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# GEOMETRIC INTERPRETATION OF HALF-PLANE CAPACITY

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#### Abstract

Schramm-Loewner Evolution describes the scaling limits of interfaces in certain statistical mechanical systems. These interfaces are geometric objects that are not equipped with a canonical parametrization. The standard parametrization of SLE is via half-plane capacity, which is a conformal measure of the size of a set in the reference upper half-plane. This has useful harmonic and complex analytic properties and makes SLE a time-homogeneous Markov process on conformal maps. In this note, we show that the half-plane capacity of a hull *A* is comparable up to multiplicative constants to more geometric quantities, namely the area of the union of all balls centered in *A* tangent to  $\mathbb{R}$ , and the (Euclidean) area of a 1-neighborhood of *A* with respect to the hyperbolic metric.

## 1 Introduction

Suppose *A* is a bounded, relatively closed subset of the upper half plane  $\mathbb{H}$ . We call *A* a compact  $\mathbb{H}$ -hull if *A* is bounded and  $\mathbb{H} \setminus A$  is simply connected. The *half-plane capacity* of *A*, hcap(*A*), is defined in a number of equivalent ways (see [1], especially Chapter 3). If  $g_A$  denotes the unique conformal

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transformation of  $\mathbb{H} \setminus A$  onto  $\mathbb{H}$  with  $g_A(z) = z + o(1)$  as  $z \to \infty$ , then  $g_A$  has the expansion

$$g_A(z) = z + \frac{\operatorname{hcap}(A)}{z} + O(|z|^{-2}), \quad z \to \infty.$$

Equivalently, if  $B_t$  is a standard complex Brownian motion and  $\tau_A = \inf\{t \ge 0 : B_t \notin \mathbb{H} \setminus A\}$ ,

$$\operatorname{hcap}(A) = \lim_{y \to \infty} y \mathbb{E}^{iy} \left[ \operatorname{Im}(B_{\tau_A}) \right].$$

Let  $\text{Im}[A] = \sup\{\text{Im}(z) : z \in A\}$ . Then if  $y \ge \text{Im}[A]$ , we can also write

$$\operatorname{hcap}(A) = \frac{1}{\pi} \int_{-\infty}^{\infty} \mathbb{E}^{x+iy} \left[ \operatorname{Im}(B_{\tau_A}) \right] dx.$$

These last two definitions do not require  $\mathbb{H} \setminus A$  to be simply connected, and the latter definition does not require *A* to be bounded but only that  $\text{Im}[A] < \infty$ .

For  $\mathbb{H}$ -hulls (that is, for relatively closed *A* for which  $\mathbb{H} \setminus A$  is simply connected), the half-plane capacity is comparable to a more geometric quantity that we define. This is not new (the second author learned it from Oded Schramm in oral communication), but we do not know of a proof in the literature<sup>3</sup>. In this note, we prove the fact giving (nonoptimal) bounds on the constant. We start with the definition of the geometric quantity.

**Definition 1.** For an  $\mathbb{H}$ -hull A, let hsiz(A) be the 2-dimensional Lebesgue measure of the union of all balls centered at points in A that are tangent to the real line. In other words

hsiz(A) = area 
$$\left[ \bigcup_{x+iy \in A} \mathscr{B}(x+iy,y) \right],$$

where  $\mathscr{B}(z,\epsilon)$  denotes the disk of radius  $\epsilon$  about z.

In this paper, we prove the following.

**Theorem 1.** For every  $\mathbb{H}$ -hull A,

$$\frac{1}{66}\operatorname{hsiz}(A) < \operatorname{hcap}(A) < \frac{7}{2\pi}\operatorname{hsiz}(A).$$

## 2 Proof of Theorem 1

It suffices to prove this for weakly bounded  $\mathbb{H}$ -hulls, by which we mean  $\mathbb{H}$ -hulls A with  $\text{Im}(A) < \infty$  and such that for each  $\epsilon > 0$ , the set  $\{x + iy : y > \epsilon\}$  is bounded. Indeed, for  $\mathbb{H}$ -hulls that are not weakly bounded, it is easy to verify that  $\text{hsiz}(A) = \text{hcap}(A) = \infty$ .

We start with a simple inequality that is implied but not explicitly stated in [1]. Equality is achieved when *A* is a vertical line segment.

**Lemma 1.** If A is an  $\mathbb{H}$ -hull, then

$$\operatorname{hcap}(A) \ge \frac{\operatorname{Im}[A]^2}{2}.$$
(1)

 $<sup>^{3}</sup>$ After submitting this article, we learned that a similar result was recently proved by Carto Wong as part of his Ph.D. research.

*Proof.* Due to the continuity of hcap with respect to the Hausdorff metric on  $\mathbb{H}$ -hulls, it suffices to prove the result for  $\mathbb{H}$ -hulls that are path-connected. For two  $\mathbb{H}$ -hulls  $A_1 \subseteq A_2$ , it can be seen using the Optional stopping theorem that hcap $(A_1) \leq \text{hcap}(A_2)$ . Therefore without loss of generality, A can be assumed to be of the form  $\eta(0, T]$  where  $\eta$  is a simple curve with  $\eta(0+) \in \mathbb{R}$ , parameterized so that hcap $[\eta(0, t]) = 2t$ . In particular, T = hcap(A)/2. If  $g_t = g_{\eta(0,t]}$ , then  $g_t$  satisfies the Loewner equation

$$\partial_t g_t(z) = \frac{2}{g_t(z) - U_t}, \quad g_0(z) = z,$$
 (2)

where  $U : [0, T] \to \mathbb{R}$  is continuous. Suppose  $\text{Im}(z)^2 > 2 \text{hcap}(A)$  and let  $Y_t = \text{Im}[g_t(z)]$ . Then (2) gives

$$-\partial_t Y_t^2 \le \frac{4Y_t}{|g_t(z) - U_t|^2} \le 4,$$

which implies

$$Y_T^2 \ge Y_0^2 - 4T > 0$$

This implies that  $z \notin A$ , and hence  $\text{Im}[A]^2 \leq 2 \text{hcap}(A)$ .

The next lemma is a variant of the Vitali covering lemma. If c > 0 and  $z = x + iy \in \mathbb{H}$ , let

$$\mathscr{I}(z,c) = (x - cy, x + cy),$$
$$\mathscr{R}(z,c) = \mathscr{I}(z,c) \times (0, y] = \{x' + iy' : |x' - x| < cy, 0 < y' \le y\}$$

**Lemma 2.** Suppose *A* is a weakly bounded  $\mathbb{H}$ -hull and c > 0. Then there exists a finite or countably infinite sequence of points  $\{z_1 = x_i + iy_1, z_2 = x_2 + iy_2, ...\} \subset A$  such that:

- $y_1 \ge y_2 \ge y_3 \ge \cdots;$
- the intervals  $\mathscr{I}(x_1, c), \mathscr{I}(x_2, c), \ldots$  are disjoint;
  - $A \subset \bigcup_{j=1}^{\infty} \mathscr{R}(z_j, 2c).$ (3)

*Proof.* We define the points recursively. Let  $A_0 = A$  and given  $\{z_1, \ldots, z_i\}$ , let

$$A_j = A \setminus \left[ \bigcup_{k=1}^j \mathscr{R}(z_j, 2c) \right].$$

If  $A_j = \emptyset$  we stop, and if  $A_j \neq \emptyset$ , we choose  $z_{j+1} = x_{j+1} + iy_{j+1} \in A$  with  $y_{j+1} = \text{Im}[A_j]$ . Note that if  $k \leq j$ , then  $|x_{j+1} - x_k| \geq 2c y_k \geq c (y_k + y_{j+1})$  and hence  $\mathscr{I}(z_{j+1}, c) \cap \mathscr{I}(z_k, c) = \emptyset$ . Using the weak boundedness of A, we can see that  $y_j \to 0$  and hence (3) holds.

**Lemma 3.** For every c > 0, let

$$\rho_c := rac{2\sqrt{2}}{\pi} \arctan\left(e^{- heta}\right), \quad \theta = \theta_c = rac{\pi}{4c}$$

Then, for any c > 0, if A is a weakly bounded  $\mathbb{H}$ -hull and  $x_0 + iy_0 \in A$  with  $y_0 = \text{Im}(A)$ , then

$$\operatorname{hcap}(A) \ge \rho_c^2 y_0^2 + \operatorname{hcap}\left[A \setminus \mathscr{R}(z, 2c)\right].$$

*Proof.* By scaling and invariance under real translation, we may assume that  $\text{Im}[A] = y_0 = 1$  and  $x_0 = 0$ . Let  $S = S_c$  be defined to be the set of all points z of the form x + iuy where  $x + iy \in A \setminus \mathscr{R}(i, 2c)$  and  $0 < u \le 1$ . Clearly,  $S \cap A = A \setminus \mathscr{R}(i, 2c)$ . Using the capacity inequality [1, (3.10)]

$$\operatorname{hcap}(A_1 \cup A_2) - \operatorname{hcap}(A_2) \le \operatorname{hcap}(A_1) - \operatorname{hcap}(A_1 \cap A_2), \tag{4}$$

we see that

$$hcap(S \cup A) - hcap(S) \le hcap(A) - hcap(S \cap A).$$

Hence, it suffices to show that

$$\operatorname{hcap}(S \cup A) - \operatorname{hcap}(S) \ge \rho_c^2.$$

Let *f* be the conformal map of  $\mathbb{H} \setminus S$  onto  $\mathbb{H}$  such that z - f(z) = o(1) as  $z \to \infty$ . Let  $S^* := S \cup A$ . By properties of halfplane capacity [1, (3.8)] and (1),

$$\operatorname{hcap}(S^*) - \operatorname{hcap}(S) = \operatorname{hcap}[f(S^* \setminus S)] \ge \frac{\operatorname{Im}[f(i)]^2}{2}.$$

Hence, it suffices to prove that

$$\operatorname{Im}[f(i)] \ge \sqrt{2}\rho = \frac{4}{\pi} \arctan\left(e^{-\theta}\right).$$
(5)

By construction,  $S \cap \mathscr{R}(z, 2c) = \emptyset$ . Let  $V = (-2c, 2c) \times (0, \infty) = \{x + iy : |x| < 2c, y > 0\}$  and let  $\tau_V$  be the first time that a Brownian motion leaves the domain. Then [1, (3.5)],

$$\operatorname{Im}[f(i)] = 1 - \mathbb{E}^{i} \left[ \operatorname{Im}(B_{\tau_{s}}) \right] \geq \mathbb{P} \left\{ B_{\tau_{s}} \in [-2c, 2c] \right\} \geq \mathbb{P} \left\{ B_{\tau_{v}} \in [-2c, 2c] \right\}.$$

The map  $\Phi(z) = \sin(\theta z)$  maps *V* onto  $\mathbb{H}$  sending [-2c, 2c] to [-1, 1] and  $\Phi(i) = i \sinh \theta$ . Using conformal invariance of Brownian motion and the Poisson kernel in  $\mathbb{H}$ , we see that

$$\mathbb{P}\left\{B_{\tau_{V}} \in \left[-2c, 2c\right]\right\} = \frac{2}{\pi} \arctan\left(\frac{1}{\sinh\theta}\right) = \frac{4}{\pi} \arctan\left(e^{-\theta}\right).$$

The second equality uses the double angle formula for the tangent.

**Lemma 4.** Suppose c > 0 and  $x_1 + iy_1, x_2 + iy_2, \dots$  are as in Lemma 2. Then

hsiz(A) 
$$\leq [\pi + 8c] \sum_{j=1}^{\infty} y_j^2$$
. (6)

If  $c \geq 1$ , then

$$\pi \sum_{j=1}^{\infty} y_j^2 \le \operatorname{hsiz}(A).$$
(7)

*Proof.* A simple geometry exercise shows that

area 
$$\left[\bigcup_{x+iy\in\mathscr{R}(z_j,2c)}\mathscr{B}(x+iy,y)\right] = [\pi+8c]y_j^2.$$

Since

$$A \subset \bigcup_{j=1}^{\infty} \mathscr{R}(z_j, 2c),$$

the upper bound in (6) follows. Since  $c \ge 1$ , and the intervals  $\mathscr{I}(z_j, c)$  are disjoint, so are the disks  $\mathscr{B}(z_j, y_j)$ . Hence,

$$\operatorname{area}\left[\bigcup_{x+iy\in A}\mathscr{B}(x+iy,y)\right] \ge \operatorname{area}\left[\bigcup_{j=1}^{\infty}\mathscr{B}(z_j,y_j)\right] = \pi \sum_{j=1}^{\infty} y_j^2.$$

*Proof of Theorem 1.* Let  $V_j = A \cap \mathscr{R}(z_j, c)$ . Lemma 3 tells us that

hcap 
$$\left[\bigcup_{k=j}^{\infty} V_{j}\right] \ge \rho_{c}^{2} y_{j}^{2} + hcap \left[\bigcup_{k=j+1}^{\infty} V_{j}\right],$$

and hence

$$\operatorname{hcap}(A) \ge \rho_c^2 \sum_{j=1}^{\infty} y_j^2.$$
(8)

Combining this with the upper bound in (6) with any c > 0 gives

$$\frac{\operatorname{hcap}(A)}{\operatorname{hsiz}(A)} \ge \frac{\rho_c^2}{\pi + 8c}.$$

Choosing  $c = \frac{8}{5}$  gives us

$$\frac{\operatorname{hcap}(A)}{\operatorname{hsiz}(A)} > \frac{1}{66}.$$

For the upper bound, choose a covering as in Lemma 2. Subadditivity and scaling give

$$\operatorname{hcap}(A) \leq \sum_{j=1}^{\infty} \operatorname{hcap}\left[\mathscr{R}(z_j, 2cy_j)\right] = \operatorname{hcap}[\mathscr{R}(i, 2c)] \sum_{j=1}^{\infty} y_j^2.$$
(9)

Combining this with the lower bound in (6) with c = 1 gives

$$\frac{\operatorname{hcap}(A)}{\operatorname{hsiz}(A)} \le \frac{\operatorname{hcap}[\mathscr{R}(i,2)]}{\pi}.$$

Note that  $\Re(i,2)$  is the union of two real translates of  $\Re(i,1)$ ,  $hcap[\Re(i,2)] \le 2hcap[\Re(i,1)]$  whose intersection is the interval (0,i]. Using (4), we see that

$$\operatorname{hcap}(\mathscr{R}(i,2)) \leq 2\operatorname{hcap}(\mathscr{R}(i,1)) - \operatorname{hcap}((0,i]) = 2\operatorname{hcap}(\mathscr{R}(i,1)) - \frac{1}{2}.$$

But  $\mathscr{R}(i, 1)$  is strictly contained in  $A' := \{z \in \mathbb{H} : |z| \le \sqrt{2}\}$ , and hence

$$\operatorname{hcap}[\mathscr{R}(i,1)] < \operatorname{hcap}(A') = 2.$$

#### Interpretation of Capacity

The last equality can be seen by considering  $h(z) = z + 2z^{-1}$  which maps  $\mathbb{H} \setminus A'$  onto  $\mathbb{H}$ . Therefore,

$$\operatorname{hcap}[\mathscr{R}(i,2)] < \frac{7}{2},$$
$$\frac{\operatorname{hcap}(A)}{\operatorname{hsiz}(A)} < \frac{7}{2\pi}.$$

and hence

An equivalent form of this result can be stated<sup>4</sup> in terms of the area of the 1-neighborhood of A (denoted hyp(A)) in the hyperbolic metric. The unit hyperbolic ball centered at a point  $x + \iota y$  is the Euclidean ball with respect to which  $x + \iota y/e$ ) and  $x = \iota ye$  are diametrically opposite boundary points. For any *c*, choosing a covering as in Lemma 2,

$$\operatorname{hyp}(A) < \left( \left(\frac{e}{2}\right)^2 \pi + 4ec \right) \sum_{j=1}^{\infty} y_j^2.$$

So by (8),

$$\frac{\operatorname{hcap}(A)}{\operatorname{hyp}(A)} > \rho_c^2 \left( \left(\frac{e}{2}\right)^2 \pi + 4ec \right)^{-1}.$$

Setting *c* to  $\frac{8}{5}$ ,

$$\frac{\mathrm{hcap}(A)}{\mathrm{hyp}(A)} > \frac{1}{100}.$$

For any  $c > \frac{e-e^{-1}}{2}$ ,

hyp(A) 
$$\ge \pi \left(\frac{e - e^{-1}}{2}\right)^2 \sum_{j=1}^{\infty} y_j^2.$$

So by (9),

$$\frac{\operatorname{hcap}(A)}{\operatorname{hyp}(A)} < \frac{\operatorname{hcap}[\mathscr{R}(i,3)]}{\pi \left(\frac{e-e^{-1}}{2}\right)^2}.$$

 $\operatorname{hcap}(\mathscr{R}(i,3)) \leq \operatorname{hcap}(\mathscr{R}(i,1)) + \operatorname{hcap}(\mathscr{R}(i,2)) - \operatorname{hcap}((0,i]) \leq 5.$ 

Therefore,

$$\frac{1}{100} < \frac{\text{hcap}(A)}{\text{hyp}(A)} < \frac{20}{\pi (e - e^{-1})^2}.$$

#### References

[1] G. Lawler, *Conformally Invariant Processes in the Plane*, American Mathematical Society, 2005. MR2129588

<sup>&</sup>lt;sup>4</sup>This formulation was suggested to us by Scott Sheffield and the anonymous referee.