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Pivotality versus noise stability for monotone transitive functions*

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Abstract

We construct a noise stable sequence of transitive, monotone increasing Boolean functions $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,1\}$ which admit many pivotals with high probability. We show that such a sequence is volatile as well, and thus it is also an example of a volatile and noise stable sequence of transitive, monotone functions.

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1 Introduction

In this note we answer the following question posed by Gil Kalai and Gady Kozma (Oberwolfach, September 2018): Is there a sequence of Boolean functions $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,1\}$ such that f_n is transitive and noise stable, but at the same time $\mathbb{P}[\operatorname{Piv}_n(\omega) \neq \emptyset] > c$ for some constant c>0 for all $n\in\mathbb{N}$?

We are going to show that the answer is positive.

Theorem 1.1. There exists a sequence of symmetric, transitive, monotone functions $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,1\}$ such that f_n is noise stable and $\lim_n \mathbb{P}[\operatorname{Piv}_n > a_n] = 1$ (here Piv_n is the pivotal set, see below) for some sequence of integers $a_n \to \infty$.

We begin by giving the necessary definitions. For further details on noise sensitivity, noise stability and their relation to the pivotal set see [GS15].

Let Γ be a group acting on the set of coordinates $[n]=\{1,2\ldots,n\}$. This action can be extended in the natural way to the configuration space $\{-1,1\}^n$, and in turn to any function $f:\{-1,1\}^n\longrightarrow \mathbb{R}$. For a function $f:\{-1,1\}^n\longrightarrow \mathbb{R}$, we denote by $f^{\gamma}(x):=f(x^{-\gamma})$ the action of $\gamma\in\Gamma$ on f.

Now f is called transitive if there is a transitive group action Γ on [n] such that $f^{\gamma}=f$ for every $\gamma\in\Gamma$. In the language of social choice theory the transitivity of a voting scheme can be interpreted as each voters are treated the same. We call a function $f:\{-1,1\}^n\longrightarrow\mathbb{R}$ transitive if there is a transitive group action on the coordinate set n and f is invariant under this action. Furthermore, in case $f(-\omega)=-f(\omega)$, for every $\omega\in\{-1,1\}^n$, we say that f is symmetric.

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Definition 1.2 (Pivotal Set). The pivotal set for a Boolean function $f: \{-1,1\}^n \longrightarrow \{-1,1\}$ is the random set of coordinates i for which $f(\omega) \neq f(\omega^i)$, where ω^i is ω with its ith coordinate flipped.

Definition 1.3 (Noise Sensitivity). Let ϵ be a positive real number. For a uniform random vector $\omega \in \{-1,1\}^{k_n}$ denote $N_{\epsilon}(\omega)$ the random vector which we obtain from ω by resampling each of its bits independently with probability ϵ . A sequence of functions $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,1\}$ is noise sensitive if

$$\lim_{n \to \infty} \text{Cov}(f_n(\omega), f_n(N_{\epsilon}(\omega))) = 0$$
(1.1)

Definition 1.4 (Noise Stability). A sequence of functions $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,1\}$ is noise stable if

$$\lim_{\epsilon \to 0} \sup_{n} \mathbb{P}[f_n(\omega) \neq f_n(N_{\epsilon}(\omega))] = 0 \tag{1.2}$$

In [GS15] Section XII. 2 a sequence of monotone, non-degenerate and noise stable Boolean functions is presented which has many pivotals with a positive probability (The construction is due to O. Schramm). This example, however, is not transitive.

These types of questions are interesting since noise sensitivity and having many pivotals are often closely related to each other; see, e.g., the case of crossing events in planar percolation [GPS10]. Noise sensitivity and noise stability of a function can both be expressed in terms of the typical size of the Spectral Sample, which is also a random subset of the index set (see [GS15]). It is an interesting fact that the first and second order marginals of the pivotal set and the spectral sample are the same. This (falsely) suggests that for a noise stable functions the pivotal set is typically small. Our result is another indication that, in general, these two random sets may show very different behavior.

Another dynamical property of Boolean functions, which may look, at first glance, almost the same as noise sensitivity, is volatility, studied in [JS16]. It roughly says that if we are updating the input bits in continuous time, then the output changes very often; see Definition 3.1 below. In Lemma 3.2 we show that having many pivotals implies being volatile, hence we obtain the following

Corollary 1.5. There exists a noise stable and volatile sequence of transitive and symmetric monotone Boolean functions.

Our construction also implies, see Corollary 3.3 below, that every (monotone) Boolean function is close to a (monotone) Boolean function that has many pivotals with high probability. As functions with these properties are also volatile, this is a strengthening of Theorem 1.4 in [F18].

2 Construction

In the sequel, we shall construct a sequence of functions $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,0,1\}$ with the following properties:

- 1. f_n is transitive
- 2. $\lim_{n} \mathbb{P}[f_n = 0] = 1$
- 3. $\lim_{n} \mathbb{P}[\exists i, j \in [k_n] : f_n(\omega^i) = 1 \text{ and } f_n(\omega^j) = -1] = 1$,

where ω^i denotes ω with its *i*th coordinate flipped. We will call a sequence of functions bribable if it satisfies the above conditions.

Using a bribable sequence f_n one can easily construct a noise stable sequence g_n of transitive, symmetric Boolean functions which admits a pivotal bit with high probability. Namely, let Maj_n denote the majority function on the corresponding bit set. Let

$$g_n = \begin{cases} \operatorname{Maj}_n & \text{if } f_n = 0 \\ f_n & \text{if } f_n \neq 0. \end{cases}$$

Obviously g_n is noise stable because of property 2 of f_n . On the other hand, conditioned on $\{f_n=0\}$ there is a pivotal bit with high probability because of property 3 of the sequence f_n .

It is also straightforward to verify that if we choose a bribable sequence f_n which is monotone and/or symmetric then the resulting g_n sequence will consist of monotone and/or symmetric functions as well (using that Maj_n is monotone and symmetric).

Now we turn to the construction of a monotone and symmetric bribable sequence. Define the Boolean function $\operatorname{Tribes}(l,k): \{-1,1\}^{lk} \longrightarrow \{0,1\}$ as follows: we group the bits in k l-element subsets, these are the so called tribes. The function takes on 1 if there is a tribe T such that for every $i \in T: \omega(i)=1$, and 0 otherwise. The Tribes function is standard example, when k_n and l_n are defined in such a way that the function is non-degenerate. It is well know that such a sequence testifies that the Kahn-Kalai-Linial theorem about the maximal influence of sequences of Boolean functions (Theorem 1.14 in [GS15]) is sharp.

We are going to show that in case the two sequences l_n, k_n are properly chosen, a slight modification of Tribes (l_n, k_n) is bribable.

Proposition 2.1. Suppose that l_n and k_n are sequences such that

$$\lim_{n \to \infty} \frac{k_n}{2^{l_n}} = 0 \tag{2.1}$$

and

$$\lim_{n \to \infty} l_n \frac{k_n}{2l_n} = \infty \tag{2.2}$$

then the sequence of functions $f_n(\omega) := \operatorname{Tribes}(l_n, k_n)(\omega) - \operatorname{Tribes}(l_n, k_n)(-\omega)$ is bribable. Moreover, there is a sequence of positive integers $a_n \to \infty$ such that $\mathbb{P}[|\operatorname{Piv}_n| > a_n] \to 1$.

Proof. Let us call a tribe T pivotal if there is exactly one $j \in T$ such that $\omega(j) = -1$. Define the random variable X_n as the number of pivotal tribes in a configuration. Note that $\mathbb{E}[X_n] = k_n l_n \frac{1}{2l_n}$.

It is clear that conditioned on the event $\{\text{Tribes}(l_n,k_n)=0\}$ we have $|\text{Piv}_n|=X_n$, where $|\text{Piv}_n|$ denotes the pivotal set of $\text{Tribes}(l_n,k_n)$. Consequently, for the respective conditional expected values:

$$\mathbb{E}[\mathsf{Piv}_n|\mathsf{Tribes}(l_n,k_n)=0]=\mathbb{E}[X_n|\mathsf{Tribes}(l_n,k_n)=0].$$

We can write $X_n = \sum_j^{k_n} Y_j$ where Y_j is the indicator of the event that the jth tribe is pivotal. For any $j \in [k_n]$ we have

$$\mathbb{P}[Y_j = 1 | \mathsf{Tribes}(l_n, k_n) = 1] = \frac{\mathbb{P}[Y_j = 1] \mathbb{P}[\mathsf{Tribes}(l_n, k_n - 1) = 1]}{\mathbb{P}[\mathsf{Tribes}(l_n, k_n) = 1]} \leq \mathbb{P}[Y_j = 1],$$

using that if the jth tribe is pivotal and there is a full 1 tribe then the latter is among the remaining k_n-1 tribes. This implies

$$\mathbb{E}[X_n|\mathsf{Tribes}(l_n,k_n)=1] \leq \mathbb{E}[X_n] \leq \mathbb{E}[X_n|\mathsf{Tribes}(l_n,k_n)=0]$$

and therefore

$$\mathbb{E}[\mathsf{Piv}_n|\mathsf{Tribes}(l_n,k_n)=0] \geq \mathbb{E}[X_n] = k_n l_n \frac{1}{2^{l_n}} \to \infty.$$

As X_n is binomially distributed with $\mathbb{E}[X_n] \to \infty$, being the sum of i.i.d. 0-1-valued random variables, there is a $a_n \to \infty$ such that

$$\lim_{n \to \infty} \mathbb{P}[X_n > a_n] = 1.$$

Observe that

$$\mathbb{P}[\mathsf{Tribes}(l_n,k_n)=0] = \left(1-\frac{1}{2^{l_n}}\right)^{k_n} \to 1.$$

Indeed, elementary calculus shows that

$$\left(1-\frac{1}{2^{l_n}}\right)^{k_n} \to 1 \text{ if and only if } \frac{k_n}{2^{l_n}} \to 0,$$

which is just (2.1) and thus holds by assumption. So clearly

$$\mathbb{P}[X_n > a_n \text{ and Tribes}(l_n, k_n) = 0] = \mathbb{P}[|\mathsf{Piv}_n| > a_n, \text{ and Tribes}(l_n, k_n) = 0] \to 1$$

and therefore also

$$\lim_{n\to\infty} \mathbb{P}[|\mathsf{Piv}_n| > a_n \mid \mathsf{Tribes}(l_n, k_n) = 0] = 1.$$

The same argument can be repeated for $-\mathsf{Tribes}(l_n,k_n)(-\omega)$. The event that neither $\mathsf{Tribes}(l_n,k_n)(\omega)$ nor $\mathsf{Tribes}(l_n,k_n)(-\omega)$ happens while the pivotal set of both is larger than a_n still holds with high probability. That is, we find pivotal bits for both $\mathsf{Tribes}(l_n,k_n)(\omega)$ and $\mathsf{Tribes}(l_n,k_n)(-\omega)$ with high probability and thus push $f_n=\mathsf{Tribes}(l_n,k_n)(\omega)-\mathsf{Tribes}(l_n,k_n)(-\omega)$ to 1 or -1, respectively.

Furthermore Tribes $(l_n,k_n)(\omega)$ – Tribes $(l_n,k_n)(-\omega)$ is monotone increasing as the sum of monotone increasing functions.

Now it only remains to show that with an appropriate choice of the sequences k_n and l_n (2.1) and (2.2) are satisfied.

First, taking the logarithm of (2.1) yields the condition

$$\log k_n - l_n \to -\infty. \tag{2.3}$$

Second, taking again logarithm from both sides in (2.2) we get

$$\log k_n + \log l_n - l_n \to \infty. \tag{2.4}$$

If we now choose $l_n = \log k_n + \frac{1}{2} \log \log k_n$ then clearly (2.3) is satisfied. As for (2.4), using that $\log l_n \ge \log \log k_n$

$$\log k_n + \log l_n - l_n \le \log k_n + \log \log k_n - (\log k_n + \frac{1}{2} \log \log k_n) = \frac{1}{2} \log \log k_n \to \infty.$$

Finally, we note that the argument remains valid with some elementary modifications in case if, instead of the uniform measure we endow the hypercube with the product measure $\mathbb{P}_p = (1 - p\delta_{-1} + p\delta_1)^{\otimes k_n}$ for some $p \in (0,1)$.

3 Volatility

Let $X_n(t)$ be the continuous time random walk on the k_n hypercube (where $X_n(0)$ is sampled according to the stationary measure) with rate 1 clocks on the edges. For a sequence of Boolean functions f_n let C_n denote the (random) number of times $f_n(X_n(t))$ changes value in the interval [0,1]. The following concepts where introduced in [JS16].

Definition 3.1 (Volatility, tameness). A sequence of functions $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,1\}$ is called volatile if the sequence C_n tends to ∞ in distribution and tame, if the sequence C_n is tight.

It is a (rather intuitive) fact that a non-degenerate noise sensitive sequence is volatile (Proposition 1.17 in [JS16]) and all tame sequences are noise stable (Proposition 1.13 in [JS16]). The Maj function is noise stable, but not tame and not volatile either.

Now we are going to relate our conditions to volatility.

Lemma 3.2. Let $f_n: \{-1,1\}^{k_n} \longrightarrow \{-1,1\}$ be a sequence of Boolean functions with the property that there is a sequence of positive integers $a_n \to \infty$ such that $\mathbb{P}[|\mathsf{Piv}_n| > a_n] \to 1$ (where Piv_n denotes the pivotal set of of f_n). Then f_n is volatile.

Proof. Let $A_n:=\{|\mathsf{Piv}_n|\leq a_n\}$. It is clear that $\mathbb{E}[\int_0^1\mathbb{1}_{X_n(t)\in A_n}dt]=\mathbb{P}[|\mathsf{Piv}_n|\leq a_n]\to 0$ so for every ϵ for large enough n it holds that

$$\mathbb{E}[\int_0^1 \mathbb{1}_{X_n(t) \in A_n} dt] < \epsilon^2$$

and therefore, using Markov's inequality

$$\mathbb{P}[\int_0^1 \mathbb{1}_{X_n(t) \in A_n} dt > \epsilon] < \epsilon.$$

By Lemma 1.5 in [JS16] volatility is equivalent with the condition

$$\lim_{n} \mathbb{P}[C_n = 0] = 0.$$

Now we show that $\mathbb{P}[C_n=0]$ can be arbitrary small. If we choose n large enough so that $e^{-(1-\epsilon)a_n}<\epsilon$

$$\mathbb{P}[C_n=0] \leq \mathbb{P}[\int_0^1 \mathbb{1}_{X_n(t) \in A_n} dt > \epsilon] + \mathbb{P}[\int_0^1 \mathbb{1}_{X_n(t) \in A_n} dt \leq \epsilon \text{ and } C_n=0] \leq \epsilon + e^{-(1-\epsilon)a_n} < 2\epsilon,$$

where we used that $C_n = 0$ can only hold as long as no pivotal bit is switched during the time we are outside of A_n .

We say that the sequences f_n and g_n o(1)-close to each other if $\lim_n \mathbb{P}[f_n \neq g_n] = 0$. In [F18] it is proved (Theorem 1.4) that for every sequence of Boolean functions there is a volatile sequence o(1)-close to it and in this sense volatile sequences are dense among all sequences of Boolean functions. Our construction has a similar conclusion. Using the fact that any sequence of Boolean functions can be slightly modified with a bribable sequence in the same way as we did with Maj, we obtain the following strengthening of Theorem 1.4 from [F18]:

Corollary 3.3. Any sequence of (monotone and/or symmetric) Boolean functions is o(1)-close to a (monotone and/or symmetric) volatile sequence with the property that $\mathbb{P}[\operatorname{Piv}_n > a_n] \to 1$ for some sequence of integers $a_n \to \infty$.

Although here we consider the uniform measure on the hypercube the same type of questions are meaningful when the uniform measure is replaced by the sequence of product measures $\mathbb{P}_{p_n}=(1-p_n\delta_{-1}+p_n\delta_1)^{\otimes k_n}$. It has to be noted that Theorem 1.4 in [F18] is valid for basically all possible sequences p_n under which the question is meaningful, while our construction works in a more restricted range of sequences p_n . Most importantly, our results extend to all sequences p_n that satisfy $0<\liminf p_n\le \limsup p_n<1$.

Furthermore, in [F18] a sequence of Boolean functions is constructed which is noise stable and volatile, but at the same time it is not o(1)-close to any non-volatile sequence.

Such a sequence, of course cannot be obtained with a small modification from some non-volatile stable sequence.

This naturally lead to the following questions:

Question 3.4. Is there a transitive, noise stable (volatile?) sequence f_n such that $\mathbb{P}[\operatorname{Piv}_n(\omega) \neq \emptyset] \to 1$ and f_n is not o(1)-close to any sequence which does not have these properties?

We think that the answer is positive to this question.

Question 3.5. Is there a transitive, monotone and noise stable (volatile?) sequence f_n such that $\mathbb{P}[\operatorname{Piv}_n(\omega) \neq \emptyset] \to 1$ and f_n is not o(1)-close to any sequence which does not have these properties?

This looks more difficult and it might be the case that the answer is negative.

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