# Fluctuations of bridges, reciprocal characteristics and concentration of measure 

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#### Abstract

Conditions on the generator of a Markov process to control the fluctuations of its bridges are found. In particular, continuous time random walks on graphs and gradient diffusions are considered. Under these conditions, a concentration of measure inequality for the marginals of the bridge of a gradient diffusion and refined large deviation expansions for the tails of a random walk on a graph are derived. In contrast with the existing literature about bridges, all the estimates we obtain hold for non asymptotic time scales. New concentration of measure inequalities for pinned Poisson random vectors are also established. The quantities expressing our conditions are the so called reciprocal characteristics associated with the Markov generator.


Résumé. Dans cet article nous exhibons des conditions sur le générateur d'un processus de Markov qui nous permettent de quantifier les fluctuations de ses ponts. Nous nous intéressons plus précisément aux marches aléatoires sur les graphes et aux diffusions de type gradient. Nous démontrons une inégalité de concentration pour la loi marginale du pont d'une diffusion gradient ainsi qu'un principe de grandes déviations pour les queues d'une marche aléatoire sur un graphe. L'originalité de nos résultats réside dans le fait qu'ils sont valables pour toute échelle de temps, tandis que ceux qui préexistent dans la litérature sont uniquement asymptotiques. Nous établissons aussi des inégalités de concentration pour des vecteurs aléatoires poissoniens conditionnés. Les paramètres, dérivés des processus markoviens, qui interviennent dans les conditions mises en évidence, sont leurs invariants réciproques.

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## 1. Introduction

In this paper we study quantitatively bridges of Markov processes over the time-interval [ 0,1$]$. Our motivation for this study is twofold. One the one hand, we want relate geometric properties of the generator of a Markov process with the dynamics of its bridges. For example, we want to know how the potential of the Langevin dynamics has to be chosen to observe bridge-marginals with small variance. The answer to this basic question is well known for the Langevin dynamics, but not for its bridge. Similar problems arise in applications, where bridges are by now widely used. On the other hand, understanding bridges is a step toward the quantitative study of reciprocal processes and Schrödinger bridges (see [24] for results in this direction). Both these family of stochastic processes are constructed as bridge mixtures and have recently been the object of renewed interest because of their connections wit Optimal Transport [38] and their use in applications [15,16]. As a guideline, independently from the details of the model, we have in mind the sketch of the motion of a bridge as divided into two symmetric phases. At first one observes an expansion phase, in which the bridge, starting from its deterministic initial position, increases its randomness. After time $1 / 2$, a contraction phase takes place, in which the damping effect of the pinning at the terminal time is so strong that randomness decreases and eventually dies out. Moreover, one also expects that the two phases enjoy some symmetry
with respect to time reversal. To summarize, one can say that the motion of bridge resembles that of an accordion. The aim of this paper is to obtain a quantitative explanation of this picture. This means that we consider a Markov process and try to understand how its semimartingale characteristics should look like in order to observe bridges where the influence of pinning over randomness is stronger than that of a reference model, for which computations can be carried out in explicit form. As we shall see, some precise answers can be given. It is interesting to note that the quantities expressing our conditions are not related to those used to measure the speed of convergence to equilibrium, as one might expect at first glance (see Remark 2.3 for a comparison with the $\Gamma_{2}$ condition of Bakry and Émery [3]).

There are many possible quantities that could be used to estimate the balance of power between pinning and randomness and make precise mathematical statements. Some of them are discussed in the sequel, depending on the model: in this paper, Brownian diffusions with gradient drift and continuous time random walks on a graph are considered.

Our results take the form of comparison theorems, which yield quantitative information on the bridge at non asymptotic time scales. In Theorem 2.1 we find conditions on the potential of a gradient diffusion for its bridges to have marginals with better concentration properties than those of an Ornsetin Uhlenbeck bridge. This is one of the main novelties with respect to the existing literature about bridges where, to the best of our knowledge, only Large Deviations-type estimates have been proved, and mostly in the short time regime, see among others [1,2,4,5,27,42,50] and [52]. The proof of this result is done by first showing an ad hoc Girsanov formula for bridges, which differs from the usual one. We then employ some tools developed in [10] to transfer log concavity of the density from the path space to the marginals, and use the well known properties of log concave distributions.

Theorems 3.2 and 3.3 concern continuous time random walks on graphs with constant speed: we find conditions on the jump rates under which the marginals of the bridge have lighter tails than those of the simple random walk. For their proof we rely on some elementary, though non trivial combinatorial constructions that allow to control the growth of the reciprocal characteristics associated with the cycles of the graph, as the length of the cycles increases. The study of bridges of continuous random walks brings naturally to consider pinned Poisson random vectors: we derive concentration of measure inequality for these distributions, using a Modified Log Sobolev Inequality and an interpolation argument.

## Reciprocal characteristics

An interesting aspect is that the conditions which we impose to derive the estimates are expressed in terms of the so called reciprocal characteristics. The reciprocal characteristics of a Markov process are a set of invariants which fully determine the family of bridges associated with it: such a concept has been introduced by Krener in [34], who was interested in developing a theory of stochastic differential equations of second order, motivated by problems in Stochastic Mechanics. Several authors then contributed to the development of the theory of reciprocal processes and second order differential equations. Important contributions are those of Clark [17], Thieullen [49], Lévy and Krener [39], and Krener [35]. Roelly and Thieullien in [44,45] introduced a new approach based on integration by parts formulae. This approach was used to study reciprocal classes of continuous time jump processes in [20,22,23]. The precise definitions are given at Definitions 2.1 and 3.1 below. However, let us give some intuition on why they are an interesting object to consider to bring some answers to the aforementioned problems. For simplicity, we assume that $\mathbb{P}^{x}$ is a diffusion with drift $b$ and unitary dispersion coefficients. It is well known that the bridge $\mathbb{P}^{x y}$ is another Brownian diffusion with unitary diffusion matrix and whose drift field $\tilde{b}$ admits the following representation:

$$
\tilde{b}(t, z)=b(t, z)+\nabla \log h(t, z)
$$

where $h(t, z)$ solves the Kolmogorov backward PDE:

$$
\partial_{t} h(t, z)+b \cdot \nabla h(t, z)+\frac{1}{2} \Delta h(t, z)=0, \quad \lim _{t \uparrow 1} h(t, z)=\delta_{y} .
$$

This is the classical way of looking at bridges as $h$-transforms, which goes back to Doob [28]. However, it might not be the most convenient one to perform explicit computations. The first reason is that $h$ is not given in explicit form. Moreover, this representation does not account for the time symmetric nature of bridges. Actually, the problem of restoring this time symmetry was one of the motivations for several definitions of conditional velocity and acceleration
for diffusions in the context of stochastic mechanics, see e.g. [25,41,49]. The theory of reciprocal processes proposes a different approach to bridges: there one looks for a family of (non-linear) differential operators $\mathfrak{A}$ with the property that the system of equations

$$
\mathscr{A} \tilde{b}=\mathscr{A} b, \quad \mathscr{A} \in \mathfrak{A}
$$

together with some boundary conditions characterizes the drift $\tilde{b}$ of $\mathbb{P}^{x y}$. For diffusions, they were computed for the first time by Krener in [34], and subsequently used by Clark [17] to characterize reciprocal processes.

For instance, in the case of 1-dimensional Brownian diffusions we have $\mathfrak{A}=\{\mathscr{A}\}$ with

$$
\mathscr{A} b=\frac{1}{2} \partial_{x x} b+b \partial_{x} b+\partial_{t} b .
$$

The advantage of this approach is to show that the drift of the bridge $\tilde{b}$ depends on $b$ only through the subfields $\mathscr{A} b$, for $\mathscr{A} \in \mathfrak{A}$, and not on anything else. In other words, two different processes with the same reciprocal characteristics share their bridges (for results of this type, see [6,20-23,29,44,45]). Therefore, one sees that any optimal condition to control the fluctuations of $\mathbb{P}^{x y}$ shall be formulated in terms of the characteristics since other conditions will necessarily involve some features of $b$ which play no role in the construction of $\mathbb{P}^{x y}$. This simple observation already rules out some naive approaches to the problems studied in this paper. Indeed, one might observe that when $\mathbb{P}^{x}$ is time homogeneous we have

$$
\mathbb{P}^{x y}\left(X_{t} \in d z\right) \propto \mathbb{P}^{x}\left(X_{t} \in z+d z\right) \mathbb{P}^{z}\left(X_{1-t} \in y+d y\right)
$$

and then an optimal criterion to control the fluctuations of the marginals of $\mathbb{P}$ suffices. But since any known condition to bound them is not expressed in terms of the reciprocal characteristics, this strategy has to be discarded. Reciprocal characteristics enjoy a probabilistic interpretation: they appear as the coefficient of the leading terms in the short time expansion of either the conditional probability of some events (see [21] for the discrete case) or the conditional mean acceleration (see [35] in the diffusion setting). Indeed, one can view the results of this article as the global version of the "local" estimates which appear in the works above. A first result in this direction has been obtained in [19], where a comparison principle for bridges of counting processes is proven. Reciprocal characteristics have been divided into two families, harmonic characteristics and rotational (closed walk) characteristics. We discuss the role of harmonic characteristics in the diffusion setting and the role of rotational characteristics for continuous time random walks on graphs.

## Organization of the paper

In Sections 2 and 3 present our main results for diffusions and random walks. They are Theorems 2.1, 3.1, 3.2 and 3.3. Section 4 is devoted to proofs. We collect in the Appendix some results on which we rely for the proofs.

## General notation

We consider Markov processes over [0,1] whose state space $\mathcal{X}$ is either $\mathbb{R}^{d}$ or the set of vertices of a countable directed graph. We always denote by $\Omega$ the càdlàg space over $\mathcal{X}$, by $\left(X_{t}\right)_{0 \leq t \leq 1}$ the canonical process, and by $\mathcal{P}(\Omega)$ the space of probability measures over $\Omega$. On $\Omega$ a Markov probability measure $\mathbb{P}$ is given, and we study its bridges. In our setting, bridges will always be well defined for every $x, y \in \mathcal{X}^{2}$ and not only in the almost sure sense. We will make clear case by case why this is possible. As usual $\mathbb{P}^{x}$ is $\mathbb{P}\left(\cdot \mid X_{0}=x\right), \mathbb{P}^{x y}$ is the $x y$ bridge, $\mathbb{P}^{x y}:=\mathbb{P}\left(\cdot \mid X_{0}=x, X_{1}=y\right)$. For $I \subseteq[0,1]$, we call $X_{I}$ the collection $\left(X_{t}\right)_{t \in I}$ and the image measure of $X_{I}$ is denoted $\mathbb{P}_{I}$. Similarly, we define $\mathbb{P}_{I}^{x}$, and $\mathbb{P}_{I}^{x y}$. For a general $\mathbb{Q} \in \mathcal{P}(\Omega)$, expectation under $\mathbb{Q}$ is denoted $\mathbb{E}_{\mathbb{Q}}$. We use the notation $\propto$ when two functions differ only by a multiplicative constant.

## 2. Bridges of gradient diffusions: Concentration of measure for the marginals

Preliminaries. We consider gradient-type diffusions. The potential $U$ is possibly time dependent and satisfies one among hypothesis (2.2.5) and (2.2.6) of Theorem 2.2.19 in [47], which ensure existence of solutions for

$$
\begin{equation*}
d X_{t}=-\nabla U\left(t, X_{t}\right) d t+d B_{t}, \quad X_{0}=x . \tag{1}
\end{equation*}
$$

Bridges of Brownian diffusions are well defined for any $x, y \in \mathbb{R}^{d}$. This fact is ensured by [13, Th. 1] and the fact that $\mathbb{P}$ admits a smooth transition density. A special notation is used for Ornstein-Uhlenbeck processes. We use ${ }^{\alpha} \mathbb{P}^{x}$ for the law of:

$$
\begin{equation*}
d X_{t}=-\alpha X_{t} d t+d B_{t}, \quad X_{0}=x \tag{2}
\end{equation*}
$$

where $\alpha>0$ is a positive constant. ${ }^{\alpha} \mathbb{P}^{x y}$ is then the $x y$ bridge of ${ }^{\alpha} \mathbb{P}^{x}$. Let us give some standard notation. For $v \in \mathbb{R}^{d}$, $v^{T}$ is the transposed vector. If $w$ is another vector in $\mathbb{R}^{d}$, we denote the inner product of $v$ and $w$ by $v \cdot w$. Similarly, if $H$ is a matrix and $v$ a vector, the product is denoted $H \cdot v$. The Hessian matrix of a function $U$ is denoted Hess $(U)$, and by $\operatorname{Hess}(U) \geq \alpha$ id we mean, as usual, that

$$
\inf _{v: v \cdot v=1} v^{T} \cdot \operatorname{Hess}(U)(z) \cdot v \geq \alpha
$$

The norm of $v \in \mathbb{R}^{d}$ is $\|v\|$. Let us now give definition of reciprocal characteristics for gradient diffusions. It goes back to Krener [34].

Definition 2.1. Let $U:[0,1] \times \mathbb{R}^{d} \rightarrow \mathbb{R}$ be a smooth potential. We define $\mathscr{U}:[0,1] \times \mathbb{R}^{d} \rightarrow \mathbb{R}$ as:

$$
\begin{equation*}
\mathscr{U}(t, z):=\left[\frac{1}{2}\|\nabla U\|^{2}-\partial_{t} U-\frac{1}{2} \Delta U\right](t, z) \tag{3}
\end{equation*}
$$

The harmonic characteristic associated with $U$ is the vector field $\nabla \mathscr{U}$.
Measuring the fluctuations. Consider the bridge-marginal $\mathbb{P}_{t}^{x y}$. We denote its density w.r.t. to the Lebesgue measure by $p_{t}^{x y}(z)$. As an indicator for the "randomness" of $\mathbb{P}_{t}^{x y}$ we use $\gamma(t)$, defined by:

$$
\begin{equation*}
\gamma(t)=\sup \left\{\beta:-\operatorname{Hess}\left(\log p_{t}^{x y}\right)(z) \geq \beta \mathbf{i d}\right\} \tag{4}
\end{equation*}
$$

It is well known that lower bounds on $\gamma(t)$ translate into concentration properties for $\mathbb{P}_{t}^{x y}$, see Theorem 2.7 of [36]. The better the bound, the stronger the concentration. In the Ornstein Uhlenbeck case, $\gamma(t):=\gamma_{\alpha}(t)$ can be explicitly computed. The actual computation will be carried out in the proof of Theorem 2.1. We have:

$$
\begin{equation*}
\gamma_{\alpha}(t)=\frac{2 \alpha(1-\exp (-2 \alpha))}{(1-\exp (-2 \alpha t))(1-\exp (-2 \alpha(1-t)))} \tag{5}
\end{equation*}
$$

Note that $\gamma_{\alpha}$ obeys few stylized facts:
(i) It is symmetric around $1 / 2$ : this reflects the time symmetry of the bridge.
(ii) It converges to $+\infty$ as $t$ converges to either 0 or 1 . This is due to the pinning.
(iii) $\gamma_{\alpha}$ is convex in $t$. This also agrees with the description of the dynamics of a bridge we sketched in the Introduction. Convexity reflects the fact that, as time passes, the balance of power between pinning and randomness goes in favor of pinning, whose impact on the dynamics grows stronger and stronger, whereas the push towards randomness stays constant, since the diffusion coefficient does not depend on time.
(iv) It is increasing in $\alpha$.

Theorem 2.1 is a comparison theorem for $\gamma(t)$. We show that if the Hessian of $\mathscr{U}$ (see (3)) enjoys some convexity lower bound, say $\frac{1}{2} \alpha^{2}$, then $\gamma(t)$ lies above $\gamma_{\alpha}(t)$. This means that $\mathbb{P}^{x y}$ is more concentrated than ${ }^{\alpha} \mathbb{P}^{x y}$.

Theorem 2.1. Let $\mathbb{P}^{x}$ be the law of (1) and $\mathscr{U}$ be defined at (3). If, uniformly in $r \in[0,1], z \in \mathbb{R}^{d}$

$$
\begin{equation*}
\operatorname{Hess}(\mathscr{U})(r, z) \geq \frac{\alpha^{2}}{2} \mathbf{i d} \tag{6}
\end{equation*}
$$

then the following estimate holds for any $t \in[0,1], R>0$, and any 1-Lipschitz function $f$ :

$$
\mathbb{P}^{x y}\left(f\left(X_{t}\right) \geq \mathbb{E}_{\mathbb{P}} x y\left(f\left(X_{t}\right)\right)+R\right) \leq \exp \left(-\frac{1}{2} \gamma_{\alpha}(t) R^{2}\right)
$$

where $\gamma_{\alpha}(t)$ is defined at (5).

The proof of Theorem 2.1 uses three main tools: the first one is an integration by parts formula for bridges of Brownian diffusions due to Roelly and Thieullen, see [44] and [45]. Such formula has the advantage of elucidating the role of reciprocal characteristics, and we reported it in the Appendix. The second one is a statement about the preservation of strong log-concavity due to Brascamp and Lieb [10]. This theorem is a quantitative version of the well known fact that marginals of log concave distributions are log concave. We refer to Remark 4.1 for more comparisons between Theorem 2.1 with some of the results of [10]. Finally, we will profit from the well known concentration of measure properties of log concave distributions, for which we refer to [36, Chapter 2].

Example 2.1. Let us consider $d=1$ and a a potential $U(z)$ of the form $a z^{4}+b z^{2}$ for some $a, b>0$. Then we have that

$$
\mathscr{U}(r, z)=8 a^{2} z^{6}+8 a b z^{4}+\left(2 b^{2}-6 a\right) z^{2}-b
$$

so that

$$
\partial_{z z} \mathscr{U}(r, z):=240 a^{2} z^{4}+96 z^{2}+\left(4 b^{2}-12 a\right) .
$$

A standard computation shows that the hypothesis (6) is satisfied iff $b \geq \sqrt{3 a}$. In this case, one can choose $\alpha=$ $2 \sqrt{2 b^{2}-6 a}$.

Remark 2.1. The condition (6) does not depend on the endpoints $(x, y)$ of the bridge.
Remark 2.2. The estimates obtained here are sharp, as the Ornstein Uhlenbeck case demonstrates: a simple computation shows that $\frac{\alpha^{2}}{2}$ id is indeed the Hessian of $\mathscr{U}$ when $\mathbb{P}^{x}={ }^{\alpha} \mathbb{P}^{x}$.

Remark 2.3. The $\Gamma_{2}$ condition of Bakry and Émery in this case reads as

$$
\operatorname{Hess}(U) \geq \alpha \mathbf{i d},
$$

which is clearly very different from (6). In particular, (6) involves derivatives of order up to four. However, a simple manipulation of Girsanov's theorem formally relates the two conditions. Consider the density $M$ of $\mathbb{P}^{x}$ with respect to the Brownian motion started at $x$. We have by Girsanov's formula (for simplicity, we assume $U$ not to depend on time):

$$
M=\exp \left(-\int_{0}^{1} \nabla U\left(X_{t}\right) \cdot d X_{t}-\frac{1}{2} \int_{0}^{1}\|\nabla U\|^{2}\left(X_{t}\right) d t\right)
$$

A standard application of Itô formula allows to rewrite $M$ as

$$
\exp (-\underbrace{U\left(X_{1}\right)}_{\Gamma_{2}}+U(x)-\frac{1}{2} \int_{0}^{1} \underbrace{\|\nabla U\|^{2}\left(X_{t}\right)-\Delta U\left(X_{t}\right)}_{=2 \mathscr{U}} d t)
$$

Imposing convexity on the first term, one obtains $\Gamma_{2}$, whereas imposing convexity on the integrand, yields (6).
Remark 2.4. Krener's notion of reciprocal characteristic goes well beyond gradient type diffusions. Indeed, they are defined for non gradient vector fields as well as for non unitary diffusion coefficients. For example, a general smooth drift field $b(t, z)$ admits two reciprocal characteristics: the harmonic charachteristic, which can be defined as in Definition 2.1, and the rotational characteristic $\left(\Psi_{i, j}\right)_{1 \leq i<j \leq d}$, which is the rotational of the drift field:

$$
\Psi_{i, j}(t, z)=\left(\partial_{i} b^{j}-\partial_{j} b^{i}\right)(t, z) .
$$

More information can be found in the papers by Krener quoted in the Introduction, or in Murr's phd thesis [40, Ch. 5]. The original motivation for the introduction of reciprocal characteristics was to describe the dynamic properties
of a class of processes called reciprocal processes, which can be written as arbitrary bridge mixtures of a given reference Markov process (in this case, a diffusion process). Such processes fail to be Markov in general. However, using reciproal characteristics, Krener described them as "second order diffusion processes", see [35, Thm 2.1]. Our concentration of measure results do not apply to general reciprocal processes, for the simple reason that concentration is not stable under mixing. However, reciprocal characteristics can be used to derive other quantitative results the reciprocal processes associated with a gradient diffusion. For instance, in [24, Thm 1.3] a comparison principle for reciprocal processes is proven under suitable assumptions on the characteristic.

## 3. Continuous time random walks

In this section we prove various estimates for the bridges of continuous time random walks with constant speed. These estimate are obtained by imposing conditions on the closed walk characteristics associated with the random walk. It is shown in [21, Th. 2.4] that the closed walk characteristics of a constant speed random walk fully determine its bridges.

Preliminaries. Let $\mathcal{X}$ be a countable set and $\mathcal{A} \subset \mathcal{X}^{2}$. The directed graph associated with $\mathcal{A}$ is defined by means of the relation $\rightarrow$. For all $z, z^{\prime} \in \mathcal{X}$ we have $z \rightarrow z^{\prime}$ if and only if $\left(z, z^{\prime}\right) \in \mathcal{A}$. We denote $\left(\mathcal{X}^{2}, \rightarrow\right)$ this directed graph, say that any $\left(z, z^{\prime}\right) \in \mathcal{A}$ is an arc and write $\left(z \rightarrow z^{\prime}\right) \in \mathcal{A}$ instead of $\left(z, z^{\prime}\right) \in \mathcal{A}$. For any $n \geq 1$ and $x_{0}, \ldots, x_{n} \in \mathcal{X}$ such that $x_{0} \rightarrow x_{1}, x_{1} \rightarrow x_{2}, \ldots, x_{n-1} \rightarrow x_{n}$, the ordered sequence ( $x_{0}, x_{1}, \ldots, x_{n}$ ) is called a walk. We adopt the notation $\mathbf{w}=\left(x_{0} \rightarrow x_{1} \rightarrow \cdots \rightarrow x_{n}\right)$. When $x_{n}=x_{0}$, the walk $\mathbf{c}=\left(x_{0} \rightarrow x_{1} \rightarrow \cdots \rightarrow x_{n}=x_{0}\right)$ is said to be closed . The length $n$ of $\mathbf{w}$ is denoted by $\ell(\mathbf{w})$. The graph distance $d(x, y)$ is the length of the shortest walk going from $x$ to $y$. We introduce a continuous time random walk $\mathbb{P}^{x}$ with intensity of jumps $j: \mathcal{A} \rightarrow \mathbb{R}_{+} . j\left(z \rightarrow z^{\prime}\right)$ is the rate at which the walk jumps from $z$ to $z^{\prime}$. To ensure existence of the process, we make some standard assumptions on $j$ and ( $\mathcal{X}, \rightarrow$ ), which are detailed at Assumptions 4.2 and 4.1. These assumptions also ensure that the bridge is defined between any pair of vertices $x, y \in \mathcal{X}$. In this paper, we consider constant speed random walks (CSRW). This means that the function $z \mapsto \bar{j}(z)=\sum_{z^{\prime}: z \rightarrow z^{\prime}} j\left(z \rightarrow z^{\prime}\right)$ is a constant. Let us define the closed walk characteristics associated with $j$. We refer to $[20,21,23]$ for an extensive discussion.

Definition 3.1. Let $(\mathcal{X}, \rightarrow)$ be a graph satisfying Assumption 4.2 and $j$ be a jump intensity satisfying Assumption 4.1. For any closed walk $\mathbf{c}=\left(x_{0} \rightarrow \cdots \rightarrow x_{n}=x_{0}\right)$ we define the corresponding closed walk characteristic as:

$$
\begin{equation*}
\Phi_{j}(\mathbf{c}):=\prod_{i=0}^{n-1} j\left(x_{i} \rightarrow x_{i+1}\right) . \tag{7}
\end{equation*}
$$

The intuition behind the fact that the closed walk characteristics determine the bridge of a random walk with constant speed is given in [21, Th 2.7]. It is shown there that they express the short time probability for any bridge to follow a given closed walk. This result is the analogous for bridges of the basic fact that the jump intensity of a random walk expresses the short time probability to observe a transition along a given arc. Let us remark that reciprocal characteristics are defined also for random walks with non constant speed. In this case, one has to add to the closed walk characteristics the so called harmonic characteristics (see Definitions 2.3 in [21]).

### 3.1. Concentration of measure for pinned Poisson random vectors

## A simple question

We fix $k \in \mathbb{N}$ and consider the graph $(\mathcal{X}, \rightarrow)$ where $\mathcal{X}=\mathbb{Z}$, and $z \rightarrow z^{\prime}$ if and only if $z^{\prime}=z-1$ or $z^{\prime}=z+k$. We consider a random walk $\mathbb{P}$ with time and space-homogeneous rates:

$$
j(z \rightarrow z+k) \equiv j_{k}, \quad j(z \rightarrow z-1) \equiv j_{-1} \quad \forall z \in \mathbb{Z} .
$$

The simple ${ }^{1}$ closed walks of $(\mathcal{X}, \rightarrow)$ are of the form

$$
\mathbf{c}=(x \rightarrow x-1 \rightarrow x-2 \rightarrow \cdots \rightarrow x-k \rightarrow x)
$$

[^0]for some $x \in \mathbb{Z}$ and, because of the homogeneity of the rates, we have
$\forall \mathbf{c}$ simple closed walk, $\quad \Phi_{j}(\mathbf{c}) \equiv j_{-1}^{k} j_{k}:=\Phi$.
We introduce random variables $N^{k}$ and $N^{-1}$ which count the number of jumps along arcs of the form $(x \rightarrow x+k)$ and $(x \rightarrow x-1)$ respectively. Obviously, under $\mathbb{P}^{0}$ the vector $\left(N^{k}, N^{-1}\right)$ is a two dimensional vector with independent components following a Poisson law of parameter $j_{k}$ and $j_{-1}$ respectively. Let us consider the 00 bridge of $\mathbb{P}, \mathbb{P}^{00}$. The distribution of $N^{k}$ is that of the first coordinate of a Poisson random vector conditioned to belong to an affine subspace, precisely $\left\{\left(n^{k}, n^{-1}\right) \in \mathbb{N}^{2}: k n^{k}-n^{-1}=0\right\}$. We call this distribution $\rho_{\Phi}$.
\[

$$
\begin{equation*}
\rho_{\Phi}(\cdot)=\mathbb{P}^{00}\left(N^{k} \in \cdot\right)=\mathbb{P}^{0}\left(N^{k} \in \cdot \mid k N^{k}-N^{-1}=0\right) \tag{8}
\end{equation*}
$$

\]

We aim at establishing a concentration of measure inequality for $\rho_{\Phi}$. This is very natural in the study of bridges: one wants to know how many jumps of a certain type the bridge performs. The role of pinning against randomness should be visible in the concentration properties of this distribution. This task is not trivial because $\rho_{\Phi}$ is no longer a Poissonian distribution. This is in contrast with the Gaussian case, where pinning a Gaussian vector to an affine subspace gives back a Gaussian vector. To gain some insight on what rates to expect let us recall Chen's characterization of the Poisson distribution (see [14]) of parameter $\lambda$, which we call $\mu_{\lambda}$ :

$$
\begin{equation*}
\forall f>0 \quad \lambda \mathbb{E}_{\mu_{\lambda}}(f(n+1))=\mathbb{E}_{\mu_{\lambda}}(f(n) n) . \tag{9}
\end{equation*}
$$

Using [20, Prop. 3.8], one finds an analogous characterization for $\rho_{\Phi}$ as the only solution of

$$
\begin{equation*}
\forall f>0 \quad \Phi \mathbb{E}_{\rho_{\Phi}}(f(n+1))=\mathbb{E}_{\rho_{\Phi}}\left(f(n) n \prod_{i=0}^{k-1}(k n-i)\right) . \tag{10}
\end{equation*}
$$

The density on the right hand side of (10) is a polynomial of degree $k+1$. By choosing $f(n)=\mathbf{1}_{n=z}$ in both (9) and (10), we obtain:

$$
\begin{equation*}
\forall z \in \mathbb{N}, \quad \frac{\mu_{\lambda}(z-1)}{\mu_{\lambda}(z)}=\frac{1}{\lambda} z, \quad \frac{\rho_{\Phi}(z-1)}{\rho_{\Phi}(z)}=\frac{z \prod_{i=0}^{k-1}(k z-i)}{\Phi} \sim \frac{z^{k+1}}{\Phi} \tag{11}
\end{equation*}
$$

from which we deduce that $\rho_{\Phi}$ has much lighter tails than $\mu_{\lambda}$. The corresponding concentration inequalities should reflect this fact. We derived the following result:

Theorem 3.1. Let $\rho_{\Phi}$ be defined by (8). Consider a 1-Lipschitz function $f$. Then, for all $R>0$ :

$$
\begin{equation*}
\rho_{\Phi}\left(f \geq \mathbb{E}_{\rho_{\Phi}}(f)+R\right) \leq \exp (-(k+1) R \log R+[\log (\Phi)+c] R+o(R)) . \tag{12}
\end{equation*}
$$

The constant $c$ is a structural constant which depends only on $k$.
In (12), and in the rest of the paper, by $o(R)$ we mean a function $g$ such that $\lim _{R \rightarrow+\infty} g(R) / R=0$. The $o(R)$ term in (12) can be made explicit: it depends on $\Phi$ and $k$, but not on $f$. By following carefully the proof of this theorem, it is possible to see that the bound (12) is interesting (i.e. the right hand side is $<1$ ) when $R \geq \Phi+\frac{1}{k+1} \Phi^{1 /(k+1)}$. The bound is very accurate for $R$ large, see Remark 4.2.

## Remark 3.1.

(i) The size of the large jump drives the leading order in the concentration rate, while the reciprocal characteristic is responsible for the exponential correction term.
(ii) The larger $k$, the more concentrated is the random variable. This is because, to compensate a large jump, a bridge has to make many small jumps and this reduces the probability of large jumps.
(iii) The smaller $\Phi$, the better the concentration. This fits with the short time interpretation of $\Phi$ given in [21, Th. 2.7].

Remark 3.2 (Sharpness). It can be seen, using Stirling's approximation and (11), that the leading order term $-(k+$ 1) $R \log R$ is optimal and the linear dependence on $\log (\Phi)$ at the exponential correction term is correct.

The proof of this theorem is based on the construction of a measure $\pi_{\Phi}$ which interpolates $\rho_{\Phi}$ and for which the modified $\log$ Sobolev (MLSI) inequality gives sharp concentration results. Several MLSI have been proposed for the Poisson distribution. We use the one which is considered for example in in [26] and [51, Cor 2.2]. The reason for this choice is that there are robust criteria (see [11]) under which such inequality holds. Other kinds of modified Logarithmic Sobolev inequalities for the Poisson law are presented in [7,8,12] and [30].

The interpolation argument is crucial to achieve the rate $-(k+1) R \log R$. Indeed, the MLSI cannot yield any better than $-R \log R$. While doing the proof, we repeat the classical Herbst's argument for the MLSI, improving on some results of [7] (which were obtained by using a different MLSI).

### 3.2. Bridges of CSRW on the square lattice: Refined large deviations for the marginals

Let $v_{1}=(1,0), v_{2}=(0,1)$. The square lattice is defined by $\mathcal{X}=\mathbb{Z}^{2}$ and by saying that the neighbors of $x$ are $x \pm v_{1}$ and $x \pm v_{2}$. We associate to any vertex $x \in \mathbb{Z}^{2}$ the clockwise oriented face $\mathbf{f}_{x}$ and two closed walks of length two, $\mathbf{e}_{x, 1}, \mathbf{e}_{x, 2}$ as follows:

$$
\begin{aligned}
& \mathbf{f}_{x}=\left(x \rightarrow x+v_{2} \rightarrow x+v_{1}+v_{2} \rightarrow x+v_{1} \rightarrow x\right) \\
& \mathbf{e}_{x, 1}=\left(x \rightarrow x+v_{1} \rightarrow x\right), \quad \mathbf{e}_{x, 2}=\left(x \rightarrow x+v_{2} \rightarrow x\right)
\end{aligned}
$$

The set of closed walks of length two is denoted $\mathcal{E}$

$$
\begin{equation*}
\mathcal{E}=\{(x \rightarrow y \rightarrow x):(x \rightarrow y) \in \mathcal{A}\}=\left\{\mathbf{e}_{x, i}, x \in \mathcal{X}, i \in\{1,2\}\right\} \tag{13}
\end{equation*}
$$

The set of clockwise oriented faces is $\mathcal{F}$

$$
\mathcal{F}:=\left\{\mathbf{f}_{x}: x \in \mathbb{Z}^{2}\right\}
$$

In this subsection we prove an analogous statement to Theorem 2.1 for CSRWs on the square lattice. A serious difficulty here is represented by the fact that there is not such a well developed theory to prove concentration of measure inequalities with Poissonian rates. In particular, all the tools we use in the proof of Theorem 2.1 do not have a "Poissonian" counterpart. To the best of our knowledge, the only result concerning Poisson-type deviation bounds for the marginals of a continuous time Markov chain is due to Joulin [32]. In Theorem 3.1 the author provides abstract curvature conditions under which such bounds hold. However, explicit construction of Markov generators fulfilling these conditions is limited to 1-dimensional birth and death processes, see Section 4. Therefore, instead of using $\gamma(t)$ (see (4)), we shall use a simpler way to measure the fluctuations of the bridge, adopting a Large Deviations viewpoint. We will look at asymptotic tail expansions, and relate the coefficients in the expansions with reciprocal characteristics. This is a much rougher measurement, but still gives interesting results. We consider the 00 bridge $\mathbb{P}^{00}$ of the simple random walk which jumps along any arc with intensity constantly equal to $\lambda$. Using some classical expansions (see Lemma A.4) one finds that

$$
\begin{equation*}
\log \mathbb{P}^{00}\left(d\left(X_{t}, \mathbb{E}_{\mathbb{P}^{00}}\left(X_{t}\right)\right) \geq R\right)=-2 R \log R+\left[\log \left(4 \lambda^{2} t(1-t)\right)+2\right] R+o(R) \tag{14}
\end{equation*}
$$

Theorem 3.2 provides a condition on the reciprocal characteristics for (14) to hold when replacing $=$ with $\leq$. The conditions are expressed as conditions on the closed walks characteristics associated to the walks in $\mathcal{E} \cup \mathcal{F}$ : we Figure 1 for a visual explanation.

Theorem 3.2. Let $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$be the intensity of a CSRW $\mathbb{P}$ on the square lattice. Assume that for some $\lambda>0$

$$
\begin{equation*}
\forall x \in \mathbb{Z}^{2}, i \in\{1,2\} \quad \Phi_{j}\left(\mathbf{e}_{x, i}\right) \leq \lambda^{2} \tag{15}
\end{equation*}
$$

and

$$
\begin{equation*}
\forall x \in \mathbb{Z}^{2} \quad \Phi_{j}\left(\mathbf{e}_{x, 2}\right) \Phi_{j}\left(\mathbf{e}_{x, 1}\right) \leq \Phi_{j}\left(\mathbf{f}_{x}\right) \leq \Phi_{j}\left(\mathbf{e}_{x+v_{1}, 2}\right) \Phi_{j}\left(\mathbf{e}_{x+v_{2}, 1}\right) \tag{16}
\end{equation*}
$$



Fig. 1. A visual explanation of condition (16): The characteristic associated with the face $\mathbf{f}_{x}$ (red) has to be larger than the product of the characteristics associated with its left and lower side (blue), and smaller than the product of the characteristics associated with its upper and right side (yellow).

Then for any $x \in \mathbb{Z}^{2}$

$$
\log \mathbb{P}^{x x}\left(d\left(X_{t}, \mathbb{E}_{\mathbb{P}^{x x}}\left(X_{t}\right)\right) \geq R\right) \leq-2 R \log R+\left[\log \left(4 \lambda^{2} t(1-t)\right)+2\right] R+o(R) .
$$

Example 3.1. Consider another random walk with space homogeneous rates. This means that for some $j_{1}, j_{-1}, j_{2}, j_{-2}$ we have

$$
j\left(x \rightarrow x+v_{1}\right) \equiv j_{1}, \quad j\left(x \rightarrow x-v_{1}\right) \equiv j_{-1}
$$

and

$$
j\left(x \rightarrow x+v_{2}\right) \equiv j_{2}, \quad j\left(x \rightarrow x-v_{1}\right) \equiv j_{-2} .
$$

With such choices, condition (16) is always verified with $=$ instead of $\leq$, and therefore Theorem 3.2 applies with $\lambda=\max \left\{j_{1} j_{-1}, j_{2} j_{-2}\right\}$.

Remark 3.3. The function $t \mapsto-\log \left(4 \lambda^{2} t(1-t)\right)$ plays the same role as $\gamma_{\alpha}(t)$ in the diffusion case and it features the same stylized facts we observed for it.

## Remark 3.4.

(i) One nice aspect of (15) and (16) is that they are local conditions, that is, for a given $\mathbf{f}_{x}$ they depend only on the closed walks of length two that intersect $\mathbf{f}$.
(ii) The fact that $j$ fulfills the hypothesis of the Theorem does not imply that $j\left(z \rightarrow z^{\prime}\right) \leq \lambda$ on every arc of the lattice. This means that there exist CSRWs whose tails are heavier than the simple random walk, but the tails of their bridges are lighter than those of the bridge of the simple random walk.
(iii) These conditions are easy to check and there are many jump intensities satisfying them. We show in Lemma 4.7 that for any $\varphi: \mathcal{E} \cup \mathcal{F} \rightarrow \mathbb{R}_{+}$there exists at least one intensity $j$ such that $\Phi_{j}(\mathbf{c})=\varphi(\mathbf{c})$ over $\mathcal{E} \cup \mathcal{F}$.
(iv) In the proof of Theorem 3.2 it is seen how condition (16) makes sure that among the simple closed walks with the same perimeter, the ones with smallest area are those which have the largest value of $\Phi_{j}(\cdot)$.

The idea of the proof of Theorem 3.2 is that the local conditions we impose on the faces ensure that for any closed walk $\Phi_{j}(\mathbf{c})$ can be controlled in terms of $\lambda^{\ell(\mathbf{c})}$. Bulding on Girsanov's theorem for continuous time random walks


Fig. 2. Left: The blue arcs form a tree $\mathcal{T}$ : each pair of red arcs forms an element of $\mathcal{E}^{*}$. Right: The closed walk $\mathbf{c}_{d \rightarrow a}$ is obtained by concatenating ( $d \rightarrow a$ ) with the unique simple walk in $\mathcal{T}$ from $a$ to $d$ (blue).
(see [18, Th. 2.3.1] or the more general results containted in [31,37]), we prove an ad hoc version for bridges, which gives us a form of the density in terms of the reciprocal closed walk characteristics. Finally, we conclude that such density has a global upper bound on path space. It is very likely that one can relax (15), (16) by imposing them only in the limit when $\|x\| \uparrow+\infty$. To simplify the presentation and the proofs, we did not consider this case.

### 3.3. Bridges of CSRW on general graphs

We consider a graph $(\mathcal{X}, \rightarrow)$ satisfying Assumption 4.2 below and a CSRW $\mathbb{P}^{x}$ on $(\mathcal{X}, \rightarrow)$ with intensity $j$. Our aim is to prove a result similar to Theorem 3.2. As the notion of faces does not exist for general graphs, we work with its natural substitute: the basis of closed walks. This notion is a slight generalization of the notion of cycle basis for an undirected graph, for which we refer to [9, Section 2.6].

## Trees and basis of the closed walks

Prior to the definition, let us recall some terminology about graphs. A subgraph of $(\mathcal{X}, \rightarrow)$ is a graph on $\mathcal{X}$ whose arc set in included in the arc set $\mathcal{A}$ of $(\mathcal{X}, \rightarrow)$. We say that two subgraphs intersect if their arc sets do so, and we say that one is included in the other if their arc sets are so. Let us recall that for a given vertex $z \in \mathcal{X}$, its outer degree is $\operatorname{deg}(z):=\left|\left\{z^{\prime \prime}:\left(z \rightarrow z^{\prime \prime}\right) \in \mathcal{A}\right\}\right|$. As in the previous subsection, the set of closed walks of length two is denoted $\mathcal{E}$. Figure 2 helps in understanding the next definition.

Definition 3.2 (Tree and basis of closed walks). Let $(\mathcal{X}, \rightarrow)$ be a graph fulfilling Assumption 4.2.
(a) We call tree a symmetric connected subgraph $\mathcal{T}$ of $(\mathcal{X}, \rightarrow)$ which spans ${ }^{2} \mathcal{X}$ and does not have closed walks of length at least three. ${ }^{3}$
(b) For a tree $\mathcal{T}, \mathcal{E}^{*}$ is the set of closed walks of length two which do not intersect $\mathcal{T}$.

$$
\begin{equation*}
\mathcal{E}^{*}=\{\mathbf{e} \in \mathcal{E}: \mathbf{e} \cap \mathcal{T}=\varnothing\} \tag{17}
\end{equation*}
$$

(c) For any $(x \rightarrow y) \in \mathcal{A} \backslash \mathcal{T}$ we denote $\mathbf{c}_{x \rightarrow y}$ the closed walk obtained by concatenating $(x \rightarrow y)$ with the only simple directed walk from $y$ to $x$ in $\mathcal{T}$.

[^1](d) Let $\mathcal{T}$ be a tree. A $\mathcal{T}$-basis of the closed walks of $(\mathcal{X}, \rightarrow)$ is any subset $\mathcal{C}$ of closed walks of the form
$$
\mathcal{C}=\mathcal{C}^{*} \cup \mathcal{E},
$$
where $\mathcal{C}^{*}$ is obtained by choosing for any $\mathbf{e}=(x \rightarrow y \rightarrow x) \in \mathcal{E}^{*}$ exactly one among $\mathbf{c}_{x \rightarrow y}$ and $\mathbf{c}_{y \rightarrow x}$. We denote the chosen element by $\mathbf{c}_{\mathrm{e}}$.

Theorem 3.3 gives a condition to control the tails of $d\left(X_{t}, x\right)$ under $\mathbb{P}^{x x}$.
Theorem 3.3. Let $(\mathcal{X}, \rightarrow)$ be a directed graph satisfying Assumption 4.2 and $1 / \delta$ its maximum outer degree. Moreover, we consider an intensity $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$satisfying Assumption 4.1 and assume that for some tree $\mathcal{T}$ and a $\mathcal{T}$-based basis for the closed walks $\mathcal{C}$ it holds that

$$
\begin{align*}
& \forall \mathbf{e} \in \mathcal{E} \backslash \mathcal{E}^{*}, \quad \Phi_{j}(\mathbf{e}) \leq(\lambda \delta)^{2},  \tag{18}\\
& \forall \mathbf{e} \in \mathcal{E}^{*}, \quad(\lambda \delta)^{\ell\left(\mathbf{c}_{\mathbf{e}}\right)-1} \Phi_{j}(\mathbf{e}) \leq \Phi_{j}\left(\mathbf{c}_{\mathbf{e}}\right) \leq(\lambda \delta)^{1-\ell\left(\mathbf{c}_{\mathbf{e}}\right)} \prod_{\substack{\mathbf{e}^{\prime} \in \mathcal{\mathcal { E }}, \mathbf{e}^{\prime} \neq \mathbf{e} \\
\mathbf{e}^{\prime} \cap \mathbf{e}_{\mathbf{e}} \neq \varnothing}} \Phi_{j}\left(\mathbf{e}^{\prime}\right) . \tag{19}
\end{align*}
$$

Then for any $x \in \mathcal{X}$ and any $t \in[0,1]$

$$
\begin{equation*}
\log \mathbb{P}^{x x}\left(d\left(X_{t}, x\right) \geq R\right) \leq-2 R \log R+R[2+2 \log (\lambda t(1-t))+3 \log (1 / \delta-1)]+o(R) \tag{20}
\end{equation*}
$$

The proof of the theorem is divided into two steps. In a first step one shows that for some constant $c, \mathbb{P}^{x x}\left(d\left(X_{t}, x\right) \geq\right.$ $R) \leq c \mathbb{S}_{\lambda}^{x x}\left(d\left(X_{t}, x\right) \geq R\right)$, where $\mathbb{S}_{\lambda}^{x}$ is the CSRW defined by:

$$
\begin{equation*}
j\left(z \rightarrow z^{\prime}\right)=\frac{\lambda}{\boldsymbol{\operatorname { d e g }}(z)} \quad \forall z \rightarrow z^{\prime} \in \mathcal{A} . \tag{21}
\end{equation*}
$$

The second step consists in estimating $\mathbb{S}_{\lambda}^{x x}\left(d\left(X_{t}, x\right) \geq R\right)$ with the right hand side of (20). Clearly, due to the fact that graph $(\mathcal{X}, \rightarrow)$ has no specific structure, the estimate we obtain is less precise than the one in Theorem 3.2. However, it can be shown to be optimal for a certain class of graphs, and it displays the same type of decay for the decay for the tails: a leading term of order $-R \log R$ and a correction term of order $R$.

Remark 3.5. Basis for closed walks have been computed explicitly for several graphs in [21, Section 4], including the complete graph and the discrete hypercube. Building on those examples, it is easy to construct jump intensities fulfilling the hypothesis of Theorem 3.3.

Remark 3.6. We show in Lemma 4.8 that to any $\varphi: \mathcal{C} \rightarrow \mathbb{R}_{+}$we can associate a CSRW whose reciprocal characteristics coincide with $\varphi$ over $\mathcal{C}$. This shows that the conditions (18) and (19) are fulfilled by a large class of Markov jump intensities. It can be seen that there exists no tree of the square lattice such that a cycle basis associated with it coincides with the faces of the lattice. Therefore Theorem 3.2 is not implied by Theorem 3.3.

## 4. Proof of the main results

## Proof of Theorem 2.1

## Preliminaries

We define $p_{t}^{x}(z)$ as the density of the marginal $\mathbb{P}_{t}^{x}$, and $p_{t}^{x y}(z)$ as the density of $\mathbb{P}_{t}^{x y}$. Clearly, if $U$ does not depend on time, we have the relation:

$$
p_{t}^{x y}(z)=\frac{p_{t}^{x}(z) p_{1-t}^{z}(y)}{p_{1}^{x}(y)} .
$$

${ }^{\alpha} p_{t}^{x}(\cdot)$ and ${ }^{\alpha} p_{t}^{x y}(\cdot)$ are defined accordingly. As Ornstein Uhlenbeck processes are Gaussian processes, for any finite set $I=\left\{0=t_{0}, t_{1}, t_{2}, \ldots, t_{l}\right\} \subseteq[0,1]$ there exists a positive definite quadratic form $\Sigma_{I}^{\alpha}$ over $\mathbb{R}^{d \times(l+1)}$ such that $\forall A \subseteq$ $\mathbb{R}^{d \times l}$ and $x \in \mathbb{R}^{d}$

$$
\begin{align*}
{ }^{\alpha} \mathbb{P}^{x}\left(X_{I} \in A\right) & =\int_{A} \exp \left(-\Sigma_{I}^{\alpha}\left(x, x^{1}, \ldots, x^{l}\right)\right) d x^{1} \cdots d x^{l} \\
& =\int_{A}\left[p_{t_{1}}^{x}\left(x^{1}\right) \prod_{j=2}^{l} p_{\Delta t_{j}}^{x^{j-1}}\left(x^{j}\right)\right] d x^{1} \cdots d x^{l}, \tag{22}
\end{align*}
$$

where we set $\Delta t_{j}:=t_{j}-t_{j-1}$. Using the transition density of the Ornstein Uhlenbeck process (see e.g. [33, Section 5.6]), we can write down the explicit expression of $\Sigma_{I}^{\alpha}$ :

$$
\begin{aligned}
& \Sigma_{I}^{\alpha}\left(x^{0}, x^{1}, \ldots, x^{l}\right) \\
& \quad=\prod_{j=1}^{l} \sqrt{\frac{\alpha}{\pi\left(1-e^{-2 \alpha \Delta t_{j}}\right)}} \exp \left(-\frac{\alpha}{\left(1-e^{-2 \alpha \Delta t_{j}}\right)}\left(x_{j}-e^{-\alpha \Delta t_{j}} x_{j-1}\right)^{2}\right),
\end{aligned}
$$

where we set $t_{0}=0$. In particular, we will be interested in the case when $I$ is the set $\Pi_{m}$ defined as

$$
\begin{equation*}
\Pi_{m}=\{0,1 / m, \ldots,(m-1) / m, 1\} . \tag{23}
\end{equation*}
$$

For $t \in[0,1]$, we define

$$
\begin{equation*}
j(t)=\max \{j: j / m<t\}, \quad \Pi_{m}^{<t}=\{0,1 / m, \ldots, j(t) / m, t\} . \tag{24}
\end{equation*}
$$

We can now prove Theorem 2.1.
Proof. In a first step we show that the density of $\mathbb{P}^{x y}$ with respect to the Brownian Bridge $\mathbb{W}^{x y}$ is given by

$$
\begin{equation*}
\frac{d \mathbb{P}^{x y}}{d \mathbb{W} x y}=\frac{1}{Z} \exp \left(-\int_{0}^{1} \mathscr{U}\left(t, X_{t}\right) d t\right):=M, \tag{25}
\end{equation*}
$$

where $\mathscr{U}$ has been defined at (3) and $Z$ is a normalization constant. To do this, we show that the measure

$$
\mathbb{Q}:=M \mathbb{W}^{x y}
$$

fulfills the hypothesis of the Duality formula by Roelly and Thieullen, see Theorem A. 1 in the Appendix. It can be easily verified that the regularity hypothesis are verified by $\mathbb{Q}$, because of the regularity of the transition density of the Brownian bridge and of the smoothness of $\mathscr{U}$. Moreover, $\mathbb{Q}\left(\left(X_{0}, X_{1}\right)=(x, y)\right)=1$. Let us now compute the directional derivative $\mathcal{D}_{h}$ of $M$. We have

$$
\begin{align*}
\mathcal{D}_{h} M(X) & =\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon}(M(X+\varepsilon h)-M(X)) \\
& =\lim _{\varepsilon \rightarrow 0} \frac{1}{Z \varepsilon} \exp \left(-\int_{0}^{1} \mathscr{U}\left(t, X_{t}+\varepsilon h(t)\right) d t\right)-\exp \left(-\int_{0}^{1} \mathscr{U}\left(t, X_{t}\right) d t\right) \\
& =\frac{1}{Z}\left[-\int_{0}^{1} \nabla \mathscr{U}\left(t, X_{t}\right) \cdot h(t) d t\right] \exp \left(-\int_{0}^{1} \mathscr{U}\left(t, X_{t}\right) d t\right) \\
& =\left[-\int_{0}^{1} \nabla \mathscr{U}\left(t, X_{t}\right) \cdot h(t) d t\right] M . \tag{26}
\end{align*}
$$

Now let us consider any simple functional $F$. By using Theorem A. $1^{4}$ for the Brownian bridge $\mathbb{W}^{x y}$, Leibniz's rule and (26) we obtain:

$$
\begin{aligned}
\mathbb{Q}\left(\mathcal{D}_{h} F\right) & =\mathbb{W}^{x y}\left(\left(\mathcal{D}_{h} F\right) M\right) \\
& =\mathbb{W}^{x y}\left(\mathcal{D}_{h}(F M)\right)-\mathbb{W}^{x y}\left(F\left(\mathcal{D}_{h} M\right)\right) \\
& =\mathbb{W}^{x y}\left((F M) \int_{0}^{1} \dot{h}(t) \cdot d X_{t}\right)+\mathbb{W}^{x y}\left((F M) \int_{0}^{1} \nabla \mathscr{U}\left(t, X_{t}\right) \cdot h(t) d t\right) \\
& =\mathbb{Q}\left(F\left[\int_{0}^{1} \dot{h}(t) \cdot d X_{t}+\int_{0}^{1} \nabla \mathscr{U}\left(t, X_{t}\right) \cdot h(t) d t\right]\right),
\end{aligned}
$$

from which (25) follows, because of the arbitrary choice of $F$. As a by-product, we obtain that, if we choose $\alpha$ as in (6), we have:

$$
\frac{d \mathbb{P}^{x y}}{d^{\alpha} \mathbb{P}^{x y}}=\exp \left(\int_{0}^{1} V\left(t, X_{t}\right) d t\right)
$$

where

$$
V\left(t, X_{t}\right)=\frac{1}{2} \alpha^{2}\|x\|^{2}-\mathscr{U}\left(t, X_{t}\right)-\log \left(Z^{\prime}\right),
$$

where $Z^{\prime}$ is a normalization constant. Note that because of (6), $V(t, \cdot)$ is concave for all $t$. The next step in the proof is to prove that $z \mapsto \frac{d \mathbb{P}_{t}^{x y}}{d^{\alpha \mathbb{P}_{t}^{x y}}}(z)$ is $\log$ concave. To do this we will show that $(x, z, y) \mapsto \frac{d \mathbb{P}_{t}^{x y}}{d^{\alpha} \mathbb{P}_{t}^{x y}}(z)$ is $\log$ concave, which is a slightly stronger statement. To this aim, we observe that, applying the Markov property for ${ }^{\alpha} \mathbb{P}^{x y}$ we have

$$
\begin{align*}
\frac{d \mathbb{P}_{t}^{x y}}{d^{\alpha} \mathbb{P}_{t}^{x y}}(z)= & \mathbb{E}_{\alpha \mathbb{P}^{x y}}\left(\exp \left(\int_{0}^{1} V\left(s, X_{s}\right) d s\right) \mid X_{t}=z\right) \\
= & \mathbb{E}_{\alpha \mathbb{P}^{x y}}\left(\exp \left(\int_{0}^{t} V\left(s, X_{s}\right) d s\right) \mid X_{t}=z\right) \\
& \times \mathbb{E}_{\alpha \mathbb{P}^{x y}}\left(\exp \left(\int_{t}^{1} V\left(s, X_{s}\right) d s\right) \mid X_{t}=z\right) . \tag{27}
\end{align*}
$$

We show that each factor is a log concave function of $(x, y, z)$. Let us consider the first factor. A further application of the Markov property for $\mathbb{P}^{x}$ gives:

$$
\mathbb{E}_{\alpha \mathbb{P}^{x y}}\left(\exp \left(\int_{0}^{t} V\left(s, X_{s}\right) d s\right) \mid X_{t}=z\right)=\mathbb{E}_{\alpha \mathbb{P}^{x}}\left(\exp \left(\int_{0}^{t} V\left(s, X_{s}\right) d s\right) \mid X_{t}=z\right):=G(x, z) .
$$

Consider a discretisation parameter $m \in \mathbb{N}$, and $\Pi_{m}, j(t), \Pi_{m}^{<t}$ as in (23), (24) and define:

$$
\begin{aligned}
& \mathcal{I}_{m}: \mathbb{R}^{d \times(j(t)+2)} \rightarrow \mathbb{R}, \\
& \mathcal{I}_{m}\left(x, x^{1}, \ldots, x^{j(t)+1}\right)=\frac{1}{m} V(0, x)+\frac{1}{m} \sum_{1 \leq j \leq j(t)-1} V\left(j / m, x^{j}\right)+((t-j(t)) / m) V\left(j(t) / m, x^{j(t)}\right)
\end{aligned}
$$

[^2]and
\[

$$
\begin{aligned}
G^{m}(x, z) & :=\mathbb{E}_{\alpha \mathbb{P}^{x}}\left(\exp \left(\mathcal{I}_{m}\left(X_{\Pi_{m}^{<t}}\right)\right) \mid X_{t}=z\right) \\
& =\mathbb{E}_{\mathbb{P}_{\mathbb{P}_{m}^{<t}}^{x}}\left(\exp \left(\mathcal{I}_{m}\left(x, x^{1}, \ldots, x^{j(t)}, x^{j(t+1)}\right) \mid x^{j(t)+1}=z\right)\right)
\end{aligned}
$$
\]

Clearly, $G^{m}(x, z) \rightarrow G(x, z)$ pointwise. The conditional density of ${ }^{\alpha} \mathbb{P}_{\Pi_{m}^{<t}}^{x}$ given $X_{t}=z$ is

$$
\begin{equation*}
\frac{1}{{ }^{\alpha} p_{t}^{x}(z)} \times\left[{ }^{\alpha} p_{1 / m}^{x}\left(x_{1}\right)\left(\prod_{j=2}^{j(t)}{ }^{\alpha} p_{1 / m}^{x^{j-1}}\left(x_{j}\right)\right){ }^{\alpha} p_{t-j(t) / m}^{x^{j}}(z)\right] \tag{28}
\end{equation*}
$$

Using (22) we rewrite both the numerator and the normalization factor at the denominator to obtain the following equivalent expression for the conditional density:

$$
\frac{\exp \left(-\Sigma_{\Pi_{m}^{<t}}^{\alpha}\left(x, x^{1}, \ldots, x^{j(t)}, z\right)\right)}{\int_{\mathbb{R}^{d \times j}(t)} \exp \left(-\Sigma_{\Pi_{m}^{<t}}^{\alpha}\left(x, x^{1}, \ldots, x^{j(t)}, z\right)\right) d x^{1} \cdots d x^{j(t)}},
$$

which then gives

$$
G^{m}(x, z):=\frac{\int_{\mathbb{R}^{d \times j(t)}} \exp \left(\mathcal{I}_{m}\left(x, x^{1}, \ldots, x^{j(t)}, z\right)-\Sigma_{\Pi_{m}^{<t}}^{\alpha}\left(x, x^{1}, \ldots, x^{j(t)}, z\right)\right) d x^{1} \cdots d x^{j(t)}}{\int_{\mathbb{R}^{d \times j(t)}} \exp \left(-\Sigma_{\Pi_{m}^{<t}}^{\alpha}\left(x, x^{1}, \ldots, x^{j(t)}, z\right)\right) d x^{1} \cdots d x^{j(t)}}
$$

By mean of the identifications

$$
\begin{aligned}
& w \hookrightarrow\left(x, x^{1}, \ldots, x^{j(t)}, z\right) \in \mathbb{R}^{d \times j(t)+2} \\
& v \hookrightarrow\left(x^{1}, \ldots, x^{j(t)}\right) \in \mathbb{R}^{d \times j(t)} \\
& v^{\prime} \hookrightarrow(x, z) \in \mathbb{R}^{d \times 2} \\
& F(w) \hookrightarrow \exp \left(\mathcal{I}_{m}(w)\right)
\end{aligned}
$$

we can rewrite $G^{m}(x, z)$ as the right hand side of (63). By the hypothesis (6) $V(t, \cdot)$ is concave for any $t \in[0,1]$. Hence $\mathcal{I}_{m}$ is concave as well. Therefore we can apply Theorem A. 2 to conclude that $G^{m}(x, z)$ is log-concave for all $m$, and therefore so is the limit. This concludes the proof that the first of the two factors appearing in (27) is log concave. With the same argument we have just used, one shows that also the other factor is log concave and therefore $\frac{d \mathbb{P}_{t}^{x y}}{d^{\alpha} \mathbb{P}_{t}^{x y}}$ is log-concave. This tells us that

$$
\begin{equation*}
\inf _{z \in \mathbb{R}^{d}, v \in \mathbb{R}^{d},\|v\|=1}-v \cdot \operatorname{Hess}\left(\log p_{t}^{x y}\right)(z) \cdot v \geq \inf _{z \in \mathbb{R}^{d}, v \in \mathbb{R}^{d},\|v\|=1}-v \cdot \operatorname{Hess}\left(\log ^{\alpha} p_{t}^{x y}\right)(z) \cdot v \tag{29}
\end{equation*}
$$

The explicit expression for ${ }^{\alpha} p_{t}^{x}(z)$ is well known, see e.g. [33, Section 5.6]:

$$
{ }^{\alpha} p_{t}^{x}(z)=\sqrt{\frac{\alpha}{\pi(1-\exp (-2 \alpha t))}} \exp \left(-\frac{\alpha}{\left(1-e^{-2 \alpha t}\right)}\left\|z-x e^{-\alpha t}\right\|^{2}\right)
$$

Therefore, as a function of $z$ :

$$
\begin{aligned}
{ }^{\alpha} p_{t}^{x y}(z) & \propto^{\alpha} p_{t}^{x}(z)^{\alpha} p_{1-t}^{z}(y) \\
& \propto \exp \left(-\frac{\alpha}{\left(1-e^{-2 \alpha t}\right)}\left\|z-x e^{-\alpha t}\right\|^{2}-\frac{\alpha}{\left(1-e^{-2 \alpha(1-t)}\right)}\left\|y-z e^{-\alpha(1-t)}\right\|^{2}\right)
\end{aligned}
$$

It is then an easy computation to show that $\mathbf{H e s s}\left(\log ^{\alpha} p_{t}^{x y}\right)(z)=-\gamma_{\alpha}(t) \mathbf{i d}$, where $\gamma_{\alpha}(t)$ had been defined at (5). Equation (29) tells that the bridge-marginal $\mathbb{P}_{t}^{x y}$ is a $\log$ concave perturbation of the marginal of the Ornstein Uhlenbeck bridge. Theorem 2.7 in [36] relates $\log$ concavity with concentration of measure. Thanks agin to (29) we are entitled to apply this theorem with the choices $\mu=\mathbb{P}_{t}^{x y}$ and $c=\gamma_{\alpha}(t)$. This gives the conclusion.

Remark 4.1. In [10, Th. 6.1] log-concavity of solutions to

$$
\partial_{t} \phi(t, z)-\frac{1}{2} \Delta \phi(t, z)+V(z) \phi(t, z)=0
$$

is established when $V$ is convex. Define now $\phi(t, z)$ as the second factor in (27) and assume for simplicity that $\alpha=0$ and $V$ not to depend on time:

$$
\phi(t, z):=\mathbb{E}_{\mathbb{W} x y}\left(\exp \left(\int_{t}^{1} V\left(X_{s}\right) d s\right) \mid X_{t}=z\right) .
$$

Using Feynman-Kac formula and the expression for the drift of the Brownian bridge we have that $\phi$ solves

$$
\partial_{t} \phi(t, z)+\frac{1}{2} \Delta \phi(t, z)+\frac{(y-z)}{(1-t)} \nabla \phi(t, z)+V(t, z) \phi(t, z)=0 .
$$

Log-concavity of $\phi$ when $V$ is concave is established in the proof of Theorem 2.1.

## Proof of Theorem 3.1

The main steps of the proof are the Lemmas 4.1 and 4.3. In Lemma 4.1 we revisit Herbst's argument, while in Lemma 4.1 we construct an auxiliary measure $\pi_{\Phi}$ for which sharp concentration bounds can be obtained through MLSI.

## A refined Herbst's argument

We apply the Herbst's argument to a Modified Log Sobolev Inequality studied, among others, by Dai Pra, Paganoni, and Posta in [26]. In their Proposition 3.1 they show that the Poisson distribution $\mu_{\lambda}(\cdot)$ of mean $\lambda$ satisfies the following inequality

$$
\begin{equation*}
\forall f>0, \quad \mathbb{E}_{\mu_{\lambda}}(f \log f)-\mathbb{E}_{\mu_{\lambda}}(f) \log \left(\mathbb{E}_{\mu_{\lambda}}(f)\right) \leq \lambda \mathbb{E}_{\mu_{\lambda}}(\nabla f \nabla \log f), \tag{30}
\end{equation*}
$$

where $\nabla f(n)$ is the discrete gradient $f(n+1)-f(n)$.
Lemma 4.1. Let $\mu_{\lambda}$ satisfy (30). Then for any 1-Lipschitz function $f: \mathbb{N} \rightarrow \mathbb{R}$

$$
\begin{equation*}
\mu_{\lambda}\left(f \geq \mathbb{E}_{\mu_{\lambda}}(f)+R\right) \leq \exp \left(-(R+2 \lambda)\left[\log \left(1+\frac{R}{2 \lambda}\right)+1\right]\right) \tag{31}
\end{equation*}
$$

In particular,

$$
\mu_{\lambda}\left(f \geq \mathbb{E}_{\mu_{\lambda}}(f)+R\right) \leq \exp (-R \log R+[\log (2 \lambda)+1] R+o(R))
$$

Remark 4.2. We are able to improve the concentration rate obtained in [7, Prop. 10] and [51, Cor 2.2] for the Poisson distribution. For instance, in [7] the following deviation bound for 1-Lipschitz functions is obtained under the Poisson distribution $\mu_{\lambda}$ of parameter $\lambda$ :

$$
\begin{equation*}
\mu_{\lambda}\left(f \geq \mathbb{E}_{\mu_{\lambda}}(f)+R\right) \leq \exp \left(-\frac{R}{4} \log \left(1+\frac{R}{2 \lambda}\right)\right) . \tag{32}
\end{equation*}
$$

Note that the right hand side can be rewritten as $-\frac{R}{4} \log (R)+\frac{\log (2 \lambda)}{4} R+o(R)$. We improve (32) to

$$
\begin{equation*}
\mu_{\lambda}\left(f \geq \mathbb{E}_{\mu_{\lambda}}(f)+R\right) \leq \exp \left(-(R+2 \lambda) \log \left(1+\frac{R}{2 \lambda}\right)+R\right) \tag{33}
\end{equation*}
$$

In this case, the rate has the form $\exp (-R \log R+(\log (\lambda)+1+\log (2)) R+o(R))$. This rate is sharp in the leading term $-R \log (R)$. Indeed, if one uses the explicit form of the Laplace transform of $\mu_{\lambda}$ one gets the following deviation bound for the identity function (see e.g. Example 7.3 in [46]):

$$
\begin{equation*}
\mu_{\lambda}\left(n \geq \mathbb{E}_{\mu_{\lambda}}(n)+R\right) \leq \exp \left(-R\left(\log \left(1+\frac{R}{\lambda}\right)-1\right)-\lambda \log \left(1+\frac{R}{\lambda}\right)\right) \tag{34}
\end{equation*}
$$

The rate here is of the form $-R \log R+(\log (\lambda)+1) R+o(R)$. This shows that (31) is sharp concerning the leading term and has the right dependence on $\lambda$ in the exponential correction term. Concerning the constants appearing in the exponential terms, we have $1+\log (2)$. We do not know whether this is sharp or not. However, nothing better than 1 is reasonable to expect because of (34).

Proof. Let $f$ be 1-Lipschitz. It is then standard to show that $f$ has exponential moments of all order. Therefore, all the expectations we are going to consider in the next lines are finite. Let us define

$$
\varphi_{\tau}:=\mathbb{E}_{\mu_{\lambda}}(\exp (\tau f)), \quad \psi_{\tau}:=\log \mathbb{E}_{\mu_{\lambda}}(\exp (\tau f))
$$

We apply the inequality (30) to $\exp (\tau f)$. Note that the left hand side reads as $\tau \partial_{\tau} \varphi_{\tau}-\varphi_{\tau} \psi_{\tau}$. The right hand side can be written as

$$
\lambda \tau \mathbb{E}_{\mu_{\lambda}}(\exp (\tau f)[\exp (\tau \nabla f)-1] \nabla f)
$$

Using that $f$ is 1-Lipschitz and the elementary fact that for all $\tau>0$

$$
\sup _{y \in[-1,1]}|y[\exp (\tau y)-1]|=\exp (\tau)-1
$$

we can bound the above expression by

$$
\lambda \tau[\exp (\tau)-1] \mathbb{E}_{\mu_{\lambda}}(\exp (\tau f))=\lambda \tau[\exp (\tau)-1] \varphi_{\tau}
$$

We thus get the following differential inequality

$$
\begin{equation*}
\tau \partial_{\tau} \varphi_{\tau}-\varphi_{\tau} \psi_{\tau} \leq \lambda \tau \varphi_{\tau}(\exp (\tau)-1) \tag{35}
\end{equation*}
$$

Dividing on both sides by $\varphi_{\tau}$ and using the chain rule, it can be rewritten as a differential inequality for $\psi$ :

$$
\begin{equation*}
\tau \partial_{\tau} \psi_{\tau}-\psi_{\tau} \leq \lambda \tau(\exp (\tau)-1), \quad \partial_{\tau} \psi_{0}=\mathbb{E}_{\mu_{\lambda}}(f), \psi_{0}=0 \tag{36}
\end{equation*}
$$

The ODE corresponding to this inequality is

$$
\begin{equation*}
\tau \partial_{\tau} h_{\tau}-h_{\tau}=\lambda \tau(\exp (\tau)-1), \quad \partial_{\tau} h_{0}=\mathbb{E}_{\mu_{\lambda}}(f), h_{0}=0 \tag{37}
\end{equation*}
$$

Note that the condition $h_{0}=0$ is implied by the form of the equation, and it is not an additional constraint. (37) admits a unique solution, given by:

$$
\begin{equation*}
h_{\tau}=\tau \mathbb{E}_{\mu_{\lambda}}(f)+\lambda \tau \gamma(\tau) \tag{38}
\end{equation*}
$$

where

$$
\begin{equation*}
\gamma(\tau)=\sum_{k=1}^{+\infty} \frac{1}{k} \frac{\tau^{k}}{k!} \tag{39}
\end{equation*}
$$

The fact that (38) is the solution to (37) can be checked directly by differentiating term by term the series defining $\gamma$ in (39). We claim that

$$
\begin{equation*}
\forall \tau \geq 0, \quad \psi_{\tau} \leq h_{\tau} \tag{40}
\end{equation*}
$$

The proof of this claim, is postponed to the Appendix section, see Propositon A.1. Given (40), a standard argument with Markov inequality yields

$$
\mu_{\lambda}\left(f \geq \mathbb{E}_{\mu_{\lambda}}(f)+R\right) \leq \exp \left(\inf _{\tau \geq 0} \psi_{\tau}-\tau \mathbb{E}_{\mu_{\lambda}}(f)-\tau R\right) \leq \exp \left(\inf _{\tau>0} \lambda \tau \gamma(\tau)-\tau R\right) .
$$

We can bound $\gamma$ in an elementary way:

$$
\gamma(\tau)=\sum_{k=1}^{+\infty} \frac{1}{k} \frac{\tau^{k}}{k!} \leq \frac{2}{\tau} \sum_{k=1}^{+\infty} \frac{\tau^{k+1}}{(k+1)!}=2 \frac{\exp (\tau)-\tau-1}{\tau}
$$

and therefore

$$
\mu_{\lambda}\left(f \geq \mathbb{E}_{\mu_{\lambda}}(f)+R\right) \leq \exp \left(\inf _{\tau>0} 2 \lambda \exp (\tau)-(2 \lambda+R) \tau-2 \lambda\right) .
$$

Solving the optimization problem yields the conclusion.
An interpolation. The idea behind the proof of Theorem 3.1 is to construct a measure $\pi_{\Phi}$ (see Definition 4.1) which "interpolates" $\rho_{\Phi}$ and for which the MLSI (30) gives sharp concentration bounds.

Definition 4.1. Let $\rho_{\Phi}$ be defined by (8). We define $\pi_{\Phi} \in \mathcal{P}(\mathbb{N})$ as follows:

$$
\begin{equation*}
\pi_{\Phi}(m)=\frac{1}{Z_{\Phi}} \rho_{\Phi}(n(m))^{1-\alpha(m)} \rho_{\Phi}(n(m)+1)^{\alpha(m)} \tag{41}
\end{equation*}
$$

where

$$
\begin{equation*}
n(m)=\lfloor m /(k+1)\rfloor, \quad \alpha(m)=m /(k+1)-n(m) . \tag{42}
\end{equation*}
$$

Another ingredient we shall use in the proof is the following criterion for MLSI, due to Caputo and Posta. What we make here is a summary of some of their results in Section 2 of the paper [11], adapted to our scopes. To keep track of the constants, we also use Lemma 1.2 of [36]. We do not reprove these results here.

Lemma 4.2 (Caputo and Posta criterion for MLSI [11]). Let $\pi \in \mathcal{P}(\mathbb{N})$ be such that

$$
\begin{equation*}
c(m):=\frac{\pi(m-1)}{\pi(m)} \tag{43}
\end{equation*}
$$

has the property that for some $v \in \mathbb{N}$

$$
\begin{equation*}
\inf _{m \geq 1} c(m+v)-c(m)>0 \tag{44}
\end{equation*}
$$

and that $\sup _{m \geq 0} c(m+v)-c(m)<+\infty$. Then the function $\tilde{c}$ defined by

$$
\begin{equation*}
\tilde{c}(m):=c(m)+\frac{1}{v} \sum_{i=0}^{v-1} \frac{v-i}{v}[c(m+i)+c(m-i)-2 c(m)] \tag{45}
\end{equation*}
$$

is uniformly increasing, that is

$$
\begin{equation*}
\inf _{m \geq 0} \tilde{c}(m+1)-\tilde{c}(m) \geq \delta \tag{46}
\end{equation*}
$$

for some $\delta>0$. Moreover, if we define $\tilde{\pi} \in \mathcal{P}(\mathbb{N})$ by

$$
\begin{equation*}
\tilde{\pi}(0)=\frac{1}{\tilde{Z}}, \quad \tilde{\pi}(m)=\frac{1}{\tilde{Z}} \prod_{i=1}^{m} \frac{1}{\tilde{c}(i)} \tag{47}
\end{equation*}
$$

then $\tilde{\pi}$ is equivalent to $\pi$ in the sense that there exist $\varepsilon>0$ such that:

$$
\begin{equation*}
\varepsilon \leq \frac{\pi(m)}{\tilde{\pi}(m)} \leq \varepsilon^{-1} \tag{48}
\end{equation*}
$$

Finally, $\pi$ satisfies the MLSI (30) with $\delta^{-1} \exp \left(4 \varepsilon^{-1}\right)$ instead of $\lambda$.
Using this criterion, we derive MLSI for $\pi_{\Phi}$.
Lemma 4.3. The measure $\pi_{\Phi}$ satisfies the MLSI (30) with a constant of the form $\Phi^{1 /(k+1)} c$, where $c$ is a constant independent from $\Phi$.

Proof. For $\Phi \in \mathbb{R}_{+}$we let $c_{\Phi}$ be defined by (43) by replacing $\pi$ with $\pi_{\Phi}$. We define $\tilde{c}_{\Phi}$ by (45) with the choice $v=k+1$. Moreover, we define $\delta_{\Phi}$ as in (46), $\tilde{\pi}_{\Phi}$ as in (47) and $\varepsilon_{\Phi}$ as in (48). Let us prove that:

$$
\begin{equation*}
\inf _{m \geq 1} c_{1}(m+k+1)-c_{1}(m)>0, \quad \sup _{m \geq 1} c_{1}(m+k+1)-c_{1}(m)<+\infty \tag{49}
\end{equation*}
$$

Equation (11) tells that:

$$
\begin{equation*}
\forall n \in \mathbb{N}, \quad \frac{\rho_{1}(n-1)}{\rho_{1}(n)}=n \times \prod_{i=0}^{k-1}(k n-i):=h(n) \tag{50}
\end{equation*}
$$

By definition of $n(m)$ and $\alpha(m)$ we have that for all $m \in \mathbb{N}, n(m+k+1)=n(m)+1$ and $\alpha(m+k+1)=\alpha(m)$. Therefore, by definition of $\pi_{1}$ :

$$
\begin{aligned}
c_{1}(m+k+1)-c_{1}(m)= & \frac{\pi_{1}(m+k)}{\pi_{1}(m+k+1)}-\frac{\pi_{1}(m-1)}{\pi_{1}(m)} \\
= & \frac{\rho_{1}(n(m-1)+1)^{1-\alpha(m-1)} \rho_{1}(n(m-1)+2)^{\alpha(m-1)}}{\rho_{1}(n(m)+1)^{1-\alpha(m)} \rho_{1}(n(m)+2)^{\alpha(m)}} \\
& -\frac{\rho_{1}(n(m-1))^{1-\alpha(m-1)} \rho_{1}(n(m-1)+1)^{\alpha(m-1)}}{\rho_{1}(n(m))^{1-\alpha(m)} \rho_{1}(n(m)+1)^{\alpha(m)}} .
\end{aligned}
$$

We have two cases:
$m \in(k+1) \mathbb{N}$. In this case $n(m-1)=n(m)-1$ and $\alpha(m)=0, \alpha(m-1)=k /(k+1)$. Therefore:

$$
\begin{aligned}
c_{1}(m+k+1)-c_{1}(m) & =\left[\frac{\rho_{1}(n(m))}{\rho_{1}(n(m)+1)}\right]^{1 / k+1}-\left[\frac{\rho_{1}(n(m)-1)}{\rho_{1}(n(m))}\right]^{1 / k+1} \\
& =h^{1 /(k+1)}(n(m)+1)-h^{1 /(k+1)}(n(m)),
\end{aligned}
$$

where the function $x \mapsto h(x)$ has been defined in (50).
$m \notin(k+1) \mathbb{N}$. In this case $n(m-1)=n(m)$ and $\alpha(m)=\alpha(m-1)+1 /(k+1)$. Therefore:

$$
\begin{aligned}
c_{1}(m+k+1)-c_{1}(m) & =\left[\frac{\rho_{1}(n(m)+1)}{\rho_{1}(n(m)+2)}\right]^{1 / k+1}-\left[\frac{\rho_{1}(n(m))}{\rho_{1}(n(m)+1)}\right]^{1 / k+1} \\
& =h^{1 /(k+1)}(n(m)+2)-h^{1 /(k+1)}(n(m)+1)
\end{aligned}
$$

It can be checked with a direct computation that $h$ is strictly increasing and $\lim _{x \rightarrow+\infty} \partial_{x} h^{1 / k+1}(x)=k^{k /(k+1)}$. Using this fact in the two expressions above yields (49). We are then entitled to apply Lemma 4.2, which tells that $\tilde{\pi}_{1}$ satisfies the MLSI (30) with a positive constant $\delta_{1}^{-1}$ and $\pi_{1}$ satisfies the MLSI with constant $\delta_{1}^{-1} \exp \left(4 \varepsilon_{1}^{-1}\right)$. Let now consider $\Phi \neq 1$. It is an elementary observation to show that $c_{\Phi}(m)=\Phi^{-1 /(k+1)} c_{1}(m)$. This means that (see Definition 4.1)

$$
\pi_{\Phi}(m)=\left[\sum_{m=0}^{+\infty} \Phi^{-m /(k+1)} \pi_{1}(m)\right]^{-1} \Phi^{-m /(k+1)} \pi_{1}(m)
$$

Moreover, by construction (see (45)) we also have that $\tilde{c}_{\Phi}=\Phi^{-1 /(k+1)} c_{1}$. This implies that $\delta_{\Phi}=\Phi^{1 /(k+1)} \delta_{1}$ and that

$$
\tilde{\pi}_{\Phi}(m)=\left[\sum_{m=0}^{+\infty} \Phi^{-m /(k+1)} \tilde{\pi}_{1}(m)\right]^{-1} \Phi^{-m /(k+1)} \tilde{\pi}_{1}(m) .
$$

It is then easy to see that, using the two expressions for $\pi_{\Phi}$ and $\tilde{\pi}_{\Phi}$ we have just derived, that $\varepsilon_{\Phi} \geq \varepsilon_{1}^{2}$. Another application of Lemma 4.2 gives that $\pi_{\Phi}$ satisfies the MLSI with constant $\Phi^{-1 /(k+1)} \delta_{1}^{-1} \exp \left(4 \varepsilon_{1}^{-2}\right)$.

We can finally prove Theorem 3.1.
Proof. Consider $f: \mathbb{N} \rightarrow \mathbb{R}$, which is 1-Lipschitz. Then define $g: \mathbb{N} \rightarrow \mathbb{R}$ by:

$$
\begin{equation*}
g(m):=(1-\alpha(m)) f(n(m))+\alpha(m) f(n(m)+1), \tag{51}
\end{equation*}
$$

where $n(m), \alpha(m)$ have been defined at (42). It is immediate to verify that $g$ is $1 /(k+1)$-Lipschitz. Because of Lemma 4.3 there exists $c$ independent from $\Phi$ such that $\pi_{\Phi}$ satisfies MLSI (30) with constant $c \Phi^{1 /(k+1)}$. We define $M:=\Phi+\frac{\Phi^{1 / k+1}}{k+1}$ Using the concentration bound from Lemma 4.1 on $(k+1) g$ we get that, for any $R>M$

$$
\begin{aligned}
& \pi_{\Phi}\left(\left\{m: g(m) \geq \mathbb{E}_{\pi_{\Phi}}(g)-M+R\right\}\right) \\
& \quad \leq \exp (-(k+1)(R-M) \log (R-M)+[c+\log \Phi](R-M)+o(R)) \\
& \quad=\exp (-(k+1) R \log (R)+[c+\log \Phi] R+o(R)),
\end{aligned}
$$

where to obtain the last inequality we used the fact that the difference $(R-M) \log (R-M)-R \log (R)$ is a function in the class $o(R)$. It is proven in Lemma A. 2 (see Appendix) that $\mathbb{E}_{\pi_{\Phi}}(g)-M \leq \mathbb{E}_{\pi}(f)$. This implies that $\pi_{\Phi}(\{m$ : $\left.\left.g(m) \geq \mathbb{E}_{\pi_{\Phi}}(g)-M+R\right\}\right) \geq \pi_{\Phi}\left(\left\{m: g(m) \geq \mathbb{E}_{\rho_{\Phi}}(f)+R\right\}\right)$. Finally, we observe that

$$
\begin{aligned}
& \pi_{\Phi}\left(\left\{m: g(m) \geq \mathbb{E}_{\rho_{\Phi}}(f)+R\right\}\right) \\
& \quad \geq \pi_{\Phi}\left(\left\{m: g(m) \geq \mathbb{E}_{\rho_{\Phi}}(f)+R, m \in(k+1) \mathbb{N}\right\}\right) \\
& \quad=\frac{1}{Z_{\Phi}} \rho_{\Phi}\left(\left\{n: f(n) \geq \mathbb{E}_{\rho_{\Phi}}(f)+R\right\}\right) \\
& \quad \geq \frac{1}{k+1} \rho_{\Phi}\left(\left\{n: f(n) \geq \mathbb{E}_{\rho_{\Phi}}(f)+R\right\}\right),
\end{aligned}
$$

where we used the arithmetic geometric mean inequality to show that

$$
Z_{\Phi}=\sum_{m=0}^{+\infty} \rho_{\Phi}(n(m))^{1-\alpha(m)} \rho_{\Phi}(n(m)+1)^{\alpha(m)} \leq k+1
$$

Summing up we have

$$
\begin{aligned}
\rho_{\Phi}\left(\left\{n: f(n) \geq \mathbb{E}_{\rho_{\Phi}}(f)+R\right\}\right) & \leq(k+1) \pi_{\Phi}\left(\left\{m: g(m) \geq \mathbb{E}_{\rho_{\Phi}}(f)+R\right\}\right) \\
& \leq(k+1) \exp (-(k+1) R \log (R)+[c+\log \Phi] R+o(R))
\end{aligned}
$$

The proof of the Theorem is now concluded.

### 4.1. Proof of Theorems 3.2 and 3.3

## Preliminaries

Let us specify the assumptions on the jump intensity.
Assumption 4.1. The jump intensity $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$verifies the following requirements:
(1) It has constant speed: there exists $v>0$ such that

$$
\begin{equation*}
\forall z \in \mathcal{X}, \quad v=\sum_{z^{\prime}: z \rightarrow z^{\prime}} j\left(z \rightarrow z^{\prime}\right):=\bar{j}(z) \tag{52}
\end{equation*}
$$

(2) It is everywhere positive: $j\left(z \rightarrow z^{\prime}\right)>0$ for all $z \rightarrow z^{\prime} \in \mathcal{A}$.

Here is some vocabulary about graphs.
Definition 4.2. Let $\mathcal{A} \subset \mathcal{X}^{2}$ specify a directed graph $(\mathcal{X}, \rightarrow)$ on $\mathcal{X}$ satisfying Assumption 4.2.
(a) The distance $d\left(z, z^{\prime}\right)$ between two vertices $z$ and $z^{\prime}$ is the length of the shortest walk joining $z$ with $z^{\prime}$. Due to point (1) of Assumption 4.2, $d$ is symmetric.
(b) If $\mathbf{w}=\left(x_{0} \rightarrow x_{1} \rightarrow \cdots \rightarrow x_{n}\right)$ is a walk, then $\mathbf{w}^{*}$ is the walk obtained by reverting the orientation of all arcs:

$$
\begin{equation*}
\mathbf{w}^{*}:=\left(x_{n} \rightarrow x_{n-1} \rightarrow \cdots \rightarrow x_{0}\right) \tag{53}
\end{equation*}
$$

(c) A closed walk $\mathbf{c}=\left(x_{0} \rightarrow x_{1} \rightarrow \cdots \rightarrow x_{n}=x_{0}\right)$ is said to be simple if the cardinality of the visited vertices $\left\{x_{0}, x_{1}, \ldots, x_{n-1}\right\}$ is equal to the length $n$ of the walk. This means that a simple closed walk cannot be decomposed into several closed walks. A non-closed walk $\mathbf{w}=\left(x_{0} \rightarrow x_{1} \rightarrow x_{2} \rightarrow \cdots \rightarrow x_{n} \neq x_{0}\right)$ is said to be simple if the cardinality of the visited vertices $\left\{x_{0}, x_{1}, \ldots, x_{n}\right\}$ is equal to the length $n+1$.

## Proof of Theorem 3.2

The proof of Theorem 3.2 is based on the following Lemma, which ensures that we can control $\Phi_{j}(\mathbf{c})$ in terms of $\lambda^{\ell(\mathbf{c})}$. To ease the notation, we write $\Phi(\cdot)$ instead of $\Phi_{j}(\cdot)$. The idea of the proof of the lemma is the following: given a closed walk $\mathbf{w}$, we can always "filp inwards" one of its corners to obtain another closed walk $\mathbf{w}^{\prime}$, which lies in the interior of $\mathbf{w}$, and is such that $\Phi_{j}(\mathbf{w}) \leq \Phi_{j}\left(\mathbf{w}^{\prime}\right)$, see Figures 4 and 5 below.

Lemma 4.4. Let $j$ be as in the hypothesis of Theorem 3.2. Then for any closed walk $\mathbf{c}, \Phi_{j}(\mathbf{c}) \leq \lambda^{\ell(\mathbf{c})}$.

Proof. We observe that it is sufficient to consider the case when $\mathbf{c}$ is simple. Simple closed walks have an orientation, which is unique, and it can be either clockwise or counterclockwise. The interior of a closed walk is then also well defined and we call area the number of squares in the interior of $\mathbf{c}$. The proof is by induction on the area of the closed walk.


Fig. 3. A simple closed walk $\mathbf{c}$ (red). $x_{1}$ is the minimum in the lexicographic order among the vertices visited by the closed walk. Because of that the walk cannot pass neither through the vertex left to $x_{1}$, nor through the vertex below $x_{1}$ (yellow). Therefore $\mathbf{c}$ must pass through the vertices above $x_{1}$ and right of $x_{1}$. If $x_{2}$ is the vertex above $x_{1}$ the walk is clockwise oriented.


Fig. 4. $\tilde{\mathbf{c}}$ is constructed by cutting $\left(x_{0} \rightarrow x_{1} \rightarrow x_{2}\right)$ from $\mathbf{c}$ and replacing it with $\mathbf{p}=\left(x_{0} \rightarrow z \rightarrow x_{2}\right)$ (blue). $\tilde{\mathbf{c}}$ has the same perimeter but smaller area than $\mathbf{c}$.

Base step. If the area of $\mathbf{c}$ is zero and $\mathbf{c}$ is simple, then $\mathbf{c}$ is a walk of length two, i.e. $\mathbf{c} \in \mathcal{E}$. The conclusion then follows by (15).
Inductive step. Consider the minimum in the lexicographic order of the vertices of $\mathbf{c}$. w.l.o.g. such vertex can be chosen to be $x_{1}$. By construction then, either $\left(x_{0}, x_{2}\right)=\left(x_{1}+\mathbf{e}_{1}, x_{1}+\mathbf{e}_{2}\right)$ or $\left(x_{0}, x_{2}\right)=\left(x_{1}+\mathbf{e}_{2}, x_{1}+\mathbf{e}_{1}\right)$, see Figure 3.
(a) $\left(x_{0}, x_{2}\right)=\left(x_{1}+\mathbf{e}_{1}, x_{1}+\mathbf{e}_{2}\right)$. We define $z, \mathbf{c}_{x_{2} \rightarrow x_{0}}$ and $\mathbf{p}$ by

$$
\begin{equation*}
z:=x_{2}+v_{1}=x_{0}+v_{2}, \quad \mathbf{c}:=\left(x_{0} \rightarrow x_{1} \rightarrow x_{2} \rightarrow \mathbf{c}_{x_{2} \rightarrow x_{0}}\right), \quad \mathbf{p}:=\left(x_{0} \rightarrow z \rightarrow x_{2}\right) . \tag{54}
\end{equation*}
$$

We also define $\tilde{\mathbf{c}}$ by concatenating $\mathbf{p}$ and $\mathbf{c}_{x_{2} \rightarrow x_{0}}$ (see Figure 4):

$$
\tilde{\mathbf{c}}:=\left(\mathbf{p} \rightarrow \mathbf{c}_{x_{2} \rightarrow x_{0}}\right) .
$$



Fig. 5. An illustration of case (a.2) in the proof of Lemma 4.4. The purple contour is $\mathbf{c}$, the green path is $\mathbf{p}$. The blue and red areas represent the interior of $\tilde{\mathbf{c}}_{1}$ and $\tilde{\mathbf{c}}_{2}$ respectively.

We then have, recalling that $\mathbf{p}^{*}$ is obtained by reversing $\mathbf{p}$ (see Definition 3.2):

$$
\begin{aligned}
\Phi(\mathbf{c}) & =j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right) \Phi\left(\mathbf{c}_{x_{2} \rightarrow x_{0}}\right) \\
& =\frac{j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right)}{\Phi(\mathbf{p})} \Phi(\mathbf{p}) \Phi\left(\mathbf{c}_{x_{2} \rightarrow x_{0}}\right) \\
& =\frac{j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right)}{\Phi(\mathbf{p})} \Phi(\tilde{\mathbf{c}}) \\
& =\frac{j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right) \Phi\left(\mathbf{p}^{*}\right)}{\Phi\left(\mathbf{p}^{*}\right) \Phi(\mathbf{p})} \Phi(\tilde{c}) \\
& =\frac{\Phi\left(\mathbf{f}_{x_{1}}\right)}{\Phi\left(\mathbf{e}_{x+v_{2}, 1}\right) \Phi\left(\mathbf{e}_{x+v_{1}, 2}\right)} \Phi(\tilde{\mathbf{c}}) .
\end{aligned}
$$

By (15), $\frac{\Phi\left(\mathbf{f}_{x_{1}}\right)}{\Phi\left(\mathbf{e}_{x_{1}+v_{2}, 1}\right) \Phi\left(\mathbf{e}_{\left.x_{1}+v_{1}, 2\right)}\right.} \leq 1$. Since $\ell(\tilde{\mathbf{c}})=\ell(\mathbf{c})$, we would be done if we could show that $\Phi(\tilde{\mathbf{c}}) \leq \lambda^{\ell(\mathbf{c})}$. We have two cases:
(a.1) z was not touched by c. In this situation, $\tilde{\mathbf{c}}$ is a simple closed walk. By construction, $\tilde{\mathbf{c}}$ lies in the interior of $\mathbf{c}$. Moreover, $\mathbf{f}_{x_{1}}$ belongs to the interior of $\mathbf{c}$ but does not belong to the interior of $\tilde{\mathbf{c}}$. Therefore, we can use the inductive hypothesis and obtain that $\Phi(\tilde{\mathbf{c}}) \leq \lambda^{\ell(\tilde{\mathbf{c}})}$, which is the desired result.
(a.2) $z$ was touched by $\mathbf{c}$. In this case $z=x_{j}$ for some $j \geq 3$. We observe that we can write $\tilde{\mathbf{c}}=\left(\tilde{\mathbf{c}}_{1} \rightarrow \tilde{\mathbf{c}}_{2}\right)$ with $\tilde{\mathbf{c}}_{1}=\left(x_{2} \rightarrow \cdots \rightarrow x_{j}=z \rightarrow x_{2}\right)$ and $\tilde{\mathbf{c}}_{2}=\left(x_{j}=z \rightarrow x_{j+1} \rightarrow \cdots \rightarrow x_{0} \rightarrow z\right)$ and that both $\tilde{\mathbf{c}}_{1}$ and $\tilde{\mathbf{c}}_{2}$ are simple closed walks which lie in the interior of $\mathbf{c}$ and have disjoint interiors, see Figure 5. Moreover, since none of the walks has $\mathbf{f}_{x_{1}}$ in its interior, by inductive hypothesis $\Phi\left(\tilde{\mathbf{c}}_{1}\right) \leq$ $\lambda^{\ell\left(\tilde{\mathbf{c}}_{1}\right)}$ and $\Phi\left(\tilde{\mathbf{c}}_{2}\right) \leq \lambda^{\ell\left(\tilde{\mathbf{c}}_{2}\right)}$. But then $\Phi(\tilde{\mathbf{c}})=\Phi\left(\tilde{\mathbf{c}}_{1}\right) \Phi\left(\tilde{\mathbf{c}}_{2}\right) \leq \lambda^{\ell\left(\tilde{c}_{1}\right)+\ell\left(\tilde{c}_{2}\right)}=\lambda^{\ell(\tilde{c})}$, which is the desired result.
(b) $\left(x_{0}, x_{2}\right)=\left(x_{1}+\mathbf{e}_{2}, x_{1}+\mathbf{e}_{1}\right)$. In this case the simple walk $\mathbf{c}$ is counterclockwise oriented. Let $\mathbf{c}_{x_{2} \rightarrow x_{0}}$ be defined as in (54) above. Moreover we define
$z:=x_{0}+v_{1}=x_{2}+v_{2}, \quad \mathbf{p}:=\left(x_{0} \rightarrow z \rightarrow x_{2}\right)$
and $\tilde{\mathbf{c}}:=\left(\mathbf{p} \rightarrow \tilde{\mathbf{c}}_{x_{2} \rightarrow x_{0}}\right)$. We have:

$$
\begin{aligned}
\Phi(\mathbf{c}) & =j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right) \Phi\left(\mathbf{c}_{x_{2} \rightarrow x_{0}}\right) \\
& =\frac{j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right)}{\Phi(\mathbf{p})} \Phi(\mathbf{p}) \Phi\left(\mathbf{c}_{x_{2} \rightarrow x_{0}}\right) \\
& =\frac{j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right)}{\Phi(\mathbf{p})} \Phi(\tilde{\mathbf{c}}) \\
& =\frac{j\left(x_{0} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{2}\right) j\left(x_{2} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{0}\right)}{j\left(x_{0} \rightarrow z\right) j\left(z \rightarrow x_{2}\right) j\left(x_{2} \rightarrow x_{1}\right) j\left(x_{1} \rightarrow x_{0}\right)} \Phi(\tilde{\mathbf{c}}) \\
& =\frac{\Phi\left(\mathbf{e}_{x_{1}, 2}\right) \Phi\left(\mathbf{e}_{x_{1}, 1}\right)}{\Phi\left(\mathbf{f}_{x_{1}}\right)} \Phi(\tilde{\mathbf{c}}) .
\end{aligned}
$$

Thanks to (16), $\frac{\Phi\left(\mathbf{e}_{x_{1}, 2}\right) \Phi\left(\mathbf{e}_{x_{1}, 1}\right)}{\Phi\left(\mathbf{f}_{x_{1}}\right)} \leq 1$. The proof that $\Phi(\tilde{\mathbf{c}}) \leq \lambda^{\ell(\mathbf{c})}$ is the same as in point (a).
We can now prove Theorem 3.2. Let us first state a simple Lemma we shall need, without proving it.
Lemma 4.5. Let $\mathbb{P}, \mathbb{Q}$ be two probability measures on the same probability space and let $\mathbb{Q} \ll \mathbb{P}$, and $M=\frac{d \mathbb{Q}}{d \mathbb{P}}$. If $A$ is an event such that $\mathbb{Q}(A)>0$ then

$$
\frac{d \mathbb{Q}[\cdot \mid A]}{d \mathbb{P}[\cdot \mid A]}=M \mathbf{1}_{A} \frac{\mathbb{P}(A)}{\mathbb{Q}(A)} .
$$

Thanks to the last two Lemmas, the proof is then an almost straightforward application of Girsanov's theorem.
Proof. Let $\mathbb{P}^{x}$ be a random walk of intensity $j$. We denote $\mathbb{S}_{\lambda}^{x}$ the random walk with constant intensity $\lambda$ started at $x$. The density of $\mathbb{P}^{x}$ w.r.t. $\mathbb{S}_{\lambda}^{x}$ is given by (see [31] or [18] for a more ad-hoc version) is

$$
\frac{d \mathbb{P}^{x}}{d \mathbb{S}_{\lambda}^{x}}=\exp \left(\sum_{i=1}^{N_{1}} \log j\left(X_{T_{i-1}} \rightarrow X_{T_{i}}\right)-\log (\lambda)-\int_{0}^{1} \bar{j}\left(t, X_{t^{-}}\right)+4 \lambda d t\right),
$$

where $N_{1}$ is the total number of jumps up to time 1 and $T_{i}$ is the $i$ th jump time. Since $\mathbb{P}^{x}$ is a CSRW, the term $\int_{0}^{1} \bar{j}\left(t, X_{t^{-}}\right) d t$ is constant. Moreover, if we call $\mathbf{w}(X)$ the random sequence $\left(X_{0} \rightarrow X_{T_{1}} \rightarrow \cdots \rightarrow X_{T_{N_{1}}}\right.$ ) and use Lemma 4.5 we obtain

$$
\frac{d \mathbb{P}^{x x}}{d \mathbb{S}_{\lambda}^{x x}} \propto \mathbf{1}_{\left\{X_{0}=X_{1}=x\right\}} \Phi_{j}(\mathbf{w}(X)) \lambda^{-\ell(\mathbf{w}(X))}
$$

But then, since on the event $\left\{X_{0}=X_{1}=x\right\}, \mathbf{w}(X)$ is a closed walk, we can apply Lemma 4.4 to conclude that the density has a global upper bound on path space. The conclusion immediately follows from Lemma A.4, which we prove in the Appendix.

## Proof of Theorem 3.3

Let us first specify the assumptions we make on the graph.
Assumption 4.2. The directed graph $(\mathcal{X}, \rightarrow)$ satisfies the following requirements:
(1) $\mathcal{A}$ is symmetric: $(x \rightarrow y) \in \mathcal{A} \Rightarrow(y \rightarrow x) \in \mathcal{A}$.
(2) It is connected: for any $x, y \in \mathcal{X}^{2}$ there exist a directed walk from $x$ to $y$.
(3) It is of bounded degree.
(4) It has no loops, meaning that $(z \rightarrow z) \notin \mathcal{A}$ for all $z \in \mathcal{X}$.

Let us prove the correspondent of Lemma 4.4. In this case the key ey step of the proof is to show that any given closed walk $\mathbf{w}$ can be suitably transformed to another closed walk $\mathbf{w}^{\prime}$ by using only the elements of $\mathcal{C}$ in such a way that $\Phi_{j}(\mathbf{w}) \leq \lambda \delta \Phi_{j}(\mathbf{w})$.

Lemma 4.6. Let $j$ satisfy the assumptions of Theorem 3.3. Then we have:

$$
\forall \mathbf{c} \in \mathcal{C}, \quad \Phi_{j}(\mathbf{c}) \leq(\lambda \delta)^{\ell(\mathbf{c})} .
$$

Proof. Again, to ease the notation, we write $\Phi$ instead of $\Phi_{j}$. The proof goes by induction on the number of elements in $\mathcal{E}^{*}$ that intersect $\mathbf{c}$. To this aim we define

$$
n(\mathbf{c})=\left|\left\{\mathbf{e} \in \mathcal{E}^{*}: \mathbf{e} \cap \mathbf{c} \neq \varnothing\right\}\right| .
$$

Base step. If $n(\mathbf{c})=0$, then $\mathbf{c} \subseteq \mathcal{T}$. It is easy to see that $\mathbf{c}$ can be decomposed into closed walks of length two. The conclusion then follows from (18).
Inductive step. Consider any $\mathbf{e} \in \mathcal{E}^{*}$ such that $\mathbf{e} \cap \mathbf{c} \neq \varnothing$. Then there are two possible cases:
$|\mathbf{e} \cap \mathbf{c}|=2$. In this case $\mathbf{c}$ can be seen as the concatenation of $\mathbf{e}$ with two other closed walks, say $\mathbf{c}_{1}, \mathbf{c}_{2}$. Clearly, $n\left(\mathbf{c}_{1}\right), n\left(\mathbf{c}_{2}\right)<n(\mathbf{c})$, and therefore applying the inductive hypothesis and (18) we have:

$$
\Phi(\mathbf{c})=\Phi\left(\mathbf{c}_{1}\right) \Phi(\mathbf{e}) \Phi\left(\mathbf{c}_{2}\right) \leq(\delta \lambda)^{\ell\left(\mathbf{c}_{1}\right)+2+\ell\left(\mathbf{c}_{2}\right)}=(\lambda \delta)^{\ell(\mathbf{c})} .
$$

$|\mathbf{e} \cap \mathbf{c}|=1$. In this case, let us call $z \rightarrow z^{\prime}$ the only arc in $\mathbf{e} \cap \mathbf{c}$. By recalling the definition of $\mathbf{c}_{\mathbf{e}}$ at point (e) of Definition 3.2, we have two subcases:
$\mathbf{c}_{\mathbf{e}}=\mathbf{c}_{z \rightarrow z^{\prime}}$. We define $\mathbf{c}_{x_{0} \rightarrow z}, \mathbf{c}_{z^{\prime} \rightarrow x_{0}}$ and $\mathbf{w}_{z^{\prime} \rightarrow z}$ through the following identities
$\mathbf{c}=\left(\mathbf{c}_{x_{0} \rightarrow z} \rightarrow z \rightarrow z^{\prime} \rightarrow \mathbf{c}_{z^{\prime} \rightarrow x_{0}}\right), \quad \mathbf{c}_{\mathbf{e}}=\left(z \rightarrow z^{\prime} \rightarrow \mathbf{w}_{z^{\prime} \rightarrow z}\right)$.
Finally, we also define $\tilde{\mathbf{c}}$ as follows
$\tilde{\mathbf{c}}=\left(\mathbf{c}_{x_{0}, z} \rightarrow \mathbf{w}_{z^{\prime} \rightarrow z}^{*} \rightarrow \mathbf{c}_{z, x_{0}}\right)$,
where $\mathbf{w}_{z^{\prime} \rightarrow z}^{*}$ is the reversed walk (see Definition 4.2). Let us remark that, by definition of $\mathbf{c}_{z \rightarrow z^{\prime}}$, we have $\mathbf{w}_{z^{\prime} \rightarrow z} \subseteq \mathcal{T}$. But then also $\mathbf{w}_{z^{\prime} \rightarrow z}^{*} \subseteq \mathcal{T}$ because $\mathcal{T}$ is a symmetric graph. Therefore $n(\tilde{\mathbf{c}})=n(\mathbf{c})-1$. We have

$$
\begin{aligned}
\Phi(\mathbf{c}) & =\Phi\left(\mathbf{c}_{x_{0} \rightarrow z}\right) j\left(z \rightarrow z^{\prime}\right) \Phi\left(\mathbf{c}_{z^{\prime} \rightarrow x_{0}}\right) \\
& =\Phi\left(\mathbf{c}_{x_{0} \rightarrow z}\right) \Phi\left(\mathbf{w}_{z^{\prime} \rightarrow z}^{*}\right) \Phi\left(\mathbf{c}_{z^{\prime} \rightarrow x_{0}}\right) \frac{j\left(z \rightarrow z^{\prime}\right)}{\Phi\left(\mathbf{w}_{z^{\prime} \rightarrow z}^{*}\right)} \\
& =\Phi\left(\tilde{\mathbf{c}} \mathbf{)} \frac{j\left(z \rightarrow z^{\prime}\right)}{\Phi\left(\mathbf{w}_{z^{\prime} \rightarrow z}^{*}\right)} .\right.
\end{aligned}
$$

Using the inductive hypothesis on $\Phi(\widetilde{\mathbf{c}})$ we have that $\Phi(\tilde{\mathbf{c}}) \leq(\lambda \delta)^{\ell(\tilde{\mathbf{c}})}=(\lambda \delta)^{\ell(\mathbf{c})+\ell\left(\mathbf{c}_{\mathbf{e}}\right)-1}$. If we could show that $\frac{j\left(t, z \rightarrow z^{\prime}\right)}{\Phi\left(\mathbf{w}_{z \rightarrow z^{\prime}}^{*}\right)} \leq(\lambda \delta)^{1-\ell\left(\mathbf{c}_{e}\right)}$, then we would be done. For this aim, let us observe that by concatenating $\mathbf{w}_{z^{\prime} \rightarrow z}^{*}$ with $z^{\prime} \rightarrow z$ we obtain $\mathbf{c}_{z^{\prime} \rightarrow z}$. Then:

$$
\begin{equation*}
\frac{j\left(z \rightarrow z^{\prime}\right)}{\Phi\left(\mathbf{w}_{z^{\prime} \rightarrow z}^{*}\right)}=\frac{j\left(z \rightarrow z^{\prime}\right) j\left(z^{\prime} \rightarrow z\right)}{\Phi\left(\mathbf{w}_{z^{\prime} \rightarrow z}^{*}\right) j\left(z^{\prime} \rightarrow z\right)}=\frac{\Phi(\mathbf{e})}{\Phi\left(\mathbf{c}_{z^{\prime} \rightarrow z}\right)} . \tag{56}
\end{equation*}
$$

Finally, we observe that

$$
\Phi\left(\mathbf{c}_{z^{\prime} \rightarrow z}\right)=\frac{1}{\Phi\left(\mathbf{c}_{z \rightarrow z^{\prime}}\right)} \prod_{\substack{\mathbf{e}^{\prime} \in \mathcal{Z}, \mathbf{e}^{\prime} \cap \mathbf{c}_{\mathbf{e}} \neq \varnothing}} \Phi\left(\mathbf{e}^{\prime}\right)=\frac{1}{\Phi\left(\mathbf{c}_{\mathbf{e}}\right)} \prod_{\substack{\mathbf{e}^{\prime} \in \mathcal{E}, \mathbf{e}^{\prime} \cap \mathbf{c}_{\mathbf{e}} \neq \varnothing}} \Phi\left(\mathbf{e}^{\prime}\right),
$$

which combined with (56) gives:
$\frac{j\left(z \rightarrow z^{\prime}\right)}{\Phi\left(\mathbf{w}_{z^{\prime} \rightarrow z}^{*}\right)}=\Phi\left(\mathbf{c}_{\mathbf{e})}\left\{\prod_{\substack{\mathbf{e}^{\prime} \in \mathcal{E}, \mathbf{e}^{\prime} \neq \mathbf{e} \\ \mathbf{e}^{\prime} \cap \mathbf{e}_{\mathbf{e}} \neq \varnothing}} \Phi\left(\mathbf{e}^{\prime}\right)\right\}^{-1}\right.$,
where we used the fact that, by construction, $\mathbf{e}$ is the only element of $\mathcal{E}$ which intersects $\mathbf{c}_{\mathbf{e}}$ and is not in $\mathcal{T}$.
Using the upper bound for $\mathbf{c}_{\mathrm{e}}$ in (19) the conclusion follows.
$\mathbf{c}_{\mathbf{e}}=\mathbf{c}_{z^{\prime} \rightarrow z}$. Let $\mathbf{c}_{x_{0} \rightarrow z}, \mathbf{c}_{z^{\prime} \rightarrow x_{0}}$ be defined as in (55), $\mathbf{w}_{z \rightarrow z^{\prime}}$ and $\tilde{\mathbf{c}}$ be defined by

$$
\mathbf{c}_{\mathbf{e}}=\left(z^{\prime} \rightarrow z \rightarrow \mathbf{w}_{z \rightarrow z^{\prime}}\right), \quad \tilde{\mathbf{c}}=\left(\mathbf{c}_{x_{0} \rightarrow z} \rightarrow \mathbf{w}_{z \rightarrow z^{\prime}} \rightarrow \mathbf{c}_{z^{\prime} \rightarrow x_{0}}\right) .
$$

We have

$$
\begin{aligned}
\Phi(\mathbf{c}) & =\Phi\left(\mathbf{c}_{x_{0} \rightarrow z}\right) j\left(z \rightarrow z^{\prime}\right) \Phi\left(\mathbf{c}_{z^{\prime} \rightarrow x_{0}}\right) \\
& =\Phi\left(\mathbf{c}_{x_{0} \rightarrow z}\right) \Phi\left(\mathbf{w}_{z \rightarrow z^{\prime}}\right) \Phi\left(\mathbf{c}_{z^{\prime} \rightarrow x_{0}}\right) \frac{j\left(z \rightarrow z^{\prime}\right)}{\Phi\left(\mathbf{w}_{z \rightarrow z^{\prime}}\right)} \\
& =\Phi(\tilde{\mathbf{c}}) \frac{j\left(z \rightarrow z^{\prime}\right)}{\Phi\left(\mathbf{w}_{z \rightarrow z^{\prime}}\right)} \\
& =\Phi(\tilde{\mathbf{c}}) \frac{j\left(z \rightarrow z^{\prime}\right) j\left(z^{\prime} \rightarrow z\right)}{\Phi\left(\mathbf{w}_{z \rightarrow z^{\prime}}\right) j\left(z^{\prime} \rightarrow z\right)} \\
& =\Phi(\tilde{\mathbf{c}}) \frac{\Phi(\mathbf{e})}{\Phi\left(\mathbf{c}_{\mathbf{e}}\right)}
\end{aligned}
$$

By construction, $n(\tilde{\mathbf{c}})=n(\mathbf{c})-1$, so we can use the inductive hypothesis together with the lower bound in (19) to obtain

$$
\Phi(\tilde{\mathbf{c}}) \frac{\Phi(\mathbf{e})}{\Phi\left(\mathbf{c}_{\mathbf{e}}\right)} \leq(\lambda \delta)^{\ell(\mathbf{c})+\ell\left(\mathbf{c}_{\mathbf{e}}\right)-1}(\lambda \delta)^{1-\ell\left(\mathbf{c}_{\mathbf{e}}\right)}=(\lambda \delta)^{\ell(\mathbf{c})},
$$

from which the conclusion follows.
The proof of Theorem 3.3 can be deduced from that of Theorem 3.2 by replacing $\mathbb{S}_{\lambda}^{x}$ with the random walk defined at (21), Lemma A. 4 with Lemma A. 3 (which we prove in the Appendix) and Lemma 4.4 with Lemma 4.6. Therefore, we shall not repeat it.

On the feasibility of (15), (16) and (18), (19)
In this section we address the problem of how to construct jump intensities satisfying (15), (16) (resp. (18), (19)). Lemma 4.7 (resp. 4.8) shows that for any arbitrary assignment of positive numbers $\varphi$ on $\mathcal{E} \cup \mathcal{F}$ (resp. $\mathcal{C}$ ) there exists at least an intensity $j$ satisfying Assumption 4.1 and such that $\Phi_{j} \equiv \varphi$ on $\mathcal{E} \cup \mathcal{F}$ (resp. $\mathcal{C}$ ). It is then possible to construct the desired jump intensities in two steps. W.l.o.g. we restrict to the square lattice, the procedure being identical in the case of a general graph.

Step 1. Construct a positive function $\varphi$ on $\mathcal{E} \cup \mathcal{F}$ such that (15), (16) hold when replacing $\Phi_{j}$ with $\varphi$. It is rather easy to see that this is possible.

Step 2. Construct $j$ such that $\Phi_{j}=\varphi$ on $\mathcal{E} \cup \mathcal{F}$. The existence of such $j$ (and a way of constructing it) is proven in Lemma 4.7.

## Square lattice

Although we are interested in the lattice case, Lemma 4.7 is easier to prove for a general planar graph. Planar graphs have a privileged set of closed walks: the faces, which are uniquely determined once a planar representation is fixed. We choose the representation in such a way that both arcs corresponding to an element of $\mathcal{E}$ lie on the same segment in the planar representation. ${ }^{5}$ As in the case of the square lattice, the set of clockwise oriented faces of a planar graph is denoted $\mathcal{F}$.

Lemma 4.7. Let $(\mathcal{X}, \rightarrow)$ be a planar directed graph satisfying Assumption 4.2. Let $\varphi: \mathcal{F} \cup \mathcal{E} \rightarrow \mathbb{R}_{+}$be bounded from above. Then there exists at least one $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$fulfilling Assumption 4.1 and such that

$$
\begin{equation*}
\forall \mathbf{f} \in \mathcal{F}, \quad \Phi_{j}(\mathbf{f})=\varphi(\mathbf{f}), \quad \forall \mathbf{e} \in \mathcal{E}, \quad \Phi_{j}(\mathbf{e})=\varphi(\mathbf{e}) . \tag{57}
\end{equation*}
$$

If $\mathcal{X}$ is a finite set, then $j$ is unique. If $\mathcal{X}$ is infinite, then all intensities $k: \mathcal{A} \rightarrow \mathbb{R}_{+}$with such properties can be written in the form

$$
k\left(z \rightarrow z^{\prime}\right)=\exp \left(\phi\left(z^{\prime}\right)-\phi(z)\right) j\left(z \rightarrow z^{\prime}\right)
$$

where $h=\exp (\phi)$ is a positive solution to:

$$
\forall z \in \mathcal{X}, \quad \sum_{z^{\prime}: z \rightarrow z^{\prime}} j\left(z \rightarrow z^{\prime}\right) h\left(z^{\prime}\right)=v h(z),
$$

for some constant $v>0$.
Proof. In a first step we show the existence of a function $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$such that (57) is satisfied. The proof goes by induction on the number of arcs of $(\mathcal{X}, \rightarrow)$. The base step is trivial. For the inductive step, consider two clockwise orient faces $\mathbf{f}_{1}, \mathbf{f}_{2}$ which are adjacent. This means that there exist $\mathbf{e}_{0}=(x \rightarrow y \rightarrow x) \in \mathcal{E}$ such that $(x \rightarrow y) \in \mathbf{f}_{1}$ and $(y \rightarrow x) \in \mathbf{f}_{2}$. Consider the graph $\left(\mathcal{X}, \rightarrow_{1}\right)$ obtained by removing $\mathbf{e}_{0}$ from $(\mathcal{X}, \rightarrow)$. This planar graph instead of the two faces $\mathbf{f}_{1}$ and $\mathbf{f}_{2}$ has a single face $\mathbf{h}$, which corresponds to the union of $\mathbf{f}_{1}$ and $\mathbf{f}_{2}$. On this $(\mathcal{X}, \rightarrow)$ we define $\psi: \mathcal{E} \backslash \mathbf{e}_{0} \cup \mathcal{F} \backslash\left\{\mathbf{f}_{1}, \mathbf{f}_{2}\right\} \cup \mathbf{h}$ as follows:

$$
\begin{align*}
& \forall \mathbf{e} \in \mathcal{E} \backslash \mathbf{e}_{0}, \quad \psi(\mathbf{e})=\varphi(\mathbf{e}), \\
& \forall \mathbf{f} \in \mathcal{F} \backslash\left\{\mathbf{f}_{1}, \mathbf{f}_{2}\right\}, \quad \psi(\mathbf{f})=\varphi(\mathbf{f}),  \tag{58}\\
& \psi(\mathbf{h})=\frac{\varphi\left(\mathbf{f}_{1}\right) \varphi\left(\mathbf{f}_{2}\right)}{\varphi\left(\mathbf{e}_{0}\right)} .
\end{align*}
$$

By the inductive hypothesis there exist $j: \mathcal{A} \backslash \mathbf{e}_{0} \rightarrow \mathbb{R}_{+}$such that

$$
\begin{equation*}
\forall \mathbf{e} \in \mathcal{E} \backslash \mathbf{e}_{0}, \quad \Phi_{j}(\mathbf{e})=\psi(\mathbf{e}) \tag{59}
\end{equation*}
$$

and

$$
\begin{equation*}
\forall \mathbf{f} \in \mathcal{F} \backslash\left\{\mathbf{f}_{1}, \mathbf{f}_{2}\right\} \cup\{\mathbf{h}\}, \quad \Phi_{j}(\mathbf{f})=\psi(\mathbf{f}) . \tag{60}
\end{equation*}
$$

Consider $\mathbf{f}_{1}=\left(x \rightarrow y \rightarrow x_{2} \rightarrow \cdots \rightarrow x\right)$ and $\mathbf{f}_{2}=\left(y \rightarrow x \rightarrow y_{2} \rightarrow \cdots \rightarrow y\right)$. We extend $j$ to $\mathbf{e}_{0}$ by defining

$$
\begin{align*}
& j(x \rightarrow y)=\varphi\left(\mathbf{f}_{1}\right)\left[j\left(y \rightarrow x_{2}\right) \prod_{i=2}^{\ell\left(\mathbf{f}_{1}\right)-1} j\left(x_{i} \rightarrow x_{i+1}\right)\right]^{-1},  \tag{61}\\
& j(y \rightarrow x)=\varphi\left(\mathbf{f}_{2}\right)\left[j\left(x \rightarrow y_{2}\right) \prod_{i=2}^{\ell\left(\mathbf{f}_{2}\right)-1} j\left(y_{i} \rightarrow y_{i+1}\right)\right]^{-1} .
\end{align*}
$$

[^3]We claim that $j$ as constructed here satisfies (57). For $\mathbf{f} \neq \mathbf{f}_{1}, \mathbf{f}_{2}$ and $\mathbf{e} \neq \mathbf{e}_{0}$, this is granted by (59) and (60). Using (61), it is seen that $\Phi_{j}\left(\mathbf{f}_{1}\right)=\varphi\left(\mathbf{f}_{1}\right)$ and $\Phi_{j}\left(\mathbf{f}_{2}\right)=\varphi\left(\mathbf{f}_{2}\right)$. Therefore we only need to check $\mathbf{e}_{0}$. Using (58), the inductive hypothesis and what we have just proven we arrive at

$$
\Phi_{j}\left(\mathbf{e}_{0}\right)=\frac{\Phi_{j}\left(\mathbf{f}_{1}\right) \Phi_{j}\left(\mathbf{f}_{2}\right)}{\Phi_{j}(\mathbf{h})}=\frac{\varphi\left(\mathbf{f}_{1}\right) \varphi\left(\mathbf{f}_{2}\right)}{\psi(\mathbf{h})} \stackrel{(58)}{=} \varphi\left(\mathbf{e}_{0}\right),
$$

which is the desired conclusion. This concludes the proof that an intensity $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$satisfying (57) exists. To complete the proof we show that it is possible to modify $j$ in such a way that both Assumption 4.1 and (57) are satisfied. For this purpose, we observe that if $j$ is an intensity satisfying (57), all other intensities $k: \mathcal{A} \rightarrow \mathbb{R}_{+}$fulfilling (57) are of the form

$$
k\left(z \rightarrow z^{\prime}\right)=\exp \left(\phi\left(z^{\prime}\right)-\phi(z)\right) j\left(z \rightarrow z^{\prime}\right)
$$

where $\phi: \mathcal{X} \rightarrow \mathbb{R}$ is some potential on $\mathcal{X}$. For Assumption 4.1 to hold, there must exist $v>0$ such that $\bar{k}(z) \equiv v$ for all $z \in \mathcal{X}$. Let us define $h:=\exp (\phi)$. What we look for is then a pair $h, v$ such that

$$
\forall z \in \mathcal{X}, \quad \sum_{z^{\prime}: z \rightarrow z^{\prime}} j\left(z \rightarrow z^{\prime}\right) h\left(z^{\prime}\right)=v h(z), \quad h(z)>0 \forall z \in \mathcal{X} .
$$

Since w.l.o.g $\mathcal{X} \subseteq \mathbb{N}$, if we define the matrix $K=\left(k_{m, n}\right)_{m, \in \mathbb{N}}$ with $k_{m, n}:=k(m \rightarrow n)$, we can rewrite the former equation as

$$
K \cdot h=v h, \quad v>0, h>0 .
$$

If $\mathcal{X}$ is finite, the existence of a solution is ensured by the standard Perron Frobenius Theorem. The uniqueness statement is a consequence of the fact that the eigenspace of the positive eigenvalue has dimension 1. If $\mathcal{X}$ is infinite and countable, we can use Corollary of Theorem 2 at page 1799 of [43]. We are entitled to use the Corollary because $(\mathcal{X}, \rightarrow)$ is of bounded degree.

## General graph

Lemma 4.8. Let $(\mathcal{X}, \rightarrow)$ be a graph fulfilling Assumption $4.2, \mathcal{T}$ be a tree and $\mathcal{C}$ be a $\mathcal{T}$-basis of the closed walks. Let $\varphi: \mathcal{C} \rightarrow \mathbb{R}_{+}$be bounded from above. Then there exist $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$such that Assumption 4.1 is satisfied and

$$
\begin{equation*}
\forall \mathbf{c} \in \mathcal{C}, \quad \Phi_{j}(\mathbf{c})=\varphi(\mathbf{c}) . \tag{62}
\end{equation*}
$$

If $\mathcal{X}$ is a finite set, then $j$ is unique. If $\mathcal{X}$ is infinite, then all other functions $k: \mathcal{A} \rightarrow \mathbb{R}_{+}$fulfilling Assumption 4.1 and (62) can be written in the form

$$
k\left(z \rightarrow z^{\prime}\right)=\exp \left(\phi\left(z^{\prime}\right)-\phi(z)\right) j\left(z \rightarrow z^{\prime}\right),
$$

where $h=\exp (\phi)$ is a positive solution to:

$$
\forall z \in \mathcal{X}, \quad \sum_{z^{\prime} ; z \rightarrow z^{\prime}} j\left(z \rightarrow z^{\prime}\right) h\left(z^{\prime}\right)=v h(z)
$$

for some constant $v>0$.
Here is the proof of Lemma 4.8.
Proof. We only show that we can construct $j: \mathcal{A} \rightarrow \mathbb{R}_{+}$such that (62) is satisfied. The proof that $j$ can be turned into an intensity $k$ satisfying Assumption 4.1 can be done following Lemma 4.7 with almost no change. For any $\mathbf{e}=(x \rightarrow y \rightarrow x) \in \mathcal{E} \backslash \mathcal{E}^{*}$ (i.e. $\mathbf{e} \subseteq \mathcal{T}$ ), we choose exactly one among $(x \rightarrow y)$ and $(y \rightarrow x)$ and set the value of $j(x \rightarrow y)$ to an arbitrary positive value. Then we set $j(y \rightarrow x)=\frac{\varphi(\mathbf{e})}{j(x \rightarrow y)}$. Next, for any $\mathbf{e} \in \mathcal{E}^{*}$ we let $x \rightarrow y$ be the
arc of e such that $\mathbf{c}_{x \rightarrow y}=\mathbf{c}_{\mathbf{e}}$. We observe that $\mathbf{c}_{x \rightarrow y}$ can be written as $\left(x \rightarrow y \rightarrow \mathbf{p}_{y \rightarrow x}\right.$ ) for some simple walk $\mathbf{p}_{y \rightarrow x}$ from $y$ to $x$ whose arcs are in $\mathcal{T}$. The value of $j$ has been already set on $\mathbf{p}_{y \rightarrow x}$ : therefore we can then set $j(x \rightarrow y)$ as $\frac{\varphi\left(\mathbf{c}_{\mathbf{e}}\right)}{\Phi_{j}\left(\mathbf{p}_{y \rightarrow x}\right)}$. Finally, we set $j$ on $y \rightarrow x$ by $j(y \rightarrow x):=\varphi(\mathbf{e}) / j(x \rightarrow y)$. It is then easy to check that the intensity $j$ so constructed satisfies (62).

## Appendix

The appendix is organized as follows: we first recall the main tools used in the proof of Theorem 2.1. Then we prove the two Lemmas A. 1 and A.2, which are needed in the proof of Theorem 3.1. Finally, we prove Lemma A.4, which is part of the proof of Theorem 3.2.

## About Theorem 2.1

We recall two of the main ingredients used in the proof. The first one is the integration by parts (duality) formula proved in [45, Th.4.1] to characterize bridges of Brownian diffusions. Here, we report a slightly simplified version of the formula, which still suffices for the scopes of this paper.

Theorem A. 1 (Integration by parts formula). Let $\mathbb{P}^{x}$ be law of

$$
d X_{t}=-\nabla U\left(t, X_{t}\right) d t+d B_{t}, \quad X_{0}=x
$$

Let $\mathbb{Q}$ be a probability measure on $C\left([0,1], \mathbb{R}^{d}\right)$ satisfying the regularity hypothesis $(\mathrm{A} 0),(\mathrm{H} 1)$, (H2) of Theorem 4.1 in [45]. Then $\mathbb{Q}$ is the bridge $\mathbb{P}^{x y}$ if and only if $\mathbb{Q}\left(\left(X_{0}, X_{1}\right)=(x, y)\right)=1$ and the formula

$$
\mathbb{E}_{\mathbb{Q}}\left(\mathcal{D}_{h} F\right)=\mathbb{E}_{\mathbb{Q}}\left(F \int_{0}^{1} \dot{h}(t) \cdot d X_{t}\right)+\mathbb{E}_{\mathbb{Q}}\left(F \int_{0}^{1} \nabla \mathscr{U}\left(t, X_{t}\right) \cdot h(t) d t\right)
$$

holds for any simple functional $F$ and any direction of differentiation $h$ which is continuous, piecewise linear and satisfies the loop condition

$$
h(1)=h(0)=0 .
$$

Let us recall that by a simple functional we mean a functional that can be written in the form $\varphi\left(X_{t_{1}}, \ldots, X_{t_{k}}\right)$ for some $\mathcal{C}_{b}^{\infty}\left(\mathbb{R}^{d \times k}\right)$ function $\varphi$ and finitely many $t_{1}, \ldots, t_{k}$. The directional Fréchet derivative $\mathcal{D}_{h} F$ of the simple functional $F$ is defined as usual:

$$
\begin{aligned}
\mathcal{D}_{h} F & =\lim _{\varepsilon \rightarrow 0} \frac{\varphi\left(X_{t_{1}}+\varepsilon h\left(t_{1}\right), \ldots, X_{t_{k}}+\varepsilon h\left(t_{k}\right)\right)-\varphi\left(X_{t_{1}}, \ldots, X_{t_{k}}\right)}{\varepsilon} \\
& =\sum_{j=1}^{k} \sum_{i=1}^{d} \partial_{x_{i}^{j}} \varphi\left(X_{t_{1}}, \ldots, X_{t_{k}}\right) h_{i}\left(t_{j}\right)
\end{aligned}
$$

The second ingredient is a Theorem proved in [10] that gives a quantitative version of the statement that marginalization preserves log-concavity. We follow the presentation of [48].

Theorem A. 2 (Preservation of strong log-concavity). Let $F: \mathbb{R}^{m+n} \rightarrow \mathbb{R}_{+}$be log concave and let $\Sigma(\cdot)$ be a positive quadratic form on $\mathbb{R}^{m+n}$. Write $w=\left(v, v^{\prime}\right)$, with $z \in \mathbb{R}^{m+n}, v \in \mathbb{R}^{m}, v^{\prime} \in \mathbb{R}^{n}$. Let $F(w)$ be jointly log-concave on $\mathbb{R}^{m+n}$ and define on $\mathbb{R}^{n}$,

$$
\begin{equation*}
G\left(v^{\prime}\right)=\frac{\int_{\mathbb{R}^{m}} F(w) \exp (-\Sigma(w)) d v}{\int_{\mathbb{R}^{m}} \exp (-\Sigma(w)) d v} \tag{63}
\end{equation*}
$$

Then $v^{\prime} \mapsto G\left(v^{\prime}\right)$ is log-concave.
For the proof we refer to [48, Theroem 13.3, pag. 204] or [10, Theorem 4.3].

## Proof of Lemma A. 1

Lemma A.1. Let $h$ be defined by (37) and $\psi$ be as in (36). Then

$$
\forall \tau>0, \quad \psi_{\tau} \leq h_{\tau}
$$

Proof. Consider $\varepsilon>0$ and define $h_{\tau}^{\varepsilon}$ as the unique solution of

$$
\begin{equation*}
\tau \partial_{\tau} h_{\tau}^{\varepsilon}-h_{\tau}^{\varepsilon}=\tau(\exp (\tau)-1), \quad \partial_{\tau} h_{0}^{\varepsilon}=\rho(f)+\varepsilon . \tag{64}
\end{equation*}
$$

Then $\eta_{0}^{\varepsilon}:=\psi_{0}-h_{0}^{\varepsilon}=0$ satisfies:

$$
\tau \partial_{\tau} \eta_{\tau}^{\varepsilon}-\eta_{\tau}^{\varepsilon} \leq 0, \quad \partial_{\tau} \eta_{0}^{\varepsilon}=-\varepsilon
$$

Since $\eta^{\varepsilon}$ is continuously differentiable, we have that $T>0$, where $T$ is defined as

$$
\begin{equation*}
T:=\inf \left\{\tau>0: \partial_{\tau} \eta_{\tau}^{\varepsilon}=0\right\} . \tag{65}
\end{equation*}
$$

Assume that $T<+\infty$. Then, at $T$, we have

$$
\begin{equation*}
T \underbrace{\partial_{\tau} \eta_{T}^{\varepsilon}}_{=0}-\eta_{T}^{\varepsilon} \leq 0 \quad \Rightarrow \quad \eta_{T}^{\varepsilon} \geq 0 . \tag{66}
\end{equation*}
$$

But this is impossible since $\eta_{0}^{\varepsilon}=0, \partial_{\tau} \eta_{\tau}^{\varepsilon}<0$ for all $\tau<T$. Therefore $\partial_{\tau} \eta_{\tau}^{\varepsilon}<0$ for all $\tau>0$. Since $\eta_{0}^{\varepsilon}=0$, we also have that $\psi_{\tau}^{\varepsilon}<0$ for all $\tau>0$. Therefore, as the choice of $\varepsilon$ was arbitrary,

$$
\forall \tau>0, \quad \psi_{\tau} \leq \inf _{\varepsilon>0} h_{\tau}^{\varepsilon}=h_{\tau} .
$$

## Proof of Lemma A. 2

## Lemma A.2.

$$
\mathbb{E}_{\pi_{\Phi}}(g)-\left(\Phi+\frac{1}{k+1} \Phi^{1 /(k+1)}\right) \leq \mathbb{E}_{\rho_{\Phi}}(f) .
$$

Proof. By construction of $g$, see (51) we can w.l.o.g assume that $f(0)=g(0)=0$. By (11), we have that $\rho_{\Phi}(n) \leq$ $\frac{\Phi}{n} \rho_{\Phi}(n-1) .{ }^{6}$ Therefore, using the 1-Lipschitzianity of $f$ and $f(0)=0$ :

$$
\mathbb{E}_{\rho_{\Phi}}(f) \geq-\sum_{n=1}^{+\infty} n \rho_{\Phi}(n) \geq-\Phi \sum_{n=1}^{+\infty} \rho_{\Phi}(n-1) \geq-\Phi .
$$

By construction, $g$ is $1 /(k+1)$ Lipschitz, and w.l.o.g. $g(0)=0$. Moreover, it is easy to see from the definition of $\pi_{\Phi}$ given at (41), that we have $\pi_{\Phi}(n) \leq \frac{\Phi^{1 / k+1}}{n} \pi_{\Phi}(n-1)$. Using all this:

$$
\mathbb{E}_{\pi_{\Phi}}(g) \leq \frac{1}{k+1} \sum_{n=1}^{+\infty} n \pi_{\Phi}(n) \leq \frac{\Phi^{1 / k+1}}{k+1} \sum_{n=1}^{+\infty} \pi_{\Phi}(n-1) \leq \frac{\Phi^{1 / k+1}}{k+1}
$$

The proof is complete.

[^4]
## Lemmas A. 3 and A. 4

Lemma A.3. Let $(\mathcal{X}, \rightarrow)$ be a graph satisfying Assumption 4.2 and let $\mathbb{S}_{\lambda}^{x}$ be the simple random walk defined at (21). Then

$$
\log \mathbb{S}_{\lambda}^{x x}\left(d\left(X_{t}, x\right) \geq R\right) \leq-2 R \log R+R[2+2 \log (\lambda t(1-t))+3 \log (1 / \delta-1)]+o(R)
$$

Proof. Let $x, y \in \mathcal{X}$. Recall that the maximum outer degree is $1 / \delta$ For simplicity, we set $1 / \delta=: \eta$. We first show that for some $c_{1}>0$

$$
\begin{equation*}
\mathbb{S}_{\lambda}^{x}\left(X_{t}=y\right) \leq c_{1} \frac{(\lambda t)^{d(x, y)}}{d(x, y)!}(\eta-1)^{d(x, y)} \tag{67}
\end{equation*}
$$

To this aim we define $\mathbf{W}_{k}$ as the set of walks of length $k$ which begin at $x$ and end at $y$. We have, by conditioning on the total number of jumps up to time $t$,

$$
\mathbb{S}_{\lambda}^{x}\left(X_{t}=y\right)=\exp (-\lambda t) \sum_{k=d(x, y)}^{+\infty} \frac{(\lambda t)^{k}}{k!} \sum_{\mathbf{w} \in \mathbf{W}_{k}} \lambda^{-k} \cdot \Phi_{j}(\mathbf{w})
$$

It is rather easy to see that $\lambda^{-k} \Phi_{j}(\mathbf{c}) \leq 1$. Moreover, the cardinality of $\mathbf{W}_{k}$ can be bounded above by $\eta(\eta-1)^{k-2}$. Using these two observations

$$
\begin{equation*}
\mathbb{S}_{\lambda}^{x}\left(X_{t}=y\right) \leq c_{0} \exp (-\lambda t) \sum_{k=d(x, y)}^{+\infty} \frac{(\lambda t)^{k}}{k!}(\eta-1)^{k} \tag{68}
\end{equation*}
$$

for some constant $c_{0}$. A standard argument based on Stirling's formula shows that the sum appearing in (68) can be controlled with its first summand, i.e. there exists a constant $c_{1}$ independent from $d(x, y)$ such that

$$
\begin{equation*}
\mathbb{S}_{\lambda}^{x}\left(X_{t}=y\right) \leq c_{1} \frac{(\lambda t)^{d(x, y)}}{d(x, y)!}(\eta-1)^{d(x, y)} \tag{69}
\end{equation*}
$$

which proves (67). Since there cannot be more than $(\eta-1)^{R}$ vertices at distance $R$ from $x$, we get that, using twice (69),

$$
\begin{aligned}
\mathbb{S}^{x x}\left(d\left(X_{t}, x\right)=R\right) & =\frac{1}{\mathbb{S}_{\lambda}^{x}\left(X_{1}=x\right)} \sum_{y: d(x, y)=R} \mathbb{S}_{\lambda}^{x}\left(X_{t}=y\right) \mathbb{S}_{\lambda}^{y}\left(X_{1-t}=x\right) \\
& \leq c_{2} \frac{\left(\lambda^{2} t(1-t)\right)^{R}}{R!^{2}}(\eta-1)^{3 R}
\end{aligned}
$$

for some $c_{2}>0$. Therefore:

$$
\mathbb{S}^{x x}\left(d\left(X_{t}, x\right) \geq R\right) \leq c_{2} \sum_{k=R}^{+\infty} \frac{\left(\lambda^{2} t(1-t)\right)^{k}}{k!^{2}}(\eta-1)^{3 k}
$$

Using again a standard argument with Stirling formula as we did in (68), we obtain

$$
\mathbb{S}^{x x}\left(d\left(X_{t}, x\right) \geq R\right) \leq c_{3} \frac{\left(\lambda^{2} t(1-t)\right)^{R}}{R!^{2}}(\eta-1)^{3 R}
$$

for some $c_{3}>0$. The conclusion follows from Stirling's formula, which allows to write $\log R!=R \log R-R+$ $o(R)$.

Lemma A.4. Let $\mathbb{S}_{\lambda}^{x}$ be the constant speed random walk on the square lattice defined by

$$
j\left(x \rightarrow x+v_{1}\right)=j\left(x \rightarrow x+v_{2}\right) \equiv \lambda .
$$

## Then

$$
\begin{equation*}
\log \mathbb{S}_{\lambda}^{x x}\left(d\left(X_{t}, \mathbb{E}_{\mathbb{S}_{\lambda}^{x x}}\left(X_{t}\right)\right) \geq R\right)=-2 R \log R+\left[\log \left(4 \lambda^{2} t(1-t)\right)+2\right] R+o(R) \tag{70}
\end{equation*}
$$

Lemma A. 4 is not directly implied by Lemma A.3. However, one can derive its proof by going along the same lines of the proof of Lemma A. 3 and use the exact computations that can be performed for the square lattice.

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[^0]:    ${ }^{1}$ See Definition 4.2 for the meaning of simple walk.

[^1]:    ${ }^{2}$ I.e. it connects all vertices of $(\mathcal{X}, \rightarrow)$.
    ${ }^{3}$ Closed walk of length two are allowed, as the graph is symmetric.

[^2]:    ${ }^{4}$ For the application we are going to make of the duality formula to be completely justified one shall extend its validity from the simple functionals to the differentiable functionals. A simple approximation argument, which we do not present here, takes care of that.

[^3]:    ${ }^{5}$ This is because we do not consider the walks of length two as faces. Faces have length at least three.

[^4]:    ${ }^{6}$ Actually, the quotient $\rho_{\Phi}(n) / \rho_{\Phi}(n-1)$ is of the order $1 / n^{k+1}$. However, here it suffices to consider $1 / n$.

