathrm{W}_{1}, \ldots, \mathrm{~W}_{\mathrm{p}}$ be an orthonormal basis of P with respect to the inner product $\langle\cdot, \cdot\rangle$. Since $\operatorname{Ad}(\mathrm{k})$ is an isometry on $\mathrm{P},\left\{\left\langle\operatorname{Ad}(\mathrm{k}) \mathrm{W}_{\mathrm{i}}, \mathrm{W}_{\mathrm{j}}\right\rangle\right\}$ is an orthogonal matrix. We have

$$
\begin{aligned}
\mathrm{p} \psi & =\sum_{\mathrm{i}} \int_{\mathrm{K}}\left\langle\operatorname{Ad}(\mathrm{k}) \mathrm{W}_{\mathrm{i}}, \mathrm{~W}_{1}\right\rangle^{2} \mathrm{dk} \\
& =\int_{K} \sum_{\mathrm{i}}\left\langle\operatorname{Ad}(\mathrm{k}) \mathrm{W}_{\mathrm{i}}, \mathrm{~W}_{1}\right\rangle^{2} \mathrm{dk}=1 .
\end{aligned}
$$

This proves Lemma 3 and hence also Lemma 2.
Let $X$ be a vector field on M. Fix $u_{0} \in \pi^{-1}(x)$. Then, for any $u \in \pi^{-1}(x)$, $u=u_{0} k$ for some $k \in K$. By Lemma 2, we have

$$
\begin{align*}
\int_{\pi^{-1}(x)} & {\left[[\tilde{X}(u)]_{K}, \tilde{X}(u)\right]_{A} \bar{\rho}_{x}(d u) } \\
& =\int_{K}\left[\left[\operatorname{Ad}\left(k^{-1}\right) \tilde{X}\left(u_{0}\right)\right]_{K}, \operatorname{Ad}\left(k^{-1}\right) \tilde{X}\left(u_{0}\right)\right]_{A} d k  \tag{18}\\
& =-\frac{1}{p}\left\|\left[\tilde{X}\left(u_{0}\right)\right]_{p}\right\|^{2} H_{d} .
\end{align*}
$$

In general, TO(M) does not have a smooth section. However, it is possible to have a smooth section defined on an open subset of $O(M)$ whose complement has zero measure. Let $\mathrm{x} \rightarrow \mathrm{u}(\mathrm{x})$ be such a smooth section. Given a vector field $X$ on $M$, let $z_{s}$ be the solution of the differential equation $(\mathrm{d} / \mathrm{ds}) \mathrm{z}_{\mathrm{s}}=\mathrm{X}\left(\mathrm{z}_{\mathrm{s}}\right)$ with $\mathrm{z}_{0}=\mathrm{x}$ and let $\mathrm{u}(\mathrm{x}, \mathrm{s})$ be the parallel displacement of $u(x)$ al ong the curve $s \mapsto z_{s}$. We have

$$
\begin{aligned}
H(X(x)) \tilde{X}(u(x) k) & =\left.\frac{d}{d s} \tilde{X}(u(x, s) k)\right|_{s=0} \\
& =\left.\frac{d}{d s} \tilde{X}\left(u\left(z_{s}\right) k_{s} k\right)\right|_{s=0}
\end{aligned}
$$

for some $k_{s} \in K$. Hence

$$
\begin{aligned}
\int H(X(x)) \tilde{X}(u) \bar{\rho}_{x}(d u) & =\left.\frac{d}{d s} \int_{K} \tilde{X}\left(u\left(z_{s}\right) k_{s} k\right) d k\right|_{s=0} \\
& =\left.\frac{d}{d s} \int_{K} \tilde{X}\left(u\left(z_{s}\right) k\right) d k\right|_{s=0} \\
& =\int_{K} X[\tilde{X}(u(x) k)] d k .
\end{aligned}
$$

Note that in the above we have used the left invariance of the Haar measure dk . Since $\tilde{X}(u k)=\mathrm{k}^{-1} \tilde{\mathrm{X}}(\mathrm{u}) \mathrm{k}$ and $\int_{\mathrm{K}} \mathrm{k}_{\beta \alpha} \mathrm{k}_{\gamma \alpha} \mathrm{dk}=(1 / \mathrm{d}) \delta_{\gamma \beta}$, we have

$$
\begin{aligned}
\int_{\mathrm{K}} \mathrm{X}[\tilde{\mathrm{X}}(\mathrm{u}(\mathrm{x}) \mathrm{k})]_{\alpha \alpha} \mathrm{dk} & =\int_{\mathrm{K}_{\beta, \gamma}} \sum_{\beta} \mathrm{X}[\tilde{\mathrm{X}}(\mathrm{u}(\mathrm{x}))]_{\beta \gamma} \mathrm{k}_{\beta \alpha} \mathrm{k}_{\gamma \alpha} \mathrm{dk} \\
& =\frac{1}{\mathrm{~d}} \sum_{\beta} \mathrm{X}[\tilde{\mathrm{X}}(\mathrm{u}(\mathrm{x}))]_{\beta \beta} .
\end{aligned}
$$

Note that since $\sum_{\beta}[\tilde{X}(u(x))]_{\beta \beta}=\operatorname{div} X(x)$, we have

$$
\begin{equation*}
\int_{O(M)}[H(X(\pi(u))) \tilde{X}(u)]_{A} \bar{\rho}(d u)=\left\{\frac{1}{d} \int_{M} X(\operatorname{div} X)(x) \rho(d x)\right\} I_{d} . \tag{19}
\end{equation*}
$$

Because

$$
\begin{aligned}
\int\left[\tilde{X}_{0}\right]_{A} \bar{\rho}_{x}(\mathrm{du}) & =\int_{K}\left[\operatorname{Ad}\left(\mathrm{k}^{-1}\right) \tilde{X}_{0}\left(\mathrm{u}_{0}\right)\right]_{A} d k \\
& =\int_{K}\left[\operatorname{Ad}\left(\mathrm{k}^{-1}\right)\left[\tilde{X}_{0}\left(\mathrm{u}_{0}\right)\right]_{P}\right]_{A} d k=0,
\end{aligned}
$$

by Theorem 1, (18) and (19), we obtain the following result.
Theorem 2. Under the hypothesis of Theorem 1, assume $\bar{\rho}(\mathrm{du})=$ $\int_{\mathrm{M}} \bar{\rho}_{\mathrm{X}}(\mathrm{du}) \rho(\mathrm{dx})$, where $\rho$ is a stationary measure of SDE (1) and $\bar{\rho}_{\mathrm{x}}$ is the normalized Haar measure on $\pi^{-1}(x)$ for all $x \in M$. Then

$$
\begin{equation*}
\Lambda=\mathrm{C}_{1} \mathrm{I}_{\mathrm{d}}+\mathrm{C}_{2} \mathrm{H}_{\mathrm{d}}, \tag{20}
\end{equation*}
$$

where

$$
\begin{aligned}
& C_{1}=(1 / 2 d) \sum_{i=1}^{k} \int_{M} X_{i}\left(\operatorname{div} X_{i}\right)(x) \rho(d x), \\
& C_{2}=(1 / 2 p) \sum_{i=1}^{k} \int_{M}\left\|\left[\tilde{X}_{i}(u(x))\right]_{p}\right\|^{2} \rho(d x),
\end{aligned}
$$

$\mathrm{p}=\operatorname{dim}(\mathrm{P})$ and $\mathrm{u}(\mathrm{x})$ is a smooth section on the bundle $\mathrm{O}(\mathrm{M})$ defined on an open subset of $M$ whose complement has zero measure We note that we may choose a different section $\mathrm{u}(\mathrm{x})$ in computing each integral in $\mathrm{C}_{2}$.
5. Stochastic flows on spheres. We now consider the stochastic flow $\phi_{\mathrm{t}}$ on the ( $\mathrm{n}-1$ )-dimensional sphere $\mathrm{S}^{\mathrm{n-1}}$ generated by the SDE (2) in Section

1 , which involves the vector fields $Y_{j_{1}-j_{m}}$. We will assume $n \geq 3$. Let $u_{t}$ be the process on $\mathrm{O}\left(\mathrm{S}^{\mathrm{n}-1}\right)$ defined in Section 1 . As before, let $\pi: \mathrm{O}\left(\mathrm{S}^{\mathrm{n}-1}\right) \rightarrow \mathrm{S}^{\mathrm{n}-1}$ be the natural projection. For $\mathrm{x} \in \mathrm{S}^{\mathrm{n-1}}$, let $\bar{\rho}_{\mathrm{x}}$ be the normalized Haar measure on the fiber $\pi^{-1}(\mathrm{x}) \equiv \mathrm{SO}(\mathrm{n}-1)$ and define $\bar{\rho}(\mathrm{du})=\int_{\mathrm{S}^{\mathrm{n}-1}} \bar{\rho}_{\mathrm{x}}(\mathrm{du}) \rho(\mathrm{dx})$, where $\rho$ is the uniform distribution on $\mathrm{S}^{\mathrm{n-1}}$.

Theorem 3. (i) The measure $\bar{\rho}$ defined above is a stationary measure for the process $u_{t}$.
(ii) $\mathrm{x}_{\mathrm{t}}=\phi_{\mathrm{t}}(\mathrm{x})$ for $\mathrm{x} \in \mathrm{S}^{\mathrm{n}-1}$ is a Brownian motion on $\mathrm{S}^{\mathrm{n}-1}$.
(iii) The Liapounov exponents of $\phi_{\mathrm{t}}$ are given by

$$
\Lambda=-\frac{n+m-2}{2} I_{n-1}+\frac{m-1}{2} H_{n-1} .
$$

Remark 2. Before proving the above theorem, we make the following remarks.
(a) When $\mathrm{m}=1$, the stochastic flow $\phi_{\mathrm{t}}$ has a single exponent $-(\mathrm{n}-1) / 2$ of multiplicity $\mathrm{n}-1$. In this case, $\phi_{\mathrm{t}}$ is known as the gradient flow and has been studied in more detail in [3] and [7].
(b) When $\mathrm{m} \geq 2, \phi_{\mathrm{t}}$ has $\mathrm{n}-1$ simple exponents:

$$
\lambda_{i}=\frac{(n-1)(m-2)}{2}-(m-1) i, \quad i=1,2, \ldots,(n-1)
$$

The case when $\mathrm{m}=2$ is considered in [9]. We note that when $\mathrm{n}=3$ the two simple exponents are -1 and -m .
(c) When $\mathrm{m}=1$, 2 or when $\mathrm{n}=3$, the stochastic flow $\phi_{\mathrm{t}}$ is asymptotically stable in the sense that all its exponents are negative. However, $\phi_{\mathrm{t}}$ becomes unstable for larger n and m . For example, its top exponent is equal to 0 when $\mathrm{n}=\mathrm{m}=4$, and is positive when $\mathrm{n}=4$ and $\mathrm{m}>4$.

The rest of this paper is devoted to the proof of Theorem 3.
To prove (i), note that $Y_{i}$, as the orthogonal projection of $\partial / \partial x_{i}$ to $S^{n-1}$, is given by $\left(\partial / \partial \mathrm{X}_{\mathrm{i}}\right)-\mathrm{x}_{\mathrm{i}} \Sigma_{\mathrm{h}} \mathrm{x}_{\mathrm{h}}\left(\partial / \partial \mathrm{x}_{\mathrm{h}}\right)$. Equation (2) can be written under the Cartesian coordinates $x_{1}, \ldots, x_{n}$ as

$$
d x_{i}=\sum_{\mathrm{j}_{1}, \ldots, \mathrm{j}_{\mathrm{m}}}\left[\mathrm{x}_{\mathrm{j}_{1}} \cdots \mathrm{x}_{\mathrm{j}_{\mathrm{m}-1}} \delta_{\mathrm{i}_{\mathrm{m}}}-\mathrm{x}_{\mathrm{j}_{1}} \cdots \mathrm{x}_{\mathrm{j}_{\mathrm{m}}} \mathrm{x}_{\mathrm{i}}\right] \circ \mathrm{dw}_{\mathrm{t}}^{\mathrm{j}_{1} \cdots \mathrm{j}_{\mathrm{m}}} .
$$

From this, one can show that (2) is invariant under orthogonal transformations in the sense that if $x_{t}$ is a solution of (2), then, for any $a \in S O(n), x_{t}^{\prime}$ defined by $x_{i}^{\prime}(t)=\sum_{j} a_{i j} x_{j}(t)$ is also a solution. Fix a point $x \in S^{n-1}$ and let $u_{t}$ be given the initial distribution $\bar{\rho}$. If we consider all the rotations which fix $\mathrm{x}_{\mathrm{t}}$, it is not hard to see that, given $\pi\left(\mathrm{u}_{\mathrm{t}}\right)=\mathrm{x}, \mathrm{u}_{\mathrm{t}}$ is equally likely to be any orthonormal frame at $x$. Hence $\bar{\rho}$ must be a stationary measure for $u_{t}$.

To show (ii), it suffices to show that its generator L is $(1 / 2) \Delta^{\prime}$, where $\Delta^{\prime}$ is the Laplace-Beltrami operator on $\mathrm{S}^{\mathrm{n-1}}$. We will reserve $\Delta$ for the ordinary Laplace operator on $R^{n}$. By the invariance of (2) under orthogonal transfor-
mations, the generator $L$ of $x_{t}$ must be a constant multiple of the Laplace-Beltrami operator $\Delta^{\prime}$ on $\mathrm{S}^{\mathrm{n}-1}$. We have

$$
\mathrm{L}=\frac{1}{2} \sum_{\mathrm{j}_{1}, \ldots, \mathrm{j}_{\mathrm{m}}}\left\{\sum_{\mathrm{i}}\left[\mathrm{x}_{\mathrm{j}_{1}} \cdots \mathrm{x}_{\mathrm{j}_{\mathrm{m}-1}} \delta_{\mathrm{i} \mathrm{j}_{\mathrm{m}}}-\mathrm{x}_{\mathrm{j}_{1}} \cdots \mathrm{x}_{\mathrm{j}_{\mathrm{m}}} \mathrm{x}_{\mathrm{i}}\right] \frac{\partial}{\partial \mathrm{x}_{\mathrm{i}}}\right\}^{2} .
$$

By direct computation, its leading terms are given by

$$
(1 / 2)\left[\Delta-\sum_{i, j} x_{i} x_{j}\left(\partial / \partial x_{i}\right)\left(\partial / \partial x_{j}\right)\right]
$$

which coincide with those of $(1 / 2) \Delta^{\prime}$. This proves (ii).
We will use spherical polar coordinates on $\mathrm{S}^{\mathrm{n-1}}$ :

$$
\begin{aligned}
& \mathrm{x}_{1}=\cos \theta_{1}, \quad \mathrm{x}_{2}=\sin \theta_{1} \cos \theta_{2}, \ldots, \mathrm{x}_{\mathrm{n}-1}=\sin \theta_{1} \cdots \sin \theta_{\mathrm{n}-2} \cos \theta_{\mathrm{n}-1}, \\
& \mathrm{x}_{\mathrm{n}}=\sin \theta_{1} \cdots \sin \theta_{\mathrm{n}-1},
\end{aligned}
$$

where $0<\theta_{\mathrm{i}}<\pi$ for $1 \leq \mathrm{i} \leq \mathrm{n}-2$ and $0<\theta_{\mathrm{n}-1}<2 \pi$. The Riemannian metric tensor is

$$
\mathrm{g}_{\mathrm{ij}}=\left\langle\frac{\partial}{\partial \theta_{\mathrm{i}}}, \frac{\partial}{\partial \theta_{\mathrm{j}}}\right\rangle=\delta_{\mathrm{ij}} \sin ^{2} \theta_{1} \cdots \sin ^{2} \theta_{\mathrm{i}-1}
$$

with $g_{11}=1$. The uniform distribution on $\mathrm{S}^{\mathrm{n}-1}$ is given by

$$
\mathrm{d} \rho=\sin ^{\mathrm{n}-2} \theta_{1} \sin ^{\mathrm{n}-3} \theta_{2} \cdots \sin \theta_{\mathrm{n}-2} \mathrm{~d} \theta_{1} \mathrm{~d} \theta_{2} \cdots \mathrm{~d} \theta_{\mathrm{n}-1} / \sigma_{\mathrm{n}},
$$

where $\sigma_{\mathrm{n}}$ is the area of $\mathrm{S}^{\mathrm{n}-1}$. We can show

$$
\begin{equation*}
\int \mathrm{x}_{1}^{2} \mathrm{~d} \rho=\frac{1}{\mathrm{n}}, \quad \int \mathrm{x}_{1}^{4} \mathrm{~d} \rho=\frac{3}{\mathrm{n}(\mathrm{n}+2)}, \quad \int \mathrm{x}_{1}^{2} \mathrm{x}_{2}^{2} \mathrm{~d} \rho=\frac{1}{\mathrm{n}(\mathrm{n}+2)} . \tag{21}
\end{equation*}
$$

The Christoffel symbols are given by

$$
\Gamma_{\mathrm{j} j}^{\mathrm{i}}=-\sin ^{2} \theta_{\mathrm{i}} \sin ^{2} \theta_{\mathrm{i}+1} \cdots \sin ^{2} \theta_{\mathrm{j}-1} \cot \theta_{\mathrm{i}}
$$

and

$$
\Gamma_{\mathrm{ij}}^{\mathrm{j}}=\Gamma_{\mathrm{ji}}^{\mathrm{j}}=\cot \theta_{\mathrm{i}} \text { for } \mathrm{i}<\mathrm{j},
$$

and all other $\Gamma_{j k}^{i}=0$. As a smooth section on $O\left(S^{n-1}\right)$, let

$$
\mathrm{u}=\left(\mathrm{u}_{1}, \mathrm{u}_{2}, \ldots, \mathrm{u}_{\mathrm{n}-1}\right)=\left(\frac{\partial}{\partial \theta_{1}}, \csc \theta_{1} \frac{\partial}{\partial \theta_{2}}, \ldots, \csc \theta_{1} \cdots \csc \theta_{\mathrm{n}-2} \frac{\partial}{\partial \theta_{\mathrm{n}-1}}\right)
$$

Then $\nabla_{\mathrm{u}_{1}} \mathrm{u}_{1}=0, \nabla_{\mathrm{u}_{\mathrm{i}}} \mathrm{u}_{1}=\left(\cot \theta_{1}\right) \mathrm{u}_{\mathrm{j}}$ for $\mathrm{j}>1$.
To prove(iii), we need to show $\mathrm{C}_{1}=-(\mathrm{n}+\mathrm{m}-2) / 2$ and $\mathrm{C}_{2}=(\mathrm{m}-1) / 2$, where $\mathrm{C}_{1}$ and $\mathrm{C}_{2}$ are constants in Theorem 2. Note that $\mathrm{Y}_{1}=-\left(\sin \theta_{1}\right) \mathrm{u}_{1}$. Let

$$
Y=Y_{\alpha}=Y_{j_{1} \cdots j_{m-1} 1}=-\left(\sin \theta_{1}\right) x_{1}^{\alpha_{1}} X_{2}^{\alpha_{2}} \cdots X_{n}^{\alpha_{n}} u_{1},
$$

where $\alpha_{\mathrm{i}}$ are nonnegative integers and $\sum_{\mathrm{i}=1}^{\mathrm{n}} \alpha_{\mathrm{i}}=\mathrm{m}-1$. In the sequel, we may omit some elementary details in rather tedious computations.

Let $\beta_{\mathrm{i}}=\sum_{\mathrm{j}=\mathrm{i}+1}^{\mathrm{n}} \alpha_{\mathrm{j}}$ for $1 \leq \mathrm{i} \leq \mathrm{n}-1$. Then

$$
\begin{aligned}
\mathrm{Y}= & -\sin \theta_{1} \prod_{\mathrm{i}=1}^{\mathrm{n}-1} \sin ^{\beta_{i}} \theta_{\mathrm{i}} \cos ^{\alpha_{i}} \theta_{\mathrm{i}} \mathrm{u}_{1}, \\
\operatorname{div} \mathrm{Y}= & \sum_{\mathrm{i}}\left\langle\mathrm{u}_{\mathrm{i}}, \nabla \mathrm{Y}\left(\mathrm{u}_{\mathrm{i}}\right)\right\rangle \\
= & {\left[-\left(\mathrm{n}+\beta_{1}-1\right) \sin ^{\beta_{1}} \theta_{1} \cos ^{\alpha_{1}+1} \theta_{1}\right.} \\
& \left.\quad+\alpha_{1} \sin ^{\beta_{1}+2} \theta_{1} \cos ^{\alpha_{1}-1} \theta_{1}\right] \prod_{\mathrm{i}=2}^{\mathrm{n}-1} \sin ^{\beta_{i}} \theta_{\mathrm{i}} \cos ^{\alpha_{i}} \theta_{\mathrm{i}} .
\end{aligned}
$$

Let $X_{\alpha}=X_{1}^{\alpha_{1}} \mathrm{X}_{2}^{\alpha_{2}} \cdots \mathrm{x}_{n}^{\alpha_{n}}$. Using $\alpha_{1}+\beta_{1}=\mathrm{m}-1$, we have

$$
\begin{aligned}
\mathrm{Y}(\operatorname{div} \mathrm{Y})= & \mathrm{m}(\mathrm{n}+\mathrm{m}-2) \mathrm{x}_{1}^{2} \mathrm{X}_{\alpha}^{2}-(\mathrm{n}+\mathrm{m}-2) \mathrm{X}_{\alpha}^{2} \\
& -(\mathrm{n}+2 \mathrm{~m}-4) \alpha_{1} \mathrm{X}_{\alpha}^{2}+\alpha_{1}\left(\alpha_{1}-1\right) \mathrm{x}_{1}^{-2} \mathrm{X}_{\alpha}^{2} .
\end{aligned}
$$

Let $\mathrm{C}_{\alpha}^{\mathrm{m}-1}=(\mathrm{m}-1)!/\left[\alpha_{1}!\alpha_{2}!\cdots \alpha_{\mathrm{n}}!\right]$. Then, by symmetry, we have

$$
\begin{aligned}
& \mathrm{C}_{1}=\frac{\mathrm{n}}{2(\mathrm{n}-1)} \sum_{\alpha} \mathrm{C}_{\alpha}^{\mathrm{m}-1} \int \mathrm{Y}_{\alpha}\left(\operatorname{div} \mathrm{Y}_{\alpha}\right) \mathrm{d} \rho \\
&=\frac{\mathrm{n}}{2(\mathrm{n}-1)} \int\{ \mathrm{m}(\mathrm{n}+\mathrm{m}-2) \mathrm{x}_{1}^{2} \sum \mathrm{C}_{\alpha}^{\mathrm{m}-1} \mathrm{X}_{\alpha}^{2} \\
& \quad-(\mathrm{n}+\mathrm{m}-2) \sum \mathrm{C}_{\alpha}^{\mathrm{m}-1} \mathrm{X}_{\alpha}^{2} \\
& \quad-(\mathrm{n}+2 \mathrm{~m}-4) \sum \mathrm{C}_{\alpha}^{\mathrm{m-1}} \alpha_{\alpha_{1}} \mathrm{X}_{\alpha}^{2} \\
&\left.\quad+\sum \mathrm{C}_{\alpha}^{\mathrm{m}-1} \alpha_{1}\left(\alpha_{1}-1\right) \mathrm{x}_{1}^{-2} \mathrm{X}_{\alpha}^{2}\right\} \mathrm{d} \rho .
\end{aligned}
$$

Using the following combinatoric identities,

$$
\begin{aligned}
\sum \mathrm{C}_{\alpha}^{m-1} \mathrm{X}_{\alpha}^{2} & =1, \quad \sum \mathrm{C}_{\alpha}^{m-1} \alpha_{1} \mathrm{X}_{\alpha}^{2}=(\mathrm{m}-1) \mathrm{x}_{1}^{2}, \\
\sum \mathrm{C}_{\alpha}^{2} \alpha_{1}\left(\alpha_{1}-1\right) \mathrm{x}_{1}^{-2} \mathrm{X}_{\alpha}^{2} & =(\mathrm{m}-1)(\mathrm{m}-2) \mathrm{x}_{1}^{2}
\end{aligned}
$$

and $\int \mathrm{x}_{1}^{2} \mathrm{~d} \rho=1 / \mathrm{n}$, we have

$$
\begin{aligned}
C_{1}= & \frac{n}{2(n-1)}\left[\frac{m(n+m-2)}{n}-(n+m-2)\right. \\
& \left.-\frac{(n+2 m-4)(m-1)}{n}+\frac{(m-1)(m-2)}{n}\right] \\
= & -\frac{n+m-2}{2} .
\end{aligned}
$$

We now calculate the matrix $\tilde{Y}$ for $Y=Y_{\alpha}$. We have $\tilde{Y}_{11}=-m x_{1} X_{\alpha}+$ $\alpha_{1} \mathrm{X}_{1}^{-1} \mathrm{X}_{\alpha}, \tilde{\mathrm{Y}}_{\mathrm{ii}}=-\mathrm{x}_{1} \mathrm{X}_{\alpha}$ and

$$
\tilde{Y}_{1 \mathrm{i}}=\left(\sin \theta_{1}\right) \mathrm{X}_{\alpha} \mathrm{x}_{\mathrm{i}}^{-1}\left[\alpha_{\mathrm{i}} \sin ^{2} \theta_{\mathrm{i}}-\beta_{\mathrm{i}} \cos ^{2} \theta_{\mathrm{i}}\right] \sin ^{-1} \theta_{\mathrm{i}}
$$

for $2 \leq \mathrm{i} \leq \mathrm{n}-1$, and all other $\tilde{\mathrm{Y}}_{\mathrm{ij}}=0$. Hence $(\tilde{\mathrm{Y}})_{\mathrm{p}}$ is given by
$\left[\begin{array}{ccccc}\frac{(n-2)\left[\alpha_{1} x_{1}^{-1}-(m-1) x_{1}\right]}{n-1} X_{\alpha} & \frac{1}{2} \tilde{Y}_{12} & \cdots & \cdots & \frac{1}{2} \tilde{Y}_{1, n-1} \\ \frac{1}{2} \tilde{Y}_{12} & -\frac{\alpha_{1} x_{1}^{-1}-(m-1) x_{1}}{n-1} x_{\alpha} & 0 & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ \frac{1}{2} \tilde{Y}_{1, n-1} & 0 & \cdots & 0 & -\frac{\alpha_{1} x_{1}^{-1}-(m-1) x_{1}}{n-1} x_{\alpha}\end{array}\right]$

We have

$$
\begin{aligned}
\left\|(\tilde{Y})_{p}\right\|^{2}= & \frac{n-2}{n-1}\left[\alpha_{1}-(m-1) x_{1}^{2}\right]^{2} x_{1}^{-2} X_{\alpha}^{2} \\
& +\frac{1}{2}\left(\sin ^{2} \theta_{1}\right) X_{\alpha}^{2} \sum_{i=2}^{n-1} x_{i}^{-2}\left[\alpha_{i} \sin ^{2} \theta_{i}-\beta_{i} \cos ^{2} \theta_{i}\right]^{2} \sin ^{-2} \theta_{i}
\end{aligned}
$$

Using $\alpha_{\mathrm{i}}+\beta_{\mathrm{i}}=\beta_{\mathrm{i}-1}$ and $\mathrm{x}_{\mathrm{i}+2}^{-2} \sin ^{2} \theta_{\mathrm{i}+1}+\mathrm{x}_{\mathrm{i}}^{-2} \sin ^{-2} \theta_{\mathrm{i}}=\mathrm{x}_{\mathrm{i}}^{-2}+\mathrm{x}_{\mathrm{i}+1}^{-2}$ and simplifying, we obtain

$$
\begin{aligned}
& \sum_{i=2}^{n-1} x_{i}^{-2}\left[\alpha_{i} \sin ^{2} \theta_{i}-\beta_{i} \cos ^{2} \theta_{i}\right]^{2} \sin ^{-2} \theta_{i} \\
& =\sum_{i=2}^{n-1} x_{i}^{-2}\left[\beta_{\mathrm{i}-1} \sin ^{2} \theta_{\mathrm{i}}-\beta_{\mathrm{i}}\right]^{2} \sin ^{-2} \theta_{\mathrm{i}} \\
& =\beta_{1}^{2} x_{2}^{-2} \sin ^{2} \theta_{2}-2 \sum_{i=2}^{n-1} \beta_{\mathrm{i}-1} \beta_{\mathrm{i}} \mathrm{x}_{\mathrm{i}}^{-2}+\beta_{\mathrm{n}-1}^{2} \mathrm{x}_{\mathrm{n}-1}^{-2} \sin ^{-2} \theta_{\mathrm{n}-1} \\
& +\sum_{i=2}^{n-2} \beta_{i}^{2}\left[x_{i+1}^{-2} \sin ^{2} \theta_{i+1}+x_{i}^{-2} \sin ^{-2} \theta_{i}\right] \\
& =\beta_{1}^{2} x_{2}^{-2} \sin ^{2} \theta_{2}-2 \sum_{i=2}^{n-1}\left(\alpha_{i}+\beta_{i}\right) \beta_{i} x_{i}^{-2} \\
& +\alpha_{n}^{2} x_{n-1}^{-2} \sin ^{-2} \theta_{n-1}+\sum_{i=2}^{n-2} \beta_{i}^{2}\left[x_{i}^{-2}+x_{i+1}^{-2}\right] \\
& =\cdots=-\beta_{1}^{2} x_{2}^{-2} \cos ^{2} \theta_{2}+\sum_{i=2}^{n} \alpha_{i}^{2} x_{i}^{-2} .
\end{aligned}
$$

Substituting the above in $(\tilde{\mathrm{Y}})_{\mathrm{p}}$ and using $\beta_{1}=\mathrm{m}-1-\alpha_{1}$, we obtain

$$
\begin{aligned}
\left\|\left(\tilde{Y}_{\alpha}\right)_{\mathrm{P}}\right\|^{2}= & \frac{\mathrm{n}-2}{\mathrm{n}-1} \alpha_{1}^{2} \mathrm{x}_{1}^{-2} \mathrm{X}_{\alpha}^{2}-\frac{(\mathrm{n}-3)(\mathrm{m}-1)}{\mathrm{n}-1} \alpha_{1} \mathrm{X}_{\alpha}^{2} \\
& +\frac{(\mathrm{n}-2)(\mathrm{m}-1)^{2}}{\mathrm{n}-1} \mathrm{x}_{1}^{2} \mathrm{X}_{\alpha}^{2}-\frac{(\mathrm{m}-1)^{2}}{2} \mathrm{X}_{\alpha}^{2} \\
& -\frac{1}{2} \alpha_{1}^{2} \mathrm{X}_{\alpha}^{2}+\frac{1}{2}\left(1-\mathrm{x}_{1}^{2}\right) \sum_{\mathrm{i}=2}^{\mathrm{n}} \alpha_{\mathrm{i}}^{2} \mathrm{x}_{\mathrm{i}}^{-2} \mathrm{X}_{\alpha}^{2}
\end{aligned}
$$

The dimension of $p$ is $p=(n+1)(n-2) / 2$. Using symmetry, some combinatoric identities like those used before and (21), we have

$$
\begin{aligned}
& \mathrm{C}_{2}=\frac{\mathrm{n}}{(\mathrm{n}+1)(\mathrm{n}-2)} \sum_{\alpha} \mathrm{C}_{\alpha}^{m-1} \int\left\|\left(\tilde{\mathrm{Y}}_{\alpha}\right)_{\mathrm{p}}\right\|^{2} \mathrm{~d} \rho \\
& =\frac{n}{(n+1)(n-2)} \\
& \times \int\left\{\frac{n-2}{n-1}\left[(m-1)(m-2) x_{1}^{2}+(m-1)\right]\right. \\
& -\frac{(n-3)(m-1)}{n-1}(m-1) x_{1}^{2} \\
& +\frac{(n-2)(m-1)^{2}}{n-1} x_{1}^{2}-\frac{(m-1)^{2}}{2} \\
& -\frac{1}{2}\left[(m-1)(m-2) x_{1}^{4}+(m-1) x_{1}^{2}\right] \\
& \left.+\frac{n-1}{2}\left(1-x_{1}^{2}\right)\left[(m-1)(m-2) x_{2}^{2}+(m-1)\right]\right\} d \rho \\
& =\frac{n}{(n+1)(n-2)}\left\{+\frac{n-2}{n-1}\left[\frac{(m-1)(m-2)}{n}+(m-1)\right]\right. \\
& +\frac{(m-1)^{2}}{n(n-1)}-\frac{(m-1)^{2}}{2} \\
& -\frac{1}{2}\left[\frac{3(m-1)(m-2)}{n(n+2)}+\frac{m-1}{n}\right] \xi \\
& +\frac{n-1}{2}\left[\frac{(m-1)(m-2)}{n}+(m-1)\right] \\
& \left.-\frac{n-1}{2}\left[\frac{(m-1)(m-2)}{n(n+2)}+\frac{m-1}{n}\right]\right\} \\
& =\frac{m-1}{2} .
\end{aligned}
$$

Theorem 3 is proved.

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