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# Power-law partial correlation network models 

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#### Abstract

We introduce a class of partial correlation network models whose network structure is determined by a random graph. In particular in this work we focus on a version of the model in which the random graph has a power-law degree distribution. A number of cross-sectional dependence properties of this class of models are derived. The main result we establish is that when the random graph is power-law, the system exhibits a high degree of collinearity. More precisely, the largest eigenvalues of the inverse covariance matrix converge to an affine function of the degrees of the most interconnected vertices in the network. The result implies that the largest eigenvalues of the inverse covariance matrix are approximately power-law distributed, and that, as the system dimension increases, the eigenvalues diverge. As an empirical illustration we analyse two panels of stock returns of companies listed in the S\&P 500 and S\&P 1500 and show that the covariance matrices of returns exhibits empirical features that are consistent with our power-law model.


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## 1. Introduction

The recent financial crises in the United States and Europe have boosted the interest in network analysis in economics and finance. These crises have forcefully shown that when the degree of interdependence in the system is excessive, a large fraction of firms may experience distress simultaneously, and the magnitude of the aggregate distress may be large relative to the entire system. In the aftermath of these crises, several authors have proposed network estimation techniques for large panels of time series. These methods are typically applied to carry out inference on the degree of interdependence among firms on the basis of market data, such as stock prices. Contributions in this area include the work of Diebold and Yılmaz [16], Hautsch et al. [21, 22], Barigozzi and Brownlees [4], Brownlees et al. [9]. An early influential contribution that analyzed the degree of interconnectedness in the financial system in the US and Europe that predates the crisis is Hartmann et al. [20]. This literature is often motivated by the claim that a high degree of interconnectedness poses threats to the stability of the entire system. However, the notion of excessive interconnectedness is typically not explicitly formalized and it often remains an elusive concept.

In this work we introduce a partial correlation network model for a random vector that is a function of a latent random graph. The model we introduce bridges ideas from partial correlation networks and graphical models [15, 28] together with random graphs [17, 12, 35]. The key feature of the model is that the cross-sectional dependence properties of the components of the random vector depend on the underlying random graph, and by considering different types of random graphs one can generate models with different cross-sectional dependence properties. In particular, in this work we focus on the important special case in which the random graph has a power-law degree distribution. This class of models is often documented to replicate well the empirical characteristics of many real-world networks [12, 35], like "small world" effects and hubs. We name the model the power-law partial correlation network model.

We derive a number of properties of the power-law partial correlation network model we introduce. The key result we establish concerns the spectrum of the covariance matrix of the random vector. We show that when the dimension of the system is large, the largest eigenvalues of the inverse covariance matrix (also known as the concentration matrix) converge to a positive affine transformation of the degrees of the most interconnected vertices. This result has a number of implications from the perspective of the class of models we consider. First, when the underlying graph has a power-law structure then the system can exhibit an excessive degree of collinearity. More precisely, the condition number of the covariance matrix diverges as the cross-sectional dimension increases. Second, the largest eigenvalues of the concentration matrix can be used to learn the power-law tail parameter of the random graph, which characterizes the power-law structure of the network. This allows us to carry out inference on the degree of interdependence in the system without having to estimate the underlying partial correlation structure of the data (typically, using LASSO as
in Peng et al. [30]), which can be computationally challenging when the system dimensionality is large.

As an empirical illustration, we analyze the covariance matrix of two large panels of stock returns of companies listed in the S\&P 500 and S\&P 1500 indices. We propose an estimator of the tail parameter of the power-law degree distribution based on the eigenvalues of the concentration matrix building up on standard procedures proposed in the literature. Estimation results deliver a power-law tail parameter lower than three, which signals, from the standpoint of our model, the presence of highly influential assets.

This paper is related to the literature on network estimation in econometrics and statistics which includes, among others, the work of Diebold and Yılmaz [16], Hautsch et al. [21, 22] and Barigozzi and Brownlees [4]. Our main message has analogies to the contribution of Acemoglu et al. [1] that shows that because of network interdependence among firms, firm specific shocks can lead to aggregate system fluctuations.

The paper is structured as follows. Section 2 presents the framework and the main results. Sections 3 and 4 provide illustrations using simulated and real data. Concluding remarks follow in Section 5.

## 2. Framework

### 2.1. Partial correlation network model

Consider an $n$-dimensional random vector $\boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{n}\right)$ that is assumed to have mean zero and invertible covariance matrix $\boldsymbol{\Sigma}=\left(\mathbb{E}\left[Y_{i} Y_{j}\right]\right)_{n \times n}$. The inverse covariance matrix $\boldsymbol{K}=\boldsymbol{\Sigma}^{-1}$, also known as the concentration or precision matrix, plays an important role in this paper. It is well known that the concentration matrix contains information on the partial correlation structure among the components of the vector $\boldsymbol{Y}[15,28]$. Partial correlation measures the linear dependence between $Y_{i}$ and $Y_{j}$ after eliminating the linear effects of the remaining $n-2$ variables in the system [see 31, chapter 5]. Formally the partial correlation between $Y_{i}$ and $Y_{j}$ may be defined as follows. Let $\boldsymbol{Y}$ be partitioned in $\left(\boldsymbol{Y}_{1}^{\prime}, \boldsymbol{Y}_{2}^{\prime}\right)^{\prime}$ where $\boldsymbol{Y}_{1}$ is a 2 dimensional vector comprising of $Y_{i}$ and $Y_{j}$ whereas $\boldsymbol{Y}_{2}$ is an $n-2$ dimensional vector comprising of the remaining variables in $\boldsymbol{Y}$. Let $\boldsymbol{\Phi}$ denote the $2 \times(n-2)$ matrix of linear least-squares regression coefficients associated with the regression of $\boldsymbol{Y}_{1}$ on $\boldsymbol{Y}_{2}$ and let $\boldsymbol{U}$ denote the vector of regression residuals $\boldsymbol{Y}_{1}-\boldsymbol{\Phi} \boldsymbol{Y}_{2}$. Then, the partial correlation coefficient $\rho^{i j}$ between $Y_{i}$ and $Y_{j}$ is defined as

$$
\rho^{i j}=\operatorname{Cor}\left(U_{1}, U_{2}\right) .
$$

Partial correlations can be expressed as a function of the entries $k_{i j}$ of the concentration matrix $\boldsymbol{K}$ using the identity

$$
\rho^{i j}=-\frac{k_{i j}}{\sqrt{k_{i i} k_{j j}}} .
$$

Thus, the $(i, j)$ entry of the concentration matrix $\boldsymbol{K}$ is zero if and only if $Y_{i}$ and $Y_{j}$ are partially uncorrelated given all other variables in the system.

In this work we propose a model for the concentration matrix $\boldsymbol{K}$ that is a function of an underlying network $\mathcal{N}$. A network $\mathcal{N}$ is defined as a simple undirected $\operatorname{graph}(\mathcal{V}, \mathcal{E})$ where $\mathcal{V}=\{1, \ldots, n\}$ is the set of vertices and $\mathcal{E}$ is the set of edges. There are a number of matrices associated with a network that are relevant in this work: the degree, the adjacency, and Laplacian matrices. The degree matrix $\boldsymbol{D}$ is defined as a diagonal matrix whose entry $D_{i i}=[\boldsymbol{D}]_{i i}$ is equal to the degree of vertex $i$, that is, the number of edges adjacent to vertex $i$. The degree of vertex $i$ is also denoted by $D_{i}$. The adjacency matrix $\boldsymbol{A}$ is defined as a matrix whose entry $A_{i, j}=[\boldsymbol{A}]_{i, j}$ is one if $i$ and $j$ are connected by an edge and it is zero otherwise. Notice that the adjacency matrix is symmetric and its diagonal terms are zero. Finally, the Laplacian matrix $\boldsymbol{L}$ of a network is defined as $\boldsymbol{L}=\boldsymbol{D}-\boldsymbol{A}$.

We now describe a simple model for a multivariate random vector whose partial correlation dependence structure is determined by a network.

Definition 1. (PARTIAL CORRELATION NETWORK MODEL) We say that the random vector $\boldsymbol{Y}$ is generated by a partial correlation network model based on network $\mathcal{N}$ and scalars $\sigma^{2}>0$ and $\phi \geq 0$ if $\boldsymbol{Y}$ has a multivariate distribution with mean zero and concentration matrix

$$
\boldsymbol{K}=\frac{1}{\sigma^{2}} \boldsymbol{I}+\frac{\phi}{\sigma^{2}} \boldsymbol{L}
$$

where $\boldsymbol{L}$ is the Laplacian matrix of $\mathcal{N}$. The coefficients $\sigma^{2}$ and $\phi$ are called the variance and the network dependence parameters, respectively.

A number of comments is in order. Our model establishes a link between the concentration matrix of the random vector $\boldsymbol{Y}$ and the Laplacian of the network $\mathcal{N}$. This is a natural model in many situations. The Laplacian matrix often arises in network analysis as its spectrum encodes several key properties of the network. For instance, the number of connected components of the network is equal to the number of zero eigenvalues of the Laplacian. Moreover, indices of centrality, inter alia eigenvector centrality, are associated with the largest eigenvalues of the Laplacian as well. We refer to Chung [11] and Brouwer and Haemers [8] for good general introductions to spectral graph theory. Importantly, the model ensures that the partial correlation between $Y_{i}$ and $Y_{j}$ is zero if and only if there is no edge between $i$ and $j$ in the network $\mathcal{N}$. Moreover, the Laplacian is diagonally dominant with positive diagonal entries, which implies that $\boldsymbol{K}$ is a strictly diagonally dominant and therefore positive definite.

It is important to clarify what type of relations are captured by the partial correlation network. Our network definition based on partial correlations captures the linear predictive dependence structure of the variables in the system that is implied by the covariance matrix. The partial correlation network can be interpreted as one of the natural generalizations of Gaussian graphical models for non-Gaussian data. If the distribution of $\boldsymbol{Y}$ is Gaussian, then the partial
correlation $\rho^{i j}$ is equal to the conditional correlation $\operatorname{Cor}\left(Y_{i}, Y_{j} \mid\left\{Y_{k}: 1 \leq k \leq\right.\right.$ $n, k \neq i, j\})$. Therefore, in this case, $\rho^{i j}=0$ implies that $Y_{i}$ and $Y_{j}$ are conditionally independendent and the partial correlation network can be interpreted as a conditional independence graph.

We provide a number of properties of the model of Definition 1 that are straightforward to verify. We begin with the regression representation of the model. The $i$-th variable in the system can be expressed as

$$
Y_{i}=\sum_{j \in N(i)} \frac{\phi}{\phi D_{i}+1} Y_{j}+\epsilon_{i}
$$

where $N(i)$ denotes the set of neighbors of vertex $i$ and $\epsilon_{i}$ is a prediction error term with mean zero and variance $\sigma_{\epsilon i}^{2}=\sigma^{2} /\left(1+\phi D_{i}\right)$. Rearranging terms, we get

$$
Y_{i}=\left(\frac{D_{i}}{D_{i}+1 / \phi}\right) \frac{1}{D_{i}} \sum_{j \in N(i)} Y_{j}+\epsilon_{i}=\frac{\psi_{i}}{D_{i}} \sum_{j \in N(i)} Y_{j}+\epsilon_{i}
$$

where $\psi_{i}=D_{i} /\left(D_{i}+1 / \phi\right)$. The last equation shows that conditionally on the other variables in the system, the realization of the $i$-th variable can be interpreted as a linear function of the average of the neighbors and a location-specific innovation.

The partial correlations implied by the model are

$$
\rho^{i j}=\frac{A_{i, j}}{\sqrt{\left.\left(D_{i}+1 / \phi\right)\left(D_{j}+1 / \phi\right)\right)}}
$$

(recall that $A_{i, j}=\mathbb{1}_{\{i \sim j\}}$ is the indicator of an edge joining vertex $i$ and vertex $j$ ). Expansion of this formula with respect to $\phi$ gives insight to the partial correlation behavior of the model. For $\phi$ close to zero we have that the partial correlations are approximately constant in the sense that, as $\phi \rightarrow 0$,

$$
\rho^{i j}=\phi A_{i, j}+O\left(\phi^{2}\right)
$$

On the other hand, when $\phi$ is large, the magnitude of the partial correlation between two variables is a decreasing function of the number of linkages of each variable, that is, as $\phi \rightarrow \infty$,

$$
\rho^{i j}=\frac{A_{i, j}}{\sqrt{D_{i} D_{j}}}+O\left(\phi^{-1}\right)
$$

The covariance matrix $\boldsymbol{\Sigma}$ of the system (see Proposition 1 in the Appendix) is

$$
\boldsymbol{\Sigma}=\sigma^{2}(\boldsymbol{I}+\phi \boldsymbol{D})^{-1}+\frac{\sigma^{2}}{\phi} \sum_{k=1}^{\infty} \boldsymbol{W}_{k}
$$

where $\boldsymbol{W}_{k}$ is what we call the weighted walk matrix of length $k$, defined as

$$
\left[\boldsymbol{W}_{k}\right]_{i, j}=\sum_{w \in \mathcal{W}_{k}} \frac{\mathbb{1}_{\{w \text { goes from } i \text { to } j\}}}{\prod_{v \in \mathcal{V}(w)}(d(v)+1 / \phi)},
$$

where $\mathcal{W}_{k}$ denotes the set of walks of length $k$ (i.e., sequences of vertices $v_{1}, \ldots, v_{k+1}$ such that for $i=1, \ldots, k$ we have that $v_{i}$ and $v_{i+1}$ are joined by an edge) in the network, $\mathcal{V}(w)$ denotes the set of vertices in walk $w, d(v)$ denotes the degree of vertex $v$ and $\mathbb{1}$ is the indicator function. Notice that two variables are correlated if and only if there exists a path in the graph that connects them and that the higher the number of walks between two variables the higher their correlation is (importantly, this is due to the fact that in our model all partial correlations are positive).

An important characteristics of our model is that it does not have a factor structure in the sense of, for example, Chamberlain and Rothschild [10], Stock and Watson $[33,34]$, and Bai [3]. According to their definitions, if $\boldsymbol{\Sigma}$ has an $r$-factor structure then its $r$ largest eigenvalues diverge as the cross-sectional dimension increases at a rate $O(n)$, while the remaining $n-r$ stay bounded. However, in the partial-correlation network model it is straightforward to see that the eigenvalues of $\boldsymbol{\Sigma}$ are bounded from above. Indeed, let $\lambda_{i}^{M}$ denote the $i$-th eigenvalue of a matrix $\boldsymbol{M}$ in a non-increasing order. Then, we have

$$
\lambda_{1}^{\boldsymbol{\Sigma}}=\frac{1}{\lambda_{n}^{\boldsymbol{K}}}=\frac{\sigma^{2}}{1+\phi \lambda_{n}^{\boldsymbol{L}}}=\sigma^{2}
$$

which follows from the fact that the smallest eigenvalue of the Laplacian of a network is zero. It is possible to consider our model as complementary to a factor model. Indeed, in the presence of a factor structure, a partial-correlation network structure can be defined for the idiosyncratic component (the component not driven by the factors) without violating the standard assumptions of factor models.

### 2.2. Partial correlation network model and random graphs

An interesting feature of the partial correlation network model we have introduced is that its cross-sectional dependence properties depend on the choice of the underlying network $\mathcal{N}$. In this work we model the underlying network $\mathcal{N}$ as a random graph. In particular, we work with an inhomogeneous random graph model known as the Chung-Lu model [12, 6]. The Chung-Lu model is a generalization of the classical Erdős-Rényi random graph [17] that allows one to model general degree distributions. In particular, the Chung-Lu model offers a flexible and versatile tool to model and analyze random graphs with a power-law degree distributions.
Definition 2. (CHUNG-LU RANDOM GRAPH MODEL) Let $\boldsymbol{w}=\left(w_{1} \ldots w_{n}\right)^{\prime} \in \mathbb{R}^{n}$ be a nonnegative weight vector such that

$$
\begin{equation*}
w_{M}^{2}=\max _{i} w_{i}^{2}<\sum_{l=1}^{n} w_{l} \tag{2.1}
\end{equation*}
$$

A Chung-Lu random graph is a simple undirected graph where the existence of an edge between vertex $i$ and $j(i \neq j)$ is determined by an independent Bernoulli
trial with probability

$$
p_{i, j}=\frac{w_{i} w_{j}}{\sum_{l=1}^{n} w_{l}}
$$

The weights $w_{i}$ are closely related to the expected degrees in the random graph, since

$$
\begin{aligned}
\mathbb{E} D_{i} & =\mathbb{E}\left(\sum_{j=1}^{n} A_{i, j}\right)=\sum_{j=1}^{n} p_{i, j} \\
& =\sum_{j: j \neq i}^{n} \frac{w_{i} w_{j}}{\sum_{l=1}^{n} w_{l}}=w_{i} \frac{\sum_{j: j \neq i}^{n} w_{j}}{\sum_{j=1}^{n} w_{j}} \approx w_{i}
\end{aligned}
$$

Note, in particular, that by (2.1),

$$
\begin{equation*}
w_{i} \geq \mathbb{E} D_{i} \geq w_{i}\left(1-\frac{w_{i}}{\sum_{j=1}^{n} w_{j}}\right)=w_{i}\left(1-\frac{w_{i}}{n \bar{w}}\right) \tag{2.2}
\end{equation*}
$$

where $\bar{w}=\frac{1}{n} \sum_{l=1}^{n} w_{i}$ is the average weight (i.e., roughly the average expected degree). Also, $\mathbb{E} D_{i} \geq \mathbb{E} D_{j}$ if and only if $w_{i} \geq w_{j}$.

By appropriately choosing the specification of the weight sequence $w_{i}$ it is possible to replicate different types of random graph models proposed in the literature. In this paper we work with random graphs with specific sparsity properties. We focus on sparse graphs in which the average weight is a positive constant $\bar{w}>0$. This sparsity assumption allows us to analyze the implications of power-law degree distribution in networks in which the total number of edges is constrained to be $O(n)$. Thus, our results are driven by the configuration of the edges rather than by their sheer number. Note that for sparse graphs Condition 2.1 in Definition 2 implies that the maximum weight $w_{M}$ cannot grow faster than $n^{1 / 2}$.

We recover the classical Erdős-Rényi model by taking $w_{i}=\bar{w}$ for all $i=$ $1, \ldots, n$. The Erdős-Rényi model is often acknowledged to be of limited power in modelling networks. In particular, the degree distribution of many networks appearing in practice seems to be much more heavy tailed than what would be implied by an Erdős-Rényi model. In order to overcome the limitations of this class of models, several authors have proposed different formulations of so-called power-law random graphs, that is, random graphs in which the degree distribution follows a power-law. In this work we find it convenient to focus on power-law random graphs derived from the Chung-Lu model. Other well-studied powerlaw random graphs include the configuration model and preferential attachment models, see [35] for a survey.

Definition 3. (POWER-LAW RANDOM GRAPH MODEL) The power-law random graph with power-law parameter $\beta>2$ is defined as a Chung-Lu random graph with weight sequence given by

$$
w_{i}=c\left(\frac{i+i_{0}-1}{n}\right)^{-1 /(\beta-1)} \quad i=1, \ldots, n
$$

with

$$
i_{0}=n\left(\frac{c}{w_{M}}\right)^{\beta-1} \text { and } c=\bar{w}\left(\frac{\beta-2}{\beta-1}\right)
$$

where $\bar{w}$ is the average weight and $w_{1}=w_{M}$ is the maximum weight.
It is straightforward to show [12] that the expected number $n_{k}$ of vertices of degree $k$ is power-law distributed, that is,

$$
\begin{equation*}
n_{k} \propto \frac{\Gamma(k-\beta+1)}{\Gamma(k+1)} \approx k^{-\beta} \tag{2.3}
\end{equation*}
$$

Power-law networks with $\beta \in(2,3)$ are particularly interesting as, empirically, this interval typically contains the vast majority of empirical estimates of the tail parameter obtained from many networks.

We define the power-law partial correlation network by associating the partial correlation model with the power-law random graph.

Definition 4. (POWER-LAW PARTIAL CORRELATION NETWORK MODEL) The power-law partial correlation network model is a partial correlation network model in which the underlying network $\mathcal{N}$ is a power-law random graph with parameters $\beta>2, \bar{w}>0$, and $w_{M}=n^{\alpha}$ with $\alpha \in(0,1 / 2)$.

One of our main findings is that the behavior of the largest eigenvalues of the concentration matrix is determined by the highest degrees in the network. The result is summarized in the following theorem.

Theorem 1. Let $\boldsymbol{Y}$ be generated by the power-law partial correlation network model with $\beta \in(2,3)$ and $\alpha<1 /(\beta-1)$. Let $\lambda_{i}^{K}$ denote the $i^{\text {th }}$ eigenvalue of the concentration matrix $\boldsymbol{K}$ ordered in descending order. Then for every $\epsilon>0$ there exist constants $C, \delta>0$ such that, with probability at least $1-n \exp \left(-C n^{\delta}\right)$, for all $i \leq n^{\min (\alpha, 1-\alpha(\beta-1))-\epsilon}$,

$$
\begin{equation*}
\lambda_{i}^{K}=\frac{1}{\sigma^{2}}\left[\phi w_{i}\left(1+O\left(n^{-\delta}\right)\right)+1\right] \tag{2.4}
\end{equation*}
$$

Our result implies that the largest eigenvalues of the concentration matrix are closely related to the power-law distribution of the degrees. By a simple concentration argument, $w_{i}$ may be replaced by either $\mathbb{E} D_{i}$ or $D_{i}$ in (2.4).

A number of comments on the implications of Theorem 1 are in order. First, notice that as the system dimension $n$ increases, the smallest eigenvalues of the covariance matrix $\boldsymbol{\Sigma}$ of the model, which are the reciprocals of the largest eigenvalues of $\boldsymbol{K}$, converge to zero. Thus, the power-law partial correlation network is a model in which, in spite of the sparsity of the underlying network, the system exhibits high collinearity among the variables. Second, the largest eigenvalues of the concentration matrix $\boldsymbol{K}$ are a noisy proxy (up to a linear transformation) of the largest degrees of the network. This suggests that these eigenvalues can be used to gain insight to the underlying degree distribution and, in particular, to the power-law tail parameter $\beta$. This is appealing in that it suggests that we


Fig 1. Network Decomposition.
can learn the degree of the power-law exponent of the power-law partial correlation network simply by analyzing the spectrum of the concentration matrix and without having to learn the entire underlying network using, for instance, sparse network estimation techniques. Last we note that Theorem 1 provides an upper bound on the largest eigenvalues of the concentration matrix, and that similar arguments to the ones used in the proof of the theorem can be used to establish an analogous lower bound.

We detail the proof of this result in the following section and we sketch here the main steps of our argument. Central to our proof is a decomposition of the power-law network $\mathcal{N}$ into two networks $\mathcal{N}_{1}$ and $\mathcal{N}_{2}$. For illustration purposes, Figure 1 contains an example of our graph decomposition using a simulated power-law network (appropriately pruned to enhance the plot readibility). Fix some $k<n$ and consider the $k$ vertices $v_{1}, \ldots, v_{k}$ with largest
expected degree in the network $\mathcal{N}$. (For instance, in Figure 1 the three vertices with highest degree are selected.) The sub-network $\mathcal{N}_{1}$ has the same set of vertices as $\mathcal{N}$ and it consists of all edges adjacent to $v_{1}, \ldots, v_{k}$, except for all edges between these vertices. (Thus, $\mathcal{N}_{1}$ is a bipartite graph with bipartition $\left\{v_{1}, \ldots, v_{k}\right\},\left\{v_{k+1}, \ldots, v_{n}\right\}$.) The network $\mathcal{N}_{2}$ (also defined on the same vertex set as $\mathcal{N}$ ) contains all remaining edges of $\mathcal{N}$.

Next we note that the Laplacian of $\mathcal{N}$ is equal to the sum of the Laplacians of $\mathcal{N}_{1}$ and $\mathcal{N}_{2}$. Thus, we can obtain bounds for the largest eigenvalues of the Laplacian of $\mathcal{N}$ using the eigenvalues of the Laplacians of $\mathcal{N}_{1}$ and $\mathcal{N}_{2}$. As it turns out, the largest eigenvalues of the Laplacian of $\mathcal{N}_{1}$ are closely related to the largest expected degrees in $\mathcal{N}$. This follows from general bounds for Laplacian eigenvalues in terms of degrees and probabilistic arguments.

Next we show that the largest eigenvalue of the Laplacian of $\mathcal{N}_{2}$ is small relative to the largest eigenvalues of the Laplacian of $\mathcal{N}_{1}$. Finally, the claim of the theorem follows by applying Weyl's inequality which allows us to establish that the largest eigenvalues of the Laplacian of $\mathcal{N}$ are close to the degrees of the largest degree vertices in the network, with high probability.

### 2.3. Proof of Theorem 1

Introduce $\ell=n^{\gamma}$ for some $\gamma<\min (\alpha, 1-\alpha(\beta-1))$. We prove that the $\ell$ largest eigenvalues of $\boldsymbol{K}$ satisfy the relation stated in the theorem.

We begin by noting that, with $w_{1}=n^{\alpha}$, the weights of the power-law random graph become

$$
w_{i}=c n^{1 /(\beta-1)}\left(c^{\beta-1} n^{1-\alpha(\beta-1)}+i-1\right)^{-1 /(\beta-1)}
$$

When $i<c^{\beta-1} n^{1-\alpha(\beta-1)}$, then within the expression in parenthesis, the first term dominates, otherwise the second. In particular, we have

$$
w_{i} \in \begin{cases}{\left[n^{\alpha} / 2^{1 /(\beta-1)}, n^{\alpha}\right]} & \text { if } i<c^{\beta-1} n^{1-\alpha(\beta-1)}  \tag{2.5}\\ {\left[c(n /(2 i))^{1 /(\beta-1)}, c(n / i)^{1 /(\beta-1)}\right]} & \text { if } i \geq c^{\beta-1} n^{1-\alpha(\beta-1)}\end{cases}
$$

The proof is based on decomposing the power-law network $\mathcal{N}$ in the union of two non-overlapping networks $\mathcal{N}_{1}$ and $\mathcal{N}_{2}$. We say that the networks $\mathcal{N}_{1}$ and $\mathcal{N}_{2}$ are non-overlapping if the networks are defined over the same vertex set and their edge sets are disjoint. That is, $\mathcal{N}_{1}=\left(\mathcal{V}, \mathcal{E}_{1}\right), \mathcal{N}_{2}=\left(\mathcal{V}, \mathcal{E}_{2}\right)$ with $\mathcal{E}_{1} \cap \mathcal{E}_{2}=\emptyset$. The union $\mathcal{N}=\mathcal{N}_{1} \cup \mathcal{N}_{2}$ of non-overlapping networks $\mathcal{N}_{1}$ and $\mathcal{N}_{2}$ is $\mathcal{N}=\left(\mathcal{V}, \mathcal{E}_{1} \cup \mathcal{E}_{2}\right)$. The Laplacian of the union of non-overlapping networks equals the sum of the Laplacians $\boldsymbol{L}=\boldsymbol{L}_{1}+\boldsymbol{L}_{2}$.

As described above, the sub-network $\mathcal{N}_{1}$ consists of all edges adjacent to the vertices $v_{1}, \ldots, v_{k}$ of highest weight, except for those edges that join two vertices $v_{i}, v_{j}$ such that $i, j \leq k$. We choose $k=n^{\rho}$ for some $\rho \in(1-\alpha(\beta-1), 1-\alpha)$. $\mathcal{N}_{2}$ contains all remaining edges of $\mathcal{N}$ so that $\mathcal{N}_{1}$ and $\mathcal{N}_{2}$ are non-overlapping and $\mathcal{N}=\mathcal{N}_{1} \cup \mathcal{N}_{2}$.

In order to estimate the largest eigenvalues of the Laplacian $\boldsymbol{L}$ of the powerlaw network $\mathcal{N}$, we write $\boldsymbol{L}$ as the sum of the Laplacians $\boldsymbol{L}_{1}$ of $\mathcal{N}_{1}$ and $\boldsymbol{L}_{2}$ of the residual network $\mathcal{N}_{2}, \boldsymbol{L}=\boldsymbol{L}_{1}+\boldsymbol{L}_{2}$. It follows from Weyl's inequality that the eigenvalues of $\boldsymbol{L}$ satisfy, for all $i=1, \ldots, n$,

$$
\begin{equation*}
\lambda_{i}^{L_{1}}+\lambda_{n}^{L_{2}} \leq \lambda_{i}^{L} \leq \lambda_{i}^{L_{1}}+\lambda_{1}^{L_{2}} \tag{2.6}
\end{equation*}
$$

Noting that the smallest eigenvalue of any Laplacian equals zero, we have $\lambda_{n}^{L_{2}}=$ 0 , and therefore, in order to prove the theorem we need to study the behavior of $\lambda_{i}^{\boldsymbol{L}_{1}}$ and $\lambda_{1}^{L_{2}}$.

First we bound from above the largest eigenvalue $\lambda_{1}^{\boldsymbol{L}_{1}}$ of the Laplacian $\boldsymbol{L}_{1}$ of the graph $\mathcal{N}_{1}$. Our main tool is a well-known bound of [2] (Proposition 3 in the Appendix) that implies that $\lambda_{1}^{L_{1}}$ is at $\operatorname{most} \max \left(D_{i}^{\mathcal{N}_{1}}+D_{j}^{\mathcal{N}_{1}}\right)$, where $D_{i}^{\mathcal{N}_{1}}$ denotes the degree of vertex $v_{i}$ in $\mathcal{N}_{1}$ and the maximum is taken over all pairs $(i, j)$ such that $v_{i}$ and $v_{j}$ are joined by an edge in $\mathcal{N}_{1}$.

Since $\mathcal{N}_{1}$ is bipartite, we have

$$
\begin{aligned}
\lambda_{1}^{\boldsymbol{L}_{1}} & \leq \max _{i \leq k} D_{i}^{\mathcal{N}_{1}}+\max _{i>k} D_{i}^{\mathcal{N}_{1}} \\
& \leq \max _{i \leq k} D_{i}+\max _{i>k} \sum_{j=1}^{k} A_{i, j}
\end{aligned}
$$

In order to bound the right-hand side, first note that

$$
\max _{i \leq k} D_{i} \leq \max _{i \leq k} \mathbb{E} D_{i}+\max _{i \leq k}\left(D_{i}-\mathbb{E} D_{i}\right) \leq n^{\alpha}+\max _{i \leq k}\left(D_{i}-\mathbb{E} D_{i}\right)
$$

By a simple Chernoff bound (see, e.g., Proposition 2 in the Appendix),

$$
\mathbb{P}\left(\max _{i \leq k}\left(D_{i}-\mathbb{E} D_{i}\right)>n^{3 \alpha / 4}\right) \leq k \mathbb{P}\left(D_{i}-\mathbb{E} D_{i}>n^{3 \alpha / 4}\right) \leq k \exp \left(-n^{\alpha / 2}\right)
$$

On the other hand, note that for $i>k$, using (2.5),

$$
\mathbb{E} \sum_{j=1}^{k} A_{i, j} \leq \frac{k w_{1} w_{i}}{n \bar{w}} \leq n^{\alpha} \frac{c n^{\rho+(1-\rho) /(\beta-1)-1}}{\bar{w}}
$$

(Note that $\beta>2$ implies $\rho+(1-\rho) /(\beta-1)<1$ and so $\mathbb{E} \sum_{j=1}^{k} A_{i, j}=o\left(n^{\alpha}\right)$.) Thus, again by Proposition 2,

$$
\begin{aligned}
& \mathbb{P}\left\{\max _{i>k} \sum_{j=1}^{k} A_{i, j}>2 n^{\alpha} \frac{c n^{\rho+(1-\rho) /(\beta-1)-1}}{\bar{w}}\right\} \\
& \quad \leq \mathbb{P}\left\{\max _{i>k}\left(\sum_{j=1}^{k} A_{i, j}-\mathbb{E} \sum_{j=1}^{k} A_{i, j}\right)>n^{\alpha} \frac{c n^{\rho+(1-\rho) /(\beta-1)-1}}{\bar{w}}\right\} \\
& \quad \leq n \exp \left(-n^{\alpha} \frac{c n^{\rho+(1-\rho) /(\beta-1)-1}}{\bar{w}}\right)
\end{aligned}
$$

Hence, since $\rho>1-\alpha(\beta-1)$ implies $\alpha+\rho+(1-\rho) /(\beta-1)-1>0$, we have that, there exist positive constants $C_{1}, \epsilon_{1}$ such that, with probability at least $1-2 n \exp \left(-C_{1} n^{\epsilon_{1}}\right)$,

$$
\begin{equation*}
\lambda_{1}^{L_{1}} \leq n^{\alpha}\left(1+C_{1} n^{-\epsilon_{1}}\right) \tag{2.7}
\end{equation*}
$$

Recall that $\ell=n^{\gamma}$ for some $\gamma<\min (\alpha, 1-\alpha(\beta-1))$ We derive a lower bound for the $\ell$-th largest eigenvalue $\lambda_{\ell}^{\boldsymbol{L}_{1}}$ of the Laplacian of $\mathcal{N}_{1}$. To this end, we use Proposition 4 that implies that

$$
\begin{equation*}
\lambda_{\ell}^{L_{1}} \geq D_{\ell}^{\mathcal{N}_{1}}-\ell \tag{2.8}
\end{equation*}
$$

Since $\ell<k, D_{\ell}^{\mathcal{N}_{1}}=\sum_{i=k+1}^{n} A_{i, \ell}$. Thus, using (2.2) and (2.5)

$$
\begin{align*}
\mathbb{E} D_{\ell}^{\mathcal{N}_{1}} & =\mathbb{E} D_{\ell}-w_{\ell} \sum_{i=1}^{k} \frac{w_{i}}{n \bar{w}} \geq w_{\ell}\left(1-\frac{w_{\ell}}{n \bar{w}}-k \frac{w_{k}}{n \bar{w}}\right) \\
& \geq w_{\ell}\left(1-\frac{n^{\alpha-1}}{\bar{w}}-\frac{c}{\bar{w}} n^{(\rho(\beta-2)+1) /(\beta-1)-1}\right) \tag{2.9}
\end{align*}
$$

Since $\ell=n^{\gamma}$ with $\gamma<1-\alpha(\beta-1)$ ), we have from the definition of the weights that

$$
\begin{aligned}
w_{\ell} & =n^{\alpha}\left(1+\frac{1}{c^{\beta-1}} n^{\gamma+\alpha(\beta-1)-1}\right)^{-1 /(\beta-1)} \\
& \geq n^{\alpha}\left(1+\frac{1}{(\beta-1) c^{\beta-1}} n^{\gamma+\alpha(\beta-1)-1}\right)^{-1}
\end{aligned}
$$

(by Bernoulli's inequality)

$$
\begin{equation*}
\geq n^{\alpha}\left(1-\frac{1}{(\beta-1) c^{\beta-1}} n^{\gamma+\alpha(\beta-1)-1}\right) \tag{2.10}
\end{equation*}
$$

Putting (2.9) and (2.10) together, we have that, for some positive constants $C_{1}, \epsilon_{1}$,

$$
\mathbb{E} D_{\ell}^{\mathcal{N}_{1}} \geq n^{\alpha}\left(1-C_{1} n^{-\epsilon_{1}}\right)
$$

By Proposition $2, D_{\ell}^{\mathcal{N}_{1}} \geq \mathbb{E} D_{\ell}^{\mathcal{N}_{1}}-n^{3 \alpha / 4}$ with probability at least $1-$ $\exp \left(-\Omega\left(n^{\alpha / 2}\right)\right)$, and thus, combining these bounds with (2.8) and (2.7), we find that there exist positive constants $C_{0}, \epsilon_{0}$ such that, with probability at least $1-\exp \left(-C_{0} n^{\epsilon_{0}}\right)$, for all $i=1, \ldots, \ell$,

$$
\begin{equation*}
n^{\alpha}\left(1-C_{0} n^{-\epsilon_{0}}\right) \leq \lambda_{i}^{\boldsymbol{L}_{1}} \leq n^{\alpha}\left(1+C_{0} n^{-\epsilon_{0}}\right) \tag{2.11}
\end{equation*}
$$

Next, we bound the largest eigenvalue $\lambda_{1}^{\boldsymbol{L}_{2}}$ of the Laplacian of the residual network $\mathcal{N}_{2}$. To this end, once again we apply the Anderson-Morley inequality (Proposition 3 below) that implies that

$$
\lambda_{1}^{L_{2}} \leq 2 \max _{i=1, \ldots, n} D_{i}^{\mathcal{N}_{2}}
$$

where $D_{i}^{\mathcal{N}_{2}}$ is the degree of vertex $v_{i}$ in $\mathcal{N}_{2}$. By the definition of $\mathcal{N}_{2}$, we have that

$$
\max _{i=1, \ldots, n} D_{i}^{\mathcal{N}_{2}} \leq \max _{i=1, \ldots, k} \sum_{j=1}^{k} A_{i, j}+\max _{i=k+1, \ldots, n} D_{i}
$$

We proceed the same way as before. First we estimate the expected values of the random variables appearing in the bound and then use Proposition 2 and the union bound to conclude. For each $i=1, \ldots, k$,

$$
\mathbb{E} \sum_{j=1}^{k} A_{i, j}=\sum_{j=1}^{k} p_{i, j} \leq k \frac{w_{1}^{2}}{n \bar{w}}=n^{\alpha} \frac{n^{\alpha+\rho-1}}{\bar{w}}
$$

(Recall that $\rho<1-\alpha$ and therefore $\mathbb{E} \sum_{j=1}^{k} A_{i, j}=O\left(n^{\alpha-\delta}\right)$ for some $\delta>0$.) On the other hand, for all $i>k$, using the fact that $\rho>1-\alpha(\beta-1)$, we have

$$
\mathbb{E} D_{i} \leq w_{i} \leq c\left(\frac{n}{k}\right)^{1 /(\beta-1)}=c n^{(1-\rho) /(\beta-1)}
$$

and therefore $\mathbb{E} D_{i}=O\left(n^{\alpha-\delta}\right)$ for a positive $\delta$. Using Proposition 2 and the union bound exactly as before, we obtain that, there exist positive constants $C_{2}, \epsilon_{2}$ such that, with probability at least $1-n \exp \left(-C_{2} n^{\epsilon_{2}}\right)$,

$$
\begin{equation*}
\lambda_{1}^{\boldsymbol{L}_{2}} \leq n^{\alpha-\epsilon_{2}} \tag{2.12}
\end{equation*}
$$

Finally, combining (2.6) with (2.11) and (2.12), we see that, there exist positive constants $C_{3}, \epsilon_{3}$ such that, with probability at least $1-n \exp \left(-C_{3} n^{\epsilon_{3}}\right)$, for all $i=1, \ldots, \ell$, the eigenvalues of the power-law network $\mathcal{N}$ satisfy

$$
\begin{equation*}
n^{\alpha}\left(1-C_{3} n^{-\epsilon_{3}}\right) \leq \lambda_{i}^{L} \leq n^{\alpha}\left(1+C_{3} n^{-\epsilon_{3}}\right) \tag{2.13}
\end{equation*}
$$

This, together with (2.10), implies that, with probability at least 1 $n \exp \left(-C_{3} n^{\epsilon_{3}}\right)$, for all $i=1, \ldots, \ell$,

$$
\left|\frac{\lambda_{i}^{L}}{w_{i}}-1\right| \leq C n^{-\delta}
$$

for some positive constants $C, \delta$. The relationship between the eigenvalues of $\boldsymbol{K}$ and $L$

$$
\lambda_{i}^{\boldsymbol{K}}=\frac{1+\phi \lambda_{i}^{L}}{\sigma^{2}}
$$

concludes the proof.

## 3. Simulation study

In this section we carry out a simulated illustration of the model introduced in the previous section to highlight some of its key properties, and we perform a Monte Carlo study to verify numerically the conclusion of Theorem 1.


Realizations of a simulated power-law (left) and Erdős-Rényi (right) random graphs.
Fig 2. Random graph simulation.

We begin by showing a realization of the power-law partial correlation network model and comparing it with a partial correlation network model based on the Erdős-Rényi random graph. The average expected degree of both networks is $\bar{w}=1$ and the size of the system is $n=500$. The variance parameter $\sigma^{2}$ and the network dependence parameter $\phi$ are both set to one. For the power-law network we also set the power-law tail parameter $\beta$ to 2.5 and the maximum expected degree $w_{M}$ to $\left\lceil 500^{0.45}\right\rceil=16$ (i.e., $\alpha=0.45$ ).

We display the realizations of the two random graphs in Figure 2. The plot of the two networks shows how the power-law model produces structures containing hubs of highly interconnected vertices, analogously to what is often encountered in the network analysis of economic and financial time series. Figure 3 shows the heat maps of the concentration and covariance matrices associated with the two networks. The power-law model delivers a more interdependent multivariate system, as it can be gauged by the inspection of the covariance matrix. In Figure 4 we report the degree distribution of the two simulated networks where it is evident that the power-law model is associated with heavier tails than the Erdős-Rényi.

A Monte Carlo experiment is run to verify the conclusion of Theorem 1. The experiment is designed as follows. In each replication, we simulate the power-law partial correlation network model and draw 5000 random vectors from it. We then compute the eigenvalues of the concentration matrix as well as the eigenvalues of sample concentration matrix obtained from the sample of random vectors. The simulation exercise is replicated 10000 times. We also carry out the same exercise using a partial correlation network model based on the Erdős-Rényi random graph.

We report the results in Figure 5, where we plot the Monte Carlo averages of the largest eigenvalues, that is $\lambda_{i}^{K}$, together with the largest expected degrees. Recall that in this current setting Theorem 1 implies that for $n$ large enough the largest eigenvalues of the power-law partial correlation network model concen-


Concentration matrices in the upper panels and corresponding covariance matrices in the lower panels. Left column: power-law partial correlation model; right column: Erdős-Rényi model.

Fig 3. Sparsity of The concentration and covariance matrices.


Degree distribution of the power-law (red) and the Erdős-Rényi (blue) random graphs.

Fig 4. Degree distribution

Power-Law model


Log-log rank-size plot for the Monte Carlo averages of 25 largest eigenvalues $\log \left(\lambda_{i}^{K}\right)$ (left, squares), estimated eigenvalues $\log \left(\widehat{\lambda}_{i}^{K}\right)$ (right, squares) with $5 \%$ and $95 \%$ quantiles (dashed lines), and expected degrees $w_{i}$ (circles) when assuming a power-law (top panel) or an ErdősRényi (bottom panel) partial correlation model.

Fig 5. eigenvalues behavior in simulated data.
tration matrix are $\lambda_{i}^{K}=w_{i}\left(1+o_{p}(1)\right)+1$. Notice that we plot adjusted eigenvalues and expected degrees using the so-called log-log rank-size plot, which is a plot of the log expected degree/eigenvalue versus its log rank. The plot shows that, as predicted by Theorem 1, the largest eigenvalues of the concentration matrix of the power-law partial correlation network model are close to the largest expected degrees of the power-law graph. Moreover, when plotted on a log-log scale, the eigenvalues lie on a straight line with a slope which is, roughly, close the negative of the power-law coefficient $\beta$. Note that for large sample sizes the impact of estimation uncertainty in the estimation of the concentration matrix is marginal. In the Erdős-Rényi model on the other hand, it is easy to see that the relationship between eigenvalues and expected degrees does not hold.

## 4. Empirical illustration

### 4.1. Data description

In this last section we carry out an empirical study to assess to which extent real data presents empirical features that are consistent with the power-law partial
correlation network model. In particular, we consider two large panels of daily stock returns both spanning the period from 2006-01-03 to 2013-12-31. The first panel contains daily stock returns of companies listed in the S\&P 500 index and that have been trading for more than 2000 days in the S\&P 500 throughout the sample period, which delivers a sample of 387 companies over 2013 time periods. The second panel is larger and contains 1234 companies listed in the S\&P 1500 index. The dependence structure of these data is clearly much more complex than the one implied by the power-law partial correlation network model and the analysis carried out in this section only aims at providing rough empirical validation for our model.

### 4.2. Controlling for common factors

As a preliminary step of our analysis we first have to control for common factors, which, as explained below, are also likely to induce interdependencies but of a different kind than those we are interested in investigating in this paper. Many empirical studies prove that stock returns are driven by few, market related, common factors [see e.g. 14]. Such feature is usually formalized by means of the Capital Asset Pricing Model (CAPM, see 32), where the return of stock $i$ on day $t$, denoted as $r_{i t}$, is generated according to

$$
\begin{equation*}
r_{i t}=a_{i}+b_{i} r_{m t}+\epsilon_{i t}, \quad i=1, \ldots, n, t=1, \ldots, T \tag{4.1}
\end{equation*}
$$

where $r_{m t}$ denotes the market return and $\boldsymbol{\epsilon}_{t}=\left\{\epsilon_{i t}, i=1, \ldots, n\right\}$ are independent vectors with zero mean and covariance $\boldsymbol{\Sigma}_{\epsilon}$. The CAPM model has important implications for our model of dependencies. Indeed, the concentration matrix implied by (4.1) is

$$
\boldsymbol{\Sigma}^{-1}=\boldsymbol{\Sigma}_{\epsilon}^{-1}-\frac{\boldsymbol{\Sigma}_{\epsilon}^{-1} \boldsymbol{b} \boldsymbol{b}^{\prime} \boldsymbol{\Sigma}_{\epsilon}^{-1}}{1+\boldsymbol{b}^{\prime} \boldsymbol{\Sigma}_{\epsilon}^{-1} \boldsymbol{b}}
$$

where $\boldsymbol{b}$ is the $n \times 1$ vector of factor loadings $b_{i}$, and, under the usual assumption of pervasive factors, i.e. $\sum_{i=1}^{n} b_{i}^{2}=O(n)$ or equivalently $\lambda_{1}^{\boldsymbol{\Sigma}}=O(n)$ [10], it is straightforward to see that the matrix $\boldsymbol{\Sigma}^{-1}$ is, in general, not sparse. Consequently the corresponding network will be fully interconnected, thus violating the assumptions of our model. Therefore, we consider the model proposed in this paper as a model for the partial correlation structure of the stocks only after conditioning on the market factor, $r_{m t}$. As it is commonly assumed in empirical finance, the market factor is here treated as observed and is here identified with the S\&P 500 or the S\&P 1500 index. We then carry out our analysis on the partial correlation structure of the idiosyncratic shocks $\epsilon_{i t}$, obtained as the residuals of the $n$ univariate least squares regressions defined in (4.1), and, according to our notation, we define as $\boldsymbol{K}=\boldsymbol{\Sigma}_{\epsilon}^{-1}$.

### 4.3. Estimation of the power-law parameter $\beta$

Theorem 1 motivates us to fit a power-law distribution to the largest eigenvalues of the concentration matrix in the attempt to estimate the power-law parame-
ter $\beta$. Different methodologies have been proposed in the literature to estimate this parameter. In particular here we adapt the popular power-law estimation methodology proposed Clauset et al. [13]. We make the simplifying assumption that the top eigenvalues of the concentration matrix $\lambda_{i}^{K}$ for $i=1, \ldots, i_{\max }$ are an ordered sample from a power-law distribution with parameter $\beta$. (In other words, we ignore the error between eigenvalues and degrees generated by the model). Note that $i_{\text {max }}$ denotes the (unknown) threshold index from which the distribution of the largest eigenvalues of $\boldsymbol{K}$ is power-law. The procedure of Clauset et al. [13] allows one to estimate simultaneously $\beta$ and $i_{\max }$. If $i_{\max }$ is known the estimation of the power-law parameters is straightforward. For a given sample of eigenvalues $\left\{\lambda_{i}^{K}\right\}_{i=1}^{i_{\text {max }}}$ the log-likelihood of the model is given by

$$
\begin{equation*}
\mathcal{L}\left(\beta \mid i_{\max }, \lambda_{1}^{\boldsymbol{K}}, \ldots, \lambda_{i_{\max }}^{\boldsymbol{K}}\right)=\ln \left[\prod_{i=1}^{i_{\max }} \frac{\beta-1}{i_{\max }}\left(\frac{\lambda_{i}^{\boldsymbol{K}}}{i_{\max }}\right)^{-\beta}\right] \tag{4.2}
\end{equation*}
$$

By maximizing (4.2), we obtain the maximum likelihood estimator of $\beta$, also known as Hill estimator [23]:

$$
\widehat{\beta}_{i_{\max }}=1+i_{\max }\left(\sum_{i=1}^{i_{\max }} \log \frac{\lambda_{i}^{K}}{\lambda_{i_{\max }}^{K}}\right)^{-1}
$$

As we are assuming that $i_{\max }$ is not known, consider next the set $\mathcal{I}$ of possible values for $i_{\max }$ and the corresponding family of estimators $\left\{\widehat{\beta}_{i_{\max }}: i_{\max } \in\right.$ $\mathcal{I}\}$. Let $\mathbb{P}\left(\lambda_{i}^{K} \geq \ell \mid \beta, i_{\max }\right)$ and $\widehat{\mathbb{P}}\left(\lambda_{i}^{K} \geq \ell \mid \beta, i_{\max }\right)$ denote, respectively, the theoretical and empirical survival functions of $\lambda_{i}^{K}$. Then Clauset et al. [13] propose to estimate the optimal threshold as

$$
i_{\max }^{*}=\underset{i_{\max } \in \mathcal{I}}{\arg \min }\left|\mathbb{P}\left(\lambda_{i}^{\boldsymbol{K}} \geq \ell \mid \widehat{\beta}_{i_{\max }}, i_{\max }\right)-\widehat{\mathbb{P}}\left(\lambda_{i}^{\boldsymbol{K}} \geq \ell \mid \widehat{\beta}_{i_{\max }}, i_{\max }\right)\right|
$$

In other words, the threshold $i_{\max }^{*}$ is such that it minimises the KolmogorovSmirnov distance between the empirical and theoretical survival functions of the eigenvalues. It can be shown that, for $i_{\max }^{*}$ large enough, $\sqrt{i_{\max }^{*}}\left(\widehat{\beta}_{i_{\max }^{*}}-\beta\right) \sim$ $N\left(0,(\beta-1)^{2}\right)$ [see e.g. 19].

### 4.4. Estimation of eigenvalues

The above procedure cannot be applied directly since we do not observe the eigenvalues of the concentration matrix, but these need to be estimated from the data. Let $\widehat{\boldsymbol{\Sigma}}_{\epsilon}$ be an estimator of the covariance matrix of the vector $\boldsymbol{\epsilon}_{t}$ (see (4.1)) obtained from a sample of size $T$ and denote by $\widehat{\lambda}_{i}^{\widehat{\boldsymbol{\Sigma}}_{\epsilon}}$ its eigenvalues. Then the eigenvalues of the concentration matrix $\boldsymbol{K}=\boldsymbol{\Sigma}_{\epsilon}^{-1}$ are estimated as $\widehat{\lambda}_{i}^{\boldsymbol{K}}=$ $\left(\widehat{\lambda}_{n-i+1}^{\widehat{\boldsymbol{\Sigma}}_{\epsilon}}\right)^{-1}$. Specifically, we consider here two possible alternative estimators of $\boldsymbol{\Sigma}_{\epsilon}$ : the sample covariance matrix estimator and the shrinkage covariance matrix

Table 1
POWER-LAW BEHAVIOR OF S\&P PANELS.

| S\&P 500 ( $n=387$ ) |  |  | S\&P $1500(n=1234)$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Threshold <br> $i_{\text {max }}$ | Sample covariance | Regularised covariance | Threshold <br> $i_{\text {max }}$ | Sample covariance | Regularised covariance |
| 100 | $\begin{gathered} 2.79 \\ (0.18) \end{gathered}$ | $\begin{gathered} 3.04 \\ (0.20) \end{gathered}$ | 250 | $\underset{(0.10)}{2.65}$ | $\underset{(0.11)}{2.87}$ |
| 150 | $\underset{(0.12)}{2.42}$ | $\begin{gathered} 2.65 \\ (0.14) \end{gathered}$ | 350 | $\begin{gathered} 2.33 \\ (0.07) \end{gathered}$ | $\underset{(0.08)}{2.50}$ |
| 200 | $\underset{(0.08)}{2.18}$ | $\begin{gathered} 2.37 \\ (0.10) \end{gathered}$ | 450 | $\underset{(0.05)}{2.13}$ | $\underset{(0.06)}{2.26}$ |
| Clauset et al. [13] | $\begin{gathered} 2.94 \\ (0.20) \end{gathered}$ | $\underset{(0.17)}{2.90}$ | Clauset et al. [13] | $\begin{gathered} 2.60 \\ (0.10) \end{gathered}$ | $\begin{gathered} 2.98 \\ (0.13) \end{gathered}$ |
| $i_{\text {max }}^{*}$ | 90 | 122 | $i_{\text {max }}^{*}$ | 266 | 230 |

Values of the estimated power-law exponent $\widehat{\beta}_{i_{\max }}$ with standard errors in parenthesis.
estimator of Ledoit and Wolf [29]. ${ }^{1}$ The second estimator is particularly useful when the sample size $T$ and the cross-sectional dimension $n$ are both large and of comparable size. Once an estimate of the eigenvalues $\left\{\widehat{\lambda}_{i}^{\boldsymbol{K}}\right\}_{i=1}^{n}$ is available we use these to compute $\widehat{\beta}_{i_{\text {max }}^{*}}$ according to the procedure outlined above.

### 4.5. Results

We report the estimated values $\widehat{\beta}_{i_{\max }}$ in Table 1 for the S\&P 500 and S\&P 1500 datasets and constructed on the basis of both the sample covariance and the regularised covariance matrix. The top panel of Table 1 reports the estimates obtained using fixed exogenous choices of the threshold $i_{\max }$, while in the bottom panel we report $\widehat{\beta}_{i_{\max }^{*}}$ and $i_{\max }^{*}$ obtained with the methodology described above. Estimates exhibit a moderate degree of variation depending on the chosen estimation approach. Interestingly, all estimates hint at a tail parameter larger than 2 and smaller than 3, indicating a heavy-tailed power-law distribution.

For both datasets considered, we show in Figure 6 the size-rank log-log plot of the largest estimated eigenvalues of the concentration matrix based on the shrinkage covariance estimator jointly with the power-law fit, obtained using $\widehat{\beta}_{i_{\text {max }}^{*}}$ and reported for different values of the intercept. Overall, we find the tail of the largest eigenvalues of the concentration matrix to be well described by a power-law parameter smaller than three.

Last, for comparison purposes it is interesting to report the estimate of the underlying partial correlation network to see if such network exhibits feature con-

[^1]

Log-log rank-size plot for the 50 largest eigenvalues $\log \left(\widehat{\lambda}_{i}^{K}\right)$. Dashed lines: power-law fit for the largest log-eigenvalues with slope $-\widehat{\beta}_{i_{\max }^{*}}$ for different values of the intercept.

Fig 6. power-Law behavior of S\&P panels.


Fig 7. partial correlation network of the S\&P500.
sistent with our power law model. We estimate the partial correlation network using the space algorithm, a LASSO estimation procedure originally proposed by Peng et al. [30]. ${ }^{2}$ the graph plot and degree distribution of the estimated networks in Figure 7 and 8 respectively. The estimated networks exhibit several features that are commonly encountered in power-law graphs. They are made up of a giant component containing several hubs and a few small components. There is substantial heterogeneity in the number of connections of each vertex and the most interconnected vertices have a large number of connections relative to the total. Accordingly, the degree distribution of the network exhibits heavy tails. Interestingly, overall the estimated partial correlation network has features that are consistent with the power-law model.

[^2]

Fig 8. Degree distribution of the S\&P 500

## 5. Conclusions

In this work we introduce a tractable class of partial correlation network models whose underlying network structure is a function of a random graph. In particular, we focus on a special case of this model where the underlying network is power-law. Power-law networks are a class of random graphs able to reproduce several of the empirical stylized facts that can be observed in real world networks, in particular small world effects and power-law degree distribution. Our central result concerns the behavior of the largest eigenvalues of the concentration matrix of the model. We show that the largest eigenvalues of the concentration matrix converge to an affine function of the degree of the vertices with largest expected degree. The result implies that when the tails of the power-law distribution are heavy and the system dimension is large, the system exhibits a high degree of collinearity. As an empirical illustration, we analyze the covariance matrix of a large panel of stock returns of companies listed in the S\&P 500 index and document that the data exhibits empirical features that are consistent with the power-law partial correlation network model.

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## Appendix A: Auxiliary results

Proposition 1. (COVARIANCE OF THE PARTIAL CORRELATION NETWORK) The covariance matrix of the partial correlation network model is

$$
\boldsymbol{\Sigma}=\sigma^{2}(\boldsymbol{I}+\phi \boldsymbol{D})^{-1}+\frac{\sigma^{2}}{\phi} \sum_{k=1}^{\infty} \boldsymbol{W}_{k}
$$

where $\boldsymbol{W}_{k}$ is defined as

$$
\begin{equation*}
\left[\boldsymbol{W}_{k}\right]_{i, j}=\sum_{w \in \mathcal{W}_{k}} \frac{\mathbb{1}_{\{w \text { goes from } i \text { to } j\}}}{\prod_{v \in \mathcal{V}(w)}(d(v)+1 / \phi)} \tag{A.1}
\end{equation*}
$$

where $\mathcal{W}_{k}$ denotes the set of walks of length $k$ in the network, $\mathcal{V}(w)$ denotes the set of vertices in walk $w, d(v)$ denotes the degree of vertex $v$ and $\mathbb{1}$ is the indicator function (and convergence is defined in spectral norm). We call $\boldsymbol{W}_{k}$ the weighted walk matrix of length $k$.

Proof. Define $\boldsymbol{C}=\boldsymbol{I}+\phi \boldsymbol{D}$ and notice that $\boldsymbol{C}$ is a diagonal matrix with positive diagonal entries. Then

$$
\boldsymbol{\Sigma}=\boldsymbol{K}^{-1}=\sigma^{2}(\boldsymbol{C}-\phi \boldsymbol{A})^{-1}
$$

$$
\begin{aligned}
& =\sigma^{2}\left(\boldsymbol{C}^{1 / 2}\left(\boldsymbol{I}-\phi \boldsymbol{C}^{-1 / 2} \boldsymbol{A} \boldsymbol{C}^{-1 / 2}\right) \boldsymbol{C}^{1 / 2}\right)^{-1} \\
& =\sigma^{2} \boldsymbol{C}^{-1 / 2}\left(\boldsymbol{I}-\phi \boldsymbol{C}^{-1 / 2} \boldsymbol{A} \boldsymbol{C}^{-1 / 2}\right)^{-1} \boldsymbol{C}^{-1 / 2}
\end{aligned}
$$

where $\boldsymbol{C}^{1 / 2}$ and $\boldsymbol{C}^{-1 / 2}$ denote diagonal matrices with diagonal equal respectively to the square root and inverse square root of the diagonal of $\boldsymbol{C}$. Notice that the eigenvalues of $\phi \boldsymbol{C}^{-1 / 2} \boldsymbol{A} \boldsymbol{C}^{-1 / 2}$ are smaller than one in absolute value. (To see this, note that $\left\|\phi \boldsymbol{C}^{-1 / 2} \boldsymbol{A} \boldsymbol{C}^{-1 / 2}\right\| \leq \phi\|\boldsymbol{A}\| /\|\boldsymbol{C}\|$ and that $\|\boldsymbol{C}\| \geq \phi D_{\max }$ and $\|\boldsymbol{A}\| \leq D_{\max }$ where $D_{\max }$ denotes the highest degree in the network.) Thus, we can apply the von Neumann series identity to $\left(\boldsymbol{I}-\phi \boldsymbol{C}^{-1 / 2} \boldsymbol{A} \boldsymbol{C}^{-1 / 2}\right)^{-1}$ and get

$$
\begin{aligned}
\boldsymbol{K}^{-1} & =\sigma^{2} \boldsymbol{C}^{-1 / 2}\left(\boldsymbol{I}+\sum_{k=1}^{\infty}\left(\phi \boldsymbol{C}^{-1 / 2} \boldsymbol{A} \boldsymbol{C}^{-1 / 2}\right)^{k}\right) \boldsymbol{C}^{-1 / 2} \\
& =\sigma^{2} \boldsymbol{C}^{-1}+\sigma^{2} \sum_{k=1}^{\infty} \boldsymbol{C}^{-1 / 2}\left(\phi \boldsymbol{C}^{-1 / 2} \boldsymbol{A} \boldsymbol{C}^{-1 / 2}\right)^{k} \boldsymbol{C}^{-1 / 2} \\
& =\sigma^{2} \boldsymbol{C}^{-1}+\sigma^{2} \sum_{k=1}^{\infty} \phi^{k} \underbrace{\boldsymbol{C}^{-1} \boldsymbol{A} \boldsymbol{C}^{-1} \boldsymbol{A} \ldots \boldsymbol{C}^{-1} \boldsymbol{A}}_{k \text { times }} \boldsymbol{C}^{-1}
\end{aligned}
$$

Recall that the $(i, j)$ element of $\boldsymbol{A}^{k}$ is equal to the number of distinct walks of length $k$ from $i$ to $j$, which can be expressed as

$$
\sum_{i_{1}=1}^{n} \sum_{i_{2}=1}^{n} \cdots \sum_{i_{k-1}=1}^{n} A_{i, i_{1}} A_{i_{1}, i_{2}} \cdots A_{i_{k-1}, j}
$$

Analogously, it is straightforward to see that the $(i, j)$ entry of $\left(\boldsymbol{C}^{-1} \boldsymbol{A}\right)^{k} \boldsymbol{C}^{-1}$ is equal to

$$
\sum_{i_{1}=1}^{n} \sum_{i_{2}=1}^{n} \cdots \sum_{i_{k-1}=1}^{n} \frac{A_{i, i_{1}}}{\phi D_{i}+1} \frac{A_{i_{1}, i_{2}}}{\phi D_{i_{1}}+1} \cdots \frac{A_{i_{k-1}, j}}{\phi D_{i_{k-1}}+1} \frac{1}{\phi D_{j}+1}
$$

We obtain the statement of the proposition by applying the last equation and rearranging terms.

Proposition 2. (See 24, 25, 18.) Let $X_{1}, \ldots, X_{n}$ be independent random variables, taking their values from $[0,1]$. If $m=\mathbb{E} S_{n}$ with $S_{n}=\sum_{i=1}^{n} X_{i}$ then for any $t \geq m$,

$$
\mathbb{P}\left\{S_{n} \geq t\right\} \leq\left(\frac{m}{t}\right)^{t} e^{t-m}
$$

In particular, for all $u \leq m$,

$$
\mathbb{P}\left\{S_{n} \geq \mathbb{E} S_{n}+u\right\} \leq e^{-u^{2} / m}
$$

On the other hand, for all $u \leq m$,

$$
\mathbb{P}\left\{S_{n} \leq \mathbb{E} S_{n}-u\right\} \leq e^{-u^{2} /(2 m)}
$$

Proposition 3. (2.) Let $\mathcal{G}$ be a graph with edge set $\mathcal{E}$. Then the maximum eigenvalue of the graph Laplacian $\boldsymbol{L}_{\mathcal{G}}$ satisfies

$$
\lambda_{1}^{L_{\mathcal{G}}} \leq \max \left\{D_{i}+D_{j} \mid(i, j) \in \mathcal{E}\right\} .
$$

Proposition 4. (7, see also 8.) Let $\mathcal{G}$ be any graph on $n$ vertices that is not the union of the complete graph $K_{m}$ and $n-m$ isolated vertices for any $m \leq n$. Then, for all $i=1, \ldots, n$,

$$
\lambda_{i}^{L_{\mathcal{G}}} \geq D_{i}-i+2
$$

where $\lambda_{i}^{L_{\mathcal{G}}}$ is the $i$-th largest eivenvalue of the Laplacian of $\mathcal{G}$ and $D_{i}$ is the $i$-th largest degree of the vertices of $\mathcal{G}$.


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[^1]:    ${ }^{1}$ Alternative regularised covariance estimators are given for example in Bickel and Levina [5], Lam and Fan [27], Lam [26].

[^2]:    ${ }^{2}$ This estimator depends on a tuning parameter which determines the degree of penalization of the LASSO procedure, which is here chosen on the basis of the BIC criterion, as suggested among others by Peng et al. [30] themselves.

